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REVIEW ARTICLE

Example-Based Learning: Integrating Cognitive and Social-Cognitive Research Perspectives

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Abstract Example-based learning has been studied from different perspectives. Cognitive research has mainly focused on *worked* examples, which typically provide students with a written worked-out didactical solution to a problem to study. Social-cognitive research has mostly focused on *modeling* examples, which provide students the opportunity to observe an adult or a peer model performing the task. The model can behave didactically or naturally, and the observation can take place face to face, on video, as a screen recording of the model's computer screen, or as an animation. This article reviews the contributions of the research on both types of example-based learning on questions such as why example-based learning is effective, for what kinds of tasks and learners it is effective, and how examples should be designed and delivered to students to optimize learning. This will show both the commonalities and the differences in research on example-based learning conducted from both perspectives and might inspire the identification of new research questions.

Keywords Worked examples · Modeling · Social learning · Cognitive load · Instructional design

Cognitive load theory (Sweller 1988, [this issue](#); Sweller *et al.* 1998; Van Merriënboer and Sweller 2005) has emphasized the evolutionary importance of learning by observing and/or imitating what other people do, say, or write (Sweller 2004; Sweller and Sweller 2006) and so has Bandura's (1977, 1986) social learning theory. Both argue that it would be

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impossible (not to mention quite dangerous) for a human being to discover by one's own experience the vast amounts of knowledge that our ancestors developed over thousands of years. It is much more efficient to borrow this knowledge from others and reorganize it to fit in with one's existing knowledge and use it to one's own purposes (the “borrowing and reorganizing” principle; Sweller and Sweller). Not surprisingly, therefore, both theories have developed research lines on different ways of learning from others. What is surprising, however, is that these lines of research tend to be quite separated and not refer to each other very much. Cognitive load theory (as well as other cognitive theories such as adaptive control of thought—rational; Anderson 1993) has focused primarily on the effects of learning by studying worked examples as opposed to learning by problem solving. It has paid little attention to investigating the effects of learning by observing others directly (“modeling”), which has mainly been studied from a social-cognitive perspective (Bandura 1977, 1986; Collins *et al.* 1989) and which we will refer to as learning from “modeling examples” from here on (cf. Van Merriënboer 1997).

In contrast to modeling examples in which a problem-solving or performance procedure is demonstrated to a learner, a worked example provides students with a written account of how a problem should be or can be solved: Next to a description of the “givens” and the goal that are provided in conventional problems, worked examples additionally provide the worked-out solution steps that are to be taken to reach the goal (Sweller and Cooper 1985). One could argue that studying worked examples is a type of observational learning though. Both Sweller (2004; Sweller and Sweller 2006) and Bandura (1977, 1986) mention the use of symbolic models in words and images as an important means for simultaneously sharing one person's knowledge with large groups of “observers” (including future generations). Moreover, observational learning of cognitive tasks requires the model to somehow externalize their cognitive actions, for example, by thinking aloud, or writing down the actions, or they will not be observable for the learner (Collins *et al.* 1989). Therefore, in this sense, studying worked examples would qualify as a kind of observational learning.

Indeed, as we will show, there are many commonalities in (research on) learning from worked examples and modeling examples, although there are also some important differences. In this article, we will review the contributions of the research on both types of example-based learning on understanding why example-based learning is effective, for what kinds of tasks and learners it is effective, and how examples should be designed and delivered to students to optimize learning. We will also address how the commonalities and differences might inspire the identification of new research questions drawing on both theoretical perspectives.

Why Is Example-Based Learning Effective?

Research on studying worked examples has consistently shown that for novice learners, instruction that relies more heavily on studying worked examples than on problem solving is more effective for learning, as well as more efficient in that better learning outcomes are often reached with less investment of time and effort during acquisition (for reviews, see Atkinson *et al.* 2000; Sweller *et al.* 1998). This is referred to as the “worked example effect” (Sweller *et al.*), and this effect has been explained in terms of the different cognitive processes evoked by problem solving and example study. Instruction that consists mainly of solving conventional problems forces novices to resort to weak problem-solving strategies such as means-ends analysis, in which learners continuously search for operators to reduce the difference between the current problem state and the goal state (Sweller 1988). This

imposes a high load on working memory but is not effective for learning: Even though such weak strategies may allow learners to succeed in solving the problem eventually (i.e., *performance*), they have been shown to contribute very little to *learning*, that is, to building a cognitive schema of how such problems should be solved. Worked examples prevent the use of such weak problem-solving strategies, allowing the learner instead to devote all the available cognitive capacity to studying the worked-out solution procedure (i.e., the relationship between problem states and operators) and constructing a cognitive schema for solving such problems (Sweller; Sweller *et al.*). Research has shown that worked examples can be used as an analogy for problem solving, either by being able to refer to the physical examples during problem solving (e.g., Reed *et al.* 1994) or by mentally referring back to the memory of a previously studied example. Moreover, what is learned from worked examples can go beyond the specific problem-solving procedure that was shown: general rules can be abstracted from the examples (e.g., Anderson and Fincham 1994; Anderson *et al.* 1997), which enables students not only to solve similar problems but also transfer problems for which (part of) the solution procedure has to be adapted (see, e.g., Cooper and Sweller 1987; Paas 1992; Paas and Van Merriënboer 1994).

One criticism of research on the worked example effect is that the control condition usually involves problem solving without any instructional support whatsoever (Koedinger and Aleven 2007). Recent studies have shown, however, that adding worked examples to *tutored* problem-solving environments (worked examples: Schwonke *et al.* 2009; video-based modeling examples: McLaren *et al.* 2008) or realistic mathematics methods (Van Loon-Hillen *et al.* *in press*) can also enhance learning, reduce acquisition time, or both. In addition, worked examples have been found to be more effective for learning than discovery learning (Tuovinen and Sweller 1999) and problem solving with a more general level of guidance provided by process steps (i.e., a description of the steps to be taken, but the steps are to be worked out by the learner; Nievelstein *et al.* 2010; Van Gog *et al.* 2006).

The effectiveness of modeling examples, on the other hand, is not usually explained in comparison with other types of learning but more in terms of the general cognitive processes that need to take place for observational learning to be effective. Bandura (1977, 1986) postulated that observers acquire a cognitive (symbolic) representation (cf. cognitive schema) of the model's behavior that outlasts the modeling situation and thus enables learners to exhibit the observed and novel behavior at later occasions. This is an important extension of earlier research on imitation in the behaviorist tradition (Miller and Dollard 1941) and implies that observational learning can occur without imitation taking place. In acquiring this representation, it is, first and foremost, required that the learner pays attention to the relevant aspects of the modeled behavior, and “selective attention is, therefore, one of the crucial subfunctions in observational learning” (Bandura 1986, p. 51). The learner's attention is influenced both by the salience of those aspects and by the characteristics of the model (we will return to this issue below, in the section on example design). Secondly, the attended information needs to be retained in memory, which requires encoding this information. Like Sweller and colleagues (Sweller and Sweller 2006; Sweller *et al.* 1998), Bandura stresses that this is not a one-on-one mapping but rather a constructive process during which information is actively (re)organized and integrated with the existing knowledge of the learner. Rehearsal, either mentally or physically, also plays an important role in retention, as well as in improvement of performance. However, learners may not always be able to produce the observed behaviors themselves. Whether or not they are able to do so depends on the quality of the cognitive representation they have acquired and on the extent to which they master the component skills. Finally, whether or not the learner will actually exhibit the behavior learned through observation is determined by motivational processes.

In sum, both cognitive and social-cognitive theories stress the importance of constructing appropriate cognitive representations to guide later performance by the learner. The nature of the attentional processes, however, may be an important difference between worked examples and modeling examples. Worked examples usually present a written, “ideal” or “didactical” procedure. In other words, it reflects the way in which students should *learn* to solve a particular problem, not necessarily how another person would actually solve it (e.g., individuals with low expertise might make errors; individuals with more expertise tend to skip steps: Blessing and Anderson 1996; Kalyuga and Sweller 2004). As a consequence, all the steps that are presented are relevant for the learner to attend to, and because it is written, little distracting information is present. In modeling examples, however, there may be a great deal of distracting information. Regardless of whether the performance of the model is observed face to face, on video, as a recording of the model's screen (McLaren *et al.* 2008), or as an animation in which the model could be represented by an animated agent (Wouters *et al.* 2008), there is much more opportunity for learners to attend to irrelevant details (e.g., the model's clothes, tone of voice, and salient but irrelevant objects present in the environment or on the screen) than in worked examples. Moreover, the model could be a teacher or an expert who is behaving didactically (e.g., Schunk 1981; Simon and Werner 1996), in which case—as in worked examples—the demonstrated steps might all be relevant to incorporate in the cognitive schema, but the model could also be a peer student with a lower, equal, or higher level of performance than the learner, in which case the demonstrated procedure may contain errors (e.g., Braaksma *et al.* 2002; Schunk and Hanson 1985). Below, we will discuss the consequences the difference in attentional processes has for the design of examples, but first, we will address the questions of for what kinds of tasks and learners example-based learning is effective.

For What Kinds of Tasks Is Example-Based Learning Effective?

The majority of research on worked examples has been conducted using highly structured cognitive tasks in domains such as algebra (e.g., Carroll 1994; Cooper and Sweller 1987; Mwangi and Sweller 1998; Sweller and Cooper 1985), statistics (e.g., Paas 1992; Quilici and Mayer 1996), geometry (e.g., Catrambone 1995, 1996; Paas and Van Merriënboer 1994; Schwonke *et al.* 2009; Tarmizi and Sweller 1988), or physics (e.g., Kalyuga *et al.* 2001; Reisslein *et al.* 2006; Van Gog *et al.* 2006, 2008; Ward and Sweller 1990). However, several recent studies have shown that worked examples can also be effective with less structured cognitive tasks such as learning how to apply an instructional design model (Hoogveld *et al.* 2005), learning argumentation skills (Schworm and Renkl 2007), learning to construct concept maps (Hilbert and Renkl 2009), learning to recognize designer styles (Rourke and Sweller 2009), or learning to reason about legal cases (Nievelein *et al.* 2010).

Like worked examples, modeling examples have also been used to teach highly structured cognitive skills such as math, although the focus in those studies was not only on how well students learned to solve math problems but also on how students' self-efficacy was influenced by modeling examples, which is an important difference with worked examples research (e.g., Schunk 1981; Schunk and Hanson 1985). Modeling examples have been used more often, however, to teach less structured skills such as writing (e.g., Braaksma *et al.* 2002, 2004; Couzijn 1999; Zimmerman and Kitsantas 2002), assertive communication (Baldwin 1992; Decker 1980), or collaboration (Rummel and Spada 2005; Rummel *et al.* 2009). In addition, they have been successfully used for teaching *metacognitive* skills such as self-regulation (e.g., Kitsantas *et al.* 2000; Zimmerman and

Kitsantas 2002) or (self-) assessment (Van Gog *et al.*, in press). In contrast to worked examples, modeling examples are also highly suitable and are widely used to teach (psycho)motor skills (see, e.g., Blandin *et al.* 1999; Wright *et al.* 1997). Research on the mirror neuron system has provided important insights into the underlying mechanisms of observational learning of motor skills, by showing that the same neural circuits that are involved in executing a motor action oneself, also respond to observing someone else executing that action (for a review, see Rizzolatti and Craighero 2004). It has also been shown that the neural circuits that are active when executing and observing motor actions respond when hearing sentences that describe such actions (Tettamanti *et al.* 2005) or when imagining performing such actions without actual movement (Grèzes and Decety 2001; Hurley 2008). An interesting open question is to what extent a similar mechanism might underlie learning cognitive skills from worked or modeling examples (see also Van Gog *et al.* 2009b).

Recent studies that have investigated example-based learning in the context of collaborative learning yielded somewhat inconsistent results (Chi *et al.* 2008; Craig *et al.* 2009; Kirschner *et al.* 2010; Rummel and Spada 2005; Rummel *et al.* 2009). Kirschner *et al.* showed that learning from “traditional” worked examples on a highly structured task (heredity problems) was more effective when done individually than collaboratively, whereas learning by solving conventional problems was more effective when done collaboratively than individually. They explained this in terms of the amount of cognitive load involved: because worked examples impose less cognitive load on individual learners than problem solving, the learning task can easily be performed by the individual, whereas problem solving imposes higher cognitive load, which can be shared by group members in collaborative learning situations (see also Kirschner *et al.* 2009). In contrast, Chi *et al.* showed that collaboratively observing a tutoring session and solving the same problems as the tutee in that session was more effective for learning than individual observation. Rummel and Spada, and Rummel *et al.* presented learners with modeling examples showing a collaborative process and showed that collaborative learning from examples was more effective than collaborative problem solving for the joint problem–solution and for acquiring collaboration skills. It thus seems that the type of task for which examples are used plays an important role in whether or not collaborative learning from the examples is effective.

Renkl *et al.* (2009) refer to examples that convey both task topic knowledge (e.g., biology, math) as well as skills such as argumentation, collaboration, or self-regulation as *double-content* examples and to examples that additionally convey strategic or heuristic knowledge as *triple-content* examples. Because the cognitive load imposed by such double or triple-content examples is much higher (i.e., there are more interacting information elements that need to be processed in working memory; Sweller *et al.* 1998), Renkl *et al.* argue that it is best to have learners focus their attention on only one of the content levels.

In sum, example-based learning is effective for learning a wide range of tasks and skills. There are some factors that can decrease or increase the effectiveness of examples for learning, though, such as learner characteristics and example design and delivery, which will be discussed in the following sections.

For What Kinds of Learners Is Example-Based Learning Effective?

Learning from worked examples has been studied in a wide variety of educational settings, ranging from primary school to university students and vocational/business training

programs. Even though worked examples can be effectively used at various educational levels, there are certain learner characteristics that may influence the effectiveness of examples, the most important one being prior knowledge of the task. Above, in explaining the worked example effect, it was already indicated that studying worked examples is more effective than problem solving *for novices*. Research on the “expertise reversal effect” has shown that students’ level of prior knowledge has an important influence on the effectiveness of instructional formats. Formats that are effective for learning when students have little or no prior knowledge may be less effective or ineffective for students with more knowledge and vice versa (Kalyuga 2007; Kalyuga *et al.* 2003). The high level of instructional guidance provided by worked examples, which fosters learning when no cognitive schemata are available yet, has been shown to be ineffective or even detrimental for learning when students have already developed cognitive schemata that can guide their problem solving (Kalyuga *et al.* 2001; Kalyuga and Sweller 2004). This can also occur when knowledge is acquired during the instruction phase, so it is important to dynamically adapt the amount of guidance provided to the learner’s level of knowledge (Kalyuga and Sweller 2004; see also paragraph on “fading” in the section on example delivery).

Although little research has been conducted in this area, another learner characteristic that may influence the effectiveness of worked examples is working memory capacity. Because studying worked examples tends to reduce cognitive load compared to problem solving (e.g., Nievelstein *et al.* 2010; Paas 1992; Paas and Van Merriënboer 1994; Van Gog *et al.* 2006), it may be even more effective for learners who have lower working memory capacity. Lower working memory capacity has been associated with certain learning disabilities and may also occur due to effects of aging. Van Gerven *et al.* (2002) showed that elderly participants benefitted relatively more from example study compared to problem solving than young participants.

The effects of observational learning through modeling have also been studied with different kinds of learners in a wide variety of (educational) settings. While most research has focussed on children, a number of studies have been conducted with adults, showing, for example, that modeling can increase the use of protective equipment in the workplace (Olson *et al.* 2009), can guide the selection of an effective memory strategy for college students (McGivern *et al.* 1986), and can improve writing and self-regulatory skills (Zimmerman and Kitsantas 2002). Interestingly, modeling is also effective for children with “abnormal” cognitive development. Such studies have shown that peer modeling, but not adult modeling, is effective for educable mentally retarded children (e.g., Barry and Overman 1977) and autistic children (e.g., Charlop *et al.* 1983).

Bandura (1986) has also noted the important mediating role of prior knowledge in learning from modeling examples. For instance, he emphasizes that modeled behavior that is too complex for the learner may result in fragmentary learning. In addition, he indicates that people with more expertise may recognize subtle aspects of performance that are not noticed by novices and that novices may have difficulty detecting errors because the ability to do so also relies on prior knowledge (see also Dunning *et al.* 2003), which may have the undesirable effect that novices may engage in cognitive/physical rehearsal of faulty behavior displayed by the model. Next to prior knowledge, another important learner characteristic that has been extensively studied in research on modeling examples is students’ self-efficacy (e.g., Schunk and Hanson 1985), which may differentially affect the effectiveness of different types of models (see also the paragraph on model–observer similarity in the section on example design). Some research has also addressed variables such as self-esteem and locus of control as mediating learner characteristics for observational learning (e.g., Halpin *et al.* 1979). Fouts and Click (1979) found that

extroverted children learned more than introverted children across three modeling conditions. Next to those learner characteristics, design characteristics of the examples also have the potential to reduce or enhance their effectiveness for learning.

How Should Examples Be Designed to Optimize Their Effectiveness?

Following the early studies on worked examples by Sweller and Cooper (1985) and Cooper and Sweller (1987), it was soon discovered that studying worked examples was not always more effective for learning than problem solving and that the design of the examples played a crucial role in this (Tarmizi and Sweller 1988). Research on this issue led to important design guidelines, such as *avoid split-attention* by integrating mutually referring information sources such as text and picture/diagram (Tarmizi and Sweller; this can also be done by providing spoken rather than written text with the pictorial information in the example; Mousavi *et al.* 1995) and *avoid redundancy*, that is, multiple sources of information should only be presented when they are both necessary for comprehension; when they can be easily understood in isolation, one of the sources is redundant and should be left out (see Chandler and Sweller 1991).

In addition, several other design measures have been investigated that might further enhance the effectiveness of worked examples. They do so primarily by stimulating more active processing of the examples or emphasizing important aspects of the procedure, which helps students not only to learn the problem-solving procedure but also to understand the underlying structure and rationale, which is necessary to be able to solve slightly novel problems (i.e., transfer). For example, students might be required to *complete steps* in partially worked-out examples (e.g., Paas 1992; Van Merriënboer *et al.* 2002). In mathematics or statistics worked examples, it has been shown that learning can be fostered by *making subgoals explicit* through labeling or visually isolating sets of steps (e.g., Catrambone 1995, 1996), by *comparing examples* of different (representations of) solution methods (Große and Renkl 2006; Rittle-Johnson *et al.* 2009), or by using conceptually oriented equations rather than computationally oriented equations (e.g., Atkinson *et al.* 2003a). Active processing and understanding can also be fostered by instructing students to *self-explain* the principles behind the worked-out solution steps (e.g., Chi *et al.* 1989; Renkl 1997, 2002). However, a precondition is that students are capable of providing high quality self-explanations, which is not always the case (see Chi *et al.* 1989; Lovett 1992; Renkl 1997). If this precondition is not met, providing high quality *instructional explanations* may enhance learning from examples (Lovett 1992). In providing instructional explanations, however, one should take into account that these may become redundant relatively quickly, at which point they need to be faded out or may start to hamper learning (Van Gog *et al.* 2008). Self-explanations and instructional explanations have also been studied with modeling examples. Decker (1980, 1984) has shown the effectiveness of instructional explanations (he calls them “learning points”) in video-based modeling examples that conveyed complex social skills such as conflict management skills. Rummel *et al.* (2009) incorporated instructional explanations in modeling examples and asked students to collaboratively explain after studying the example, which yielded better results than observing the modeling example without these additional instructional and self-explanations.

Some studies on worked examples have deviated from presenting a didactical solution and have used *erroneous* examples with an instruction for students to find and fix the errors (e.g., Große and Renkl 2007) or with additional *feedback* (e.g., Kopp *et al.* 2008) to stimulate students to process the examples more deeply. As mentioned before, modeling

examples that show a model's natural rather than didactical behavior are likely to contain errors and also often show the correction of those errors by the model. Baldwin (1992) investigated the use of only positive (or correct) models or a combination of positive and negative (or incorrect) modeling examples on assertive communication. The combination of positive and negative models had a positive effect on trainees' transfer performance 4 weeks later but not on immediate behavioral reproduction; trainees who had observed only positive models performed better on the behavioral reproduction task. Große and Renkl used a similar design, but with worked examples on probability calculation, and showed an interaction with students' prior knowledge: Providing both correct and incorrect solutions fostered far transfer performance for students with more prior knowledge, whereas correct solutions only worked better for students with low prior knowledge. Kopp *et al.* showed that the acquisition of diagnostic knowledge from worked examples was fostered when erroneous examples were provided in combination with elaborated feedback, but when only correct response feedback was provided, erroneous examples were detrimental for learning. Using modeling examples, Blandin and Proteau (2000) showed that observation of a model practising a motor skill allowed the observer to develop mechanisms for error detection and correction similar to those developed through physical practice. Furthermore, Badets *et al.* (2006) showed that giving an observer infrequent feedback (i.e., 50%, on every other trial) on the correctness of the model's performance enhanced the observer's own performance, as well as the observer's ability to detect errors both in the model's and his/her own performance, compared to feedback given on every trial (i.e., 100%). These findings indicate that the role of feedback in enhancing learning is similar in learning by doing and observational learning situations. An interesting finding from brain research for modeling examples (and maybe also worked examples) showing errors is that an event-related potential component called error-related negativity is found when we make a mistake ourselves and also when we observe someone making a mistake (Van Schie *et al.* 2004). Therefore, the same neural circuits are involved not only in performing actions by oneself and observing others perform those actions (Rizzolatti and Craighero 2004) but also in monitoring self-executed and observed actions.

The *imagination effect* shows that imagining or—as Bandura (1986) calls it—cognitively rehearsing the procedure presented in examples enhances learning compared to studying only—at least for students with prior knowledge. For students without prior knowledge, imagining has detrimental effects, and for them, studying the procedure is more effective (Cooper *et al.* 2001; Ginns *et al.* 2003; note that this is another instance of the expertise reversal effect; Kalyuga 2007). Bandura reviews findings that cognitive rehearsal of the observed behavior can enhance learning, provided that it is accurate and indicates that the effect is more likely to be obtained with tasks that rely on more extensive cognitive processing (see also Driskell *et al.* 1994; Feltz and Landers 1983). This was also shown by Leahy and Sweller (2005, 2008) who demonstrated that the imagination effect is more likely to be obtained with complex materials (i.e., materials that are high in intrinsic load, containing many interacting information elements; Sweller *et al.* 1998). As mentioned earlier, brain research has shown that imagining performance of motor tasks activates the same neural circuits as performing or observing those tasks (e.g., Hurley 2008).

Using modeling examples based on screen recordings from participants in problem-solving conditions (yoked design), Osman (2008) showed that the *goal-free effect* applies to example-based learning as well. The goal-free effect has been studied in cognitive load research with problem-solving tasks (e.g., Ayres 1993; Paas *et al.* 2001; Sweller and Levine 1982) and shows that learning is enhanced when students are not provided with a specific goal during problem solving. Providing students with no or a nonspecific goal is assumed

to prevent the use of means-ends analysis, thereby leading to better learning (Sweller and Levine 1982). Apparently, this benefit applies not only to the performer but also to the observer's learning (Osman).

There are a number of other design characteristics that do not play a role in worked examples but are relevant for modeling examples, such as *model–observer similarity* in sex, age, competence, or background, of which the first three have been studied most (for a review, see Schunk 1987). As Schunk notes, “similarity serves as an important source of information for gauging behavioral appropriateness, formulating outcome expectations, and assessing one's self-efficacy for learning or performing tasks” (p. 149). One source of similarity is sex, but results from studies concerning similarity in sex between models and observers are inconclusive. For instance, Bandura and Kupers (1964) found that neither the sex of the model, nor the sex of the observing child, nor the congruence in the sex of model and observer showed an influence on learning. In contrast, in a study by Bandura *et al.* (1963), sex did play an important role for learning. The decisive difference between the two studies was the content of the modeled behavior: In the former study, children observed and learned to self-reinforce for performance in a game, whereas in the latter study, children observed models perform aggressive behaviors toward a doll, so ideas about sex-appropriateness or stereotyping played a role in the latter. More recently, Weeks *et al.* (2005) found that when healthy elderly women observed physiotherapists demonstrating exercises, participants provided higher ratings of self-efficacy when their model was a female as well, but for men, the sex of their model did not prove to be of influence.

A second source of similarity is age. With children who were low achieving in mathematics, Schunk and Hanson (1985) showed that peer models were more effective than adult models (who were more effective than no models) in enhancing self-efficacy and learning outcomes. With educable mentally retarded children, Barry and Overman (1977) also found peer models to be more effective. Other studies, however, have shown no differences due to similarity in age (see also Weeks *et al.* 2005), and Schunk suggests that (perceived) competence of the model and self-efficacy may interact with similarity in age to influence model preference and learning. The model's (perceived) competence plays a role in that competent models lead to better learning than incompetent models, but as a standard for comparison or self-evaluation, equally competent models seem to be preferred (see Schunk). This is also supported by the above-cited study by Bandura and Kupers (1964): they found adult models to be more effective for children's observational learning than peers.

Related to model competence, an important factor seems to be whether the model is a mastery model displaying faultless performance or a coping model whose performance includes errors that are corrected and expressions of uncertainty that is gradually reduced. Schunk and Hanson (1985) found no differential effects of a peer coping or a peer mastery model (both were better than an adult model, which was better than no model), but Schunk *et al.* (1987) showed that coping peer models were more effective than mastery peer models and that children who observed coping peer models judged themselves to be more similar in competence to the models. Braaksma *et al.* (2002) gave learners in two observational learning conditions both good and weak peer models. The conditions differed in instruction, with one group being asked to focus on the weak model (which model did less well? Explain briefly what this model did worse) and the other on the good model (which model did well? Explain briefly what this model did well). They found that weak learners learned more from focusing on weak models, whereas better learners learned more from focusing on good models. George *et al.* (1992) investigated self-efficacy and muscular endurance of nonathletic female students after watching videotapes of a model performing a leg-

extension endurance task. Participants who watched nonathletic models reported higher self-efficacy and extended their legs significantly longer than those watching athletic models (sex of the model did not have an effect on either measure).

Related to the issue of model competence is the degree of difference in model and observer expertise. Naturally (i.e., nondidactically) behaving experts may not be the best models for cognitive tasks because they have often automated their task performance to a large extent. This not only means that they perform very fast and tend to skip steps (Blessing and Anderson 1996; Kalyuga and Sweller 2004), which might make it difficult for students to see or follow what the model is doing but also means that the model may have difficulty verbalizing what s/he is doing because the performance does not require controlled processing (Feldon 2007). It has also been suggested that the level of abstraction of instructions provided by experts may pose problems for novices' understanding and that instructions provided by somewhat advanced individuals led to better task performance (Hinds *et al.* 2001). On the other hand, the higher level of abstraction in expert instructions seemed to be more beneficial for solving novel tasks (i.e., transfer; Hinds *et al.* 2001). Moreover, expert models might be more effective for advanced students to learn from, as they might be less bothered by the skipping of steps, as their own knowledge base is closer to that of the expert and they are more likely to know what the relevant aspects of performance are that they need to attend to (cf. Bandura 1986). Therefore, an interesting question for future research is whether the level of model expertise affects learning and whether it has differential effects depending on learner expertise. A study by Boekhout *et al.* (in press) showed that both first and second year physiotherapy students learned to take patients' histories better from expert worked examples than from advanced student worked examples. However, this is not a task where knowledge automation and abstraction plays a large role, so further research would be required with tasks in which experts might use more abstract terms than advanced students, such as, for instance, in recalling or reasoning about medical cases (e.g., Rikers *et al.* 2000).

Finally, an extreme form of model–observer similarity is attained in self-modeling, in which children watch (edited) videotapes of themselves performing the model behavior, which has proven highly effective (and as effective as peer modeling) in promoting academic and behavioral skills (Schunk and Hanson 1989; for a review, see Hitchcock *et al.* 2003).

In modeling examples that consist of screen recordings with spoken text (e.g., McLaren *et al.* 2006, 2008; Rummel and Spada 2005; Rummel *et al.* 2009; Van Gog *et al.* 2009a) or in animated modeling examples with a pedagogical agent and spoken text (e.g., Atkinson 2002; Wouters *et al.* 2009), issues of perceived similarity to the model may also arise because of students' associations with the speaker's voice (e.g., sex, age). Kim (2007) found that similarity in competence also played an important role when students learned from an anthropomorphized pedagogical agent. Academically, strong students recalled more after working with a high-competent agent, while academically weak students profited more from a low-competent agent. Therefore, in these kinds of examples, even when they show a didactical procedure, model–observer similarity may play a role as well. This should be further investigated and, if necessary, be taken into account in the design of the examples.

Moreover, there are some design principles that multimedia research has shown to enhance (perceived) social presence and thereby lead to better learning: the personalization, voice, and image principles (Mayer 2005). The personalization principle means that people learn more deeply when words in a multimedia presentation are in conversational rather than formal style (e.g., using “I” and “you”), the voice principle that people learn more deeply when words in a multimedia message are spoken in a standard-accented human voice rather than a machine voice or foreign-accented human voice, and the image principle

that people do not necessarily learn more deeply when the speaker's image is present on the screen (Mayer 2005). The image principle seems to suggest that visual presence of the model is not strictly necessary for learning to be effective, which seems to be good news for screen-recording modeling examples. In fact, having the model present live or on video might have adverse effects on the learner's attention. On the one hand, eye tracking research has shown that our gaze allocation is socially directed, that is, we tend to follow another person's gaze (which is often used in magic tricks to misdirect observers' attention; Kuhn *et al.* 2008). On the other hand, eye tracking research has shown that we tend to look primarily at the person's *face* (as much as 95% of the time in face-to-face situations and 89% of the time on video), rather than at his or her gestures, for example (Gullberg and Holmqvist 2002). Although this might be different in learning situations than in “natural” situations, a study by Louwerse *et al.* (2009) on humanoid animated agents that are often used in multimedia learning materials showed that students tend to look at faces of those agents as they would at real humans, that is, they look primarily at the agent's face (study 1) or looked primarily at the agent's face when it spoke (Study 2). This might imply that in modeling examples in which the model is present, the learner's visual attention may be drawn toward the model, especially when s/he is speaking, rather than to the task aspects the model is talking about.

Finally, there are some guidelines from research on the effectiveness of animations that might be relevant for the design of screen recording or animated modeling examples. Because the information in screen recordings or animated modeling examples is often transient, students' understanding might be compromised if they do not attend to the right information at the right time because it can be gone the next moment. When the verbal explanation provided by the model is not sufficient to guide students' attention to the right information at the right time, other means of doing so are available, such as cueing (i.e., perceptually highlighting) certain information elements (for a review, see De Koning *et al.* 2009) or showing students where the model is looking by displaying the model's eye movements superimposed on the video (Van Gog *et al.* 2009a, b). The transience of information is also an important difference between worked examples and modeling examples. Worked examples generally provide learners with a complete overview of the procedure, whereas modeling examples may either build up that overview step by step (i.e., each step that is worked out remains visible, while the model works on the next step; e.g., McLaren *et al.* 2008), in which case, at the end, a complete worked example is essentially available or show only one step at a time that makes way for the next step (e.g., Spanjers, Wouters, Van Gog and Van Merriënboer *in press*; Wouters *et al.* 2009). In case of the latter, the transience of the information requires learners to maintain each presented step in working memory while attending to the step that is currently being executed and processing them in relation to each other. This is extremely cognitively demanding, especially for novice students, and might hamper learning (e.g., Ayres and Paas 2007). Segmenting such transient examples might help novices' learning because it gives them the necessary time to process information and/or makes them more aware of the structure of the problem-solving procedure (see Spanjers, Van Gog and Van Merriënboer *in press*).

How Should Examples Be Delivered to Optimize Their Effectiveness?

Although he stresses that observational learning can occur without immediate imitation taking place, Bandura (1986) also indicates that giving students the opportunity to practice the behavior themselves in between observations of modeling examples may foster learning

because practice allows them to note deficiencies in their own performance, which may increase their attention to those aspects during a future observation of a model's performance. This is, in fact, the way in which the majority of studies on the worked example effect were designed: *example–problem pairs* were used, and these were shown to be more effective for learning than engaging in problem solving only (Carroll 1994; Cooper and Sweller 1987; Kalyuga *et al.* 2001; Kalyuga and Sweller 2004; Mwangi and Sweller 1998; Sweller and Cooper 1985), at least for low ability or low prior knowledge learners (Cooper and Sweller 1987; Kalyuga *et al.* 2001). Studies on modeling examples have also implemented this principle (e.g., Simon and Werner 1996). Sweller and Cooper (1985) stated that engaging in solving a similar problem immediately after example study may be more motivating for students because it is more active than studying another example would be. As far as we know, however, there are no empirical data yet that support this suggestion.

In line with the finding that imitation does not seem to be necessary for learning, worked examples research has demonstrated that studying *examples only* is also more effective for learning than engaging in problem solving only (Nievelstein *et al.* 2010; Van Gerven *et al.* 2002; Van Gog *et al.* 2006). In fact, it can be questioned whether the opportunity to practice indeed has added value for learning: A recent study found that both examples only and example–problem pairs were more effective than problem solving and problem–example pairs, and there was no significant difference between examples only and example–problem pairs (Van Gog *et al.* 2010).

Problem–example pairs allow for noting deficiencies in students' own performance, which may increase their attention to those aspects during example study, but in the study of Van Gog *et al.* (2010), problem–example pairs were less effective for learning than example–problem pairs and examples only and did not lead to better learning than problem solving only. A possible explanation is that students are very often unable to diagnose their own performance deficiencies (for a review, see Bjork 1999). The studies by Paas (1992) and Paas and Van Merriënboer (1994) are interesting in this respect. Their problem-solving conditions were given a worked example of the same problem as feedback when they did not succeed in solving a problem within a certain time or certain number of attempts. Therefore, the example was *identical* to the problem students had just attempted to solve, which would allow students to pay attention to the exact steps that proved to be problematic for them. Nevertheless, the examples conditions (Paas 1992: two examples, then a problem; Paas and Van Merriënboer 1994: examples only) were more effective than the problem-solving condition in which examples were given as feedback when the student could not solve the problem. This suggests that those novice learners were not able to use the examples as feedback effectively, presumably because they were not able to accurately diagnose their own performance deficiencies. The ability to do so seems to be related to one's knowledge of the tasks (Dunning *et al.* 2003), which novices lack. This fits with the findings of Reisslein *et al.* (2006), who found an interaction of example–problem pairs and problem–example pairs with learners' prior knowledge: Whereas low prior knowledge learners benefited most from example–problem pairs, high prior knowledge learners benefited most from problem–example pairs. In *tutored* problem solving, however, learners can request help immediately when they experience that they cannot solve a particular step, which is unproblematic for novices and, in this case, help consisting of annotated worked examples has been shown to be more efficient (equal test performance achieved in less learning time) than help consisting of hints (Ringenberg and VanLehn 2006).

An effective delivery strategy for cognitive tasks that takes into account the learner's developing knowledge of a task (which, as described previously, affects the effectiveness of

worked examples) is the *completion or fading* strategy, in which completion problems with increasingly more steps for the learner to complete serve as a bridge between studying fully worked-out examples and problem solving (for a review, see Renkl and Atkinson 2003). Reisslein *et al.* (2006) found no overall differences between fading, problem–example pairs, and example–problem pairs, but Renkl *et al.* (2002) and Atkinson *et al.* (2003b) did find a fading strategy to be more effective than example–problem pairs, especially backward fading in which the last solution steps are omitted first in the completion problems.

Note that in motor learning, the effects of combinations of example study and practice may be very different. Shea *et al.* (2000) studied effects of physical practice only, observation (i.e., modeling examples) only, and no practice and found physical practice to be more effective than observational practice for retention, but there were no differences on transfer. However, in a second experiment, they showed that combined (alternating) physical practice and observation was more effective for transfer than physical practice only. Weeks and Anderson (2000) compared the effects of viewing 10 video-based modeling examples before practice, viewing one before practice and the others during practice (one every three attempts) and viewing five before practice and the others during (the first half of) practice (one every three attempts). The latter group attained the highest scores, followed by the all prepractice group.

Finally, another effective delivery strategy for worked examples (Paas and Van Merriënboer 1994), completion problems (Van Merriënboer *et al.* 2002), and modeling examples (Wright *et al.* 1997) is not presenting them in a typical blocked sequence by problem type or category (e.g., AAA-BBB-CCC-DDD), but in a *random sequence* (e.g., A-C-D-B-B-C-A-D-A-B-D-C). Although random sequencing tends to increase cognitive load and decrease performance during training, it does lead to better learning and transfer outcomes, so this increase in cognitive load is due to processes that are germane or effective for learning. Presumably, a random sequence challenges learners to compare the different procedures associated with the different types of problems, which may help them, for example, to learn which problem features are relevant for a certain solution procedure and which are not, whereas in a blocked schedule, only one procedure has to be kept in mind during a block of tasks (Paas and Van Merriënboer).

Conclusion

This review, which was by no means exhaustive, has discussed studies on example-based learning conducted from a cognitive and social-cognitive perspective. Table 1 provides an overview of the commonalities and differences between both lines of research that we discussed. What stands out is the wide variety of tasks, contexts, and learners for which example-based learning can be effectively applied. While this is certainly a strength because it shows that example-based learning is a widely applicable method, the heterogeneity in the kinds of examples used, the tasks for which they are used, and the learners who participate in the studies also make it difficult to draw definitive conclusions about what works, when, and for whom. For example, in the studies by Braaksma *et al.* (2002) and Kim (2007), the weaker students learned more effectively from the weak models, whereas in the study by Große and Renkl (2007), only students with more prior knowledge benefited from erroneous examples. These studies differ on so many points, however, that it is hard to draw a conclusion about what might have caused the seemingly different findings.

Table 1 Overview of the Most Prominent Commonalities and Differences Between Worked Examples and Modeling Examples Research as Discussed in This Article (i.e., Not Exhaustive)

	Worked Examples	Modeling Examples
Form	Text based	Live observation Observing a video of the model Observing a screen-capture video (model not visible) Observing an animation
Solution procedure/model	Ideal/didactical	Didactical Natural performance by peer/adult
Type of task/skill	Highly structured problems Less structured problems/tasks	Highly structured problems Less structured problems/tasks Social skills Metacognitive skills (Psycho)motor skills
Type of learner	Primary school age to adult	Primary school age to adult
Learner characteristics, effects of	Prior knowledge Aging	Prior knowledge Self-efficacy
Process/Outcome measures	Learning/retention Transfer Cognitive load Time on task	Learning/retention Transfer Self-efficacy
Design, effects of	Split-attention Redundancy Completing steps Making subgoals explicit Comparing procedures Self-explanations Instructional explanations Finding and fixing errors Imagining/cognitive rehearsal	Model sex Model age Model competence (i.e., making and/or correcting errors) Self-explanations Instructional explanations Feedback on model performance Imagining / cognitive rehearsal
Delivery, effects of	Ratio/alternation of examples and problems Fading from examples to problems Random sequencing	Ratio/alternation of examples and problems Random sequencing

We hope that future research on example-based learning will draw on both perspectives to identify and address novel research questions. Studies using examples consisting of screen captures may allow for a particularly powerful combination of both approaches. For example, an ideal procedure can be shown, and when steps are built up consecutively (e.g., McLaren *et al.* 2008), the end result is a complete worked example. In addition, there are some design guidelines that have been identified in cognitive load and worked examples research that are relevant for the design of such examples as well (e.g., avoid split-attention, avoid redundancy) and so are principles from multimedia research. Finally, even though the

model may not be visible in the screen capture, some characteristics identified in modeling examples, such as the model's age, sex, and performance (e.g., coping vs. mastery), might be relevant, as they might affect the results. Future studies from either perspective might also draw on the strong points of the other perspective. For example, research on worked examples might address effects of/on self-efficacy as a mediating or outcome variable or the effects of showing nondidactical procedures in examples (cf. Boekhout *et al.* [in press](#)), whereas research on modeling examples might address the effects of different design and delivery strategies identified as effective in worked examples research, as well as effects of modeling examples on cognitive load.

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