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MATHEMATICAL MODELS FOR INFORMATION PROCESSING SYSTEMS

A THESIS

Presented to

The Faculty of the Graduate Division

by

George Henry Brooks

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FOR
INFORMATION PROCESSING SYSTEMS

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SUMMARY

The principal objective of this research is to develop mathematical models by means of which information processing systems can be described and which can be manipulated to afford a better means of analysis and synthesis of these systems. A secondary objective is to develop these models in such a manner that they are readily adaptable for computation by means of a digital computer and the associated peripheral equipment, so that this principal processor within the information processing system may be of assistance in the analysis and development of the system itself. These objectives were attained by means of the following specific developments:

1. A basic model was developed which is capable of duplicating the results of previous investigators, but with substantial improvements in ease of computation and in the amount of information made available relative to the system under study.

2. Two improved models were developed which are shown to be more adequate representations of an information processing system in that they recognize differences in types of data and the transitions which data undergo during the processing steps. These data types and data transitions were ignored in the prior work and in the basic model.

3. Algorithms were developed for conditioning the study data gathered by an analyst for computation using the two improved models.

4. Detailed machine procedures and computer programs were written for the implementation of the computational algorithms on equipment

of the sort commonly found in a typical manufacturing, commercial, or institutional situation.

The usual approach to analysis and design of information processing systems can be characterized as being essentially intuitional. Extensive use is made, in practice, of conceptual aids in the nature of flow charts and block diagrams, and much of the system description is done in prose form. The relations which exist between the system inputs and the outputs is frequently only vaguely defined.

Prior investigators Lieberman (18) and Homer (14) proposed the representation of the simple relations between systems elements in matrix form, and manipulation of these relations by multiplication of the matrices (Lieberman) or a series of column operations (Homer). In each case, the result was a solution matrix which purported to represent the compound relations of the system, and which gave a measure of the redundancy of data within the system. In the case of Lieberman's multiplication technique, data input was permitted at only the lowest level of the system hierarchy, and the multiplication was tedious and time consuming. In the case of Homer's column operation technique, data input was permitted at intermediate system levels, but a great deal of information relative to the intermediate system relations was lost in the computation, and the computation was lengthy and not amenable to computer use.

The basic model developed in the current research is essentially a matrix inversion of a triangular matrix. It is patterned after a similar model first advanced by Vazsonyi (30) and later improved by Giffler (9) in the context of materials assembly systems. In this

model the simple system relations which Lieberman displayed in a series of matrices and which Homer displayed in a single non-square matrix are displayed in a square, triangularized matrix, S . It is then shown that a solution matrix S^* is the inverse of the matrix $(I - S)$, and that this solution matrix S^* contains the solution obtained by both Lieberman and Homer. In addition, all of the intermediate results, some of which are never obtained by the Lieberman model, and all of which are lost by the Homer model, are retained in the solution matrix of this model. In addition, because of the triangularity of the S and S^* matrices, the inversion required is easier to compute than is either of the prior models.

The basic nature of information systems is then further explored. It is established that three basic types of data exist in such a system. These three types are distinguished as identification data, such as department numbers; quantitative data which arise basically from a count or measurement; and existence data which primarily indicate either that some activity has taken place or the status of some activity.

It is further established that the essential purpose of an information processing system is to change the form of the input data by changing it from quantitative to existence type data, by summarization, or by computation of some nature. Nine categories of such data transitions are recognized and discussed.

It is developed that a model for an information processing system must recognize these three data types and the transitions which the data undergo. In order to implement this recognition, three basic types of system relations are defined, instead of the single type of relation implied in the prior work and in the basic model.

These three systems relations are denoted as prime relations, concomitant relations, and deletion relations. A prime relation is that relation which exists when an element of a system is required for the preparation of a higher level element in a system. A concomitant relation arises in conjunction with the transition of data from quantitative to existence type, or in conjunction with a computation. A deletion relation exists when a data element is brought to some level of a system because it is a part of a record which contains other usable data, but where the data element itself is not required at that level.

Based on the recognition of the three types of system relation, two improved models are developed. In one of these, only prime and concomitant relations are used, while the other uses all three types of relation. The first results in a solution matrix wherein all of the lower level data elements which are required for the preparation of a higher level report are indicated, whether or not the lower level data actually appear on the higher level report. This matrix, S^* , is referred to as comprising a "composed of" type of analysis. The second model results in a solution matrix S'^* , which shows for a given higher level report only those lower level elements which actually appear on the report. This is referred to as a "contained in" type of analysis.

While the prime relation uses regular numerals as quantifiers in the S matrix representing the simple system relations, it was necessary to define special quantifiers for both concomitant and deletion relations. The concomitant quantifier gives rise to a special multiplication-like operator, while the deletion relation gives rise to a

logical, rather than arithmetic, operator. The combination of prime and concomitant quantifiers in the matrices representing the information system complicated the inverse relationship shown for the basic model, and it was necessary to prove a theorem relative to the associativity of multiplication of matrices containing both prime and concomitant quantifiers. It was then possible to show that the S^* matrix of the first refined model was indeed the inverse of the $(I - S)$ matrix, as in the basic model.

The deletion relation quantifier is a logical operator, and it is shown that the inverse relationship no longer holds for the solution matrix S'^* and the matrix $(I - S')$ of the second refined model. It is shown, however, that they differ only by two logical operations occurring in the computation as a result of the deletion function.

Since both models depend on the triangular nature of the matrices for their computational base, a method of triangularization of the indices is developed. This technique permits the analyst to use any arbitrary designation for the systems elements, and does not require him to be concerned with system levels or the required triangularity.

In practice, the models presented would require the use of a digital computer and associated equipment for computation, so the algorithms have been programmed for a typical computer. In addition, a method has been developed and programmed to establish the amount of computer memory required for a given specific program and system.

CHAPTER I

INTRODUCTION

Purpose

The purpose of this research is to attempt to bring to the field of business information processing the concise notation, non-ambiguous description, and computational rigor of mathematics and mathematical models. It is hoped that the techniques of systems analysis and design developed during the course of this research will supplement, at least to an extent, the intuitional, non-quantitative approaches now used for information systems analysis and synthesis, and will result in economies both in systems development and in routine systems operation.

Background of the General Problem

The processing of information is a problem which is not new, but one which has become much more important within the past few years. The development of ancient languages, number systems, and rudimentary mathematics can be traced to the need of the ancients to compute and record taxes. The Bible abounds in references to taxation and census-taking, both of which imply an accompanying task of information processing. The making of decisions implies prior data processing of at least an elementary sort, as decisions are not possible without knowledge, however incomplete, of the possible outcomes of the alternative courses of action.

In modern context, information processing has come to imply mechanical, electro-mechanical and electronic processing of data. This concept has its beginning in the mid-1880's, when Dr. Herman Hollerith developed a mechanical method of processing census data, using the "unit card" principle now so familiar. The first set of equipment was installed in the Department of Health in Baltimore, Maryland for the processing of public health data in 1889. The Bureau of Census had equipment in time to process the data of the 1890 census. Dr. Hollerith later founded the Tabulating Machine Company, from which later emerged the International Business Machines Corporation (26, Schmidt, R. N., and Meyers, W. E.).

During the next several years, until the early 1950's, most of the development in the field was in refining and speeding up the equipment developed earlier. The basic concept remained unchanged: information relative to a single transaction was transcribed to a punched unit record card, and this card was then used for the updating of records and the preparation of reports. All processing was done in "batches," due to the limitations of flexibility of the equipment.

In the scientific community, strong interest was manifested in this equipment as a means for performing scientific calculations. However, the limitations of the equipment were such that many persons, starting in the 1920's, sought other, more sophisticated, equipment for performing scientific computation. Out of these early efforts emerged, in the late 1930's, some crude computers. Under the impetus of World War II, these crude computers were greatly refined, and then played a significant role in the development of the atomic bomb and other mili-

tary developments.

One of the computers developed during the war was the Eniac, the development of Dr. John W. Mauchly and J. Presper Eckert at the Moore School of Engineering at the University of Pennsylvania. This computer was the world's first all-electronic, high-speed, large scale computer. Eckert and Mauchly later developed the Edvac, which was the first stored program computer, and which was the forerunner of Univac, the first commercial electronic computer. The first Univac I was delivered to the Census Bureau in 1951.

The introduction of the Univac I was followed quite rapidly by the entry into the field of several computers from many manufacturers, notably IBM. It is significant to note that virtually all of the computers introduced in the mid-1950's, including the popular IBM 650, were designed essentially for scientific computation, and were used for business information processing only by virtue of clever programming and sacrifice of efficiency of internal operation. Despite this handicap, the advent of stored program digital computers helped to cause what has come to be recognized as a revolution not only in the processing of information, but in the basic philosophy of operating a business enterprise as well.

Other factors beyond the development of the digital computer contributed to this revolution. One of the most important but perhaps the least recognized is the work done in the early 1950's by the United States Steel Company (1, American Management Association). This work was undertaken to establish the feasibility of a "Common Language" with a view toward extensive automation of clerical operations using the

then existing punch card equipment. Common language was defined as (2, Moore Business Forms, Inc.):

A recording medium that (a) comprehends the 26 letters of the alphabet, the 10 decimal digits, and a minimum of special characters and functions, and (b) has the ability to mechanize the transfer of raw data directly between the office and communications machines manufactured by different suppliers.

This group did not entirely succeed in their goal of establishing a single common language, but rather established two: punched cards and punched paper tape. To these have been added more recently magnetic tape and direct processor to processor communication. However, the group did accomplish two other things which have had a profound effect on the development of information processing. The first of these was that they did succeed in interesting manufacturers of all sorts of data processing equipment--adding machines, bookkeeping machines, typewriters, calculating machines, Addressograph machines, etc.--in adding either tape or card input and output devices to the equipment to permit the creation of data in mechanized form as a by-product of the necessary operation, and to permit the communication of data between equipment without human intervention. Second, the group established the basic principles of Integrated Data Processing.

The importance of the concepts of Integrated Data Processing to the revolution in information processing cannot be overstated (5, Ellis, H.).

When I. D. P. was first introduced, many companies and governmental agencies began to exploit successfully this systems concept, in separate segments of their businesses. While this was going on, some of the same or different groups within companies, were doing considerable work, in getting on-stream their new high speed digital computers.

Many of these early starters realized that the integrated systems approach would be the most effective method to use, to get the most out of their computers--some did not. But most seemed to have the same goal in mind, and that was--that much mechanized data processing should be employed in order to get more action and value out of the results of data origination, transmission, processing, and data usage. In other words, improve the aids to decision making, by employing the least data manipulation, and retrieving the most value from existing and dynamic information.

There was, however, some unjustified optimism among those companies that did not use the integrated approach as a part of their data processing systems. Their systems were too machine oriented and not sufficiently systems concept oriented. What happened seemed to be this: That, as various mechanized systems (computerized or not) began to take hold, independently, in several segments of a business, some segments found their system to become stymied sooner or later and other segments discovered expensive problems to be overcome in data manipulation; also to find later, that their companies' combined systems were not sufficiently integrated and compatible, and would run somewhat short on expected accomplishment.

Another important contributing factor to the revolution in information processing has been, of course, the emergence of a discipline called variously systems engineering, operations research, applied mathematics and statistics, management science, etc., depending on the point of view of the individual describing the discipline. Whatever the title applied, this discipline has as its principle features the use of the scientific method and mathematical techniques for the purpose of optimizing the overall operation of the concern. The reason that this factor has been so important to information processing is that optimization in an enterprise concerns itself directly with the decision processes of the enterprise. In turn, the decision processes are entirely dependent on information processing, so that attention has been drawn automatically to this all-important facet of the enterprise. It might be said that information is the common thread running through-

out the fabric of an organization.

Since the development of information processing technology has been so rapid in the past few years as to be termed "revolutionary," it is not surprising that one fails to find a unified body of either theory or practice in the field. Much of the development both in individual companies and at large has been accomplished by "trial-and-error" and "brute-strength-and-awkwardness" approaches. Many computer installations have been made without adequate prior justification. Individual companies have used specific equipment far beyond the design expectations of the manufacturer. Since the first computers were designed as scientific computers, all of the early installations for information processing were basically make-shift in nature, and only the great speed differential between computers and electro-mechanical equipment and the ingenuity of the programmers made them relatively successful.

In discussion of the present state of the art of information processing, it is helpful to distinguish between "exterior systems" and "interior systems." The exterior system embraces the entire operation under consideration--the set of decisions to be made routinely to control the operation, the set of input data to be processed in order that an optimal decision may ultimately be made, the required data origination, data transmission, data processing, report structure, and provision for data storage and subsequent retrieval, and the set of decision functions which will be used in conjunction with the processed data in order to arrive at specified decisions.

The interior system refers to the details of machine programming. It embraces such factors as card and record format, report format, operating rules, and most importantly, equipment programming itself. It concerns itself primarily with the data processing portion of the exterior system, but is also partially involved with data origination, data transmission, and data storage and retrieval insofar as the details of programming are involved.

Because of the complexity of the task of machine programming, the interior systems have had more attention in the literature and in practice. There are many books devoted to this aspect, as well as several periodicals, all of which are "hardware" or interior systems oriented. Relatively little has been written with regard to the design of the total, or exterior, system.

The general approach to exterior systems design at the present state of development is an intuitional one. Much of the information necessary for the design of the system is obtained by means of interviews with a large number of the working personnel of the organization, only a few of whom have any real qualification for giving pertinent answers. Too often, the systems engineer is forced to settle for a statement of what information management wants, rather than what management needs.

Almost the sole device for systems analysis and description is the graphical flow chart, accompanied by written or tabulated descriptive information. Many of these charting techniques have been dignified by a copyrighted name (19, National Cash Register Company)(6, Evans, O. Y.), but they are essentially similar and provide at best a systematic approach. There is no provision for quantifying data, nor

for manipulation with a view to optimization.

In interior systems design, the flow chart is also used extensively, probably more so than for exterior systems. The complexity of computer programming has also forced the development, by both equipment manufacturers and users, of compilers--computer routines which will accept pseudo-English, problem-oriented instructions and convert them into machine language programs. Technical compilers were developed first, and have been available for some years; commercial or business compilers, due to greater differences in terminology, have only been made available quite recently.

The existence of compilers does not alter the basic fact, however, that business problems are largely uniquely programmed for each specific problem and each specific installation. The common payroll, which has been highly refined over the years, is seldom programmed identically, even in plants of the same division of a company. Similarly, "canned" or library programs, such as are widely available for technical problems, are not widely used in the information processing field, for the primary reason that the generality which exists between problems and installations has either not been perceived or has not been characterized. A few library programs are available; IBM for example offers MOS (Management Operating Systems) and PAL (Programmed Applications Library) programs to users of certain of their equipment, but these programs usually need extensive modification for use in a given installation.

Importance of the Problem

This lack of adequate means of systems analysis and design for both interior and exterior systems is a serious one. The penalty for this lack is essentially an economic one, but one that is difficult or impossible to assess. These economic penalties arise in the following basic ways:

1. The inability to rigorously characterize the exterior system results in a failure to optimize the total system design. At best, the design is sub-optimized by parts. At worst only a feasible system is designed, with little real thought given to optimality. To the extent that the system is less than optimally designed, the enterprise pays a corresponding economic penalty in terms of less than optimal return on investment.

2. Systems development using these inadequate techniques is costly. The interview technique is time consuming, both of systems engineering and operating personnel's time. The intuitional approach results in wasteful meetings, discussions, and inefficient use of facilities and manpower. Graphic representations of systems are tedious, time-consuming, and costly to prepare. Frequently several man-years of effort are devoted to charting the existing system before any creative work even begins.

3. In interior systems design, the two principal penalties are the cost of programming personnel, and the cost of operating either a larger computer than is needed or of using a smaller computer for more shifts than are really necessary. The philosophy of the development of compilers was to trade some of the speed of the computer for some of

the effort of programming. That is, it is much quicker and easier to program with the use of a compiler, so that fewer and perhaps less highly trained programmers can be used. However, machine time is used to compile the program, and, more importantly, the resulting program is not as efficient in the use of machine time as a carefully written program in machine language.

It should be noted that this latter factor is much less important in scientific computation than in information processing. In scientific programming, programs are usually used at most several times until the problem leading to the program is solved, and may never be used again by a given installation. The whole emphasis is in permitting the scientist or engineer to communicate with the computer in a language as near like the language normally used by the scientist as possible, and with minimum knowledge of computers and computer technology on the part of the scientist.

In information processing, the programs are used repetitively, sometimes several times a day, for at least several months and frequently several years. Any inefficiency in the program can raise the computation time, and therefore the cost, by a large amount through this frequent use. In the early days of programming when computers were severely limited in speed and capacity, a great deal of work was done in "optimizing" of programs for efficient running. With the advent of large memories and faster internal computing speeds, the immediate necessity of optimization of programs was lessened, and compilers became possible and popular. However, the fact that the penalty is less apparent has not diminished its cost; it has only permitted a trade-off for program-

ming time. The penalty is a very real one, and is one which is too frequently overlooked.

In view of these economic penalties, it seems apparent that there is a real need for development of more rigorous and efficient means of systems analysis and design, for both internal and external systems.

The Specific Problem

The specific problem which will be attacked in this research relates to the methods used for description and analysis of existing or proposed information systems. As previously noted, the methods now in prevalent use are essentially qualitative. Description is usually done in either prose or graphic form, and any manipulation of the elements of the system is done on an essentially intuitive basis.

The models which will be presented will permit description on a quantitative basis, and will eliminate the necessity for prose description and the drawing of flow diagrams in most cases. Furthermore, the models will furnish information to the analyst relative to the areas within a given system which require study, and will furnish a basis for system design improvements by simulating the effect of any proposed changes.

CHAPTER II

LITERATURE SURVEY

Introduction

Despite the popularity of the subject of computers and data processing, the literature relative to quantitative or even systematic approaches to systems analysis and synthesis is remarkably sparse. Certainly much has been written in the broad field of information processing, but the vast majority of the material is either directed toward specific hardware or is narrative of a specific installed system for a specific enterprise.

Compilers

The greatest quantity of material to be found concerns itself with the subject of compilers. Under the stimulus of the U. S. Department of Defense, a group composed of representatives of the several computer manufacturers and governmental and industrial users was formed in 1959 for the purpose of producing "an English-like programming language which can be used with many different types of data processing systems" (8, International Business Machines Corp.). This group is known as the CODASYL group, where CODASYL is the acronym for Conference On Data Systems Languages. The principal output of this group to date is a language called COBOL (Common Business Oriented Language). The general requirement now is that any computer furnished for government use be accompanied by a COBOL compiler which will accept a certain re-

quired set of pseudo-English statements by means of which business computation programs can be written and presumably run on the computer of any manufacturer. In addition to the required set of language, the manufacturer is free to implement further elective language to exploit the unique features of his equipment.

On the surface, COBOL appears to be a simple language. For example, very complex computations can be written in English-like sentences such as the following:

```
SUBTRACT DEDUCTIONS FROM GROSS GIVING NET.
```

```
PERFORM TAX-CALCULATION.
```

```
IF STOCK IS LESS THAN ORDER-POINT PERFORM REORDER-ROUTINE.
```

```
WRITE MONTHLY-STATEMENT.
```

This simplicity, together with the promise that a program written for one machine can be used on another machine, even of another manufacture, would seem to be very desirable. However, COBOL is not as simple as it appears to be, and the literature indicates that COBOL leaves much to be desired. Indeed, some authorities have serious reservations about the entire compiler approach.

In a particularly critical article Grosch (12) states:

One major agreement, for instance, is on the original concept of commonality: American and British, commercial and scientific, manufacturer and user, large machine owner and small, all agree that magic languages do not--repeat, not--make it possible to transfer work from one machine to another.

On the question of economics many voices are raised: Patrick in the opening sentences at Rand; Gruenberger and Gordon later; Paine and Glennie in the Northampton College (BCS) discussions. All point to the hidden costs of the magic language: long compile times, repeated re-compilation during debugging, longer running times, and--surprise, surprise!--higher prices on the machines to cover the manufacturers' software investment.

Shaw (27) tends to agree with the foregoing comments pointing out the deficiencies of programming languages:

Another reason for the existence of an overwhelming variety of programming languages is the fact that most of these languages are not machine independent. Even the ones that claim to be are not really. Thus, the motivation toward a standard notation for those areas that could be machine independent is considerably weakened by the argument, "If the language is going to be different anyway, why not make it lots different?"

Shaw also claims that the machine-independent languages are in fact harmful:

This proliferation of "machine-independent" programming languages has two well-known and pernicious effects: it inhibits the communication of information processing procedures between people and computers both, and what's worse, it distracts attention and effort from that which is to be communicated--namely, procedures for solving real, worthwhile problems. Interestingly enough, these two effects are exactly those which each individual language is supposed to ameliorate. In conjunction, therefore, these languages tend to defeat their own purposes, with the result that the computing industry is, today, suffering from too much of a good thing.

In another article discussing both scientific and commercial compilers, Orchard-Hays (22) summarizes the feelings of several of the writers when he states:

However, many feel COBOL is overly elaborate and does not deal with the real problems of data processing.

He also makes the point that COBOL, in spite of its supposed generality, has over 30 versions now published. In another analysis of COBOL (and ALGOL), Cantrell (4) indicates many deficiencies:

The current COBOL and ALGOL families of languages are very elaborate and sophisticated languages. They are very general . . . This generality is accompanied by a profusion of rules and regulations. . . . As a result these languages are considerably harder to learn to use effectively than more simple languages.

. . . COBOL Procedures statements are relatively easy to read but the reader has to be well educated to understand the Data Description statements.

The English language design of COBOL makes it a verbose language. . . . The programmer has been relieved of machine details only to be faced with the problems of spelling words correctly and learning the exact meanings of some 256 "key words" in a new vocabulary. Often each word has several different meanings depending on its context. . . . This is not English but "pseudo-English" with its own specific grammar.

. . . But our newer languages, such as COBOL, have not added features to do things which we could not do in our older languages. Instead they have added more and fancier ways of doing things which we could do fairly well anyway. We do not appear to be developing better languages, only fancier ones. . . .

COBOL and ALGOL and their derivative languages appear to have been designed on the basis that anything can be implemented and that the consideration of compiler requirements in language design would lead to somewhat more machine oriented languages. We might say that this language design method is really no concern of the user. He doesn't have to use all of those fancy features if he doesn't want to. But when slow compilers, producing inefficient object programs come out a year or two late, the user begins to suspect that he would have been better off without all these frills. The user could never afford to buy hardware that was designed without any consideration of the cost of manufacturing it. It appears that he can hardly afford to wait for, and then waste computer time with, languages which were not designed for the best compromise between language utility and implementation requirements.

. . . Many compilers produce quite efficient object programs. Others are not so good. Horror stories of 10% to 20% efficient object programs are passed from user to user. Unfortunately many of these stories are true.

Despite criticisms of COBOL, it has become the established language for business data processing, albeit by Government fiat. The original CODASYL group, now expanded, is active, and with others is seeking for improved means of programming. One very promising adjunct to COBOL is the use of decision tables. Originally proposed by Kavanagh (15, 16) and Grad (10), under the acronym of TABSOL, the concept is currently under appraisal by the CODASYL group, where the technique is called DETAB-X (23, Pollack, S. L.).

Decision Tables

Decision tables are a systematic method for describing and documenting the flow of logic in a program. Like COBOL, certain descriptive material is written in pseudo-English, and in fact, in some versions COBOL statements per se are used. The general arrangement of the decision table format is as shown in Table 1.

Table 1. Decision Table Format

TABLE HEADER	
STUB HEADER	RULE HEADER ENTRY HEADER
CONDITION STUB	CONDITION ENTRY
ACTION STUB	ACTION ENTRY

The essence of the technique can perhaps best be gained from a small example adapted from a published procedures manual, and shown in Table 2 (6, op. cit.).

Table 2. Example of a Decision Table

TABLE: CREDIT CHECK								
LINE NR.	VERB	OPERAND	OP	OPERAND	RULE 1	RULE 2	RULE 3	RULE 4
					OPERAND	OPERAND	OPERAND	OPERAND
1		SPECIAL CLEAR	EQ		1	0	0	0
2		CREDIT LIMIT	GE	OK*		Y	N	N
3		PAY EXPERIENCE	EQ				GOOD	BAD
4	MOVE	'APPROVED'	TO	ORDER STATUS	X	X	X	
5	MOVE	'REJECT'	TO	ORDER STATUS				X

OK* = In process amount + Accounts Receivable amount + Order amount.

In this decision table, the rules for performing a credit check are specified:

Rule 1 states: If special clearance is EQ (equal) to 1, then move the word 'approved' to order status.

Rule 2 states: If special clearance is equal to 0 and the credit limit is GE (greater than or equal to) OK then move the word 'approved' to order status.

Rule 3 states: If special clearance is equal to 0 and the credit limit is not greater than or not equal to OK and pay experience is equal to GOOD, then move the word 'approved' to order status.

Rule 4 states: (in conjunction with rule 5) If special clearance is equal to 0 and the credit limit is not greater than or not equal to OK, and pay experience is BAD, then move the word 'reject' to order status.

The advantages of the use of decision tables (with the current connotation that they will be used in conjunction with COBOL), are cited as (10, op. cit.):

- Conciseness and clarity
- Completeness
- Meaningful relationships

Kavanagh is somewhat more enthusiastic (16, op. cit.):

Structure tables force a logical, step-by-step analysis of the decision. . . . are easily understood by human beings regardless of their functional background. . . . form an excellent basis for communication between functional specialists and systems engineers. . . . go a long way toward solving the difficult systems documentation problem. . . . format is so simple. . . . that engineers, planners, and other functional specialists can write structure tables for their own decision-making problems with very little training and practically no knowledge of computers or programming. . . . errors are reported at the source language level, thus permitting the functional specialist to debug without a knowledge of computer coding. . . . offer levels of accuracy unequalled in manual systems. . . . are easy to maintain.

The literature does not disclose extensive application of the decision table technique, so that it is difficult to evaluate the practical merit of the method. It does appear that the concept is helpful to interior systems design; it also appears that some of the same criticisms which are attached to COBOL may also be applicable to TABSOL and DETAB-X. In particular, it seems evident that many rules and stipulations will accompany this language. The preliminary manual cited requires some 80 pages and is acknowledged to be incomplete. It is also

felt that the same lack of general compatibility will become evident as these languages are implemented for the machines of various manufacturers. However, there is at least some semblance of a rigorous approach evident in this technique.

Graphic and Tabular Methods

Another area of occasional interest in recent writings has been that of graphic or tabular methods for either interior or exterior systems description. Grad and Canning (11) have proposed a graphical technique, while Evans (7) has proposed a tabular method. In addition, almost every computer manufacturer and almost every text relative to information processing proposes a graphic or tabular approach to systems design, under the generic title of "flow charting." None of the several graphical techniques investigated appeared to have any unique features; they will not, therefore, be discussed here.

Generalization Methods

Some attempts at generalization of interior systems design have been made, and have been relatively fruitful. The concept here, as outlined by McGee (20), and later by McGee and Tellier (21), is to write very general programs for operations such as sorting, report generation, and file maintenance, and to use these programs rather than writing specific programs for single-purpose operations. The concept has been quite widely accepted, and nearly every manufacturer of equipment has available generalized sorts and report generator programs. It should be noted that the principle advantage of these routines is the saving of

programming time and effort, at the expense of running time on the computer. It should also be noted that McGee specifically does not attempt to generalize the calculations involved in an information processing system.

Quantitative Approaches

The body of literature relative to what might be called quantitative approaches to either interior or exterior systems design is woefully small, and much of the material which does appear addresses itself to particular aspects of systems design rather than to the general problem. For example, Wagner (31) writes of the use of decision theory to determine the amount of specific data necessary for making a given decision, while Rowe (25) discusses the use of simulation and display matrices in analysis of management control systems.

Two papers, by Lieberman (18) and Homen (14) are worthy of extensive note. Since they furnish a foundation for the present research, a separate section will be devoted to these two papers later in this chapter. Basically, these two papers used matrices for the description of systems and the manipulation of systems elements. With minor expansion, Kozmetsky and Kirschner (17) printed the Lieberman model as an appendix to their book. The principle expansion was in terms of a more lucid explanation of the use of the model, and more flexibility in its application.

A similar matrix approach, but a much more cumbersome one, was taken by Henderson (13). He assayed the construction of a five-dimensional model, his dimensions being "Functional distinction, natural

structure, managerial prerogative, substantive content, and time." Even though he speaks of five dimensions, his matrices are two-dimensional arrays. One matrix is used for each report, so that a given system requires a large number of matrices. He further requires that a value be attached to each piece of data, so that an objective function can be written.

Henderson is able to cast his model in the form of an integer linear programming problem. The conclusion is reached, however, that the solution of the linear programming model cannot be found because of the very large number of constraints. It is interesting to note that 69 equations are used to merely describe the kinds of constraints.

In another approach, Young and Kent (32) propose the use of essentially a symbolic logic method for exterior systems design, with some connotation of interior systems design as well. Information sets, document sets, and set relationships are defined using established set and symbolic notation. While this approach is excellent from a descriptive point of view, great difficulties are encountered in manipulation of such a model. In the article, the authors resorted to a clever but rather complicated graphical technique which, while useful, does not offer the advantages of the Lieberman-Homer models.

In a graduate project at Purdue (29, Thomas, W. H.), a similar conclusion was reached; that symbolic logic is quite effective for describing systems, but that algorithms for manipulation of the model so obtained are not presently available, nor does it appear that they will become available for some time. Such a development must await a great deal of research in pure mathematics.

The Lieberman Technique

Lieberman's notation is as follows (18, op. cit.):

i = identification data; e.g., employee number.

q = quantitative data; e.g., hours worked.

Both i and q are subscripted by the same series (say k) for indexing of specific data elements.

B_r = the r th business function; e.g., production control.

S_m = the m th source data form; e.g., time card.

R_n = the n th report form; e.g., stock status report.

M = general notation for a matrix. A subscript s indicates a source data matrix, a numerical subscript indicates the level of an intermediate matrix, a subscript B indicates a matrix of the requirements of the business functions for given reports R .

The matrices may be called incidence matrices, since the rule for an entry in a given matrix is that a cell value of 1 is assigned if a given report requires a given piece of data, and is zero otherwise. The formation of the matrices is best seen by a simple example.

The first matrix, M_s , has a row for each i_k and q_k , and a column for each S_m . Table 3 shows an M_s matrix which presumes a system with six data pieces and four source data forms.

The interpretation given to this matrix is, for example, that identification data item 1 appears on source forms 1 and 4, while quantitative data item 5 appears on source forms 3 and 4.

Table 3. The M_s Matrix

	S_1	S_2	S_3	S_4
i_1	1	0	0	1
i_2	1	1	1	0
i_3	0	1	0	1
q_4	1	1	0	1
q_5	0	0	1	1
q_6	1	1	1	1

The first level report structure can now be shown in matrix form, as in Table 4, which assumes five first level reports, and uses a superscript on R to indicate the report level.

Table 4. The M_1 Matrix

	R_1^1	R_2^1	R_3^1	R_4^1	R_5^1
S_1	1	1	1	1	1
S_2	0	1	0	0	1
S_3	0	0	1	1	1
S_4	0	1	0	1	1

A similar interpretation is placed on the entries in this matrix. For example, source form number 2 is required for reports 2 and 5. Similarly, a matrix for second level reports can be constructed, as shown in

Table 5, where three second level reports are assumed.

Table 5. The M_2 Matrix

	R_1^2	R_2^2	R_3^2
R_1^1	1	0	1
R_2^1	1	1	1
R_3^1	0	0	1
R_4^1	0	0	1
R_5^1	1	0	0

Finally, assuming a two level report structure, the M_B matrix can be constructed, showing the use of second level reports by the several business functions. In Table 6, two business functions are assumed.

Table 6. The M_B Matrix

	B_1	B_2
R_1^2	1	1
R_2^2	0	1
R_3^2	1	0

At this point, certain information can be gained by examination of the matrices. For example, it is seen that S_4 contains all but one piece of the basic data in the system; one might investigate the feasibility of adding one piece of data to S_4 and eliminating the other source forms. It is also possible by adding rows and columns of the matrices to gain a measure of the use of a given piece of data or a given report.

Table 7. The $(M_S)(M_1)$ Matrix

	R_1^1	R_2^1	R_3^1	R_4^1	R_5^1
i_1	1	2	1	2	2
i_2	1	2	2	2	3
i_3	0	2	0	1	2
q_4	1	3	1	2	3
q_5	0	1	1	2	2
q_6	1	3	2	3	4

It is now noted that if the four matrices are taken in the sequence M_S, M_1, M_2, M_B , that they are conformable for matrix multiplication. Performing the first multiplication, the $(M_S)(M_1)$ matrix shown in Table 7 is obtained. This matrix shows the number of ways that each piece of source information is available to each of the first level reports. Thus q_6 is available to R_5^1 in four different ways, while i_3

is not available to R_1^1 or to R_3^1 . This first product matrix can now be multiplied by M_2 to show the availability of source data to the second level reports. In turn, the product matrix so obtained can be multiplied by the M_B matrix, which will show the availability of source data to the business functions. Performing these two further multiplications results in the final, or solution matrix, for the entire system shown in Table 8.

Table 8. The Solution Matrix

	B_1	B_2
i_1	11	7
i_2	13	8
i_3	7	6
q_4	14	10
q_5	7	4
q_6	17	11

This resultant matrix presumes to show the redundancy of the system, and examination of the original and intermediate matrices is proposed to disclose ways in which the redundancy can be reduced. The interpretation of the solution matrix is that a given cell shows the

number of ways which a given piece of source data is being made available to a given business function.

As presently constituted, Lieberman's model is best adapted to analysis of existing systems, or design of new systems where it is suitable to use the old system as a point of departure. Lieberman alludes to the fact that the model might be used for synthesis of new systems, by essentially constructing a final matrix of data sources to business functions, then using an 'inversion' function to work backward to the M_s matrix. He does not contemplate the usual matrix inversion, however, and discussion of this phase is deferred to a "later" paper which has not appeared.

The Homer Technique

The basic contribution of Lieberman was to furnish a concise basis for the description of exterior systems, and to gain some measure of the data redundancy of a system. Homer (14, op. cit.) pointed out some weaknesses of the Lieberman model and proposed techniques for overcoming these weaknesses and for improving the computational procedures.

Since the first phase of the current research will reproduce Homer's results with a considerable simplification of procedure and with more resultant information, it is appropriate, for purposes of comparison, to include Homer's notation, argument, and technique at this point. His mathematical development will not be included, since it justifies only his technique, and is not pertinent to the method to be developed in this current research.

Notation

Homer's notation is as follows (14, p. 501):

d_i = the i th item of data in a system: $i = 1, 2, \dots, m$.

$R_{k(j)}$ = the k th report (or document) at the j th level; $j = 1, 2, \dots, n$; $k = 1, 2, \dots, p_j$. In particular, let:

$R_{k(1)}$ = the k th source document.

B_r = the r th business function; $r = 1, 2, \dots, q$

M_{j-1} = the matrix which depicts the components required for the preparation of j th level reports. In particular, let:

M_0 = the matrix which depicts which items of data appear on which source documents.

M_n = the matrix which depicts which n th level reports are used in performing the various business functions. (This implies that business functions are carried out at the $n = 1$ level.)

Limitations of Lieberman Model

Homer cited the following conditions which "hinder the establishment" of the Lieberman model (14, p. 505):

1. Cases where it is extremely difficult to define the level of a report, because it is prepared not only from j th level reports, but also reports of level $j - 1$, $j - 2$, etc.
2. Similarly, cases where business functions are performed not only on the basis of n th level reports, but on lower level reports as well.
3. Cases where some business functions are performed at the $n + 1$ level, others at lower levels.
4. Cases where items of data enter a system at some level higher than $j = 1$.

5. Cases where reports are prepared outside the scope of the study, (outside the enterprise, often) and enter the system at some relatively high level.

6. Cases in which some $R_k(j)$ is a terminal report for some $j < n$; such as records primarily historical in nature, or summary reports prepared for use outside the scope of the study.

Such conditions result in a series of matrices which are incompatible for multiplication, for the row headings of M_j are not necessarily identical to the column headings of M_{j-1} .

Homer then develops an example, first using Lieberman's technique to demonstrate that the resultant matrices are indeed non-conformable (incompatible) for multiplication. He then develops two methods of resolving this difficulty.

The first of these techniques is that of augmenting the individual matrices (of Lieberman) with dummy vectors in order to force conformability for matrix multiplication. Then the series of matrix multiplications is performed exactly as contemplated by Lieberman in order to obtain the solution matrix. Since this method is rather lengthy, and is not as good a method as Homer's second technique, it will not be further described.

Homer's Second Method

In Homer's second method, a single matrix S is formed, using the elements of the M_{j-1} and M_n matrices. Then a solution, S^* , is obtained by performing a series of elementary column operations on S .

The rules for formation of the S matrix are (14, p. 508):

1. A row is established for each d_i and for each R_k in the system; i. e., for each component except the B_r 's.

2. A column is established for each R_k and for each B_r in the system; i. e., for each component of the system except the d_j 's.

3. As before, the number 1 will be inserted in each cell to represent an item of information appearing in a report, one report used to produce another, or a report used to perform a business function. In other words, those cells which would contain a 1 under the method of . . . (First method) . . . would contain a 1 under this method.

4. Each R_k will be represented by both a column and a row. Into each cell formed by the intersection of an identical row and column (r_{kk}), the value -1 will be inserted.

5. All other cells will be labelled zero.

6. The matrix can now be analyzed as follows:

- a. Should any column contain only zeros, the report or business function represented is outside the scope of the problem being investigated, and the column should be removed.
- b. Should any row contain only zeros, the report or the item of information represented is not a component of the system, and the row should be removed.
- c. Should any column contain -1 as the only non-zero entry, the component represented by that column is really an input to the system. The column should be removed.
- d. Should any row contain -1 as the only non-zero entry, the component represented by that row is really an output of the system. The row should be removed.
- e. In the event that the application of the above rules results in the deletion of both the row and column representing the same component, this is an indication that that component is not a member of the system under investigation.

The S matrix for Homer's example is shown as Figure 1. Homer indicates that the system inputs are data elements d_1, d_2, \dots, d_7 , and reports $R_{4(1)}$ and $R_{6(2)}$, while the outputs are the report $R_{4(2)}$, and business functions B_1, \dots, B_4 .

An algorithm is then developed by means of which the solution

matrix S^* in Figure 2 is developed (14, p. 509):

1. Identify the cells formed by the intersection of input rows and output columns; that is, the solution area.
2. Perform the necessary elementary column operations to reduce to zero each entry in an output column other than those in the solution area.
3. The resulting values in the solution area represent the solution of the algorithm; that is, they show the number of ways in which each input "reaches" each output.
4. Since each elementary column operation may not only reduce to zero the cell which is being operated upon, but may also introduce non-zero entries into other cells which are supposed to be reduced to zero, it is wise to proceed in a systematic fashion, from the bottom row of the matrix up.

The S^* matrix contains in its solution spaces (heavily outlined in Figure 2) the same data as would have been contained in the solution obtained by matrix multiplication, except that they are in different orders. Homer claims the following benefits for his second method, in addition to solving the problem of non-conformability (14, p. 511):

1. No attempt need be made by the analyst to force reports into classification by level.
2. Computation is greatly simplified in that only elementary column operations are required.
3. Inputs and outputs of the system are immediately identifiable, as are components outside the scope of the study.
4. The sequence in which components are listed is immaterial. No time or effort need be spent in ordering data.
5. Because of its simplicity, the method is well adapted to simulating the effect of changes in the system.
6. Any intermediate results (analogous to some $N_{a,b}$ where $a > 0$, $b < n$) can be obtained by defining "input rows" and "output rows" to be the rows and columns of the matrix of the desired result, and forming the solution area accordingly. Any $N_{a,b}$ so obtained can then be used to compute $N_{a,c}$ ($c > b$).

	$R_1(1)$	$R_2(1)$	$R_3(1)$	$R_1(2)$	$R_2(2)$	$R_3(2)$	$R_4(2)$	$R_5(2)$	B_1	B_2	B_3	B_4
d_1	0	1	1	0	0	0	0	0	0	0	0	0
d_2	1	1	1	0	0	0	0	0	0	0	0	0
d_3	0	0	1	0	0	0	0	0	0	0	0	0
d_4	1	0	1	0	0	0	0	0	0	0	0	0
d_5	0	1	0	0	0	0	0	0	0	0	0	0
d_6	0	0	0	1	0	1	1	1	0	0	0	0
d_7	0	0	0	0	0	0	0	0	1	1	1	0
$R_1(1)$	-1	0	0	1	0	1	1	1	0	0	0	0
$R_2(1)$	0	-1	0	0	0	0	0	0	1	1	0	0
$R_3(1)$	0	0	-1	1	1	0	1	1	0	0	0	0
$R_4(1)$	0	0	0	0	1	1	0	0	0	0	0	0
$R_1(2)$	0	0	0	-1	0	0	0	0	0	1	1	1
$R_2(2)$	0	0	0	0	-1	0	0	0	1	1	0	1
$R_3(2)$	0	0	0	0	0	-1	0	0	1	0	0	1
$R_5(2)$	0	0	0	0	0	0	0	-1	0	1	1	0
$R_6(2)$	0	0	0	0	0	0	0	0	1	0	0	0

Figure 1. S Matrix from Homer's Example (14, p. 509)

	$R_1(1)$	$R_2(1)$	$R_3(1)$	$R_1(2)$	$R_2(2)$	$R_3(2)$	$R_4(2)$	$R_5(2)$	B_1	B_2	B_3	B_4
d_1	0	1	1	0	0	0	1	0	2	4	2	2
d_2	1	1	1	0	0	0	2	0	3	6	4	4
d_3	0	0	1	0	0	0	1	0	1	3	2	2
d_4	1	0	1	0	0	0	2	0	2	5	4	4
d_5	0	1	0	0	0	0	0	0	1	1	0	0
d_6	0	0	0	1	0	1	1	1	1	2	2	2
d_7	0	0	0	0	0	0	0	0	1	1	1	0
$R_1(1)$	-1	0	0	1	0	1	0	1	0	0	0	0
$R_2(1)$	0	-1	0	0	0	0	0	0	0	0	0	0
$R_3(1)$	0	0	-1	1	1	0	0	1	0	0	0	0
$R_4(1)$	0	0	0	0	1	1	0	0	2	1	0	2
$R_1(2)$	0	0	0	-1	0	0	0	0	0	0	0	0
$R_2(2)$	0	0	0	0	-1	0	0	0	0	0	0	0
$R_3(2)$	0	0	0	0	0	-1	0	0	0	0	0	0
$R_5(2)$	0	0	0	0	0	0	0	-1	0	0	0	0
$R_6(2)$	0	0	0	0	0	0	0	0	1	0	0	0

Figure 2. S^* Matrix from Homer's Example (14, p. 510)

Subsidiary Literature

During the course of later presentation of the research, an analogy will be drawn between an information system and a materials flow system. The research will also draw upon the work of two authors in this area. It is therefore pertinent to present the work of these two authors at this point, even though their work was done in a context quite different from that of information systems analysis.

Vazsonyi (30) considered the widespread problem of a materials system wherein raw materials and purchased parts are used to produce a hierarchy of sub-assemblies and assemblies and, finally, finished product. He developed a technique known as the "Gozinto theorem"* wherein the statements of relation between individual parts in the system are used to develop a matrix which represents the "total requirements factor," or the amount of each lower level component required for a given higher level assembly or sub-assembly.

Vazsonyi does not actually state and prove a theorem, but rather defines some relationships existing in the materials system and develops a method of computing a total requirement factor matrix. The main line of his reasoning and development starts with the portrayal of the materials system as a directed graph, which he calls a "Gozinto diagram."

In this diagram, as shown in Figure 3, the several parts and assemblies are represented by the nodes (circles) of the graph, and the

* Vazsonyi introduces a note of humor into his book by a footnote which attributes this theorem to "the celebrated Italian mathematician Zepartzat Gozinto," with reference to his "Collected Works, Vol. 3."

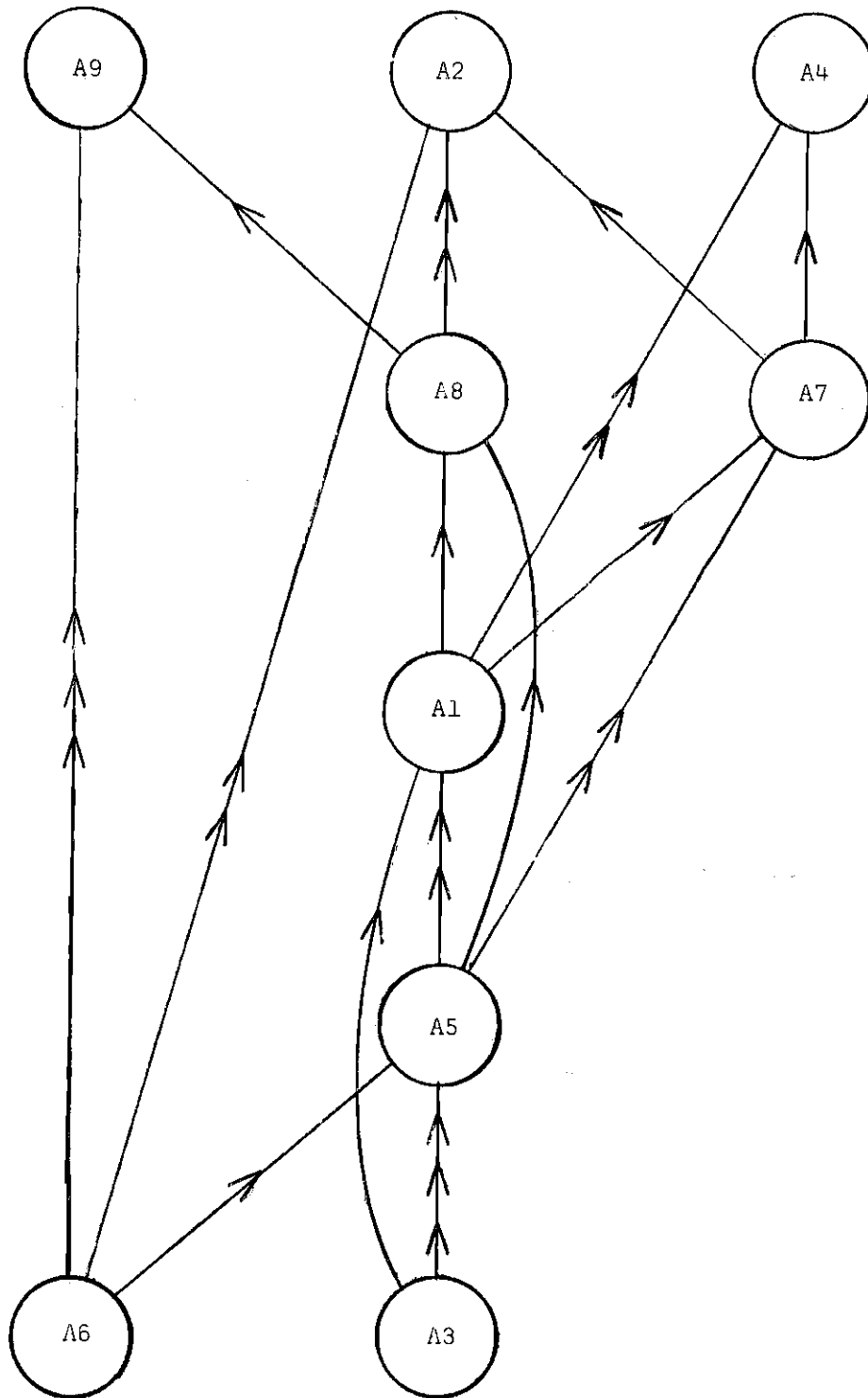


Figure 3. The Gozinto Graph (30, p. 430).

relationships which exist between parts and assemblies are denoted by lines connecting the nodes. The arrows on the line define both the direction of relationship and the number of a given part or sub-assembly at the beginning node which are required for fabrication of the sub-assembly or assembly represented by the node at the end of the line.

From this graphical conception of the materials system, the "next assembly quantity matrix" shown in Figure 4 can be developed by inspection. In this matrix, the row index i is the index of the node at which a line begins, the column index j is the index of the node at which a line ends, and the cell value is the number of arrows on the connecting line. The next step is to develop, again by inspection of the graph and simple calculation, a "total requirement factor matrix," depicted in Figure 5. Notation is then developed, wherein N denotes the next assembly quantity matrix, with n_{ij} the cells therein, and T is the total requirement factor matrix, with cells t_{ij} . Both N and T are of dimension $n \times n$, where n is the number of parts and assemblies in the system. By appeal to the graphical representation and the two matrices, he is then able to show that the computation of the cells t_{ij} can be accomplished by use of the relationship:

$$t_{ij} = \sum_k n_{ik} t_{kj}, \quad i \neq j, \quad (1)$$

where k indexes over the columns of N and the rows of T .*

* While concise, this equation is not computationally efficient, requiring, as Vazsonyi notes, solution of large systems of simultaneous equations.

	1	2	3	4	5	6	7	8	9
1	0	0	0	2	0	0	1	1	0
2	0	0	0	0	0	0	0	0	0
3	1	0	0	0	3	0	0	0	0
4	0	0	0	0	0	0	0	0	0
5	2	0	0	0	0	0	2	1	0
6	0	2	0	0	1	0	0	0	3
7	0	1	0	1	0	0	0	0	0
8	0	2	0	0	0	0	0	0	1
9	0	0	0	0	0	0	0	0	0

Figure 4. The Next Assembly Quantity Matrix
(30, p. 431)

	1	2	3	4	5	6	7	8	9
1	1	3	0	3	0	0	1	1	1
2	0	1	0	0	0	0	0	0	0
3	7	33	1	27	3	0	13	10	10
4	0	0	0	1	0	0	0	0	0
5	2	10	0	8	1	0	4	3	3
6	2	12	0	8	1	1	4	3	6
7	0	1	0	1	0	0	1	0	0
8	0	2	0	0	0	0	0	1	1
9	0	0	0	0	0	0	0	0	1

Figure 5. The Total Requirement Factor Matrix
(30, p. 432)

Also, to make equation (1) hold, the relation

$$t_{ij} = 1, i = j \quad (2)$$

is defined, on an essentially arbitrary basis, but with the justification that this diagonal 1 reflects the inherent self-identity of a part.

It is next observed that equation (1) is a matrix multiplication, wherein N is post-multiplied by T , and that equation (2) represents the addition of the identity matrix (I) of rank n . Therefore, the whole relation can be represented by the matrix equation:

$$T = NT + I \quad (3)$$

It is then noted that this equation can be successively rewritten:

$$T - NT = I$$

$$(I - N)T = I$$

and finally:

$$T = (I - N)^{-1} \quad (4)$$

if the inverse exists.*

The T matrix is therefore the inverse of the $(I - N)$ matrix, where I is the identity matrix and N has known values. Vazsonyi notes at this point that the matrices are triangular, and that for this reason the inversion is relatively easy to perform. He does not exploit this triangularity to any extent, however.

In a later work Giffler (9), in the same context of determination of total requirements factors in a materials assembly system, more fully explored the properties of the N, T, and $(I - N)$ matrices. He defines three matrices, N, T, and C. N corresponds to a bill of materials, and the typical element n_{ij} is the quantity of "i" which is directly consumed per unit of "j." T corresponds to "total requirements," with elements t_{ij} being the quantity of "i" which must be manufactured or purchased per unit of "j." C is a "consumption matrix" where the c_{ij} represent the total quantity of "i" consumed, directly or indirectly, per unit of "j." Giffler's N and T matrices are precisely the same as those defined by Vazsonyi. All matrices are of dimension $n \times n$.

It is first shown that the consumption matrix C is related to the bill of materials matrix N by:

* Vazsonyi does not point out that the relation between equations (3) and (4) depend on the existence of the inverse of $(I - N)$, which in turn implies that this matrix must be non-singular. However, this is easily shown, since N is strictly triangular, and therefore $(I - N)$ is triangular. In a triangular matrix, the determinant is equal to the product of the diagonal elements. In this case, $(I - N)$ has 1's on the diagonal, the determinant is equal to 1, the matrix is therefore non-singular, and $(I - N)^{-1}$ exists.

$$c_{ij} = n_{ij} + \sum_k c_{ik} n_{kj}, \quad (5)$$

that is, that the consumption of i per unit of j is the sum of the direct consumption and the indirect consumption through the k th commodities (sub-assemblies) which in turn are consumed directly in i .

This relation is then expressed in matrix notation,

$$C = N + CN \quad (6)$$

which by appropriate manipulation becomes

$$C = N(I - N)^{-1} \quad (7)$$

where I is the $n \times n$ identity matrix.

It is then noted that if the matrix N is squared, the matrix N^2 will have elements

$$n_{ij}^2 = \sum_k n_{ik} n_{kj} \quad (8)$$

where n_{ij}^2 represents "second-level consumption" of i per unit of j . By extension, n_{ij}^m would represent m th level consumption of i per unit of j in the matrix N^m , and direct consumption would be equivalent to n_{ij}^1 in the original N matrix. By this argument, the consumption matrix C for an m - level system can be written:

$$C = N + N^2 + N^3 + \dots + N^m. \quad (9)$$

It is then shown that since the consumption of commodities (parts and sub-assemblies) in other commodities is finite, the series on the right hand side of equation (9) terminates, that is, n^{m+1} is null for some finite m . It is then observed that the elements of T are related to those of C by:

$$t_{ij} = \begin{cases} c_{ij}, & \text{if } i \neq j \\ 1 + c_{ij}, & \text{if } i = j \end{cases} \quad (10)$$

which can be expressed by:

$$\begin{aligned} T &= I + C \\ &= I + N + N^2 + \dots + N^m. \end{aligned} \quad (11)$$

Multiplying both sides by $(I - N)$,

$$(I - N)T = (I - N)(I + N + N^2 + \dots + N^m) \quad (12)$$

and performing the indicated operation on the right and cancelling yields

$$(I - N)T = I \quad (13)$$

and

$$T = (I - N)^{-1} \quad (14)$$

which is precisely the result obtained by Vazsonyi.

Giffler then exploits the triangularity of the N , $(I - N)$, and T matrices, in particular the fact that $(I - N)$ is the forward solution of its own inverse, to develop a pair of iterative equations for the computation of $(I - N)^{-1}$ when N is strictly triangular and non-negative. Assuming upper triangularity,

$$\begin{aligned} t_{ij} &= \sum_{k=1}^{j-1} t_{ik} n_{kj}, & j > i \\ &= 1, & j = i \end{aligned} \quad (15)$$

while in the case of lower triangularity,*

$$\begin{aligned} t_{ij} &= \sum_{k=j}^{i-1} n_{ik} t_{kj}, & j < i \\ &= 1, & j = i \end{aligned} \quad (16)$$

These equations require solving for rows from top to bottom in the case of equation (15) and for columns from left to right in the case of equation (16). As will be developed later, this is not the most

* Giffler stated this equation erroneously, in that his summation was from $k = i$ to $j - 1$, which does not give the proper result.

desirable order of solution for computer operation.

In order to fully exploit the triangular nature of the N and T matrices, it is necessary to have a method of arranging the arbitrary designations of parts, sub-assemblies and assemblies in such a manner that the resulting matrices will be in the triangular form desired. Giffler (9, p. 18-34) provides the essential basis for triangularization. He first approaches the matter from the point of view of the cells within a matrix, and notes that triangularization can be done by a series of row and corresponding column permutations of a matrix that is triangular in nature, but not in form. He also defines pairs of permutation matrices which can be devised, and used to pre- and post-multiply a given matrix in order to triangularize it. Since this technique requires prior determination of the permutations to be made, it does not appear to be suitable for machine operation, and will therefore not be discussed further.

By looking at the essential nature of a triangularized N matrix (in the material assembly system) Giffler observed that triangularity could be achieved if the commodities and parts could be so ordered that "no commodity follows a commodity in which it is consumed and that assigning commodities to successive rows and columns in the same order must produce a (strict) triangular N." This definition will produce an upper triangular matrix. For lower triangularity, the word "follows" in the quotation above is replaced by "precedes."

Based on this definition, Giffler then develops the following algorithm:

1. For each $n_{ij} \neq 0$, list the pair (i,j). Assuming that

there are m such pairs, assign the successive position numbers $1, 2, \dots, m$ to each component index i . Assign the position numbers $m + 1, m + 2, \dots, 2m$ to each assembly index j . Let $(i, m + i)$ represent the position numbers of the i th pair.

2. Select the highest positioned component index. Assume that it occupies position i . (Actually at the outset it must occupy position 1.) Look for the first match of the index against an index in positions $m + i, m + i + 1, \dots, 2m$. If a match cannot be made repeat Step 2 with the next highest component index. If no match can be made with any component index, transfer to OUT.

3. Say that Step 2 produces a match with the index in position $m + j$. In this event exchange the indices occupying position i and j and the indices occupying positions $m + i$ and $m + j$. Make a record of the exchanging indices.

4. Compare the exchanging indices in Step 3 with previously exchanged indices. If the indices have exchanged previously, transfer to TERMINATE. If the indices have not exchanged previously, repeat Step 2 with the next-highest component index.

TERMINATE. If the algorithm reaches this step, N is cyclic.

OUT. If the algorithm reaches this step, N is non-cyclic.

When the algorithm has run to OUT, all component indices will be listed in their (strict) triangularizing order. The indices of the products will be missing because they are not components. This deficiency can be corrected by adding a zero'th row and column to N and making all $n_{i0} = 1$ if i is the index of a product. This is the same as to assume a common fictitious commodity in which all products are consumed.

Giffler asserts that the above method is "readily mechanized by punch card collating equipment." The method produces an upper triangular matrix, but by reversing i and j indices, the algorithm will lower triangularize as well.

Summary and Conclusions

To summarize, relatively little has been done in a quantitative sense for either interior or exterior systems design. As currently practiced, information processing systems design is largely an art,

rather than a science. The use of compilers, especially generalized compilers such as COBOL, is extensive, but these compilers are widely criticized. Decision tables seem to be a desirable adjunct to the compilers for internal systems description and analysis, but many of the criticisms directed toward the compilers is also directed to decision tables. Generalized routines, such as sort routines and report generators, are used extensively, but also have the limitation of requiring valuable computer time in order to save programming effort.

Some advance has been made by the Lieberman and Homer models, but the techniques are not widely used. It is believed that additional work in the direction indicated by these models is justified. Symbolic logic has been suggested as a means of analysis but has the limitation of difficulty of manipulation which renders it relatively weak as either an exterior or interior systems design tool.

In conclusion it is appropriate to quote from two rather similar articles which point out the need for investigation of the sort contemplated, without, however, indicating the direction which the investigation should take! Postley (24) comments:

But while new triumphs in scientific computing have been derived from a sound base of mathematical theory and research, no such base exists in the business field. The principles of accounting and record keeping operations are reasonably well-defined for non-computer-oriented systems. But these principles must undergo substantial revisions when we consider . . . applying them to data processing equipment, . . . Thus, a second dimension in the classification of scientific or business data processing is the presence of well developed mathematical and engineering theory for scientific information systems and the almost complete lack of a fundamental theory of business information systems.

About a year later Steel (28) stated:

. . . data processing is not really clearly understood by anyone. . . . Any attempt to bring some order into the present chaos must face the unpleasant fact that no fundamental theory exists for immediate application. This is the key difference between commercial data processing and scientific computing. . . . The absence of a corresponding fundamental discipline underlying data processing requirements has prevented the parallel development of technique for those problems whose solution now seems to occupy the bulk of computer time in the world.

CHAPTER III

SCOPE OF STUDY AND BASIS FOR IMPROVEMENT

Introduction

The purpose of this chapter is to present a brief overview of the work to be shown in detail in following chapters, and to discuss certain matters pertaining to prior work in the field and certain characteristics of information processing systems which will furnish a basis for improvement of techniques of systems analysis.

The research to be presented has three basic phases. In phase I, the work of Homer and Lieberman will be duplicated with improvement in terms of the amount of information made available about the system under study and in terms of ease of computation. Chapter IV will present the mathematical development, an algorithm, and a numerical example illustrating this phase.

Later in this chapter it will be shown that while this first phase represents an improvement, the model does not adequately represent an information system in that it does not embrace consideration of types of data and data transitions. Phase II therefore presents a mathematical development, algorithms, and numerical examples for two refined techniques. Chapter V will contain the mathematical development, while Chapter VI will present the algorithms and numerical examples.

Since the study of any real system would result in such a number of systems relations that the algorithms could not be used on a manual

basis, phase III of the research will be devoted to a discussion and development of the use of mechanical and electronic equipment for obtaining numerical solutions using the refined algorithms. The algorithms were, in fact, developed from the point of view that computer methods rather than manual methods would be used in practice. Chapter VII will contain a general discussion of computer considerations, while details of machine operation will appear in the Appendices.

Considerations for Refinement

While Chapter IV will present a method which will reproduce the results of Homer and Lieberman with improvements of computability and usability, it will be pertinent to examine critically both the prior work and the phase I work of this writer with a view to substantial refinements which will permit a more widespread use of the techniques in analysis of real systems. As a first step in this direction, it is pertinent to develop and discuss the types of data which may be found in an information processing system, and to develop the types of transitions through which these data may pass between the input and output stages. Based on this, the limitations of the prior work and the phase I work may be seen, and refinements made.

Data Types

The data which arise in an information processing system may be classified into three basic types, based entirely upon the essential nature of the data rather than its source or intended usage. The three types may be designated as identification data, quantitative data, and status or existence data.

Type one, identification data, is represented by such items of data as payroll numbers, stock numbers, machine numbers, dates, times, locations, and the like.

Type two, quantitative data, is usually originated as a result of a count, measurement, or computation. Included are such data as the amount of product produced on a machine, the tensile strength of a sample subjected to a quality test, the number of pounds shipped on a shipment, the number of employees absent from a given shift, the amount of payment made to an employee or a vendor. Type two information is used largely, but not exclusively, at the lower echelons of the enterprise, for the purpose of making immediate decisions, conveying instructions and short term results, and preparing working documents such as invoices and vouchers.

Type three data are characterized as those data which indicate status or existence, e. g., a specific commodity is assigned to a machine, a failure has occurred in a given process, a given quality test was performed, a specific shipment has been made. Frequently this is the type of information which the control groups and administrative functions of an enterprise are concerned with, since the mere existence of an event is often sufficient for some action to be taken. For example the fact that a shipment has been made is an indication to the order-invoice section that the customer should be billed.

It should be noted that data may be, and frequently are, converted from type two to type three data merely by taking the presence of some quantitative data as indication that some action has taken place. For example, the existence of a non-zero entry in the hours

worked column of an employment record is construed as evidence that the employee was present. This conversion of type two to type three data is not in general reversible, nor can the original type two data be regained unless specific provisions are made for its storage and subsequent retrieval.

It is also important to note that neither type two nor type three data are meaningful unless accompanied by the proper type one identification data. Frequently a single item of identification data suffices for several pieces of type two and/or type three data, but if some of the type two or type three data are removed by some processing step, or if type two data are converted to type three data, or if some other type of data conversion is made, the type one data must still be reproduced in order to identify the surviving data. One implication of this fact is that apparent redundancy of type one data in an information system cannot be viewed in the same light as redundancy of type two or type three data, since the identification data must carry through the system in substantially unchanged form on every document and report.

Furthermore, it is not uncommon for a single item of type one or type two data to carry with it several items of type one data. For example, the type two data "pounds shipped" will very likely carry a date, invoice number, customer number, product number, bill of lading number, packing slip number, etc. In a payroll sub-system, the gross wage may be identified by employee number, department number, social security number, date, shift, and other information required to reflect the fact of paying the employee in the several pertinent accounts.

A consequence of this concept of data types is that it may not

always be wise, in practice, to analyze the type one data separately from the type two or type three data which it is forced to accompany. It may be better from the point of view of both analysis and synthesis of the information system to view the type one data as either coupled to some corresponding type two or type three data, or to view the type one data as a subset of the appropriate type two or type three data, or perhaps merely to view the type one data as a constant running throughout the given sub-system.

One further concept is of interest in trying to reduce the overall amount of data in the system. Since in many cases type three information can be generated or deduced from appropriate type two data, it will be worthwhile to examine instances of creation or maintaining type three data with a view to obtaining the same result as a by-product of the necessary creation or maintaining of the corresponding type two information. Any means of analysis should furnish a means of examining type three data items, particularly when both types of data pertaining to a given event are carried on the same document or report, or are used by the same business function.

Data Transitions

One of the primary functions of an information processing system is to perform prescribed transitions on the input data in order to make it more meaningful to the intended user. Information has been defined as "processed and organized data." It is therefore appropriate to examine the essential nature of the data transitions which take place in a system, and to characterize them in a manner to make them amenable to description and analysis. The following transitions can take place:

1. Data can change types. As discussed in the preceding section, the presence of quantitative data (Type two) may be interpreted as indicating status or existence (Type three). The important fact here is that the data are not the same, and should not bear the same identification for analysis.

2. Data may terminate. This usually arises when a report is extracted for a higher level report, leaving behind unwanted data.

3. Data are summarized, with only the total going on to a higher level. A common example is that the number of hours worked by an individual employee is summarized by department, and only department totals are carried forward in the system.

4. Data are computed, with only the results being preserved in upper levels of the system. An example is that pounds shipped times price per pound may be computed, and only the extension used in some higher level documents.

5. Data are generated in the processor or process, and used either as an intermediate step in a computation or as a basis for comparison. In some cases these data never appear on a report as such, but are lost after the processing purpose for which they were created has been fulfilled. A prime example, but not the only one, is the generation of "proof totals" in a computer run to assure that all data were included in the run.

6. Data, either input or processed, are stored and later retrieved. These delayed data are usually either in original form, such as "last months sales," or in cumulative form, such as "sales year-to-date."

7. Data may be generated on the passage of time. For example in a hospital billing system, the room charges are created by the fact of a room being occupied at midnight. In industrial context, burden charges are (artificially) presumed to be generated by the passage of a calendar month. This transition is, in effect, a special case of data origination, but since it usually arises without overt action having taken place, it can also be considered as a data transition.

8. Occurrence-generated data are those data which arise based on the operation of some decision rule. For example, if three successive absences of an employee occur, this may occasion the preparation of a report to the plant medical section for the purpose of checking whether such absence is due to medical reasons. This data transition almost always gives rise to origination of type three data, and frequently calls for the recovery of stored data as well.

9. System constants are those data, usually of type two, which are used repetitively and largely automatically in computations. For example, in quality control computations, the figure "3" is frequently used as a constant by which the computed standard deviation is multiplied in order to establish control limits. In payroll computation, the number "40" is frequently used when it has been established that an employee has worked the standard work week. This type of transition may also be viewed as a special kind of data origination.

The principle effect of these data transitions from the point of view of the analysis of a system is that, in general, input data do not survive in pure form through the system and into the higher level reports, except for the type one identification data. Rather, the higher

level reports consist largely of data which have been summarized, computed, and otherwise derived through the transitions of input data. Therefore, the analysis technique must be such that these transitions are explicitly recognized and properly treated.

A Materials Flow System Analogy

Since phase I of the current research is based on a prior work done in the area of materials flow systems, it is fruitful to briefly discuss these systems, and to draw an analogy between a materials control system and an information processing system. It will later be shown that the analogy fails at critical points, which furnish a basis for further refinement.

The materials flow system is characterized by input to the system in the medium of raw materials and purchased parts, intermediate stages of sub-assembly and assembly, commonly denoted by the term "in-process inventory," and final stages of finished product. In addition, some of the intermediate assemblies may be sold as such for replacement purposes, or for use by other manufacturers for purposes of further assembly.

The computation usually associated with this system is called the "materials requirement determination." Given a production forecast or schedule in terms of finished products and saleable intermediates, the task is to compute the amount of raw material and purchased parts, and the number of assemblies, sub-assemblies, sub-sub-assemblies, etc., which will be required in order to support the production commitments.

As a manual task, this computation is one which is tedious,

error-prone, and expensive. It was therefore one of the first, after the payroll, to be considered as a punch-card application when such equipment became available. The IBM Corporation, realizing the broad requirement, several years ago developed the so-called "explosion" technique, which used the abilities of conventional card equipment to do this task. While this card "explosion" was a major improvement over manual methods, and made effective use of then available equipment, the technique had one inherent flaw. This was that each level of assembly required a separate, sequential "pass" through the processing equipment, starting with the finished product and ending with the raw materials and purchased parts. This also implied that the order and structure of the materials system be carefully determined, and that the level of entry of each component be carefully specified in advance of the computation. This determination was usually made by tedious manual methods, and usually by engineering personnel who could understand drawings and bills of material.

With the advent of stored program digital computers, it was natural to utilize the higher processing speeds and improved machine logic to improve the method. However, the same inherent problem of multiple passes, one for each level, remained, due to the inability to logically relate the several levels of assembly. At the present time almost all processing is done by this technique, however, despite the limitations involved.

As cited in Chapter II, Vazsonyi (30) developed and reported the so-called "Gozinto" method of materials requirements determination, while Giffler (9) improved the technique somewhat and furnished certain

essential proofs. This writer (3) modified and refined the technique for the purpose of materials requirements determinations, and showed the feasibility of the technique under certain circumstances of assembly hierarchy and computer memory configuration.

The analogy between the assembly of products and the structure of a business information system is readily drawn. The origination of data at some place where an event takes place corresponds to "raw material." Data arising from other systems or exterior sources can be considered as "purchased parts." Sub-assemblies in the plant correspond to work sheets, intermediate reports, and working decks, tapes, and records. Prepared reports compare to finished product, and it can be noted that within the report structure there are levels in the same sense that there are levels of assembly. It should be noted that the analogy is not perfect, and that many circumstances arising in a data system do not find a counterpart in the materials system. However, these difficulties will be discussed and treated in a later section. In this section, it will only be noted that the basic "Gozinto" technique, with some modifications of computational procedure discussed in Chapter IV, can reproduce the results of Homer and Lieberman with full preservation of system relationships and improvement of computational nicety.

Criticism of Prior Work and of Current Phase I Work

The Homer-Lieberman Models

In the Literature Survey, certain criticisms of the Lieberman model were made by Homer, and Homer proposed two methods to alleviate these difficulties. These methods represent a vast improvement over

the basic technique originated by Lieberman, by eliminating the problem of non-conformability of matrices, and indeed, by the elimination of the necessity for performing a whole series of matrix multiplications. In addition, the benefits claimed are for the most part desirable ones. However, some of Homer's cited benefits* warrant some discussion.

In benefits one and four, the point is made that the analyst need not spend time in ordering data, nor in classifying the reports into levels in order that the computation technique will function. This is quite true. On the other hand, in a real situation, it is desirable to know the report levels, and an ordering of the data is very helpful in understanding the system under study. It is significant to note that Homer, in his example, did order the sequence of data and reports with respect to their levels, even while pointing out that it was not necessary to the processing of his model.

In benefit six, a procedure is outlined by means of which intermediate results can be obtained. This is not seen to be a benefit, but rather a loss of information over the basic Lieberman technique. While it is true that the information can be recovered, it requires additional computation, which tends to reduce the effectiveness of the model.

In benefit five, and in benefit two, the simplicity and ease of computation are cited. It is true that the method is an improvement over the matrix multiplication method. However, the performance of column operations, while not difficult, is time consuming, and would be tedious for other than a trivial problem. While it is true that the

* See Chapter II, page 31.

technique could be programmed for a digital computer, it would require extensive memory search techniques which would be difficult to program and time-consuming to operate.

Perhaps the greatest criticism of the technique is that much of the data is lost in the computation, and because of the lack of ordering (unless particular effort is made to do so), the results are difficult to interpret. In addition, after the S matrix is formed, a search of the matrix is desirable, if not required, in order to eliminate non-applicable or erroneously included data from the matrix.

In view of the foregoing criticisms, it is then desirable to develop a technique and computational scheme which will meet Homer's original objections to Lieberman's model, to achieve the benefits inherent in Homer's model, and to gain such other benefits as may be possible. The model developed in Chapter IV is one such technique.

The Phase I Model

While the Phase I Model to be presented in Chapter IV will alleviate many of the short-comings of the Homer-Lieberman models, several other criticisms pertain uniformly to both the prior models and the Phase I model. Since the refinements in later chapters will be attached to the model proposed by this writer, however, the criticisms will be discussed in the light of this latter model.

The two essential criticisms of the basic algorithm is that no distinction is made of data type, and that no provision is made for recognition of the data transitions which arise in the processing. These shortcomings result in a final solution matrix, S^* , which does not give an adequate representation of the system under study, and which

in fact may be misleading.

A principal effect on the S^* matrix is that redundancy tends to be overstated for all three types of data. The inability to recognize type one data also leads to attaching undue importance to necessary duplication of identification data. The inflated indication of redundancy results from the fact that the model as constituted carries through the system data which in fact have been lost due to one of the transitions having taken place.

The second effect on the S^* matrix brought on by this same failure to recognize data transitions is that upper levels indicate the presence of information which in fact is not available from the report in question. It is true that the data may have been required in the report preparation, but they do not appear in the report as such. In this sense, the S^* matrix is misleading, and can lead to erroneous conclusions in the systems design.

The failure to recognize data transitions has also resulted in a model which considers only the external reports of the system, and which has neglected entirely the more voluminous internal reports, working papers, summary decks, tape records, etc. The volume and number of these latter is frequently much greater than the published reports, and are extremely important in designing a well functioning system. Some of this prior omission can be rectified by merely making a more detailed analysis, but recognition of data transition type is necessary for full inclusion of these important considerations in the systems analysis.

Some of the types of transitions lead to specific difficulties of computation or interpretation of the S^* matrix. These are detailed

below:

1. As previously indicated, several of the transition types lead to overstatements of redundancy. This occurs on changing of data from type two to type three, termination, summarization, and computation. Redundancy from the first two transitions is of a fairly simple nature in that an indication of the changed or terminated data is carried through into the higher level report structure as shown in the S^* matrix. Redundancy indications from summarization and computation is more malignant, in that it compounds much more rapidly. For example, if five daily reports are summarized into a weekly total, the S^* matrix will give the indication that the final report includes five daily figures; it may contain none whatsoever.

2. Stored data creates the problem of non-triangularity, or cycling, in the S matrix. For example, presume that a report R_1 , containing weekly payroll totals, is stored for a week, then retrieved in order to use the prior week's total as a comparison for the current week's payroll total on the current week's R_1 report. This would result in the incompatible description that report R_1 is required for the preparation of report R_1 . This is true in a sense, but the analysis technique must recognize that last week's report is not the same entity as the current report. They are alike in data format, but entirely different in data content.

3. There is danger that time-generated, occurrence-generated, and constant data may not be properly recognized, and that their effect on the system may be lost. This difficulty is largely one of care in examination and description of the system rather than inadequacy of the

mathematical model. It should be noted, however, that the examination of occurrences to determine whether the criteria for generation of data has been met may appear to cause redundant use of the information when such is not really the case.

In addition to the difficulties caused by data types and data transitions, there are further difficulties arising from the nature of analysis desired. The S* matrix shows essentially for each report the lower level reports and input data which are prerequisite for the preparation of the given report, or, to state it in another way, the lower level reports and data which the upper level report is "composed of." While this is important, it is also important for the analyst to have a concise statement, preferably in the same format, of the actual data content of each report. In the present form, the S* matrix not only does not contain this information, but is misleading in this respect in that it indicates "composed of" information which may be erroneously interpreted as being "contained in" information.

A very frequent data processing operation is that of "match-merging" wherein two reports (usually in card or tape form) are collated, or merged into physical or conceptual juxtaposition by the device of matching type one data between the two reports. For example, one input card may contain a payroll number and the number of hours worked. An internal master record is maintained which contains payroll number, rate of pay, and department number. A match-merge is performed, comparing the two files on payroll number, and physically placing together each master card with the associated transaction card(s) containing the same payroll number. This operation produces a very great indication

of redundancy of the identification number, when in fact only a single statement of the identification is carried forward through the system. This fact lends further credence to the previous statement that apparent redundancy of type one data is not necessarily a cause for concern.

A further cause of difficulty in using the existing algorithms lies in the fact that in defining the relationships which exist between data elements, there is no single, unique way in which a given information system must be viewed. Depending upon the circumstances, and, unfortunately, the point of view of the analyst, there are several viewpoints which might be taken. For example, one might choose to look at a given system as a hierarchy of reports, with only secondary consideration given to the data and computations involved. Again, the same system might be viewed with primary emphasis placed on the data content, and secondary consideration of the specific documents and reports upon which the data appears. A third viewpoint might emphasize the organizational aspects of the system, with principal attention given to the organizational level responsible for report preparation. In practice, all of these points of view are used, frequently on the same study.

Unfortunately, the difference in viewpoint can be reflected in a difference of definition of the relationships between systems elements. Since the S and S^* matrices are functions of the defining relationships, this means that the difference in viewpoint can be reflected by real difference in the final S^* matrix. In other words, there is no assurance that S^* offers a unique representation of the system under study.

Based on the foregoing discussion, the refinement of the model

for systems analysis must then permit and indeed demand that proper recognition be given to data types and data transitions. In addition, this refined technique must also provide means of eliminating or minimizing the other noted criticisms. Refinements will fall, in general, into two related categories:

1. Improved definition of relationships between data systems elements, by recognition of the types of data and of data transitions. These definitions will be made in the next section of this chapter.

2. Development of algorithms which will permit the inclusion of these new definitions, and which also furnish a means for systems analysis on a basis of the content of reports in addition to the former sole basis of composition of reports. This development will be the subject of Chapters V and VI.

Relationships Between Systems Elements

Consideration of the basic data types, data transitions, and the essential nature of information systems indicates that the relationships which exist between systems elements may be placed into three categories, rather than the single category assumed in the prior work and in the current phase I work. Before describing these three categories it is desirable, however, to define the term "system element" more rigorously.

Definition of System Element

1. By "simple element" will be meant any piece of recorded data, numerical, alphabetical, or symbolic, which exists in the system as an input, output, or intermediate piece of data, regardless of the form of

recording.

2. By "compound element" will be meant any report, form, document, card, tape, or disk record of any nature containing one or more pieces of recorded data (simple elements), and from which the simple elements can be recovered and made meaningful to humans without arithmetic computation.

3. Where it is not necessary to distinguish between simple and compound elements, the term "system element" or simply "element" will be used.

By the above, a record kept on magnetic tape of each employee would be a compound element, and each individual piece of data within this record, such as payroll number, name, address, wage rate, etc., would be a simple element. However, the figure "Average weekly pay for the past six weeks," if it required a computation based on simple elements stored within this record as opposed to being already stored, would not be a system element.

Definitions of Systems Relations

The three categories of relationship between systems elements may now be described and defined. The relationship implied in the Homer-Lieberman models and in the Phase I model is essentially a relationship of composition. That is, the relationship merely indicates that a system element of lower order is required for the preparation of an element of higher order. There is no implication of computation, nor of change of data type from type two to type three. This relationship will be defined, for the refined algorithms, as a "prime relation."

Definition of Prime Relation. By prime relation will be understood that relationship which indicates that an element at some given level of a data system is merely required for the preparation of some higher level element. By this definition, all data input is prime, as well as some elements at higher levels.

Definition of Concomitant Relation. A second category of relationship involves computed data, and the transition of type two data to type three data. In this relationship, one or more simple elements undergo a transition, either from type two to type three data, or through the operation of some arithmetic process or logic process. In this process, a new piece of data is created, and some or all of the lower level data may be lost. An important factor in a relation of this sort is that it always occurs in conjunction with the preparation of a compound element (record or report) of some sort. It has therefore been defined as a "concomitant relation."

By concomitant relation will be understood that relationship which occurs during the preparation of a record or report wherein an arithmetic operation involving simple elements of an order lower than the level of the element being prepared, or wherein a transition from type two to type three data takes place. The constituent elements of the computation, or the type two data from which the type three data were inferred may or may not also appear in the new compound element being derived. If they do appear, they will also bear prime relationships.

Definition of Deletion Relation. The situation frequently arises in an information system that a record, document, or report which is used for the preparation of a higher level element contains more basic ele-

ments than are required. In this case, the necessary information is extracted from the lower level report, and the unwanted data are terminated, or from the point of view of the balance of the system, are deleted. Therefore a third category of relationship is defined, called a "deletion relation."

By deletion relation will be understood that relationship which exists when an element from a lower level is brought to a higher level by virtue of being included within a compound element which is required at a higher level, but which in itself does not become an integral part of the higher level.

A deletion relation is a negative relationship, and even more strongly, is a blocking relationship, in that it is used to indicate that an element is terminated, absolutely and finally, on a given route through the system. This relationship will prevent a false indication of a given piece of information being available on a report when in fact it was only used at a lower level.

As will be shown in Chapters V and VI, the proper use of the prime and concomitant relations will eliminate much of the false redundancy indications in the S^* matrix, and will produce a matrix that represents the system under study on a "composed of" basis. The use of all three types of relations will result in a final matrix, S'^* , which will represent the system on a "contained in" basis.

Rules for Treatment of Data Types and Transitions

With the relations defined, rules can now be given for treatment of the three data types and the several types of data transitions.

1. It is not necessary to make formal distinction between the

three types of data. The defined relationships will enable adequate analysis to be made. Type one data will give false indications of redundancy, but since this factor can be readily checked, it is not felt desirable to take the step to eliminate it.*

2. The use of prime relations is straightforward, and can be applied according to the definition, noting that all input has a prime relation to the compound element on which it is recorded.

3. The following transitions can be classed as concomitant:

- a. Changes from type two to type three data.
- b. Summarizations.
- c. Computations.
- d. Within-processor generation.
- e. Occurrence-generated data.

4. The following transitions may be treated as deletion relations if the definition is met:

- a. The type two data when a transition to type three has been made.
- b. Data terminations.
- c. Summarizations. (The undesired factors.)
- d. Computations. (The undesired factors.)
- e. Within-processor generation.
- f. Occurrence-generated data.

* The redundancy of type one data is caused primarily by the fact of merge operations, as previously discussed. If one desired to eliminate this redundancy, the judicious use of concomitant relations would do so. However, this researcher feels that the indication of number of merges is desirable as a measure of system complexity.

5. Time-generated data should be treated as input data, but may then be subjected to the deletion relation if the definition is satisfied.

6. System constants should be treated as input data, and may then be subjected to the concomitant and deletion relations if the definitions are satisfied.

7. Data which are stored, then retrieved after a fixed time to act as comparative data should be treated as new input, and should therefore be given a different designation in the analysis from that which obtained when the element was stored.

Use of the New Techniques

It is desirable at this juncture to give a general overview of the phases of a typical analysis using the algorithms to be developed, so that these algorithms may be viewed in the broader context of systems analysis. It should be noted that the algorithm presented in Chapter IV is not intended for application, but is only a developmental step leading to the refined algorithms presented in later chapters.

1. The first analysis step is that of identification of the systems elements and definition of the system relations, together with their quantifying symbols which will be introduced in Chapter V. The sources of information are the usual ones encountered in data systems study--the reports, documents, and records themselves, procedures manuals, existing flow charts, and the like. Note that it is not necessary to prepare flow charts of the system, nor is it necessary to display the relationships in matrix form in actual practice. In some

cases, such visual displays may be useful conceptual aids, however.

2. Card decks containing the specification of the system relations are prepared, so that the algorithms can be used for mechanical and electronic computation of the system matrix. This is a simple clerical task, best done by someone other than the analyst.

3. The third step is to perform the necessary computations of the algorithms to be presented in Chapter VI. In practice, this computation will be entirely by mechanical and electronic equipment. The output will be the S^* and S'^* solution matrices, representing respectively a "composed of" and a "contained in" analysis of the system.

4. These output matrices will then be scrutinized by the analyst. Further comment relative to the interpretation to be placed on these matrices will be made in conjunction with the later presentation of a numerical example. At any rate, the analysis of the matrices will suggest certain actions to the analyst. The possible results of these actions can be simulated by making appropriate changes in the definitions of the system relations, and recomputation of the solution matrices. In a complex system, this repetition may take place several times during the design and development stages, as new ideas and concepts are introduced.

Finally, a firm design is established, and the final solution matrices and the cards representing the system will find a new role as a convenient and concise means of documentation of the system as designed. Furthermore, any required redesign may be accomplished with a minimum amount of restudy and reprocessing.

CHAPTER IV

THE BASIC MODEL

Introduction

In this chapter, use will be made of the analogy drawn in Chapter III between a materials flow system and an information processing system in order to modify certain work done in the field of materials flow system analysis for use in the present context. The work of Vazsonyi (30) and Giffler (9) will be drawn upon and modified in order to present a mathematical basis for the basic model. An algorithm will be developed on this mathematical basis, and Homer's (14) example will be used to demonstrate that the basic model developed preserves the solution obtained by Homer. Finally, the basic model will be discussed briefly, pointing out its benefits over the Homer technique.

The Mathematical Basis

As was discussed in Chapter III, a strong, but not completely valid, analogy can be drawn between a material assembly system and an information processing system. Indeed, it is common practice to represent an information processing system graphically as a flow diagram or flow chart. These flow charts are subject to exactly the same interpretation and conversion to matrix form as Vazsonyi's "Gozinto diagram" shown in Figure 3, and the flow diagram of Giffler's presentation (9, p. 4). The symbols used in the flow chart represent the systems ele-

ments, while the connecting lines represent the relations which exist between the elements. It is not usual in flow charts to express the number of lower level elements required for the next higher level, but this information could readily be added if desired.

An S matrix may then be defined as a matrix representation of the flow chart of the information system under study. The cells s_{ij} may be defined as the number of times a given system element i is used directly in preparation of system element j , which conforms exactly to the definition of n_{ij} in the materials assembly system.* In this basic algorithm, in order to conform to the practice of Lieberman and Homer, a cell s_{ij} will be equal either to one, if a relationship exists, or to zero if no relationship exists. This is an unneeded restraint to the basic algorithm, however.

Similarly, the S^* matrix of the basic algorithm corresponds with the T matrix of the materials assembly system. The cells s_{ij}^* of S^* may be defined as the quantity of i which is accumulated in the processing per unit of j .** It is also possible to define a consumption relation and corresponding matrix C, where the cells c_{ij} represent the total quantity of element i "consumed" in the preparation of element j , either

* The reader is referred to the summary of Vazsonyi's and Giffler's work presented in Chapter II in comparing the S, S^* , and C matrices to the N, T, and C matrices, and to the development in general.

** It will be shown in Chapter V that the definition of the S^* and C matrices in this chapter is inaccurate in an information processing system, and that observation of this inaccuracy is the basis for refinement of the technique. However, these definitions must be assumed in the basic algorithm in order to show correspondence to the techniques of Homer and Lieberman.

directly or indirectly. This matrix corresponds directly to the C matrix of Giffler's development.

In justification of the C matrix, Lieberman's basic notion can be examined.* His concept was to form a series of matrices, one for each level of the system under study. The first of this series, matrix M_S , represents as rows the items of data and as columns the source documents upon which they appear. The second matrix, M_1 , showed the source documents as rows, the first level of reports as columns. Subsequent matrices M_2, M_3, \dots, M_B , used the column designation of the preceding matrix as row designation, and the reports to be produced at that level as column designations. Lieberman's technique then consists of successive multiplication of the matrices to obtain a solution matrix,

$$M = (((\dots((M_S M_1)M_2)M_3)\dots)M_B) \quad (1)$$

Using this Lieberman technique as a point of departure, let there be defined a series of matrices to be multiplied together as above in order to obtain a final system matrix M. However, let the cells of the matrices be any arbitrary integer quantity, rather than being confined to zero or one as in the Lieberman model.

Assuming a three-level system, the matrices E, F, and G, shown in Table 9, can be defined, with the small letters in the cells denoting any arbitrary integers, and the numerals denoting system elements as rows and columns also being arbitrarily assigned. It would now be an

* See the summary of Lieberman's work in Chapter II.

easy matter to obtain the product matrix M for the three matrices, where $M = (AB)C = A(BC) = ABC$ because of associativity.

Leaving Lieberman's model, let now the same data be displayed in a single S matrix, according to the prior definition of S . Also, let S be partitioned as shown in Table 10.

Table 9. Matrices E , F , and G

$$E = \begin{array}{c|ccc} & 3 & 4 & 5 \\ \hline 1 & a & b & c \\ 2 & d & e & f \end{array}$$

$$F = \begin{array}{c|ccc} & 6 & 7 & 8 \\ \hline 3 & g & h & i \\ 4 & j & k & \ell \\ 5 & m & n & o \end{array}$$

$$G = \begin{array}{c|ccc} & 9 & 10 & 11 \\ \hline 6 & p & q & r \\ 7 & s & t & u \\ 8 & v & w & x \end{array}$$

Table 10. S Matrix (Partitioned)

	11	10	9	8	7	6	5	4	3	2	1
11	0	0	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0	0	0
9	0	0	0	0	0	0	0	0	0	0	0
8	x	w	v	0	0	0	0	0	0	0	0
7	u	t	s	0	0	0	0	0	0	0	0
6	r	q	p	0	0	0	0	0	0	0	0
5	0	0	0	o	n	m	0	0	0	0	0
4	0	0	0	l	k	j	0	0	0	0	0
3	0	0	0	i	h	g	0	0	0	0	0
2	0	0	0	0	0	0	f	e	d	0	0
1	0	0	0	0	0	0	c	b	a	0	0

It can be immediately recognized that the partitioning of S in Table 10 results in a 4 x 4 partitioned matrix S_p , where the original E, F, and G matrices are contained within the partitioned matrix. This can be displayed as:

$$S_p = \begin{pmatrix} 0 & 0 & 0 & 0 \\ G & 0 & 0 & 0 \\ 0 & F & 0 & 0 \\ 0 & 0 & E & 0 \end{pmatrix} \quad (2)$$

Now, by the ordinary rules of matrix multiplication and addition, the following matrices can be obtained:

$$S_P^2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ FG & 0 & 0 & 0 \\ 0 & EF & 0 & 0 \end{pmatrix} \quad (3)$$

$$S_P^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ EFG & 0 & 0 & 0 \end{pmatrix} \quad (4)$$

$$S_P^4 = (0) \text{ (Null)} \quad (5)$$

$$S_P + S_P^2 + S_P^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ G & 0 & 0 & 0 \\ FG & F & 0 & 0 \\ EFG & EF & E & 0 \end{pmatrix} \quad (6)$$

It is now noted that the product EFG found in S_P^3 is precisely the objective of the multiplication in the Lieberman model, and is therefore also the solution space in Homer's model. In addition, the products EF and FG in S_P^2 are seen to be the two-level relationships of the system, while the single level relationships are preserved in the S_P matrix. If the indicated multiplications of E, F, and G were per-

formed, and the results inserted in the right-hand side of Equation 6, the result would then meet precisely the definition given for the C matrix.

Therefore, by extension, the relationship

$$C = S + S^2 + S^3 + \dots + S^m \quad (7)$$

must hold, where m is the number of levels in the system under study.*

The definition of the matrix S^* now permits the observation that:

$$s_{ij}^* = \begin{cases} c_{ij}, & \text{if } i \neq j \\ 1 + c_{ij}, & \text{if } i = j \end{cases} \quad (8)$$

from which

$$\begin{aligned} S^* &= I + C \\ S^* &= I + S + S^2 + \dots + S^m \\ (I - S)S^* &= (I - S)(I + S + S^2 + \dots + S^m) \end{aligned} \quad (9)$$

and continuing by steps identical to those in the material systems case, the conclusion may be reached that

$$S^* = (I - S)^{-1} \quad (10)$$

* The foregoing argument helps to clarify the statement made by Giffler relative to the C and N matrices, Equation 9, Chapter II.

if the inverse exists. Since S is strictly triangular, $(I - S)$ must be triangular. In a triangular matrix, the determinant is equal to the product of the diagonal elements, therefore, since the determinant of $(I - S) = 1$, the matrix is non-singular, and $(I - S)^{-1}$ exists.

In summary, it is seen that the solution of Lieberman and therefore of Homer is imbedded within the more general solution of the $S - S^*$ matrix relationship. Furthermore, the S , C , and S^* matrices represent the information system in the same sense as the series of matrices of Lieberman, and the two modifications proposed by Homer. That the representation is not entirely adequate has already been commented upon, and later chapters will develop a more adequate representation.

Computational Considerations

It was previously noted (Chapter II, Equations (15) and (16)) that Giffler had developed iterative equations for the computation of the T matrix, given N . With appropriate changes of notation, these equations could form the basis for a computational algorithm for the computation of the S^* matrix. These equations, however, would require the storage in computer memory of the entire S matrix prior to the start of computation and would offer little, if any, possibility for data compression in memory. In any matrix operation using a digital computer, the problem of exceeding available memory capacity exists, and in this case will act as an upper bound on the number of systems elements which can be accommodated in the computation. Therefore, in order to permit overlap of input and computation, and to provide a basis for compression of data in computer memory, a modified algorithm has been developed.

which permits computation without storing the S matrix, which permits both compression of data and discarding of data as the computation progresses, and furthermore, will accommodate within its structure the more complex relationships to be developed in connection with the refined algorithms.

In the development to follow, it is assumed that S and S^* are lower triangular as a matter of expository convenience. With suitable changes, these matrices could be assumed to be upper triangular, with no loss of validity.

If S and S^* matrices are examined it is noted that the diagonal of S^* consists of cells each with the value of 1, placed there by the definition of S^* and the operation of Equation 8. Several of the columns on the right hand end of S^* have the diagonal 1 as the only non-zero entry in the column, and there are several other such columns scattered through the matrix. This condition will always exist, since these columns represent input elements.

It is now noted that every column, except for the diagonal 1, is a linear combination of the columns to the right of it, with the coefficients of the combination being specified by the corresponding column of the S matrix.*

It is also apparent that a given cell of the S matrix is required in the computation only once. Furthermore, the result would be the same, for a given column, if the order of multiplication and addition of col-

* It is for this reason that Homer was able to obtain his S^* matrix by a series of column operations.

umns were permuted, since the order of linear combination does not affect the value of the column vector.

This immediately suggests that a computer program could be written which would make use of the relationships shown above, by starting computation on the right hand end of the S^* matrix, and reading s_{ij} values from the bottom of the column up. This would also permit reading the s_{ij} from input, rather than storing them, since they will be used only once, in a systematic manner.

Based on the above, the following expression may be written, by means of which the j th column of S^* may be computed.

$$S_j^* = \sum_{k=j+1}^n s_{kj} S_k^* \quad \text{if } j < i \quad (11)$$

$$s_{ij}^* = 1 \quad \text{if } j = i \quad (12)$$

$$s_{ij}^* = 0 \quad \text{if } j > i \quad (13)$$

In these expressions, S_j^* is the j th column vector of S^* for cells below the diagonal, S_k^* is the k th column vector of S^* for $k > j$, and n is the total number of systems elements in the information processing system. It is assumed that computation will start with the rightmost column of S^* and proceed column by column to the left.

The Basic Algorithm

The basic algorithm for formation and solution of a system matrix is as follows: (The notation is the same as Homer's, for comparative purposes.)

1. Form the system matrix S according to the following rules:
 - a. Denote each item of information as d_i , each report or document by R_k , and each business function by B_r . The report level need not be specified. (In the example which follows they have been specified in order to conform to Lieberman's technique and Homer's notation for comparative purposes.)
 - b. Establish both a row and a column for each B_r , R_k , and d_i . The sequence of the rows and columns must be such that the business functions, B_k , are listed first, followed by the R_k reports, and finally the input data d_i . Within the R_k , the rule must be followed that no report precedes a report in which the first report is needed for the preparation of the second. The order of rows and columns must be identical.*
 - c. Define each cell as 1 if a data item d_i is used in a given report or directly by a business function, a report R_k is used in preparation of another report, or a report R_k is used by a business function B_r .

* An algorithm to be presented in conjunction with the refined model will furnish a simple means for assuring that the row and column designations of the S and S* matrices are properly ordered for triangularity.

Define all other cells as zero. The matrix so defined should be strictly lower triangular.

2. Prepare a format for the solution matrix S^* , with the same row and column designations in the same order as for the matrix S .

3. Place 1's on the diagonal of the solution matrix.

4. Start computation at the lower right hand corner cell. The computation will proceed column by column, from right to left until the left-most column has been completed.

5. Establish a column vector V , initially zeros, outside the S^* matrix. This is a working vector, and should contain as many cells as there are cells below and including the diagonal cell in the column of S^* which is currently being computed. The top cell of V corresponds to the diagonal element of the column being computed, while the bottom cell of V corresponds to the bottom cell of the column being computed.

(Note: In the first iteration there is but one cell, the diagonal itself. Computation of all the columns representing data items d_i is trivial, but necessary in computer operation from a conceptual point of view.)

6. Look at the corresponding column of the S matrix, starting at the bottom of the column. If this cell is non-zero, determine the row designation of the cell in question, and find the column with the same designation. If the cell is zero, repeat step 6 for the cell next above.

7. Multiply the column so obtained by the value of the non-zero cell, and add the result to V . Repeat steps 6 and 7, working up the column, until the diagonal is reached. When the diagonal is

reached, add the vector V to the column of the S^* matrix being computed. (The only non-zero entry in this column up to this point will have been the 1 on the diagonal.) Choose the column of the S^* matrix immediately to the left, and repeat from step 5. When all columns have been computed, a triangular matrix will have been generated, with 1's on the principal diagonal, and zeros above this diagonal.

A Comparative Example

In order to illustrate the proposed technique and in order to furnish a basis for comparison with Homer's method, the data from Homer's example have been used, and are shown in Figure 6, while the resultant S^* matrix is shown in Figure 7.

It will perhaps assist in understanding the foregoing algorithm if the computation of one of the columns is shown in detail. Since the first several columns are either trivial or easy to compute, the computation of the column labeled R5(2) will be treated. Assume that all columns of the S^* matrix to the right of R5(2) have been computed and entered as shown, and that R5(2) and all columns to the left have a 1 on the diagonal as the only non-zero entry. (Columns to the left of the column being computed, in both the S and S^* matrices cannot enter into the computation.) The computation starts with step 5 of the algorithm, and a column vector V , of 13 cells, initially zero, is established. In step 6, it is seen that the bottom cell of the R5(2) column of the S matrix is zero. Therefore, step 6 is repeated, and the second from the bottom cell is found to contain a 1. The row designation of this cell is d6. The multiplication of the correspondingly labeled

column by the cell value, and subsequent addition to the V vector, is shown in Table 11. Note that only column values below the diagonal are of interest, because of triangularity.

Step 6 is then repeated, finding zero values on the next six iterations. On the seventh iteration, a 1 is found, with the row designated as R3(1). The multiplication of the correspondingly labeled column by the cell value, and the addition to the previous V vector is shown in Table 12.

Table 11. Computation of Column R5(2)--First Step

Cell Value (From S)		Column d6 (From S*)		Product	Vector V
					0
					0
					0
					0
					0
					0
					0
					0
1	X	1	=	1	1
		0		0	0

	B1	B2	B3	B4	R1(2)	R2(2)	R3(2)	R4(2)	R5(2)	R6(2)	R1(1)	R2(1)	R3(1)	R4(1)	d1	d2	d3	d4	d5	d6	d7	
B1																						
B2																						
B3																						
B4																						
R1(2)		1	1	1																		
R2(2)	1	1		1																		
R3(2)	1			1																		
R4(2)																						
R5(2)		1	1																			
R6(2)	1																					
R1(1)					1			1	1	1												
R2(1)	1	1																				
R3(1)					1	1			1	1												
R4(1)						1	1															
d1												1		1								
d2											1	1		1								
d3														1								
d4											1			1								
d5												1										
d6					1			1	1	1												
d7	1	1	1																			

Blank cell denotes a zero entry.
 Data is same as in Homer's example (Figure 1).

Figure 6. S Matrix--Improved Technique

	B1	B2	B3	B4	R1(2)	R2(2)	R3(2)	R4(2)	R5(2)	R6(2)	R1(1)	R2(1)	R3(1)	R4(1)	d1	d2	d3	d4	d5	d6	d7	
B1	1																					
B2		1																				
B3			1																			
B4				1																		
R1(2)		1			1																	
R2(2)	1	1				1																
R3(2)	1						1															
R4(2)								1														
R5(2)		1	1						1													
R6(2)	1									1												
R1(1)	1	2	2	2	1		1	1	1		1											
R2(1)	1	1										1										
R3(1)	1	3	2	2	1	1		1	1				1									
R4(1)	2	1	2			1	1							1								
d1	2	4	2	2	1	1		1	1			1	1		1							
d2	3	6	4	4	2	1	1	2	2		1	1	1			1						
d3	1	3	2	2	1	1		1	1				1				1					
d4	2	5	4	4	2	1	1	2	2		1		1					1				
d5	1	1										1							1			
d6	1	2	2	2	1		1	1	1											1		
d7	1	1	1																			1

Blank cell denotes a zero entry.
Cells in Homer's "Solution Spaces" are outlined.

Figure 7. S^* Matrix--Improved Technique

Table 12. Computation of Column R5(2)--Second Step

Cell Value		Column R3(1)	=	Product	Vector V
					0
					0
					0
					0
1	X	1	=	1	1
		0		0	0
		1		1	1
		1		1	1
		1		1	1
		1		1	1
		0		0	0
		0		0	1
		0		0	0

Step 6 is again repeated, and a zero cell encountered. The next repetition of step 6 finds a 1 with a row designation of R1(1). Table 13 details the computation for this cell.

Table 13. Computation of Column R5(2)--Third Step

Cell Value		Column R1(1)	=	Product	Vector V
					0
					0
1	X	1	=	1	1
		0		0	0
		0		0	1
		0		0	0
		0		0	1
		1		1	2
		0		0	1
		1		1	2
		0		0	0
		0		0	1
		0		0	0

Another repetition of step 6 again finds a zero value in the S matrix, while yet another encounters the diagonal cell. At this point the vector V is added to the R5(2) column of the S^* matrix, which was previously zero except for the diagonal element. This gives the result shown in this column in Figure 7.

Discussion

The cells in Figure 7 corresponding to the cells in the "solution space" of Homer's S^* matrix in Figure 2 have been outlined. A comparison of the two figures shows that the cell values of corresponding cells are identical in value, although the arrangement of cells is somewhat different. It is thus seen that the proposed technique reproduces Homer's basic results, as was also shown in the mathematical development.

In addition, it will be noted that the S^* matrix of the proposed technique preserves all original and intermediate information system relationships. For example, several of the reports are intermediate reports, and their data content was lost in the Homer model unless auxiliary computations were made. The presented technique clearly defines the composition of all of these intermediate reports, which might in a real system be important working documents. Furthermore, if redundancy does indeed exist, a basis is furnished for tracing this redundancy through the information system.

In summary, it appears that this model is an improvement to the existing models, and resolves Homer's objections to the Lieberman model. Except for benefits one and four, the benefits of Homer's model are met or exceeded. As will be seen in subsequent chapters, a triangulariza-

tion procedure will be presented which would, in conjunction with this basic model, also result in meeting benefits one and four.

Further discussion of the interpretation and manipulation of the S and S^* matrices, and their use in systems design could be made at this time. However, both the Homer model and the one just presented have serious limitations in practice, due to failure to consider certain differences in data types and in presenting spurious indications of redundancy. These limitations have been discussed in Chapter III and techniques will be developed to eliminate or minimize them in later chapters.

CHAPTER V

THE REFINED MODELS--MATHEMATICAL DEVELOPMENT

Introduction

This chapter will treat the mathematical considerations pertaining to the refined models. Since efficient computer manipulation of the refined models depends on the triangular nature of the S and S' matrices to be defined, the first portion of the chapter will deal with the logic of triangularization. Following this portion, a mathematical treatment of the refinements will be developed, wherein the several objections inherent to the basic model will be resolved.

Notation

The three categories of systems relations defined and discussed in Chapter III cause very different action in the refined algorithms. It is therefore necessary to define the notation to be used, and the rules of computation within and between the three categories of relation prior to pursuing the mathematical development.

The three categories of relation will carry notation and quantification as follows:

1. Prime relations will be denoted by a pair (i, j) where j is the identification of the element which requires the i th type of element in its preparation. The number of i elements required will be denoted by a non-negative integer, k .*

For example, the designation $D1\ W1\ 1$ denotes a prime relation where element $W1$ requires one of element $D1$ in its preparation. All input elements will result in an arbitrary prime relation, and an arbitrary designation pair $(0,j)\ 1$. As will be seen, this designation is necessary in order that triangularization of the S matrix may be accomplished.**

2. Deletion relations will be denoted by a pair (i,j) where j is the identification of the element from which the i th element is to be deleted. The deletion itself is denoted by the negative integer -1 . The character 1 is symbolic, rather than numeric, and any negative integer will have the same effect of deleting all reference to the i th element from the j th element, and from higher level elements which in turn use the j th element.

For example, the designation $C1\ R1\ -1$ denotes a deletion relation where reference to element $C1$ is to be deleted from element $R1$ and from all subsequent elements which use $R1$.

For brevity, the terminology "pairs (i,j) " or simply "pairs" will be used in future discussion to refer to the above notations when such use is not confusing.

3. Concomitant relations will be denoted by an n -tuple (i,j, k, \dots, n) of element identifications where j is the identification of the

* In practical operation, if no relation exists, a zero will be assumed.

** The designations used as examples, may be seen in graphic form in Figure 9, Chapter VI.

compound element wherein the result of the computation or transition will reside, i is the identification of the simple element being computed, and k, \dots, n are identifications of the factors (simple elements) entering the computation or transition. The relation is quantified by the symbol (c) , where c is an integer. The symbol (c) has special multiplication-like properties in the operation of the algorithms.

As an example of the notation of concomitant relations, the designation $C1 W3 D3 S1 (1)$ denotes the fact that simple elements $D3$ and $S1$ are used in the computation of simple element $C1$, this computation arising in the preparation of compound element $W3$, and that simple element $C1$ appears in compound element $W3$. The designation $C4 R2 C2 (1)$ indicates that simple element $C2$ makes a transition to become simple element $C4$, this transition arising in the preparation of compound element $R2$, and $C4$ appears in $R2$.

Note that a concomitant relation has at least three, and up to (finite) n , element designations. In the formation of the S matrix, the quantifier (c) pertains to the relation (i,j) and to the relations (i,k) , (i,l) , \dots , (i,n) , but does not pertain to the relations between j and subsequent indices nor k and subsequent indices.

In the computation of the algorithms to be presented, the symbol (c) has special properties which are defined as follows, where (c) is the quantifier for a concomitant relation, \ast is the operator in the multiplication-like operation being defined, k is a non-zero integer, and 0 is an ordinary numeric zero:

$$(c) \times k = (ck) = k \times (c)$$

$$(c) \times 0 = 0 = 0 \times (c)$$

$$(c_1) \times (c_2) = 0$$

The symbol (c) behaves as in ordinary addition for addition with zero; that is, $(c) + 0 = 0 + (c) = (c)$. It will later be shown that addition of (c) with values other than zero never arises.

Triangularization

Triangularization is an essential part of the computational technique leading to the solution matrices of the refined models. In order to obviate tedious labor on the part of the systems analyst, it is desirable that this triangularization be done by mechanical means, and that the computational system accept designations of systems elements which are entirely arbitrary. It is necessary that the designations of the systems elements be consistent and unique. That is, each system element must be designated by one and only one set of characters, and different elements must not be given the same designation.

The arrangement of a matrix which is triangular in nature into triangular form is essentially a matter of interchanging rows and columns until the desired arrangement is reached, and is therefore a logical rather than a mathematical problem. There are many ways of accomplishing this task, most of which are not adaptable for machine operation. Giffler (9, p. 18-34) describes one such method for triangularization. This method, however, has several limitations which will be discussed in Chapter VII. An algorithm will also be presented

in Chapter VI which is readily adaptable to mechanization, and which overcomes the objections to the Giffler method.

The essential basis for the new algorithm rests on the definition of triangularity derived from observation of the triangularized matrix. Restated in terms of an information processing system and of lower triangularity, the S matrix (and therefore the S^* matrix) will be lower triangular if the row and column indices of S are both assigned in the same order, and in such a manner that the index of a given system element precedes the indices of every system element which is required in its preparation.

In order to take arbitrarily identified and arbitrarily ordered pairs of elements between which some relationship exists and place these pairs in a relationship such that the preceding definition holds, the following can be noted:

1. In any information system, there are two subsets of elements which are unique. One of these subsets is the subset of elements comprising the input elements, and which is unique in the fact that no other elements are required in their preparation. The other is the subset of elements comprising the output from the system, which is unique in the fact that these elements are never required in the preparation of other system elements.

2. If one or the other of these two subsets of elements can be identified, it can be removed from the set of all elements. Assume that the output subset is identified, and that all elements of the output subset are removed from the system. There will then exist another subset of systems elements which were formerly required only for the

preparation of the output subset, and which now has the same property as the removed subset; that is, that these elements are not required in the preparation of other (reduced) system elements.

3. If this subset can be identified and removed, then the argument of 2, above, can be repeated for the further reduced system. The argument can indeed be repeated, removing successively lower levels of subsets, until the lowest level (input) only remains, and this level has already been shown to be unique. The same argument would apply if the input subset were assumed to be the first identified and removed. In this case, successively higher levels of subsets would be removed, until only the output subset remained.

Consider now the set of all pairs (i,j) where j is the arbitrary designation of a system element which requires the i th system element in its preparation, and where each input element causes the formation of a pair $(0,j)$ reflecting the fact that no element is required for the preparation of an input element. Clearly, the input subset can be identified by recognition of the $i = 0$ in the pair (i,j) . The output subset can be recognized as the subset of pairs (i,j) which have an identification j which does not appear in any pair (i,j) as an i index. Now assume that the output subset is removed from the set, leaving a reduced set. The removal of the pairs (i,j) of the output subset removed, in addition to the unique j 's, the identification i of all elements required for preparation of the elements j . These i identifications still exist, however, as j identification on some elements remaining in the reduced set. At least some of the remaining elements in the set were required only for preparation of the removed j elements.

These elements can now be recognized by the same method used to recognize the original output subset; that is, as a subset of pairs (i,j) which have an identification j which does not appear in any pair (i,j) as an i index. By repetition, the entire set can be exhausted, one subset at a time. This will produce the desired triangular condition.

Basis for Refinement

Having established the basis for the basic model and for triangularization, it is now pertinent to turn attention to the additional considerations leading to the refined algorithms. The primary considerations involve the recognition of the existence of three data types, the several types of transitions, and the three categories of system relations defined in Chapter III. Other substantiating information can be gathered from the section "The Mathematical Basis" in Chapter IV. In this latter, it was noted that both the S^* and C matrix definitions, while accurate for the basic algorithm in order to show correspondence to the techniques of Lieberman and Homer, were not accurate in their description of an information processing system.

Consider first the S^* matrix. It was defined, in analogy to the T matrix of the material assembly system, as the matrix wherein the cells s_{ij}^* are defined as the quantity of i which is accumulated in the processing per unit of j. The inaccuracy of this definition lies in the fact that data in a data system do not "accumulate" in the sense implied, and that therefore the analogy to the material system breaks down. Rather than "accumulate" in a physical sense, data are only reproduced, or copies, in their movement from level to level of a system.

Rather than being used up, in the sense of materials, they are in essence only borrowed, for the purpose of copying, and their basic form is not changed through the pure act of copying or transcribing from one form to another. It is this false accumulation which gives false indications of redundancy in the basic S^* matrix.

By the same argument, the C matrix is also ill-defined and erroneous in its representation of the true system. This matrix, where c_{ij} represents the total quantity of element i consumed in the preparation of element j, also carries the connotation that data are physically "used up" in preparation of a higher level element, and are no longer available for use elsewhere in the system. In both of these matrices, the connotation is carried that if five reports require a given piece of data, then these data must be supplied as five separate pieces.

These two matrices also do not recognize the fact that unlike a materials system, in which all the matter which enters the system subsequently leaves the system imbedded within some finished product (neglecting waste), in a data system some of the elements are lost irretrievably during the course of processing. For example, type two data make an irreversible transition to type three data, and the type two data progress no further or are even destroyed.

Furthermore, the two matrices do not recognize the fact that elements are created within a system (e. g., a multiplication of two numbers) in which lower level system elements are used, but do not appear as such within the element created, and in which the substance of the lower level elements is completely lost. In a material assembly system, the fitting of two parts together physically results in a new element,

but generally the two contributing elements are still physically present and frequently physically recognizable. Such is not always true when information system elements are combined to form new elements.

The recognition of data types and data transitions, together with the recognition of the shortcomings of the existing S^* and C matrices, furnish a basis for reformulation of the systems relations and redefinition of the matrices, so that refined algorithms can be developed.

The reformulation of the system relations takes the form of defining three categories of system relations--prime, concomitant, and deletion. These have been defined in Chapter III, and notation assigned in a prior section of this chapter. Recognition of these three categories also permits development of two separate, but similar, means of analysis, one on the basis of the composition of reports, the other on the content of reports. The composition type analysis will be developed first.

Development of Composition Type Analysis

The composition type of analysis will depend on the two categories of relations denoted as prime and concomitant. Using these two relations, the S matrix need not be redefined. The cells s_{ij} have been defined as the number of times a given system element i is used directly in the preparation of system element j . Both prime and concomitant relations meet this definition, prime in the sense of use by being transcribed, concomitant in the sense of elements being used in computation or in a transition from type two to type three data.

S^* must be redefined to include both types of system relations. The cells s_{ij}^* of S^* are now defined as the number of times the data element i is used or is available for use in the preparation of data element j . The "or is available for use" provides for indication of true redundancy, while the concurrent use of both prime and concomitant relations prevents indication of false redundancy, as will be shown later. The unit diagonal cells are not so explicitly contained in this definition, but should be construed to be included, if only by the plausible argument that some form is required upon which to record the contributing elements.

The C matrix, used only in the development, must also be redefined. Due to its identity to the S^* matrix, except for the unit diagonal elements, it should be similarly defined. The cells c_{ij} of C are now defined as the number of times the data element i is used or is available for use in the preparation of data element j , either directly or indirectly.

The essential difference between the C and S^* matrix, other than the evident one that S^* has unit cells on the diagonal, is that the elements of C contain the information desired in the analysis, but is difficult to compute, while S^* contains the same information, but because of the diagonal 1's is easy to compute. Conversely, it is difficult to develop the connection between the S and S^* matrix without using the concept of the C matrix. Therefore, the C matrix, with its similarity to the S^* matrix is convenient to use in developing the mathematical background, but can be dispensed with in numerical computation.

The development follows the development of the basic model to some extent, except that the matter is more complex, due to the introduction of the concomitant relation and its quantifier (c). As mentioned in a previous section, this quantifier leads to some multiplication-like operations. These operations were developed in consideration of the method to be used in computing the S^* matrix and may be justified on that basis. If the symbol (c) appears to the left of the operator \times , it will be used in computation as a scalar multiplying a vector on the right of the operator. If it appears on the right of the operator, it will be in the role of a cell in a vector.

Properties of Matrices

In the proof of the basic model, the common property of associativity of matrices was assumed in order to show that $C = S + S^2 + \dots + S^m$. In order to follow a similar proof for the refined model, it is now desirable to examine the system of matrices which might be formed representing the relationships between two adjacent system levels. These matrices are of the Lieberman-Homer type, except that both regular scalars and concomitant relation quantifiers are present in the matrix. These matrices are analogous to the matrices E, F, and G in the proof of the basic algorithm.

In consideration of the definition of prime and concomitant relations, several observations can immediately be made relative to the structure of these matrices, and may be stated as axioms. Prior to stating these axioms, however, some terms will be defined in order to shorten the discussion to follow.

Definitions.

Concomitant index is a row or column index in a matrix wherein the row or column index is the identification of a system element which is formed as a result of a concomitant relation.

Regular index is a row or column index in a matrix wherein the row or column index is the identification of a system element which is formed as a result of a prime relation.

A concomitant cell in a matrix is a cell wherein the value is a concomitant relation quantifier, (c).

A regular cell in a matrix is a cell wherein the value is a regular scalar, n.

System Matrix Axioms.

Axiom 1. The lowest level system matrix will never have a concomitant index as a row index, since all row indices refer to input elements which have been defined to have a prime relation.

Axiom 2. A given concomitant index will appear first as a column index in the matrix representing the level at which the element is formed, and as a row index in the matrix representing the next higher system level. This follows directly from the definition and notation for concomitant relation.

Axiom 3. A concomitant index may appear as both a row and column index in the case where an element created by a concomitant relation is subsequently used to create another concomitant relation.

Axiom 4. If a concomitant index is a column index, then the cells of that column will have only the values zero or (c); that is, concomitant cells, because the entire column is defined by the i, k, \dots, n indices of the concomitant n -tuple (i, j, k, \dots, n) with a single quantifier.

Axiom 5. If a concomitant index is a row index, then the cells of that row will be concomitant cells, with value zero or (c). In this case the row is defined either by the i, j indices of a concomitant n -tuple, or by the creation of a new concomitant element using a previously created concomitant element.

Matrix Multiplication. Consider two matrices, A and B, conformable for multiplication in the usual sense. Under the usual rules for multiplication of matrices, the element in the (i, k) cell of $AB = (d_{ik})$ is:

$$d_{ik} = \sum_j a_{ij} b_{jk} \quad (1)$$

In matrix multiplication where the matrix consists of both regular and concomitant cells, three cases can be distinguished. Since in all cases the index j may be either a regular or concomitant index, the set of indices j may be divided into two subsets:

$$j_1 = [j: j \text{ is a regular index}],$$

$$j_2 = [j: j \text{ is a concomitant index}].$$

Then the matrix multiplication may be written as:

$$d_{ik} = \sum_{j \in j_1} a_{ij} b_{jk} + \sum_{j \in j_2} a_{ij} b_{jk} \quad (2)$$

Case 1. In this case, both i and k are regular indices. Then:

$$d_{ik} = \sum_j a_{ij} b_{jk} = \sum_{j \in j_1} a_{ij} b_{jk} + \sum_{j \in j_2} a_{ij} b_{jk} = n \text{ (or zero)}. \quad (3)$$

The summation over $j \in j_1$ in this case consists of multiplication of regular cells. The summation over $j \in j_2 = 0$, since by Axioms 4 and 5, both a_{ij} and b_{jk} are either zero or (c) , and by prior definition, $0 * (c) = 0 = (c) * 0$, and $(c_1) * (c_2) = 0$. Therefore, d_{ik} is either zero or a regular cell, n .

Case 2A. In this case, i is a regular index and k is a concomitant index. Then:

$$d_{ik} = \sum_{j \in j_1} a_{ij} b_{jk} + \sum_{j \in j_2} a_{ij} b_{jk} = (c) \text{ (or zero)} \quad (4)$$

In summation over $j \in j_1$, a_{ij} is a regular cell, b_{jk} is a concomitant cell or zero by Axiom 4. Therefore the result of this portion of the summation is a concomitant cell (c) . In summation over $j \in j_2$, a_{ij} is either zero or (c) by Axiom 4, and b_{jk} is either zero or (c) by Axiom 3 or 4. This summation is therefore zero, and d_{ik} is either zero or a concomitant cell (c) .

Case 2B. If i is a concomitant index and k is a regular index,

then

$$d_{ik} = \sum_{j \in j_1} a_{ij} b_{jk} + \sum_{j \in j_2} a_{ij} b_{jk} = (c) \text{ (or zero)} \quad (5)$$

In summation over $j \in j_1$, a_{ij} is either zero or (c) by Axiom 4 and b_{jk} is a regular cell. As in Case 2A, the result is a concomitant cell (c) or zero. The summation $j \in j_2 = 0$, as in prior cases, since both a_{ij} and b_{jk} must be either zero or (c). Therefore, d_{ik} is either zero or a concomitant cell (c).

Case 3. Both i and k are concomitant indices, and

$$d_{ik} = \sum_{j \in j_1} a_{ij} b_{jk} + \sum_{j \in j_2} a_{ij} b_{jk} = 0 \quad (6)$$

In this case, the summation over $j \in j_1 = 0$ and the summation over $j \in j_2 = 0$, since all a_{ij} and b_{jk} are either zero or (c). Therefore, $d_{ik} = 0$.

Based on the above cases, the following Lemmas can be stated:

Lemma 1. In matrix multiplication where both concomitant and regular indices and cells are present, if indices i and k are both regular indices, then the product cell d_{ik} is a regular cell, n, or zero.

Lemma 2. If either i or k is a concomitant index, and the other index is a regular index, then d_{ik} is a concomitant cell, (c), or zero.

Lemma 3. If both i and k are concomitant indices, then the product cell $d_{ik} = 0$.

Lemma 4. $\sum_{j \in j_2} a_{ij} b_{jk} = 0$, regardless of the i and k indices.

Lemma 5. The addition $(c) + n$, for $n \neq 0$, never occurs in the matrix multiplication, so it is therefore unnecessary to define addition involving concomitant relation quantifiers other than $(c) + 0 = 0 + (c) = (c)$.

Theorem 1. (Associativity) In series of matrix multiplications involving matrices with both regular and concomitant indices and cells, multiplication is associative.

The proof is as follows. Consider three matrices P , Q , and R , conformable for multiplication in the usual sense, and composed of both regular and concomitant cells, and indexed by both regular and concomitant indices. From the immediately prior results, the element in the (i,k) place in PQ , d_{ik} , is

$$d_{ik} = \sum_{j \in j_1} p_{ij} q_{jk} \quad (7)$$

and the element in the (i,ℓ) place in $(PQ)R$ is

$$b_{i\ell} = \sum_{k \in k_1} d_{ik} r_{k\ell} = \sum_{k \in k_1} \sum_{j \in j_1} p_{ij} q_{jk} r_{k\ell} \quad (8)$$

where summations over $j \in j_2$ and $k \in k_2$ are omitted because of Lemma 4.

The (i, ℓ) place in $P(QR)$, $b'_{i\ell}$, may be similarly computed. The (j, ℓ) place of QR has the element $c_{j\ell}$,

$$c_{j\ell} = \sum_{k \in k_1} q_{jk} r_{k\ell}, \quad (9)$$

and the (i, ℓ) place of $P(QR)$ is

$$b'_{i\ell} = \sum_{j \in j_1} p_{ij} c_{j\ell} = \sum_{j \in j_1} \sum_{k \in k_1} p_{ij} q_{jk} r_{k\ell}. \quad (10)$$

In view of the mixing of regular and concomitant indices and cells, it is now pertinent to show that the (i, ℓ) place of PQR is identical regardless of the order of multiplication and summation. There are 16 combinations of the four indices i, j, k , and ℓ . These combinations are shown in Figure 8, together with the $d_{ik}, c_{j\ell}$,

$\sum_{k \in k_1} d_{ik} r_{k\ell}$, and $\sum_{j \in j_1} p_{ij} c_{j\ell}$ established through the application of Lemmas 1 through 5. It is seen that in all 16 combinations, identical results are obtained regardless of order of summation, so that the conclusion may be reached that $d_{i\ell} = d'_{i\ell}$.

In combination 1, all indices are regular, and the resulting cell is regular or zero by Lemma 1.

In combination 2, i is regular, k is regular, and $j \in j_1$, so d_{ik} is a regular cell or zero. However, ℓ is a concomitant index, so $b'_{i\ell}$ is concomitant or zero by Lemma 2. Now, j is regular, ℓ is concomitant, and k is regular, so that $c_{j\ell}$ is a concomitant cell or zero

Index Combination	Index				d_{ik}	$c_{j\ell}$	$b_{i\ell}$	$b'_{i\ell}$
	i	j	k	ℓ				
1	R	R	R	R	n	n	n	n
2	R	R	R	C	n	(c)	(c)	(c)
3	R	R	C	R	(c)	0	0	0
4	R	C	R	R	0	(c)	0	0
5	C	R	R	R	(c)	n	(c)	(c)
6	R	R	C	C	(c)	0	0	0
7	R	C	R	C	0	0	0	0
8	C	R	R	C	(c)	(c)	0	0
9	R	C	C	R	0	0	0	0
10	C	R	C	R	0	0	0	0
11	C	C	R	R	0	(c)	0	0
12	C	C	C	R	0	0	0	0
13	C	C	R	C	0	0	0	0
14	C	R	C	C	0	0	0	0
15	R	C	C	C	0	0	0	0
16	C	C	C	C	0	0	0	0

R = Regular Index.

n = Regular Cell.

C = Concomitant Index.

(c) = Concomitant Cell.

$$b_{i\ell} = \sum_{k \in k_1} d_{ik} r_{k\ell}$$

$$b'_{i\ell} = \sum_{j \in j_1} p_{ij} c_{j\ell}$$

Figure 8. Index Combinations and Resultant Cell Values in Successive Matrix Multiplication.

by Lemma 2. But again, since i is regular, Lemma 2 indicates that $b'_{i\ell}$ is a concomitant cell or zero. Combination 5 results in a concomitant or zero cell by a similar argument.

All other combinations result in $b_{i\ell} = b'_{i\ell} = 0$. In the combinations 7, 9, 10, 12, 13, 14, 15, and 16, both d_{ik} and $c_{j\ell}$ are zero by either Lemma 3 or Lemma 4. In combination 3, $c_{j\ell} = 0$ by Lemma 4, so $b'_{i\ell} = 0$. The cell d_{ik} is concomitant by Lemma 2, then $b_{i\ell} = 0$ by Lemma 4. A similar argument holds for combinations 4, 6, and 11. In combination 8 both $b_{i\ell}$ and $b'_{i\ell}$ are zero by Lemma 3, as both i and ℓ are concomitant indices. This Lemma would also apply to combinations 10, 13, 14, and 16.

It will also be useful to prove the following theorem:

Theorem 2. (Existence of Identity) $IA = A = AI$, where A is a matrix with both regular and concomitant cells, and I is an identity matrix of proper size and in the usual sense.

In proof, let $a'_{j\ell}$ be the (j,ℓ) cell of IA . Then

$$a'_{j\ell} = \sum_k \delta_{jk} a_{k\ell}, \quad (11)$$

where δ_{jk} is the Kronecker delta. Then since $1 * (c) = (c)$ by definition, it is evident that both regular and concomitant cells are preserved under this multiplication, and $IA = A$. In the same manner, if a''_{km} is the (k,m) cell of AI ,

$$a''_{km} = \sum_l a_{kl} \delta_{lm}, \quad (12)$$

and $AI = A$.

Development of the "Composed of" Model

As in the case of the basic algorithm, the system relations expressed in the S matrix may also be expressed in a series of matrices, where each matrix represents the relations, both prime and concomitant, which exist between two adjacent levels of the information system under study. Because of the nature of concomitant relations, and to permit the entry and exit of systems elements at any level, a technique similar to Homer's first method must be used in order to force conformability of these matrices for multiplication. The following rules will assure such conformability:

1. Assume an n -level information system, with between level matrices A, B, C, \dots, N . Start with the lowest level matrix, A , and write as row indices the identification of all input elements.
2. Write as column indices of A the identification of all elements which use, on either a prime or concomitant basis, the input elements listed in the rows.
3. Enter in the cells of A the appropriate quantifier, either prime or concomitant.
4. Write as row indices for the next higher system matrix B the column indices of matrix A .
5. Write as column indices of B the identification of all elements which use, on either a prime or concomitant basis, the elements listed in the rows.
6. Enter in the cells of B the appropriate quantifier, either prime or concomitant.

7. Continue in this manner for matrices C, D, ..., N. The column indices of N will all be the identification of output reports, but some output reports may not be present due to leaving the system at a lower level. Some matrices will show a given identification as both a row and a column index, due to higher level elements being composed of elements from more than one lower level.

Consider now a three level system, with matrices P, Q, and R, defined and established as above. The letters in the cells of the matrices in Table 14 are arbitrary quantifiers, either prime or concomitant, subject to the definition of these relations, and to the previously shown Lemmas relative to formation of matrices consisting of both prime and concomitant elements.

Let the matrices P, Q, and R be as shown in Table 14. Note that the matrix R has element 8 as both a row and column index, which is interpreted as the fact that elements enter element 8 at two levels. The cell R_{88} is of course empty.

In a manner corresponding direct to the argument advanced in developing the basic algorithm, these three matrices might now be multiplied together in the manner of the Lieberman model, and the products PQ, QR, and PQR would contain the information relative to indirect system relations.

Also in a manner corresponding to the development of the basic algorithm, let the same data be displayed in a single matrix S_a , where S_a differs from S only in that element 8 appears twice as both a row and column index, but without duplication of non-zero information. Also, let S_a be partitioned into the 4 x 4 matrix shown in Table 15.

Table 14. Matrices P, Q, and R

	4	5
1	a	b
2	c	d
3	e	f

	6	7	8	9
4	g	h	i	j
5	k	l	m	n

	8	10
6	o	p
7	q	r
8	-	s
9	t	u

This partitioned matrix can be represented by the following matrix, where the original matrices P, Q, and R are contained within the partitioned S_a matrix:

$$S_a = \begin{pmatrix} 0 & 0 & 0 & 0 \\ R & 0 & 0 & 0 \\ 0 & Q & 0 & 0 \\ 0 & 0 & P & 0 \end{pmatrix} \quad (13)$$

Table 15. The S_a Matrix

	8	10	6	7	8	9	4	5	1	2	3
8	0	0	0	0	0	0	0	0	0	0	0
10	0	0	0	0	0	0	0	0	0	0	0
6	o	p	0	0	0	0	0	0	0	0	0
7	q	r	0	0	0	0	0	0	0	0	0
8	0	s	0	0	0	0	0	0	0	0	0
9	t	u	0	0	0	0	0	0	0	0	0
4	0	0	g	h	i	j	0	0	0	0	0
5	0	0	k	l	m	n	0	0	0	0	0
1	0	0	0	0	0	0	a	b	0	0	0
2	0	0	0	0	0	0	c	d	0	0	0
3	0	0	0	0	0	0	e	f	0	0	0

Now, since Theorem 1 assures associativity of matrix multiplication, and since addition of concomitant relation quantifiers with zero is defined, the following matrices can be obtained:

$$S_a^2 = \left\{ \begin{array}{cccc} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ QR & 0 & 0 & 0 \\ 0 & PQ & 0 & 0 \end{array} \right\} \quad (14)$$

$$S_a^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \text{PQR} & 0 & 0 & 0 \end{pmatrix} \quad (15)$$

S_a^4 is null.

$$S_a + S_a^2 + S_a^3 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ R & 0 & 0 & 0 \\ \text{QR} & Q & 0 & 0 \\ \text{PQR} & \text{PQ} & 0 & 0 \end{pmatrix} \quad (16)$$

It is now noted that in S_a^2 the intermediate level products PQ and QR are found, and that in S_a^3 the product PQR is found. The summation of the three matrices, when expanded to the original dimension of S_a , meets the definition of C_a , where C_a is the same as C except for the fact that element 8 appears twice as a row and a column index. Since this is purely a matter of notation, S_a is equivalent to S, and C_a is equivalent to C. C_a can be converted to C, while still preserving triangularity, by adding the right-most column 8 to the other column 8, then removing any duplication between the two rows with index 8, and deleting the lower of the two rows.

It has therefore been shown that

$$C_a = S_a + S_a^2 + S_a^3 + \dots + S_a^m$$

and because of the equivalence of C_a and C , S_a and S ,

$$C = S + S^2 + S^3 + \dots + S^m . \quad (17)$$

By definition of the matrix S^* ,

$$S^* = I + C \quad (18)$$

$$S^* = I + S + S^2 + S^3 + \dots + S^m . \quad (19)$$

Then, multiplying both sides by $(I - S)$ and carrying out the multiplication,

$$(I - S)S^* = (I - S)(I + S + S^2 + \dots + S^m)$$

$$(I - S)S^* = I^2 - S + S - S^2 + S^2 - \dots -$$

$$S^m + S^m - S^{m+1} .$$

But S^{m+1} is null, and $I^2 = I$, so

$$(I - S)S^* = I \quad (20)$$

and multiplying through by $(I - S)^{-1}$,

$$S^* = (I - S)^{-1} . \quad (21)$$

That this inverse exists is shown by observing that $(I - S)$ is triangular by definition, with determinant $|(I - S)| = 1$. $(I - S)$ is therefore non-singular, and the inverse exists.

It has been shown then that S and S^* have the same relation when concomitant indices and quantifiers are employed as in the basic algorithm when all systems relations were presumed to be prime. The computation also proceeds in the same general manner, except that special rules pertaining to "multiplication" obtain when concomitant relation quantifiers are encountered. An example will be presented in Chapter VI.

Development of Containment Type Analysis

The containment type of analysis depends on all of the three categories of relations, defined as prime, concomitant, and deletion. The addition of the deletion relation requires a redefinition of both the S matrix and the S^* matrix. These redefined matrices will be denoted S' and S'^* , respectively.

As noted in the earlier section of this chapter entitled "Notation," the deletion relation quantifier -1 is symbolic, rather than numeric. Furthermore, the deletion relation leads to an operation in the computation of the S'^* matrix which is logical rather than arithmetic in nature. For this reason, it is not possible to offer a development of the computational procedure on a mathematical basis, but only a development on the logical basis. In fact, it can be shown, by attempting the multiplication, that

$$S'^*(I - S') \neq I \quad (22)$$

and that therefore the relationship between the S and S^{*} matrices shown in the previous section is not true for S' and S'^{*}.

Definition of S' and S'^{*} Matrices

In the definition of the S matrix, the cells s_{ij} were defined as the number of times a given system element i is used directly in the preparation of system element j, where both prime and concomitant relations met the definition. In the case of prime relations, however, where the i index of the relationship is the identification of a compound element, the compound element itself (a report, tape record, or the like) will not physically appear, or be "contained in" the compound element denoted by the j index of the prime relationship. Furthermore, some of the simple elements included within the ith compound element may neither be used nor contained in the jth element.

In order to exclude the ith compound element from appearing in the jth compound element of S'^{*}, a change in definition of the solution matrix and a change of computational method is required. The exclusion of the unused simple elements within the ith compound element leads to the deletion relation and a corresponding change in definition of the matrix S'.

The matrix S' is now defined as that matrix where the cells s'_{ij} represent the number of times a given system element i is used directly in the preparation of system element j in the case of prime and concomitant relations, and as the simple system element k which is contained in compound element i, but which will not physically be included

in compound element j in the case of a deletion relation.

The matrix S'^* is defined as that matrix where the cells s'_{ij} represent the number of times the simple data element i which actually appears in compound element j is used or is available for use in preparation of data element j .

It should be noted that the definition of S' represents the inclusion of the deletion relation in the previously defined S matrix, while the definition of S'^* represents the blocking out of any element, simple or compound, which does not actually appear in a given compound element.

Effect on Computation

The effect on computation, in comparison to computation of the "Composed of" matrix S^* , is that of adding two logical operations to the mathematical operation of inverting the $(I - S')$ matrix. These two logical operations prevent the realization of a true inverse, but result in the definition of S'^* being met in the solution.

The first logical operation is the prevention of any compound element from appearing in another compound element in S'^* . This is done by recognizing that any column in S'^* which contains a non-zero entry other than on the diagonal is compound; and that the diagonal element, which represents the compound element itself, must be ignored in the computation of an element at a higher system level.

The second logical operation is the preventing of any reference to a simple element from appearing in a compound element where a deletion relation is indicated in the S' matrix. This is done by the simple method of merely viewing the presence of a deletion relation in s'_{pq} as

a block to permitting any entry, prime or concomitant, from appearing in the corresponding cell, s'_{pq}^* of S'^* . This in turn will prevent the carrying of the deleted element to any higher level compound element.

The algorithm for computation of the S'^* matrix to be presented in the next chapter will therefore bear a strong resemblance to the algorithm for computation of S^* , except for provision for carrying out the two logical operations indicated above in addition to the mathematical operations leading to what might be called a pseudo-inverse of $(I - S')$.

CHAPTER VI

THE REFINED MODELS--ALGORITHMS AND EXAMPLES

Introduction

Based on the development of Chapter V, this chapter will present algorithms by means of which the specifications of systems relations prepared by the systems analyst may be arranged in the required triangular form and the computation of the system solution matrices S^* and S'^* performed. At this time, the algorithms are presented for expository purposes as algorithms for manual computation. They were developed specifically, however, for machine computation, and Chapter VII and the Appendices contain further discussion of the implications of machine computation and restatements of the algorithms in language more appropriate for such use. In order to illustrate the triangularization and computation of the solution matrices, a very small numerical example is presented, and this example is also used as a basis for discussion of interpretation of the solution matrices.

Triangularization Algorithm

In the previous chapter, it was established that the desired triangularity of the S and S' matrices could be realized by recognizing and removing first the highest level of systems element designations from the set of all designations, then the next highest, and so on until all designations had been removed. The algorithm to be presented merely represents a systematic means of such recognition and removal. On a

manual basis, a single list of the pairs (i,j) could be used rather than a double list, but for subsequent mechanized operation, a double list is desirable.

Because of the way that the triangularization algorithm operates, the method of identification of system elements is not critical, and any element can be designated by any arbitrary numerical or alphanumerical designation, with the only restraint being that the identification be consistent and unique--that is, a given identification pertain to only one element, and that a given item have only one identification.

In many real systems, some sort of forms control is exercised, wherein every report is given a distinctive number. If such is the case, this number is perfectly useful for identification purposes and may be so used. Business function (if designated as "elements" for purposes of analysis) might well be designated by the section number of the organization manual which describes the function. The identification of data has usually not been accomplished uniquely and consistently prior to the start of a systems study. A useful technique in this case is merely to assign a serial number to each piece of data as it is discovered in the system, without regard to the system level at which it is encountered.

In the example in a later section, an identification which is partly mnemonic is used. This has been done purely for expository purposes, and is not recommended in practice. From the point of view of computer operation, a purely digital identification is preferred.

In the algorithm to follow, it is presumed that the elements of the system have been given the required unique and consistent design-

nations, and that the definition of prime relations (pairs) and concomitant relations (n-tuples) has been done. Deletion relations are not a factor in triangularization, and the pairs defining deletion relations should be set aside until the formation of the S' matrix takes place.

1. Prepare two identical lists, each containing all pairs (i,j), together with the quantifier, if desired.* Designate these two lists as list A and list B. Order list A on the j index, with minor ordering within the j index on the i index. Order list B on the i index, with minor ordering within the i index on the j index.

2. Compare each j, in turn, in list A to the i in list B. Remove from list A all pairs (i,j) for which a j in list A does not have an equal i in list B.

- B. Remove from list B all pairs (i,j) which were removed from list A in step 2. Record the order of removal of j indices from list A. The j indices of the pairs removed are the designations of the highest order elements of the information processing system.

4. If the lists A and B are not exhausted, repeat steps 2 and 3 on the reduced lists, which will remove successively lower level system elements. If the lists are exhausted, go to step 5.

5. When the lists are exhausted, the record of order of removal of pairs represents the order of listing of row and column elements in

* The quantifiers are not required in triangularization, but it is usually convenient for the quantifier to accompany the pair or n-tuple, particularly in machine versions of the algorithm.

the S and S' matrices for the prime relations. Now arrange a list of concomitant relations (n -tuples) in the same order based on the second index of the n -tuple, j' , and within a given j' , if an element designation appears both as an i index (first position in n -tuple) and as an index k, ℓ, \dots, n , then the n -tuple containing the element as an i index follows all n -tuples where it appears as a k, ℓ, \dots, n index. Then for every j in the record of removal of pairs from list A for which there is a $j' = j$ in the list of concomitant relations, insert after j in the record of removal the first index, i , of the concomitant n -tuple.

The triangularization of the system elements is complete, and for manual determination of the S, S', S^* and S'^* matrices this condition is adequate. For determination by the use of a computer, it is necessary to re-index the elements. This technique will be presented in Appendix B, since it is not of interest in the general development of the algorithms.

Formation of S and S' Matrices

In computation by means of a computer, it is not necessary to form the S and S' matrices. It is, however, necessary in the manual computation. Furthermore, even though the two matrices are not formed in the computer solution, the S and S' matrices exist in conceptual form, in the medium of card or tape records. The formation of the matrices in conceptual form or for manual computation is governed by the following rules:

1. For both the S and S' matrix, label both rows and columns in the same order as the record of removal of pairs established in

step 3 of the triangularization algorithm, as augmented by the inclusion of indices from the n-tuples as specified in step 5. This labeling should proceed to the right of the columns and downward for the rows, starting at the upper left hand corner of the matrix.

2. For the S matrix, record all prime relations by entering the quantifying numeral in the cell denoted by the pair (i,j). Record all concomitant relations with the concomitant quantifier (c) for each cell, where the cell indices are determined by considering the first element designation i of the n-tuple as a row index, and the second element designation j as a column index; and then by considering the first element designation i as a column index and each of the remaining element designations k, l, ..., n, in turn, as row indices, until the n-tuple is exhausted. Note that an n-tuple of s element designations will produce s - 1 cells in the S matrix.

3. For the S' matrix, follow steps 1 and 2, above. In addition, record all deletion relations as -1 in the matrix, using the same rules for determining the proper cell as for the prime relations.

The S--S* Algorithm

Having formed the S matrix, the S* solution matrix may be computed using the following algorithm:

1. Prepare a format for the solution matrix S*, with the same row and column designations in the same order as in the S matrix.

Place 1's on the diagonal of the solution matrix.

2. Start computation at the lower right hand cell. The computation will proceed column by column, from right to left until the left-

most column has been computed.

3. Establish a column vector V , initially zeros, outside the S^* matrix. This is a working vector, and should contain as many cells as there are cells below and including the diagonal cell in the column of S^* which is currently being computed. The top cell of V corresponds to the diagonal element of the column being computed, while the bottom cell of V corresponds to the bottom cell of the column being computed.

4. Examine the bottom cell of the column in S with the same column designation as the column being computed in S^* . If this cell is non-zero, determine the row index of the cell in the S matrix, and find the column of S^* with this same index. If the cell is zero, determine whether this cell is on the prime diagonal of the matrix, indicated by the fact that the row index $i =$ the column index j . If it is the diagonal cell, go to step 6. If the cell is not the diagonal cell (and is zero), repeat step 4 for the cell in the S matrix next above this cell in the same column.

5. Multiply the non-zero value of the cell established in step 4 by the column of S^* found as a result of step 4 and add the product to V . In this multiplication the usual rules of multiplication obtain for the ordinary numerals quantifying prime relations, but when a concomitant quantifier is involved, either in the cell value or in the column vector, the relations specified in the "Notation" section, Chapter V must be used.

Choose the cell in the S matrix next above the current cell in the same column, and repeat step 4 and step 5.

6. When a diagonal cell is reached, as indicated by the operation of step 4, add the vector V to the column of the S^* matrix under consideration. Then choose the column of the S^* matrix immediately to the left of the one just computed, and repeat the algorithm from step 3. When all columns have been computed, a triangular solution matrix S^* will have been generated.

The $S' - S'^*$ Algorithm

The S'^* matrix is computed from the S' matrix using an algorithm which is a modification of the $S - S^*$ algorithm. Steps 1, 2, and 3 are identical, with appropriate change of notation from S to S' and S^* to S'^* . The balance of the steps are as follows:

4. Examine the bottom cell of the column in S' with the same column designation as the column being computed in S'^* . If this cell is non-zero, determine which of the relation types is represented by the quantifier in the cell. If the cell entry is a deletion relation, -1 , insert an X in the corresponding cell of Vector V , then repeat step 4 for the cell in the S matrix next above this cell in the same column of S' . The purpose of this X is to prevent any further entries from any source being placed in that particular cell.

If the cell entry is the quantifier for either a prime or concomitant relation, determine the row index of the cell in the S' matrix, and find the column of S'^* with the same index. If the cell is zero, determine whether this cell is on the prime diagonal of the matrix, indicated by the fact that the row index $i =$ the column index j . If it is the diagonal cell, go to step 6. If the cell is not the diagonal

cell (and is zero), repeat step 4 for the cell in the S' matrix next above this cell in the same column.

5. If the cell is a concomitant relation quantifier, multiply the cell by the column of S'^* found as a result of step 4, observing the special rules for such multiplication previously specified. If the cell value is a regular numeral, determine whether the column of S'^* found in step 4 has any non-zero cells other than the diagonal cell. If it has not, multiply the cell value by the column vector (which consists of zeros except for the diagonal element) and add the product to the vector V . If the column has non-zero, non-diagonal values, multiply the cell value by the column vector ignoring the diagonal cell (or treating it as zero), and add the product to the vector V . In both of these multiplications, observe the previously defined rules for multiplication involving concomitant quantifiers. Also observe the presence of an X in the vector V as blocking any further entry.

Choose the cell in the S' matrix next above the current cell in the same column, and repeat step 4 and step 5.

6. When a diagonal cell is reached, as indicated by the operation of step 4, add the vector V to the column of the S'^* matrix under consideration, now treating an X in vector V as a zero. Then choose the column of the S'^* matrix immediately to the left of the one just computed, and repeat the algorithm from step 3. When all columns have been computed, a triangular solution matrix S'^* will have been generated.

A Numerical Example

In order to illustrate the operation of the refined algorithms, and to furnish a basis for discussion of the interpretation of the S^* and S'^* solution matrices, a small numerical example will be presented. In this example, the input to the system is a daily time report, listing payroll number, department number, and hours worked, recorded on a punched card. Processing, by unit record equipment, is to compute daily labor dollars by department and total, and weekly department total labor dollars, compared to the prior week. In addition to these two reports, cards containing payroll number, department number, hours worked and labor dollars are to be created for subsequent use in the payroll operation. Mnemonic designations for the several systems elements have been used for ease in discussion; as previously emphasized, element designations can be purely arbitrary for these algorithms. Also, for purely expository purposes, a flow chart of the system is shown in Figure 9.

The following list designates the systems elements:

D1 - Payroll number.

D2 - Department number.

D3 - Hours worked.

S1 - Hourly rate. (This is a constant for a given payroll number, and is stored, with the payroll number, in a master deck.)

C1 - Individual cost. ($C1 = D3 \times S1$)

C2 - Department total cost, daily. ($C2 = C1$ summed over D2)

C3 - Grand total, daily. ($C3 = \text{sum of all } C2$)

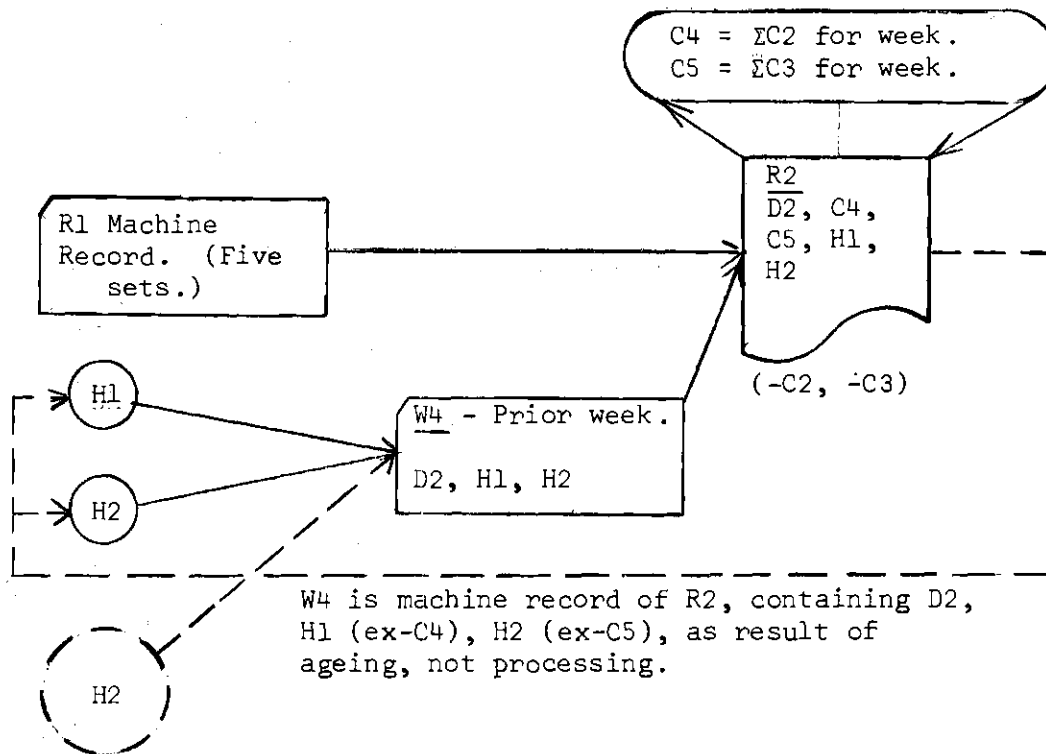
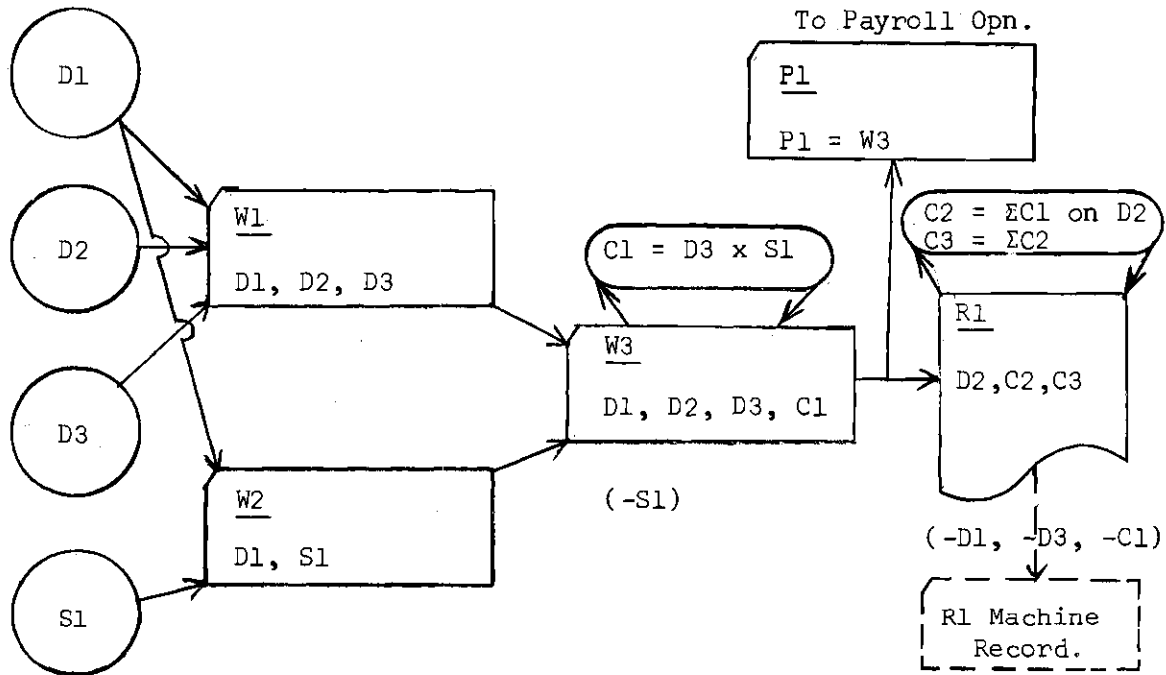


Figure 9. Flow Chart for System of Example.

- C4 - Department total, weekly. (C4 = C2 summed over 5 days)
- C5 - Grand total, weekly. (C5 = C3 summed over 5 days)
- H1 - C4 value for previous week.
- H2 - C5 value for previous week.
- R1 - Daily report.
- R2 - Weekly report.
- W1 - Input record. (Working paper, contains D1, D2, D3)
- W2 - Master card. (Contains S1 and D1)
- W3 - Card containing C1, D1, D2, D3.
- W4 - Card containing same contents as R1, but aged one week. (Contains D2, H1, H2)
- P1 - Card to payroll operation. Has same content as W3.

From the verbal description of the system (and in this case from the flow diagram, Figure 9), the following prime relations can be established. The first six are input data, which are arbitrarily designated $(0, j)$, with a quantifier of 1.

0	D1	1	
0	D2	1	
0	D3	1	
0	H1	1	} These two elements follow the rule stating that "aged" data be treated as new input.
0	H2	1	
0	S1	1	
D1	W1	1	
D2	W1	1	
D3	W1	1	
D1	W2	1	
S1	W2	1	
W1	W3	1	
W2	W3	1	
W3	P1	1	
W3	R1	1	
H1	W4	1	
H2	W4	1	
R1	R2	5	Five daily reports required for weekly report.

W4 R2 1
D2 W4 1

The concomitant relations are those pertaining to data transitions, and for this system are as follows:

C1 W3 D3 S1 (1)
C2 R1 C1 (1)
C3 R1 C2 (1)
C4 R2 C2 (1)
C5 R2 C3 (1)

The deletion relations are:

C1 R1 -1
D1 R1 -1
D3 R1 -1
S1 W3 -1
C2 R2 -1
C3 R2 -1

The systems relations having been established, the next step is that of triangularization. The deletion relations are not used in this process, and the concomitant relations are not used until step 5. The first step is the preparation of ordered lists A and B, which appear as Table 16.

In performing step 2 of the algorithm, using the lists A and B, one notes that the first j in list A is D1. Looking down the list B, it is noted that there is an $i = D1$ in the list, the seventh pair down. Therefore, the pair (or pairs) with $j = D1$ in list A is retained. Similarly, for $j = D2, D3, H1,$ and $H2$ in list A a corresponding i in list B is found. Finally, $j = P1$ in list A is encountered, with no corresponding $i = P1$ in list B. Therefore the pair W3 P1 is removed from list A, as indicated in Table 16 by underscoring.

Table 16. Lists A and B, Ordered for Triangularization*

<u>LIST A</u>		<u>LIST B</u>	
i	j	i	j
0	D1	0	D1
0	D2	0	D2
0	D3	0	D3
0	H1	0	H1
0	H2	0	H2
<u>W3</u>	<u>P1</u>	0	S1
<u>W3</u>	<u>R1</u>	D1	W1
<u>R1</u>	<u>R2</u>	D1	W2
<u>W4</u>	<u>R2</u>	D2	W1
0	S1	D3	W1
D1	W1	H1	W4
D2	W1	H2	W4
D3	W1	<u>R1</u>	<u>R2</u>
D1	W2	<u>S1</u>	<u>W2</u>
S1	W2	W1	W3
W1	W3	W2	W3
W2	W3	<u>W3</u>	<u>P1</u>
H1	W4	<u>W3</u>	<u>R1</u>
H2	W4	<u>W4</u>	<u>R2</u>

* The underscored entries in the table represent the pairs removed in the first iteration of the algorithm.

The next entry, $j = R1$ finds $i = R1$ in list B, so the pair is retained in list A. However, the next entry with $j = R2$ does not have a corresponding $i = R2$ in list B, so both of the pairs in list A with $j = R2$ are removed, as indicated by the underscored pairs. The balance

of the j 's in list A find corresponding i 's in list B, and so remain in the list.

In step 3, all pairs (i,j) removed from list A in step 2 are now also removed from list B. This operation is again indicated in Table 16 by the underscored entries in list B. Also, the order of removal of pairs from list A is recorded at this time. Since lists A and B are not exhausted, step 4 now indicates that reduced lists A and B be formed, and steps 2 and 3 be repeated on these reduced lists. These reduced lists and the removals due to the second iteration of steps 2 and 3 are shown in Table 17.

Step 2 this time resulted in the removal of pairs from list A where $j = R1$ and $j = W4$, since corresponding i 's in list B could not be found. Step 3 resulted in the removal of the same pairs from list B, and the listing of the order of removal of pairs from list A. Since the lists A and B were not exhausted, step 4 now calls for preparation of further reduced lists A and B, shown in Table 18, together with the pairs removed as a result of the next, or third, iteration.

On this third iteration, the pairs in list A involving $j = H1$, $H2$, and $W3$ are removed from list A, and subsequently from list B. The reduced lists A and B shown in Table 19 remain, and a fourth iteration removed pairs involving $j = W1$ and $W2$. Further reduced lists A and B (not shown) would be subjected to a fifth iteration which would remove the balance of the pairs from both lists.

Since both lists are now exhausted, the algorithm proceeds to step 5. At this point, the record of order of removal of pairs from list A, prepared in step 3 of the algorithm is used. In addition, the

list of concomitant n-tuples is ordered as indicated in step 5 of the algorithm is now used in conjunction with the record of order of removal in order to establish an augmented order of removal which will give the proper order of indices for the S , S' , S^* and S'^* matrices by including those elements formed by a concomitant relation. Table 20 shows these three lists.

Table 17. First Reduction of Lists A and B^{*}

<u>LIST A</u>		<u>LIST B</u>	
i	j	i	j
0	D1	0	D1
0	D2	0	D2
0	D3	0	D3
0	H1	0	H1
0	H2	0	H2
W3	R1	0	S1
<u>0</u>	<u>S1</u>	D1	W1
D1	W1	D1	W2
D2	W1	D2	W1
D3	W1	D3	W1
D1	W2	H1	W4
S1	W2	<u>H2</u>	<u>W4</u>
W1	W3	S1	W2
W2	W3	W1	W3
H1	W4	W2	W3
<u>H2</u>	<u>W4</u>	W3	R1

* The underscored entries in the table represent the pairs removed in the second iteration of the algorithm.

The S and S' matrices may now be formed, using the augmented list (Table 20) for the row and column indices. The prime and concomitant relations are shown in the S matrix, while the S' matrix shows all three categories of relations. Figures 10 and 12 show the S and S' matrices, respectively, which are obtained from the data of the example by application of the rules of S and S' matrix formation.

Table 18. Second Reduction of Lists A and B*

<u>LIST A</u>		<u>LIST B</u>	
i	j	i	j
0	D1	0	D1
0	D2	0	D2
0	D3	0	D3
0	H1	0	H1
0	H2	0	H2
0	S1	0	S1
D1	W1	D1	W1
D2	W1	D1	W2
D3	W1	D2	W1
D1	W2	D3	W1
S1	W2	S1	W2
W1	W3	W1	W3
W2	W3	W2	W3

* The underscored entries in the table represent the pairs removed in the third iteration of the algorithm.

Table 19. Third Reduction of Lists A and B*

<u>LIST A</u>		<u>LIST B</u>	
<u>i</u>	<u>j</u>	<u>i</u>	<u>j</u>
0	D1	0	D1
0	D2	0	D2
0	D3	0	D3
0	S1	0	S1
<u>D1</u>	<u>W1</u>	<u>D1</u>	<u>W1</u>
<u>D2</u>	<u>W1</u>	<u>D1</u>	<u>W2</u>
<u>D3</u>	<u>W1</u>	<u>D2</u>	<u>W1</u>
<u>D1</u>	<u>W2</u>	<u>D3</u>	<u>W1</u>
<u>S1</u>	<u>W2</u>	<u>S1</u>	<u>W2</u>

* The underscored entries in the table represent the pairs removed in the fourth iteration of the algorithm.

The S^* and S'^* matrices, shown in Figures 11 and 13, are then obtained by the operation of the two refined algorithms presented. In order to show more clearly the operation of the algorithms, the details of computation of the R2 column of each output matrix will be shown. In both cases, presume that the computation has been completed for all columns to the right of the R2 column. The algorithm will then be entered at step 3. The $S - S^*$ algorithm will be demonstrated first.

1. The vector V is established, with 17 cells being required, all zero initially.

Table 20. Record of Order of Removal, Ordered Concomitant N-Tuples, and Augmented Record of Order of Removal.

Order of Removal	Ordered N-Tuples	Augmented Order of Removal
P1	C5 R2 C3	P1
R2	C4 R2 C2	R2
R1	C3 R1 C2	C5
W4	C2 R1 C1	C4
H1	C1 W3 D3 S1	R1
H2		C3
W3		C2
W1		W4
W2		H1
D1		H2
D2		W3
D3		C1
S1		W1
		W2
		D1
		D2
		D3
		S1

2. In step 4, the bottom cell of the R2 column of S would be examined, and found to be zero. Step 4 would therefore be repeated for the next to bottom cell, which is also zero. Step 4 would then be repeated ten times, each time encountering a zero value, and thus passing to the next higher cell in the column.

3. On the 11th iteration, the cell value 1 would be encountered. Since the cell is non-zero, the row index W4 would be established, and the W4 Column of S^* would be obtained. Step 5 of the algorithm then calls for the multiplication of the cell value 1 by the column vector

	P1	R2	C5	C4	R1	C3	C2	W4	H1	H2	W3	C1	W1	W2	D1	D2	D3	S1
P1																		
R2																		
C5		(1)																
C4		(1)																
R1		5																
C3			(1)		(1)													
C2				(1)	(1)	(1)												
W4		1																
H1									1									
H2									1									
W3	1				1													
C1							(1)					(1)						
W1												1						
W2												1						
D1													1	1				
D2								1					1					
D3												(1)	1					
S1												(1)		1				

Blank cell denotes zero entry.

Figure 10. S Matrix--Refined Algorithm.

	P1	R2	C5	C4	R1	C3	C2	W4	H1	H2	W3	C1	W1	W2	D1	D2	D3	S1
P1	1																	
R2		1																
C5		(1)	1															
C4		(1)		1														
R1		5			1													
C3		(5)	(1)		(1)	1												
C2		(5)		(1)	(1)	(1)	1											
W4		1						1										
H1		1						1	1									
H2		1						1		1								
W3	1	5			1						1							
C1	(1)	(5)			(1)		(1)				(1)	1						
W1	1	5			1						1		1					
W2	1	5			1						1			1				
D1	2	10			2						2		1	1	1			
D2	1	6			1			1			1		1			1		
D3	1	5			1						1	(1)	1				1	
S1	1	5			1						1	(1)		1				1

Blank cell denotes zero entry.

Figure 11. S^* Matrix--Refined Algorithm.

	P1	R2	C5	C4	R1	C3	C2	W4	H1	H2	W3	C1	W1	W2	D1	D2	D3	S1
P1																		
R2																		
C5		(1)																
C4		(1)																
R1		5																
C3		-1	(1)		(1)													
C2		-1		(1)	(1)	(1)												
W4		1																
H1									1									
H2									1									
W3	1				1													
C1					-1		(1)					(1)						
W1												1						
W2												1						
D1					-1								1	1				
D2								1					1					
D3					-1							(1)	1					
S1											-1	(1)		1				

Blank cell denotes zero entry.

Figure 12. S' Matrix--Refined Algorithm.

	P1	R2	C5	C4	R1	C3	C2	W4	H1	H2	W3	C1	W1	W2	D1	D2	D3	S1
P1	1																	
R2		1																
C5		(1)	1															
C4		(1)		1														
R1					1													
C3			(1)		(1)	1												
C2				(1)	(1)	(1)	1											
W4								1										
H1		1						1	1									
H2		1						1		1								
W3											1							
C1	(1)						(1)				(1)	1						
W1													1					
W2														1				
D1	2										2		1	1	1			
D2	1	6						1			1		1			1		
D3	1										1	(1)	1				1	
S1												(1)		1				1

Blank cell denotes zero entry.

Figure 13. S^{**} Matrix--Refined Algorithm.

W4, and the addition of the product to Vector V. This operation is shown in Table 21.

Table 21. Computation of Column R2 of S^* --First Step

Cell	X	Col W4	=	Product	+	Vector V Before	=	Vector V After	Row Index
						0		0	R2
						0		0	C5
						0		0	C4
						0		0	R1
						0		0	C3
						0		0	C2
1		1		1		0		1	W4
		1		1		0		1	H1
		1		1		0		1	H2
		0		0		0		0	W3
		0		0		0		0	C1
		0		0		0		0	W1
		0		0		0		0	W2
		0		0		0		0	D1
		1		1		0		1	D2
		0		0		0		0	D3
		0		0		0		0	S1

4. Step 4 would then be repeated for the cell next above in the column of S , but again a zero would be encountered. This would cause another repetition of step 4, another encountering of a zero value, then the next iteration of step 4 would encounter the value 5. The row index is R1, so the R1 column of S^* would be obtained. This time, the multiplication--addition process would be as shown in Table 22. Note that the concomitant relation is involved, invoking the use of the multiplication-

like operation previously described for some cells.

5. The next repetition of step 4 encounters the concomitant quantifier (1), with row index C4, which requires column C4, of S^* , for computation. The operation is shown in Table 23.

Table 22. Computation of Column R2 of S^* --Second Step

Cell	X	Col R1	=	Product	+	Vector V Before	=	Vector V After	Row Index
						0		0	R2
						0		0	C5
						0		0	C4
5		1		5		0		5	R1
		(1)		(5)		0		(5)	C3
		(1)		(5)		0		(5)	C2
		0		0		1		1	W4
		0		0		1		1	H1
		0		0		1		1	H2
		1		5		0		5	W3
		(1)		(5)		0		(5)	C1
		1		5		0		5	W1
		1		5		0		5	W2
		2		10		0		10	D1
		1		5		1		6	D2
		1		5		0		5	D3
		1		5		0		5	S1

6. On the next iteration, the value (1) is found with row index C5. The computation is shown in Table 24.

7. The next iteration of step 4 encounters a zero cell which is the diagonal cell. Step 6 then requires the addition of the vector V to the R2 column of S^* . This column has only a 1 in the diagonal cell,

so this operation amounts to transcribing vector V into the S^* matrix, with a 1 placed in the R2,R2 cell. This completes the computation of this column.

Table 23. Computation of Column R2 of S^* --Third Step

Cell	X	Col C4	=	Product	+	Vector V Before	=	Vector V After	Row Index
						0		0	R2
						0		0	C5
(1)		1		(1)		0		(1)	C4
		0		0		5		5	R1
		0		0		(5)		(5)	C3
		(1)		0		(5)		(5)	C2
		0		0		1		1	W4
		0		0		1		1	H1
		0		0		1		1	H2
		0		0		5		5	W3
		0		0		(5)		(5)	C1
		0		0		5		5	W1
		0		0		5		5	W2
		0		0		10		10	D1
		0		0		6		6	D2
		0		0		5		5	D3
		0		0		5		5	S1

The computation of a column of S^* proceeds in a similar manner.

Entering the algorithm at step 3, for column R2:

1. The vector V is established, with 17 cells being needed, all zero initially.

2. Step 4 would encounter zeros on the first 10 iterations, until a 1 is finally encountered with W4 as row index and W4 as the column of

S^{**} to be used in multiplication. Step 5 would then result in the computation detailed in Table 25.

Table 24. Computation of Column R2 of S^{**} --Fourth Step

Cell	X	Col C5	=	Product	+	Vector V Before	=	Vector V After	Row Index
(1)		1		(1)		0		0	R2
		0		0		0		(1)	C5
		0		0		(1)		(1)	C4
		(1)		0		5		5	R1
		0		0		(5)		(5)	C3
		0		0		(5)		(5)	C2
		0		0		1		1	W4
		0		0		1		1	H1
		0		0		1		1	H2
		0		0		5		5	W3
		0		0		(5)		(5)	C1
		0		0		5		5	W1
		0		0		5		5	W2
		0		0		10		10	D1
		0		0		6		6	D2
		0		0		5		5	D3
		0		0		5		5	S1

The critical point of this computation is the examination of column W4 for structure, and the ignoring of the diagonal cell because of the presence of other non-zero entries in the column.

3. The next two iterations of step 4 encounter deletion relations which result in the placing of an X in vector V in the C2 and C3 positions. These X's will prevent any further entries in these cells. These two iterations will not be shown, but the result will be reflected

in subsequent detailed computations.

Table 25. Computation of Column R2 of S' --First Step

Cell	X	Col W4	=	Product	+	Vector V Before	=	Vector V After	Row Index
						0		0	R2
						0		0	C5
						0		0	C4
						0		0	R1
						0		0	C3
						0		0	C2
1		1 (ignored)		0		0		0	W4
		1		1		0		1	H1
		1		1		0		1	H2
		0		0		0		0	W3
		0		0		0		0	C1
		0		0		0		0	W1
		0		0		0		0	W2
		0		0		0		0	D1
		1		1		0		1	D2
		0		0		0		0	D3
		0		0		0		0	S1

4. The value 5, corresponding to row R1 is next found, and column R1 is obtained. Column R1 has non-zero, non-diagonal values, so the diagonal cell is treated as zero in the computation shown in Table 26.

It should be noted that the X's placed in vector V by action of the deletion relations have blocked out the 5's obtained in the product vector for the C3 and C2 cells.

5. The next encountered values in the R2 column of S' are both concomitant relations, and the computation would be exactly the same as

for the corresponding cells of the earlier example, with, of course, a different vector V due to different prior operations. The net result would be the insertion of (1) in the vector V in the C5 and C4 positions. Finally, addition of the vector V to the column R2 of S^{**} would give the result shown in Figure 13. Note that the deletion symbol X in the vector V is treated as a zero in this final addition.

Table 26. Computation of Column R2 of S^{**} --Fourth Step

Cell	X	Col R1	=	Product	+	Vector V Before	=	Vector V After	Row Index
						0		0	R2
						0		0	C5
						0		0	C4
5		1 (ignored)		0		0		0	R1
		1		5		X		X	C3
		1		5		X		X	C2
		0		0		0		0	W4
		0		0		1		1	H1
		0		0		1		1	H2
		0		0		0		0	W3
		0		0		0		0	C1
		0		0		0		0	W1
		0		0		0		0	W2
		0		0		0		0	D1
		1		5		1		6	D2
		0		0		0		0	D3
		0		0		0		0	S1

Discussion of the Example

In order to discuss the example, it is informative to introduce an S^{**} matrix, shown in Figure 14, produced by the use of the unrefined

algorithm presented in Chapter IV, with no consideration given to concomitant and deletion relations, and with the prime relations established from a report-oriented point of view.

It is immediately evident from the figure that the S^* matrix produced with the refined algorithm has eliminated the false indications of redundancy. The entries with value 5 in the S^* matrix of the refined algorithm are valid representations of the fact that five reports R1, one for each of the five days of the week, were used in preparation of R2. The D2 entry of 6 indicates the merging of the five R1 reports on department number, then the merging of W4, containing the historical data, with the five daily reports. The entry 10 for D1 might be viewed as false redundancy, but again, it represents the merging of a W1 with a W2 for the initial computation of C1, recorded on W3, then the subsequent merging of five R1's for the R2 report. C4 and C5 are noted as values which were prepared as a computation concomitant to the preparation of R2, which conforms to the actual system concept. Similar comments could be made relative to R1, W3, and P1, and it is seen that the refined S^* matrix is a true representation of the system on a "composed of" basis.

Turning attention to the S'^* matrix, Figure 13, it is seen that it is an accurate representation of the system on a "contains" basis, with the possible exception of values greater than one for identification type data in P1, R2, and W3. Again, these values represent the merging of compound elements on the basis of the identification data, and is thought to represent useful information.

It might be argued that the S'^* matrix represents information

	P1	R2	C4	C5	W4	H1	H2	R1	C2	C3	W3	C1	W1	W2	D1	D2	D3	S1
P1	1																	
R2		1																
C4		1	1															
C5		1		1														
W4		1			1													
H1		1			1	1												
H2		1			1		1											
R1		10	5	5				1										
C2		10	5	5				1	1									
C3		10	5	5				1		1								
W3	1	20	10	10				2	1	1	1							
C1	1	20	10	10				2	1	1	1	1						
W1	1	20	10	10				2	1	1	1	1	1					
W2	1	20	10	10				2	1	1	1	1		1				
D1	2	40	20	20				4	2	2	2	2	1	1	1			
D2	1	21	10	10	1			2	1	1	1	1	1			1		
D3	1	20	10	10				2	1	1	1	1	1				1	
S1	1	20	10	10				2	1	1	1	1		1				1

Blank cell denotes zero entry.

System is same as for Figures 11 and 13, but computation is by unrefined algorithm.

Figure 14. S* Matrix--Unrefined Algorithm.

which is known prior to computation, from flow charts of the system and other basic data. To an extent, this is true. However, part of the aim of this research is to eliminate the necessity for flow charting, and the S^* matrix is an effective substitute.

It may be observed that both S^* and S'^* show that P1 is identical in data composition and content to W3. Furthermore, both of these documents are in card form, so that P1 is not needed except perhaps as a matter of processing convenience. In a real system analysis such an indicated duplication would be investigated with a view to possible elimination.

CHAPTER VII

CONSIDERATIONS OF MECHANIZATION AND COMPUTER OPERATION

Introduction

In current day practice, it is usual and expected that numerical values arising from the use of a given mathematical technique will be obtained by means of a digital computer. In the early days of computer operations, algorithms which were designed for manual operation required substantial modification in many cases before they could successfully be used for computer operation, and a whole new subject, that of numerical analysis, has sprung up as a branch of the mathematics.

A more recent trend has been to write algorithms specifically from the point of view of the essential computer logic necessary for numerical calculation. Giffler's whole work (9) has adopted this style, with real advantage to those who seek to employ his algorithms. It is also now commonly seen in the literature that an appendix of an article contain at least the flow diagram, and perhaps the program listing in FORTRAN or ALGOL, in order to facilitate both understanding and possible use by the reader.

In the work under discussion, it seems even more appropriate that the algorithms be stated in language appropriate to computer usage, and that the computational portion of the techniques be specified in terms meaningful to those engaged in computer operations. The research is, in effect, an attempt to permit the central processor of the infor-

mation system under study to become introspective relative to the system it serves. The algorithms in preceding chapters were developed with the view in mind that their computation under real world considerations would be done by means of digital computers and associated equipment, even though it was necessary to present the algorithms as if they were to be manually computed, for expository purposes.

Sections of the Appendix will be devoted to restatement of the algorithms presented in terms of detailed instructions for triangularizing indices by means of punched card equipment, and flow charts and program listings for the computation of the S^* and S'^* solution matrices. Every attempt has been made to preserve generality from the point of view of equipment, especially in the flow diagrams. However, since programs must be written for real machines, some generality has been lost in the fact that the procedures and program listings apply only to the specific machine for which they are written, except that in some cases, as specifically noted, the program would run on equipment with fewer special features.

For the triangularization process, only a card sorter, collator, and reproducing punch are required. Any of the models currently on the market are suitable.

The two algorithms for producing the S^* and S'^* solution matrices have been written for an IBM 1401 computer, with a minimum of 8K memory, and 4 tape drives. Advanced programming features are also required. The equipment was chosen specifically because it is representative of the type and size of equipment which might be found in a typical manufacturing, commercial, or institutional situation. It is felt that in-

stallations using equipment of similar or greater capabilities could readily adapt or re-write the programs to suit their own capabilities. For other IBM equipment in the 1400 series, this adaptation would of course be very simple.

In order to make the maximum use of the logic capabilities and of available memory, the programming has been done in 1401 Autocoder language. This language necessitates the use of 4 tape drives for compilation. The algorithms could also be programmed in ALGOL or FORTRAN, but with substantial loss of operating speed and memory capacity.

Triangularization and Reindexing

An essential part of the computational technique leading to the S^* and S'^* solution matrices is the triangularization of the S and S' matrices. In order to obviate tedious labor, it is desirable that the mechanized portion of the computational system accept designations of systems elements which are entirely arbitrary; that is, that the analyst need not be concerned with the mechanics of triangularization nor the subsequent reindexing of elements for computer operation.

Giffler (9, p. 18-34) presents an algorithm which can be used for triangularization, and he claims that it can be accomplished on punch card equipment. Trials made using this algorithm disclose several important limitations, however.

1. The algorithm is not in fact amenable to operation on punch card equipment. The collator is not capable of interchanging cards as the algorithm requires, it can only select and segregate matches or mis-matches. Neither is the collator capable of recording the exchanges

and comparing the current exchange with all prior ones.

2. The algorithm can be programmed for computer operation, but in actual trials it proved to be an inefficient operation, in that the matter of recording and comparing index changes required repeated table look-up operations.

3. The i indices are left scattered in the final ordering obtained by operation of the algorithm. That is, if there are several pairs (i,j) in the system with the same i value, and only some of the i find matches on the following j 's, then the pairs with the same i will not be contiguous in the resulting ordering. This fact makes the required reindexing (for computer solution of the ensuing computations) very difficult, or else requires a further step to consolidate the indices.

4. Since the list is not reduced in size as the algorithm progresses, it is necessary to store, and operate with, the entire list during the entire computation. Furthermore, no output can be realized from the computer until the entire triangularization is complete, which results in long overall computation times.

For these reasons, a new algorithm was developed, which has been stated both in manual form (p. 121) and mechanized (Appendix B) form. Both forms also contain provision for handling concomitant and deletion relations as well as prime relations.

In the new algorithm, the use of two decks of cards (lists A and B in the manual version) permits the use of a collator to both recognize and remove the successive subsets, while careful ordering of the initial set and of the order of removal prevents the scattering

of indices noted in Giffler's method. Reindexing for computer operation is readily done, and consists simply of assigning sequential numbers to the elements of the triangularized lists or decks in a systematic manner.

Computation of the Solution Matrices

The principle concern in development of computational methods for mechanization of the algorithms for computation of S^* and S'^* was that of limitations of memory, particularly if a computer of modest size is to be used. It is therefore necessary to give every consideration to computational techniques in order to conserve this scarce memory space.

Again, Giffler (Chapter II, p. 40) established computational expressions for the inversion of the $(I - N)$ matrix which could be easily translated to computer operation. However, his computational method would require that the S matrix be stored in memory in its entirety before computation could start, and that the S^* matrix be overlaid on the S matrix as computation proceeded. This was due to the fact that the computational equations required solution of columns from left to right in the case of a lower triangular matrix. Reconsideration of the computation, which is reflected in the statement of the algorithms in Chapter VII, shows that if the computation proceeds from right to left (in a lower triangular matrix) it is not necessary to store the S matrix at all. It is only necessary to read from a card a single cell s_{ij} , and then to perform all the computation required by the entry s_{ij} at one time, storing the results in memory in the S^* matrix.

The recognition of the ability to eliminate storage of the S matrix permits consideration of methods of compressing the S^* matrix in memory as it is generated, and other means of conserving memory space. It is readily noted that an uncompressed S^* matrix, due to triangularity, will have as an upper bound,

$$C = \frac{n^2 + n}{2} \quad (1)$$

cells, including the diagonal cells, where n is the number of systems elements under consideration. In addition, some space would be required for identification, work areas, and, of course, the computer program.

A first saving in memory allocation can be made by observing that the diagonal 1's are arbitrarily present in every column of S^* , and that they could always be supplied, if needed, by the program on recognition that the cell in question has index $i = j$. In the program, the cells so conserved will be used for column and row identification and other information.

A substantial saving in memory space can be realized by observing that S^* has many zero cells. By further consideration of the property discussed in Chapter V relative to formation of columns as linear combinations of columns to the right, it can be noted that a given column of the S^* matrix will never have non-zero elements with row index i smaller than the smallest non-zero cell row index of the same column of the S matrix, except for the diagonal element itself, which will not be stored as such. That is, if there are zero cells between the diagonal and the

first (highest in column) non-zero cell in a given column of the S matrix, then the S^* matrix will have at least these same zero cells. This observation permits two things to be done:

1. These specific cells need not be stored in the matrix, thereby conserving storage. The detailed method of accomplishing this will be discussed in the Appendix dealing with the computer program.

2. A means is provided to compute the number of zero cells of this type, so that the prior statement of the upper bound of memory required can be improved. The computation is based on the fact that if the triangularized list of systems relations is re-ordered with major ordering on the column index j and minor ordering on the row index i , then the first pair (i,j) within a group of identical j indicates the cell which will occupy the highest non-zero position of the j th column of S , and therefore of S^* . Then the number of intervening zero cells between the diagonal cell and this highest cell is $i - (j + 1)$. If a j index is not present in the list, a null column of S is indicated, and the column in S^* will have only the diagonal cell. In this case, the number of zero cells is $n - j$, where n is the number of system elements in the system under study.

Define a list R of all pairs (i,j) in a system. Define a sublist L as the pairs $(i,j) \in R$ such that i is the smallest index associated with a given column index j . Note that for a given system, there will be some columns j with no pairs (i,j) . Then the number Z of zero cells of the type under discussion is:

$$Z = \sum_{\substack{j=1 \\ j \in L}}^n i_j - (j+1) + \sum_{\substack{j=1 \\ j \notin L}}^n (n-j) \quad (2)$$

Then the upper limit U on storage required for a given matrix will be:

$$U = \frac{n^2 + n}{2} - Z \quad (3)$$

A simple program to compute Z and U from the input cards will be found in Appendix D.

One further possibility for conservation of storage space derives from the computation of S^* from the point of view of linear combinations of columns. This depends on the property that after a column computation involving a given s_{ij} , if there are no further non-zero values to the left of s_{ij} in the same (i th) row, there will be no further need in the calculation for the corresponding column of S^* with index $j = i$. Presuming that this column has been presented in some form of output, this column can then be discarded in its entirety, making room for other column vectors, and therefore permitting a larger S^* matrix to be computed and stored.

In order to use this property, it is necessary to locate and designate the cells s_{ij} having this property. This is easily done by ordering the triangularized list (sorting the cards) with major sequence on i , minor sequence on j . Then the first occurrence of each i in the list will identify the proper cells. These cells can be identified by tagging; that is, punching some designator in the card

in an appropriate field.

This last method of compression is valuable under circumstances when a problem could not otherwise be run on a given computer. Its use, however, complicates the programming because of the fact that the discarding of a vector is accompanied by the need to completely rearrange the remaining portion of the S^* matrix in memory, and changing the internal indexing. This also increases the running time, substantially in some cases. It is therefore recommended that the method be used only when absolutely necessary. The programs in the Appendix do not incorporate this feature.

CHAPTER VIII

CONCLUSIONS AND RECOMMENDATIONS

Conclusions

The development of mathematical models for the description and manipulation of information system relationships represents an attempt to quantify a process which has been approached in the past on an essentially qualitative and intuitional basis. Only very limited attempts in this direction are shown in the literature.

The basic model developed in Chapter IV has no real meaning from the point of view of application, but serves as an essential bridge between the prior work of Lieberman (18) and Homer (14) and the refined models presented in Chapters V and VI. The basic model did, however, succeed in reproducing the results of the prior investigators with some computational and conceptual improvement, but it failed to adequately represent system under study.

The recognition of differences between types of data and of the existence of transitions of data within the system led to the definition of three types of system relations instead of the single type presumed in the prior work and in the basic model. This in turn permitted extension of the basic model to the two refined models.

From an operation point of view, examination of the S^* and S'^* matrices by the analyst will disclose possible areas of system improve-

ment. The existence of a number larger than expected[†] in a given cell will indicate the possibility of redundancy in the number of times a given element is made available for preparation of a given report. The partial or complete duplication of a column will suggest the possibility of eliminating or combining two or more reports. Comparison of columns of S^* and S'^* will give an indication of data elements from lower levels which might easily be added to higher level reports in order to make them more useful.

The fact that the matrices may represent a proposed system as well as an existing system permits comparison and evaluation of relative redundancy in two systems. Furthermore, the fact that the algorithms are mechanized allows the use of the technique for simulation of proposed system changes, and can in this manner be used for synthesis as well as analysis of information systems.

In summary, the benefits of the refined techniques are that the shortcomings noted in prior work have largely been overcome. In detail, it is felt that the refined techniques have achieved the following benefits:

1. The three basic types of data, and the several transitions to which data may be subjected, have been explicitly recognized, and notational and computational techniques have been devised to adequately deal with them.

2. The overstatement of redundancy inherent in prior techniques

[†] The analyst would expect the number five, for example, if five daily reports were summarized to produce a weekly report.

has been eliminated for type two and type three data, and reduced to a legitimate indication of frequency of merging for type one data. A major concern in the analysis of systems is to assure that adequate information reaches the decision maker with a minimal amount of duplicate data origination and processing. The refined models can furnish a basis for elimination of duplication of origination, and can do much in disclosing duplication of processing.

3. By definition of the categories of system relations, and specification of rules for establishing these relations, the analyst is forced to carefully define each observed relation, rather than merely indicating that some relation exists. Further, he is forced to look at the system from a data element point of view, as opposed to the organizational or report hierarchy point of view, which assures that a more detailed analysis will be made. This results in removing much of the distinction between the interior and exterior system, which should be of advantage in realizing an effective final design.

4. The analyst is freed from a great deal of tedious description of a prose or graphic nature. The proposed technique does not require the preparation of flow charts or block diagrams. Furthermore, the analyst need only be concerned with defining the relations, and need not be concerned with determining the level at which they occur, nor with arranging them in any particular order. The mechanized algorithms perform this function for him as a necessary step in the overall analysis. The time of the analyst is freed for examination of the solution matrices which are a true and adequate representation of the system from both a "composed of" and "contains" point of view.

5. A very great part of the entire analysis technique can be programmed for a digital computer, greatly reducing the clerical activity required of the analyst, and also greatly reducing the volume of data which he must examine. The two solution matrices contain much of the data needed for analysis of the system.

6. Since the computation is carried out in the computer, it becomes feasible to introduce changes of definitions of relations on a trial basis. In this way, the technique can be used for simulation of proposed system changes, and can in this manner be used for synthesis as well as analysis of data systems.

7. An adequate solution for the problem of cycling caused by ageing of data has been advanced by treating stored, then subsequently retrieved data, as a new data origination.

8. All of the benefits cited by Homer (Chapter II, p. 31) have been met, and in most cases, exceeded.

In general it is believed that the models presented will furnish an adequate representation of information processing systems of the type encountered in practice. Like all models, they will not cover all conceivable situations in complete detail, but they will adequately represent the principal structure of a system. It would be difficult, for example, to represent the situation where a randomly selected portion of the data is used in the preparation of a report, such as is sometimes done in more sophisticated systems. Furthermore, the model represents only the structure of the system, and does not consider the volume of a given data element to be processed.

It can be fairly stated, then, that while this research is

believed to be a step, hopefully a major one, in the direction of quantitative analysis of information processing systems, that much remains to be done before information systems analysis can be viewed as a science, rather than an art.

Recommendations

Since in consideration of the total field of information processing so much remains to be done, the recommendations for further study must be considered as indicative rather than inclusive.

Of a practical and applicatory nature, the models of the current research should be applied to a number of real applications, to determine the range of the models' applicability. Care should be taken to include project-oriented organizations as well as those engaged in more repetitive activities.

In a more theoretical vein, the following studies are suggested:

1. Investigation of other models for the structural examination of information processing systems.
2. Investigation of means for characterizing information processing systems in terms of the volume of processing.
3. Investigation of the use of random variables as quantifiers for the system relations.
4. Investigation of the essential similarities between computational subsystems (e.g., payroll and inventory accounting) with a view to developing general methods of computation.
5. Investigation of the basic compatibility of programming languages (e.g., COBOL) and information processing systems requirements.

APPENDIX A

GLOSSARY

The following Glossary of terms unique to this research is presented:

Composed of - A kind of information systems analysis where, for a given report, all of the lower level data which were required for the preparation of the report are indicated, whether or not they actually appear on the report as prepared. Used in opposition to the term "Contained in."

Compound Element - Any report, form, document, card, tape, or disk record of any nature containing one or more pieces of recorded data (simple elements), and from which the simple elements can be recovered and made meaningful to humans without arithmetic computation.

Concomitant Relation - A relationship within an information system which occurs in conjunction with the preparation of a compound element wherein one or more simple elements undergo a transition.

Concomitant Cell - A cell in a matrix wherein the value is a concomitant relation quantifier, (c).

Concomitant Index - A row or column index of a matrix where the index is the identification of a system element formed as a result of a concomitant relation.

Contained in - A kind of information system analysis where, for a given report, only the lower level system elements which actually appear on the report are indicated. Used in opposition to the term "Composed of."

Data Transition - An operation within an information system wherein the input data are transformed in some manner to make them more usable to the decision maker. Nine forms of transition are identified and discussed (p. 52).

Deletion Relation - The system relation which exists when an element from a lower level is brought to a higher level by virtue of being included within a compound element which is required at a higher level, but which in itself does not become an integral part of the higher level. It is used to indicate that an element is terminated on a given route through the system.

Exterior System - The entire operation under consideration, including the set of decisions made routinely to control the operation, the set of input data to be processed in order that a decision may ultimately be made, the required data origination, data transmission, data processing, report structure, provision for data storage and subsequent retrieval, and the set of decision function which will be used in conjunction with the processed data in order to arrive at specified decisions.

Identification Data - A simple element of an information system which indicates the relation of other types of data to some physical system. Examples are payroll numbers, stock numbers, machine numbers and department numbers.

Interior System - The interior system refers to the details of machine programming and operation. It embraces such factors as card and record format, report format, operating rules, and equipment programming itself.

Pair, or Pair (i,j) - Denotes the notation used to indicate a prime or deletion relation.

N-tuple (i,j,k,...,n) - The notation used to indicate concomitant relations.

Prime Relation - The system relation which indicates that an element at some given level of a data system is merely required for the preparation of some higher level element. All data input is prime to the first document upon which it is recorded and to its source.

Quantifier - A symbol used to express either numerically or symbolically the extent of a system relation. Prime relations use as a quantifier ordinary numerals n , concomitant relations employ a special quantifier (c) , where c is an integer, and deletion relations use a symbolic quantifier -1 .

Quantitative Data - Data which arise as a result of a count, measurement, or computation.

Regular Cell - A cell in a matrix wherein the value is a regular scalar, n .

Regular Index - A row or column index of a matrix where the index is the identification of a system element formed as a result of a prime relation.

Simple Element - Any piece of recorded data, numeric, alphabetic, or symbolic, which exists in an information system as input, output, or intermediate form, regardless of the means of recording.

Status Data - Data which indicate status or existence. This type of data is not quantitative.

System Element - General term for either a simple element or a

compound element where the distinction is not needed.

Triangularization - The logical operation of ordering the identifications of system elements in such a manner that when these identifications are used as indices for the S and S' matrices, the matrices will be in triangular form.

Type One Data - Identification data.

Type Two Data - Quantitative data.

Type Three Data - Status data.

APPENDIX B

MECHANIZED TRIANGULARIZATION AND REINDEXING

Triangularization

For this process, a choice is available between the use of a computer and use of conventional card equipment. Since the operation is essentially that of alternately sorting and collating, both of which are accomplished in computers only with a great attendant loss of efficiency, it is felt that the equipment of choice for problems of usual size is the conventional card equipment.

The detailed procedure, paraphrasing the manual algorithm, presumes as input manually prepared (but not necessarily ordered) lists of prime and deletion relation pairs (i,j) and concomitant relation n -tuples (i,j,k,\dots,n) , together with their respective quantifiers n , -1 , or (c) .

1. Establish the maximum length of identification present in the lists, and establish a card format such that there are two fields, each the length of the maximum length of identification. A third field, usually two digits in length, should be established for recording the quantifiers.

2. For each of the prime and deletion relations, punch a card showing each pair of identifications (including the arbitrary $i = 0$ identification for input elements) together with the quantifier punched in the three designated fields. In the balance of the discussion of the procedure, the field associated with the first (i th) identification of the pair will be referred to as the " i field," the field associated

with the second (jth) identification of the pair as the "j field," and the quantifier as the "q field." The quantifier for prime relations will be punched as an unsigned numeric value. The quantifier for deletion relations will be punched as J (11 - 1 punch), where the 11 punch will be construed as negation.

3. For each of the concomitant relation n-tuples, punch the following cards, using the same format as established in step 1, and with the quantifier for all cards punched as A (12 - 1 punch):

a. Punch a card showing the first designation, i, of the n-tuple in the i field and the second designation j of the n-tuple in the j field, and the quantifier A in the q field. Also punch an 11 zone punch in column 80.

b. Punch cards, one for each designation beyond the second designation j, with the first designation of the n-tuple, i, in the j field, and the third or subsequent designations k, ..., n in the i field, and the quantifier A in the q field.

As an example, the n-tuple K23 B10 J19 P14 would result in three cards being punched:

K23 B10 A X (Col. 80)

J19 K23 A

P14 K23 A

All punching in steps 2 and 3 will have all fields right justified.

4. If the manual listings were not separate, separate the three lists by sorting on the units position of the q field. No zone indicates

prime relations, 11 zone indicates deletions, 12 zone indicates concomitant relations.

5. It is possible, in the practical case, that duplicate cards exist either through error, or through the fact that input elements used in more than one report have been identified twice. To eliminate duplicates, sort each of the three decks established in step 4 regarding the i and j fields as a single field, then check for duplicates on the collator.

6. Set aside, temporarily, the concomitant and deletion relation decks. Reproduce the prime relations deck, preferably on cards of a different color. Designate one of these prime relations decks as deck A, the other as deck B.

7. Sort the concomitant relations deck on column 80. Set aside temporarily the cards without an 11 punch in column 80. Designate the concomitant relations cards with a punch in column 80 as deck C.

8. Sort deck A with minor on the i field and major on the j field. Sort deck B with minor on the j field and major on the i field. Sort deck C with major on the j field.

9. On the collator, perform a three pocket match, with deck A in the primary feed, wired to read the j field, deck B in the secondary feed, wired to read the i field. Select unequal primaries. All basic set-up switches must be on except multi-S & S. The result of this operation will be the selection of all system elements which appear as a j designation only. On the first pass, this will be the highest level elements of the system. This step corresponds to step 2 of the manual algorithm.

10. Sort deck B with a minor on the i field and major on the j field. Only the major sort is physically required, due to the previous sort on this deck. Deck B is now in the same sequence as the original deck A.

11. On the collator, perform a three pocket match, with deck B in the primary feed, the cards selected from deck A in step 9 in the secondary feed, both feeds wired to read a combined i and j field. Select equal primaries. All basic set-up switches must be on except multi-S & S. This operation results in removing from deck B the cards corresponding to the cards selected from deck A in step 9. This step corresponds with step 3 of the manual algorithm. The highest system element cards have now been removed from both decks. The cards selected from deck B may be discarded.

12. On the collator, perform a two pocket match-merge with the deck C in the primary feed and the cards selected from deck A in step 9 in the secondary feed, both feeds wired to read the j field. Select equal secondaries to merge behind primaries. The result of this operation is to place concomitant relations adjacent to and behind the elements to which they pertain. The step performs the function of ordering of the concomitant relations done in the first part of step 5 of the manual algorithm.

13. Sort deck A with minor on the j field and major on the i field. Only the major sort is physically required, due to the previous sort on this deck.

14. Deck A and deck B now correspond to the reduced lists of the manual algorithm, except that the role of deck A and deck B have

been interchanged. Change the designation of deck A to deck B, and deck B to deck A, and repeat steps 9 through 14 until all three decks are exhausted, with the connotation in these steps that the reduced decks A, B, and C are being used, and that decks A and B interchange designation at the completion of each pass. At each pass, successively lower levels of systems elements will be removed.

If level designation is desired, the merged deck resulting at the end of step 12 can be gang punched with a suitable designation to indicate level. For the concomitant cards (11 punch in column 80), the level pertains to the designation in the *i* field, while for the prime relation cards, it pertains to the *j* field. Such designation is elective, since the algorithms to follow do not require this designation.

If on some pass step 9 results in no cards being selected, a cycle has been encountered, and the operation must be terminated in order to permit the manual determination of the cause of the cycle. The cause will be either a punching or other clerical error in transcription, or an error on the part of the analyst in defining the system relations.

15. The single deck resulting from the accumulation of decks produced on the several passes through step 12 is now reproduced, with selection to reproduce cards exactly in the absence of a punch in column 80, and interchange of the *j* and *i* fields in the presence of a punch in column 80. This performs the second portion of the manual step 5, that of inserting after *j* in the record the first index, *i*, of the *n*-tuple when $j' = j$.

At the completion of this step the triangularization, as such, has been completed. It is now necessary for computer operation of the

balance of the technique to reindex the systems elements, and to take certain other steps for preparation of the input for the $S - S^*$ and $S' - S'^*$ algorithms.

Reindexing and Input Preparation

The essential purposes of the steps in this section are to re-index the systems elements in order to simplify the computation of the S^* and S'^* matrices, to recombine the decks representing the three categories of system relations, and to arrange the cards in proper order for input to the further algorithms.

The numbering scheme used for reindexing depends largely upon the computer to be used, the conventions used in addressing its memory, and the memory location which will be used as a location for the lower right hand corner of the matrix. Furthermore, two possibilities exist in this respect:

1. An absolute indexing system can be used, wherein the initial number assigned and the increment between assignments is determined based on the three considerations above.

2. A relative indexing system may be used, where the consecutive integers 1, 2, 3, ..., n are assigned, and the programs for the algorithms for specific machine configurations make a conversion within the computer from the relative system to a system which is absolute for the machine in question.

Regardless of the choice made, the following machine operations

are applicable.*

1. Prepare a master deck with the desired numbering sequence punched in a convenient field. In addition, punch 11 in any convenient column, e.g., column 79, as a control punch.

2. Merge this master deck with the reproduced deck obtained in step 15 of the previous section.

3. Reproduce the old identification number (j field) into an appropriate field of the master deck. Punch control on the reproducer to punch on 11 in column 79.

4. Sort the master cards, now with the sequence number and old identification number, out of the combined deck based on the 11 punch in column 79. The non-master cards are of no further use.

5. Take now the deck which was the input to step 15 of the preceding section, that is, the deck from which the reproduction was made, the deletion relations deck which was previously laid aside, and the balance of the concomitant relations cards which do not have an 11 punch in column 80. Combine these cards into a single deck, hereinafter referred to as the "input deck."

6. Sort the input deck on the j field. Sort the master deck on the old identification field.

7. Merge the master deck with the input deck, comparing on the sort fields of step 6, and placing the master card ahead of each old

* A different, more efficient method can be used if a sequential numbering device is available on the reproducing punch. It has not been specified here, as this equipment is seldom available.

identification (j field).

8. Reproduce the new identification (index j) into the input deck in an appropriate field. Punch control to punch on non-11 in column 79.

9. Sort the master cards out of the combined deck, based on the presence of an 11 punch in column 79.

10. Re-sort the input deck on the i field. There will be a substantial number of cards with zero in the i field, and these cards may now be discarded.

11. Merge the master deck with the input deck, comparing on the sort fields of step 10, and placing the master card ahead of each old identification (i field). Some master cards will not find corresponding cards in the input deck.

12. Reproduce the new identification (index i) into the input deck in an appropriate field. Punch control to punch on non-11 in column 79.

13. Sort the master cards out of the combined deck, based on the presence of an 11 punch in column 79.

The reindexing is complete at this point. The old i and j fields will not be used in the computer operation as such, but must be preserved if it is desired to have the computer output in terms of the original identifications. In order to avoid confusion in the balance of the discussion relative to input preparation, the new index fields, whether reproduced into a new card or not, will be now referred to as the i and j fields.

It will be recalled that in the manual computation of the S^* and

S'^* matrices, the first cell of the S or S' matrix used was that which was the lowest in the right-most non-zero column. In the computer solution, the S and S' matrices are not formed in memory, but exist conceptually, represented by the input deck created in the immediately preceding steps. The row and column indices of the cell are represented by the i and j fields, respectively, and the cell value is in the q field.

At this point, therefore, due to the method of creating the input deck, it is in reverse order from that required by the computation. It must therefore be re-sorted into proper order; that is, so that the input will be read up columns, starting at the right-most non-zero column of the (conceptual) S or S' matrix. In addition, it is desirable to place a sequence number in each input card in order to guard against lost or out-of-sequence data in future operations. The next two steps perform this operation.

14. Re-sort the input deck, with minor on the i field (row index) and major on the j field (column index). This is a reverse sort. Remove cards from pockets of the sorter nines first, zeros last.

15. Sequence number the input deck, using any convenient field, and any standard sequencing technique.

The input deck is now ready to be used for the computation of the S^* and S'^* matrices.

APPENDIX C

COMPUTER PROGRAMS FOR SYSTEMS ANALYSIS

Introduction

To implement the computation of the basic algorithms, four computer programs have been written and tested. The first program computes the number of zero cells below the diagonal of S^* and above the first non-zero entry of a given column, and estimates an upper bound for the memory required for a given matrix. The other three programs perform the computation of the S^* and S'^* matrices, and furnish a printout of the non-zero matrix elements.

The program designations, their function, and the form and sequence of input and output is as follows:

Program 1. This program computes information relative to the number of zero cells between the diagonals and the highest non-zero cells in the columns of S^* . The number of such cells is indicated, and the program also indicates the upper bound on the number of cells required and the actual amount of memory space needed in the computer for program 2 as written. The input to this program is a lead card, the same used in program 2 and program 3, specifying the dimension of the S matrix. This is followed by the input cards obtained from the reindexing operation, re-sorted with major sort on the j field, minor sort on the i field.

Program 2. This program computes the S^* matrix, and has as output one card for each non-zero cell of S^* , including the diagonal cells. The input required is the triangularized, reindexed deck obtained from

the operations detailed in Appendix B. In addition, a lead card is required to indicate the dimension of the S matrix; that is, the number of systems elements in the system. Deletion relation cards can be left in the input deck, as the program will merely pass them.

Program 3. This program computes the S'^* matrix. Input and output are the same as for program 2.

Program 4. This program takes the output of program 2 or program 3, finds the original designations of the systems elements, and prints the column designations of the columns of S^* or S'^* , the row designation of non-zero cells in the column (if any), and the value of the cell. The input is (1) the master deck from step 13 of the reindexing operation, Appendix B; (2) a lead card containing titling information for the print-out; and (3) the output cards from either program 2 or program 3, in the order of major sort on the j field, minor sort on the i field.

Principal Program Features

The main consideration in writing these programs was that of conserving memory in order to accommodate as large as possible a matrix. Since in many installations only a card type 1401 is available, the programs do not use tape in the execution of the programs, although it is required for compilation. However, programs compiled on a tape machine can be run on a card machine, so the compilation could be done by a service bureau, execution on the user's machine. All programs are written in 1401 Autocoder. If larger system matrices were required in a given case, programs 2 and 3 could be re-written to use either

tape or disk memory.

Programs 2 and 3 are essentially alike, with program 3 differing in only a few instructions in order to handle the logical operations called for by the deletion relation. A lead card establishes the dimension of the matrix in both cases, where the dimension is the number of systems elements in the system under study. Program 2 ignores cards with the deletion relation. After the first data card is read, all of the cells of the columns with a column index greater than that shown on the first card are computed, since these columns all consist of merely the diagonal cell. They are also punched as computed. The program then follows the algorithm substantially as outlined in Chapter VI, except that columns are not extracted for the multiplication, nor is a vector V designated as such. Rather, the multiplication takes place a cell at a time and the product is added directly to the proper cell of the column being computed. Two multiplication routines are used, one for regular quantifiers on the input card (labeled REGMUL)*, and one for concomitant quantifiers (labeled CONCOM). Since most of the quantifiers encountered in practice will be either 1 or (1), these multiplication routines are actually addition routines, with the routine repeated the number of times indicated by the quantifier.

As each column is completed, it is punched, one card for each cell, starting at the bottom of the column. Zero cells are not punched. Zero cells between the top non-zero cell and the diagonal are not stored, but are counted, and the number of such cells is stored along

* Labels refer to the subroutine labeling on the program listings, Appendix D.

with the column number in a data word representing the diagonal cell. The diagonal 1 is not stored, but is inferred as needed by the equality of row and column index.

Each card, as it is read, requires searching memory for the proper column for multiplication. This is accomplished by first establishing the number of columns to be skipped, which is one less than the difference between the row and column index on the input card. Then, using the data word associated with the diagonal element of each column, the location of the next can be computed based on column index, matrix dimension, and the number of zero cells eliminated from the given column. When the proper number has been skipped, the address of the proper column is available.

In program 3, deletion cards force a machine character # (Pound) into the proper cell of the column being computed to prevent any further entries into that cell. Other cards for the same column require examination of each cell for the presence of # to avoid placing any other value there. When a column is complete, the cells containing # are changed to zero, and are therefore not punched.

The other change in program 3 is that if a column has any non-zero entries other than the diagonal, then the diagonal is not used in the computation. This is accomplished by recognition that columns with only the diagonal element have stored only the data word containing the column index and the number of zero cells which were eliminated.

Program 2 requires about 1650 positions of memory including the read, punch and print areas. Therefore, in a 1401 with 8K memory, 6350 positions are available for the matrix. Due to the zero cell

elimination, storage requirements will differ with specific application. However, since about 112 elements can be accommodated without any matrix compression, it is estimated that this size machine will accommodate the matrix for an information system of about 150 elements. If a larger 1401 is available, the program can be modified to make use of the larger memory merely by changing the constant labeled HIGH in the program listings to a figure one less than the machine capacity. While program 3 requires about 1850 positions, less storage is needed for the S^* matrix, so that program 2 is the guiding program.

Program 4 is a relatively straightforward print routine. The master cards used in reindexing the original input deck are used to set up a table in memory bearing both the original and the new indices. The output cards from either program 2 or 3 are then read, the old indices from the table associated with the new ones from the cards, and the indices and values printed out, seven per line, with the proper column index. Concomitant cells are indicated by an asterisk (*).

Program 1 is also straightforward, and computes the quantities shown in Chapter VII relative to the amount of computer space the matrix for a given system will require. This program is intended for use prior to program 2 and 3, if there is doubt about the amount of storage required. If the final quantity printed as a result is less than 6350, then a 1401 with 8K memory will accommodate the system matrix.

Appendix D shows complete program listings in 1401 Autocoder for these programs. Comments in the listings specify input and output card format, and indicate the purpose of major sections of the programs.

APPENDIX D

Table 27. Program 1—Compute Upper Bound of Matrix Size

COMPUTE UPPER BOUND OF MATRIX SIZE				GH8-1	PAGE	1			
SEQ	PG	LIN	LABEL OP OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
101	1	01	000 JOB COMPUTE UPPER BOUND OF MATRIX SIZE						
102	1	02	CTL 4401						
103	99	99	* INPUT CARD FIELDS - I-FIELD CC 23-25, J-FIELD CC 26-28						
104	99	99	* SORT IS J-FIELD MAJOR, I-FIELD MINOR. LEAD CARD HAS S-MATRIX						
105	99	99	* DIMENSION IN CC 1-3.						
106	1	03	ORG 333				0333		
107	99	99	* SETS COUNTERS, READS LEAD CARD						
108	1	04	BEG14 MLCWA +0000,ZED=4	7	0333	L 772	776		4
109	1	05	MLCWA +001,JAY=3	7	0340	L 779	782		4
110	1	06	SW 1	4	0347	, 001			4
111	1	07	R	1	0351	L			4
112	1	08	ZA 3,ENN=3	7	0352	+ 003	785		4
113	1	09	SW 23,26	7	0359	, 023	026		4
114	1	091	MLCWA +000,REALJ=3	7	0366	L 788	791		5
115	1	092	MLCWA '0',SWONE=1	7	0373	L 792	793		5
116	99	99	* READS CARD, TESTS LAST CARD, TEST TO SEE IF THIS COLUMN HAS						
117	99	99	* BEEN COMPUTED.						
118	1	10	READ R	1	0380	L			5
119	1	11	BLC SETSW	5	0381	B 433	A		5
120	1	111	MLZS +1,28	7	0386	Y 794	028		5
121	1	12	C 28,REALJ	7	0393	C 028	791		5
122	1	13	BU TEST	5	0400	B 417	/		5
123	1	14	B READ,SWONE,0	8	0405	B 380	793 0		6
124	1	15	B REST	4	0413	B 516			6
125	99	999	* DETERMINES WHETHER J-INDEX DENOTES NON-NULL OR NULL COLUMN						
126	1	17	TEST C 28,JAY	7	0417	C 028	782		6
127	1	18	BE JINL	5	0424	B 444	S		6
128	1	19	B JNDIL	4	0429	B 491			6
129	99	999	* SETS SWITCH ON LAST CARD						
130	2	01	SETSW MLNS +1,SWONE	7	0433	D 794	793		6
131	2	02	B READ*6	4	0440	B 386			6
132	99	999	* COMPUTES NUMBER OF ZERO CELLS BETWEEN DIAGONAL AND FIRST NON-						
133	99	999	* ZERO CELL IN NON-NULL COLUMN						
134	2	04	JINL MLC 28,REALJ	7	0444	M 028	791		7
135	2	05	A +1,JAY	7	0451	A 794	782		7
136	2	06	A 25,ZED	7	0458	A 025	776		7
137	2	07	S 28,ZED	7	0465	S 028	776		7
138	2	08	S +1,ZED	7	0472	S 794	776		7
139	2	09	B READ,SWONE,0	8	0479	B 380	793 0		8
140	2	10	B REST	4	0487	B 516			8
141	99	999	* COMPUTES NUMBER OF ZERO CELLS IN NULL COLUMN						
142	2	12	JNDIL A ENN,ZED	7	0491	A 785	776		8
143	2	13	S JAY,ZED	7	0498	S 782	776		8
144	2	14	A +1,JAY	7	0505	A 794	782		8
145	2	15	B TEST	4	0512	B 417			8
146	99	999	* COMPUTES NUMBER OF ZERO CELLS IN NULL COLUMNS AFTER LAST						
147	99	999	* INPUT CARD						

Table 27. Program 1—Compute Upper Bound of Matrix Size (Continued)

ROW	NO	LINE	LABEL	OP	OPERANDS	SIZE	CT	LOCN	INSTRUCTION	TYPE	CARD	
148	2	17	REST	C	JAY,ENL	7	0516	C 782	785		9	
149	2	18		SE	DOYND	5	0523	B 553	5		9	
150	2	19		A	ENR,ZED	7	0528	A 785	776		9	
151	2	20		S	JAY,ZED	7	0535	S 782	776		9	
152	2	21		A	+1,JAY	7	0542	A 794	782		9	
153	2	22		B	REST	4	0549	B 516			9	
154	99	999	* COMPUTES AND PRINTS TOTAL ZERO CELLS %, UPPER BOUND OF CELLS									
155	99	999	* II MATRIX, U, AND NUMBER OF MEMORY POSITIONS NEEDED.									
156	3	01	DEYDD	ZA	ENR,PRDD-4	7	0553	+ 785	744		10	
157	3	02		M	ENR,PRDD	7	0560	+ 785	748		10	
158	3	03		MLCWA	PRDD,SAVE=7	7	0567	L 748	801		10	
159	3	04		A	ENR,PRDD	7	0574	A 785	748		10	
160	3	05		ZA	PRDD,PRDD-2	7	0581	+ 748	739		10	
161	3	06		M	+5,PRDD	7	0588	+ 802	741		11	
162	3	07		S	ZED,PRDD-1	7	0595	S 776	740		11	
163	3	08		CS	332	4	0602	/ 332			11	
164	3	09		CS		1	0606	/			11	
165	3	10		MLCWA	*NUMBER OF ZERO CELLS Z IS*,230	7	0607	L 827	230		11	
166	3	11		MLCWA	EDITA,235	7	0614	L 752	235		11	
167	3	12		MCE	ZED,235	7	0621	E 776	235		12	
168	3	13		W		1	0628	Z			12	
169	3	14		CC	K	2	0629	F K			12	
170	3	141		LS	299	4	0631	/ 299			12	
171	3	15		MLCWA	*UPPER BOUND U IS*,220	7	0635	L 843	220		12	
172	3	16		MLCWA	EDITB,230	7	0642	L 781	230		12	
173	3	161		MCE	BPRDD-1,230	7	0649	E 740	230		12	
174	3	17		W		1	0656	Z			13	
175	3	18		CC	K	2	0657	F K			13	
176	3	19		CS	299	4	0659	/ 299			13	
177	3	20		A	ENR,SAVE	7	0663	A 785	801		13	
178	3	21		A	ENR,SAVE	7	0670	A 785	801		13	
179	3	22		A	ENR,SAVE	7	0677	A 785	801		13	
180	3	23		S	ZED,SAVE	7	0684	S 776	801		13	
181	3	24		S	ZED,SAVE	7	0691	S 776	801		14	
182	3	25		MLCWA	*AMOUNT OF 1401 STORAGE NEEDED IS*,237	7	0698	L 875	237		14	
183	4	01		MLCWA	EDITC,245	7	0705	L 768	245		14	
184	4	02		MCE	SAVE,245	7	0712	E 801	245		14	
185	4	03		MLCWA	*POSITIONS FOR PROGRAM NO 1*,272	7	0719	L 901	272		14	
186	4	04		W		1	0726	Z			14	
187	4	05		CC	L	2	0727	F L			14	
188	4	06		H	BEGIN	4	0729	. 333			15	
189	99	999	* CONSTANTS AND SYMBOLS									
190	5	1	PRDD	DCW	=9	9	0741				15	
191	5	13	PRDD	DCW	=7	7	0746				15	
192	5	14	EDITA	DCW	* 5*	4	0752				15	
193	5	15	EDITB	DCW	*	9	0761				15	
194	5	16	EDITC	DCW	*	7	0768				16	
				DCW	+0000	4	0772			LII	16	
			195	ZED	+04	4	0775			AKFA	16	
					+001	3	0779			LII	16	

Table 27. Program 1—Compute Upper Bound of Matrix Size (Continued)

SEC	LN	LABEL	OP	OPERANDS	SEQ	CT	LOCN	INSTRUCTION	TYPE	CARD
	109	JAY		=03	3	0782			AREA	16
	112	END		=03	3	0785			AREA	16
				+006	3	0788			LIT	16
	114	AFALJ		=03	3	0791			AREA	17
				0	1	0792			LIT	17
	115	SWUNL		=01	1	0793			AREA	17
				+1	1	0794			LIT	17
	128	SAVE		=07	7	0801			AREA	17
				+5	1	0802			LIT	17
	169			*NUMBER OF ZERO CELLS Z IS*	25	0827			LIT	17
	171			*UPPER BOUND OF IS*	15	0843			LIT	18
	182			*AMOUNT OF 1401 STORAGE NEEDED IS*	32	0875			LIT	19
	185			*POSITIONS FOR PROGRAM NO 1*	26	0901			LIT	20
195	17	END		BEGIN			7 333 080			21

Table 28. Test Input—Program 1

018	TEST PROGRAM	
	W3	P101011001
	C5	R20A003002
	C4	R20A004002
	R1	R205005002
	C3	R20J006002
	C2	R20J007002
	W4	R201008002
	C3	C50A006003
	C2	C40A007004
	C3	R10A006005
	C2	R10A007005
	W3	R101011005
	C1	R10J012005
	D1	R10J015005
	D3	R10J017005
	C2	C30A007006
	C1	C20A012007
	H1	W401009008
	H2	W401010008
	D2	W401016008
	C1	W30A012011
	W1	W301013011
	W2	W301014011
	S1	W30J018011
	D3	C10A017012
	S1	C10A018012
	D1	W101015013
	D2	W101016013
	D3	W101017013
	D1	W201015014
	S1	W201016014
		0031
		0030
		0029
		0028
		0027
		0026
		0025
		0024
		0023
		0022
		0021
		0020
		0019
		0018
		0017
		0016
		0015
		0014
		0013
		0012
		0011
		0010
		0009
		0008
		0007
		0006
		0005
		0004
		0003
		0002
		0001

Table 29. Test Output--Program 1

NUMBER OF ZERO CELLS Z IS 45

UPPER BOUND U IS 126

AMOUNT OF 1401 STORAGE NEEDED IS 288 POSITIONS FOR PROGRAM NO 1

Table 30. Program 2--Compute Composed of Analysis Matrix

SEQ	LN	LIN	LABEL	OP	OPERANDS	SEQ	CT	LOCK	INSTRUCTION	TYPE	CARD
101	1	01	JOB	JOB	COMPUTE COMPOSED OF ANALYSIS MATRIX						
102	1	02		CTL	4401						
103	99	99			* INPUT CARD FIELDS- J-FIELD CC 21-22, I-FIELD CC 23-25, J-FIELD						
104	99	99			* CC 26-28, CARD SEQUENCE NUMBER CC 76-79. SORT IS A REVERSE SORT						
105	99	99			* J-FIELD MAJOR, I-FIELD MINOR						
106	99	99			* PROGRAM STARTS AT SETUP, WHICH IS IN PUNCH AREA AND IS CLEARED						
107	99	99			* AFTER USE, ANY RESTART EXCEPT SEQUENCE ERROR REQUIRES RELOADING						
108	99	99			* OF PROGRAM. LEAD CARD HAS MATRIX SIZE IN CC 1-3						
109	99	99			* READS LEAD CARD, SETS COUNTERS						
110	11	01		ORG	81					0081	
111	11	02		CS	199		4	0081	/	199	4
112	11	021		MLCWA	'9999',1540		7	0085	L	V21 W40	4
113	11	03		B	READ		4	0092	B	333	4
114	11	04		ORG	101					3101	
115	11	05	Setup	CS	80		4	0101	/	080	5
116	11	06		SW	1,11		7	0105	,	001 011	5
117	11	07		R			1	0112	1		5
118	11	08		ZA	3,COLND		7	0113	+	003 094	5
119	11	09		SW	21,23		7	0120	,	021 023	5
120	11	10		SW	26,76		7	0127	,	026 076	5
121	11	11		ZA	+1,5E4		7	0134	+	V22 V07	6
122	11	12		MLC	COLND,DIMFN		7	0141	M	094 V10	6
123	11	13		MLNS	+1,SW1		7	0148	D	V22 V18	6
124	11	14		MLNS	+0,SW4		7	0155	D	V23 V50	6
125	11	15		B	81		4	0162	B	081	6
126	99	99			* SETS ALL COLUMNS WITH INDEX GREATER THAN THAT OF FIRST DATA						
127	99	99			* CARD READ						
128	12	01		ORG	201					0201	
129	12	02	EARLY	MLC	HIGH,EARLY+13		7	0201	M	091 214	7
130	12	03		MLCWA	GAP,0		7	0208	L	097 000	7
131	12	04		MLC	HIGH,**14		7	0215	M	091 235	7
132	12	05		MA	THREE,**7		7	0222	=	V00 235	7
133	12	06		MLCWA	COLND,0		7	0229	L	094 000	7
134	12	07		MLCWA	COLND,106		7	0236	L	094 106	8
135	12	071		MLZS	'0',106		7	0243	Y	V24 106	8
136	12	08		B	PDIAG		4	0250	B	092	8
137	12	09	STPL	S	+1,COLND		7	0254	S	V22 094	8
138	12	10		S	23,COLND		7	0261	C	028 094	8
139	12	11		SE	RESET		5	0268	E	291 S	8
140	12	12		A	+1,GAP		7	0273	A	V22 097	9
141	12	13		MA	SIX,HIGH		7	0280	=	V03 091	9
142	12	14		S	EARLY		4	0287	S	201	9
143	12	15	Reset	MLNS	+0,SW1		7	0291	D	V23 V18	9
144	12	16		B	COLSET		4	0295	B	177	9
145	1	03		ORG	333					0333	
146	99	99			* THIS SECTION READS DATA CARD, PERFORMS SEQUENCE CHECK, AND						
147	99	99			* PASSES SELECTION SELECTION CARD. TEST IN CONTROL BREAK ON J-INDEX						

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LN	LABEL	OP	OPERANDS	SFX	CT	LOGN	INSTRUCTION	TYPE	CARD	
148	99	99	*		CARD ESTABLISHES NUMBER OF COLUMNS TO SKIP IN SEARCH FOR PROMPT							
149	99	99	*		COLUMN FOR MULTIPLICATION. SLIDE FINDS THE COLUMN.							
150	1	04	READ	R		1	0333	L			10	
151	1	041		MLZS	+0,79	7	0334	Y	V23	079	10	
152	1	05		C	79,560	7	0341	C	079	V07	10	
153	1	05		GD	MIXED	5	0346	B	747	/	10	
154	1	07		A	+1,560	7	0353	A	V22	V07	10	
155	1	071		MLZS	+0,26	7	0360	Y	V23	028	10	
156	1	05		BWZ	READ,22,K	8	0367	V	333	022	K	11
157	1	09	CARD	C	28,COLND	7	0375	C	028	094	11	
158	1	10		BH	CLOSE	5	0382	B	785	U	11	
159	1	11		MLC	HIGH,SEARCH=3	7	0387	M	091	V27	11	
160	1	12		MA	SIX,SEARCH	7	0394	=	V16	V27	11	
161	1	13		MLCWA	25,LOOK=3	7	0401	L	025	V30	12	
162	1	14		S	28,LOOK	7	0408	S	028	V30	12	
163	1	15		S	+1,LOOK	7	0415	S	V22	V30	12	
164	1	16		MLCWA	COLND,ARL=3	7	0422	L	w20	V33	12	
165	1	17		A	+2,ARL	7	0429	A	V34	V33	12	
166	1	18	SLIDE	MLCWA	ARL,ARL=3	7	0436	L	V33	V37	13	
167	1	19		C	+00%,LOOK	7	0443	C	V40	V30	13	
168	1	20		BE	THIS	5	0450	B	505	S	13	
169	1	21		MLC	SEARCH,++4	7	0455	M	V27	465	13	
170	1	22		S	0,ARL	7	0462	S	000	V37	13	
171	1	221		MLZS	*0*,ARL	7	0469	Y	V24	V37	14	
172	1	23		MA	ARL	4	0476	=	V37		14	
173	1	24		MA	ARL,SEARCH	7	0480	=	V37	V27	14	
174	1	25		S	+1,LOOK	7	0487	S	V22	V30	14	
175	2	01		S	+1,2RL	7	0494	S	V22	V33	14	
176	2	02		B	SLIDE	4	0501	B	436		14	
177	99	99	*		FINDS BOTTOM OF COLUMN TO BE MULTIPLIED.							
178	2	03	THIS	MLCWA	DIMEN,NOML=3	7	0505	L	V10	V43	15	
179	2	04		MLC	SEARCH,++11	7	0512	M	V27	529	15	
180	2	05		MA	THRETY,++4	7	0519	=	V00	529	15	
181	2	06		S	0,NOML	7	0526	S	000	V43	15	
182	2	07		MLCWA	NOML,ARL	7	0533	L	V43	V37	15	
183	2	08		MLC	SEARCH,++4	7	0540	M	V27	550	16	
184	2	09		S	0,ARL	7	0547	S	000	V37	16	
185	2	091		MLZS	*0*,ARL	7	0554	Y	V24	V37	16	
186	2	10		MA	ARL	4	0561	=	V37		16	
187	2	11		MLCWA	SEARCH,TRACE=3	7	0565	L	V27	V46	16	
188	2	12		MA	ARL,TRACE	7	0572	=	V37	V46	16	
189	2	13		MLCWA	HIGH,FOLLOW=3	7	0579	L	091	V49	17	
190	2	14		BWZ	CONCOM,22,B	3	0586	V	849	022	3	17
191	2	15		B	REGMUL	4	0594	B	618		17	
192	99	99	*		TEST FOR LAST CARD							
193	2	15	REMAIN	BEH	LAST	5	0598	B	607	A	17	
194	2	17		S	BEAL	4	0603	B	333		17	
195	99	99	*		SLIDE SWITCH ON LAST CARD							
196	2	18	LAST	NEWS	1,SEARCH	7	0607	D	001	V50	17	
197	2	19		B	CLOSE	4	0614	B	785		17	

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LN	LABEL	OP	OPERANDS	SEX	CT	LOCN	INSTRUCTION	TYPE	CARD
198	99	99	*		MULTIPLICATION FOR REGULAR NUMERAL ON INPUT CARD. BACK IS A						
199	99	99	*		REENTRY POINT FOR HOLDZ.						
200	99	99	*		COMP IS A REENTRY POINT FOR ZZONE AND REPLIC						
201	3	01	REGMUL	ZA	22,CTR2	7		0618	+ 022	V52	18
202	3	02		S	+1,CTR2	7		0625	S V22	V52	18
203	3	03		C	TRACE,SEARCH	7		0632	C V46	V27	18
204	3	04		DE	DIAG	5		0639	B 751	S	18
205	3	05		MLC	FOLLOW,++7	7		0644	M V49	657	18
206	3	06		BWZ	HOLDZ,0,S	8		0651	V 813	000 S	19
207	3	08	BACK	MLC	TRACE,++11	7		0659	M V46	676	19
208	3	09		MLC	FOLLOW,++7	7		0666	M V49	679	19
209	3	10		A	0,0	7		0673	A 000	000	19
210	3	11		BCE	REPLIC,SW3,1	8		0680	B 824	V58 1	19
211	3	12		MLC	TRACE,++7	7		0686	M V46	701	20
212	3	13		BWZ	ZZONE,0,S	8		0695	V 733	000 S	20
213	3	14	COMP	C	+00,CTR2	7		0703	C V54	V52	20
214	3	15		BU	REGMUL+7	5		0710	B 829	7	20
215	3	16		MA	TWON,TRACE	7		0715	= V13	V46	20
216	3	17		MA	TWON,FOLLOW	7		0722	= V13	V49	21
217	3	18		B	REGMUL	4		0727	B 616		21
218	99	99	*		TAGS A CELL AS CONCOMITANT QUANTIFIER						
219	3	20	ZZONE	MLC	FOLLOW,++7	7		0733	M V49	746	21
220	3	21		MLZS	SLASH,0	7		0740	Y V17	000	21
221	3	22		B	COMP	4		0747	B 703		21
222	99	99	*		FINDS NUMBER OF NON-STORED ZERO CELLS IN COLUMN. SETS ADDRESS FG						
223	99	99	*		FORCING IN OF MULTIPLICATION OF DIAGONAL						
224	4	01	DIAG	MLC	SEARCH,++4	7		0751	M V27	761	21
225	4	02		ZA	0,CTR3	7		0758	+ 000	V57	22
226	4	04		C	+000,CTR3	7		0765	C V40	V57	22
227	4	05		BE	INS	5		0772	B 735	S	22
228	4	05.1		S	+1,CTR3	7		0777	S V22	V57	22
229	4	06		MA	TWON,FOLLOW	7		0784	= V13	V49	22
230	4	07		B	DIAG+14	4		0791	B 765		22
231	99	99	*		MULTIPLICATION OF DIAGONAL						
232	4	08	INS	MLC	FOLLOW,++7	7		0795	M V49	808	23
233	4	09		A	22,0	7		0802	A 022	000	23
234	4	10		B	REMAIN	4		0809	B 593		23
235	99	99	*		SETS SWITCH FG INDICATE CONCOMITANT CELL IN COLUMN						
236	4	12	HOLDZ	MLNS	+1,SW3=1	7		0813	B V22	V58	23
237	4	13		B	BACK	4		0820	B 659		23
238	99	99	*		TAGS A CELL AS A CONCOMITANT QUANTIFIER, RESETS A SWITCH						
239	4	14	REPLIC	MLC	FOLLOW,++7	7		0824	M V49	837	23
240	4	15		MLZS	SLASH,0	7		0831	Y V17	000	24
241	4	16		MLNS	+0,SW3	7		0838	B V23	V58	24
242	4	17		B	COMP	4		0845	B 703		24
243	99	99	*		MULTIPLICATION FOR A CONCOMITANT QUANTIFIER ON INPUT CARD						
244	99	99	*		ZONE FORCES A ZERO WHEN CONCOMITANTS ARE MULTIPLIED TOGETHER						
245	3	01	CONCOR	ZA	22,CTR2	7		0849	+ 022	V52	24
246	3	02		S	+1,CTR2	7		0856	S V22	V52	24
247	3	03		C	TRACE,SEARCH	7		0863	C V46	V27	24

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
248	5	04		BE	CONDIA			0870	B 974 S		25
249	5	041		MLC	TRACE,++7			0875	M V46 888		25
250	5	042		C	+00,0			0882	C V54 000		25
251	5	043		BE	ZEDIN			0889	B 956 S		25
252	5	05		MLL	TRACE,++7			0894	M V46 907		25
253	5	06		BWZ	ZEDIN,0,S			0901	V 956 000 S		25
254	5	07		MLC	TRACE,++11			0909	M V46 926		26
255	5	08		MLC	FOLLOW,++7			0916	M V49 929		26
256	5	09		A	0,0			0923	A 000 000		26
257	5	10		MLL	FOLLOW,++7			0930	M V49 943		26
258	5	11		MLZS	SLASH,0			0937	Y V17 000		26
259	5	12		C	+00,CTR2			0944	C V54 V52		27
260	5	13		BU	CONCOM+7			0951	B 856 /		27
261	5	14	ZEDIN	MA	TWON,TRACE			0956	= V13 V46		27
262	5	15		MA	TWON,FOLLOW			0963	= V13 V49		27
263	5	16		B	CONCOM			0970	B 849		27
264	99	99			* FINDS NUMBER OF NON-STORED ZERO CELLS - CONCOMITANT MULTI						
265	5	18	CONDIA	MLC	SEARCH,++4			0974	M V27 984		27
266	5	19		ZA	0,CTR3			0981	+ 000 V57		28
267	5	21		C	+000,CTR3			0988	C V40 V57		28
268	5	22		BF	CONDIA			0995	B #18 S		28
269	5	221		S	+1,CTR3			1000	S V22 V57		28
270	5	23		MA	TWON,FOLLOW			1007	= V13 V49		28
271	5	24		B	CONDIA+14			1014	B 988		28
272	99	99			* MULTIPLICATION OF DIAGONAL - CONCOMITANT						
273	6	01	CONDIA	MLC	FOLLOW,++7			1018	M V49 #31		29
274	6	02		A	22,0			1025	A 022 000		29
275	6	03		MLC	FOLLOW,++7			1032	M V49 #45		29
276	6	04		MLZS	SLASH,0			1039	Y V17 000		29
277	6	05		B	REMAIN			1046	B 998		29
278	99	99			* FORMS AND STORES DATA WORD IN PLACE OF DIAGONAL. CONTAINS COLUMN						
279	99	99			* INDEX AND NUMBER OF ZERO CELLS ELIMINATED						
280	7	01	SETDIG	MLC	TOP,++7			1050	M W08 #63		30
281	7	02		MLCWA	GAP,0			1057	L 097 000		30
282	7	03		MA	THRETN,TOP			1064	= W00 W08		30
283	7	04		MLC	TOP,++7			1071	M W08 #84		30
284	7	05		MLCWA	COLNO,0			1078	L 094 000		30
285	7	06		MLC	BOTTOM,HIGH			1085	M #11 091		30
286	99	99			* PUNCHES DIAGONAL CELL CARD ON LAST COLUMN GIVES JOB DONE						
287	99	99			* MESSAGE AND HALTS						
288	7	08	PDIA6	MLCWA	106,103			1092	L 106 103		31
289	7	09		MLCWA	#01,108			1099	L V60 108		31
290	7	10		P				1106	4		31
291	7	11		B	STEPR,S#1,1			1107	S 254 V18 1		31
292	7	12		S	+1,COLNO			1115	S V22 094		31
293	7	13		B	CULST,SW4,0			1122	B 177 V50 0		31
294	7	131		CS	332			1130	Z 332		32
295	7	132		CS				1134	/		32
296	7	133		MLC	'JOB DONE',203			1135	M V68 208		32
297	7	134		W				1142	2		32

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
298	7	135		H	*-4	4		1143	.	/42	32
299	7	99	*		ERROR ROUTINE FOR SEQUENCE CHECK						
300	7	14	MIXED	CS	332	4		1147	/	332	32
301	7	15		CS		1		1151	/		32
302	7	16		MLC	*SEQUENCE-NEXT SB	7		1152	M	W05 237	33
303	7	161		MLZS	'0',SFQ	7		1159	Y	V24 V07	33
304	7	17		MLC	SEQ,221	7		1166	M	V07 221	33
305	7	171		MLZS	+1,SEQ	7		1173	Y	V22 V07	33
306	7	18		W		1		1180	2		33
307	7	19		H	READ	4		1181	.	333	33
308	7	99	*		ON COLUMN CONTROL BREAK, FINDS ENDS OF COLUMN						
309	8	01	CLUSE	B	EARLY,SW1,1	8		1185	B	Z01 V18 L	34
310	8	02		MLC	CELLS+6,TOP=3	7		1193	M	U18 W08	34
311	8	03		MLC	HIGH,BOTTOM=3	7		1200	M	U91 W11	34
312	8	04		MLC	COLNO,1,6	7		1207	M	U94 106	34
313	8	041		MLZS	'0',106	7		1214	Y	V24 106	34
314	8	05		MLC	DIMEN,ROWND=3	7		1221	M	V10 W14	35
315	8	06		MLCWA	+00,GAP	7		1228	L	V40 U97	35
316	7	99	*		ELIMINATES ZERO CELLS UNDER DIAGONAL						
317	8	07	HERE	MLC	TOP,**7	7		1235	M	W08 S48	35
318	8	08		C	+00,0	7		1242	C	V54 000	35
319	8	09		BU	PUNCH	5		1249	B	S72 /	35
320	8	10		MA	'002',TOP	7		1254	=	W17 W08	36
321	8	11		A	+1,GAP	7		1261	A	V22 U97	36
322	8	12		B	HERE	4		1268	B	S35	36
323	7	99	*		PUNCH ROUTINE, EXCEPT DIAGONAL. ZERO CELLS NOT PUNCHED						
324	7	99	*		STEP CHANGES ADDRESSES						
325	8	13	PUNCH	MA	TWON,TOP	7		1272	=	V13 W08	36
326	8	131		C	TOP,BOTTOM	7		1279	C	W08 W11	36
327	8	132		BE	SETDIG	5		1286	B	#50 S	36
328	8	14		MLC	BOTTOM,**7	7		1291	M	W11 T04	37
329	8	15		C	+00,0	7		1298	C	V54 000	37
330	8	16		BE	STEP	5		1305	B	T47 S	37
331	8	17		MLCWA	ROWND,103	7		1310	L	W14 103	37
332	8	171		MLZS	'0',103	7		1317	Y	V24 103	37
333	8	18		MLC	BOTTOM,**4	7		1324	M	W11 T34	38
334	8	19		MLCWA	0,103	7		1331	L	000 108	38
335	8	191		BWZ	SWEEP,108,B	8		1338	V	U78 108 B	38
336	8	20		P		1		1346	4		38
337	8	21	STEP	MA	TWON,BOTTOM	7		1347	=	V13 W11	38
338	8	22		C	TOP,BOTTOM	7		1354	C	W08 W11	38
339	8	23		BF	SETDIG	5		1361	B	#50 S	39
340	8	24		S	+1,ROWND	7		1366	S	V22 W14	39
341	8	25		B	PUNCH+7	4		1373	B	S79	39
342	7	99	*		FINDS NUMBER OF CELLS IN NEXT COLUMN TO BE COMPUTED. CELLS						
343	7	99	*		SFIS EACH CELL TO ZERO, ALSO TESTS TO KEEP FROM STARTING TOO						
344	7	99	*		LARGE A MATRIX.						
345	9	01	COLSET	MLC	DIMEN,COLN=3	7		1377	M	V10 W20	39
346	9	02		S	COLNO,COLN	7		1384	S	U94 W20	39
347	9	03		MLC	+00,CTRL=3	7		1391	M	V40 W23	39

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD	
348	9	04		MA	SIXX,HIGH	7		1398	= V03 U91		40	
349	9	05		MLC	HIGH,CELLS+6	7		1405	M U91 U18		40	
350	9	06	CELLS	MLCWA	+00,0	7		1412	L V54 000		40	
351	9	07		A	+1,CTR1	7		1419	A V22 W23		40	
352	9	08		C	CTR1,COLEN	7		1426	C W23 W20		40	
353	9	09		BE	CARD	5		1433	B 375 S		41	
354	9	10		MA	TWON,CELLS+6	7		1438	= V13 U18		41	
355	9	11		C	'999',1640	7		1445	C V21 W40		41	
356	9	12		DU	DVRFLD	5		1452	B U61 /		41	
357	9	13		B	CELLS	4		1457	B U12		41	
358	99	99		* ERROR ROUTINE IF MEMORY CAPACITY IS EXCEEDED								
359	9	15	DVRFLD	CS	332	4		1461	/ 332		41	
360	9	16		CS		1		1465	/		41	
361	9	17		MLC	'MEMORY FULL',211	7		1466	M W34 211		42	
362	9	18		W		1		1473	Z		42	
363	9	19		H	*-4	4		1474	. U73		42	
364	99	99		* CLEARS PLUS SIGN FROM REGULAR CELL								
365	9	26	SWEEP	MLZS	'0',108	7		1478	Y V24 108		42	
366	9	27		B	STEP-1	4		1485	B 146		42	
367	99	99		* CONSTANTS AND SYMBOLS								
368	10	01	HIGH	DSA	7999	3		1491	19Z		42	
369	10	02	CULNG	DCW	+000	3		1494			42	
370	10	03	GAP	DCW	+000	3		1497			43	
371	10	04	THREEN	DSA	15997	3		1500	19G		43	
372	10	05	SIXW	DSA	15994	3		1503	19D		43	
373	10	06	SEQ	DCW	+0000	4		1507			43	
374	10	07	DIME4	DCW	+000	3		1510			43	
375	10	08	TWON	DSA	15998	3		1513	19h		43	
376	10	10	SIX	DSA	006	3		1516	006		43	
377	10	11	SLASH	DC	/'	1		1517			44	
378	10	12	SW1	DCW	'0'	1		1518			44	
				DCW	'999'	3		1521		LIT	44	
					+1	1		1522		LIT	44	
					+0	1		1523		LIT	44	
					'0'	1		1524		LIT	45	
159			SEARCH		=03	3		1527		AREA	45	
161			LUOK		=03	3		1530		AREA	45	
164			BRL		=03	3		1533		AREA	45	
					+2	1		1534		LIT	45	
166			ARL		=03	3		1537		AREA	45	
					+000	3		1540		LIT	45	
178			NOML		=03	3		1543		AREA	46	
187			TRACC		=03	3		1546		AREA	46	
189			FULLON		=03	3		1549		AREA	46	
196			SW4		=01	1		1550		AREA	46	
201			CTR2		=02	2		1552		AREA	46	
					+00	2		1554		LIT	46	
225			CTR3		=03	3		1557		AREA	46	
236			SW3		=01	1		1558		AREA	47	
					'01'	2		1560		LIT	47	

Table 30. Program 2—Compute Composed of Analysis Matrix (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
		296			'JOB DONE'	8		1568		LIT	47
		302			'SEQUENCE-NEXT SB	37		1605		LIT	48
		310	TOP		=03	3		1608		AREA	49
		311	BOTTOM		=03	3		1611		AREA	49
		314	ROWNO		=03	3		1614		AREA	49
					'002'	3		1617		LIT	49
		345	COLEN		=03	3		1620		AREA	49
		347	CTRL		=03	3		1623		AREA	49
		351			'MEMORY FULL'	11		1634		LIT	49
379	12	17		END	SETUP				/ 101 060		50

Table 31. Program 3—Compute Contained in Analysis Matrix

SEQ	PG	LN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
101	1	01	000	JOB	COMPUTE CONTAINED IN ANALYSIS MATRIX						
102	1	02		CTL	4401						
103	99	99			* INPUT CARD FIELDS- Q-FIELD CC 21-22, I-FIELD CC 23-25, J-FIELD						
104	99	99			* CC 26-28, CARD SEQUENCE NUMBER CC 76-79. SORT IS A REVERSE SORT						
105	99	99			* J-FIELD MAJOR, I-FIELD MINOR						
106	99	99			* PROGRAM STARTS AT SETUP, WHICH IS IN PUNCH AREA AND IS CLEARED						
107	99	99			* AFTER USE. ANY RESTART EXCEPT SEQUENCE ERROR REQUIRES RELOADING						
108	99	99			* OF PROGRAM. LEAD CARD HAS MATRIX SIZE IN CC 1-3						
109	99	99			* READS LEAD CARD, SETS COUNTERS						
110	11	01		ORG	81				J081		
111	11	02		CS	199	4	0081	/	199		4
112	11	021		MLCWA	'999',1850	7	0085	L	X20	Y50	4
113	11	03		B	READ	4	0092	B	333		4
114	11	04		ORG	101				J101		
115	11	05	SETUP	CS	80	4	0101	/	080		5
116	11	06		SW	1,11	7	0105	,	001	011	5
117	11	07		R		1	0112	1			5
118	11	08		ZA	3,COLNO	7	0113	+	003	W92	5
119	11	09		SW	21,23	7	0120	,	021	023	5
120	11	10		SW	26,76	7	0127	,	026	076	5
121	11	11		ZA	+1,SEQ	7	0134	+	X21	X05	6
122	11	12		MLC	COLNO,DIMEN	7	0141	M	W92	X08	6
123	11	13		MLNS	+1,S#1	7	0148	D	X21	X16	6
124	11	14		MLNS	+0,S#4	7	0155	D	X22	X49	6
125	11	15		B	81	4	0162	B	081		6
126	99	99			* SETS ALL COLUMNS WITH INDEX GREATER THAN THAT OF FIRST DATA						
127	99	99			* CARD READ						
128	12	01		ORG	201				J201		
129	12	02	EARLY	MLC	HIGH,EARLY+13	7	0201	M	W89	214	7
130	12	03		MLCWA	GAP,0	7	0208	L	W95	000	7
131	12	04		MLC	HIGH,#+14	7	0215	M	W89	235	7
132	12	05		MA	THREE,#+7	7	0222	=	W98	235	7
133	12	06		MLCWA	COLNO,0	7	0229	L	W92	000	7
134	12	07		MLCWA	COLNO,106	7	0236	L	W92	106	8
135	12	071		MLZS	'0',106	7	0243	Y	X23	106	8
136	12	08		D	PDIAG	4	0250	B	S24		8
137	12	09	STEPR	S	+1,COLNO	7	0254	S	X21	W92	8
138	12	10		C	28,COLNO	7	0261	C	028	W92	8
139	12	11		BE	RESET	5	0266	B	291	S	8
140	12	12		A	+1,GAP	7	0273	A	X21	W95	9
141	12	13		MA	SIX, HIGH	7	0280	=	X01	W89	9
142	12	14		B	EARLY	4	0287	B	201		9
143	12	15	RESET	MLNS	+0,S#1	7	0291	D	X22	X16	9
144	12	16		S	COLSET	4	0298	B	V39		9
145	1	03		ORG	333				J333		
146	99	99			* THIS SECTION READS DATA CARD, PERFORMS SEQUENCE CHECK, AND						
147	99	99			* BRANCHES ON DELETION CARD. TEST IS CONTROL BREAK ON J-INDEX.						

Table 31. Program 3—Compute Contained in Analysis Matrix (Continued)

SEQ	PG	LINE	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
148	99	99	* CARD ESTABLISHES NUMBER OF COLUMNS TO SKIP IN SEARCH FOR PROPER								
149	99	99	* COLUMN FOR MULTIPLICATION. SLIDE FINDS THE COLUMN.								
150	1	04	READ	R		1		0333	L		10
151	1	04L		MLZS	+0,77	7		0334	Y	X22 079	10
152	1	05		C	79,569	7		0341	C	079 X05	10
153	1	06		BU	MIXED	5		0348	B	S79 /	10
154	1	07		A	+1,500	7		0353	A	X21 X05	10
155	1	07L		MLZS	+0,28	7		0360	Y	X22 028	10
156	1	09	CARD	C	28,COLW	7		0367	C	028 W92	11
157	1	10		BH	CLOSE	5		0374	B	117 0	11
158	1	01		BWZ	DELETE,22,K	8		0379	V	977 022 K	11
159	1	11		MLC	HIGH,SEARCH=3	7		0387	M	W89 X26	11
160	1	12		MA	SIX,SEARCH	7		0394	=	X14 X26	11
161	1	13		MLCWA	25,LOOK=3	7		0401	L	C25 X29	12
162	1	14		S	28,LOOK	7		0408	S	028 X29	12
163	1	15		S	+1,LOOK	7		0415	S	X21 X29	12
164	1	16		MLCWA	COLEN,BRL=3	7		0422	L	Y24 X32	12
165	1	17		A	+2,BRL	7		0429	A	X33 X32	12
166	1	18	SLIDE	MLCWA	BRL,ARL=3	7		0436	L	X32 X36	13
167	1	19		C	+00,LOOK	7		0443	C	X39 X29	13
168	1	20		DE	THIS	5		0450	B	505 5	13
169	1	21		MLC	SEARCH,++4	7		0455	M	X26 465	13
170	1	22		S	0,ARL	7		0462	S	C00 X36	13
171	1	22L		MLZS	+0,ARL	7		0469	Y	X23 X36	14
172	1	23		MA	ARL	4		0476	=	X36	14
173	1	24		MA	ARL,SEARCH	7		0480	=	X36 X26	14
174	1	25		S	+1,LOOK	7		0487	S	X21 X29	14
175	2	01		S	+1,BRL	7		0494	S	X21 X32	14
176	2	02		B	SLIDE	4		0501	B	436	14
177	99	99	* FINDS BOTTOM OF COLUMN TO BE MULTIPLIED.								
178	2	03	THIS	MLCWA	DIMEN,NUML=3	7		0505	L	X08 X42	15
179	2	04		MLC	SEARCH,++11	7		0512	M	X26 529	15
180	2	05		MA	THREVEN,++4	7		0519	=	W98 529	15
181	2	06		S	0,NUML	7		0526	S	C00 X42	15
182	2	07		MLCWA	NUML,ARL	7		0533	L	X42 X36	15
183	2	08		MLC	SEARCH,++4	7		0540	M	X26 550	16
184	2	09		S	0,ARL	7		0547	S	C00 X36	16
185	2	09L		MLZS	+0,ARL	7		0554	Y	X23 X36	16
186	2	10		MA	ARL	4		0561	=	X36	16
187	2	11		MLCWA	SEARCH,TRACE=3	7		0565	L	X26 X45	16
188	2	12		MA	ARL,TRACE	7		0572	=	X36 X45	16
189	2	13		MLCWA	HIGH,FOLLOW=3	7		0579	L	W89 X48	17
190	2	14		BWZ	CONCOM,22,B	8		0586	V	902 022 b	17
191	2	15		B	NULL	4		0594	B	625	17
192	99	99	* TEST FOR LAST CARD								
193	2	15L	REMAI	MLZS	+9,ARL	7		0598	D	X22 X17	17
194	2	16		ELC	LAST	5		0605	D	614 A	17
195	2	17		B	REAR	4		0610	B	333	17
196	99	99	* SETS SWITCH ON LAST CARD								
197	2	18	LAST	MLZS	1,SW=1	7		0614	D	001 X47	18

Table 31. Program 3—Compute Contained in Analysis Matrix (Continued)

SEQ	PC	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
196	2	19		B	CLOSE	4		0621	B T17		18
197	99	99			* MULTIPLICATION FOR REGULAR NUMERAL ON INPUT CARD. BACK IS A						
200	99	99			* REENTRY POINT FOR HOLDZ.						
201	99	99			* COMP IS A REENTRY POINT FOR ZZONE AND REPLIC						
202	3	001	NULL	C	'000',ARL	7		0625	C X52 X36		18
203	3	002		BU	CONDIT	5		0632	B 785 /		18
204	3	01	REGMUL	ZA	22,CTR2=2	7		0637	+ 022 X54		18
205	3	02		S	+1,CTR2	7		0644	S X21 X54		18
206	3	03		C	TRACE,SEARCH	7		0651	C X45 X26		19
207	3	04		BE	PATCH	5		0658	B 796 S		19
208	3	05		MLC	FOLLOW,++7	7		0663	M X48 676		19
209	3	06		BWZ	HOLDZ,0,S	8		0670	V 866 000 S		19
210	3	07		MLC	FOLLOW,++7	7		0678	M X48 691		19
211	3	071		BCE	COMP+12,0,=	8		0685	B 749 000 =		20
212	3	08	BACK	MLC	TRACE,++11	7		0693	M X45 710		20
213	3	09		MLC	FOLLOW,++7	7		0700	M X48 713		20
214	3	10		A	0,0	7		0707	A 000 000		20
215	3	11		BCE	REPLIC,SW3,1	8		0714	B 877 X60 1		20
216	3	12		MLC	TRACE,++7	7		0722	M X45 735		21
217	3	13		BWZ	ZZONE,0,S	8		0729	V 767 000 S		21
218	3	14	COMP	C	+00,CTR2	7		0737	C X56 X54		21
219	3	15		BU	REGMUL+7	5		0744	B 644 /		21
220	3	16		MA	TWON,TRACE	7		0749	= X11 X45		21
221	3	17		MA	TWON,FOLLOW	7		0756	= X11 X48		22
222	3	18		B	REGMUL	4		0763	B 637		22
223	99	99			* TAGS A CELL AS CONCOMITANT QUANTIFIER						
224	3	20	ZZONE	MLC	FOLLOW,++7	7		0767	M X48 780		22
225	3	21		MLZS	SLASH,0	7		0774	Y X15 000		22
226	3	22		B	COMP	4		0781	B 737		22
227	99	99			* SETS A SWITCH TO BYPASS MULTIPLICATION WHEN COLUMN CONSISTS						
228	99	99			* OF ONLY THE DIAGONAL						
229	3	15	CONDIT	MLNS	+1,SW5	7		0785	D X21 X17		22
230	3	16		B	REGMUL	4		0792	B 637		23
231	99	99			* FINDS NUMBER OF NON-STORED ZERO CELLS IN COLUMN, SFXS ADDRESS FO						
232	99	99			* FORCING IN OF MULTIPLICATION OF DIAGONAL						
233	4	001	PATCH	B	REMAIN,SW5,1	8		0796	B 598 X17 1		23
234	4	01	DIAG	MLC	SEARCH,++4	7		0804	M X26 814		23
235	4	02		ZA	0,CTR3=3	7		0811	+ 000 X59		23
236	4	04		C	+000,CTR3	7		0818	C X39 X59		23
237	4	05		BE	INS	5		0825	B 848 S		23
238	4	051		S	+1,CTR3	7		0830	S X21 X59		24
239	4	06		MA	TWON,FOLLOW	7		0837	= X11 X48		24
240	4	07		B	DIAG+14	4		0844	B 818		24
241	99	99			* MULTIPLICATION OF DIAGONAL						
242	4	08	INS	MLC	FOLLOW,++7	7		0848	M X45 861		24
243	4	09		A	22,0	7		0855	A 022 000		24
244	4	10		B	REMAIN	4		0862	B 598		24
245	99	99			* SETS SWITCH TO INDICATE CONCOMITANT CELL IN COLUMN						
246	4	12	HOLDZ	MLNS	+1,SW3=1	7		0856	D X21 X60		25
247	4	13		B	BACK	4		0873	B 693		25

Table 31. Program 3—Compute Contained in Analysis Matrix (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
248	99	99	* TAGS A CELL AS A CONCOMITANT QUANTIFIER, RESETS A SWITCH								
249	4	14	REPLC	MLC	FOLLOW, **7	7		0877	M	X48 890	25
250	4	15		MLZS	SLASH, 0	7		0884	Y	X15 000	25
251	4	16		MLNS	+0, SW3	7		0891	D	X22 X60	25
252	4	17		B	COMP	4		0898	B	737	25
253	99	99	* MULTIPLICATION FOR A CONCOMITANT QUANTIFIER ON INPUT CARD								
254	99	99	* ZEDIN FORCES A ZERO WHEN CONCOMITANTS ARE MULTIPLIED TOGETHER								
255	5	01	CONCOM	ZA	Z2,CTR2	7		0902	+	022 X54	26
256	5	02		S	+1,CTR2	7		0909	S	X21 X54	26
257	5	03		C	TRACE,SEARCH	7		0916	C	X45 X26	26
258	5	04		BE	CONDIS	5		0923	B	706 S	26
259	5	041		MLC	TRACE, **7	7		0928	M	X45 941	26
260	5	042		C	+00,0	7		0935	C	X56 000	27
261	5	043		DE	ZEDIN	5		0942	D	#88 S	27
262	5	05		MLC	TRACE, **7	7		0947	M	X45 960	27
263	5	06		SWZ	ZEDIN, 0, S	8		0954	V	#88 000 S	27
264	5	061		MLC	FOLLOW, **7	7		0962	M	X48 975	27
265	5	062		BCE	ZEDIN, 0, =	8		0969	B	#88 000 =	28
266	99	99	* PUTS -=SYMBOL IN COLUMN TO INDICATE DELETION								
267	6	06	DELETE	MLC	CELLS+6, FOLLOW	7		0977	M	V80 X48	28
268	6	07		MLC	Z5, NOML	7		0984	M	025 X42	28
269	6	08		S	COLNO, NOML	7		0991	S	W92 X42	28
270	6	09		S	+1, NOML	7		0998	S	X21 X42	28
271	6	091		MLZS	*0, NOML	7		1005	Y	X23 X42	29
272	6	10		MA	NOML	4		1012	=	X42	29
273	6	11		MA	NOML, FOLLOW	7		1016	=	X42 X48	29
274	6	12		MLC	FOLLOW, **7	7		1023	M	X48 #36	29
275	6	13		MLCWA	*0=*, 0	7		1030	L	X62 000	29
276	6	14		B	REMAIN	4		1037	B	598	29
277	5	07		MLC	TRACE, **11	7		1041	M	X45 #58	30
278	5	08		MLC	FOLLOW, **7	7		1048	M	X48 #61	30
279	5	09		A	0, 0	7		1055	A	000 000	30
280	5	10		MLC	FOLLOW, **7	7		1062	M	X48 #75	30
281	5	11		MLZS	SLASH, 0	7		1069	Y	X15 000	30
282	5	12		C	+00, CTR2	7		1076	C	X56 X54	31
283	5	13		BU	CONCOM+7	5		1083	B	909 /	31
284	5	14	ZEDIN	MA	TWON, TRACE	7		1088	=	X11 X45	31
285	5	15		MA	TWON, FOLLOW	7		1095	=	X11 X48	31
286	5	16		B	CONCOM	4		1102	B	902	31
287	99	99	* FINDS NUMBER OF NON-STORED ZERO CELLS - CONCOMITANT MULT								
288	5	18	CONDIS	MLC	SEARCH, **4	7		1106	M	X26 /16	31
289	5	19		ZA	0, CTR3	7		1113	+	000 X59	32
290	5	21		C	+000, CTR3	7		1120	C	X39 X59	32
291	5	22		BE	CONINS	5		1127	B	750 S	32
292	5	221		S	+1, CTR3	7		1132	S	X21 X59	32
293	5	23		MA	TWON, FOLLOW	7		1139	=	X11 X48	32
294	5	24		B	CONDIS+14	4		1146	B	720	32
295	99	99	* MULTIPLICATION OF DIAGONAL - CONCOMITANT								
296	6	01	CONINS	MLC	FOLLOW, **7	7		1150	M	X48 /63	33
297	6	02		A	Z2, 0	7		1157	A	022 000	33

Table 31. Program 3—Compute Contained in Analysis Matrix (Continued)

JOB	NO.	LIN	LABEL	OP	OPERANDS	SEX	CL	LOCN	INSTRUCTION	TYPE	CARD
298	6	03		MLC	FOLLOW, **7	7		1164	M X48	/77	33
299	6	04		MLZS	SLASH, 7	7		1171	Y X15	000	33
300	6	05		B	REMAI	4		1176	B	598	33
301	99	99			* FORMS AND STORES DATA WORD IN PLACE OF DIAGONAL. CONTAINS COLUMN						
302	99	99			* INDEX AND NUMBER OF ZERO CELLS ELIMINATED						
303	7	01	SETDIO	MLC	TOP, **7	7		1182	M Y12	/95	33
304	7	02		MLCWA	GAP, 0	7		1189	L W95	000	34
305	7	03		MA	THRESH, TOP	7		1196	= W98	Y12	34
306	7	04		MLC	TOP, **7	7		1203	M Y12	S16	34
307	7	05		MLCWA	COLNO, 0	7		1210	L W92	000	34
308	7	06		MLC	BOTTOM, HIGH	7		1217	M Y15	W89	34
309	99	99			* PUNCHES DIAGONAL CELL CARD ON LAST COLUMN. GIVES JOB DONE						
310	99	99			* MESSAGE AND HALTS						
311	7	05	PDIA	MLCWA	106, 103	7		1224	L 106	103	35
312	7	03		MLCWA	*01*, 103	7		1231	L X64	108	35
313	7	10		P		1		1233	4		35
314	7	11		B	STEPR, SW1, 1	3		1239	J 254	X16 L	35
315	7	12		S	*1, COLNO	7		1247	S X21	W92	35
316	7	13		B	COLSET, S44, 0	3		1254	B V39	X49 0	35
317	7	131		CS	332	4		1262	/	332	36
318	7	132		CS		1		1266	/		36
319	7	133		MLC	*JOB DONE*, 208	7		1267	M X72	208	36
320	7	134		W		1		1274	Z		36
321	7	135		H	*-4	4		1275	.	S74	36
322	99	99			* ERROR ROUTINE FOR SEQUENCE CHECK						
323	7	14	MIXED	CS	332	4		1279	/	332	36
324	7	15		CS		1		1283	/		36
325	7	15		MLC	*SEQUENCE-NEXT IS FIX AND RESTART*, 237	7		1284	M Y09	237	37
326	7	161		MLZS	*0*, 500	7		1291	Y X23	X05	37
327	7	17		MLC	SEQ, 221	7		1298	M X05	221	37
328	7	171		MLZS	*1, 500	7		1305	Y X21	X05	37
329	7	18		W		1		1312	Z		37
330	7	19		H	READ	4		1313	.	333	37
331	99	99			* ON COLUMN CONTROL BREAK, FINDS FIRST COLUMN						
332	6	01	CLUSE	B	EARLY, SW1, 1	6		1317	B 201	X16 L	38
333	6	02		MLC	CELLS*6, TOP*3	7		1325	M V80	Y12	38
334	6	03		MLC	HIGH, BOTTOM*3	7		1332	M W89	Y15	38
335	6	04		MLC	COLNO, 106	7		1339	M W92	106	38
336	6	041		MLZS	*0*, 106	7		1346	Y X23	106	38
337	6	05		MLC	DIMEN, 8 DIMEN*3	7		1353	M X08	Y18	39
338	6	05		MLCWA	*00*, 00*	7		1360	L X39	W95	39
339	99	99			* ELIMINATES ZERO CELLS FROM DIAGONAL						
340	6	061	HERE	MLC	TOP, **7	7		1367	M Y12	180	39
341	6	062		B	REMOVE, 0, 7	3		1374	B W40	000	39
342	6	07		MLC	TOP, **7	7		1382	M Y12	/95	39
343	6	08		C	*00, 0	7		1389	C X36	000	40
344	6	09		BU	PUNCH	3		1396	J 019	/	40
345	6	10		MA	*002*, TOP	7		1401	= Y21	Y12	40
346	6	11		C	*1, GAP	7		1408	4 X21	W95	40
347	6	12		C	HERE	4		1415	4 167		40

Table 31. Program 3←Compute Contained in Analysis Matrix (Continued)

SFC	LG	LIN	LABEL	OP	OPERANDS	SFX	CT	ADDR	INSTRUCTION	TYPE	CARD
343	99	99	*		PUNCH ROUTINE, EXCEPT DIAGONAL. ZERO CELLS NOT PUNCHED						
344	99	99	*		STEP CHANGES ADDRESSES						
350	8	13	PUNCH	MA	TWON, TOP	7		1419	= X11 Y12		40
351	8	131		C	TOP, BOTTOM	7		1426	C Y12 Y15		41
352	8	132		BE	SETDIG	5		1433	B /82 S		41
353	8	133		MLC	BOTTOM, **7	7		1438	M Y15 U51		41
354	8	134		B	TAKOUT, 0, =	8		1445	R W58 000 =		41
355	8	14		MLC	BOTTOM, **7	7		1453	M Y15 U66		41
356	8	15		C	+00, 0	7		1460	C X56 000		42
357	8	16		Be	STEP	5		1467	C V09 S		42
358	8	17		MLCWA	ROWNO, 103	7		1472	L Y18 103		42
359	8	171		MLZS	103, 103	7		1479	Y X23 103		42
360	8	18		MLC	BOTTOM, **4	7		1486	M Y15 U96		42
361	8	19		MLCWA	0, 108	7		1493	L C00 108		43
362	8	191		BWZ	SWEEP, 108, B	8		1500	V W76 108 B		43
363	8	20		P		1		1508	4		43
364	8	21	STEP	MA	TWON, BOTTOM	7		1509	= X11 Y15		43
365	8	22		C	TOP, BOTTOM	7		1516	C Y12 Y15		43
366	8	23		BE	SETDIG	5		1523	B /82 S		43
367	8	24		S	+1, ROWNO	7		1528	S X21 Y18		44
368	8	25		B	PUNCH+7	4		1535	C U26		44
369	99	99	*		FINDS NUMBER OF CELLS IN NEXT COLUMN TO BE COMPUTED. CELLS						
370	99	99	*		SETS EACH CELL TO ZERO, ALSO TESTS TO KEEP FROM STORING 100						
371	99	99	*		LARGE A MATRIX.						
372	9	01	CULSET	MLC	DIMEN, COLFN=3	7		1539	M X08 Y24		44
373	9	02		S	CULNO, CULLN	7		1546	S W92 Y24		44
374	9	03		MLC	+000, CTRL=3	7		1553	M X39 Y27		44
375	9	04		MA	SIX3, HIGH	7		1560	= X01 W89		44
376	9	05		MLC	HIGH, CELLS+6	7		1567	M W89 V80		45
377	9	06	CELLS	MLCWA	+00, 5	7		1574	L X56 000		45
378	9	07		A	+1, CTRL	7		1581	A X21 Y27		45
379	9	08		C	CTRL, COLFN	7		1588	C Y27 Y24		45
380	9	09		BE	CARD	5		1595	B 367 S		45
381	9	10		MA	TWON, CELLS+6	7		1600	= X11 V80		46
382	9	11		C	**99*, 1150	7		1607	C X20 Y50		46
383	9	12		BU	OVERFLOW	5		1614	B W23 /		46
384	9	13		B	CELLS	4		1619	B V74		46
385	99	99	*		ERROR ROUTINE IF MEMORY CAPACITY IS EXCEEDED						
386	9	15	OVERFLOW	CS	332	4		1623	/ 332		46
387	9	16		CS		1		1627	/		46
388	9	17		MLC	*MEMORY FULL*, 211	7		1628	M Y38 211		46
389	9	18		W		1		1635	2		47
390	9	19		H	**4	4		1636	= W35		47
391	99	99	*		REMOVE AND TAKOUT CHANGE --SYMBOL TO ZERO AFTER COLUMN IS						
392	99	99	*		COMPUTED						
393	9	20		MLC	TOP, **7	7		1640	M Y12 W53		47
394	9	21		MLCWA	+00, 0	7		1647	L X56 000		47
395	9	22		B	VERT+15	4		1654	C T32		47
396	9	23	TAKOUT	MLC	BOTTOM, **7	7		1658	M Y15 W71		47
397	9	24		MLCWA	+00,	7		1665	L X56 000		47

Table 31: Program 3--Compute Contained in Analysis Matrix (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
398	9	25		B	STEP	4		1672	B V09		48
399	99	99	*		CLEAR PLUS SIGN FROM REGULAR CELL						
400	9	26	SWEEP	MLZS	'0',108	7		1676	Y X23 108		48
401	9	27		B	STEP-1	4		1683	B V08		48
402	99	99	*		CONSTANTS AND SYMBOLS						
403	10	01	HIGH	DSA	7999	3		1689	I72		48
404	10	02	COLNU	DCW	+000	3		1692			48
405	10	03	GAP	DCW	+000	3		1695			48
406	10	04	THREE	DSA	15997	3		1698	I90		48
407	10	05	SIXN	DSA	15994	3		1701	I90		49
408	10	06	SEQ	DCW	+0000	4		1705			49
409	10	07	DIMEN	DCW	+000	3		1708			49
410	10	08	TWON	DSA	15998	3		1711	I90		49
411	10	10	SIX	DSA	006	3		1714	006		49
412	10	11	SLASH	DC	'/'	1		1715			49
413	10	12	SW1	DCW	'0'	1		1716			49
414	10	14	SW5	DC	'0'	1		1717			49
				DCW	'999'	3		1720		LIT	49
					+1	1		1721		LIT	50
					+0	1		1722		LIT	50
					'0'	1		1723		LIT	50
159		SEARCH		=03		3		1726		AREA	50
161		LOOK		=03		3		1729		AREA	50
164		BRL		=03		3		1732		AREA	50
				+2		1		1733		LIT	50
166		ARL		=03		3		1736		AREA	51
				+000		3		1739		LIT	51
178		NOML		=03		3		1742		AREA	51
187		TRACE		=03		3		1745		AREA	51
189		FOLLOW		=03		3		1748		AREA	51
197		SW4		=01		1		1749		AREA	51
				'000'		3		1752		LIT	51
204		CTR2		=02		2		1754		AREA	52
				+00		2		1756		LIT	52
235		CTR3		=03		3		1759		AREA	52
246		SW3		=01		1		1760		AREA	52
				'0='		2		1762		LIT	52
				'01'		2		1764		LIT	52
319				'JOB DONE'		8		1772		LIT	52
325				'SEQUENCE-NEXT SB	FIX AND RESTART'	37		1809		LIT	53
333		TOP		=03		3		1812		AREA	54
334		BOTTOM		=03		3		1815		AREA	54
337		ROWNO		=03		3		1818		AREA	54
				'002'		3		1821		LIT	54
372		COLEN		=03		3		1824		AREA	54
374		CTRL		=03		3		1827		AREA	54
388				'MEMORY FULL'		11		1836		LIT	54
415	12	17	END	SETUP					/ 101 080		55

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Table 32. Test Input--Program 2 and 3

TEST PROGRAM		
S1	W201018014	0001
D1	W201015014	0002
D3	W101017013	0003
D2	W101016013	0004
D1	W101015013	0005
S1	C10A018012	0006
D3	C10A017012	0007
S1	W30J018011	0008
W2	W301014011	0009
W1	W301013011	0010
C1	W30A012011	0011
D2	W401016008	0012
H2	W401010008	0013
H1	W401009008	0014
C1	C20A012007	0015
C2	C30A007006	0016
D3	R10J017005	0017
D1	R10J015005	0018
C1	R10J012005	0019
W3	R101011005	0020
C2	R10A007005	0021
C3	R10A006005	0022
C2	C40A007004	0023
C3	C50A006003	0024
W4	R201008002	0025
C2	R20J007002	0026
C3	R20J006002	0027
R1	R205005002	0028
C4	R20A004002	0029
C5	R20A003002	0030
W3	P101011001	0031

Table 34. Program 4—Print Solution Matrices

SEQ	PG	LIN	LABEL	UP	OPERANDS	SFX	CT	LOCK	INSTRUCTION	TYPE	CARD
101	1	01	000	JOB	PRINT SOLUTION MATRICES						
102	1	02		CTL	4401						
103	99	99	*		INPUT IS MASTER DECK FROM REINDEXING STEP. NEW INDICES ARE						
104	99	99	*		IN CC 1-3, ORIGINAL INDICES IN CC 4-13. SORT IS ON NEW INDEX						
105	99	99	*		NEXT IS TITLE CARD, TITLE IN CC 1-40, TYPE OF ANALYSIS IN						
106	99	99	*		CC 52-64.						
107	99	99	*		NEXT ARE OUTPUT CARDS FROM PROGRAM 1 OR 2, MAJOR SORT ON J-FIELD						
108	99	99	*		CC 4-6, MINOR ON I-FIELD CC 1-3. Q-FIELD IS CC 7-8						
109	1	03		URG	333				0333		
110	99	99	*		CLEAR PUNCH AREA, SETS CONSTANTS						
111	1	04	READY	CS	332	4		0333	/	332	4
112	1	05		CS		1		0337	/		4
113	1	06		CS		1		0338	/		4
114	1	061		MLZS	'0',BASIC-1	7		0339	Y	C41 C30	4
115	1	07		SW	1,4	7		0346	,	001 004	4
116	1	08		MLCWA	'000',IND1	7		0353	L	C44 089	4
117	99	99	*		READS AND STORES MASTER CARDS						
118	1	09	MREAD	R		1		0360	1		4
119	1	10		BWZ	SHIFT,79,2	8		0361	Y	394 079 2	5
120	1	11		MLCWA	3,NEW	7		0369	L	003 771	5
121	1	12		MLCWA	13,ULD	7		0376	L	013 701	5
122	1	13		MA	'013',IND1	7		0383	=	C47 089	5
123	1	14		B	MREAD	4		0390	0	360	5
124	99	99	*		PRINTS HEADINGS, SETS UP FOR DATA CARDS						
125	1	16	SHIFT	CW	4	4		0394	1	004	5
126	1	17		MLCWA	40,284	7		0398	L	040 284	6
127	1	18		W		1		0405	2		6
128	1	19		CC	L	2		0406	F	L	6
129	1	20		CC	L	2		0408	F	L	6
130	1	21		SW	51	4		0410	,	051	6
131	1	211		CS	299	4		0414	/	299	6
132	1	22		MLCWA	'ELEMENT',215	7		0418	L	C54 215	6
133	1	23		MLCWA	64,280	7		0425	L	064 280	7
134	1	24		W		1		0432	2		7
135	1	25		CC	L	2		0433	F	L	7
136	2	01		CS	80	4		0435	/	080	7
137	2	011		CS	299	4		0439	/	299	7
138	2	02		SW	1,4	7		0443	,	001 004	7
139	2	03		SW	7	4		0450	,	007	7
140	2	04		MLCWA	'000',IND2	7		0454	L	C44 094	8
141	2	05		MLCWA	'000',IND1	7		0461	L	C44 089	8
142	99	99	*		READS DATA CARDS, CHECKS FOR LAST CARD, CHECKS FOR COLUMN						
143	99	99	*		CONTROL BREAK, CHECK FOR FULL PRINT LINE						
144	2	11	MREAD	R		1		0468	1		8
145	2	12		BLC	FINAL	5		0469	B	707 A	8
146	2	13		C	6,3	7		0474	C	006 003	8
147	2	14		BE	CLOSE	5		0481	B	622 S	8

Table 34. Program 4—Print Solution Matrices (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LUCN	INSTRUCTION	TYPE	CARD
148	2	15		BCE	PRINT,CTR1,H	8		0486	D 598 C62 H		9
149	99	99	* FINDS ORIGINAL ROW INDICES CORRESPONDING TO NFK INDICES, PLACLS								
150	99	99	* IN PRINT AREA. ALSO QUANTITY TO PRINT AREA. ASSEMBLES SEVEN								
151	99	99	* CELLS DATA, THEN BRANCHES TO PRINT								
152	2	16	SEEK	MLC	BASIC,WHERE=3	7		0494	M C31 C57		9
153	2	17		ZA	3,PROD-3	7		0501	+ 003 C34		9
154	2	18		M	+13,PROD	7		0508	* C59 C37		9
155	2	19		SW	PROD-2	4		0515	, C35		9
156	2	191		S	+1,PROD	7		0519	S C60 C37		10
157	2	192		MLZS	*0*,PROD	7		0526	Y C41 C37		10
158	2	20		MA	PROD,WHERE	7		0533	= C37 C57		10
159	2	201		CW	PROD-2	4		0540) C35		10
160	2	22		MLC	WHERE,++4	7		0544	M C57 554		10
161	2	23		MLC	0,ROWIND+X2	7		0551	M 000 2K5		10
162	2	24		MLCWA	EDIT2,QUANT+X2	7		0558	L C39 2K9		11
163	2	25		MCE	8,QUANT+X2	7		0565	E 008 2K9		11
164	2	251		BWZ	STAR,8,S	8		0572	V 713 008 S		11
165	3	01	ENTRA	A	+1,CTR1=2	7		0580	A C60 C62		11
166	3	02		MA	*017*,IND2	7		0587	= C65 094		11
167	3	03		B	DREAD	4		0594	B 468		12
168	99	99	* PRINTS SEVEN CELL VALUES, THEN RESETS FOR NEXT PRINT LINE								
169	3	07	PRINT	W		1		0598	2		12
170	3	08		CS	332	4		0599	/ 332		12
171	3	09		CS		1		0603	/		12
172	3	12		MLCWA	*000*,IND2	7		0604	L C44 094		12
173	3	13		ZA	+1,CTR1	7		0611	+ C60 C62		12
174	3	14		B	SEEK	4		0618	B 494		12
175	99	99	* RESETS FOR NEXT COLUMN								
176	3	16	CLOSE	C	*001*,6	7		0622	C C68 006		13
177	3	17		BE	ONLY	5		0629	B 649 S		13
178	3	18		W		1		0634	2		13
179	3	19		CS	332	4		0635	/ 332		13
180	3	20		CS		1		0639	/		13
181	3	21		MA	*013*,IND1	7		0640	= C47 089		13
182	3	22		CC	K	2		0647	F K		13
183	3	23	ONLY	MLC	*INPUT DATA*,ROWIND+X0	7		0649	M C78 225		14
184	3	25		MLC	OLD,212	7		0656	M 701 212		14
185	3	26		MLCWA	*000*,IND2	7		0663	L C44 094		14
186	3	27		ZA	+1,CTR1	7		0670	+ C60 C62		14
187	3	28		BCE	DREAD,SW2,+	8		0677	B 468 C40 +		14
188	3	261		W	DONE	4		0685	Z 689		15
189	99	99	* END OF JOB ROUTINE								
190	4	01	DONE	CC	K	2		0689	F K		15
191	4	011		CS	299	4		0691	/ 299		15
192	4	02		MLCWA	*JOB DONE*,212	7		0695	L C86 212		15
193	4	03		W		1		0702	2		15
194	4	04		H	*-4	4		0703	- 702		15
195	99	99	* SELTS SWITCH ON LAST CARD								
196	4	07	FINAL	MLNS	+1,SW2	7		0707	D C60 C40		15
197	4	08		B	DREAD+6	4		0714	B 474		16

Table 34. Program 4--Print Solution Matrices (Continued)

SEQ	PG	LIN	LABEL	OP	OPERANDS	SFX	CT	LOCN	INSTRUCTION	TYPE	CARD
178	99	99	* SETS SYMBOL * TO IDENTIFY CONCOMITANT CELL								
199	4	10	STAR	MLC	'*',230+X2	7		0716	M C87 2L0		16
200	4	11		B	ENTRA	4		0725	B 580		16
201	99	99	* SYMBOLS AND CONSTANTS								
202	5	01	DICTRY	DA	200X13,X1			0729	3328		49
203	5	02	GLD		4,13			0741		FIELD	49
204	5	03	NEW		1,3			0731		FIELD	83
205	5	04	IND1	EQU	89			0089			
206	5	06	BASIC	DCW	+DICTRY	3		3331	7S9		116
207	5	07	PROD	DCW	=6	6		3337			116
208	5	08	QUANT	EQU	229			0229			
209	5	09	RUNIT	EQU	225			0225			
210	5	10	IND2	EQU	94			0094			
211	5	11	CU112	DCW	' 0'	2		3339			116
212	5	12	SW2	DCW	+0	1		3340			116
				DCW	'0'	1		3341		LIT	116
					'000'	3		3344		LIT	117
					'013'	3		3347		LIT	117
	132				'ELEMENT'	7		3354		LIT	117
	152	WHERE			=03	3		3357		AREA	117
					+13	2		3359		LIT	117
					+1	1		3360		LIT	117
	165	CIR1			=02	2		3362		AREA	117
					'017'	3		3365		LIT	118
					'001'	3		3368		LIT	118
	133				'INPUT DATA'	10		3378		LIT	118
	192				'JOB DONE'	8		3386		LIT	118
					'*'	1		3387		LIT	118
213	5	13	END	READY					7 333 080		119

Table 35. Test Input—Program 4—Composed of Analysis

TEST INPUT - PROGRAM 4 - COMPOSED OF ANALYSIS.

NAME OF OF MASTER CARDS USED FOR REINDEXING AND OUTPUT CARDS FROM PROGRAM 2.

001	P1	-
002	R2	-
003	C5	-
004	L4	-
005	R1	-
006	C3	-
007	C2	-
008	W4	-
009	H1	-
010	H2	-
011	W3	-
012	C1	-
013	W1	-
014	W2	-
015	D1	-
016	D2	-
017	D3	-
018	S1	-
S* MATRIX - COMPOSED OF ANALYSIS		IS COMPOSED OF
00100101		
01100101		
01200107		
01300101		
01400101		
01500102		
01600101		
01700101		
01800101		
00200201		
00300207		
00400207		
00500205		
0060020V		
0070020V		
00800201		
00900201		
01000201		
01100205		
0120020V		
01300205		
01400205		
01500210		
01600206		
01700205		
01800205		
00300301		
00600307		
00400401		
00700407		
00500501		
00600507		
00700507		
01100501		
01200507		
01300501		
01400501		

Table 35. Test Input—Program 4—Composed of Analysis (Continued)

01500502
01600501
01700501
01800501
00600601
0070060/
00700701
0120070/
00800801
00900801
01000801
01600801
00900901
01001001
01101101
0120110/
01301101
01401101
01501102
01601101
01701101
01801101
01201201
0170120/
0180120/
01301301
01501301
01601301
01701301
01401401
01501401
01801401
01501501
01601601
01701701
01801801

Table 36. Test Output—Program 4—Composed of Analysis

(* Denotes Concomitant Cell Value)

ELEMENT	IS COMPOSED OF													
P1	W3 S1	1 1	C1	1*	W1	1	W2	1	D1	2	D2	1	D3	1
R2	C5 H2 D3	1* 1 5	C4 W3 S1	1* 5 5	R1 C1	5 5*	C3 W1	5* 5	C2 W2	5* 5	W4 D1	1 10	H1 D2	1 6
C5	C3	1*												
C4	C2	1*												
R1	C3 D2	1* 1	C2 D3	1* 1	W3 S1	1 1	C1	1*	W1	1	W2	1	D1	2
C3	C2	1*												
C2	C1	1*												
W4	H1	1	H2	1	D2	1								
H1	INPUT DATA													
H2	INPUT DATA													
W3	C1	1*	W1	1	W2	1	D1	2	D2	1	D3	1	S1	1
C1	D3	1*	S1	1*										
W1	D1	1	D2	1	D3	1								
W2	D1	1	S1	1										
D1	INPUT DATA													
D2	INPUT DATA													
D3	INPUT DATA													
S1	INPUT DATA													

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Table 37. Test Input—Program 4—Contained in Analysis

TEST DECK - PROGRAM 4 - CONTAINED IN ANALYSIS

MADE UP OF MASTER CARDS USED FOR REINDEXING AND OUTPUT CARDS FROM PROGRAM 3.

001	P1	-
002	R2	-
003	C3	-
004	C4	-
005	R1	-
006	C3	-
007	C2	-
008	W4	-
009	H1	-
010	H2	-
011	W3	-
012	C1	-
013	W1	-
014	W2	-
015	D1	-
016	D2	-
017	D3	-
018	S1	-

S-PRIME - MATRIX - CONTAINED IN ANALYSIS

CONTAINS

00100101		
01200107		
01500102		
01600101		
01700101		
00200201		
00300207		
00400207		
00900201		
01000201		
01600208		
00300301		
00600307		
00400401		
00700407		
00500501		
00600507		
00700507		
01600501		
00600501		
00700607		
00700701		
01200707		
00800801		
00900801		
01000801		
01600801		
00900901		
01001001		
01101101		
01201107		
01501102		
01601101		
01701101		
01201201		
01701207		
01801207		

Table 37. Test Input—Program 4—Contained in Analysis (Continued)

01301301
01501301
01601301
01701301
01401401
01501401
01801401
01501501
01601601
01701701
01801801

Table 38. Test Output—Program 4—Contained in Analysis

(* Denotes Concomitant Cell Value)

ELEMENT		CONTAINS					
P1	C1 1*	D1 2	D2 1	D3 1			
R2	C5 1*	C4 1*	H1 1	H2 1	D2 6		
C5	C3 1*						
C4	C2 1*						
R1	C3 1*	C2 1*	D2 1				
C3	C2 1*						
C2	C1 1*						
H4	H1 1	H2 1	D2 1				
H1	INPUT DATA						
H2	INPUT DATA						
W3	C1 1*	D1 2	D2 1	D3 1			
C1	D3 1*	S1 1*					
W1	D1 1	D2 1	D3 1				
W2	D1 1	S1 1					
D1	INPUT DATA						
D2	INPUT DATA						
D3	INPUT DATA						
S1	INPUT DATA						

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VITA

George H. Brooks was born in Hamden, Connecticut, on April 9, 1919, the son of Frank W. and Nellie O. (née Marquet) Brooks. He attended public school in Adams Basin and Spencerport, New York, graduating from Spencerport High School in June, 1936.

From his graduation until May, 1940, the author worked as a mechanic in the Allen-Wales Adding Machine Corporation, Ithaca, New York, and for a year, until June, 1941, as an Assistant Section Chief in the Census Bureau, Washington, D. C.

In June, 1941, the author entered the United States Army as a Private. He was discharged from the Army as a Technical Sergeant in September, 1943, to accept a commission as Second Lieutenant. He served in the South Pacific area, and was returned to the United States in January, 1946 and released from active duty as Captain. He subsequently served two three-month tours of duty as Captain, Chemical Corps, in 1947 and 1950.

In December, 1942, while in the military service, he was married to Hope Lewis. In September, 1946, he entered the University of Florida to pursue a program of study in Industrial Engineering. In January, 1947, a daughter, Marcia Hope, was born. He was graduated from the University of Florida in January, 1950, with the degree Bachelor of Industrial Engineering, with honors. He was elected to Phi Eta Sigma, freshman scholastic honorary, Sigma Tau, engineering honorary, and Phi Kappa Phi, scholastic honorary societies.

In June, 1950, the author entered the Georgia Institute of Technology where he undertook a program of study in Industrial Engineering, which he completed in June, 1951, and was awarded the degree Master of Science in Industrial Engineering. During the course of his studies he was also employed as part-time instructor in the School of Industrial Engineering.

In June, 1951, the author was employed by the Engineering Service Division, Engineering Department, E. I. duPont de Nemours and Co., Inc., Wilmington, Delaware. During the first three years of this employment he was assigned to the Spruance Cellophane plant, Richmond, Virginia, where he was the Chief Standards Engineer. In January, 1952, a son, Ralph Marquet, was born. In 1954 the author returned to Wilmington where he became a consultant and consultant supervisor in the Engineering Service Division. His experience for several years was in connection with the development of information and management control systems for several duPont operating departments.

In September, 1959, he accepted a position as Assistant Professor of Industrial Engineering at Purdue University. He was promoted to the rank of Associate Professor in September, 1961. He also did extensive consultation for the International Business Machines Corporation and the Community Hospital, Indianapolis, Indiana.

In 1963 the author was granted a National Science Foundation Science Faculty Fellowship, and re-entered the Georgia Institute of Technology to pursue a Ph.D. program in the School of Industrial Engineering. At the expiration of his fellowship, he accepted a position as Professor of Industrial and Systems Engineering at the University

of Florida, where he is now employed.

The following publications resulted from the author's research and consulting activities while at Purdue:

"A New Technique for Prediction of Future Hospital Bed Needs," *Hospital Management*, Vol. 97, No. 6, June, 1964. (with H. L. Beenhakker)

"Predicting Hospital Bed Needs," *International Nursing Review*, (London), Vol. 11, No. 3, June, 1964. (with H. L. Beenhakker and W. C. McLin)

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