



UDC 528.23

SPHEROIDAL SPLINE INTERPOLATION AND ITS APPLICATION IN GEODESY

Mostafa KIANI¹, Nabi CHEGINI^{2*}, Abdolreza SAFARI¹, Borzoo NAZARI¹¹*School of Surveying and Geospatial Engineering, University of Tehran, Tehran, Iran*²*Department of Mathematics, Tafresh University, Tafresh 39518-79611, Iran*

Received 07 October 2019; accepted 15 September 2020

Abstract. The aim of this paper is to study the spline interpolation problem in spheroidal geometry. We follow the minimization of the norm of the iterated Beltrami-Laplace and consecutive iterated Helmholtz operators for all functions belonging to an appropriate Hilbert space defined on the spheroid. By exploiting surface Green's functions, reproducing kernels for discrete Dirichlet and Neumann conditions are constructed in the spheroidal geometry. According to a complete system of surface spheroidal harmonics, generalized Green's functions are also defined. Based on the minimization problem and corresponding reproducing kernel, spline interpolant which minimizes the desired norm and satisfies the given discrete conditions is defined on the spheroidal surface. The application of the results in Geodesy is explained in the gravity data interpolation over the globe.

Keywords: spheroid, discrete Dirichlet and Neumann conditions, norm minimization, spline interpolation, Green's function, gravity data interpolation.

Introduction

This paper is concerned with finding a minimizer of the applied specific operator, which is either the iterated Beltrami-Laplace or consecutive iterated Helmholtz, to the particular Hilbert space in the sense of norm on a smooth manifold. The minimizer satisfies the Dirichlet or Neumann conditions at given points of the manifold.

The applications of this problem are in a number of fields in mathematical physics and engineering, e.g., Earth's gravity field and linear elasticity theory. The solution of the minimization problem has physical interpretation. For instance, in elasticity theory it means minimizing the bending energy of a thin layer.

In order to solve the minimization problem, spline interpolation approach is considered. Based on what the domain is and which boundary conditions are used, different problems of finding spline interpolant must be solved.

In the spherical domain, the spline interpolation has been investigated in a number of different studies including Freeden et al. (2018), Freeden (1981), Keller and Borkowski (2019), Sloan and Womersley (2002), Baramidze et al. (2006), and Wahba (1981, 1990). In Freeden et al. (2018), spherical splines and zonal kernels are defined in the context of Sobolev and reproducing kernel

Hilbert spaces. In Freeden and Gutting (2013), spherical spline approximation of discrete boundary value problems is defined for a smooth or regular surface. In Freeden and Gutting (2018), spline interpolation and exact integration for the Beltrami-Laplace operator are discussed on the spherical surface. In Freeden et al. (1998), a complete discussion of the spherical splines, Green's functions for the iterated Beltrami-Laplace and consecutive iterated Helmholtz operators, pseudo-differential operators, and radial basis functions (RBFs) are presented. The theory of spline functions through distribution theory, surface Green's functions for the consecutive iterated Helmholtz operator and their existence, uniqueness and computational procedures are presented in Freeden (1984) and Freeden (1981). Based on Green's function, spline functions and zonal kernels are introduced in Freeden and Schreiner (2009).

The principle of employing the least squares 2D bi-cubic spline approximation method to estimate a smoothed surface of a 2D data set are presented in Amiri-Simkooei et al. (2018). Thin plate splines and their applications in Geodesy are studied in Keller and Borkowski (2019) in the context of a reproducing kernel Sobolev space. The local spherical thin plate splines are also derived and compared with the global spherical splines. The applications

*Corresponding author. E-mail: nabichegini@tafreshu.ac.ir

in interpolating the GRACE satellites' positions in their ground-track repeat orbit and the Total Electron Content (TEC) in the ionosphere are presented. In Klees et al. (2008), the concept of RBFs is employed to locally interpolate gravity data. Several types of spherical RBFs are introduced and implemented to interpolate residual gravity anomalies using GPS-Leveling data. In Sloan and Womersley (2002), the data interpolation in Geodesy is discussed by the concepts of minimum energy. Spherical harmonics are taken as the fundamental bases and the weight coefficients. Spherical interpolating and smoothing splines for a set of linearly independent evaluation functionals are discussed in Wahba (1981). Moreover, reproducing kernels are given in an analytic integral representation.

We are motivated by the minimization problem for data interpolation on the surface of a spheroid. Physical explanation for the importance of spheroidal surface can be observed in the interpolation of gravity data in Earth's gravity field, with its geometry being better defined with a spheroid. Earth is impacted by a number of different (inner and outer) forces, which make its shape irregular. To approximate this rough surface, we can use a sphere. However, observations have confirmed the spheroidal shape of the Earth. So, having a mathematical framework for interpolation on this special surface is highly needed. Although many works have been done on the spherical (spline) interpolation, there is little done on the spheroidal case. An important work for outer spheroidal spline, namely, Abel-Poisson kernel spline, has been done in Akhtar and Michel (2012); However, the case where data are on the surface of spheroid is fundamentally different and is investigated in the present paper.

This paper is organized as follows. Preliminaries and minimization problems are stated in Section 1. Section 2 is devoted to the surface Green's functions approach for Dirichlet and Neumann conditions at the given points of the spheroid. This section is ended with finding the iterated and consecutive iterated surface Green's functions. The definition of spline interpolant is developed in Section 3. Application of spheroidal spline interpolation for Gravity Data in Geodesy are presented in Section 4. At the end, conclusions are stated. In Appendix A, the eigenvalues and eigenfunctions of the Beltrami-Laplace equation are derived. Finally, the approximate formula for iterated Green's function is given in Appendix B.

1. Preliminaries and minimization problem

Similar to a sphere, an oblate spheroid is a surface of revolution with genus zero. Because of the inequality of its axes, it acquires a special geometry different from a sphere. Several important operators and definitions that are used frequently in the paper are given in the following.

Definition 1.1. Let a and b be the semi-major and semi-minor axes of the oblate spheroid, respectively. The eccentricity of the corresponding oblate spheroid is defined by

$$e^2 = \frac{a^2 - b^2}{a^2}.$$

Let θ and λ be the co-latitude and the longitude, respectively. The oblate spheroidal coordinate system is defined as

$$(x, y, z) = (a \sin \theta \cos \lambda, a \sin \theta \sin \lambda, a \sqrt{1 - e^2} \cos \theta). \quad (1)$$

Remark 1.1. The second eccentricity is defined by $e'^2 = \frac{e^2}{1 - e^2}$. The prolate spheroidal coordinate system is defined when e^2 is replaced by e'^2 in the oblate spheroidal coordinates (1).

Definition 1.2. On a differentiable manifold of dimension n , the iterated Beltrami-Laplace operator is defined by

$$\Delta_B^v = \frac{1}{\sqrt{g}} \partial_{i_v j_v} \left(\frac{\sqrt{g}}{g_{i_v j_v}} \partial^{i_v j_v} \left(\dots \left(\frac{1}{\sqrt{g}} \partial_{i_1 j_1} \left(\frac{\sqrt{g}}{g_{i_1 j_1}} \partial^{i_1 j_1} \right) \right) \dots \right) \right), \quad (2)$$

where, for $i, j = 1, 2, \dots, n$, g_{ij} and g are the elements and determinant of a metric tensor, respectively.

For the case $v = 1$ in (2), the operator Δ_B is called the Beltrami-Laplace operator. This operator in spheroidal coordinates (θ, λ) is represented by

$$\Delta_B = \frac{1}{a^2 (1 - e^2 \sin^2 \theta)} \frac{\partial^2}{\partial \theta^2} + \frac{\cot \theta}{a^2 (1 - e^2 \sin^2 \theta)^2} \frac{\partial}{\partial \theta} + \frac{1}{a^2 \sin^2 \theta} \frac{\partial^2}{\partial \lambda^2}. \quad (3)$$

The i -th Helmholtz operator is defined as sum of the Beltrami-Laplace operator and the negative of its i -th eigenvalue p_i , namely,

$$\Delta_{H_i} = \frac{1}{a^2 (1 - e^2 \sin^2 \theta)} \frac{\partial^2}{\partial \theta^2} + \frac{\cot \theta}{a^2 (1 - e^2 \sin^2 \theta)^2} \frac{\partial}{\partial \theta} + \frac{1}{a^2 \sin^2 \theta} \frac{\partial^2}{\partial \lambda^2} - p_i. \quad (4)$$

The consecutive iterated Helmholtz operator of degree v , with its i -th element acting q_i times, is defined as

$$\Delta_{H_C} = \Delta_{H_0}^{q_1} \dots \Delta_{H_v}^{q_v}. \quad (5)$$

Definition 1.3. Let us denote \mathcal{E} as the surface of a spheroid. The Hilbert space of all infinitely differentiable functions for the operator \mathcal{L} of the form (2), (4) and (5) is defined as

$$H(\mathcal{E}) = \{F | F \in C^\infty(\mathcal{E}) \text{ and } \mathcal{L}F \in L^2(\mathcal{E})\}.$$

Definition 1.4. Under particular interpolation conditions, the function $S \in H(\mathcal{E})$ is called a spline interpolant when it is the solution of one of the following problems

- Minimization problem of the iterated Beltrami-Laplace operator

$$S = \arg \min_{f \in H(\mathcal{E})} \|\Delta_B^\nu f\|_{L^2(\mathcal{E})}. \quad (6)$$

- Minimization problem of the consecutive iterated Helmholtz operator

$$S = \arg \min_{f \in H(\mathcal{E})} \|\Delta_{H_0}^{q_1} \cdots \Delta_{H_v}^{q_v} f\|_{L^2(\mathcal{E})}. \quad (7)$$

As an interpolation problem, the following set of J distinct points

$$\mathcal{D} = \{\eta_1, \dots, \eta_J\} \subset \mathcal{E},$$

is given such that the given functionals applied to S at points $\eta_1, \eta_2, \dots, \eta_J$ are known real values U_1, U_2, \dots, U_J , respectively. In this paper, the given functionals for the minimization problems (6) and (7), are either of the following cases

- discrete Dirichlet condition at \mathcal{D} , namely,

$$S(\eta_i) = U_i, i = 1, \dots, J, \quad (8)$$

- discrete Neumann condition at \mathcal{D} , namely,

$$\frac{\partial S}{\partial \mathbf{n}}(\eta_i) = U_i, i = 1, \dots, J,$$

where \mathbf{n} is outward normal vector to \mathcal{E} .

Remark 1.2. The existence and uniqueness of the solutions of problems (6) and (7) are guaranteed (for more details, see Freedon, 1981).

Definition 1.5. With homogeneous discrete Dirichlet and Neumann conditions at \mathcal{D} , the following Hilbert spaces are defined

$$H_0^D(\mathcal{E}) = \{F \in H(\mathcal{E}) \mid F(\eta_i) = 0, i = 1, \dots, J\}, \quad (9)$$

$$H_0^N(\mathcal{E}) = \{F \in H(\mathcal{E}) \mid \frac{\partial F}{\partial \mathbf{n}}(\eta_i) = 0, i = 1, \dots, J\}.$$

Remark 1.3. The space $H(\mathcal{E})$ is of key importance to define the spline interpolant. This space can be written as the direct sum of the null space of the operator and the Hilbert space $H_1^t(\mathcal{E})$ for $t = D, N$. To find the spline interpolant in the Hilbert space $H(\mathcal{E})$, the reproducing kernel in $H_1^t(\mathcal{E})$, for $t = D, N$, has to be constructed.

2. Surface Green's functions

In order to define reproducing kernels, a common approach is to find surface Green's functions (see Freedon, 1981). According to the differential operators of the form (2)–(5), the surface Green's functions are derived for discrete Dirichlet and Neumann conditions. Following the method of Green's function, described in Greenberg (2015), it can be shown that

$$\iint_{\mathcal{E}} G \Delta_B F d\sigma = \iint_{\mathcal{E}} F \Delta_B G d\sigma. \quad (10)$$

Formula (10) also holds for operators Δ_B^ν and Δ_{H_C} as operator Δ_B .

2.1. System of surface spheroidal harmonics for Green's functions

In order to derive Green's functions, one needs to have a fundamental system of surface spheroidal harmonics. As mentioned in Remark 1.3, we have the following decomposition

$$H(\mathcal{E}) = H_0^t(\mathcal{E}) \oplus \mathcal{N}_{\mathcal{L}}(\mathcal{E}),$$

where $t = D, N$, depends on the discrete Dirichlet or Neumann conditions while $\mathcal{N}_{\mathcal{L}}(\mathcal{E})$ is the null space of operator \mathcal{L} on the surface \mathcal{E} . The surface spheroidal harmonics are the solution of the homogeneous Beltrami-Laplace equation on the spheroid \mathcal{E} . This problem is solved in Appendix A.

If the solution has a zero degree eigenfunction, then the problem of finding the generalized Green's function has to be considered. The generalized Green's function is independent of the given data. Based on the definition of spline interpolant similar to Freedon (1984), Freedon and Schreiner (2009), and Wahba (1981), this type of Green's function can be exploited for both discrete Dirichlet and Neumann conditions. In the following subsections, the first Green's functions are introduced. These functions do not possess a zero order eigenfunction. With these functions, the fundamental system of surface harmonics are designed. Also the second Green's functions are created for discrete Neumann condition. It can be observed that the second Green's functions possess a zero order eigenfunction. In the case of generalized Green's functions, a set of complete orthonormal basis of surface spheroidal harmonics with a zero degree eigenfunction is formed.

2.2. First Green's function

For $\xi, \eta \in \mathcal{E}$ and \mathcal{L} in the form of (2), the function $G(\xi, \eta)$ is called the first Green's function or Green's function for Dirichlet condition, when it satisfies

$$\mathcal{L}G(\xi, \eta) = \delta(\xi - \eta), \quad (11)$$

where δ denotes the Dirac delta function. Relation (10) holds for discrete Dirichlet condition (8). From (10) and (11), it is simply concluded that

$$F(\eta) = \iint_{\mathcal{E}} G(\xi, \eta) \Delta_B F(\xi) d\xi.$$

For finding the first Green's function, a general method, proposed in Felsen and Marcuritz (1994), is considered. According to this method, a singular point is placed on the spheroid's poles $\theta = 0, \pi$. Thus the Green's function is singular at these points. Furthermore, the Green's function obeys the laws of wave propagation. For instance, the surface and its factor from which the wave crosses are indispensably important.

Proposition 2.1. Let the points ξ and η be on the spheroid \mathcal{E} , with spheroidal coordinates (θ, λ) and (θ', λ') , respectively. By setting the standard notation $\theta_{<} = \min(\theta, \theta')$ and $\theta_{>} = \max(\theta, \theta')$, the first Green's function in $H_0^D(\mathcal{E})$ is

$$G(\theta, \theta'; \lambda, \lambda') = \frac{a^2}{2\pi} e \ln \left(\left| \sqrt{2e \cos \theta_{<}} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{<}} \right| \right) + \frac{a^2}{4\pi} \ln \left(\left| \frac{\sqrt{1 - e^2 \sin^2 \theta_{<}} - \cos \theta_{<}}{\sqrt{1 - e^2 \sin^2 \theta_{<}} + \cos \theta_{<}} \right| \right) - \sum_{m=1}^{\infty} \frac{a^2}{2\pi m} u_m v_m \cos(m(\lambda - \lambda')), \quad (12)$$

where

$$u_m(\theta, \theta') = \left(\left| \sqrt{2e \cos \theta_{<}} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{<}} \right| \right)^{me} \times \left(\left| \frac{\sqrt{1 - e^2 \sin^2 \theta_{<}} - \cos \theta_{<}}{\sqrt{1 - e^2 \sin^2 \theta_{<}} + \cos \theta_{<}} \right| \right)^{\frac{m}{2}};$$

$$v_m(\theta, \theta') = \left(\left| \frac{1}{\sqrt{2e \cos \theta_{>}} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{>}}} \right| \right)^{me} \times \left(\left| \frac{\sqrt{1 - e^2 \sin^2 \theta_{>}} + \cos \theta_{>}}{\sqrt{1 - e^2 \sin^2 \theta_{>}} - \cos \theta_{>}} \right| \right)^{\frac{m}{2}}.$$

The series representation in (12) is uniformly convergent, at point $\xi = \eta$ and poles $\theta = 0, \pi$.

Proof. From (3) and (11), it can be shown that

$$\frac{1}{1 - e^2 \sin^2 \theta} \frac{\partial^2 G}{\partial \theta^2} + \frac{\cot \theta}{(1 - e^2 \sin^2 \theta)^2} \frac{\partial G}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2 G}{\partial \lambda^2} = a^2 \delta(\theta, \theta'; \lambda, \lambda'). \quad (13)$$

By splitting the Dirac delta function $\delta(\theta, \theta'; \lambda, \lambda')$ into products of two Dirac delta functions in azimuth and latitude components and dividing them by the surface factor, Equation (13) is reformulated to

$$\frac{1}{1 - e^2 \sin^2 \theta} \frac{\partial^2 G}{\partial \theta^2} + \frac{\cot \theta}{(1 - e^2 \sin^2 \theta)^2} \frac{\partial G}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2 G}{\partial \lambda^2} = a^2 \frac{\delta(\theta - \theta') \delta(\lambda - \lambda')}{\sqrt{1 - e^2 \sin^2 \theta} \sin \theta}. \quad (14)$$

To solve (14), the method of separation of variables is considered as

$$G(\theta, \theta'; \lambda, \lambda') = G_\theta(\theta, \theta') G_\lambda(\lambda, \lambda').$$

Based on the distribution theory (see details in Felsen and Marcuritz (1994)), the azimuth delta function can be written as

$$\delta(\lambda - \lambda') = \frac{1}{2\pi} \left(1 + 2 \sum_{m=1}^{\infty} \cos m(\lambda - \lambda') \right). \quad (15)$$

By substituting (15) in (14) and (13), the first green's function is expressed by the following series

$$G(\theta, \theta'; \lambda, \lambda') = a^2 G_0(\theta, \theta') + a^2 \sum_{m=1}^{\infty} G_m(\theta, \theta') \cos m(\lambda - \lambda'). \quad (16)$$

From (16) and (13), it is deduced that

$$\frac{d}{d\theta} \left(\frac{\sin \theta}{\sqrt{1 - e^2 \sin^2 \theta}} \frac{dG_0}{d\theta} \right) = \frac{1}{2\pi} \delta(\theta - \theta'). \quad (17)$$

Solving Equation (17) leads to

$$G_0(\theta) = a_0 \left(e \ln \left(\left| \sqrt{2e \cos \theta} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta} \right| \right) + \frac{1}{2} \ln \left(\left| \frac{\sqrt{1 - e^2 \sin^2 \theta} - \cos \theta}{\sqrt{1 - e^2 \sin^2 \theta} + \cos \theta} \right| \right) \right). \quad (18)$$

By integrating both sides of (17) in the interval $(\theta' - \epsilon, \theta' + \epsilon)$ and tending ϵ to zero, it is obtained that

$$\frac{dG_0}{d\theta} \Big|_+ - \frac{dG_0}{d\theta} \Big|_- = \frac{1}{2\pi} \frac{\sqrt{1 - e^2 \sin^2 \theta}}{\sin \theta}. \quad (19)$$

From Equation (19) and (18), The coefficient a_0 in (18) is

$$a_0 = \frac{1}{2\pi}.$$

To calculate G_m in (16), the following equation must be solved

$$\frac{d}{d\theta} \left(\frac{\sin \theta}{\sqrt{1 - e^2 \sin^2 \theta}} \frac{dG_m}{d\theta} \right) - m^2 \frac{\sqrt{1 - e^2 \sin^2 \theta}}{\sin \theta} G_m = \frac{1}{\pi} \delta(\theta - \theta'). \quad (20)$$

It can be shown that the Equation (20) leads to the eigenvalue problem

$$\frac{\sin \theta}{\sqrt{1 - e^2 \sin^2 \theta}} \frac{d}{d\theta} \left(\frac{\sin \theta}{\sqrt{1 - e^2 \sin^2 \theta}} \frac{dG_m}{d\theta} \right) = m^2 G_m.$$

This eigenvalue problem yields

$$\frac{\sin \theta}{\sqrt{1 - e^2 \sin^2 \theta}} \frac{dG_m}{d\theta} = \pm m G_m. \quad (21)$$

The solutions of Equation (21) for $+m$ and $-m$ are, respectively,

$$u_m(\theta, \theta') = \left(\left| \sqrt{2e \cos \theta_{<}} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{<}} \right| \right)^{me} \times \left(\left| \frac{\sqrt{1 - e^2 \sin^2 \theta_{<}} - \cos \theta_{<}}{\sqrt{1 - e^2 \sin^2 \theta_{<}} + \cos \theta_{<}} \right| \right)^{\frac{m}{2}}; \quad (22)$$

$$v_m(\theta, \theta') = \left(\frac{1}{\sqrt{2e \cos \theta_{>} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{>}}} \right)^{me} \times \left(\frac{\sqrt{1 - e^2 \sin^2 \theta_{>} + \cos \theta_{>}}{\sqrt{1 - e^2 \sin^2 \theta_{>} - \cos \theta_{>}} \right)^{\frac{m}{2}}. \tag{23}$$

Therefore, G_m can be written as

$$G_m(\theta, \theta') = a_m u_m v_m.$$

Again by performing the same task as for (19), it can be concluded that

$$\frac{dG_m}{d\theta} \Big|_+ - \frac{dG_m}{d\theta} \Big|_- = \frac{1}{\pi} \frac{\sqrt{1 - e^2 \sin^2 \theta}}{\sin \theta},$$

and then

$$a_m = -\frac{1}{2\pi m}.$$

Substituting G_0 and G_m in (16) leads to the solution given in (12). The functions

$$\frac{1}{\sqrt{2e \cos \theta_{<} + \sqrt{2} \sqrt{1 - e^2 \sin^2 \theta_{<}}},$$

$$\frac{\sqrt{1 - e^2 \sin^2 \theta_{<} + \cos \theta_{<}}{\sqrt{1 - e^2 \sin^2 \theta_{<} - \cos \theta_{<}}},$$

are, respectively, ascending and descending functions in the interval $(0, \pi)$. The choices of signs $>$ or $<$ in (22) and (23) make the series in (12) uniformly convergent.

2.3. Second Green's function

Again suppose that the operator \mathcal{L} has the form (2) with $\nu = 1$. The function $G(\xi, \eta)$ is called second Green's function or Green's function for discrete Neumann condition, when it is the solution of the following problem

$$\mathcal{L}G(\xi, \eta) = \delta(\xi - \eta) - \frac{1}{A_{\mathcal{E}}}, \tag{24}$$

where

$$A_{\mathcal{E}} = 2\pi a^2 \left(1 + \frac{1 - e^2}{2e} \ln \left(\frac{1 + e}{1 - e} \right) \right)$$

is the surface area of the spheroid \mathcal{E} . From (24) and (10), it is deduced that

$$F(\eta) = \frac{1}{A_{\mathcal{E}}} \int_{\mathcal{E}} F(\xi) d\sigma + \iint_{\mathcal{E}} G(\xi, \eta) \Delta_B F(\xi) d\sigma.$$

Remark 2.1. If the complete system of surface harmonics is chosen, then the generalized Green's function could be used for any set of linearly independent evaluation functionals (see Wahba, 1981). Therefore, the generalized Green's function under discrete Dirichlet conditions at \mathcal{D} also satisfies (24).

In the following Proposition, the second and fourth order approximate formulas are given for the second Green's function.

Proposition 2.2. The second and fourth order expansions for the second Green's function of Beltrami-Laplace operator are, respectively,

$$G(\theta, \theta'; \lambda, \lambda') \simeq \frac{a^2}{A_{\mathcal{E}}} \ln(1 - \cos \theta \cos \theta' - \sin \theta \sin \theta' \cos(\lambda - \lambda')) + \frac{a^2 \ln 2}{A_{\mathcal{E}}} - \frac{a^2 e^2}{A_{\mathcal{E}}} (\cos^2 \theta + \cos^2 \theta') - \frac{a^2}{A_{\mathcal{E}}}; \tag{25}$$

$$G(\theta, \theta'; \lambda, \lambda') \simeq \frac{a^2}{A_{\mathcal{E}}} \ln(1 - \cos \theta \cos \theta' - \sin \theta \sin \theta' \cos(\lambda - \lambda')) + \frac{a^2 \ln 2}{A_{\mathcal{E}}} - \frac{a^2 e^2}{A_{\mathcal{E}}} (\cos^2 \theta + \cos^2 \theta') - \frac{a^2 e^4}{A_{\mathcal{E}}} \left(\frac{\cos^2 \theta}{2 \cos^2 \frac{\theta}{2}} \left(\frac{1}{12} \cos \theta + \frac{1}{3} \cos^2 \theta - \frac{1}{4} \right) \right) + \left(\frac{\cos^2 \theta'}{2 \cos^2 \frac{\theta'}{2}} \left(\frac{1}{12} \cos \theta' + \frac{1}{3} \cos^2 \theta' - \frac{1}{4} \right) \right) + \frac{a^2 e^4}{A_{\mathcal{E}}} (\cos^2 \theta + \cos^2 \theta') - \frac{a^2}{A_{\mathcal{E}}}. \tag{26}$$

Proof. First of all, the following appropriate conformal mapping must be provided

$$\zeta = T(\theta) e^{i\lambda}. \tag{27}$$

With this conformal map, the spheroid is mapped to the complex plane where two-dimensional variables can be represented in a complex variable. We set $\mathcal{O}(\zeta, \tau) = G(\theta, \theta'; \lambda, \lambda')$, where $\tau = T(\theta') e^{i\lambda'}$. This means that the second Green's function is shown in the complex plane as the function $\mathcal{O}(\zeta, \tau)$. By using (27) in (24), it can be shown that

$$(1 + \zeta \bar{\zeta}) \frac{\partial^2 \mathcal{O}}{\partial \zeta \partial \bar{\zeta}} - 2e^2 \zeta \bar{\zeta} \frac{\partial^2 \mathcal{O}}{\partial \zeta \partial \bar{\zeta}} + e^2 \zeta \frac{\partial \mathcal{O}}{\partial \zeta} + e^2 \bar{\zeta}^2 \frac{\partial^2 \mathcal{O}}{\partial \bar{\zeta}^2} + e^2 \bar{\zeta} \frac{\partial \mathcal{O}}{\partial \bar{\zeta}} + e^2 \zeta^2 \frac{\partial^2 \mathcal{O}}{\partial \zeta^2} = a^2 \left(\delta(\zeta - \bar{\zeta}) - \frac{1}{A_{\mathcal{E}}} \right), \tag{28}$$

where $\bar{\zeta}$ denotes the conjugate of ζ . By using (27), it is easy to show that

$$\frac{\partial}{\partial \theta} = T'(\theta) e^{i\lambda} \frac{\partial}{\partial \zeta} + T''(\theta) e^{-i\lambda} \frac{\partial}{\partial \bar{\zeta}}; \tag{29}$$

$$\frac{\partial^2}{\partial \theta^2} = T'''(\theta) e^{i\lambda} \frac{\partial}{\partial \zeta} + T''''(\theta) e^{-i\lambda} \frac{\partial}{\partial \bar{\zeta}} + (T'(\theta) e^{i\lambda})^2 \frac{\partial^2}{\partial \zeta^2} + (T'(\theta) e^{-i\lambda})^2 \frac{\partial^2}{\partial \bar{\zeta}^2} + 2(T'(\theta))^2 \frac{\partial^2}{\partial \zeta \partial \bar{\zeta}}; \tag{30}$$

$$\frac{\partial^2}{\partial \lambda^2} = 2\zeta\bar{\zeta} \frac{\partial^2}{\partial \zeta \partial \bar{\zeta}} - \zeta \frac{\partial}{\partial \zeta} - \bar{\zeta} \frac{\partial}{\partial \bar{\zeta}} - \zeta^2 \frac{\partial^2}{\partial \zeta^2} - \bar{\zeta}^2 \frac{\partial^2}{\partial \bar{\zeta}^2}. \quad (31)$$

To have a conformal map, all terms in (28) have to be removed, except $\frac{\partial^2}{\partial \zeta \partial \bar{\zeta}}$. By using (29)–(31), the following equation is derived

$$\begin{aligned} & \frac{1}{1-e^2 \sin^2 \theta} \left((T''(\theta) e^{i\lambda} \frac{\partial G}{\partial \zeta} + T'''(\theta) e^{-i\lambda} \frac{\partial G}{\partial \bar{\zeta}} + (T'(\theta) e^{i\lambda})^2 \frac{\partial G}{\partial \zeta} + \right. \\ & \left. (T'(\theta) e^{-i\lambda})^2 \frac{\partial^2 G}{\partial \bar{\zeta}^2} 2(T'(\theta))^2 \frac{\partial G}{\partial \zeta} \right) + \\ & \frac{\cot \theta}{(1-e^2 \sin^2 \theta)^2} \left(T'(\theta) e^{i\lambda} \frac{\partial G}{\partial \zeta} + T'(\theta) e^{-i\lambda} \frac{\partial G}{\partial \bar{\zeta}} \right) + \\ & \frac{1}{1-\sin^2 \theta} \left(2\zeta\bar{\zeta} \frac{\partial^2 G}{\partial \zeta \partial \bar{\zeta}} - \zeta \frac{\partial G}{\partial \zeta} - \bar{\zeta} \frac{\partial G}{\partial \bar{\zeta}} - \zeta^2 \frac{\partial^2 G}{\partial \zeta^2} - \bar{\zeta}^2 \frac{\partial^2 G}{\partial \bar{\zeta}^2} \right) = \\ & \delta(\zeta - \bar{\zeta}) - \frac{1}{A_{\mathcal{E}}}. \end{aligned}$$

Therefore, it holds that

$$\frac{1}{1-e^2 \sin^2 \theta} (T'(\theta) \exp(i\lambda))^2 = \frac{1}{\sin^2 \theta} (T(\theta) \exp(i\lambda))^2. \quad (32)$$

Choosing the positive root of Equation (32) gives

$$T(\theta) = \exp \left(\int \frac{\sqrt{1-e^2 \sin^2 \theta}}{\sin \theta} d\theta \right),$$

or in a more precise representation as

$$\begin{aligned} T(\theta) = & \left(\left| \sqrt{2}e \cos \theta + \sqrt{2} \sqrt{1-e^2 \sin^2 \theta} \right| \right)^e \times \\ & \left(\frac{\sqrt{1-e^2 \sin^2 \theta} - \cos \theta}{\sqrt{1-e^2 \sin^2 \theta} + \cos \theta} \right)^{\frac{1}{2}}. \end{aligned} \quad (33)$$

Substituting (33) into (27) and (28) leads to

$$\frac{\partial^2 \mathcal{O}}{\partial \zeta \partial \bar{\zeta}} = -\frac{a^2}{4A_{\mathcal{E}}} \sin^2 \theta \frac{1}{T^2(\theta)}.$$

The second green's function problem is closely associated with the Hamiltonian problem in spheroidal geometry. The Hamiltonian formula is a representation of the system's total dynamic energy for moving vortexes on the spheroid \mathcal{E} . To achieve the Green's function, we change the Hamiltonian formula for dynamic energy (see more details in Castilho and Machado (2008)). For this reason, an appropriate conformal factor is proposed as

$$\mu(\theta) = \frac{T(\theta)}{\sin \theta}. \quad (34)$$

Note that the conformal factor $\mu(\theta)$ is not constant while the eccentricity satisfies $e < 1$. Therefore, the function $T(\theta)$ can be expanded around e as

$$\begin{aligned} T(\theta) = & \tan \frac{\theta}{2} + \\ & \left(2 \cos^2 \frac{\theta}{2} + \cot \frac{\theta}{2} + \frac{1}{2} \sin^2 \theta + \frac{1}{4} \cot^2 \frac{\theta}{2} \right) e^2 + \dots \end{aligned}$$

Following Castilho and Machado (2008), it is concluded that

$$\Psi(\zeta_1, \zeta_2) = \frac{1}{A_{\mathcal{E}}} \ln \left(\sum_{j=0}^{\infty} \mu_j(\theta) e^{2j} \sum_{j=0}^{\infty} \mu_j(\theta') e^{2j} \|\zeta_1 - \zeta_2\| \right), \quad (35)$$

where μ_j for $j=0,1,\dots$, are coefficients of power series of function μ around e . In (35), the two distinct points of the complex plane, ζ_1 and ζ_2 , are the results of applying the conformal map (34) to the distinct points (θ, λ) and (θ', λ') on \mathcal{E} , respectively. By using

$$\begin{aligned} \|\zeta_1 - \zeta_2\| = & \left(\left\langle T(\theta) \exp(i\lambda) - T(\theta') \exp(i\lambda'), \right. \right. \\ & \left. \left. T(\theta) \exp(i\lambda) - T(\theta') \exp(i\lambda') \right\rangle \right)^{\frac{1}{2}}, \end{aligned}$$

the following formula is obtained

$$\|\zeta_1 - \zeta_2\| = (T^2(\theta) + T^2(\theta') - 2T(\theta)T(\theta') \cos(\lambda - \lambda'))^{\frac{1}{2}}.$$

Using the second order Taylor series expansion of the function $\ln(t)$ stated in (35), the second Green's function is approximated as

$$\begin{aligned} G(\theta, \theta'; \lambda, \lambda') \simeq & \frac{a^2}{A_{\mathcal{E}}} \ln(1 - \cos \theta \cos \theta' - \sin \theta \sin \theta' \cos(\lambda - \lambda')) + \\ & \frac{a^2 \ln 2}{A_{\mathcal{E}}} - \frac{a^2 e^2}{A_{\mathcal{E}}} (\cos^2 \theta + \cos^2 \theta'). \end{aligned} \quad (36)$$

Since the null space of the Beltrami-Laplace operator contains only constant functions, then adding $\frac{-a^2}{A_{\mathcal{E}}}$ to (36) gives

$$\begin{aligned} G(\theta, \theta'; \lambda, \lambda') \simeq & \frac{a^2}{A_{\mathcal{E}}} \ln(1 - \cos \theta \cos \theta' - \sin \theta \sin \theta' \cos(\lambda - \lambda')) + \\ & \frac{a^2 \ln 2}{A_{\mathcal{E}}} - \frac{a^2 e^2}{A_{\mathcal{E}}} (\cos^2 \theta + \cos^2 \theta') - \frac{a^2}{A_{\mathcal{E}}}. \end{aligned}$$

Using the fourth order Taylor series expansion of the function $\ln(t)$ in (35) leads to the approximate formula (26).

The surface area $A_{\mathcal{E}}$ is smaller than the surface area of its corresponding sphere. Therefore, the spheroidal Green's function is smaller than the spherical Green's function.

2.4. Iterated Green's functions

We consider the iterated problem for the first and second Green's functions where the Beltrami-Laplace operator acts ν times. From the general theory of Green's functions as presented in Freedman and Schreiner (2009), iterated Green's function G_{ν} satisfies the following convolution

$$G_{v+1}(\xi, \eta) = \iint_{\mathcal{E}} G_v(\xi, \zeta) G_v(\zeta, \eta) d\zeta. \tag{37}$$

Similar to the proposed method in Greenberg (2015), this problem can be solved based on eigenvalue expansion. For solving (37), one needs to find the eigenvalues, p , and eigenfunctions, N , of the Beltrami-Laplace operator, i.e.,

$$(\Delta_B - p)N(\xi) = 0.$$

Based on Appendix A, $p = -n(n+1)$ with $n \in \mathbb{Z}^+$ and $N(\xi) = K_{nm}(\xi)$, where reproducing kernel $K_{nm}(\xi)$ is given for both Dirichlet and Neumann conditions in (53). Therefore, the following relation is obtained

$$G_1(\xi, \eta) = \sum_{k=1}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{-k(k+1)}.$$

From (37) and orthogonality of functions $K_{nm}(\xi)$ with respect to the inner product in $L^2(\mathcal{E})$, the iterated Green's function is given by

$$G_v(\xi, \eta) = \sum_{k=1}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1))^v}. \tag{38}$$

For the iterated problem with discrete Neumann condition at \mathcal{D} , we get

$$F(\eta) = \frac{1}{A_{\mathcal{E}}} \iint_{\mathcal{E}} F(\xi) d\sigma + \iint_{\mathcal{E}} G_v(\xi, \eta) \Delta_B^v F(\xi) d\sigma.$$

For The iterated problem with discrete Dirichlet conditions at \mathcal{D} , we have

$$F(\eta) = \iint_{\mathcal{E}} G_v(\xi, \eta) \Delta_B^v F(\xi) d\sigma.$$

2.5. Green's function for the iterated Helmholtz operator

Suppose that \mathcal{L} is of the form (4). The Green's function for the i -th Helmholtz operator is defined as

$$(\mathcal{L} + i(i+1))G_H^i(\xi, \eta) = \delta(\xi - \eta) - \sum_{m=-i}^{+i} K_{im}(\xi)K_{im}(\eta). \tag{39}$$

The term $\sum_{m=-i}^{+i} K_{im}(\xi)K_{im}(\eta)$ is the null space of the Helmholtz operator. From the general theory of Green's functions (see Greenberg, 2015; Szymtkowski, 2006, and references therein), this term must be added to the Green's function equation for the Helmholtz operator. Based on the eigenvalue expansion method, the solution of (39) is represented by

$$G_H^i(\xi, \eta) = \sum_{k=1, k \neq i}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{i(i+1) - k(k+1)}.$$

From (37), the following formula is obtained

$$G_{H_{v+1}}^i(\xi, \eta) = \iint_{\mathcal{E}} G_{H_v}^i(\xi, \zeta) G_{H_v}^i(\zeta, \eta) d\zeta.$$

The orthogonality of the functions $K_{nm}(\xi)$ leads to

$$G_{H_v}^i(\xi, \eta) = \sum_{k=1, k \neq i}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(i(i+1) - k(k+1))^v}. \tag{40}$$

By using (39) and (10), we have

$$F(\eta) = \sum_{m=-i}^{+i} K_{im}(\eta) \iint_{\mathcal{E}} F(\xi) K_{im}(\xi) d\xi + \iint_{\mathcal{E}} G_{H_v}^i(\xi, \eta) (\Delta_B + i(i+1)) F(\xi) d\xi.$$

2.6. Green's function for the consecutive iterated Helmholtz operator

We consider the consecutive Helmholtz operator by setting $q_0 = \dots = q_i = 1$ in (5). Based on the null space of the consecutive Helmholtz operator and following (39), the Green's function for the i -th degree satisfies

$$\begin{aligned} & (\Delta_B \dots (\Delta_B + i(i+1))) G(\xi, \eta) = \\ & \delta(\xi - \eta) - \sum_{k=0}^i \sum_{m=-k}^{+k} K_{km}(\xi)K_{km}(\eta). \end{aligned} \tag{41}$$

Taking into account the following convolution

$$G_{H_C}^i(\xi, \eta) = \iint_E G_{H_C}^{i-1}(\xi, \zeta) G_{H_C}^i(\zeta, \eta) d\zeta$$

and using the eigenvalue expansion procedure in Freedon and Schreiner (2009), it could be shown that

$$G_{H_C}^i(\xi, \eta) = \sum_{k=i+1}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1)) \dots (i(i+1) - k(k+1))}.$$

By using (41) and (10), it is concluded that

$$\begin{aligned} F(\eta) &= \sum_{k=0}^i \sum_{m=-k}^{+k} K_{km}(\eta) \iint_{\mathcal{E}} F(\xi) K_{km}(\xi) d\xi + \\ & \iint_{\mathcal{E}} G_{H_C}^i(\xi, \eta) (\Delta_{H_0}) \dots (\Delta_{H_i}) F(\xi) d\xi. \end{aligned}$$

Similar to (38) and (40), the consecutive iterated Helmholtz Green's function reads as

$$G_{H_{C_{q_0, \dots, q_i}}}^i(\xi, \eta) = \sum_{k=i+1}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1))^{q_1} \dots (i(i+1) - k(k+1))^{q_i}}$$

and

$$\begin{aligned} F(\eta) &= \sum_{k=0}^i \sum_{m=-k}^{+k} K_{km}(\eta) \iint_E F(\xi) K_{km}(\xi) d\xi + \\ & \iint_{\mathcal{E}} G_{H_{C_{q_0, \dots, q_i}}}^i(\xi, \eta) (\Delta_{H_0}^{q_0}) \dots (\Delta_{H_i}^{q_i}) F(\xi) d\xi \end{aligned}$$

is finally obtained.

3. Spline interpolant

So far, the Green's functions on the spheroid \mathcal{E} have been derived. According to Freedden (1984) and (1981), we introduce the corresponding reproducing kernels and spline interpolants. For an admissible system of points $\{\eta_i \mid i=1, \dots, J\}$, we consider the Lagrange basis function $\{L_{k,J} \mid k=1, \dots, J\} \subset H(\mathcal{E})$ such that

$$L_{k,J}(\eta_i) = \delta_{ki} \quad k, i = 1, \dots, J,$$

where δ denotes the Kronecker symbol.

Definition 3.1. For the unisolvent system of points $\{\eta_i \mid i=1, \dots, J\}$ and discrete Dirichlet and Neumann conditions

- Reproducing kernel for the iterated Beltrami-Laplace operator is

$$\begin{aligned} \mathcal{K}(\xi, \eta) = & G_v(\xi, \eta) - \sum_{k=1}^M G_v(\xi, \eta_j) L_{k,J}(\eta) + \\ & \sum_{k=1}^M G_v(\eta, \eta_j) L_{k,J}(\xi) + \\ & \sum_{k=1}^M \sum_{i=1}^M L_{k,J}(\xi) G_v(\eta_j, \eta_i) L_{i,J}(\eta). \end{aligned}$$

- Reproducing kernel for the consecutive iterated Helmholtz operator is

$$\begin{aligned} \mathcal{K}(\xi, \eta) = & G_{H_{C_{q_0, \dots, q_i}}^i}(\xi, \eta) - \\ & \sum_{k=1}^M G_{H_{C_{q_0, \dots, q_i}}^i}(\xi, \eta_j) L_{k,J}(\eta) + \\ & \sum_{j=1}^M G_{H_{C_{q_0, \dots, q_i}}^i}(\eta, \eta_j) L_{j,J}(\xi) + \\ & \sum_{j=1}^M \sum_{i=1}^M L_{j,J}(\xi) G_{H_{C_{q_0, \dots, q_i}}^i}(\eta_j, \eta_i) L_{i,J}(\eta). \end{aligned}$$

According to the considerations given in Freedden (1984), the definition of the spline function is presented in the following.

Definition 3.2. In the Hilbert space $H(\mathcal{E})$, the spline interpolant is defined as

$$S(\xi) = \sum_{j=1}^{J_1} c_j L_{j,J}(\xi) + \sum_{j=J_1+1}^J c_j \mathcal{K}(\xi, \eta_j),$$

where J_1 denotes the first J_1 elements of points which constitute an admissible system.

Note that the whole formulas for Green's functions and spline interpolants are valid and applicable in the prolate spheroidal coordinate system.

4. Application in gravity data interpolation in geodesy: interpolating global potential data

There are many applications to the spline functions, including gravity data interpolation, satellite position interpolation between observation points, and TEC interpolation between the discrete measurements in the Ionosphere (Keller & Borkowski, 2019). We show how the results obtained in the previous sections can be applied to globally interpolate gravity data. To make the $5^\circ \times 5^\circ$ and $4^\circ \times 4^\circ$ grid data, Potential values derived by EGM-2008 geopotential model (up to 2190 degree) are interpolated. Then these values are compared with the actual grid produced by the potential formula. The process of determining the unknown coefficients of the spline interpolation is exactly the same as that of the sphere (for more detail, see Freedden, 1981; Keller & Borkowski, 2019). We notice that the spherical coefficients in the potential formula have to convert to the ellipsoidal coefficients via the relations stated in Jekeli (1988). After the computations, we get the following Figure 1.

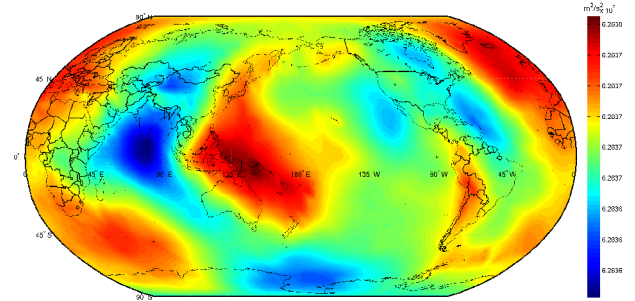


Figure 1. Potential over the globe, $5^\circ \times 5^\circ$ -grid

Then the following steps are performed

- According to (9), subtract the mean from the potential data on the surface of the ellipsoid. Consequently we get the following Figure 2.

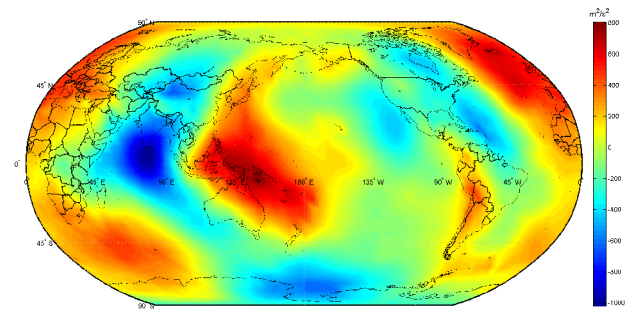


Figure 2. Potential over the globe, after subtracting the mean

- By using the ellipsoidal spline interpolation, interpolate the data in the previous step for $4^\circ \times 4^\circ$ and add the removed mean after interpolation. Then we get the following Figure 3.
- To determine the difference, subtract the actual $4^\circ \times 4^\circ$ grid derived from the potential formula from the $4^\circ \times 4^\circ$ interpolated grid (Figure 4).

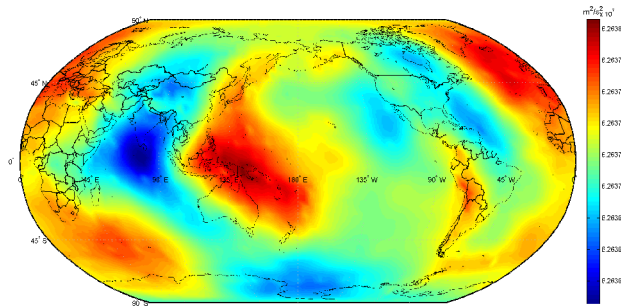


Figure 3. Potential over the globe, $4^\circ \times 4^\circ$ -grid interpolated

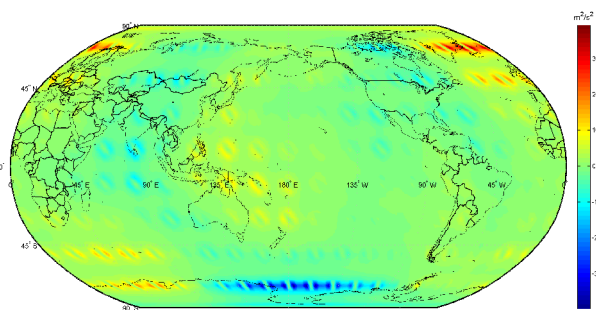


Figure 4. Difference of potential over the globe between $4^\circ \times 4^\circ$ -grid interpolated and actual $4^\circ \times 4^\circ$ -grid derived from the potential formula

Conclusions

For solving the minimization problem on the spheroid, the surface Green's function approach has been chosen. Under the specific interpolation conditions, the Green's functions for the Beltrami-Laplace and consecutive Helmholtz operators and their iterations have been derived. By using the Green's functions, the corresponding reproducing kernels of the operators and the interpolation conditions on the given points have been introduced. Based on the reproducing kernels, the spline interpolants, as the minimizer of the problem, are presented.

It is verified that this work is the generalization of the minimization problem on a sphere. This means that the spline interpolant formulas on a sphere could be obtained by the corresponding formulas on a spheroid when the eccentricity tends to zero. This work can be used in different areas of study, including Earth's gravity field where the geometrical structure of the Earth is better modeled with a spheroid. In future work, we intend to extend the minimization problem of spheroidal smoothing spline to ellipsoidal geometry for a set of linearly independent evaluation functionals.

Author contributions

All four authors contributed to the derivation of the formulae and the writing of the manuscript. A. Safari and M. Kiani did the data analysis for the section in numerical computations.

References

- Akhtar, N., & Michel, V. (2012). Reproducing-kernel-based splines for the regularization of the inverse ellipsoidal gravimetric problem. *Applicable Analysis*, 91(12), 2105–2132. <https://doi.org/10.1080/00036811.2011.590479>
- Amiri-Simkooei, A. R., Hosseini-Asl, M., & Safari, A. (2018). Least squares 2D bi-Cubic spline approximation: Theory and applications. *Measurement*, 127, 366–378. <https://doi.org/10.1016/j.measurement.2018.06.005>
- Baramidze, V., Lai, M. J., & Shum, C. K. (2006). Spherical splines for data interpolation and fitting. *Society for Industrial and Applied Mathematics Journal on Scientific Computing*, 28(1), 241–259. <https://doi.org/10.1137/040620722>
- Castilho, C., & Machado, H. (2008). The -Vortex problem on a symmetric ellipsoid: a perturbation approach. *Journal of Mathematical Physics*, 49(2). <https://doi.org/10.1063/1.2863515>
- Felsen, L. B., & Marcuritz, N. (1994). *Radiation and Scattering of Waves*. IEEE Press Series on Electromagnetic Waves. John Wiley Sons, Inc. <https://doi.org/10.1109/9780470546307>
- Freeden, W., Nashed, M. Z., & Schreiner, M. (2018). *Spherical sampling*. Springer, Switzerland. <https://doi.org/10.1007/978-3-319-71458-5>
- Freeden, W., & Gutting, M. (2013). *Applied and numerical harmonic analysis*. Springer, Basel.
- Freeden, W., & Gutting, M. (2018). *Integration and cubature methods: A geomathematically oriented course*. Taylor Francis Group. <https://doi.org/10.1201/9781315195674>
- Freeden, W., Gervens, T., & Schreiner, M. (1998). *Constructive approximation on the sphere*. Clarendon press, Oxford University Press, UK.
- Freeden, W. (1984). Spherical spline interpolation: Basic theory and computational aspects. *Journal of Computational and Applied Mathematics*, 11(3), 367–375. [https://doi.org/10.1016/0377-0427\(84\)90011-6](https://doi.org/10.1016/0377-0427(84)90011-6)
- Freeden, W., & Schreiner, M. (2009). *Spherical functions of mathematical geosciences*. Springer-Verlag, Berlin Heidelberg. <https://doi.org/10.1007/978-3-540-85112-7>
- Freeden, W. (1981). On spherical spline interpolation and approximation. *Mathematical Methods in the Applied Sciences*, 3(1), 551–575. <https://doi.org/10.1002/mma.1670030139>
- Greenberg, M. D. (2015). *Application of Green's functions in science and engineering*. Dover Books on Engineering, Library of cataloging in publication data. Courier Dover Publications.
- Jekeli, C. (1988). The exact transformation between ellipsoidal and spherical harmonic expansions. *Manuscripta geodaetica*, 13, 106–113.
- Keller, W., & Borkowski, A. (2019). Thin plate spline interpolation. *Journal of Geodesy*, 93, 1251–1269. <https://doi.org/10.1007/s00190-019-01240-2>
- Klees, R., Tenzer, R., Prutkin, I., & Wittwer, T. (2008). A data-driven approach to local gravity field modelling using spherical radial basis functions. *Journal of Geodesy*, 82, 457–471. <https://doi.org/10.1007/s00190-007-0196-3>
- Sloan, I. H., & Womersley, R. S. (2002). Good approximation on the sphere; with application to geodesy and the scattering of sound. *Journal of Computational and Applied Mathematics*, 149, 227–237. [https://doi.org/10.1016/S0377-0427\(02\)00532-0](https://doi.org/10.1016/S0377-0427(02)00532-0)
- Szmytkowski, R. (2006). Closed form of the generalized Green's function for the Helmholtz operator on the two dimensional unit sphere. *Journal of Mathematical Physics*, 47(6). <https://doi.org/10.1063/1.2203430>

Wahba, G. (1981). Spline interpolation and smoothing on the sphere. *Society for Industrial and Applied Mathematics Journal on Scientific and Statistical Computing*, 2(1), 5–16. <https://doi.org/10.1137/0902002>

Wahba, G. (1990). *Spline models for observational data*. Society for Industrial and Applied Mathematics, Philadelphia, Pennsylvania. <https://doi.org/10.1137/1.9781611970128>

APPENDIX

A. Eigenvalues and eigenfunctions of the Beltrami-Laplace operator

Let us consider the problem of finding eigenvalues, p , and eigenfunctions, N , of the Beltrami-Laplace operator as the following

$$(\Delta_B - p)N(\xi) = 0, \quad \forall \xi = (\theta, \lambda) \in \mathcal{E}. \tag{42}$$

This problem can be written in the oblate coordinate system (θ, λ) as

$$\frac{1}{1 - e^2 \sin^2 \theta} \frac{\partial^2 N}{\partial \theta^2} + \frac{\cot \theta}{(1 - e^2 \sin^2 \theta)^2} \frac{\partial N}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2 N}{\partial \lambda^2} - a^2 p N = 0. \tag{43}$$

Using the method of separation of variables

$$N(\theta, \lambda) = N_1(\theta)N_2(\lambda),$$

problem (43) leads to the following system of equations

$$\begin{aligned} &\frac{1}{1 - e^2 \sin^2 \theta} \frac{\partial^2 N_1 N_2}{\partial \theta^2} + \frac{\cot \theta}{(1 - e^2 \sin^2 \theta)^2} \frac{\partial N_1 N_2}{\partial \theta} + \\ &\frac{1}{\sin^2 \theta} \frac{\partial^2 N_1 N_2}{\partial \lambda^2} = a^2 p N_1 N_2; \\ &\frac{\sin^2 \theta}{1 - e^2 \sin^2 \theta} \frac{N_1''}{N_1} + \frac{\sin \theta \cos \theta}{(1 - e^2 \sin^2 \theta)^2} \frac{N_1'}{N_1} - a^2 p \sin^2 \theta = -\frac{N_2''}{N_2}. \end{aligned} \tag{44}$$

Since Green's functions are periodic on \mathcal{E} , we have

$$-\frac{N_2''}{N_2} = m^2. \tag{45}$$

Equation (45) has the independent solutions

$$N_{2,m}(\lambda) = \cos m\lambda, \sin m\lambda, \quad m = 1, 2, \dots$$

We discuss the case $m = 0$ later for Equation (45). Substituting (45) in (44) leads to

$$\frac{1}{1 - e^2 \sin^2 \theta} \frac{d^2 N_1(\theta)}{d\theta^2} + \frac{\cot \theta}{(1 - e^2 \sin^2 \theta)^2} \times \frac{dN_1(\theta)}{d\theta} - \left(a^2 p + \frac{m^2}{\sin^2 \theta} \right) N_1(\theta) = 0. \tag{46}$$

To find p , we expand (46) with respect to $e \sin \theta$ as the following

$$\begin{aligned} &N_1''(\theta) \sum_{j=0}^{\infty} e^{2j} \sin^{2j} \theta + \cot \theta \left(\sum_{j=0}^{\infty} e^{2j} \sin^{2j} \theta \right)^2 N_1'(\theta) - \\ &\left(a^2 p + \frac{m^2}{\sin^2 \theta} \right) N_1(\theta) = 0 \end{aligned}$$

and so

$$\begin{aligned} &N_1''(\theta) + \cot \theta N_1'(\theta) - \left(p + \frac{m^2}{\sin^2 \theta} \right) N_1(\theta) = \\ &-N_1''(\theta) \left(\sum_{j=1}^{\infty} e^{2j} \sin^{2j} \theta \right) - \\ &\cot \theta \sum_{j,k=1}^{\infty} e^{2j+2k} \sin^{2j+2k} \theta N_1'(\theta) + (1 - a^2) N_1(\theta). \end{aligned} \tag{47}$$

Based on Lagrange solution of an inhomogeneous second order differential equation, the solution of (47), expressed in an implicit form, reads as

$$\begin{aligned} &N_{1,1}(\theta) = -P_{\ell,m}(\theta) \int \sin_2 \theta (Q_{\ell,m}(\theta) N_1''(\theta) \sum_{j=1}^{\infty} (e \sin \theta)^{2j} + \\ &Q_{\ell,m}(\theta) N_1'(\theta) \sum_{j=1}^{\infty} (e \sin \theta)^{2j+2k} + Q_{\ell,0}(\theta) (a^2 - 1) N_1(\theta)) d\theta; \\ &N_{1,2}(\theta) = -Q_{\ell,m}(\theta) \int \sin_2 \theta (P_{\ell,m}(\theta) N_1''(\theta) \sum_{j=1}^{\infty} (e \sin \theta)^{2j} + \\ &P_{\ell,m}(\theta) N_1'(\theta) \sum_{j=1}^{\infty} (e \sin \theta)^{2j+2k} + P_{\ell,0}(\theta) (a^2 - 1) N_1(\theta)) d\theta, \end{aligned}$$

where ℓ is the biggest integer that is less or equal than $\frac{\sqrt{1+4p}-1}{2}$, $P_{\ell,m}$ and $Q_{\ell,m}$ are, respectively, generalized Legendre polynomials of the first and second kind of order (ℓ, m) . Thus we have

$$N_1(\theta) = P_{\ell,m} + \frac{\Gamma(s-m+1)}{\Gamma(s-m+1)} (N_{1,1}(\theta) + N_{1,2}(\theta)),$$

$$Q_{\ell,m} + \frac{\Gamma(s-m+1)}{\Gamma(s-m+1)} (N_{1,1}(\theta) + N_{1,2}(\theta)),$$

where $s = \frac{\sqrt{1+4p}-1}{2}$ and Γ is the Gamma function. It is deduced that the number p in the eigenvalue problem (42) is exactly the same as $-n(n+1)$ with $n \in \mathbb{Z}^+$ in the eigenvalue problem for spherical case. Therefore, the number p in (42) can be written as $-p(p+1)$ where

$p = 0, 1, 2, \dots$. With this important result, Equation (46) can be written as

$$\frac{1}{1-e^2 \sin^2 \theta} \frac{d^2 N_1(\theta)}{d\theta^2} + \frac{\cot \theta}{(1-e^2 \sin^2 \theta)^2} \frac{dN_1(\theta)}{d\theta} + \left(a^2 p(p+1) - \frac{m^2}{\sin^2 \theta} \right) N_1(\theta) = 0. \tag{48}$$

This equation is solved by the aid of series expansion. By setting $t = \cos \theta$, Equation (48) yields

$$\frac{1-t^2}{1-e^2+e^2 t^2} \frac{d^2 N_1(t)}{dt^2} - \frac{2t-e^2 t-e^2 t^3}{(1-e^2+e^2 t^2)^2} \frac{dN_1(t)}{dt} + \left(a^2 p(p+1) - \frac{m^2}{1-t^2} \right) N_1(t) = 0. \tag{49}$$

Taking into account the self-adjointness requirement for the eigenvalue expansion method (see Greenberg (2015), the self-adjoint factor for Equation (49) reads as

$$\sigma(t) = \exp \left(\int \frac{te^2}{1-e^2+e^2 t^2} dt \right) = \sqrt{1-e^2+e^2 t^2}.$$

By using this factor, Equation (48) is written as

$$\frac{1-t^2}{(1-e^2+e^2 t^2)^{\frac{1}{2}}} \frac{d^2 N_1(t)}{dt^2} - \frac{2t-e^2 t-e^2 t^3}{(1-e^2+e^2 t^2)^{\frac{3}{2}}} \frac{dN_1(t)}{dt} + \sqrt{1-e^2+e^2 t^2} \left(a^2 p(p+1) - \frac{m^2}{1-t^2} \right) N_1(t) = 0. \tag{50}$$

Equation (50) with $e = 0$ is the Legendre equation. Based on the series expansion method, a Taylor series representation around zero exists for Equation (50). Therefore, the solution of Equation (50) is expressed by

$$N_1(t) = \sum_{n=0}^{\infty} a_n t^n. \tag{51}$$

Substitution of (51) in (50) gives

$$a_{n+2} = -\frac{c_1 a_n + c_2 a_{n-2} + c_3 a_{n-4} + c_4 a_{n-6}}{(1-e^2)(n+1)(n+2)}, \tag{52}$$

where

$$\begin{aligned} c_1 &= n \left((3e^2 - 2)(n-1) + e^2 - 2 \right) - a^2 p(p+1)(2e^2 - 1 - e^4) - m^2(1-e^2)^2; \\ c_2 &= (n-2) \left((1-3e^2)(n-3) + 2 - 2e^2 \right) - a^2 p(p+1)(-4e^2 + 1 + 3e^4) - 2m^2 e^2(1-e^2); \\ c_3 &= e^2(n-4)^2 - a^2 p(p+1)e^2(2-3e^2) - m^2 e^4; \\ c_4 &= -a^2 p(p+1)e^4. \end{aligned}$$

The recursive formula (52) needs the following initial conditions

$$\begin{aligned} a_2 &= \frac{(-a^2 p(p+1) + m^2)(1-e^2)}{2} a_0; \\ a_3 &= \left(\frac{2-e^2}{6(1-e^2)} + \frac{(-a^2 p(p+1) + m^2)(1-e^2)}{6} \right) a_1; \\ a_4 &= (-a^2 p(p+1))(-a^2 p(p+1) + 2m^2) \times \\ &\quad (1-e^2)^2 + 6 - 8e^2 + \\ &\quad m^2(4(2-e^2) + m^2(1-e^2)^2) \frac{a_0}{24}; \\ a_5 &= \left((-a^2 p(p+1) + m^2)(1-e^2) - \frac{3}{20} \frac{7e^2 - 6}{1-e^2} \right) a_3 - \\ &\quad \left(\frac{1}{10} - 2m^2 e^2 + \frac{-a^2 p(p+1)(1-4e^2 + 3e^4)}{20(1-e^2)} \right) a_1; \\ a_7 &= \left((-a^2 p(p+1) + m^2)(1-e^2) - \frac{5}{42} \frac{13e^2 - 10}{1-e^2} \right) a_5 - \\ &\quad \left(\frac{2-4e^2}{7(1-e^2)} - 2m^2 e^2 + \frac{-a^2 p(p+1)(1-4e^2 + 3e^4)}{42(1-e^2)} \right) a_3 - \\ &\quad \left(\frac{-a^2 p(p+1)e^2(2-3e^2) + e^2 - m^2 e^4}{42(1-e^2)} \right) a_1. \end{aligned}$$

The following considerable points about the solutions of the problem (42) can be observed

- The Beltrami-Laplace equation is a type of the Sturm-Liouville equation. Therefore, the solutions of the Beltrami-Laplace equation are orthogonal in the sense of $L^2(\mathcal{E})$ -inner product.
- In contrast to the Legendre functions, these functions are not polynomial.
- For odd and even number p , the solution is odd and even function, respectively.
- The coefficient a_0 or a_1 is chosen so that for $m = 0$, $N_1(1) = 1$.
- We consider equation (50) with $m = 0$. In this case, the coefficients a_n , for $n = 0, 1, \dots$, are expressed by

$$a_{n+2} = -\frac{d_1 a_n + d_2 a_{n-2} + d_3 a_{n-4}}{(1-e^2)(n+1)(n+2)},$$

where

$$d_2 = -(e^2(n-2)^2 - 2a^2 p(p+1)e^2(1-e^2)), d_3 = a^2 p(p+1)e^4,$$

with the conditions

$$\begin{aligned} a_2 &= \frac{-a^2 p(p+1)(1-e^2)}{2} a_0; \\ a_3 &= \left(\frac{-a^2 p(p+1)(1-e^2)}{6} + \frac{2-e^2}{6(1-e^2)} \right) a_1; \end{aligned}$$

$$a_4 = \left(\frac{-a^2 p(p+1)e^2}{6} + \frac{a^2 p(p+1)(1-e^2)}{2} \times \left(-\frac{1}{2} + \frac{a^2 p(p+1)(1-e^2)}{12} \right) \right) a_0;$$

$$a_5 = \left(\frac{e^2}{20(1-e^2)} + \frac{-a^2 p(p+1)e^2}{10} + \left(\frac{3}{20} \times \frac{5e^2-4}{1-e^2} + \frac{a^2 p(p+1)(1-e^2)}{20} \right) \times \left(\frac{a^2 p(p+1)(1-e^2)}{6} - \frac{2-e^2}{6(1-e^2)} \right) \right) a_1.$$

In Figure 5, the functions $N_{1,n}, P_n$ for $n=0,1,2$ (left panel) and $N_{1,n,m}, P_{n,m}$ for $n=2$ and $m=1,2$ (right panel) are shown. For $e=0.06$ (ten times that of the Earth), all series in (51) are truncated to their first 100 coefficients.

By normalizing the solutions of problem (42) with respect to the weight function

$$w(t) = \sqrt{1-e^2 + e^2 t^2},$$

the orthonormal basis is formed by

$$K_{nm}(\xi) = \frac{N_{1,n,m}(t)N_{2,m}(\lambda)}{\sqrt{\int_{-1}^{+1} \int_0^{2\pi} (N_{1,n,m}(t)N_{2,m}(\lambda))^2 w(t)d\lambda dt}}, \quad (53)$$

or

$$K_{nm}(\xi) = \frac{N_{1,n,m}(t)N_{2,m}(\lambda)}{\sqrt{\pi(1+\delta_{m0}) \sum_{i,j=0}^{\infty} a_i a_j (1-(-1)^{i+j+1}) \frac{\sqrt{1-e^2} F\left(-\frac{1}{2}, \frac{i+j+1}{2}; \frac{i+j+3}{2}, -\frac{e^2}{1-e^2}\right)}{(i+j+1)}}},$$

where F represents the Hypergeometric function.

Remark 4.1. In (53), the function $N_{2,m}(\lambda)$ is chosen

$$N_{2,m}(\lambda) = \cos m\lambda + \sin m\lambda,$$

$$N_{2,m}(\lambda) = \sin m\lambda, \quad N_{2,m}(\lambda) = \cos m\lambda,$$

for generalized, Dirichlet, and Neumann conditions, respectively.

For Generalized conditions, we consider the following particular function

$$K_{00}(\xi) = \frac{1}{\sqrt{2\pi \left(1 + \frac{1-e^2}{2e} \ln \left(\frac{1+e}{1-e} \right) \right)}}. \quad (54)$$

B. Approximate formula for the iterated second Green's function

This Appendix is concerned with finding an approximate formula for the following iterated Green's function

$$G_v(\xi, \eta) = \sum_{k=1}^{\infty} \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1))^v}.$$

From (53), it is deduced that

$$K_{nm}(\xi) \leq \frac{1}{\|K_{nm}\|}.$$

in which we have assumed that $N_2(\lambda) = \cos m\lambda$ is equal to 1, so $m=0$ and

$$K_{n0}(\xi) \leq \frac{1}{\|K_{n0}\|}.$$

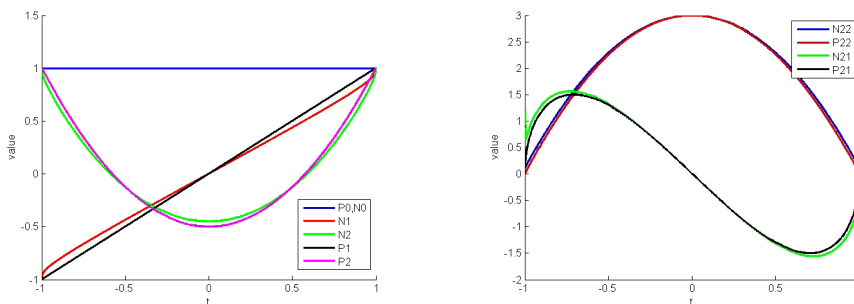


Figure 5. Left: $N_{1,n}$ and P_n ; right: $N_{1,n,m}$ and $P_{n,m}$

Similar to the spherical case, it can be concluded that

$$\|K_{nm}(\xi)\|^2 = \pi(1 + \delta_{m0}) \int_{-1}^{+1} (\sum_{j=0}^{\infty} a_j t^j)^2 \sqrt{1 - e^2 + e^2 t^2} dt.$$

On the other hand, it could be readily observed that

$$\|K_{nm}\| \leq \frac{1}{\|K_{00}\|}. \tag{55}$$

From (55) and (54), it can be concluded that

$$\|K_{nm}\| \leq \sqrt{2\pi \left(1 + \frac{1 - e^2}{2e} \ln \left(\frac{1 + e}{1 - e}\right)\right)}.$$

Based on the given desired precision ϵ , it is needed to find r such that

$$\|G_v(\xi, \eta) - \sum_{k=1}^r \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1))^v}\| \leq \epsilon.$$

Therefore, the integer number r satisfies

$$|\epsilon| \leq \frac{2r + 3}{\|K_{00}\|^2 (r + 1)^v (r + 2)^v},$$

or

$$|\epsilon| \leq \frac{2r + 3}{2\pi \left(1 + \frac{1 - e^2}{2e} \ln \left(\frac{1 + e}{1 - e}\right)\right) (r + 1)^v (r + 2)^v}.$$

Finally the Green's function $G_v(\xi, \eta)$ is approximated by

$$G_v(\xi, \eta) \simeq \sum_{k=1}^r \sum_{m=-k}^{+k} \frac{K_{km}(\xi)K_{km}(\eta)}{(-k(k+1))^v}.$$