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Significance of Coriolis Force on Eyring-Powell Flow Over A Rotating Non-uniform Surface

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Abstract

Coriolis force plays significant roles in natural phenomena such as atmospheric dynamics, weather patterns, etc. Meanwhile, to circumvent the unreliability of Newtonian law for flows involving varying speed, Eyring-Powell fluid equations are used in computational fluid dynamics. This paper unravels the significance of Coriolis force on Eyring-Powell fluid over the rotating upper horizon-tal surface of a paraboloid of revolution. Relevant body forces are included in the Navier-Stokes equations to model the flow of non-Newtonian Eyring-Powell fluid under the influence of Coriolis force. Using similarity transformation, the governing equations are nondimensionalized, thereby transforming the nonlinear partial differential equations to a system of boundary value nonlinear ordinary differential equations. The shooting technique is adopted to convert the boundary value problem to an initial value problem, which is in turn solved using the Runge-Kutta-Gill Scheme. At low Coriolis force, temperature profiles increase as Eyring-Powell parameter increases, whereas at high Coriolis force, temperature profiles decrease with increasing Eyring-Powell parameter.

Keywords: Coriolis Force; Eyring-Powell; Non-uniform surface; Upper horizontal surface of a paraboloid of revolution; Rotating surface; Non-Newtonian fluid

MSC 2010 No.: 76F10, 76A05, 76U05, 76N20, 76A02

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1. Introduction

A fluid deforms continuously when shear stress is applied (Kaur et al. (2020); Urbina et al. (2020); Dessie and Fissha (2020): Choudhury and Ahmed (2018): Abualnaia (2018)). When shear stress (not up to the yield strength) is applied on a fluid and then removed, the fluid is expected to retract to its original form, retaining its properties. In the case that the shear stress is applied for a long time, the fluid may deform permanently. This tendency of a fluid to deform permanently is called creep. It is clear that exposing a fluid to high stress, just below its yield strength, can lead to creep. Creep occurs in paints, clay slips, cellulose derivatives, greases, etc. This kind of flow can be modeled to involve breaking two types of bond: a strong bond and a weak bond. The strong bond obeys the exponential law while the weak bond obeys the weak law. These fluids can be modeled as the Eyring-Powell fluid whose stress tensor τ is defined by the hyperbolic-sine law (Kubat and Rigdahl (1976); Linz and Dohle (1999); Powell and Eyring (1944); Urbina et al. (2020); Xu (2016); Yoon and Ghajar (1987)). Importance of Eyring-Powell fluids in physical substances includes the formation of fog, thermal insulation and underground energy transport (Babu et al. (2016); Nadeem et al. (2012); Malik et al. (2013); Mamun et al. (2016); Patel and Timol (2009); Rahimi et al. (2017); Sirohi et al. (1987)). Research carried out on Eyring-Powell fluid includes a three-dimensional flow of Eyring-Powell fluid, magnetohydrodynamic flow of Eyring-Powell, buoyancy-induced flow of Eyring-Powell fluid over different surfaces such as a plane horizontal surface, a stretching surface, inclined planes, etc. In most of the cases, it was recorded that Eyring-Powell parameter and buoyancy have a positive effect on the flow velocity but temperature responds negatively to buoyancy (Abualnaja (2018); Choudhury and Ahmed (2018); Dessie and Fissha (2020); Mushtaq et al. (2013); Agbaje et al. (2016); Koriko et al. (2017); Jafarimoghaddam (2019); Nawaz et al. (2019); Umar et al. (2019); Alsaedi et al. (2020); Kumar and Srinivas (2020); Wagas et al. (2020); Hayat et al. (2013); Javed et al. (2013); Siddiqui et al. (2014); Babu et al. (2016)). One work that contradicts most of the existing results is that of Abegunrin et al. (Abegunrin et al. (2017)) where Blasius flow of Eyring-Powell fluid over a non-uniform surface is considered. Abegunrin et al. recorded that the overall flow velocity

Coriolis force is the fictitious force responsible for the deflection of the trajectory of an object moving in a rotating frame of reference. Coriolis effect has been found to be significant in many physical and natural situations. Coriolis effect is the only perfect explanation for the changes in weather patterns, the direction of cyclonic storms, the arrangement of Earth's magnetic and electric currents in columns, etc. More so, many of the physical surfaces in nature and application are neither a horizontal plane nor a vertical plane but parabolic in nature. In order to generalize these surfaces, Animasaun (2016) introduced the upper horizontal surface of a paraboloid of revolution (*uhspr.*) which generalizes surfaces with uniform thickness (such as, the horizontal plane, vertical plane, inclined plane) and surfaces with a non-uniform thickness (such as the outer surface of a bullet, the Earth's surface, etc.). Since the proposal of this surface, several authors have carried out researches to unravel flows over surface with non-uniform surfaces (Animasaun (2016); Animasaun (2018); Hudson et al. (1978); Hussain et al. (2017); Kaur et al. (2020); Khasawneh et al. (2009); Koriko et al. (2020b); Kumar (2018); Lee et al. (2017); Liang and Chan (2005);

decreases with Eyring-Powell parameter.

Makinde and Animasaun (2016); Malik et al. (2013); Mamun et al. (2016); Mitteilungen (1972); Zin et al. (2017); Zhavoronkov et al. (1978)).

To the best of our knowledge, the flow of Eyring-Powell fluid over a rotating non-uniform surface has not been investigated. Motivated by this fact, we investigate the flow of Eyring-Powell fluid over a surface that is neither a horizontal nor a vertical nor a perfectly inclined plane is studied while taking the influence of Coriolis force into consideration. The flow configuration and the governing equations with the similarity variables and the dimensionless equations are presented in Section 2. The equations are solved numerically and the simultaneous effects of Eyring-Powell parameter, buoyancy, deformation parameter with Coriolis force are investigated. The graphs are discussed in Section 4.

2. Formulation of Governing Equations

A two-dimensional Eyring-Powell fluid flow is considered in this study. The fluid and the heated surface are assumed to be in rigid body rotation at uniform angular velocity Ω . The flow configuration is shown in Figure 1. The fluid flows over the region $y \ge 0$. As a result of the angular velocity Ω , the system produces Coriolis force $2\Omega \times V$, where the velocity V of the fluid is V = (u, v, w). The stress tensor τ is defined by the hyperbolic-sine law

$$\tau = \mu \nabla \overrightarrow{v} + \frac{1}{B} \sinh^{-1} \left(\frac{1}{C} \nabla \overrightarrow{v} \right), \tag{1}$$

where the second term is responsible for the deformation of the fluid. Using the body forces proposed by Koriko et al. (2020b) and Koriko et al. (2020a) and validate by Oke et al. (2020b) and Oke et al. (2020a), the continuity, momentum and energy equations for a two dimensional Eyring-Powell fluid are

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0, \tag{2}$$

$$u\frac{\partial u}{\partial x} + v\frac{\partial u}{\partial y} + 2\frac{\Omega\aleph w}{U_0(x+b)^{2-m}} = \frac{\mu}{\rho}\frac{\partial^2 u}{\partial y^2} + \left(\frac{m+1}{2}\right)g\beta\left(T-T_\infty\right) + \frac{1}{\rho BC}\left(1 - \frac{1}{2C^2}\left(\frac{\partial u}{\partial y}\right)^2\right)\frac{\partial^2 u}{\partial y^2} - \frac{1}{\rho}\frac{\partial p}{\partial x},\tag{3}$$

$$u\frac{\partial w}{\partial x} + v\frac{\partial w}{\partial y} - 2\frac{\Omega \aleph u}{U_0(x+b)^{2-m}} = \frac{\mu}{\rho}\frac{\partial^2 w}{\partial y^2} + \left(\frac{m+1}{2}\right)g\beta\left(T-T_\infty\right) + \frac{1}{\rho BC}\left(1 - \frac{1}{2C^2}\left(\frac{\partial w}{\partial y}\right)^2\right)\frac{\partial^2 w}{\partial y^2} - \frac{1}{\rho}\frac{\partial p}{\partial x}, \tag{4}$$

$$u\frac{\partial T}{\partial x} + v\frac{\partial T}{\partial y} = \frac{\kappa}{\rho c_P} \frac{\partial^2 T}{\partial y^2},\tag{5}$$

subject to the boundary conditions

at
$$y = A (x+b)^{\frac{1-m}{2}}$$
: $u = U_0 (x+b)^m$, $v = 0$, $w = 0$, $T = T_w$, (6)

as
$$y \to \infty : u \to 0, \ w \to 0, \ T \to T_{\infty},$$
 (7)

where μ is the coefficient of viscosity, ρ is the fluid density, g is the acceleration due to gravity, β is the coefficient of thermal expansion, T is the temperature of the fluid, c_p is the specific heat capacity, κ is the thermal conductivity and $T_w = A (x + b)^{\frac{1-m}{2}}$. The Bernoulli equation for the free stream flow of a boundary layer where there is no viscosity is given as

$$\frac{p}{\rho} + \frac{U_e^2}{2} = \text{constant} \ \Rightarrow \ \frac{\partial}{\partial x} \left(\frac{p}{\rho} + \frac{U_e^2}{2} \right) = 0 \ \Rightarrow \ -\frac{1}{\rho} \frac{\partial p}{\partial x} = 0.$$



Figure 1. Flow configuration

The governing equations are rendered dimensionless by using the similarity variables

$$u = \frac{\partial \psi}{\partial y}, \ v = -\frac{\partial \psi}{\partial x}, \ w(\eta) = U_0 \left(x+b\right)^m h(\eta), \ \theta = \frac{T-T_\infty}{T_w - T_\infty},\tag{8}$$

$$\psi = \left(\frac{2}{m+1}\right)^{\frac{1}{2}} (\nu U_0)^{\frac{1}{2}} (x+b)^{\frac{m+1}{2}} f(\eta), \eta = y \left(\frac{m+1}{2} \frac{U_0}{\nu}\right)^{\frac{1}{2}} (x+b)^{\frac{m-1}{2}}, \tag{9}$$

and the nondimensionalized equations become

$$\left(1 + \epsilon - \epsilon \delta\left(\frac{m+1}{2}\right) f''^2\right) f''' - \frac{2m}{m+1} f'^2 + f'' f - \frac{K}{(m+1)} h + Gr\theta = 0,$$
(10)

$$\left(1 + \epsilon - \epsilon \delta\left(\frac{m+1}{2}\right)h'^{2}\right)h'' - \frac{2m}{m+1}hf' + h'f + \frac{K}{(m+1)}f' + Gr\theta = 0,$$
(11)

$$\theta'' + Prf\theta' - Pr\left(\frac{1-m}{m+1}\right)f'\theta = 0, \qquad (12)$$

with the boundary conditions

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at
$$\eta = \chi$$
: $f' = 1, \ f = \left(\frac{1-m}{m+1}\right)\chi, \ h = 0, \ \theta = 1,$ (13)

as
$$\eta \to \infty : f' \to 0, \ h \to 0, \ \theta \to 0,$$
 (14)

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where

$$\epsilon = \frac{1}{\mu BC}, \ \delta = \frac{U_0^3}{2\nu C^2} \left(x+b\right)^{(3m-1)},\tag{15}$$

$$K = \frac{4\Omega}{U_0^2 (x+b)}, \ Gr = \frac{g\beta \left(T_w - T_\infty\right)}{U_0^2 \left(x+b\right)^{2m-1}},\tag{16}$$

$$Pr = \frac{\rho c_P \nu}{\kappa}, \quad \chi = A \left(\frac{m+1}{2} \frac{U_0}{\nu}\right)^{\frac{1}{2}}$$
(17)

K is the rotational parameter, Gr is Grashof number, Pr is Prandtl number, χ is the thickness parameter, m is the surface non-uniformity index and ϵ , and δ are the Eyring-Powell parameters. The quantities of practical interest are the coefficients of skin friction along the x- and z-directions and the heat transfer rate and they are defined respectively as

$$Re_{x}^{\frac{1}{2}}C_{fx} = F''(0),$$

$$Re_{x}^{\frac{1}{2}}C_{fz} = H'(0),$$

$$Re_{x}^{-\frac{1}{2}}N_{ux} = -\Theta'(0)$$

3. Numerical Solution

Analytical approach, semi-analytical approach and numerical approach are the three methods adopted for solving differential equations (Oke (2017)). However, analytical methods are not always feasible due to the non-linearity of models generated from physical and industrial applications; this makes semi-analytical and numerical approaches the most viable tools. In this study, a numerical approach is adopted to unravel the dynamics of the flow under consideration. The Runge-Kutta Gill Formula is used. This scheme involves using the fourth-order Runge Kutta method alongside some constants introduced by Gill. The method is described for an ordinary differential equation of the form

$$y' = f(y), \ y(t_0) = y_0,$$

as

$$\begin{aligned} k_1 &= hf\left(y_n\right), \ k_2 &= hf\left(y_n + \frac{1}{2}k_1\right), \\ k_3 &= hf\left(y_n + ak_1 + bk_2\right), \ k_4 &= hf\left(y_n + ck_2 + dk_3\right), \\ y_{n+1} &= y_n + \frac{1}{6}\left(k_1 + 2bk_2 + 2dk_3 + k_4\right), \end{aligned}$$

where

$$a = \frac{\sqrt{2}-1}{2}, \ b = \frac{2-\sqrt{2}}{2}, \ c = \frac{\sqrt{2}}{2}, \ d = \frac{\sqrt{2}+2}{2},$$

which is stable for $h \leq (2.8/\lambda)$. As $\epsilon \to 0$ and $\delta \to 0$, the flow reduces to the one considered in (Koriko et al. (2020b)). The results of this study is validated by comparing with the results of Koriko et al. (2020b) and the comparison is shown in Table 1.

K		$f^{\prime\prime}\left(0 ight)$		$h^{\prime}\left(0 ight)$	- heta'(0)	
	Present	(Koriko et al. (2020b))	Present	(Koriko et al. (2020b))	Present	(Koriko et al. (2020b))
0	-0.314749068	-0.314749068	0.615690322	0.615690322	3.439015982	3.439015982
0.1	-0.320716879	-0.320716880	0.672570086	0.672570086	3.437631190	3.437631200
0.2	-0.329661029	-0.329661030	0.729005666	0.729005666	3.435503462	3.435503462
0.3	-0.341459563	-0.341459563	0.784465936	0.784465933	3.432658578	3.432658578
0.4	-0.355891566	-0.355891570	0.838434304	0.838434301	3.429141050	3.429141050
0.5	-0.372633523	-0.372633523	0.890450675	0.890450673	3.425020944	3.425020944

Table 1. Validation of results for coefficients of friction and heat transfer coefficients

4. Results and Discussion

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Equations governing the flow of Eyring-Powell fluid over a rotating non-uniform surface are formulated as partial differential equations in Equation 2 through Equation 5 and the similarity variables in equation 8 through Equation 9 are used to render them dimensionless as the ordinary differential equations in Equation 10 through Equation 12. Since the analytical solution of the governing equations is difficult to obtain (Oke (2017)), the dynamics of the flow as Coriolis force increases from low to moderately high is studied by numerically solving Equation 10 through Equation 12 using Runge-Kutta-Gills method alongside Shooting Technique and the results are illustrated as graphs. Specifically, the effects of Grashof number Gr (i.e. buoyancy), velocity index m (surface non-uniformity index), Eyring-Powell parameter ϵ (rate of fluid deformation) and Prandtl number Pr (ratio of momentum diffusivity to thermal diffusivity) as Coriolis effect increases are analyzed.

The effects of Coriolis force is measured by increasing the rotational parameter K which is proportional to the Coriolis force. By fixing all flow conditions such that Gr = 5, Pr = 2.0, m = 0.3, $\epsilon = 0.1$, $\delta = 0.1$, and $\chi = 0.25$, the effects of Coriolis force on the flow are studied. The counterclockwise rotation of the surface (as shown in Figure 1) reduces the kinetic energy of the fluid parcels in the positive z-direction. The variation in the kinetic energy causes the velocity profile in the x-direction to reduce as Coriolis force increases (as illustrated in Figure 2) and the velocity profile in the z-direction to increase as Coriolis force increases (as illustrated in Figure 3). More energy is added to the system as Coriolis force increases (see Figure 4 and the zoomed portion in 5). It is important to mention that the rotation parameter cannot exceed a certain value (which in this case is 0.5), otherwise the flow becomes turbulent and the Coriolis effects become difficult to measure. It appears that there are periodic solutions at 0.5 < K < 1.0 and no unique solution at K > 1.0.

The Grashof number measures buoyancy effect on the flow. In this study, buoyancy effect is measured on the flow by setting Pr = 2.0, m = 0.3, $\epsilon = 0.1$, $\delta = 0.1$, and $\chi = 0.25$ and increasing the Grashof number. Buoyancy converts the heat energy to internal kinetic energy for the fluid particles. It is therefore expected that the velocity profiles in both directions are enhanced and this is supported by Figure 6 and Figure 7 where the velocity profiles in x- and z-directions respectively increase as Grashof number increases. As a result of this, as Coriolis force increases

alongside Grashof number, the effect of Grashof number is impeded on velocity profiles in the x-direction but enhanced on velocity profiles in the z-direction. Hence, it is valid to ascertain that the maximum velocity profile in the x-direction is obtained at high Grashof number but low Coriolis force. More so, the maximum velocity profile in the z-direction is obtained at high Grashof number and high Coriolis force. More so, it is clear that heat energy is converted causing a reduction in temperature profiles as observed in Figure 8. It is also observed from Figure 8 that increasing Coriolis force impedes the decreasing effect of Grashof number on the temperature profiles, hence maximum temperature profile is obtained at high Coriolis force but low Grashof number.

A continuous increase of the surface non-uniformity index m from 0 to 1 gradually changes the surface from the upper horizontal surface of a paraboloid of revolution to a flat sheet. To study the effect of the surface non-uniformity index m, other parameters are set as Gr = 5, Pr = 2.0, $\epsilon = 0.1, \delta = 0.1, \text{ and } \chi = 0.25$. It is worth mentioning that as m increases from 0 to 1, the nonuniformity is gradually removed and the required energy for climbing the non-uniformity reduces. The system does less work and the fluid flow is enhanced in all direction. Figure 9 and Figure 10 show that the velocity profiles in the x- and z-directions increase respectively as the surface non-uniformity index m increases. It is also observed that increasing Coriolis force counters the effect of increasing surface non-uniformity index m on the velocity profiles in the x-direction (see Figure 9), hence maximum velocity profile in the x-direction is obtained on a slowly rotating uniform surface but maximum velocity profile in the z-direction is obtained on a moderately fastrotating uniform surface. Meanwhile, increasing Coriolis force magnifies the effect of increasing surface non-uniformity index m on the velocity profiles in the z-direction (see (10)). Figure 11 shows that the temperature profile also increases with increasing surface non-uniformity index m. It is remarked here that the maximum temperature profile is obtained on a moderately fast-rotating uniform surface.

The Eyring-Powell parameter ϵ measures the rate of deformation of the fluid and the fluid becomes Newtonian as $\epsilon \to 0$. It is worthwhile to note that shear thinning occurs with the increase in the value of ϵ . From Figure 12, it is revealed that velocity profiles in the x-direction increases as Eyring-Powell parameter ϵ increases. A shown in Figure 13, as Eyring-Powell parameter ϵ increases, velocity profiles in the z-direction decreases within the boundary layer but increases at the free stream. It is valid to remark that the minimum velocity profile in the x-direction occurs as $\epsilon \to 0$ (i.e., Newtonian flow) at high Coriolis force and the maximum velocity profile in the z-direction occurs as $\epsilon \to 0$ (i.e Newtonian flow) at high Coriolis force. It can be seen from Figure 14 (the zoomed portion is shown in Figure 15) that the temperature profiles respond to increasing Eyring-Powell parameter ϵ differently at different Coriolis force. At low Coriolis force, temperature profiles increase as Eyring-Powell parameter ϵ increases whereas at high Coriolis force, temperature profiles decrease with increasing Eyring-Powell parameter ϵ .

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Figure 2. Effect of increasing Coriolis force on the velocity profile in the x-direction



Figure 3. Effect of increasing Coriolis force on the velocity profile in the z-direction



Figure 4. Effect of increasing Coriolis force on the temperature profile



Figure 5. Zoomed portion of Figure 4

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Figure 6. Effect of Grashof number Gr on velocity profiles in the x-direction at low and large Coriolis force



Figure 7. Effect of Grashof number Gr on velocity profiles in the z-direction at low and large Coriolis force



Figure 8. Effect of Grashof number Gr on temperature profiles at low and large Coriolis force



Figure 9. Effect of velocity index m on velocity profiles in the x-direction at low and large Coriolis force



Figure 10. Effect of velocity index m on velocity profiles in the z-direction at low and large Coriolis force



Figure 11. Effect of velocity index m on temperature profiles at low and large Coriolis force



Figure 12. Effect of Eyring-Powell parameter ϵ on velocity profiles in the x-direction at low and large Coriolis force



Figure 13. Effect of Eyring-Powell parameter ϵ on velocity profiles in the z-direction at low and large Coriolis force



Figure 14. Effect of Eyring-Powell parameter ϵ on temperature profiles at low and large Coriolis force



Figure 15. Zoomed portion of Figure 14

As shown in Table 2, the coefficient of skin friction in both x- and z-directions and the heat transfer rate decrease with increasing Eyring-Powell parameter and increase in the Coriolis force causes a further decrease. It can be seen from Table 3 that increase in Grashof number causes

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an increase in the coefficient of skin friction in both x- and z-direction and the heat transfer rate. Meanwhile, as Coriolis force increases, the coefficient of skin friction in z-direction and the heat transfer rate decreases while the coefficient of skin friction in both x-direction and the heat transfer rate increase the more. The effect of Coriolis force on the coefficient of skin friction in both x- and z-direction and the heat transfer rate when all other parameters are fixed is shown in Table 4. It is clear that increase in rotation leads to a decrease in the coefficient of skin friction in both x-direction and the heat transfer rate but an increase in the coefficient of skin friction in the z-direction.

K	Gr	m	ϵ	C_{fx}	C_{fz}	N_{ux}
0.01	5.0	0.3	0.1	0.6787	1.7097	1.6562
0.01	5.0	0.3	0.5	0.4508	1.3257	1.6468
0.01	5.0	0.3	0.9	0.3147	1.0685	1.6410
0.50	5.0	0.3	0.1	0.5687	2.0801	1.6334
0.50	5.0	0.3	0.5	0.3692	1.6398	1.6291
0.50	5.0	0.3	0.9	0.2517	1.3260	1.6269

Table 2. Variation of quantities of interest with Eyring-Powell parameter ϵ at low and at high rotation

Table 3. Variation of quantities of interest with Grashof number Gr at low and at high rotation

K	m	ϵ	Gr	C_{fx}	C_{fz}	N_{ux}
0.01	0.3	0.1	5	0.6772	1.6912	1.6562
0.01	0.3	0.1	10	1.9702	3.1026	1.7703
0.01	0.3	0.1	15	3.1796	4.4358	1.8574
0.01	0.3	0.1	20	4.3613	5.768	1.9299
0.5	0.3	0.1	5	0.5682	2.0465	1.6334
0.5	0.3	0.1	10	1.8313	3.5422	1.7476
0.5	0.3	0.1	15	3.0171	4.9572	1.8352
0.5	0.3	0.1	20	4.1752	6.3879	1.9082

Table 4. Variation of quantities of interest with Coriolis force

K	χ	C_{fx}	C_{fz}	N_{ux}
0.001	0.25	0.6786	1.6848	1.6564
0.1	0.25	0.6621	1.7559	1.6532
0.3	0.25	0.6206	1.901	1.6447
0.5	0.25	0.5682	2.0465	1.6334

5. Conclusion

The flow of Eyring-Powell non-Newtonian fluid over a rotating non-uniform surface is studied and the combined effect of the pertinent parameters and Coriolis force are investigated. The outcomes are listed below.

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- (1) Effects of increasing Coriolis force under constant conditions are:
 - reduction in velocity profiles in the x-direction.
 - increase in velocity profiles in the z-direction.
- (2) Effects of simultaneous increase in both Grashof number and Coriolis force are:
 - the maximum velocity profile in the x-direction is obtained at high Grashof number but low Coriolis force.
 - the maximum velocity profile in the *z*-direction is obtained at high Grashof number and high Coriolis force.
 - the maximum temperature profile is obtained at high Coriolis force but low Grashof number.
- (3) As the surface becomes more uniform:
 - (a) the maximum velocity profile in the x-direction is obtained on a slowly rotating uniform surface
 - (b) the maximum velocity profile in the z-direction is obtained on a moderately fast rotating uniform surface.
 - (c) the maximum temperature profile is obtained on a moderately fast rotating uniform surface.
- (4) Effects of Eyring-Powell parameter are:
 - (a) the minimum velocity profile in the x-direction occurs for a Newtonian flow at high Coriolis force
 - (b) the maximum velocity profile in the z-direction occurs for a Newtonian flow at high Coriolis force.
 - (c) at low Coriolis force, temperature profiles increase as Eyring-Powell parameter ϵ increases whereas at high Coriolis force, temperature profiles decrease with increasing Eyring-Powell parameter ϵ .

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