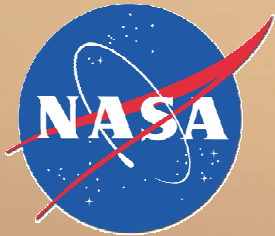


The Phoenix Mars Landing

An Initial Look



Presented by M. R. Grover¹

E. S. Bailey¹, J. P. Chase¹, B. D. Cichy¹, P. N. Desai², D. B. Eldred¹, P. E. Laufer¹, M. E. Lisano¹, J. L. Prince², E. M. Queen² and E. D. Skulsky¹

¹Jet Propulsion Laboratory, California Institute of Technology

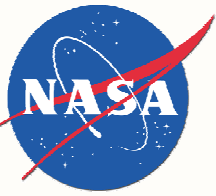
²NASA Langley Research Center

International Planetary Probe Workshop 6

25 June 2007

Atlanta, Georgia, USA

**National Aeronautics and Space Administration
Jet Propulsion Laboratory, California Institute of Technology**



Acknowledgements

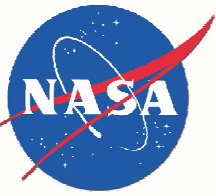


Special Acknowledgement: Lockheed Martin Phoenix Entry Descent & Landing Team

**T. D. Gasparrini
B. R. Haack
M. A. Johnson
T. M. Linn
T. A. Priser
J. A. St. Pierre**

And the entire Lockheed Martin Phoenix Team

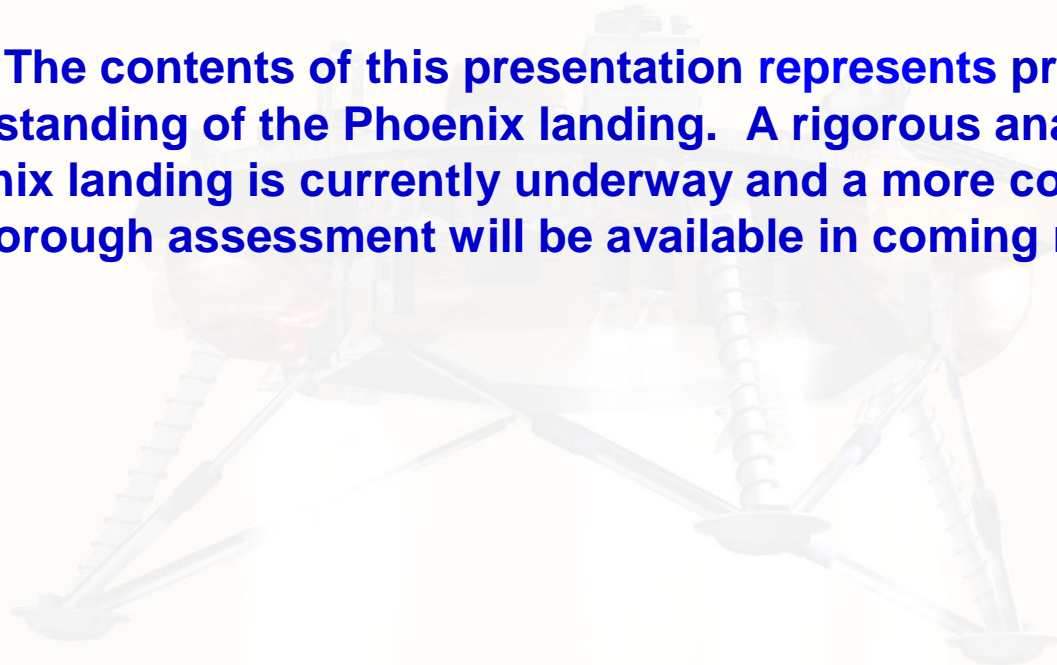


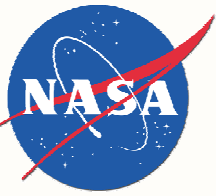


Landing Analysis Maturity



The contents of this presentation represents present understanding of the Phoenix landing. A rigorous analysis of the Phoenix landing is currently underway and a more complete and thorough assessment will be available in coming months.



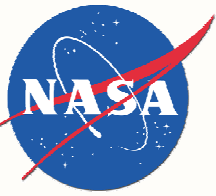


The Phoenix Story

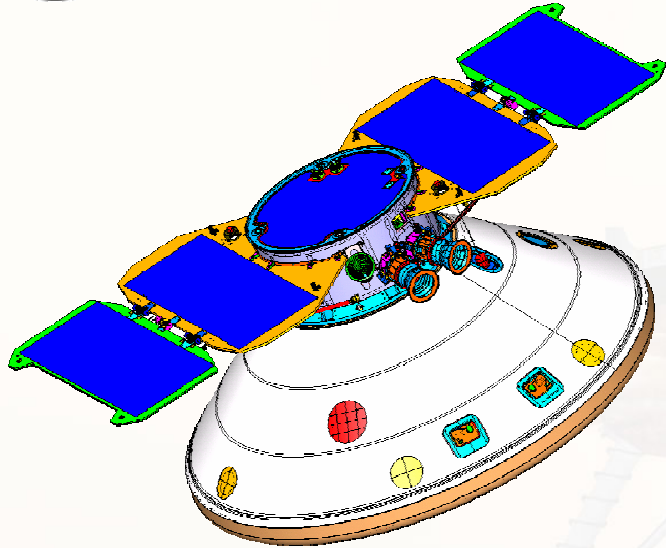


- **Started as Mars Surveyor 2001 Lander**
 - Faster, better, cheaper spacecraft
 - Sister spacecraft of Mars Polar Lander
 - Cancelled after Mars Polar Lander failure in 1999
 - Not enough time to address findings of MPL failure review prior to 2001 launch window
- **Reborn as Phoenix in 2003**
 - Same spacecraft, modified science payloads
 - Enhanced radar
 - Addition of EDL communication system
 - Enhanced test program
 - Launched Aug 4th, 2007

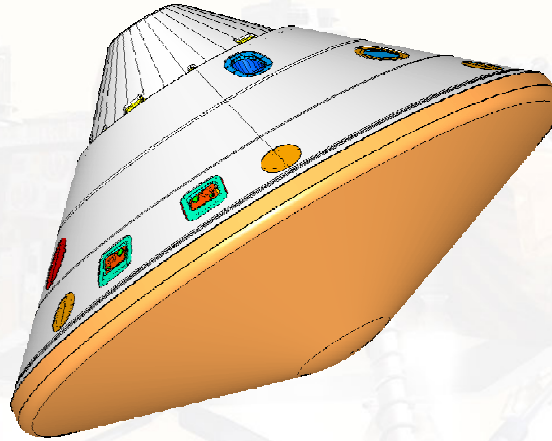




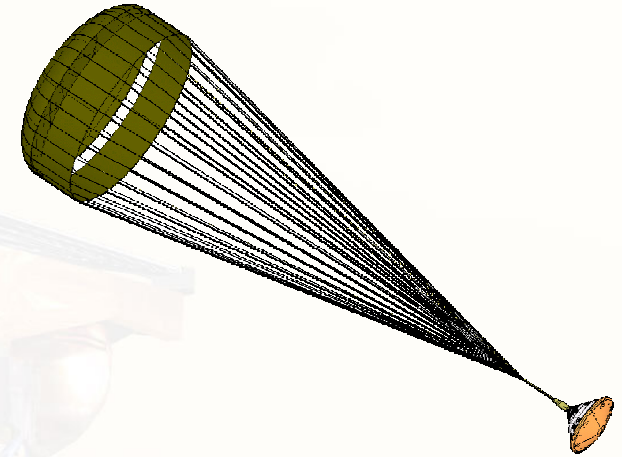
Spacecraft Overview



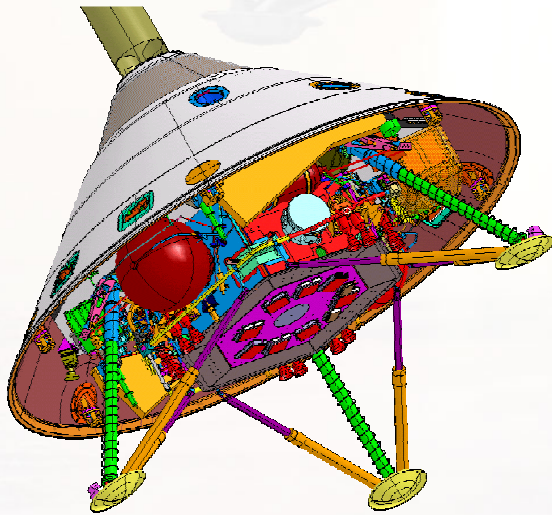
Pre-Entry Configuration



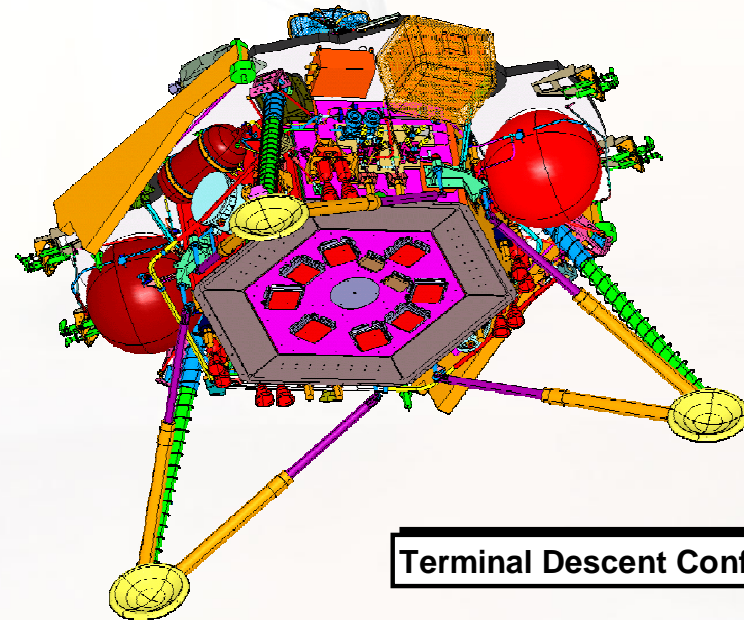
Entry Configuration



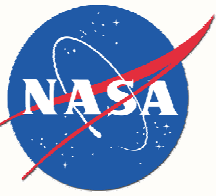
Parachute Configuration



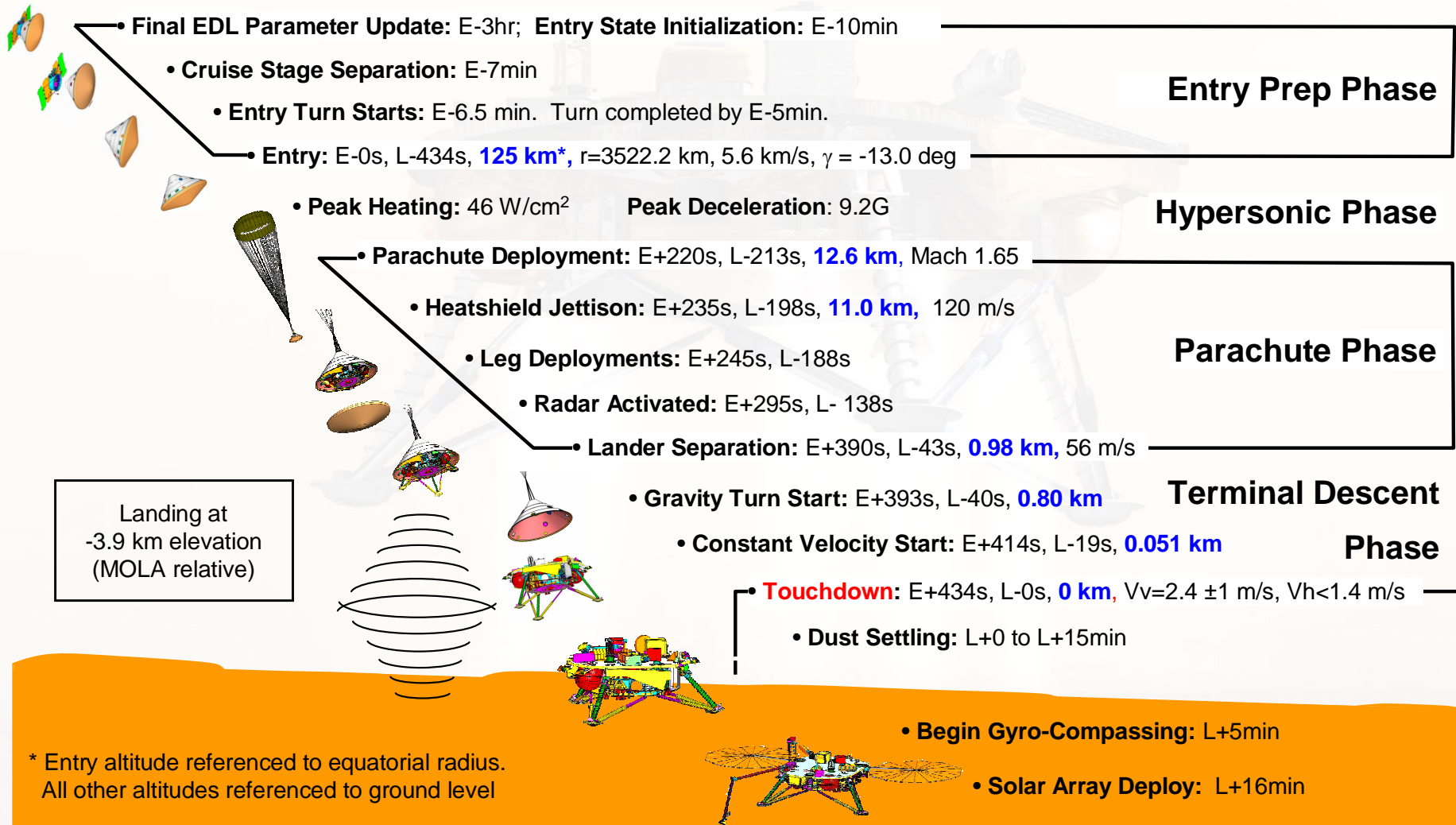
Post HS & Leg Deploy Configuration



Terminal Descent Configuration



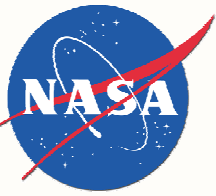
EDL Nominal Design



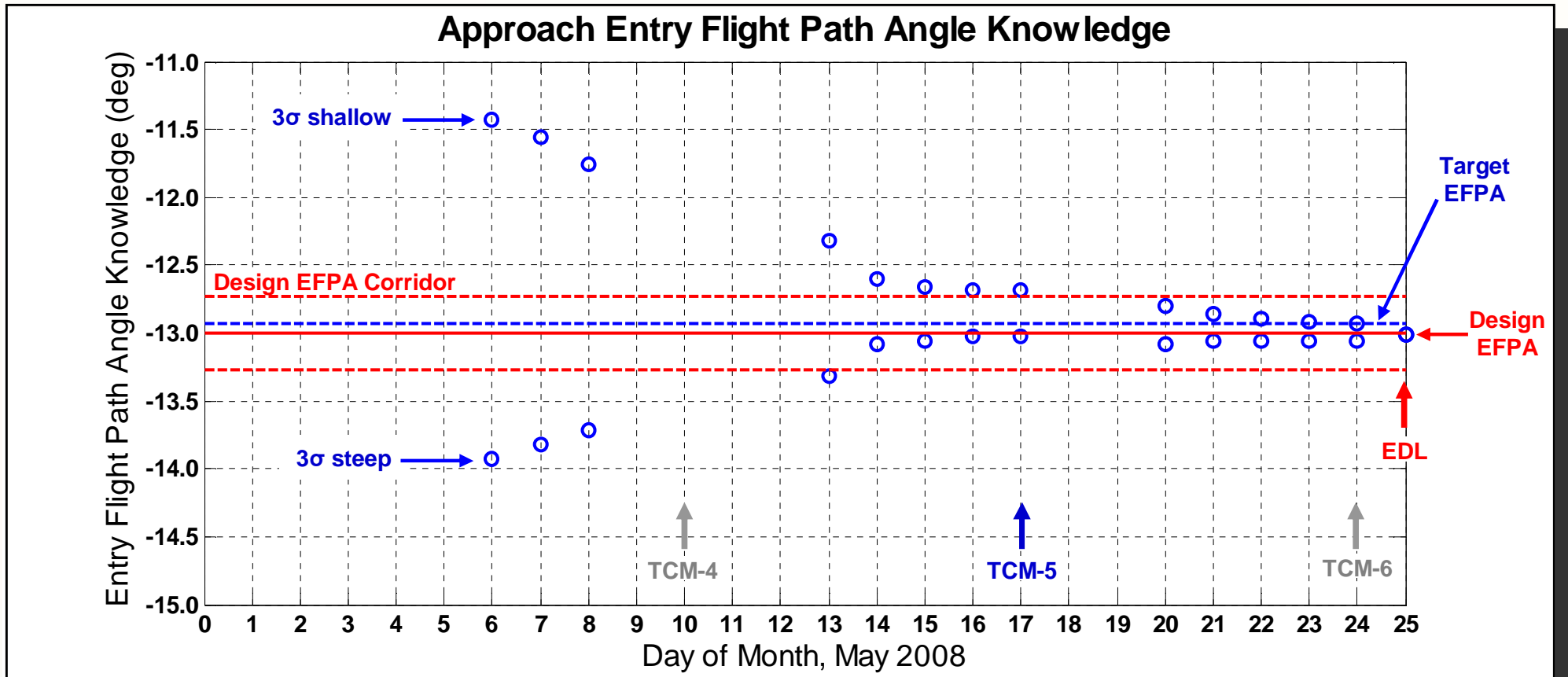
* Entry altitude referenced to equatorial radius.
All other altitudes referenced to ground level

Note: Information in this graphic represents a nominal entry (c726-102). Dispersions exist around all values.

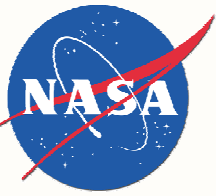
Feb 2008



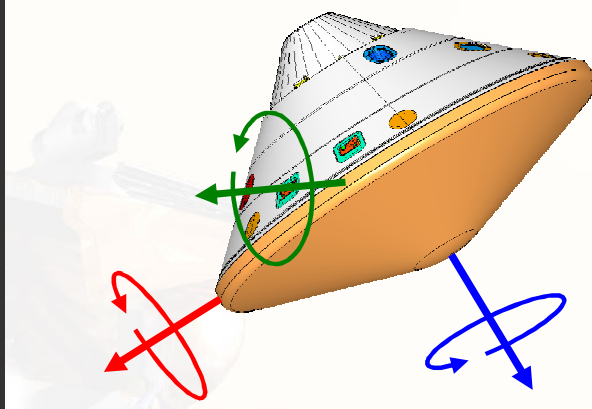
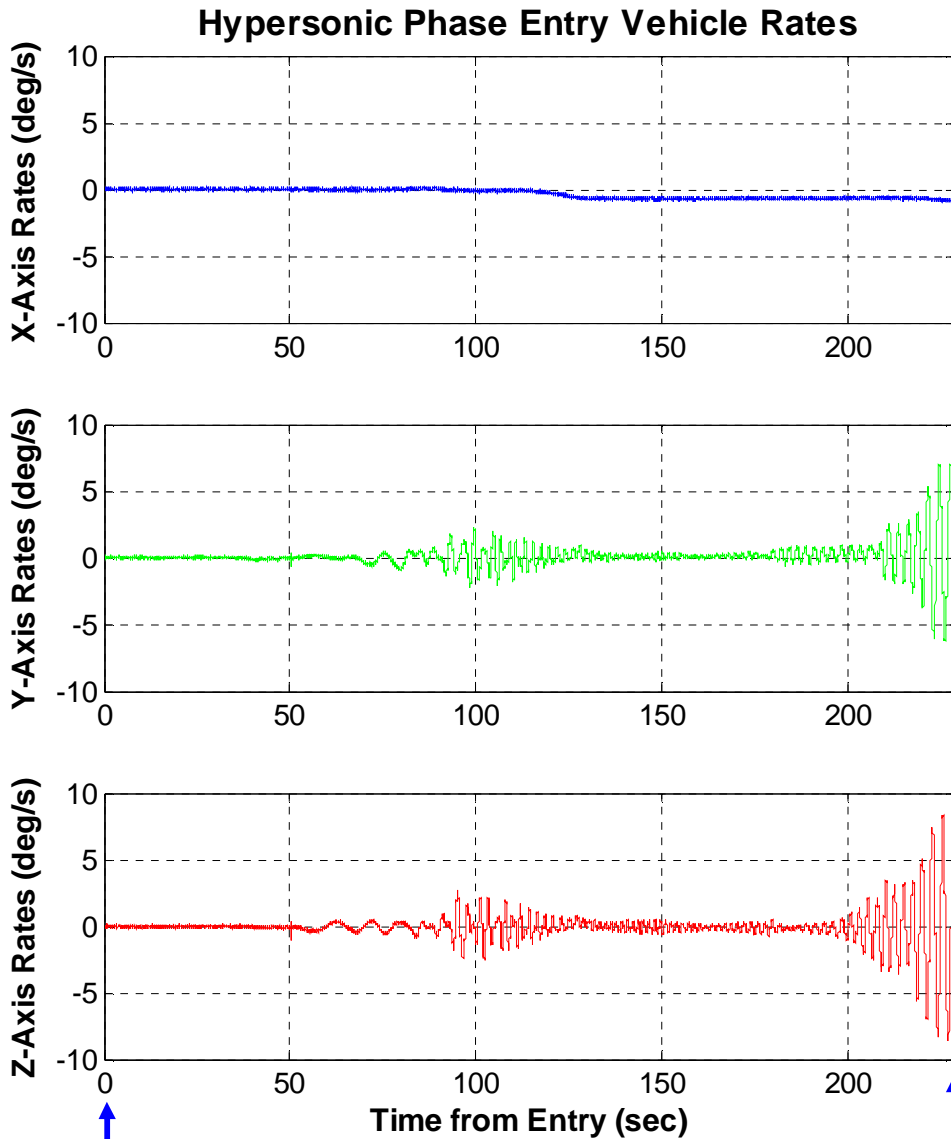
Final Approach EFPA Knowledge



- TCM-4 cancelled: If executed TCM-5 too small
- TCM-6 cancelled: Landing safety criteria all within desired limits
- Navigated final pre-entry EFPA determination: $-13.007^\circ \pm 0.003^\circ$



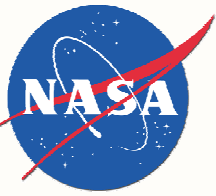
Hypersonic Phase



- Rates during hypersonic and supersonic flight are within expected values
- Angle of attack reconstruction underway at LaRC

Parachute
Deployment

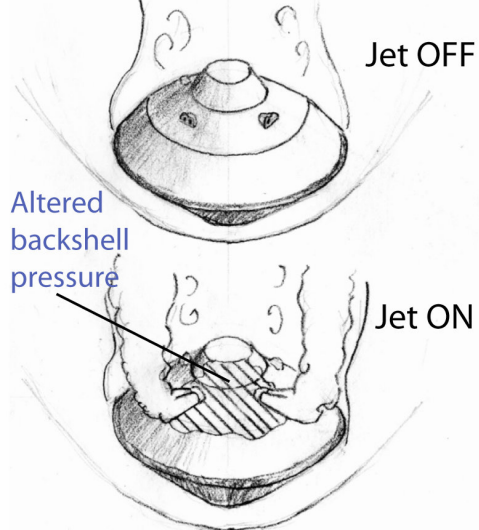
Entry
Interface



Aero/RCS Interaction Issue

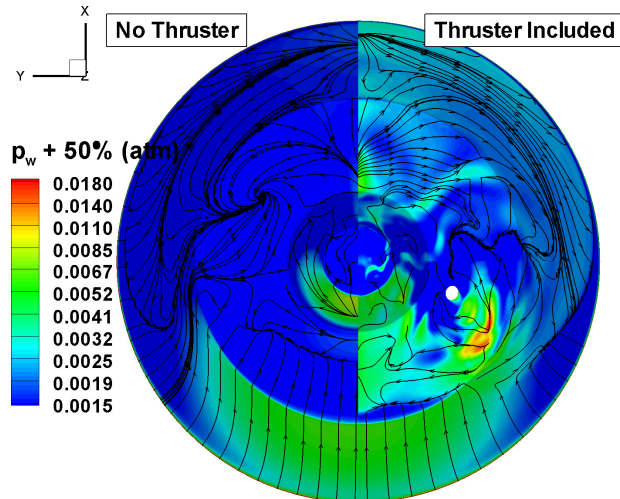


JET INTERACTIONS

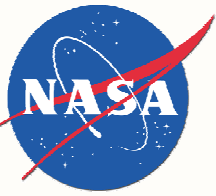


Jets can alter pressure on backshell, resulting in different control moments than intended

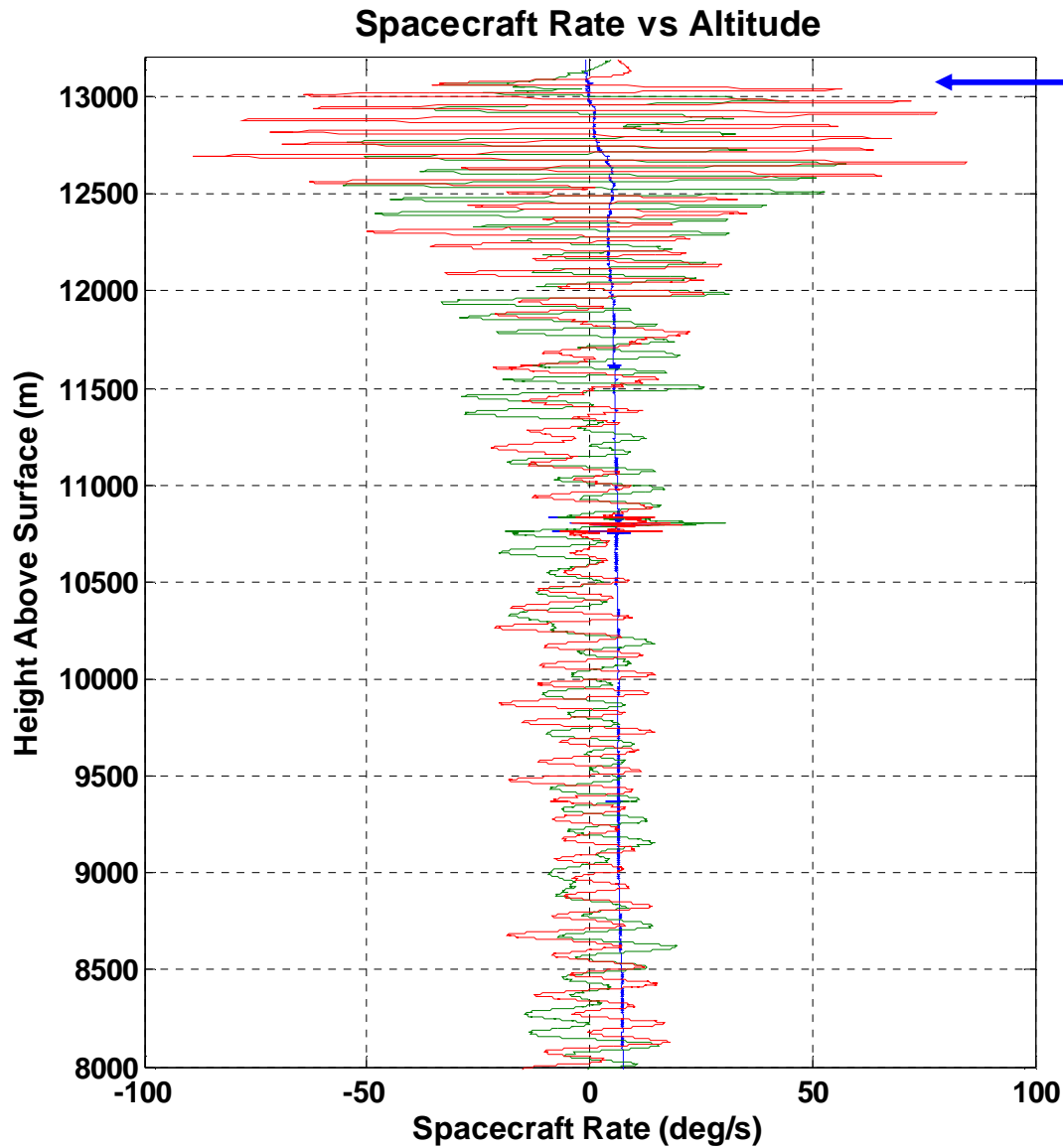
- CFD solutions of Aero/RCS flow field shows potential for strong interaction
 - RCS Pitch authority is degraded and Yaw authority is low to non-existent (potential for control reversal exists)
 - Potential of large attitude at parachute deployment leading to excessive wrist mode dynamics impacting radar performance



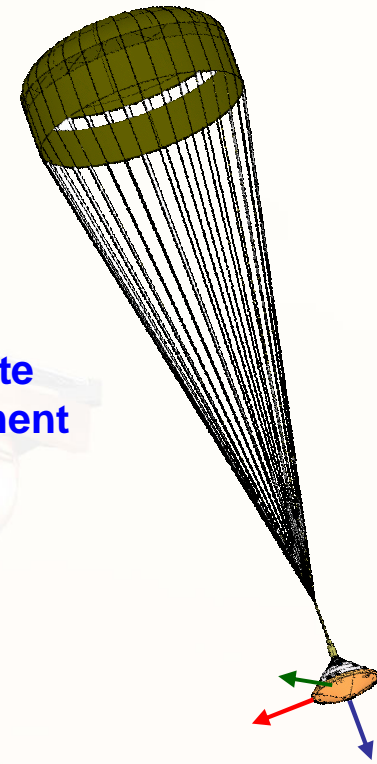
- Mitigation recommendation was to open up control system deadbands during entry from early-Hypersonic regime through Supersonic regime to minimize/eliminate RCS firings
 - Relying on inherent capsule stability to traverse flight regimes
 - **There were no RCS firings from Hypersonic 2 through Lander separation**



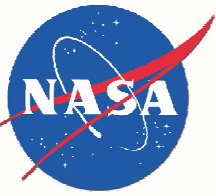
Parachute Phase



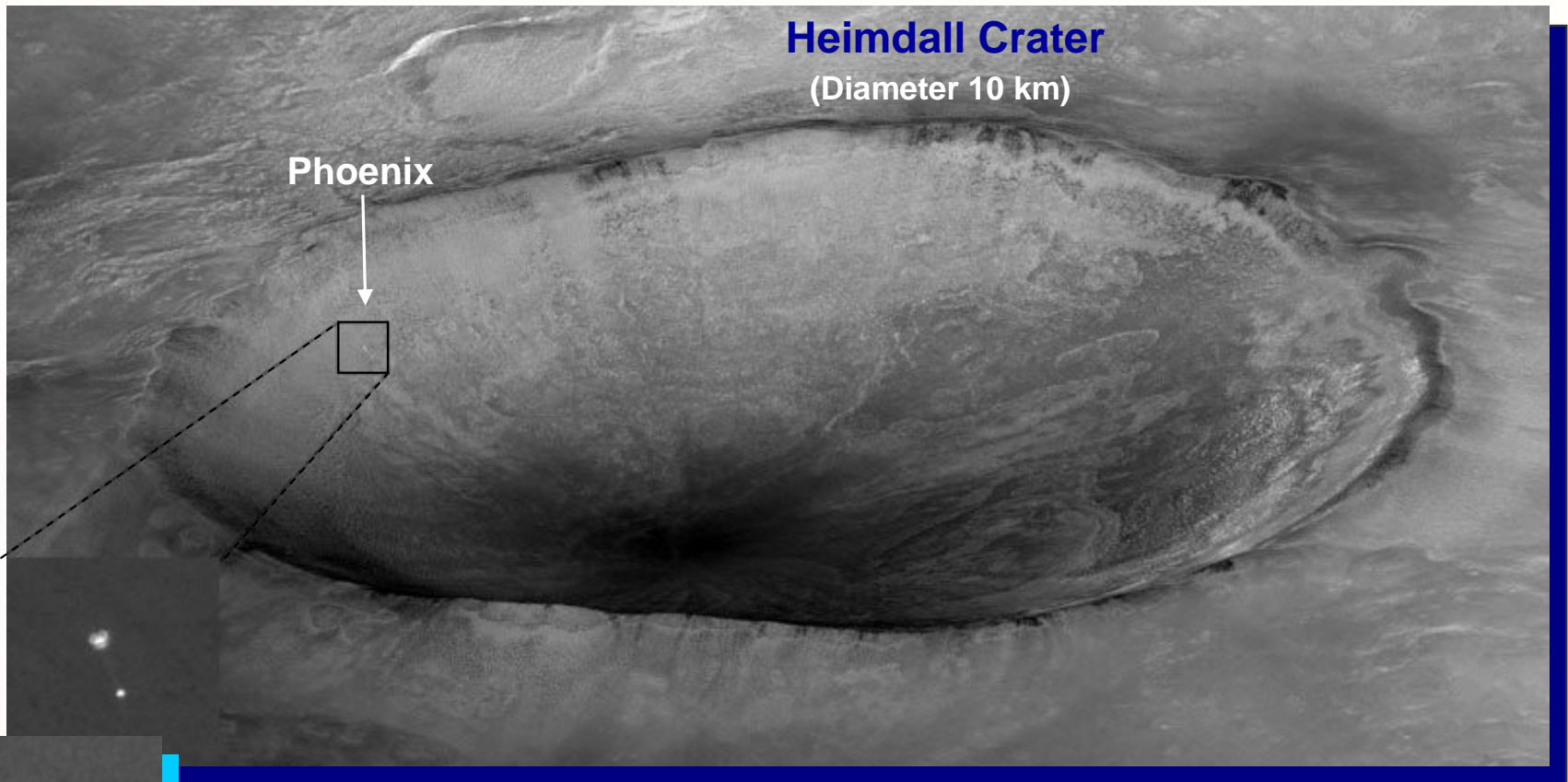
Parachute
Deployment



- Parachute deployment conditions:
 - Dyn. Press.: 492 Pa
 - Mach: 1.68
 - Altitude: 13.26 km
- As expected, “wrist mode” rates were high immediately after parachute deployment, but damped quickly



Phoenix on the Parachute - Spectacular!

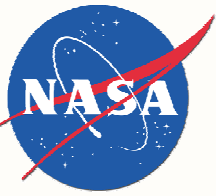


Heimdall Crater
(Diameter 10 km)

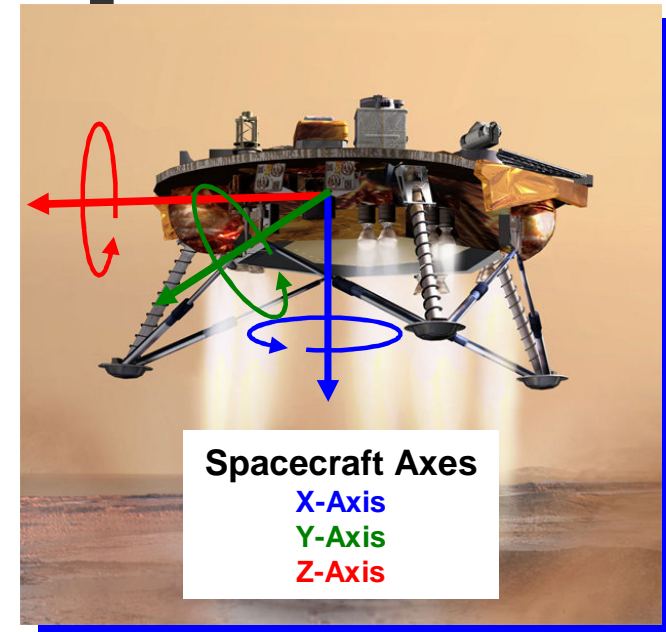
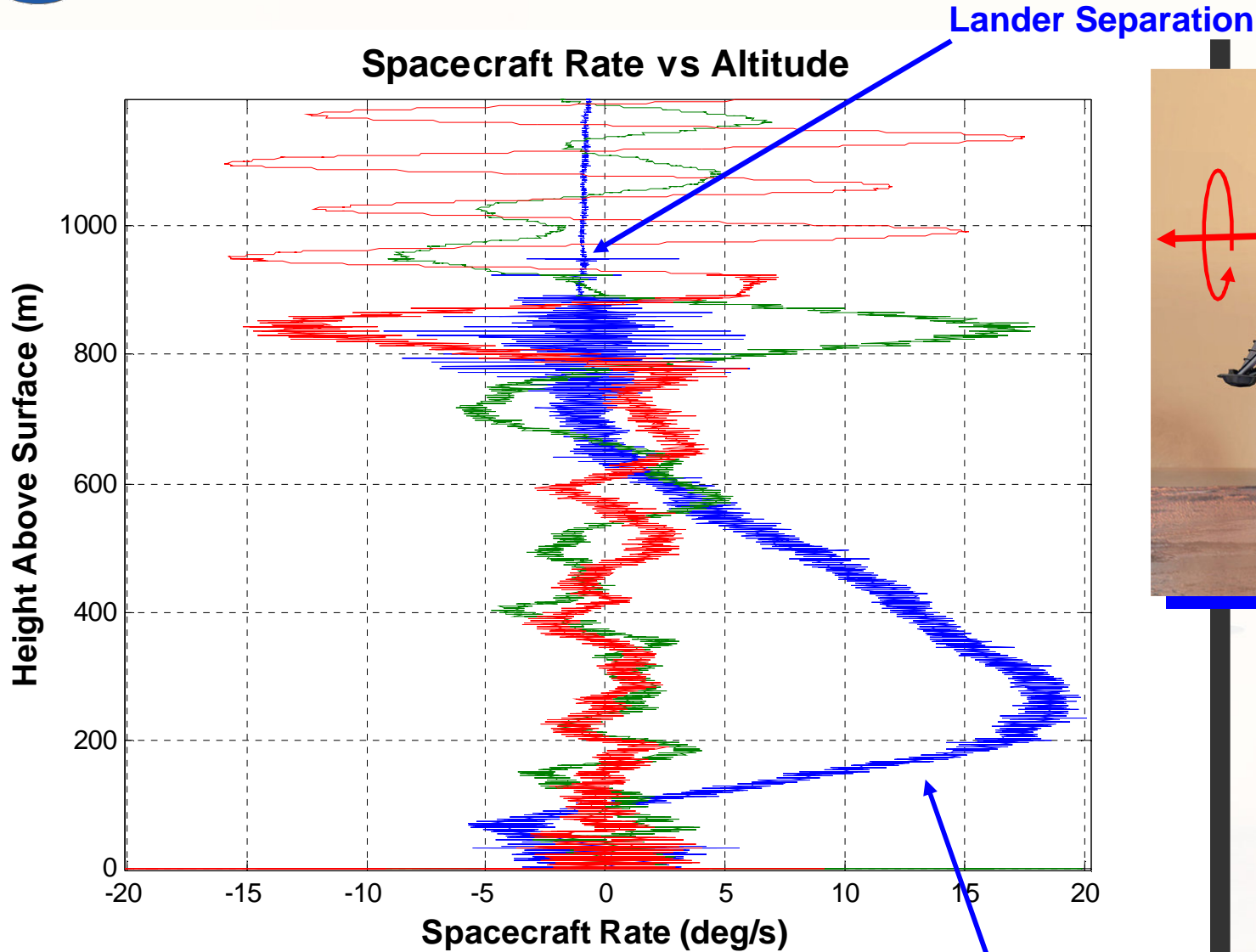
Phoenix

- Image captured from orbit by Mars Reconnaissance Orbiter HiRISE camera
- Image shows EDL system 47 seconds after parachute deployment approx. 9.2 km above surface
- Phoenix is 20 km in front of Heimdall Crater

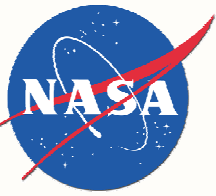




Terminal Descent Phase



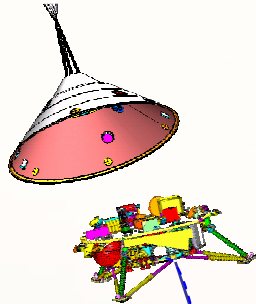
- Lander rates during terminal descent are very benign relative to worst-case simulation prior to landing



EDL Modifications: Terminal Descent Subphase Evolution



2004
Tip-Up and Gravity Turn



Small Magnitude Wind →

2005
Tip-Up and Gravity Turn
With BAM

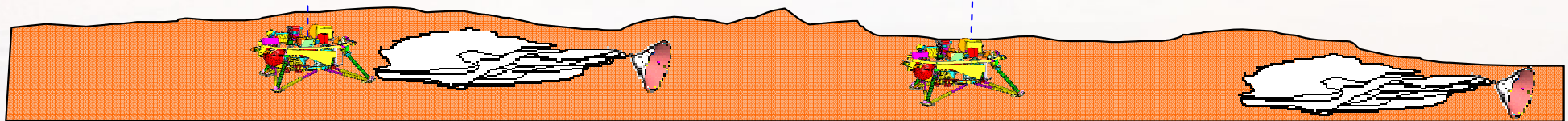


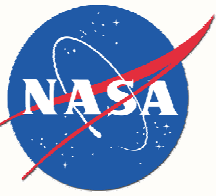
← Extra delta-v in upwind direction

BAM angle

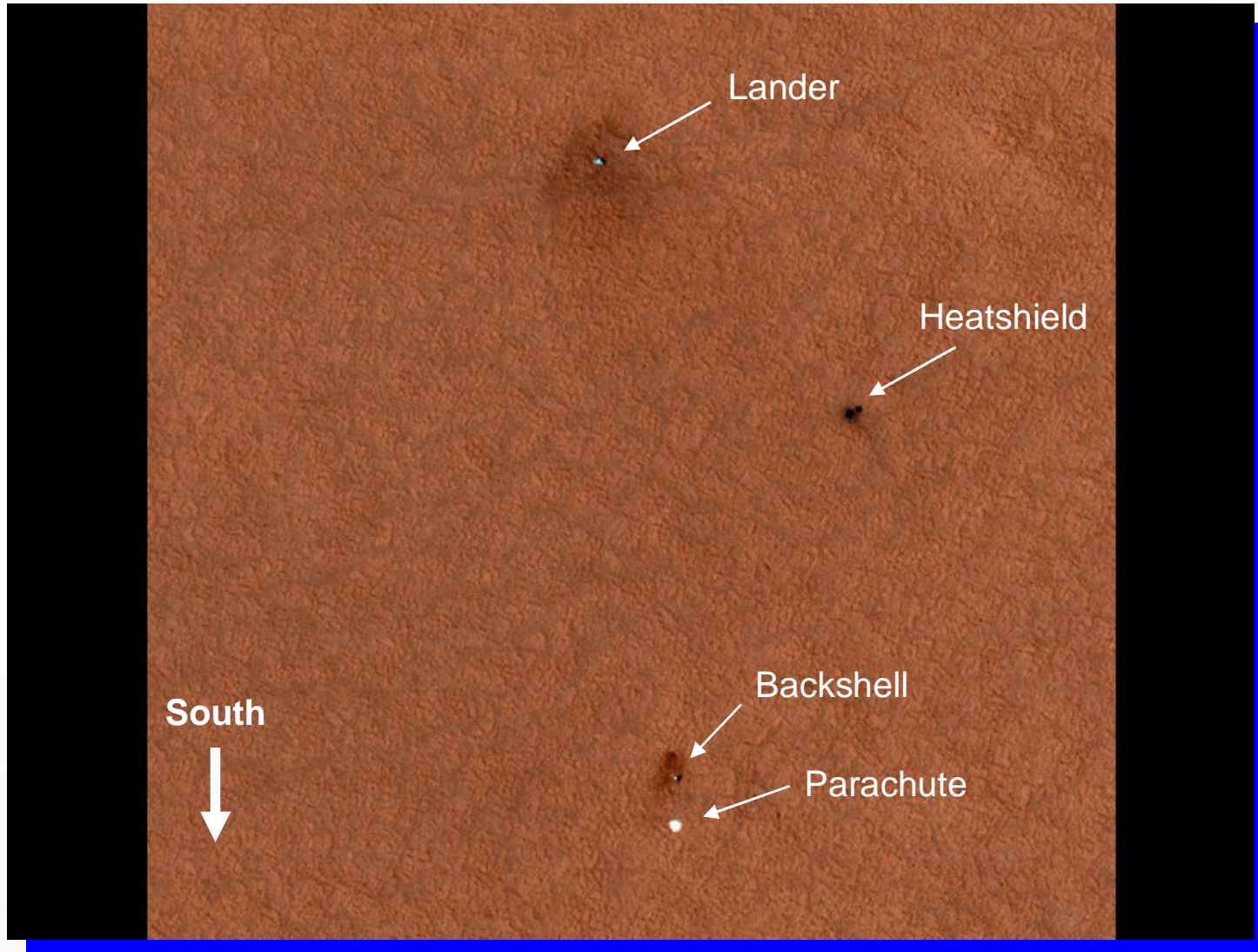
Horizontal velocity prior to Lander separation was ~15 m/s, so **NO BAM** Maneuver performed

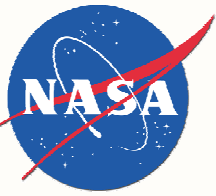
BAM
Backshell Avoidance Maneuver





MRO Surface Image

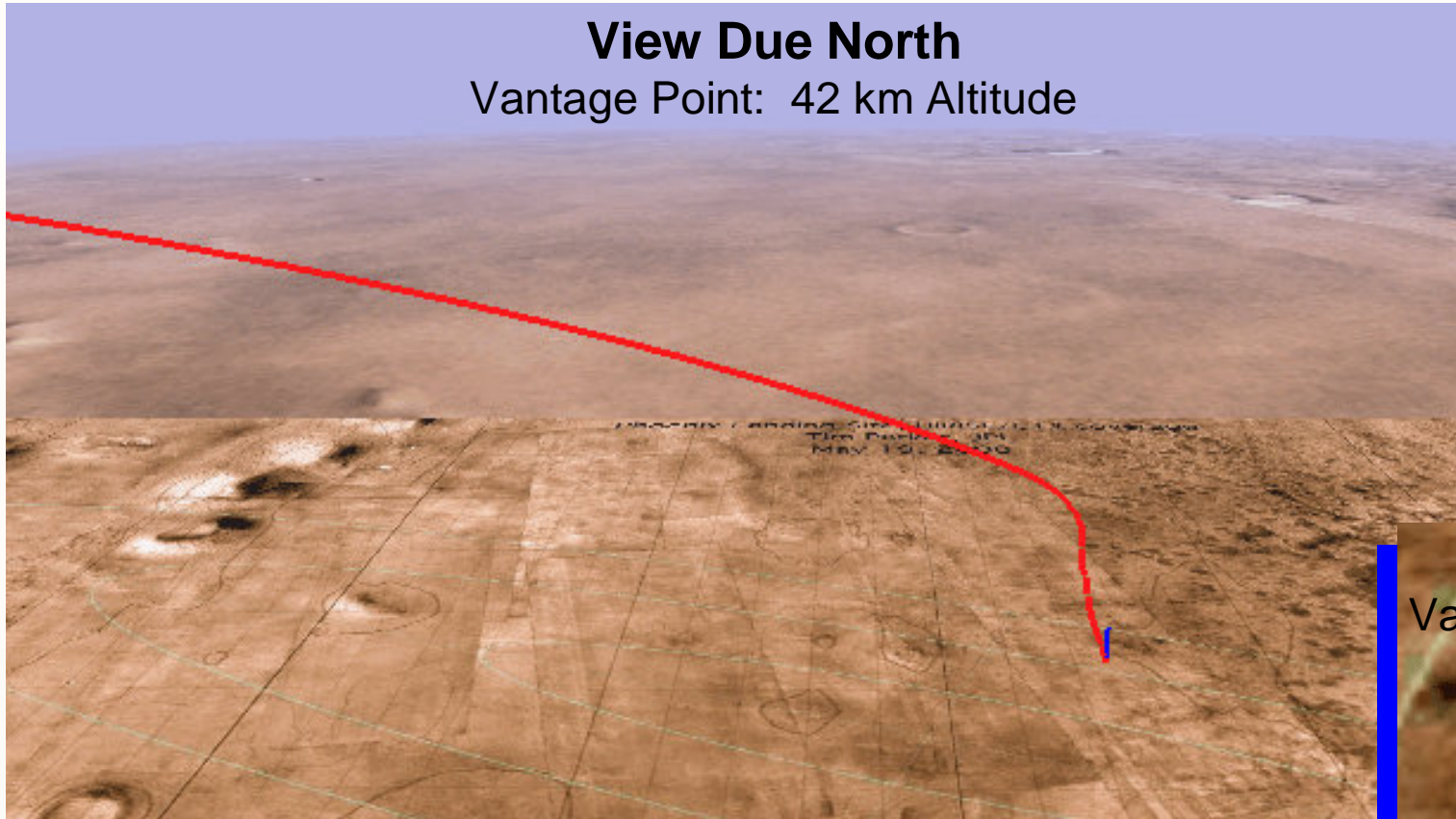




Trajectory Reconstruction

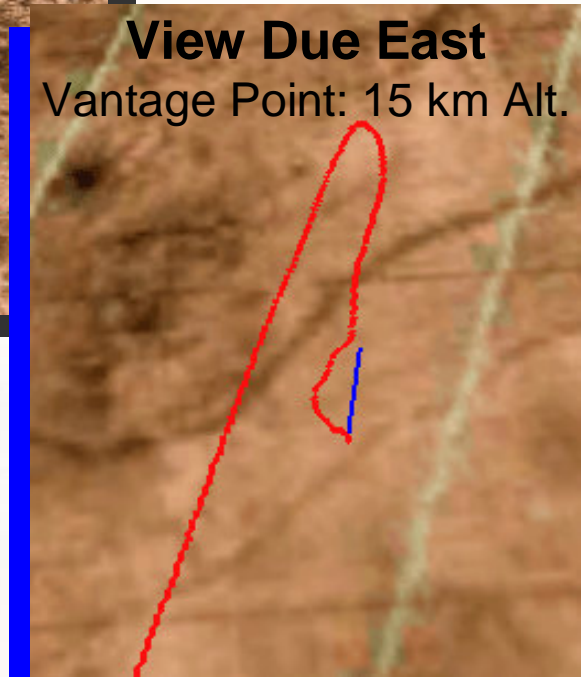


View Due North
Vantage Point: 42 km Altitude

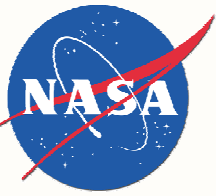


**Trajectory
Visualization**

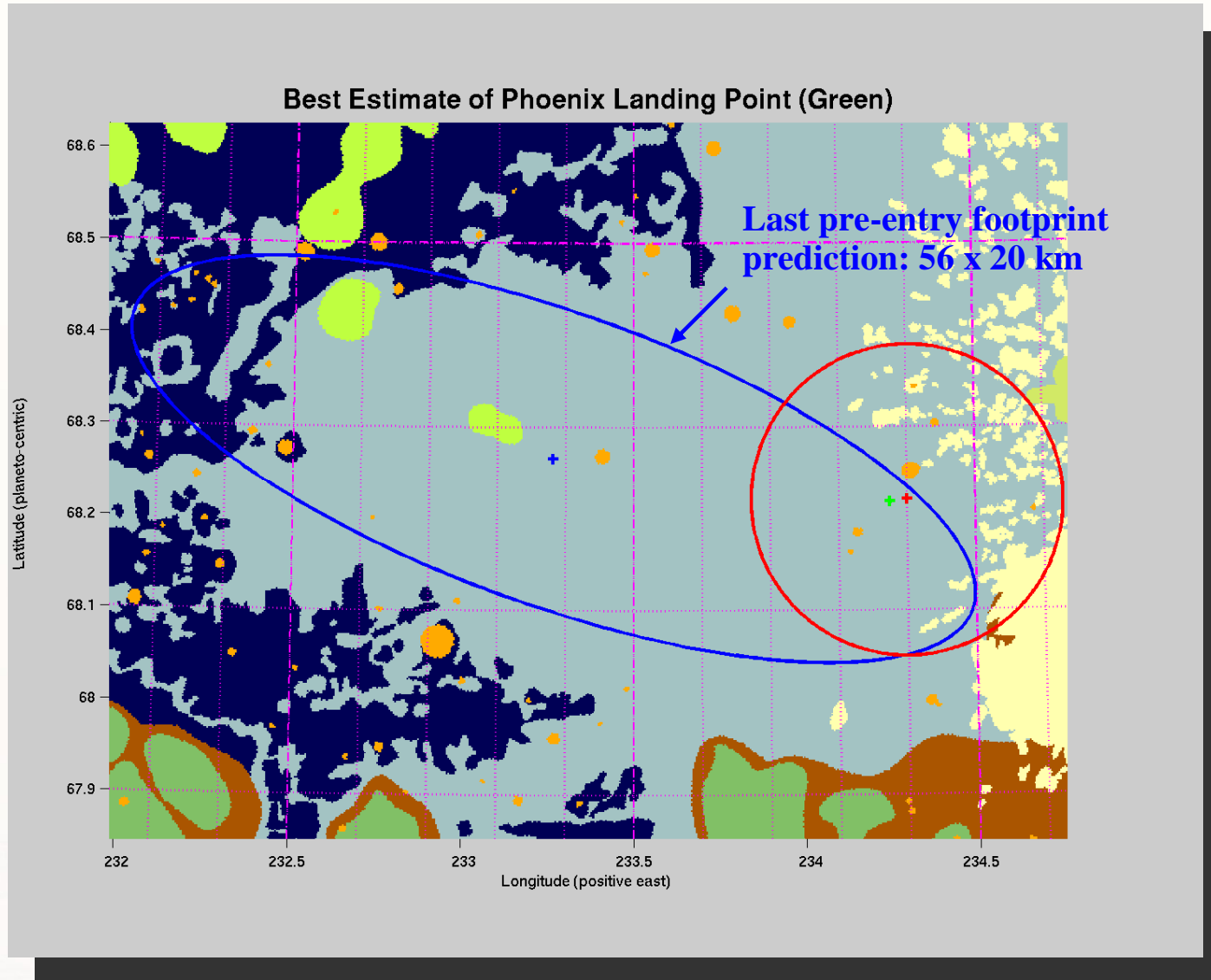
View Due East
Vantage Point: 15 km Alt.



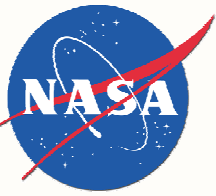
- **Trajectory created by back propagation of 200Hz IMU data**
- **Influence of winds appears apparent during descent on parachute**



Landing Footprint



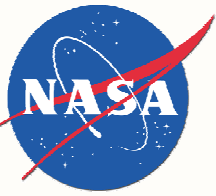
**Design Footprint
Requirement: 110 x 20 km**



Baseline Simulation vs Flight



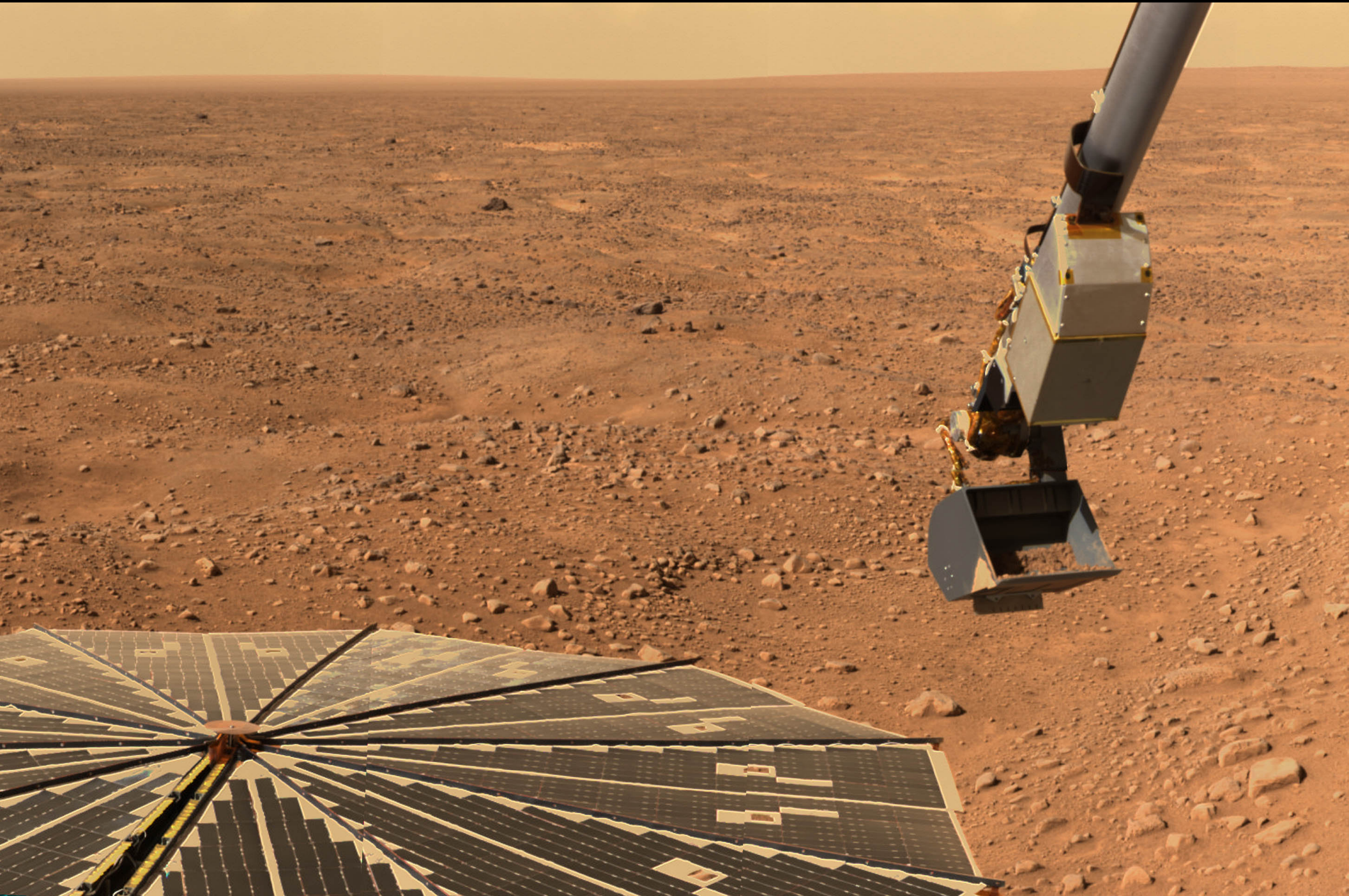
Parameter	Units	6-dof Monte Carlo			Preliminary Reconstructed Flight Value
		99% Low	Mean	99% High	
Hypersonic Flight					
Peak Acceleration, Time from Entry	sec				122.5
Peak Acceleration	Earth g	8.76	9.25	9.79	
Parachute Deployment					
Time from Entry	sec	211.3	219.9	229.4	227.9
Height	km	10	12.7	15.7	13.13
Dynamic Pressure	Pa	452.5	490.5	533.0	492.0
Mach Number		1.45	1.64	1.89	1.68
Total Angle-of-Attack	deg	0.20	2.30	7.30	
Attitude Rate	deg/s	0.40	4.50	16.20	9.2
Heatshield Jettison					
Time from Entry	sec	226.4	235.0	244.5	242.9
Height	km	8.4	11.1	14.0	
Lander Separation					
Time from Entry	sec	348.5	392.7	437.2	404.9
Height	m	923.4	977.3	1260.8	960.0
Vertical Velocity	m/s				55.1
Horizontal Velocity	m/s				15.0
Total Angle-of-Attack	deg	0.78	8.50	23.80	
Attitude Rate	deg/s	3.7	37.0	109.8	18.0
Touchdown					
Time from Entry	sec	391.8	436.2	480.9	446.2
Vertical Velocity	m/s	1.46	2.13	2.74	2.38
Horizontal Velocity	m/s	0.05	0.48	1.20	0.06
Total Prop Usage	kg	35.1	37.4	41.6	37.6

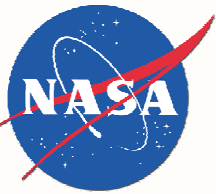


JPL & LaRC EDL Operations Team

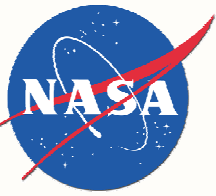


Phoenix on the Northern Plains of Mars!

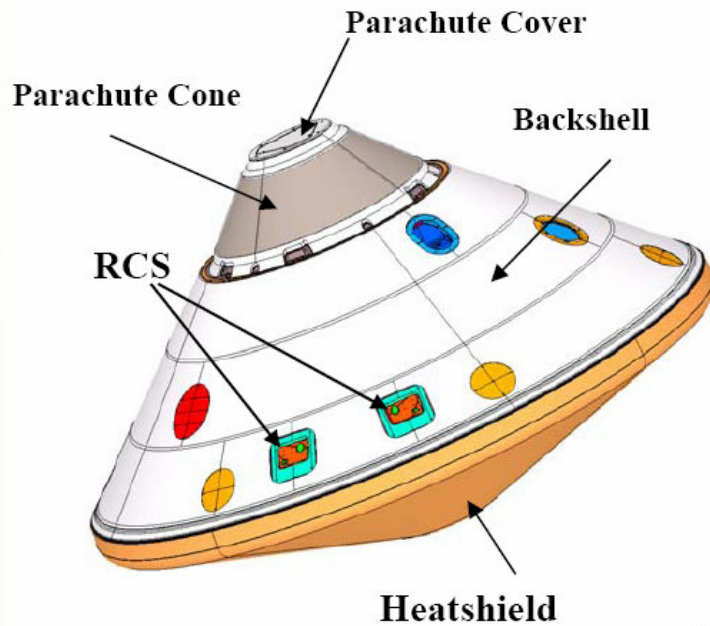




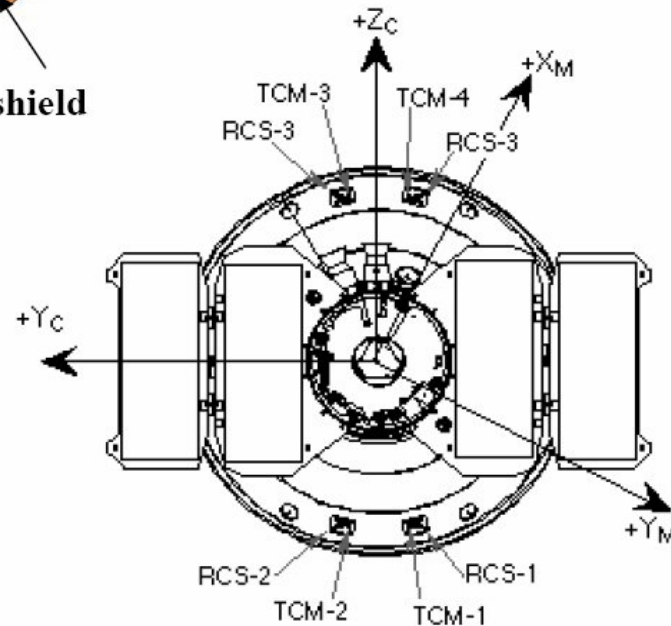
Back-Up Slides

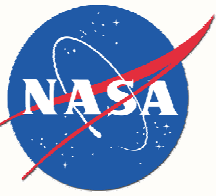


Phoenix Thruster Geometry



- TCM thrusters used for Pitch/Yaw control
- RCS thrusters used for Roll control





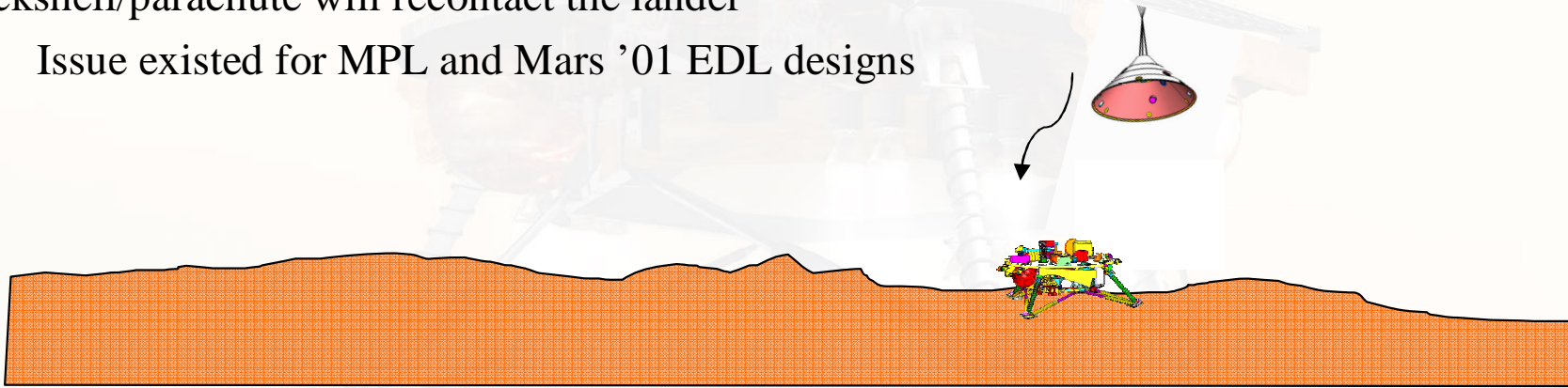
EDL Modifications: Terminal Descent Subphase Evolution



Terminal Descent Redesign Driver

In cases of low wind and no wind terminal descent scenarios, there is an increased probability the backshell/parachute will recontact the lander

- Issue existed for MPL and Mars '01 EDL designs



New Requirement

The distance between the center of mass of the lander and center of mass of the backshell shall be greater than 35m from 5s after lander separation to touchdown of both bodies

