

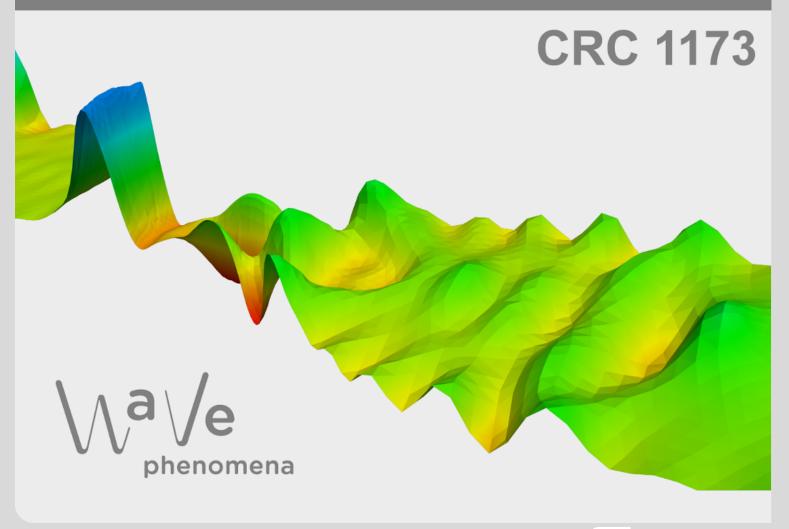


Monotonicity in inverse scattering for Maxwell's equation

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Monotonicity in inverse scattering for Maxwell's equations

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Abstract

We consider the inverse scattering problem to recover the support of penetrable scattering objects in three-dimensional free space from far field observations of scattered timeharmonic electromagnetic waves. The observed far field data are described by far field operators that map superpositions of plane wave incident fields to the far field patterns of the corresponding scattered waves. We discuss monotonicity relations for the eigenvalues of linear combinations of these operators with suitable probing operators. These monotonicity relations yield criteria and algorithms for reconstructing the support of scattering objects from the corresponding far field operators. To establish these results we combine the monotonicity relations with certain localized vector wave functions that have arbitrarily large energy in some prescribed region while at the same time having arbitrarily small energy on some other prescribed region. Throughout we suppose that the relative magnetic permeability of the scattering objects is one, while their real-valued relative electric permittivity may be inhomogeneous and the permittivity contrast may even change sign. Numerical examples illustrate our theoretical findings.

Mathematics subject classifications (MSC2010): 35R30, (65N21)

Keywords: Inverse scattering, Maxwell's equations, monotonicity, far field operator, inhomogeneous medium

Short title: Monotonicity in inverse electromagnetic scattering

1 Introduction

We discuss an inverse scattering problem for time-harmonic Maxwell's equations, where the goal is to determine the position and the shape of a collection of compactly supported scattering objects from far field observations of scattered electromagnetic waves. We focus on a qualitative reconstruction method that is closely related to the linear sampling method (see, e.g., [8, 22]) and the factorization method (see, e.g., [34, 35, 36]). We extend the monotonicity based approach from [18] (see also [1, 28, 29]) from scalar wave propagation described by the Helmholtz equation to electromagnetic wave propagation governed by Maxwell's equations. This monotonicity method is formulated in terms of far field operators that map superpositions of incident plane waves to the far field patterns of the corresponding scattered waves. It exploits monotonicity properties of the eigenvalues of linear combinations of these operators with suitable probing operators. Throughout we assume that the scattering objects are penetrable, non-magnetic and non-absorbing, i.e., the magnetic permeability μ is constant throughout \mathbb{R}^3 , while the real-valued electric permittivity ε is constant outside the support of the scatterer but may be inhomogeneous inside the scattering objects.

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Monotonicity based shape reconstruction techniques have first been analyzed for the inverse conductivity problem in [16, 30], extending an earlier monotonicity based reconstruction scheme that has been proposed in [45]. The method is related to monotonicity principles for the Laplace equation which have been established in [32, 33]. It has been further developed in [26, 27, 31], and its numerical implementation has been considered in [13, 14, 15]. More recently, an extension to impenetrable conductivity inclusions has been provided in [9]. The results from [30] have been extended to an inverse coefficient problem for the Helmholtz equation on bounded domains in [28, 29], and in [18] the approach has been generalized to an inverse medium scattering problem for the Helmholtz equation on unbounded domains. Inverse obstacle scattering problems have been considered in [1, 12], and an inverse crack detection problem has been studied in [11]. For further recent contributions on monotonicity based reconstruction methods for inverse problems for various other partial differential equations we refer, e.g., to [5, 6, 23, 24, 41, 44, 46]. The main contribution of this work is a generalization of the analysis from [18] to an inverse medium scattering problem scattering problem scattering problem scattering problem scattering problem scattering problem scattering problems for the main contribution of this work is a generalization of the analysis from [18] to an inverse medium scattering problem scattering problems for the analysis from [18] to an inverse medium scattering problem scattering prob

As in the scalar case, we establish a monotonicity relation that basically says that a suitable unitary transform of the difference of two far field operators corresponding to two different scattering objects is positive or negative definite up to a finite dimensional subspace, if the difference of the reciprocals of the corresponding electric permittivities is either non-negative or non-positive pointwise almost everywhere. The main difficulty in the analysis of the monotonicity relation for Maxwell's equations stems from the large null-space of the curl operator and the need for suitable compact embeddings. This is one reason for assuming that the magnetic permeability is constant. The same assumption has been made in [34, 35].

We combine the monotonicity relation with so-called localized vector wave functions to establish the rigorous characterization of the shape of the scattering objects in terms of the corresponding far field operators. Localized vector wave functions are solutions to the scattering problem corresponding to suitable incident fields that have arbitrarily large energy on some prescribed region $B \subseteq \mathbb{R}^3$, while at the same time having arbitrarily small energy on a different prescribed region $\Omega \subseteq \mathbb{R}^3$, assuming that $\mathbb{R}^3 \setminus \overline{\Omega}$ is connected and $B \not\subseteq \Omega$. Similar classes of solutions have, e.g., already been studied for the Laplace equation [16], for the Helmholtz equation on bounded domains [29] and on unbounded domains [18], and for Maxwell's equations on bounded domains [25]. It is interesting to note that, in contrast to factorization and linear sampling methods, the characterizations of the support of the scattering objects in terms of the far field operator developed in [18] and in this work are independent of so-called transmission eigenvalues (see, e.g., [7, 10] for an account on the latter). On the other hand, the monotonicity relation for far field operators is somewhat related to well-known monotonicity principles for the phases of the eigenvalues of the so-called scattering operator, which have been discussed in [40] to describe transmission eigenvalues in terms of far field operators (see also [3, 38, 39] for further results in this direction). Another potential advantage of the monotonicity based approach is that it only requires the relative electric permittivity to be strictly larger or strictly smaller than one locally near any point on the boundary of the scattering objects.

The monotonicity based shape characterizations consist in comparing a given (observed) far field operator to certain probing operators to decide whether some probing domains $B \subseteq \mathbb{R}^3$ corresponding to the probing operators are contained inside the support $D \subseteq \mathbb{R}^3$ of the unknown scatterers, or whether they contain the support of the scatterers. These probing operators can either be simulated far field operators corresponding to the probing domains, or simulated linearizations of such far field operators as considered in this work. We present numerical results for the radially symmetric case and for sign-definite scattering objects, i.e., where the relative electric permittivity is either strictly larger or strictly smaller than 1 a.e. inside the scatterer. A stable numerical implementation of the monotonicity based shape characterization for the indefinite case, where the assumption on the sign of the permittivity contrast is waived, is more elaborate and still requires further research efforts.

The outline of this work is as follows. After introducing some notation in the next section, we briefly recall the mathematical formulation of the scattering problem in Section 3. In Section 4 we discuss a monotonicity principle for the far field operator, and in Section 5 we establish the existence of localized vector wave functions for Maxwell's equations on unbounded domains. We combine the monotonicity principle and the localized vector wave functions to develop rigorous characterizations of the support of sign-definite scattering objects in terms of the far field operator in Section 6. In Sections 7 and 8 we establish corresponding results for the indefinite case, and in Section 9 we present numerical results.

2 Preliminaries

We start by introducing some notation (see, e.g., [10, 37, 42] for details). The boldface Latin letters $\boldsymbol{x}, \boldsymbol{y}$ refer to generic points in $\mathbb{R}^3, \boldsymbol{x} \cdot \boldsymbol{y}$ and $\boldsymbol{x} \times \boldsymbol{y}$ denote the inner product and the vector product of \boldsymbol{x} and \boldsymbol{y} , and $|\boldsymbol{x}|$ is the Euclidean norm of \boldsymbol{x} . By $B_R(0) \subseteq \mathbb{R}^3$ we denote the ball of radius R > 0 centered at the origin.

For a bounded smooth domain $\Omega \subseteq \mathbb{R}^3$ we define

$$H(\operatorname{\mathbf{curl}};\Omega) := \left\{ \boldsymbol{u} \in L^2(\Omega, \mathbb{C}^3) \mid \operatorname{\mathbf{curl}} \boldsymbol{u} \in L^2(\Omega, \mathbb{C}^3) \right\}, \\ H_{\operatorname{loc}}(\operatorname{\mathbf{curl}}; \mathbb{R}^3 \setminus \overline{\Omega}) := \left\{ \boldsymbol{u} \in L^2_{\operatorname{loc}}(\mathbb{R}^3 \setminus \overline{\Omega}, \mathbb{C}^3) \mid \operatorname{\mathbf{curl}} \boldsymbol{u} \in L^2_{\operatorname{loc}}(\mathbb{R}^3 \setminus \overline{\Omega}, \mathbb{C}^3) \right\}$$

where $L^2_{loc}(\mathbb{R}^3 \setminus \overline{\Omega}, \mathbb{C}^3)$ is the space of complex-valued locally square integrable vector fields on $\mathbb{R}^3 \setminus \overline{\Omega}$. The unit outward normal vector field on $\partial\Omega$ is denoted by $\boldsymbol{\nu}$, and for smooth functions on $\partial\Omega$ the surface gradient **Grad** and the surface vector curl **Curl** may be defined in the usual way via parametric representation. The dual operators of – **Grad** and **Curl** (with respect to the duality pairing given by the L^2 bilinear forms) are the surface divergence Div and the surface scalar curl Curl. Denoting by $H_t^{-1/2}(\partial\Omega, \mathbb{C}^3)$ the Hilbert space of tangential $H^{-1/2}(\partial\Omega, \mathbb{C}^3)$ -vector fields, let

$$\begin{aligned} H^{-1/2}(\operatorname{Div};\partial\Omega) &:= \left\{ \phi \in H_t^{-1/2}(\partial\Omega,\mathbb{C}^3) \mid \operatorname{Div} \phi \in H^{-1/2}(\partial\Omega,\mathbb{C}) \right\}, \\ H^{-1/2}(\operatorname{Curl};\partial\Omega) &:= \left\{ \phi \in H_t^{-1/2}(\partial\Omega,\mathbb{C}^3) \mid \operatorname{Curl} \phi \in H^{-1/2}(\partial\Omega,\mathbb{C}) \right\}. \end{aligned}$$

Then the space $H^{-1/2}(\text{Div};\partial\Omega)$ is naturally identified with the dual space of $H^{-1/2}(\text{Curl};\partial\Omega)$. Throughout we write the dual pairing between $H^{-1/2}(\text{Div};\partial\Omega)$ and $H^{-1/2}(\text{Curl};\partial\Omega)$ as an integral for notational convenience.

For any regular vector field \boldsymbol{u} on Ω we define the tangential traces $\gamma_t(\boldsymbol{u}) := \boldsymbol{\nu} \times \boldsymbol{u}|_{\partial\Omega}$ and $\pi_t(\boldsymbol{u}) := (\boldsymbol{\nu} \times \boldsymbol{u}|_{\partial\Omega}) \times \boldsymbol{\nu}$. These can be extended to continuous linear, surjective operators

$$\gamma_t : H(\operatorname{\mathbf{curl}}; \Omega) \to H^{-1/2}(\operatorname{Div}; \partial \Omega), \qquad \pi_t : H(\operatorname{\mathbf{curl}}; \Omega) \to H^{-1/2}(\operatorname{Curl}; \partial \Omega),$$
(2.1)

and for all $\boldsymbol{u}, \boldsymbol{w} \in H(\mathbf{curl}; \Omega)$ we have the integration by parts formula

$$\int_{\Omega} (\operatorname{\mathbf{curl}} \boldsymbol{u}) \cdot \boldsymbol{w} \, \mathrm{d}\boldsymbol{x} - \int_{\Omega} \boldsymbol{u} \cdot (\operatorname{\mathbf{curl}} \boldsymbol{w}) \, \mathrm{d}\boldsymbol{x} = \int_{\partial\Omega} (\boldsymbol{\nu} \times \boldsymbol{u}) \cdot ((\boldsymbol{\nu} \times \boldsymbol{w}) \times \boldsymbol{\nu}) \, \mathrm{d}\boldsymbol{s} \,.$$
(2.2)

Similarly, the map r, which is given by $r(\phi) := \nu \times \phi$ for any smooth vector field ϕ on $\partial\Omega$, can be extended to an isomorphism $r : H^{-1/2}(\text{Div};\partial\Omega) \to H^{-1/2}(\text{Curl};\partial\Omega)$. For the matter of readability, we will use the classical notation $\nu \times \cdot$ and $(\nu \times \cdot) \times \nu$ for the trace operators in (2.1), and for the isomorphism r throughout this work.

The subspace of $H(\operatorname{curl}; \Omega)$ -functions with vanishing tangential traces is denoted by

$$H_0(\operatorname{\mathbf{curl}};\Omega) := \left\{ \boldsymbol{u} \in H(\operatorname{\mathbf{curl}};\Omega) \mid \boldsymbol{\nu} \times \boldsymbol{u}|_{\partial\Omega} = 0 \right\}.$$

We also write ν for the outward normal vector field on the unit sphere S^2 , and accordingly we define

$$L^2_t(S^2, \mathbb{C}^3) := \left\{ u \in L^2(S^2, \mathbb{C}^3) \mid \boldsymbol{\nu} \cdot \boldsymbol{u} = 0 \text{ a.e. on } S^2 \right\}.$$

3 Scattering by an inhomogeneous medium

We consider the propagation of time-harmonic electromagnetic waves in non-magnetic media in \mathbb{R}^3 . Let $k = \omega \sqrt{\varepsilon_0 \mu_0}$ be the wave number at an angular frequency $\omega > 0$ in free space with electric permittivity $\varepsilon_0 > 0$ and magnetic permeability $\mu_0 > 0$. An incident field $(\mathbf{E}^i, \mathbf{H}^i)$ is an entire solution to Maxwell's equations

$$\operatorname{curl} \boldsymbol{E}^{i} - \mathrm{i}\omega\mu_{0}\boldsymbol{H}^{i} = 0, \quad \operatorname{curl} \boldsymbol{H}^{i} + \mathrm{i}\omega\varepsilon_{0}\boldsymbol{E}^{i} = 0 \qquad \text{in } \mathbb{R}^{3}.$$
(3.1)

We suppose that such an incident field is scattered by an inhomogeneous medium with space dependent electric permittivity ε , and constant magnetic permeability $\mu = \mu_0$. We denote by $\varepsilon_r := \varepsilon/\varepsilon_0$ the *relative electric permittivity* of the inhomogeneous medium, and we assume that $\varepsilon_r^{-1} = 1 - q$ for some real-valued contrast function

$$q \in \mathcal{Y}_D := \left\{ f \in L^{\infty}(\mathbb{R}^3) \mid f|_D \in W^{1,\infty}(D,\mathbb{R}), \ \operatorname{supp}(f) = \overline{D}, \ \operatorname{ess\,inf}(1-f) > 0 \right\},$$

where $D \subseteq \mathbb{R}^3$ is open and bounded of class C^0 . The *total field* $(\mathbf{E}_q, \mathbf{H}_q)$ excited by an incident field $(\mathbf{E}^i, \mathbf{H}^i)$ in the inhomogeneous medium satisfies

$$\operatorname{curl} \boldsymbol{E}_q - \mathrm{i}\omega\mu_0 \boldsymbol{H}_q = 0, \quad \operatorname{curl} \boldsymbol{H}_q + \mathrm{i}\omega\varepsilon\boldsymbol{E}_q = 0 \qquad \text{in } \mathbb{R}^3.$$
(3.2)

Rewriting

$$(\boldsymbol{E}_q, \boldsymbol{H}_q) = (\boldsymbol{E}^i, \boldsymbol{H}^i) + (\boldsymbol{E}_q^s, \boldsymbol{H}_q^s)$$
(3.3)

as a superposition of the incident field $(\mathbf{E}^i, \mathbf{H}^i)$ and the *scattered field* $(\mathbf{E}^s_q, \mathbf{H}^s_q)$, we assume that the scattered field satisfies the Silver-Müller radiation condition

$$\lim_{|\boldsymbol{x}|\to\infty} \left(\sqrt{\varepsilon_0}\,\boldsymbol{x}\times\boldsymbol{E}_q^s(\boldsymbol{x}) - |\boldsymbol{x}|\sqrt{\mu_0}\boldsymbol{H}_q^s(\boldsymbol{x})\right) = 0 \tag{3.4}$$

uniformly with respect to all directions $\hat{x} := x/|x| \in S^2$.

It will often be convenient to eliminate either the electric field or the magnetic field from (3.1)–(3.4) and to work with one of the second order formulations given by

$$\operatorname{curl}\operatorname{curl} E^{i} - k^{2}E^{i} = 0 \quad \operatorname{in} \mathbb{R}^{3}, \qquad \qquad \operatorname{curl}\operatorname{curl} H^{i} - k^{2}H^{i} = 0 \quad \operatorname{in} \mathbb{R}^{3}, \qquad (3.5a)$$

$$\operatorname{curl}\operatorname{curl} \boldsymbol{E}_q - k^2 \varepsilon_r \boldsymbol{E}_q = 0 \quad \text{in } \mathbb{R}^3, \qquad \operatorname{curl} (\varepsilon_r^{-1} \operatorname{curl} \boldsymbol{H}_q) - k^2 \boldsymbol{H}_q = 0 \quad \text{in } \mathbb{R}^3, \quad (3.5b)$$

$$\boldsymbol{E}_{q} = \boldsymbol{E}^{i} + \boldsymbol{E}_{q}^{s} \quad \text{in } \mathbb{R}^{3}, \qquad \qquad \boldsymbol{H}_{q} = \boldsymbol{H}^{i} + \boldsymbol{H}_{q}^{s} \quad \text{in } \mathbb{R}^{3}, \qquad (3.5c)$$

 $\lim_{|\boldsymbol{x}|\to\infty} \left(\boldsymbol{x}\times\operatorname{\mathbf{curl}}\boldsymbol{E}_q^s(\boldsymbol{x}) + \mathrm{i}k|\boldsymbol{x}|\boldsymbol{E}_q^s(\boldsymbol{x})\right) = 0, \quad \lim_{|\boldsymbol{x}|\to\infty} \left(\boldsymbol{x}\times\operatorname{\mathbf{curl}}\boldsymbol{H}_q^s(\boldsymbol{x}) + \mathrm{i}k|\boldsymbol{x}|\boldsymbol{H}_q^s(\boldsymbol{x})\right) = 0, \quad (3.5d)$

respectively.

Remark 3.1. Throughout this work, Maxwell's equations are always to be understood in a weak sense. For instance, $E_q, H_q \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ are solutions to (3.2) (or equivalently to (3.5b)) if and only if either

$$\int_{\mathbb{R}^3} \left(\operatorname{\mathbf{curl}} \boldsymbol{E}_q \cdot \operatorname{\mathbf{curl}} \boldsymbol{\psi} - k^2 \varepsilon_r \boldsymbol{E}_q \cdot \boldsymbol{\psi} \right) \, \mathrm{d} \boldsymbol{x} = 0 \qquad \text{for all } \boldsymbol{\psi} \in H_0(\operatorname{\mathbf{curl}}; \mathbb{R}^3) \,,$$

or

$$\int_{\mathbb{R}^3} \left(\varepsilon_r^{-1} \operatorname{\mathbf{curl}} \boldsymbol{H}_q \cdot \operatorname{\mathbf{curl}} \boldsymbol{\psi} - k^2 \boldsymbol{H}_q \cdot \boldsymbol{\psi} \right) \, \mathrm{d} \boldsymbol{x} = 0 \qquad \text{for all } \boldsymbol{\psi} \in H_0(\operatorname{\mathbf{curl}}; \mathbb{R}^3) \,,$$

respectively. Standard regularity results (see, e.g., [47]) yield smoothness of (E_q, H_q) and (E_q^s, H_q^s) in $\mathbb{R}^3 \setminus \overline{B_R(0)}$, whenever $B_R(0)$ contains the scatterer D, and similarly the entire solution (E^i, H^i) is smooth throughout \mathbb{R}^3 . In particular the Silver-Müller radiation condition (3.4) is well defined.

Suppose that the incident field $(\mathbf{E}^i, \mathbf{H}^i) \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3) \times H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ satisfies (3.1). Using either a volume integral equation approach (see [36, pp. 113–118]) or a variational formulation on $B_R(0)$ involving the exterior Calderon operator (see, e.g., [42, pp. 262–272]), Riesz–Fredholm theory can be applied to show existence of a solution to (3.2)–(3.4), provided uniqueness holds. Under our assumptions on the coefficients, uniqueness of solutions to (3.2)–(3.4) follows, e.g., from [4, Thm. 2.1].

Throughout this work we call a solution to Maxwell's equations on an unbounded domain that satisfies the Silver-Müller radiation condition a *radiating solution*. \Diamond

The scattered field (E_q^s, H_q^s) has the asymptotic behavior

$$\boldsymbol{E}_{q}^{s}(\boldsymbol{x}) = \frac{e^{i\boldsymbol{k}|\boldsymbol{x}|}}{4\pi|\boldsymbol{x}|} \left(\boldsymbol{E}_{q}^{\infty}(\widehat{\boldsymbol{x}}) + \mathcal{O}(|\boldsymbol{x}|^{-1}) \right), \quad \boldsymbol{H}_{q}^{s}(\boldsymbol{x}) = \frac{e^{i\boldsymbol{k}|\boldsymbol{x}|}}{4\pi|\boldsymbol{x}|} \left(\boldsymbol{H}_{q}^{\infty}(\widehat{\boldsymbol{x}}) + \mathcal{O}(|\boldsymbol{x}|^{-1}) \right)$$
(3.6)

as $|\mathbf{x}| \to \infty$, uniformly in $\hat{\mathbf{x}} = \mathbf{x}/|\mathbf{x}|$ (see, e.g., [42, Cor. 9.5]). The electric and magnetic far field patterns $\mathbf{E}_q^{\infty}, \mathbf{H}_q^{\infty} \in L^2_t(S^2, \mathbb{C}^3)$ are given by

$$\boldsymbol{H}_{q}^{\infty}(\widehat{\boldsymbol{x}}) = \widehat{\boldsymbol{x}} \times \int_{\partial B_{R}(0)} \left(\mathrm{i}k(\boldsymbol{\nu} \times \boldsymbol{H}_{q}^{s})(\boldsymbol{y}) + (\boldsymbol{\nu} \times \mathrm{\mathbf{curl}}\,\boldsymbol{H}_{q}^{s})(\boldsymbol{y}) \times \widehat{\boldsymbol{x}} \right) e^{-\mathrm{i}k\widehat{\boldsymbol{x}} \cdot \boldsymbol{y}} \, \mathrm{d}s(\boldsymbol{y}) \,, \qquad (3.7a)$$

$$\boldsymbol{E}_{q}^{\infty}(\widehat{\boldsymbol{x}}) = \widehat{\boldsymbol{x}} \times \int_{\partial B_{R}(0)} \left(\mathrm{i}k(\boldsymbol{\nu} \times \boldsymbol{E}_{q}^{s})(\boldsymbol{y}) + (\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{E}_{q}^{s})(\boldsymbol{y}) \times \widehat{\boldsymbol{x}} \right) e^{-\mathrm{i}k\widehat{\boldsymbol{x}} \cdot \boldsymbol{y}} \, \mathrm{d}s(\boldsymbol{y}) \,, \tag{3.7b}$$

(see, e.g., [36, p. 121]). In particular, $H_q^{\infty}(\widehat{x}) = \sqrt{\frac{\varepsilon_0}{\mu_0}} \widehat{x} \times E_q^{\infty}(\widehat{x})$ for all $\widehat{x} \in S^2$. For the special case of a *plane wave incident field*

$$oldsymbol{E}^i(oldsymbol{x};oldsymbol{ heta},oldsymbol{p}) := -\sqrt{rac{\mu_0}{arepsilon_0}}(oldsymbol{ heta} imesoldsymbol{p})\,e^{\mathrm{i}koldsymbol{ heta}\cdotoldsymbol{x}}\,,\quadoldsymbol{H}^i(oldsymbol{x};oldsymbol{ heta},oldsymbol{p}) := oldsymbol{p}\,e^{\mathrm{i}koldsymbol{ heta}\cdotoldsymbol{x}}\,,\quadoldsymbol{K}\in\mathbb{R}^3$$

we explicitly indicate the dependence on the direction of propagation $\boldsymbol{\theta} \in S^2$ and on the polarization $\boldsymbol{p} \in \mathbb{C}^3$, which must satisfy $\boldsymbol{p} \cdot \boldsymbol{\theta} = 0$. Accordingly we write $(\boldsymbol{E}_q(\cdot; \boldsymbol{\theta}, \boldsymbol{p}), \boldsymbol{H}_q(\cdot; \boldsymbol{\theta}, \boldsymbol{p}))$, $(\boldsymbol{E}_q^s(\cdot; \boldsymbol{\theta}, \boldsymbol{p}), \boldsymbol{H}_q^s(\cdot; \boldsymbol{\theta}, \boldsymbol{p}))$, and $(\boldsymbol{E}_q^{\infty}(\cdot; \boldsymbol{\theta}, \boldsymbol{p}), \boldsymbol{H}_q^{\infty}(\cdot; \boldsymbol{\theta}, \boldsymbol{p}))$ for the corresponding scattered field, the total field, and the far field pattern, respectively.

The magnetic far field operator is defined as

$$F_q: L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3), \quad (F_q \boldsymbol{p})(\widehat{\boldsymbol{x}}) := \int_{S^2} \boldsymbol{H}_q^\infty(\widehat{\boldsymbol{x}}; \boldsymbol{\theta}, \boldsymbol{p}(\boldsymbol{\theta})) \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}), \quad (3.8)$$

and it is compact and normal (see, e.g., [36, Thm. 5.7]). Moreover, the magnetic scattering operator

$$\mathcal{S}_q: L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3), \quad \mathcal{S}_q \boldsymbol{p} := \left(I + \frac{\mathrm{i}k}{8\pi^2} F_q\right) \boldsymbol{p}, \qquad (3.9)$$

is unitary. Consequently the eigenvalues of F_q lie on the circle of radius $8\pi^2/k$ centered in $8\pi^2 i/k$ in the complex plane (cf., e.g., [36, Thm. 5.7]).

For any given $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ the tangential vector field $F_q \mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ is the far field pattern of the scattered magnetic field $\mathbf{H}^s_{\mathbf{p}}$ due to the incident field

$$\boldsymbol{E}_{\boldsymbol{p}}^{i}(\boldsymbol{x}) := -\sqrt{\frac{\mu_{0}}{\varepsilon_{0}}} \int_{S^{2}} \left(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta})\right) e^{\mathrm{i}\boldsymbol{k}\boldsymbol{\theta}\cdot\boldsymbol{x}} \,\mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \,, \quad \boldsymbol{H}_{\boldsymbol{p}}^{i}(\boldsymbol{x}) := \int_{S^{2}} \boldsymbol{p}(\boldsymbol{\theta}) e^{\mathrm{i}\boldsymbol{k}\boldsymbol{\theta}\cdot\boldsymbol{x}} \,\mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \,, \quad \boldsymbol{x} \in \mathbb{R}^{3} \,. \tag{3.10}$$

The latter is called a *Herglotz wave pair* with density p. We write $(E_{q,p}, H_{q,p})$ and $(E_{q,p}^s, H_{q,p}^s)$ for the corresponding total field and the scattered field, respectively. By linearity we have

$$\boldsymbol{E}_{q,\boldsymbol{p}}(\boldsymbol{x}) = \int_{S^2} \boldsymbol{E}_q(\boldsymbol{x};\boldsymbol{\theta},\boldsymbol{p}(\boldsymbol{\theta})) \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \,, \quad \boldsymbol{H}_{q,\boldsymbol{p}}(\boldsymbol{x}) = \int_{S^2} \boldsymbol{H}_q(\boldsymbol{x};\boldsymbol{\theta},\boldsymbol{p}(\boldsymbol{\theta})) \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \,, \quad \boldsymbol{x} \in \mathbb{R}^3 \,. \tag{3.11}$$

4 A monotonicity relation for the magnetic far field operator

The following extension of the Loewner order will be used to describe relative orderings of compact self-adjoint operators. Given two compact self-adjoint linear operators $A, B : X \to X$ on a Hilbert space X, we say that

$$A \leq_r B$$
 for some $r \in \mathbb{N}$,

if B - A has at most r negative eigenvalues. Similarly, we write $A \leq_{\text{fin}} B$ if $A \leq_r B$ holds for some $r \in \mathbb{N}$, and the notations $A \geq_r B$ and $A \geq_{\text{fin}} B$ are defined accordingly.

The next lemma was shown in [29, Cor. 3.3].

Lemma 4.1. Let $A, B : X \to X$ be two compact self-adjoint linear operators on a Hilbert space X with inner product $\langle \cdot, \cdot \rangle$, and let $r \in \mathbb{N}$. Then the following statements are equivalent:

- (a) $A \leq_r B$
- (b) There exists a finite-dimensional subspace $V \subseteq X$ with $\dim(V) \leq r$ such that

$$\langle (B-A)v, v \rangle \ge 0 \quad \text{for all } v \in V^{\perp}$$

Lemma 4.1 implies that \leq_{fin} and \geq_{fin} are transitive relations (see [29, Lem. 3.4]). The theorem below gives a *monotonicity relation* for the magnetic far field operator in terms of this modified Loewner order. As usual the real part of a linear operator $A : X \to X$ on a Hilbert space X is the self-adjoint operator given by $\text{Re}(A) := \frac{1}{2}(A + A^*)$.

Theorem 4.2. Let $D_1, D_2 \subseteq \mathbb{R}^3$ be open and bounded of class C^0 , and let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$. Then there exists a finite-dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})\boldsymbol{p}} \, \mathrm{d}s\right) \geq \int_{\mathbb{R}^3} (q_2 - q_1) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{for all } \boldsymbol{p} \in V^{\perp} \,.$$
(4.1)

In particular

$$q_1 \le q_2 \qquad implies \ that \qquad \operatorname{Re}(\mathcal{S}_{q_1}^* F_{q_1}) \le_{\operatorname{fin}} \operatorname{Re}(\mathcal{S}_{q_1}^* F_{q_2}). \tag{4.2}$$

Remark 4.3. Recalling (3.9) and using that S_1 and S_2 are unitary operators, we find that

$$\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1}) = \frac{8\pi^2}{\mathrm{i}k} \mathcal{S}_{q_1}^*(\mathcal{S}_{q_2} - \mathcal{S}_{q_1}) = \left(\frac{8\pi^2}{\mathrm{i}k} \mathcal{S}_{q_2}^*(\mathcal{S}_{q_2} - \mathcal{S}_{q_1})\right)^* = \left(\mathcal{S}_{q_2}^*(F_{q_2} - F_{q_1})\right)^*.$$

Accordingly $\operatorname{Re}(\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})) = \operatorname{Re}(\mathcal{S}_{q_2}^*(F_{q_2} - F_{q_1}))$, and therefore the monotonicity relations (4.1)–(4.2) remain valid, if we replace $\mathcal{S}_{q_1}^*$ by $\mathcal{S}_{q_2}^*$ in these formulas.

Applying Remark 4.3 we may interchange the roles of q_1 and q_2 in Theorem 4.2, except for $S_{q_1}^*$, to obtain the following result.

Corollary 4.4. Let $D_1, D_2 \subseteq \mathbb{R}^3$ be open and bounded of class C^0 , and let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$. Then there exists a finite-dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})\boldsymbol{p}} \, \mathrm{d}s\right) \leq \int_{\mathbb{R}^3} (q_2 - q_1) |\operatorname{curl} \boldsymbol{H}_{q_2, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{for all } \boldsymbol{p} \in V^{\perp} \,.$$
(4.3)

Before we establish the proof of Theorem 4.2, we discuss three preparatory lemmas. In the first lemma we collect some integral identities for the magnetic field.

Lemma 4.5. Let $D \subseteq B_R(0)$ be open and of class C^0 , and let $q \in \mathcal{Y}_D$. Then,

$$\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s = \int_{B_R(0)} q \, \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}}} \, \mathrm{d}\boldsymbol{y} \qquad \text{for all } \boldsymbol{p} \in L^2_t(S^2, \mathbb{C}^3) \,, \tag{4.4}$$

and, for any $\boldsymbol{\psi} \in H(\mathbf{curl}; B_R(0))$,

$$\int_{B_R(0)} \left(\varepsilon_r^{-1} \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}^s \cdot \operatorname{curl} \boldsymbol{\psi} - k^2 \boldsymbol{H}_{q,\boldsymbol{p}}^s \cdot \boldsymbol{\psi} \right) \, \mathrm{d}\boldsymbol{x} + \int_{\partial B_R(0)} \left(\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}^s \right) \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{s}$$
$$= \int_{B_R(0)} q \, \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \operatorname{curl} \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} \,. \tag{4.5}$$

Moreover, if $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$ for some $D_1, D_2 \subseteq B_R(0)$ that are open and of class C^0 , then

$$\int_{\partial B_R(0)} \left(\boldsymbol{H}_{q_j,\boldsymbol{p}}^s \cdot \left(\boldsymbol{\nu} \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_l,\boldsymbol{p}}^s} \right) - \overline{\boldsymbol{H}_{q_l,\boldsymbol{p}}^s} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_j,\boldsymbol{p}}^s \right) \right) \, \mathrm{d}s \,=\, \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_j} \boldsymbol{p} \cdot \overline{F_{q_l} \boldsymbol{p}} \, \mathrm{d}s \quad (4.6)$$

for any $j, l \in \{1, 2\}$.

Proof. Let $\boldsymbol{p} \in L^2_t(S^2, \mathbb{C}^3)$. Then the scattered field $\boldsymbol{H}^s_{q, \boldsymbol{p}} \in H_{\text{loc}}(\operatorname{\mathbf{curl}}; \mathbb{R}^3)$ satisfies

 $\operatorname{curl}(\varepsilon_r^{-1}\operatorname{curl}\boldsymbol{H}_{q,\boldsymbol{p}}^s) - k^2\boldsymbol{H}_{q,\boldsymbol{p}}^s = -\operatorname{curl}(\varepsilon_r^{-1}\operatorname{curl}\boldsymbol{H}_{\boldsymbol{p}}^i) + k^2\boldsymbol{H}_{\boldsymbol{p}}^i = \operatorname{curl}(q \operatorname{curl}\boldsymbol{H}_{\boldsymbol{p}}^i) \quad (4.7)$

in \mathbb{R}^3 . Multiplying (4.7) by $\psi \in H(\mathbf{curl}; B_R(0))$ and integrating by parts using (2.2) yields

$$\int_{B_{R}(0)} \varepsilon_{r}^{-1} \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}^{s} \cdot \operatorname{curl} \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} = \int_{B_{R}(0)} q \, \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^{i} \cdot \operatorname{curl} \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} + k^{2} \int_{B_{R}(0)} \boldsymbol{H}_{q,\boldsymbol{p}}^{s} \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} - \int_{\partial B_{R}(0)} (\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}^{s}) \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{s} \,.$$
(4.8)

This implies (4.5).

Likewise,

$$\int_{B_{R}(0)} \varepsilon_{r}^{-1} \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^{i} \cdot \operatorname{curl} \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} = -\int_{B_{R}(0)} q \, \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^{i} \cdot \operatorname{curl} \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} + k^{2} \int_{B_{R}(0)} \boldsymbol{H}_{\boldsymbol{p}}^{i} \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} - \int_{\partial B_{R}(0)} (\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^{i}) \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{s} \quad (4.9)$$

for any $\boldsymbol{\psi} \in H(\operatorname{curl}; B_R(0))$. Subtracting (4.9) with $\boldsymbol{\psi} = \overline{\boldsymbol{H}_{q,\boldsymbol{p}}^s}$ from the complex conjugate of (4.8) with $\boldsymbol{\psi} = \overline{\boldsymbol{H}_{\boldsymbol{p}}^i}$ shows that

$$0 = \int_{B_R(0)} q \,\overline{\operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}} \cdot \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^i \, \mathrm{d}\boldsymbol{x} \\ - \int_{\partial B_R(0)} \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}}^s} \right) \cdot \boldsymbol{H}_{\boldsymbol{p}}^i - \left(\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^i \right) \cdot \overline{\boldsymbol{H}_{q,\boldsymbol{p}}^s} \right) \, \mathrm{d}s \, .$$

On the other hand, we obtain using (3.10) and (3.7) that

$$\begin{split} &\int_{\partial B_R(0)} \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{curl} \boldsymbol{H}_{q, \boldsymbol{p}}^s} \right) \cdot \boldsymbol{H}_{\boldsymbol{p}}^i - \left(\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}}^i \right) \cdot \overline{\boldsymbol{H}_{q, \boldsymbol{p}}^s} \right) \, \mathrm{d}s \\ &= \int_{S^2} \boldsymbol{p}(\boldsymbol{\theta}) \cdot \int_{\partial B_R(0)} \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{curl} \boldsymbol{H}_{q, \boldsymbol{p}}^s} \right)(\boldsymbol{x}) + \mathrm{i}k \left(\left(\boldsymbol{\nu} \times \overline{\boldsymbol{H}_{q, \boldsymbol{p}}^s} \right)(\boldsymbol{x}) \times \boldsymbol{\theta} \right) \right) e^{\mathrm{i}k\boldsymbol{\theta} \cdot \boldsymbol{x}} \, \mathrm{d}s(\boldsymbol{x}) \, \mathrm{d}s(\boldsymbol{\theta}) \\ &= \int_{S^2} \boldsymbol{p}(\boldsymbol{\theta}) \cdot \overline{\boldsymbol{H}_{q, \boldsymbol{p}}^\infty(\boldsymbol{\theta})} \, \mathrm{d}s(\boldsymbol{\theta}) = \int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s \, . \end{split}$$

This shows (4.4).

Now let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$ for some $D_1, D_2 \subseteq B_R(0)$ that are open and of class C^0 , and let r > R. Then, $H^s_{q_j, p}, H^s_{q_l, p} \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ fulfill

$$\operatorname{curl}\operatorname{curl}\boldsymbol{H}_{q,\boldsymbol{p}}^{s} - k^{2}\boldsymbol{H}_{q,\boldsymbol{p}}^{s} = 0 \quad \text{in } B_{r}(0) \setminus \overline{B_{R}(0)}$$

for $q \in \{q_j, q_l\}$. Thus, Green's formula gives

$$\int_{\partial B_{R}(0)} \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{l},\boldsymbol{p}}^{s}} \right) \cdot \boldsymbol{H}_{q_{j},\boldsymbol{p}}^{s} - \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{j},\boldsymbol{p}}^{s} \right) \cdot \overline{\boldsymbol{H}_{q_{l},\boldsymbol{p}}^{s}} \right) \, \mathrm{d}s$$

$$= \int_{\partial B_{r}(0)} \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{l},\boldsymbol{p}}^{s}} \right) \cdot \boldsymbol{H}_{q_{j},\boldsymbol{p}}^{s} - \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{j},\boldsymbol{p}}^{s} \right) \cdot \overline{\boldsymbol{H}_{q_{l},\boldsymbol{p}}^{s}} \right) \, \mathrm{d}s \, . \quad (4.10)$$

Applying the Silver-Müller radiation condition (3.5d) and inserting the far field expansion (3.6) we obtain that

$$\begin{split} \int_{\partial B_r(0)} & \left(\left(\boldsymbol{\nu} \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_l, \boldsymbol{p}}^s} \right) \cdot \boldsymbol{H}_{q_j, \boldsymbol{p}}^s - \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_j, \boldsymbol{p}}^s \right) \cdot \overline{\boldsymbol{H}_{q_l, \boldsymbol{p}}^s} \right) \mathrm{d}s \\ &= 2\mathrm{i}k \int_{\partial B_r(0)} \boldsymbol{H}_{q_j, \boldsymbol{p}}^s \cdot \overline{\boldsymbol{H}_{q_l, \boldsymbol{p}}^s} \, \mathrm{d}s + o(1) = \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_j} \boldsymbol{p} \cdot \overline{F_{q_l} \boldsymbol{p}} \, \mathrm{d}s + o(1) \end{split}$$

as $r \to \infty$. Together with (4.10) this shows (4.6).

In the next lemma we establish an integral identity for the left hand side of (4.1) (see also Remark 4.7 below).

Lemma 4.6. Let $D_1, D_2 \subseteq B_R(0)$ be open and of class C^0 , and let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$. Then,

$$\int_{S^{2}} \left(\boldsymbol{p} \cdot \overline{F_{q_{2}}\boldsymbol{p}} - \overline{\boldsymbol{p}} \cdot F_{q_{1}}\boldsymbol{p} \right) \, \mathrm{d}s + \frac{\mathrm{i}k}{8\pi^{2}} \int_{S^{2}} F_{q_{1}}\boldsymbol{p} \cdot \overline{F_{q_{2}}\boldsymbol{p}} \, \mathrm{d}s + \int_{B_{R}(0)} (q_{1} - q_{2}) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{1},\boldsymbol{p}}|^{2} \, \mathrm{d}\boldsymbol{x} \\
= \int_{B_{R}(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}} (\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s} - \boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s})|^{2} - k^{2} |\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s} - \boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s}|^{2} \right) \, \mathrm{d}\boldsymbol{x} \\
+ \int_{\partial B_{R}(0)} \overline{(\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s} - \boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s})} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} (\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s} - \boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s}) \right) \, \mathrm{d}\boldsymbol{s}$$
(4.11)

for any $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$.

Proof. Let $p \in L^2_t(S^2, \mathbb{C}^3)$. Using (4.6) with j = 1 and l = 2 we find that

$$2\operatorname{Re}\left(\int_{\partial B_{R}(0)}\overline{\boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s}}\cdot\left(\boldsymbol{\nu}\times\operatorname{\mathbf{curl}}\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s}\right)\,\mathrm{d}s\right)$$
$$=\int_{\partial B_{R}(0)}\left(\overline{\boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s}}\cdot\left(\boldsymbol{\nu}\times\operatorname{\mathbf{curl}}\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s}\right)+\overline{\boldsymbol{H}_{q_{2},\boldsymbol{p}}^{s}}\cdot\left(\boldsymbol{\nu}\times\operatorname{\mathbf{curl}}\boldsymbol{H}_{q_{1},\boldsymbol{p}}^{s}\right)\right)\,\mathrm{d}s+\frac{\mathrm{i}k}{8\pi^{2}}\int_{S^{2}}F_{q_{1}}\boldsymbol{p}\cdot\overline{F_{q_{2}}\boldsymbol{p}}\,\mathrm{d}s\,.$$

Therewith, we deduce that

$$\begin{split} &\int_{B_{R}(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(H_{q_{2},p}^{s} - H_{q_{1},p}^{s})|^{2} - k^{2} |H_{q_{2},p}^{s} - H_{q_{1},p}^{s}|^{2} \right) \,\mathrm{d}x \\ &+ \int_{\partial B_{R}(0)} \overline{(H_{q_{2},p}^{s} - H_{q_{1},p}^{s})} \cdot \left(\nu \times \operatorname{\mathbf{curl}}(H_{q_{2},p}^{s} - H_{q_{1},p}^{s}) \right) \,\mathrm{d}s \\ &= \int_{B_{R}(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}} H_{q_{2},p}^{s}|^{2} - k^{2} |H_{q_{2},p}^{s}|^{2} \right) \,\mathrm{d}x + \int_{B_{R}(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}} H_{q_{1},p}^{s}|^{2} - k^{2} |H_{q_{1},p}^{s}|^{2} \right) \,\mathrm{d}x \\ &- 2 \operatorname{Re} \left(\int_{B_{R}(0)} \left(\varepsilon_{r,2}^{-1} \operatorname{\mathbf{curl}} H_{q_{2},p}^{s} \cdot \overline{\operatorname{\mathbf{curl}}} H_{q_{1},p}^{s} - k^{2} H_{q_{2},p}^{s} \cdot \overline{H_{q_{1},p}^{s}} \right) \,\mathrm{d}x \\ &+ \int_{\partial B_{R}(0)} \overline{H_{q_{1},p}^{s}} \cdot \left(\nu \times \operatorname{\mathbf{curl}} H_{q_{2},p}^{s} \right) \,\mathrm{d}s \right) \\ &+ \int_{\partial B_{R}(0)} \left(\overline{H_{q_{2},p}^{s}} \cdot \left(\nu \times \operatorname{\mathbf{curl}} H_{q_{2},p}^{s} \right) + \overline{H_{q_{1},p}^{s}} \cdot \left(\nu \times \operatorname{\mathbf{curl}} H_{q_{1},p}^{s} \right) \right) \,\mathrm{d}s \\ &+ \frac{\mathrm{i}k}{8\pi^{2}} \int_{S^{2}} F_{q_{1}} \mathbf{p} \cdot \overline{F_{q_{2}} \mathbf{p}} \,\mathrm{d}s \,. \end{split}$$

Applying (4.5) gives

$$\begin{split} &\int_{B_R(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)|^2 - k^2 |\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \right) \,\mathrm{d}\boldsymbol{x} \\ &+ \int_{\partial B_R(0)} \overline{(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \right) \,\mathrm{d}\boldsymbol{s} \\ &= \int_{B_R(0)} q_2 \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_2,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x} + \int_{B_R(0)} q_1 \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x} \\ &+ \int_{B_R(0)} (q_1 - q_2) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \,\mathrm{d}\boldsymbol{x} - 2 \operatorname{Re} \Big(\int_{B_R(0)} q_2 \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x} \Big) \\ &+ \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_1} \boldsymbol{p} \cdot \overline{F_{q_2} \boldsymbol{p}} \,\mathrm{d}\boldsymbol{s} \,. \end{split}$$

Furthermore,

$$\begin{split} &\int_{B_R(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)|^2 - k^2 |\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \right) \,\mathrm{d}\boldsymbol{x} \\ &+ \int_{\partial B_R(0)} \overline{(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)\right) \,\mathrm{d}\boldsymbol{s} \\ &= \int_{B_R(0)} q_2 \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_2,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x} + 2 \operatorname{Re}\left(\int_{B_R(0)} (q_1 - q_2) \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x}\right) \\ &- \int_{B_R(0)} q_1 \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s \,\mathrm{d}\boldsymbol{x} + \int_{B_R(0)} (q_1 - q_2) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \,\mathrm{d}\boldsymbol{x} \\ &+ \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_1} \boldsymbol{p} \cdot \overline{F_{q_2} \boldsymbol{p}} \,\mathrm{d}\boldsymbol{s} \\ &= \int_{B_R(0)} q_2 \operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{q_2,\boldsymbol{p}} \,\mathrm{d}\boldsymbol{x} - \int_{B_R(0)} q_1 \overline{\operatorname{\mathbf{curl}}} \boldsymbol{H}_{\boldsymbol{p}}^i \cdot \operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}} \,\mathrm{d}\boldsymbol{x} \\ &+ \int_{B_R(0)} (q_1 - q_2) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \,\mathrm{d}\boldsymbol{x} + \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_1} \boldsymbol{p} \cdot \overline{F_{q_2} \boldsymbol{p}} \,\mathrm{d}\boldsymbol{s} . \end{split}$$

Finally, applying (4.4) gives

$$\begin{split} &\int_{B_R(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)|^2 - k^2 |\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \right) \, \mathrm{d}\boldsymbol{x} \\ &+ \int_{\partial B_R(0)} \overline{(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \right) \, \mathrm{d}\boldsymbol{s} \\ &= \int_{S^2} \left(\boldsymbol{p} \cdot \overline{F_{q_2}\boldsymbol{p}} - \overline{\boldsymbol{p}} \cdot F_{q_1}\boldsymbol{p} \right) \, \mathrm{d}\boldsymbol{s} + \int_{B_R(0)} (q_1 - q_2) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 d\boldsymbol{x} \\ &+ \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} F_{q_1}\boldsymbol{p} \cdot \overline{F_{q_2}\boldsymbol{p}} \, \mathrm{d}\boldsymbol{s} \, . \end{split}$$

Remark 4.7. Using (3.9) we find that

$$\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1}) = F_{q_2} - F_{q_1} - \frac{\mathrm{i}k}{8\pi^2} (F_{q_1}^*F_{q_2} - F_{q_1}^*F_{q_1}),$$

and thus,

$$\operatorname{Re}\left(\mathcal{S}_{q_{1}}^{*}(F_{q_{2}}-F_{q_{1}})\right) = \operatorname{Re}\left(F_{q_{2}}-F_{q_{1}}-\frac{\mathrm{i}k}{8\pi^{2}}F_{q_{1}}^{*}F_{q_{2}}\right).$$

Accordingly, the real part of the first two integrals on the left hand side of (4.11) satisfies

$$\operatorname{Re}\left(\int_{S^{2}} \left(\boldsymbol{p} \cdot \overline{F_{q_{2}}\boldsymbol{p}} - \overline{\boldsymbol{p}} \cdot F_{q_{1}}\boldsymbol{p}\right) \,\mathrm{d}s + \frac{\mathrm{i}k}{8\pi^{2}} \int_{S^{2}} F_{q_{1}}\boldsymbol{p} \cdot \overline{F_{q_{2}}\boldsymbol{p}} \,\mathrm{d}s\right)$$
$$= \operatorname{Re}\left(\int_{S^{2}} \boldsymbol{p} \cdot \overline{\left(F_{q_{2}} - F_{q_{1}} - \frac{\mathrm{i}k}{8\pi^{2}}F_{q_{1}}^{*}F_{q_{2}}\right)\boldsymbol{p}} \,\mathrm{d}s\right) = \operatorname{Re}\left(\int_{S^{2}} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_{1}}^{*}(F_{q_{2}} - F_{q_{1}})\boldsymbol{p}} \,\mathrm{d}s\right). \quad (4.12)$$

Since F_{q_1} and F_{q_2} are compact, the operator $S_{q_1}^*(F_{q_2} - F_{q_1})$ is compact as well, and using (3.9) once more it is immediately seen that $S_{q_1}^*(F_{q_2} - F_{q_1})$ is normal.

Next we show that the right hand side of (4.11) is nonnegative if the density $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ belongs to the complement of a certain finite dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$. We consider the exterior Calderon operator $\Lambda : H^{-1/2}(\text{Div}; \partial B_R(0)) \to H^{-1/2}(\text{Curl}; \partial B_R(0))$, which maps boundary data $\psi \in H^{-1/2}(\text{Div}; \partial B_R(0))$ to the tangential trace $(\boldsymbol{\nu} \times \operatorname{curl} \boldsymbol{w}|_{\partial B_P(0)}) \times \boldsymbol{\nu}$ of the radiating solution $\boldsymbol{w} \in H(\operatorname{curl}; B_R(0))$ to the exterior boundary value problem

> $\operatorname{curl}\operatorname{curl} \boldsymbol{w} - k^2 \boldsymbol{w} = 0 \quad \operatorname{in} \mathbb{R}^3 \setminus \overline{B_R(0)},$ $\boldsymbol{\nu} \times \boldsymbol{w} = \boldsymbol{\psi} \quad \text{on } \partial B_R(0),$

(see, e.g., [42, pp. 248–250]). We note that this operator is invertible (see, e.g., [42, Lem. 9.20], and we define the space

$$\mathcal{X} := \left\{ \boldsymbol{u} \in H(\mathbf{curl}; B_R(0)) \mid \operatorname{div} \boldsymbol{u} = 0 \text{ in } B_R(0) \\ \operatorname{and} \boldsymbol{\nu} \cdot \boldsymbol{u}|_{\partial B_R(0)} = k^{-2} \operatorname{Curl}(\Lambda(\boldsymbol{\nu} \times \boldsymbol{u}|_{\partial B_R(0)})) \right\}$$

equipped with the norm $\|\cdot\|_{\mathcal{X}} := \|\cdot\|_{H(\operatorname{curl};B_R(0))}$. Then $(\mathcal{X}, \|\cdot\|_{\mathcal{X}})$ is a Hilbert space (see, e.g., [42, Lem. 10.3]) and the embedding operator $J: \mathcal{X} \to L^2(B_R(0), \mathbb{C}^3)$ is compact (see, e.g., [42, Lem. 10.4]).

From (3.5b) we see that $\operatorname{div}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) = 0$ in \mathbb{R}^3 and

$$\begin{split} \boldsymbol{\nu} \cdot (\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \big|_{\partial B_R(0)} &= k^{-2} \boldsymbol{\nu} \cdot \mathbf{curl} \mathbf{curl} (\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \big|_{\partial B_R(0)} \\ &= k^{-2} \operatorname{Curl} (\left(\boldsymbol{\nu} \times \mathbf{curl} (\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \big|_{\partial B_R(0)} \right) \times \boldsymbol{\nu}) \\ &= k^{-2} \operatorname{Curl} (\Lambda (\boldsymbol{\nu} \times (\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \big|_{\partial B_R(0)})) . \end{split}$$

This shows that $\mathbf{H}_{q_2,\mathbf{p}}^s - \mathbf{H}_{q_1,\mathbf{p}}^s \in \mathcal{X}$. Using the Lax-Milgram lemma, we define for any $q = 1 - \varepsilon_r^{-1} \in \mathcal{Y}_D$ with $D \subset B_R(0)$ open and bounded of class C^0 a bounded linear self-adjoint operator $I_q: \mathcal{X} \to \mathcal{X}$ with bounded inverse by

$$\langle I_q \boldsymbol{u}, \boldsymbol{v} \rangle_{H(\operatorname{\mathbf{curl}}; B_R(0))} = \int_{B_R(0)} \varepsilon_r^{-1} \big(\overline{\operatorname{\mathbf{curl}} \boldsymbol{u}} \cdot \operatorname{\mathbf{curl}} \boldsymbol{v} + \overline{\boldsymbol{u}} \cdot \boldsymbol{v} \big) \, \mathrm{d} \boldsymbol{x} \quad \text{ for all } \boldsymbol{u}, \boldsymbol{v} \in \mathcal{X} \,.$$

Furthermore, let $K : \mathcal{X} \to \mathcal{X}$ and $K_q : \mathcal{X} \to \mathcal{X}$ be given by

$$Koldsymbol{u} \,:=\, J^*Joldsymbol{u} \qquad ext{and} \qquad K_qoldsymbol{v} \,:=\, J^*ig(arepsilon_r^{-1}Joldsymbol{v}ig)\,,$$

respectively. Then K and K_q are compact self-adjoint linear operators, and for any $v \in \mathcal{X}$,

$$\langle (I_q - K_q - k^2 K) \boldsymbol{v}, \boldsymbol{v} \rangle_{\mathcal{X}} = \int_{B_R(0)} \left(\varepsilon_r^{-1} |\operatorname{\mathbf{curl}} \boldsymbol{v}|^2 - k^2 |\boldsymbol{v}|^2 \right) \, \mathrm{d} \boldsymbol{x}$$

For $0 < \varepsilon < R$ we denote by $N_{\varepsilon} : \mathcal{X} \to H^{-1/2}(\operatorname{Curl}; \partial B_R(0))$ the compact linear operator that maps $\boldsymbol{v} \in \mathcal{X}$ to the tangential trace $(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{v}_{\varepsilon}|_{\partial B_R(0)}) \times \boldsymbol{\nu}$ of the radiating solution to the exterior boundary value problem

$$\operatorname{curl}\operatorname{curl} \boldsymbol{v}_{\varepsilon} - k^{2}\boldsymbol{v}_{\varepsilon} = 0 \quad \text{in } \mathbb{R}^{3} \setminus \overline{B_{R-\varepsilon}(0)}, \qquad \boldsymbol{\nu} \times \boldsymbol{v}_{\varepsilon} = \boldsymbol{\nu} \times \boldsymbol{v} \quad \text{on } \partial B_{R-\varepsilon}(0).$$

Given any $v \in \mathcal{X}$ that can be extended to a radiating solution of Maxwell's equations

$$\operatorname{curl}\operatorname{curl} \boldsymbol{v} - k^2 \boldsymbol{v} = 0 \quad \text{in } \mathbb{R}^3 \setminus \overline{B_{R-\varepsilon}(0)},$$

we find that

$$N_{\varepsilon} \boldsymbol{v} = \left(\boldsymbol{\nu} imes \operatorname{\mathbf{curl}} \boldsymbol{v} |_{\partial B_R(0)}
ight) imes \boldsymbol{\nu} \qquad ext{and} \qquad \Lambda^{-1} N_{\varepsilon} \boldsymbol{v} = \left. \boldsymbol{\nu} imes \boldsymbol{v} |_{\partial B_R(0)}
ight.$$

Accordingly,

$$\langle N_{\varepsilon}^* \Lambda^{-1} N_{\varepsilon} \boldsymbol{v}, \boldsymbol{v} \rangle_{\mathcal{X}} = \langle \Lambda^{-1} N_{\varepsilon} \boldsymbol{v}, N_{\varepsilon} \boldsymbol{v} \rangle_{L^2(\partial B_R(0), \mathbb{C}^3)} = - \int_{\partial B_R(0)} (\boldsymbol{\nu} \times \operatorname{\mathbf{curl}} \boldsymbol{v}) \cdot \overline{\boldsymbol{v}} \, \mathrm{d}s,$$

and in particular this holds for $\boldsymbol{v} = \boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s$ if the ball $B_{R-\varepsilon}(0)$ contains $\overline{D_1} \cup \overline{D_2}$.

Lemma 4.8. Let $D_1, D_2 \subset B_R(0)$ be open and of class C^0 , and let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$. Then there exists a finite dimensional subspace $V \subset L^2_t(S^2, \mathbb{C}^3)$ such that

$$\begin{split} &\int_{B_R(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)|^2 - k^2 |\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \right) \,\mathrm{d}\boldsymbol{x} \\ &+ \operatorname{Re} \left(\int_{\partial B_R(0)} \overline{(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)} \cdot \left(\boldsymbol{\nu} \times \operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \right) \times \boldsymbol{\nu} \,\mathrm{d}s \right) \geq 0 \quad \text{for all } \boldsymbol{p} \in V^{\perp} \,. \end{split}$$

Proof. Let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$ for some $D_1, D_2 \subset B_R(0)$ that are open and of class C^0 , and let $\varepsilon > 0$ be sufficiently small, so that $\overline{D_1} \cup \overline{D_2} \subset B_{R-\varepsilon}(0)$. Then

$$\begin{split} \int_{B_R(0)} \left(\varepsilon_{r,2}^{-1} |\operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)|^2 - k^2 |\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s|^2 \right) \, \mathrm{d}\boldsymbol{x} \\ &+ \operatorname{Re} \left(\int_{\partial B_R(0)} \overline{(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s)} \cdot (\boldsymbol{\nu} \times \operatorname{\mathbf{curl}}(\boldsymbol{H}_{q_2,\boldsymbol{p}}^s - \boldsymbol{H}_{q_1,\boldsymbol{p}}^s) \, \mathrm{d}\boldsymbol{s} \right) \\ &= \left\langle \left(I_{q_2} - K_{q_2} - k^2 K - \operatorname{Re}(N_{\varepsilon}^* \Lambda^{-1} N_{\varepsilon}) \right) (A_2 - A_1) \boldsymbol{p}, (A_2 - A_1) \boldsymbol{p} \right\rangle_{\mathcal{X}}, \end{split}$$

where, for j = 1, 2 we denote by $A_j : L^2_t(S^2, \mathbb{C}^3) \to \mathcal{X}$ the bounded linear operator that maps densities $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ to the restriction of the corresponding scattered magnetic field $\mathbf{H}^s_{q_j, \mathbf{p}}$ to $B_R(0)$.

We denote by W the sum of eigenspaces of the compact self-adjoint operator $K_{q_2} + k^2 K + \text{Re}(N_{\varepsilon}^* \Lambda^{-1} N_{\varepsilon})$ associated to eigenvalues larger than

$$c_{\min} := \operatorname*{ess inf}_{x \in B_R(0)} \varepsilon_{r,2}^{-1}(x) > 0.$$

The subspace W is finite dimensional and

$$\left\langle \left(I_{q_2} - K_{q_2} - k^2 K - \operatorname{Re}(N_{\varepsilon}^* \Lambda^{-1} N_{\varepsilon}) \right) \boldsymbol{w}, \boldsymbol{w} \right\rangle_{\mathcal{X}} \ge 0 \quad \text{for all } \boldsymbol{w} \in W^{\perp}$$

We observe that, for any $\boldsymbol{p} \in L^2_t(S^2, \mathbb{C}^3)$,

$$(A_2 - A_1)\boldsymbol{p} \in W^{\perp}$$
 if and only if $\boldsymbol{p} \in \left((A_2 - A_1)^*W\right)^{\perp}$.

Since dim $((A_2 - A_1)^*W) \le \dim(W) < \infty$, choosing $V := (A_2 - A_1)^*W$ ends the proof. \Box

Proof of Theorem 4.2. We take the real part of (4.11) and use (4.12). Then Lemma 4.8 yields the result.

5 Localized vector wave functions

We establish the existence of *localized vector wave functions*, which are solutions to (3.5) that have arbitrarily large energy on some prescribed region and arbitrarily small energy on another prescribed region. This extends related results for solutions to Maxwell's equations on bounded domains from [25]. The localized vector wave functions will be used to justify the shape characterizations for sign definite scattering objects in Section 6 below.

Theorem 5.1. Suppose that $D \subseteq \mathbb{R}^3$ is open and bounded of class C^0 , let $q \in \mathcal{Y}_D$, and let $B, \Omega \subseteq \mathbb{R}^3$ be open and bounded such that $\mathbb{R}^3 \setminus \overline{\Omega}$ is connected.

If $B \not\subseteq \Omega$, then for any finite dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ there exists a sequence $(\mathbf{p}_m)_{m \in \mathbb{N}} \subseteq V^{\perp}$ such that

$$\int_{B} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \quad and \quad \int_{\Omega} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to 0 \quad as \ m \to \infty,$$
(5.1)

where $H_{q,p_m} \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ is given by (3.11) with $p = p_m$.

The proof of Theorem 5.1 combines the following three lemmas.

Lemma 5.2. Suppose that $D \subseteq \mathbb{R}^3$ is open and of class C^0 , let $q \in \mathcal{Y}_D$, and assume that $\Omega \subseteq \mathbb{R}^3$ is open and bounded. We define

$$L_{q,\Omega}: L_t^2(S^2, \mathbb{C}^3) \to L^2(\Omega, \mathbb{C}^3), \quad L_{q,\Omega} \, \boldsymbol{p} := \operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}}|_{\Omega} = -\mathrm{i}\omega\varepsilon \boldsymbol{E}_{q,\boldsymbol{p}}|_{\Omega}.$$
 (5.2)

Then, $L_{q,\Omega}$ is a compact linear operator and its adjoint is given by

$$L_{q,\Omega}^*: L^2(\Omega, \mathbb{C}^3) o L_t^2(S^2, \mathbb{C}^3) , \quad L_{q,\Omega}^* \boldsymbol{f} := \sqrt{rac{\mu_0}{arepsilon_0}} \mathcal{S}_q^*(\boldsymbol{
u} imes \boldsymbol{e}^\infty) ,$$

where $e^{\infty} \in L^2_t(S^2, \mathbb{C}^3)$ is the far field pattern of the radiating solution $e \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ to

$$\operatorname{curl}\operatorname{curl}\boldsymbol{e} - k^2 \varepsilon_r \boldsymbol{e} = \mathrm{i}\omega \varepsilon \boldsymbol{f} \qquad in \ \mathbb{R}^3 \,. \tag{5.3}$$

Proof. The integral representation (3.11) shows that $L_{q,\Omega}$ is a Fredholm integral operator with square integrable kernel, which implies the compactness (see, e.g., [10, p. 354]).

The existence of a unique radiating solution $e \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ to (5.3) follows again by combining the uniqueness result from [4] with Riesz–Fredholm theory (see, e.g., [36, pp. 113–118] or [42, pp. 262–272]). Let R > 0 sufficiently large such that $\overline{D} \cup \overline{\Omega} \subseteq B_R(0)$. Multiplying (5.3) by $\psi \in H(\text{curl}; B_R(0))$ and integrating by parts shows that

$$\int_{B_R(0)} \left(\operatorname{\mathbf{curl}} \boldsymbol{e} \cdot \operatorname{\mathbf{curl}} \boldsymbol{\psi} - k^2 \varepsilon_r \boldsymbol{e} \cdot \boldsymbol{\psi} \right) \, \mathrm{d}\boldsymbol{x} \\ = \int_{B_R(0)} \mathrm{i}\omega \varepsilon \boldsymbol{f} \cdot \boldsymbol{\psi} \, \mathrm{d}\boldsymbol{x} + \int_{\partial B_R(0)} (\boldsymbol{\nu} \times \boldsymbol{\psi}) \cdot \operatorname{\mathbf{curl}} \boldsymbol{e} \, \mathrm{d}s \,.$$
(5.4)

Combining (5.2), the complex conjugate of (5.4), and integrating by parts we obtain from (3.5) that, for any $\mathbf{f} \in L^2(\Omega, \mathbb{C}^3)$ and $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$,

$$\int_{\Omega} (L_{q,\Omega} \boldsymbol{p}) \cdot \overline{\boldsymbol{f}} \, \mathrm{d}\boldsymbol{x} = -\int_{B_{R}(0)} \mathrm{i}\omega\varepsilon \boldsymbol{E}_{q,\boldsymbol{p}} \cdot \overline{\boldsymbol{f}} \, \mathrm{d}\boldsymbol{x} \\
= \int_{B_{R}(0)} \left(\mathrm{curl} \, \boldsymbol{E}_{q,\boldsymbol{p}} \cdot \overline{\mathrm{curl} \, \boldsymbol{e}} - k^{2}\varepsilon_{r} \boldsymbol{E}_{q,\boldsymbol{p}} \cdot \overline{\boldsymbol{e}} \right) \, \mathrm{d}\boldsymbol{x} - \int_{\partial B_{R}(0)} (\boldsymbol{\nu} \times \boldsymbol{E}_{q,\boldsymbol{p}}) \cdot \overline{\mathrm{curl} \, \boldsymbol{e}} \, \mathrm{d}\boldsymbol{s} \\
= \int_{\partial B_{R}(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \mathrm{curl} \, \boldsymbol{E}_{\boldsymbol{p}}^{i} - (\boldsymbol{\nu} \times \boldsymbol{E}_{\boldsymbol{p}}^{i}) \cdot \overline{\mathrm{curl} \, \boldsymbol{e}} \right) \, \mathrm{d}\boldsymbol{s} \\
+ \int_{\partial B_{R}(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \mathrm{curl} \, \boldsymbol{E}_{q,\boldsymbol{p}}^{s} - (\boldsymbol{\nu} \times \boldsymbol{E}_{q,\boldsymbol{p}}^{s}) \cdot \overline{\mathrm{curl} \, \boldsymbol{e}} \right) \, \mathrm{d}\boldsymbol{s} \, .$$
(5.5)

We discuss the two integrals on the right hand side of (5.5) separately. Using (3.10) we find for the first integral that

r

$$\begin{split} \int_{\partial B_R(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \operatorname{\mathbf{curl}} \boldsymbol{E}_{\boldsymbol{p}}^i - (\boldsymbol{\nu} \times \boldsymbol{E}_{\boldsymbol{p}}^i) \cdot \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}} \right) \, \mathrm{d}s \\ &= \int_{\partial B_R(0)} \left(\left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\boldsymbol{e}(\boldsymbol{x})} \right) \cdot \left(\mathrm{i}\omega\mu_0 \int_{S^2} \boldsymbol{p}(\boldsymbol{\theta}) e^{\mathrm{i}k\boldsymbol{x}\cdot\boldsymbol{\theta}} \, \mathrm{d}s(\boldsymbol{\theta}) \right) \\ &- \left(\sqrt{\frac{\mu_0}{\varepsilon_0}} \int_{S^2} (\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta})) e^{\mathrm{i}k\boldsymbol{x}\cdot\boldsymbol{\theta}} \, \mathrm{d}s(\boldsymbol{\theta}) \right) \cdot \left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}(\boldsymbol{x})} \right) \right) \, \mathrm{d}s(\boldsymbol{x}) \\ &= \int_{S^2} \boldsymbol{p}(\boldsymbol{\theta}) \cdot \int_{\partial B_R(0)} \left(\mathrm{i}\omega\mu_0 \left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\boldsymbol{e}(\boldsymbol{x})} \right) - \sqrt{\frac{\mu_0}{\varepsilon_0}} \left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}(\boldsymbol{x})} \right) \times \boldsymbol{\theta} \right) e^{\mathrm{i}k\boldsymbol{x}\cdot\boldsymbol{\theta}} \, \, \mathrm{d}s(\boldsymbol{\theta}) \, . \end{split}$$

On the other hand, the representation formula for the far field pattern e^{∞} of e analogous to (3.7) gives

$$\begin{split} \sqrt{\frac{\mu_0}{\varepsilon_0}} \boldsymbol{\theta} \times \overline{\boldsymbol{e}^{\infty}(\boldsymbol{\theta})} &= \int_{\partial B_R(0)} \left(\left(\boldsymbol{\theta} \times \left(\mathrm{i} \omega \mu_0 \left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\boldsymbol{e}(\boldsymbol{x})} \right) \right) \right) \times \boldsymbol{\theta} \\ &- \sqrt{\frac{\mu_0}{\varepsilon_0}} \left(\boldsymbol{\nu}(\boldsymbol{x}) \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}(\boldsymbol{x})} \right) \times \boldsymbol{\theta} \right) e^{\mathrm{i} k \boldsymbol{x} \cdot \boldsymbol{\theta}} \, \mathrm{d} \boldsymbol{s}(\boldsymbol{x}) \end{split}$$

for $\boldsymbol{\theta} \in S^2$, and thus

$$\int_{\partial B_R(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \operatorname{\mathbf{curl}} \boldsymbol{E}_{\boldsymbol{p}}^i - (\boldsymbol{\nu} \times \boldsymbol{E}_{\boldsymbol{p}}^i) \cdot \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}} \right) \, \mathrm{d}s = \sqrt{\frac{\mu_0}{\varepsilon_0}} \int_{S^2} \boldsymbol{p}(\boldsymbol{\theta}) \cdot \left(\boldsymbol{\theta} \times \overline{\boldsymbol{e}^{\infty}(\boldsymbol{\theta})}\right) \, \mathrm{d}s(\boldsymbol{\theta}) \,. \tag{5.6}$$

Next, we consider the second integral on the right hand side of (5.5) and apply the radiation condition (3.5d) as well as the far field expansion (3.6). This gives, as $R \to \infty$,

$$\begin{split} &\int_{\partial B_R(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \operatorname{\mathbf{curl}} \boldsymbol{E}_{q,\boldsymbol{p}}^s - (\boldsymbol{\nu} \times \boldsymbol{E}_{q,\boldsymbol{p}}^s) \cdot \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}} \right) \, \mathrm{d}s \\ &= \int_{S^2} \int_{\partial B_R(0)} \left(-\left(\frac{\boldsymbol{x}}{|\boldsymbol{x}|} \times \operatorname{\mathbf{curl}} \boldsymbol{E}_q^s(\boldsymbol{x}; \boldsymbol{\theta}, \boldsymbol{p}) \right) \cdot \overline{\boldsymbol{e}(\boldsymbol{x})} \\ &\quad + \boldsymbol{E}_q^s(\boldsymbol{x}; \boldsymbol{\theta}, \boldsymbol{p}) \cdot \left(\frac{\boldsymbol{x}}{|\boldsymbol{x}|} \times \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}(\boldsymbol{x})} \right) \right) \, \mathrm{d}s(\boldsymbol{x}) \, \mathrm{d}s(\boldsymbol{\theta}) \\ &= 2\mathrm{i}k \int_{S^2} \int_{\partial B_R(0)} \boldsymbol{E}_q^s(\boldsymbol{x}; \boldsymbol{\theta}, \boldsymbol{p}) \cdot \overline{\boldsymbol{e}(\boldsymbol{x})} \, \mathrm{d}s(\boldsymbol{x}) \, \mathrm{d}s(\boldsymbol{\theta}) + o(1) \\ &= \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} \int_{S^2} \boldsymbol{E}_q^\infty(\widehat{\boldsymbol{x}}; \boldsymbol{\theta}, \boldsymbol{p}) \cdot \overline{\boldsymbol{e}^\infty(\widehat{\boldsymbol{x}})} \, \mathrm{d}s(\widehat{\boldsymbol{x}}) \, \mathrm{d}s(\boldsymbol{\theta}) + o(1) \, . \end{split}$$

Recalling that $H^{\infty}_{q}(\widehat{x}) = \sqrt{\frac{\varepsilon_{0}}{\mu_{0}}} \, \widehat{x} \times E^{\infty}_{q}(\widehat{x})$ for all $\widehat{x} \in S^{2}$, we obtain

$$\int_{S^2} \int_{S^2} E_q^{\infty}(\widehat{\boldsymbol{x}}; \boldsymbol{\theta}, \boldsymbol{p}) \cdot \overline{\boldsymbol{e}^{\infty}(\widehat{\boldsymbol{x}})} \, \mathrm{d}s(\widehat{\boldsymbol{x}}) \, \mathrm{d}s(\boldsymbol{\theta}) = \sqrt{\frac{\mu_0}{\varepsilon_0}} \int_{S^2} (F_q \boldsymbol{p})(\widehat{\boldsymbol{x}}) \cdot \left(\widehat{\boldsymbol{x}} \times \overline{\boldsymbol{e}^{\infty}(\widehat{\boldsymbol{x}})}\right) \, \mathrm{d}s(\widehat{\boldsymbol{x}}) \, ,$$

and the second integral on the right hand side of (5.5) becomes

$$\int_{\partial B_R(0)} \left((\boldsymbol{\nu} \times \overline{\boldsymbol{e}}) \cdot \operatorname{\mathbf{curl}} \boldsymbol{E}_{q,\boldsymbol{p}}^s - (\boldsymbol{\nu} \times \boldsymbol{E}_{q,\boldsymbol{p}}^s) \cdot \overline{\operatorname{\mathbf{curl}} \boldsymbol{e}} \right) \, \mathrm{d}s$$
$$= \sqrt{\frac{\mu_0}{\varepsilon_0}} \frac{\mathrm{i}k}{8\pi^2} \int_{S^2} \boldsymbol{p}(\widehat{\boldsymbol{x}}) \cdot \overline{F_q^*(\widehat{\boldsymbol{x}} \times \boldsymbol{e}^\infty(\widehat{\boldsymbol{x}}))} \, \mathrm{d}s(\widehat{\boldsymbol{x}}) + o(1) \, . \quad (5.7)$$

Combining (5.5), (5.6), (5.7), and (3.9) we finally obtain that

$$\int_{D} (L_{q,\Omega} \boldsymbol{p}) \cdot \boldsymbol{\overline{f}} \, \mathrm{d}\boldsymbol{x} = \sqrt{\frac{\mu_0}{\varepsilon_0}} \int_{S^2} \boldsymbol{p}(\boldsymbol{\widehat{x}}) \cdot \overline{\mathcal{S}_q^*(\boldsymbol{\widehat{x}} \times \boldsymbol{e}^\infty(\boldsymbol{\widehat{x}}))} \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\widehat{x}}) \,.$$

Lemma 5.3. Suppose that $D \subseteq \mathbb{R}^3$ is open and of class C^0 , and let $q \in \mathcal{Y}_D$. Let $B, \Omega \subseteq \mathbb{R}^3$ be open and bounded such that $\mathbb{R}^3 \setminus (\overline{B} \cup \overline{\Omega})$ is connected and $\overline{B} \cap \overline{\Omega} = \emptyset$. Then,

$$\mathcal{R}(L_{q,B}^*) \cap \mathcal{R}(L_{q,\Omega}^*) = \{0\},\$$

and $\mathcal{R}(L_{q,B}^*), \mathcal{R}(L_{q,\Omega}^*) \subseteq L_t^2(S^2, \mathbb{C}^3)$ are both dense.

Proof. We assume that $\phi \in \mathcal{R}(L_{q,B}^*) \cap \mathcal{R}(L_{q,\Omega}^*)$. Then, we know from Lemma 5.2 that there exist sources $f_B \in L^2(B, \mathbb{C}^3)$ and $f_\Omega \in L^2(\Omega, \mathbb{C}^3)$ such that

$$oldsymbol{\phi} \,=\, \sqrt{rac{\mu_0}{arepsilon_0}} \mathcal{S}_q^*(oldsymbol{
u} imes oldsymbol{e}_B^\infty) \,=\, \sqrt{rac{\mu_0}{arepsilon_0}} \mathcal{S}_q^*(oldsymbol{
u} imes oldsymbol{e}_\Omega^\infty)\,,$$

where $e_B, e_\Omega \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ are radiating solutions to

 $\operatorname{\mathbf{curl}\,\mathbf{curl}\,} \mathbf{e}_B - k^2 \varepsilon_r \mathbf{e}_B = \mathrm{i} \omega \varepsilon \mathbf{f}_B \quad \text{and} \quad \operatorname{\mathbf{curl}\,\mathbf{curl}\,} \mathbf{e}_\Omega - k^2 \varepsilon_r \mathbf{e}_\Omega = \mathrm{i} \omega \varepsilon \mathbf{f}_\Omega \qquad \text{in } \mathbb{R}^3.$

Since S_q is unitary, Rellich's lemma (see, e.g., [42, Cor. 9.29]) and the unique continuation principle (see [4]) imply that $e_B = e_{\Omega}$ in $\mathbb{R}^3 \setminus (\overline{B} \cup \overline{\Omega})$, and we may define $e \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ by

$$oldsymbol{e} := egin{cases} oldsymbol{e}_B = oldsymbol{e}_\Omega & ext{in } \mathbb{R}^3 \setminus (\overline{B} \cup \overline{\Omega}) \,, \ oldsymbol{e}_B & ext{in } \Omega \,, \ oldsymbol{e}_\Omega & ext{in } B \,. \end{cases}$$

Then e is a radiating solution to

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e} - k^2 \varepsilon_r \boldsymbol{e} = 0 \quad \text{in } \mathbb{R}^3.$$

The uniqueness result [4, Thm. 2] shows that e must vanish identically in \mathbb{R}^3 . In particular $e^{\infty} = 0$, and thus $\phi = 0$.

To show that $\mathcal{R}(L_{q,B}^*) \subseteq L_t^2(S^2, \mathbb{C}^3)$ is dense, we prove the injectivity of the operator $L_{q,B}$. Suppose that $L_{q,B}\mathbf{p} = -ik\varepsilon \mathbf{E}_{q,\mathbf{p}}|_B = 0$. Then $\mathbf{E}_{q,\mathbf{p}}|_B = 0$, and unique continuation (see [4]) implies that $\mathbf{E}_{q,\mathbf{p}} = 0$ in \mathbb{R}^3 . In particular, $\mathbf{E}_{\mathbf{p}}^i = \mathbf{E}_{q,\mathbf{p}}^s$ is an entire radiating solution to Maxwell's equations (3.5a), and therefore $\mathbf{E}_{\mathbf{p}}^i = \mathbf{H}_{\mathbf{p}}^i = 0$ in \mathbb{R}^3 . Thus, [10, Thm. 3.27] gives $\mathbf{p} = 0$. The denseness of $\mathcal{R}(L_{q,\Omega}^*) \subseteq L_t^2(S^2, \mathbb{C}^3)$ follows analogously.

In the next lemma we quote a special case of Lemma 2.5 in [29].

Lemma 5.4. Let X, Y and Z be Hilbert spaces, and let $A : X \to Y$ and $B : X \to Z$ be bounded linear operators. Then,

$$\exists C > 0: \|Ax\| \le C \|Bx\| \quad \forall x \in X \quad if and only if \quad \mathcal{R}(A^*) \subseteq \mathcal{R}(B^*).$$

Now we establish the proof of Theorem 5.1.

Proof of Theorem 5.1. Let $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ be a finite dimensional subspace. Without loss of generality we assume that $\overline{B} \cap \overline{\Omega} = \emptyset$ and that $\mathbb{R}^3 \setminus (\overline{B} \cup \overline{\Omega})$ is connected (otherwise we replace B by a sufficiently small ball $\widetilde{B} \subseteq B \setminus \Omega_\rho$, where Ω_ρ denotes a sufficiently small neighborhood of Ω). We introduce the orthogonal projection $P_V : L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3)$ onto V. From Lemma 5.3 we know that $\mathcal{R}(L^*_{q,B}) \subseteq L^2_t(S^2, \mathbb{C}^3)$ is dense and therefore $\mathcal{R}(L^*_{q,B})$ is infinite dimensional. Together with the fact that $\mathcal{R}(L^*_{q,B}) \cap \mathcal{R}(L^*_{q,\Omega}) = \{0\}$, a dimensionality argument (cf. [29, Lem. 4.7]) shows that

$$\mathcal{R}(L_{q,B}^*) \not\subseteq \mathcal{R}(L_{q,\Omega}^*) + V = \mathcal{R}\left(\left[L_{q,\Omega}^* \mid P_V^*\right]\right) = \mathcal{R}\left(\left[L_{q,\Omega}^* \mid P_V^*\right]\right).$$

From Lemma 5.4 it follows that there does not exist a constant C > 0 such that

$$\|L_{q,B}\boldsymbol{p}\|_{L^{2}(B)}^{2} \leq C^{2} \left\| \begin{bmatrix} L_{q,\Omega} \\ P_{V} \end{bmatrix} \boldsymbol{p} \right\|_{L^{2}(\Omega) \times L^{2}_{t}(S^{2})}^{2} = C^{2} \left(\|L_{q,\Omega}\boldsymbol{p}\|_{L^{2}(\Omega)}^{2} + \|P_{V}\boldsymbol{p}\|_{L^{2}_{t}(S^{2})}^{2} \right)$$

holds for all $p \in L^2_t(S^2, \mathbb{C}^3)$. This means that one can find a sequence $(\widetilde{p}_m)_{m \in \mathbb{N}} \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

 $\|L_{q,B}\widetilde{\boldsymbol{p}}_m\|_{L^2(B)}^2 \to \infty \quad \text{and} \quad \|L_{q,\Omega}\widetilde{\boldsymbol{p}}_m\|_{L^2(\Omega)}^2 + \|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2)}^2 \to 0$

as $m \to \infty$. Setting $\boldsymbol{p}_m := \widetilde{\boldsymbol{p}}_m - P_V \widetilde{\boldsymbol{p}}_m \in V^{\perp}$ for all $m \in \mathbb{N}$ yields

$$\begin{aligned} \|L_{q,B}\boldsymbol{p}_m\|_{L^2(B)} &\geq \|L_{q,B}\widetilde{\boldsymbol{p}}_m\|_{L_2(B)} - \|L_{q,B}\| \|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2)} \to \infty \qquad \text{as } m \to \infty \,, \\ \|L_{q,\Omega}\boldsymbol{p}_m\|_{L^2(\Omega)} &\leq \|L_{q,\Omega}\widetilde{\boldsymbol{p}}_m\|_{L^2(\Omega)} + \|L_{q,\Omega}\| \|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2)} \to 0 \qquad \text{as } m \to \infty \,. \end{aligned}$$

Recalling that $L_{q,B}\boldsymbol{p}_m = \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}_m}|_B$ and $L_{q,\Omega}\boldsymbol{p}_m = \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}_m}|_{\Omega}$, this ends the proof. \Box

Theorem 5.5. Suppose that $D_1, D_2 \subseteq \mathbb{R}^3$ are open and bounded of class C^0 , let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$, and assume that $\Omega \subseteq \mathbb{R}^3$ is open and bounded. If $q_1(x) = q_2(x)$ for a.e. $x \in \mathbb{R}^3 \setminus \overline{\Omega}$, then there exist constants c, C > 0 such that

$$c\int_{\Omega} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \leq \int_{\Omega} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_2, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \leq C\int_{\Omega} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x}$$

for all $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$.

Proof. Lemma 5.2 shows that, for any $f \in L^2(\Omega, \mathbb{C}^3)$,

$$L_{q_1,\Omega}^* \boldsymbol{f} = \sqrt{\frac{\mu_0}{\varepsilon_0}} \mathcal{S}_{q_1}^* (\boldsymbol{\nu} \times \boldsymbol{e}_1^\infty) \quad \text{and} \quad L_{q_2,\Omega}^* \boldsymbol{f} = \sqrt{\frac{\mu_0}{\varepsilon_0}} \mathcal{S}_{q_2}^* (\boldsymbol{\nu} \times \boldsymbol{e}_2^\infty), \quad (5.8)$$

where e_j^{∞} , j = 1, 2, are the far field patterns of radiating solutions to

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e}_j - k^2 \varepsilon_{r,j} \boldsymbol{e}_j = \mathrm{i}\omega \varepsilon \boldsymbol{f} \qquad \mathrm{in} \ \mathbb{R}^3 \,.$$

Moreover, we observe that

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e}_{1} - k^{2}\varepsilon_{r,2}\boldsymbol{e}_{1} = \mathrm{i}\omega\varepsilon_{2}\left(\frac{\varepsilon_{1}}{\varepsilon_{2}}\boldsymbol{f} - \frac{k^{2}}{\mathrm{i}\omega\varepsilon_{2}}(\varepsilon_{r,2} - \varepsilon_{r,1})\boldsymbol{e}_{1}\right) \quad \text{in } \mathbb{R}^{3},$$

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e}_{2} - k^{2}\varepsilon_{r,1}\boldsymbol{e}_{1} = \mathrm{i}\omega\varepsilon_{1}\left(\frac{\varepsilon_{2}}{\varepsilon_{1}}\boldsymbol{f} - \frac{k^{2}}{\mathrm{i}\omega\varepsilon_{1}}(\varepsilon_{r,1} - \varepsilon_{r,2})\boldsymbol{e}_{2}\right) \quad \text{in } \mathbb{R}^{3}.$$

Since by assumption $\varepsilon_{r,1} - \varepsilon_{r,2}$ vanishes a.e. outside of Ω , this implies that

$$\sqrt{\frac{\mu_0}{\varepsilon_0}} \mathcal{S}_{q_2}^*(\boldsymbol{\nu} \times \boldsymbol{e}_1^{\infty}) = L_{q_2,\Omega}^* \left(\frac{\varepsilon_1}{\varepsilon_2} \boldsymbol{f} + \mathrm{i} k^2 \frac{(\varepsilon_{r,2} - \varepsilon_{r,1})}{\omega \varepsilon_2} \boldsymbol{e}_1 \right),$$
(5.9a)

$$\sqrt{\frac{\mu_0}{\varepsilon_0}} \mathcal{S}_{q_1}^*(\boldsymbol{\nu} \times \boldsymbol{e}_2^\infty) = L_{q_1,\Omega}^* \left(\frac{\varepsilon_2}{\varepsilon_1} \boldsymbol{f} + ik^2 \frac{(\varepsilon_{r,1} - \varepsilon_{r,2})}{\omega \varepsilon_1} \boldsymbol{e}_2 \right).$$
(5.9b)

Combining (5.8) and (5.9), we obtain that $\mathcal{R}(\mathcal{S}_{q_1}L^*_{q_1,D}) = \mathcal{R}(\mathcal{S}_{q_2}L^*_{q_2,D})$. Since \mathcal{S}_{q_1} and \mathcal{S}_{q_2} are unitary operators, the assertion follows from Lemma 5.4.

Our first application of Theorem 5.1 is the following simple uniqueness result for the inverse scattering problem. This should be compared to (4.2) in Theorem 4.2.

Theorem 5.6. Suppose that $D_1, D_2 \subseteq \mathbb{R}^3$ are open and bounded of class C^0 , let $q_1 \in \mathcal{Y}_{D_1}$ and $q_2 \in \mathcal{Y}_{D_2}$. If $O \subseteq \mathbb{R}^3$ is an unbounded domain such that

$$q_1 \leq q_2 \qquad a.e. \text{ in } O, \tag{5.10}$$

and if $B \subseteq O$ is open with

$$q_1 \leq q_2 - c$$
 a.e. in B for some $c > 0$,

then

$$\operatorname{Re}(\mathcal{S}_{q_1}^*F_{q_1}) \not\geq_{\operatorname{fin}} \operatorname{Re}(\mathcal{S}_{q_1}^*F_{q_2}).$$

In particular, $F_{q_1} \neq F_{q_2}$.

Proof. Suppose that there is a finite dimensional subspace $V_1 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})\boldsymbol{p}} \, \mathrm{d}s\right) \leq 0 \quad \text{for all } \boldsymbol{p} \in V_1^{\perp}.$$

Then, Theorem 4.2 shows that there exists another finite dimensional subspace $V_2 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})\boldsymbol{p}} \, \mathrm{d}s\right) \geq \int_{\mathbb{R}^3} (q_2 - q_1) \, |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{ for all } \boldsymbol{p} \in V_2^{\perp}.$$

Defining $V := V_1 + V_2$, we obtain from (5.10) that, for any $\boldsymbol{p} \in V^{\perp}$,

$$0 \geq \operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})\boldsymbol{p}} \, \mathrm{d}s\right) \geq \int_{\mathbb{R}^3} (q_2 - q_1) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x}$$

$$= \int_O (q_2 - q_1) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} + \int_{\mathbb{R}^3 \setminus \overline{O}} (q_2 - q_1) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x}$$

$$\geq c \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} - \left(\|q_1\|_{L^{\infty}(\mathbb{R}^3)} + \|q_2\|_{L^{\infty}(\mathbb{R}^3)} \right) \int_{\mathbb{R}^3 \setminus \overline{O}} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_1,\boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x}.$$

However, this contradicts Theorem 5.1 with $D = D_1$, $q = q_1$, and $\Omega = \mathbb{R}^3 \setminus \overline{O}$, which guarantees the existence of $(\mathbf{p}_m)_{m \in \mathbb{N}} \subseteq V^{\perp}$ with

$$\int_{B} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{1},\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \quad \text{and} \quad \int_{\mathbb{R}^{3} \setminus \overline{O}} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q_{1},\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to 0 \quad \text{as } m \to \infty.$$

Thus, $\operatorname{Re}(\mathcal{S}_{q_1}^*(F_{q_2} - F_{q_1})) \not\leq_{\operatorname{fin}} 0.$

6 Shape reconstruction for sign definite scatterers

We discuss criteria to determine the shape of a scattering object D with permittivity contrast $q \in \mathcal{Y}_D$ from observations of the corresponding far field operator F_q . In this section we consider the special case when the contrast function q is either strictly positive or strictly negative a.e. on D. The general case will be treated in Section 8 below.

Let $B \subseteq \mathbb{R}^3$ be open and bounded. The Herglotz operator $H_B : L^2_t(S^2, \mathbb{C}^3) \to L^2(B, \mathbb{C}^3)$ is defined by

$$(H_B \boldsymbol{p})(\boldsymbol{y}) := \int_{S^2} \operatorname{curl}_{\boldsymbol{y}} \left(e^{\mathrm{i}k\boldsymbol{y}\cdot\boldsymbol{\theta}} \boldsymbol{p}(\boldsymbol{\theta}) \right) \, \mathrm{d}s(\boldsymbol{\theta}) = \mathrm{i}k \int_{S^2} e^{\mathrm{i}k\boldsymbol{y}\cdot\boldsymbol{\theta}} \left(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta}) \right) \, \mathrm{d}s(\boldsymbol{\theta}) \,, \qquad \boldsymbol{y} \in B \,.$$

Accordingly, the adjoint operator $H^*_B: L^2(B,\mathbb{C}^3) \to L^2_t(S^2,\mathbb{C}^3)$ satisfies

$$(H_B^* \boldsymbol{f})(\widehat{\boldsymbol{x}}) \,=\, \mathrm{i} k\, \widehat{\boldsymbol{x}} imes \int_B e^{-\mathrm{i} k \boldsymbol{y} \cdot \widehat{\boldsymbol{x}}} \boldsymbol{f}(\boldsymbol{y}) \,\,\mathrm{d} \boldsymbol{y}\,, \qquad \widehat{\boldsymbol{x}} \in S^2\,,$$

and

$$(H_B^*H_B\boldsymbol{p})(\widehat{\boldsymbol{x}}) = -k^2 \,\widehat{\boldsymbol{x}} \times \left(\int_{S^2} \left(\int_B e^{\mathrm{i}k\boldsymbol{y} \cdot (\boldsymbol{\theta} - \widehat{\boldsymbol{x}})} \,\mathrm{d}\boldsymbol{y} \right) \left(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta}) \right) \,\mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \right), \qquad \widehat{\boldsymbol{x}} \in S^2$$

In the following, we consider the probing operator $T_B: L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3)$ corresponding to the probing domain B, which is defined by

$$T_B \boldsymbol{p} := H_B^* H_B \boldsymbol{p} \,. \tag{6.1}$$

This operator is compact and self-adjoint, and for all $p \in L^2_t(S^2, \mathbb{C}^3)$ we have that

$$\int_{S^2} \boldsymbol{p} \cdot \overline{T_B \boldsymbol{p}} \, \mathrm{d}s = \int_B \left(\mathrm{i}k \int_{S^2} e^{\mathrm{i}k\boldsymbol{y}\cdot\boldsymbol{\hat{x}}} \left(\boldsymbol{\hat{x}} \times \boldsymbol{p}(\boldsymbol{\hat{x}}) \right) \, \mathrm{d}s(\boldsymbol{\hat{x}}) \right) \cdot \left(\overline{\mathrm{i}k \int_{S^2} e^{\mathrm{i}k\boldsymbol{y}\cdot\boldsymbol{\theta}} \left(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta}) \right) \, \mathrm{d}s(\boldsymbol{\theta})} \right) \, \mathrm{d}\boldsymbol{y}$$

$$= \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \,,$$
(6.2)

where H_{p}^{i} is the incident magnetic field from (3.10). This should be compared to (4.4).

The theorem below considers the case when the contrast function q is strictly positive a.e. on D.

Theorem 6.1. Let $D \subseteq \mathbb{R}^3$ be open and bounded of class C^0 such that $\mathbb{R}^3 \setminus \overline{D}$ is connected, and let $q \in \mathcal{Y}_D$. Suppose that $0 < q_{\min} \leq q \leq q_{\max} < 1$ for some constants $q_{\min}, q_{\max} \in \mathbb{R}$, and let $B \subseteq B_R(0)$ be open and bounded.

(a) If $B \subseteq D$, then

$$\alpha T_B \leq_{\text{fin}} \operatorname{Re}(F_q) \quad \text{for all } \alpha \leq q_{\min}.$$

(b) If $B \not\subseteq D$, then

$$\alpha T_B \not\leq_{\text{fin}} \operatorname{Re}(F_q) \quad for any \, \alpha > 0.$$

Proof. Let $B \subseteq D$ and $\alpha \leq q_{\min}$. Theorem 4.2 with $q_1 = 0$ and $q_2 = q$ guarantees the existence of a finite dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \geq \int_D q \, |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{for all } \boldsymbol{p} \in V^{\perp} \, .$$

Since $B \subseteq D$ and $q_{\min} \ge \alpha$, (6.2) yields

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \ge \alpha \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} = \alpha \int_{S^2} \boldsymbol{p} \cdot \overline{T_B \boldsymbol{p}} \, \mathrm{d}s \quad \text{for all } \boldsymbol{p} \in V^{\perp}.$$

Now applying Lemma 4.1 shows part (a).

Next we assume that $B \not\subseteq D$ and that there exists $\alpha > 0$ with $\alpha T_B \leq_{\text{fin}} \text{Re}(F_q)$. The latter implies the existence of a finite dimensional subspace $V_1 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\alpha \int_{S^2} \boldsymbol{p} \cdot \overline{T_B \boldsymbol{p}} \, \mathrm{d}s \leq \operatorname{Re} \left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s \right) \quad \text{for all } \boldsymbol{p} \in V_1^{\perp}.$$
(6.3)

Moreover, Corollary 4.4 with $q_1 = 0$ and $q_2 = q$ shows that there is a finite dimensional subspace $V_2 \subseteq L_t^2(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \leq \int_D q \, |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \leq q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{for all } \boldsymbol{p} \in V_2^{\perp}.$$
(6.4)

We set $V := V_1 + V_2$. Combining (6.3) and (6.4) we obtain that

$$lpha \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d} \boldsymbol{x} \le q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d} \boldsymbol{x} \quad \text{ for all } \boldsymbol{p} \in V^{\perp} \,.$$

To further estimate the right hand side we use Theorem 5.5 with $q_1 = 0$, $q_2 = q$, and $\Omega = D$, and we find that

$$\alpha \int_{B} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \leq Cq_{\max} \int_{D} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \qquad \text{for all } \boldsymbol{p} \in V^{\perp}$$

with some C > 0. However, this contradicts Theorem 5.1 with q = 0 and $\Omega = D$, which implies the existence of a sequence $(\mathbf{p}_m)_{m \in \mathbb{N}} \subseteq V^{\perp}$ such that

$$\int_{B} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \quad \text{and} \quad \int_{D} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \to 0 \quad \text{as } m \to \infty.$$

The next result is analogous to Theorem 6.1, but with contrast functions that are strictly negative a.e. on D.

Theorem 6.2. Let $D \subseteq \mathbb{R}^3$ be open and bounded of class C^0 such that $\mathbb{R}^3 \setminus \overline{D}$ is connected, and let $q \in \mathcal{Y}_D$. Suppose that $-\infty < q_{\min} \le q \le q_{\max} < 0$ for some constants $q_{\min}, q_{\max} \in \mathbb{R}$, and let $B \subseteq B_R(0)$ be open and bounded.

(a) If $B \subseteq D$, then there exists a constant C > 0 such that

$$\alpha T_B \geq_{\text{fin}} \operatorname{Re}(F_q) \quad \text{for all } \alpha \geq Cq_{\max}.$$

(b) If $B \not\subseteq D$, then

$$\alpha T_B \geq_{\text{fin}} \operatorname{Re}(F_q) \quad \text{for any } \alpha < 0.$$

Proof. Suppose that $B \subseteq D$. Applying Corollary 4.4 with $q_1 = 0$ and $q_2 = q$ we obtain a finite dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \leq \int_D q \, |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \leq q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \quad \text{for all } \boldsymbol{p} \in V^{\perp} \, .$$

Furthermore, Theorem 5.5 with $q_1 = 0$, $q_2 = q$, and $\Omega = D$ shows that there exists a constant C > 0 such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \leq C q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \qquad \text{for all } \boldsymbol{p} \in V^{\perp}$$

In particular,

$$\operatorname{Re}(F_q) \leq_{\operatorname{fin}} \alpha T_B \quad \text{for all } \alpha \geq Cq_{\max},$$

and part (a) is proven.

For part (b) we assume that $B \not\subseteq D$, and that there exists $\alpha < 0$ with $\alpha T_B \geq_{\text{fin}} \text{Re}(F_q)$. This means that there exists a finite dimensional subspace $V_1 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\alpha \int_{S^2} \boldsymbol{p} \cdot \overline{T_B \boldsymbol{p}} \, \mathrm{d}s \ge \operatorname{Re} \left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s \right) \quad \text{for all } \boldsymbol{p} \in V_1^{\perp} \,.$$
(6.5)

On the other hand, Theorem 4.2 with $q_1 = 0$ and $q_2 = q$ gives a finite dimensional subspace $V_2 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \ge \int_D q \, |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \ge q_{\min} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \,. \tag{6.6}$$

Let $V := V_1 + V_2$. Combining (6.5) and (6.6) we deduce that

$$lpha \int_B |\operatorname{\mathbf{curl}} oldsymbol{H}^i_{oldsymbol{p}}|^2 \, \mathrm{d} oldsymbol{x} \ge q_{\min} \int_D |\operatorname{\mathbf{curl}} oldsymbol{H}^i_{oldsymbol{p}}|^2 \, \mathrm{d} oldsymbol{x} \qquad ext{for all } oldsymbol{p} \in V^\perp \, .$$

Applying Theorem 5.1 with q = 0 and $\Omega = D$ gives a sequence $(\boldsymbol{p}_m)_{m \in \mathbb{N}} \subseteq V^{\perp}$ satisfying

$$\int_{B} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \quad \text{and} \quad \int_{D} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2} \, \mathrm{d}\boldsymbol{x} \to 0 \quad \text{as } m \to \infty.$$

Since $\alpha < 0$, this yields a contradiction.

7 Simultaneously localized vector wave functions

To justify a shape characterization similar to Theorems 6.1 and 6.2 for indefinite scattering objects, i.e., for the general case when the constrast function q is neither strictly positive nor strictly negative a.e. on D, we require a refined version of Theorem 5.1. In Theorem 7.1 we not only control the energy of the total field $H_{q,p}$, as was done in Theorem 5.1, but also the energy of the incident field H_p^i . Similar results have been established for the Schrödinger equation in [24], for the Helmholtz obstacle scattering problem in [1], and for the Helmholtz medium scattering problem in [19].

Theorem 7.1. Let $D \subseteq \mathbb{R}^3$ be open and bounded of class C^0 , and let $q \in \mathcal{Y}_D$ with $q|_D \in C^1(\overline{D})$. Let $E, M \subseteq \mathbb{R}^3$ be open and Lipschitz bounded such that $\operatorname{supp}(q) \subseteq \overline{E} \cup \overline{M}, \mathbb{R}^3 \setminus (\overline{E} \cup \overline{M})$ is connected, and $E \cap M = \emptyset$. Assume furthermore that there is a connected subset $\Gamma \subseteq \partial E \setminus \overline{M}$ that is relatively open and $C^{2,1}$ -smooth.

Then for any finite dimensional subspace $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ there exists a sequence $(\mathbf{p}_m)_{m\in\mathbb{N}} \subseteq V^{\perp}$ such that

$$\int_{E} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \qquad and \qquad \int_{M} (|\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} + |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2}) \, \mathrm{d}\boldsymbol{x} \to 0$$

as $m \to \infty$, where $H^i_{p_m}, H_{q,p_m} \in H_{\text{loc}}(\operatorname{curl}; \mathbb{R}^3)$ are given by (3.10) and (3.11) with $p = p_m$.

The proof of Theorem 7.1 relies on the following two lemmas. Lemma 7.2 extends the result of Lemma 5.2. The goal is to allow for more general arguments for the adjoint $L_{a,\Omega}^*$.

Lemma 7.2. Suppose that $D \subseteq \mathbb{R}^3$ is open and of class C^0 , let $q \in \mathcal{Y}_D$, and assume that $\Omega \subseteq \mathbb{R}^3$ is open and bounded. We define

$$L_{q,\Omega}: L^2_t(S^2, \mathbb{C}^3) \to H(\operatorname{\mathbf{curl}}; \Omega), \quad L_{q,\Omega} \, \boldsymbol{p} := \, \operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}}|_{\Omega} = \, -\mathrm{i}\omega\varepsilon \boldsymbol{E}_{q,\boldsymbol{p}}|_{\Omega}.$$

Then, $L_{q,\Omega}$ is a linear operator and its adjoint is given by

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$$L_{q,\Omega}^*: H(\operatorname{\mathbf{curl}}; \Omega)^* o L_t^2(S^2, \mathbb{C}^3) \,, \quad L_{q,\Omega}^* \boldsymbol{f} \, := \, \sqrt{rac{\mu_0}{arepsilon_0}} \mathcal{S}_q^*(\boldsymbol{
u} imes \boldsymbol{e}^\infty) \,,$$

where $H(\operatorname{curl}; \Omega)^*$ is the dual of $H(\operatorname{curl}; \Omega)$, and $e^{\infty} \in L^2_t(S^2, \mathbb{C}^3)$ is the far field pattern of the radiating solution $e \in H_{\operatorname{loc}}(\operatorname{curl}; \mathbb{R}^3)$ to

$$\operatorname{url}\operatorname{curl} \boldsymbol{e} - k^2 \varepsilon_r \boldsymbol{e} = \mathrm{i}\omega \varepsilon \boldsymbol{f} \qquad in \ \mathbb{R}^3.$$

Proof. This follows from the same arguments that have been used in the proof of Lemma 5.2. \Box

Lemma 7.3. Let $D \subseteq \mathbb{R}^3$ be open and bounded of class C^0 , and let $q \in \mathcal{Y}_D$ with $q|_D \in C^1(\overline{D})$. Let $E, M \subseteq \mathbb{R}^3$ be open and Lipschitz bounded such that $\operatorname{supp}(q) \subseteq \overline{E} \cup \overline{M}, \mathbb{R}^3 \setminus (\overline{E} \cup \overline{M})$ is connected, and $E \cap M = \emptyset$. Assume furthermore that there is a connected subset $\Gamma \subseteq \partial E \setminus \overline{M}$ that is relatively open and $C^{2,1}$ -smooth. Then,

$$\mathcal{R}(L_{q,E}^*) \not\subseteq \mathcal{R}\left(\left[L_{q,M}^* \mid L_{0,M}^*\right]\right)$$

and there exists an infinite dimensional subspace $Z \subseteq \mathcal{R}(L_{a,E}^*)$ such that

$$Z \cap \mathcal{R}(\left[L_{q,M}^* \, \big| \, L_{0,M}^*\right]) = \{0\}$$

Proof. Let $\mathbf{h} \in \mathcal{R}(L_{q,E}^*) \cap \mathcal{R}([L_{q,M}^* | L_{0,M}^*])$. Lemma 7.2 shows that there are $\mathbf{f}_{q,E} \in H(\mathbf{curl}; E)^*$ and $\mathbf{f}_{q,M}, \mathbf{f}_{0,M} \in H(\mathbf{curl}; M)^*$ such that the far field patterns $\mathbf{e}_{q,E}^{\infty}, \mathbf{e}_{q,M}^{\infty}, \mathbf{e}_{0,M}^{\infty}$ of the radiating solutions $\mathbf{e}_{q,E}, \mathbf{e}_{q,M}, \mathbf{e}_{0,M} \in H_{\mathrm{loc}}(\mathbf{curl}; \mathbb{R}^3)$ to

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e}_{q,M} - k^2 \varepsilon_r \boldsymbol{e}_{q,M} = \mathrm{i}\omega \varepsilon \boldsymbol{f}_{q,M} \qquad \text{in } \mathbb{R}^3,$$

 $\operatorname{curl}\operatorname{curl}\boldsymbol{e}_{0,M} - k^2\boldsymbol{e}_{0,M} = \mathrm{i}\omega\varepsilon\boldsymbol{f}_{0,M} \qquad \text{in } \mathbb{R}^3,$

satisfy

$$\sqrt{rac{arepsilon_0}{\mu_0}}oldsymbol{h}\,=\,\mathcal{S}_q^stig(oldsymbol{
u} imesoldsymbol{e}_{q,E}^\inftyig)\,=\,oldsymbol{
u} imesoldsymbol{e}_{0,M}^\infty+\mathcal{S}_q^stig(oldsymbol{
u} imesoldsymbol{e}_{q,M}^\inftyig)\,.$$

Here we used that S_0 is the identity operator. Accordingly, recalling the definition of the scattering operator in (3.9), we find that

$$0 = \boldsymbol{\nu} \times \boldsymbol{e}_{q,E}^{\infty} - \boldsymbol{\nu} \times \boldsymbol{e}_{q,M}^{\infty} - \mathcal{S}_q \left(\boldsymbol{\nu} \times \boldsymbol{e}_{0,M}^{\infty} \right)$$

= $\boldsymbol{\nu} \times \boldsymbol{e}_{q,E}^{\infty} - \boldsymbol{\nu} \times \boldsymbol{e}_{q,M}^{\infty} - \boldsymbol{\nu} \times \boldsymbol{e}_{0,M}^{\infty} - \frac{\mathrm{i}k}{8\pi^2} F_q \boldsymbol{e}_{0,M}^{\infty}$
= $\boldsymbol{\nu} \times \boldsymbol{e}_{q,E}^{\infty} - \left(\boldsymbol{\nu} \times \boldsymbol{e}_{q,M}^{\infty} + \boldsymbol{\nu} \times \boldsymbol{e}_{0,M}^{\infty} + \boldsymbol{\nu} \times \boldsymbol{e}_q^{\infty} \right),$

where e_q^{∞} is the far field of a radiating solution $e_q^s \in H_{\text{loc}}(\mathbf{curl}; \mathbb{R}^3)$ to

$$\operatorname{curl}\operatorname{curl} \boldsymbol{e}_q^s - k^2 \varepsilon_r \boldsymbol{e}_q^s = k^2 (1 - \varepsilon_r) \boldsymbol{e}^i \qquad ext{in } \mathbb{R}^3$$

for some entire solution $e^i \in H_{\text{loc}}(\operatorname{\mathbf{curl}}; \mathbb{R}^3)$ of

$$\operatorname{curl}\operatorname{curl} e^i - k^2 e^i = 0 \quad \text{in } \mathbb{R}^3$$

Since $\operatorname{supp}(q) \subseteq \overline{E} \cup \overline{M}$ and $\mathbb{R}^3 \setminus (\overline{E} \cup \overline{M})$ is connected, Rellich's lemma and unique continuation guarantee that

$$e_{q,E} - (e_{q,M} + e_{0,M} + e_q^s) = 0$$
 in $\mathbb{R}^3 \setminus (\overline{E} \cup \overline{M})$

(cf., e.g., [10, Thm. 6.10]).

Next we discuss the regularity of the traces of $\boldsymbol{\nu} \times \boldsymbol{e}_{q,E}|_{\Gamma} = \boldsymbol{\nu} \times (\boldsymbol{e}_{q,M} + \boldsymbol{e}_{0,M} + \boldsymbol{e}_q^s)|_{\Gamma}$ at the boundary segment $\Gamma \subseteq \partial E \setminus \overline{M}$. W.l.o.g. we may assume that Γ is bounded away from \overline{M} . Since $\operatorname{supp}(\boldsymbol{f}_{q,M} + \boldsymbol{f}_{0,M}) \subseteq \overline{M}$, regularity results for time-harmonic Maxwell's equations from [47] show that any point $\boldsymbol{x} \in \Gamma$ has an open neighborhood $U \subseteq \mathbb{R}^3$ such that $(\boldsymbol{e}_{q,M} + \boldsymbol{e}_{0,M} + \boldsymbol{e}_q)|_{E \cap U} \in$ $H^2(E \cap U, \mathbb{C}^3)$ and $(\boldsymbol{e}_{q,M} + \boldsymbol{e}_{0,M} + \boldsymbol{e}_q)|_{U \setminus \overline{E}} \in H^2(U \setminus \overline{E}, \mathbb{C}^3)$, where $\boldsymbol{e}_q = \boldsymbol{e}^i + \boldsymbol{e}_q^s$. Accordingly, applying the trace operator on $H^2(U \setminus \overline{E}, \mathbb{C}^3)$ and taking the cross product with $\boldsymbol{\nu} \in C^{1,1}(\Gamma, \mathbb{R}^3)$, we find that

$$\boldsymbol{\nu} \times (\boldsymbol{e}_{q,M} + \boldsymbol{e}_{0,M} + \boldsymbol{e}_q)|_{\Gamma} \in H_t^{\frac{2}{2}}(\Gamma \cap U, \mathbb{C}^3)$$

(see [21, p. 21])

Since $\boldsymbol{x} \in \Gamma$ was arbitrary and \boldsymbol{e}^i is smooth this implies that

$$oldsymbol{
u} imesoldsymbol{e}_{q,E}|_{\Gamma}\,=\,oldsymbol{
u} imes(oldsymbol{e}_{q,M}+oldsymbol{e}_{0,M}+oldsymbol{e}_q^s)|_{\Gamma}\,\in\,H^{rac{3}{2}}_t(\Gamma,\mathbb{C}^3)$$

To prove the lemma, we will construct a sufficiently large class of sources $\boldsymbol{f} \in H(\operatorname{curl}; E)^*$ such that $L_{q,E}^* \boldsymbol{f} \notin \mathcal{R}([L_{q,M}^* | L_{0,M}^*])$. Let $\boldsymbol{g} \in H^{-\frac{1}{2}}(\operatorname{Div}; \partial E)$ such that $\operatorname{supp}(\boldsymbol{g}) \subseteq \Gamma$. Accordingly, let $\boldsymbol{U}^+ \in H_{\operatorname{loc}}(\operatorname{curl}; \mathbb{R}^3 \setminus \overline{E})$ be the radiating solution to the exterior boundary problem

$$\operatorname{curl}\operatorname{curl} \boldsymbol{U}^{+} - k^{2}\varepsilon_{r}\boldsymbol{U}^{+} = 0 \quad \text{in } \mathbb{R}^{3} \setminus \overline{E}, \qquad \boldsymbol{\nu} \times \boldsymbol{U}^{+} = \boldsymbol{g} \quad \text{on } \partial E, \qquad (7.1)$$

(see, e.g., [37, Thm. 5.64]). Similarly, we define $U^- \in H(\operatorname{curl}; E)$ as the solution to the interior boundary value problem

curl curl
$$U^- - k^2 (\varepsilon_r + i) U^- = 0$$
 in E , $\boldsymbol{\nu} \times U^- = \boldsymbol{g}$ on ∂E , (7.2)

(see, e.g., [37, Thm. 4.41]). Therewith we define $U \in L^2_{loc}(\mathbb{R}^3)$ by

$$oldsymbol{U} := egin{cases} oldsymbol{U}^- & ext{in } E\,, \ oldsymbol{U}^+ & ext{in } \mathbb{R}^3\setminus\overline{E}\,, \end{cases}$$

and $\boldsymbol{f} \in H(\boldsymbol{\mathrm{curl}}; E)^*$ by

$$oldsymbol{f} \, := \, rac{1}{\mathrm{i}\omegaarepsilon} \Big(\mathrm{i}k^2oldsymbol{U}^- - \pi_t^*ig(oldsymbol{
u} imes \mathbf{curl}\,oldsymbol{U}igert_{\partial E}^+ - oldsymbol{
u} imes \mathbf{curl}\,oldsymbol{U}igert_{\partial E}^-ig) \Big) \,,$$

where $\pi_t^* : H^{-1/2}(\text{Div}; \partial E) \to H(\text{curl}; E)^*$ denotes the adjoint of the interior tangential trace operator $\pi_t : H(\text{curl}; E) \to H^{-1/2}(\text{Curl}; \partial E)$ with $\pi_t(\mathbf{V}) = (\mathbf{\nu} \times \mathbf{V}|_{\partial E}) \times \mathbf{\nu}$. Then $\mathbf{U} \in H_{\text{loc}}(\text{curl}; \mathbb{R}^3)$ (see, e.g., [42, Lem. 5.3]), and the weak formulations of (7.1) and (7.2) show that

$$\operatorname{curl}\operatorname{curl} \boldsymbol{U} - k^2 \varepsilon_r \boldsymbol{U} = \mathrm{i}\omega \varepsilon \boldsymbol{f} \quad \mathrm{in} \ \mathbb{R}^3$$

Accordingly, $L_{q,E}^* \boldsymbol{f} = \sqrt{\mu_0/\varepsilon_0} \, \mathcal{S}_q^*(\boldsymbol{\nu} \times \boldsymbol{U}^\infty)$, where $\boldsymbol{U}^\infty \in L_t^2(S^2, \mathbb{C}^3)$ coincides with the far field of the radiating solution \boldsymbol{U}^+ to the exterior boundary value problem (7.1). If $\boldsymbol{g} \notin H_t^{\frac{3}{2}}(\partial E, \mathbb{C}^3)$, then our regularity considerations from above show that $L_{q,E}^* \boldsymbol{f} \notin \mathcal{R}([L_{q,M}^* \mid L_{0,M}^*])$.

Now let

$$X \subseteq \left\{ \boldsymbol{g} \in H^{-\frac{1}{2}}(\operatorname{Div}; \partial E) \mid \operatorname{supp}(\boldsymbol{g}) \subseteq \Gamma \right\}$$

be an infinite dimensional subspace of $H^{-1/2}(\text{Div};\partial E)$ such that $X \cap H_t^{\frac{3}{2}}(\partial E, \mathbb{C}^3) = \{0\}$. Let $G_E : H^{-\frac{1}{2}}(\text{Div};\partial E) \to L_t^2(S^2, \mathbb{C}^3)$ be the operator that maps $\boldsymbol{g} \in H^{-\frac{1}{2}}(\text{Div};\partial E)$ to the far field pattern of the radiating solution \boldsymbol{U}^+ of the exterior boundary value problem (7.1). Then Rellich's lemma and unique continuation show that G_E is one-to-one, and thus

$$Z := \sqrt{\frac{\mu_0}{\varepsilon_0}} \,\mathcal{S}_q^* G_E(X) \subseteq L_t^2(S^2, \mathbb{C}^3)$$

is an infinite dimensional subspace as well. Furthermore, we have just shown that

$$Z \subseteq \mathcal{R}(L_{q,E}^*) \quad \text{and} \quad Z \cap \mathcal{R}\left(\left[L_{q,M}^* \mid L_{0,M}^*\right]\right) = \{0\}.$$

Now we give the proof of Theorem 7.1.

Proof of Theorem 7.1. Let $V \subseteq L^2_t(S^2, \mathbb{C}^3)$ be a finite dimensional subspace. We denote by $P_V: L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3)$ the orthogonal projection on V. Combining Lemma 7.3 with a simple dimensionality argument (see [29, Lem. 4.7]) shows that

$$Z \not\subseteq \mathcal{R}\left(\left[L_{q,M}^* \mid L_{0,M}^*\right]\right) + V = \mathcal{R}\left(\left[L_{q,M}^* \mid L_{0,M}^* \mid P_V\right]\right),$$

where $Z \subseteq \mathcal{R}(L_{a,E}^*)$ denotes the subspace in Lemma 7.3. Thus,

$$\mathcal{R}(L_{q,E}^*) \not\subseteq \mathcal{R}(\left[L_{q,M}^* \left| L_{0,M}^* \right| P_V\right])$$

and accordingly Lemma 5.4 implies that there is no constant C > 0 such that

$$\begin{aligned} \|L_{q,E}\boldsymbol{p}\|_{L^{2}(E)}^{2} &\leq C^{2} \left\| \begin{bmatrix} L_{q,M} \\ L_{0,M} \\ P_{V} \end{bmatrix} \boldsymbol{p} \right\|_{L^{2}(M) \times L^{2}(M) \times L^{2}_{t}(S^{2},\mathbb{C}^{3})} \\ &= C^{2} \left(\|L_{q,M}\boldsymbol{p}\|_{L^{2}(M)}^{2} + \|L_{0,M}\boldsymbol{p}\|_{L^{2}(M)}^{2} + \|P_{V}\boldsymbol{p}\|_{L^{2}_{t}(S^{2},\mathbb{C}^{3})}^{2} \right) \end{aligned}$$

for all $\boldsymbol{p} \in L^2_t(S^2, \mathbb{C}^3)$. Hence, there exists as sequence $(\widetilde{\boldsymbol{p}}_m)_{m \in \mathbb{N}} \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that

$$\|L_{q,E}\widetilde{\boldsymbol{p}}_m\|_{L^2(E)} \to \infty \qquad \text{as } m \to \infty,$$

$$\|L_{q,M}\widetilde{\boldsymbol{p}}_m\|_{L^2(M)} + \|L_{0,M}\widetilde{\boldsymbol{p}}_m\|_{L^2(M)} + \|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2,\mathbb{C}^3)} \to 0 \qquad \text{as } m \to \infty.$$

Setting $\boldsymbol{p}_m := \widetilde{\boldsymbol{p}}_m - P_V \widetilde{\boldsymbol{p}}_m \in V^{\perp} \subseteq L^2_t(S^2, \mathbb{C}^3)$ for any $m \in \mathbb{N}$, we finally obtain

$$\|L_{q,E}\boldsymbol{p}_m\|_{L^2(E)} \geq \|L_{q,E}\widetilde{\boldsymbol{p}}_m\|_{L^2(E)} - \|L_{q,E}\| \|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2,\mathbb{C}^3)} \to \infty \quad \text{as } m \to \infty,$$

and

$$\begin{split} \|L_{q,M}\boldsymbol{p}_m\|_{L^2(M)} + \|L_{0,M}\boldsymbol{p}_m\|_{L^2(M)} &\leq \|L_{q,M}\widetilde{\boldsymbol{p}}_m\|_{L^2(M)} + \|L_{0,M}\widetilde{\boldsymbol{p}}_m\|_{L^2(M)} \\ &+ (\|L_{q,M}\| + \|L_{0,M}\|)\|P_V\widetilde{\boldsymbol{p}}_m\|_{L^2_t(S^2,\mathbb{C}^3)} \to 0 \qquad \text{as } m \to \infty \,. \end{split}$$

Since $L_{q,E}\boldsymbol{p}_m = \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}_m}|_E$, $L_{q,M}\boldsymbol{p}_m = \operatorname{curl} \boldsymbol{H}_{q,\boldsymbol{p}_m}|_M$, and $L_{0,M}\boldsymbol{p}_m = \operatorname{curl} \boldsymbol{H}_{\boldsymbol{p}_m}^i|_M$, this ends the proof.

8 Shape reconstruction for indefinite scatterers

We consider the general case when the constrast function q is neither strictly positive nor strictly negative a.e. on the support D of the scatterer. While the criteria developed in Theorems 6.1 and 6.2 determine whether a certain probing domain B is contained in the support D of the scattering object or not, the criterion in Theorem 8.1 characterizes whether a certain probing domain B contains the support D of the scatterer or not.

Theorem 8.1. Let $D \subseteq \mathbb{R}^3$ be open and bounded such that ∂D is piecewise $C^{2,1}$ and $\mathbb{R}^3 \setminus \overline{D}$ is connected. Let $q \in \mathcal{Y}_D$ with $q|_D \in C^1(\overline{D})$, and suppose that $-\infty < q_{\min} \leq q \leq q_{\max} < 1$ a.e. on D for some constants $q_{\min}, q_{\max} \in \mathbb{R}$. Furthermore, we assume that for any point $\mathbf{x} \in \partial D$ on the boundary of D, and for any neighborhood $U \subseteq D$ of \mathbf{x} in D, there exists a connected unbounded domain $O \subseteq \mathbb{R}^3$ with $\emptyset \neq E := O \cap D \subseteq U$ such that

$$q|_E \ge q_{\min,E} > 0 \qquad or \qquad q|_E \le q_{\max,E} < 0 \tag{8.1}$$

for some constants $q_{\min,E}, q_{\max,E} \in \mathbb{R}$.

Let $B \subseteq \mathbb{R}^3$ open such that $\mathbb{R}^3 \setminus \overline{B}$ is connected.

(a) If $D \subseteq B$, then there exists a constant C > 0 such that

 $\alpha T_B \leq_{\text{fin}} \operatorname{Re}(F_q) \leq_{\text{fin}} \beta T_B \quad \text{for all } \alpha \leq \min\{0, q_{\min}\}, \ \beta \geq \max\{0, Cq_{\max}\}.$

(b) If $D \not\subseteq B$, then

 $\alpha T_B \not\leq_{\text{fin}} \operatorname{Re}(F_q) \text{ for any } \alpha \in \mathbb{R} \text{ or } \operatorname{Re}(F_q) \not\leq_{\text{fin}} \beta T_B \text{ for any } \beta \in \mathbb{R}.$

Proof of Theorem 8.1. Let $D \subseteq B$. Using Corollary 4.4 and Theorem 5.5 with $q_1 = 0$ and $q_2 = q$ we find that there exists a constant C > 0 and a finite dimensional subspace $V_1 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that, for all $\mathbf{p} \in V_1^{\perp}$ and any $\beta \geq \max\{0, Cq_{\max}\}$,

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \leq \int_D q |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \leq q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q, \boldsymbol{p}}|^2 \, \mathrm{d}\boldsymbol{x} \\ \leq C q_{\max} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \leq \beta \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x}.$$

On the other hand, Theorem 4.2 with $q_1 = 0$ and $q_2 = q$ gives a finite dimensional subspace $V_2 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that, for all $\mathbf{p} \in V_2^{\perp}$ and any $\alpha \leq \min\{0, q_{\min}\}$,

$$\operatorname{Re}\left(\int_{S^2} \boldsymbol{p} \cdot \overline{F_q \boldsymbol{p}} \, \mathrm{d}s\right) \geq \int_D q |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \geq q_{\min} \int_D |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} \geq \alpha \int_B |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x}.$$

Thus, part (a) is proven.

Part (b) is shown by contradiction. Let $D \not\subseteq B$, then $U := D \setminus B$ is not empty. By assumption there exists a point $\boldsymbol{x} \in \overline{U} \cap \partial D$ and a connected unbounded open neighborhood $O \subseteq \mathbb{R}^3$ of \boldsymbol{x} with $O \cap D \subseteq U$ and $O \cap B = \emptyset$, such that (8.1) is satisfied with $E := O \cap D$. Let R > 0 be large enough such that $B, D \subseteq B_R(0)$. Without loss of generality we suppose that $O \cap B_R(0)$, and $B_R(0) \setminus \overline{O}$ are connected.

If $q|_E \ge q_{\min,E} > 0$ we assume that $\operatorname{Re}(F_q) \le_{\operatorname{fin}} \beta T_B$ for some $\beta \in \mathbb{R}$. Applying the monotonicity relation (4.1) in Theorem 4.2 with $q_1 = 0$ and $q_2 = q$, we find that there exists a finite dimensional subspace $V_3 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that, for any $\boldsymbol{p} \in V_3^{\perp}$,

$$0 \geq \int_{S^2} \boldsymbol{p} \cdot \left(\overline{\operatorname{Re}(F_q)\boldsymbol{p} - \beta T_B \boldsymbol{p}}\right) \, \mathrm{d}s \geq \int_{B_R(0)} (q - \beta \chi_B) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x}$$

$$= \int_{B_R(0)\setminus\overline{O}} (q - \beta \chi_B) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} + \int_{B_R(0)\cap O} (q - \beta \chi_B) |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x}$$

$$\geq -(||q||_{L^{\infty}(\mathbb{R}^3)} + |\beta|) \int_{B_R(0)\setminus\overline{O}} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x} + q_{\min,E} \int_E |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}}^i|^2 \, \mathrm{d}\boldsymbol{x}.$$

However, this contradicts Theorem 5.1 with B = E, $\Omega = B_R(0) \setminus \overline{O}$, and q = 0, which yields a sequence $(\mathbf{p}_m)_{m \in \mathbb{N}} \subseteq V_3^{\perp}$ with

$$\int_E |\operatorname{\mathbf{curl}} \boldsymbol{H}^i_{\boldsymbol{p}_m}|^2 \, \mathrm{d}\boldsymbol{x} \to \infty \qquad \text{and} \qquad \int_{B_R(0)\setminus\overline{O}} |\operatorname{\mathbf{curl}} \boldsymbol{H}^i_{\boldsymbol{p}_m}|^2 \, \mathrm{d}\boldsymbol{x} \to 0 \qquad \text{as } m \to \infty \,.$$

Thus, $\operatorname{Re}(F_q) \not\leq_{\operatorname{fin}} \beta T_B$ for all $\beta \in \mathbb{R}$.

Now assume that $q|_E \leq q_{\max,E} < 0$, and that $\alpha T_B \leq_{\text{fin}} \text{Re}(F_q)$ for some $\alpha \in \mathbb{R}$. Then the monotonicity relation (4.3) in Corollary 4.4 with $q_1 = 0$ and $q_2 = q$ shows that there exists a

finite dimensional subspace $V_4 \subseteq L^2_t(S^2, \mathbb{C}^3)$ such that, for any $\boldsymbol{p} \in V_4^{\perp}$,

$$egin{aligned} 0 &\leq \int_{S^2} oldsymbol{p} \cdot ig(\overline{\operatorname{Re}(F_q)oldsymbol{p} - lpha T_Boldsymbol{p}}ig) \,\mathrm{d}s \,\leq \, \int_{B_R(0)} ig(q|\operatorname{\mathbf{curl}}oldsymbol{H}_{q,oldsymbol{p}}|^2 - lpha \chi_B|\operatorname{\mathbf{curl}}oldsymbol{H}_{p}|^2ig) \,\mathrm{d}x \ &= \int_{B_R(0)\setminus\overline{O}} ig(q|\operatorname{\mathbf{curl}}oldsymbol{H}_{q,oldsymbol{p}}|^2 - lpha \chi_B|\operatorname{\mathbf{curl}}oldsymbol{H}_{p}|^2ig) \,\mathrm{d}x \ &+ \int_{B_R(0)\cap O} ig(q|\operatorname{\mathbf{curl}}oldsymbol{H}_{q,oldsymbol{p}}|^2 - lpha \chi_B|\operatorname{\mathbf{curl}}oldsymbol{H}_{p}|^2ig) \,\mathrm{d}x \ &\leq q_{\max}\int_{B_R(0)\setminus\overline{O}}|\operatorname{\mathbf{curl}}oldsymbol{H}_{q,oldsymbol{p}}|^2 \,\mathrm{d}x + |lpha|\int_{B_R(0)\setminus\overline{O}}|\operatorname{\mathbf{curl}}oldsymbol{H}_{p}|^2 \,\mathrm{d}x + q_{\max,E}\int_E|\operatorname{\mathbf{curl}}oldsymbol{H}_{q,oldsymbol{p}}|^2 \,\mathrm{d}x \,. \end{aligned}$$

Let $M := B_R(0) \setminus \overline{O}$. Since ∂D is piecewise $C^{2,1}$ smooth, there is a connected subset $\Gamma \subseteq \partial E \setminus \overline{M}$ that is relatively open and $C^{2,1}$ smooth. Using Theorem 7.1 we obtain a sequence $(\mathbf{p}_m)_{m \in \mathbb{N}} \subseteq V_4^{\perp}$ such that

$$\int_{E} |\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} \, \mathrm{d}\boldsymbol{x} \to \infty \qquad \text{and} \qquad \int_{B_{R}(0) \setminus \overline{O}} (|\operatorname{\mathbf{curl}} \boldsymbol{H}_{q,\boldsymbol{p}_{m}}|^{2} + |\operatorname{\mathbf{curl}} \boldsymbol{H}_{\boldsymbol{p}_{m}}^{i}|^{2}) \, \mathrm{d}\boldsymbol{x} \to 0$$

as $m \to \infty$. However, since $q_{\max,E} < 0$ this gives a contradiction. Therefore, $\alpha T_B \not\leq_{\text{fin}} \text{Re}(F_q)$ for all $\alpha \in \mathbb{R}$, and this ends the proof of part (b).

9 Numerical examples

We discuss numerical examples for the shape characterizations developed in Sections 6 and 8. The main issue here is that numerical approximations of the operators F_q and T_B are necessarily finite dimensional. Accordingly, the question, whether suitable combinations of these operators are positive or negative definite up to some finite dimensional subspace (see Theorems 6.1, 6.2, and 8.1) needs to be carefully relaxed.

9.1 An explicit radially symmetric example

To illustrate the results from Theorems 6.1, 6.2, and 8.1 we consider the special case when the scatterer D and the probing domain B are concentric balls.

Let $D = B_{r_D}(0)$ be a ball of radius $r_D > 0$ centered at the origin with constant electric permittivity contrast q < 1, i.e., the relative electric permittivity is $\varepsilon_r^{-1} = 1 - q > 0$. We derive series expansions for the incident magnetic field and for the corresponding magnetic far field pattern to obtain explicit formulas for the eigenvalue decomposition of the magnetic far field operator F_q from (3.8).

Let Y_n^m , $m = -n, \ldots, n, n \in \mathbb{N}$, denote a complete orthonormal system of spherical harmonics of order n in $L^2(S^2)$. Then, the vector spherical harmonics

$$oldsymbol{U}_n^m(oldsymbol{ heta}) := rac{1}{\sqrt{n(n+1)}} \operatorname{{f Grad}}_{S^2} Y_n^m(oldsymbol{ heta}), \qquad oldsymbol{V}_n^m(oldsymbol{ heta}) := oldsymbol{ heta} imes oldsymbol{U}_n^m(oldsymbol{ heta}), \qquad oldsymbol{ heta} \in S^2\,,$$

for $m = -n, \ldots, n, n = 1, 2, \ldots$, form a complete orthonormal system in $L^2_t(S^2, \mathbb{C}^3)$. Accordingly, we define the *spherical vector wave functions*

$$\boldsymbol{M}_{n}^{m}(\boldsymbol{x}) := -j_{n}(k|\boldsymbol{x}|)\boldsymbol{V}_{n}^{m}(\widehat{\boldsymbol{x}}), \qquad \boldsymbol{N}_{n}^{m}(\boldsymbol{x}) := -h_{n}^{(1)}(k|\boldsymbol{x}|)\boldsymbol{V}_{n}^{m}(\widehat{\boldsymbol{x}}), \qquad \boldsymbol{x} \in \mathbb{R}^{3}, \qquad (9.1)$$

for $m = -n, \ldots, n, n = 1, 2, \ldots$, where j_n and $h_n^{(1)}$ denote the spherical Bessel and Hankel function of degree n. We note that the normalization factors used in (9.1) differ from what is used elsewhere in the literature (see, e.g., [10, Sec. 6.5]).

Given a tangential vector field

$$\boldsymbol{p} = \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(a_n^m \boldsymbol{U}_n^m + b_n^m \boldsymbol{V}_n^m \right) \in L_t^2(S^2, \mathbb{C}^3) , \qquad (9.2)$$

we obtain from (3.10) and [10, Thm. 6.29] that

$$oldsymbol{H}_{oldsymbol{p}}^{i}(oldsymbol{x}) \,=\, rac{4\pi\,\mathrm{i}^{n-1}}{k}\sum_{n=1}^{\infty}\sum_{m=-n}^{n}ig(a_{n}^{m}\,\mathrm{\mathbf{curl}}\,oldsymbol{M}_{n}^{m}(oldsymbol{x}) -\mathrm{i}k\,b_{n}^{m}oldsymbol{M}_{n}^{m}(oldsymbol{x})ig)\,,\qquadoldsymbol{x}\in\mathbb{R}^{3}\,.$$

Applying separation of variables a short computation shows that the corresponding scattered magnetic field outside the support of the scatterer is given by

$$\boldsymbol{H}_{q,\boldsymbol{p}}^{s}(\boldsymbol{x}) = \frac{4\pi\,\mathrm{i}^{n-1}}{k} \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(c_{n}^{m}\,\mathrm{curl}\,\boldsymbol{N}_{n}^{m}(\boldsymbol{x}) - \mathrm{i}k\,d_{n}^{m}\boldsymbol{N}_{n}^{m}(\boldsymbol{x}) \right), \qquad \boldsymbol{x} \in \mathbb{R}^{3} \setminus \overline{D}\,,$$

with

$$\begin{split} c_n^m &= a_n^m \frac{(\kappa r_D) j_n(kr_D) j'_n(\kappa r_D) - (kr_D) j_n(\kappa r_D) j'_n(kr_D)}{(kr_D) j_n(\kappa r_D) (h_n^{(1)})'(kr_D) - (\kappa r_D) h_n^{(1)}(kr_D) j'_n(\kappa r_D)},\\ d_n^m &= b_n^m \frac{\varepsilon_r^{-1} j_n(kr_D) \big(j_n(\kappa r_D) + (\kappa r_D) j'_n(\kappa r_D) \big) - j_n(\kappa r_D) \big(j_n(kr_D) + (kr_D) j'_n(kr_D) \big)}{(kr_D) j_n(\kappa r_D) (h_n^{(1)})'(kr_D) - (\kappa r_D) \varepsilon_r^{-1} j'_n(\kappa r_D) h_n^{(1)}(kr_D) + q h_n^{(1)}(kr_D) j_n(\kappa r_D) \big)}, \end{split}$$

and $\kappa := k\sqrt{\varepsilon_r}$. Recalling that the far field patterns of the spherical vector wave functions N_n^m and curl N_n^m are given by

$$(\boldsymbol{N}_n^m)^{\infty}(\widehat{\boldsymbol{x}}) = -\frac{4\pi \,(-\mathrm{i})^{n+1}}{k} \boldsymbol{V}_n^m(\widehat{\boldsymbol{x}})\,,\qquad (\operatorname{curl} \boldsymbol{N}_n^m)^{\infty}(\widehat{\boldsymbol{x}}) = 4\pi \,(-\mathrm{i})^n \boldsymbol{U}_n^m(\widehat{\boldsymbol{x}})\,,\qquad \widehat{\boldsymbol{x}} \in S^2\,,$$

for $m = -n, \ldots, n, n = 1, 2, \ldots$ (see, e.g., [10, Thm. 6.28]), we find that

$$\boldsymbol{H}_{q,\boldsymbol{p}}^{\infty}(\widehat{\boldsymbol{x}}) = \frac{(4\pi)^2}{\mathrm{i}k} \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(c_n^m \boldsymbol{U}_n^m(\widehat{\boldsymbol{x}}) + d_n^m \boldsymbol{V}_n^m(\widehat{\boldsymbol{x}}) \right), \qquad \widehat{\boldsymbol{x}} \in S^2.$$

Accordingly, the eigenvalues and eigenvectors of the magnetic far field operator F_q are given by $(\lambda_n^{(j)}, \boldsymbol{v}_{m,n}^{(j)}), n \ge 1, -n \le m \le n, j = s, t$ with

$$\lambda_n^{(s)} = \frac{(4\pi)^2}{\mathrm{i}k} \frac{(\kappa r_D) j_n(kr_D) j'_n(\kappa r_D) - (kr_D) j_n(\kappa r_D) j'_n(kr_D)}{(kr_D) j_n(\kappa r_D) (h_n^{(1)})'(kr_D) - (\kappa r_D) h_n^{(1)}(kr_D) j'_n(\kappa r_D)},\tag{9.3a}$$

$$\lambda_n^{(t)} = \frac{(4\pi)^2}{\mathrm{i}k} \frac{\varepsilon_r^{-1} j_n(kr_D) (j_n(\kappa r_D) + (\kappa r_D) j'_n(\kappa r_D)) - j_n(\kappa r_D) (j_n(kr_D) + (kr_D) j'_n(kr_D))}{(kr_D) j_n(\kappa r_D) (h_n^{(1)})'(kr_D) - (\kappa r_D) \varepsilon_r^{-1} j'_n(\kappa r_D) h_n^{(1)}(kr_D) + q h_n^{(1)}(kr_D) j_n(\kappa r_D)},$$
(9.3b)

and

$$\boldsymbol{v}_{m,n}^{(s)}(\widehat{\boldsymbol{x}}) = \boldsymbol{U}_n^m(\widehat{\boldsymbol{x}}), \qquad \boldsymbol{v}_{m,n}^{(t)}(\widehat{\boldsymbol{x}}) = \boldsymbol{V}_n^m(\widehat{\boldsymbol{x}}), \qquad \widehat{\boldsymbol{x}} \in S^2.$$
 (9.3c)

Similarly, we consider for the test domain $B = B_{r_B}(0)$ a ball of radius $r_B > 0$ centered at the origin. Then the probing operator $T_B : L^2_t(S^2, \mathbb{C}^3) \to L^2_t(S^2, \mathbb{C}^3)$ from (6.1) satisfies

$$(T_B \boldsymbol{p})(\widehat{\boldsymbol{x}}) = k^2 \Big(\int_{S^2} \Big(\int_{B_{r_B}(0)} e^{\mathrm{i}k\boldsymbol{y}\cdot(\boldsymbol{\theta}-\widehat{\boldsymbol{x}})} \, \mathrm{d}\boldsymbol{y} \Big) \big(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta}) \big) \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \Big) \times \widehat{\boldsymbol{x}}$$

$$= k^2 \Big(\int_{S^2} \Big(\int_0^{r_B} 4\pi \rho^2 j_0(k\rho|\boldsymbol{\theta}-\widehat{\boldsymbol{x}}|) \, \mathrm{d}\rho \Big) \big(\boldsymbol{\theta} \times \boldsymbol{p}(\boldsymbol{\theta}) \big) \, \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \Big) \times \widehat{\boldsymbol{x}} , \qquad \widehat{\boldsymbol{x}} \in S^2 .$$

$$(9.4)$$

Here we used the integral representation of j_0 (see, e.g., [10, (2.45)]. Substituting the vector spherical harmonics expansion (9.2) into (9.4) we find that

$$(T_{B}\boldsymbol{p})(\hat{\boldsymbol{x}}) = 4\pi k^{2} \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(a_{n}^{m} \int_{0}^{r_{B}} \int_{S^{2}} j_{0}(k\rho|\boldsymbol{\theta} - \hat{\boldsymbol{x}}|) \boldsymbol{V}_{n}^{m}(\boldsymbol{\theta}) \, \mathrm{d}s(\boldsymbol{\theta}) \, \rho^{2} \, \mathrm{d}\rho \right. \\ \left. - b_{n}^{m} \int_{0}^{r_{B}} \int_{S^{2}} j_{0}(k\rho|\boldsymbol{\theta} - \hat{\boldsymbol{x}}|) \boldsymbol{U}_{n}^{m}(\boldsymbol{\theta}) \, \mathrm{d}s(\boldsymbol{\theta}) \, \rho^{2} \, \mathrm{d}\rho \right) \times \hat{\boldsymbol{x}}$$

$$= \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(a_{n}^{m} \left((4\pi k)^{2} \int_{0}^{r_{B}} j_{n}^{2}(k\rho)\rho^{2} \, \mathrm{d}\rho \right) \boldsymbol{U}_{n}^{m}(\hat{\boldsymbol{x}}) \right. \\ \left. + b_{n}^{m} \left((4\pi)^{2} \int_{0}^{r_{B}} \left((j_{n}(k\rho) + k\rho j_{n}'(k\rho))^{2} + n(n+1)j_{n}^{2}(k\rho) \right) \, \mathrm{d}\rho \right) \boldsymbol{V}_{n}^{m}(\hat{\boldsymbol{x}}) \right)$$

$$(9.5)$$

(see, e.g., [10, Thm. 6.29]). Accordingly, the eigenvalues and eigenvectors of the probing operator T_B are given by $(\mu_n^{(j)}, \boldsymbol{v}_{m,n}^{(j)}), n \ge 1, -n \le m \le n, j = s, t$ with

$$\mu_n^{(s)} = \frac{(4\pi)^2}{k} \int_0^{kr_B} j_n^2(\rho) \rho^2 \,\mathrm{d}\rho \,, \tag{9.6a}$$

$$\mu_n^{(t)} = \frac{(4\pi)^2}{k} \int_0^{kr_B} \left(n(n+1)j_n^2(\rho) + (j_n(\rho) + \rho j_n'(\rho))^2 \right) \,\mathrm{d}\rho \,, \tag{9.6b}$$

and

$$\boldsymbol{v}_{m,n}^{(s)}(\widehat{\boldsymbol{x}}) = \boldsymbol{U}_n^m(\widehat{\boldsymbol{x}}), \qquad \boldsymbol{v}_{m,n}^{(t)}(\widehat{\boldsymbol{x}}) = \boldsymbol{V}_n^m(\widehat{\boldsymbol{x}}), \qquad \widehat{\boldsymbol{x}} \in S^2.$$
(9.6c)

Assuming that 0 < q < 1, the criteria established in Theorem 6.1 and Theorem 8.1 show that

- (a) if $r_B < r_D$, i.e., when $B \subseteq D$, then $0 \leq_{\text{fin}} \operatorname{Re}(F_q) \alpha T_B$ when $\alpha \leq q$ but $0 \not\geq_{\text{fin}} \operatorname{Re}(F_q) \alpha T_B$ for any $\alpha \in \mathbb{R}$. This means that $\operatorname{Re}(F_q) \alpha T_B$ has infinitely many positive eigenvalues for any $\alpha \in \mathbb{R}$ but only finitely many negative eigenvalues when $\alpha \leq q$.
- (b) if $r_B > r_D$, i.e., when $B \not\subseteq D$, then $\operatorname{Re}(F_q) \alpha T_B \leq_{\operatorname{fin}} 0$ when $\alpha \geq Cq$ with C > 0 as in Theorem 5.5, but $0 \not\leq_{\operatorname{fin}} \operatorname{Re}(F_q) - \alpha T_B$ for any $\alpha \in \mathbb{R}$. This means that $\operatorname{Re}(F_q) - \alpha T_B$ has infinitely many negative eigenvalues for any $\alpha \in \mathbb{R}$ but only finitely many positive eigenvalues when $\alpha \geq Cq$.

A similar characterization for negative contrasts $-\infty < q < 0$ can be obtained from Theorems 6.2 and 8.1.

To illustrate this characterization, we choose q = 0.5, i.e., $\varepsilon_r = 2$, and we evaluate the eigenvalues $\operatorname{Re}(\lambda_n^{(j)}(r_D))$, $\mu_n^{(j)}(r_B)$, and $\operatorname{Re}(\lambda_n^{(j)}(r_D)) - \alpha \mu_n^{(j)}(r_B)$, j = s, t, with wave number k = 1, radius of the obstacle r = 5, $\alpha = 0.5$, and $n = 1, \ldots, 1000$ for different values of the radius $r_B \in [0, 25]$ of the test domain B using (9.3) and (9.6). In Figure 9.1 we show plots of the number of negative eigenvalues (left plot) and of the number of postive eigenvalues (right plot) $\operatorname{Re}(\lambda_n^{(j)}(r_D))$ (dotted), $\mu_n^{(j)}(r_B)$ (dashed), and $\operatorname{Re}(\lambda_n^{(j)}(r_D)) - \alpha \mu_n^{(j)}(r_D)$ (solid), j = s, t, within the range $n = 0, \ldots, 1000$ as a function of r_B .

As suggested by Theorems 6.1 and 8.1 there is a sharp transition in the behavior of the eigenvalues of $\operatorname{Re}(F_q) - \alpha T_B$ at $r_B = r_D = 5$, which could be used to estimate the value of r_D . In these plots the contribution of the operator $\operatorname{Re}(F_q)$ dominates in the superposition $\operatorname{Re}(F_q) - \alpha T_B$ as long as $r_B < r_D$ (i.e., when $B \subseteq D$), while the contribution of the operator αT_B dominates when $r_B > r_D$ (i.e., when $D \subseteq B$).

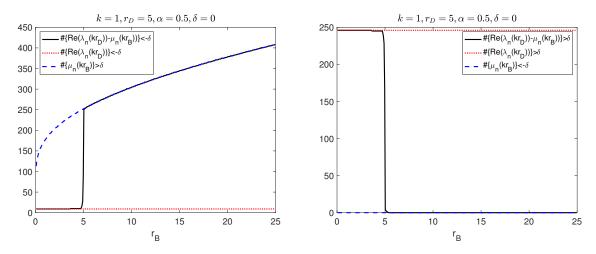


Figure 9.1: Number of positive eigenvalues (left) and number of negative eigenvalues (right) $\operatorname{Re}(\lambda_n(r_D))$ (dotted), $\mu_n(r_B)$ (dashed), and $\operatorname{Re}(\lambda_n(r_D)) + \mu_n(r_B)$ (solid) within the range $n = 0, \ldots, 1000$ as function of r_B .

9.2 A sampling strategy for sign-definite scatterers

We discuss a numerical realization of the criteria established in Theorems 6.1 and 6.2. To discretize the magnetic far field operator F_q from (3.8) we use a truncated vector spherical harmonics expansion. Let $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ as in (9.2), then applying F_q gives

$$F_{q}\boldsymbol{p} = \sum_{n=1}^{\infty} \sum_{m=-n}^{n} \left(a_{n}^{m} F_{q} \boldsymbol{U}_{n}^{m} + b_{n}^{m} F_{q} \boldsymbol{V}_{n}^{m} \right) \in L_{t}^{2}(S^{2}, \mathbb{C}^{3}).$$
(9.7)

Studying the singular value decomposition of the linear operator that maps current densities supported in the ball $B_R(0)$ of radius R around the origin to their radiated far field patterns, it has been observed in [20] that for a large class of practically relevant source distributions the radiated far field pattern is well approximated by a vector spherical harmonics expansion of order $N \gtrsim kR$. This study suggests to truncate the series in (9.7) at an index N that is at least slightly larger than the radius of the smallest ball around the origin that contains the scattering object. Accordingly, we use the matrix

$$\boldsymbol{F}_{q} := \begin{bmatrix} \langle F_{q}\boldsymbol{U}_{n}^{m}, \boldsymbol{U}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} & \langle F_{q}\boldsymbol{V}_{n}^{m}, \boldsymbol{U}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \\ \langle F_{q}\boldsymbol{U}_{n}^{m}, \boldsymbol{V}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} & \langle F_{q}\boldsymbol{V}_{n}^{m}, \boldsymbol{V}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \end{bmatrix} \in \mathbb{C}^{Q \times Q}$$
(9.8)

with Q = 2N(N+2) as a discrete approximation of F_q .

Next, we consider an equidistant grid of sampling points

$$\Delta = \{ \boldsymbol{z}_{ij\ell} = (ih, jh, \ell h) \mid -J \leq i, j, \ell \leq J \} \subseteq [-R, R]^3$$
(9.9)

with step size h = R/J in the region of interest $[-R, R]^3$. For each $\mathbf{z}_{ij\ell} \in \Delta$ we consider a probing operator $T_{B_{ij\ell}}$ as in (6.1), where the probing domain $B_{ij\ell} = B_{h/2}(\mathbf{z}_{ij\ell})$ is a ball of radius h/2 centered at $\mathbf{z}_{ij\ell}$. This probing operator satisfies, for any $\mathbf{p} \in L^2_t(S^2, \mathbb{C}^3)$ and $\hat{\mathbf{x}} \in S^2$,

$$\begin{aligned} (T_{B_{ij\ell}}\boldsymbol{p})(\widehat{\boldsymbol{x}}) \ &= \ k^2 \Big(\int_{S^2} e^{\mathrm{i}k\boldsymbol{z}\cdot(\boldsymbol{\theta}-\widehat{\boldsymbol{x}})} \Big(\int_{B_{h/2}(0)} e^{\mathrm{i}k\boldsymbol{y}\cdot(\boldsymbol{\theta}-\widehat{\boldsymbol{x}})} \ \mathrm{d}\boldsymbol{y} \Big) \Big(\boldsymbol{\theta}\times\boldsymbol{p}(\boldsymbol{\theta})\Big) \ \mathrm{d}\boldsymbol{s}(\boldsymbol{\theta}) \Big) \times \widehat{\boldsymbol{x}} \\ &= \ e^{-\mathrm{i}k\boldsymbol{z}\cdot\widehat{\boldsymbol{x}}} \Big(T_{B_{h/2}(0)} \big(e^{\mathrm{i}k\boldsymbol{z}\cdot(\cdot)}\boldsymbol{p} \big) \Big) (\widehat{\boldsymbol{x}}) \,. \end{aligned}$$

Combining this representation with the eigenvalue expansion of $T_{B_{h/2}(0)}$ that we have derived in the previous subsection (see (9.5) and (9.6)), we find that $T_{B_{ij\ell}}$ has the same eigenvalues $\mu_n^{(s)}, \mu_n^{(t)}$ as $T_{B_{h/2}(0)}$, but the corresponding eigenvectors for $T_{B_{ij\ell}}$ are

$$\widetilde{\boldsymbol{v}}_{m,n}^{(s)}(\widehat{\boldsymbol{x}}) = e^{-\mathrm{i}k\boldsymbol{z}\cdot\widehat{\boldsymbol{x}}}\boldsymbol{U}_n^m(\widehat{\boldsymbol{x}}) \quad \text{and} \quad \widetilde{\boldsymbol{v}}_{m,n}^{(t)}(\widehat{\boldsymbol{x}}) = e^{-\mathrm{i}k\boldsymbol{z}\cdot\widehat{\boldsymbol{x}}}\boldsymbol{V}_n^m(\widehat{\boldsymbol{x}}), \quad \widehat{\boldsymbol{x}}\in S^2.$$

Accordingly we find for $\boldsymbol{A}_{n}^{m} \in \{\boldsymbol{U}_{n}^{m}, \boldsymbol{V}_{n}^{m}\}$ and $\boldsymbol{B}_{n'}^{m'} \in \{\boldsymbol{U}_{n'}^{m'}, \boldsymbol{V}_{n'}^{m'}\}$ with $n, n' \geq 1, -n \leq m \leq n$, and $-n' \leq m' \leq n'$ that

$$\langle T_{B_{ij\ell}} \boldsymbol{A}_{n}^{m}, \boldsymbol{B}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})}$$

$$= \sum_{b=1}^{\infty} \sum_{a=-b}^{b} \left(\mu_{a}^{(s)} \langle \boldsymbol{A}_{n}^{m}, e^{-ik\boldsymbol{z}\cdot(\cdot)} \boldsymbol{U}_{b}^{a} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \langle e^{-ik\boldsymbol{z}\cdot(\cdot)} \boldsymbol{U}_{b}^{a}, \boldsymbol{B}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \right.$$

$$+ \mu_{a}^{(t)} \langle \boldsymbol{A}_{n}^{m}, e^{-ik\boldsymbol{z}\cdot(\cdot)} \boldsymbol{V}_{b}^{a} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \langle e^{-ik\boldsymbol{z}\cdot(\cdot)} \boldsymbol{V}_{b}^{a}, \boldsymbol{B}_{n'}^{m'} \rangle_{L_{t}^{2}(S^{2}, \mathbb{C}^{3})} \right).$$

$$(9.10)$$

Truncating the series in (9.10) and applying a quadrature rule on S^2 to evaluate the inner products (see, e.g., [2, Sec. 5.1]), we obtain a discrete approximation

$$\boldsymbol{T}_{B_{ij\ell}} := \begin{bmatrix} \langle T_{B_{ij\ell}} \boldsymbol{U}_n^m, \boldsymbol{U}_{n'}^{m'} \rangle_{L^2_t(S^2, \mathbb{C}^3)} & \langle T_{B_{ij\ell}} \boldsymbol{V}_n^m, \boldsymbol{U}_{n'}^{m'} \rangle_{L^2_t(S^2, \mathbb{C}^3)} \\ \langle T_{B_{ij\ell}} \boldsymbol{U}_n^m, \boldsymbol{V}_{n'}^{m'} \rangle_{L^2_t(S^2, \mathbb{C}^3)} & \langle T_{B_{ij\ell}} \boldsymbol{V}_n^m, \boldsymbol{V}_{n'}^{m'} \rangle_{L^2_t(S^2, \mathbb{C}^3)} \end{bmatrix} \in \mathbb{C}^{Q \times Q}$$
(9.11)

of $T_{B_{ij\ell}}$ for any $-J \leq i, j, \ell \leq J$. The results from [20] suggest to truncate the series in (9.10) at an index larger than $k|\mathbf{z}_{ij\ell}|$. In the following we use the same truncation index $N \gtrsim \sqrt{3}kR$ for \mathbf{F}_q and $T_{B_{ij\ell}}$ for any $-J \leq i, j, \ell \leq J$, and thus also the same Q = 2N(N+2).

To implement the criteria from Theorems 6.1 and 6.2 we compute for each grid point $z_{ij\ell} \in \Delta$ the eigenvalues $\lambda_1^{(ij\ell)}, \ldots, \lambda_Q^{(ij\ell)} \in \mathbb{R}$ of the self-adjoint matrix

$$\boldsymbol{A}_{B_{ij\ell}} := \operatorname{sign}(q)(\operatorname{Re}(\boldsymbol{F}_q) - \alpha \boldsymbol{T}_{B_{ij\ell}}) \in \mathbb{C}^{Q \times Q}, \qquad 1 \le i, j, \ell \le J.$$
(9.12)

For numerical stabilization, we discard those eigenvalues whose absolute values are smaller than some threshold. This number depends on the quality of the data. If there are good reasons to believe that $\mathbf{A}_{B_{ij\ell}}$ is known up to a perturbation of size $\delta > 0$ (with respect to the spectral norm), then we can only trust in those eigenvalues with magnitude larger than δ (see, e.g., [17, Thm. 7.2.2]). To obtain a reasonable estimate for δ , we use the magnitude of the non-unitary part of $\mathbf{S}_q := (\mathbf{I}_Q + (ik/(8\pi^2)\mathbf{F}_q), i.e.$ we take $\delta = \|\mathbf{S}_q^*\mathbf{S}_q - \mathbf{I}_Q\|_2$, since this quantity should be zero for exact data and be of the order of the data error, otherwise.

Assuming that the electric permittivity contrast q is either larger or smaller than zero a.e. in $\operatorname{supp}(q)$, and that the parameter $\alpha \in \mathbb{R}$ satisfies the conditions in part (a) of Theorems 6.1 or 6.2, respectively, we then simply count for each test ball $B_{ij\ell}$ the number of negative eigenvalues of $A_{B_{ij\ell}}$, and we define the *indicator function* $I_{\alpha} : \Delta \to \mathbb{N}$,

$$I_{\alpha}(z_{ij\ell}) = \#\{\lambda_n^{(ij\ell)} \mid \lambda_n^{(ij\ell)} < -\delta \,, \, 1 \le n \le N\} \,, \qquad 1 \le i, j, \ell \le J \,. \tag{9.13}$$

Theorems 6.1–6.2 suggest that I_{α} is larger on sampling points $z_{ij\ell} \in \Delta$ that are not contained in the support supp(q) of the scattering object than on sampling points $z_{ij\ell} \in \Delta$ that are contained in supp(q).

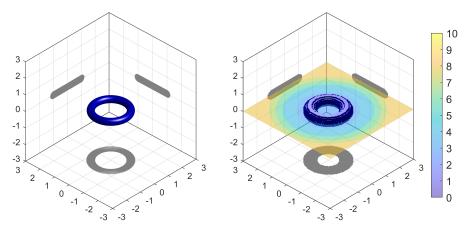


Figure 9.2: Visualization of the exact shape of the scattering object in Example 9.1 (left), and of isosurface $I_{20} = 2$ of the indicator function from (9.13) using simulated far field data without additional noise (right).

Example 9.1. We consider a scattering object D that has the shape of a torus as shown in Figure 9.2 (left). We use q = 0.5 for the contrast function (i.e., the relative electric permittivity is $\varepsilon_r = 2$), k = 1 for the wave number, and N = 5 for truncation index in the vector spherical harmonics expansions (9.7) and (9.10) (i.e., Q = 70 in (9.8), (9.11) and (9.12)). We simulate the far field matrix $\mathbf{F}_q \in \mathbb{C}^{Q \times Q}$ using the C++ boundary element library Bempp [43].

For the reconstructions we use the sampling grid \triangle from (9.9) with step size h = 0.05 in the region of interest $[-3,3]^3$, i.e., we have 161 grid points in each direction. In Figure 9.3 we show color coded plots of the indicator function I_{α} from (9.13) in the x_1, x_2 -plane, i.e., we plot the number of those eigenvalues of $A_{B_{ij\ell}}$ from (9.12) that are smaller than $-\delta$ for all grid points with vanishing third component. We use $\delta = 10^{-14}$ for the threshold parameter, and we examine six different values for α , namely $\alpha \in \{0.01, 0.1, 0.5, 1, 10, 20\}$. We observe that the values of I_{α} are smaller for grid points inside the scattering object than outside, and that this number increases the farther away a grid point is from the scattering object, as we would expect from Theorem 6.1. The condition $\alpha \leq q_{\min}$ in the second part of Theorem 6.1 is satisfied only for $\alpha \in \{0.01, 0.1, 0.5\}$. On the other hand the hole inside the cross-section of the torus becomes visible in these reconstruction when α is chosen sufficiently large. For $\alpha = 20$, we provide a three dimensional reconstruction in Figure 9.2. Inspecting the middle picture in the bottom row of Figure 9.3 suggests to plot the isosurface $I_{20} = 2$, which is shown in Figure 9.3 (right). The position and the shape of the torus are nicely reconstructed. We note that it was observed in [18] for the corresponding scalar scattering problem governed by the Helmholtz equation that the quality of the reconstructions of this monotonicity base scheme increases with increasing wave number also for smaller values of α .

To get an idea about the sensitivity of the reconstruction algorithm with respect to noise in the data, we redo this computation but add a complex-valued uniformly distributed additive error to the simulated far field data before starting the reconstruction procedure. The resulting reconstructions are shown in Figure 9.4 for two different noise levels. In these reconstructions the noise is only accounted for via the threshold parameter δ in (9.13): We use $\delta = 0.001$ for 0.1% noise and $\delta = 0.01$ for 1% noise. The results clearly get worse with increasing noise level, but they still contain useful information on the location and the shape of the scatterer.

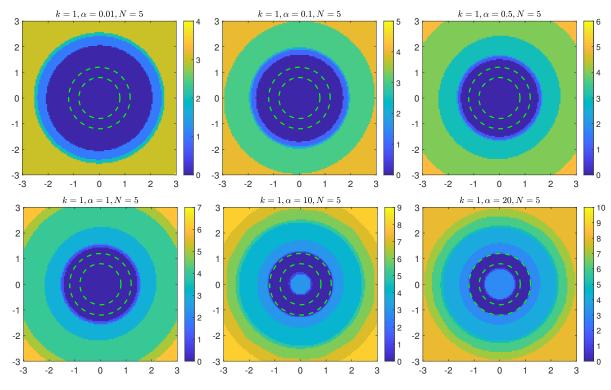


Figure 9.3: Visualization of the indicator function I_{α} for $\alpha \in \{0.01, 0.1, 0.5, 1, 10, 20\}$ in the x_1, x_2 -plane using simulated far field data without additional noise. The dashed lines show the exact boundaries of the cross-section of the scatterer.

Conclusions

In this work we have considered the inverse scattering problem to reconstruct the shape of a scattering object from far field observations of scattered electromagnetic waves.

We have established monotonicity based shape characterizations for inhomogeneous nonmagnetic compactly supported scattering objects. These shape characterizations can be translated into novel monotonicity tests to determine the support of unknown scattering objects from far field observations of scattered electromagnetic waves corresponding to infinitely many plane wave incident fields.

The techniques that we used to prove these results are closely related to other qualitative reconstruction methods like the linear sampling method or the factorization method. An advantage of our results is that they apply to indefinite scattering configurations, and that they also hold when the wave number is a transmission eigenvalues. However, our criteria are more elaborate to implement than traditional sampling methods, and in particular a stable numerical implementation of the monotonicity test for the indefinite case from Theorem 8.1 still requires further research efforts.

Acknowledgments

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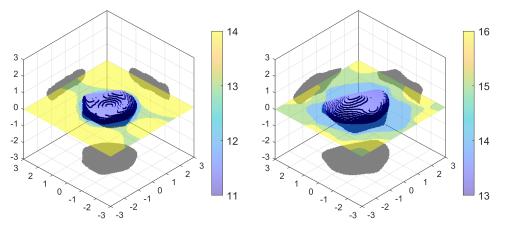


Figure 9.4: Visualization of the isosurfaces $I_{20} = 11$ (left) and $I_{20} = 13$ (right) of the indicator function from (9.13) using simulated far field data with 0.1% (left) and 1% (right) complex-valued uniformly distributed additive noise.

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