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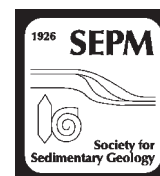
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USING IMAGE-BASED SIZE ANALYSIS FOR DETERMINING THE SIZE DISTRIBUTION AND FLUX OF EOLIAN PARTICLES SAMPLED IN COASTAL NORTHERN CHILE (23° S)

VALENTINA FLORES-AQUEVEQUE,^{1,2} SANDRINE CAQUINEAU,³ STEPHANE ALFARO,² JORGE VALDÉS,⁴ AND GABRIEL VARGAS¹

¹Departamento de Geología, Facultad de Ciencias Físicas y Matemáticas, Universidad de Chile, Plaza Ercilla 803, Santiago, Chile

²LISA, UMR CNRS/INSU 7583, Universités de Paris-Est Créteil et Paris-Diderot, 61 avenue du Général de Gaulle, Créteil, France

³IPSL/LOCEAN, UPMC/CNRS/IRD/MNHN, Centre IRD France Nord, 32 avenue Henri Varagnat, 93143 Bondy CEDEX, France

⁴Laboratorio de Sedimentología y Paleoambientes (LASPAL), Instituto de Ciencias Naturales Alexander von Humboldt, Facultad de Ciencias del Mar y de Recursos Biológicos, Universidad de Antofagasta, Laboratorio Mixto Internacional PALEOTRACES, IRD-UA-UFF, Avenida Universidad de Antofagasta s/n, Antofagasta, Chile
e-mail: v.flores.a@gmail.com

ABSTRACT: The aim of this study was to determine the size distribution and flux of the mineral fraction collected in marine sediment traps in Mejillones Bay (23° S) using image-based size analysis. In this bay the material settling in the water column is a mixture of biogenic particles and lithic grains. The sediments analyzed correspond to four samples collected in the austral spring of 2008. We used image-based size analysis because it presents several advantages, which makes it an ideal method to study fine marine sediments. This analysis also yielded important information about the aspect and the morphology of the particles. In order to analyze the lithic fraction only, different pretreatments were applied and size—analyses were carried out with and without image information. Besides the main lithic components (quartz, feldspar, amphiboles, and micas), some nonlithic particles corresponding mainly to organic-matter remains were observed in the images, showing that the pretreatment was not fully effective. Biogenic silica and unexpected dark particles of probable anthropogenic origin were also detected. To avoid the influence of nonlithic grains in the analysis, the images were filtered based on the aspect of the particles using various discrimination tools. Before and after this removal, the size distributions of the samples were estimated and used to calculate the total flux. As compared to the flux of lithic particles, this total flux displays a systematic overestimation of up to 12%. As a consequence, using image-based size analysis allows not only enhancing the determination of the size distribution and flux but also controlling and improving the pretreatments protocols.

INTRODUCTION

The assessment of particulate-matter size distributions based on image analysis is an underutilized tool in environmental disciplines, despite its great potential for characterizing such fine material as marine or lacustrine sediments, ashes, loess, and particles of eolian origin (e.g., Frančičković-Bilinski et al. 2003; Buurman et al. 2001). Conventional methods, using the measurement of sedimentation velocities in water, such as the settling methods based on Stokes' law have several drawbacks. Their results depend on the laboratory technique, and even on the operator. They are also time-consuming, have a limited size-resolution capacity, and require large amounts of material (10–20 g for the pipette method and 40 g for the hydrometer; Eshel et al. 2004). In contrast, size measurements based on image analysis are fast, precise and replicable, allow the analysis of very small samples (< 1 mg), and provide a very good size resolution.

Comparisons of the results provided by classical methods with those of more recent technologies (laser diffraction, hydrophotometer, Coulter counter, etc.) indicate that differences may be attributable mostly to the morphology and mineralogical composition of the particles (e.g., Beuselinck et al. 1998; Eshel et al. 2004; Frančičković-Bilinski et al. 2003; Konert and Vanderbergh 1997). Indeed, because classical methods assume that the particles are spherical and have a uniform mass density equal to quartz, settling methods yield equivalent diameters. For prolate

particles, or for mixtures of particles with different densities, these equivalent-sphere size distributions can hardly be considered as representative of the actual size distributions. Discrepancies between idealized and real size distributions can be even greater when significant interparticle morphological differences are involved. Indeed, nonspherical particles tend to sediment with their largest section perpendicular to the direction of their fall (Krumbein 1942), which increases the resistance of the fluid to their movement, reduces their falling velocity (Matthews 1991), and eventually leads to an overestimation of their size. This bias does not occur for results derived from image analysis. On the contrary, analyses based on images can provide important information on the morphology of particles, and therefore about their genesis, subsequent transport, and depositional processes.

This study presents the results of the analyses performed on particles collected in marine sediment traps installed in the Mejillones Bay (23° S) (Fig. 1), which is located near an important upwelling center of the coastal Atacama Desert of northern Chile (Rodríguez et al. 1991; Ruttant et al. 1998; Marín and Olivares 1999; Marín et al. 2003). We focused on the determination of the characteristics of the mineral particles, the objective being to characterize their size distribution and quantify the flux of wind-transported particles being deposited at the sea surface. To do that, pretreatments were applied to the samples in order to remove the nonlithic particles. After this, a size analysis based on images was used in two ways. For the first approach the images displayed by the

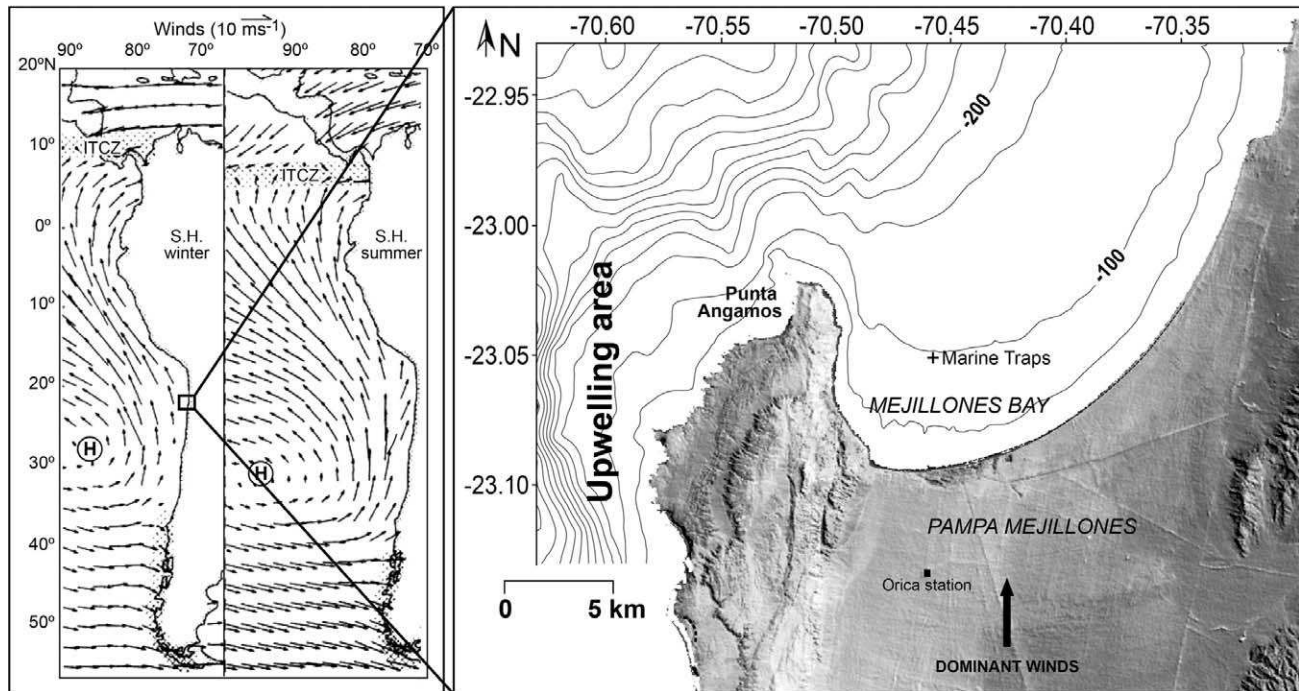


FIG. 1.—Location of the experimental site. Left panel: The subtropical anticyclone (H) and associated surface winds over the southeast Pacific (modified from Strub et al. 1998) (S.H.: Southern Hemisphere). Right panel: Map of the Mejillones Peninsula on which the location of the marine trap, bathymetry, and the main geomorphological features are reported.

system are ignored and therefore results are similar to those obtained, for example, with a laser granulometer. In the second method the images are used to recognize and eliminate, if necessary, nonlithic particles. The preparation of the samples and the techniques used are explained in detail in the “Methods” section. The “Results and Discussion” section summarizes the results of the particle size distributions and flux analyses for the original pretreated series and the filtered (only lithic particles) data. The last section presents a comparison between both methodologies and highlights the implication for visualizing the particles to improve results and for adapting the protocols of the applied pretreatments.

METHODS

Study Area

Along the coast of Northern Chile, the dryness (rainfall $< 4 \text{ mm year}^{-1}$) induced by the subtropical anticyclone is enhanced by the presence of the Andes (Rutllant et al. 2003; Muñoz 2008), the cold waters of the Humboldt Current system (Strub et al. 1998), and coastal upwelling events driven all year round by southerly winds (Strub et al. 1998; Rutllant et al. 1998). In spring and summer, the high frequency of clear skies combined with the greatest influence of the anticyclone leads to an intensification of these winds along the coast (Rutllant et al. 1998, 2003). Ocean–atmosphere–land interactions are amplified around the capes and peninsulas like Punta Angamos (Rutllant et al. 1998, 2003), located at the northwesternmost point of the Mejillones Peninsula (-70.52° E , -23.04° S ; -70.40° , -23.54°) (Fig. 1), resulting in enhanced coastal upwelling and ocean productivity (primary-productivity values measured within the bay have reached $138 \text{ mg C m}^{-3} \text{ h}^{-1}$ (Rodríguez et al. 1991), while the annual production can reach 1070 g C m^{-2} (Marín et al. 1993)). The strong southerly winds also promote erosion and subsequent transport of mineral particles from the Pampa Mejillones, a flat desert surface located along the central-northern area of the peninsula, towards the homonymous bay (Fig. 1) (Flores-Aqueveque et al. 2009, 2010).

Together with the hyperaridity, this setting drives the accumulation of organic-rich biogenic marine sediments (TOC concentrations of 8.5% in the bottom of the bay (Valdés et al. 2009)) including eolian terrigenous particles on the sea floor (Vargas et al. 2004; Valdés et al. 2004), which can be used for high-resolution paleoceanographic reconstructions (Vargas et al. 2007).

Methods

Sampling and Sample Preparation.—The samples analyzed correspond to the material collected in the Mejillones Bay between September 25 and November 5, 2008, using marine sediment traps of 8:1 (length:diameter) ratio as recommended by Blomqvist and Håkansson (1981) and Bale (1998). Two identical systems were placed about 5 km from the shore ($23^\circ 03' 19'' \text{ S}$ – $70^\circ 27' 28.9'' \text{ W}$) at two different depths (27 and 70 m) under the sea surface (Fig. 1).

The traps are plastic bottles of 1 L capacity filled with water of known salinity (40 psu) in which 1 ml of HgCl_2 was added to avoid bacterial proliferation. The traps were set up and collected by scuba divers.

In order to eliminate salt, the content of the bottles was washed after collection with deionized water (Wilde et al. 1970) and centrifuged at 4000 rpm for three successive cycles of 25 minutes each. After this, the samples were dried, weighed, and separated approximately in two halves; one half was used in the size-distribution analysis.

The organic matter was dissolved by subjecting the sample to the action of 40 ml of H_2O_2 (30%) solution (Kilmer and Alexander 1949). This mixture was heated at 60° C for several days until the organic matter was eliminated. After that, the sample was rinsed with deionized water following the same procedure as before.

To eliminate the residual biogenic silica (diatoms, spicules, etc.) and to avoid the dissolution of silica from clay minerals contained in the sediments, the remaining material was treated with 30 ml of a Na_2CO_3 solution (1%) and heated at 90° C for 3 hours (Conley and Schelske 2001).

TABLE 1.—Number of particles and total weight before and after pretreatments.

Sample	Particles (units)	Total Weight (μg)	Weight after Pretreatment (μg)
T2 sup	320882	59000	94.5
T2 fon	568163	54000	54.9
T1 sup	917209	74000	267.6
T1 fon	291006	52000	77.6

To homogenize the mixture and facilitate the reaction, an ultrasonic shaking was applied every 30 minutes. Finally, the samples were repeatedly washed with deionized water and centrifuged at 4000 rpm until the solution became almost neutral (pH: 6–7) again.

Grain-Size Analyses and Data Treatment.—After pretreatment, the samples were analyzed with the Sysmex FPIA3000 (Malvern Instruments, in which FPIA stands for flow particle image analyzer) automated image analysis system. This system is based on a CCD (*charge coupled device*) camera that captures images of all the particles homogeneously suspended in an aqueous solution by rotation (600 rpm) as they pass through the measurement cell. Thus, this system gives the size distribution and also displays images of the individual particles. If one ignores the images, this method provides size information comparable to that obtained with a laser granulometer and both methods can be compared to check the efficiency of the pretreatments.

After magnification ($\times 10$) the images were automatically analyzed and several geometrical aspect criteria of the individual particles were determined: width (W), length (L), elongation (L/W), perimeter (P), surface (S), convexity (C), and equivalent spherical diameter (d, defined as the diameter of the spherical particle having the same surface as the measured particle). Moreover, the optical density, or degree of blackness, was determined for every particle using the gray level on the scale of 0–256 used in the digitalization of the images (0 corresponds to pure black and 256 to pure white). As shown below, these morphological and optical parameters are essential to recognize and eliminate the particles of noneolian origin from the size distributions. Therefore, an original (nonfiltered) and a filtered (lithic particles only) size distribution can be obtained.

Due to the optical magnification, only particles with equivalent diameters between 0.5 and 200 μm can be detected by this method. The whole measurement range is divided into 225 equal logarithmical steps. A log scale was chosen because the water-suspended sediment is assumed to be a mixture of several lognormally distributed particle populations (e.g., Brun-Cottan 1986). Because the size bins selected by the manufacturer are very narrow, the number of particles counted in some of them can be limited to just a few unities and, thus, the associated relative error can be important. In order to reduce errors we divided the number of size bins by a factor of five (we use 45 instead of the 225 original ones) and grouped the number of particles counted in each class. From these number counts, the mass of particles present in each size class was determined using the spherical assumption and the mass density of quartz (2.65 g cm^{-3}). Then, we applied the iterative least-square method proposed by Gomes et al. (1990) to each mass distribution for determining the numerical characteristics (amplitude A, geometric mean diameter Gmd, and geometric standard deviation Gsd) of the individual lognormal populations whose combinations forms the overall size distribution.

Estimation of the Vertical Flux of Particles from the Size Analysis.—Each sediment trap catches the particles settling in the water column. Thus, the size-resolved decantation flux can be estimated simply by dividing the mass of the collected particles in each size bin by the surface

of the circular opening (diameter = 10.4 cm) of the trap and by the duration of the collection period. A comparison of the total (nonfiltered) and the mineral (filtered) flux was performed to quantify the effectiveness of the pretreatments. In each case, the deconvolution procedure of Gomes et al. (1990) was also applied to the size-resolved fluxes for assessing the contribution of each individual particle population to the overall decantation flux.

RESULTS AND DISCUSSION

Characteristics of the Original Samples

In all the analyzed samples, the number of particles counted lies between 291,006 and 917,209 (Table 1). Although particles as large as 160.0 μm were occasionally observed, the number of particles larger than 100.0 μm usually amounts to a few units only. After taking into account that only a half of the original sample was analyzed, the conversion into mass of the number counts yields values of the total mass ranging between 54.9 and 267.6 μg (Table 1). We used image analysis to check the efficiency of the pretreatments. As expected, most of the particles ($> 58\%$) in each size class display the features typical of mineral grains. The main mineral species found were quartz and feldspar (Fig. 2A, B), amphiboles (Fig. 2C), and micas (Fig. 2D). This mineralogical composition is similar to the erodible fraction of the desert soils, and to the eolian particles moving across the pampa (Flores-Aqueveque et al. 2010).

Nonlithic particles can be sorted into three different categories: 1) particles of irregular aspect characteristic of organic matter (Fig. 2E), 2) very dark particles (Fig. 2F) probably of anthropogenic origin and produced by industrial activities (Valdés et al. 2004), and 3) non-dissolved diatoms (Fig. 2G) or other biogenic particles with a more elongated morphology (Fig. 2H, I). These nonlithic particles can be removed from the initial size distribution using various criteria based on the aspect of the particles as detailed in the following section.

Removal of Nonmineral Particles

The organic matter (Fig. 2E) was eliminated using the convexity (C) criterion. This parameter measures the surface roughness of the particle. It is calculated as the ratio of the area of the particle (A) to the area contained inside an imaginary ribbon tied around it (A + B):

$$C = A / (A + B) \quad (1)$$

C has values between 0 and 1, and increases with the convexity of the particle. In practice, we decided to eliminate particles with $C < 0.8$ on the basis of the examination of many individual particles of organic matter. The number of particles removed varies between 1 and 710 (Table 2). All these particles have diameters between 2.2 and 95.2 μm and represent from 0.04 to 33.2% of the original mass of the samples (Table 2).

The dark particles, i.e., those with the lowest intensity (Fig. 2F), were eliminated using the color criterion. The software calculates the mean “intensity” (I) of each photographed particle as the average of all the gray-scale values of its different pixels. After observing many particles, a threshold value of $I = 50$ was chosen to eliminate selectively the anthropogenic particles. This type of grain covers a larger range of diameters and was present in the four size modes defined previously. On average, it represents about $13.8 \pm 6.6\%$ of the total mass (Table 2).

The particles recognized as biogenic silica (diatom fragments, spicules, etc.) (Fig. 2G, H, I) differ from the lithic ones by their more elongated (prolate) shape. Thus, these particles were eliminated on the basis of their width/length (W/L) ratio. The numerical threshold of elimination was arbitrarily fixed at $W/L < 0.3$. The observation of the images of the removed particles revealed that together with nonlithic material some amphiboles had also been discarded by the automated procedure. These mineral particles were reintegrated manually into the size distribution.

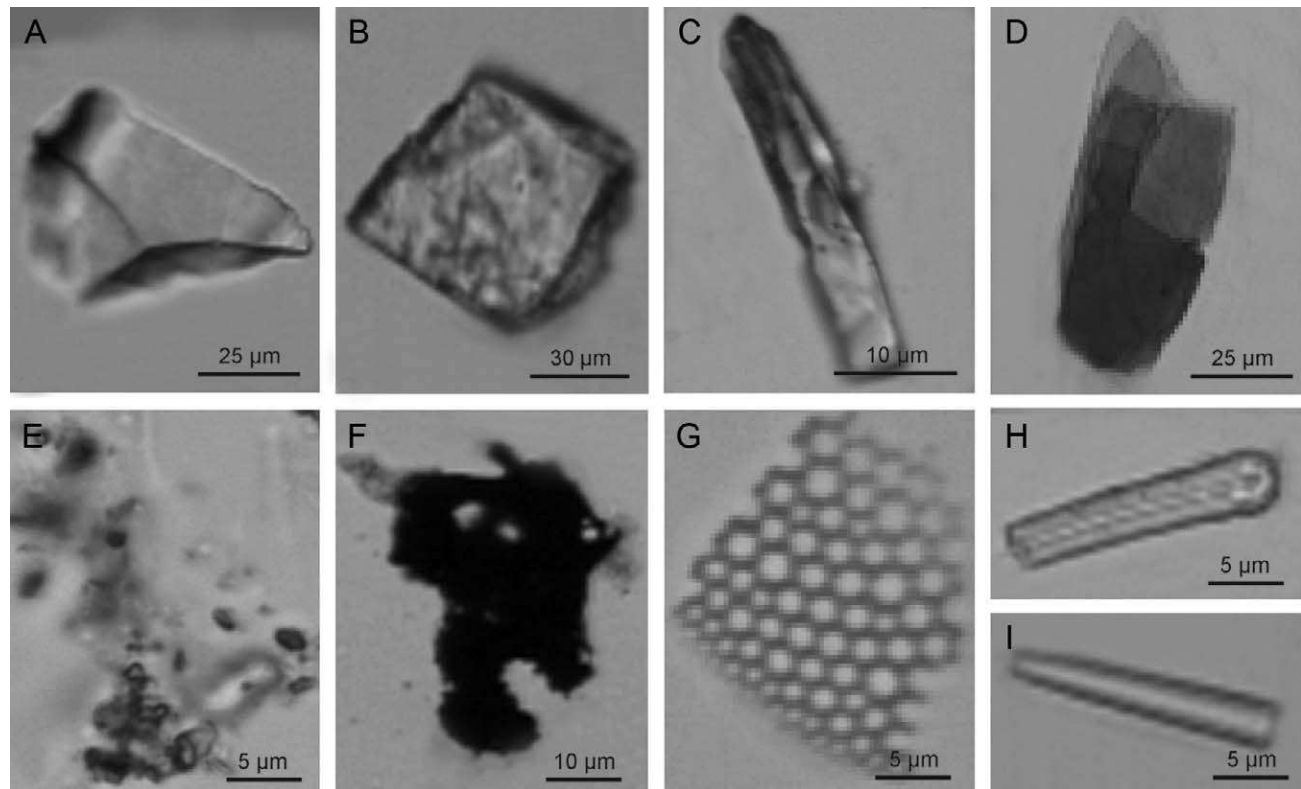


FIG. 2.—Examples of the various types and sizes of particles found in the analyzed samples. Photos A–D correspond to mineral particles. **A, B)** Quartz with equivalent diameters of 72 and 101 μm , respectively. **C)** Amphibole, 117 μm . **D)** Mica, 99 μm . **E)** Organic matter (32 μm). **F)** Dark particles (41 μm) of anthropogenic origin. **G–I)** fragments of biogenic silica with diameters of 22, 2.5, and 2.0 μm , respectively.

The particles eliminated using the W/L criterion have equivalent diameters between 0.5 and 57.5 μm . They represent less than 1.7% of the initial mass of particles (Table 2).

In summary, the three types of nonmineral particles constituted between < 0.1 and 33.2% of the initial mass of the samples (Table 2). In this fraction, the presence of the organic matter was much larger than the biogenic silica (33.2% versus 1.7%), indicating that the pretreatment used to remove organic matter was less effective than the one used to eliminate spicules and diatoms. The lack of application of a special treatment to remove the dark anthropogenic particles explains why their contribution to the total mass amounts to between 7.9 and 19.9%, which makes it a significant component of the original samples.

These results corroborate that our method presents additional advantages as compared to other types of image-based size analyses

(e.g., Beuselinck et al. 1998; Eshel et al. 2004; Frančišković-Bilinski et al. 2003; Konert and Vandenberghe 1997; Lira and Pina 2007; Vaasma 2008). The visual recognition tool and the possibility of eliminating nonlithic particles manually greatly improve the accuracy of the size-distribution assessments.

Size Distribution and Sedimentation Fluxes

Original Nonfiltered Data.—For determining the main modes and their characteristics, the size distributions of the original (nonfiltered) data were analyzed with the deconvolution method of Gomes et al. (1990). All samples are represented by a mixture of at least four main modes, two very fine ones and two significantly coarser. The finest mode (Mode 1, Table 3) is centered at 2.0 μm . Its amplitude varies between 1.4 and 6.1 μg ,

TABLE 2.—Amount, size-ranges and mass (total and%) of the 3 types of nonlithic particles not removed by the pre-treatments intended to eliminate them from the collected samples. Identification of these particles was based on morphological characteristics of the individual particles (see text for details).

Sample	Nonlithic Particles											
	Organic Matter				Dark Particles				SiO ₂ Biogenic			
	N° Particles	Size-range	Total Mass (μg)	%	N° Particles	Size-range	Total Mass (μg)	%	N° Particles	Size-range	Total Mass (μg)	%
T2sup	97	4.9–43.0	0.47	0.5	13	21.0–97.8	7.42	7.9	2108	0.5–30.5	0.21	0.2
T2fon	1	20.5–22.8	0.02	0.04	35	13.8–124.1	10.95	19.9	4872	0.5–57.5	0.95	1.7
T1sup	51	7.3–77.0	3.58	1.3	60	11.4–138.0	50.95	19.1	6967	0.5–33.0	0.89	0.3
T1fon	710	2.2–95.2	25.78	33.2	2	28.1–124.1	6.61	8.5	2854	0.5–39.7	0.33	0.4
Mean	215		7.46	8.8	28		18.98	13.8	4200		0.60	0.7
S.D.	332		12.31	16.3	26		21.39	6.6	2183		0.38	0.7

TABLE 3.—Parameters (geometric mean diameter (Gmd), geometric standard deviation (Gsd) and amplitude (A)) of the 4 lognormal modes of the original (nonfiltered) samples, whose combination best fits the measured size distributions.

Sample	Mode 1			Mode 2			Mode 3			Mode 4		
	Gmd (μm)	A (μg)	Gsd	Gmd (μm)	A (μg)	Gsd	Gmd (μm)	A (μg)	Gsd	Gmd (μm)	A (μg)	Gsd
T2sup	2.0	1.4	1.5	8.0	7.2	2.0	33.0	8.5	1.4	72.0	60.9	1.4
T2fon	2.0	5.1	1.5	12.0	18.2	2.0	33.0	7.4	1.4	95.0	25.3	1.4
T1sup	2.0	6.1	1.5	10.0	18.3	2.0	42.0	44.8	1.4	120.0	221.0	1.4
T1fon	2.0	1.4	1.5	10.0	11.2	2.0	37.0	10.7	1.4	83.0	56.3	1.4

and its Gsd is equal to 1.5 μm in all cases. The second fine mode (Mode 2, Table 3) has a Gmd in the 8.0–12.0 μm range and a more important amplitude ($A = 7.2$ – $18.3 \mu\text{g}$) than Mode 1. Its Gsd is also larger ($= 2.0 \mu\text{m}$) than Mode 1. Mode 3 (Table 3) is much coarser and narrower than the previous modes, with diameters between 33.0 and 42.0 μm , and $Gsd = 1.4 \mu\text{m}$ in all cases. Its amplitude is also quite variable, with values between 7.4 and 44.8 μg . The coarsest mode (Mode 4, Table 3) is between 70.0 and 120.0 μm . It is the most important mode in terms of mass, with amplitudes between 25.3 and 221.0 μg . In all the cases the standard deviation is $Gsd = 1.4 \mu\text{m}$. It should be noted that the largest diameter value (120.0 μm) of this mode was obtained only in the superficial trap during the second sampling period (T1sup). It presents the largest mass of the collected particles. However, this giant mode corresponds to only 20 particles with diameters above 100.0 μm . Note that “giant” particles were present in all samples, but usually in a very limited amount (< 3 units).

The calculated total flux of particles ranged between 364.9 and 1260.2 $\mu\text{g day}^{-1} \text{m}^{-2}$, with the larger values achieved in the traps closest to the surface (Table 4). For the upper trap, the difference between the two sampling periods (45%) is larger than the one (10%) observed in the lower trap (Table 4).

The average contributions of Modes 1 and 2 to the overall flux are the lowest (20.8 ± 14.5 and $81.5 \pm 38.2 \mu\text{g day}^{-1} \text{m}^{-2}$, respectively). For these two modes, the variability is about 70% and 47%, respectively. The contribution of the two coarse modes is more important and also more variable than the fine modes. The individual flux of Mode 3 ranged between 50.4 and 210.7 $\mu\text{g day}^{-1} \text{m}^{-2}$ with a variability of 82%, whereas Mode 4 contributed between 185.9 and 1040.4 $\mu\text{g day}^{-1} \text{m}^{-2}$ to the total flux with a variability of 80% (Table 4).

Comparison of the original flux with the one obtained adding the contributions of each individual mode shows that the deconvolution method largely reproduces the original size distribution. However, in most cases a slight (between 2% and 8%) overestimation of the total flux is observed.

Lithic Particles.—The fitting method of Gomes et al. (1990) was applied again to the size distributions cleansed of their nonmineral fraction. Figure 3 illustrates an example of the deconvolution procedure applied to the size distributions measured for the samples collected at 27 m

TABLE 4.—Values of the sedimentation fluxes for the 4 individual lithic-particle modes of nonfiltered samples.

Sample	Fluxes ($\mu\text{g day}^{-1} \text{m}^{-2}$)				Total Modes	Total Original
	Mode 1	Mode 2	Mode 3	Mode 4		
T2sup	10.6	53.2	62.6	448.2	574.6	695.2
T2fon	37.3	133.7	54.1	185.9	410.9	404.1
T1sup	28.6	86.3	210.7	1040.4	1366.1	1260.2
T1fon	6.7	52.8	50.4	265.1	375.1	364.9
Mean	20.8	81.5	94.5	484.9		
S.D.	14.5	38.2	77.7	386.3		
% S.D.	70%	47%	82%	80%		

and 70 m below sea level between October 10 and November 5, 2008 (T1sup and T1fon). In these two cases as well as in the others not represented in Figure 3, the measured size distributions can be represented by a mixture of at most four lognormally distributed populations of particles whose parameters are reported in Table 5. The finest mode is characterized by a geometric mean diameter (Gmd) of 2.0 μm (Mode 1) and presents a relatively narrow geometric standard deviation ($Gsd = 1.5 \mu\text{m}$). The mass of particles of this mode varies between 0.9 and 6.0 μg . The second-finest mode has a Gmd between 7.0 and 11.0 μm (Mode 2) and is broader than mode 1 ($Gsd = 2.0 \mu\text{m}$). It represents a mass of particles between 7.1 and 21.1 μg . The third mode, which has a Gmd between 30.0 and 50.0 μm (Mode 3), is also present in all samples. The corresponding mass varies between 6.2 and 44.3 μg . Finally, the coarsest mode (Mode 4) presents diameters in the 70.0–120.0 μm range, with masses between 14.6 and 151.1 μg . As was the case with the original (nonfiltered) size distribution, the larger particles (120.0 μm) of Mode 4 are obtained only in the T1sup sample. After removal of nonlithic particles, the amount of this giant mode decreases to 14 particles.

The sedimentation fluxes calculated (in $\mu\text{g day}^{-1} \text{m}^{-2}$) for each mode are presented in Table 6. Comparing the results obtained at the two depths shows that the flux of particles for modes 1 and 2 is relatively independent of depth. Their average values are 17.8 ± 12.3 and $79.4 \pm 42.2 \mu\text{g day}^{-1} \text{m}^{-2}$, respectively, with a variability of 69% (given by the standard deviation) for mode 1 and 53% for mode 2. These values are lower than the ones obtained for mode 3 (variability of 93% for an average of $87.3 \mu\text{g day}^{-1} \text{m}^{-2}$) and for mode 4 (variability of 82% for an average of $342.1 \mu\text{g day}^{-1} \text{m}^{-2}$).

This gives a total flux between 508.8 and 1047.6 $\mu\text{g day}^{-1} \text{m}^{-2}$ for the upper trap, and between 237.2 and 313.3 $\mu\text{g day}^{-1} \text{m}^{-2}$ for the lower one. These results are consistent with the decrease of the particle flux with depth mentioned by Pace et al. (1987) and Buesseler et al. (2007). As observed in Table 6, the flux of particles accumulated in the upper trap during the second period is more than 50% larger than the one accumulated during the first period. In the lower trap, the difference between the two periods is only around 24%. This difference could be due to the limited settling velocities of the particles in the water column. The particles falling into the bay will reach the upper trap relatively rapidly but the trap farther from the surface only after a delay. Similarly, the largest variability observed in the flux of the coarser modes ($> 30.0 \mu\text{m}$) can probably be explained by their large settling velocity and their short residence time in the water column. As a consequence of this, their concentrations are thought to be more closely linked to, and reflect better, the sporadic inputs of desert dust from the pampa than the sources for the finest particles (Mode 1 and Mode 2). Both observations agree with Siegel et al. (1990), whose analyses showed that large, rapidly sinking particles would be more representative of local conditions than the smaller, slowly sinking grains, which could be averaged over greater distances from the sampling site.

In this case also, comparison of the original fluxes with those estimated from the sum of the contributions of the individual modes indicates that the deconvolution method fits the filtered size distribution relatively well, since it underestimates by only 1% and 19% the fluxes of the first period (T2sup and T2fon; Sept. 25 to Oct. 10, 2008), and overestimates the fluxes

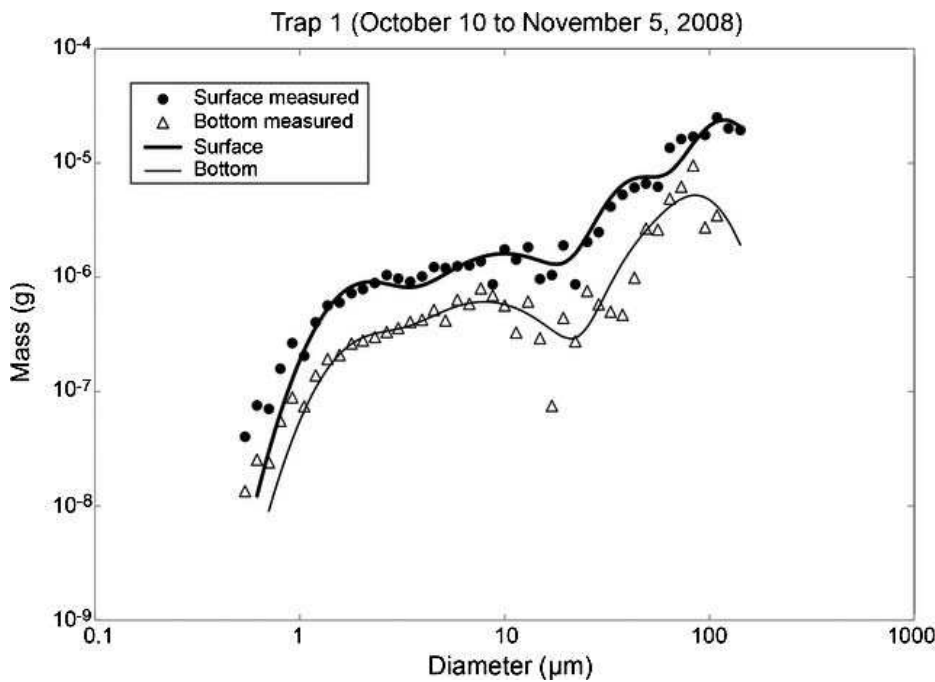


FIG. 3.—Deconvolution results of the measured size distribution for the lithic fraction of the samples collected during Oct. 10 and Nov. 5, 2008.

of the second period (T1sup and T1fon; Oct. 10 to Nov. 5, 2008) by only 5% and 12%, respectively.

CONCLUSION

By comparing the results of both methods it can be observed that after removal of the nonlithic particles the particle modes remain in the same size ranges, especially the two finest modes. In general, filtering of the size distributions leads to a decrease in the mass (amplitude) of the size modes. This decrease, which is more significant in the case of the two coarse modes, is particularly remarkable for Mode 4. In this case, the lowering of the contribution is directly due to the elimination of the anthropogenic dark particles, whereas in the case of Mode 3 this decrease is associated with the combined removals of the dark particles and of the organic matter. Despite its frequent occurrence, the presence of residues of biogenic silica (2108 to 6967 units; Table 2) does not seem to modify the size distribution importantly because of their very fine diameters and, consequently, low mass.

The estimated fluxes are also influenced by the changes in the amplitude of the size modes resulting from the filtering. A decrease was observed in most of the cases, indicating that, with values between 13% and 58% above the corrected ones, use of nonfiltered size distributions generally leads to an important overestimation of the fluxes. This overestimation is also due to the assumption that all particles have the same density (i.e., quartz), which in the case of nonlithic particles might constitute a gross overestimation.

These results also indicate that some of the pretreatments used to remove nonlithic particles are not as efficient as expected. Analysis of the content of the original samples in nonlithic particles shows that the occurrence of biogenic silica is low, almost systematic, and roughly constant (0.7% of variation) in all the samples. Thus, their presence could be properly predicted and estimated for this type of sample. In contrast, the large variability (16.3%) of the content of residual organic matter not only evidences the low efficiency of the protocols, which should be reviewed and modified, but it also excludes the possibility of using a systematic correction of the fluxes derived from the nonfiltered size distributions. Finally, the observation of dark particles in the samples was unexpected. For lack of an appropriate chemical removal treatment, imaging is the only practical way available for discriminating these dark particles from the lithic ones. Therefore, image-based size analysis seems to be an accurate technique allowing determination of the size distribution and flux of this type of fine sediments. More generally, it is a powerful tool for: 1) controlling, adapting, and improving the removal protocols of biogenic silica and organic matter, 2) recognizing unexpected particles which cannot be pretreated, and 3) correcting the particulate-matter size distribution of the presence of these particles.

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TABLE 5.—Parameters (geometric mean diameter (Gmd), geometric standard deviation (Gsd) and amplitude (A)) of the 4 lognormal modes of the lithic fraction of the samples, whose combination best fits the measured size distributions.

Sample	Mode 1			Mode 2			Mode 3			Mode 4		
	Gmd (µm)	A (µg)	Gsd	Gmd (µm)	A (µg)	Gsd	Gmd (µm)	A (µg)	Gsd	Gmd (µm)	A (µg)	Gsd
T2sup	2.0	0.9	1.5	7.0	7.1	2.0	30.0	6.2	1.4	70.0	54.9	1.4
T2fon	2.0	3.9	1.5	11.0	17.5	2.0	30.0	6.5	1.4	90.0	14.6	1.4
T1sup	2.0	6.0	1.5	10.0	21.1	2.0	45.0	44.3	1.4	120.0	151.1	1.4
T1fon	2.0	1.6	1.5	8.0	8.0	2.0	50.0	9.9	1.4	90.0	30.9	1.4

TABLE 6.—Values of the sedimentation fluxes for the 4 individual lithic-particle modes of the lithic fraction.

Sample	Fluxes ($\mu\text{g day}^{-1} \text{m}^{-2}$)				Total Modes	Total Lithic
	Mode 1	Mode 2	Mode 3	Mode 4		
T2sup	6.7	52.1	45.9	404.1	508.8	630.5
T2fon	28.6	128.9	48.1	107.7	313.3	316.4
T1sup	28.4	99.1	208.5	711.6	1047.6	998.2
T1fon	7.6	37.6	46.7	145.3	237.2	211.4
Mean	17.8	79.4	87.3	342.1	526.7	
S.D.	12.3	42.2	80.8	279.3	365.6	
% S.D.	69%	53%	93%	82%	69%	

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