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Quantum Control with Spinor Bose-Einstein Condensates

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Quantum Control with Spinor Bose-Einstein Condensates

HILARY M. HURST

OPEN QUANTUM FRONTIER INSTITUTE WORKSHOP

COLORADO SCHOOL OF MINES

FEBRUARY 21, 2020

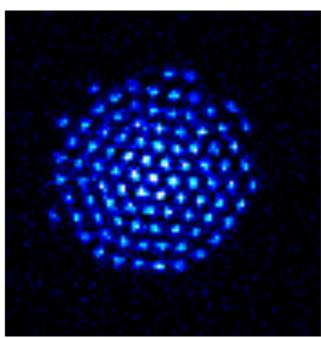
Quantum Simulation: Engineering the Quantum World

"...if you want to make a simulation of nature, you'd better make it quantum mechanical."

- Richard Feynman

'bottom up' approach:

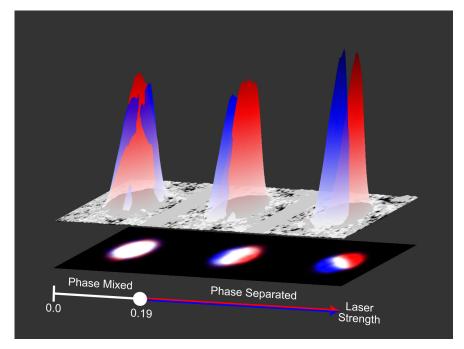
- designer quantum building blocks
- i.e. 'perfect' crystals trapped ions:



J. Bollinger, NIST

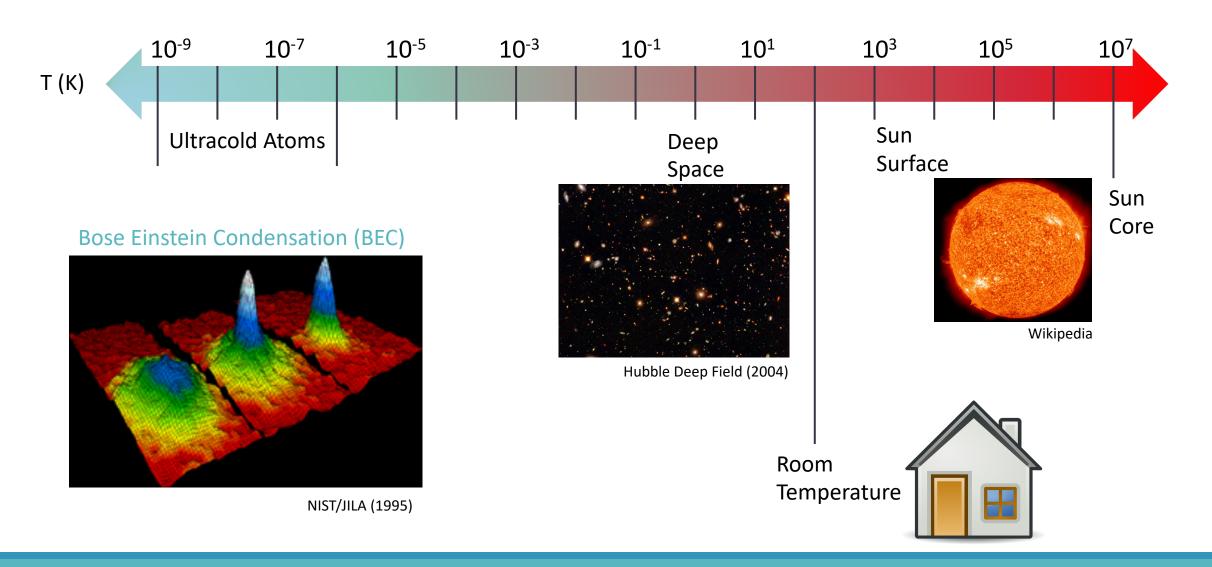
'top down' approach:

- engineering new dynamics via external fields
- i.e. coupling motional and spin states in quantum gases:



I. B. Spielman, NIST

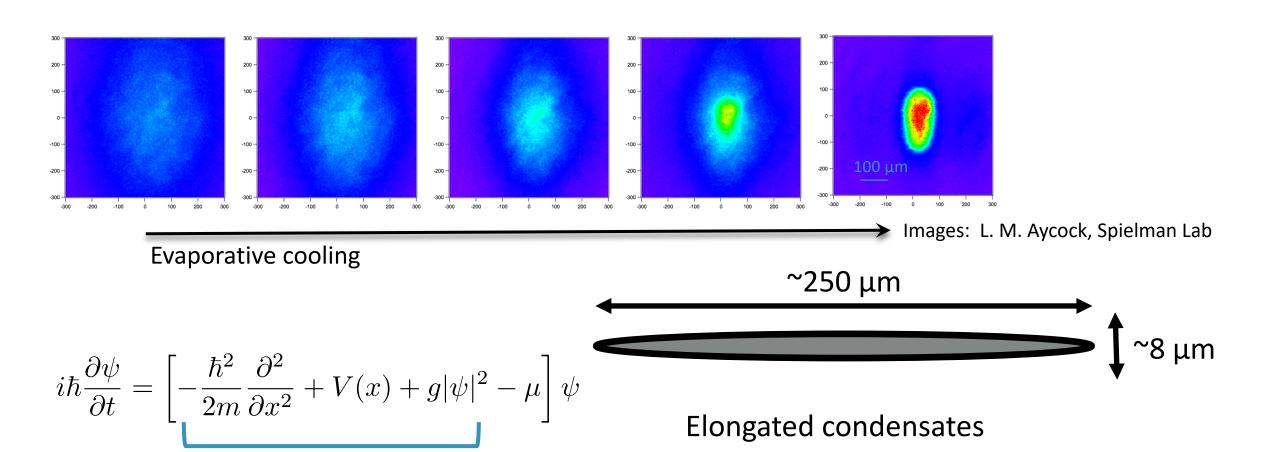
Our Platform: Ultracold Atoms (They are Really, Really Cold)



Our Platform II: Bose-Einstein Condensates

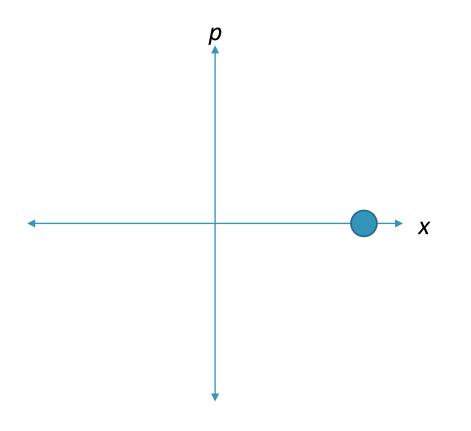
 \mathcal{H}

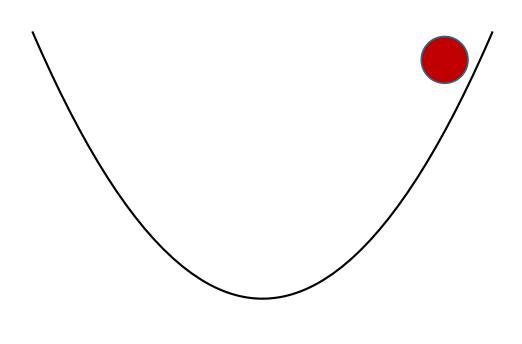
BEC 'Wavefunction' : $\psi(x,t)$



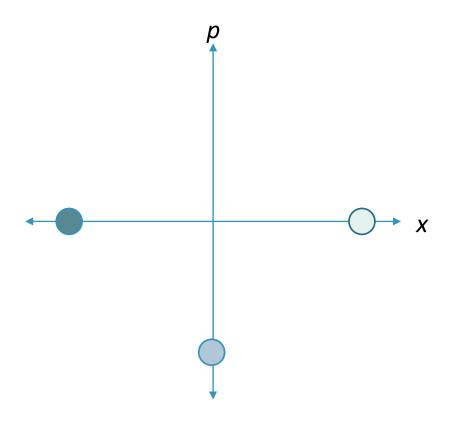
T ~ 10 nK

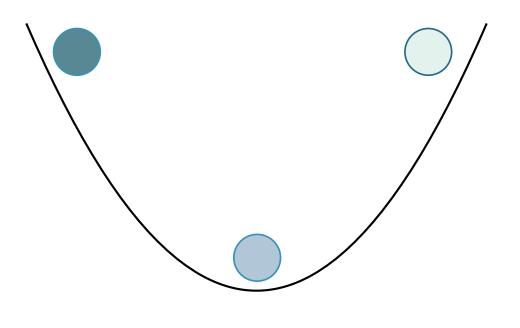
Measuring Quantum Objects: Phase Space





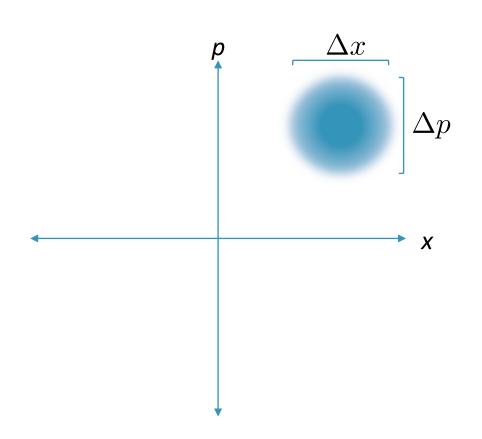
Measuring Quantum Objects: Phase Space





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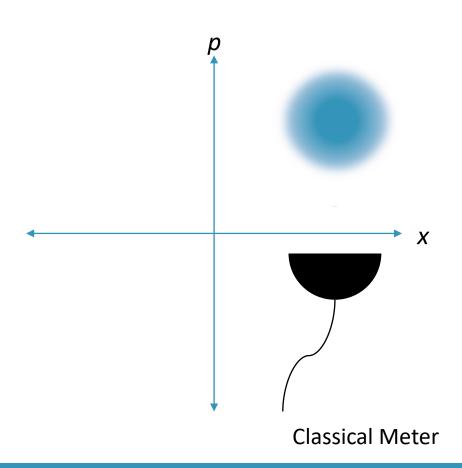
Weak Measurement: An Outline



$$\Delta x \Delta p \ge \frac{\hbar}{2}$$

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

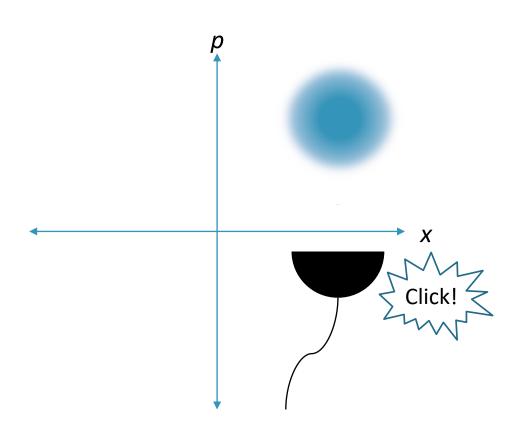
Projective Measurement



Before Measurement:

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

Projective Measurement



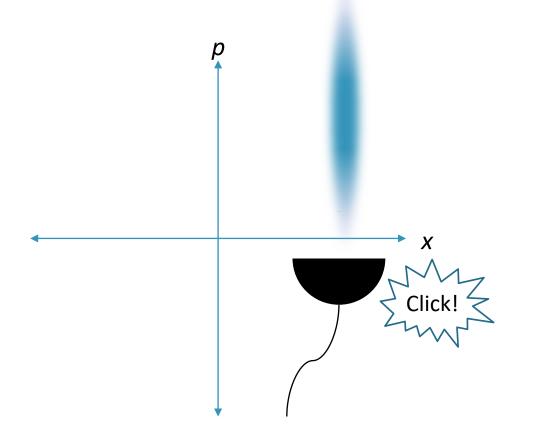
Before Measurement:

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

Measure Position:

$$\mathcal{M}_{|x} = \langle \psi | \hat{x} | \psi \rangle$$

Projective Measurement



Before Measurement:

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

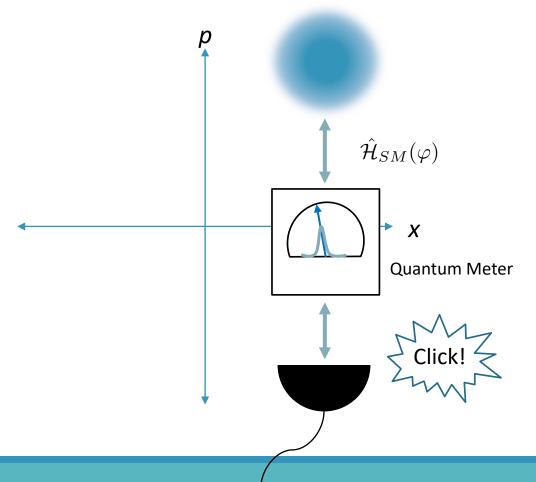
Measure Position:

$$\mathcal{M}_{|x} = \langle \psi | \hat{x} | \psi \rangle$$

After Measurement:

$$|\psi_{|x}\rangle = c_x |x\rangle \to |x\rangle$$

Weak Measurement



Before Measurement:

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

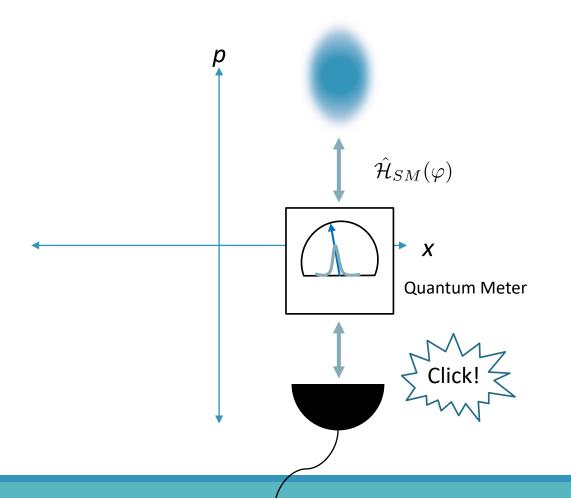
Measure Position:

Random noise

$$\mathcal{M}_{|x} = \langle \psi | \hat{x} | \psi \rangle + \frac{m}{\varphi}$$

'measurement strength' <1

Weak Measurement



Before Measurement:

$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

Measure Position:

Random noise

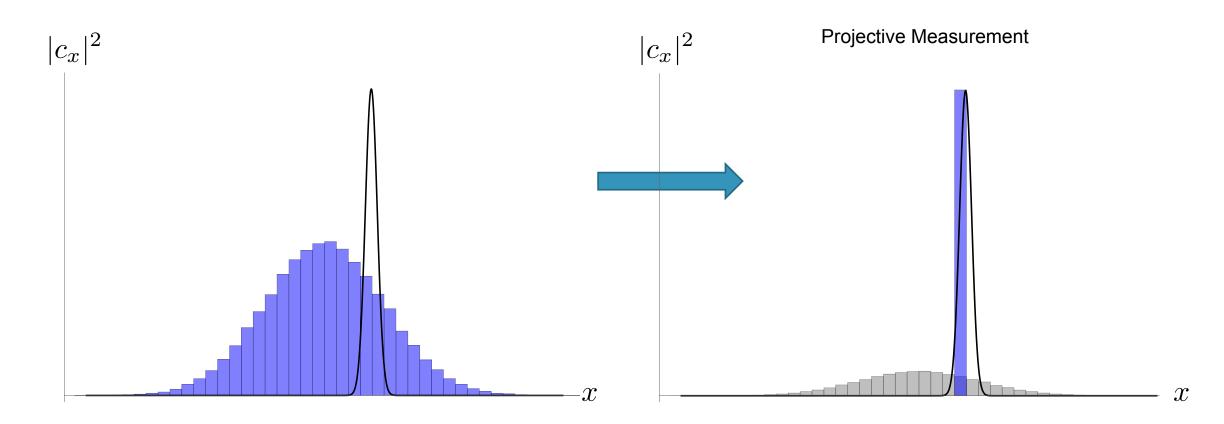
$$\mathcal{M}_{|x} = \langle \psi | \hat{x} | \psi \rangle + \frac{m}{\varphi}$$

After Measurement:

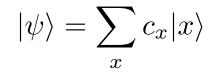
$$|\psi_{|x}
angle = \sum_x \tilde{c}_x |x
angle$$
 'measurement strength' < 1

Quantum Backaction

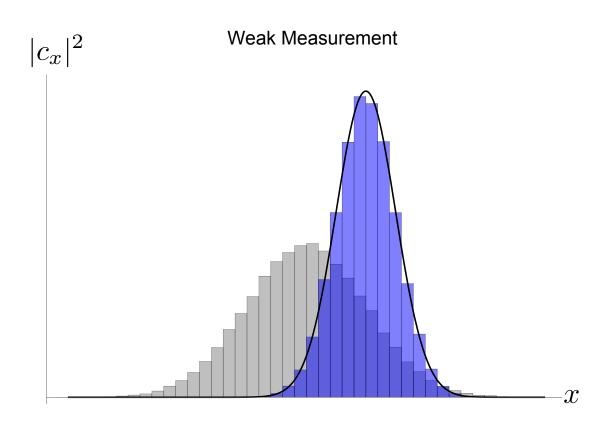
$$|\psi\rangle = \sum_{x} c_x |x\rangle$$

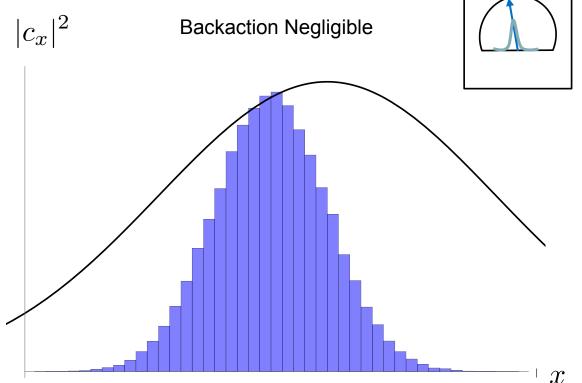


Quantum Backaction

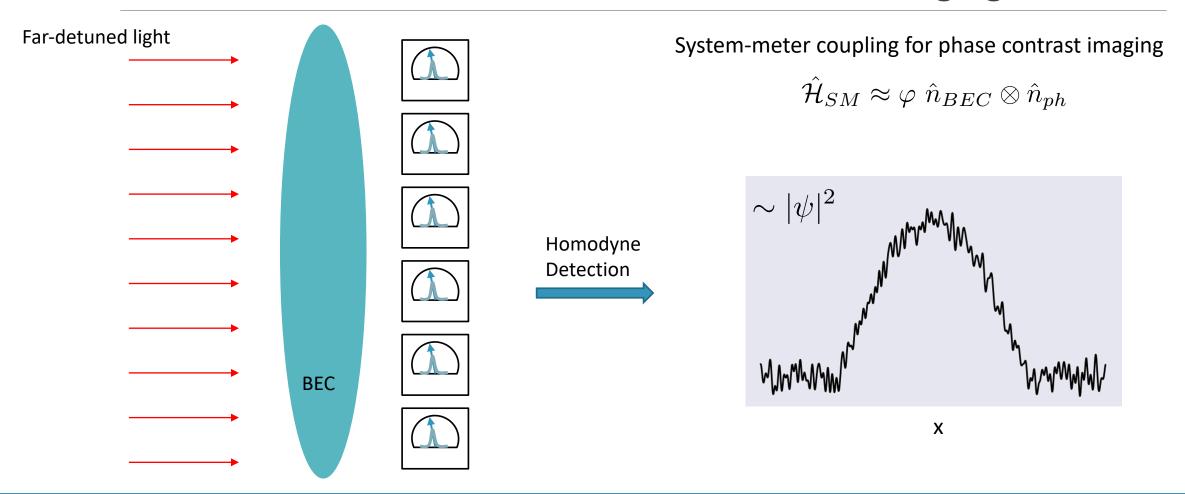








Weak Measurement For BEC: Phase-Contrast Imaging

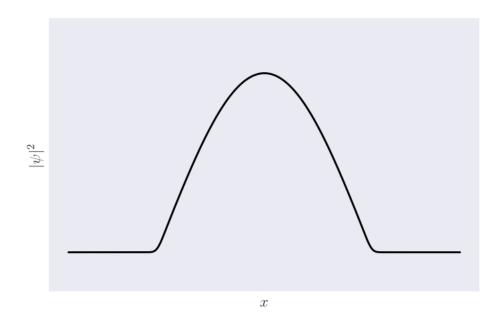


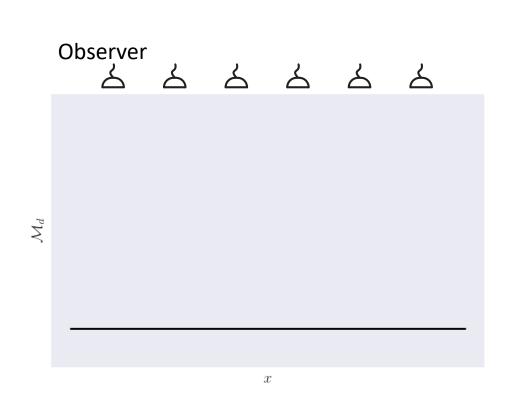
Example: Measuring BEC Density

$$d\psi_H = -i \left[\mathcal{H} - \mu \right] \psi dt$$
$$d\psi_M = \left[-\frac{\varphi^2}{4} dt + \varphi m(x) \sqrt{dt} \right] \psi$$

Stochastic Evolution Equation (@ mean-field level)

System Evolution

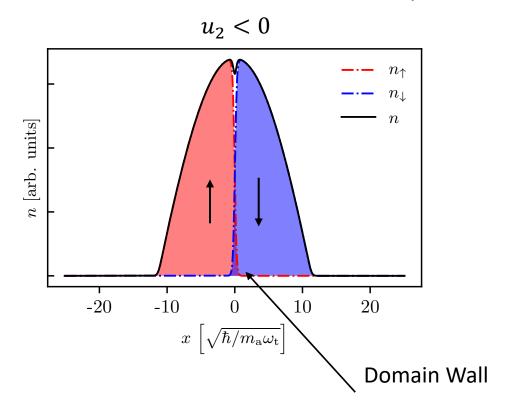


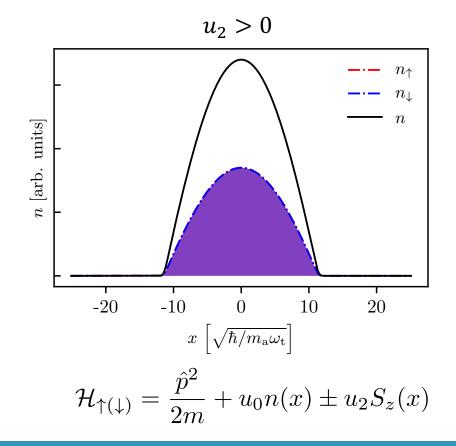


Spin-1/2 BECs

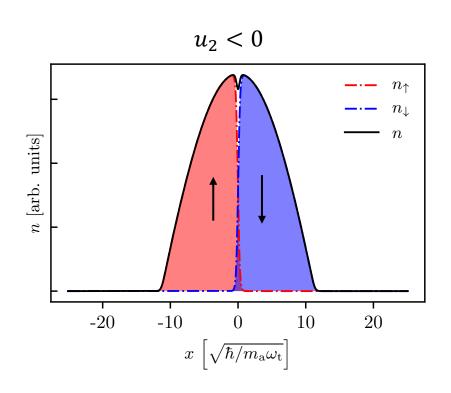
$$E_{\rm int} \sim u_2 \int dx \ [n_{\uparrow}(x) - n_{\downarrow}(x)]^2 = u_2 \int dx \ S_z^2(x)$$

Spinor Bose-Einstein condensates: multiple internal states

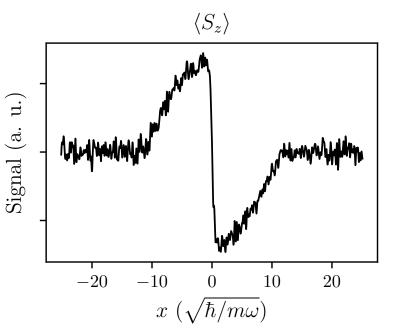




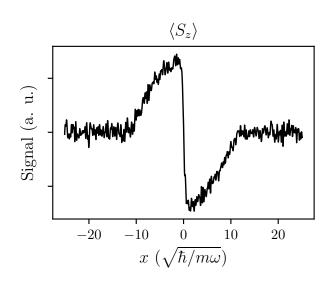
Weak Measurement For Domain Walls

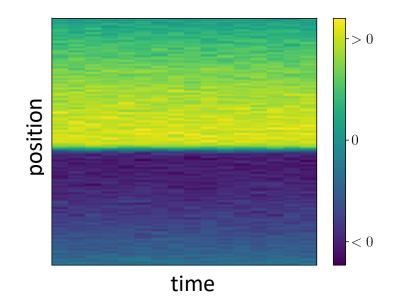


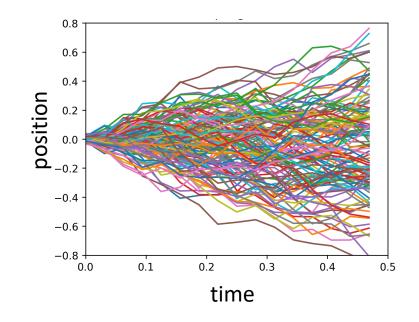
$$\mathcal{M}_z(x) = \langle \hat{S}_z(x) \rangle + \frac{m(x)}{\varphi}$$



Real-Time Picture of Domain Wall Dynamics

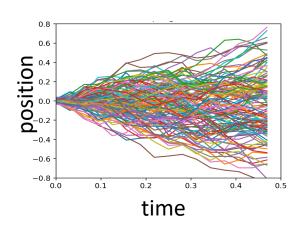


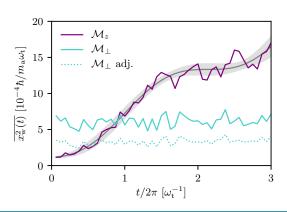




Quantifying Measurement Backaction

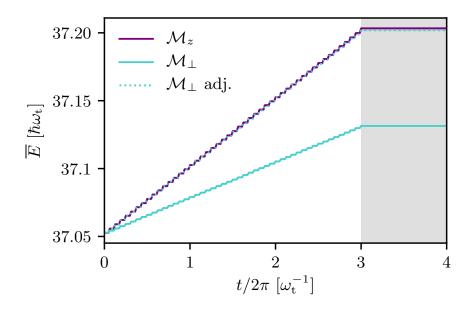
Domain Wall Diffusion





Heating

- Measurement backaction adds energy to the system
- Measurement observable affects heating



Feedback for Hamiltonian Engineering

My Claim: Using feedback signals derived from weak measurement, we can alter the effective Hamiltonian for the system dynamics

$$\mathcal{H} = \frac{\hat{p}^2}{2m} + u_0 n(x) + u_2 S_z(x) \hat{\tau}^z + V[\mathcal{M}(x)] \qquad V[\mathcal{M}(x)] = g_2 \mathcal{M}_z(x) \hat{\tau}^z$$

$$d\psi_{H'} = -i \left[\mathcal{H}_{\text{eff}} - \mu \right] \psi dt$$

$$d\psi_{M'} = \left[-\frac{\varphi^2}{4} dt + \varphi w(x, \varphi) \sqrt{dt} \right] \psi$$

$$\mathcal{H}_{\text{eff}} \approx \frac{\hat{p}^2}{2m} + u_0 n(x) + \frac{u_2 + g_2}{2} S_z(x) \hat{\tau}^z$$

u2 and g2 both affect the steady-state condensate phase

Time-Dependent Feedback

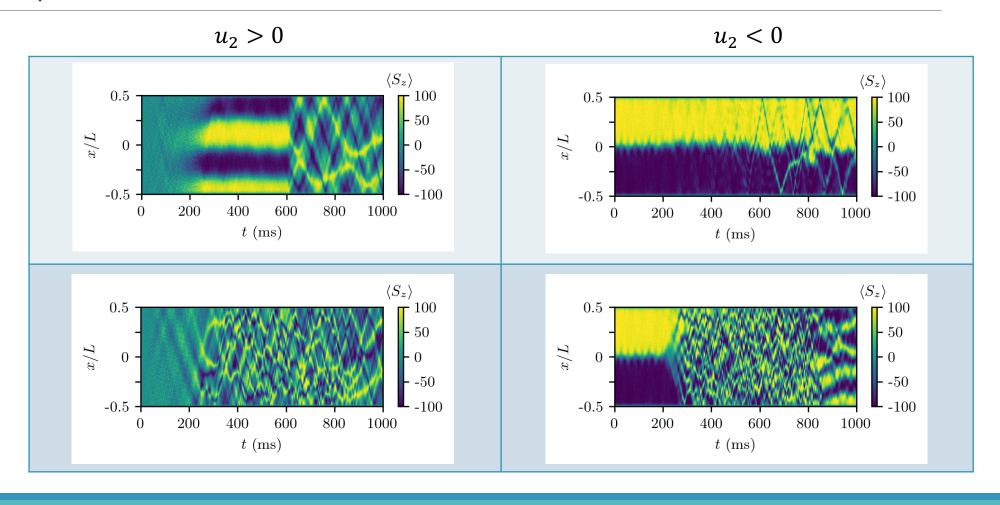
$$\mathcal{H}_{\text{eff}} \approx \frac{\hat{p}^2}{2m} + u_0 n(x) + (u_2 + g_2) S_z(x) \hat{\tau}^z$$

Protocol 1:

g2 < 0 on from 200 to 600 ms

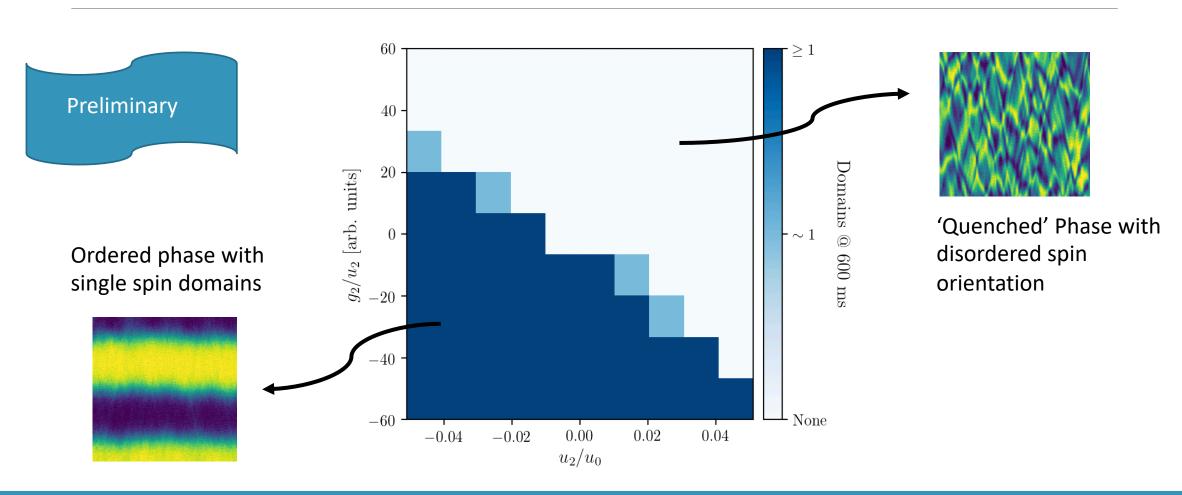
Protocol 2:

g2 > 0 on from 200 to 600 ms



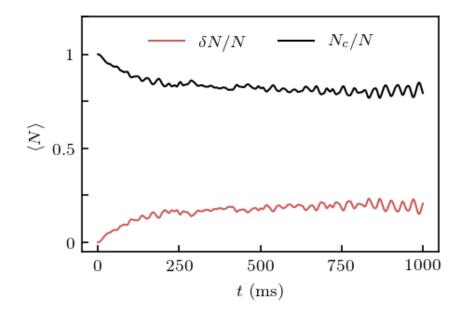
Steady-State Phase Diagram

$$\mathcal{H}_{\text{eff}} \approx \frac{\hat{p}^2}{2m} + u_0 n(x) + (u_2 + g_2) S_z(x) \hat{\tau}^z$$

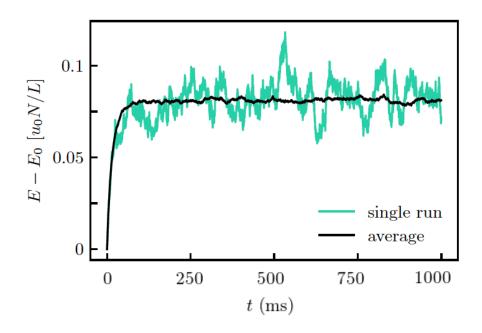


Feedback Cooling

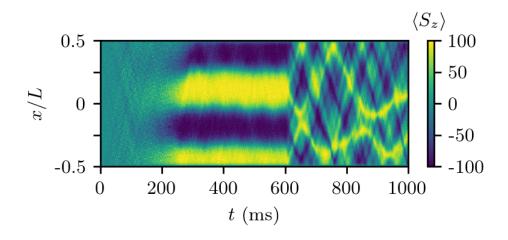
Condensate Fraction Stabilizes over ~ 200 ms



Energy Stabilizes over ~50 ms

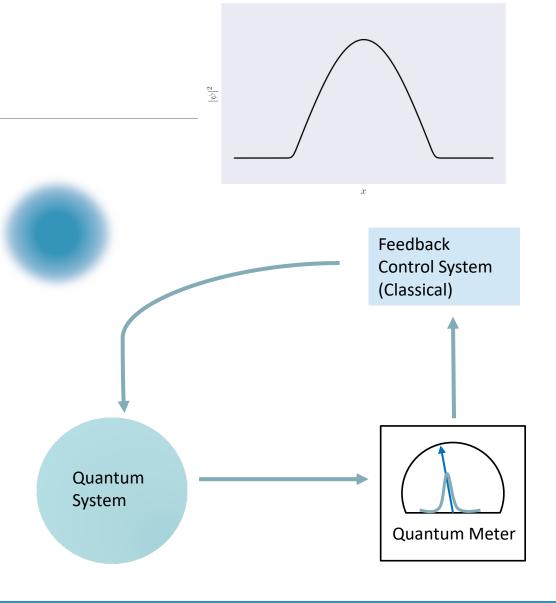


A Pathway to Quantum Control



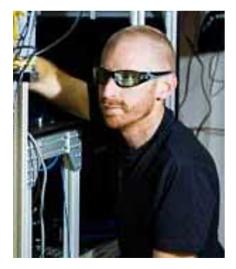
Weak Measurement for Domain Walls *Physical Review A* **99**, 053612 (2019)

Feedback-Induced Phase Transitions in Spinor BEC - posting soon!



Thanks to...





Ian Spielman (PI) UMD, JQI/NIST

