

UNIVERSITI PUTRA MALAYSIA

DIRECT BLOCK METHODS FOR SOLVING SPECIAL SECOND ORDER ORDINARY DIFFERENTIAL EQUATIONS AND THEIR PARALLEL IMPLEMENTATIONS

## YAP LEE KEN

FS 200818

DIRECT BLOCK METHODS FOR SOLVING SPECIAL SECOND ORDER ORDINARY DIFFERENTIAL EQUATIONS AND THEIR PARALLEL IMPLEMENTATIONS

By

YAP LEE KEN

Thesis Submitted to the School of Graduate Studies, Universiti Putra Malaysia, in Fulfilment of the Requirements for the Degree of Master of Science

# Abstract of thesis presented to the Senate of Universiti Putra Malaysia in fulfilment of the requirement for the degree of Master of Science 

# DIRECT BLOCK METHODS FOR SOLVING SPECIAL SECOND ORDER ORDINARY DIFFERENTIAL EQUATIONS AND THEIR PARALLEL IMPLEMENTATIONS 

By<br>\section*{YAP LEE KEN}

March 2008

Chair : Associate Professor Dr Fudziah Binti Ismail, PhD<br>Faculty : Science

This thesis focuses mainly on deriving block methods of constant step size for solving special second order ODEs. The first part of the thesis is about the construction and derivation of block methods using linear difference operator. The regions of stability for both explicit and implicit block methods are presented. The numerical results of the methods are compared with existing methods. The results suggest a significant improvement in efficiency of the new methods.

The second part of the thesis describes the derivation of the $r$-point block methods based on Newton-Gregory backward interpolation formula. The numerical results of explicit and implicit $r$-point block methods are presented to illustrate the effectiveness of the methods in terms of total number of steps taken, accuracy and execution time. Both the explicit and implicit methods are more efficient compare to the existing method.

The $r$-point block methods that calculate the solution at $r$-point simultaneously are suitable for parallel implementation. The parallel codes of the block methods for the solution of large systems of ODEs are developed. Hence the last part of the thesis discusses the parallel execution of the codes.

The parallel algorithms are written in C language and implemented on Sun Fire V1280 distributed memory system. The fine-grained strategy is used to divide a computation into smaller parts and assign them to different processors. The performances of the $r$-point block methods using sequential and parallel codes are compared in terms of the total steps, execution time, speedup and efficiency. The parallel implementation of the new codes produced better speedup as the number of equations increase. The parallel codes gain better speedup and efficiency compared to sequential codes.

# Abstrak tesis yang dikemukakan kepada Senat Universiti Putra Malaysia sebagai memenuhi keperluan untuk ijazah Master Sains. <br> KAEDAH BLOK LANGSUNG BAGI MENYELESAIKAN PERSAMAAN PEMBEZAAN KHAS PERINGKAT KEDUA DAN IMPLEMENTASINYA SECARA SELARI 

Oleh

## YAP LEE KEN

March 2008

Pengerusi : Associate Professor Dr Fudziah Binti Ismail, PhD<br>Fakulti : Sains

Tumpuan utama tesis ini adalah untuk menerbitkan kaedah blok dengan saiz langkah malar untuk menyelesaikan persamaan pembezaan khas secara langsung. Bahagian pertama tesis ini adalah berkaitan dengan pembentukan dan terbitan kaedah blok dengan menggunakan pengoperasi beza linear. Rantau kestabilan untuk kedua-dua kaedah tersirat dan kaedah tak tersirat turut dipersembahkan. Keputusan berangka kaedah tersebut dibandingkan dengan kaedah yang sedia ada. Keputusan berangka menunjukkan penambahbaikan yang ketara dalam kecekapan kaedah baharu tersebut.

Bahagian kedua tesis ini menghuraikan terbitan kaedah blok $r$-titik berdasarkan formula sisipan belakang Newton-Gregory. Keputusan kaedah $r$-titik tersirat dan kaedah $r$-titk tak tersirat telah ditunjukkan untuk mengilustrasi keberkesanan
kaedah dari segi jumlah langkah yang diambil, kejituan dan masa pelaksanaan. Kedua-dua kaedah tersirat dan kaedah tak tersirat adalah lebih cekap berbanding dengan kaedah yang sedia ada.

Kaedah blok $r$-titik yang mengira penyelesaian pada $r$-titik serentak adalah sesuai untuk implementasi selari. Kaedah blok dengan kod selari untuk penyelesaian sistem persamaan pembezaan telah dibangunkan. Seterusnya bahagian akhir tesis ini membincangkan kod implementasi selari tersebut.

Algoritma selari ditulis dalam bahasa C dan dilaksana di sistem memori bertaburan Sun Fire V1280. Strategi fine-grained digunakan untuk membahagi perhitungan ke bahagian-bahagian kecil dan menugaskan bahagian-bahagian kecil ini ke pemproses yang berlainan. Implementasi kaedah blok $r$-titik yang menggunakan kod jujukan dan kod selari dibandingkan dari segi jumlah langkah, masa pelaksanaan, kecepatan dan keberkesanan. Kod selari kaedah baru menghasilkan kecepatan yang lebih baik apabila bilangan persamaan bertambah. Kod selari mencapai kecepatan dan kecekapan yang lebih baik berbanding dengan kod jujukan.

## ACKNOWLEDGEMENTS

First and foremost, I would like to show my deepest appreciation and gratitude to the Chairman of the Supervisory Committee, Associate Professor Dr Fudziah Binti Ismail for her invaluable assistance, advice and guidance throughout the duration of the studies. I also wish to express my sincere thank to Associate Professor Dr Mohamed Bin Othman and Yang Berbahagia Professor Dato’ Dr Mohamed Bin Suleiman for their guidance towards the successful completion of the thesis.

Special thanks due to Universiti Putra Malaysia for providing the financial support in the form of Graduate Research Assistantship throughout the duration of my studies. The guidance and advice of Dr Zanariah Binti Majid are gratefully acknowledged.

Finally my deepest appreciation goes to my beloved family especially my parents for their unconditional love, support and understanding throughout the course of my studies. I also would like to thank my friends for their understanding support and encouragement throughout the course of my research.

I certify that an Examination Committee has met on 24 March 2008 to conduct the final examination of Yap Lee Ken on her degree thesis entitled "DIRECT BLOCK METHODS FOR SOLVING SPECIAL SECOND ORDER ORDINARY DIFFERENTIAL EQUATIONS AND THEIR PARALLEL IMPLEMENTATIONS" in accordance with Universiti Pertanian Malaysia (Higher Degree) Act 1980 and Universiti Pertanian Malaysia (Higher Degree) Regulations 1981. The Committee recommends that the student be awarded the Master of Science.

Members of the Examination Committee were as follows:

Malik Hj. Abu Hassan, PhD

Professor
Faculty of Science
University Putra Malaysia
(Chairman)
Zainiddin K. Eshkuvatov, PhD
Lecturer
Faculty of Science
Universiti Putra Malaysia
(Internal Examiner)

## Norihan Binti Md. Ariffin, PhD

Senior Lecturer
Faculty of Science
Universiti Putra Malaysia
(Internal Examiner)

Norhashidah Hj. Mohd. Ali, PhD

Associate Professor
School of Mathematical Sciences
Universiti Science Malaysia
(External Examiner)

Date:

This thesis was submitted to the Senate of Universiti Putra Malaysia and has been accepted as fulfilment of the requirement for the degree of Master of Science. The members of the Supervisory Committee were as follows:

## Fudziah Ismail, PhD

Associate Professor
Faculty of Science
Universiti Putra Malaysia
(Chairman)

Mohamed Suleiman, PhD
Professor
Faculty of Science
Universiti Putra Malaysia
(Member)

## Mohamed Othman, PhD

Associate Professor
Faculty of Science Computer and Information Technology
Universiti Putra Malaysia
(Member)

# AINI IDERIS, PhD <br> Professor and Dean <br> School of Graduate Studies <br> Universiti Putra Malaysia 

Date:

## DECLARATION

I declare that the thesis is my original work except for quotations and citations which have been duly acknowledged. I also declare that it has not been previously, and is not concurrently, submitted for any other degree at Universiti Putra Malaysia or at any other institution.

YAP LEE KEN
Date: 15 May 2008

TABLE OF CONTENTS
Page
ABSTRACT ..... ii
ABSTRAK ..... iv
ACKNOWLEDGEMENTS ..... vi
APPROVAL ..... vii
DECLARATION ..... ix
LIST OF TABLES ..... xiii
LIST OF FIGURES ..... xix
LIST OF ABBREVIATIONS ..... xxiv
CHAPTER
1 INTRODUCTION TO NUMERICAL ORDINARY DIFFERENTIAL EQUATIONS (ODEs) AND PARALLEL COMPUTING ..... 1
1.1 Introduction to numerical ODEs ..... 2
1.2 Linear Multistep Method ..... 3
1.3 Divided Differences ..... 9
1.4 Newton-Gregory Backward Interpolation Formula ..... 10
1.5 Introduction to Parallel Computing ..... 13
1.6 Parallel Architecture ..... 13
1.7 Sun Fire V1280 Architecture ..... 16
1.8 Parallel Algorithms in IVP Solvers ..... 18
1.9 Performance Metrics of Parallel Algorithms ..... 19
1.9.1 Execution Time ..... 20
1.9.2 Speedup ..... 20
1.9.3 Efficiency ..... 21
1.10 Problem Statement ..... 21
1.11 Objectives of the Studies ..... 22
2 LITERATURE REVIEW ..... 23
2.1 Background to Numerical Multistep Methods ..... 23
2.2 Survey on Block Methods ..... 24
2.3 Review on Implementation of Predictor-Corrector Methods ..... 25
2.4 Review on Parallel Implementation ..... 26
2.5 Literature on Performance Analysis ..... 28
3 DERIVATION OF MULTISTEP BLOCK METHODS USING LINEAR DIFFERENCE OPERATOR ..... 29
3.1 Introduction ..... 29
3.2 Derivation of Explicit 3-Point 1-Block Method ..... 32
3.2.1 Stability of Explicit 3-Point 1-Block Method ..... 34
3.2.2 Test Problems ..... 36
3.2.3 Numerical Results ..... 38
3.2.4 Discussion ..... 43
3.3 Derivation of Implicit 3-Point 1-Block Method ..... 45
3.3.1 Stability of Implicit 3-Point 1-Block Method ..... 49
3.3.2 Numerical Results ..... 50
3.3.3 Discussion ..... 54
4 EXPLICIT R-POINT BLOCK METHODS INBACKWARD DIFFERENCE FORM FOR SOLVINGSPECIAL SECOND ORDER ODEs DIRECTLY56
4.1 Introduction ..... 56
4.2 Derivation of First Point of Explicit Block Method ..... 57
4.3 Derivation of Second Point of the Explicit Block Method ..... 62
4.4 Derivation of Third Point of the Explicit Block Method ..... 65
4.5 Derivation of Explicit R-Point Block Method ..... 68
4.6 Stability ..... 69
4.7 Test Problems ..... 71
4.8 Numerical Results ..... 71
4.9 Discussion I ..... 88
4.9.1 Total number of steps taken ..... 88
4.9.2 Accuracy ..... 88
4.9.3 Execution Time ..... 90
4.10 Numerical Results II ..... 91
4.11 Discussion II ..... 98
5 IMPLICIT R-POINT BLOCK METHODS IN BACKWARD DIFFERENCE FORM FOR SOLVING SPECIAL SECOND ORDER ODEs DIRECTLY ..... 99
5.1 Introduction ..... 99
5.2 Derivation of First Point of Implicit Block Method ..... 99
5.3 Derivation of Second Point of Implicit Block Method ..... 103
5.4 Derivation of Third Point of Implicit Block Method ..... 107
5.5 Derivation of Implicit R-Point Block Method ..... 111
5.6 Test Problems ..... 113
5.7 Numerical Results I ..... 113
5.8 Discussion I ..... 129
5.8.1 Total Number of Steps Taken ..... 129
5.8.2 Accuracy ..... 129
5.8.3 Execution Time ..... 131
5.9 Numerical Results II ..... 132
5.10 Discussion II ..... 139
6 PARALLEL EXPLICIT AND IMPLICIT BLOCK ALGORITHMS ..... 140
6.1 Introduction ..... 140
6.2 Problem Description and Objectives ..... 141
6.3 Parallel Algorithms for Explicit Block Methods ..... 142
6.3.1 Parallel Implementation of Explicit 2-Point Block Method ..... 142
6.3.2 Parallel Implementation of Explicit 3-Point Block Method ..... 146
6.4 Parallel Algorithms for Implicit Block Methods ..... 148
6.4.1 Parallel Implementation of Implicit 2-Point Block Method ..... 148
6.4.2 Parallel Implementation of Implicit 3-Point Block Method ..... 153
6.5 Test Problems ..... 155
6.6 Numerical Results ..... 156
6.7 Discussion ..... 180
6.7.1 Total Number of Steps Taken ..... 180
6.7.2 Execution Time ..... 180
6.7.3 Speedup ..... 181
6.7.4 Efficiency ..... 183
6.8 Summary ..... 184
7 CONCLUSION AND FUTURE WORK ..... 185
7.1 Conclusion ..... 185
7.2 Future Work ..... 186
BIBLIOGRAFY ..... 188
BIODATA OF STUDENT ..... 192
LIST OF PUBLICATIONS ..... 193

## LIST OF TABLES

Table Page
3.1 Performance comparison between E2P1B and E3P1B for solving Problem 3.1 of special second order ODEs ..... 40
3.2 Performance comparison between E2P1B and E3P1B for solving Problem 3.2 of special second order ODEs ..... 40
3.3 Performance comparison between E2P1B and E3P1B for solving Problem 3.3 of special second order ODEs ..... 41
3.4 Performance comparison between E2P1B and E3P1B for solving Problem 3.4 of special second order ODEs ..... 41
3.5 Performance comparison between E2P1B and E3P1B for solving Problem 3.5 of special second order ODEs ..... 42
3.6 Performance comparison between E2P1B and E3P1B for solving Problem 3.6 of special second order ODEs ..... 42
3.7 Performance comparison between I2P1B and I3P1B for solving Problem 3.1 of special second order ODEs ..... 51
3.8 Performance comparison between I2P1B and I3P1B for solving Problem 3.2 of special second order ODEs ..... 51
3.9 Performance comparison between I2P1B and I3P1B for solving Problem 3.3 of special second order ODEs ..... 52
3.10 Performance comparison between I2P1B and I3P1B for solving Problem 3.4 of special second order ODEs ..... 52
3.11 Performance comparison between I2P1B and I3P1B for solving Problem 3.5 of special second order ODEs ..... 53
3.12 Performance comparison between I2P1B and I3P1B for solving Problem 3.6 of special second order ODEs ..... 53
4.1 Integration coefficients of the first point for explicit block method ..... 61
4.2 Integration coefficients of the second point for explicit block method ..... 64
4.3 Integration coefficients of the third point for explicit block method ..... 67
4.4 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.1 of special second order ODEs when $k=4$ ..... 73
4.5 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.1 of special second order ODEs when $k=6$ ..... 73
4.6 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.1 of special second order ODEs when $k=9$ ..... 74
4.7 Performance comparison between E1PN, E2PBN andE3PBN for solving Problem 3.2 of special second orderODEs when $k=4$
4.8 Performance comparison between E1PN, E2PBN andE3PBN for solving Problem 3.2 of special second orderODEs when $k=6$75
4.9 Performance comparison between E1PN, E2PBN andE3PBN for solving Problem 3.2 of special second orderODEs when $k=9$
4.10 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.3 of special second order ODEs when $k=4$ ..... 76
4.11 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.3 of special second order ODEs when $k=6$ ..... 76
4.12 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.3 of special second order ODEs when $k=9$ ..... 77
4.13 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.4 of special second order ODEs when $k=4$ ..... 77
4.14 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.4 of special second order ODEs when $k=6$ ..... 78
4.15 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.4 of special second order ODEs when $k=9$ ..... 78
4.16 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.5 of special second order ODEs when $k=4$ ..... 79
4.17 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.5 of special second order ODEs when $k=6$ ..... 79
4.18 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.5 of special second order ODEs when $k=9$ ..... 80
4.19 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.6 of special second order ODEs when $k=4$ ..... 80
4.20 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.6 of special second order ODEs when $k=6$
4.21 Performance comparison between E1PN, E2PBN and E3PBN for solving Problem 3.6 of special second order ODEs when $k=9$
4.22 Performance comparison between E1PN, E2PBN, E3PBN and E1PO, E2PBO, E3PBO for solving Problem 3.1 of special second order ODEs when $k=4$ ..... 92
4.23 Performance comparison between E1PN, E2PBN, E3PBN and E1PO, E2PBO, E3PBO for solving Problem 3.2 of special second order ODEs when $k=4$
4.24 Performance comparison between E1PN, E2PBN, E3PBNand E1PO, E2PBO, E3PBO for solving Problem 3.3 ofspecial second order ODEs when $k=4$
4.25 Performance comparison between E1PN, E2PBN, E3PBN and E1PO, E2PBO, E3PBO for solving Problem 3.4 of special second order ODEs when $k=4$95
4.26 Performance comparison between E1PN, E2PBN, E3PBN and E1PO, E2PBO, E3PBO for solving Problem 3.5 of special second order ODEs when $k=4$ ..... 96
4.27 Performance comparison between E1PN, E2PBN, E3PBN and E1PO, E2PBO, E3PBO for solving Problem 3.6 of special second order ODEs when $k=4$ ..... 97
5.1 Integration coefficients of the first point of the implicit block method ..... 102
5.2 Integration coefficients of the second point of the implicit block method ..... 106
5.3 Integration coefficients of the third point of the implicit block method ..... 110
5.4 Performance comparison between I1PN, I2PBN and I3PBNfor solving Problem 3.1 of special second order ODEs when$k=4$
5.5 Performance comparison between I1PN, I2PBN and I3PBNfor solving Problem 3.1 of special second order ODEs when$k=6$114
5.6 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.1 of special second order ODEs when $k=9$ ..... 115
5.7 Performance comparison between I1PN, I2PBN and I3PBNfor solving Problem 3.2 of special second order ODEs when$k=4$
5.8 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.2 of special second order ODEs when $k=6$116
5.9 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.2 of special second order ODEs when $k=9$
5.10 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.3 of special second order ODEs when $k=4$117
5.11 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.3 of special second order ODEs when $k=6$117
5.12 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.3 of special second order ODEs when $k=9$
5.13 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.4 of special second order ODEs when $k=4$ ..... 118
5.14 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.4 of special second order ODEs when $k=6$ ..... 119
5.15 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.4 of special second order ODEs when $k=9$ ..... 119
5.16 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.5 of special second order ODEs when $k=4$
5.17 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.5 of special second order ODEs when $k=6$
5.18 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.5 of special second order ODEs when $k=9$
5.19 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.6 of special second order ODEs when $k=4$
5.20 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.6 of special second order ODEs when $k=6$122
5.21 Performance comparison between I1PN, I2PBN and I3PBN for solving Problem 3.6 of special second order ODEs when $k=9$
5.22 Performance comparison between I1PN, I2PBN, I3PBN and I1PO, I2PBO, I3PBO for solving Problem 3.1 of special second order ODEs when $k=4$
5.23 Performance comparison between I1PN, I2PBN, I3PBN and
I1PO, I2PBO, I3PBO for solving Problem 3.2 of special second order ODEs when $k=4$122
5.24 Performance comparison between I1PN, I2PBN, I3PBN and I1PO, I2PBO, I3PBO for solving Problem 3.3 of special second order ODEs when $k=4$
5.25 Performance comparison between I1PN, I2PBN, I3PBN and I1PO, I2PBO, I3PBO for solving Problem 3.4 of special second order ODEs when $k=4$ ..... 136
5.26 Performance comparison between I1PN, I2PBN, I3PBN and I1PO, I2PBO, I3PBO for solving Problem 3.5 of special second order ODEs when $k=4$ ..... 137
5.27 Performance comparison between I1PN, I2PBN, I3PBN and I1PO, I2PBO, I3PBO for solving Problem 3.6 of special second order ODEs when $k=4$ ..... 138
6.1 Performance comparison between sequential and parallel explicit block methods for solving Problem 6.1 when $N=3000, b=1$ ..... 158
6.2 Performance comparison between sequential and parallel implicit block methods for solving Problem 6.1 when $N=3000, b=1$ ..... 159
6.3 Performance comparison between sequential and parallel explicit block methods for solving Problem 6.2 when $N=100$, $b=1$ ..... 160
6.4 Performance comparison between sequential and parallelimplicit block methods for solving Problem 6.2 when $N=100$,$b=1$161

## LIST OF FIGURES

## Figure

## Page

1.1 Shared Memory Architecture 15
1.2 Distributed Memory Architecture 15
1.3 Architecture of the Sun Fire V1280 Server 17
$3.1 \quad$ 2-Point 1-Block Method 30
3.2 3-Point 1-Block Method 30
3.3 Stability Region of Explicit 3-Point 1-Block Method 35
3.4 Stability Region of Implicit 3-Point 1-Block Method 50
4.1 Total Steps Comparison for Solving Problem 3.1 when $k=4 \quad 82$
$\begin{array}{ll}\text { 4.2 } & \text { Execution Time Comparison for Solving Problem } 3.1 \text { when } \\ k=4\end{array}$
4.3 Total Steps Comparison for Solving Problem 3.2 when $k=4 \quad 83$
4.4 Execution Time Comparison for Solving Problem 3.2 when
$k=4$
4.5 Total Steps Comparison for Solving Problem 3.3 when $k=4 \quad 84$
$\begin{array}{ll}\text { 4.6 } & \begin{array}{l}\text { Execution Time Comparison for Solving Problem } 3.3 \text { when } \\ k=4\end{array} \\ 84\end{array}$
4.7 Total Steps Comparison for Solving Problem 3.4 when $k=4 \quad 85$
4.8 Execution Time Comparison for Solving Problem 3.4 when
$k=4$
4.9 Total Steps Comparison for Solving Problem 3.5 when $k=4 \quad 86$
$\begin{array}{ll}\text { 4.10 } & \text { Execution Time Comparison for Solving Problem } 3.5 \text { when } \\ k=4\end{array}$
4.11 Total Steps Comparison for Solving Problem 3.6 when $k=4 \quad 87$
$\begin{array}{ll}\text { 4.12 } & \text { Execution Time Comparison for Solving Problem } 3.6 \text { when } \\ k=4\end{array}$
5.1 Total Steps Comparison for Solving Problem 3.1 when $k=4$ ..... 123
5.2 Execution Time Comparison for Solving Problem 3.1 when $k=4$ ..... 123
5.3 Total Steps Comparison for Solving Problem 3.2 when $k=4$ ..... 124
5.4 Execution Time Comparison for Solving Problem 3.2 when $k=4$ ..... 124
5.5 Total Steps Comparison for Solving Problem 3.3 when $k=4$ ..... 125
5.6 Execution Time Comparison for Solving Problem 3.3 when $k=4$ ..... 125
5.7 Total Steps Comparison for Solving Problem 3.4 when $k=4$ ..... 126
5.8 Execution Time Comparison for Solving Problem 3.4 when $k=4$ ..... 126
5.9 Total Steps Comparison for Solving Problem 3.5 when $k=4$ ..... 127
5.10 Execution Time Comparison for Solving Problem 3.5 when $k=4$ ..... 127
5.11 Total Steps Comparison for Solving Problem 3.6 when $k=4$ ..... 128
5.12 Execution Time Comparison for Solving Problem 3.6 when $k=4$ ..... 128
6.1 Sequential Implementation of Explicit 2-Point Block Method ..... 142
6.2 Program Fragment of the Sequential Implementation of Explicit 2-Point Block Method ..... 143
6.3 Parallel Implementation of Explicit 2-Point Block Method ..... 144
6.4 Program Fragment of the Parallel Implementation of the Explicit 2-Point Block Method ..... 146
6.5 Sequential Implementation of Explicit 3-Point Block Method ..... 147
6.6 Parallel Implementation of Explicit 3-Point Block Method ..... 147
6.7 Sequential Implementation of Implicit 2-Point Block Method ..... 149
6.8 Program Fragment of the Sequential Implementation of Implicit 2-Point Block Method ..... 150
6.9 Parallel Implementation of Implicit 2-Point Block Method ..... 151
6.10 Program Fragment of the Parallel Implementation of Implicit 2-Point Block Method ..... 152
6.11 Sequential Implementation of Implicit 3-Point Block Method ..... 154
6.12 Parallel Implementation of Implicit 3-Point Block Method ..... 154
6.13 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-2}$ ..... 162
6.14 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-3}$ ..... 162
6.15 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-4}$ ..... 163
6.16 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-5}$ ..... 163
6.17 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-2}$ ..... 164
6.18 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-3}$ ..... 164
6.19 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-4}$ ..... 165
6.20 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-5}$ ..... 165
6.21 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-2}$ ..... 166
6.22 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-3}$ ..... 166
6.23 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-4}$ ..... 167
6.24 Speedup Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-5}$ ..... 167
6.25 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-2}$ ..... 168
6.26 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-3}$ ..... 168
6.27 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-4}$ ..... 169
6.28 Speedup Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-5}$ ..... 169
6.29 Speedup versus Number of Processors with Explicit Block Methods for Solving Problem 6.1 when $h=10^{-5}$ ..... 170
6.30 Speedup versus Number of Processors with Implicit Block Methods for Solving Problem 6.1 when $h=10^{-5}$ ..... 170
6.31 Speedup versus Number of Processors with Explicit Block Methods for Solving Problem 6.2 when $h=10^{-5}$ ..... 171
6.32 Speedup versus Number of Processors with Implicit Block Methods for Solving Problem 6.2 when $h=10^{-5}$ ..... 171
6.33 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-2}$ ..... 172
6.34 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-3}$ ..... 172
6.35 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-4}$ ..... 173
6.36 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.1 when $h=10^{-5}$ ..... 173
6.37 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-2}$ ..... 174
6.38 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-3}$ ..... 174
6.39 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-4}$ ..... 175
6.40 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.1 when $h=10^{-5}$ ..... 175
6.41 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-2}$ ..... 176
6.42 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-3}$ ..... 176
6.43 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-4}$ ..... 177
6.44 Efficiency Comparison between PE2PBN and PE3PBN for Solving Problem 6.2 when $h=10^{-5}$ ..... 177
6.45 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-2}$ ..... 178
6.46 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-3}$ ..... 178
6.47 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-4}$ ..... 179
6.48 Efficiency Comparison between PI2PBN and PI3PBN for Solving Problem 6.2 when $h=10^{-5}$ ..... 179

## LIST OF ABBREVIATIONS

| IVP | : Initial Value Problems |
| :---: | :---: |
| ODEs | : Ordinary Differential Equations |
| SISD | : Single Instruction Single Data |
| SIMD | : Single Instruction Multiple Data |
| MISD | : Multiple Instruction Single Data |
| MIMD | : Multiple Instruction Multiple Data |
| CPUs | : Central Processing Units |
| MPI | : Message Passing Interface |
| E2P1B | : Explicit 2-Point 1-Block |
| E3P1B | : Explicit 3-Point 1-Block |
| I2P1B | : Implicit 2-Point 1-Block |
| I3P1B | : Implicit 3-Point 1-Block |
| E1P | : Explicit 1-Point |
| E2PB | : Explicit 2-Point Block |
| E3PB | : Explicit 3-Point Block |
| I1P | : Implicit 1-Point |
| I2PB | : Implicit 2-Point Block |
| I3PB | : Implicit 3-Point Block |
| PE2PB | : Parallel Explicit 2-Point Block |
| PI2PB | : Parallel Implicit 2-Point Block |
| PE3PB | : Parallel Explicit 3-Point Block |
| PI3PB | : Parallel Implicit 3-Point Block |

