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Age and sex influence social interactions, but not associations, within a killer whale pod

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62 Abstract

63 Social structure is a fundamental aspect of animal populations. In order to understand 64 the function and evolution of animal societies, it is important to quantify how individual attributes, such as age and sex, shape social relationships. Detecting these influences 65 66 in wild populations under natural conditions can be challenging, especially when social 67 interactions are difficult to observe and broad-scale measures of association are used 68 as a proxy. In this study, we use unoccupied aerial systems to observe association, 69 synchronous surfacing, and physical contact within a pod of southern resident killer 70 whales (Orcinus orca). We show that interactions do not occur randomly between 71 associated individuals, and that interaction types are not interchangeable. While age 72 and sex did not detectably influence association network structure, both interaction 73 networks showed significant social homophily by age and sex, and centrality within the 74 contact network was higher among females and young individuals. These results 75 suggest killer whales exhibit interesting parallels in social bond formation and social 76 life histories with primates and other terrestrial social mammals, and demonstrate how 77 important patterns can be missed when using associations as a proxy for interactions 78 in animal social network studies.

79 Introduction

Individual characteristics such as and sex and age often influence social relationships and underly variation in social position in animal societies. Understanding how these characteristics shape social structure under natural conditions can shed light on numerous aspects of behavioural ecology, including social life history evolution (e.g. Machanda & Rosati 2020) and the mechanisms underlying social bond formation (e.g. Gerber et al. 2020), while also providing potentially vital information about populationlevel processes such as gene flow and disease transmission (Kurvers et al. 2014).

87 Social network analysis has become an important tool for understanding these 88 processes over the last two decades (Brent et al. 2011; Webber & Vander Wal 2019), 89 however uncovering the drivers of social network structure is challenging. Studies of 90 animal social networks require data on the rates of relevant social behaviours between 91 identified individuals (Whitehead 2008a; Croft et al. 2008, Farine & Whitehead 2015), 92 which often require a great deal of sampling to measure precisely (Whitehead 2008b). Furthermore, the structure of observed social networks is dependent on the 93 94 behavioural definition of edges (Castles et al. 2014).

95 While social structure fundamentally arises from the patterns of repeated interactions 96 between individuals (Hinde 1976), social interactions are often difficult to observe in 97 free-ranging animals, as interactions may be subtle, rare, or not visible from traditional observation platforms. Therefore, many studies of social structure in free-ranging 98 99 animal populations utilize association indices, measuring the probability that 100 individuals are found within the same group or a particular spatial proximity during a 101 sampling period (reviewed by Webber & Vander Wal 2019). As association provides 102 the opportunity for interaction, these associations are typically assumed to generally

103 reflect patterns of interactions between individuals (Whitehead & Dufault 1999), 104 however there is still debate over the degree to which associations can reflect true 105 interactions (e.g. Farine 2015). Using behavioural proxies of relationships that are too 106 broad or do not represent the relationships of interest may mask the influences of 107 individual characteristics on social network structure.

108 In this study, we quantify the influence of age and sex on social relationships in a pod 109 of resident killer whales (Orcinus orca). Previous studies of killer whale societies have 110 suggested that individuals do not show social homophily by age or sex (Tavares et al. 111 2017; Esteban et al. 2015; Williams & Lusseau 2006), and analyses of individual 112 network centrality with respect to age and sex in this species have produced mixed 113 results (Baird & Whitehead 2000; Williams & Lusseau 2006; Tavares et al. 2017). The 114 apparent lack of age and sex structure in killer whale social networks is somewhat 115 surprising in the context of other well-studied dolphin species, where social networks 116 are commonly structured by age and sex (e.g. Hawkins et al. 2019; Hartman et al. 117 2008; Elliser & Herzing 2014; Leu et al. 2020; Webster et al. 2009). This discrepancy 118 may be due to the definitions used to construct killer whale social networks. Because 119 killer whales live and move in stable social units, the position of individuals and the 120 patterns of edges within association networks are likely to primarily reflect attributes 121 and relationships at the level of the unit, rather than the individual (e.g. lvkovich et al. 122 2009; Williams & Lusseau 2006). This system therefore provides an opportunity to test 123 the degree to which the use of broad-scale association patterns can mask important 124 effects of individual characteristics in animal societies.

Here, we utilize unoccupied aerial systems (UAS) to quantify association (defined as individuals detected simultaneously, and therefore with the opportunity to be observed interacting), synchronous surfacing, and physical contact among individually identified 128 killer whales. In delphinids, synchrony can beneficial during cooperative behaviours 129 (Myers et al. 2017) and may be important for maintaining and establishing social 130 relationships (Connor et al. 2006; McCue et al. 2020). Similarly, physical contact often 131 signals social affiliation between closely bonded individuals (Connor et al. 2005; 132 Dudzinski et al. 2017) and may be important for reconciliation after aggressive 133 interactions (Weaver 2003). We hypothesized that both of these interactions would 134 occur non-randomly between associated individuals, and that any influence of age and 135 sex on social structure, both in terms of social homophily and individual centrality 136 within the social network, would be more clear when analysing these interactions than 137 when analysing associations.

138

139 Methods

140 Study population

The southern resident killer whales are a small (< 80 individuals), closed population inhabiting the coastal waters of the northeastern Pacific, with their core habitat being the inland waters of Washington, USA and British Columbia, Canada. This population has been subject to a complete annual census carried out by the Center for Whale Research since 1976. All individuals can be visually identified using unique markings, body shapes and sizes, and scarring.

The southern residents exhibit lifelong bisexual philopatry to maternal social groups.
The basic social unit is the matriline, composed of close relatives with a recent
common maternal ancestor. Closely related matrilines form pods, larger semi-stable
social groups with a shared vocal dialect (Bigg, et al., 1990; Parsons et al. 2009). This

population contains three pods, designated J, K, and L pod, which at the time of thestudy contained 22, 18 and 32 individuals, respectively.

153

154 *Field observations*

155 During the summer of 2019, we collected video observations using a small UAS (DJI 156 Phantom 4 Pro V2) launched from a small motorized vessel (21 ft. Grady White), or 157 using a larger aircraft (DJI Matrice 600) launched from shore. Focal subgroups (sets 158 of whales in close physical proximity to each other which could be captured 159 simultaneously on video) were located by observers prior to launching the aircraft. 160 Subgroups were primarily chosen for follows based on logistical factors, such as 161 distance from the launch point and the presence of whale watch and research vessels. 162 Preference was typically given to larger subgroups to maximize the possible number 163 of interactions observed over a given observation period. We correct for potential 164 biases introduced by this preference in our permutation analysis (see below). During 165 on-water operations, the vessel maintained a low speed (< 7 kts) when within 1 km of 166 whales. The vessel was usually positioned behind groups of whales, at a distance of 167 200-400 m (see Ayers et al., (2012) for details on vessel maneuvering).

When in the air, one crew member piloted the aircraft, while another served as a visual observer to aid in maintaining visual line-of-sight and situational awareness. A third team member was designated as a general observer, tasked with monitoring whale behaviour during research flights and assisting with operations. The aircraft maintained an altitude between 30 and 120 meters while above whales, and was typically positioned to the side of or behind the animals. The angle of the camera and position of the aircraft were adjusted to ensure a clear view of the full subgroup. Operations were limited to conditions conducive to the safe operation of the UAS and clear observation of animals below the water (no rain, wind below 10 kts, sea state less than Beaufort 3). We collected footage of southern residents over 13 days. For most of these days (10/13), only members of J pod were present. To avoid spurious inferences about relationships involving K or L pod, we chose to restrict our analysis to days in which only J pod was present.

All data was collected under research permits issues by the US National Marine Fisheries Service (NMFS permits 21238 and 22141) and all pilots were licensed under Federal Aviation Administration Part 1077. Research was approved by the University of Exeter College of Life and Environmental Sciences ethics committee. During flights, we monitored focal groups to determine if behavioural responses occurred as the UAS approached, however no behavioural responses were observed during the study.

187

188 Video analysis

We analyse all video in BORIS software (Friard & Gamba, 2016). Analysis of each video clip proceeded by first identifying all whales that were visible at any point during the video by their unique markings, body shapes and size, and scarring. Then, in random order, each whale was followed for the entirety of the video. We coded a state variable for individual visibility, indicating when each individual was on screen and identifiable. We considered individuals to be associated when they were simultaneously visible in the video (Figure 1).

We code physical contact as an undirected point event, recorded when individuals initially come into contact. As we were interested in patterns of affiliative social relationships, we excluded aggressive interactions such as fluke strikes and biting. We also exclude observations of nursing. Potential sexual contacts were not excluded, as
affiliative socialization often includes sexual behaviour in this population (Noren &
Hauser, 2016; Osborne, 1986).

Synchronous surfacing was also coded as an undirected point event. Individuals were considered to have breathed in synchrony if they surfaced within one adult female body length (approx. 6 m) and at some point during their surfacing both individuals' blowholes were simultaneously above the water's surface. Individuals could be recorded synchronously surfacing with multiple partners in a single surfacing, however we did not use a chain-rule, and therefore synchronous surfacings were not transitive. As both interactions were coded as point events, they did not preclude one another.

Our sequential follow protocol generates two records of each interaction, potentially at slightly different time points. We ensured all interactions were recorded for both individuals and that all individuals were coded as visible during all of their interactions, with errors corrected by re-analyzing the video. We set the interaction time as the midpoint between the two records. The median difference in time between the two records was 0.203 seconds (IQR = 0.23) for synchronous surfacing and 0.439 seconds (IQR = 0.656) for contact.

216

217 Determining age, sex, and kinship

In 2019, all surviving members of J pod were born after the study began in 1976, and thus their ages (in years) are known with certainty. The sexes of all individuals in this pod were determined based on obvious sexual dimorphism in mature individuals and from genital coloration in young individuals. 222 Maternal kinship was estimated based on behaviourally defined mother-calf dyads. 223 These relationships have been universally supported by subsequent genetic sampling 224 (Ford et al. 2018). From known mother-calf relationships, we constructed a maternal 225 pedigree and estimated a maternal relatedness matrix using the kinship2 R package 226 (Sinnwel & Therneu 2020).

227

228 Social network construction

We constructed interaction networks by dividing each dyad's total interaction by their total observation time. Initial analysis suggested interactions did not occur in bouts (see supplementary materials), so each interactions was treated as independent. Each dyad's observation time was summarized as the total amount of time that one or both of the individuals was visible.

234
$$rate_{ij} = \frac{x_{ij}}{t_i + t_j - t_{ij}}$$
 (1)

Here, x_{ij} is the number of interactions observed between individuals *i* and *j*, t_i and t_j are the total time (in seconds) *i* and *j* were visible, respectively, and t_{ij} is the amount of time both *i* and *j* were visible simultaneously. We calculate interaction rates separately for synchronous surfacings and contacts. We quantify the reliability of our interaction networks by estimating the correlation between true and observed interaction rates following Whitehead (2008b) (see supplementary materials for details).

We construct an association network representing the proportion of sampling time inwhich individuals co-occurred in our observations:

243
$$association_{ij} = \frac{t_{ij}}{t_i + t_j - t_{ij}}$$
 (2)

244 where the variable definitions are the same as in equation 1. This index is comparable 245 to the "simple ratio index" commonly used in animal social network analysis (Cairns & 246 Schwager, 1987). Like other association indices, the edges in this network range from 247 0 (never co-occurred) to 1 (always observed together). This index represents the proportion of time that individuals were detected together, not the amount of time they 248 249 truly spent together; Individuals could fail to be detected while in association if they 250 were outside of the camera's field of view, or if they submerged to a depth where they 251 were no longer visible. During data collection, the camera captured an area with a 252 median maximum distance between any two recorded points of 85 m (IQR = 30; see 253 supplementary materials for methods). This distance is comparable to previous killer 254 whale studies where a cutoff of 10 body lengths (roughly 70 m) has been used (e.g. 255 Williams & Lusseau 2006). Social networks construction and all further analysis was 256 carried out in R (R Core Team 2020).

257

258 Comparing associations and interaction rates

We first tested whether the structure of the two interaction networks could be explained solely by dyadic association and sampling. We construct a null model for our interaction networks that maintains both individual detection history and temporal variation in the observed overall rate of interactions. For each observed interaction, we randomly sample two individuals coded as visible at the time of the interaction as the new interaction partners. We repeat this procedure 10,000 times, re-calculating interaction rates for each randomisation to generate 10,000 randomised networks.

266 We first test whether interaction rates are more variable than expected given 267 associations. We do this by using the coefficient of variation (CV) as a test statistic. The CV is a measure of the variation in interaction rates. When individuals have strongly preferred and avoided interaction partners, the CV of interaction rates will be higher than when individuals interact at random (Whitehead 2008a). We reject the null hypothesis that interactions occurred randomly between associates if the observed CV is greater than the upper 95% confidence interval of CVs from the randomised networks.

274 We additionally test whether the correlations between associations and interactions 275 are different from expected if interactions occurred randomly by calculating 276 Spearman's rank correlation (r_s) between interaction rates and association indices in 277 both the observed and randomised interaction networks. If r_s in the observed data lies 278 within the 95% CI of r_s values from the randomised networks, we do not reject the null 279 hypothesis that interaction patterns match those expected given random interactions 280 between associates. If the observed r_s is lower than the lower 95% CI of the 281 randomised values, the rates of social interaction between individuals cannot be directly inferred from patterns of association. We additionally compare these 282 283 correlations to the null hypothesis of no correlation between the networks using Mantel 284 tests, using the vegan package in R (Oksanen et al. 2019). Note that the Mantel test 285 has a different null hypothesis than the randomization of the raw data. While our 286 randomization of the raw data represents the null hypothesis that interactions occur 287 randomly between associated individually (and thus associations reflect interactions), 288 the Mantel test proposes the null hypothesis that association and interaction rates are 289 independent.

291 Comparing surfacing and contact networks

292 Next, we investigated whether there were structural differences in the two interaction 293 networks. We again use randomizations to test the null hypothesis that interaction types are interchangeable, using the procedure proposed by Franz & Alberts (2015). 294 295 Each observed interaction is labelled according to which type of interaction it 296 represented in the original data. Over 10,000 permutations, these labels are shuffled 297 and the two resulting networks are calculated. We determine whether there are 298 differences in the CV between the networks by comparing the observed difference in 299 CV to the distribution of differences from the randomised networks as above. We test 300 whether the networks are less correlated than expected if interaction types were 301 interchangeable by comparing the r_s between the observed networks to a distribution 302 of r_s values generated from the randomised networks, as above. We also test the 303 correlation between these two networks against the null hypothesis of no relationship 304 using a Mantel test.

305

306 Effects of age, sex, and kinship on edge strength

We next test the role of kinship, age, and sex in the structuring of edges in the association, contact, and synchronous surfacing networks. To quantify the relationship between both synchronous surfacing and contact rates and our predictors, we use generalised linear models (GLMs), with a negative binomial error structure. These models can be expressed as:

$$312 x_{ij} \sim NB(\lambda_{ij}, \theta) (3)$$

313
$$\log(\lambda_{ij}) = \beta_0 + \beta_1 R_{ij} + \beta_2 (-|a_i - a_j|) + \beta_3 (1 - |s_i - s_j|) + \log(t_i + t_j - t_{ij})$$

where $\lambda_{i,j}$ and θ are the mean and dispersion parameters for the negative binomial distribution, respectively, R_{ij} is the estimated maternal kinship between *i* and *j*, a_i is individual *i*'s age in years, s_i is the sex of individual *i* (0 = female, 1= male), and the β are estimated regression parameters and the term log($t_i + t_j - t_{ij}$) is an exposure term.

318 Similarly, we quantify the relationship between our predictors and association patterns319 with a beta regression model:

320
$$association_{ij} \sim \text{Beta}(\mu_{ij}, \phi)$$
 (4)

321
$$\operatorname{logit}(\mu_{ij}) = \beta_0 + \beta_1 R_{ij} + \beta_2 (-|a_i - a_j|) + \beta_3 (1 - |s_i - s_j|)$$

where μ_{ij} and ϕ are the mean and precision parameter of the beta distribution. In this model, dyadic sampling effort was included as a proportional weight in the fitting process. As there were zeros in the association data, we transformed these values following Smithson & Verkuilen (2006):

326
$$y' = \frac{y(N-1)+0.5}{N}$$
 (5)

Here, *y* are the original values, *y*' are the transformed values, and *N* is the sample size (here, the number of dyads). We fit these models in R, using the MASS package for negative binomial regression (Venables & Ripley 2002) and the betareg package for beta regression (Cribari-Neto & Zeileis, 2010).

We use a permutation procedure to determine the statistical significance of regression coefficients. We use the double-semi-partialling method developed by Dekker et al., (2007) with 10,000 randomizations, using the Wald's *Z* as our test statistics. Our method is equivalent to multiple regression quadratic assignment procedure (MRQAP), but fitting GLMs instead of least squares regression. We therefore refer to this procedure as a generalised linear model quadratic assignment procedure(GLMQAP).

338

339 Effects of age and sex on network centrality

Finally, we determine the influence of age and sex on network centrality in our three networks. As using a large number of centrality measures can lead to false positives in statistical analyses (Webber et al. 2020), we choose just one index: eigenvector centrality. Eigenvector centrality depends on direct and indirect connectivity in the network; individuals with high eigenvector centrality have numerous, strong connections to individuals that are also well connected. In the remainder of the manuscript, we refer to eigenvector centrality scores simply as individuals'

347 "centrality".

348 We fit linear mixed effects models to identify the relationship between centrality and 349 individual attributes. These models had the form:

$$350 \qquad \log(centrality_i) \sim N(\mu_i, \sigma_{residual}) \tag{6}$$

351 $\mu_i = \beta_0 + \beta_1 s_i + \beta_2 a_i + \beta_3 \log(t_i) + \varepsilon_{m_i}$

352 $\varepsilon \sim N(0, \sigma_{matriline})$

Here ε is a matriline-level random effect (with m_i indicating matriline membership), controlling for correlations in social network positions between matriline members (Williams & Lusseau 2006), and the terms *a*, *s*, and *t* are as in equation 3. The term for log(*t*) is used here to correct for the effect of sampling intensity on centrality measures (Franks & Weiss et al. 2021). Using the logarithm of centrality improved the data's adherence to the model's assumptions of normally distributed residuals and linearity, and initial visual examination suggested a log-log relationship between 360 centrality and sampling intensity was appropriate across all three networks. These361 models were fit using the Ime4 R package (Bates et al. 2015).

We test our regression coefficients using a double-semi-partialling permutation procedure (Dekker et al. 2007), with permutation constrained within matrilines. We compare the observed *t*-values to 10,000 permutations to derive *p*-values. We do not test for interactions between age and sex, as double semi-partialling cannot test interaction effects.

367

368 Data accessibility

The processed contact, surfacing, and association networks, measures of dyadic sampling effort, estimated maternal kinship, individual attributes, and functions to conduct GLMQAP and general double-semi-partialling are included in the "aninet" R package on GitHub (<u>https://github.com/MNWeiss/aninet</u>). The raw time-series of detections and interactions, and R code necessary to reproduce all analyses, are available in the online supplementary material.

375

376 **Results**

377 Data description

Over 10 days of sampling, we collected a total of 651 minutes of video. During this footage, a median of 4 individuals were visible at any given time (interquartile range = 3). All individuals were observed on at least 3 different days, and each individual whale was videoed for a mean of 125.96 minutes (SD = 57.65). Each pair of animals was observed for an average of 213.68 minutes total (SD = 58.17). While a relatively short 383 period, this is an increase in sampling relative to the only other study using UAS to 384 construct cetacean social networks (Hartman et al. 2020). We estimate that the 385 observed interaction rates were strongly correlated with the true interaction rates 386 (contact $r_{est} = 0.98$; surfacing $r_{est} = 0.98$). During our observations, we recorded 831 387 instances of physical contact between individuals, and 1617 synchronous surfacing 388 interactions (Table S1). Contact and synchronous surfacing behaviours did not tend 389 to occur simultaneously; 1.5% of contacts occurred within one second of the same 390 pair synchronously surfacing. Pairs of whales were visible simultaneously for an 391 average of 38.24 minutes (SD = 30.61).

392

393 Comparing interactions to association patterns

394 Rates of both interaction types were significantly more varied than expected given 395 random interactions between associates (surfacing: Observed = 2.31, 95% CI 396 Random = [1.09, 1.23], p < 0.001; contact: Observed = 2.46, 95% CI Random = [1.27, 1.23]1.47], p < 0.001). Both interaction networks were significantly positively correlated with 397 398 the association network under the null hypothesis of no relationship (surfacing: $r_s =$ 399 0.79, p < 0.001; contact: $r_s = 0.59$, p < 0.001). The interaction networks were, however, 400 significantly less strongly correlated with the association network than expected if 401 interactions occurred randomly between associates (surfacing: 95% CI random $r_s =$ 402 [0.85, 0.90], p < 0.001; contact: 95% CI random $r_s = [0.70, 0.78]$, p < 0.001).

403

404 Comparison of interaction types

Rates of the two interaction types did not have statistically significant differences in
their coefficients of variation. (Observed difference in CV = 0.23, 95% CI Random = [-

407 0.17, 0.24], p = 0.07). The two networks were more correlated than expected under 408 the null hypothesis of no relationship between contact and surfacing rates ($r_s = 0.72$, 409 p < 0.001), but significantly less correlated than expected if the two interaction types 410 were interchangeable (95% CI Random = [0.80, 0.87], p < 0.001).

411

412 Influence of age, sex, and kinship on edge strength

413 As expected, maternal kinship was an important predictor of association and

414 interaction rates across all three networks (all p < 0.001; Table S3). In the

415 association network, neither age similarity nor sex similarity predicted edge weights.

416 In both interaction networks, however, interaction rates were significantly related to

417 age similarity (surfacing: $\beta = 0.06 \pm 0.01$, Z = 5.32, p = 0.005; contact: $\beta = 0.12 \pm 0.01$

418 0.02, Z = 6.82, p < 0.001) and sex similarity (surfacing: $\beta = 0.60 \pm 0.20$, Z = 2.98, p =

419 0.02; contact: $\beta = 1.27 \pm 0.28$, Z = 4.58, p = 0.002).

420

421 Influence of age and sex on social centrality

Across all three networks, increased sampling intensity was related to greater observed centrality (all p < 0.04, Table S4). In the synchronous surfacing and association network, we found no evidence that age or sex influenced centrality (all p> 0.05; Table S4). However, in the contact network, we found statistically significant effects of age and sex on centrality. There was a negative correlation between age and centrality ($\beta = -0.03 \pm 0.01$, t = -3.30, p = 0.006), and males were less central than females ($\beta = -0.58 \pm 0.16$, t = -3.59, p = 0.004).

430 **Discussion**

431 In this study, we observed direct social interactions in a killer whale pod to better 432 understand the role of age and sex in structuring social relationships. Associations 433 were not strongly organized by age or sex, but were primarily structured by matrilineal 434 kinship. In contrast, both synchronous surfacing rates and physical contact rates 435 showed significant assortment by age and sex. In addition, we found evidence that 436 younger individuals and females were particularly central in the contact network, 437 suggesting age and sex related variation in social strategies, a pattern that was not 438 clear in the association or synchronous surfacing networks.

439 The potential issues with using association to quantify social structure have been 440 extensively debated in the methodological literature (Whitehead & Dufault 1999; 441 Castles et al. 2014; Farine 2015; Carter et al. 2015), however they have rarely been 442 addressed in cetaceans and other aquatic species (but see Leu et al. 2020 and 443 Lusseau 2007) or in the context of detecting the influence of individual attributes on 444 network structure. Our results demonstrate how inferences about network structure in 445 relation to individual characteristics can be missed when using association indices as 446 a proxy for interaction rates. The effects of age and sex on the strength of network 447 edges were only clear when analysing interaction rates, rather than associations, 448 supporting previous studies which found no assortment by age or sex in killer whale 449 association networks across multiple populations (Williams & Lusseau 2006; Esteban 450 et al. 2015; Tavares et al. 2017). This suggests that while age and sex are important 451 determinants of social interactions, these effects are difficult or impossible to detect 452 from association patterns. While physical contact and synchronous surfacing were 453 highly correlated, they were not interchangeable, and age and sex effects on social centrality were only found in the contact network. This suggests that physical contacts, 454

which can only be consistently observed from the air in this system, may provide
greater power for analysing individual social affiliations. This result adds to a growing
body of work demonstrating the power of UAS for studying cetacean sociality
(Hartman et al. 2020; Nielsen et al. 2019; Ramos et al. 2020).

459 There are several mechanisms that could drive the observed correlations between 460 age, sex, and social structure. One hypothesis relates to energetics and behavioural 461 budget, a factor that has frequently been proposed to explain sexual segregation in 462 terrestrial ungulates (Ruckstuhl 2007). Adult male killer whales are considerably larger 463 than females, and thus have greater energetic requirements (Noren 2011) and spend 464 more time foraging (Tennessen et al. 2019), which may drive males' lower social 465 centrality. This may also lead to decoupled behavioural states between the sexes, 466 contributing to assortment by sex in the interaction networks. Similarly, young 467 individuals have a large portion of their energetic needs met by nursing (Newsome et 468 al. 2009) or from prey sharing (Wright et al. 2016), which may lead to greater time 469 spent socializing, primarily with other young individuals. Further work may shed light 470 on how killer whale groups, which are composed of individuals with highly 471 heterogenous energetic requirements, maintain cohesion.

472 The finding that killer whales become less social as they age aligns with social life 473 histories found in other social mammals. In humans and non-human primates, 474 individuals become less social and maintain fewer relationships as they age, 475 potentially due to adaptive social selectivity or senescence (Machanda & Rosati 2020; 476 Wrzus et al. 2013). Our results suggest that decreased sociality with age may be more 477 widespread among social mammals, including killer whales. This apparent simiarlity 478 between primate and killer whale social life history is particularly interesting given the 479 convergent reproductive life histories in killer whales and humans (Johnstone & Cant 480 2010). Individuals may also actively form important relationships and social skills at a 481 young age, as in other matrilineal societies (Chiyo et al. 2010; Goldenberg et al. 2016). 482 While further work is needed to explore these and other possible mechanisms, our 483 results demonstrate that killer whales may be a powerful system for testing hypotheses 484 about the evolution of sex differences in sociality and social life histories in mammals.

485 These results may also have conservation implications for this population. Previous 486 studies have highlighted the potential role of infectious disease risk in killer whale 487 population dynamics (Gaydos et al. 2004; Raverty et al. 2017), and both contact and synchronous surfacing have been identified as disease transmission pathways in 488 489 cetaceans (Leu et al. 2020). Our results suggest that young, female individuals may 490 be at greater risk of exposure to skin-borne pathogens, such as cetacean poxvirus 491 (Van Bressem et al. 1999). The assortment of both synchronous surfacing and 492 physical contact by age and sex suggests that the impacts of any given disease 493 outbreak may be spread unevenly between demographic classes, spreading to 494 individuals of similar age and sex of the initially infected whale.

A limitation of the current study and method is that social interactions can only be observed by UAS when they occur relatively close to the surface. In addition, only a single social group was studied. Further studies using animal-borne devices may provide additional data on interactions that occur deeper in the water column, and analysing the full population may reveal further patterns.

500 Our results demonstrate how potentially important patterns in social relationships may 501 only emerge at very fine scales. As association-based social networks are ubiquitous 502 in studies of numerous terrestrial and aquatic systems, our results strongly suggest 503 that, where possible, association data should be combined with analyses of relevant 504 social interactions when analysing social relationships. In particular, when individual 505 movement patterns are primarily governed by membership to stable social units, 506 analysing direct interactions may be crucial for uncovering individual level drivers of 507 social structure.

508

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- 726

727 Figures



728

Figure 1. Observing killer whale social interactions using UAS. A-B: The aircraft is 729 730 flown over focal killer whale sub-groups (A). All individuals detected simultaneously 731 were considered to be associated, and both synchronous surfacing and physical contact interactions were recorded between identified individuals (B). C-D: Example 732 video stills of synchronous surfacing between individuals J36 and J47 (C) and physical 733 734 contact between individuals J44 and J53 (D). Killer whale side profiles based on Huh, **BY-SA** 735 illustration by Chris used under а CC 3.0 license 736 (https://creativecommons.org/licenses/by-sa/3.0/).



Figure 2. Network structure and social centrality in a resident killer whale pod. Panels show sociograms (top) and eigenvector centrality measures (bottom) for (from left to right) association, synchronous surfacing, and physical contact networks. Edge thicknesses in the sociograms are proportional to association or interaction rate, and nodes are placed according to the ForceAtlas2 algorithm (Jacomy et al. 2014). Across all plots, node shape indicates sex and node color indicates matriline membership, and node size in the sociograms indicates individual age (as shown in the legend). Note the log scale for the y-axis in the lower plots.

754 Supplemental materials for:

- ⁷⁵⁵ Age and sex influence social interactions,
- ⁷⁵⁶ but not associations, within a killer whale
- 757 pod

758 Supplementary methods

- 759 Estimating maximum distance captured
- 760 We use the field of view of the camera lens and the flight records stored by the UAS
- to estimate the maximum distance between any two points in the video. Given the
- 762 drone's vertical field of view θ and horizontal field of view ϕ (in degrees), the drone's
- altitude *w* (in meters), and the camera gimbal's pitch *p* (in degrees from a straight
- down view), we estimate the locations of the corners of the frame relative to the
- 765 drone, which we set as the origin.
- We first calculate the distance to the top of the screen y_1 and the bottom of the screen y_2 :
- 768 $y_1 = \tan\left(p + \frac{\theta}{2}\right)w$
- 769 $y_2 = \tan\left(p \frac{\theta}{2}\right)w$
- The widths of the top of the frame (*a*) and the bottom of the frame (*b*) can then becalculated as:
- 772 $a = 2 \cdot \tan\left(\frac{\phi}{2}\right) \sqrt{y_1^2 + w^2}$
- 773 $b = 2 \cdot \tan\left(\frac{\phi}{2}\right) \sqrt{y_2^2 + w^2}$

The *x* coordinates for the top two corners of the frame are then {-*a*/2, *a*/2}, while the *x* coordinates of the bottom two corners are {-*b*/2, *b*/2}. We then have our four points $x = \{-a/2, a/2, -b/2, b/2\}, y = \{y_1, y_1, y_2, y_2\}$. We measure the distances between all four points, recording the maximum distance. We record this for all flight records during the study period during which the video was active, and report the median along with the 25% and 75% quantiles.

780

781 Bout analysis

782 In order to test whether interactions could be broken into bouts, we measured the 783 waiting times between observed interactions between dyads in each video clip. If 784 interactions between dyads occurred in bouts, we would expect these waiting times 785 to arise from a mixture of two exponential distributions, one representing the waiting 786 time within bouts, and the other representing waiting times between bouts. In 787 contrast, if interactions did not occur in bouts, we expect these waiting times to fit a 788 single exponential distribution (Langton et al. 1995). We fit these two models in the 789 flexmix package in R (Gruen & Leisch 2008). For both interaction types, we then 790 compare these models using the Bayesian information criteria (BIC). Lower values of 791 BIC indicate that the model is a better fit to the data, penalized for model complexity.

In both interaction types, model comparisons suggested that the mixture of two
exponential distributions fit the data less well than the single exponential distribution,
with differences in BIC > 10 (Table S2). We therefore analysed each interaction as
an independent event, rather than measuring bouts of interaction.

796

797

799	Table S2. Model selection for exponential mixtures				
	Interaction type	Model	BIC		
	Synchronous ourfacing	Single exponential	6679.487		
	Synchronous surracing	Two exponentials	6692.541		
	Physical contact	Single exponential	3806.613		
	Physical contact	Two exponentials	3818.561		
800		·			

801

802 Estimating reliability of interaction networks

803 We assume that our observed interaction counts *x* are drawn from a Poisson

distribution where the rates themselves are drawn from a gamma distribution with

shape parameter k and scale parameter θ . The expected number of observed

806 interactions is then the true rate multiplied by the sampling time (t_{ij}) .

807
$$x_{ij} \sim \text{Poisson}(\lambda_{ij}t_{ij})$$

808
$$\lambda_{ij} \sim \text{Gamma}(k, \theta)$$

809 We are interested in estimating the correlation between the true rates λ_{ij} and the 810 estimated interaction rates $\frac{x_{ij}}{t_{ij}}$.

811 We estimate the parameters of the underlying Gamma distribution by fitting a 812 negative-binomial distribution with mean μ and dispersion ϕ to the observed 813 interaction counts:

814
$$x_{ij} \sim \text{NB}(\mu t_{ij}, \phi)$$

815 We use our negative binomial fit to extract the estimated shape and scale 816 parameters of the underlying Gamma distribution:

817
$$p = \frac{\phi}{\phi + \mu}$$

818
$$\theta = \frac{1-p}{p}$$

819 $k = \phi$

820 The mean and variance of the underlying Gamma distribution are then

821
$$Mean(\lambda) = k\theta$$

822
$$\operatorname{Var}(\lambda) = k\theta^2$$

823 Therefore, the coefficient of variation of the true interaction rates (social

824 differentiation, *S*) is:

$$S = \frac{\sqrt{k\theta^2}}{k\theta} = \frac{1}{\sqrt{k}}$$

Following equation 4 in Whitehead (2008), we then estimate the correlation between the observed and estimated interaction rates (r_{est}) as

828
$$r_{est} = \sqrt{\frac{1}{1 + \frac{1}{S^2 \times G}}}$$

829 where

$$6 = \frac{\sum_i \sum_j x_{ij}}{N(N-1)}$$

831 In order to assess whether this a reasonable estimate, we plot the empirical

832 distribution of interaction rates against the estimated gamma distributions. For both

833 interaction rates, the fitted Gamma distributions appear to be reasonable

approximations of the empirical interaction rates, allowing for sampling noise (FigureS1).

836



Figure S1. Empirical distributions of interaction rates compared to fitted gamma distributions. Grey histograms indicate the observed distribution of estimated interaction rates, and the red lines are the estimated density of the Gamma distribution fit using maximum likelihood.

843

844 Permutation analysis for centrality in mixed effect models.

845 We adopt a double-semi-partialling approach for testing the fixed effects in our mixed 846 effect models of social centrality. For each fixed predictor *X*, we partial out the

847 covariance between *X* and all other fixed predictors *Z* by fitting the linear model

848 $X = \beta Z + \varepsilon$

and extracting the residuals ε . We then replace *X* with ε in the original model, and carry out 10000 permutations of these residuals. To account for matriline membership, we permute these residuals within matriline. We repeat this procedure for each predictor, using the *t*-value as the test statistic to derive *p*-values for all fixed predictors.

855 Supplementary results

857	Table S1 Summary of attributes and observation effort for each individual in J pod in
858	the summer of 2019.

Matriline	ID	Birth Year	Sex	Observation time (min)	Sync. surfacings	Contacts
	J27	1991	М	85	63	4
14.4	J31	1995	F	206	315	91
JII	J39	2003	М	121	77	45
	J56	2019	F	203	302	141
	J37	2001	F	137	232	119
14.4	J40	2004	F	173	218	114
J14	J45	2009	М	134	134	58
	J49	2012	М	163	195	95
	J16	1972	F	28	18	9
146	J26	1991	М	46	14	17
J10	J36	1999	F	37	29	28
	J42	2007	F	34	20	20
	J35	1998	F	166	227	105
	J44	2009	М	159	139	75
J17	J46	2009	F	219	259	190
	J47	2010	М	145	163	99
	J53	2015	F	181	223	190
	J19	1979	F	86	50	15
J19	J41	2005	F	131	219	120
	J51	2015	М	140	176	78
100	J22	1985	F	77	93	30
JZZ	J38	2003	М	99	68	32

Table 33. GLINGAP results for each response network.				IK.			
	Response	Family	Predictor	Estimate	Std. Error	Ζ	<i>p</i> *
	Association	Beta	Kinship	3.54	0.48	7.38	<0.001
			Age similarity	0.02	0.01	4.00	0.071
			Sex similarity	0.14	0.11	1.33	0.188
-		Negative binomial	Kinship	6.40	0.46	13.91	<0.001
	Synchronous surfacing		Age similarity	0.06	0.01	5.32	0.005
			Sex similarity	0.60	0.20	2.98	0.020
	Physical contact	Negative binomial	Kinship	8.91	1.12	7.97	<0.001
			Age similarity	0.12	0.02	6.82	<0.001
			Sex similarity	1.27	0.28	4.58	0.002
*p-values derived from 10,000 permutations of predictor residua					siduals		

866

867

868

Table S4. Regression analysis of eigenvector centrality.

Network	Predictor	Estimate	Std. Error	t	<i>p</i> *
	Sampling	0.44	0.14	3.15	0.038
Association	Age	0.00	0.003	0.09	0.965
	Sex	-0.01	0.06	-0.11	0.808
Curachiranaua	Sampling	1.68	0.21	7.89	0.011
Synchronous	Age	-0.01	0.01	-0.94	0.300
Sundering	Sex	-0.34	0.17	-2.01	0.066
	Sampling	1.88	0.35	5.40	< 0.001
Physical contact	Age	-0.03	0.01	-3.30	0.006
	-				
	Sex	-0.58	0.16	-3.59	0.004

*p-values derived from 10,000 permutations of predictor residuals within matrilines 869

870

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865

ble 62 CLMOAD regults for each response notwork

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