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# OPTIMAL CO-ADAPTED COUPLING FOR THE SYMMETRIC RANDOM WALK ON THE HYPERCUBE 

By Stephen Connor and Saul Jacka<br>University of Warwick<br>Abstract Let $X$ and $Y$ be two simple symmetric continuous-time random walks on the vertices of the $n$-dimensional hypercube, $\mathbb{Z}_{2}^{n}$. We consider the class of co-adapted couplings of these processes, and describe an intuitive coupling which is shown to be the fastest in this class.

1. Introduction. Let $\mathbb{Z}_{2}^{n}$ be the group of binary $n$-tuples under coordinatewise addition modulo 2 : this can be viewed as the set of vertices of an $n$ dimensional hypercube. For $x \in \mathbb{Z}_{2}^{n}$, we write $x=(x(1), \ldots, x(n))$, and define elements $\left\{e_{i}\right\}_{0}^{n}$ by

$$
e_{0}=(0, \ldots, 0) ; \quad e_{i}(k)=\mathbf{1}_{[i=k]}, i=1, \ldots, n,
$$

where 1 denotes the indicator function. For $x, y \in \mathbb{Z}_{2}^{n}$ let

$$
|x-y|=\sum_{i=1}^{n}|x(i)-y(i)|
$$

denote the Hamming distance between $x$ and $y$.
A continuous-time random walk $X$ on $\mathbb{Z}_{2}^{n}$ may be defined using a marked Poisson process $\Lambda$ of rate $n$, with marks distributed uniformly on the set $\{1,2, \ldots, n\}$ : the $i^{\text {th }}$ coordinate of $X$ is flipped to its opposite value (zero

[^0]or one) at incident times of $\Lambda$ for which the corresponding mark is equal to $i$. We write $\mathcal{L}\left(X_{t}\right)$ for the law of $X$ at time $t$. The unique equilibrium distribution of $X$ is the uniform distribution on $\mathbb{Z}_{2}^{n}$.

Suppose that we now wish to couple two such random walks, $X$ and $Y$, starting from different states.

Definition 1.1. A coupling of $X$ and $Y$ is a process $\left(X^{\prime}, Y^{\prime}\right)$ on $\mathbb{Z}_{2}^{n} \times \mathbb{Z}_{2}^{n}$ such that

$$
X^{\prime} \stackrel{\mathcal{D}}{=} X \quad \text { and } \quad Y^{\prime} \stackrel{\mathcal{D}}{=} Y
$$

That is, viewed marginally, $X^{\prime}$ behaves as a version of $X$, and $Y^{\prime}$ as a version of $Y$.

For any coupling strategy $c$, write $\left(X_{t}^{c}, Y_{t}^{c}\right)$ for the value at $t$ of the pair of processes $X^{c}$ and $Y^{c}$ driven by strategy $c$, although this superscript notation may be dropped when no confusion can arise. (We assume throughout that $\left(X^{c}, Y^{c}\right)$ is a coupling of $X$ and $Y$.) We then define the coupling time by

$$
\tau^{c}=\inf \left\{s \geq 0: X_{s}^{c}=Y_{s}^{c}\right\}
$$

For $t \geq 0$, let

$$
U_{t}^{c}=\left\{1 \leq i \leq n: X_{t}^{c}(i) \neq Y_{t}^{c}(i)\right\}
$$

denote the set of unmatched coordinates at time $t$, and let

$$
M_{t}^{c}=\left\{1 \leq i \leq n: X_{t}^{c}(i)=Y_{t}^{c}(i)\right\}
$$

be its complement. A simple coupling technique appears in (1), and may be described as follows:

- if $X(i)$ flips at time $t$, with $i \in M_{t}$, then also flip coordinate $Y(i)$ at time $t$ (matched coordinates are always made to move synchronously);
- if $\left|U_{t}\right|>1$ and $X(i)$ flips at time $t$, with $i \in U_{t}$, also flip coordinate $Y(j)$ at time $t$, where $j$ is chosen uniformly at random from the set $U_{t} \backslash\{i\} ;$
- else, if $U_{t}=\{i\}$ contains only one element, allow coordinates $X(i)$ and $Y(i)$ to evolve independently of each other until this final match is made.

This defines a valid coupling of $X$ and $Y$, for which existing coordinate matches are maintained and new matches made in pairs when $\left|U_{t}\right| \geq 2$. It is also an example of a co-adapted coupling.

Definition 1.2. A coupling $\left(X^{c}, Y^{c}\right)$ is called co-adapted if there exists a filtration $\left(\mathcal{F}_{t}\right)_{t \geq 0}$ such that

1. $X^{c}$ and $Y^{c}$ are both adapted to $\left(\mathcal{F}_{t}\right)_{t \geq 0}$
2. for any $0 \leq s \leq t$,

$$
\mathcal{L}\left(X_{t}^{c} \mid \mathcal{F}_{s}\right)=\mathcal{L}\left(X_{t}^{c} \mid X_{s}^{c}\right) \quad \text { and } \quad \mathcal{L}\left(Y_{t}^{c} \mid \mathcal{F}_{s}\right)=\mathcal{L}\left(Y_{t}^{c} \mid Y_{s}^{c}\right) .
$$

In other words, $\left(X^{c}, Y^{c}\right)$ is co-adapted if $X^{c}$ and $Y^{c}$ are both Markov with respect to a common filtration, $\left(\mathcal{F}_{t}\right)_{t \geq 0}$. Note that this definition does not imply that the joint process $\left(X^{c}, Y^{c}\right)$ is Markovian, however.

In this paper we search for the best possible coupling of the random walks $X$ and $Y$ on $\mathbb{Z}_{2}^{n}$ within the class $\mathcal{C}$ of all co-adapted couplings.
2. Co-adapted couplings for random walks on $\mathbb{Z}_{2}^{n}$. In order to find the optimal co-adapted coupling of $X$ and $Y$, it is first necessary to
be able to describe a general coupling strategy $c \in \mathcal{C}$. To this end, let $\Lambda_{i j}$ ( $0 \leq i, j \leq n$ ) be independent unit-rate marked Poisson processes, with marks $W_{i j}$ chosen uniformly on the interval $[0,1]$. We let $\left(\mathcal{F}_{t}\right)_{t \geq 0}$ be any filtration satisfying

$$
\sigma\left\{\bigcup_{i, j} \Lambda_{i j}(s), \bigcup_{i, j} W_{i j}(s): s \leq t\right\} \subseteq \mathcal{F}_{t}, \quad \forall t \geq 0
$$

The transitions of $X^{c}$ and $Y^{c}$ will be driven by the marked Poisson processes, and controlled by a process $\left\{Q^{c}(t)\right\}_{t \geq 0}$ which is adapted to $\left(\mathcal{F}_{t}\right)_{t \geq 0}$. Here, $Q^{c}(t)=\left\{q_{i j}^{c}(t): 1 \leq i, j, \leq n\right\}$ is a $n \times n$ doubly sub-stochastic matrix. Such a matrix implicitly defines terms $\left\{q_{0 j}^{c}(t): 1 \leq j \leq n\right\}$ and $\left\{q_{i 0}^{c}(t): 1 \leq i \leq n\right\}$ such that

$$
\begin{array}{ll} 
& \sum_{i=0}^{n} q_{i j}^{c}(t)=1 \quad \text { for all } 1 \leq j \leq n \text { and } t \geq 0, \\
\text { and } \quad \sum_{j=0}^{n} q_{i j}^{c}(t)=1 \quad \text { for all } 1 \leq i \leq n \text { and } t \geq 0 . \tag{2.2}
\end{array}
$$

For convenience we also define $q_{00}^{c}(t)=0$ for all $t \geq 0$.
Note that any co-adapted coupling ( $X^{c}, Y^{c}$ ) must satisfy the following three constraints, all of which are due to the marginal processes $X^{c}(i)(i=$ $1, \ldots, n$ ) being independent unit rate Poisson processes (and similarly for the processes $\left.Y^{c}(i)\right)$ :

1. At any instant the number of jumps by the process $\left(X^{c}, Y^{c}\right)$ cannot exceed two (one on $X^{c}$ and one on $Y^{c}$ );
2. All single and double jumps must have rates bounded above by one;
3. For all $i=1, \ldots, n$, the total rate at which $X^{c}(i)$ jumps must equal one.

A general co-adapted coupling for $X$ and $Y$ may therefore be defined as follows: if there is a jump in the process $\Lambda_{i j}$ at time $t \geq 0$, and the mark $W_{i j}(t)$ satisfies $W_{i j}(t) \leq q_{i j}(t)$, then set $X_{t}^{c}=X_{t-}^{c}+e_{i}(\bmod 2)$ and $Y_{t}^{c}=Y_{t-}^{c}+e_{j}(\bmod 2)$. Note that if $i($ respectively $j)$ equals zero, then $X_{t}^{c}=X_{t-}^{c}$ (respectively, $Y_{t}^{c}=Y_{t-}^{c}$ ), since $e_{0}=(0, \ldots, 0)$.

From this construction it follows directly that $X^{c}$ and $Y^{c}$ both have the correct marginal transition rates to be continuous-time simple random walks on $\mathbb{Z}_{2}^{n}$ as described above, and are co-adapted.
3. Optimal coupling. Our proposed optimal coupling strategy, $\hat{c}$, is very simple to describe, and depends only upon the number of unmatched coordinates of $X$ and $Y$. Let $N_{t}=\left|U_{t}\right|$ denote the value of this number at time $t$. Strategy $\hat{c}$ may be summarised as follows:

- matched coordinates are always made to move synchronously (thus $N^{\hat{c}}$ is a decreasing process);
- if $N$ is odd, all unmatched coordinates of $X$ and $Y$ are made to evolve independently until $N$ becomes even;
- if $N$ is even, unmatched coordinates are coupled in pairs - when an unmatched coordinate on $X$ flips (thereby making a new match), a different, uniformly chosen, unmatched coordinate on $Y$ is forced to flip at the same instant (making a total of two new matches).

Note the similarity between $\hat{c}$ and the coupling of Aldous described in Section 1 if $N$ is even these strategies are identical; if $N$ is odd however, $\hat{c}$ seeks to restore the parity of $N$ as fast as possible, whereas Aldous's coupling continues to couple unmatched coordinates in pairs until $N=1$.

Definition 3.1. The matrix process $\hat{Q}$ corresponding to the coupling $\hat{c}$ is as follows:

- $\hat{q}_{i i}(t)=1$ for all $i \in M_{t}$ and for all $t \geq 0$;
- if $N_{t}$ is odd, $\hat{q}_{i 0}(t)=\hat{q}_{0 i}(t)=1$ for all $i \in U_{t}$;
- if $N_{t}$ is even, $\hat{q}_{i 0}(t)=\hat{q}_{0 i}(t)=\hat{q}_{i i}(t)=0$ for all $i \in U_{t}$, and

$$
\hat{q}_{i j}=\frac{1}{\left|U_{t}\right|-1} \quad \text { for all distinct } i, j \in U_{t}
$$

The coupling time under $\hat{c}$, when $\left(X_{0}, Y_{0}\right)=(x, y)$, can thus be expressed as follows:
$\hat{\tau}=\tau^{\hat{c}}= \begin{cases}E_{0}+E_{1}+E_{2}+\cdots+E_{m-1}+E_{m} & \text { if }|x-y|=2 m \\ E_{0}+E_{1}+E_{2}+\cdots+E_{m-1}+E_{m}+E_{2 m+1} & \text { if }|x-y|=2 m+1,\end{cases}$
where $\left\{E_{k}\right\}_{k \geq 0}$ form a set of independent Exponential random variables, with $E_{k}$ having rate $2 k$. (Note that $E_{0} \equiv 0$ : it is included merely for notational convenience.)

Now define

$$
\begin{equation*}
\hat{v}(x, y, t)=\mathbb{P}\left[\hat{\tau}>t \mid X_{0}=x, Y_{0}=y\right] \tag{3.2}
\end{equation*}
$$

to be the tail probability of the coupling time under $\hat{c}$. The main result of this paper is the following.

Theorem 3.2. For any states $x, y \in \mathbb{Z}_{2}^{n}$ and time $t \geq 0$,

$$
\begin{equation*}
\hat{v}(x, y, t)=\inf _{c \in \mathcal{C}} \mathbb{P}\left[\tau^{c}>t \mid X_{0}=x, Y_{0}=y\right] . \tag{3.3}
\end{equation*}
$$

In other words, $\hat{\tau}$ is the stochastic minimum of all co-adapted coupling times for the pair $(X, Y)$.

It is clear from the representation in (3.1) that $\hat{v}(x, y, t)$ only depends on $(x, y)$ through $|x-y|$, and so we shall usually simply write

$$
\hat{v}(k, t)=\mathbb{P}\left[\hat{\tau}>t \mid N_{0}=k\right],
$$

with the convention that $\hat{v}(k, t)=0$ for $k \leq 0$. Note, again from (3.1), that $\hat{v}(k, t)$ is strictly increasing in $k$. For a strategy $c \in \mathcal{C}$, define the process $S_{t}^{c}$ by

$$
S_{t}^{c}=\hat{v}\left(X_{t}^{c}, Y_{t}^{c}, T-t\right),
$$

where $T>0$ is some fixed time. This is the conditional probability of $X$ and $Y$ not having coupled by time $T$, when strategy $c$ has been followed over the interval $[0, t]$ and $\hat{c}$ has then been used from time $t$ onwards. The optimality of $\hat{c}$ will follow by Bellman's principle (see, for example, (5)) if it can be shown that $S_{t \wedge \tau^{c}}^{c}$ is a submartingale for all $c \in \mathcal{C}$, as demonstrated in the following lemma. (Here and throughout, $s \wedge t=\min \{s, t\}$.)

Lemma 3.3. Suppose that for each $c \in \mathcal{C}$ and each $T \in \mathbb{R}_{+}$,

$$
\left(S_{t \wedge \tau^{c}}^{c}\right)_{0 \leq t \leq T} \quad \text { is a submartingale }
$$

Then equation (3.3) holds.
Proof. Notice that $S_{0}^{c}=\hat{v}(x, y, T)$ and $S_{T \wedge \tau^{c}}^{c}=\mathbf{1}_{\left[T<\tau^{c}\right]}$. If $S_{.}^{c} \wedge^{c}$. is a submartingale it follows by the Optional Sampling Theorem that

$$
\mathbb{P}\left[\tau^{c}>T\right]=\mathbb{E}\left[S_{T \wedge \tau^{c}}^{c}\right] \geq S_{0}^{c}=\hat{v}(x, y, T)=\mathbb{P}[\hat{\tau}>T]
$$

and hence the infimum in (3.3) is attained by $\hat{c}$.

Now, (point process) stochastic calculus yields:

$$
\begin{equation*}
d S_{t}^{c}=d Z_{t}^{c}+\left(\mathcal{A}_{t}^{c} \hat{v}-\frac{\partial \hat{v}}{\partial t}\right) d t \tag{3.4}
\end{equation*}
$$

where $Z_{t}^{c}$ is a martingale, and $\mathcal{A}_{t}^{c}$ is the "generator" corresponding to the matrix $Q^{c}(t)$. Since the Poisson processes $\Lambda_{i j}$ are independent, the probability of two or more jumps occurring in the superimposed process $\bigcup \Lambda_{i j}$ in a time interval of length $\delta$ is $O\left(\delta^{2}\right)$. Hence, for any function $f: \mathbb{Z}_{2}^{n} \times \mathbb{Z}_{2}^{n} \times \mathbb{R}^{+} \rightarrow \mathbb{R}$, $\mathcal{A}_{t}^{c}$ satisfies

$$
\mathcal{A}_{t}^{c} f(x, y, t)=\sum_{i=0}^{n} \sum_{j=0}^{n} q_{i j}^{c}(t)\left[f\left(x+e_{i}, y+e_{j}, t\right)-f(x, y, t)\right] .
$$

Setting $f=\hat{v}$ gives:

$$
\begin{aligned}
\mathcal{A}_{t}^{c} \hat{v}(x, y, t) & =\sum_{i=0}^{n} \sum_{j=0}^{n} q_{i j}^{c}(t)\left[\hat{v}\left(x+e_{i}, y+e_{j}, t\right)-\hat{v}(x, y, t)\right] \\
& =\sum_{i=0}^{n} \sum_{j=0}^{n} q_{i j}^{c}(t)\left[\hat{v}\left(\left|x-y+e_{i}+e_{j}\right|, t\right)-\hat{v}(|x-y|, t)\right] .
\end{aligned}
$$

In particular, since $\hat{v}$ is invariant under coordinate permutation, if $N_{t}^{c}=$ $|x-y|=k$ then

$$
\begin{equation*}
\mathcal{A}_{t}^{c} \hat{v}(x, y, t)=\sum_{m=-2}^{2} \lambda_{t}^{c}(k, k+m)[\hat{v}(k+m, t)-\hat{v}(k, t)], \tag{3.5}
\end{equation*}
$$

where $\lambda_{t}^{c}(k, k+m)$ is the rate (according to $\left.Q^{c}(t)\right)$ at which $N_{t}^{c}$ jumps from $k$ to $k+m$. More explicitly,

$$
\begin{array}{ll}
\lambda_{t}^{c}(k, k+2)=\sum_{\substack{i, j \in M_{t} \\
i \neq j}} q_{i j}^{c}(t), & \lambda_{t}^{c}(k, k+1)=\sum_{i \in M_{t}}\left(q_{i 0}^{c}(t)+q_{0 i}^{c}(t)\right), \\
\lambda_{t}^{c}(k, k-2)=\sum_{\substack{i, j \in U_{t} \\
i \neq j}} q_{i j}^{c}(t), & \lambda_{t}^{c}(k, k-1)=\sum_{i \in U_{t}}\left(q_{i 0}^{c}(t)+q_{0 i}^{c}(t)\right), \tag{3.7}
\end{array}
$$

and

$$
\begin{equation*}
\lambda_{t}^{c}(k, k)=\sum_{i \in U_{t}, j \in M_{t}}\left(q_{i j}^{c}(t)+q_{j i}^{c}(t)\right)+\sum_{i=1}^{n} q_{i i}^{c}(t) . \tag{3.8}
\end{equation*}
$$

It follows from the definition of $Q$ and equations (3.6) to (3.8) that these terms must satisfy the linear constraints:

$$
\begin{aligned}
& \lambda_{t}^{c}(k, k-2)+\frac{1}{2} \lambda_{t}^{c}(k, k-1) \leq k, \quad \text { and } \\
& \lambda_{t}^{c}(k, k-2)+\frac{1}{2} \lambda_{t}^{c}(k, k-1)+\lambda_{t}^{c}(k, k)+\frac{1}{2} \lambda_{t}^{c}(k, k+1)+\lambda_{t}^{c}(k, k+2)=n
\end{aligned}
$$

Denote by $L_{n}$ the set of non-negative $\lambda$ satisfying the constraints

$$
\begin{equation*}
\lambda(k, k-2)+\frac{1}{2} \lambda(k, k-1) \leq k, \quad \text { and } \tag{3.9}
\end{equation*}
$$

$$
\begin{equation*}
\lambda(k, k-2)+\frac{1}{2} \lambda(k, k-1)+\lambda(k, k)+\frac{1}{2} \lambda(k, k+1)+\lambda(k, k+2)=n . \tag{3.10}
\end{equation*}
$$

Returning to equation (3.4):

$$
d S_{t}^{c}=d Z_{t}^{c}+\left(\mathcal{A}_{t}^{c} \hat{v}-\frac{\partial \hat{v}}{\partial t}\right) d t
$$

We wish to show that $S_{t \wedge \tau^{c}}^{c}$ is a submartingale for all couplings $c \in \mathcal{C}$. We shall do this by showing that $\mathcal{A}_{t}^{c} \hat{v}$ is minimised by setting $c=\hat{c}$. This is sufficient because $S_{t \wedge \hat{\tau}}^{\hat{c}}$ is a martingale (and so $\mathcal{A}_{t}^{\hat{c}} \hat{v}-\partial \hat{v} / \partial t=0$ ). Now, from equation (3.5) we know that

$$
\mathcal{A}_{t}^{c} \hat{v}(k, t)=\sum_{m=-2}^{2} \lambda_{t}^{c}(k, k+m)[\hat{v}(k+m, t)-\hat{v}(k, t)] .
$$

Thus we seek to show that, for all $k \geq 0$ and for all $t \geq 0$,

$$
\begin{equation*}
\max _{\lambda \in L_{n}} \sum_{m=-2}^{2} \lambda(k, k+m)[\hat{v}(k, t)-\hat{v}(k+m, t)] \geq 0 \tag{3.11}
\end{equation*}
$$

For each $t$, this is a linear function of non-negative terms of the form $\lambda(k, k+m)$. Thanks to the monotonicity in its first argument of $\hat{v}$, the terms appearing in the left-hand-side of (3.11) are non-positive if and only if $m$ is non-negative. Hence we must set

$$
\begin{equation*}
\lambda(k, k+1)=\lambda(k, k+2)=0 \tag{3.12}
\end{equation*}
$$

in order to achieve the maximum in (3.11).
It now suffices to maximise

$$
\begin{equation*}
\lambda(k, k-1)[\hat{v}(k, t)-\hat{v}(k-1, t)]+\lambda(k, k-2)[\hat{v}(k, t)-\hat{v}(k-2, t)], \tag{3.13}
\end{equation*}
$$

subject to the constraint in (3.9).
Combining (3.9) and (3.13) yields the final version of our optimisation problem:

$$
\begin{equation*}
\text { maximise } \quad \lambda(k, k-1)\left([\hat{v}(k, t)-\hat{v}(k-1, t)]-\frac{1}{2}[\hat{v}(k, t)-\hat{v}(k-2, t)]\right) \tag{3.14}
\end{equation*}
$$

subject to $\quad 0 \leq \lambda(k, k-1) \leq 2 k$.
The solution to this problem is clearly given by:

$$
\lambda(k, k-1)= \begin{cases}2 k & \text { if }[\hat{v}(k, t)-\hat{v}(k-1, t)]>\frac{1}{2}[\hat{v}(k, t)-\hat{v}(k-2, t)]  \tag{3.16}\\ 0 & \text { otherwise }\end{cases}
$$

These observations may be summarised as follows:

Proposition 3.4. For $\lambda \in L_{n}$, the maximum value of

$$
\sum_{m=-2}^{2} \lambda(k, k+m)[\hat{v}(k, t)-\hat{v}(k+m, t)]
$$

is achieved at $\lambda^{*}$, where $\lambda^{*}$ satisfies the following:

$$
\begin{aligned}
& \lambda^{*}(k, k+1)=\lambda^{*}(k, k+2)=0 ; \\
& \lambda^{*}(k, k-2)+\frac{1}{2} \lambda^{*}(k, k-1)=k ; \\
& \lambda^{*}(k, k-1)= \begin{cases}2 k & \text { if }[\hat{v}(k, t)-\hat{v}(k-1, t)]>\frac{1}{2}[\hat{v}(k, t)-\hat{v}(k-2, t)] \\
0 & \text { otherwise } .\end{cases}
\end{aligned}
$$

Our final proposition shows that $\lambda^{*}(k, k-1)=2 k$ if and only if $k$ is odd.

Proposition 3.5. For any fixed $t \geq 0$,

$$
\begin{equation*}
2[\hat{v}(k, t)-\hat{v}(k-1, t)]-[\hat{v}(k, t)-\hat{v}(k-2, t)] \geq 0 \quad \text { if } k \text { is odd, and } \tag{3.17}
\end{equation*}
$$

$$
\begin{equation*}
2[\hat{v}(k, t)-\hat{v}(k-1, t)]-[\hat{v}(k, t)-\hat{v}(k-2, t)] \leq 0 \quad \text { if } k \text { is even. } \tag{3.18}
\end{equation*}
$$

Proof. Define $\hat{V}_{\alpha}$ by

$$
\begin{aligned}
\hat{V}_{\alpha}(k) & =\int_{0}^{\infty} e^{-\alpha t} \hat{v}(k, t) d t \\
& =\frac{1}{\alpha}\left(1-\mathbb{E}\left[e^{-\alpha \hat{\tau}}\right]\right) .
\end{aligned}
$$

We also define $d(k, t)=\hat{v}(k, t)-\hat{v}(k-1, t)$, and for $\alpha \geq 0$ let

$$
D_{\alpha}(k)=\int_{0}^{\infty} e^{-\alpha t} d(k, t) d t
$$

be the Laplace transform of $d(k, \cdot)$. Given the representation in equation (3.1) of $\hat{\tau}$ as a sum of independent Exponential random variables, it follows that

$$
\hat{V}_{\alpha}(k)= \begin{cases}\frac{1}{\alpha}\left(1-\prod_{i=1}^{m} \frac{2 i}{2 i+\alpha}\right) & \text { if } k=2 m  \tag{3.19}\\ \frac{1}{\alpha}\left(1-\frac{2(2 m+1)}{2(2 m+1)+\alpha} \prod_{i=1}^{m} \frac{2 i}{2 i+\alpha}\right) & \text { if } k=2 m+1\end{cases}
$$

To ease notation, let

$$
\phi_{\alpha}(m)=\prod_{i=1}^{m} \frac{2 i}{2 i+\alpha} .
$$

The following equality then follows directly from consideration of the transition rates corresponding to strategy $\hat{c}$ :
for all $\alpha \geq 0$ and $m \geq 1$,
$1-\alpha \hat{V}_{\alpha}(2 m)+2 m\left[\hat{V}_{\alpha}(2 m-2)-\hat{V}_{\alpha}(2 m)\right]=\phi_{\alpha}(m)+\frac{2 m}{\alpha}\left[\phi_{\alpha}(m)-\phi_{\alpha}(m-1)\right]$

$$
\begin{aligned}
& =\phi_{\alpha}(m)+\frac{2 m}{\alpha} \phi_{\alpha}(m)\left[1-\frac{2 m+\alpha}{2 m}\right] \\
& =0
\end{aligned}
$$

Similarly,

$$
\begin{equation*}
1-\alpha \hat{V}_{\alpha}(2 m-1)+2(2 m-1)\left[\hat{V}_{\alpha}(2 m-2)-\hat{V}_{\alpha}(2 m-1)\right]=0 . \tag{3.21}
\end{equation*}
$$

Now suppose that $k=2 m$, and hence is even. We wish to prove that

$$
d(2 m-1, t)-d(2 m, t) \geq 0 \quad \text { for all } t \geq 0
$$

which is equivalent to showing that $D_{\alpha}(2 m-1)-D_{\alpha}(2 m)$ is totally (or completely) monotone (by the Bernstein-Widder Theorem; Theorem 1a of (3), Ch. XIII.4).

We proceed by subtracting equation (3.21) from (3.20):

$$
\begin{aligned}
0=-\alpha\left[\hat{V}_{\alpha}(2 m)-\hat{V}_{\alpha}(2 m-1)\right] & +2 m\left[\hat{V}_{\alpha}(2 m-2)-\hat{V}_{\alpha}(2 m)\right] \\
& +2(2 m-1)\left[\hat{V}_{\alpha}(2 m-1)-\hat{V}_{\alpha}(2 m-2)\right] \\
=-\alpha D_{\alpha}(2 m)-2 m\left[D_{\alpha}(2 m)\right. & \left.+D_{\alpha}(2 m-1)\right]+2(2 m-1) D_{\alpha}(2 m-1)
\end{aligned}
$$

and so

$$
\begin{equation*}
D_{\alpha}(2 m-1)-D_{\alpha}(2 m)=\frac{2+\alpha}{2 m-2} D_{\alpha}(2 m) \tag{3.22}
\end{equation*}
$$

It therefore suffices to show that $(2+\alpha) D_{\alpha}(2 m)$ is completely monotone.
Now note from the form of $\hat{V}$ in equation (3.19), that

$$
(2+\alpha) D_{\alpha}(2 m)=2 \Theta_{\alpha}(2 m)
$$

where $\Theta_{\alpha}(2 m)$ is the Laplace transform of

$$
\theta(2 m, t)=\mathbb{P}\left[\sum_{i=0}^{m} E_{i}>t\right]-\mathbb{P}\left[\sum_{i=0}^{m-1} E_{i}+E_{2 m-1}>t\right],
$$

where $\left\{E_{i}\right\}_{i \geq 0}$ form a set of independent Exponential random variables, with $E_{i}$ having parameter $2 i$. But since $\theta(2 m, t)$ is strictly positive for all $t$, it follows that $(2+\alpha) D_{\alpha}(2 m)$ is completely monotone, as required. This proves that, for any fixed $t \geq 0$,

$$
\begin{equation*}
2[\hat{v}(k, t)-\hat{v}(k-1, t)]-[\hat{v}(k, t)-\hat{v}(k-2, t)] \leq 0 \tag{3.23}
\end{equation*}
$$

whenever $k$ is even. Thus inequality (3.18) holds in this case.
Now suppose that $k=2 m+1$, and hence is odd. In this case we wish to show that inequality (3.17) holds, which is equivalent to showing that $D_{\alpha}(2 m+1)-D_{\alpha}(2 m)$ is completely monotone. Now, substituting $m+1$ for $m$ in equation (3.21) yields

$$
\begin{equation*}
1-\alpha \hat{V}_{\alpha}(2 m+1)+2(2 m+1)\left[\hat{V}_{\alpha}(2 m)-\hat{V}_{\alpha}(2 m+1)\right]=0 . \tag{3.24}
\end{equation*}
$$

Proceeding as above, we subtract equation (3.20) from (3.24):

$$
\begin{aligned}
0=-\alpha\left[\hat{V}_{\alpha}(2 m+1)-\hat{V}_{\alpha}(2 m)\right] & +2(2 m+1)\left[\hat{V}_{\alpha}(2 m)-\hat{V}_{\alpha}(2 m+1)\right] \\
& +2 m\left[\hat{V}_{\alpha}(2 m)-\hat{V}_{\alpha}(2 m-2)\right]
\end{aligned}
$$

$$
\begin{equation*}
=-\alpha D_{\alpha}(2 m+1)-2(2 m+1) D_{\alpha}(2 m+1)+2 m\left[D_{\alpha}(2 m)+D_{\alpha}(2 m-1)\right] . \tag{3.25}
\end{equation*}
$$

Then it follows from equation $(3.22)$ that

$$
\begin{equation*}
(2 m-2) D_{\alpha}(2 m-1)=(2 m+\alpha) D_{\alpha}(2 m) \tag{3.26}
\end{equation*}
$$

Substitution of equation (3.26) into $(3.25)$ gives

$$
0=(4 m+2-\alpha)\left[D_{\alpha}(2 m)-D_{\alpha}(2 m+1)\right]+2\left[D_{\alpha}(2 m-1)-D_{\alpha}(2 m)\right]
$$

and so

$$
\begin{equation*}
D_{\alpha}(2 m+1)-D_{\alpha}(2 m)=\frac{2}{4 m+2+\alpha}\left[D_{\alpha}(2 m-1)-D_{\alpha}(2 m)\right] \tag{3.27}
\end{equation*}
$$

But, since we have already seen that $D_{\alpha}(2 m-1)-D_{\alpha}(2 m)$ is completely monotone, the right-hand-side of equation 3.27 is the product of two completely monotone functions, and so is itself completely monotone (3), as required.

Now we may complete the

Proof of Theorem 3.2. Thanks to Lemma 3.3 and Proposition 3.4, Proposition 3.5, along with equations (3.12 and 3.16, shows that any optimal choice of $Q(t), Q^{*}(t)$, is of the following form:

- when $N_{t}$ is odd:

$$
\begin{aligned}
& q_{i 0}^{*}(t)=q_{0 i}^{*}(t)=1 \text { for all } i \in U_{t},\left(\text { and so } \lambda_{t}^{*}\left(N_{t}, N_{t}-1\right)=2 N_{t}\right) \\
& q_{i i}^{*}(t)=1 \text { for all } i \in M_{t}
\end{aligned}
$$

- when $N_{t}$ is even:

$$
\begin{align*}
& q_{i 0}^{*}(t)=q_{0 i}^{*}(t)=q_{i i}^{*}(t)=0 \text { for all } i \in U_{t},\left(\text { and so } \lambda_{t}^{*}\left(N_{t}, N_{t}-1\right)=0\right)  \tag{3.28}\\
& q_{i i}^{*}(t)=1 \text { for all } i \in M_{t}
\end{align*}
$$

This is in agreement with our candidate strategy $\hat{Q}$ (recall Definition 3.1). From equation (3.28) it follows that the values of $q_{i j}^{*}(t)$ for distinct $i, j \in U_{t}$ must satisfy

$$
\sum_{\substack{i, j \in U_{t} \\ i \neq j}} q_{i j}^{*}(t)=\left|U_{t}\right|
$$

but are not constrained beyond this. Our choice of

$$
\hat{q}_{i j}(t)=\frac{1}{\left|U_{t}\right|-1}
$$

satisfies this bound, and so $\hat{c}$ is truly an optimal co-adapted coupling, as claimed.

Remark 3.6. Observe that when $k=1$, equation (3.1) implies that $\hat{v}(1, t)=\hat{v}(2, t)$ for all $t$. The optimisation problem in (3.14) and (3.15) simplifies in this case to the following:

$$
\begin{align*}
\text { maximise } & \lambda(1,0) \hat{v}(1, t)  \tag{3.29}\\
\text { subject to } & \frac{1}{2} \lambda(1,0)+\lambda(1,1)+\frac{1}{2} \lambda(1,2) \leq n \tag{3.30}
\end{align*}
$$

As above, this is achieved by setting $\lambda(1,0)=2$. Note from equation (3.30), however, that when $k=1$ there is no obligation to set $\lambda(1,2)=0$ in order to attain the required maximum. Indeed, due to the equality between $\hat{v}(1, t)$ and $\hat{v}(2, t)$, when $k=1$ it is not sub-optimal to allow matched coordinates to evolve independently (corresponding to $\lambda_{t}^{c}(1,2)>0$ ), so long as strategy $\hat{c}$ is used once more as soon as $k=2$.
4. Maximal coupling. Let $X$ and $Y$ be two copies of a Markov chain on a countable space, starting from different states. The coupling inequality
(see, for example, (6)) bounds the tail distribution of any coupling of $X$ and $Y$ by the total variation distance between the two processes:

$$
\begin{equation*}
\left\|\mathcal{L}\left(X_{t}\right)-\mathcal{L}\left(Y_{t}\right)\right\|_{T V} \leq \mathbb{P}[\tau>t] \tag{4.1}
\end{equation*}
$$

(4) showed that there always exists a maximal coupling of $X$ and $Y$ : that is, one which achieves equality for all $t \geq 0$ in the coupling inequality. However, in general such a coupling is not co-adapted. In light of the results of Section 3, where it was shown that $\hat{c}$ is the optimal co-adapted coupling for the symmetric random walk on $\mathbb{Z}_{2}^{n}$, a natural question is whether $\hat{c}$ is also a maximal coupling.

This is certainly not the case in general. Suppose that $X$ and $Y$ are once again random walks on $\mathbb{Z}_{2}^{n}$, with $X_{0}=(0,0, \ldots, 0)$ and $Y_{0}=(1,1, \ldots, 1)$ : calculations as in (2) show that the total variation distance between $X_{t}$ and $Y_{t}$ exhibits a cutoff phenomenon, with the cutoff taking place at time $T_{n}=\frac{1}{4} \log n$ for large $n$. This implies that a maximal coupling of $X$ and $Y$ has expected coupling time of order $T_{n}$. However, it follows from the representation of $\hat{\tau}$ in equation (3.1) that

$$
\begin{equation*}
\mathbb{E}\left[\hat{\tau} ;\left|X_{0}-Y_{0}\right|=n=2 m\right]=\mathbb{E}\left[E_{1}+E_{2}+\cdots+E_{m-1}+E_{m}\right] \sim \frac{1}{2} \log (n) \tag{4.2}
\end{equation*}
$$

It follows that $\hat{c}$ is not, in general, a maximal coupling.
A faster coupling of $X$ and $Y$ was proposed by (7). This coupling also makes new coordinate matches in pairs, but uses information about the future evolution of one of the chains in order to make such matches in a more efficient manner. This coupling is very near to being maximal (it captures the correct cutoff time), but is of course not co-adapted.

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