# Verification in ASL and 

related specification languages

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#### Abstract

In recent years a new framework for specification has been defined around $A S L$ [SW 83, Wir 86, ST 88a, ST 88b]. Stress has been put on defining a specification language consisting of a few powerful specification building operations (SBO's for short) with simple semantics and an elegant implementation notion. Some important features of this work are the generalization to an arbitrary institution [GB 84] of a lot of previous work done on algebraic specification and the study of behavioural abstraction in the context of a model-oriented specification language.

This basic research on formal specifications is generally regarded as the basis for a new generation of specification languages. These specification languages will instantiate $A S L$ with their institution of interest, and will define their own specification constructs and implementation notion in terms of $A S L$ 's primitive SBO's and implementation notion.

However, any useful formal framework for program development needs an inference system for the implementation relation, i.e. proofs that one specification implements another must be produced by a fixed family of rules without modeltheoretical considerations. This poses a new and difficult problem to $A S L$ due to its model-oriented nature and the great generality of both the implementation relation and the SBO's.

In this thesis we study this problem starting from a simple specification language with only three SBO's, and progressively adding other common SBO's. In the course of this analysis we encounter four main problems for the verification of implementations: hiding of auxiliary functions, behavioural abstraction, reachability constraints and parameterization. These problems can be considered classical of algebraic specifications and the study of their verification aspects at an institution-independent level provides valuable results for many other specification languages.


New results for the verification of implementations w.r.t. specifications with hidden parts and abstracted specifications at an institution-independent level are the main contribution of the thesis. Verification of reachability constraints is shown to be below the institutional level. In this case, a common institution for constraints is formally presented showing some ignored verification aspects. Finally, an original presentation of parameterization and structured implementations concludes the thesis.

In conclusion, this thesis presents a collection of sublanguages, inference systems and side conditions which add a new dimension to the fascinating job started by $A S L$ in [SW 83].

## Statement

The work described in this thesis is my own and the thesis was composed by myself. Parts of chapters 3 and 4 were previously published in [Far 89] and [Far 90], respectively.

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## Chapter 1

## Introduction

### 1.1 Specifying software systems

Generally a specification is a description of a system establishing some requirements that the engineer must fulfil in the implementation of the system. Alternatively, a specification can be a document describing the properties of a system to the users.

Similarly, in computer science, specifications appear as descriptions of tasks that programs should achieve and as descriptions of programs for the users. Ideally, these descriptions must capture all the requirements/properties which need to be fulfilled/known and only those. In practice, these two kinds of specifications are confused in only one, and we talk about specifications of program behaviours which happen to be all that a user needs to know and all that the programmer needs to fulfil.

A common approach to the specification of software systems considers a system to be a black box and its specification to be a description of the relation between the input and the output of the system. These specifications are known as algebraic specifications.

## Algebraic specifications

Algebraic specifications are called algebraic because they only refer to the functionality of the system and can denote, at most, an algebra defining the input/output relation of a system.

When the output is uniquely defined for each input, an algebraic specification denotes an algebra. Otherwise, an algebraic specification denotes a class of algebras, i.e. all the algebras which satisfy the input/output requirements in the specification.

This approach simplifies specifications greatly; perhaps too much, since it ignores possible requirements on time, limited resources, non-determinism, synchronization, etc. Nevertheless, the problem of correctness, i.e. the production of results according to the requirements, is conveniently isolated in the algebraic framework.

There exist a large variety of algebraic specification languages. They differ in the logics used to express the input/output requirements, in the operations used to structure the specification and in the semantics.

Very popular among specification languages are those using equations to express requirements, parameterization to structure specifications and initial semantics to interpret them (see [GTW 76, EM 85]). We shall say that these languages follow the initial approach to specification.

Alongside the initial approach there are many other alternative approaches. Some of them, like the initial approach, use equations and define each specification to denote an isomorphic class of algebras, for example the final approach [Wan 79, Kam 83] and the initial-behavioural approach [GGM 76, NO 88].

Other specification languages have a loose semantics allowing a specification to denote a class of non-isomorphic algebras. Among these CLEAR [BG 77, BG 80] and LARCH [GHW 85] use semantics based on theories, whereas ASL-related specification languages allow specifications to denote arbitrary classes of algebras [SW 83, Wir 86, ST 88a] or structures [WB 89].

Finally, common non-algebraic specification languages such as Z [Spi 85] and VDM [Jon 80] use a model to specify a software system. These languages are not considered algebraic because they present a mathematical model for the system instead of some requirements on the relationship between the input and the output of the system. Nevertheless, semantics as those given to Z in [Spi 85] consider that an abstract model specification denotes only the algebra implicitly described through the model. In this sense, these specification languages are also algebraic. The basic difference remaining between abstract model specifications such as Z and common algebraic specifications is the way in which requirements are expressed, that is using some predefined mathematical models or using some axioms and a satisfaction relation between axioms and models respectively.

The reasons for this proliferation of specification languages can be found in the difficulties of combining a specification language with a flexible notion of implementation and an effective verification method.

## Formal production of software

All frameworks for the formal development of programs consist of three basic elements: a specification language, a notion of implementation and an inference system to prove implementations correct.

These three elements together allow us to write a high level specification of the problem and refine it successively into more detailed specifications until a
specification is obtained which is so low level that it can be executed, in other words a program. And finally, provided the implementation relation is transitive, the proof system allows us to prove the correctness of the program w.r.t. its original specification by proving that each refinement step is a correct implementation.

The requirements for a good specification language are basically two: sufficient expressive power and simplicity of use. The first requirement should ensure that a specification language allows us to describe the behaviour of the software systems we want to specify. The second requirement concerns various aspects of the language such as modularity, readability, re-usability, etc.

A good notion of implementation is expected to relate a high level specification to a more concrete, detailed or complete specification. Formalizing this relation, including all that our intuition suggests and no more, is a very vague task. Normally, the implementation relation is expected to be transitive and to embody informal concepts such as:

- $A$ implements $B$ if $A$ completes the input/output description given in $B$.
- $A$ implements $B$ if $A$ can simulate $B$.
- $A$ implements $B$ if $A$ is more deterministic than $B$.

Finally, an inference system should be available for proving that such implementation relations hold, i.e. proving that $A$ implements $B$ for any of the cases mentioned above. These proofs are called correctness proofs and we can say that $A$ is proven correct w.r.t. $B$ if $A$ is proven to implement $B$. This terminology extends the idea of a program being correct w.r.t. a specification.

The nature of these proofs depends on the definition of implementation chosen, but it always involves proving that all the input/output requirements in $B$ are satisfied by the models of $A$ or something 'constructed' from them. A good
inference system should be sound and complete with respect to the relation of implementation, so that all valid implementations and only those can be derived in the system.

If we look at the literature we find many proposed notions of implementation but none of them is in very widespread use. The reason comes from the difficulty of combining useful specification languages and implementation concepts with practical proof systems. The different frameworks can be roughly classified áccording to the priority given to each of these issues.

The most common specification languages are the ones stressing the proof capabilities which are considered the bottleneck for the framework. For this purpose, the expressive power of specifications and the flexibility of the implementation notion are constrained in different ways so that sensible verification methods are attained.

OBJ [FGJM 85], among others, is developed on top of a re-writing engine. This results in a good proof system for the language but it limits from the beginning all aspects of the specification language and the implementation notion.

Specification languages with semantics expressed in terms of theories (LARCH [GHW 85]) or, even, presentations (finite sets of sentences) provide complete proof systems by definition, provided the underlying logic has a sound and complete inference system. Unlike OBJ these languages do not expect automatic proofs but they still enforce serious constraints on the specification language and the implementation notion.

Other frameworks for formal program development stress the need for a comfortable specification language to ease specification design. Some languages propose the use of a high level of modularity and stronger logics, e.g. Clear [BG 80], others
encourage specifications via the use of abstract models allowing the definition of type representations, e.g. Z [Spi 85].

Finally, most recent approaches stress the need for a simple, composable and general implementation notion. Among these languages we find most of the specification languages with loose semantics, such as $A S L$ [SW 83].

## 1.2 $A S L$ and related languages

$A S L$ was originally presented by D.Sannella and M.Wirsing in [SW 83] and developed later in [Wir 86, ST 88a].
$A S L$ is a specification language designed around a few specification building operations (SBO's) with simple semantics and powerful enough to describe most of the operations in other specification languages and most of the relations of simulation used in implementation notions.

At the same time, $A S L$ has institution-independent semantics [ST 88a] which means that $A S L$ is independent of the logic used to express the requirements in a specification and, also, independent of the nature of the models which can be algebras or other mathematical structures. The notion of implementation used in $A S L$ [ST 88 b ] is institution-independent, transitive (vertically composable) and distributes w.r.t. the structure of specifications (horizontally composable).

The purpose of $A S L$ is to investigate the foundations of algebraic specification languages. In this sense, $A S L$ shows that a lot of work can be done at the institution-independent level, in particular the semantics of the SBO's, the definition of implementation, results on vertical and horizontal composability, some inference rules for sentences, equivalences among specification terms, etc.
$A S L$ is not so much an established specification language as a tool for research. For this reason, ASL often appears with slightly different semantics or SBO's, and
sometimes, $A S L$ is completely hidden behind friendlier specification languages such as PLUSS [Gau 84]. In this thesis, we shall also play with the basic SBO's, building a number of different languages and sublanguages. Because of that, we often refer to them collectively as $A S L$ and related languages.

Among other specification frameworks, the framework based on $A S L$ is distinguished by the stress on generality and flexibility, disregarding systematically the existence (or not) of good verification methods.

Focussing research on specification semantics and implementation has led to a very general framework where verification faces at least as many difficulties as in all other specification frameworks combined.

This thesis seeks a formal system for proving implementation steps to be correct in $A S L$ and related languages. In the process, we use $A S L$ as a tool to investigate the verification of implementations in general. Analogously to results obtained for the semantics of structuring operations and the implementation notion, we shall show how many verification aspects are independent of the logic used and, also, exhibit trade-offs between sensible verification methods and the expressive power of specifications and the flexibility of implementations.

### 1.3 Verification: what are the main problems?

In this section the main problems faced in the verification of implementations in $A S L$ and related languages are surveyed.

In order to be formal, verification must rely on an inference system, that is, a fixed collection of axioms and inference rules which can be combined in formal
proofs. In this sense, verification techniques based on semantic constructions between models such as [Hoa 72] and [Sch 87] are discarded.

The problem with inference systems is that they work at the level of theories and there are some very common concepts in algebraic specification which can only be properly described at the level of models. There are four main sources of problems:

1. Hiding auxiliary functions is a simple abstraction operation with a very simple semantics at the level of models. However, at the level of theories, theory morphisms are a very poor approximation to hiding.
2. Similarly, behavioural abstraction can only be described by a theory morphism in very concrete cases where a set of observations characterize a behaviour (see chapter 5) whereas defining behavioural abstraction at the level of models only takes a few lines.
3. Induction principles associated to reachability constraints are a second order concept and can be described at a model theoretic level by means of infinitary rules such as

$$
\frac{P(0), P(1), \ldots, P(k), \ldots}{\forall n \cdot P(n)}
$$

for natural numbers. On the other hand, there is no first order consistent and complete axiomatizable theory for arithmetic, by Gödel's first incompleteness theorem (cf. [Bar 77, BJ 80]), so theories are inadequate for specifying the natural numbers completely.
4. Parameterization produces neat structured specifications if the meaning of the parameters is respected by all the parameterized specifications used, i. $\epsilon$.
if they are invariant ${ }^{1}$. At the theory level, conservative extensions are a very poor approximation to invariance.

Due to at least these four reasons, specification languages tend to discard some of these common constructions in order to ease verification.

### 1.4 Related work

Although this thesis studies verification of implementation steps in $A S L$, the actual work refers to verification of implementation steps in arbitrary specification languages using the mentioned four constructions.

For this reason, this does not only relate to specific work on verification in $A S L$ such as [Bre 89], but also to a lot of previous work on proving correctness of implementations w.r.t. structured algebraic specifications.

In the following we review work and results in different frameworks for each of the four main sources of verification problems.

## Hiding in the literature

Hiding some of the components specified in an algebraic specification is an old common practice in equational specifications [GTW 76] which is fully justified in [TWW 78, BBTW 81]. The use of hidden parts enhances the expressive power of equational logic to include all functions of interest (semi-computable functions).

[^0]For the same reason that using hidden parts enhances expressive power, it prevents an adequate semantics based on presentations or theories, and it makes verification rather difficult.

In the literature, verification is frequently restricted to proving theorems from specifications with hidden parts. This is not a major problem and an institutionindependent and complete rule is given in [ST 88a].

On the other hand, proving implementations correct w.r.t. specifications with hidden parts is difficult. Proofs are frequently ad hoc, exploiting the implementation of the hidden components (if present) or using a general weakening rule for adding some extra components to the implementation.

Similarly, in abstract model specifications many details of the representation are hidden, i.e. they do not need to be implemented. In this context, the problem is known as specification bias and it gives rise to known problems in the verification of data reifications (see [Jon 86]).

Some specification languages such as CLEAR [BG 80] and LARCH [GHW 85] prefer to substitute true hiding by a theory-based SBO. This is not a solution to the problem but a decision to give up true hiding in exchange for another SBO with a better proof treatment but with less expressive power and, probably, less clear semantics.

## Behavioural abstraction in the literature

Algebraic specifications aim to describe the input/output behaviour of a system. Good algebraic frameworks for software development should allow any system respecting the input/output behaviour of a specification to be among its valid implementations. Unfortunately, this is frequently not the case.

Since early work in [GGM 76] the initial approach to specification has been questioned for its unsatisfactory treatment of behaviour. The final approach and, more successfully, the initial-behavioural approach give semantics to equational specifications in such a way that all desired implementations are valid.

This improvement of the semantics results in a loss on the proof-theoretical side. In the initial approach all ground terms are different unless they can be proven equal using equational logic [GM 81, MS 85], i.e. equational logic is complete for ground equations. This property is lost in the final and initial-behavioural approaches.

Theorem proving is still feasible in the final and initial-behavioural approaches using proofs by consistency [KM 87, Lin 87] but they are rather more cumbersome. Note, also, that for proving implementations correct, the initial approach is much simpler since all requirements for ground terms are encapsulated in a finite presentation.

In many approaches abstraction is related to an explicit or implicit collection of observable sentences or terms, e.g. ASL [Wir 86, ST 87]. In these cases correctness proofs might proceed by proving that all observable consequences of a specification are satisfied in its implementation. In practice, some of these proofs are not difficult using induction on observable contexts [Hen 88, Hen 89].

Outside the scope of equational specifications, specification languages with loose semantics frequently interpret the equality symbol used in specifications as an arbitrary equivalence relation or congruence [WB 89]. This solution works for some well-known examples where the implementation of the equality symbol involves, basically, an abstraction function from the values of the implementation to those in the specification. However, no attempt has been made to relate this technique to a formal notion of behaviour.

Finally, in abstract model specifications a strong concern with behavioural abstraction has led to abandoning implementation relations based on abstraction functions, as has been common practice since [Hoa 72], in favor of relations between abstract and concrete values [ Nip 86 , Jon $86, \mathrm{Sch} 87$ ]. This results in more complicated proofs of correctness.

## Reachability constraints in the literature

A reachability constraint prevents models of an abstract data type from having more values than those finitely generated by its operations; i.e. a reachability constraint imposes an induction principle. This technique is frequently used in algebraic specifications in order to specify standard models such as natural numbers, finite lists, etc.

Reachability constraints can be explicitly applied in some specification languages but, often, they are automatically imposed by the semantics of the language. In any case, reachability constraints increase the expressive power of first order specification languages but make a complete theorem prover out of the question [MS 85].

The lack of a complete proof system for first order theories with an induction principle does not seem very serious since, very frequently, a common induction rule such as structural induction [Bur 69] allows all desired theorems to be proven.

Nevertheless, for proving implementations correct, reachability constraints in one specification must be satisfied by reachability constraints in another specification. This aspect of proofs of correctness has long been neglected [Fa: 39].

Some theory-based specification languages prefer to substitute :rue induction principles by a structural induction schema (see the LARCH semantics in [GHW 85]); this results in a simpler proof system but reduces the expressive
power, e.g. it prevents specifications from distinguishing between standard and non-standard natural numbers.

## Persistency in the literature

Parameterized specifications are persistent if they do not affect the meaning of their parameters.

Since early work in the initial approach [TWW 78, Ore 83, EM 85] persistency has been shown to be a sufficient and almost necessary property for interpreting parameter passing as putting together the equations from the parameterized specification and the parameter. In other words, persistency allows the prover to ignore the functional semantics of parameterized specifications and work safely with the combination of equational presentations.

Conversely, if parameter passing is defined to be a putting together of sets of equations, persistency guarantees a functional interpretation of parameterized specifications which results in clearer semantics allowing structured implementation and verification.

Results in [Ore 83] show persistency to be a necessary condition for correct parameter passing in the initial approach. H.Ganzinger presents in [Gan 83] a proof-theoretic sufficient condition for persistency in the same context.

For specification languages with loose semantics the standard notion of persistency must be generalized from relations between models to relations between classes of models. In this thesis, we use two different generalizations, one called persistency and another called invariance, both defined in chapter 2.

In the context of specification languages with loose semantics, persistency (resp. invariance) is rarely mentioned [Ber 87]. However, the basic concerns about structured implementation and verification are explicitly stated [GB 80, ST 88b].

In practice, performing structured correctness proofs depends a great deal on preserving the meaning of whole subspecifications during implementation steps [Far 89]. This idea is formalized in this thesis by the relationship between invariance and a calculus for the management of subspecifications in proofs of correctness.

### 1.5 Overview of the thesis

ASL is basically the combination of five SBO's plus mechanisms for abstraction and parameterization. Starting from a subset of three of these SBO's and adding, later, the rest one by one or in groups we define and study many different sublanguages of $A S L$.

This thesis progresses from simpler to more difficult sublanguages studying the verification of implementation steps in each of them. This journey includes the study of theorem proving in $A S L$ and of the four main sources of verification problems mentioned above.

Chapter 2 introduces the necessary background for the thesis. In particular, it includes the definition of the specification language, the implementation relation, and the notion of logical system (institution) which parameterizes the specification language.

Chapter 3 gives an account of the results obtained by substituting actual specifications by theories approximating them. In this way, verification of correctness of implementation steps is reduced to theorem proving. This procedure is shown to be insufficient unless specifications are severely constrained. This chapter introduces the notion of $M$-completeness for characterizing inference rules, shows
that the rule for hiding is not M -complete, and gives various inference rules for common algebraic constructors.

Chapter 4 deals exclusively with the problem of hiding, first in isolation and then in the context of the other specification building operations. This chapter defines an institution-independent strategy for proving implementations correct w.r.t. specifications with hidden parts, shows that this strategy is sound and complete provided some conditions are met, and discusses the nature of these side conditions as well as how they can be established.

Chapter 5 deals with the problem of abstraction and behavioural abstraction. First some general notions related to the definition of abstraction are discussed, with the result that abstraction is identified with a certain kind of hiding and verification techniques for it are therefore inherited from chapter 4. Behavioural abstraction and related proof techniques used in the literature are analyzed in the context of our general results.

Chapter 6 deals with the problem of reachability constraints. In this case, there is little to say for an arbitrary institution, so detailed research is dedicated to the algebraic case. An inference system for the inference of reachability constraints in the algebraic framework is presented and shown to be sound and complete for single constraints and sets of independent constraints. Some known concepts such as sufficient completeness are revisited in relation to the interaction of reachability constraints and equations.

Finally, chapter 7 faces the matter of structure in specifications. In particular, it studies in which cases the structure of specifications can be used to structure proofs of correctness. Notions such as invariance turn out to be essential and are introduced via an inference system for shared subspecifications.

In summary, we expect to provide a wide review of the most important problems in the formal verification of implementations, working in a framework general
enough to include most possible cases. This panoramic view of the situation should help to distinguish the good kind of specifications and implementations, i.e. those which possess adequate proof methods.

## Chapter 2

## Preliminaries

### 2.1 Institutions

The concept of institution [GB 84] formalizes the idea of logical system. An institution is a category of models and a family of sentences, both indexed by a category of signatures and with a relation of satisfaction between models and sentences, such that satisfaction is preserved by translations along signature morphisms. These minimal requirements allow very many logical systems to be viewed as institutions, in particular, most of those used in formal specifications such as equational logic, Horn clause logic, higher order logic, infinitary logic, etc.

## Definition 2.1.1 An institution I consists of

1. a category SIG, whose objects are called signatures,
2. a functor Sen :SIG $\rightarrow$ Set, giving for each signature $\Sigma$ a set whose elements are called sentences over that signature, $\Sigma$-sentences,
3. a functor Mod : SIG $\rightarrow$ Cat $^{\text {op }}$ giving for each signature $\Sigma$ a category whose objects are called models over that signature, $\Sigma$-models, and whose arrows are called $\Sigma$-morphisms,
4. and a relation $\models_{\Sigma} \subseteq|\operatorname{Mod}(\Sigma)| \times \operatorname{Sen}(\Sigma)$ for each $\Sigma \in|S I G|$, called $\Sigma$ satisfaction, such that for each morphism $\sigma: \Sigma 1 \rightarrow \Sigma 2$ in $S I G$, the satisfaction condition

$$
M \models_{\Sigma 2} \operatorname{Sen}(\sigma)(\varphi) \quad \text { iff } \quad \operatorname{Mod}(\sigma)(M) \models_{\Sigma 1} \varphi
$$

holds for all $M \in|\operatorname{Mod}(\Sigma 2)|$ and $\varphi \in \operatorname{Sen}(\Sigma 1)$.

It is common practice to write $\sigma(\varphi)$ instead of $\operatorname{Sen}(\sigma)(\varphi)$ and $\left.M\right|_{\sigma}$ instead of $\operatorname{Mod}(\sigma)(M)$, so that the satisfaction condition can be expressed as $\cdot$

$$
M \models_{\Sigma 2} \sigma(\varphi) \quad \text { iff }\left.\quad M\right|_{\sigma} \models_{\Sigma 1} \varphi
$$

It is also very common to extend $\Sigma$-satisfaction from sentences to sets of sentences, so that for any $\Phi \subseteq \operatorname{Sen}(\Sigma)$ and model $M \in|\operatorname{Mod}(\Sigma)|$ satisfaction is defined as:

$$
M \models_{\Sigma} \Phi \stackrel{\text { def }}{\Longleftrightarrow} \forall \varphi \in \Phi . M \models_{\Sigma} \varphi
$$

Similarly, $\Sigma$-satisfaction can be extended to a relation between sets of $\Sigma$-sentences, so that for any $\Phi 1, \Phi 2 \subseteq \operatorname{Sen}(\Sigma)$ satisfaction is defined as:

$$
\Phi 1 \vDash_{\Sigma} \Phi 2 \stackrel{\text { def }}{\Longleftrightarrow} \forall M \in|\operatorname{Mod}(\Sigma)| . M \vDash_{\Sigma} \Phi 1 \Rightarrow M \vDash_{\Sigma} \Phi 2
$$

Particular cases include the satisfaction of a sentence by a set of sentences $\Phi \models_{\Sigma} \varphi$ and satisfaction between single sentences, $\varphi \models_{\Sigma} \varphi^{\prime}$, for $\varphi, \varphi^{\prime} \in \operatorname{Sen}(\Sigma)$ and $\Phi \subseteq$ $\operatorname{Sen}(\Sigma)$.

Occasionally, we shall use the notion $\#_{\Sigma}$ between $\Sigma$-models and sets of $\Sigma$ sentence to mean that a $\Sigma$-model does not satisfy any sentence in a set of $\Sigma$ sentences.

These concepts were first introduced in [BG 80] and studied further in [GB 84, GB 86, GB 90, Tar 86a, Tar 86b]. The concept of institution allows the structural mechanisms of a specification language to be defined for an arbitrary institution [ST 88a], so that a great deal of work can be done, once and for all, at an institution independent level and reused for any particular institution.

Sometimes the notion of institution is too general and some extra conditions are frequently added. Unless the contrary is stated, we shall assume institutions to have a finitely co-complete category of signatures and a finitely co-continuous model functor, like institutions with composable signatures in [ST 92] and reasonable and exact institutions in [DGS 91].

Intuitively, these properties allow the symbols defined in different signatures to be put together in a single signature without confusion but respecting "shared" symbols, in particular a pushout signature is a finite co-limit in SIG. Moreover, if the model functor Mod preserves finite co-limits (finitely co-continuous), every finite co-limit diagram in $S I G$ produces a limit diagram in Cat. In particular these properties imply the amalgamation lemma (cf. [EM 85, ST 88b]).

Lemma 2.1.2 (Amalgamation lemma) Let $\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle$ be an institution such that $S I G$ is finitely co-complete and Mod is finitely co-continuous. Consider a pushout in SIG as in the diagram:


Then, for any two models $A \in|\operatorname{Mod}(\Sigma 1)|$ and $B \in|\operatorname{Mod}(\Sigma 2)|$ such that $\left.A\right|_{\sigma 1}=$ $\left.B\right|_{\sigma 2}$, there exists a unique $\Sigma 12$-model $A \oplus B$ such that $\left.(A \oplus B)\right|_{\sigma 2^{\prime}}=A$ and $\left.(A \oplus B)\right|_{\sigma 1^{\prime}}=B . A \oplus B$ is called the amalgamated union of $A$ and $B$.

A fundamental piece missing in the definition of institution is an inference system allowing a sentence to be concluded from a set of sentences in a given logical system. That is why sometimes a institution $I$ is equipped with a sound inference system $\vdash^{\mathbf{I}}$, as in [HST 89a].

Usually an inference system $\vdash^{\mathrm{I}}$ is presented in the form of some axioms and some inference rules which allow us to conclude judgements of the form

$$
\Phi \vdash \vdash_{\Sigma}^{\mathbf{I}} \varphi
$$

where $\varphi$ is a $\Sigma$-sentence and $\Phi$ is a finite set of $\Sigma$-sentences for a signature $\Sigma$ in $\mathbf{I}$.
Therefore, an inference system $\vdash^{\text {I }}$ denotes a r.e. relation between finite sets of sentences and sentences over each signature. We shall call this relation the consequence relation of $\vdash^{\mathbf{I}}$ written $\mathcal{R}_{\Sigma}\left(\vdash_{\mathbf{I}}\right) \subseteq \mathcal{P}(\operatorname{Sen}(\Sigma)) \times \operatorname{Sen}(\Sigma)$ for every signature $\Sigma$ in $I$,

$$
\Phi \vdash_{\Sigma}^{\mathbf{I}} \varphi \stackrel{\text { def }}{\Longleftrightarrow}(\Phi, \varphi) \in \mathcal{R}_{\Sigma}\left(\vdash^{\mathbf{I}}\right)
$$

An inference system $\vdash^{I}$ is sound w.r.t. $I$ if

$$
\Phi \vdash_{\Sigma}^{\mathrm{I}} \varphi \Longrightarrow \Phi \vDash_{\Sigma} \varphi
$$

And it is complete if the converse holds,

$$
\Phi \vdash_{\Sigma}^{\mathrm{I}} \varphi \Longleftarrow \Phi \vDash_{\Sigma} \varphi
$$

The most common institutions used in formal specifications, such as equational logic, first order logic, Horn clause logic, etc., are equipped with sound and complete inference systems. This thesis will assume that every institution $I$ is equipped with a sound inference system $\vdash^{\mathbf{I}}$; completeness of $\vdash^{\mathrm{I}}$ will not be required.

Finally we need a concept to relate different institutions. Although some details have been a topic of discussion, we shall adopt institution morphisms as defined in [GB 84] with a slight technical difference as proposed in [ST 92].

Definition 2.1.3 Let

$$
\mathbf{I} \mathbf{1}=\left\{S I G 1, M o d 1, S e n 1, \models^{1}\right\} \quad \text { and } \quad \mathbf{I} \mathbf{2}=\left\{S I G 2, \operatorname{Mod} 2, S e n 2, \models^{2}\right\}
$$

be two institutions. Then, an institution morphism $\alpha: \mathbf{I} 1 \rightarrow \mathbf{I} 2$ consists of

1. a functor $\alpha_{S I G}: S I G 1 \rightarrow S I G 2$,
2. a natural transformation $\alpha_{M o d}: \operatorname{Mod} 1^{o p} \Rightarrow \alpha_{S I G}^{o p}: \operatorname{Mod} 2^{o p},{ }^{1}$ that is for each $\Sigma \in|S I G 1|$ (i.e. $\Sigma \in\left|S I G 1^{o p}\right|$ ) there exists a functor

$$
\alpha_{M o d} \Sigma: \operatorname{Mod} 1(\Sigma) \rightarrow \operatorname{Mod} 2\left(\alpha_{S I G}(\Sigma)\right)
$$

which is consistent with changes of signature; i.e. for all signature morphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$ in $S I G 1$ (i.e. $\sigma^{o p}: \Sigma^{\prime} \rightarrow \Sigma$ in $S I G 1^{o p}$ ),

$$
\operatorname{Mod} 1^{o p}\left(\sigma^{o p}\right) ; \alpha_{M o d} \Sigma=\alpha_{M o d} \Sigma^{\prime} ;\left(\alpha_{S I G}^{o p} ; \operatorname{Mod} 2^{o p}\right)\left(\sigma^{o p}\right)
$$

3. a natural transformation $\alpha_{S e n}: \alpha_{S I G} ;$ Sen $2 \Rightarrow$ Sen 1 , that is for each $\Sigma \in$ $|S I G 1|$ there exists a function,

$$
\alpha_{S e n} \Sigma: \operatorname{Sen} 2\left(\alpha_{S I G}(\Sigma)\right) \rightarrow \operatorname{Sen} 1(\Sigma)
$$

which is consistent with changes of signature; i.t. for all signature morphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$ in SIG1

$$
\alpha_{S e n} \Sigma ; S e n 1(\sigma)=\left(\alpha_{S I G} ; S e n 2\right)(\sigma) ; \alpha_{S e n} \Sigma^{\prime}
$$

such that the following satisfaction condition holds

$$
M \models_{\Sigma}^{1} \alpha_{S e n} \Sigma(\varphi) \quad \text { iff } \quad \alpha_{M o d} \Sigma(M) \models_{\alpha_{S I G}(\Sigma)}^{2} \varphi
$$

for all $\Sigma \in|S I G 1|, M \in \operatorname{Mod} 1(\Sigma)$ and $\varphi \in \operatorname{Sen} 2\left(\alpha_{S I G}(\Sigma)\right)$.

Intuitively, an institution morphism describes the situation in which satisfaction is independent of the change of institution.

[^1]
## $2.2 \quad A S L$ and constructors

In the following we give the syntax and semantics of a specification language like the one described in [SW 83, ST 88a, Wir 86] parameterized by an institution I. Note that here we use the name $A S L$ for the union of six specification building operations - SBO's for short - to which parameterization mechanisms, an abstraction operation and some other SBO's called constructors may be added a posteriori.

## Syntax

$A S L(\mathbf{I})$ is a specification language with raw terms

$$
S P==A_{\Phi} S P\left|T_{\sigma} S P\right| D_{\sigma} S P\left|M_{(\sigma, \nu)} S P\right| S P U S P \mid \epsilon_{\Sigma}
$$

where $\Phi$ is a finite set of sentences, $\Sigma$ a signature and $\sigma$ and $\iota$ signature morphisms in the institution $\mathbf{I}$.

Now, we can recursively define a signature for each of these terms.

Definition 2.2.1 Given an institution $\mathbf{I}$, the signature of an $A S L(\mathbf{I})$ term $S P$, written Sig $[S P]$, is defined as follows:

$$
\begin{array}{ll}
\operatorname{Sig}\left[A_{\Phi} S P\right]=\operatorname{Sig}[S P] & \operatorname{Sig}\left[T_{\sigma} S P\right]=\uparrow \sigma \\
\operatorname{Sig}\left[D_{\sigma} S P\right]=\downarrow \sigma & \operatorname{Sig}\left[M_{(\sigma, \iota} S P\right]=\operatorname{Sig}[S P] \\
\operatorname{Sig}[S P 1 U S P 2]=\operatorname{Sig}[S P 1] & \operatorname{Sig}\left[\epsilon_{\Sigma}\right]=\Sigma
\end{array}
$$

where the notation $\downarrow \sigma$ and $\uparrow \sigma$ refers respectively to the source and target objects of an arrow $\sigma$.

Among all raw terms we can distinguish the well-formed terms, which are those satisfying the following context conditions:

Definition 2.2.2 Given a specification SP of signature $\Sigma$,

- $A_{\Phi} S P$ is well-formed if $\Phi \subseteq \operatorname{Sen}(\Sigma)$ and $S P$ is well-formed.
- $T_{\sigma} S P$ is well-formed if $\downarrow \sigma=\Sigma$ and $S P$ is well-formed.
- $D_{\sigma} S P$ is well-formed if $\uparrow \sigma=\Sigma$ and $S P$ is well-formed.
- $M_{(\sigma, \iota)} S P$ is well-formed if $\uparrow \sigma=\downarrow \iota$ and $\uparrow(\sigma ; \iota)=\Sigma$ and $S P$ is well-formed.
- SP1 U SP2 is well-formed if SP1 and SP2 have the same signature and SP1 and SP2 are both well-formed.
- $\epsilon_{\Sigma}$ is well-formed.


## Semantics

Every well-formed specification $S P$ in $A S L(\mathbf{I})$ denotes a signature $\operatorname{Sig}[S P]$ in $S I G$ and a class of models $\operatorname{Mod}[S P]$ among the models $|\operatorname{Mod}(\operatorname{Sig}[S P])|$. The signature of a well-formed specification $\operatorname{Sig}[S P]$ is as defined for all specification terms and $\operatorname{Mod}[S P]$ is defined recursively as follows:

Definition 2.2.3 Given an institution $\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle$, the class of models denoted by a well-formed specification in $\operatorname{ASL}(\mathbf{I})$, written $\operatorname{Mod}[S P]$. is defined as follows:

$$
\begin{aligned}
& \operatorname{Mod}\left[A_{\Phi} S P\right]=\{M \in \operatorname{Mod}[S P] \mid M \models \Phi\} \\
& \operatorname{Mod}\left[T_{\sigma} S P\right]=\left\{M \in|\operatorname{Mod}(\uparrow \sigma)||M|_{\sigma} \in \operatorname{Mod}[S P]\right\}
\end{aligned}
$$

```
\(\operatorname{Mod}\left[D_{\sigma} S P\right]=\left\{\left.M\right|_{\sigma} \mid M \in \operatorname{Mod}[S P]\right\}\)
\(\operatorname{Mod}\left[M_{\langle\sigma,\rangle\rangle} S P\right]=\left\{M \in \operatorname{Mod}[S P]|M|_{\iota}\right.\) is \(\sigma\)-minimal \(\}\)
\(\operatorname{Mod}[S P 1 \quad U S P 2]=\operatorname{Mod}[S P 1] \cap \operatorname{Mod}[S P 2]\)
\(\operatorname{Mod}\left[\epsilon_{\Sigma}\right]=|\operatorname{Mod}(\Sigma)|\)
```

where a model $M \in|\operatorname{Mod}(\uparrow \sigma)|$ is $\sigma$-minimal if for every model $N \in|\operatorname{Mod}(\uparrow \sigma)|$, any monomorphism $m: N \rightarrow M$ such that $\left.m\right|_{\sigma}:\left.\left.N\right|_{\sigma} \rightarrow M\right|_{\sigma}$ is an isomorphism, is in fact an isomorphism in $\operatorname{Mod}(\uparrow \sigma)$.

Intuitively, $A_{\Phi}$ is the basic specification mechanism requiring some axioms to be satisfied. These axioms can be a list of equations, some first order axioms or something else depending on the institution used.
$T_{\sigma}$ and $D_{\sigma}$ provide the mechanisms to enlarge, reduce and modify the signature of a specification and the models accordingly, e.g. in the course of an enrichment or hiding. According to their original names in [ST 88a], $T_{\sigma}$ and $D_{\sigma}$ for $\sigma: \Sigma \rightarrow \Sigma^{\prime}$ should be read as:

- translate a $\Sigma$-specification $S P$ to another signature $\Sigma^{\prime}$ along $\sigma$, and
- derive a $\Sigma$-specification from a specification $S P$ over a richer signature $\Sigma^{\prime}$ using $\sigma$
respectively.
$U$ allows specifications over the same signature to be combined, giving the union of their requirements. Frequently, the specifications to be combined refer to different components of a system and, therefore, they are defined over different signatures. In this case, a $T_{\sigma}$ operator should be used to expand the signature of each specification to a common one so that $U$ can be applied.

Although defined as a binary SBO, $U$ is often used as an n-ary operation meaning a successive application of binary $U$ operations. Associativity of $U$ makes the order of application irrelevant.
$M_{(\sigma, \lambda)}$ allows some basic models of a specification to be selected. The precise meaning of basic model varies according to the meaning of the arrows in the category of models. Later, we shall see that taking models to be algebras and monomorphisms in $\operatorname{Mod}(\uparrow \sigma)$ to be injective homomorphisms, $M_{\langle\sigma,\rangle\rangle}$ constrains some sorts to be finitely generated. For a given target signature $\uparrow \iota$, the choice of $\sigma$ and $\iota$ decides which sorts are finitely generated and which operations are the generators.

Occasionally in some proofs we may use another SBO, namely $\{-\}$. This operation takes a model and delivers a specification as follows: Given a signature $\Sigma$ and a $\Sigma$-model $A$,

- $\{A\}$ is well-formed
$-\operatorname{Sig}[\{A\}]=\Sigma$ and $\operatorname{Mod}[\{A\}]=\{A\}$

Equality between $A S L$ specifications will be often used to indicate that two specifications have the same signature and class of models

$$
S P 1=S P 2 \text { iff } \operatorname{Sig}[S P 1]=\operatorname{Sig}[S P 2] \quad \text { and } \quad \operatorname{Mod}[S P 1]=\operatorname{Mod}[S P 2]
$$

We shall use the name selectors for those SBO's $L$ which always yield a specification with a class of models contained in the class of models of the parameter,
i.e. $\operatorname{Mod}[L S P] \subseteq \operatorname{Mod}[S P]$ for any specification $S P . \operatorname{In} A S L, A_{\Phi}, M_{(\sigma,\rangle)}$ and $U^{2}$ are selectors.

We shall use the name constructors for those SBO's $k$ whose semantics are defined pointwise by a function $f_{k}$ over the class of models of the parameter, i.e. $\operatorname{Mod}[k S P]=\left\{f_{k}(M) \mid M \in \operatorname{Mod}[S P]\right\}$ for any specification $S P$. In $A S L, D_{\sigma}$ is a constructor where $f_{D_{\sigma}}$ is $\|_{\sigma}$.

There some general facts of interest holding for the different SBO's.

Proposition 2.2.4 Specification building operations $U, A_{\Phi}, M_{\{\sigma,\rangle\rangle}, T_{\sigma}$ and all constructors are monotonic w.r.t. inclusion of model classes, i.e. if $\operatorname{Mod}[S P 1] \subseteq$ $\operatorname{Mod}[S P 2]$ then $\operatorname{Mod}[\xi S P 1] \subseteq \operatorname{Mod}[\xi S P 2]$ for all $S B O$ 's $\xi$ and specifications SP1 and SP2.

Proof Immediate from their definition.
Because of this fact, the following inequality

$$
\operatorname{Mod}[\xi S P 1] \cup \operatorname{Mod}[\xi S P 2] \subseteq \operatorname{Mod}[\xi S P 12]
$$

where $\operatorname{Mod}[S P 12]=\operatorname{Mod}[S P 1] \cup \operatorname{Mod}[S P 2]$ holds in general. Moreover, the opposite inclusion holds for $S P 1, S P 2$ built using the SBO's defined above.

Proposition 2.2.5 Specification building operations $U, A_{\Phi}, M_{\langle\sigma,\rangle\rangle}, T_{\sigma}$ and all constructors distribute over the union of model classes, i.e. for all specifications $S P^{\prime}, S P 1, S P 2$ and $S P 12$ such that $\operatorname{Mod}[S P 12]=\operatorname{Mod}[S P 1] \cup \operatorname{Mod}[S P 2]$,
$\operatorname{Mod}\left[A_{\Phi} S P 12\right]=\operatorname{Mod}\left[A_{\Phi} S P 1\right] \cup \operatorname{Mod}\left[A_{\Phi} S P 2\right]$

[^2]$\operatorname{Mod}\left[M_{(\sigma,\rangle)} S P 12\right]=\operatorname{Mod}\left[M_{\langle\sigma, \downarrow} S P 1\right] \cup \operatorname{Mod}\left[M_{(\sigma, \downarrow)} S P 2\right]$
$\operatorname{Mod}\left[S P^{\prime} U S P 12\right]=\operatorname{Mod}\left[S P^{\prime} \cup S P 1\right] \cup \operatorname{Mod}\left[S P^{\prime} U S P 2\right]$

$\operatorname{Mod}\left[S P 12 U S P^{\prime}\right]=\operatorname{Mod}\left[\begin{array}{lll}S P 1 & U S P^{\prime}\end{array}\right] \cup \operatorname{Mod}\left[S P 2 U S P^{\prime}\right]$
$\operatorname{Mod}\left[T_{\sigma} S P 12\right]=\operatorname{Mod}\left[T_{\sigma} S P 1\right] \cup \operatorname{Mod}\left[T_{\sigma} S P 2\right]$
$\operatorname{Mod}[k S P 12]=\operatorname{Mod}[k S P 1] \cup \operatorname{Mod}[k S P 2] \quad$ for all constructors $k$

Proof By definition, the fact that a model $M \in \operatorname{Mod}[S P 12]$ is included or not in $\operatorname{Mod}\left[A_{\Phi} S P 12\right], \operatorname{Mod}\left[M_{(\sigma, \iota)} S P 12\right], \operatorname{Mod}\left[S P^{\prime} U S P 12\right]$ and $\operatorname{Mod}\left[S P 12 U . S P^{\prime}\right]$ depends on $M$ and on $\Phi, M_{(\sigma, \iota)}$ and $S P^{\prime}$ respectively, but not on which other models appear in SP12. This "pointwise" selection of the models results in distributivity over the union of model classes.

In the case of $T_{\sigma}$ and an arbitrary constructor $k$ the resulting class of models $\operatorname{Mod}\left[T_{\sigma} S P 12\right]$ (and $\operatorname{Mod}[k S P 12]$ respectively) is defined pointwise for each model in $\operatorname{Mod}[S P 12]$. Hence, distributivity also holds.

Distributivity of a SBO over the union of model classes implies that that SBO is defined pointwise, i.e. $\operatorname{Mod}[\xi S P]=\bigcup_{A \in \operatorname{Mod}[S P]} \operatorname{Mod}[\xi\{A\}]$. This property is not to be confused with distributivity of a SBO over $U$.

Proposition 2.2.6 Specification building operations $U, A_{\Phi}, M_{(\sigma, \gamma)}, T_{\sigma}$ and all injective constructors distribute over $U$, i.e. $\operatorname{Mod}[\xi(S P 1 U S P 2)]=\operatorname{Mod}[\xi S P 1 U \xi S P 2]$.

Proof Since all these SBO's distribute over the union of model classes, we have that

$$
\operatorname{Mod}[\xi(S P 1 \quad U S P 2)]=\bigcup_{A \in \operatorname{Mod}\left[S P_{1} \quad U S P 2\right]} \operatorname{Mod}[\xi\{A\}]
$$

and, by definition of $U$,

$$
\operatorname{Mod}[\xi(S P 1 U S P 2)]=\bigcup_{A \in \operatorname{Mod}[S P 1] \cap \operatorname{Mod}[S P 2]} \operatorname{Mod}[\xi\{A\}] \subseteq \operatorname{Mod}[\xi S P 1 U \xi S P 2]
$$

On the other direction, we must ensure that each $\mathrm{SBO} \xi$ satisfies that

$$
\forall A \in \operatorname{Mod}[\xi\{M 1\}], B \in \operatorname{Mod}[\xi\{M 2\}] . A \neq B
$$

for any two different models $M 1$ and $M 2$.
Injective constructors are just those constructors satisfying this property.
The same property holds trivially for selectors since they do not change any model, and also for $T_{\sigma}$ since two models cannot be equal and have two different reducts.

There are two other properties of interest of an arbitrary SBO's w.r.t. a specification.

Definition 2.2.7 Given a specification building operation $\xi$, a specification $S P$ and a pair of morphisms $\langle\iota, \sigma\rangle$ such that $\uparrow \iota=\operatorname{Sig}[S P], \uparrow \sigma=\operatorname{Sig}[\xi S P]$ and $\Sigma=\downarrow \iota=\downarrow \sigma$, then


- $\xi$ is persistent w.r.t. $S P$ and $\langle\iota, \sigma\rangle$ iff for all models $A \in \operatorname{Mod}[S P]$, there exists a model $B \in \operatorname{Mod}[\xi S P]$ with the same reduct, $\left.A\right|_{\iota}=\left.B\right|_{\sigma}$.
- $\xi$ is invariant w.r.t. $S P$ and $\langle\iota, \sigma\rangle$, iff for all models $A \in \operatorname{Mod}[S P]$, every model $B \in \operatorname{Mod}[\xi\{A\}]$ has the same reduct, $\left.A\right|_{\iota}=\left.B\right|_{\sigma}$.

Note that a SBO $\xi$ can be persistent w.r.t. a specification $S P$ and a pair of morphisms $\langle\iota, \sigma\rangle$ without being invariant and vice versa. In the case of persistency, invariance may fail because for some $A \in \operatorname{Mod}[S P]$ the reduct $\left.A\right|_{\text {, }}$ belongs to $\operatorname{Mod}\left[D_{\sigma} \xi S P\right]$ but not to $\operatorname{Mod}\left[D_{\sigma} \xi\{A\}\right]$. In the opposite direction, if invariance holds, for some $A \in \operatorname{Mod}[S P]$ it may happen that $\operatorname{Mod}[\xi\{A\}]=\emptyset$ and that $\left.A\right|_{\iota} \notin \operatorname{Mod}\left[D_{\sigma} \xi S P\right]$.
$k+A S L$

In a stepwise process of refinement, it is often convenient to mix parts of a specification with pieces of program corresponding to parts of the specification which have already been implemented.

In order to formalize this, we can consider these pieces of program to be also SBO's. By doing so, we enrich $A S L$ to give a richer specification language $k+A S L$ by adding a generic specification building operation $\langle P, \Lambda\rangle$, where $P$ stands for a piece of program and $\Lambda$ for some properties $P$ satisfies.

Definition 2.2.8 A programming language $\mathcal{L}$ is compatible with an institution $\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle$ if each program $P$ in $\mathcal{L}$ denotes a triple

$$
\llbracket P \rrbracket=\left(\Sigma 1, \Sigma 2, f_{P}\right)
$$

where $\Sigma 1, \Sigma 2 \in|S I G|$ and $f_{P}:|\operatorname{Mod}(\Sigma 1)| \rightarrow|\operatorname{Mod}(\Sigma 2)|$.

Then, the new SBO can be formally defined as follows.

Definition 2.2.9 Given an institution $\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle$ and a compatible programming language $\mathcal{L}$, and let $P$ be a program in $\mathcal{L}$ with semantics

$$
\llbracket P \rrbracket=\left(\Sigma 1, \Sigma 2, f_{P}\right)
$$

then, $\langle P, \Lambda\rangle S P$ is well-formed if $S P$ is well-formed, $S i g[S P]=\dot{\Sigma} 1$ and $\Lambda \subseteq$ $\mathcal{P}(\operatorname{Sen}(\Sigma 1)) \times \operatorname{Sen}(\Sigma 2)$ such that for all $(\Phi, \varphi) \in \Lambda$ and $M \in|\operatorname{Mod}(\Sigma 1)|$,

$$
M \models_{\Sigma 1} \Phi \Rightarrow f_{P}(M) \models_{\Sigma 2} \varphi
$$

Moreover, the signature and models for such a well-formed $\langle P, \Lambda\rangle S P$ are defined as:

- $\operatorname{Sig}[\langle P, \Lambda\rangle S P]=\Sigma 2$
- $\operatorname{Mod}[\langle P, \Lambda\rangle S P]=\left\{f_{P}(M) \mid M \in \operatorname{Mod}[S P]\right\}$

The semantics of $\langle P, \Lambda\rangle$ are completely defined by the program $P$. The purpose of $\Lambda$ is to state all the relevant properties of $P$ in order to allow verification of specification entailments involving such a program (see chapters 3 and 7).

Note that these pieces of program are SBO's in $k+A S L$ and, more precisely, they are constructors, the so-called generic constructors.

Now, $k+A S L$ is not only parameterized by an institution but also by the programming language used in the generic constructors, thus $k+\operatorname{ASL}(\mathbf{I}, \mathcal{L})$.

## $\lambda+A S L$

Normally $A S L$ comes equipped with a parameterization mechanism based on $\lambda$ abstraction (see for example [SW 83, Wir 86, ST 88a]). Here, we consider such a mechanism as an extra feature which can be added to $A S L$, i.e. to the original six SBO's, to make up the richer language $\lambda+A S L$.

Raw terms in $\lambda+A S L$ are those of $A S L$ plus those generated by the inclusion of specification variables and lambda applications:

$$
S P==\ldots\left|X_{\Sigma}\right|(\lambda X: \Sigma . S P) S P
$$

the signature of which is defined by:

$$
\operatorname{Sig}\left[X_{\Sigma}\right]=\Sigma \quad \operatorname{Sig}[(\lambda X: \Sigma . S P 1) S P 2]=\operatorname{Sig}[S P 1]
$$

Well-formed terms in $\lambda+A S L$ are those closed terms whose actual parameters are of the required signature and which respect all the rules laid down in the definition of well-formed term in $A S L$. This can be summarized saying that well-formed terms in $\lambda+A S L$ are recursively defined by the 6 rules given in the definition of a well-formed $A S L$ term (Definition 2.2.2) plus the following seventh rule:

- $(\lambda X: \Sigma . S P 1) S P 2$ is well-formed if $\operatorname{Sig}[S P 2]=\Sigma$ and $S P 2$ and $S P 1\left[\epsilon_{\Sigma} / X_{\Sigma}\right]$ are both well-formed.
where $S P 1\left[\epsilon_{\Sigma} / X_{\Sigma}\right]$ is the specification term $S P 1$ where all free occurrences of $X_{\Sigma}$ have been substituted by $\epsilon_{\Sigma}$.

Finally, the models of a well-formed term are defined by adding:

$$
\operatorname{Mod}[(\lambda X: \Sigma . S P 1) S P 2]=\operatorname{Mod}\left[S P 1\left[S P 2 / X_{\Sigma}\right]\right]
$$

to those rules laid down for $A S L$. By definition of well-formed term in $\lambda+A S L$, solving all parameter substitutions reduces any well-formed $\lambda+A S L$ term to a wellformed $A S L$ term for which Mod has already been defined. As for simply typed lambda calculus, the Church-Rosser property guarantees Mod to be well-defined over well-formed terms in $\lambda+A S L$ and, in particular, $\operatorname{Sig}[(\lambda X: \Sigma . S P 1) S P 2]=$ $\operatorname{Sig}\left[S P 1\left[S P 2 / X_{\Sigma}\right]\right]$ for well-formed terms.

Since well-formed terms are always closed, the signature of each variable can always be inferred from the context. For this reason, subscripts indicating the signature of each variable will be dropped.

Lambda expressions of the form $(\lambda X: \Sigma . S P)$ are operations which can be used to build up specifications, i.e. they are SBO's but not specifications. For this reason verification of structured specifications, treated in the last chapter of the thesis, is mostly about arbitrary specification terms satisfying some semantical conditions between terms and subterms. Parameterization can be used to group explicitly (at the syntactical level) specification terms with semantical significance.

SBO's of the form ( $\lambda X: \Sigma . S P$ ) are monotonic w.r.t. the inclusion of model classes like ordinary SBO's in $A S L$, however. it may be the case that ( $\lambda X: \Sigma . S P$ ) does not distribute over the union of model classes despite the fact that all SBO's
used in $S P$ distribute. This is due to the possible multiple occurrences of a formal parameter $X$ in $S P$ [SST 90].
$\alpha+A S L$

Occasionally we may use the name $\alpha+A S L$ to refer to the extension of $A S L$ with an abstraction SBO as in [SW 83, ST 87]. However, no details will be given of that new operation until chapter 5 where it will be shown to be redundant.

## 2.3 $A S L(\mathrm{EQ})-A S L$ in the algebraic institution

Although most of the work in this thesis is valid for an arbitrary institution, in section 6.3 referring to reachability constraints, sections $3.4,6.4 .1$ and 7.3 .1 referring to $F Q R D$-constructors (see definition below), and section 5.3 .1 referring to behavioural abstraction, the algebraic institution is used.

This is probably the most widely used institution in work on formal specification and merits some special attention. In this section we review some basic definitions from algebra and revisit $A S L(\mathrm{I})$ in the case where I is the algebraic institution EQ, i.e. $A S L(\mathrm{EQ})$.

## The algebraic institution : EQ

In the following the institution EQ is defined by providing a category of signatures $S I G$, a model functor $A l g: S I G \rightarrow$ Cat $^{o p}$, a sentence functor $E q: S I G \rightarrow S e t$ and satisfaction relations $\left\{\models_{\Sigma}\right\}_{\Sigma \in|S I G|}$.

A signature is a pair $\langle S, \Omega\rangle$ where $S$ is a set of names (sort names) and $\Omega$ is a family of sets of names (operation names) $\left\{\Omega_{\omega, s}\right\}_{\omega \in S^{*}, s \in S}$. An element $f$ of $\Omega_{\omega, s}$ is denoted by $f: \omega \rightarrow s$.

A signature morphism $\sigma:\langle S, \Omega\rangle \rightarrow\left\langle S^{\prime}, \Omega^{\prime}\right\rangle$ is a pair $\left\langle\sigma_{S}, \sigma_{\Omega}\right\rangle$ where $\sigma_{S}$ : $S \rightarrow S^{\prime}$ and $\sigma_{\Omega}$ is a family of sets of functions $\left\{\sigma_{\omega, s}: \Omega_{\omega, s} \rightarrow \Omega_{\sigma_{S}(\omega), \sigma_{S}(s)}^{\prime}\right\}_{\omega \in S^{\bullet}, s \in S}$ where $\sigma_{S}^{*}(\omega)$ means application of $\sigma_{S}$ to every component of $\omega$, i.e. $\sigma_{S}^{*}\left(s_{1} \ldots s_{n}\right)=$ $\sigma_{S}\left(s_{1}\right) \ldots \sigma_{S}\left(s_{n}\right)$.

Two signature morphisms $\sigma 1:\langle S, \Omega\rangle \rightarrow\left\langle S^{\prime}, \Omega^{\prime}\right\rangle$ and $\sigma 2:\left\langle S^{\prime}, \Omega^{\prime}\right\rangle \rightarrow\left\langle S^{\prime \prime}, \Omega^{\prime \prime}\right\rangle$ compose by composing the functions they consist of; i.e.

$$
\sigma 1 ; \sigma 2=\left\langle\sigma 1_{S} ; \sigma 2_{S^{\prime}},\left\{\sigma 1_{\omega, s} ; \sigma 2_{\sigma 1_{S}^{*}}(\omega), \sigma 1_{\mathcal{S}}(s)\right\}_{\omega \in S^{*}, s \in S}\right\rangle
$$

Identity morphisms are those with a pair of identity functions between sorts and operation names.

Signatures together with signature morphisms form the category $S I G$ of signatures of EQ.

For the sake of readability, we shall omit the subscripts and superscripts of $\sigma$.

Given a signature $\Sigma=\langle S, \Omega\rangle$ a (total) $\Sigma$-algebra consists of an $S$-indexed family of sets (carriers) $|A|=_{\text {def }}\left\{|A|_{s}\right\}_{s \in S}$ and function $f_{A}:|A|_{s_{1}} \times \ldots \times|A|_{s_{n}} \rightarrow|A|_{s}$ for every $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Omega$.

Let $A$ and $B$ be two $\Sigma$-algebras. A $\Sigma$-homomorphism from $A$ to $B, h$ : $A \rightarrow B$, is an $S$-indexed family of functions $\left\{h_{s}\right\}_{s \in S}$ between the corresponding carriers, i.e. $h_{s}:|A|_{s} \rightarrow|B|_{s}$, which is consistent with the operations in $\Omega$, i.e. for all $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Omega$ and $a_{1} \in|A|_{s_{1}}, \ldots, a_{n} \in|A|_{s_{n}}, h_{s}\left(f_{A}\left(a_{1}, \ldots, a_{n}\right)\right)=$ $f_{B}\left(h_{s_{1}}\left(a_{1}\right), \ldots, h_{s_{n}}\left(a_{n}\right)\right)$.

Two $\Sigma$-homomorphisms $h 1: A \rightarrow B$ and $h 2: B \rightarrow C$ compose by composing the functions they consist of, i.e. $h 1 ; h 2=\left\{h 1_{s} ; h 2_{s}\right\}_{s \in S}$. Identity $\Sigma$ -
homomorphisms $h: A \rightarrow A$ consist of an identity function $h_{s}$ for each carrier $|A|_{s}$.

The algebras over a signature $\Sigma$ together with their $\Sigma$-homomorphisms form a category $\operatorname{Alg}(\Sigma)$.

Given a signature morphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$, the $\sigma$-reduct of a $\Sigma^{\prime}$-algebra $A^{\prime}$ is defined as the $\Sigma$-algebra $\left.A^{\prime}\right|_{\sigma}$ such that for all sorts $s$ in $\Sigma,\left|\left(\left.A^{\prime}\right|_{\sigma}\right)\right|_{s}={ }_{d e f}\left|A^{\prime}\right|_{\sigma(s)}$ and for all $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Sigma, f_{\left.A^{\prime}\right|_{\sigma}}=\sigma(f)_{A^{\prime}}$.

We can also define the $\sigma$-reduct of a $\Sigma^{\prime}$-homomorphism $h^{\prime}: A^{\prime} \rightarrow B^{\prime}$, where $A^{\prime}$ and $B^{\prime}$ are $\Sigma^{\prime}$-algebras, as the $\Sigma$-homomorphism $\left.h^{\prime}\right|_{\sigma}:\left.\left.A^{\prime}\right|_{\sigma} \rightarrow B^{\prime}\right|_{\sigma}$ with $\left(\left.h^{\prime}\right|_{\sigma}\right)_{s}={ }_{d e f} h_{\sigma(s)}^{\prime}$ for all sorts $s$ in $\Sigma$.

With this, $-\left.\right|_{\sigma}$ turns out to be a functor from $\operatorname{Alg}\left(\Sigma^{\prime}\right)$ to $A \lg (\Sigma)$, and therefore we can define $\mathrm{Alg}: S I G \rightarrow C a t^{o p}$ as the functor mapping each signature $\Sigma$ to a category of models $A \lg (\Sigma)$ and each signature morphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$ to $\left.\right|_{\sigma}$ : $A \lg \left(\Sigma^{\prime}\right) \rightarrow A \lg (\Sigma)$, that is, $A l g$ is the model functor in $\mathbf{E Q}$.

Given a signature $\Sigma=\langle S, \Omega\rangle$, a $\Sigma$-term $t$ of sort $s$ over an $S$-indexed set of variables $X$ disjoint from $\Omega$, is either a variable $x \in X_{s}$ or the composition of a function name $f: s_{1}, \ldots, s_{n} \rightarrow s \in \Omega^{3}$ with $\Sigma$-terms $t_{1}, \ldots, t_{n}$ over $X$ of sort $s_{1}, \ldots, s_{n}$ respectively.

The set of terms over each sort plus the rules for composing smaller terms to form bigger terms constitute a $\Sigma$-algebra, the so-called term algebra, $T_{\Sigma}(X)$. The carrier of a sort $s$ in $T_{\Sigma}(X)$ consists of all $\Sigma$-terms of sort $s$ over $X$.

A valuation of $X$ over a $\Sigma$-algebra $A$ is a $\Sigma$-homomorphism $\nu: T_{\Sigma}(X) \rightarrow A$.

[^3]Fact 2.3.1 $A$ valuation $\nu$ of $X$ over $A$ is uniquely defined by the values assigned to each variable in $X$ and, if $X$ is empty, $\nu$ over $A$ is unique.

The latter is the case because a $\Sigma$-term without variables can be uniquely evaluated in a $\Sigma$-algebra $A$ by substituting each constant and function name by its value in $A$, thus there is a unique $\Sigma$-homomorphism $\nu: T_{\Sigma}(\emptyset) \rightarrow A ;$ ie. $T_{\Sigma}(\emptyset)$, usually written $T_{\Sigma}$, is an initial object in the category $\operatorname{Alg}(\Sigma)$. Analogously for terms with variables, the value of a term over $X$ in an algebra $A$ is uniquely determined by the values assigned to the variables.

Final objects in $\operatorname{Alg}(\Sigma)$ are algebras with each carrier being a singleton. In this case, all functions and constants have a unique possible interpretation and therefore, there is a unique $\Sigma$-homomorphism from an arbitral $J \Sigma$-algebra $A$ to a final $\Sigma$-algebra $\perp_{\Sigma}, h: A \rightarrow \perp_{\Sigma}$.

Given a signature $\Sigma=\langle S, \Omega\rangle$, a $\Sigma$-equation consists of an $S$-indexed set of variables $X$ and a pair of $\Sigma$-terms over $X$ of the same sort $s \in S, t 1, t 2 \in\left|T_{\Sigma}(X)\right|_{s}$, and it is normally denoted by $\forall X . t 1=t 2$. A $\Sigma$-algebra $A$ satisfies a $\Sigma$-equation, $A \models \forall X . t 1=t 2$, if $t 1$ and $t 2$ evaluate to the same value, $\nu(t 1)=\nu(t 2)$ (written also $A, \nu \models t 1=t 2$ ), for all valuations $\nu: T_{\Sigma}(X) \rightarrow A$.

Given a signature orphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$, the translation of a $\Sigma$-term $t$ over $X$ according to $\sigma$ is a $\Sigma^{\prime}$-term over $\sigma(X), \sigma(t)$, where $\sigma(X)$ is a $S^{\prime}$-indexed set of variables such that, for all $s \in S$

$$
x_{s}{ }^{4} \in \sigma(X)_{\sigma(s)} \quad \text { iff } \quad x \in X_{s}
$$

and $\sigma(X)_{s^{\prime}}$ is empty for those sorts $s^{\prime} \in S^{\prime}$ which are not the image of any sort in $S$. Then, $\sigma(t)$ is the $\Sigma^{\prime}$-term over $\sigma(X)$ resulting from the substitution

[^4] venting two variables of different sorts to have the same name.
of all function names $f$ in $t$ by $\sigma(f)$ and variables $x \in X_{s}$ by $x_{s} \in \sigma(X)_{\sigma(s)}$. Finally, the translation of the $\Sigma$-equation $\forall X . t 1=t 2$ along $\sigma$ is the $\Sigma^{\prime}$-equation $\forall X^{\prime} . \sigma(t 1)=\sigma(t 2)$ where $X^{\prime}$ is $\sigma(X)$.

The functor $E q$ mapping each signature $\Sigma$ to the set of $\Sigma$-equations and each signature morphism $\sigma$ to the translation function between equations, is the sentence functor $E q: S I G \rightarrow$ Set of EQ. And each satisfaction relation $\models_{\Sigma}$ is as defined above between $\Sigma$-algebras and $\Sigma$-equations.

Fact 2.3.2 (GB 84) The satisfaction condition holds in EQ.

It is the case that $S I G$ has finite co-limits and $A l g$ preserves finite co-limits, therefore the amalgamation lemma holds in EQ.

Moreover, the institution EQ is equipped with a sound and complete inference system $\vdash^{\mathrm{EQ}}$. This is called multi-sorted equational logic and it has been extensively used in algebraic specification (c.f. [GM 81, EM 85]).

## Some more algebraic background

Given a set of $\Sigma^{\prime}$-equations $e q$, we can define $\operatorname{Mod}\left[A_{e q} \epsilon_{\Sigma^{\prime}}\right]$ to be the full subcategory of $A \lg \left(\Sigma^{\prime}\right)$ composed of those algebras satisfying the equations in eq. It is a well-known result of universal algebra (see [GTW 76]) that:

Fact 2.3.3 For every morphism $\sigma: \Sigma \rightarrow \Sigma^{\prime}$ and set of $\Sigma^{\prime}$-equations eq, the left adjoint Fre $e_{\sigma}^{e q}: \operatorname{Alg}(\Sigma) \rightarrow \operatorname{Mod}\left[A_{e q} \epsilon_{\Sigma^{\prime}}\right]$ of the reduct functor $\left.\right|_{\sigma}: \operatorname{Mod}\left[A_{e q} \epsilon_{\Sigma^{\prime}}\right] \rightarrow$ $A \lg (\Sigma)$ exists.

In particular, considering $\Sigma$ to be an empty signature, Free $e_{\sigma}^{e q}$ can only be applied to the empty algebra and it produces an initial $\Sigma^{\prime}$-algebra (unique up to isomorphism) in the category $\operatorname{Mod}\left[A_{e q} \epsilon_{\Sigma^{\prime}}\right]$ of $\Sigma^{\prime}$-algebras which satisfy eq.

A subalgebra $B$ of a $\Sigma$-algebra $A$ is another $\Sigma$-algebra such that for every sort $s$ in $\Sigma,|B|_{s} \subseteq|A|_{s}$ and for all $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Sigma$ and $b_{1} \in|B|_{s_{1}}, \ldots, b_{n} \in|B|_{s_{n}}$, $f_{A}\left(b_{1}, \ldots, b_{n}\right)=f_{B}\left(b_{1}, \ldots, b_{n}\right)$.

We say that a subalgebra of a $\Sigma$-algebra $A$ is reachable on sort $s$ if it differs from $A$ only on $|A|_{s}$, and it contains no proper subalgebra which differs only on $|A|_{s}$. Similarly reachability can be defined with respect to a set of sorts.

Fact 2.3.4 For all $\langle S, \Omega\rangle$-algebras $A$ and set of sorts $G \subseteq S$ there is a unique reachable subalgebra Reach $_{G}(A)$ of $A$ on sorts $G$.

Taking all carriers of sorts not in $G$ as identical to the corresponding carriers in $A$, we can construct the subalgebra $\operatorname{Reach}_{G}(A)$ taking as carriers for sorts in $G$ only those values in $A$ which are finitely generated from constants and values of sorts not in $G$. By construction, all values in $\operatorname{Reach}_{G}(A)$ should be included in any subalgebra of $A$ which respects carriers of sorts not in $G$; hence uniqueness.

Intuitively, Reach $_{G}$ removes from each carrier of each sort in $G$ those values which can not be computed (reached) using the operations in $\Omega$ and the values of the sorts not in $G$. Often, these non-reachable values are called "junk".

The definition of reachable algebra on a set of sorts is clearly related to the general notion of minimal model. Consider a category of algebras $\operatorname{Alg}(\langle S, \Omega\rangle)$ and a set of distinguished sorts $G \subseteq S$, then the models of a well-formed specification $M_{\left\langle\sigma, i d_{(S, \Omega)}\right\rangle} S P$ where $\sigma:\left\langle S \backslash G, \Omega^{\prime}\right\rangle \hookrightarrow\langle S, \Omega\rangle$ with an arbitrary set of function names $\Omega^{\prime} \subseteq \Omega$ are:

$$
\{A \in \operatorname{Mod}[S P] \mid A \text { is reachable on sorts } G\}
$$

If a second morphism $\iota:\langle S, \Omega\rangle \rightarrow \Sigma$ is considered then the models of the specification $M_{\langle\sigma, \iota\rangle} S P$ are:
$\left\{A \in \operatorname{Mod}[S P]|A|_{2}\right.$ is reachable on sorts $\left.G\right\}$

Alternatively to the definition above, we can also say that a $\langle S, \Omega\rangle$-algebra $A$ is reachable on sorts $G \subseteq S$ if there is a ( $S \backslash G$ )-sorted set of variables $X$ (disjoint from $\Omega$ ) such that for every value $v \in|A|_{r}$ of a sort $r \in G$ there exists a term $t_{v} \in\left|T_{(S, \Omega)}(X)\right|$ and a valuation $\nu: T_{\langle S, \Omega\rangle}(X) \rightarrow A$ such that $\nu\left(t_{v}\right)=v$. Because of this definition reachable algebras are also called finitely generated algebras.

Let $V / \equiv$ denote the quotient of the set $V$ modulo the equivalence relation $\equiv \subseteq V \times V$.

A congruence $\sim$ on a $\langle S, \Omega\rangle$-algebra $A$ is a $S$-sorted equivalence relation $\sim \subseteq|A| \times|A|$ which is consistent with the operations of $A$, i.e. for all $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Omega$, if $a_{1}, b_{1} \in|A|_{s_{1}}, \ldots, a_{n}, b_{n} \in|A|_{s_{n}}$ and $a_{1} \sim b_{1}, \ldots, a_{n} \sim b_{n}$ then $f_{A}\left(a_{1}, \ldots, a_{n}\right) \sim f_{A}\left(b_{1}, \ldots, b_{n}\right)$. Some well-known facts of universal algebra follow:

Fact 2.3.5 Let $\sim$ be a congruence on a $\Sigma$-algebra $A$, then $A / \sim$ is a well-defined $\Sigma$-algebra, where $\left.|A| \sim\right|_{s}=|A|_{s} \mid \sim$ and for all $f: s_{1}, \ldots, s_{n} \rightarrow s$ in $\Sigma$ and $a_{1} \in|A|_{s_{1}}, \ldots, a_{n} \in|A|_{s_{n}}, f_{A / \sim}\left(\left[a_{1}\right], \ldots,\left[a_{n}\right]\right)=\left[f_{A}\left(a_{1}, \ldots, a_{n}\right)\right]$.

Fact 2.3.6 For any set eq of $\Sigma$-equations and $\Sigma$-algebra $A$ there is a least congruence $\sim_{A}^{e q}$ such that $A / \sim_{A}^{e q}=e q$.

## Constructors $F Q R D$

In algebraic specifications is common to express implementation relations via the combination of some constructors [Ehr 81, EKMP 82, ST 88b]. For this use, there are some standard constructors used in equational specifications, namely, free-extension, quotient, restriction to the reachable subalgebra and derive along a signature morphism.

| term | $\operatorname{Sig}[t e r m]$ | $\operatorname{Mod}[$ term $]$ | Context conditions |
| ---: | :--- | :--- | :--- |
| $F_{\sigma}^{e q} S P$ | $\uparrow \sigma$ | $\left\{F r e e_{\sigma}^{e q}(A) \mid A \in \operatorname{Mod}[S P]\right\}$ | $\operatorname{Sig}[S P]=\downarrow \sigma ; e q \subseteq \operatorname{Sen}(\uparrow \sigma)$ |
| $Q_{e q} S P$ | $\operatorname{Sig}[S P]$ | $\left\{A / \sim_{A}^{e q} \mid A \in \operatorname{Mod}[S P]\right\}$ | $e q \subseteq \operatorname{Sen}(\operatorname{Sig}[S P])$ |
| $R_{G} S P$ | $\operatorname{Sig}[S P]$ | $\left\{\operatorname{Reach}_{G}(A) \mid A \in \operatorname{Mod}[S P]\right\}$ | $G \subseteq \operatorname{Sorts}(\operatorname{Sig}[S P])$ |

Note that derive is not included since $D_{\sigma}$ is already one of the six SBO's in $A S L$ and therefore it enjoys institution-independent semantics in contrast to $F_{\sigma}^{e q}, Q_{e q}$ and $R_{G}$.

These constructors are powerful enough to describe useful implementation relations [Ehr 81], they have simple model-theoretical semantics and they have been treated in the literature together with equational specifications for a long time. In this thesis, generic constructors as defined in 2.2 .9 are preferred because of their institution-independent semantics and their explicit proof-theoretical significance, nevertheless $F Q R D$ constructors will still be considered in some sections where concrete examples are presented.

## Abstraction

Although no abstraction operation has been defined for $A S L$ above, $A S L(\mathrm{EQ})$ is frequently extended to include an abstraction SBO which closes the class of models of a specification w.r.t. behavioural equivalence [SW 83, ST 87]. In the algebraic institution, this is often understood as defining some sorts of a specification to be non-observable.

The semantics of abstraction will be discussed in detail in chapter 5 , both for the general case and for EQ.

## Algebras as functors

Since early work by F.W.Lawvere [Law 63] (cf. [GTWW 75, Poi 86]), there has been an alternative categorical definition of an algebra.

Given an algebraic signature $\Sigma=\langle S, \Omega\rangle$, there is a category $S t_{\Sigma}$ with finite products, defined as follows:

1. objects are words $\omega \in S^{*}$,
2. morphisms are tuples of $\Sigma$-terms $\left\langle t_{1}, \ldots, t_{n}\right\rangle\left(x_{1}, \ldots, x_{m}\right): s_{1} \ldots s_{m} \rightarrow s_{1}^{\prime} \ldots s_{n}^{\prime}$ where $x_{i}$ is a variable of sort $s_{i}$ for all $i=1, \ldots, m$ and $t_{j}$ is a term of sort $s_{j}^{\prime}$ over variables $x_{1}, \ldots, x_{m}$ for all $j=1, \ldots, n$,
3. and composition is substitution

$$
\begin{aligned}
& \left\langle t_{1}, \ldots, t_{n}\right\rangle\left(x_{1}, \ldots, x_{m}\right) ;\left\langle t_{1}^{\prime}, \ldots, t_{p}^{\prime}\right\rangle\left(y_{1}, \ldots, y_{n}\right) \\
& =\left\langle t_{1}^{\prime}\left[t_{1} / y_{1}, \ldots, t_{n} / y_{n}\right], \ldots, t_{p}^{\prime}\left[t_{1} / y_{1}, \ldots, t_{n} / y_{n}\right]\right\rangle\left(x_{1}, \ldots, x_{m}\right)
\end{aligned}
$$

Intuitively, the objects are sort names and the morphisms are the function names in $\Sigma$ going from the parameter sorts to the result sort. Since morphisms must be closed under composition, all composite functions must also be included. Moreover, since functions in $\Sigma$ may have no parameters (constants) or more than one parameter, sort names must be replaced by words of sort names and functions by tuples of functions.

Note that in the literature, except in [Poi 86], it is customary to consider the arrows in $S t_{\Sigma}$ reversed, that is going from the sort of the result to the sorts of the parameters. In this case $S t_{\Sigma}$ is closed under finite sums (co-products) instead of products, but this difference is irrelevant.

Now, $\Sigma$-algebras can be seen as product-preserving functors from $S t_{\Sigma}$ to the category of sets Set.

Theorem 2.3.7 (Law 63) The category of $\Sigma$-algebras is isomorphic to the category of functors $F: S t_{\Sigma} \rightarrow$ Set preserving finite products with natural transformations as morphisms.

This functorial view of algebras will be used in chapter 5 in connection with the definition of behaviour, and also as a motivation for the category of specifications considered in chapter 7.

### 2.4 Derived syntax

Although the syntax of specifications has been fixed above, such a presentation of specifications is only useful for expressing inference rules or structural properties in a concise form. The actual writing of specifications becomes tedious and unreadable unless a derived language or at least a derived syntax is used.

Since its first appearance in [SW 83], $A S L$ has been promoted as a kernel language upon which real specification languages can be defined. In this sense, the semantics of languages such as PLUSS [Gau 84, BGM 89] and Extended ML [ST 86] have been defined in terms of $A S L$. However, in the examples given in this thesis we want to use as little extra syntax as possible, that is why we shall only define a concrete syntax for a few common constructions in $A S L(\mathbf{E Q})$.

1. $S P=$ sorts $S$ \{sort names operations $\Omega$ \{function names over sorts in $S$ \} axioms $\Phi \quad$ \{sentences over the signature $\langle S, \Omega\rangle\}$ end
defines $S P$ to be the specification $A_{\Phi} \epsilon_{\{S, \Omega)}$ in $A S L(E Q)$ and any other institution with algebraic signatures. These specifications are commonly called basic specifications.
2. $S P=$ sorts $S$
hidden sorts $H S$ \{hidden sort names\}
operations $\Omega$ \{function names over sorts in $S$ \}
hiddenoperations $H \Omega$ \{hidden function names over sorts $S \cup H S$ \}
axioms $\Phi \quad\{$ sentences over $\langle S \cup H S, \Omega \cup H \Omega\rangle\}$
end
defines $S P$ to be a basic specification with a part of the signature hidden, $D_{\iota} A_{\Phi} \epsilon_{(S \cup H S, \Omega \cup H \Omega\rangle}$ where $\iota$ is the inclusion $\iota:\langle S, \Omega\rangle \hookrightarrow\langle S \cup H S, \dot{\Omega} \cup H \Omega\rangle$.
3. Let $S P^{\prime}$ be a specification over a signature $\left\langle S^{\prime}, \Omega^{\prime}\right\rangle$, then
```
SP = Enrich SP' by
        sorts S
        operations \Omega {functions names over sorts in S\cupS'}
        axioms }\Phi\quad{\mathrm{ sentences over }\langleS\cup\mp@subsup{S}{}{\prime},\Omega\cup\mp@subsup{\Omega}{}{\prime}\rangle
    end
```

defines $S P$ to be a specification $A_{\Phi} T_{\imath} S P^{\prime}$ where $\iota$ is the inclusion of the signature $\left\langle S^{\prime}, \Omega^{\prime}\right\rangle$ into the extended signature $\left\langle S \cup S^{\prime}, \Omega \cup \Omega^{\prime}\right\rangle$. Enrich is defined for $A S L$ over any institution having algebraic signatures.

Enriched specifications may be written as $\left(A_{\Phi} T_{\iota}\right) S P^{\prime}$ in order to emphasize each single enrichment. This can be formalized in terms of parameterized specifications as follows:

Definition 2.4.1 $A n$ enrichment by $\Sigma_{e}$-axioms $\Phi_{\varepsilon}$ w.r.t. a signature inclusion $\iota_{e}: \Sigma \hookrightarrow \Sigma_{e}$ is a parameterized specification $\left(\lambda X: \Sigma . A_{\Phi_{e}} T_{\iota_{e}} X\right)$ which produces a specification over $\Sigma_{e}$ when it is applied to a specification over $\Sigma$. Enrichments are usually written as $\left(A_{\Phi_{e}} T_{\iota_{e}}\right)$.

This notation is particularly useful in the following case where two enrichments are considered. We also use this notation in institutions without algebraic signatures, where the combination of translation along a signature morphism and imposing axioms has an effect analogous to enrichment in EQ.
4. $S P=$ Enrich $S P^{\prime}$ by

$$
\text { Hidden } \quad\{\text { Hidden enrichment }\}
$$

sorts $H S$ operations $H \Omega$ axioms $\Phi_{k}$ in $\{$ Visible enrichment $\}$ sorts $S$ operations $\Omega$ axioms $\Phi_{v}$ end
defines $S P$ to be a specification $D_{\iota_{h}^{\prime}}\left(A_{\Phi_{v}} T_{\iota_{v}}\right)\left(A_{\Phi_{h}} T_{\iota_{h}}\right) S P^{\prime}$ where $\iota_{h}, \iota_{h}^{\prime}$ and $\iota_{v}$ are inclusions as follows, assuming $\left\langle S^{\prime}, \Omega^{\prime}\right\rangle$ to be the signature of $S P^{\prime}$ :

$$
\begin{gathered}
\iota_{h}:\left\langle S^{\prime}, \Omega^{\prime}\right\rangle \hookrightarrow\left\langle S^{\prime} \cup H S, \Omega^{\prime} \cup H \Omega\right\rangle \\
\iota_{v}:\left\langle S^{\prime} \cup H S, \Omega^{\prime} \cup H \Omega\right\rangle \hookrightarrow\left\langle S^{\prime} \cup H S \cup S, \Omega^{\prime} \cup H \Omega \cup \Omega\right\rangle \\
\iota_{h}^{\prime}:\left\langle S^{\prime} \cup S, \Omega^{\prime} \cup \Omega\right\rangle \hookrightarrow\left\langle S^{\prime} \cup H S \cup S, \Omega^{\prime} \cup H \Omega \cup \Omega\right\rangle
\end{gathered}
$$

Note that enriching with the help of some auxiliary sorts and functions results in a different specification term than enriching a specification with a part of the signature hidden, which produces $D_{i_{h}^{\prime}}^{\prime}\left(A_{\Phi_{v} \cup \Phi_{h}} T_{\iota_{h} ; \iota_{v}}\right) S P^{\prime}$. Although both terms specify the same class of models, the former specification term is appropriate for those specification transformations defined in chapter 4.
5. Let $S P^{\prime}$ be a specification over a signature $\left\langle S^{\prime}, \Omega^{\prime}\right\rangle, G$ and $S$ be disjoint sets of sorts included in $S^{\prime}$ and $F$ be a subset of $\Omega^{\prime}$ using sorts in $S \cup G$, then
$S P=$ Reachable on $G$ using $F$ from $S$ $S P^{\prime}$
also written $M_{\langle G, F, S\rangle} S P^{\prime}$, defines $S P$ to have as models those models of $S P^{\prime}$ in which the carriers of sorts in $G$ are finitely generated by the functions in $F$ using the carriers of sorts in $S$. Formally, $S P$ is $M_{\langle\sigma, \iota\rangle} S P^{\prime}$ where $\iota$ and $\sigma$ are signature inclusions as follows:

$$
\langle S, \emptyset\rangle \stackrel{\sigma}{\hookrightarrow}\langle S \cup G, F\rangle \stackrel{\iota}{\hookrightarrow}\left\langle S^{\prime}, \Omega^{\prime}\right\rangle
$$

An $M_{\langle\sigma, \iota\rangle}$ operator in EQ, and in particular $M_{\langle G, F, S\rangle}$, is commonly called a reachability constraint. Often the same name is used in other institutions where $M_{(\sigma,\rangle)}$ is similarly related to reachable or finitely generated models.

In chapter 6 , constraints $M_{(\sigma, \iota)}$ are treated as sentences $\ll \sigma, \iota \gg$ in an institution with constraints (Theorem 6.2.1). In particular, constraints $M_{(G, F, S)}$ written in the form

$$
\text { Reachable on } G \text { using } F \text { from } S
$$

can be used as sentences in the axioms part of a specification.
6. $S P=$ Non observable on $N O$ \{Non-observable sorts \}

$$
S P^{\prime}
$$

defines $S P$ to be a specification $T_{o} D_{o} S P$ where $o$ is an abstraction morphism shifting sorts in $N O$ from observable to non-observable. The definition of $o$ and the meaning of $T_{o} D_{o}$ will be clear once abstraction morphisms and behaviours are defined in chapter 5 .

### 2.5 Other institutions

In this thesis results at the institutional level are regarded as exceptions. Most work studies institution-independent aspects of verification while isolated sections are expressed mainly in terms of $A S L(\mathbf{E Q})$. However, other common institutions are also used.

Some results in chapter 6 and many examples through this thesis refer to institutions which enrich the algebraic institution EQ by adding other kinds of sentences and extending the satisfaction relation accordingly. In these cases, both the category of algebraic signatures $S I G$ and the model functor $A l g$ are as in EQ. Normally the sentences of EQ are enriched with conditional equations, disjunctions, negation, etc.

Technically, it is easier to define the institutions of first order logic FOL and first order logic with equality FOLEQ, then most institutions of interest are specializations of FOLEQ (as presented in [GB 84]). In the following a similar simplified presentation is given:

## FOL

Given the category $S I G$ of algebraic signatures, $S I G_{F}$ is a category as follows:

- Objects: Pairs $\langle\Sigma, Q\rangle$ where $\Sigma=\langle S, \Omega\rangle$ is a standard algebraic signature, $\Sigma \in|S I G|$, and $Q$ is a $S$-sorted set where each $Q_{s}$ is a set of binary predicate symbols.
- Morphisms: Pairs $\langle\sigma, f\rangle:\langle\Sigma 1, Q 1\rangle \rightarrow\langle\Sigma 2, Q 2\rangle$ where $\sigma: \Sigma 1 \rightarrow \Sigma \cdot$ is an algebraic signature morphism and $f: Q 1 \rightarrow Q 2$ a function mapping each $r \in Q 1_{s}$ to a predicate $f(r) \in Q 2_{\sigma(s)}$ for all $s \in S$.

For any object $\Pi=\langle\Sigma, Q\rangle$ in $\left|S I G_{F}\right|$, we define a $\Pi$-structure $\mathcal{A}$ to consist of a $\Sigma$-algebra $\mathcal{A}_{\Sigma}$ and a relation $r_{\mathcal{A}} \subseteq\left|\mathcal{A}_{\Sigma}\right|_{s} \times\left|\mathcal{A}_{\Sigma}\right|_{s}$ for each $r \in Q_{s}$.

Let A and B be two $\Pi$-structures. A structure morphism $h: \mathcal{A} \rightarrow \mathcal{B}$ is a $\Sigma$-homomorphism $h: \mathcal{A}_{\Sigma} \rightarrow \mathcal{B}_{\Sigma}$ such that for all $r \in Q_{s}$ in $\Pi$ and $(a, b) \in r_{\mathcal{A}}$, $\left(h_{s}(a), h_{s}(b)\right) \in r_{\mathcal{B}}$.

The structures over an object $\Pi$ together with their structure morphisms form a category $\operatorname{Str}(\mathrm{II})$.

Given a morphism $\tau=\langle\sigma, f\rangle: \Pi \rightarrow \Pi^{\prime}$ in $S I G_{F}$, the $\tau$-reduct of a $\Pi^{\prime}$-structure $\mathcal{A}^{\prime}$ is defined as the $\Pi$-structure $\left.\mathcal{A}^{\prime}\right|_{\tau}$ such that $\left(\left.\mathcal{A}^{\prime}\right|_{\tau}\right)_{\Sigma}=\left.\left(\mathcal{A}_{\Sigma}^{\prime}\right)\right|_{\sigma}$ and $r_{\left.\mathcal{A}^{\prime}\right|_{\tau}}=f(r)_{\mathcal{A}^{\prime}}$. Moreover, the $\tau$-reduct of a $\Pi^{\prime}$-structure morphism $h^{\prime}$ is the II-structure morphism $\left.h^{\prime}\right|_{\tau}=\left.h^{\prime}\right|_{\sigma}$.

Hence $\|_{\tau}$ is a functor from $\operatorname{Str}\left(\Pi^{\prime}\right)$ to $\operatorname{Str}(\Pi)$ and $\operatorname{Str}: S I G_{F} \rightarrow C a t^{o p}$ is the functor mapping each object $\Pi$ in $S I G_{F}$ to the category of structures $\operatorname{Str}(\Pi)$ and each morphism $\tau$ in $S I G_{F}$ to the reduct functor $\left.\right|_{\tau}$.

The set of first order formulae over an object $\Pi=\langle\Sigma, Q\rangle$ in $S I G_{F}$ and an $S$-sorted set of variables $X$ is recursively defined as the smallest set $F o l(\Pi)$ such that:

1. for all $t 1, t 2 \in\left|T_{\Sigma}(X)\right|_{s}$ and $r \in Q_{s}, r(t 1, t 2)$ is in $\operatorname{Fol}(\Pi)$.
2. true and false are in $\operatorname{Fol}(\Pi)$.
3. $\neg F$ is in $\operatorname{Fol}(\Pi)$, provided $F \in \operatorname{Fol}(\Pi)$.
4. $F 1 \wedge F 2$ and $F 1 \vee F 2$ are in $F o l(\Pi)$, provided $F 1, F 2 \in F o l(\Pi 1)$.
5. $\forall x: s . F$ and $\exists x: s . F$ are in $F o l(\Pi)$, provided $F \in F o l(\Pi)$ and $x \in X_{s}$.

First order sentences over $\Pi$, $\operatorname{Fos}(\Pi)$, are those formulae in $\operatorname{Fol}(\Pi)$ without free variables, i.e. every variable in a sentence occurs in the scope of a quantifier which binds that variable.

Satisfaction between a first order $\Pi$-formulae and a $\Pi$-structure $\mathcal{A}$ w.r.t. a valuation $\nu: T_{\Sigma}(X) \rightarrow \mathcal{A}_{\Sigma}$ is defined as follows:

1. $\mathcal{A}, \nu \vDash r(t 1, t 2)$ iff $(\nu(t 1), \nu(t 2)) \in r_{\mathcal{A}}$.
2. $\mathcal{A}, \nu \vDash$ true and $\mathcal{A}, \nu \not \models$ false.
3. $\mathcal{A}, \nu \vDash F 1 \wedge F 2$ iff $\mathcal{A}, \nu \models F 1$ and $\mathcal{A}, \nu \vDash F 2$.
4. $\mathcal{A}, \nu \models F 1 \vee F 2$ iff $\mathcal{A}, \nu \models F 1$ or $\mathcal{A}, \nu \models F 2$.
5. $\mathcal{A}, \nu \vDash \neg F$ iff $\mathcal{A}, \nu \not \vDash F$.
6. $\mathcal{A}, \nu \vDash \forall x: s . F$ iff for all $v \in\left|\mathcal{A}_{\Sigma}\right|_{s}, \mathcal{A}, \nu_{(x, v)} \vDash F$.
7. $\mathcal{A}, \nu \models \exists x: s . F$ iff there exists a value $v \in\left|\mathcal{A}_{\Sigma}\right|_{s}, \mathcal{A}, \nu_{(x, v)} \models F$.
where $\nu_{(x, v)}: T_{\Sigma}(X) \rightarrow \mathcal{A}_{\Sigma}$ is the valuation which maps $x$ to $v$ and the rest of the variables $x^{\prime} \in X$ to $\nu\left(x^{\prime}\right)$.

Satisfaction between a first order $\Pi$-sentence $\varphi$ and a $\Pi$-structure $\mathcal{A}$ is defined as follows:

$$
\mathcal{A} \vDash \varphi \stackrel{\text { def }}{\Longleftrightarrow} \mathcal{A}, \nu_{i} \models \varphi
$$

where $\nu_{i}$ is the unique valuation $\nu_{i}: T_{\Sigma} \rightarrow \mathcal{A}_{\Sigma}$.
First order sentences can be translated along a morphism $\tau$ in $S I G_{F}$ grans lating the terms and variables involved in each sentence, analogously to the wa: that terms and variables in equations are translated along algebraic signature morphisms. These translations preserve satisfaction and therefore, $S I G_{F}$. Str. Fos and $\vDash$ form an institution.


We shall refer to this institution as the institution of first order logic, denoted FOL. Compared to the standard institution of multisorted first order logic (see [GB 84]), this is a simplified version restricting predicates to be binary and with arguments of the same sort.

First order logic with equality, FOLEQ, is another institution similar to FOL but with a distinguished infix predicate $=$, over each sort $s$ in all signatures. This predicate is called equality and it must be preserved by signature morphisms, $\tau\left(=_{s}\right)==_{\tau(s)}$. Moreover, every structure in FOLEQ must interpret the equality predicate as the identity relation.

If we restrict the predicates of a FOLEQ structure to only the distinguished equality predicate, structures and first order signatures are in a one-to-one correspondence with algebras and algebraic signatures respectively. In the following, we shall use the term ALG for the institution whose signatures are algebraic signatures, models are algebras, sentences are first order sentences using a single binary predicate $=$ over each sort and satisfaction is as in FOLEQ, i.e. $=$ must be interpreted as identity on each sort. In fact, taking ALG and limiting the logical connectives used in first order sentences we can get institutions such as conditional equational logic or equational logic.

Most examples, unless limitation to EQ is necessary, are given in ALG and the derived syntax defined in section 2.4 for $A S L(\mathbf{E Q})$ is used for $A S L$ (ALG). Occasionally, some examples in sections 5.4.2 and 6.4.3 use FOL.

### 2.6 Entailment in $A S L$

$A S L$, like any other specification language, needs a notion of implementation or refinement by means of which we can state that one specification refines/implements another specification. This question has been deeply studied in [ST 88b].

Here, we choose a notation closer to logic and say that $S P 2$ entails $S P 1$, written $S P 2 \vDash S P 1$, if $\operatorname{Sig}[S P 2]=\operatorname{Sig}[S P 1]$ and $\operatorname{Mod}[S P 2] \subseteq \operatorname{Mod}[S P 1]$. Íncluding constructors and abstraction in our specification language allows complex relations of implementation such as the constructor and abstractor implementations described in [ST 88b] to be viewed as entailments. For example, $S P 2 \vDash S P 1$ iff $S P 1 \leadsto S P 2$ in the notation of [ST 88a].

This thesis is mostly dedicated to finding an inference system for entailment. Since this task depends critically on the complexity of the structure of the antecedent $S P 2$ and the consequent $S P 1$, we shall increase their complexities step by step. For example:

- $A S L \models A S L$ refers to entailments where the antecedent and the consequent are written using the six basic SBO's. This corresponds to so-called refinements in [ST 88b] and implementations in [SW 83].
- $k+A S L \models A S L$ refers to entailments where the antecedent can make use of the SBO's in $A S L$ plus the constructors (generic constructors $\langle P, \Lambda\rangle$ related to a programming language and/or $F Q R D$ constructors in $A S L(\mathrm{EQ})$ ), whereas the consequent can only use the six basic SBO's. This case includes constructor implementations as in [ST 88b].
- $k+A S L \vDash \alpha+A S L$ refers to entailments as in the previous case but allowing the consequent to include abstraction. This case includes abstractor implementations as in [ST 88b].
- $A S L \models A$ refers to entailments where the consequent is a set of sentences (a specification using only $A_{\Phi}$ and $\epsilon_{\Sigma}$ as specification building operations). This refers to theorem proving in $A S L$; in particular $S P \vDash \varphi$ is a special case where the consequent is $A_{\{\varphi\}} \epsilon_{\Sigma}$ for a certain signature $\Sigma$.
- $D A T U \vDash A T U$ refers to entailments whose antecedent uses $D_{\sigma}, A_{\Phi}, T_{\sigma}, U$ and $\epsilon_{\Sigma}$ whereas the consequent can only use $A_{\Phi}, T_{\sigma} U$ and $\epsilon_{\Sigma}$.

At the end of the thesis there is an index referring to the different entailments considered and where they are treated. In general, this thesis progresses from the easy to the difficult cases.

## Chapter 3

## Theorem proving

### 3.1 Introduction

Proving theorems in the context of specifications can have two purposes. In the first place, proving that all models of a specification satisfy a certain property helps us to understand what the specification means. This is especially useful in specification design when we want to check that our specifications mean what we expect. Consider for example a specification of sets in terms of emptyset, singleton and union, as in figure 3-1. Taking the finitely generated sets (Fin_Set) we obtain a specification of finite sets; however, this might not be clear to the user.

Alternatively, sets can be specified in terms of $\emptyset$ and insert as if they were lists with two extra axioms identifying those lists which differ in the order of the elements or the number of occurrences of an element (commutativity and idempotence of insertion). We may wonder if in the specification Fin_Set, given above, an operation insert defined as

```
\foralle:elem; S:set. insert(e, S)={e}\cupS
```

satisfies properties such as commutativity and idempotence. If this is the case we would feel more confident about our specification Fin_Set.

```Chapter 3. Theorem proving
```

```
Set = sorts elem, set
```

Set = sorts elem, set
operations
operations
0: set
0: set
U_: set, set -> set
U_: set, set -> set
{-}: elem -> set
{-}: elem -> set
axioms
axioms
S:set. S U \emptyset=s
S:set. S U \emptyset=s
S:set. S U S = S
S:set. S U S = S
V1, S2:set. S1 U S2 = S2 U S1
V1, S2:set. S1 U S2 = S2 U S1
\forall S1, S2, S3:set. (S1 U S2) U S3 = S1 U(S2 U S3)
\forall S1, S2, S3:set. (S1 U S2) U S3 = S1 U(S2 U S3)
end
end
Fin_Set = Reachable on {set} using {\emptyset, _U_, {-}} from {elem}

```
Fin_Set = Reachable on {set} using {\emptyset, _U_, {-}} from {elem}
```56
    Set

Figure 3-1: Sets of elements

In the second place, theorem proving plays an important role in proving entailments between specifications and, therefore, in proving correctness of implementations.

In order to prove a specification entailment correct it must be proven that all the properties required in the consequent are satisfied by the antecedent. These properties are not exclusively axioms, they may include reachability constraints and other kinds of requirements depending on the specification language considered. Nevertheless, axioms are going to be an important part of the requirements and therefore, a large amount of theorem proving is commonly involved in proofs of correctness of entailments.

Consider for example the specifications Set and Fin_Set and an implementation by lists. If we take Set, the specification (consequent) is just a collection of axioms and correctness can be proven by proving each axiom in Set to be a theorem of
the implementation (antecedent). If we impose a reachability constraint on Set, we obtain Fin_Set which cannot be reduced to a collection of axioms (not even an infinite one); however, any proof of correctness has to include a proof that the axioms in Set hold in the implementation independently of how the reachability constraint is verified.

Because of the double use of theorem proving, we are not only interested in how to prove theorems from specifications but also to which extent a specification (consequent) can be reduced to a collection of axioms, which could then be shown to be a consequence of another specification, the antecedent. This idea is usually formalized in terms of reduction rules which transform structured specifications into plain lists of axioms.

In this chapter, we are concerned with theorem proving for \(k+A S L\); in other words, we restrict the general problem \(S P 2 \vDash S P 1\) to the case where \(S P 2\) is a specification in the language \(k+A S L\) and the consequent \(S P 1\) is a set of axioms, i.e. has the form \(A_{\Phi} \epsilon_{\Sigma}\).

In the following sections inference rules for the different SBO's are given to allow us to infer theorems from specifications in \(k+A S L\). Some reduction rules will also be given; however, it is not necessary to give many of these explicitly since the definition of an exact inference rule (see 3.3.11 below) characterizes inference rules which can be used to transform structured specifications into equivalent collections of axioms.

\subsection*{3.2 Proving \(A T U \vDash A\)}

In this section we focus on antecedents in \(A T U . A T U\) is the simplest structured specification language since all specifications can be reduced to an equivalent collection of axioms, i.e. a specification of the form \(A_{\Phi} \epsilon_{\Sigma}\); in this sense it can be said that \(A T U\) is equivalent to \(A\).

The reduction can be easily done by repeatedly applying the following equivalences from left to right:
\(T_{\sigma} A_{\Phi} \epsilon_{\Sigma}=A_{\sigma(\Phi)} \epsilon_{\Sigma^{\prime}} \quad\) for \(\sigma: \Sigma \rightarrow \Sigma^{\prime} \quad T_{\sigma} \epsilon_{\Sigma}=\epsilon_{\Sigma^{\prime}} \quad\) for \(\sigma: \Sigma \rightarrow \Sigma^{\prime}\)
\(A_{\Phi 1} \epsilon_{\Sigma} U A_{\Phi 2} \epsilon_{\Sigma}=A_{\Phi 1 \cup \Phi 2} \epsilon_{\Sigma} \quad \epsilon_{\Sigma} U S P=S P\)
\(A_{\Phi 1} A_{\Phi 2} \epsilon_{\Sigma}=A_{\Phi 1 \cup \Phi 2} \epsilon_{\Sigma}\)
\(S P U \epsilon_{\Sigma}=S P\)

This fact has been presented in the literature under different names. These equivalences are considered as definitions of \(T\) and \(U\) in presentation semantics [EM 85] \({ }^{1}\) or in module algebra [BHK 86] but, in specification languages with model-oriented semantics such as \(A S L\), they take the form of equivalences. Specifications of the form \(A_{\Phi} \epsilon_{\Sigma}\) are called flat specification and the reduction from arbitrary structured specifications to flat specifications is called flattening.

The equivalence between \(A T U\) and \(A\) allows us to reduce theorem proving over \(A T U\) to theorem proving over \(A\), transferring the inference to the underlying logic since \(A_{\Phi 1} \epsilon_{\Sigma} \models A_{\Phi 2} \epsilon_{\Sigma}\) holds in \(A S L(\mathbf{I})\) if and only if \(\Phi 1 \models_{\Sigma} \Phi 2\) with the satisfaction relation \(\vDash\) of \(\mathbf{I}\). Hence, we can use the inference system \(\vdash^{\mathbf{I}}\) available for that institution.

\footnotetext{
\({ }^{1}\) Called first level semantics in [EM 85].
}

The structure provided by \(T\) and \(U\) can be removed before starting to prove theorems. However, the structure may be useful in guiding the theorem prover towards the premises needed in the proof of a theorem (see [SB 83] for details). For this reason, although we are glad to know that \(A T U\)-specifications can be reduced to \(A\)-specifications, we shall not always do that reduction in our proofs. We prefer to give an inference system strong enough to perform such reductions if the user wants but he can also ignore them if it is convenient.

This feature of \(T\) and \(U\) can be used for solving \(A T U \models A\) but also for solving \(A T U \vDash A T U\). This has no analogy in the other SBO's. Neither \(M_{\iota}, D_{\sigma}\) nor abstraction can be reduced (eliminated) in a language of presentations; that is why verifying specification entailments involving them is difficult, particularly if \(M_{\iota}\), \(D_{\sigma}\) or abstraction appear in the consequent (see chapters 6,4 and 5 respectively).

\subsection*{3.3 Proving \(A S L \models A\)}

In this section we are concerned with proving theorems from \(A S L\) specifications. Some research in [ST 88a] proved the following inference rules to be sound:
\[
\begin{array}{cc}
\frac{S P 1 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi} & \frac{S P 2 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi} \\
\frac{S P \vdash \varphi}{T_{\sigma} S P \vdash \sigma(\varphi)} & \frac{S P \vdash \sigma(\varphi)}{D_{\sigma} S P \vdash \varphi}
\end{array} \frac{S P \vdash \varphi}{M_{(\sigma,<)} S P \vdash \varphi}
\]

The main task of this section is to complete this list of rules and to provide a characterization of them in order to know how good they are and, in particular, if they give rise to reductions of specifications to presentations. First, we give some general definitions about how a theory relates to a class of models and, analogously, how an inference rule relates to a specification building operation.

\subsection*{3.3.1 Theories versus model classes}

In general, a set of sentences \(\Phi\) denotes the class of models satisfying \(\Phi\) but some classes of models cannot be represented by a set of sentences and, in particular, this turns out to be the case for the model classes of some specifications in \(A S L(\mathbf{E Q})\). In this section we study the possible relations between a class of \(\Sigma\)-models \(\Gamma\) and a theory \(\Delta\) over \(\Sigma\) which tries to capture the properties of \(\Gamma\) in an institution \(\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle\).

Definition 3.3.1 Given a class of \(\Sigma\)-models \(\Gamma\), we define \(T h[\Gamma]\) as
\[
T h[\Gamma]=\left\{\varphi \in \operatorname{Sen}(\Sigma) \mid \Gamma \models_{\Sigma} \varphi\right\}
\]

Given a set of \(\Sigma\)-sentences \(\Phi\), we define \(\operatorname{Mod}[\Phi]\) as
\[
\operatorname{Mod}[\Phi]=\left\{M \in|\operatorname{Mod}(\Sigma)| \mid M \models_{\Sigma} \Phi\right\}
\]

Then, the closure of a set of \(\Sigma\)-sentences \(\Phi\) under semantic entailment is the set of \(\Sigma\)-sentences \(C l(\Phi)=T h[\operatorname{Mod}[\Phi]]\).
\(A\) theory \(\Delta\) over \(\Sigma\) is a set of \(\Sigma\)-sentences closed under semantic entailment; i.e. \(C l(\Delta)=\Delta\).

Corollary 3.3.2 For every two theories \(\Delta_{1}\) and \(\Delta_{2}\), satisfaction between theories, \(\Delta_{1} \models_{\Sigma} \Delta_{2}\), is equivalent to theory inclusion, \(\Delta_{1} \supseteq \Delta_{2}\).

The operators \(T h\) and Mod on classes of models and sets of sentences form a Galois connection [BG S0].

In the following we define some relations between a class of models and a theory which tries to capture its properties.

Definition 3.3.3 Given a class of \(\Sigma\)-models \(\Gamma\) and a theory \(\Delta\) over \(\Sigma\),
\(\Delta\) is sound w.r.t. \(\Gamma\) if \(\Delta \subseteq T h[\Gamma]\).
\(\Delta\) is complete w.r.t. \(\Gamma\) if \(\Delta \supseteq T h[\Gamma]\).
\(\Delta\) is M -sound w.r.t. \(\Gamma\) if \(\operatorname{Mod}[\Delta] \supseteq \Gamma\).
\(\Delta\) is M -complete w.r.t. \(\Gamma\) if \(\operatorname{Mod}[\Delta] \subseteq \Gamma\).
When the inclusions are proper we use the terms strictly sound, strictly complete, and so on.
\(\Delta\) is exact w.r.t. \(\Gamma\) if \(\operatorname{Mod}[\Delta]=\Gamma\).

Definition 3.3.4 Given a specification \(S P\) and a theory \(\Delta\) over \(\operatorname{Sig}[S P], \Delta\) is sound (complete, M-sound, M-complete or exact) w.r.t. to \(S P\) if \(\Delta\) is sound (complete, M-sound, M-complete or exact) w.r.t. Mod[SP].

These definitions are related by the following propositions.

Proposition 3.3.5 \(\Delta\) is sound w.r.t. \(\Gamma\) iff \(\Delta\) is \(M\)-sound w.r.t. \(\Gamma\).

Proposition 3.3.6 If \(\Delta\) is \(M\)-complete w.r.t. \(\Gamma\) then \(\Delta\) is complete w.r.t. \(\Gamma\).

Corollary 3.3.7 If \(\Delta\) is exact w.r.t. \(\Gamma\) then \(\Delta\) is sound and complete w.r.t. \(\Gamma\).

These follow from standard properties of Galois connections and from the definition of theory. For example:

Proof of Proposition 3.3.5 If \(\Delta\) is sound w.r.t. \(\Gamma\) then \(\Delta \subseteq T h[\Gamma]\). Applying \(\operatorname{Mod}\) on both sides gives \(\operatorname{Mod}[\Delta] \supseteq \operatorname{Mod}[\operatorname{Th}[\Gamma]]\), and recalling that \(\operatorname{Mod}[\operatorname{Th}[\Gamma]] \supseteq \Gamma\) we get \(\operatorname{Mod}[\Delta] \supseteq \Gamma\) which is the definition of \(M\)-sound.

If \(\Delta\) is M -sound w.r.t. \(\Gamma\) then \(\operatorname{Mod}[\Delta] \supseteq \Gamma\). Applying \(T h\) on both sides, and recalling that \(\Delta \subseteq T h[\operatorname{Mod}[\Delta]]\) we get \(\Delta \subseteq T h[\Gamma]\) which is the definition of sound.

Note that proposition 3.3 .5 is a consequence of the Galois connection since \(\Gamma \subseteq \operatorname{Mod}[T h[\Gamma]]\) and \(\Phi \subseteq T h[\operatorname{Mod}[\Phi]]\) for arbitrary classes of models \(\Gamma\) and sets of sentences \(\Phi\). The inclusion in the opposite direction does not always hold, i.e. there are generally more models in the closure \(\operatorname{Mod}[T h[\Gamma]]\) than in \(\Gamma\). However, since theories are already closed under entailment \(\operatorname{Th}[\operatorname{Mod}[\Delta]] \subseteq \Delta\) holds, hence proposition 3.3.6.

As a result of the difference between complete and \(M\)-complete we find that a theory \(\Delta\) can relate to a class of models \(\Gamma\) in six different possible ways: \(\Delta\) can be exact; sound and complete but not exact; sound but not complete; M-complete but not sound; complete but neither M -complete nor sound; or not related to \(\Gamma\). But not all these cases can occur for the same class of models.

Definition 3.3.8 A class of models \(\Gamma\) is axiomatizable if \(\Gamma=\operatorname{Mod}[T h[\Gamma]]\).

Proposition 3.3.9 A class of models \(\Gamma\) is axiomatizable iff every complete theory w.r.t. \(\Gamma\) is also \(M\)-complete w.r.t. \(\Gamma\).

Proof Assume every theory \(\Delta\) complete w.r.t. \(\Gamma\) is also \(M\)-complete w.r.t. \(\Gamma\). Take \(\Delta\) to be \(T h[\Gamma]\). Trivially, \(T h[\Gamma] \subseteq T h[\Gamma]\), hence \(T h[\Gamma]\) is complete w.r.t. \(\Gamma\). By the assumption, \(T h[\Gamma]\) must also be \(M\)-complete w.r.t. \(\Gamma\), i.e. \(\operatorname{Mod}[T h[\Gamma]] \subseteq \Gamma\). Finally, since by definition of \(T h\) and \(M o d\) it holds that \(\Gamma \subseteq \operatorname{Mod}[T h[\Gamma]]\) we conclude that \(\operatorname{Mod}[T h[\Gamma]]=\Gamma\).

In the other direction, suppose \(\Gamma\) is axiomatizable. If \(\Delta\) is a complete theory w.r.t. \(\Gamma\) then \(\Delta \supseteq T h[\Gamma]\). Applying \(\operatorname{Mod}\) on both sides, \(\operatorname{Mod}[\Delta] \subseteq \operatorname{Mod}[T h!\Gamma]]=\Gamma\). hence \(\Delta\) is also M -complete w.r.t. \(\Gamma\).

Now we can classify theories again. For an axiomatizable class of models a theory can be exact, sound (and M-sound) but not complete, complete (and Mcomplete) but not sound, or not related.

On the other hand, if a class of models is not axiomatizable all the relations are possible except the exact one.

\subsection*{3.3.2 Inference rules versus SBO's}

Inference rules are rules which allow us to infer a theory from another theory.

\section*{\(+\)}

Definition 3.3.10 \(A n\) inference rule \(\Lambda\) from \(\Sigma_{1}\) to \(\Sigma_{2}\) is a binary relation between sets of \(\Sigma_{1}\)-sentences and \(\Sigma_{2}\)-sentences.

The theory \(\Delta_{\text {inf }}\) inferred from a theory \(\Delta\) using \(\Lambda\) is \(\Delta_{\text {inf }}=\operatorname{Cl}\left(\left\{\varphi \mid \exists \Phi_{1} \subseteq\right.\right.\) \(\left.\left.\Delta .\left(\Phi_{1}, \varphi\right) \in \Lambda\right\}\right)\).

Rules such as
\[
\frac{S P \vdash \varphi}{T_{\sigma} S P \vdash \sigma(\varphi)}
\]
used in [ST 88a] have an immediate interpretation as inference rules in this sense:
\[
\Lambda=\{(\{\varphi\}, \sigma(\varphi)) \mid \varphi \text { is a } \operatorname{Sig}[S P] \text {-sentence }\}
\]

Similarly, expressions such as \(\xi S P \vdash \varphi\) (provided \(P(\xi, \varphi)\) ) denote inference rules. In this case, the inferred sentences \(\varphi\) are independent of the specification to which \(\xi\) is applied. The inference rule denoted by such an expression is
\[
\Lambda=\{(\emptyset, \varphi) \mid P(\xi, \varphi)\}
\]

For example, \(A_{\Phi} S P \vdash \varphi(\) if \(\varphi \in \Phi)\) denotes an inference rule whose inferred theory is the closure of \(\Phi\).

Note that inference rules infer theories, therefore, we do not consider the actual sentences that a rule can deliver but only their closure. If we say that a rule
\[
\frac{S P \vdash f(\varphi)}{\xi S P \vdash g(\varphi)}
\] sole aspect of an inference rule which is of interest in the lowing results.
is complete, this means, in practice, that it is complete when it is used together with rules such as
\[
\frac{S P \vdash \varphi 1 \quad S P \vdash \varphi 2}{S P \vdash \varphi}\left(\varphi 1, \varphi 2 \vdash \vdash^{\mathbf{I}} \varphi\right)
\]
for a sound and complete inference system \(\vdash^{I}\).
Now, we can extend the definitions given for theories w.r.t. specifications to definitions for inference rules w.r.t. SBO's:

Definition 3.3.11 Given a unary \(S B O \xi\) we say that:
An inference rule \(\Lambda\) is sound w.r.t. \(\xi\), if whenever it is applied to a theory \(\Delta\) which is sound w.r.t. a specification \(S P\) (i.e. w.r.t. \(M o d[S P]\) ), it yields a sound theory w.r.t. \(\xi S P\) (i.e. w.r.t. \(\operatorname{Mod}[\xi S P]\) ).

An inference rule \(\Lambda\) is M -complete w.r.t. \(\xi\), if whenever it is applied to a theory \(\Delta\) which is \(M\)-complete w.r.t. a specification \(S P\), it yields an \(M\)-complete theory w.r.t. \(\xi S P\).

An inference rule \(\Lambda\) is complete w.r.t. \(\xi\), if whenever it is applied to a theory \(\Delta\) which is complete w.r.t. a specification \(S P\), it yields a complete theory w.r.t. \(\xi S P\).

An inference rule \(\Lambda\) is exact w.r.t. \(\xi\), if whenever it is applied to a theory \(\Delta\) which is exact w.r.t. a specification \(S P\), it yields an exact theory w.r.t. \(\xi S P\) (equivalently, \(\Lambda\) is exact w.r.t. \(\xi\) if \(\Lambda\) is sound and \(M\)-complete w.r.t. \(\xi\) ).

For binary or n-ary SBO's we can easily extend the definitions of inference rule and inferred theory in order to infer a theory from several theories. Then, the definition of soundness ( M -completeness, completeness or exactness) of the inference rule requires sound (M-complete, complete or exact) theories for each of the arguments.

With reference to the presentation of an inference rule, it is worth noticing that the union of inference rules between the same signatures is also an inference rule. Therefore, we can also characterize collections of inference rules as sound, complete, M-complete or exact, meaning that the union of them is sound, complete, M-complete or exact.

The inference rules given in [ST 88a] for \(U, T_{\sigma}, D_{\sigma}\) and \(M_{(\sigma, \iota)}\), plus some others for \(A_{\Phi}\) can be characterized as follows:

\section*{Theorem 3.3.12}
\(\frac{S P 1 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi} \quad \frac{S P 2 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi}\)
Sound and M-complete (exact).
\(\frac{S P \vdash \varphi}{T_{\sigma} S P \vdash \sigma(\varphi)}\)
Sound and M-complete (exact).
\(\frac{S P \vdash \sigma(\varphi)}{D_{\sigma} S P \vdash \varphi}\)
Sound and complete.
\(\frac{S P \vdash \varphi}{M_{\langle\sigma, \iota\rangle} S P \vdash \varphi}\)
Sound.
\(\frac{S P \vdash \varphi}{A_{\Phi} S P \vdash \varphi} \quad A_{\Phi} S P \vdash \varphi \quad(\) if \(\varphi \in \Phi) \quad\) Sound and \(M\)-complete (exact).

\section*{Proof}
- \(\frac{S P 1 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi} \quad \frac{S P 2 \vdash \varphi}{S P 1 U S P 2 \vdash \varphi}\) is a sound and M-complete inference rule w.r.t. \(U\).

Let \(\Delta 1\) and \(\Delta 2\) be M-complete theories w.r.t. \(S P 1\) and \(S P 2\), i.e. \(\operatorname{Mod}[\Delta i] \subseteq\) \(\operatorname{Mod}[S P i]\) for \(i \in\{1,2\}\). The inferred theory is \(\Delta_{i n f}=C l(\Delta 1 \cup \Delta 2)\). Then, by monotonicity of the intersection, \(\operatorname{Mod}[\Delta 1] \cap \operatorname{Mod}[\Delta 2] \subseteq \operatorname{Mod}[S P 1] \cap\) \(\operatorname{Mod}[S P 2]=\operatorname{Mod}[S P 1 \quad U S P 2]\), and by the definition of the models of a theory
\[
\operatorname{Mod}[\Delta 1] \cap \operatorname{Mod}[\Delta 2]=\operatorname{Mod}[\Delta 1 \cup \Delta 2]=\operatorname{Mod}[C l(\Delta 1 \cup \Delta 2)]
\]

We conclude that \(\Delta_{\text {inf }}\) is an M-complete theory for \(S P 1 U S P 2\).
Analogously, and considering the inclusion in the opposite way the inference rule can be proved M -sound and therefore sound.
- \(\frac{S P \vdash \varphi}{T_{\sigma} S P \vdash \sigma(\varphi)} \quad\) is a sound and M-complete inference rule w.r.t. \(T_{\sigma}\).

Given an M-complete theory \(\Delta\) for \(S P\), the inferred theory has models \(\operatorname{Mod}\left[\Delta_{\text {inf }}\right]=\{A \in|\operatorname{Mod}(\uparrow \sigma)| \mid A \vDash \operatorname{Cl}(\sigma(\Delta))\}\) or, equivalently, \(\{A \in\) \(|\operatorname{Mod}(\uparrow \sigma)| \mid A \vDash \sigma(\Delta)\}\) which by the satisfaction condition is
\[
\left\{A \in|\operatorname{Mod}(\uparrow \sigma)||A|_{\sigma} \vDash \Delta\right\}
\]

Finally, by definition of the models of a theory, the same class of models can be expressed as \(\left\{A \in|\operatorname{Mod}(\uparrow \sigma)||A|_{\sigma} \in \operatorname{Mod}[\Delta]\right\}\) which, by M-completeness of \(\Delta\), is included in \(\left\{A \in|\operatorname{Mod}(\uparrow \sigma)||A|_{\sigma} \in \operatorname{Mod}[S P]\right\}=\operatorname{Mod}\left[T_{\sigma} S P\right]\). We conclude that \(\Delta_{i n f}\) is an M-complete theory for \(T_{\sigma} S P\).

Analogously, and considering the inclusion in the opposite way the inference rule can be proved M -sound and therefore sound.
- \(\quad \frac{S P \vdash \sigma(\varphi)}{D_{\sigma} S P \vdash \varphi} \quad\) is a sound and complete inference rule w.r.t. \(D_{\sigma}\).

Let be \(\Delta\) a sound theory w.r.t. \(S P\). The inferred theory is \(\Delta_{i n f}=C l\left(\sigma^{-1} \Delta\right)\) where \(\sigma^{-1} \Delta=\left\{\varphi_{1} \in \operatorname{Sen}(\downarrow \sigma) \mid \sigma\left(\varphi_{1}\right) \in \Delta\right\}\). Then,
\[
\begin{aligned}
\operatorname{Mod}[S P] & \subseteq \operatorname{Mod}[\Delta] & & \text { since } \Delta \text { is sound w.r.t. } S P \\
& \subseteq \operatorname{Mod}\left[\sigma\left(\sigma^{-1} \Delta\right)\right] & & \text { by definition of } \sigma^{-1} \Delta \\
& =\left\{A \in|\operatorname{Mod}(\uparrow \sigma)| \mid A \models \sigma\left(\sigma^{-1} \Delta\right)\right\} & & \\
& =\left\{A \in|\operatorname{Mod}(\uparrow \sigma)||A|_{\sigma} \models \sigma^{-1} \Delta\right\} & & \text { by the satisfaction condition }
\end{aligned}
\]

Applying the \(\sigma\)-reduct functor to both sides
\[
\begin{aligned}
\operatorname{Mod}\left[D_{\sigma} S P\right] & \subseteq\left\{\left.A\right|_{\sigma}|A \in| \operatorname{Mod}(\uparrow \sigma) \mid \text { and }\left.A\right|_{\sigma} \vDash \sigma^{-1} \Delta\right\} \\
& \subseteq\left\{A \in|\operatorname{Mod}(\downarrow \sigma)| \mid A \models \sigma^{-1} \Delta\right\} \\
& =\operatorname{Mod}\left[\sigma^{-1} \Delta\right] \\
& =\operatorname{Mod}\left[\Delta_{\text {inf }}\right]
\end{aligned}
\]
therefore the rule is sound.

On the other hand, let \(\Delta\) be a complete theory w.r.t. \(S P, T h[\operatorname{Mod}[S P]] \subseteq\) \(\Delta\), and consider an arbitrary sentence \(\varphi \in T h\left[\operatorname{Mod}\left[D_{\sigma} S P\right]\right]\). By definition of \(T h\), every model of \(D_{\sigma} S P\) satisfies \(\varphi\). Hence, for all \(M \in \operatorname{Mod}[S P]\), \(\left.M\right|_{\sigma} \vDash \varphi\). Applying the satisfaction condition, \(M \models \sigma(\varphi)\). Since \(M\) is an arbitrary model of \(S P\), we can generalize to \(\operatorname{Mod}[S P] \vDash \sigma(\varphi)\). Hence, \(\sigma(\varphi) \in \operatorname{Th}[\operatorname{Mod}[S P]] \subseteq \Delta\) and by definition of \(\Delta_{\text {inf }}, \varphi \in \Delta_{\text {inf }}\). Generalizing again, we obtain that \(T h\left[\operatorname{Mod}\left[D_{\sigma} S P\right]\right] \subseteq \Delta_{\text {inf }}\) as desired.
- \(\frac{S P \vdash \varphi}{M_{\langle\sigma,\rangle} S P \vdash \varphi} \quad\) is a sound inference rule w.r.t. \(M_{\langle\sigma,\rangle\rangle}\).

For all sound theories \(\Delta\) for \(S P\), since \(M\) is a selector, \(\operatorname{Mod}\left[M_{(\sigma, \gamma\rangle} S P\right] \subseteq\) \(\operatorname{Mod}[S P] \subseteq \operatorname{Mod}[\Delta]=\operatorname{Mod}\left[\Delta_{i n f}\right]\).
- \(\frac{S P \vdash \varphi}{A_{\Phi} S P \vdash \varphi} \quad A_{\Phi} S P \vdash \varphi(\) if \(\varphi \in \Phi) \quad\) is a sound and M-complete inference rule w.r.t. \(A_{\Phi}\).

For every M-complete \(\Delta\) for \(S P\), the inferred theory \(\Delta_{\text {inf }}=C l(\Delta \cup \Phi)\) has models \(\operatorname{Mod}\left[\Delta_{i n f}\right]=\{A \in \operatorname{Mod}[\Delta] \mid A \vDash \Phi\}\). Considering the definition of \(A_{\Phi}\) and the M -completeness of \(\Delta\) it follows that \(\operatorname{Mod}\left[\Delta_{\text {inf }}\right] \subseteq\{A \in\) \(\operatorname{Mod}[S P] \mid A \models \Phi\}=\operatorname{Mod}\left[A_{\Phi} S P\right]\).

Analogously, and considering the inclusion in the opposite way the inference rule can be proved M -sound and therefore sound.

Technically, our version of \(A S L\) differs from [ST 88a] in the definition of \(A_{\Phi}\) as a SBO instead of using basic specifications. For this reason, we need an extra rule of inference for \(\epsilon_{\Sigma}\). In this case, since \(\epsilon_{\Sigma}\) is a nullary SBO, we can directly present a theory instead of an inference rule.

\section*{Proposition 3.3.13 The set of tautologies over \(\Sigma\) is an exact theory w.r.t. \(\epsilon_{\Sigma}\).}

Proof Trivial since all models satisfy tautologies.

The most interesting aspect of this characterization is that the completeness of the inference rule for \(D_{\sigma}\) does not entail M-completeness. This can be shown by an example from [BHK 86] which may be translated into \(A S L\) over the institution ALG as in figure 3-2.

The models of NStNat are the non-standard models of the natural numbers. It is well-known that there exist non-standard models of the natural numbers elementarily equivalent to the standard model, therefore the class of models denoted by NStNat is not axiomatizable in first order logic.

Summing up, we have a specification \(S P\) with an exact theory ( \(S P\) is the specification NStNat before hiding reach and inf), and a non-axiomatizable specification of the form \(D_{\sigma} S P\), the specification NStNat. In this situation, no exact rule for \(D_{\sigma}\) can exist since such a rule should infer an exact theory for \(D_{\sigma} S P\) from an exact theory for \(S P\).
```

NStNat = sorts nat
hiddensorts
operations
0: nat
suc: nat -> nat
hidden_operations
reach: nat -> nat
inf: nat
axioms
X: nat. 0; suc(x)
\forallx,y:nat. (\operatorname{suc}(x)=suc(y)) => (x=y)
reach(0)=0
\forallx:nat. (reach}(x)=0)=>(reach(\operatorname{suc}(x))=0
reach(inf)=suc(0)
end

```

Figure 3-2: Non-standard natural numbers

In specification languages with (first order) theory-based semantics such as LARCH, the models of a specification analogous to NStNat include the standard model of the natural numbers against all intuition.

Looking at the inference rules given above, we may feel disappointed by the rule for \(M_{(\sigma, c)}\). The relation of \(M_{(\sigma, c)}\) to term generated models and therefore to induction seems clear, but no rule takes advantage of that. In fact, an induction rule cannot be treated at the same level as the other rules because it is not institution independent.

Induction, in contrast to the rules given above, assumes the existence of terms and therefore of sorts and algebraic-like signatures. Moreover, by its institution independent definition, \(M_{\langle\sigma, \gamma\rangle}\) only happens to impose finite term generation insofar as the morphisms in each category, \(\operatorname{Mod}(\Sigma)\), of models over a signature \(\Sigma\) are functions over the carriers of each sort. That means that our assumptions are not only on the nature of the signatures and the models but also on the morphisms between the models. Consider for example, a category of models over \(\Sigma\) whose objects are algebras, \(|A l g(\Sigma)|\), but whose morphisms are not homomorphisms but an ordering according to the cardinality of the carriers. Then, \(M_{(\sigma, \gamma)}\) does not have anything to do with term generated models or induction.

Nevertheless, we are especially interested in those cases where \(M_{(\sigma,\rangle)}\) is related to induction. In the following we give the obvious rule for \(M_{\langle\sigma,\rangle\rangle}\) in an institution such as FOLEQ.

\section*{Induction rule}

As mentioned in the preliminaries, most constraints \(M_{\langle\sigma,\rangle}\) are of the form \(M_{\langle G, F, S\rangle}\) when they refer to an institution where constraints are interpreted as reachability constraints.

Proving inductive consequences has been extensively treated in the literature. We shall only give a brief account of the results.

A second order induction axiom can fully express the effect of a reachability constraint on one sort; e.g. in the case of arithmetic \(M_{\{\{n a t\},\{0, s u c\}, \varnothing\rangle}\) amounts to
\[
\forall P .(P(0) \wedge \forall x .(P(x) \Rightarrow P(\operatorname{suc}(x)))) \Rightarrow(\forall x . P(x))
\]

However, if the second order axiom is replaced by a first order schema \((A(0) \wedge \forall x .(A(x) \Rightarrow A(\operatorname{suc}(x)))) \Rightarrow \forall x . A(x)\) for all first order formulae \(A\) restricting \(A\) to be a predicate expressible in first order logic, completeness is lost by Gödel's incompleteness theorem.

This induction schema is an example of structural induction where the generated terms are ordered by the relation between a term and its immediate subterms. The idea of translating a reachability constraint into a structural induction schema does not rule out using other induction schemes such as complete induction:
\[
\forall x .(\forall z .(z<x \Rightarrow A(z)) \Rightarrow A(x)) \Rightarrow \forall x . A(x) \text { for all first order formulae } A
\]
which can be derived from the schema of structural induction (see [Men 71] page 126).

In general, structural induction is extensively used in computer science [Bur 69, BM 79, GG 88] but it is not always so simple as in the case of arithmetic since we must deal with multisorted structures with possibly mutually recursive generators. Frequently induction must be nested or simultaneously done on several sorts and often auxiliary predicates for the sorts of the parameters must be guessed by heuristics (see [BM 79] for details).

Consider for example a specification \(S P\) with sorts \(\{s 1, s 2, s 3, s 4\}\) where the latter two are constrained by \(M_{\langle G, F, S\rangle}\) with
\[
\begin{aligned}
G=\{s 3, s 4\} \quad F= & \{f 1: s 1 \rightarrow s 3, \\
& f 2: s 2, s 3 \rightarrow s 4 \\
& f 3: s 3, s 4 \rightarrow s 4\}
\end{aligned}
\]

In this case we can simultaneously prove predicates \(Q_{s 3}\) and \(Q_{s 4}\) by induction as follows:
\[
\begin{aligned}
& S P \vdash \forall x: s 1 . Q_{s 3}(f 1(x)) \\
& S P \vdash \forall x: s 2 ; y: s 3 . Q_{s 3}(y) \Rightarrow Q_{s 4}(f 2(x, y)) \\
& \frac{S P \vdash \forall y 3: s 3 ; y 4: s 4 .\left(Q_{s 3}(y 3) \wedge Q_{s 4}(y 4)\right) \Rightarrow Q_{s 4}(f 3(y 3, y 4))}{M_{(G, F, S)} S P \vdash\left(\forall y: s 3 . Q_{s 3}(y)\right) \wedge\left(\forall y: s 4 . Q_{s 4}(y)\right)}
\end{aligned}
\]

After these considerations a general structural induction rule for \(M_{(G, F, S)}\) can be defined as follows.

Proposition 3.3.14 Given a specification SP over a set of sorts including disjoint sets \(S\) (basic sorts) and \(G\) (generated sorts), the rule
\[
\frac{S P \vdash \wedge_{s \in G} \wedge_{o p \in F,} \forall \bar{x}: S, \bar{y}: G .\left(\bar{Q}(\bar{y}) \Rightarrow Q_{s}(o p(\overline{x y}))\right)}{M_{\langle G, F, S\rangle} S P \vdash \wedge_{s \in G} \forall y: s . Q_{s}(y)}
\]
is sound where \(Q\) is a \(G\)-indexed set of predicates, \(\bar{x}\) a \(S\)-sorted sequence of variables, \(\bar{y}\) a \(G\)-sorted sequence of variables, \(\overline{x y}\) is the concatenation of \(\bar{x}\) and \(\bar{y}, F_{s}\) those operations in \(F\) delivering a value of sort \(s\), and \(\bar{Q}\) the conjunction of the appropriate predicates in \(Q\) applied to a given \(G\)-sorted sequence of variables.

Proof We shall simultaneously prove that
\[
\forall y: s . Q_{s}(y)
\]
holds for the models of \(M_{(G, F, S)} S P\) for all \(s \in G\) assuming that the premises of the rule hold for the models of \(S P\).

Since \(s\) is a generated sort, by definition of \(M_{(G, F, S)}\) in EQ, every value \(a\) of sort \(s\) in \(G\) must be the value of a term \(t_{a} \in\left|T_{(G U S, F)}(\bar{x})\right|\) for an \(S\)-sorted set of
variables \(\bar{x}\). Since \(t_{a}\) uses only the function symbols in \(F\), we can substitute the conclusion \(\forall y: s . Q_{s}(y)\) by the schema \(\forall \bar{x}: S . Q_{s}(t(\bar{x}))\) for an arbitrary term \(t\) of sort \(s\) using only the function symbols in \(F\).

Assuming that all the premises in the rule hold, we start structural induction on \(t(\bar{x})\) :
- Let the term \(t(\bar{x})\) be a constant \(c\) of sort \(s\). Then, \(Q_{s}(c)\) holds since it is among the premises of the form \(\left(\bar{Q}(\bar{y}) \Rightarrow Q_{s}(o p(\overline{x y}))\right)\) for empty \(\overline{x_{s}}\) and \(\bar{y}\).
- Let \(t(\bar{x})\) be a term \(o p\left(\overline{x_{0}}, t_{1}\left(\overline{x_{1} y_{1}}\right), \ldots, t_{n}\left(\overline{x_{n} y_{n}}\right)\right)\), with subterms \(t_{1}, \ldots, t_{n}\) of sorts \(s_{1}, \ldots, s_{n}\) in \(G, S\)-sorted sequences of variables \(\overline{x_{0}}, \ldots, \overline{x_{n}}\) and \(G\)-sorted sequences of variables \(\overline{y_{1}}, \ldots, \overline{y_{n}}\), and \(o p \in F\). By induction hypothesis, predicates \(Q\) hold for the respective subterms, i.e.
\[
\forall \overline{x_{0}}, \overline{x_{1}}, \ldots, \overline{x_{n}}: S . \overline{y_{1}}, \ldots, \overline{y_{n}}: G . Q_{s_{1}}\left(t_{1}\left(\overline{x_{1} y_{1}}\right)\right) \wedge \ldots \wedge Q_{s_{n}}\left(t_{n}\left(\overline{x_{n} y_{n}}\right)\right)
\]

Moreover, considering the premise
\[
\forall \overline{x_{0}}: S . y_{1}: s_{1} . \ldots y_{n}: s_{n} .\left(Q_{s_{1}}\left(y_{1}\right) \wedge \ldots \wedge Q_{s_{n}}\left(y_{n}\right)\right) \Rightarrow Q_{s}\left(o p\left(\overline{x_{0}}, y_{1}, \ldots, y_{n}\right)\right)
\]
in the rule, we conclude that
\[
\forall \overline{x_{0}}, \overline{x_{1}}, \ldots, \overline{x_{n}}: S . \overline{y_{1}}, \ldots, \overline{y_{n}}: G . Q_{s}\left(o p\left(\overline{x_{0}}, t_{1}\left(\overline{x_{1} y_{1}}\right), \ldots, t_{n}\left(\overline{x_{n} y_{n}}\right)\right)\right)
\]

Finally, since \(Q_{s}(t(\bar{x}))\) holds for all terms \(t\) using function symbols in \(F\) and variables in \(S\), we conclude that
\[
M_{\langle G, F, S\rangle} S P \models \forall y: s . Q_{s}(y)
\]

This rule looks very demanding since properties for generated sorts can only be proven simultaneously with a property for each generated sort. In practice,
if we are interested in proving \(\forall x: s . P(x)\), a complete family \(Q\) with \(Q_{s}=P\) can be chosen. In the example above, properties for \(s 3\) can be proven by taking \(Q_{s 4}=t r u e\) since no value of \(s 3\) can be generated from the values of \(s 4\). However. in general other \(Q_{s^{\prime}}\) may be needed and theorem provers must undertake some synthesis of auxiliary predicates, see e.g. Boyer-Moore's theorem prover [BM 79].

Structural induction is a first order schema. In \(A S L(\mathbf{E Q})\) such a schema cannot be expressed as it is above since no quantifiers or implications are available in \(\mathbf{E Q}\). In this case, structural induction has to be moved to the metalanguage.

Despite the fact that other induction schemes can be explicitly derived from structural induction, the system is bound to be incomplete due to basic results of mathematical logic. We shall call those systems which fail to be incomplete only because of induction satisfactory systems, in order to distinguish them from other - generally worse - incomplete systems.

\subsection*{3.4 Proving \(k+A S L \models A\)}

In order to prove theorems from specifications with constructors, a few more inference rules are given. Generic constructors and \(F Q R D\)-constructors are considered, however complete rules are never attained.

Generic constructors \(\langle P, \Lambda\rangle\)

Generic constructors come with a sound inference rule embedded in their definition:

Proposition 3.4.1 \(\frac{S P \vdash \Phi}{\langle P, \Lambda\rangle S P \vdash \varphi} \quad\) provided \((\Phi, \varphi) \in \Lambda \quad\) is a sound inference rule.

Soundness is trivial by definition. The incompleteness of the rule is also clear since there is no way to know what the program \(P\) really does, apart from what is recorded in \(\Lambda\).

The advantages of such constructors are methodological. Carrying \(\Lambda\) allows us to treat the program \(P\) as a black box: Whatever the program \(P\) does, it will be unknown unless it is explicitly asserted in \(\Lambda\). This restricts greatly the use we can make of \(P\) but it makes sure that, whenever it is used, all that we need to know (prove) about it is in \(\Lambda\).

\section*{\(F Q R D\)-constructors}

The standard algebraic constructors \(F Q R D\) in EQ are the most well-known set of constructors. Although they make sense only in the context of an algebraic-like institution, some details are worth giving.

Contrary to generic constructors such as \(\langle P, \Lambda\rangle\), constructors in \(F Q R D\) are, essentially, model-theoretical operations. For this reason, inference rules for \(F, Q\) and \(R\) ( \(D\) has already been treated at the institution-independent level) are scarce and may depend on awkward side conditions.

Proposition 3.4.2 \(\frac{e q \vdash \forall X . t 1=t 2}{Q_{e q} S P \vdash \forall X . t 1=t 2} \quad\) is a sound inference rule.

Proof By definition of quotient \(A / \sim_{e q} \vDash e q\) for all \(A \in \operatorname{Mod}[S P]\), then by soundness of equational logic eq \(\vdash \forall X . t 1=t 2\) implies that \(A / \sim_{e q} \vDash \forall X . t 1=t 2\) for all \(A \in \operatorname{Mod}[S P]\), hence \(Q_{e q} S P \models \forall X . t 1=t 2\).

Proposition 3.4.3 \(\frac{S P \vdash \forall X . t 1=t 2}{Q_{e q} S P \vdash \forall X . t 1=t 2} \quad\) is a sound inference rule.
Proof Let \(A\) be a model of \(S P\) and \(\sim\) a congruence on \(A\), and assume that
\[
A \models \forall X . t 1=t 2 \quad \text { but } \quad A / \sim \not \models \forall X . t 1=t 2
\]

Then, there must exist a valuation \(\nu_{\sim}: T_{S i g[S P]}(X) \rightarrow A / \sim\) such that \(A / \sim, \nu_{\sim} \not \forall\) \(t 1=t 2\). Define \(\nu: T_{S i g[S P]}(X) \rightarrow A\) to be a valuation which delivers for each \(x \in X\) a representative of \(\nu_{\sim}(x)\), i.e. \([\nu(x)]=\nu_{\sim}(x)\).

Since congruences commute w.r.t. all operations in \(A, \nu_{\sim}(t 1)=[\nu(t 1)]\) and consequently \([\nu(t 1)] \neq[\nu(t 2)]\) so their representatives must be different \(\nu(t 1) \neq\) \(\nu(t 2)\), hence
\[
A, \nu \not \models t 1=t 2
\]

Thus \(A \not \models \forall X . t 1=t 2\), which is a contradiction.

Proposition 3.4.4
\[
\frac{S P \vdash \forall X . t 1=t 2}{R_{G} S P \vdash \forall X . t 1=t 2} \quad \text { is a sound inference rule. }
\]

Proof Let \(A\) be a model of \(S P\) and \(A^{\prime}\) a subalgebra of \(A\), and assume that
\[
A \models \forall X . t 1=t 2 \quad \text { but } \quad A^{\prime} \not \models \forall X . t 1=t 2
\]

Then, there must exist a valuation \(\nu^{\prime}\) such that \(A^{\prime}, \nu^{\prime} \notin t 1=t 2\). Define \(\nu\) : \(T_{S i g[S P]}(X) \rightarrow A\) to be a valuation which extends \(\nu^{\prime}\) to \(A\), i.e. \(\nu(x)=\nu^{\prime}(x)\) for all \(x \in X\).

Finally, since the interpretation of the function symbols in \(A\) and \(A^{\prime}\) is the same when applied to values existing in the subalgebra \(A^{\prime}\) we conclude that
\[
\nu(t 1)=\nu^{\prime}(t 1) \neq \nu^{\prime}(t 2)=\nu(t 1)
\]

Hence, \(A, \nu \not \models t 1=t 2\). Thus \(A \not \models \forall X . t 1=t 2\), which is a contradiction.

Proposition 3.4.5
\[
\frac{e q \vdash \forall X . t 1=t 2}{F_{\sigma}^{e q} S P \vdash \forall X . t 1=t 2}
\]
is a sound inference rule.

Proof By definition, for \(\sigma: \Sigma \rightarrow \Sigma^{\prime}, \operatorname{Fre} e_{\sigma}^{e q}: \operatorname{Alg}(\Sigma) \rightarrow \operatorname{Mod}\left[\left(\Sigma^{\prime}, e q\right\rangle\right]\). Then, it holds that \(\operatorname{Mod}\left[F_{\sigma}^{e q} S P\right] \subseteq \operatorname{Mod}\left[\left\langle\Sigma^{\prime}, e q\right\rangle\right]\) and since \(\operatorname{Mod}\left[\left\langle\Sigma^{\prime}, e q\right\rangle\right]=\operatorname{Mod}[C l(e q)]\) it follows that all semantic consequences of eq hold in \(\operatorname{Mod}\left[F_{\sigma}^{e q} S P\right]\). By soundness of equational logic the rule is sound.

A free extension \(F_{\sigma}^{e q} S P\) is sufficiently complete if it does not add new values to the old sorts, although it can confuse (quotient) some of the old values. Formally, \(F_{\sigma}^{e q} S P\) is sufficiently complete if the unit associated to the pair \(F_{\sigma}^{e q}\) and \(\left.\right|_{\sigma}\) for all \(A \in \operatorname{Mod}[S P]\) is a surjective homomorphism from \(A\) to \(\left.\left(\right.\) Free \(\left._{\sigma}^{e q} A\right)\right|_{\sigma}\).

A free extension \(F_{\sigma}^{e q} S P\) is consistent (or hierarchically consistent) if it preserves the old values of the old sorts along the extension, although it may add new ones. Formally, \(F_{\sigma}^{e q} S P\) is consistent if the unit associated to the pair \(F_{\sigma}^{e q}\) and \(\|_{\sigma}\) for all \(A \in \operatorname{Mod}[S P]\) is a injective homomorphism from \(A\) to \(\left.\left(\right.\) Free \(\left.{ }_{\sigma}^{e q} A\right)\right|_{\sigma}\).

Note that these definitions generalize the standard definitions of consistent and sufficiently complete free extension which refer exclusively to the reachable models of \(S P\) or, equivalently, to its initial model (see [Ber 87] for discussion).

Proposition 3.4.6 \(\frac{S P \vdash \forall X . t 1=t 2}{F_{\sigma}^{e q} S P \vdash \sigma(\forall X . t 1=t 2)} \quad\) is a sound inference rule provided \(F_{\sigma}^{e q} S P\) is sufficiently complete and consistent.

Proof If a free extension is sufficiently complete and consistent then it preserves the meaning of the symbols in \(S P\). Formally, the unit associated to the pair \(F_{\sigma}^{e q}\) and \(\left.\right|_{\sigma}\) for all \(A \in \operatorname{Mod}[S P]\) is an isomorphism from \(A\) to \(\left.\left(\right.\) Free \(\left._{\sigma}^{e q} A\right)\right|_{\sigma}\)
\[
\forall A \in \operatorname{Mod}[S P] .\left.\left(\text { Free }_{\sigma}^{e q} A\right)\right|_{\sigma} \cong A
\]

Considering an arbitrary model \(A \in \operatorname{Mod}[S P]\) and an equation \(\forall X . t 1=t 2\), if \(A \vDash \forall X . t 1=t 2\) then \(\left.\left(F r e e_{\sigma}^{e q} A\right)\right|_{\sigma} \vDash \forall X . t 1=t 2\) and, by the satisfaction condition, Free \(_{\sigma}^{e q} A \models \sigma(\forall X . t 1=t 2)\).

\subsection*{3.5 Specification entailment}

The main conclusion that can be extracted from the inference rules given in this chapter and their characterizations is the following:

Proofs of specification entailment based on reducing specifications to equivalent theories are of very limited use.

In fact, we can only expect an exact reduction of specifications to theories for \(A T U\)-specifications, since no other SBO has an exact rule. This result was already expected due to the greater expressive power of specifications in \(A S L(\mathbf{I})\) than common theories in I for common institutions used in formal specification.

This result shows the most striking difference, from a proof theoretic standpoint, between \(A S L\) and other common specification languages where semantics are directly given in terms of presentations or theories.

Once the idea of reducing specifications to theories has been discarded, emphasis has been put on the characterization of some inference rules (mostly obtained from [ST 88a]).

The definition of sound and M-complete inference rules helps us to analyze the nature of some inference rules and provides a better alternative than reducing specifications to exact theories; that is, reducing specifications to sound or Mcomplete theories.

We can use these reductions to prove \(S P 2 \vDash S P 1\) as follows:

Theorem 3.5.1 (Basic rule) Given an institution \(\mathbf{I}\), if there exists an M-complete theory \(\overline{\Delta_{1}}\) for SP1, a sound theory \(\underline{\Delta_{2}}\) for \(S P 2\) and \({\underline{\Delta_{2}}} \vdash_{\mathrm{I}} \overline{\Delta_{1}}\), then \(S P 2 \models S P 1\).

Proof Since \(\vdash_{I}\) is sound, \(\underline{\Delta_{2}} \vdash_{I} \overline{\Delta_{1}}\) implies \(\underline{\Delta_{2}} \vDash \overline{\Delta_{1}}\), which by corollary 3.3.2 means that \(\underline{\Delta_{2}} \supseteq \overline{\Delta_{1}}\). Applying \(\operatorname{Mod}\) we get \(\operatorname{Mod}\left[\Delta_{2}\right] \subseteq \operatorname{Mod}\left[\overline{\Delta_{1}}\right]\), and by definition of M -complete and M -sound (equivalent to sound) \(\operatorname{Mod}\left[S P_{2}\right] \subseteq \operatorname{Mod}\left[\Delta_{2}\right] \subseteq\) \(\operatorname{Mod}\left[\overline{\Delta_{1}}\right] \subseteq \operatorname{Mod}\left[S P_{1}\right]\).

The situation where the theorem applies can be represented by the diagram on the right. Every figure represents a class of models; in particular, squares represent axiomatizable classes of models.


The theorem states that the inclusion of the two ovals can be proved by showing the inclusion of the two squares. In practice, this can be performed by a theorem prover using the inference system provided with the institution \(\vdash^{I}\) plus the inference rules presented in this chapter, in such a way that only sound rules are use for the antecedent \(S P 2\) and only M-complete rules are used for the consequent \(S P 1\).

Looking at the drawing the basic rule seems obvious but also the lack of anything better unless every class of models described by the specification language can be characterized by an exact theory. The situation can only be improved by increasing the expressive power of theories and/or weakening the expressiveness of the specification language.

Going back to the inference rules provided in this chapter, we find no M complete rules apart from those which are also sound, and therefore exact. In principle, M-complete rules may not be sound and still be useful during the application of the Basic rule defined above. This is clear in the case of an abstraction
operation \(\alpha\) where a rule
\[
\frac{S P \vdash \varphi}{\alpha S P \vdash \varphi}
\]
is not sound since some "non-observable" theorems in SP may not hold in the abstracted specification \(\alpha S P\), however, the rule is useful in the sense that an entailment
\[
S P 2 \models \alpha S P 1
\]
could be proven correct by showing that \(S P 2 \vDash S P 1\), since the rule for abstraction is M-complete. Essentially, we prove that the antecedent satisfies more requirements than those needed.

Unfortunately, our research did not produce any interesting M-complete rule for \(D_{\sigma}\) or \(M_{\langle\sigma,\rangle\rangle}\) even among unsound rules.

Restricting to the inference rules presented in this chapter, the rules in \(\vdash^{1}\) and the basic rule, entailments \(S P 2 \models S P 1\) can only be proven to hold if \(S P 1\) is an \(A T U\)-specification. The limitation to \(A T U\) means, for institutions such as \(\mathbf{E Q}\), that we are unable to specify standard models of natural numbers or to use any hiding/abstraction mechanism in the consequent. In the context of a stepwise refinement of specification into programs, the antecedent of the first entailment is used as the consequent of the second entailment and so on,
\[
S P_{n} \vDash S P_{n-1} \vDash \ldots \vDash S P 2 \models S P 1
\]
hence the restriction to \(A T U\)-specifications is extended from the original specification of the problem \(S P 1\) to \(S P_{n-1}\).

On the other hand, \(S P 2\) can be a specification in \(k+A S L\) since the basic rule only requires sound inference rules for those SBO's used in the antecedent. The problem on this side comes from the incompleteness of some sound rules which may prevent some valid entailments from being derivable. This is particularly true for \(M_{(\sigma, \ell)}\) and some model oriented constructors such as \(F_{\sigma}^{e q}, R_{G}\) and \(Q_{e q}\) in EQ.

All these considerations lead to a very limited collection of provable entailments \(S P 2 \vDash S P 1\). In following chapters we shall gradually improve the situation but we can already identify which are the main problems.

The impossibility of using \(D_{\sigma}\) in the consequent is the first important problem. A solution will be found in chapters 4 and 5 .

The impossibility of using \(M_{\langle G, F, S\rangle}\) in the consequent despite having an induction rule is the second problem. A solution in EQ will be found in chapter 6.

However, the impossibility of using constructors in the consequent is not such an important problem. Constructors are normally thought of as pieces of a specification which have already been implemented during a refinement step (see constructor implementations in [ST 88b]). Therefore, later refinements should not re-implement constructors.

According to this view, constructors are mostly relevant in the antecedent. Constructors in the consequent will play a very limited role mostly related to decomposing large consequents for modular verification. These structural aspects of verification are addressed in chapter 7.

\section*{Chapter 4}

\section*{Specifications with hidden parts}

\subsection*{4.1 Introduction}

In the last chapter we came across the particular nature of \(D_{\sigma} . D_{\sigma}\) is the only SBO having no exact inference rule despite having a sound and complete inference rule.

In the context of proving \(S P 2 \vDash S P 1\), such a characterization means that using \(D_{\sigma}\) in \(S P 2\) has no unpleasant consequences since every valid theorem in \(S P 2\) (over \(D A T U\) ) can be inferred (completeness). However, \(D_{\sigma}\) cannot be eliminated from a specification (no exact rule) and therefore, if \(D_{\sigma}\) is used in \(S P 1\), proving \(S P 2 \models S P 1\) cannot be reduced to simple theorem proving.

This technical problem happens to be a well-known problem in proofs of correctness of implementation steps. Specifications using \(D_{\sigma}\) are known in the literature as specifications with hidden parts (hidden functions and/or hidden sorts) [TWW 78], or specifications with a bias [Jon 80]. In any case, when such specifications act as consequent, i.e. when they express the requirements which must be met by the antecedent or implementation, verification becomes hard.

Many algebraic specifications of a system, especially if they are large, provide a lot of information describing functions and data types which are not interesting to
the user of the system or to the person implementing that system. This auxiliary structure (hidden parts) helps to define the functions and sorts of interest but they are not meant to be implemented.

Hidden parts are the standard way to express requirements in abstract model specifications. In VDM, for example, data types are specified by representing them in terms of some predefined types such as lists, sets, mappings and sequences. These predefined types are the means for expressing requirements but they are not intended to be implemented. Changing the representation of the specified data types in the implementation is known as data reification [Jon 80, Jon 86], and correctness proofs can be very difficult. For example, consider a compiler function which is specified by a simple interpreter and then implemented in a more efficient way without respecting any of the structures by means of which compiler was specified. The proof of correctness would be a great deal more difficult than the proof of correctness of a direct implementation of the interpreter.

Algebraic specifications became popular as a way to define the elements of a system without representing them in terms of more primitive concepts, avoiding the definition of any extra structure. However, it has been shown that hidden functions are in general necessary for specifying computable functions in equational logic [Maj 77, TWW 78, BBTW 81], therefore the use of hiding is not characteristic of a specification style but is a fundamental SBO for writing abstract specifications.

The necessity of using hidden functions in order to specify some computable functions proves that in some institutions some extra expressiveness is achieved using hiding; this results in the impossibility of flattening arbitrary specifications containing \(D_{\sigma}\). Technically, the characterization of the inference rule for \(D_{\sigma}\) as complete but not M-complete witnesses this fact.

In some powerful logics, such as second order logic (SOL), the hiding of functions does not provide enhanced power. But in common logics used in formal specification, such as equational or first order logic, it certainly does. Intuitively,
hiding can be seen as a second order feature which can be added to weaker logics. Thus, correctness proofs in \(D A T U \vDash D A T U\) are going to cause some of the same difficulties as the introduction of second order existential quantifiers does in SOL.

\subsection*{4.1.1 Example}

The cases we are mostly interested in are those where some auxiliary functions/sorts are defined in order to specify some desired functions/sorts but the implementation does not follow the bias, i.e. the auxiliary structure is not implemented. With these cases, we expect to cover the most common difficulties involved in proofs of entailment w.r.t. specifications with hidden parts.

For example, suppose we want to add a function mre: listnat \(\rightarrow\) nat which computes the most repeated element in a list, to a specification ListNat of lists of natural numbers. Soon we realize that the available functions in \(L\) ist Nat, i.e.
```

[]: list
{empty list}
_ :: _: nat, list -> list
car: list -> nat
cdr: list -> list
{removes the first element from a list}
0: nat
suc: nat -> nat
_ \geq_: nat, nat -> bool
true, false: bool

```
are not enough to conveniently define the new function. We proceed by defining an auxiliary function which counts the number of repetitions of a natural number in a list of natural numbers, as in figure 4-1.

Any efficient implementation of mre will not implement count itself but will instead implement a function which computes simultaneously the frequencies of

\section*{Chapter 4. Specifications with hidden parts}
```

SP1 = Enrich ListNat by
Hidden
sorts
operations
count: listnat, nat -> nat
axioms
\forallx:nat. count([], x) = 0
|:nat; l:listnat. count(x::l, x) = suc(count(l,x))
* x1,x2:nat; l:listnat.
(x1\not=x2) =>(count (x1::1,x2) = count (1,x2))
in
sorts
operations
mre: listnat -> nat
axioms
(1) }\quad\forallx:nat; l:listnat. (count(1, mre(1)) \geq count(l,x))=tru
end

```

Figure 4-1: Lists with a mre (most repeated element) function
all elements in the list. In a stepwise refinement methodology, the specification in figure 4-2 leads in the direction of the desired implementation by defining mre in terms of a new function frequencies: listnat \(\rightarrow\) set (nat \(x\) nat) and some extra structure defining sets of pairs of natural numbers SetPairsNat (with sort name set (nat x nat)) and lists of pairs of natural numbers ListPairsNat (with sort name list(nat \(x\) nat)).

The function frequencies yields a set of pairs, where each pair contains a counter and an element of the argument list; for example
```

frequencies([1,3,2,1])={(1,3),(1,2),(2,1)}

```

Then we have that
```

car(sort(frequencies([1,3,2,1])))=(2,1)

```
and so \(\operatorname{mre}([1,3,2,1])=1\).
In the next refinement step frequencies can be made visible, i.e. forced to be implemented, or its definition may be changed to yield a table. Moreover picking the largest element need not be implemented using car (sort (. . ) ). Eventually, after a few steps we obtain a correct and efficient implementation.

The above refinement step is proven correct by showing that the axiom (1) which defines mre in the specification \(S P 1\) can be deduced from the implementation, \(S P 2\), together with the definition of count (the hidden part of \(S P 1\) ); this repeats the "proof procedure" already used in [San 86]. Informally the proof proceeds by proving that:
1. The frequencies of the elements of a list are in the set created by frequencies.
```

| l:listnat; x:nat.
(count (l, x)\not=0) =>(count (l,x),x)\in frequencies(l) = true

```
```

SP2 = Enrich ListNat by
Hidden
sorts
operations
{operations of SetPairsNat and ListPairsNat}
sort: set(nat x nat) -> list(nat x nat)
frequencies: listnat -> set(nat x nat)
axioms

```
        \{axioms of SetPairsNat and ListPairsNat\}
        frequencies([])= \(\emptyset\)
        \(\forall\) l:listnat; \(x: n a t\).
            ( \(\exists\) i:nat. (i,x) \(\in\) frequencies \((1)=\) true \() \Rightarrow\)
            ( \(\forall\) i:nat. (i,x) \(\in\) frequencies \((1)=\) true \(\Rightarrow\)
            frequencies \((x:: 1)=\) frequencies \((1) \backslash\{(i, x)\} \cup\{(i+1, x)\})\)
        \(\forall 1\) :listnat; \(x:\) nat.
            ( \(\nexists \mathrm{i}:\) nat. \(\quad(\mathrm{i}, \mathrm{x}) \in\) frequencies \((1)=\) true \() \Rightarrow\)
            (frequencies \((x:: 1)=\) frequencies( 1 ) \(\cup\{(1, x)\}\) )
        \{ Axioms for sorting a set of pairs by the first
        element of the pair, in decreasing order \}
in
    sorts
    operations
        mre: listnat -> nat
    axioms
        \(\operatorname{mre}([])=0\)
        \(\forall\) l:listnat. \(\quad(1 \neq[]) \Rightarrow\)
        \((\operatorname{mre}(1)=\operatorname{proj} 2(\operatorname{car}(\operatorname{sort}(\) frequencies(1) \()))\)
end
2. All counters in the set created by frequencies denote frequencies.
```

i,x:nat; l:listnat.
((i,x) frequencies(l) = true) => i = count(l, x)

```
3. By definition of sort and car the term car(sort(s)) yields the pair in the set \(s\) with the highest counter.
```

$\forall$ s:set (nat $x$ nat). $\quad(s \neq \emptyset) \Rightarrow$
$((\forall i, y:$ nat. $(i, y) \in s=$ true $) \Rightarrow(\operatorname{proj} 1(\operatorname{car}(\operatorname{sort}(s))) \geq i=$ true $))$

```
4. Similarly taking \(s\) to be the set of frequencies of a list 1 ,
```

car(sort(frequencies(l)))

```
yields the pair with the highest frequency.
```

\forall l:listnat. (l=[]) V
(( }\forall\textrm{x}:\mathrm{ nat. (i,x) ffrequencies(l) = true) }
(proj1(car(sort(frequencies(l))))\geqi = true))

```
5. Hence, mre (1) is the most repeated element in 1 provided 1 is not an empty list, and zero when 1 is empty. Therefore, it is always the case that:


Apart from the technicalities of the proof, the interest of this example arises from the difficulty in generalizing this style of proof to a specification language with arbitrary use of hiding and justifying that it is sound.

The rest of the chapter is divided into six sections. Section 2 gives a formal presentation of the problem and some simple strategies are shown not to be satisfactory. Section 3 emphasizes the special structure of specifications such as SP1
and introduces two properties applicable to specifications of this form: persistency and independence. In section 4 the inheriting strategy, a formal version of the strategy used in the above example, is presented and proved sound for persistent hidden parts. In section 5 the inheriting strategy is proven complete for independent specifications. Section 6 generalizes the inheriting strategy to the case of \(k+A S L \models D A T U\). Finally, section 7 copes with some difficult cases falling out of the scope of the inheriting strategy.

\subsection*{4.2 Proving \(D A \models D A\)}

A general setting in which to study entailment proofs between specifications with hidden parts is \(A S L \models A S L\). For the time being, we shall ignore reachability constraints (see chapter 6) and focus on \(D A T U \vDash D A T U\).

However, the problem can be simplified to \(D A \models D A\) without loss of generality since considering some transformation rules in addition to those for \(A T U\) in section 3.2 allows the elimination of \(T\) and \(U\) in \(D A T U\).

Proposition 4.2.1 The following specification transformations are sound for all specifications SP, SP1 and SP2, morphisms \(\sigma\) and \(\sigma 1\), and set \(\Phi\) of sentences
\[
\begin{gathered}
A_{\Phi} D_{\sigma} S P=D_{\sigma} A_{\sigma(\Phi)} S P \\
T_{\sigma} D_{\sigma 1} S P=D_{\sigma 1^{\prime}} T_{\sigma^{\prime}} S P \\
S P 1 U D_{\sigma} S P 2=D_{\sigma}\left(T_{\sigma} S P 1 U S P 2\right) \\
D_{\sigma} S P 1 U S P 2=D_{\sigma}\left(S P 1 U T_{\sigma} S P 2\right)
\end{gathered}
\]
where \(\sigma 1^{\prime}\) and \(\sigma^{\prime}\) are defined by the following pushout diagram:


\section*{Proof}
1. \(A_{\Phi} D_{\sigma} S P=D_{\sigma} A_{\sigma(\Phi)} S P\)

The proof can be presented as a chain of equalities between classes of models:
\[
\begin{aligned}
& \operatorname{Mod}\left[A_{\Phi} D_{\sigma} S P\right] \\
& =\left\{\left.A\right|_{\sigma}|A \in \operatorname{Mod}[S P] \wedge A|_{\sigma} \models \Phi\right\} \\
& =\left\{\left.A\right|_{\sigma} \mid A \in \operatorname{Mod}[S P] \wedge A \models \sigma(\Phi)\right\} \quad \text { by the satisfaction condition. } \\
& =\operatorname{Mod}\left[D_{\sigma} A_{\sigma(\Phi)} S P\right]
\end{aligned}
\]
2. \(T_{\sigma} D_{\sigma 1} S P=D_{\sigma 1^{\prime}} T_{\sigma^{\prime}} S P\)

The proof can be presented as a chain of equalities between classes of models:
```

$\operatorname{Mod}\left[T_{\sigma} D_{\sigma 1} S P\right]$
$=\left\{A|A|_{\sigma} \in \operatorname{Mod}\left[D_{\sigma 1} S P\right]\right\}$
$=\left\{A|\exists B \in \operatorname{Mod}[S P] . B|_{\sigma 1}=\left.A\right|_{\sigma}\right\}$
$=\left\{\left.C\right|_{\sigma^{\prime}}|C|_{\sigma^{\prime}} \in \operatorname{Mod}[S P]\right\} \quad$ since for every $A$ and $B$ such that $\left.B\right|_{\sigma 1}=\left.A\right|_{\sigma}$,
there is a $C$ such that $\left.C\right|_{\sigma 1^{\prime}}=A$ and $\left.C\right|_{\sigma^{\prime}}=B$
i.e. $C=A \oplus B$.
$=\left\{\left.C\right|_{\sigma 1^{\prime}} \mid C \in \operatorname{Mod}\left[T_{\sigma^{\prime}} S P\right]\right\}$
$=\operatorname{Mod}\left[D_{\sigma 1}, T_{\sigma^{\prime}} S P\right]$

```
3. \(S P 1 U D_{\sigma} S P 2=D_{\sigma}\left(T_{\sigma} S P 1 U S P 2\right)\)

The proof can be presented as a chain of equalities between classes of models:
\(\operatorname{Mod}\left[\begin{array}{lll}S P 1 & U & D_{\sigma} S P 2\end{array}\right]\)
\(=\left\{A \mid A \in \operatorname{Mod}[S P 1] \wedge\left(\exists B \in \operatorname{Mod}[S P 2] .\left.B\right|_{\sigma}=A\right)\right\}\)
\(=\left\{\left.B\right|_{\sigma} \mid B \in \operatorname{Mod}[S P 2] \wedge B \in \operatorname{Mod}\left[T_{\sigma} S P 1\right]\right\}\)
\(=\operatorname{Mod}\left[D_{\sigma}\left(T_{\sigma} S P 1 \quad U S P 2\right)\right]\)
4. \(D_{\sigma} S P 1 \cup S P 2=D_{\sigma}\left(S P 1 U T_{\sigma} S P 2\right)\)

Proven analogously to 3 above.

Theorem 4.2.2 Every specification \(S P\) over DATU is equivalent to a specification of the form \(D_{\sigma} A_{\Phi} \epsilon_{\Sigma}\), where the reduction from \(S P\) to \(D_{\sigma} A_{\Phi} \epsilon_{\Sigma}\) is computable.

Proof It is enough to consider the reduction rules from \(A T U\) to \(A\), the commutativity rules for \(D_{\sigma}\) given above (considered from left to right) and the rule
\[
D_{\sigma} D_{\sigma^{\prime}} S P=D_{\sigma ; \sigma^{\prime}} S P
\]
where \(\uparrow \sigma=\downarrow \sigma^{\prime}\). Then, every specification \(S P\) in \(D A T U\) can be transformed first into a specification \(D_{\sigma} S P^{\prime}\) for some signature morphism \(\sigma\) and a specification \(S P^{\prime}\) in \(A T U\) (using the commutativity rules for \(D_{\sigma}\) ) and, from that, it can be transformed into a specification \(D_{\sigma} A_{\Phi} \epsilon_{\Sigma}\) using the rules in section 3.2.

These proofs are among those presented in [EWT 83]. Nevertheless, in [EWT 83] the result is only stated for the particular institution they use. Results in [Bre 89] also repeat a similar proof, however all results are unnecessarily restricted to algebraic signatures and to \(D_{\sigma}\) with injective signature morphisms. For this reason, proofs have been given again instead of using a corollary to the normal form results in [Bre 89] or [EWT 83].

Taking advantage of these results, \(D A T U \vDash D A T U\) is reduced without loss of generality to the following task:

Task 1: \(\quad D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma} H 2 \neq D_{\sigma 1} A_{\Phi 1} \epsilon_{\Sigma H 1}\)
Given two finite presentations \(\Phi 1\) and \(\Phi 2\) over signatures \(\Sigma H 1\) and \(\Sigma H 2\) which are two extensions of \(\Sigma\), prove that
all models over \(\Sigma\) obtained by restricting models of \(\Phi 2\) can be obtained by restricting models of \(\Phi 1\).

Note: In order to simplify notation signature morphisms \(\sigma 1\) and \(\sigma 2\) are assumed to be inclusions \(\iota 1\) and \(\iota 2\). However, no advantage of this assumption will be taken unless stated.

Given such a task there are only two reasonable things one may try to do: prove that \(\Phi 1\) follows from \(\Phi 2\) in an appropriate signature, or prove that all visible consequences of \(\Phi 1\) follow from \(\Phi 2\). Unfortunately, the first approach only works for some trivial cases and the second one is unsound.

\section*{First naïve approach.}

In this approach we want to mix in our reasoning sentences over \(\Sigma H 1\) and over \(\Sigma H 2\) without confusing their auxiliary symbols; therefore, we consider the pushout signature \(\Sigma H\) and try to prove that \(\iota 1^{\prime}(\Phi 2) \models \iota 2^{\prime}(\Phi 1)\) (we will also write this as \(\Phi 2 \models_{\Sigma H} \Phi 1\) ).


In an institution such as first order logic, this amounts, by the Craig interpolation lemma, to the existence of a finite set of sentences \(\Phi\) over \(\Sigma\) such that
\[
\text { (2) } \Phi 2 \models_{\Sigma H 2} \Phi \quad \text { and } \quad \Phi \models_{\Sigma H 1} \Phi 1
\]

Turning around the argument, a refinement \(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\iota 1} A_{\Phi 1} \epsilon_{\Sigma H 1}\) can only be proven correct in this fashion if there exists an intermediate flat specification \(A_{\Phi} \epsilon_{\Sigma}\) such that \(\Phi\) satisfies (2).

However, if this is the case, the symbols in the hidden part of \(\Phi 1\) are rather trivial since their properties can be inferred from sentences in \(\Phi\) which do not mention them.

This approach offers surprisingly little. We may think that at least those implementations which proceed by implementing the hidden part should be provably correct. For example, given a the specification \(S P 1\) in figure 4-1 as consequent we propose \(S P 3\) in figure 4-3 as antecedent.

In this case the proof is easier because the implementation follows the bias of the specification, and we can directly prove that \(\Phi 2 \vDash_{\Sigma H 2} \Phi 1\).

The difference with the approach just proposed is the existence of a morphism \(\iota 3\) (identity in this example) which is missing in the general case.


On the the other hand, the existence of \(\iota 3\) does not guarantee that a refinement can be proved correct in this fashion since the same symbols may have different meanings in the two specifications.

For example, consider the result returned by count in the specification \(S P 4\) (see figure 4-4). In this case, the result of count is double the result returned by count in \(S P 1\). Therefore, although \(S P 4 \vDash S P 1\) is a correct entailment and \(\operatorname{Sig}[S P 4]=\operatorname{Sig}[S P 1]\), the bias is not followed and the proof method above does not work.

\section*{Second naïve approach}

More realistic is the second approach where we prove that:
\[
\Phi 2 \models_{\Sigma H 2} \iota 1^{-1}(C l(\Phi 1))
\]
    sorts
    operations
        count: listnat, nat -> nat
    axioms
        \{ Axioms of count as in SP1\}
in
    sorts
    operations
        mre: listnat -> nat
    axioms
        \(\operatorname{mre}([])=0\)
        \(\forall x: n a t ; 1: l i s t n a t\).
            (count \((1, x)+1 \leq \operatorname{count}(1, \operatorname{mre}(1))=\) true \(\Rightarrow\)
            \(\operatorname{mre}(x: 1)=\operatorname{mre}(1))\)
        \(\forall x: n a t ; 1: l i s t n a t\).
                (count \((1, x)+1>\operatorname{count}(1, \operatorname{mre}(1))=\) true \(\Rightarrow\)
                    mre(x::1) \(=x\) )
end

Figure 4-3: Lists with a mre function, version 3
```

SP4= Enrich ListNat by
Hidden
sorts
operations
count: listnat, nat -> nat
axioms
|}\mathrm{ :nat. count ([],x)=0
|:nat; l:listnat. count(x::l, x) = count(l,x) + 2
\forall x1,x2:nat; l:1istnat.
(x1\not=x2) =>(count (x1::1,x2) = count (1,x2))
in
sorts
operations
mre: listnat -> nat
axioms
{ Axioms of mre as in SP3}
end

```

Figure 4-4: Lists with a mre function, version 4
where \(\iota 1^{-1}\) forgets the sentences which mention symbols not in \(\Sigma\). Unfortunately, due to the difference in expressive power between flat specifications (even if they are infinite) and presentations with hidden parts studied in [Maj 77, TWW 78], this proof strategy is, in general, unsound [BHK 86, Far 89]. For example (from [BHK 86]), suppose we are asked to prove
\[
\text { Nat } \models \text { NStNat }
\]
where \(N a t\) is a specification of the natural numbers including the standard interpretation alongside the non-standard interpretations, whereas NStNat (figure 3-2) specifies the class of the non-standard models of the natural numbers. It is wellknown that all the first-order properties of the non-standard models of the natural numbers are satisfied by the standard models; however the entailment is incorrect.

In many cases this strategy is sound but \(\iota 1^{-1}(C l(\Phi 1))\) is infinite and not finitely presentable, making the proof very hard. Even worse, if the strategy is sound and \(\iota 1^{-1}(C l(\Phi 1))\) happens to be equivalent to a finite presentation \(\Phi\), we may be able to prove that \(\Phi 2 \models \Phi\) but it may be difficult to prove the equivalence between \(\Phi\) and \(\iota 1^{-1}(C l(\Phi 1))\), in particular this may be as difficult as the original task.

Consider for example the specification of max: listnat \(\rightarrow\) nat which yields the maximum element of a list of natural numbers, by means of an auxiliary function sort: listnat \(\rightarrow\) listnat, as in figure 4-5.

The function max can be directly specified using the available operations in ListNat:
```

max: listnat -> nat
max([]) = 0
\foralll:listnat;x:nat.
(max(1)>x = true }=>\mathrm{ max(x::1) = max(1))
| l:listnat;x:nat.
(max(1) \leqx = true }=>\operatorname{max}(x::1)=x

```
```

Enrich ListNat by
Hidden
sorts
operations
sort: listnat -> listnat
axioms
{ Axioms for sorting }
in
sorts
operations
max: listnat -> nat
axioms
max([]) = 0
| l:listnat. l }\not=[]=>\operatorname{max}(1)=\operatorname{car(sort(1))
end

```

Figure 4-5: Lists with a max function

Then, the visible consequences of SP5 can be finitely axiomatized by adding (3) to ListNat so that an implementation \(D_{c 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\) can be proven correct by proving \(\Phi 2 \vDash\) ListNat \(\cup(3)\). In this case, the strategy turns out to be sound.

But, in fact, there is still the problem of proving that the proposed axiomatization (3) is correct, in other words, that ListNat U (3) \(\models S P 5\), but this is just another instance of our general task in the particular case that \(\Sigma H 2\) is equal to \(\Sigma\), which can be as difficult as the task we started with (see e.g. histogram example in [San 86]).

\section*{A strategy based on second order existential quantifiers}

A hiding operator, \(D_{\iota}\) with an inclusion \(\iota\), can be seen to a certain extent as a second order existential quantifier. If we can quantify over functions it is very easy to specify functions such as mre in figure 4-1 by writing a sentence such as the following:
\(\exists^{2}\) count: listnat, nat \(\rightarrow\) nat. \{Axioms for count \} \(\wedge\) \{Axioms for mre\}

Keeping this analogy in mind, a new strategy resembling the introduction rule for \(\exists^{2}\) in SOL can be found. The introduction rule of \(\exists^{2}\) says that before being able to assert that a function with a certain property exists. an explicit function with that property must be given; then, introducing \(\exists^{2}\) discharges (hides) this function.

In the implementation of mre via frequencies, the \(\exists^{2}\)-strategy amounts to explicitly including count in the implementation in spite of the fact that it is not needed. Once count is in the implementation. the proof can easily be performed ignoring the hiding.

Formally this strategy can be presented as the following rule:

Proposition 4.2.3 Given signature morphisms \(\sigma 1: \Sigma \rightarrow \Sigma H 1, \sigma 2: \Sigma \rightarrow \Sigma H 2\) and \(\sigma: \Sigma H 1 \rightarrow \Sigma H\), and sets of sentences \(\Phi 1 \subseteq \operatorname{Sen}(\Sigma H 1), \Phi 2 \subseteq \operatorname{Sen}(\Sigma H 2)\) and \(\Phi \subseteq \operatorname{Sen}(\Sigma H)\), then
\(\frac{D_{\sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash A_{\Phi 1} \epsilon_{\Sigma H 1} \quad D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\sigma 1 ; \sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}}{D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\sigma 1} A_{\Phi 1} \epsilon_{\Sigma H 1}}\) is sound.

Proof Soundness follows immediately from the transitivity of \(\vDash\) and the monotonicity of \(D_{\sigma 1}\) w.r.t. model class inclusion (entailment), since the conclusion is the composition of the premises after applying \(D_{\sigma 1}\) to both sides of the first premise.

Note that \(\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right)\) is an enrichment to the antecedent (implementation) which must be guessed. The second premise can be seen as a side condition guaranteeing the persistency of \(\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right)\) w.r.t. \(D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\) and \(\left\langle i d_{\Sigma},(\sigma 1 ; \sigma)\right\rangle\), and the first premise is the desired proof ignoring the hiding provided by \(D_{\sigma 1}\). The following theorem shows that this rule can solve our task (Task 1).

Theorem 4.2.4 (Wir 91) Given signature morphisms \(\sigma 1: \Sigma \rightarrow \Sigma H 1\) and \(\sigma 2\) : \(\Sigma \rightarrow \Sigma H 2\), a set \(\Phi 1\) of \(\Sigma H 1\)-sentences and a set \(\Phi 2\) of \(\Sigma H 2\)-sentences such that
\[
D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\sigma 1} A_{\Phi 1} \epsilon_{\Sigma H 1}
\]
then, there exists a signature \(\Sigma H\), a morphism \(\sigma: \Sigma H 1 \rightarrow \Sigma H\) and a set \(\Phi\) of \(\Sigma H\)-sentences such that
\[
D_{\sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models A_{\Phi 1} \epsilon_{\Sigma H 1}
\]
and
\[
D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\sigma 1 ; \sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}
\]

Proof Take \(\sigma\) and \(\Phi\) to be \(i d_{\Sigma H 1}\) and \(\Phi 1\) respectively and substitute in the conclusion of the theorem
\[
\left(A_{\Phi 1} T_{\sigma 1}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models A_{\Phi 1} \epsilon_{\Sigma H 1} \quad D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\sigma 1}\left(A_{\Phi 1} T_{\sigma 1}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}
\]

The first entailment holds trivially since any model of the antecedent has to satisfy \(\Phi 1\) and therefore it is also a model of \(A_{\Phi 1} \epsilon_{\Sigma H 1}\).

In order to prove the second entailment, consider an arbitrary model \(A \in\) \(\operatorname{Mod}\left[D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\right]\). According to the assumption, \(D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\sigma 1} A_{\Phi 1} \epsilon_{\Sigma H 1}\), we know that \(A \in \operatorname{Mod}\left[D_{\sigma 1} A_{\Phi 1} \epsilon_{\Sigma H 1}\right]\). By definition of \(D_{\sigma 2}\) and \(D_{\sigma 1}\), there exists a \(\Sigma H 2\)-model \(B\) and a \(\Sigma H 1\)-model \(C\) such that
\[
A=\left.B\right|_{\sigma 2}=\left.C\right|_{\sigma 1} \quad B \models_{\Sigma H 2} \Phi 2 \quad C \models_{\Sigma H 1} \Phi 1
\]
thus \(A \in \operatorname{Mod}\left[D_{\sigma 1}\left(A_{\Phi 1} T_{\sigma 1}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\right]\).

Considering this theorem and the normal form result in theorem 4.2.2 for specifications in \(D A T U\), we may think that \(\operatorname{DATU}(\mathbf{I}) \vDash D A T U(\mathbf{I})\) has a sound and complete inference system, provided \(\vdash^{\mathbf{I}}\) is sound and complete. However, this is not the case unless persistency, i.e. \(D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\sigma 1 ; \sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\), can be proven. A similar result found in [Wir 91] asserts the existence of a complete inference system for \(D A T U \models D A T U\) but that relies on the fact that persistency is treated as a side condition instead of a premise.

In a more general form the \(\exists^{2}\)-strategy can be presented as:
\[
\frac{P S P 2 \models S P 1 \quad S P 2 \models D_{\sigma 1} P S P 2}{S P 2 \models D_{\sigma 1} S P 1}
\]
where \(P\) is a parameterized specification \((\lambda X: \downarrow \sigma 1 . S P)\) taking specifications over \(\downarrow \sigma 1\) and producing specifications over \(\uparrow \sigma 1=\operatorname{Sig}[S P 1]\).

Analogously to the rule above, soundness of this rule follows immediately from the transitivity of \(\vDash\) and the monotonicity of \(D_{\sigma 1}\) w.r.t. entailment.

In fact, the first rule corresponds to the particular case in which \(S P 2\) and \(S P 1\) are specifications \(D_{\sigma 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\) and \(A_{\Phi 1} \epsilon_{\Sigma H 1}\), and \(P\) is a parameterized specification ( \(\left.\lambda X: \downarrow \sigma 1 . D_{\sigma} A_{\Phi} T_{\sigma 1 ; \sigma} X\right)\). Nevertheless, for specifications in \(D A T U\) the normalization results in theorem 4.2.2 allow the first rule to be used without loss of generality.

The drawback of the \(\exists^{2}\)-strategy is the need to guess \(\Phi\), or \(P\) in general. In the following sections a technique is presented for taking \(\Phi\) to be a part of \(\Phi 1\) in cases such as count in the specification of mre. But, in general, guessing \(\Phi\) amounts to implementing the hidden part of the consequent specification in order to prove correctness, and this is indeed a high price for not following the specification bias.

We conclude that given the general task of proving entailments between specifications with hidden parts, naïve techniques fail to handle examples such as the one in section 4.1.1, and indeed there are very few cases where entailment can be proven. Alternatively, a complete strategy exists but it requires the prover to do a lot of work. In the following section we present some restrictions to the general case needed to handle all the examples presented, using a method like the one sketched for the example at the end of section 4.1.1.

\subsection*{4.3 Persistent and independent enrichments}

The main difference between the general case as it has been presented in the last section and the examples, is the existence of a structure in the axioms of the examples which allows us to distinguish some of them as defining the hidden part
and some others as using the hidden part in order to define a visible enrichment. Therefore, we shall assume that our task carries such a structure.

In general, we shall distinguish within the visible part, \(\Sigma\), those visible symbols in terms of which the hidden symbols are defined, \(\Sigma 0\), the inclusion along the hidden enrichment, \(\iota l_{h}\), and finally the inclusion along the (visible) enrichment \(\iota_{v}\) on top of the hidden enrichment.


In the example \(S P 1\) in figure \(4-1, \Sigma 0\) is the signature of \(L i s t N a t, ~ \iota 1_{k}\) adds count, and \(\iota_{v}\) adds mre producing the whole signature \(\Sigma H 1\), which is then constrained by hiding count along \(\iota\).

In general, we shall require signature morphisms \(\iota_{h}, \iota 1_{v}, \iota_{E}\) and \(\iota 1\) as in the figure to form a pushout diagram. In the case where all morphisms are inclusions, \(\Sigma H 1\) is the union of \(\Sigma\) and \(\Sigma 0 H 1\), and \(\Sigma 0\) is their intersection.

Such a structure of the signature must be imposed upon the sentences so that, instead of having a single set of sentences \(\Phi 1\) over \(\Sigma H 1\) and consequent \(D_{c 1} \Phi 1 \epsilon_{\Sigma H 1}\), we have three sets of sentences:
\(\Phi 1_{0}\) : set of sentences over \(\Sigma 0\).
\(\Phi 1_{h}\) : set of sentences over \(\Sigma 0 H 1\) specifying the hidden part.
\(\Phi 1_{v}\) : set of sentences over \(\Sigma H 1\) specifying a visible enrichment using the hidden part.

Therefore the task becomes:

Task 2: \(\quad D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\)
Now, we must establish the conditions under which such a decomposition capture the informal ideas of specifying the hidden part and using the hidden part for
specifying a visible enrichment. In order to do that, we define the concepts of persistent and independent enrichment.

Definition 4.3.1 An enrichment by \(\Sigma_{e}\)-axioms \(\Phi_{e}\) w.r.t. a signature inclusion \(\iota_{e}: \Sigma \hookrightarrow \Sigma_{e}\) is a parameterized specification \(\left(\lambda X: \Sigma . A_{\Phi_{e}} T_{\iota_{e}} X\right)\) which produces a specification over \(\Sigma_{e}\) when it is applied to a specification over \(\Sigma\). Enrichments are usually written as \(\left(A_{\Phi_{e}} T_{\iota_{e}}\right)\).

Given a signature inclusion \(\iota_{e}: \Sigma \hookrightarrow \Sigma_{e}\) and a set of \(\Sigma_{e}\)-sentences \(\Phi_{e}\), an enrichment \(\left(A_{\Phi_{e}} T_{\iota e}\right)\) (or \(\left.\lambda X: \Sigma . A_{\Phi_{e}} T_{\iota_{e}} X\right)\) is persistent w.r.t. a \(\Sigma\)-specification \(S P\) iff \(\left(A_{\Phi_{e}} T_{\iota_{e}}\right)\) is persistent \(S P\) and \(\left\langle i d_{\Sigma}, \iota_{e}\right\rangle\), i.e. for all \(A \in \operatorname{Mod}[S P]\) there is a model \(B \in \operatorname{Mod}\left[\left(A_{\Phi_{e}} T_{\iota_{e}}\right) S P\right]\) which extends \(A,\left.B\right|_{\iota_{e}}=A\).

Given signature morphisms \(\iota_{E}, \iota 1_{v}, \iota 1\) and \(\iota 1_{h}\) forming a pushout diagram as in the figure above, and sets of sentences \(\Phi 1_{h}\) over \(\Sigma 0 H 1\) and \(\Phi 1_{v}\) over \(\Sigma H 1\), an enrichment \(\left(A_{\Phi_{1}} T_{t 1_{h}}\right)\) is independent w.r.t. a \(\Sigma 0\)-specification \(S P\) and an enrichment \(\left(A_{\Phi 1_{v}} T_{t 1_{v}}\right)\) iff for all \(A \in \operatorname{Mod}\left[\left(A_{\Phi 1_{h}} T_{i 1_{h}}\right) S P\right]\) and \(B \in\) \(\operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{11_{v}}\right)\left(A_{\Phi 1_{h}} T_{i 1_{h}}\right) S P\right]\) such that \(\left.B\right|_{\iota_{E}}=\) \(\left.A\right|_{1_{h}}\), there exists \(C \in \operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{11_{v}}\right)\left(A_{\Phi 1_{h}} T_{11_{h}}\right) S P\right]\)
 such that \(\left.C\right|_{1_{v}}=A\) and \(\left.C\right|_{11}=B\).

\section*{Remarks}
1. An enrichment to a presentation is a theory extension, and a persistent enrichment is a particular kind of conservative extension, in the terminologyof [Kei 77, BP 90].
2. If \(\iota 1_{k}\) and \(\iota 1_{v}\) are inclusions, we can require \(\iota 1\) and \(\iota_{E}\) to be inclusions as well without loss of generality. Moreover, if the pushout of inclusions exists, inclusions \(\iota 1\) and \(\iota_{E}\) are unique given \(\iota_{h}\) and \(\iota 1_{v}\).
3. Often translations \(T_{\iota}\) where \(\iota\) is an inclusion can be inferred from the context. In this case, they can be omitted so that \(\Phi_{e}\) is used instead of ( \(A_{\Phi_{e}} T_{\iota_{e}}\) ) for arbitrary enrichments. Moreover, we write \(\left[\Phi 1_{h}\right]\) to denote hidden enrichments so that \(D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\) can be written as \(\Phi 1_{v}\left[\Phi 1_{h}\right] S P\).

We shall use this short notation in some explanations, though the full notation is kept in the results and their proofs.
4. Since \(M o d\) is assumed to preserve finite co-limits, according to the amalgamation lemma, there is a unique model \(C\) which is the amalgamated union \(A \oplus B\) (w.r.t. \(\|_{c 1_{h}}\) and \(-\left.\right|_{\iota E}\) ). Therefore, we can define independent enrichments by saying that: \(\Phi 1_{h}\) is independent w.r.t. \(S P\) and \(\Phi 1_{v}\) iff the class of models of \(\Phi 1_{v} \Phi 1_{h} S P\) is closed under amalgamated unions between models of \(\Phi 1_{h} S P\) and models of \(\Phi 1_{v}\left[\Phi 1_{h}\right] S P\).

From an intuitive point of view, persistency of a hidden enrichment \(\Phi 1_{h}\) w.r.t. a specification \(S P\) ensures that no models of \(S P\) is indirectly excluded by some requirements of \(\Phi 1_{h}\), i.e. \(\left[\Phi 1_{h}\right] S P\) is equivalent to \(S P\) or, as expressed in the \(\exists^{2}\)-strategy, \(S P \models\left[\Phi 1_{h}\right] S P\). Independence of a hidden enrichment \(\Phi 1_{h}\) w.r.t. specification \(S P\) and a later visible enrichment \(\Phi 1_{v}\) means that the choice of a particular model in the hidden part does not exclude any of the models of the overall specification \(\Phi 1_{v}\left[\Phi 1_{h}\right] S P\).

In next section we shall see how these conditions relate to entailment proofs, but we show first how independence is related to persistency.

\section*{Independence versus persistency}

We might think that a more natural condition to place upon a visible enrichment on top of a hidden enrichment is to require persistency for the visible enrichment, at least w.r.t. the hidden symbols. This notion is formalized as relative persistency.

Definition 4.3.2 Given signature morphisms \(\iota_{E}, \iota_{v}\), \(\iota 1\) and \(\iota_{h}\) forming a pushout diagram as in the figure, an enrichment \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\) is relatively persistent w.r.t. a previous enrichment \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) and a specification SP, iff for all \(A \in \operatorname{Mod}\left[\left(A_{\Phi_{1}} T_{\iota_{1}}\right) S P\right]\) for which there exists \(B \in \operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\right]\) such that \(\left.B\right|_{L_{E}}=\left.A\right|_{\iota 1_{h}}\), there exists \(C \in\) \(\operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\imath 1_{h}}\right) S P\right]\) such that \(\left.C\right|_{c 1_{v}}=A\).


This property states persistency of the second enrichment w.r.t. that part of the signature added during the first (hidden) enrichment. Technically, \(C\) extends \(A\) as in the definition of persistent enrichment, but now \(A\) is not an arbitrary model; hence, relative persistency is weaker that persistency. Intuitively, the axioms of \(\Phi 1_{v}\) cannot further constrain the symbols to be hidden but can add new requirements on the visible symbols defined in \(S P\).

It is not difficult to see that independence entails relative persistency.

Proposition 4.3.3 If an enrichment \(\left(A_{\Phi_{1}} T_{\iota 1_{h}}\right)\) is independent w.r.t. a specification SP and a later enrichment \(\left(A_{\Phi 1_{v}} T_{\Delta 1_{v}}\right)\), then \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\) is relatively persistent w.r.t. \(\left(A_{\Phi 1_{h}} T_{\imath 1_{h}}\right)\) and \(S P\).

Proof Definitions 4.3.1 and 4.3.2 define independence and relative persistency in the context of four signature morphisms \(\iota_{E}, \iota 1_{v}, \iota 1\) and \(\iota 1_{h}\) forming a pushout
diagram as in the figure above, and sets of sentences \(\Phi 1_{k}\) over \(\Sigma 0 H 1\) and \(\Phi 1_{v}\) over \(\Sigma H 1\).

By definition of independence, for all \(A \in \operatorname{Mod}\left[\left(A_{\Phi_{1} h_{1}} T_{1_{h}}\right) S P\right]\) and \(B \in \operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\imath 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\right]\) such that \(\left.B\right|_{\iota E}=\left.A\right|_{\iota 1_{h}}\), there exists \(C \in \operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{\imath 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\right]\) such that \(\left.C\right|_{\iota 1_{v}}=A\), hence relative persistency holds.

But, independence is more than relative persistency of the visible enrichment. Consider the specifications:
```

Ex11 = sorts s
operations a,b: s
axioms a\not=b
end
Ex12 = Enrich Ex11 by
Hidden
sorts
operations h: s
axioms
in
sorts
operations v: s
axioms v=h
end

```

Here, both enrichments are persistent but the hidden enrichment fails to be independent because there exists an algebra \(\{a=1, b=2, v=1, h=2\}\) which is not a model of the overall specification ( \(E x 12\) without considering \(h\) hidden) but which can be obtained as the amalgamated union of a model of \(\operatorname{Ex} 12\{a=1, b=\)
\(2, v=1\}\) and a model of the Ex11 with the hidden enrichment \(\{a=1, b=2, h=\) \(2\}\).

Since neither relative persistency nor persistency (as in Ex12) are enough to guarantee independence, we may think that persistency is weaker than independence as relative persistency has been shown to be. However, independence of ( \(A_{\Phi 1_{h}} T_{\iota 1_{h}}\) ) w.r.t. \(S P\) and ( \(A_{\Phi 1_{v}} T_{\iota 1_{v}}\) ) does not guarantee persistency of ( \(A_{\Phi 1_{v}} T_{\iota 1_{v}}\) ) w.r.t. \(\left(A_{\Phi_{1}} T_{\iota 1_{h}}\right) S P\). Consider for example:
```

Ex21 = sorts s
operations a,b: s
axioms
end
Ex22 = Enrich Ex21 by
Hidden
sorts
operations h: s
axioms
in
sorts
operations v: s
axioms
v=a
v=b
end

```

In this case the hidden enrichment is independent: given models for \(\{s ; a, b, v\}\) and \(\{s ; a, b, h\}\) if \(v=a=b\) in the first and both agree in \(\{s ; a, b\}\) then their amalgamated union is a model of the overall specification (Ex22 without considering \(h\) hidden). But the visible enrichment is not persistent since it requires \(a=b\).

Summing up, independence and persistency are unrelated. Relative persistency is a weak notion of persistency which is necessary for independence.

\section*{Independence versus persistent functors}

It is very common to find cases like count in \(S P 1\) where the hidden part is totally defined; i.e. \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is a persistent functor over the models of \(S P\). Then independence follows automatically:

Proposition 4.3.4 Given a specification \(\left(A_{\Phi 11_{h}} T_{1_{h}}\right) S P\) such that for all \(A \in\) \(\operatorname{Mod}[S P]\) there exists exactly one (up to isomorphism) \(B \in \operatorname{Mod}\left[\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\right]\) such that \(\left.B\right|_{\iota 1_{h}}=A\), then for every enrichment \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\) and morphisms \(\iota 1\) and \(\iota_{E}\) forming a pushout diagram as in the earlier figure, \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is independent w.r.t. \(S P\) and \(\left(A_{\Phi 1 v} T_{\imath 1_{v}}\right)\).

Proof For any given model \(B\) of \(D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1 v}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\), there is (up to isomorphism) a unique \(A \in \operatorname{Mod}\left[\left(A_{\Phi_{1}} T_{1_{1}}\right) S P\right]\) such that \(\left.A\right|_{\iota_{1} h}=\left.B\right|_{\iota_{E}}\). On the other hand, by definition of \(D_{\iota 1}\) there exists a \(C \in \operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) S P\right]\) such that \(\left.C\right|_{\iota 1}=B\). Since \(\left.C\right|_{\iota 1_{h} ; 11_{v}}=\left.A\right|_{c 1_{h}}\), by the uniqueness of \(A\) we conclude that \(C\) is also an extension of \(A,\left.C\right|_{11_{v}}=A\).

The relation between persistent functors and amalgamated unions is not new. If we consider a specification language where specifications only denote isomorphic classes of models and hidden enrichments are required to be persistent functors (such as basic and parameterized specifications in the initial approach [EM 85]) the extension lemma establishes a similar connection.

\section*{Persistency in some particular cases}

If we consider models to be algebras without empty carriers and signature morphisms to be inclusions, persistency of a enrichment ( \(A_{\Phi 1_{h}} T_{\iota 1_{h}}\) ) w.r.t. \(S P\) depends exclusively on the relationship between \(S P\) and the presentation \(\Phi 1_{h}\). Hence, enrichments \(\left(A_{\emptyset} T_{\iota}\right)\) for an inclusion \(\iota\) are persistent w.r.t. any specification \(S P\) over the appropriate signature.

On the other hand, if a non-injective morphism \(\sigma\) is considered, persistency of ( \(A_{\Phi} T_{\sigma}\) ) w.r.t. \(S P\) also depends on \(\sigma\). For example, let \(s 1\) and \(s 2\) be two sorts which are mapped to the same sort \(s 12\) by an algebraic signature morphism \(\sigma\); then no model \(A \in \operatorname{Mod}[S P]\) with different carriers \(|A|_{s 1}\) and \(|A|_{s 2}\) can be extended to a model of \(T_{\sigma} S P\), or to a model of \(\left(A_{\Phi} T_{\sigma}\right) S P\) for any \(\Phi\).

Similarly, if models of \(S P\) include algebras with empty carriers, extending the signature of the specification may add constants and functions preventing some carriers from being empty, hence violating persistency.

\subsection*{4.4 Inheriting strategy - soundness}

As we noticed in section 4.1.1, some proofs of specification entailment can be carried out by importing the hidden part of the consequent into the antecedent and then proving that the visible part of the consequent follows from the enriched antecedent. The machinery introduced in the last section provides the means to formalize such a proof strategy.

The notation corresponding to task 2 is enhanced with a new pushout as in figure \(4-6\), so that signature \(\Sigma H\) combines the hidden symbols of the antecedent and the consequent.


Figure 4-6: Signature morphisms in Task 2.

Now for task 2
\[
D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
abbreviated as \(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models \Phi 1_{v}\left[\Phi 1_{h}\right] \Phi 1_{0}\), we can offer the following rule:

Theorem 4.4.1 (Inheriting strategy) Given presentations \(\Phi 1_{0}\) over \(\Sigma 0, \Phi 1_{h}\) over \(\Sigma 0 H 1, \Phi 1_{v}\) over \(\Sigma H 1\) and \(\Phi 2\) over \(\Sigma H 2\), the rule
is sound, provided the signature morphisms are arranged according to the two pushouts of figure 4-6 and \(\left(A_{\Phi 1_{h}} T_{\mathfrak{\iota 1}_{h}}\right)\) is a persistent enrichment w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\).

Proof For an inconsistent presentation \(\Phi 2\) the theorem holds trivially.

Otherwise, let \(A\) be a model of \(D_{t 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\); then there exists \(B_{2} \vDash \Phi 2\) such that \(\left.B_{2}\right|_{\iota 2}=A\), and \(C \in \operatorname{Mod}\left[\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi_{10}} \epsilon_{\Sigma 0}\right]\) such that \(\left.C\right|_{\iota 1_{h}}=\left.A\right|_{\iota_{E}} . C\) is guaranteed to exist because, by the rule's second premise \(\Phi 2 \models_{\Sigma H} \Phi 1_{0}\) so \(\left.A\right|_{\iota_{E}} \vDash \Phi 1_{0}\) and, by persistency of \(\left(A_{\Phi_{1}} T_{\iota_{1} h}\right),\left.A\right|_{\iota_{E}}\) can be extended to an algebra \(C\) as required.

Now, we consider amalgamated unions \(B_{1}=A \oplus C\) and \(G=B_{1} \oplus B_{2}\) according to the diagram at the right.

By the satisfaction condition it can be shown that \(G \models_{\Sigma H} \Phi 2 \cup \Phi 1_{h}\). Then from the rule's first premise \(G \models \Phi 1_{v}\), therefore \(\left.G\right|_{\iota_{h}^{\prime}} \in\) \(\operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{i 1_{v}}\right)\left(A_{\Phi_{1}} T_{i 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right]\) and finally \(A=\) \(\left.G\right|_{\iota 1 ; \iota 2_{h}^{\prime}} \in \operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 11_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right]\).


Persistency is a sufficient condition for the soundness of the rule but it is not necessary. That is, a correct entailment
\[
D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
may satisfy the premises of the rule and \(\left(A_{\Phi_{h}} T_{\iota 1_{h}}\right)\) not be persistent w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\).
The crucial point for considering persistency as an adequate condition has to do with the quantification it involves, i.e. which parts of which specifications are involved in the condition for soundness among \(\Phi 1_{0}, \Phi 1_{h}, \Phi 1_{v}\) and \(\Phi 2\). For example, let
\[
\begin{aligned}
& \forall \Phi 1_{0}, \Phi 1_{h}, \Phi 1_{v}, \Phi 2 . \\
& \quad \text { Condition }\left(\Phi 1_{0}, \Phi 1_{h}, \Phi 1_{v}, \Phi 2\right) \Longleftrightarrow \operatorname{Rule}\left(\Phi 1_{0}, \Phi 1_{h}, \Phi 1_{v}, \Phi 2\right)
\end{aligned}
\]
mean that Condition is a necessary and sufficient condition for soundness of the rule. In our case we have (by theorem 4.4.1 and theorem 4.4.3 below)
\[
\begin{aligned}
& \forall \Phi 1_{0}, \Phi 1_{h} . \\
& \quad \text { Persistent }\left(A_{\Phi 1_{h}} T_{1_{h}}\right) \text { wrt } A_{\Phi 1_{0}} \epsilon_{\Sigma 0} \Longleftrightarrow \forall \Phi 1_{v}, \Phi 2 . \operatorname{Rule}\left(\Phi 1_{0}, \Phi 1_{h}, \Phi 1_{v}, \Phi 2\right)
\end{aligned}
\]
which means that persistency is adequate when we look for a condition on \(\Phi 1_{0}\) and \(\Phi 1_{h}\) independently of what \(\Phi 1_{v}\) and \(\Phi 2\) might be. From a methodological point of
view, this is satisfactory since we would expect that specifications (consequents) are written before their implementations (antecedents) and that inner enrichments are written before outer ones; thus, at the time of writing the specification of the hidden part \(\Phi 1_{h}\), only \(\Phi 1_{0}\) is known.

Other sufficient conditions for soundness can be found which involve different parts of the specifications, e.g.

Proposition 4.4.2 (Inheriting strategy 2) Given presentations \(\Phi 1_{0}\) over \(\Sigma 0\), \(\Phi 1_{h}\) over \(\Sigma 0 H 1, \Phi 1_{v}\) over \(\Sigma H 1\) and \(\Phi 2\) over \(\Sigma H 2\), the rule
\[
\frac{\Phi 2, \Phi 1_{h} \vDash_{\Sigma H} \Phi 1_{v} \quad \Phi 2 \vDash_{\Sigma H} \Phi 1_{0}}{D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}}
\]
is sound, provided the signature morphisms are arranged according to the two pushouts of figure 4-6 and \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is a persistent enrichment w.r.t. \(D_{\iota E} ;{ }_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\).

Proof Looking at the proof of theorem 4.4.1 we realize that only models \(\left.A\right|_{\text {LE }}\) for \(A \in \operatorname{Mod}\left[D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\right]\) need to be extended to \(\Sigma 0 H 1\), thus persistency of \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) w.r.t. \(D_{\iota E} ; \iota 2 A_{\Phi 2} \epsilon_{\Sigma H 2}\) guarantees soundness.

This condition is weaker than persistency of \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) since it requires persistency over fewer models as \(\operatorname{Mod}\left[D_{\iota E ; \iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\right] \subseteq \operatorname{Mod}\left[A_{\Phi 1_{0}} \epsilon_{\Sigma \mathbf{0}}\right]\). It is also an analogous condition to that required in the \(\exists^{2}\)-strategy which generalizes the inheriting strategy. Nevertheless, this soundness condition asks for requirements on the antecedent (implementation side), and that may not methodologically desirable. This condition is used in the following chapters where hiding is combined with abstraction and reachability constraints; however, it is not an adequate condition to consider when designing specifications which are to appear as consequents in specification entailment proofs.

To conclude we prove, as promised above, that persistency is indeed necessary as a condition on \(\Phi 1_{0}\) and \(\Phi 1_{h}\).

Theorem 4.4.3 Given finite presentations \(\Phi 1_{0}\) over \(\Sigma 0\) and \(\Phi 1_{h}\) over \(\Sigma 0 H 1\), if the rule
\[
\frac{\Phi 2, \Phi 1_{h} \models_{\Sigma H} \Phi 1_{v} \quad \Phi 2 \models_{\Sigma H} \Phi 1_{0}}{D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}}
\]
is sound for all \(\Phi 2\) and \(\Phi 1_{v}\), then \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is persistent w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\), provided signatures and morphisms are arranged as in figure 4-6.

Proof Given a non-persistent \(\left(A_{\Phi 1_{h}} T_{11_{h}}\right)\) w.r.t. \(A_{\Phi_{10}} \epsilon_{\Sigma 0}\), there exists a model of \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) which cannot be extended to a model of \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\), hence
\[
A_{\Phi 1_{0}} \epsilon_{\Sigma 0} \not \models D_{\iota 1_{h}}\left(A_{\Phi 1_{h}} T_{\imath 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
then if we choose \(\Phi 2\) and \(\Phi 1_{v}\) such that \(\Phi 2=\left(\iota_{E} ; \iota 2\right)\left(\Phi 1_{0}\right)\) and \(\Phi 1_{v}=\emptyset\) we get
\[
D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \not \vDash=D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
while the premises of the rule hold trivially.

So far, we have presented the inheriting strategy as a rule for proving specification entailments involving consequents with a persistent hidden enrichment. Now, we shall show that the inheriting strategy is good enough for proving all correct specification entailments involving consequents with an independent hidden enrichment.

\subsection*{4.5 Inheriting strategy - completeness}

In this section we show how the inheriting strategy is sufficient for proving refinements of specifications with an independent hidden enrichment. Later the converse will be proven as well, confirming from a proof-theoretic standpoint that independence is not just intuitively reasonable but also very convenient.

Theorem 4.5.1 Given a correct entailment
\(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi_{1}} \epsilon_{\Sigma 0}\)
where \(\left(A_{\Phi_{1}} T_{\iota 1_{h}}\right)\) is independent w.r.t.
\(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) and \(\left(A_{\Phi 1_{v}} T_{\iota 1}\right)\), then it is always the case that
\(\Phi 2 \models_{\Sigma H} \Phi 1_{0}\) and \(\Phi 2, \Phi 1_{h} \models_{\Sigma H} \Phi 1_{v}\)
provided signatures and morphisms are arranged as in the figure on the right.

Proof The first entailment (1) \(\Phi 2 \models_{\Sigma H} \Phi 1_{0}\) holds from the composition of the two following entailments:
\[
\begin{aligned}
& D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \models D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0} \\
& D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0} \models T_{\iota E} A_{\Phi_{10} \epsilon_{\Sigma 0}}
\end{aligned}
\]
where the first entailment is an assumption of the lemma and the second holds trivially.

In order to prove that \(\Phi 2, \Phi 1_{h} \models_{\Sigma H} \Phi 1_{v}\), we assume the contrary (2) \(\Phi 2, \Phi 1_{h} \not \forall_{\Sigma H}\) \(\Phi 1_{v}\) and prove that the hidden enrichment cannot be independent.

By (1) and (2) there exists a \(\Sigma H\)-algebra \(G\) such that
\[
G \models_{\Sigma H} \Phi 1_{0} \cup \Phi 2 \cup \Phi 1_{h} \quad G \not \forall_{\Sigma H} \Phi 1_{v}
\]

Taking the appropriate reducts it is clear that
\[
\begin{gathered}
\left.G\right|_{\Sigma O H 1} \in \operatorname{Mod}\left[\left(A_{\Phi_{1}} T_{\iota_{1}}\right) A_{\Phi \Phi_{0}} \epsilon_{\Sigma 0}\right] \\
\left.G\right|_{\Sigma} \in \operatorname{Mod}\left[D_{\iota 2} A_{\Phi_{2} \epsilon_{\Sigma H}}\right]
\end{gathered}
\]
\[
\left.G\right|_{\Sigma H 1} \notin \operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0} \epsilon_{\Sigma 0}}\right]
\]

and since the entailment is correct we can also conclude that
\[
\left.G\right|_{\Sigma} \in \operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right]
\]

Now, taking the amalgamated union \(\left.\left.G\right|_{\Sigma O H 1} \oplus G\right|_{\Sigma}=\left.G\right|_{\Sigma H 1}\) we come to a contradiction with independence, since according to it \(\left.G\right|_{\Sigma H_{1}}\) should be a model of \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) but it is not.

With theorems 4.4 .1 and 4.5 .1 we have the basis for a sound and complete inference system for specifications with persistent and independent hidden enrichments. Moreover, we give another theorem justifying the choice of independence as an adequate property w.r.t. the completeness of the rule, just as we gave theorem 4.4.3 to justify the choice of persistency w.r.t. soundness. We start with a new definition:

Definition 4.5.2 A model \(A\) of a specification \(S P\) is abstract implementable iff there exists a flat specification \(A_{\Phi} \epsilon_{\Sigma}\) such that \(A_{\Phi} \epsilon_{\Sigma} \models S P\) and \(A \in \operatorname{Mod}\left[A_{\Phi} \epsilon_{\Sigma}\right]\).

Abstract implementability heavily depends on the expressiveness of the logical system used in specifications. In FOLEQ we cannot expect it to hold in general, but if we allow code as axioms, then all computable models are abstract implementable.

In the following theorem, the necessity of independence as a condition for completeness depends critically on the abstract implementability of one model.

Theorem 4.5.3 Given finite presentations \(\Phi 1_{0}\) over \(\Sigma 0, \Phi 1_{h}\) over \(\Sigma 0 H 1\) and \(\Phi 1_{v}\) over \(\Sigma H 1\), if \(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) implies that \(\Phi 2, \Phi 1_{h} \vDash_{\Sigma H} \Phi 1_{v}\) for all finite presentations \(\Phi 2\) over \(\Sigma H 2\), then \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is independent w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) and \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\), provided signatures and morphisms are arranged as in figure \(4-6\) and all models of \(D_{\iota 1}\left(A_{\Phi 1_{v}} T_{11_{v}}\right)\left(A_{\Phi 1_{h}} T_{11_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) are abstract implementable.

Proof Given a specification \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) such that \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) is not independent w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) and ( \(A_{\Phi 1_{v}} T_{\imath 1 v}\) ), there exist \(A\) and \(C\) such that
\[
\begin{gathered}
C \in \operatorname{Mod}\left[\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right] \quad A \in \operatorname{Mod}\left[D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right] \\
\left.A\right|_{\Sigma 0}=\left.C\right|_{\Sigma 0} \\
A \oplus C \notin \operatorname{Mod}\left[\left(A_{\Phi 1_{v}} T_{\imath 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\imath 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\right]
\end{gathered}
\]

But, if \(A\) is abstract implementable there exists a flat specification \(A_{\Phi_{A}} \epsilon_{\Sigma}\) such that
\[
A \in \operatorname{Mod}\left[A_{\Phi_{A}} \epsilon_{\Sigma}\right] \quad A_{\Phi_{A}} \epsilon_{\Sigma} \models D_{\imath 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
and by the amalgamation lemma \(A \oplus C\) must satisfy \(\Phi 1_{k}, \Phi 1_{0}\) and \(\Phi_{A}\)
\[
A \oplus C \models_{\Sigma H} \Phi 1_{h} \cup \Phi_{A}
\]
but, since \(A \oplus C\) is not a model of \(\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) we know that
\[
A \oplus C \not \forall_{\Sigma H} \Phi 1_{v}
\]
hence, \(\Phi_{A}, \Phi 1_{h} \not \models_{\Sigma H} \Phi 1_{v}\).
Finally, taking \(\Phi 2\) to be \(\iota 2\left(\Phi_{A}\right)\) we have both
\[
D_{\iota 2} A_{\Phi_{2} \epsilon_{\Sigma H 2}}=D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1 v}\right)\left(A_{\Phi 1_{h}} T_{\imath 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}
\]
and
\[
\Phi 2, \Phi 1_{k} \not \vDash_{\Sigma H} \Phi 1_{v}
\]

The fact that \(A\) might be not abstract implementable does not matter for our purpose. We are only concerned with showing that no weaker condition than independence can be required in order to obtain completeness for the rule. Then the above lemma must be understood as saying: Independence is a necessary condition for completeness, for an arbitrary logical system.

Independence is not necessary for the success of the inheriting strategy. In fact, for any consequent \(D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) where independence does not hold, there exist an antecedent \(A_{\square} \epsilon_{\Sigma}\) where \(\square\) is the contradiction, such that \(A_{\square} \epsilon_{\Sigma} \vDash D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) can be proven using the inheriting strategy.

Nevertheless, in practice, the lack of independence of \(\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right)\) w.r.t. \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) and ( \(A_{\Phi 1_{v}} T_{\iota 1_{v}}\) ) arises because some elements defined in the visible enrichment are "closely" dependent on the interpretation of the hidden elements, as in specification Ex 12 above. In such cases, each model of the visible part corresponds to only one or a few possible models of the hidden part; therefore, each visible model excludes some possible interpretations of the hidden symbols. In this situation, the models of the antecedent \(\operatorname{Mod}\left[D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\right]\), unless empty, contain a model \(A\) for which there exists a model \(C \in \operatorname{Mod}\left[\left(A_{\Phi_{1} h} T_{1_{1}}\right) A_{\Phi_{10}} \epsilon_{\Sigma 0}\right]\) such that \(\left.A\right|_{\iota_{E}}=\left.C\right|_{\iota 1_{h}}\) but \(A \oplus C \not \models_{\Sigma H} \Phi 1_{v}\) as in the proof above, hence the inheriting strategy fails.

In conclusion, although independence is not necessary from a formal point of view, it is necessary nearly always in practice.

\subsection*{4.6 Proving \(k+A S L \models D A T U\)}

The results for task 2 are good but it remains to be seen how they can be used in a more general context such as \(k+A S L \models D A T U\).

We start by relaxing the form of the antecedent specification from \(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\) to an arbitrary specification over \(k+A S L\).

\subsection*{4.6.1 Generalizing the antecedent}

Unlike specifications in DATU, it is not always clear how an arbitrary specification \(S P 2\) in \(k+A S L\) can be reduced to an equivalent specification of the form \(D_{\iota 2} A_{\Phi 2} \epsilon_{\Sigma H 2}\). Sometimes, we can expect to obtain a sound theory \(\Phi 2\) w.r.t. \(S P 2\) such that \(\Phi 2, \Phi 1_{k} \models_{\Sigma H} \Phi 1_{v}\) and \(\Phi 2 \models_{\Sigma H} \Phi 1_{0}\). Then, by soundness of the inheriting strategy (where \(\iota 2\) is the identity on \(\Sigma\) ) it follows that:
\(S P 2 \models A_{\Phi 2} \epsilon_{\Sigma} \vDash D_{\imath 1}\left(A_{\Phi 1_{v}} T_{\imath 1_{v}}\right)\left(A_{\Phi_{1}} T_{\imath 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\)

Alternatively, we can generalize the inheriting strategy so that the hidden enrichment can be inherited by \(S P 2\) leading to an enriched antecedent
\[
\left(A_{\iota 1_{v}\left(\Phi 1_{h}\right)} T_{\iota 1}\right) S P 2
\]

This generalized strategy can be presented leaving premises in the form of specification entailments, as in the \(\exists^{2}\)-strategy.


Proposition 4.6.1 Given presentations \(\Phi 1_{0}\) over \(\Sigma 0, \Phi 1_{k}\) over \(\Sigma 0 H 1, \Phi 1_{v}\) over \(\Sigma H 1\) and a specification \(S P 2\) over \(\Sigma\), the rule
\[
\left.\left.\frac{\left(A_{\iota 1}\left(\Phi 1_{h}\right)\right.}{} T_{\iota 1}\right) S P 2 \models\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0} \epsilon_{\Sigma 0}} \quad S P 2 \models D_{\iota 1}\left(A_{\iota 1_{v}\left(\Phi 1_{h}\right)} T_{\iota 1}\right) S P 2\right)
\]
is sound.

Soundness follows immediately from the soundness of the \(\exists^{2}\)-strategy. On the other hand, completeness considerations like those exhibited by the inheriting strategy in the last section are not applicable.

\subsection*{4.6.2 Generalizing the consequent}

Similarly we can generalize each component of the consequent specification so that \(D_{\iota 1}\left(A_{\Phi 1_{v}} T_{\iota 1_{v}}\right)\left(A_{\Phi 1_{h}} T_{\iota 1_{h}}\right) A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\) is substituted by a specification in \(\lambda+D A T U\) of the form
\[
D_{\imath 1} P_{v} P_{h} S P 1
\]
where parameterized specifications \(P_{v}\) for \(\left(\lambda X: \Sigma 0 H 1 . P_{v}(X)\right)\) and \(P_{h}\) for \((\lambda X\) : \(\left.\Sigma 0 . P_{h}(X)\right)\) take the place of the visible and hidden enrichment respectively, and the specification \(S P 1\) takes the place of \(A_{\Phi 1_{0}} \epsilon_{\Sigma 0}\).

Applying the \(\exists^{2}\)-strategy we obtain a rule as follows:
\[
\frac{P_{h}^{\prime} S P 2 \models P_{v} P_{h} S P 1 \quad S P 2 \models D_{\iota} P_{h}^{\prime} S P 2}{S P 2 \models D_{\iota 1} P_{v} P_{h} S P 1}
\]
where \(P_{h}^{\prime}\) for \(\left(\lambda X: \Sigma . P_{h}^{\prime}(X)\right)\) is an arbitrary parameterized specification and \(\iota^{\prime}\) is a signature morphism \(\iota^{\prime}: \operatorname{Sig}[S P 2] \rightarrow \operatorname{Sig}\left[P_{h}^{\prime} S P 2\right]\).

We can say that the inheriting strategy is being used when \(P_{h}^{\prime}\) is an "extension" of \(P_{h}\). It is not the purpose of this section to discuss in general the extensibility of parameterized specifications which has been a popular topic of discussion in the initial approach [TWW 78, EM 85, Ore 87] and also in \(A S L\) [SST 90]. Here, we
just consider that the inheriting strategy is a particular instance of the \(\exists^{2}\)-strategy where \(P_{h}^{\prime}\) is obtained by extending \(P_{h}\) from parameter specifications over \(\Sigma 0\) to parameter specifications over \(\Sigma\).

\subsection*{4.6.3 \(D A T U^{*}\) consequent}

Despite the previous generalizations it is clear that consequent will not always have a form like:
\[
D_{\imath 1} P_{v} P_{h} S P 1
\]

Among the specifications in DATU we shall distinguish those which restrict the use of \(D_{\sigma}\) to the context of persistent and independent hidden enrichment and call that sub-language \(D A T U^{*}\). fo

Using the \(\exists^{2}\)-strategy (described in section 4.2) and the rules reducing arbitrary specifications in \(D A T U\) to the form \(D_{\iota} A_{\Phi} \epsilon_{\Sigma}\) (see theorem 4.2.2) we have a complete inference system for \(D A T U \vDash D A T U\), provided \(\vdash^{\mathbf{I}}\) is sound and complete and persistency can be decided.

Nevertheless, restricting to specification entailment in \(D A T U \vDash D A T U^{*}\) has the advantage that they can be proven using the inheriting strategy instead of the \(\exists^{2}\)-strategy. This makes a very significant difference to provers which do not need to guess a convenient enrichment at each application of the \(\exists^{2}\)-strategy. Moreover, since persistency and independence of the hidden enrichment are implicitly required, \(D A T U \models D A T U^{*}\) has a complete inference system.

The _* notation will be used in other chapters below in order to require the same restrictions on the use of \(D_{\sigma}\) in \(D A T U^{*}\) in more complex specification languages such as \(A S L^{*}\) and \(k+A S L^{*}\).
- \(0^{*}\) includes only those specifications of the form (after ligation) \(\Phi l_{v}\left[\Phi l_{h}\right] \Phi 1_{0}\) with \(\Phi_{l}\) being a persistent independent hidden enrichment. this condition. DATU\& DATU* has a complete inference

\subsection*{4.7 Difficult cases}

Inheriting the hidden part from the consequent to the antecedent is a fruitful strategy in those cases where a distinguished set of axioms defines the hidden part precisely enough. Persistency and independence ensure that. Nevertheless, when these side conditions are not satisfied we are driven into a more general strategy such as the \(\exists^{2}\)-strategy.

In this section some guidance is given for those cases where the consequent has the form
\[
D_{\imath 1} P_{v} P_{h} S P 1
\]
but either persistency of \(P_{h}\) w.r.t. \(S P 1\) or independence of \(P_{h}\) w.r.t. \(S P 1\) and \(P_{v}\) fail.

\subsection*{4.7.1 Failing independence}

Many times independence fails in specifications with a persistent hidden part. This is normally the case for specifications whose auxiliary functions or sorts are not defined with enough detail. We may not bother defining very precisely an auxiliary function because for each of its possible realizations there are some valid models of the visible part. However, this leads to a failure of independence. Consider for example, the specification of a scheduling function as in figure \(4-7\).

Although scheduler seems to be hidden, the function next gives some information about which choice of the function has been assumed. This dependency of a visible function on a hidden function which is not completely defined prevents the hidden enrichment from being independent.
```

Schdler = Enrich ListNat by
Hidden
sorts
operations
scheduler: listnat -> listnat
axioms
{ Axioms requiring 'scheduler' to deliver
some arbitrary permutation of the parameter. }
in
sorts
operations
next: listnat -> nat
axioms
\forall l:listnat. next(1)=car(scheduler(1))
end

```

Figure 4-7: Specification of a scheduler

If scheduler were completely defined as being, for example, a function to sort a list in descending order then the hidden enrichment would become independent automatically (see proposition 4.3.4).

On the other hand, if next is a less completely defined function, independence can hold without changing scheduler. For example, suppose the only requirement on next (1) is to yield a value of the list scheduler (1):
```

|:listnat. next(l) E scheduler(l) = true .

```

Now, the hidden enrichment is independent because no realization of next excludes a possible behaviour of scheduler.

Using the \(\exists^{2}\)-strategy amounts to requiring the completion of the definition of the hidden part as far as needed to attain independence.

Consider an antecedent SP2 where next produces the maximum of the list. The entailment \(S P 2 \vDash\) Schdler cannot be proven correct by the inheriting strategy. The lack of independence means that we are not inheriting enough axioms to complete the proof.

The \(\exists^{2}\)-strategy can be seen as a procedure which forces the prover to complete the definition of the hidden part as far as necessary to complete the proof. For example, choosing \(\Phi\) in the \(\exists^{2}\)-strategy to be the definition of scheduler as a sorting function in descending order would suffice. In general \(\Phi\) can be chosen to be \(\Phi 1_{h}\) - as in the inheriting strategy - plus some extra axioms completing the definition of the hidden symbols.

In consequence, we can say that the hidden symbols can be used in the visible part insofar as they are adequately defined. If some hidden symbols are inadequately defined w.r.t. how they are used, the hidden enrichment lacks independence and the definition of the hidden symbols generally needs to be completed
during the proof of correctness (see discussion at the end of section 4.5 about independence being generally needed for the success of the inheriting strategy).

\subsection*{4.7.2 Failing persistency}

Non-persistent hidden parts are a more serious problem although not so frequent in practice.

A non-persistent hidden part cannot be inherited to the antecedent because this could cause some of the antecedent's models to be excluded from consideration in the proof, leading to a situation where an incorrect entailment is proven correct.

Non-persistent hidden enrichments can be considered errors in the sense that the existence of some auxiliary functions and sorts should be transparent to the rest of the specification.

Applying the \(\exists^{2}\)-strategy amounts to asking for a new persistent definition, \(\Phi\), of the hidden part. In other words, such a strategy is equivalent to going back to the specification, writing a correct (persistent) definition, \(\Phi\), of the hidden part, leaving the old \(\Phi 1_{h}\) as additional requirements on the visible part - added to \(\Phi 1_{v}\) or \(\Phi 1_{0}\) - and starting the proof of correctness according to the inheriting strategy.

\section*{Chapter 5}

\section*{Abstracted specifications}

\subsection*{5.1 Introduction}

In this chapter we are concerned with specifications using abstraction and behavioural abstraction. Unlike the other SBO's in \(A S L\), the definition of abstract has been controversial (c.f. [SW 83, ST 87]) as has also been the general notion of abstraction in the field of algebraic specifications (c.f. [GGM 76, Rei 87, MG 85, NO 88]) and its relationship to the notion of abstract implementation (c.f. [Hoa 72, Ehr 81, EKMP 82, BBC 86]).

Since early work in [GGM 76], the interpretation of an abstract data type as an algebra (abstracted) up to isomorphism has been seriously debated. The problem is essentially linked to the distinction between observable and non-observable sorts.

If all sorts are observable then abstraction up to isomorphism is appropriate in the sense that it fully captures the idea of a system seen as a black box. The sorts of the algebra represent the different kinds of input/output values while the functions (their graphs) represent the relation of the input to the output.

However, algebras, when denoting data types, contain at least one sort representing the values of the data type in question (distinguished phylum in [GH 78]). The values of this data type are, in general, abstract entities which do not correspond to any kind of input/output value (observable value for short), e.g. states
in an automaton. Abstraction w.r.t. isomorphism only admits as models of a data type algebras with isomorphic carriers. So, in the case of the specification of an automaton which recognizes a particular language, automata with different configurations of states cannot be models of the same specification, even if they recognize the same language.

In order to bring into algebraic specification an idea similar to equivalence of automata, the notion of behaviour of an algebra w.r.t. some observable sorts has been defined (among others in [GGM 76, MG 85]). Then, two algebras are behaviourally equivalent if they have the same behaviour \({ }^{1}\), that is if they agree on all computations from observable sorts to observable sorts. Applying behavioural abstraction to a specification closes its class of models with respect to behavioural equivalence.

Behavioural abstraction can be generalized to non-algebraic institutions by explicitly indicating those sentences which are observable, as does abstract in [ST 87, ST 88a]. Then, behavioural abstraction becomes the particular case in which the observable sentences are all the equations between terms of observable sorts.

In this chapter we shall propose a new account for abstraction and in particular behavioural abstraction according to the following informal requirements.
1. Abstraction should be defined as an institution-independent operation, like the other SBO's in ASL.

\footnotetext{
\({ }^{1}\) Most frequently, behavioural equivalence is defined without an explicit definition of behaviour.
}
2. Behavioural abstraction should be a particular instance of abstraction for the case in which models are algebras and observations are defined in terms of observable sorts.
3. The user should be able to decide if a sort is observable or not when defining a specification. Moreover, any specification can be further abstracted, whenever it is used in a bigger context, for example by turning some observable sorts into non-observable sorts.
4. Abstraction in \(A S L\) should be related to \(D_{\sigma}\) since both operations "hide", in an informal sense, some details of a specification which do not need to be implemented.

This is realized by considering an institution morphism from the original institution to another abstracted institution where \(T_{\sigma} D_{\sigma}\) happens to mean abstraction in some cases or exactly what it meant in the original institution in others.

But before giving details of this approach, some others are surveyed showing which of the above requirements are not satisfied.

\section*{Historical survey}

Without pretending to be exhaustive, a few approaches are sketched trying to capture the range of alternatives among specification languages with tight or loose semantics, and among the latter distinguishing those with a notion of institution from the rest.

Probably the simplest way to deal with behavioural abstraction is to ignore it, considering specifications to denote isomorphic classes of algebras and proposing a relation of abstract implementation as in [GTW 76, EKMP 82, Ehr 81]. In this
case, those models which are behaviourally equivalent to a model of the specification without being isomorphic to it, are expected to be valid implementations. For example, many algebras which fail to be models of a specification are among the valid implementations because there exists a homomorphism from them to a model of the specification (quotient step in [EKMP 82, Ehr 81]).

Often abstract implementation are such that by considering an appropriate restriction of the signature, taking a subalgebra and performing a quotient \({ }^{2}\), any valid implementation can be turned into a model isomorphic to the initial model of the specification. Therefore, as in [Hoa 72], a value can be represented by several values in the implementation but never the other way round. In an example such as the automaton specification referred above, if it is the case that the automaton denoted by the initial model of the specification (up to isomorphism) is not minimal then some behaviourally equivalent models will not be valid implementations. Hence, this approach fails the second requirement.

Some other approaches genuinely concerned with behaviour and still faithful to initial semantics have been developed [Rei 81, Rei 87, MG 85, NO 88].

Reichel's work explicitly introduces abstraction via canons of behaviour. Essentially, two algebras are behaviourally equivalent if they have a common quotient via congruences which leave their observable carriers untouched. This definition takes good care of specifications such as the automaton example above, but junk in non-observable sorts must be preserved in the implementation. Hence the second requirement does not hold.

In [MG 85] a definition for behaviour of an algebra is presented as a new algebra whose operations are the observations of the former one, i.e. those sequences of

\footnotetext{
\({ }^{2} \mathrm{~A}\) subalgebra must be chosen before taking the quotient. Reversing the order of the operations results in a weaker notion of implementation [EKMP 82].
}
old operations computing observable values from observable values (a new concise categorical definition will be given below). Behavioural abstraction is obtained by including as models of an abstracted specification all algebras having the same behaviour. In [Niv 87, NO 88] a similar setup is defined by changing the notion of homomorphism in such a way that isomorphism means behavioural equivalence. Both works lead to the same notion of behaviour and make it compatible with initiality. Nivela's work goes further, taking into account the most common constructions related to initial semantics, but what we consider more relevant is that in her approach behaviour is a concept embedded into a new institution instead of being defined separately. These approaches fail in the first requirement since their notions of behaviour are intimately linked to EQ (the standard institution of total algebras and equational logic).

Another way to avoid the problems posed by the initial approach of [GTW 76] is to consider the model designated by a specification to be not the initial one but the final one [GGM 76, \(\operatorname{Kam} 83\), Wan 79]. In this way a notion of implementation based on homomorphism will succeed in examples such as the automaton specification mentioned above since the final model is precisely the minimal automaton recognizing the required language. However, apart from technical problems related to the existence of final models, this approach violates the third requirement since there is no explicit way to apply or not to apply finality.

Specification languages with loose semantics fit more comfortably with the problem of defining behaviour. Since the models of a specification do not need to be isomorphic, one possibility is to change the definition of satisfaction for equations between non-observable values to mean equivalence w.r.t. all visible contexts; hence, the equality symbol means indistinguishability (see for instance [Hen 88 , Gog 90]). Problems with behaviour and loose semantics usually appear when look-
ing at proof techniques or when trying to generalize the idea of abstraction to an arbitrary institution.

First, we consider cases such as [WB 89] where equality is treated as in standard first order logic. Following [Men 71], equality is an ordinary predicate symbol satisfying some extra axioms, namely, reflexivity, transitivity, symmetry and extensionality w.r.t. any well-formed formula. Normal models are those in which the equality symbol is interpreted as identity, but other models are possible. In [WB 89] multi-sorted first order logic with equality is used in this way, so that for many specifications their class of models is automatically closed up to behavioural equivalence. The advantages are proof-theoretical but from the point of view of abstraction this approach fails the third requirement since the user cannot decide in which sorts equality should mean identity, and it fails the second requirement as well since no model of an specification with an inequality \(a \neq b\) can give the same value to \(a\) and \(b\), even if \(a\) and \(b\) belong to a non-observable sort.

Other approaches making an explicit distinction between observable and nonobservable sorts when using equations lead to [Gog 90] where this is concisely presented as a new institution for behaviour. The only inconvenience is its commitment to EQ which makes the first requirement fail.

Heading towards a more general definition of behaviour, [SW 83], [Wir 86] and [ST 87] propose to consider observable terms and observable sentences as an alternative to observable sorts. [Wir 86] accompanies generality with some proof theoretical results but only [ST 87] presents a institution independent definition: Observational abstraction. An approach based on an observability predicate Obs() such as [Wir 86] does not satisfy our third requirement properly since a given specification cannot be further abstracted later by any means, contrary to what an abstraction operation in [ST 87], a closure as proposed below, the parameter passing mechanism in [Gog 90] or even a Non-Obs() assertion can do.

An abstract obs operation as in [ST 87] defines abstraction w.r.t. an arbitrary
set of sentences Obs called observations. Models of an abstracted specification abstract obs \(S P\) include all those models over \(\operatorname{Sig}[S P]\) which satisfy the same observations as a model of \(S P\). In particular, observable sorts can be defined in terms of observations by including enough sentences in \(O b s\) so that the carrier of an observable sort is completely determined up to isomorphism. This approach satisfies our requirements except for the last one. Unfortunately, this new operation does not relate (observational) abstraction to \(D_{\sigma}\), the other abstraction mechanism in ASL.

In our proposal we aim to preserve the good properties of abstract but shifting the general problem of abstraction from the specification language into the underlying institution as in [NO 88] and [Gog 90], so that abstract becomes a derived operation: a particular instance of \(T_{\sigma} D_{\sigma}\).

\section*{Proof techniques}

Despite the multitude of approaches to behavioural abstraction, the available proof techniques for proving behavioural equivalence are essentially two: explicit definition of congruences and proving agreement on all observations.

Consider for example the classic implementation of a stack by an array and a pointer. The axiom
\[
\forall \text { S:stack; x:elem. pop }(\text { push }(x, S))=S
\]
is not satisfied in the implementation as such. The first proof technique suggests to formalize the appropriate congruence on array-pointer pairs which corresponds to stack equality, e.g. all arrays with the same pointer which agree in the values of the array for indexes below the pointer are considered equal (see for example [Wan 82, WB 89]). The second proof technique substitutes the problematic axiom by its infinite set of observable consequences, i.e.
```

\forall S:stack; x:elem. top(pop(push(x,S))) = top(S)
\forall S:stack; x:elem. top(push(y,pop(push(x,S)))) = top(push(y,S))

```
and proves that all these hold in the implementation. By considering the recursive definition of observation, an induction schema can be used (see context induction in [Hen 88]).

All the approaches to behavioural abstraction can be classified depending on which proof technique they use, if any.

Model theoretical notions of implementation such as in [Hoa 72] and behavioural inclusion such as that in [Sch 87] (page 223) consider, by definition, that an abstract implementation must satisfy the (infinite) set of observable theorems of the specification. However, the main result of such approaches is precisely showing that an appropriate kind of congruence characterizes all such implementations. Hence, the latter method is normally used in the proofs.

For example, given a notion of observation such as equalities between closed terms of observable sorts, we obtain a notion of behavioural equivalence between algebras, i.e. two algebras are behaviorally equivalent if they satisfy the same observations. Then, a model-theoretical construction between algebras, e.g. correspondences in [Sch 87] and abstraction functions in [Hoa 72], is proposed in such a way that if the construction can be done between two algebras then they will be behaviourally equivalent. Defining an abstraction function amounts to using a congruence, e.g. in the case of stacks, all arrays with equal values below the pointer are mapped to the same abstract stack. Then, these characterizations can be understood as a proof of soundness of a technique such as the construction of an abstraction function (or correspondence).

Algebraic specification approaches such as [Ehr 81, EKMP 82] do not use an explicit notion of abstraction, but a notion of implementation which embeds it (see historical survey above). In this case a quotient step is included in the implementation notion. This quotient involves a congruence relating those values of the implementation which represent the same abstract value. Hence these approaches use explicit definition of congruences.

Also some loose approaches justify the use of congruences taking a first order interpretation of equality, e.g. [Wan 82, WB 89].

In contrast, those approaches taking definitions of abstraction in terms of observations or observable sorts without exploring any further, are committed to proving that antecedent and consequent agree on all observations. Therefore, notions of abstraction such as in [NO 88, MG 85, Gog 90] support, by default, proving agreement on all observations. We have also in this group: [ST 87] which gives an explicit rule for abstract, [Wir 86] which extends the calculus of equational implications with some explicit rules for handling the Obs() predicate, [Hen 88] which provides context induction to deal with an infinite number of observations and [Lin 87] which uses proofs by consistency.

In this chapter, since abstraction is treated as a particular meaning for \(T_{\sigma} D_{\sigma}\) we shall revisit the proof techniques for hiding presented in the last chapter, which give rise to the two well-known proof techniques just surveyed.

\subsection*{5.2 Abstractions}

At a very general level, we view the abstraction operation in \(A S L\) as \(T_{\sigma} D_{\sigma}\) in an abstracted institution. In this sense, the abstracted institution is the enrichment of an (original) institution by some new signatures and signature morphisms and the corresponding models and sentences. This extra structure corresponds, intuitively, to abstract models (behaviours), abstract signatures (behaviour signatures) and observations.

Imagine the case of the institution for equational logic \(\mathbf{E Q}\). We can define a new institution \(\operatorname{Beh}(E Q)\) where signatures are either standard algebraic signatures such as \(\langle S, \Omega\rangle\) or abstracted signatures containing an explicit set of observable sorts, e.g. \(\langle\langle S, \Omega\rangle, O\rangle\) where \(O \subseteq S\), as is standard in behavioural abstraction. Models over the abstracted signatures are behaviours as defined in [MG 85] instead of algebras, and the reduct functor - \(l_{0}\) for a signature morphism \(o:\langle\langle S, \Omega\rangle, O\rangle \rightarrow\langle S, \Omega\rangle\) maps each \(\langle S, \Omega\rangle\)-algebra to its behaviour. Sentences over an abstracted signature are those sentences of the original institution which cannot distinguish between two algebras with the same behaviour. The result is an abstracting institution morphism \(\alpha: \mathbf{E Q} \rightarrow \operatorname{Beh}(\mathbf{E Q})\) from the original institution EQ to the abstracted institution Beh(EQ).

The abstraction operation in \(A S L\) is \(T_{o} D_{o}\). Therefore, the essence of abstraction is the reduct functor \(\mathrm{H}_{0}\) which maps to the same behaviour - model of \(\operatorname{Mod}(\langle\langle S, \Omega\rangle, O\rangle)\) - all those algebras in \(\operatorname{Alg}(\langle S, \Omega\rangle)\) which are behaviourally equivalent. Thus, \(T_{0} D_{0}\) performs the closure of the models of a specification \(S P\) over \(\langle S, \Omega\rangle\) w.r.t. behavioural equivalence.
\[
\operatorname{Mod}\left[T_{o} D_{o} S P\right]=\left\{A \in \operatorname{Alg}(\langle S, \Omega\rangle)|A|_{o}=\left.B\right|_{o} \text { and } B \in \operatorname{Mod}[S P]\right\}
\]

In the following sections we shall study some abstracted institutions and how proof techniques for \(T\) and \(D\) can be used in \(\alpha+A S L \vDash \alpha+A S L\), but first we shall devote some time to a general definition of abstraction.

Definition 5.2.1 Given two institutions,
\[
\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle \quad \alpha \mathbf{I}=\left\langle\alpha S I G, \alpha M o d, \alpha S e n, \models^{\alpha}\right\rangle
\]
and an institution morphism \(\left\langle\alpha_{S I G}, \alpha_{M o d}, \alpha_{S e n}\right\rangle\),
\[
\begin{aligned}
& \alpha_{S I G}: S I G \rightarrow \alpha S I G \\
& \alpha_{M o d}: M o d^{o p} \Rightarrow \alpha_{S I G}^{o p} ; \alpha M o d^{o p} \\
& \alpha_{S e n}: \alpha_{S I G} ; \alpha S e n \Rightarrow S e n
\end{aligned}
\]
then \(\alpha \mathrm{I}\) is an abstracted institution w.r.t. the original institution I if \(\alpha_{S I G}\) is a full and faithful functor (i.e. there exists a full subcategory of \(\alpha S I G\) isomorphic to \(S I G\) in Cat) and there exists a functor \(C: \alpha S I G \rightarrow S I G\) and natural transformations \(\mathrm{i}: \alpha_{S I G} ; C \Rightarrow I d_{S I G}\) and \(\mathrm{o}: I d_{\alpha S I G} \Rightarrow C ; \alpha_{S I G}\) forming an adjunction \(\left\langle C, \alpha_{S I G}, \mathbf{o}, \mathbf{i}\right\rangle\).

Morphisms such as \(\left\langle\alpha_{S I G}, \alpha_{M o d}, \alpha_{S e n}\right\rangle\) are then called abstracting institution morphisms.

Functor \(\alpha_{S I G}\) maps the original signatures and signature morphisms in \(S I G\) to their corresponding signatures and signature morphisms in the full subcategory of \(\alpha S I G\) isomorphic to \(S I G\); functor \(C\) yields the original signature (signature morphism) corresponding to each abstract signature (signature morphism) \({ }^{3}\); natural transformation i gives for each original signature \(\Sigma\) a morphism \(i_{\Sigma}: C\left(\alpha_{S I G}(\Sigma)\right) \rightarrow\)

\footnotetext{
\({ }^{3}\) The name \(C\) is chosen to mean concrete, as opposite to abstract.
}
\(\Sigma\); and natural transformation o gives for each signature \(\Pi\) in the abstracted institution a morphism \(o_{\Pi}: \Pi \rightarrow \alpha_{S I G}(C(\Pi))\), that is, if \(\alpha_{S I G}\) is an inclusion, \(o_{\Pi}\) is a morphism from \(\Pi\) to its corresponding original signature.

A few facts follow directly from the definition (see [Mac 71]).

Fact 5.2.2 Given an arbitrary abstracting institution morphism
\[
\left\langle\alpha_{S I G}, \alpha_{M o d}, \alpha_{S e n}\right\rangle: \mathbf{I} \rightarrow \alpha \mathbf{I}
\]
with adjunction \(\left\langle C, \alpha_{S I G}, \mathbf{o}, \mathbf{i}\right\rangle\), then
1. for every signature \(\Sigma\) in \(S I G, \Sigma \cong C\left(\alpha_{S I G}(\Sigma)\right), \quad(\) see \([\operatorname{Mac} 71]\) page 88\()\)
2. \(C\) preserves colimits,
3. \(\alpha_{\text {SIG }}\) preserves limits,
4. for all \(\Sigma \in|S I G|\), all morphisms \(h: \Pi \rightarrow \alpha_{S I G}(\Sigma)\) in \(\alpha S I G\) can be uniquely decomposed into \(h=o_{\Pi} ; \alpha_{S I G}(\sigma)\) where \(\sigma: C(\Pi) \rightarrow \Sigma\) is a morphism in SIG and \(o_{\Pi}: \Pi \rightarrow \alpha_{S I G}(C(\Pi))\) is the unit for \(\Pi\).

In practice, \(S I G\) can be chosen to be a full subcategory of \(\alpha S I G\) so that \(\left\langle C, \alpha_{S I G}, \mathbf{o}\right\rangle\) is a reflection. Then, \(\Sigma\) can be thought of as identical to \(C\left(\alpha_{S I G}(\Sigma)\right)\) and \(\alpha_{S I G}(\Sigma)\); morphisms \(i_{\Sigma}: C\left(\alpha_{S I G}(\Sigma)\right) \rightarrow \Sigma\) as identity morphisms \(i d_{\Sigma}\) in \(S I G\), and morphisms \(o_{\Pi}: \Pi \rightarrow \alpha_{S I G}(C(\Pi))\) as morphisms in \(\alpha S I G\) mapping an arbitrary \(\Pi\) to its corresponding original signature \(C(\Pi)\), e.g. for \(C(\Pi)=\Sigma, o_{\Pi}: \Pi \rightarrow \Sigma\) in \(\alpha S I G\).

Notational conventions The original institution is denoted by I and the abstracted institution by \(\alpha \mathbf{I}\) as in the definition. The unit of \(C\) is usually denoted by \(o\) and unit morphisms \(o_{\Pi}\) are called abstraction morphisms. Functor \(\alpha_{S I G}\) and
the morphisms \(i_{\Sigma}\), corresponding to the counit \(i\), will be systematically dropped since they can be cancelled to the left and to the right, in other words we shall proceed as if (as is frequent in practice) \(\Sigma=\alpha_{S I G}(\Sigma)=C\left(\alpha_{S I G}(\Sigma)\right.\) ) and \(i_{\Sigma}=i d_{\Sigma}\). The symbol \(\Sigma\) will be reserved to denote objects of \(S I G\) (original signatures) and \(\Pi\) for arbitrary or proper objects of \(\alpha S I G\) (abstracted signatures).

This definition of abstraction allows to view some known institutions as abstracted institutions, e.g. the institution of first order logic in section 5.4 .2 below. However, we normally think of the abstracted institution as an enrichment of a given original one. The following section formalizes this construction.

\subsection*{5.2.1 Quotient abstracted institutions}

Following [ST 87], an abstraction operation on a specification \(S P\) over \(\Sigma\) yields another specification \(\alpha_{\equiv} S P\) over the same signature whose models are the closure of the original class of models w.r.t. a given signature-sorted equivalence relation \(\equiv\) among the models \({ }^{4}\). For each \(\Sigma\)-specification \(S P\)
\[
\operatorname{Mod}\left[\alpha_{\equiv} S P\right]=\left\{A \in|\operatorname{Mod}(\Sigma)| \mid A \equiv_{\Sigma} B, B \in \operatorname{Mod}[S P]\right\}
\]

Keeping this general idea in mind we define the following enrichment to a given institution.

Definition 5.2.3 Given an institution \(\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle\), and the following:

\footnotetext{
\({ }^{4}\) In \([\) ST 87\(] \equiv\) is not sorted by the signatures, but this difference is not important.
}
1. A category \(\alpha S I G\) with a full inclusion \({ }^{5} \alpha_{\text {SIG }}: S I G \rightarrow \alpha S I G\).
2. A reflection \(\left\langle C, \alpha_{S I G}, \mathbf{o}\right\rangle\) with \(C: \alpha S I G \rightarrow S I G\) and \(\mathbf{o}: I d_{\alpha S I G} \Rightarrow C ; \alpha_{S I G}\).
3. An \(|\alpha S I G|\)-sorted equivalence relation \(\equiv\) among the models of \(\mathbf{I}\) such that \(\equiv п \subseteq|\operatorname{Mod}(C(\Pi))| \times|\operatorname{Mod}(C(\Pi))|\) for all \(\Pi \in|\alpha S I G|\).
\(\forall A, B \in|\operatorname{Mod}(C(\pi 2))| .\left.\left.~ A \equiv \equiv_{\pi 2} B \Rightarrow A\right|_{C(h)} \equiv_{\pi 1} B\right|_{C(h)}\) for all \(h: \pi \mid \rightarrow \pi 2\) in \(\alpha S\)
4. An \(|\alpha S I G|\)-sorted set \(O b s\) of sentences in I such that \(O b s_{\Pi} \subseteq \operatorname{Sen}(C(\Pi))\) for all \(\Pi \in|\alpha S I G|\).
\(\forall \varphi \in \operatorname{sen}(C(\pi 1)) . \quad \varphi \in O b s_{\pi 1} \Rightarrow C(h)(\varphi) \in O b s_{\pi 2} \quad\) for all \(h_{1}: \pi 1 \rightarrow \pi 2\) in \(\alpha S\) Functor \(\alpha\) Mod \(: \alpha S I G \rightarrow\) Cat \(^{\circ p}\) and \(\alpha\) Sen \(: \alpha S I G \rightarrow\) Set, and a relation \(\vDash_{\Pi}^{\alpha} \in\) \(|\alpha \operatorname{Mod}(\Pi)| \times \alpha S e n(\Pi)\) for each \(\Pi \in|\alpha S I G|\) are defined as follows \({ }^{6}\) :
- \(\alpha \operatorname{Mod}(\Sigma)=\operatorname{Mod}(\Sigma)\) if \(\Sigma\) is one of the original signatures. Otherwise, \(\alpha \operatorname{Mod}(\Pi)=\operatorname{Mod}(C(\Pi)) / \equiv_{\Pi}\).
\(\alpha \operatorname{Mod}(\sigma)=\operatorname{Mod}(\sigma)\) if \(\sigma\) is one of the original signature morphisms. For every unit morphism \(o_{\Pi}: \Pi \rightarrow C(\Pi)\) in \(\alpha S I G, \alpha \operatorname{Mod}\left(o_{\Pi}\right)\) is a mapping from every model \(M\) in \(\operatorname{Mod}(\Sigma)\) to its equivalence class \([M]\) in \(\operatorname{Mod}(\Sigma) / \equiv_{\Pi}\), also written \(\left.M\right|_{o_{\Pi}}\).
- \(\alpha \operatorname{Sen}(\Sigma)=\operatorname{Sen}(\Sigma)\) if \(\Sigma\) is one of the original signatures. Otherwise, \(\alpha \operatorname{Sen}(\Pi)=\) \(O b s_{\Pi}\).
\(\alpha \operatorname{Sen}(\sigma)=\operatorname{Sen}(\sigma)\) if \(\sigma\) is one of the original signature morphisms. For every unit morphism \(o_{\Pi}: \Pi \rightarrow C(\Pi)\) in \(\alpha S I G, \alpha \operatorname{Sen}\left(o_{\Pi}\right)\) is an inclusion from \(O s_{\Pi}\) into \(\operatorname{Sen}(\Sigma)\), usually called \(o_{\Pi}\) as well.

\footnotetext{
\({ }^{5}\) Functor \(\alpha_{S I G}\) is defined to be a full inclusion instead of an arbitrary faithful and full functor in order not to overload the notation.
}
\({ }^{6}\) Proof that these functors are well-defined is included in the following proposition. he category of models over a signature is considered discrete.
- \(\models_{\Sigma}^{\alpha}=\models_{\Sigma}\) if \(\Sigma\) is one of the original signatures. Otherwise, \(M \models_{\Pi}^{\alpha} \varphi\) ff for all \(A \in M, A \models_{C(\Pi)} \varphi\) in \(\mathbf{I}\).

If \(\left\langle\alpha S I G, \alpha M o d, \alpha S e n, \models^{\alpha}\right\rangle\) satisfies the satisfaction condition then it is called a quotient abstracted institution of I, denoted by \(\alpha \alpha_{\overline{\bar{O}}}^{\underline{\prime}} \mathbf{s}\).


In the above definition \(\alpha M o d\) and \(\alpha S e n\) are only defined on the objects of \(\alpha S I G\), the original morphisms and the unit morphisms. The following proposition shows that to be enough.

Proposition 5.2.4 Given a situation as in the previous definition, \(\alpha\) Mod and \(\alpha S e n\) are well-defined functors over all morphisms in \(\alpha S I G\).

Proof In their definition \(\alpha M o d\) and \(\alpha S e n\) are explicitly defined over all objects, original morphisms and unit morphisms in \(\alpha S I G\). Now, we must prove that they are implicitly defined for an arbitrary orphism \(h: \Pi 1 \rightarrow \Pi 2\) in \(\alpha S I G\).

Since \(\left\langle C, \alpha_{S I G}, o\right\rangle\) is a reflection, the unit morphisms \(o_{\Pi 1}\) and \(o_{\Pi 2}\) make the following diagram commute in \(\alpha S I G\).
ions on \(O b\) and \(\equiv\) allow \(\alpha\) Mod and \(\alpha \operatorname{Sen}\) defined over \(h: \pi 1 \rightarrow \pi 2\) a \(\operatorname{Mod}(h)([A] \equiv \pi 2)=[A \mid c(h)] \equiv \pi l \quad\), for all \(A \in|\operatorname{Mod}(C(\pi 2))|\) \(\alpha \operatorname{Sen}(h)(\varphi)=\operatorname{Sen}(C(h))(\varphi)\), for all \(\varphi \in O b s \pi 1\)
functors. In the following we prove their uniqueness.


Consider two possible functors \(\alpha \operatorname{Mod}_{1}\) and \(\alpha \mathrm{Mod}_{2}\) which satisfy the requirements given for \(\alpha\) Mod.

For all unit morphisms \(o_{\Pi}\) we know that \(\alpha M o d_{1}\) and \(\alpha M o d_{2}\) agree and since they are functors

we have that
\[
-\left.\right|_{o_{2} 2} ; \alpha M o d_{1}(h)=-\left.\right|_{o_{12}} ; \alpha M o d_{2}(h)
\]

And finally, since \(-\left.\right|_{o^{\prime} 2}\) is a surjective mapping onto \(\alpha \operatorname{Mod}(\Pi 2)\) and therefore epi and left-cancellable, the equation is reduced to
\[
\alpha \operatorname{Mod}_{1}(h)=\alpha M o d_{2}(h)
\]
hence \(\alpha M o d\) is well-defined.

The same reasoning applies to \(\alpha S e n\) with the difference that the inclusions \(\alpha \operatorname{Sen}\left(o_{\Pi}\right): \operatorname{Sen}(C(\Pi)) \hookleftarrow \alpha \operatorname{Sen}(\Pi)\) go in the opposite direction and they are not epi but mono.

Since \(\alpha M o d\) and \(\alpha S e n\) are guaranteed to be well-defined we only need a condition between \(\equiv\) and \(O b s\) characterizing when \(\left\langle\alpha \operatorname{Sig}, \alpha M o d, \alpha S e n, \models^{\alpha}\right\rangle\) is indeed a quotient abstracted institution.

Theorem 5.2.5 Given a situation as in the previous definition
\[
\left\langle\alpha S i g, \alpha M o d, \alpha S e n, \models^{\alpha}\right\rangle
\]
satisfies the satisfaction condition iff for all signatures \(\Pi\) in \(\alpha S I G\), models \(A, B \in\) \(|\operatorname{Mod}(C(\Pi))|\) and sentences \(\varphi \in \alpha \operatorname{Sen}(\Pi)\),
\[
A \equiv_{\Pi} B \quad \Rightarrow \quad\left(A \models_{C(\Pi)} \varphi \Leftrightarrow B \models_{c(\Pi)} \varphi\right)
\]

Proof Assuming the satisfaction condition to hold and considering an abstraction morphism \(o_{\Pi}: \Pi \rightarrow \Sigma\) in \(\alpha S I G\), i.e. \(C(\Pi)=\Sigma\), we have that for all \(\varphi \in \alpha \operatorname{Sen}(\Pi)\) (implicitly \(o_{\Pi}(\varphi)=\varphi \in \operatorname{Sen}(\Sigma)\) )
\[
\forall A \in \operatorname{Mod}(\Sigma) \cdot\left(\left.A\right|_{o_{\Pi}} \models_{\Pi}^{\alpha} \varphi \Leftrightarrow A \models_{\Sigma} \varphi\right)
\]

Since \(-\left.\right|_{o_{\text {II }}}\) maps \(A\) to its equivalence class \([A]_{\equiv_{\Pi}} \in \operatorname{Mod}(\Sigma) / \equiv_{\Pi}\), by definition of \(\vDash{ }_{\Pi}^{\alpha}\) this can be rewritten as
\[
\forall A \in \operatorname{Mod}(\Sigma) \cdot\left(\left(\forall B \in[A]_{\Xi_{\mathrm{\Pi}}} \cdot B \models_{\Sigma} \varphi\right) \Leftrightarrow A \models_{\Sigma} \varphi\right)
\]

Taking the implication from right to left we can produce the following sequence of equivalences
\(\forall A \in \operatorname{Mod}(\Sigma) .\left(\left(\forall B \in[A]_{\equiv_{\Pi}} . B \vDash_{\Sigma} \varphi\right) \Leftarrow A \models_{\Sigma} \varphi\right)\)
\(\Longleftrightarrow \forall A \in \operatorname{Mod}(\Sigma) .\left(\forall B \in[A]_{\equiv_{\mathrm{I}}} . B \models_{\Sigma} \varphi\right) \vee\left(A \not \models_{\Sigma} \varphi\right)\)
\(\Longleftrightarrow \forall A \in \operatorname{Mod}(\Sigma) .\left(\forall B \in \operatorname{Mod}(\Sigma) .\left(A \equiv_{\Pi} B \Rightarrow B \models_{\Sigma} \varphi\right)\right) \vee\left(A \not \vDash_{\Sigma} \varphi\right)\)
\(\Longleftrightarrow \forall A \in \operatorname{Mod}(\Sigma) .\left(\forall B \in \operatorname{Mod}(\Sigma) .\left(A \not \equiv \exists_{\Pi} B\right) \vee\left(B \models_{\Sigma} \varphi\right)\right) \vee\left(A \not \vDash_{\Sigma} \varphi\right)\)
\(\Longleftrightarrow \forall A, B \in \operatorname{Mod}(\Sigma) .\left(A \not \equiv_{\Pi} B\right) \vee\left(B \models_{\Sigma} \varphi\right) \vee\left(A \not \vDash_{\Sigma} \varphi\right)\)
\(\Longleftrightarrow \forall A, B \in \operatorname{Mod}(\Sigma) .\left(A \equiv_{\Pi} B \Rightarrow\left(A \vDash_{\Sigma} \varphi \Rightarrow B \vDash_{\Sigma} \varphi\right)\right)\)

Considering that \(A \equiv{ }_{\Pi} B\) is equivalent to \(B \equiv_{\Pi} A\), we can apply this fact twice on the same pair of models to obtain
\[
\forall A, B \in \operatorname{Mod}(\Sigma) .\left(A \equiv_{\Pi} B \Rightarrow\left(A \models_{\Sigma} \varphi \Leftrightarrow B \models_{\Sigma} \varphi\right)\right)
\]
for all \(\varphi \in \alpha \operatorname{Sen}(\Pi)\).
In the other direction, \(\left.\right|_{\sigma}\) satisfies the satisfaction condition whenever \(\sigma\) is an original morphism because the satisfaction condition is already satisfied in \(\mathbf{I}\).

For each abstraction morphism \(o_{\Pi}: \Pi \rightarrow \Sigma\), i.e. \(C(\Pi)=\Sigma\), and models \(A, B \in \operatorname{Mod}(\Sigma)\), we assume that for all sentences \(\varphi \in \alpha \operatorname{Sen}(\Pi)\)
\[
A \equiv_{\Pi} B \Rightarrow\left(A \models_{\Sigma} \varphi \Leftrightarrow B \models_{\Sigma} \varphi\right)
\]

Taking the implication from left to right and writing explicitly the quantifiers over models we have that for all sentences \(\varphi \in \alpha \operatorname{Sen}\) (II)
\[
\left.\forall A, B \in \operatorname{Mod}(\Sigma) .\left(A \equiv_{\Pi} B \Rightarrow\left(A \models_{\Sigma} \varphi \Rightarrow B \models_{\Sigma} \varphi\right)\right)\right)
\]

The same chain of equivalences as before can be applied to obtain
\[
\forall A \in \operatorname{Mod}(\Sigma) .\left(\left(\forall B \in[A]_{\cong_{\mathrm{I}}} . B \models_{\Sigma} \varphi\right) \Leftarrow A \models_{\Sigma} \varphi\right)
\]

Implication in the opposite direction holds trivially since \(A \in[A]_{\equiv_{\mathrm{I}}}\), hence
\[
\forall A \in \operatorname{Mod}(\Sigma) .\left(\left(\forall B \in[A]_{\cong_{\Pi}} \cdot B \models_{\Sigma} \varphi\right) \Leftrightarrow A \models_{\Sigma} \varphi\right)
\]

Using the definition of \(\models_{\Pi}^{\alpha}\) and \(\left.\right|_{o_{\Pi}}\) we get
\[
\forall A \in \operatorname{Mod}(\Sigma) .\left(\left.A\right|_{o_{\Pi}} \models_{\Pi}^{\alpha} \varphi \Leftrightarrow A \models_{\Sigma} \varphi\right)
\]
for all \(\varphi \in \alpha \operatorname{Sen}(\Pi)\), as desired.

Finally we have to prove that the satisfaction condition holds for an arbitrary morphism \(h: \Pi 1 \rightarrow \Pi 2\) in \(\alpha S I G\).

Since \(\left\langle C, \alpha_{S I G}, o\right\rangle\) is a reflection, the unit morphisms \(o_{\Pi 1}\) and \(o_{\Pi 2}\) make the following diagram commute in \(\alpha S I G\).


Since \(\alpha S e n\) is a functor the corresponding diagram in the category of sets also commutes, i.e.
\[
\alpha \operatorname{Sen}(h) ; \alpha \operatorname{Sen}\left(o_{\Pi 1}\right)=\alpha \operatorname{Sen}\left(o_{\Pi 1}\right) ; \operatorname{Sen}(\sigma)
\]

Taking an arbitrary sentence \(\varphi \in \operatorname{Sen}(\Pi 1)\), we get
\[
\alpha \operatorname{Sen}\left(o_{\Pi 2}\right)(\alpha \operatorname{Sen}(h)(\varphi))=\operatorname{Sen}(\sigma)\left(\alpha \operatorname{Sen}\left(o_{\Pi 1}\right)(\varphi)\right)
\]
and since \(\alpha \operatorname{Sen}\left(o_{\Pi 1}\right)\) and \(\alpha \operatorname{Sen}\left(o_{\Pi 2}\right)\) are inclusions, this is reduced to \(\alpha \operatorname{Sen}(h)(\varphi)=\) \(\operatorname{Sen}(\sigma)(\varphi)\); that is to say, in the standard shorter notation:
\[
h(\varphi)=\sigma(\varphi)
\]

Now, for every model \(M \in|\operatorname{Mod}(\Sigma 2)|\) since the satisfaction condition holds in the original institution, we have that
\[
\left.M\right|_{\sigma} \models_{\Sigma 1} \varphi \Leftrightarrow M \models_{\Sigma 2} h(\varphi)
\]

Since the satisfaction condition holds w.r.t. unit morphisms (proved above), we know also that
\[
\left.\left.\left(\left.M\right|_{\sigma}\right)\right|_{o_{\Pi 1}} \models_{\Pi 1}^{\alpha} \varphi \Leftrightarrow M\right|_{\sigma} \models_{\Sigma 1} \varphi
\]
and similarly
\[
\left.M\right|_{o_{\Pi 2}} \models_{\Pi 2}^{\alpha} h(\varphi) \Leftrightarrow M \models_{\Sigma 2} h(\varphi)
\]

At the same time, since \(\alpha M o d\) is a functor the following diagram commutes guaranteeing that \(\left.\left(\left.M\right|_{o \Pi 2}\right)\right|_{h}=\left.\left(\left.M\right|_{\sigma}\right)\right|_{o_{\Pi 1}}\).


Combining the last three equivalences with this equation we conclude that:
\[
\left.\left.\left(\left.M\right|_{o_{12}}\right)\right|_{h} \models_{\Pi 1}^{\alpha} \varphi \Leftrightarrow M\right|_{o_{\Pi 2}} \models_{\Pi 2}^{\alpha} h(\varphi)
\]

Now, it suffices to note that \(\alpha \operatorname{Mod}\left(o_{\Pi 2}\right)\) (written \(\left.\left.\right|_{o_{\Pi 2}}\right)\) is a full functor. Therefore, every model in \(|\alpha \operatorname{Mod}(\Pi 2)|\) is a \(o_{\Pi 2}\)-reduct of at least one model in \(|\operatorname{Mod}(\Sigma 2)|\). Hence, any equivalence holding for an arbitrary reduct \(\left.M\right|_{\sigma_{\Pi 2}}\) also holds for an arbitrary \(A \in|\alpha \operatorname{Mod}(\Pi 2)|\), i.e.
\[
\left.A\right|_{h} \models_{\Pi 1}^{\alpha} \varphi \Leftrightarrow A \models_{\Pi 2}^{\alpha} h(\varphi)
\]

Finally, we can easily show quotient abstract institutions to be abstracted institutions as defined in page 135.

Proposition 5.2.6 Given a quotient abstract institution \(\alpha \overline{\overline{\bar{O}}}{ }_{\bar{s}} \mathrm{I}\), there exists a abstracting institution morphism from \(\mathbf{I}\) to \(\alpha \overline{\overline{0}}{ }_{b s} \mathbf{I}\).

Proof Given institutions \(\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle\) and
\[
\alpha_{\overline{\bar{O}} b_{s}} \mathbf{I}=\left\langle\alpha S I G, \alpha M o d, \alpha S e n, \models^{\alpha}\right\rangle
\]
as those in definition 5.2.3, we consider the tuple \(\left\langle\alpha_{S I G}, \alpha_{M o d}, \alpha_{S e n}\right\rangle\) defined as:
1. \(\alpha_{S I G}: S I G \rightarrow \alpha S I G\) is the full inclusion from the signatures in I to the signatures in \(\alpha \overline{\overline{\bar{O}}}{ }_{b s} \mathbf{I}\).
2. \(\alpha_{M o d}: M o d^{o p} \Rightarrow \alpha_{S I G}^{o p} ; \alpha M o d^{o p}\) is defined for all signatures \(\Sigma \in|S I G|\) as the identity functor
\[
\alpha_{M o d} \Sigma=I d_{M o d(\Sigma)}
\]
3. \(\alpha_{S e n}: \alpha_{S I G} ; \alpha S e n \Rightarrow S e n\) is defined for all signatures \(\Sigma \in|S I G|\) as the identity function
\[
\alpha_{S e n} \Sigma=I d_{S e n(\Sigma)}
\]

Using these definitions it is not difficult to verify that all the conditions required by institution morphisms hold and, in particular, the satisfaction condition
\[
M \models_{\Sigma} \alpha_{S e n} \Sigma(\varphi) \quad \text { iff } \quad \alpha_{M o d} \Sigma(M) \vDash_{\alpha_{S I G}(\Sigma)}^{\alpha} \varphi
\]
for all \(\Sigma \in|S I G|, M \in \alpha \operatorname{Mod}(\Sigma)\) and \(\varphi \in \alpha \operatorname{Sen}\left(\alpha_{S I G}(\Sigma)\right)\), becomes
\[
M \models_{\Sigma} \varphi \quad \text { iff } \quad M \models_{\Sigma}^{\alpha} \varphi
\]
for all \(\Sigma \in|S I G|, M \in \alpha \operatorname{Mod}(\Sigma)\) and \(\varphi \in \alpha \operatorname{Sen}(\Sigma)\). Furthermore, considering the definitions of \(\alpha S e n\) and \(\alpha M o d\) over original signatures in definition 5.2.3, we obtain a trivial statement:
\[
M \models_{\Sigma} \varphi \quad \text { iff } \quad M \models_{\Sigma} \varphi
\]
for all \(\Sigma \in|S I G|, M \in \operatorname{Mod}(\Sigma)\) and \(\varphi \in \operatorname{Sen}(\Sigma)\).
Finally, since reflections are adjunctions and inclusion functors are always faithful, we conclude that
\[
\left\langle\alpha_{S I G}, \alpha_{M o d}, \alpha_{S e n}\right\rangle: \mathbf{I} \rightarrow \alpha \overline{\overline{\bar{O}} b s} \overline{\mathbf{I}}
\]
is an abstracting institution morphism.

From now on, we shall drop the subscripts for abstraction morphisms so that an abstraction morphism \(o: \Pi \rightarrow \Sigma\) implicitly refers to a unit morphism \(o_{\Pi}: \Pi \rightarrow\) \(\alpha_{S I G}(C(\Pi))\) whose target signature is an original signature \(\Sigma\).

In a quotient abstracted institution \(\alpha \overline{\overline{\bar{O}}}_{b s} \mathrm{I}\) and for an abstraction morphism \(o: \Pi \rightarrow \Sigma\), the closure operator \(T_{o} D_{o}\) means abstraction in the sense of \(\alpha_{\equiv}\) in [ST 87]; i.e. for any \(\Sigma\)-specification \(S P\)
\[
\operatorname{Mod}\left[T_{o} D_{o} S P\right]=\left\{A \in|\operatorname{Mod}(\Sigma)| \mid A \equiv_{\Pi} B, B \in \operatorname{Mod}[S P]\right\}
\]

In general, the closure operator \(T_{\sigma} D_{\sigma}\) for a signature morphism \(\sigma: \Sigma 1 \rightarrow \Sigma 2\) is equivalent to an abstraction with respect to the kernel induced by the reduct functor \(\left.\right|_{\sigma}\), i.e. \(\operatorname{Ker}\left(-\left.\right|_{\sigma}\right) \subseteq|\operatorname{Mod}(\Sigma 2)| \times|\operatorname{Mod}(\Sigma 2)|\) and \(T_{\sigma} D_{\sigma} S P=\alpha_{\operatorname{Ker}(-\mid \sigma)} S P\) for any \(\Sigma 2\)-specification \(S P\). The construction of \(\alpha \overline{\bar{\sigma}}_{b s} \mathbf{I}\) is just a way to force the kernel for abstraction morphisms to be a given equivalence relation \(\equiv\).

We can conclude that abstraction in \(A S L\) is defined as follows:

Definition 5.2.7 Abstraction in \(A S L\left(\alpha_{\overline{\bar{O}}}^{b_{s}} \mathrm{I}\right)\) is a derived \(S B O \alpha_{\equiv_{\Pi}}\) defined as
\[
\alpha_{\equiv_{\mathrm{n}}}=\lambda X: \Sigma . T_{o} D_{o} X
\]
for each abstraction morphism \(o: \Pi \rightarrow \Sigma\).

\subsection*{5.2.2 Observational abstractions}

Following [ST 87], an abstraction operation \(\alpha_{\equiv}\) is called observational abstraction w.r.t. a signature-sorted set of sentences \(O b s\) if \(\equiv\) is a signature-sorted equivalence \(\equiv^{O b s}\) such that for each signature \(\Sigma\) and for every \(A, B \in \operatorname{Mod}(\Sigma)\),
\[
A \equiv_{\Sigma}^{O s_{s}} B \Longleftrightarrow\left(\forall \varphi \in O b s_{\Sigma} . A \vDash \varphi \Leftrightarrow B \models \varphi\right)
\]

This concept can be easily defined for quotient abstracted institutions as follows:
 is called observational, and denoted by \(\alpha_{O b s} \mathbf{I}\), if for each signature \(\Pi\) and models \(A, B \in \operatorname{Mod}(C(\Pi))\), the equivalence relation \(\equiv{ }_{\Pi}\) satisfies
\[
A \equiv \begin{aligned}
& \Pi \\
& \text { iff }
\end{aligned} \forall \varphi \in \alpha \operatorname{Sen}(\Pi) \cdot\left(A \vDash_{C(\Pi)} \varphi \Leftrightarrow B \vDash_{C(\Pi)} \varphi\right)
\]

Note that observations are ordinary sentences which cannot discriminate between two equivalent models (this requirement comes from theorem 5.2.5). Observational abstractions occur in the particular case that the equivalence relation
\(\equiv_{\Pi}\) is exactly the one induced by the observations \(O b s_{\Pi}\) which, by definition of a quotient abstracted institution, is \(\alpha \operatorname{Sen}(\Pi)\).

In this case \(A \equiv_{\Pi} B\) can be tested by checking if \(A\) and \(B\) agree on the observations \(O b s_{\Pi}\). For this reason, observational abstraction is related to the existence of proof techniques for entailment when the consequent contains abstraction, i.e. for \(D A T U \models \alpha+D A T U\), as for example in proving entailment w.r.t. a behaviourally abstracted specification.

In a non-observational abstraction we cannot know if two \(\Sigma\)-models which satisfy the same observations are equivalent or not w.r.t. \(\equiv_{\Pi}\) for an abstraction morphism \(o: \Pi \rightarrow \Sigma\). This makes it impossible, at the specification level, to decide if \(S P 2 \vDash \alpha_{\equiv_{\Pi}} S P 1\) is correct. For example, suppose \(\equiv_{\Pi}\) is the identity relation and \(\mathrm{Obs}_{\Pi}\) is empty; then all \(\Sigma\)-models satisfy the observable theorems of a specification \(\alpha_{\equiv_{\text {п }}} S P 1\) but none of them is a model of \(\alpha_{\equiv_{\text {п }}} S P 1\) unless it is also a model of \(S P 1\).

\subsection*{5.3 Proving satisfaction of all observable theorems}

In this section we study in which cases \(S P 2 \vDash \alpha_{\equiv_{\Pi}} S P 1\) can be proven by showing all observable theorems of the consequent \(S P 1\) to hold in the antecedent \(S P 2\). This relies, essentially, on the provability of behavioural equivalence between two models by proving agreement on all observations, but some side conditions render these proofs particularly interesting.

In terms of specification entailment, we intend to prove \(S P 2 \vDash \alpha_{\equiv_{\text {II }}} S P 1\) by proving that there is a sound theory \(\Delta 2\) w.r.t. \(S P 2\) and an M -complete theory \(\Delta 1\)
w.r.t. \(S P 1\) such that
\[
\Delta 2 \models_{\Sigma} \Delta 1 \cap O b s_{\Pi}
\]
which is equivalent to requiring the inference rule
\[
\frac{S P \models \varphi}{\alpha_{\equiv \mathrm{\#}} S P \models \varphi} \varphi \in O b s_{\Pi}
\]
to be M-complete w.r.t. \(\alpha_{\equiv п}\).
Substituting \(\alpha_{\equiv_{\mathrm{I}}}\) by its definition \(T_{o} D_{o}\), we realize that the inference rule just introduced for abstraction is the composition of the inference rules given for \(T_{\sigma}\) and \(D_{\sigma}\) in chapter 3, taking into consideration that \(\varphi \in O b s_{\Pi}\) if \(o(\varphi)=\varphi\).
\[
\frac{S P \vdash \sigma(\varphi)}{D_{\sigma} S P \vdash \varphi} \quad \frac{S P \vdash \varphi}{T_{\sigma} S P \vdash \sigma(\varphi)}
\]

Unfortunately, the rule for \(D_{\sigma}\) is not M -complete and, therefore, the rule for \(\alpha_{\equiv \mathrm{E}}\) is not M -complete unless some side conditions are met.

Definition 5.3.1 A quotient abstracted institution \(\alpha{\overline{\overline{\bar{O}}}{ }_{b s} \mathrm{I}}\) is called well-behaved if for every abstraction morphism \(o: \Pi \rightarrow \Sigma\), theory \(\Delta\) over \(\Sigma\) and partition \(\langle O, \bar{O}\rangle\) of the set of \(\Pi\)-observations (i.e. \(O \cap \bar{O}=\emptyset\) and \(O \cup \bar{O}=O b s_{\Pi}\) ), it is the case that whenever there exists a model \(A \in \operatorname{Mod}(\Sigma)\) such that
\[
A \neq_{\Sigma}\left(\Delta \cap O b s_{\Pi}\right) \cup O \quad \text { and } \quad A \not \#_{\Sigma} \bar{O}
\]
then, there exists also \(B \in \operatorname{Mod}(\Sigma)\) such that
\[
B \models_{\mathrm{\Sigma}} \Delta \cup O \quad \text { and } \quad B \nVdash_{\Sigma} \bar{O}
\]

Intuitively, we can imagine \(\Delta\) to be an abstracted specification and \(A\) a model satisfying the observable theorems of that specification, i.e. \(A \models \Delta \cap O b s_{\Pi}\). Then, in a well-behaved institution, there must exist a model \(B\) of \(\Delta\) which is observationally equivalent to \(A\), hence \(A\) is a model of the abstracted \(\Delta\).

In particular, a well-behaved abstracted institution requires observations to be rich enough so that if a theory \(\Delta\) is inconsistent with a certain partition \(\langle O, \bar{O}\rangle\) of the observations, then this partition should also be inconsistent with the observable part of the theory \(\Delta \cap O b s_{\Pi}\).
 straction morphism. If \(\Delta\) is an inconsistent theory over \(\Sigma\) then \(\Delta \cap O b s_{\Pi}\) is also inconsistent.

Proof If there exists \(A\) such that \(A \models_{\Sigma} \Delta \cap O b s_{\Pi}\) then we can partition \(O b s_{\Pi}\) into \(\left\langle O b s_{A}, \overline{O b s_{A}}\right\rangle\) with \(O b s_{A}=\left\{\varphi \in O b s_{\Pi} \mid A \models_{\Sigma} \varphi\right\}\) and \(\overline{O b s_{A}}=O b s_{\Pi} \backslash O b s_{A}\). Applying the definition of well-behaved institution, \(\Delta\) must be consistent.

Theorem 5.3.3 Given a well-behaved observational institution \(\alpha_{\text {Obs }} \mathrm{I}\), the inference rule
\[
\frac{S P \models \varphi}{D_{o} S P \models \varphi} \varphi \in O s_{\Pi}
\]
for every abstraction morphism o: \(\Pi \rightarrow \Sigma\) is \(M\)-complete.

Proof Let \(\Delta\) be an \(M\)-complete theory for \(S P\), i.e. \(\operatorname{Mod}[\Delta] \subseteq \operatorname{Mod}[S P]\). The inferred theory is \(\Delta_{\mathrm{inf}}=\Delta \cap O b s_{\Pi}\).

If \(\Delta\) is inconsistent so is \(\Delta_{\text {inf }}\) by the previous lemma, and \(\operatorname{Mod}\left[\Delta_{\text {inf }}\right] \subseteq \operatorname{Mod}\left[D_{o} S P\right]\) holds trivially.

Otherwise, it is enough to show that for all \(\Pi\)-models \(M\) such that \(M \models_{\Pi}^{\alpha} \Delta_{\text {inf }}\) there exists a model \(B \in \operatorname{Mod}[S P]\) such that \(B \in M\), since applying reducts \(M=\left.B\right|_{o} \in \operatorname{Mod}\left[D_{o} S P\right]\) as desired.

In an observational institution, \(M\) is characterized by a partition \(\left\langle O b s_{M}, \overline{O b s_{M}}\right\rangle\) of the set of observations \(O b s_{\Pi}\) depending on whether they are satisfied or they are not satisfied in \(M\), i.e. \(O b s_{M} \cup \overline{O b s_{M}}=O b s_{\Pi}\) and
\[
M=\left\{A \in \operatorname{Mod}(\Sigma) \mid A \models_{\Sigma} O b s_{M}, A \not \#_{\Sigma} \overline{O b s_{M}}\right\}
\]

Moreover, by construction, \(M\) is an equivalence class of \(\Sigma\)-models w.r.t. \(\equiv_{O b s}\) and therefore it cannot be empty. Hence, there exists a \(\Sigma\)-model \(A \in M\) and, since \(M \neq{ }_{\Pi}^{\alpha} \Delta_{i n f}\),
\[
A \models_{\Sigma}\left(\Delta \cap O b s_{\Pi}\right) \cup O b s_{M} \quad \text { and } \quad A \nVdash_{\Sigma} \overline{O b s_{M}}
\]

In a well-behaved institution, there must exist a \(\Sigma\)-model \(B\) such that \(B \models_{\Sigma}\) \(\Delta \cup O b s_{M}\) and \(B \not \#_{\Sigma} \overline{O b s_{M}}\), therefore \(B \in M\). At the same time, \(B \in \operatorname{Mod}[\Delta]\) and by M-completeness of \(\Delta, B \in \operatorname{Mod}[S P]\) as required.

Since the soundness of the rule without the side condition has already been proven (see section 3.3), the rule is exact.

Corollary 5.3.4 In a well-behaved observational institution \(\alpha_{0 b s} \mathrm{I}\), any specification \(S P\) in \(\alpha+A T U\) is equivalent to a presentation \(\Phi_{S P} \subseteq \operatorname{Sen}(\operatorname{Sig}[S P])\) which can be obtained by adding an equivalence
\[
\alpha_{\equiv \Pi} A_{\Phi} \epsilon_{\Sigma}=A_{C l(\Phi) \cap O b_{\mathrm{s}}} \epsilon_{\Sigma}
\]
to those given for \(A T U\) in section 3.2.

Unfortunately, the theory \(C l(\Phi) \cap O b s_{\Pi}\) may not have a finite presentation even if \(C l(\Phi)\) has. This is the case of the common specification of stacks where a non-observable axiom
\[
\operatorname{pop}(\operatorname{push}(x, S))=S
\]
gives rise to an infinite set of observable consequences
```

top(pop(push(x,S))) = top(S)
top(push(y, pop(push(x,S)))) = top(push(y,S))

```
which cannot be expressed by an equivalent finite presentation. This problem arises also in first order logic [Sch 91] and prevents abstraction in a well-behaved observational institution from being trivial. In practice, well-behaved observational abstractions allow entailment proofs by proving satisfaction of all observable theorems, but they do not tell us how to perform such proofs. In the end, we must rely on appropriate proof techniques such as context induction [Hen 88] or proof by consistency [Lin 87].

Comparing our proof results for abstraction in well-behaved observational institutions to those in [ST 87, ST 88a], a few comments can be made.

Defining abstraction to be the closure \(T_{o} D_{0}\) allows us to give the inference rule for abstraction in terms of those for \(D_{\sigma}\) and \(T_{\sigma}\), so that no extra rule is needed.

Well-behaviour of an abstracted institution is not such a new requirement. Fact 13 in [ST 87] shows that in order to be able to reduce abstracted first order presentations to equivalent first order presentations, observations are required to be closed under negation and conjunction. Well-behaviour can be derived from this closure.

Using an institution-independent notion of negation and conjunction, we can extend that result to an arbitrary quotient abstracted institution. Consider for example the definition of closure under negation and conjunction given in [Tar 86a] for an arbitrary institution, then the following result follows:

Proposition 5.3.5 Given an institution \(\alpha \overline{\overline{0} b_{s}} \mathrm{I}\) with a reflection \(\left\langle C, \alpha_{S I G}, \mathbf{o}\right\rangle\), if for every \(\Pi \in|\alpha S I G|\) each \(O b_{\Pi}\) is closed under negation and (possibly infinitary) conjunction, then \(\alpha_{\overline{\bar{O}}{ }_{b s}} \mathbf{I}\) is well-behaved.

Proof Let \(o: \Pi \rightarrow \Sigma\) be an abstraction morphism, \(\Delta\) a theory over \(\Sigma,\langle O, \bar{O}\rangle\) a partition of \(O b s_{\Pi}\) and \(A\) a model such that \(A \models_{\Sigma}\left(\Delta \cap O b s_{\Pi}\right) \cup O\) and \(A \not \#_{\Sigma} \bar{O}\).

If \(\Delta \cup O\) is consistent, there exists a model \(B \models_{\Sigma} \Delta \cup O\). Moreover, for any observation \(\bar{\varphi} \in \bar{O}\) its negation \(\varphi\) must belong to \(O\), since \(A\) must satisfy either \(\varphi\) or \(\bar{\varphi}\). Then, \(B\) cannot satisfy \(\bar{\varphi}\) because \(B \models_{\Sigma} O\); hence \(B \not \nVdash \Sigma \bar{O}\).

If \(\Delta \cup O\) is inconsistent, we come to a contradiction in each possible case:
1. If \(\Delta\) is inconsistent then the contradiction \(\square\) (negation of the conjunction of an empty set of sentences \(\neg(\wedge \emptyset)\) ) is in \(\Delta\) and therefore in \(\Delta \cap O b s_{\Pi}\) since \(O b s_{\Pi}\) is closed under negation and conjunction. Hence \(A\) satisfying \(\Delta \cap O b s_{\Pi}\) cannot exist.
2. If \(O\) is inconsistent then \(A\) satisfying \(O\) cannot exist.
3. Otherwise, there exists a set of sentences \(\Phi \subseteq O\) in contradiction with \(\Delta\). Since \(O b s_{\Pi}\) is closed under infinite conjunctions there exists \(\varphi_{\Phi} \in O b s_{\Pi}\) equivalent to \(\Phi\) and, since it is closed under negation, \(\neg \varphi_{\Phi} \in O b s_{\Pi}\) as well. Since \(\Delta \cup \Phi\) is inconsistent, \(\Delta\) must include \(\neg \varphi_{\Phi}\), hence \(\neg \varphi_{\Phi} \in \Delta \cap O b s_{\Pi}\). Finally \(\left(\Delta \cap O b s_{\Pi}\right) \cup O\) is inconsistent since \(\varphi_{\Phi} \in O\).

If the logic of the sentences is compact, closure under possibly infinitary conjuctions can be replaced by closure under finite conjunctions, like in the case of first order logic in fact 13 of [ST 87].

Another example in [ST 87] where observations are open formulae fails to be well-behaved. That proposal is intuitively sound since it includes as observable all values of an observable sort, even those which are not reachable - note that if observations are first order sentences we cannot refer individually to non-reachable
values. Unfortunately, such a modification leads to a logic of open formulae which is no longer compact - see the counterexample in [ST 87] where an infinite set of observations are in contradiction with a first order sentence while no finite subset is.

In this chapter we are not so much concerned with the problem of finding a realistic set of observations which is at the same time well-behaved, as was the case in [ST 87]. Our goal is to develop a certain proof theory for specifications with abstraction, and in this sense observational and well-behaved institutions are those allowing entailment proofs to be performed by proving satisfaction of all observable theorems.

In the following we review some common abstracted institutions for behavioural abstraction, and analyze them for observationality and well-behaviour.

\subsection*{5.3.1 Behavioural abstraction and EQ}

Probably the most well-known example of abstraction is behavioural abstraction of an equational specification w.r.t. some non-observable sorts. In the following we present some abstracted institutions related to this idea.

\section*{\(\operatorname{Beh}(E Q)\)}

This abstracted institution matches the standard intuition of behavioural abstraction w.r.t. some non-observable sorts (as in [MG 85, NO 88, ST 87, Gog 90] reviewed above).

First a category of signatures of behaviour is defined (as explicitly given in [Gog 90] and implicitly standard long before):

Definition 5.3.6 Given the category SIG of algebraic signatures, signatures of behaviour form a category \(\operatorname{Beh}(S I G)\) as follows:
- Objects: Pairs \(\langle\Sigma, O\rangle\) where \(\Sigma\) is an object of \(S I G\) and \(O\) a set of sorts in \(\Sigma\).
- Morphisms: Arrows \(\sigma:\langle\Sigma 1, O 1\rangle \rightarrow\langle\Sigma 2, O 2\rangle\) where \(\sigma: \Sigma 1 \rightarrow \Sigma 2\) is a morphism in \(S I G\) such that \(\sigma(O 1) \subseteq O 2\). Identities and composition are as in \(S I G\).

According to this definition there is a full subcategory of \(\operatorname{Beh}(S I G)\) which is isomorphic to \(S I G\), namely the full subcategory containing signatures \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\). Hence, there is a full and faithful functor \(B e h_{S I G}: S I G \rightarrow B e h(S I G)\) which maps each signature \(\Sigma\) to its equivalent \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\) and is the identity on signature morphisms.

Behaviours of algebras w.r.t. some observable sorts can be defined as in [MG 85], or equivalently, a concise definition can be given in terms of the functorial interpretation of an algebra.

Definition 5.3.7 Given an algebraic signature \(\Sigma\) and an algebra
\[
A: S t_{\Sigma} \rightarrow S e t
\]
then, the behaviour of an algebra \(A\) w.r.t. a set of sorts \(O\) in \(\Sigma\) is a functor
\[
M: S t_{\Sigma}(O) \rightarrow \text { Set }
\]
where \(\operatorname{St}_{\Sigma}(O)\) is the minimal full subcategory of \(S t_{\Sigma}\) containing all the sorts in \(O\) and being closed under products. Then, \(M\) is the restriction of \(A\) to such \(a\) subcategory.

A behaviour \(M\) is also an algebra since, like \(A\), it is a product preserving functor from a category with finite products to Set. However, the signature of \(M\) is no longer \(\Sigma\) but a generally infinite signature with a function name for each \(\Sigma\)-term using variables over observable sorts and delivering a value of an observable sort, as explicitly defined in [MG 85].

Now we are able to define an abstracted institution w.r.t. EQ using signatures in Beh \((S I G)\), considering behaviours to be the models of the abstracted signatures, and equations between terms over observable sorts to be the sentences of the abstracted signatures.

Technically, we shall define the new abstracted institution as a quotient abstracted institution, repeating the construction given in definition 5.2.3. In order to perform such a construction original signatures are required to form a full subcategory of \(\alpha S I G\); since this is not the case for \(S I G\) we are going to consider \(S I G^{\prime}\) to be the full subcategory of signatures in \(\alpha S I G\) of the form ( \(\Sigma, \operatorname{Sorts}(\Sigma)\) ) and \(\mathbf{E Q}^{\prime}=\left\langle S I G^{\prime}, A l g^{\prime}, E q^{\prime}, \models^{\prime}\right\rangle\) to be the obvious equational institution defined over \(S I G^{\prime}\), i.e. \(\operatorname{Alg}(\Sigma)=\operatorname{Alg}^{\prime}(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle), E q(\Sigma)=E q^{\prime}(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle)\) and \(\models_{\Sigma}=\models_{\left(\Sigma, S_{o r t s}(\Sigma)\right)}\).

Lemma 5.3.8 Let \(B e h_{S I G}\) be the full inclusion from \(S I G^{\prime}\) to \(\operatorname{Beh}(S I G), C\) : Beh \((S I G) \rightarrow S I G^{\prime}\) a functor defined as follows
\[
C(\langle\Sigma, O\rangle)=\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle \quad C(\sigma)=\sigma
\]
and o : \(I d_{B e h(S I G)} \Rightarrow C ; B e h_{S I G}\) a natural transformation such that for every \(B e h(S I G)\) signature \(\langle\Sigma, O\rangle\),
\[
o_{(\Sigma, O)}:\langle\Sigma, O\rangle \rightarrow\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle
\]

Then, \(\left\langle C, B e h_{S I G}, \mathbf{o}\right\rangle\) is a reflection.
Proof We shall prove that for each signature of behaviour \(\langle\Sigma, O\rangle\) its unit morphism \(o_{\langle\Sigma, O\rangle}:\langle\Sigma, O\rangle \rightarrow\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\) is a universal arrow.

Since morphisms in \(\operatorname{Beh}(S I G)\) are also morphisms in \(S I G^{\prime}\) and each morphism \(o_{(\Sigma, O)}\) in \(\operatorname{Beh}(S I G)\) is just the identity \(i d_{\left(\Sigma, S_{o r t s}(\Sigma)\right)}\) in \(S I G^{\prime}\), it is trivial that for each morphism \(h:\langle\Sigma, O\rangle \rightarrow\left\langle\Sigma^{\prime}, O^{\prime}\right\rangle-\) which is also a morphism \(h:\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle \rightarrow\) \(\left\langle\Sigma^{\prime}, \operatorname{Sorts}\left(\Sigma^{\prime}\right)\right\rangle\) in \(S I G^{\prime}\) - there exists a unique \(h^{\prime}\) such that
\[
i d_{(\Sigma, S o r t s(\Sigma))} ; h^{\prime}=h
\]
because \(h^{\prime}\) must be \(h\).

The abstracted institution \(\operatorname{Beh}(E Q)\) is defined as follows:

Theorem 5.3.9 Let \(\mathbf{E Q}^{\prime}=\left\langle S I G^{\prime}, A l g^{\prime}, E q^{\prime}, \models^{\prime}\right\rangle\) be the institution of equational logic with signatures of the form \(\langle\Sigma\), sorts \((\Sigma)\rangle\) for all \(\Sigma \in|S I G|\) and consider the following:
1. The category \(\operatorname{Beh}(S I G)\) and the full inclusion \(B_{\text {eh }}{ }_{S I G}: S I G^{\prime} \rightarrow B e h(S I G)\).
2. The reflection \(\left\langle C, B e h_{S I G}, o\right\rangle\) with \(C: B e h(S I G) \rightarrow S I G^{\prime}\) and \(\mathrm{o}: I d_{B e h(S I G)} \Rightarrow C ; B e h_{S I G}\) as defined in lemma 5.3.8.
3. The \(|\operatorname{Beh}(S I G)|\)-sorted equivalence relation \(\equiv\) between algebras defined for all \(\langle\Sigma, O\rangle \in|B e h(S I G)|\) and \(\Sigma\)-algebras (i.e. \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\)-algebras) \(A\) and \(B\) as: \(A \equiv(\Sigma, o\rangle B\) iff \(A\) and \(B\) have the same behaviour w.r.t. \(O\).
4. The \(|\operatorname{Beh}(S I G)|\)-sorted set of equations Obs defined for all \(\langle\Sigma, O\rangle\) as:
\[
O b s_{\langle\Sigma, O\rangle}=\{\forall X . t 1=t 2 \in E q(\Sigma) \mid \operatorname{sort}(t 1) \in O, \operatorname{sorts}(X) \subseteq O\}
\]

Then, \(\operatorname{Beh}(\mathbf{E Q})=\left\langle\operatorname{Beh}(S I G), \alpha \operatorname{Mod}, \alpha S e n, \models^{\alpha}\right\rangle\) defined as in definition 5.2.3 using the above components is a quotient abstracted institution of \(\mathbf{E Q}^{\prime}\).

Proof Applying proposition 5.2.4 and theorem 5.2.5, \(\mathbf{B e h}(\mathbf{E Q})\) is an institution unless two algebras with the same behaviour can satisfy different sets of observations.

However, for all \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle \in\left|S I G^{\prime}\right|\) and \(\Sigma\)-equations (i.e. \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\) equations) \(\forall X . t 1=t 2 \in O b s_{(\Sigma, o)}\), both terms \(t 1\) and \(t 2\) correspond to morphisms in \(S t_{\Sigma}\) which are also in \(S t_{\Sigma}(O)\) since they are arrows from a product of
observable sorts - sorts of variables in \(X\) - to an observable sort - the sort of \(t 1\) and \(t 2\).

All \(\Sigma\)-algebras (i.e. \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\)-algebras) \(A\) and \(B\) with the same behaviour \(M\) map morphisms \(t 1\) and \(t 2\) in \(S t_{\Sigma}\) to the same functions \(M(t 1)=A(t 1)=B(t 1)\) and \(M(t 2)=A(t 2)=B(t 2)\) in Set. If functions \(M(t 1)\) and \(M(t 2)\) produce the same result for all valuations of the variables in \(X\), equation \(\forall X . t 1=t 2\) is satisfied by \(A\) and \(B\); otherwise, neither \(A\) or \(B\) satisfy the equation. Hence, the equation does not distinguish \(A\) from \(B\).

By construction, the closure \(T_{o} D_{o}\) w.r.t. an abstraction morphism \(o:\langle\Sigma, O\rangle \rightarrow\) \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\) is behavioural abstraction, for a notion of behaviour as in [MG 85]. If \(T_{0} D_{o}\) is applied to a specification \(S P\) with a class of models closed up to isomorphism, then \(T_{o} D_{o} S P\) is also closed up to isomorphism, as with behavioural abstraction in the sense of [SW 83, NO 88, ST 87].

Unfortunately, \(\mathbf{B e h}(\mathbf{E Q})\) is not observational.
In first place, in order for \(\operatorname{Beh}(\mathbf{E Q})\) to be observational the set of algebras behaviourally equivalent to any given one should be closed up to isomorphism but, in this case, it is not. This can be easily fixed by changing \(A \equiv(\Sigma, 0) B\) to mean that \(A\) and \(B\) have isomorphic behaviours w.r.t. \(O\), so that \(T_{o} D_{o}\) directly means behavioural abstraction as is standard. We shall refer to this variant by Beh'(EQ).

However, there are still cases where two algebras satisfying the same observable equations are not behaviourally equivalent (see examples in [ST 87]).

This lack of observationality is caused by non-reachable values in observable sorts. Since equations can only refer to them globally, two algebras may satisfy
the same equations while non-reachable values are more numerous in one algebra than in the other. This is analogous to cases where non-isomorphic algebras satisfy the same equations, e.g. all non-empty algebras over a signature without function symbols or constants satisfy the same trivial equations.

The lack of observationality, as discussed at the end of section 5.2.2, prevents Beh(EQ) from being useful at specification entailment proofs; in particular, theorem 5.3.3 does not apply.

\section*{BehR(EQ)}

The lack of observationality of \(\operatorname{Beh}^{\prime}(\mathbf{E Q})\) can be solved by considering only reachable algebras.

Unlike ordinary algebras, reachable algebras are characterized up to isomorphism by a set of equations, i.e. if two reachable algebras satisfy the same ground equations then they are isomorphic.

Similarly, since behaviours are also algebras, reachable behaviours are characterized up to isomorphism by a set of observable equations.

Proposition 5.3.10 If two \(\Sigma\)-algebras \(A\) and \(B\) are reachable on observable sorts \(O\) and they satisfy exactly the same ground observable equations in \(O b_{(\Sigma, O)}\), then the behaviours of \(A\) and \(B\) w.r.t. \(O\) are isomorphic.

Proof Let \(M\) and \(N\) be the behaviours of \(\Sigma\)-algebras \(A\) and \(B\) w.r.t. \(O\).
Behaviours \(M\) and \(N\) are algebras over a, generally, infinite signature \(\Sigma_{O}\) which, by construction, has sorts \(O\) and functions names all \(\Sigma\)-terms from observable to observable sorts.

Considering that \(A\) and \(B\) are reachable on sorts \(O\), their behaviors \(M\) and \(N\) are reachable \(\Sigma_{O}\)-algebras. Moreover, since observable equations in \(O b s_{\langle\Sigma, O\rangle}\) are
pairs of \(\Sigma\)-terms from observable to observable sorts, we have that \(\Sigma_{0}\)-equations are equivalent to equations in \(\mathrm{Obs}_{(\Sigma, O)}\).

If \(A\) and \(B\) satisfy exactly the same ground observable equations in \(O b s_{\langle\Sigma, O\rangle}\), their behaviours \(M\) and \(N\) satisfy exactly the same ground \(\Sigma_{O}\)-equations, hence \(M\) and \(N\) are isomorphic.

Let the institution \(\operatorname{BehR}(E Q)\) be as \(\mathrm{Beh}^{\prime}(\mathrm{EQ})\) but considering only those signature morphisms which are isomorphisms in \(S I G\) and those algebras which are reachable, i.e. with models defined for all \(\langle S, \Omega\rangle \in|S I G|\) as
\[
|\operatorname{Mod}(\langle S, \Omega\rangle)|=\{A \in|A \lg (\langle S, \Omega\rangle)| \mid A \text { is reachable on } S\}
\]

The restriction on the signature morphisms guarantees the \(\sigma\)-reduct of a reachable algebras to be also reachable. Then, taking observations to be all ground equations over observable sorts, the following results hold:

Theorem 5.3.11 BehR(EQ) is an observational institution.

Proof For all abstraction morphisms \(o: \Pi \rightarrow \Sigma\), the set of observable equations \(O b s_{\Pi}\) includes all ground equations over observable sorts. Therefore, by proposition 5.3.10, any pair of reachable algebras \(A, B \in|A l g(\Sigma)|\) such that
\[
\forall \varphi \in O b s_{\Pi} \cdot\left(A \models_{\Sigma} \varphi \Leftrightarrow B \models_{\Sigma} \varphi\right)
\]
must have isomorphic behaviours, hence \(A \equiv \Pi\).

Conversely, if \(A \equiv_{\Pi} B\) then, by theorem 5.2 .5 , both models must agree on all observations. Hence, \(\operatorname{Beh} \mathbf{R}(\mathbf{E Q})\) is observational.

In order to prove that \(\operatorname{BehR}(\mathbf{E Q})\) is also well-behaved, we must recall that multi-sorted equational logic \(\vdash^{\mathrm{EQ}}\) (c.f. [GM 81, EM 85]) is a complete inference system w.r.t. satisfaction in EQ, that initial algebras satisfy the "no confusion" principle, i.e. given a set of equations \(\Phi\) if an initial algebra among those satisfying \(\Phi\) satisfies a ground equation \(\varphi\) then \(\Phi \models \varphi\), and also the following fact:

Fact 5.3.12 (Hen 88) Given a equational presentation \(\Phi\) over \(\Sigma\) and a set of observable sorts \(O\) in \(\Sigma\), all observable ground consequences of \(\Phi\) in \(\vdash^{\mathrm{EQ}}\) can be derived from the observable ground consequences of each equation in \(\Phi\).

A proof of a more general fact can be found in theorem 6.22 of [Hen 88]. This fact is used in [Hen 88] to prove the soundness of context induction, here, the same fact serves to prove the well-behaviour of \(\operatorname{BehR}(E Q)\).

Theorem 5.3.13 BehR(EQ) is a well-behaved institution.

Proof Let \(o: \Pi \rightarrow \Sigma\) be an abstraction morphism, \(\Delta\) an equational theory over \(\Sigma, A\) a \(\Sigma\)-algebra satisfying \(\Delta \cap O b s_{\Pi}\) (the observable theorems of \(\Delta\) ) and \(\langle O, \bar{O}\rangle\) the partition of \(O b s_{\Pi}\) such that
\[
A \models_{\Sigma} O \quad \text { and } \quad A \nVdash_{\Sigma} \bar{O}
\]

Then, we take \(B\) to be an initial \(\Sigma\)-algebra (unique up to isomorphism) satisfying equations \(\Delta \cup O\) and prove that \(B \#_{\Sigma} \bar{O}\). Assume \(B \models \varphi\), by cases:
1. \(\varphi\) is not a ground equation. In this case, by definition of \(\bar{O}, \varphi \notin \bar{O}\) trivially.
2. \(\varphi\) is a ground equation. Since initial algebras satisfy the "no confusion" principle ground equations cannot be satisfied by \(B\) unless they follow from \(\Delta \cup O\), hence \(\Delta \cup O \vDash_{\Sigma} \varphi\) which, by completeness of \(\vdash^{\mathrm{EQ}}\), is equivalent to \(\Delta \cup O \vdash^{\text {EQ }} \varphi\).

In this situation we can use fact 5.3 .12 to conclude that \(\varphi\) can be derived from the observable ground consequences of each equation in \(\Delta \cup O\). By induction on the length of such a derivation we prove that \(\varphi\) is not in \(\bar{O}\) :
(a) \(\varphi\) is an observable ground consequence of an equation \(\varphi^{\prime} \in \Delta \cup O\). If \(\varphi^{\prime} \in \Delta\), since \(\Delta\) is closed under entailment, \(\varphi\) must also be in \(\Delta\) and therefore \(\varphi \notin \bar{O}\). On the other hand, if \(\varphi^{\prime} \in O\) it means that \(A\) satisfies \(\varphi^{\prime}\) and therefore \(A\) satisfies \(\varphi\), hence \(\varphi \notin \bar{O}\).
(b) \(\varphi\) follows from some observable ground consequences \(\Phi\) of each equation in \(\Delta \cup O\). By the induction hypothesis no equation in \(\Phi\) belongs to \(\bar{O}\), hence \(\Phi \subseteq O\). Then, by definition of \(O, A\) satisfies \(\Phi\) and therefore \(A\) satisfies \(\varphi\), hence \(\varphi \notin \bar{O}\).

We conclude that no equation satisfied by \(B\) is in \(\bar{O}\) and therefore \(B \not \#_{\Sigma} \bar{O}\) as expected.

Well-behaviour of \(\operatorname{BehR}(E Q)\) follows from the existence of initial models among those satisfying a set of equations, restricting to ground observations and fact 5.3.12. The same properties and, therefore, well-behaviour also hold in \(\operatorname{Beh}(E Q)\) if observations are required to be ground equations.

\section*{Other institutions}

The reader might protest that using \(\operatorname{BehR}(\mathbf{E Q})\) is too much restrictive, in particular because limiting signature morphisms to be isomorphisms prevents writing any sensible structured specification. In this situation we can search for still another institution.

First, as proposed in [ST 87] we can shift to a stronger logic so that observations can be open formulae. Doing this, we stick to the standard semantics of
behavioural abstraction as in [SW 83, MG 85, NO 88] and obtain an observational institution, however well-behaviour is lost. We shall call this abstracted institution BehO(EQ).

Alternatively, we can preserve well-behaviour by not changing the notion of observation or model, and obtain observationality by changing the relation \(\equiv\langle\Sigma, 0\rangle\) and thus the semantics of \(T_{o} D_{o}\) when some observable sorts are not finitely generated. We shall call such an abstracted institution BehQ(EQ).

Proposition 5.3.14 Let \(\mathbf{E Q}^{\prime}=\left\langle S I G^{\prime}, A l g^{\prime}, E q^{\prime}, \models^{\prime}\right\rangle\) be the institution for equational logic with signatures of the form \(\langle\Sigma\), sorts \((\Sigma)\rangle\) for all \(\Sigma \in|S I G|\) and consider the following:
1. The category \(\operatorname{Beh}(S I G)\) and the full inclusion \(B e h_{S I G}: S I G^{\prime} \rightarrow B e h(S I G)\).
2. The reflection \(\left\langle C, B e h_{S I G}, 0\right\rangle\) with \(C: \operatorname{Beh}(S I G) \rightarrow S I G^{\prime}\) and \(\mathrm{o}: I d_{B e h(S I G)} \Rightarrow C ; B_{S I G}\) as defined in lemma 5.3.8.
3. The \(|\operatorname{Beh}(S I G)|\)-sorted equivalence relation \(\equiv\) between algebras defined for all \(\langle\Sigma, O\rangle \in|\operatorname{Beh}(S I G)|\) and \(\Sigma\)-algebras (i.e. \(\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\)-algebras) A and \(B\) as:
\[
A \equiv{ }_{(\Sigma, o\rangle} B \quad \text { iff } \quad \forall \varphi \in O b s_{\langle\Sigma, o\rangle} .\left(A \models_{\Sigma} \varphi \Leftrightarrow B \vDash_{\Sigma} \varphi\right)
\]
4. The \(|B e h(S I G)|\)-sorted set of equations Obs defined for all \(\langle\Sigma, O\rangle\) as:
\[
O b s_{(\Sigma, O)}=\{\forall X . t 1=t 2 \in E q(\Sigma) \mid \operatorname{sort}(t 1) \in O, \operatorname{sorts}(X) \subseteq O\}
\]

Then, \(\mathbf{B e h Q}(\mathbf{E Q})=\left\langle\operatorname{Beh}(S I G), \alpha \operatorname{Mod}, \alpha S e n, \models^{\alpha}\right\rangle\) defined as in definition 5.2.3 using the above components is an observational institution \(\alpha_{O b s} \mathrm{EQ}^{\prime}\).

Proof Applying proposition 5.2.4 and theorem 5.2.5, BehQ(EQ) is a quotient abstracted institution. Considering definition 5.2.8, BehQ(EQ) is observational trivially.

Another institution we may think of is Beh(ALG); i.e. we repeat over ALG the construction of \(\operatorname{Beh}(\mathbf{E Q})\) over \(\mathbf{E Q}\). In this case, the notion of abstraction in \(\operatorname{Beh}(A L G)\) is like that in \(\operatorname{Beh}(E Q)\) and the only difference concerns observations, which now can be defined to be closed under negation and conjunction in order to have a well-behaved abstracted institution. This approach, despite dealing with first order sentences over equality, is basically an algebraic approach.

\section*{Some comparisons}

The above institutions for behaviour are closely related to those explicitly or implicitly defined in [SW 83, MG 85, ST 87, NO 88, Hen 88, Gog 90].

Among them the only one defining explicitly an institution for behaviour is [Gog 90], the so-called hidden sort equational institution. However, the models over signatures with non-observable sorts are just ordinary algebras, therefore for a morphism \(o:\langle\Sigma, O\rangle \rightarrow\langle\Sigma, \operatorname{Sorts}(\Sigma)\rangle\), it holds that \(\operatorname{Mod}\left[T_{o} D_{o} S P\right]=\operatorname{Mod}[S P]\).

The closest of these approaches to \(\operatorname{Beh}(\mathrm{EQ})\) is [GM 82, MG 85]. Behaviours as defined here are equivalent to theirs (from there comes the name) although their definition is not formulated in terms of functors but directly considering infinitary signatures with a new function symbol for each term from observable sorts to observable sorts expressible in the original signature.

In [NO 88] the models over a signature with non-observable sorts are as in [Gog 90] but there are more arrows between them. The new homomorphisms
relate behaviourally equivalent algebras in such a way that closure under isomorphism produces the same result as in \(\operatorname{Beh}^{\prime}(\mathbf{E Q})\), i.e. closure up to behavioural equivalence.

Finally, \(\alpha_{\equiv}\) in [ST 87] uses an explicit relation of equivalence between models as we do, although equivalence classes of models are not considered models at all, nor is an explicit institution for behaviour defined. The two approaches presented in [ST 87] are observational by definition; the one using ground observations corresponds to \(\operatorname{BehQ}(E Q)\) and the other using open formulae coriesponds to \(\mathrm{BehO}(\mathrm{EQ})\).

In [Hen 88] only finitely generated models are considered and, usually, only a part of the carrier of a sort is defined as observable, however when whole carriers are considered observable we obtain abstraction as in BehR(EQ). Note that in [Hen 88] behavioural equivalence is defined directly as the satisfaction of the same observations, which happens to be consistent with the standard notion of behavioural equivalence due to the observationality and well-behaviour of this institution.

Provided that all specifications define isomorphism-closed classes of models, the semantics of \(T_{0} D_{o}\) in \(\mathbf{B e h}^{\prime}(\mathbf{E Q})\) (also [NO 88]), \(\mathbf{B e h O}(\mathbf{E Q})\) (also [ST 87]) and Beh(EQ) (also [MG 85]) are the same. If we are only concerned with algebras with reachable observable sorts, then \(\operatorname{BehR}(E Q)\) (also [Hen 88]) and BehQ(EQ) (also [ST 87]) are also the same.

We can conclude that, among the institutions considered here, in order to obtain an M -complete rule for abstraction and keep behavioural abstraction as meaning what is expected, we should use \(\operatorname{BehR}(E Q)\). Essentially, we should not hide the generators of observable sorts.

\subsection*{5.4 Treating abstraction as hiding}

In the introduction of this chapter we informally classified proving techniques related to behavioural equivalence in essentially two categories: those using explicit definition of congruences and those proving agreement on all observations.

In our framework, the second technique relates to entailment proofs by proving satisfaction of all observable theorems studied in the last section. There, we paid attention to those cases in which abstraction is "better" than hiding, in the sense that it has an exact inference rule.

In this section we treat abstraction as ordinary hiding, that is, we apply the proofs techniques developed for hiding in chapter 4 to the particular case where the operation \(D_{\sigma}\) uses an abstraction morphism o, i.e. \(D_{o}\). This approach does not require an exact rule for abstraction.

In the case of behavioural abstraction in first order logic, this abstraction as hiding approach turns out to be related to proofs by explicit definition of congruences as used in the literature.

\subsection*{5.4.1 Verification techniques for \(T_{o} D_{o}\)}

Chapter 4 presented some proof techniques for the verification of entailments between specifications in DATU. Considering abstraction to be the application of a pair \(T_{o} D_{o}\) using an abstraction morphism \(o\), the same techniques are applicable to the verification of entailments between abstracted specifications. However, some problems arise depending of which abstracted institution we use. For instance, taking \(\operatorname{Beh}(E Q)\) to be our working institution leads to rather poor results.

Consider task 1 as presented on page 92 and take \(\sigma 1\) and \(\sigma 2\) to be an abstraction morphism \(o: \Pi \rightarrow \Sigma\) :
\[
D_{o} A_{\Phi 2} \epsilon_{\Sigma} \models D_{o} A_{\Phi 1} \epsilon_{\Sigma}
\]


All results in chapter 4 related to the inheriting strategy rely on a pushout diagram of signatures which combine in one single signature the visible symbols plus the hidden symbols of the antecedent and the consequent. This basic construct delivers a trivial result in the case of \(\operatorname{Beh}(S I G)\) and an abstraction morphism o as in the figure.

\section*{Proposition 5.4.1 Given the following diagram in \(\operatorname{Beh}(S I G)\)}

where \(S\) is the set of sorts in \(\Sigma\) and \(O \subseteq S\), then the pushout signature is also \(\langle\Sigma, S\rangle\).

Proof Assume there exists a signature \(\left\langle\Sigma^{+}, O^{+}\right\rangle\)and a pair of signature morphisms \(\sigma 1, \sigma 2:\langle\Sigma, S\rangle \rightarrow\left\langle\Sigma^{+}, O^{+}\right\rangle\)such that \(o ; \sigma 1=o ; \sigma 2\) (the diagram commutes).

Since signature morphisms in \(\operatorname{Beh}(S I G)\) are also signature morphisms in \(S I G\), we can consider the original category of signatures, so that the new two morphisms must satisfy \(i d_{\Sigma} ; \sigma 1=i d_{\Sigma} ; \sigma 2\), hence \(\sigma 1=\sigma 2\). This proves that there exists a
morphism \(\sigma\) from \(\langle\Sigma, S\rangle\) to \(\left\langle\Sigma^{+}, O^{+}\right\rangle\); e.g. \(\sigma=\sigma 1=\sigma 2\)


Since the top part of the diagram must also commute, \(\sigma 1=i d_{(\Sigma, S)} ; \sigma\), and identities are cancellable so uniqueness of \(\sigma\) follows immediately.

In this situation, techniques based on the pushout of signatures turn out to be irrelevant since proving that the axioms of the consequent follow from the antecedent in the pushout signature is the same as ignoring abstraction, e.g. using the rule
\[
\frac{S P 2 \models S P 1}{T_{o} D_{o} S P 2 \models T_{o} D_{o} S P 1}
\]

The lack of "proper" pushouts compels us to use abstracted institutions with a richer category of signatures such as \(S I G_{F}\) in the next section, or to use the \(\exists^{2}\)-strategy where a pushout of signatures is not required.

Apart from the lack of a "proper" pushout of signatures, \(\operatorname{Beh}(\mathbf{E Q})\) has still another problem regarding the application of the inheriting strategy.

The inheriting strategy is based on the "inheritance" of some axioms \(\Phi 1_{k}\) specifying some auxiliary hidden symbols from the consequent to the antecedent. In the context of abstraction, the auxiliary symbols include a sort which is not hidden but made non-observable; then, \(\Phi 1_{h}\) should include those axioms defining
the auxiliary sort. Unfortunately, in \(\operatorname{Beh}(\mathbf{E Q})\) it does not make sense for an axiom to specify a sort; in other words, it is not possible to divide the equations of a specification in two, those specifying the sorts and those specifying the functions on those sorts.

This situation is improved in the institution of first order logic where equality is defined as an ordinary predicate. In this case, the definition of the equality predicate for non-observable sorts plays the role of \(\Phi 1_{h}\) in the inheriting strategy. Also in a institution with equational logic and reachability constraints" (see next chapter), the situation is improved since equations among generators and the reachability constraint itself can play the role of \(\Phi 1_{h}\).

\section*{Using the \(\exists^{2}\)-strategy}

Due to the difficulties discussed above entailment proofs in \(\operatorname{Beh}(\mathbf{E Q})\) as in Task 1 have to rely on the \(\exists^{2}\)-strategy:
\[
\frac{D_{\sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} S P 2 \models S P 1 \quad D_{\sigma 2} S P 2 \models D_{\sigma 1 ; \sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) D_{\sigma 2} S P 2}{D_{\sigma 2} S P 2 \models D_{\sigma 1} S P 1}
\]
where \(\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right)\) is an enrichment to the antecedent (implementation) which must be guessed. Considering \(\sigma 1\) and \(\sigma 2\) to be an abstraction morphism \(o: \Pi \rightarrow \Sigma\) we obtain
\[
\frac{D_{\sigma}\left(A_{\Phi} T_{\sigma}\right) T_{o} D_{o} S P 2 \models S P 1 \quad D_{o} S P 2 \models D_{o ; \sigma}\left(A_{\Phi} T_{o ; \sigma}\right) D_{o} S P 2}{D_{o} S P 2 \models D_{o} S P 1}
\]
where \(\Phi\) is a set of \(\Sigma\)-sentences.
The second premise of the rule requires \(\left(A_{\Phi} T_{o ; \sigma}\right)\) to be persistent w.r.t. \(D_{o} S P 2\). In the particular case where \(\sigma\) is the identity, it means that \(\Sigma\)-sentences in \(\Phi\) should not exclude any model (behaviour) in \(\operatorname{Mod}\left[D_{o} S P 2\right]\); hence \(\Phi\) may include \(\Sigma\)-sentences without observable consequences. Phrasing the same idea the other way round we obtain the following proposition:

Proposition 5.4.2 Given an observational and well-behaved institution \(\alpha_{\text {Obs }} \mathrm{I}\), an abstraction morphism \(o: \Pi \rightarrow \Sigma\), specifications SP2 and SP1 over \(\Sigma\) and a set of \(\Sigma\)-sentences \(\Phi\) such that no consequence of \(\Phi\) is observable in \(\Pi\), i.e. \(C l(\Phi) \cap O b s_{\Pi}=\emptyset\), then
\[
\frac{A_{\Phi} T_{o} D_{o} S P 2 \models S P 1}{D_{o} S P 2 \models D_{o} S P 1}
\]
is sound.
Proof Take an arbitrary model \(M\) in \(\operatorname{Mod}\left[D_{o} S P 2\right]\). According to the semantics of \(D_{\sigma}, M\) is the \(o\)-reduct of a \(\Sigma\)-model \(A\) in \(M o d[S P 2]\),
\[
M=\left.A\right|_{0} \quad A \in \operatorname{Mod}[S P 2]
\]

Divide \(O b s_{\Pi}\) into two sets of observations \(O\) and \(\bar{O}\) such that
\[
A \models_{\Sigma} O \quad A \not \neq \Sigma^{\bar{O}}
\]

Since \(\Phi\) has no observable consequences, \(A\) satisfies \(\left(C l(\Phi) \cap O b s_{\Pi}\right) \cup O\) and, by definition of well-behaved institution, there exists a \(\Sigma\)-model \(B\) such that
\[
B \models_{\Sigma} \Phi \cup O \quad B \nVdash_{\Sigma} \bar{O}
\]

Moreover, \(B\) satisfies the same observations as \(A\) therefore, in an observational institution, we know that
\[
M=\left.A\right|_{o}=\left.B\right|_{o}
\]

Considering that the models of \(D_{o}\left(A_{\Phi} T_{o}\right) D_{o} S P 2\) are:
\[
\left\{\left.B\right|_{o} \mid B \not \models_{\Sigma} \Phi \wedge\left(\exists A \in \operatorname{Mod}[S P 2] .\left.A\right|_{o}=\left.B\right|_{o}\right)\right\}
\]
we can conclude that \(M \in \operatorname{Mod}\left[D_{o}\left(A_{\Phi} T_{o}\right) D_{o} S P 2\right]\) and in general
\[
D_{o} S P 2 \models D_{o}\left(A_{\Phi} T_{o}\right) D_{o} S P 2
\]

Considering that this entailment holds, the rule proposed is a particular case of the \(\exists^{2}\)-strategy, hence soundness follows.

In order to understand well the strength of the \(\exists^{2}\)-strategy it is important noting that \(S P 2\) and \(\Phi\) affect the specification
\[
A_{\Phi} T_{o} D_{o} S P 2
\]
at different levels, contrary to what happens in a specification such as \(T_{o} D_{o} A_{\Phi} S P 2\). In \(\operatorname{Beh}\) (ALG), the models of \(A_{\Phi} T_{o} D_{o} S P 2\) are algebras which satisfy \(\Phi\) and have a behaviourally equivalent algebra in \(\operatorname{Mod}[S P 2]\) whereas, in the second specification, models are algebras with a behaviourally equivalent algebra which is a model of \(S P 2\) and satisfies \(\Phi\). Therefore, a model of \(A_{\Phi} T_{0} D_{o} S P 2\) may have a behaviour the algebras of which cannot be a model of SP2 and satisfy \(\Phi\) at the same time, hence
\[
A_{\Phi} T_{o} D_{o} S P 2 \not \vDash T_{o} D_{o} A_{\Phi} S P 2
\]

In relation to the \(\exists^{2}\)-strategy, this means that an enrichment \(\left(A_{\Phi} T_{o}\right)\) may be persistent w.r.t. \(D_{o} S P 2\) despite the fact that neither ( \(A_{\Phi} T_{i d_{\Sigma}}\) ) nor ( \(T_{0} D_{o} A_{\Phi} T_{i d_{\Sigma}}\) ) are persistent w.r.t. \(S P 2\). This last situation arises in the following example.

Consider the following purported entailment:
\[
D_{o} S P 2 \models D_{o} S P 1
\]
where \(S P 2\) and \(S P 1\) are specifications as in figure \(5-1\) and \(o\) is an abstraction morphism which makes sort \(s\) non-observable, i.e. \(o:\{\langle\{s\},\{a, b\}\rangle, \emptyset\rangle \rightarrow\) \(\langle\langle\{s\},\{a, b\}\rangle,\{s\}\rangle\).

Using the \(\exists^{2}\)-strategy and taking \(\sigma\) to be the identity morphism and \(\Phi\) to be \(\{a \neq b\}\), we are required to prove that
\[
\begin{gathered}
A_{\{a \neq b\}} T_{o} D_{o} S P 2 \models S P 1 \\
D_{o} S P 2 \models D_{o}\left(A_{\{a \neq b\}} T_{o}\right) D_{o} S P 2
\end{gathered}
\]

The first entailment holds trivially since the only axiom in SP1 follows immediately from the antecedent using the inference rules shown for \(A_{\Phi}\) in chapter 2.
\begin{tabular}{|c|c|}
\hline \multirow[t]{6}{*}{\(S P 1=\)} & sorts s \\
\hline & operations \\
\hline & a : s \\
\hline & b : s \\
\hline & axioms \(\mathrm{a} \neq \mathrm{b}\) \\
\hline & end \\
\hline \multirow[t]{6}{*}{\(S P 2=\)} & sorts s \\
\hline & operations \\
\hline & a: s \\
\hline & b : s \\
\hline & axioms a \(=\mathrm{b}\) \\
\hline & end \\
\hline
\end{tabular}

\section*{Figure 5-1:}

The second entailment requires the persistency of the chosen enrichment. In an observational and well-behaved institution this is also trivial since \(a \neq b\) has no observable consequences. Otherwise, we should check that each algebra satisfying \(a=b\) is behaviourally equivalent to another algebra satisfying \(a \neq b\) w.r.t. the set \(\emptyset\) of observable sorts. In this case, this is not difficult to verify since no sort is observable and \(\{a \neq b\}\) is a consistent presentation.

On the other hand, it is clear that \(A_{\{a \neq b\}} S P 2\) is inconsistent and therefore
\[
D_{o} S P 2 \not \models D_{o} A_{\{a \neq b\}} S P 2 \quad D_{o} S P 2 \not \models D_{o} T_{o} D_{o} A_{\{a \neq b\}} S P 2
\]

When this kind of situation does not arise, we can use the following simplified rule
\[
\frac{A_{\Phi} T_{o} D_{o} S P 2 \models S P 1 \quad D_{o} S P 2 \models D_{o} A_{\Phi} S P 2}{D_{o} S P 2 \models D_{o} S P 1}
\]
since
\[
D_{o} A_{\Phi} S P 2 \models D_{o} A_{\Phi} T_{o} D_{o} S P 2
\]
follows immediately from \(S P 2 \vDash T_{o} D_{o} S P 2\) and the monotonicity of the SBO's.

\subsection*{5.4.2 Behavioural abstraction and first order logic}

Work done in the context of the algebraic institution EQ can be repeated for FOL and FOLEQ considering predicates to be functions delivering values of a distinguished observable sort Bool. In this section we take a different but rather common approach, suitable to institutions where equality is treated as an ordinary predicate which does not need to be the identity in the models. In this case, pushouts of abstracted signatures can contain two different equality relations, one from the consequent specification and one from the antecedent specification, leading to proof techniques based on the handling of different equalities during the proof of refinement, as in [Wan 82]. This approach generalizes the so-called ultra-loose approach where equality is treated as an ordinary predicate [WB 89], in this case visible.

Technically first order signatures (from \(S I G_{F}\) ) play the role of the signatures of the abstracted institution among which we distinguish a subcategory of signatures to play the role of "original" signatures, namely, those signatures with a single predicate "三s" for each sort \(s\).

Definition 5.4.3 Recall that \(S I G_{F}\) is the category of multisorted first order signatures as defined in section 2.5. SIG \(\equiv\) is its full subcategory with objects: pairs \(\langle\Sigma, Q\rangle\) where \(\Sigma=\langle S, \Omega\rangle\) is an algebraic signature, \(\Sigma \in|S I G|\), and \(Q\) is a \(S\)-sorted set where each \(Q_{s}\) is a singleton \(\left\{\equiv_{s}\right\}\).

Then, the inclusion functor \(S I G_{\equiv} \hookrightarrow S I G_{F}\) forms a reflection with a functor \(C\) as follows:

Lemma 5.4.4 A functor \(C: S I G_{F} \rightarrow S I G_{\equiv}\) defined over every signature \(\langle\Sigma, Q\rangle\) and morphism \(\langle\sigma, f\rangle:\langle\Sigma 1, Q 1\rangle \rightarrow\langle\Sigma 2, Q 2\rangle\) in \(S I G_{F}\) as
\[
\begin{gathered}
C(\langle\Sigma, Q\rangle)=\left\langle\Sigma,\left\{\left\{\equiv_{s}\right\} \mid s \in \operatorname{Sorts}(\Sigma)\right\}\right\rangle \\
C(\langle\sigma, f\rangle)=\left\langle\sigma,\left\{P \mapsto \equiv_{\sigma(s)} \mid P \in Q 1_{s} \text { and } s \in \operatorname{Sorts}(\Sigma 1)\right\}\right\rangle
\end{gathered}
\]
is a left adjoint of the inclusion \(S I G_{=} \hookrightarrow S I G_{F}\) with unit \(\mathbf{o}\) where \(o_{\langle\Sigma, Q\rangle}=\left\langle i d_{\Sigma}, c_{Q}\right\rangle\) and \(c_{Q}\) is the unique \(S\)-sorted function from each set of relations \(Q_{s}\) to the singleton \(\left\{\equiv_{s}\right\}\).

Proof We shall prove that for each signature \(\langle\Sigma, Q\rangle\) in \(S I G_{F}\), its unit morphism \(\left\langle i d_{\Sigma}, c_{Q}\right\rangle:\langle\Sigma, Q\rangle \rightarrow\left\langle\Sigma,\left\{\left\{\equiv_{s}\right\} \mid s \in \operatorname{Sorts}(\Sigma)\right\}\right\rangle\) is a universal arrow.


Let \(\langle\sigma, f\rangle\) be an arbitrary morphism as in the diagram, then there is a unique \(\left\langle\sigma^{\prime}, f^{\prime}\right\rangle\) making the diagram commute \(\left\langle i d_{\Sigma}, c_{Q}\right\rangle ;\left\langle\sigma^{\prime}, f^{\prime}\right\rangle=\langle\sigma, f\rangle\) since:
1. there is a unique \(\sigma^{\prime}\) such that \(i d_{\Sigma} ; \sigma^{\prime}=\sigma\), that is \(\sigma^{\prime}=\sigma\),
2. there is a unique function \(f^{\prime}\) sorted by \(\operatorname{Sorts}(\Sigma)\) with codomain \(\left\{\left\{\equiv_{s}\right\} \mid s \in\right.\) \(\left.\operatorname{Sorts}\left(\Sigma^{\prime}\right)\right\}\) since each \(\left\{\equiv_{s}\right\}\) is a singleton, and singletons are final objects in Set.

Considering the institution of first order logic FOL, we can define an institution FOL \(\equiv\) which restricts FOL to the category of signatures \(S I G_{\equiv}\).

Taking into account the functor \(C\) in the previous lemma, the institution morphism (inclusion) from FOL \(_{\equiv}\) to \(\mathbf{F O L}\) is an abstracting institution morphism. Therefore, hiding of equality can be formalized as an abstraction operator along an abstraction morphism such as \(\left\langle i d_{\Sigma}, c_{Q}\right\rangle\).

An abstraction operation \(T_{\left(i d_{\Sigma}, c_{Q}\right)} D_{\left(i d_{\Sigma}, c_{Q}\right)}\) w.r.t. an arbitrary abstraction mor\(\operatorname{phism}\left\langle i d_{\Sigma}, c_{Q}\right\rangle:\langle\Sigma, Q\rangle \rightarrow\left\langle\Sigma,\left\{\left\{\equiv_{s}\right\} \mid s \in \operatorname{Sorts}(\Sigma)\right\}\right\rangle\) in FOL relaxes the meaning of equality of those sorts with an empty \(Q_{s}\) in the abstracted signature. If \(Q_{s}\) is empty, \(D_{\left\langle i d_{\Sigma}, c_{Q}\right\rangle}\) hides " \(\equiv_{s}\) " and \(T_{\left\{i d_{\Sigma}, c_{Q}\right\rangle}\) restores it with an arbitrary meaning, so that after the abstraction the equality symbol can denote an arbitrary predicate. If \(Q_{s}\) is not empty \(D_{\left(i d_{\Sigma}, c_{Q}\right\rangle}\) makes several copies of the identity and \(T_{\left(i d_{\Sigma}, c_{Q}\right)}\) collapses them again, so that the resulting predicate is again the same.

Considering the inheriting strategy, abstraction w.r.t. \(\mathrm{FOL}_{\equiv} \rightarrow\) FOL has two advantages over abstraction w.r.t. \(\mathbf{E Q} \rightarrow \mathbf{B e h}(\mathbf{E Q})\).

In first place, the category of abstract signatures \(S I G_{F}\) is rich enough to include "proper" pushouts.

Proposition 5.4.5 The following diagram is a pushout in \(S I G_{F}\)

where \(i 1\) and \(i 2\) form a pushout in Set w.r.t. the two \(c_{Q}\) and \(\uplus\) denotes disjoint union.

Proof It must be a pushout since it is the pairing of two pushouts in \(S I G\) and Set respectively.

Such pushouts are very important when proving entailment between abstracted specifications because they allow the hidden equalities of the antecedent and the consequent to be combined in a single signature, as is common practice in the case of hidden functions.

The second advantage concerns the identification of some axioms as specifying the hidden part. Since equality is treated as an ordinary predicate, some axioms specifying \(\equiv\) are included in the specification. Then, equality predicates on non-observable sorts are regarded as auxiliary functions defined in the hidden enrichment and the axioms specifying these predicates are regarded as axioms \(\Phi 1_{h}\) in the inheriting strategy.

This kind of abstraction is weaker than behavioural abstraction. Models of an abstracted signature are reducts forgetting the equality symbols but not the carriers of the non-observable sorts; consequently \(\left.A\right|_{o}=\left.B\right|_{o}\) implies that \(|A|_{s}=|B|_{s}\) for all sorts \(s\), therefore \(T_{o} D_{o}\) does not mean behavioural abstraction. Nevertheless, treating abstraction as the hiding of \(\equiv\) results in a sound proof strategy and many practical implementations such as stacks implemented by array-pointer pairs, can be proven correct in this fashion.

There are still a number of issues which make the hiding of equality a very peculiar kind of of hiding.

We know from chapter 4 that the inheriting strategy is sound only for persistent hidden enrichments and complete when the hidden enrichment is independent w.r.t. the visible enrichment and the basic specification.

In the case of abstraction w.r.t. FOL \(_{\equiv} \rightarrow\) FOL, the definition of equality predicates frequently violates persistency and is very rarely independent.

Consider for example the specification of stacks Stack in figure \(5-2^{7}\). Axioms like
\[
\forall \text { s:stack; e:elem. pop(push }(s, e)) \equiv \text { stack } s
\]
or even
\[
\forall s, s^{\prime}: s t a c k . s \equiv_{s t a c k} s^{\prime} \Rightarrow \operatorname{pop}(s) \equiv_{s t a c k} p o p\left(s^{\prime}\right)
\]
violate independence because the interpretation of pop (visible enrichment) is dependent on the interpretation of \(\equiv_{\text {stack }}\) (hidden enrichment).

Usually lack of independence forces the user to complete those axioms defining the hidden part \(\Phi 1_{h}\) (see section 4.7). In the case of Stack implemented by arrays with pointers, the extra axioms correspond to the definition of \(\equiv_{\text {stack }}\) in terms of the implementation. This fact prevents, in the context of FOL, entailment proofs with abstracted consequents from being fully automatized.

A more serious problem is the lack of persistency. In the context of hiding auxiliary functions, this was regarded as a bug in the specification design (see section 4.7).

In the case of abstraction in FOL, persistency is violated if the definition of \(\equiv{ }_{s}\) for a non-observable sort \(s\) imposes requirements on the structure of the carrier set.

\footnotetext{
\({ }^{7}\) Note that predicates are added to the concrete syntax defined in chapter 2 in order to represent specifications in \(A S L(\mathbf{F O L})\).
}
```

SElem = sorts stack, elem
predicates _ =elem -: elem }\times\mathrm{ elem
operations
axioms
\foralle:elem. e\equiveleme
\foralle1,e2:elem. e1 \elem}e2=>e2\equivelem e1

```

```

end

```

Stack \(=\) Enrich SElem by
Hidden
sorts
predicates _ \(\equiv_{\text {stack }}\) : stack \(\times\) stack
operations
axioms
\(\forall\) s:stack. \(s \equiv_{s t a c k} s\)
\(\forall \cdot s 1, s 2: s t a c k . s 1 \equiv_{s t a c k} s 2 \Rightarrow s 2 \equiv_{s t a c k} s 1\)
\(\forall \mathrm{s} 1, \mathrm{~s} 2, \mathrm{~s} 3: \mathrm{stack} .\left(\mathrm{s} 1 \equiv_{\mathrm{stack}} \mathrm{s} 2 \wedge \mathrm{~s} 2 \equiv_{\mathrm{stack}} \mathrm{s} 3\right) \Rightarrow \mathrm{s} 1 \equiv_{\mathrm{stack}} \mathrm{s} 3\)
in
sorts
predicates
operations
empty: stack
push: stack, elem -> stack
top: stack -> elem
pop: stack -> stack
axioms
[1] \(\forall\) s:stack; e:elem. pop(push(s, e)) \(\equiv_{\text {stack }} s\)
\(\forall\) s:stack; e:elem. top(push(s, e)) \(\equiv_{e l e m}\) e
\(\forall \mathrm{s}, \mathrm{s}^{\prime}:\) stack. \(s \equiv_{\text {stack }} s^{\prime} \Rightarrow\left(\operatorname{pop}(s) \equiv_{s t a c k} p o p\left(s^{\prime}\right) \wedge\right.\) top \(\left.(s) \equiv_{\text {elem }} t o p\left(s^{\prime}\right)\right)\)
\(\forall \mathrm{s}, \mathbf{s}^{\prime}: \mathrm{stack}^{\prime}, \theta, \theta^{\prime}:\) elem. \(\left(s \equiv_{s t a c k} s^{\prime} \wedge e \equiv_{\text {elem }} \Theta^{\prime}\right) \Rightarrow \operatorname{push}(s, e) \equiv_{s t a c k} \operatorname{push}\left(s^{\prime}, e^{\prime}\right)\)
end

For example, we can write first order axioms specifying \(\equiv s\) to be an equivalence relation such that \(\neg(\mathrm{a} \equiv \mathrm{s} \mathrm{b})\) analogously to \(S P 1\) in figure \(5-1\). This means that no model can assign the same values to constants a and b , thus the definition of \(\equiv_{s}\) (hidden enrichment) is not persistent w.r.t. an empty specification \(\epsilon_{\{\{s\},\{a, b\}\}}\). In consequence, implementations analogous to \(S P 2\) in figure 5-1 assigning the same value to non-observable constants \(a\) and \(b\) are incorrect.

In such cases the lack of persistency can be understood as an indication that the hiding of \(\equiv\), is not a good method for treating abstraction.

This is not only true for the inheriting strategy but also for the \(\exists^{2}\)-strategy since in such an example no persistent enrichment to
```

SP2 = sorts s
predicates _ =s_: s < s
operations
a: s
b: s
axioms a=sb
end

```
 time.

On the other hand, if only first order sentences of the form \(\forall X . t 1 \equiv_{s} t 2\) are considered, then all hidden enrichments specifying \(\equiv_{s}\) are persistent. This is in fact what happens in equational specifications such as Stack when equations are "read" as first order sentences in which the equality symbol denotes a congruence relation.


Figure 5-3: Automaton specified in Automat

\subsection*{5.5 Example}

To close this chapter, we shall dedicate some time to the case of finite automata. This example was used in the introduction of the chapter and it is at the very origin of the whole issue of behavioural abstraction.

We shall sketch three correctness proofs for three similar specification entailments in Beh(ALG). In each case, we prove that an abstract specification of the automaton Automat in figure \(5-3\) is implemented by a specification of the automaton ImplAut in figure 5-4, but the notion of abstraction is different in each case. This gives an idea of the trade-off between abstraction and proof complexity, as well as exhibiting the smooth transition from hiding to behavioural abstraction.

Consider the first order specification of a five-state automaton in figure 5-5. Intuitively, Automat specifies a five state automaton as in figure \(5-3\) with a final state \(f\) and an error state \(e\). The transitions are computed by a function \(t\) and a predicate v_check determines the sequences of values accepted by the automaton,


Figure 5-4: Automaton specified in ImplAut
in this case the language:
\[
a a^{*} b
\]

State 1 accepts the first \(a\), state 2 accepts the second a or an ending \(b\), and state 3 accepts successive a's or an ending \(b\). The same language can be recognized by a four state automaton where 2 and 3 are combined into a single state.

Imagine that we choose an implementation with a single state for 2 and 3 , and two error states discriminating the errors produced after the final state from the others, as in figure 5-4. This can be formalized as the specification ImplAut in figure 5-6.

Now we shall prove that \(D_{\sigma 2}\) ImplAut \(\models D_{\sigma 1}\) Automat for appropriate morphisms \(\sigma 2\) and \(\sigma 1\). Three different cases are considered.

Visible v_check In the first case we choose \(\sigma 1\) and \(\sigma 2\) to be inclusions with source signature
\[
\begin{aligned}
\downarrow \sigma 1=\downarrow \sigma 2= & \text { sorts } \mathrm{v}, \text { bool, list of } \mathrm{v} \\
& \text { operations } \mathrm{a}, \mathrm{~b}: \mathrm{v}
\end{aligned}
\]
```

Automat = sorts
state, v, bool, list of v
operations
e,f,1,2,3: state
a,b: v
true, false: bool
[]: list of v
-::-: v, list of v -> list of v
t: state, v -> state
check: state, list of v -> bool
v_check: list of v -> bool
axioms
a\not=b ^( ( \forallx:v. (x=a) \vee( }\textrm{x}=\textrm{b})
true\not=false ^ ( }\forallx:bool. (x=true) V(x=false) )
{Some axioms defining list of v, [] and ::} }
|}:v.,t(e,x)=e^t(f,x)=
t(1,a)=2\wedget(1,b)=e ^t(2,a)=3 ^t(2,b)=f
t(3,a)=3 ^ t(3,b)=f
s:state. (s=1)\vee(s=2)\vee(s=3)\vee(s=e)\vee(s=f)
1\not=2\wedge 1\not=3 ^ 1\not=e ^ 1\not=f
2\not=3 ^ 2\not=e ^ 2\#f
3\not=e ^ 3\not=f
e\not=f
check(f,[])= true
*s:state. (s\not=f) => check(s,[])= false
*:state; h:v; tl:list of v.
check(s,h::tl)=check(t(s,h),tl)
\foralll:list of v. v_check(1)=check(1,1)
end

```

Figure 5-5: Automaton recognizing \(a a^{*} b\), version 1
\(\dagger\) Details on the specification of lists of values are omitted. In the following chapter we shall see how reachability constraints can be used as sentences.
```

ImplAut = sorts
state, v, bool, list of v
operations
e1,e2,f,1,2: state
a,b: v
true, false: bool
[: list of v
-::-: v, list of v -> list of v
t: state, v -> state
check: state, list of v -> bool
v_check: list of v -> bool
axioms
a\not=b ^(\forallx:v. (x=a) \vee(x=b))
true\not=false ^ ( }\forall\mathbf{x:bool. (x=true)V(x=false) )
{Some axioms defining list of v, [] and ::}
|:v. t(e1,x)=e1 ^ t(e2,x)=e2 ^t(f,x)=e2
t(1,a)=2\wedget(1,b)=e1\wedget(2,a)=2\wedget(2,b)=f
s:state. (s=1)\vee(s=2)\vee(s=e1)\vee(s=e2)\vee(s=f)
1\not=2^1\not=e1^1\not=e2^1\not=f
2\not=e1 ^ 2\not=e2 ^ 2\#f
e1\not=e2 ^ e1\not=f
e2\not=f
check(f,[])= true
*s:state. (s\not=f) \# check(s,[])= false
|:state; h:v; tl:list of v.
check(s,h::tl)=check(t(s,h),tl)
| l:list of v. v_check(1)=check(1,1)
end

```

Figure 5-6: Automaton recognizing \(a a^{*} b\), version 2
```

true, false: bool
[]: list of v
_::_: v, list of v -> list of v
v_check: list of v -> bool

```

In other words, we hide state, e, f, 1, 2, 3, t and check in Automat. This is the case of a specification with a hidden part as defined in the previous chapter and not a proper abstraction as defined in this chapter

In order to apply the inheriting strategy the specification \(D_{\sigma 1}\) Automat has to be re-written in the form of a specification with a hidden enrichment defining state, \(e, f, 1,2,3, t\) and check, and a visible enrichment defining v_check. The resulting specification looks like this:
```

Values = sorts v, bool, list of v
operations
a,b:v
true, false: bool
[]: list of v
_::_: v, list of v -> list of v
axioms
a\not=b ^(\forallx:v. (x=a) \vee (x=b) )
end

```
Automat 1 = Enrich Values by
    Hidden
        sorts state
        operations
```

            e,f,1,2,3: state
            t: state, v -> state
            check: state, list of v -> bool
    ```
```

    axioms ...
    in
sorts
operations
v_check: list of v -> bool
axioms
\forall1:list of v. v_check(1)=check(1,1)
end

```

The hidden enrichment consists of all the axioms in Automat except those defining the visible sorts v , list of v and bool and the last axiom specifying v_check. Briefly, the non-trivial part of a proof according to the inheriting strategy is to prove that:

where old_state, old_e, old_1, ... are those symbols in the pushout signature corresponding to the sort state and constants e, 1, ... in Automat 1.

In this case, the hidden enrichment is persistent w.r.t. the specification of sorts \(v\) and bool and it is also independent since the relevant states and functions of the hidden part are totally defined.

A theorem prover proceeding by induction on the list 1 completes the proof.

Visible check In the second case we choose \(\sigma 1\) and \(\sigma 2\) to be morphisms in \(\operatorname{Beh}(S I G)\) with the following abstract signature \(\Pi\) as source:
\[
\begin{aligned}
\Pi=\downarrow \sigma 1=\downarrow \sigma 2= & \text { sorts } \mathrm{v}, \text { bool, list of } \mathrm{v} \\
& \text { non_obs_sorts state }
\end{aligned}
\]
```

operations a, b: v
true, false: bool
[]: list of v
-::-: v, list of v -> list of v
check: state, list of v -> bool
v_check: list of v -> bool

```

In other words, we make the function check: state, list of \(v->\) bool visible and the sort state visible but non-observable.

In order to distinguish hiding from abstraction we decompose \(\sigma 1\) and \(\sigma 2\) into \(o\); \(\iota 1\) and into \(o ; \iota 2\) respectively, as in the diagram aside, so that the target signature of \(o\) is:

```

\Sigma=sorts v, bool, list of v, state
operations a, b: v
true, false: bool
[]: list of v
_::_: v, list of v -> list of v
check: state, list of v -> bool
v_check: list of v -> bool

```

Then, we prove that
\[
D_{o} D_{\iota 2} \text { ImplAut } \models D_{o} D_{\iota 1} \text { Automat }
\]
applying the \(\exists^{2}\)-strategy simultaneously to the hiding and the abstraction steps. This is performed by adding a persistent enrichment \(\left(A_{\Phi} T_{o ; \iota 1 ; \iota 2^{\prime}}\right)\) to the antecedent, i.e. proving that
\[
D_{\iota 2^{\prime}} A_{\Phi} T_{\iota 1 ; \iota 2^{\prime}} T_{o} D_{o} D_{\iota 2} \text { ImplAut } \vDash \text { Automat }
\]

In this case the set of \(\Sigma H\)-sentences \(\Phi\) is chosen to be the union of the following three sets:
1. Sentences specifying the hidden functions in \(D_{\iota 1}\) Automat:
```

{\forallx:v. old_t(olde,x)=olde ^ old_t(oldf, x)=olde,
old_t(old_1,a)=old2 ^ old_t(old_1,b)=old_e,
old_t(old2,a)=old_3 ^ old_t(old_2,b)=old_f,
old_t(old_3,a)=old_3 ^ old_t(old_3,b)=old_f,
\foralls:state. (s=old_1)\vee(s=old_2)}\vee(s=old_3)\vee(s=old_e)\vee(s=oldf)
old_1\not=old_2 ^ old_1\not=old_3 ^ old_1\not=old_e ^ old_1fold_f,
... }

```
where old_t, old_e, old_1, ... are those symbols in the pushout signature corresponding to the function t and constants e, 1, .. in Automat.
2. Equations between states in Automat and states in ImplAut:
```

{old_1=1 , old_2=2, old_e=e1, old_e=e2, oldf=f }

```
3. All sentences specifying the hidden functions in \(D_{\iota 2}\) ImplAut except axioms:
```

{ s:state. (s=1)\vee(s=2)\vee(s=e1)\vee(s=e2)\vee(s=f),
e1\not=e2}

```

Adding the hidden functions in \(D_{\iota 2}\) ImplAut amounts to ignore \(D_{\iota 2}\) during the proof, as it happens in the inheriting strategy. In this case, however, this cannot be done since these two axioms are inconsistent with the previous sets of sentences already included in \(\Phi\). Excluding these axioms solves the problem.

The sentences in \(\Phi\) are consistent among themselves and with the observations from \(D_{o} D_{t 2}\) ImplAut. This fact is enough to guarantee the persistency of
\(\left(A_{\Phi} T_{\iota 1 ; \iota 2^{\prime}} T_{o}\right)\) w.r.t. \(D_{o} D_{\iota 2}\) ImplAut since the specification \(D_{o} D_{\iota 2} I m p l A u t\) defines a unique behaviour (up to isomorphism).

Finally, the proof is concluded by proving that:
\[
\Phi \models\left\{\begin{array}{l}
\text { check(old_f, }[])=\text { true } \\
\forall s: s t a t e .(s \neq 0 l d f) \Rightarrow \operatorname{check}(s,[])=\text { false } \\
\forall s: s t a t e ; h: v ; \text { tl:list of } v . \\
\quad \operatorname{check}(s, h:: t l)=\operatorname{check}(o l d t(s, h), t l) \\
\forall l: l i s t \text { of } v . \\
\quad \text { v_check }(l)=\operatorname{check}\left(o l d \_1, l\right)
\end{array} .\right.
\]
which follows from the definition of check in \(\Phi\) (taken from ImplAut) considering that old \(1=1\) and old_f=f in the first, second and fourth sentence, and working case by case through each possible state \(s\) and value \(h\) in the third sentence.

Visible \(t\) Analogously to the previous case, we could also make the transition function \(t\) : state, \(v \rightarrow\) state visible and come to another solution by taking \(\Phi\) to include the definition of \(t\) in ImplAut instead of the definition of t in Automat and proving that:
\(\Phi \models\left\{\begin{array}{l}\text { check(old_f, }[])=\text { true } \\ \forall \text { s:state. }(s \neq o l d f) \Rightarrow \text { check }(s,[])=\text { false } \\ \forall \text { l:list of } v . \\ \quad \text { v_check }(1)=c h e c k\left(o l d \_1,1\right) \\ \forall x: v . t\left(o l d \_e, x\right)=o l d e ~ \\ t \\ t\left(o l d \_f, x\right)=o l d \_e \\ t\left(o l d \_1, a\right)=o l d \_2 \wedge t\left(o l d \_1, b\right)=o l d \_e ~ \\ t\left(o l d \_2, a\right)=o l d \_3 \\ t\left(o l d \_2, b\right)=o l d \_f \wedge t\left(o l d \_3, a\right)=o l d \_3 \wedge t\left(o l d \_3, b\right)=o l d \_f\end{array}\right.\)
which follows from the definition of t in \(\Phi\) (taken from ImplAut) considering that old_1=1, old_2=2, old_e=e1, old_e=e2 and old_f=f. Note that, unlike in the
previous case, the axiom
```

\foralls:state; h:v; tl:list of v. check(s,h::tl)=check(t(s,h),tl)

```
does not need to be considered since it is directly included in \(\Phi\).

There are two conclusions we can extract from these three proofs.
In first place, the situation of having a specification with a hidden part or a behaviourally abstract specification are very similar. The difference is just a technicality depending on which functions and sorts we want to hide; for example if we want to "hide" sort state but let check or \(t\) be visible, then state has to be considered as a visible but non-observable sort and the whole specification behaviourally abstracted.

The second conclusion regards the complexity of entailment proofs. The more we hide/abstract the consequent specification the harder we have to work at the level of theorem proving.

In the first case of the example we hide more than in the other two cases and a theorem prover has to perform induction over lists of values. In the last case, we hide very little and, although quite a lot of work may be involved in checking the persistency of the chosen enrichment (checking consistency of \(\Phi\) with the observable consequences of ImplAut), the actual amount of theorem proving is reduced to a few simple substitutions.

On the other hand, the use of proper abstraction in the last two cases requires choosing the right set of sentences \(\Phi\). This demands a creative task from the prover and a proof of persistency which might be very difficult to obtain.

Interpreting specifications Automat and ImplAut in first order logic and treating abstraction as the hiding of the equality predicate \(\equiv_{\text {state }}\) between states does
not lead to a correct proof of the entailment since axioms in Automat require states 2 and 3 to be different. This will also happen in the ultra-loose approach.

\section*{Chapter 6}

\section*{Specifications with reachability constraints}

\subsection*{6.1 Introduction}

This chapter is concerned with entailments where specifications use \(M_{(\sigma, c)}\), and reachability constraints in particular. We shall survey problems such as \(M T U \models\) \(M T U, D M T U \vDash D M T U\) and \(A S L \vDash A S L\). On the whole, we go over the same problems tackled before, but considering constraints \(M_{\langle\sigma,\rangle}\) and a mixture of constraints and axioms \(M A\), instead of just axioms \(A_{\Phi}\).

Some ideas from the theory of institutions, in particular, duplex institutions, allow operations such as \(M_{\{\sigma,\rangle\rangle}\) to be viewed as a special case of \(A_{\{\varphi\}}\). The only problem is that, contrary to more common institutions, duplex institutions I generally lack an underlying inference system \(\vdash^{1}\).

The reasons why a language with institution independent semantics distinguishes two operations \(A_{\Phi}\) and \(M_{(\sigma, \iota)}\) are mainly historical. Frequently, however, there is a well-known inference system for sentences whereas there is no inference system available for sentences combined with constraints.

The proving techniques related to languages ATU, DATU, DATU* and \(\alpha+\) \(A T U\) extend immediately to \(M A T U, D M A T U\) (i.e. \(A S L\) ), DMATU* (also called
\(\left.A S L^{*}\right)\) and \(\alpha+M A T U\) respectively. However, a inference system dealing with combined sets of sentences and constraints is needed.

Since the institution independent treatment of \(M_{\{\sigma, \lambda\rangle}\) with respect to proofs is very poor, we shall devote most of this chapter to working out an inference system for reachability constraints in EQ. This can be understood as a typical example of combining two different kinds of sentences with two different inference systems into one institution. Using such a popular institution also allows the whole system to be put into practice for useful specifications.

Section 2 recalls those results in the theory of institutions which allow \(M_{(\sigma, c)}\) to be regarded as a special case of \(A_{\Phi}\). Section 3 studies the particular case of reachability constraints in EQ, presenting an inference system \(H\) to cope with \(M \models M\) and an inference system \(H^{\mathrm{EQ}}\) in order to cope with \(M A \models M A\). Section 4 studies MATU, DMATU and \(\alpha+D M A T U\) as straightforward extensions of \(A T U, D A T U\) and \(\alpha+D A T U\) where axioms are a mixture of ordinary sentences and constraints.

\subsection*{6.2 Institutions with constraints}

Constraints \(M_{\langle\sigma, \downarrow\rangle}\) can be considered as sentences provided their satisfaction is invariant under change of signature (satisfaction condition).

In order not to confuse a SBO \(M_{\langle\sigma,\rangle}\) with the corresponding sentence, we introduce the following notation:

Theorem 6.2.1 Given an institution \(\mathbf{I}=\langle S I G, M o d, S e n, \models\rangle\), there exists an institution with constraints over \(\mathbf{I}, \mathbf{I}^{\prime}=\left\langle S I G, M o d, S e n^{\prime}, \models^{\prime}\right\rangle\) such that for all \(\Sigma \in|S I G|\)
- \(\operatorname{Sen}^{\prime}(\Sigma)=\operatorname{Sen}(\Sigma) \cup\{\ll \sigma, \iota \gg \mid \sigma, \iota\) are morphisms in \(S I G, \uparrow \sigma=\downarrow \iota\), and \(\uparrow\) \(\iota=\Sigma\}\)
- Sen' \(\left(\sigma^{\prime}\right)\) for a signature morphism \(\sigma^{\prime}: \Sigma \rightarrow \Sigma^{\prime}\) extends \(\operatorname{Sen}\left(\sigma^{\prime}\right)\) to take account of the new sentences so that for all \(\Sigma\)-sentences \(\ll \sigma, \iota \gg\),
\[
\operatorname{Sen}^{\prime}\left(\sigma^{\prime}\right)(\ll \sigma, \iota \gg)=\ll \sigma,\left(\iota ; \sigma^{\prime}\right) \gg
\]
- \(\models_{\Sigma}^{\prime}\) extends \(\vDash_{\Sigma}\) to take account of the new sentences so that for all \(M \in\) \(|\operatorname{Mod}(\Sigma)|\) and \(\Sigma\)-sentence \(\ll \sigma, \iota \gg, M \models_{\Sigma}^{\prime} \ll \sigma, \iota \gg\) iff \(\left.M\right|_{c}\) is \(\sigma\)-minimal.

Proof It is not difficult to see that constraints \(\langle\sigma, \iota \gg\), like ordinary sentences, satisfy the satisfaction condition. Considering an arbitrary signature \(\Sigma\), a \(\Sigma\) sentence \(<\sigma, \iota \gg\), a signature morphism \(\sigma^{\prime}: \Sigma \rightarrow \Sigma^{\prime}\) and a \(\Sigma\)-model \(M\),
\[
M \models_{\Sigma^{\prime}}^{\prime} \ll \sigma,\left(\iota ; \sigma^{\prime}\right) \gg \text { iff }\left.M\right|_{\sigma^{\prime}} \models_{\Sigma}^{\prime} \ll \sigma, \iota \gg
\]
holds trivially since \(\left.\left(\left.M\right|_{\sigma^{\prime}}\right)\right|_{\iota}=\left.M\right|_{\left(\iota ; \sigma^{\prime}\right)}\), hence both sides are satisfied if and only if \(\left.M\right|_{\left(\iota ; \sigma^{\prime}\right)}\) is \(\sigma\)-minimal.

A similar situation is explained and generalized in [GB 90], where an institution \(\mathbf{C}(\mathbf{I})\) is constructed by adding data constraints to an arbitrary institution I. Or, more generally, a duplex institution \(\mathbf{D}(\alpha)\) can be defined for an arbitrary institution morphism \(\alpha\).

It is also usual practice to prove that a particular kind of constraint satisfies the satisfaction condition and add it directly to the original institution, e.g. bounded data constraints in [Mos 89].

In terms of the specification language, \(M_{\langle\sigma, t\rangle}\) becomes superfluous since we can choose a institution with constraints \(\mathbf{I}^{\prime}\) which includes constraints as sentences so that
\[
M_{(\sigma, \iota)} S P \quad \text { can be written } \quad A_{\{<\sigma, »>\}} S P
\]

We are generally concerned with inference systems for specifications over an arbitrary institution equipped with an underlying inference system for its sentences \(\vdash^{\mathrm{I}}\). Therefore, if constraints are included in the institution, the treatment of \(M\) is transferred to the institution level which should provide an underlying inference system \(\vdash^{\mathbf{I}^{\prime}}\).

We may wonder if this is fair and why other SBO's are not transferred to the institution level. The difference is that the rest of the operations - \(T_{\sigma}, U, D_{\sigma}\) and \(\alpha\) - have a proof theoretical treatment at the institution independent level, whereas \(M_{\langle\sigma, \imath\rangle}\) only has institution independent semantics in terms of the morphisms in the category of models, and these morphisms are completely independent from the rest of the institution, in particular, independent of the sentences and their satisfaction. Therefore, nothing substantial can be said about proving entailment between specifications with constraints \(M_{(\sigma, \ell)}\) in an arbitrary institution.

Attempts to improve this situation propose to enrich the definition of institution, which would make it feasible to give \(M_{(\sigma, \gamma)}\) a proof theoretical treatment at the institution independent level. In this direction, some work is in progress [GB 86, Poi 89, Mes 89].

\subsection*{6.3 Reachability constraints}

Reachability and data constraints are introduced in specification languages in order to increase their expressive power. In particular, they are useful for the definition of standard models up to isomorphism.

It is known that axiomatizations in FOL cannot be categorical unless they describe a finite model, by the Löwenheim-Skolem theorem. Moreover, even if we restrict our models to countable ones, it is not always the case that a \(\aleph_{0}\)-categorical axiomatization exists; e.g. sound axiomatizations of arithmetic always include
non-standard countable models. Summing up, implicit or explicit reachability constraints are needed if we want to be able to talk about things such as the standard model of arithmetic in a first order language.

In nature, a reachability constraint can be seen as a second order axiom or an infinitary axiom. For example, arithmetic can be defined up to isomorphism by
\[
\forall P .(P(0) \wedge(\forall n . P(n) \Rightarrow P(\operatorname{suc}(n))) \Rightarrow(\forall n . P(n))
\]
or by
\[
\forall n .(n=0) \vee(n=\operatorname{suc}(0)) \vee(n=\operatorname{suc}(\operatorname{suc}(0))) \vee \ldots
\]

However, there is no complete inference system for second order logic [Bar 77], \({ }^{\boldsymbol{+}}\) and inference systems for infinitary logic \(L_{\omega_{1} \omega}\) use infinitary rules in order to be complete [Sco 66].

On the other hand, a reachability constraint provides a sound induction schema which can be added to our inference system as described in in section 3.3.2 and, what is more important, entailment can still be proved correct by relating the reachability constraints used in the antecedent and the consequent. In fact, what is a disadvantage when we try to prove theorems from a constrained specification, becomes an advantage when proving entailment.

For example, in FOL an entailment \(S P 2 \vDash M_{\{s\}} S P 1\) can only be correct if \(S P 2\) also contains a reachability constraint on sort \(s\) or all the models of \(S P 2\) have a finite carrier for sort \(s\). Otherwise, by the Löwenheim-Skolem theorem, there would exist some infinite models of \(S P 2\) having a carrier of \(s\) of a higher cardinality than in any model of \(M_{\{s\}} S P 1\).

But before we start intermixing constraints with other sentences, let us focus on a simpler case.
[Bar 77] Ch.A.1, \(\oint 5\) and [BJ 80] page 203

\subsection*{6.3.1 A logic of reachability constraints}

In this section we produce an inference system for specifications \(M \models M\) in EQ. Or, in other words, we find an adequate underlying inference system for an algebraic institution whose only sentences are reachability constraints. We shall call this system \(H^{H}\).

First, an inference system can be given capturing those cases where a constraint is strictly stronger than another one; e.g. when the generators of every sort are preserved or reduced in the antecedent, while the set of constrained sorts is preserved or enlarged. These cases correspond to trivial cases that can be automatically checked, and indeed they are very much used in practice.

We start by recalling some notation from chapter 2 . There, we decided that algebraic specifications \(M_{\langle\sigma, \iota\rangle} S P\) for signature inclusions \(\sigma\) and \(\iota\) as follows:
\[
\langle S, \emptyset\rangle \stackrel{\sigma}{\hookrightarrow}\langle S \cup G, F\rangle \stackrel{\iota}{\hookrightarrow}\left\langle S^{\prime}, \Omega^{\prime}\right\rangle
\]
will be written \(M_{\langle G, F, S\rangle} S P\). Moreover, in this situation, an algebra over \(\langle S \cup G, F\rangle\) is \(\sigma\)-minimal if it is reachable on sorts \(G\). In other words, given a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-algebra \(A\) its \(\ell\)-reduct is \(\sigma\)-minimal if there is a \(S\)-sorted set of variables \(X\) (disjoint from \(\Omega\) ) such that for every value \(v \in|A|_{r}\) of a sort \(r \in G\) there exists a term \(t_{v} \in\left|T_{\langle S \cup G, F\rangle}(X)\right|\) and a valuation \(\nu:\left.T_{\langle S \cup G, F\rangle}(X) \rightarrow A\right|_{\iota}\) such that \(\nu\left(t_{v}\right)=v\).

Reachability constraints are sentences in an institution with constraints over \(\mathbf{E Q}\), therefore a reachability constraint \(M_{\langle G, F, S\rangle}\) is a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg\). In general, a triple \(\ll G, F, S \gg\) is a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence if \(G\) and \(S\) are disjoint. \(G \cup S \subseteq S^{\prime}\), functions names in \(F\) use sorts in \(S \cup G\) and \(F \subseteq \Omega^{\prime}\). Henceforth. \(\Sigma\)-sentences which happen to be constraints are called \(\Sigma\)-constraints.

In this section we shall restrict our attention to reachability constraints of the form \(\ll G, F, S \gg\). This can be done without loss of generality if we consider
only injective signature morphisms, so that a reachability constraint \(\ll G, F, S \gg\) translated along \(\sigma^{\prime}\) is equivalent to \(\ll \sigma^{\prime}(G), \sigma^{\prime}(F), \sigma^{\prime}(S) \gg\). For non-injective morphisms this is not generally true since two generated sorts could be identified into a single sort having as generators all the generators of the two original sorts.

In the following we shall define which are the generator operations of a generated sort and which generated sorts are one-point.

Definition 6.3.1 Given a signature \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\), the generators of a generated sort \(r \in G\) w.r.t. a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg\), are the constants \(k: r\) and operations \(f: \bar{s} \rightarrow r\) used in the set of terms \(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{r}\) where \(X_{S}\) is a non-empty \(S\)-indexed set of variables. The generators of \(r\) w.r.t. \(\ll G, F, S \gg\) are denoted by \(F_{r}\).

A generated sort \(r \in G\) is one-point w.r.t. a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg\) if \(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{r}\) is a singleton for \(X_{S}\) being a \(S\)-indexed set of variables with at least two variables of each sort.
\(A\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg\) is \(\emptyset\)-free iff for all sorts \(r\) in \(G\),
\[
\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{r} \neq \emptyset
\]
where \(X_{S}\) is a non-empty \(S\)-indexed set of variables.

Note that the union of all generators \(\bigcup_{r \in G} F_{r}\) can be smaller than \(F\) due to an operation op: \(\bar{s} \rightarrow s \in F\) over an unconstrained sort \(s \notin G\) or due to a sort \(r \in G\) which has no terms \(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{r}=\emptyset\) despite having an operation \(o p: \bar{s} \rightarrow r \in F\).

Consider the following example:
\[
S=\{s 1, s 2\} \quad \Omega=\{f 1: s 1 \rightarrow s 2
\]
\[
\begin{gathered}
c 1: s 2 \\
c 2: s 2\} \\
G=\{s 3, s 4\} \quad F=\{f 2: s 1, s 2 \rightarrow s 3 \\
f 3: s 2, s 3 \rightarrow s 1 \\
f 4: s 4 \rightarrow s 3 \\
\\
f 5: s 4 \rightarrow s 4\}
\end{gathered}
\]

In the term model \(T_{\{S \cup G, \Omega \cup F\}}\), the carriers of \(s 1, s 3\) and \(s 4\) are empty, and \(\left|T_{\langle S \cup G, \Omega \cup F\rangle}\right|_{s 2}=\{c 1, c 2\}\). In the free generated model \(T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\), the carrier of \(s 4\) is still empty but the carriers of \(s 1, s 2\) and \(s 3\) are infinite:
\(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{s 1}=\{x, z, f 3(y, f 2(x, y)), f 3(y, f 2(x, f 2(z, y))), \ldots\}\)
\(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{83}=\{f 2(x, y), f 2(x, f 2(z, y)), f 2(f 3(y, f 2(x, y)), y), \ldots\}\)
for all \(x, z \in X_{s 1}\) and \(y \in X_{s 2}\). At the same time \(F_{s 3}=\{f 2\}\) and \(F_{s 4}=\emptyset\).

Using these definitions it is possible to prove the following results about consistency in a language of reachability constraints.

Lemma 6.3.2 All models of a \(\Sigma\)-constraint \(\ll G, F, S \gg\) are isomorphic to a persistent extension of a quotient of \(T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\) for some \(S\)-indexed set of variables \(X_{S}\).

Proof Given an arbitrary \(\Sigma\)-algebra \(A \models_{\Sigma} \ll G, F, S \gg\), take \(X_{S}\) to be an \(S\) indexed set of variables with as many variables in each sort \(s \in S\) as values in \(|A|_{s}\). By definition of finitely generated and construction of \(T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\), there is a surjective homomorphism \(h:\left.T_{\langle S \cup G, F\rangle}\left(X_{S}\right) \rightarrow A\right|_{\iota}\) for \(\iota:\langle S \cup G, F\rangle \rightarrow\) \(\Sigma\). Considering the kernel induced by \(h\), we conclude that \(\left.A\right|_{c}\) is isomorphic to \(T_{\langle S \cup G, F\rangle}\left(X_{S}\right) / \operatorname{Ker}(h)\).

Proposition 6.3.3 Some results about consistency are the following:
1. Every individual \(\langle S \cup G, F\rangle\)-sentence \(\ll G, F, S \gg\) is consistent \({ }^{1}\).
2. Every finite set of \(\emptyset\)-free reachability constraints over a signature is consistent.

Proof The first fact can be proven considering that a term generated model \(T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\) for any \(S\)-indexed set of variables \(X_{S}\) satisfies trivially \(<\dot{G}, F, S \gg\).

The second fact can be proven considering a final \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-algebra \(\perp\). In this case all terms \(\left|T_{\langle S \cup G, F\rangle}\left(X_{S}\right)\right|_{\text {, for every }}\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg, S\)-indexed set of variables \(X_{S}\) and sort \(s \in S^{\prime}\), evaluate to the same value in \(\perp\). Hence the existence of a term for each sort in \(G\) guarantees reachability, \(\perp \vDash_{\left(S^{\prime}, \Omega^{\prime}\right)}\) \(\ll G, F, S \gg\).

Despite these results, it is not easy to check if an arbitrary set of reachability constraints is consistent or not.

For example consider the following \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-constraints:
\[
\begin{gathered}
S^{\prime}=\{s 1, s 2, s 3\} \quad \Omega^{\prime}=\{f 1: s 1 \rightarrow s 2 \\
f 2: s 1 \rightarrow s 3 \\
c 2: s 2 \\
c 1=\ll\{s 2, s 3\},\{f 1, f 2\},\{s 1\} \gg \quad c 2=\ll\{s 3\}, \emptyset, \emptyset \gg
\end{gathered}
\]

\footnotetext{
\({ }^{1}\) Note that a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-sentence \(\ll G, F, S \gg\) may not be consistent because a sort \(r \in G\) has no generators but there exists a function symbol in \(\Omega^{\prime} \backslash F\) with co-arity \(r\).
}

Constraint \(c 2\) requires the carrier of sort \(s 3\) to be empty since no generators or generating sorts are included. Constraint \(c 1\) requires carriers of \(s 2\) and \(s 3\) to be generated from \(s 1\) using functions \(f 1\) and \(f 2\); if \(s 3\) has an empty carrier \(s 1\) and \(s 2\) must also have empty carriers. Finally, since \(\Omega^{\prime}\) includes a constant \(c 2: s 2\), the carrier of sort \(s 2\) cannot be empty in any \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-algebra, hence the union of \(c 1\) and \(c 2\) is inconsistent.

Assumption From now on, we assume our constraints to be \(\emptyset\)-free. This can be effectively checked and guarantees consistency, which is a rather natural condition for a specification building operation.

Definition 6.3.4 A consequence relation \(\vdash\) between \(\Sigma\)-constraints is defined as \(\ll G 2, F 2, S 2 \gg \vdash \ll G 1, F 1, S 1 \gg\) iff the following two conditions hold:
1. All generated sorts are inherited: \(G 1 \subseteq G 2\).
2. For all generated sorts \(r \in G 1\), no new generators are added, \(F 1_{r} \supseteq F 2_{r}\), or \(r\) is a one-point sort w.r.t. \(\ll G 2, F 2, S 2 \gg\).

Theorem 6.3.5 Given two \(\emptyset\)-free \(\Sigma\)-constraints \(\ll G 1, F 1, S 1 \gg\) and \(\ll G 2, F 2, S 2 \gg\), then
\[
\ll G 2, F 2, S 2 \gg \vDash<G 1, F 1, S 1 \gg \quad \text { iff } \quad \ll G 2, F 2, S 2 \gg \vdash \ll G 1, F 1, S 1 \gg
\]

Soundness proof Let \(\iota 1\) and \(\iota 2\) be the inclusions \(\langle S 1 \cup G 1, F 1\rangle \hookrightarrow \Sigma\) and \(\langle S 2 \cup G 2, F 2\rangle \hookrightarrow \Sigma, A\) a \(\Sigma\)-model of \(\ll G 2, F 2, S 2 \gg\) and assume \(\ll G 2, F 2, S 2 \gg \vdash\) \(\ll G 1, F 1, S 1 \gg\). Then, by definition of satisfaction, every value \(v \in|A|_{T}\) for \(r \in G 2\) can be reached by some term \(t \in\left|T_{\langle S 2 \cup G 2, F 2\rangle}\left(X_{S 2}\right)\right|_{r}\) for an \(S 2\)-indexed set of variables \(X_{S 2}\) and a valuation \(\nu 2:\left.T_{\langle S 2 \cup G 2, F 2\rangle}\left(X_{S 2}\right) \rightarrow A\right|_{\iota 2}\),
\[
\nu 2(t)=v
\]

Since \(G 1 \subseteq G 2\), the same holds for all \(r \in G 1\).
Replace all subterms \(t 1, \ldots, t n\) of \(t\) of sorts in \(S 1\) by new variables \(x 1, \ldots, x n\) to yield a term \(t^{\prime}\). By construction of \(t\), the new variables are of sorts in \(S 2 \cup\) \(G 2\), hence there exists an ( \(S 2 \cup G 2\) )-indexed set of variables \(X_{S}\) including those variables in \(X_{S 2}\) and the new variables \(x 1, \ldots, x n\). Extend \(\nu 2\) to a valuation \(\nu 2^{\prime}\) : \(\left.T_{\langle S 2 \cup G 2, F 2\rangle}\left(X_{S}\right) \rightarrow A\right|_{\iota 2}\) such that \(\nu 2^{\prime}(x i)=\nu 2(t i)\) for each new variable \(x i\).

If no new generators are added, \(F 1_{r} \supseteq F 2_{r}\), we can show, by induction on the height of \(t^{\prime}\), that \(t^{\prime} \in\left|T_{\left\{S_{1 \cup G 1, F 1\rangle}\right.}\left(X_{S_{1}}\right)\right|_{r}\) where \(X_{S_{1}}\) is an \(S 1\)-indexed set including variables \(x 1, \ldots, x n\).

Suppose that \(t^{\prime}\) is \(o p(x)\) for a certain function symbol \(o p: s \rightarrow r\). If neither \(s \in S 1\) nor \(s \in G 1\), then \(o p \notin F 1_{r}\) and therefore \(o p\) cannot be a generator in \(F 2_{r}\) in contradiction with op belonging to a term \(t \in\left|T_{\langle S 2 \cup G 2, F 2\rangle}\left(X_{S 2}\right)\right|_{r}\). If \(s \in G 1\) then \(s \in G 2\) as well but, by construction of \(t^{\prime}\), the variable \(x\) can only be of a sort in \(S 1\) or in \(S 2\) and no sort can be in \(G 1 \cap G 2\) and in \(S 1 \cup S 2\) at the same time, hence we conclude that \(s \in S 1\). By construction of \(t^{\prime}, x \in X_{S 1}\) is a new variable and \(o p \in F 1_{r}\) thus \(t^{\prime} \in\left|T_{\left\{S_{1 \cup G 1, F 1\rangle}\right.}\left(X_{S 1}\right)\right|_{r}\).

Suppose that \(t^{\prime}\) is \(o p\left(t^{\prime \prime}\right)\) for a certain function symbol \(o p: s \rightarrow r\). As before, \(s\) must belong to either \(S 1\) or \(G 1\). If \(s \in S 1\) then, by construction \(t^{\prime \prime}\) must be a variable \(x\) and the previous case applies. If \(s \in G 1\), by the induction hypothesis \(t^{\prime \prime} \in\left|T_{\langle S 1 \cup G 1, F 1\rangle}\left(X_{S_{1}}\right)\right|_{s}\) and since \(o p \in F 1_{r}, t^{\prime} \in\left|T_{\langle S 1 \cup G 1, F 1\rangle}\left(X_{S_{1}}\right)\right|_{r}\) as well.

If op has several parameters the same reasoning applies to each of them.
Summing up, \(t^{\prime} \in\left|T_{\left\langle S_{\left.1 \cup G 1, F_{1}\right\rangle}\right.}\left(X_{S_{1}}\right)\right|_{r}\) for an \(S 1\)-indexed set of variables \(X_{S_{1}}\) and there is a valuation \(\nu 1:\left.T_{\left\langle S_{1 \cup G 1, F 1\rangle}\right.}\left(X_{S_{1}}\right) \rightarrow A\right|_{\iota 1}\) such that \(\nu 1(x i)=\nu 2^{\prime}(x i)\) for the new variables \(x 1, \ldots, x n\), and \(t^{\prime}\) evaluates to the same value as \(t\), i.e. \(\nu 1\left(t^{\prime}\right)=v\). as expected.

In those cases where \(r\) is a one-point sort, the carrier \(|A|_{r}\) must be a singleton and therefore reachable from whatever set of generators we chose for \(r\)
provided at least one term of sort \(r\) can be generated, and this is guaranteed since \(\ll G 1, F 1, S 1 \gg\) is \(\emptyset\)-free.

Completeness proof Assuming \(\ll G 2, F 2, S 2 \gg \forall \ll G 1, F 1, S 1 \gg\), we consider those cases in which the inference can fail:
1. If \(G 1 \nsubseteq G 2\) then we can choose a sort \(r \in G 1\) which is not generated in \(\ll G 2, F 2, S 2 \gg\). Now, consider a final algebra \(A\) over \(\Sigma\) extended in sort \(r\) to a bigger carrier, e.g. \(|A|_{r}=\{\perp, \star\}\) while for all \(s^{\prime} \neq r,|A|_{s^{\prime}}=\{\perp\}\) and the functions taking a parameter of sort \(r\) are extended in the only possible way, i.e. yielding always \(\perp\). By construction \(A\) still satisfies \(\ll G 2, F 2, S 2 \gg\) but it fails to satisfy \(<G 1, F 1, S 1 \gg\) since \(\star\) cannot be generated in \(A\); hence \(\ll G 2, F 2, S 2 \gg \not \forall_{\Sigma} \ll G 1, F 1, S 1 \gg\).
2. If for a sort \(r \in G 1\) it happens that \(F 1_{r} \nsupseteq F 2_{r}\) and \(r\) is not a one-point sort w.r.t. \(\ll G 2, F 2, S 2 \gg\), we can choose a generator op \(: \bar{s} \rightarrow r \in F 2_{r}\) which is not a generator in \(F 1_{r}\).

Now, we consider the \(\Sigma\)-algebra \(A\) with carriers \(|A|_{s}=\{\perp, \star\}\) for all sorts except for one-point sorts w.r.t. \(\ll G 2, F 2, S 2 \gg\) which take carriers \(|A|_{s^{\prime}}=\) \(\{\perp\}\), and constants and functions defined as follows:
- Functions (or constants) \(f: \bar{s} \rightarrow r\) which are not in \(F 2_{r}\) always yield \(\perp\), i.e. if \(f \notin F 2_{r}\) then \(f(\bar{x})=\perp\).
- Functions \(f: s 1, \ldots, s n \rightarrow r\) which are the only generator of a sort, \(F 2_{r}=\{f\}\), are the identity on one of the parameters of the sorts with biggest carrier, i.e. \(f(x 1, \ldots, x n)=x i\) such that \(|A|_{s i} \supseteq|A|_{s j}\) for \(j=1, \ldots, n\).
- For functions (or constants) which are generators of a sort with several generators, \(F 2_{r}=\{f 1, f 2, \ldots\}\), we pick one of them to yield always \(\star\)
while the rest of the generators always yield \(\perp\). If \(o p \in F 2_{r}\) then \(o p\) is the generator which is chosen to yield \(\star\).

By construction of \(A\) and since \(\ll G 2, F 2, S 2 \gg\) is \(\emptyset\)-free, \(\perp\) and \(\star\) are reachable in all sorts which are not one-point sorts w.r.t. \(\ll G 2, F 2, S 2 \gg\), hence \(A \vDash \ll G 2, F 2, S 2 \gg\). However, \(A \not \models \ll G 1, F 1, S 1 \gg\) because \(\star \in|A|_{r}\) is not reached unless \(o p\) is used.

As argued in [Far 89] many entailments preserve the generators from antecedent to consequent and simple matching of identical constraints is very frequent. Here, this result generalizes previous work on matching constraints to the point that it achieves completeness for single \(\emptyset\)-free constraints of the form \(\ll G, F, S \gg\) in the absence of other kinds of sentences.

The next step towards a true logic of constraints is to extend such an inference system to deal with several simultaneous \(\emptyset\)-free constraints. But this brings some new problems.

A reachability constraint which constrains several sorts simultaneously can be a stronger requirement than a set of constraints containing a single reachability constraint for each sort. Consider for example a signature \(\Sigma=\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\) with
\[
S^{\prime}=\{s 1, s 2\} \quad \Omega^{\prime}=\{f: s 1 \rightarrow s 2, ~(g: s 2 \rightarrow s 1\}
\]
and a \(\Sigma\)-algebra \(A\) with \(|A|_{s 1}=\{0,1, e\}\) and \(|A|_{s 2}=\left\{0^{\prime}, 1^{\prime}, e^{\prime}\right\}\) such that \(c 1=0\), \(c 2=0^{\prime}, f(0)=f(1)=1^{\prime}, g\left(0^{\prime}\right)=g\left(1^{\prime}\right)=1, f(e)=e^{\prime}\) and \(g\left(e^{\prime}\right)=e\). Values \(e\)
and \(e^{\prime}\) are mutually generated, hence algebra \(A\) satisfies constraints,
\[
A \models_{\Sigma} \ll\{s 1\},\{c 1, g\},\{s 2\} \gg \quad \text { and } \quad A \models_{\Sigma} \ll\{s 2\},\{c 2, f\},\{s 1\} \gg
\]
but \(A\) does not satisfy a constraint on both sorts simultaneously
\[
A \not \models_{\Sigma} \ll\{s 1, s 2\},\{c 1, c 2, f, g\}, \emptyset \gg
\]
since neither \(e\) nor \(e^{\prime}\) are ever generated using \(c 1, c 2, f\) and \(g\).
This situation arises because sorts \(s 1\) and \(s 2\) are mutually dependent sorts according to the following definition:

Definition 6.3.6 Two sorts \(s 1\) and \(s 2\) are mutually dependent in a signature \(\langle S, \Omega\rangle\) iff \(s 1 \rightarrow^{*} s 2\) and \(s 2 \rightarrow{ }^{*} s 1\), where \(\rightarrow{ }^{*}\) is the transitive closure of the relation \(\rightarrow\) defined between sorts in \(S\) as follows: \(s^{\prime} \rightarrow s\) iff there exists a function name \(f: \omega \rightarrow s\) in \(\Omega\) and \(s^{\prime}\) is included in the sequence \(\omega\).

On the other hand, joining sets of generators generally leads to weaker constraints. Consider for example,
\[
A \vDash_{\Sigma} \ll\{s 1\},\{c 1, f, g\},\{s 2\} \gg
\]
but \(A\) does not satisfy the two constraints,
\[
A \not \forall_{\Sigma} \ll\{s 1\},\{c 1\},\{s 2\} \gg \quad \text { and } \quad A \nmid_{\Sigma} \ll\{s 1\},\{f, g\},\{s 2\} \gg
\]

Taking in consideration the contrary effect of joining sets of sorts and joining sets of generators, we define a correct join constraint in such a way that generators cannot be joined and joining sorts has no effect.

Definition 6.3.7 The join constraint of two \(\Sigma\)-constraints \(\ll G 1, F 1, S 1 \gg\) and \(\ll G 2, F 2, S 2 \gg\), written \(\ll G 1, F 1, S 1 \gg \bowtie \ll G 2, F 2, S 2 \gg\), is another \(\Sigma\)-constraint \(\ll G \bowtie, F \bowtie, S \bowtie \gg\) such that
```

G\bowtie=G1\cupG2
F\bowtie =( U \i\inG1 }F\mp@subsup{1}{i}{})\cup(\mp@subsup{U}{j\inG2}{}F\mp@subsup{2}{j}{}
S\bowtie=(S1\cupS2)\(G1\cupG2)

```

The result is called a correct join constraint if \(G 1\) and \(G 2\) are disjoint and every pair of mutually generated sorts \(r 1\) and \(r 2\) in \(\langle G \bowtie \cup S \bowtie, F \bowtie\rangle\) is also mutually generated in either \(\langle G 1 \cup S 1, F 1\rangle\) or in \(\langle G 2 \cup S 2, F 2\rangle\).

Correct join constraints relate to their component constraints according to the following results:

Proposition 6.3.8 For every correct join constraint \(\ll G 1, F 1, S 1 \gg \oiint<G 2, F 2, S 2 \gg\) over \(\Sigma\),
\[
\ll G 1, F 1, S 1 \gg \pitchfork \ll G 2, F 2, S 2 \gg \models_{\Sigma}\{\ll G 1, F 1, S 1 \gg, \ll G 2, F 2, S 2 \gg\}
\]

Proof By construction of the join constraint, all generated sorts of \(\ll G 1, F 1, S 1 \gg\) are inherited, \(G 1 \subseteq G \bowtie\). Moreover, since \(G 1\) and \(G 2\) are disjoint the set of generators \(F \bowtie_{r}\) for a sort in \(r \in G 1\) is as \(F 1_{r}\) and, in general \(F \bowtie_{r} \subseteq F 1_{r}\) for all \(r \in G 1\). Hence,
\[
\ll G 1, F 1, S 1 \gg \infty \ll G 2, F 2, S 2 \gg \leqslant \ll 1, F 1, S 1 \gg
\]

By soundness of \(\vdash\), the first constraint follows from the join, and similarly for the second constraint.

Correct join constraints can only bring together generated sorts which are not mutually generated. In the example shown above, joining constraints
\[
\ll\{s 1\},\{c 1, g\},\{s 2\} \gg \quad \text { and } \quad \ll\{s 2\},\{c 2, f\},\{s 1\} \gg
\]
is not correct since \(f\) generates \(s 2\) from \(s 1\) and \(g\) generates \(s 1\) from \(s 2\).
Correct join constraints are always weaker than the union of the original constraints.

Proposition 6.3.9 For all correct join constraints \(\ll G 1, F 1, S 1 \gg \bowtie \ll G 2, F 2, S 2 \gg\) over \(\Sigma\),
\[
\{\ll G 1, F 1, S 1 \gg, \ll G 2, F 2, S 2 \gg\} \models_{\Sigma} \ll G 1, F 1, S 1 \gg \bowtie \ll G 2, F 2, S 2 \gg
\]

Proof Let \(\iota 1, \iota 2\) and \(\iota\) be the inclusions \(\langle S 1 \cup G 1, F 1\rangle \hookrightarrow \Sigma,\langle S 2 \cup G 2, F 2\rangle \hookrightarrow \Sigma\) and \(\langle S \bowtie \cup G \bowtie, F \bowtie\rangle \hookrightarrow \Sigma, A\) a model of \(\{\ll G 1, F 1, S 1 \gg, \ll G 2, F 2, S 2 \gg\}\) and \(v\) a value in a generated carrier \(|A|_{r}\) for \(r \in G 1\) (the following argument is symmetric for \(r \in G 2\) ).

By definition of satisfaction, since \(A \models_{\Sigma} \ll G 1, F 1, S 1 \gg\), there exists a term \(t \in\left|T_{\langle S 1 \cup G 1, F 1\rangle}\left(X_{S_{1}}\right)\right|_{r}\) for an \(S 1\)-indexed set of variables \(S 1\) and a valuation \(\nu:\left.T_{\left(S_{1 \cup G 1, F 1)}\right.}\left(X_{S 1}\right) \rightarrow A\right|_{\iota 1}\) such that \(\nu(t)=v\).

Let \(x 1, \ldots, x n \in X_{S 1}\) be the free variables of \(t\) from which \(x 1, \ldots, x k\) belong to sorts in \(G 2\). Since \(A \models_{\Sigma} \ll G 2, F 2, S 2 \gg\) the values denoted by variables \(x 1, \ldots, x k\) can also be generated. Let \(v i\) be the value of \(\nu(x i)\) for \(i=1, \ldots, k\); there exists a term \(t i \in\left|T_{(S 2 U G 2, F 2)}\left(X_{S 2}\right)\right|\) for each \(v i\) for an \(S 2\)-indexed set of variables and a valuation \(\nu^{\prime}:\left.T_{\langle S 2 \cup G 2, F 2\rangle}\left(X_{S 2}\right) \rightarrow A\right|_{\iota 2}\) such that \(\nu^{\prime}(t i)=v i\).

Combining \(X_{S_{1}}\) and \(X_{S 2}\) into a single \(((S 1 \cup S 2) \backslash G 2)\)-indexed set of variables \(X\) and combining valuations \(\nu\) and \(\nu^{\prime}\) into one valuation \(\nu^{\prime \prime}:\left.T_{\langle S \bowtie \cup G \bowtie, F \bowtie\rangle}(X) \rightarrow A\right|_{\iota}\), we have that
\[
\nu^{\prime \prime}(t[t 1 / x 1, \ldots, t k / x k])=v
\]

Considering the free variables in \(t 1, \ldots, t k\) belonging to sorts in \(G 1\) we can iterate the process again until only variables of sorts in \((S 1 \cup S 2) \backslash(G 1 \cup G 2)\) are left.

By definition of correct join constraint, we are guaranteed not to fall into a cycle. No mutual dependency of the sorts generated in one constraint w.r.t. those
sorts generated in the other constraint guarantees a well-founded ordering for induction.

In the base case the free variables of \(t\) are assumed to be of sorts in \(S \bowtie\), and in the induction step values \(v 1, \ldots, v k\) are generated, by induction hypothesis, by terms \(t 1^{\prime}, \ldots, t k^{\prime}\) over an ( \(S \bowtie\) )-indexed set of variables.

Summing up, there exists always a term \(t^{\prime} \in\left|T_{(S \bowtie \cup G \bowtie, F \bowtie)}\left(X_{S \infty}\right)\right|_{r}\) and an \((S \bowtie)\)-indexed set of variables \(X_{S \bowtie}\), and valuation \(\nu^{\prime \prime}\) such that \(\nu^{\prime \prime}\left(t^{\prime}\right)=v\).

Since all generated sorts in the join constraint are also generated in \(\ll G 1, F 1, S 1 \gg\) or \(\ll G 2, F 2, S 2 \gg\), it follows that \(A \vDash \ll G 1, F 1, S 1 \gg \bowtie \ll G 2, F 2, S 2 \gg\), as expected.

In practice, correctness of a join constraint is commonly satisfied. Consider a specification language based on \(A S L(\mathrm{EQ})\) where specifications \(M_{(G 1, F 1, S 1)} \ldots M_{\langle G n, F n, S n\rangle} S P\) are guaranteed to satisfy that:
1. Reachability constraints do not constrain already generated sorts, i.e. Gj in \(M_{(G j, F j, S j)}\) is disjoint from \(\bigcup_{j<i \leq n} G i\).
2. Generating sorts in one constraint are not constrained in successive constraints, i.e. \(S j\) in \(M_{\langle G j, F j, S j\rangle}\) is disjoint from \(\bigcup_{1 \leq i<j} G i\).

From this and the fact the generated and generating sorts are disjoint in each constraint, it can be concluded that all join constraints \(\ll G j, F j, S j \gg \bowtie<G k, F k, S k \gg\) for \(k<j\) are correct.

It is normal practice in specification design to use constraints arranged in such sequences. More general definitions of reachability constraint, such as the one we use, are chosen on theoretical grounds. In our case, such a general \(\ll G, F, S \gg\)
satisfies the satisfaction condition and algebraic laws such as commutativity analogously to arbitrary sentences. Although we treat this more general case, we can well believe that correctness of join constraints is very common in practice.

In the following we give an inference system for multiple constraints which is complete when constraints of the form \(\ll G, F, S \gg\) are arranged in sequences as above.

Definition 6.3.10 A consequence relation \(\sharp\) between finite sets of constraints is defined by the following set of rules:
\begin{tabular}{|c|c|c|c|c|}
\hline & & \multicolumn{3}{|l|}{\(\ll G 2, F 2, S 2 \gg \ll G 1, F 1, S 1 \gg\)} \\
\hline \(\overline{C H \emptyset} \quad \overline{\emptyset H}\) & > \({ }^{\text {d }}\) & \(\{\ll G 2, F\) & H \({ }^{\text {d }} \ll\) & \(F 1, S 1 \gg\}\) \\
\hline \multicolumn{5}{|c|}{\(\ll G 1, F 1, S 1 \gg \ll G 2, F 2, S 2 \gg\) is correct} \\
\hline \multicolumn{5}{|l|}{\(\overline{\ll G 1, F 1, S 1 \gg, \ll G 2, F 2, S 2 \gg\} \Vdash\{\ll G 1, F 1, S 1 \gg \lll k 2, F 2, S 2 \gg\}}\)} \\
\hline \(C 21{ }^{+} \mathrm{Cl}\) & \(C 2 H C 11\) & C2 H C 12 & \(C 2 H\) - 3 & \(C 3 H+C 1\) \\
\hline \(C 21 \cup C 22 H C 1\) & C2H & \(1 \cup C 12\) & & \\
\hline
\end{tabular}

\section*{Theorem 6.3.11 (Soundness) For all sets of \(\emptyset\)-free reachability constraints \(C 1\)} and \(C 2\),
\[
C 2 H C 1 \quad \Longrightarrow \quad C 2 \vDash C 1
\]

Proof We prove soundness of a proof in \(H\) by induction on the rules used.

\section*{Case \(\overline{0 F\{《 \theta, F, S>\}}\)}

By definition of satisfaction all models of the appropriate signature satisfy a constraint with no generated sorts, hence \(\emptyset \models\{\ll \emptyset, F, S \gg\}\).

Case \(\frac{<G 2, F 2, S 2 \gg \vdash<G 1, F 1, S 1 \gg}{\{\ll G 2, F 2, S 2 \gg+\{<G 1, F 1, S 1>\}}\)
By soundness of \(\vdash\) (Theorem 6.3.5), it must hold that \(\ll G 2, F 2, S 2 \gg \lll 1, F 1, S 1 \gg\); hence
\[
\{\ll G 2, F 2, S 2 \gg\} \models\{\ll G 1, F 1, S 1 \gg\}
\]

Case \(\frac{<G 1, F 1, S 1 \gg \infty<G 2, F 2, S 2 \gg \text { is correct }}{\{<G 1, F 1, S 1>,<G 2, F 2, S 2>\} \vdash\{<G 1, F 1, S 1 \gg \infty<G 2, F 2, S 2>\}}\)

Immediate by proposition 6.3.9.

Cases \(\overline{C \vdash \emptyset} \quad \frac{C 21+C 1}{C 21 \cup C 22 \vdash C 1} \quad \frac{C 2 \vdash C 11 \quad C 2 \vdash C 12}{C 2+C 11 \cup C 12} \quad \frac{C 2+C 3}{C 2+C 1} \quad C 1+C 1\)

These rules are sound by the definition of satisfaction between sets of sentences in an institution.

This inference system can be proven complete w.r.t. entailment between sets of constraints having correct joins as discussed before. In order to do that, it is enough to replace each set of constraints by the join of all its constraints. By propositions 6.3 .8 and 6.3 .9 such a reduction is sound, so that completeness of \(\mathbb{H}\) follows directly from completeness of \(\vdash\).

Theorem 6.3.12 (Completeness) For all sets of \(\emptyset\)-free reachability constraints \(C 1\) and \(C 2\) such that all joins among constraints in C1 and in C2 are correct,
\[
C 2 \vDash C 1 \quad \Longrightarrow \quad C 2 H C 1
\]

Proof For all \(C 2 \models C 1\) we can prove by structural induction on \(C 1\) that a formal proof can be derived in \(H\).

Case \(C 1=\emptyset\)
\(C 2 \vDash C 1\) holds for all \(C 2\) since \(C 2 \sharp \emptyset\) is immediately derivable by the first inference rule.

Case \(C 1=\{\ll G 1, F 1, S 1 \gg\}\)

By structural induction on \(C 2\) we prove that \(C 2 \models C 1\) implies \(C 2 H C 1\) for any singleton \(C 1\) :
- If \(C 2=\emptyset\) and \(C 2 \vDash \ll G 1, F 1, S 1 \gg\), it follows that \(\ll G 1, F 1, S 1 \gg\) cannot impose any restriction at all, so \(G 1\) must be empty. In that case, \(\emptyset H-\{<\emptyset, F 1, S 1 \gg\}\) is immediately derivable by the second inference rule.
- If \(C 2=\{\ll G 2, F 2, S 2 \gg\}\) then by completeness of \(\vdash\) for single constraints (Theorem 6.3.5) and the third inference rule, it follows that
\[
\{\ll G 2, F 2, S 2 \gg\} \Vdash\{\ll G 1, F 1, S 1 \gg\}
\]
is derivable.
- If \(C 2=C 21 \cup C 22\) we consider the join \(\ll G 21, F 21, S 21 \gg\) of all constraints in \(C 21\), and the join \(\ll G 22, F 22, S 22 \gg\) of all constraints in C22. By proposition 6.3.9 \(C 21 \models \ll G 21, F 21, S 21 \gg\) and, by induction hypothesis, \(C 21 \Vdash\{\ll G 21, F 21, S 21 \gg\}\). Similarly \(C 22 \Vdash\{\ll G 22, F 22, S 22 \gg\}\). Combining these derivations and using the fourth rule we can derive that
\[
C 21 \cup C 22 \Vdash\{\ll G 21, F 21, S 21 \gg \bowtie \ll G 22, F 22, S 22 \gg\}
\]

At the same time, by proposition 6.3 .8 , we have that \(\ll G 21, F 21, S 21 \gg \vDash\) \(C 21\) and \(\ll G 22, F 22, S 22 \gg \mathcal{F} 22\), hence
\[
\{\ll G 21, F 21, S 21 \gg, \ll G 22, F 22, S 22 \gg\} \vDash \ll G 1, F 1, S 1 \gg
\]

Applying proposition 6.3.8 again we conclude that
\[
\ll G 21, F 21, S 21 \gg \pitchfork \ll G 22, F 22, S 22 \gg \vDash<G 1, F 1, S 1 \gg
\]

Finally, by the previous case,
\[
\{\ll G 21, F 21, S 21 \gg \bowtie \ll G 22, F 22, S 22 \gg\} H\{\ll G 1, F 1, S 1 \gg\}
\]
is derivable. Putting this derivation together with that above using the last rule we conclude that \(C 12 \cup C 22 \nVdash\{\ll G 1, F 1, S 1 \gg\}\).

Case \(C 1=C 11 \cup C 12\)

Whenever it is the case that \(C 2 \models C 11 \cup C 12\), it is guaranteed that all models of \(C 2\) are also models of \(C 11\) and \(C 12\); i.e.
\[
C 2 \models C 11 \quad C 2 \vDash C 12
\]

Therefore, by induction hypothesis it holds that \(C 2 \sharp C 11\) and \(C 2 H C 11\), so that applying the sixth rule \(C 2 H C 11 \cup C 12\) can be derived.

Similarly to the inference system proposed for single constraints, \(H\) only takes account of the simplest implications and it is complete for constraints of the form \(\ll G, F, S \gg\). Unfortunately, this requires constraints in \(C 2\) to constraint disjoint sets of sorts. Consider for example a more difficult case such as:
\[
\begin{array}{r}
S^{\prime}=\{s\} \quad \Omega^{\prime}=\{a: s \\
b: s \\
c: s\}
\end{array}
\]
and \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-constraints
\[
\begin{array}{cc}
c 1=\ll\{s\},\{a, b\}, \emptyset \gg & c 2=\ll\{s\},\{a, c\}, \emptyset \gg \\
c 3=\ll\{s\},\{b, c\}, \emptyset \gg & c=\ll\{s\},\{a\}, \emptyset \gg
\end{array}
\]

In this case, it holds that \(\{c 1, c 2, c 3\} \vDash\{c\}\) since among all \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-algebras only the trivial (one-point) algebras satisfy the three constraints \(c 1, c 2\) and \(c 3\), and all these models satisfy \(c\), although \(\{c 1, c 2, c 3\} \nVdash\{c\}\).

From a more technical standpoint, examples such as this are quite peculiar since they deal with "finite" constraints; e.g. c1 is equivalent to a sentence \(\forall x\) : \(S .(x=a \vee x=b)\), and by translating all three constraints to this form we can
infer using FOLEQ that \(\forall x: S . a=x\). If we deal with constraints which are only equivalent to proper infinitary sentences, then a finite consequence such as \(\forall x: S . a=x\) could never hold because of some fundamental results of model theory (see theorem 6 in [KK 67]).

Nonetheless, as argued before, multiple constraints on one sort are not used in practice; only a generalization of constraints in order to make them comparable to normal sentences has introduced such a possibility. Therefore, we should consider \(H\) as complete for a specification language whose only sentences are reachability constraints of the form \(\ll G, F, S \gg\). In terms of specifications in \(A S L\), \(H^{-}\)provides a complete inference system in this sense for \(M \models M\).

\subsection*{6.3.2 Reachability constraints and sentences}

In section 6.3.1, we dealt with an algebraic institution whose only sentences are reachability constraints. However, reachability constraints are never used on their own but, most probably, combined with equations, conditional equations or first order sentences with equality.

From a proof-theoretical standpoint, we have two different kinds of sentences: reachability constraints equipped with a complete inference system \(\mathbb{H}^{-}\)as defined above and ordinary sentences with another inference system \(\vdash^{\mathbf{I}}\), in the case of equational logic a complete inference system \(\vdash^{\mathbf{E Q}}\).

By taking the union of these two kinds of sentences, we can easily define a new institution with constraints over \(\mathbf{I}\) as in theorem 6.2.1, but there is very little we can directly say about inference for such mixed sets of sentences. Some general work on the combination of different logics can be found in [HST 89a], but not much can be said in general.

In the following we refer to EQ with reachability constraints, but also to other institutions with signatures, models, terms and reachability constraints as in EQ, e.g. ALG.

In terms of specifications in \(A S L\), we are addressing the problem of \(M A \models M A\).

\section*{Independent strategy}

The results obtained for a logic of constraints give raise to an immediate strategy for proving entailments such as \(A_{C 2} A_{\Phi 2} \epsilon_{\Sigma} \vDash A_{C 1} A_{\Phi 1} \epsilon_{\Sigma}\) in EQ, namely
\[
\frac{\Phi 2 \vdash^{\mathrm{EQ}} \Phi 1 \quad C 2 H C 1}{A_{C 2} A_{\Phi 2} \epsilon_{\Sigma} \models_{\Sigma} A_{C 1} A_{\Phi 1} \epsilon_{\Sigma}}
\]
where \(\Phi 1\) and \(\Phi 2\) are sets of \(\Sigma\)-sentences and \(C 1\) and \(C 2\) are sets of \(\Sigma\)-constraints.
This is called the independent strategy because it corresponds to taking the union of the inference rules of the different logics in order to prove entailment between heterogeneous sets of sentences. However, given the two complete inference system \(\vdash^{\mathrm{EQ}}\) and \(\mathbb{H}\) their union is incomplete w.r.t. the union of their sentences. Cases where the independent strategy fails are easy to find, e.g.
```

M{G1,F1,S1)}\mp@subsup{A}{\Phi1}{}\mp@subsup{\epsilon}{\Sigma}{}=\mathrm{ Reachable on {nat} by {0, suc}
sorts nat
operations
0: nat
suc: nat->nat
_+_ : nat, nat->nat
axioms
|}\mathrm{ n:nat. 0+n=n
|},\textrm{m}:\mathrm{ nat. (suc m)+n=suc(m+n)
|,m:nat. m+n=n+m
end

```
```

M{G2,F2,S2\rangle}\mp@subsup{A}{\Phi2\epsilonE}{}=\mathrm{ Reachable on {nat} by {0, suc, +}
sorts nat
operations
0: nat
suc: nat->nat
_+_ : nat, nat->nat
axioms
|}\mathrm{ :nat. 0+n=n
\foralln,m:nat. (suc m)+n=suc(m+n)
end

```
where it is the case that \(\Phi 2 \vdash^{\mathrm{EQ}} \Phi 1\) and \(\ll G 2, F 2, S 2 \gg \forall \ll G 1, F 1, S 1 \gg\) but the refinement is correct, \(M_{\langle G 2, F 2, S 2)} A_{\Phi 2} \epsilon_{\Sigma} \models M_{(G 1, F 1, S 1\rangle} A_{\Phi 1} \epsilon_{\Sigma}\).

In order to improve this situation, specific rules must be given to infer sentences from sentences and constraints, \(M A \models A\), and to infer constraints from sentences and constraints, \(M A \vDash M\). The first problem has already been tackled using induction principles in theorem proving (section 3.3.2), whereas the second problem remains to be studied. The results are expressed in the form of an inference system for constraints parameterized by a set of sentences, i.e. \(\ll G 2, F 2, S 2 \gg \vdash_{\Phi} \ll G 1, F 1, S 1 \gg\) means that \(\ll G 1, F 1, S 1 \gg\) can be inferred from \(\Phi\) and \(\ll G 2, F 2, S 2 \gg\).

\section*{Characterization of \(\vdash_{\Phi}\)}

As we saw in section \(6.3 .1, \ll G 2, F 2, S 2 \gg \leqslant \ll 1, F 1, S 1 \gg\) checks whether all generated sorts in \(\ll G 1, F 1, S 1 \gg\) were already generated in \(\ll G 2, F 2, S 2 \gg\) by the same or fewer generators. Now, \(\vdash_{\Phi}\) must take into account that some generators in \(\ll G 2, F 2, S 2 \gg\) may be excluded during the check because they are redundant w.r.t. the rest of the generators and \(\Phi\).

Definition 6.3.13 Given a \(\Sigma\)-reachability constraint \(\ll G, F, S \gg\) and a generated sort \(r \in G\), a generator op \(\in F_{r}\) is redundant in \(\ll G, F, S \gg\) w.r.t. a set of \(\Sigma\)-sentences \(\Phi\) if for all \(\Sigma\)-algebras \(A\) such that \(A \models_{\Sigma} \Phi\)
\[
A \vDash_{\Sigma} \ll G, F, S \gg \quad \text { iff } \quad A \models_{\Sigma} \ll G, F \backslash\{o p\}, S \gg
\]

In general, a pair \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) is redundant in a \(\Sigma\)-constraint \(\ll G, F, S \gg\) w.r.t. \(\Phi\) if \(S^{\prime \prime} \subseteq S, F^{\prime \prime} \subseteq F\) and for all algebras such that \(A \models_{\Sigma} \Phi\)
\[
A \models_{\Sigma} \ll G, F, S \gg \quad \text { iff } \quad A \models_{\Sigma} \ll G, F \backslash F^{\prime \prime}, S \backslash S^{\prime \prime} \gg
\]

Considering the definition of satisfaction of a reachability constraint, redundancy of a pair \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) in a \(\Sigma\)-constraint \(\ll G, F, S \gg\) can be rephrased as follows:

Let \(\iota\) and \(\iota^{\prime \prime}\) be inclusions
\[
\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle \stackrel{\iota^{\prime \prime}}{\hookrightarrow}\langle G \cup S, F\rangle \stackrel{\iota}{\hookrightarrow} \Sigma
\]
and A a \(\Sigma\)-algebra such that \(A \models_{\Sigma} \Phi\) and \(A \vDash_{\Sigma} \ll G, F, S \gg\), if all values of a sort \(r \in G\) are denoted by a term \(t \in\left|T_{\langle G \cup S, F\rangle}\left(X_{S}\right)\right|_{r}\) for an \(S\)-indexed set of variables \(X_{S}\) and under a valuation \(\nu:\left.T_{\langle G \cup S, F\rangle}\left(X_{S}\right) \rightarrow A\right|_{ı}\), then all values can also be produced by a term \(t^{\prime} \in\left|T_{\left(G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle}\left(X_{S \backslash S^{\prime \prime}}\right)\right|_{r}\) for an \(\left(S \backslash S^{\prime \prime}\right)\)-indexed set of variables \(X_{S \backslash S^{\prime \prime}}\) and under a valuation
\[
\nu^{\prime}:\left.T_{\left(G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right)}\left(X_{S \backslash S^{\prime \prime}}\right) \rightarrow A\right|_{\iota^{\prime \prime} ; \iota}
\]

This definition of redundancy can be considerably simplified if algebras with empty carriers are not taken into account.

Definition 6.3.14 Given a set of sorts \(S\), the \(S\)-indexed set of variables \(\mathcal{X}_{S}\) is defined as follows: for all sorts \(s \in S, \mathcal{X}_{s}=\left\{x_{i} \mid i \in \mathcal{N}\right\}\) where \(\mathcal{N}\) is the set of the natural numbers.

Lemma 6.3.15 Given a signature inclusion \(\iota:\langle G \cup S, F\rangle \hookrightarrow \Sigma\), a \(\Sigma\)-constraint \(\ll G, F, S \gg\) and a model \(A \vDash_{\Sigma} \ll G, F, S \gg\) without empty carriers, then for every value \(v \in|A|_{r}\) for \(r \in G\) there exists \(t_{v} \in\left|T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{r}\) and a valuation \(\nu:\left.T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right) \rightarrow A\right|_{\iota}\) such that \(\nu\left(t_{v}\right)=v\).

Proof By definition of satisfaction of a \(\Sigma\)-constraint \(\ll G, F ; S \gg\), for every model \(A \models_{\Sigma} \ll G, F, S \gg\) there exists an \(S\)-indexed set of variables \(X_{S}\) such that for each value \(v \in|A|_{r}\) for \(r \in G\) there exists a valuation \(\nu:\left.T_{\{G \cup S, F\rangle}\left(X_{S}\right) \rightarrow A\right|_{\text {c }}\) and a term \(t_{v} \in\left|T_{\langle G \cup S, F\rangle}\left(X_{S}\right)\right|\) such that \(\nu\left(t_{v}\right)=v\). In other words, each value \(v\) is generated from a finite set of values of each sort \(s \in S\)
\[
V_{s}=\left\{\nu(x) \mid x \text { is a variable in } t_{v} \text { of sort } s\right\}
\]

We can order the values in \(V_{s}\) so that \(V_{s}=\left\{v_{1}, \ldots, v_{n}\right\}\). Then, a valuation \(\nu^{\prime}\) : \(T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\) can be defined for each sort \(s\) in \(S\) as follows:
\[
\begin{array}{ll}
\nu^{\prime}\left(x_{i}\right)=v_{i} & \text { for all } i=1, \ldots, n \\
\nu^{\prime}\left(x_{i}\right)=\perp & \text { for all } i>n
\end{array}
\]
where \(\perp\) is an arbitrary element in \(|A|_{s}\). Since \(A\) has no empty carriers, \(\nu^{\prime}\) is well defined and, by definition, there exists a term \(t^{\prime} \in\left|T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{r}\) such that \(\nu^{\prime}\left(t^{\prime}\right)=v\).

Assumption In the following we shall assume all models to be algebras without empty carriers. This does not produce any problem since reachability constraints are already assumed to be \(\emptyset\)-free.

In order to take care of redundancy in \(\vdash_{\Phi}\) and to produce, at the same time, a sensible inference system, we have to avoid referring to models and particular valuations. In the following two sufficient criteria for redundancy are presented.

\section*{First proof criterion}

Proposition 6.3.16 (First proof criterion) Given a set of \(\Sigma\)-sentences \(\Phi\), \(a\) \(\Sigma\)-constraint \(<G, F, S \gg\) and a pair \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) such that \(S^{\prime \prime} \subseteq S, F^{\prime \prime} \subseteq F\) and
\[
\forall t \in\left|T_{(G \cup S, F\rangle}\left(\mathcal{X}_{s}\right)\right|_{r} . \exists t^{\prime} \in \mid T_{\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right)}\left(\left.\mathcal{X}_{\left.S \backslash S^{\prime \prime}\right)}\right|_{r} . \Phi \models_{\Sigma} \forall \mathcal{X}_{s .} t=t^{\prime}\right.
\]
for every sort \(r \in G\) then \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) is redundant in \(\ll G, F, S \gg\) w.r.t. \(\Phi\).
Proof Let \(\iota\) and \(\iota^{\prime \prime}\) be the inclusions
\[
\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle \stackrel{\iota^{\prime \prime}}{\leftrightarrows}\langle G \cup S, F\rangle \hookrightarrow \Sigma
\]
and \(A\) a \(\Sigma\)-algebra without empty carriers satisfying \(\Phi\) and \(\ll G, F, S \gg\). According to lemma 6.3.15, every value \(v \in|A|_{r}\) for \(r \in G\) can be produced by a term \(t_{v} \in\left|T_{\langle G u S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{r}\) using a valuation \(\nu:\left.T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right) \rightarrow A\right|_{\text {c }}\) such that \(\nu(t)=v\). By assumption, there exists also a term
\[
t_{v}^{\prime} \in\left|T_{\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle}\left(\mathcal{X}_{S \backslash S^{\prime \prime}}\right)\right|_{r} \subseteq\left|T_{(G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{r}
\]
such that \(\Phi \vDash_{\Sigma} \forall X . t_{v}=t_{v}^{\prime}\), hence \(\nu\left(t_{v}^{\prime}\right)=v\).
Taking the \(\iota^{\prime \prime}\)-reduct of the valuation \(\nu\), we obtain a homomorphism over \(\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle\)
\[
\left.\nu\right|_{\iota^{\prime \prime}}:\left.\left.T_{(G U S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{\iota^{\prime \prime}} \rightarrow A\right|_{\iota^{\prime \prime} ; \iota}
\]
which by definition can be restricted to terms in \(\left|T_{\left(G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right)}\left(\mathcal{X}_{S \backslash S^{\prime \prime}}\right)\right|\)
\[
\nu^{\prime}:\left.T_{\left\langle G \cup\left(S \backslash S S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right)}\left(\mathcal{X}_{S \backslash S^{\prime \prime}}\right) \rightarrow A\right|_{\iota^{\prime \prime} ; \iota}
\]
so that \(\nu^{\prime}\) is a valuation with \(\nu^{\prime}\left(t_{v}^{\prime}\right)=v\) thus \(A \models_{\Sigma} \ll G, F \backslash F^{\prime \prime}, S \backslash S^{\prime \prime} \gg\).
Entailment in the other direction follows immediately from
\[
\ll G, F \backslash F^{\prime \prime}, S \backslash S^{\prime \prime} \gg \vdash \ll G, F, S \gg
\]
and soundness of \(\vdash\) w.r.t. constraint entailment (Theorem 6.3.5).

This fact together with an inference system \(\vdash^{\mathbf{A L G}}\) provide a sufficient criterion for checking redundancy of some sorts and functions in a reachability constraint w.r.t. a presentation. For example, consider
```

\Sigma= sorts nat
operations
0: nat ....
suc: nat -> nat
_+ : nat, nat -> nat
\Phi={ \foralln:nat. 0+n=n,
\foralln,m:nat. (suc m)+n=suc(m+n)}

```

It is not difficult to check that " + " is redundant in \(\ll\{\) nat \(\},\{0\), suc,+\(\}, \emptyset \gg\) w.r.t. \(\Phi\) using the above criterion. In this case, it is enough to prove by structural induction on terms of sort nat that every term containing " + " is equal to a term without " + ".

In fact, the above criterion characterizes redundancy in EQ when the set of generating carriers \(S\) in a constraint \(\ll G, F, S \gg\) is empty.

Proposition 6.3.17 Given a signature \(\langle G, F\rangle\), a set of \(\langle G, F\rangle\)-equations \(\Phi\) and a constraint \(\ll G, F, \emptyset \gg\), if a pair \(\left\langle\emptyset, F^{\prime \prime}\right\rangle\) is redundant in \(\ll G, F, \emptyset \gg\) w.r.t. \(\Phi\), then
\[
\forall t \in\left|T_{\langle G, F\rangle}\right|_{r} . \exists t^{\prime} \in\left|T_{\left\langle G, F \backslash F^{\prime \prime}\right\rangle}\right|_{r} . \Phi \models_{\langle G, F\rangle} \forall \emptyset . t=t^{\prime}
\]
for all sorts \(r \in G\).

Proof Let \(\iota\) be the inclusion
\[
\left\langle G, F \backslash F^{\prime \prime}\right\rangle \stackrel{\iota}{\hookrightarrow}\langle G, F\rangle
\]
and \(I\) the quotient of \(T_{\langle G, F\rangle}\) modulo the least congruence generated by the equations in \(\Phi\). By definition of least congruence, we have that
\[
\nu_{I}(t)=\nu_{I}\left(t^{\prime}\right) \quad \text { iff } \quad \Phi \vDash_{\langle G, F\rangle} \forall \emptyset \cdot t=t^{\prime}
\]
where \(\nu_{I}: T_{\langle G, F\rangle} \rightarrow I\) maps each term to its quotient class of terms in the algebra \(I\). In other words, the algebra \(I\) under valuation \(\nu_{I}\) characterizes those equations satisfied by all the models of \(\Phi\).

By definition of \(I\), it is clear that \(I \models_{\langle G, F\rangle} \Phi\) and also that \(I \models_{\langle G, F\rangle} \ll \dot{G}, F, \emptyset \gg\), and since \(\left\langle\emptyset, F^{\prime \prime}\right\rangle\) is redundant in \(\ll G, F, \emptyset \gg\) w.r.t. \(\Phi, I \vDash_{\langle G, F\rangle} \ll G, F \backslash F^{\prime \prime}, \emptyset \gg\) as well.

Then, every term \(t \in\left|T_{(G, F)}\right|_{r}\) for \(r \in G\) denotes a value \(\nu_{I}(t) \in|I|_{r}\) which can be generated by a term \(t^{\prime} \in\left|T_{\left(G, F \backslash F^{\prime \prime}\right)}\right|_{r}\) under a valuation which can only be \(\nu_{I}\), i.e. \(\nu_{I}\left(t^{\prime}\right)=\nu_{I}(t)\), hence \(\Phi \models_{\langle G, F\rangle} \forall \emptyset\). \(t=t^{\prime}\).

\section*{Redundancy and sufficient completeness}

Sufficient completeness of a free extension \(F_{\sigma}^{e q} S P\), as defined on page 77, means that no new values are added to old carriers. In particular, having a generated sort \(r \in G\) with a redundant generator \(o p \in F_{r}\) in \(\ll G, F, \emptyset \gg\) w.r.t. a set of equations eq is equivalent to sufficient completeness of \(F_{\iota}^{e q}\left(F_{\sigma} \epsilon_{(\theta, \emptyset)}\right)\) with
\[
\langle\emptyset, \emptyset\rangle \stackrel{\sigma}{\hookrightarrow}\langle G, F \backslash\{o p\}\rangle \stackrel{\iota}{\hookrightarrow}\langle G, F\rangle
\]

In fact sufficient completeness as originally defined [GH 78] looks very similar to our criterion for checking redundancy (when all sorts are generated), whereas our definition in chapter 3 is analogous to the model theoretic definition in [Gau 78, Gan 83, EM 85].

In the literature, both definitions refer to initial semantics, and while the model theoretic definition requires that: no new values are added to old carriers, the proof theoretic definition requires that: every new term must be provably equal to an old one (using equational logic). For equational specifications with initial semantics both definitions are equivalent but for loose semantics their trivial generalizations are not equivalent any more [Ber 87].

\section*{Second proof criterion}

Unfortunately, if sentences are not equations, there are redundancies that we cannot prove using the above criterion, even if the set of generating carriers \(S\) is empty. For example:
```

\Sigma'= sorts nat
operations
0: nat
suc: nat -> nat
rand: nat -> nat
\Phi'={ \forall n:nat. 0+n=n,
\foralln,m:nat. (suc m)+n=suc(m+n),
|n:nat. rand (n)=n V rand (n)=suc(n)}

```

In this case the function rand is clearly redundant in \(\ll\{\) nat \(\}\), \(\{0\), suc, rand \(\}, \emptyset \gg\) w.r.t. \(\Phi^{\prime}\) since rand cannot produce other natural numbers than those generated by 0 and suc. However, the proof criterion fails since given a term rand \((0) \in\) \(\left|T_{\{\{\text {nat }\},\{0, \text { suc,rand }\}\}}\right|\) there is no term \(t^{\prime} \in\left|T_{\{\{\text {nat }\},\{0, \text { suc }\})}\right|\) such that for all \(A\) satisfying \(\Phi^{\prime}, A \models \operatorname{rand}(0)=\mathrm{t}^{\prime}\).

A difference between satisfying the above criterion and actual redundancy is that, for redundancy, given a term \(t\), the term \(t^{\prime}\) may be different for each model of \(\Phi\), while in the above criterion, \(t^{\prime}\) must be same in all models of \(\Phi\). For this reason, the proof criterion is not a necessary condition for redundancy in ALG.

\section*{In tight specification-languages-where-onty-one-model-of- \(\Phi\)-is-considered fop. to isemerphim), for example the initial model, this problem-disappears.}

Cases such as the redundant function rand make us think that our proof criterion should be improved.

Proving redundancy as it stands in the definition involves a quantification over models which is not acceptable from a proof-theoretic point of view. We cannot expect to give a different term equivalent to rand (0) for each possible model of \(\Phi^{\prime}\). However, if we want to prove that rand is redundant, we can show that all possible results of rand \((t)\) are natural numbers generated by 0 and sue, assuming that term \(t\) is generated by 0 and sue.


Proposition 6.3.18 (Second proof criterion) Given a set of \(\Sigma\)-sentences \(\Phi\) including set theory, a \(\Sigma\)-constraint \(\ll G, F, S \gg\) and a pair \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) such that \(S^{\prime \prime} \subseteq S, F^{\prime \prime} \subseteq F\) and
\[
\forall t \in\left|T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\right| . \exists T^{\prime} \subseteq\left|T_{\left\langle G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle}\left(\mathcal{X}_{S \backslash S^{\prime \prime}}\right)\right| . \Phi \models_{\Sigma} \forall \mathcal{X}_{S} . t \in T^{\prime}
\]
then \(\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle\) is redundant in \(\ll G, F, S \gg\) w.r.t. \(\Phi\).

notation "t \(\in T\) " must be understood as an infinitary disjunction \(\left.=t^{\prime} \mid t^{\prime} \in T^{\prime}\right\}\). This implies extending \(E Q\) to include disjunction en equations and, in particular. infinitary disjunctions.

Proof The proof proceeds analogously to the proof for the first criterion (proposition 6.3.16) taking into consideration that if a \(\Sigma\)-algebra without empty sorts \(A\) satisfies
\[
A \models_{\Sigma} \forall \mathcal{X}_{S} . t \in T^{\prime}
\]
there exists a term
\[
t_{v}^{\prime} \in T^{\prime} \subseteq\left|T_{\left(G \cup\left(S \backslash S^{\prime \prime}\right), F \backslash F^{\prime \prime}\right\rangle}\left(\mathcal{X}_{S \backslash S^{\prime \prime}}\right)\right|_{r} \subseteq\left|T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right)\right|_{r}
\]
and a valuation \(\nu:\left.T_{\langle G \cup S, F\rangle}\left(\mathcal{X}_{S}\right) \rightarrow A\right|_{\imath}\) such that \(\nu\left(t_{v}\right)=\nu\left(t_{v}^{\prime}\right)\).

The second criterion is almost equivalent to redundancy when \(T^{\prime}\) includes all terms \(t^{\prime}\) equivalent to \(t\) in some model of \(\Phi\). At the same time, the second criterion is equivalent to the first criterion when \(T^{\prime}\) is a singleton.

Redundancy of the function rand in the example presented above can be proven using the second proof criterion by taking \(T^{\prime}=\{t, \operatorname{suc}(t)\}\) for every term \(t \in\) \(\left|T_{\{\{n a t\},\{0, s u c\}\rangle}\right|\).

This second criterion is defined for FOEEQ-including theory ameng theirsenfortunately this prevents their inference systems from being complete using finite rules
 this approach satisfactory just as we consider an induction schema satisfactory for proving inductive theorems.

According to this second criteria for redundancy, we can give an inference system \(\vdash_{\Phi}\) between constraints parameterized by a set of sentences \(\Phi\) which extends \(\vdash\).as follows:
\[
\begin{gathered}
\ll G 1, F 1, S 1 \gg \vdash \ll G 2, F 2, S 2 \gg \\
\ll G 1, F 1, S 1 \gg \vdash_{\Phi} \ll G 2, F 2, S 2 \ggg \\
\frac{\left\langle S^{\prime \prime}, F^{\prime \prime}\right\rangle \text { is redundant in } \ll G, F, S \gg \text { w.r.t. } \Phi}{\ll G^{\prime} F, S \gg \vdash_{\Phi} \ll G, F \backslash F^{\prime \prime}, S \backslash S^{\prime \prime} \gg}
\end{gathered}
\]

An inference system \(H_{\Phi}\) between sets of constraints is defined to be the same as \(\nVdash\), but using \(\vdash_{\Phi}\) instead of \(\vdash\) for single constraints.

Completeness of \(\mathbb{H}_{\Phi}\) does not hold. This is so because of the same considerations as in \(\mathbb{H}\) about using several constraints on one sort. Another reason for this is because, as has just been said, we have no complete system for redundancy, which leads to incompleteness of \(\vdash_{\Phi}\).

\section*{Solving \(M A \vDash M A\)}

Taking into consideration the proof criteria for redundancy, we can also give an overall inference system for mixed sets of constraints and sentences in ALG. Such a system must include: the inference system for sentences \(\vdash^{\text {ALG }}\), the inference system for sets of constraints \(\mathbb{H}\), an induction schema such as the one proposed for \(M A \models A\) in section 3.3.2 and a rule to take care of redundant generators.

An inference system \(\mathbb{H}^{\text {ALG }}\) between pairs consisting of a set of equations and a set of reachability constraints is defined by the following rule:
\[
\frac{\Phi 2 \vdash^{\mathbf{A L G}+I N D(C 2)} \Phi 1 \quad C 2 H_{\Phi 2} C 1}{\langle C 2, \Phi 2\rangle H^{\mathbf{A L G}}\langle C 1, \Phi 1\rangle}
\]
where \(\vdash^{\text {ALG }+I N D(C 2)}\) is the inference system \(\vdash^{\text {ALG }}\) plus the induction rules which follow from reachability constraints in \(C 2\).

In the general case, the system is incomplete for several main reasons:
1. Incompleteness of the induction rule w.r.t. the inductive consequences of a theory.
2. Incompleteness of theory which reults in incompleteness the second criterion for redundancy.
3. Incompleteness caused by the simultaneous use of constraints over the same sort.
4. Incompleteness caused by the existence of sets of sentences which can entail reachability constraints on their own.

The first two reasons have been sufficiently explained. The third refers to the incompleteness of \(\mathbb{H}\) unless the sets of constraints can be correctly joined as discussed in section 6.3.1 and in the example with three constants on page 210.

The fourth reason refers to those cases where reachability can be imposed by the sole use of sentences. In institutions such as EQ or FOLEQ, this is the case for presentations with only finite models. For example:
\[
\forall x: \text { bool. }(x=\text { true }) \vee(x=\text { false }) \vDash \ll\{\text { bool }\},\{\text { true }, \text { false }\}, \emptyset \gg
\]
where a reachability constraint is equivalent to a first order sentence. In this case, we should explicitly add a rule inferring a reachability constraints from disjunctions of the form \(\forall x: r .(x=v 1) \vee(x=v 2) \vee \ldots \vee(x=v n)\).

In other institutions the problem can become harder. For example, if we consider FOL with only enumerable models, rational numbers are axiomatizable using only sentences (see page 76 of [Men 71]). Therefore a reachability constraint over rational numbers follows from a set of first order sentences.

Summing up, incompleteness arises in very specific situations about which we can do very little in general. In practice, almost all entailments we find in algebraic specifications, and in particular the example on page 212 where the independent strategy fails, are derivable in the system presented above. For this reason, we shall consider \(\Vdash^{\text {ALG }}\) satisfactory w.r.t. \(M A \models M A\) in ALG.

\subsection*{6.4 Structured specifications with constraints}

Our purpose in this section is proving entailments \(A S L \models A S L\) and \(A S L \models M\) in particular, using the satisfactory inference systems already developed for \(D A T U \vDash\) \(D A T U\) and \(M A \models M A\).

Since reachability constraints can be seen as a particular kind of sentences and the inference system for \(D A T U \models D A T U\) is parameterized by the underlying logic of the sentences \(\vdash^{\mathrm{I}}\) but is institution independent otherwise, we obtain an inference system for \(A S L \models A S L\) by using our satisfactory inference system for \(D A T U \vDash D A T U\) and an underlying inference system dealing with ordinary sentences and constraints. In the case of ALG and restricting signature morphisms to be injective, \(\Vdash^{\text {ALG }}\) can be used.

In the following, we shall briefly revisit the inference rules for theorem proving and the inheriting strategy for \(D_{\sigma}\) but keeping in mind that sentences are reachability constraints or a mixture of constraints and another kind of sentences such as equations.

\subsection*{6.4.1 Proving constraints from specifications}

In chapter 3 theorem proving was studied, in particular \(D A T U \vDash A\), and it was shown to be adequate for \(D A T U \models A T U\) due to the M -completeness of the inference rules for \(T_{\sigma}\) and \(U\). Results in theorem 3.3.12 are independent of the nature of the sentences, and therefore they hold for reachability constraints. For example, we can say that
\[
\frac{S P \vdash \ll \sigma, \iota \gg}{T_{\sigma^{\prime}} S P \vdash \sigma^{\prime}(\ll \sigma, \iota \gg)} \quad \text { is sound and M-complete (exact) }
\]
and similarly for sentences being pairs consisting of a set of constraints and a set of ordinary sentences, e.g.
\[
\frac{S P \vdash\langle\sigma(C), \sigma(\Phi)\rangle}{D_{\sigma} S P \vdash\langle C, \Phi\rangle} \quad \text { is sound and complete }
\]

As explained in chapter 3, SBO's with an exact inference rule can be eliminated to yield a normalized specification. That is why inference systems for \(A T U \vDash\) \(A T U, M T U \vDash M T U\) and \(M A T U \vDash M A T U\) are immediate from the underlying inference systems \(\vdash^{\mathbf{I}}, \mathbb{H}^{-}\)and \(H^{\mathbf{I}}\) for \(A \models A, M \vDash M\) and \(M A \models M A\) respectively.

In the case of specifications with constructors \(k+A S L \models A\), little has been said in general. For generic constructors, an explicitly given relation between sentences is all that can be inferred whereas for \(F Q R\)-constructors the results given are only valid for equations.

If sentences happen to be constraints, generic constructors \(\langle P, \Lambda\rangle\) should include an explicit relation between constraints in \(\Lambda\). In the case of \(F R Q\) in the algebraic institution \(\mathbf{E Q}\) with reachability constraints, some new inference rules are given below.

Proposition 6.4.1 \(\quad \frac{S P \vdash \ll G, F, S \gg}{Q_{e q} S P \vdash \ll G, F, S \gg} \quad\) is a sound inference rule.

Proof Given a signature inclusion \(\iota:\langle G \cup S, F\rangle \hookrightarrow \operatorname{Sig}[S P]\) and an algebra \(A \in\) \(\operatorname{Mod}[S P]\), for \(r \in G\) and for every \(v \in|A|_{r}\) there exists a term \(t_{v} \in\left|T_{\langle G \cup S . F\rangle}\left(X_{S}\right)\right|_{r}\) and a valuation \(\nu: T_{\langle G U S, F\rangle}\left(X_{S}\right) \rightarrow A\) such that \(\nu\left(t_{v}\right)=v\). By definition of the quotient algebra \(A / \sim_{A}^{e q}\) there exists a surjective valuation \(\nu_{Q}: T_{\langle G \cup S, F\rangle}\left(X_{S}\right) \rightarrow\) \(A /\left.\sim_{A}^{e q}\right|_{\text {c }}\) defined as \(\nu_{Q}(t)=[\nu(t)]\). Then \(\nu_{Q}\left(t_{v}\right)=[v]\) and, since \(\nu_{Q}\) is surjective. all values in \(\left|A / \sim_{A}^{e q}\right|_{r}\) (quotient classes of values in \(|A|_{r}\) ) are some valuation of some term in \(T_{\langle G u S, F\rangle}\left(X_{S}\right)\).

Proposition 6.4.2
\[
\overline{R_{G} S P \vdash \ll G, \Omega, S \backslash G \gg} \quad \text { where } \operatorname{Sig}[S P]=\langle S, \Omega\rangle \text { is }
\] a sound inference rule.

Proof Given a \(\langle S, \Omega\rangle\)-algebra \(A \in \operatorname{Mod}[S P]\), by definition of \(\operatorname{Reach}_{G}, \operatorname{Reach}_{G}(A)\) is reachable on sorts in \(G\); that is to say, carriers \(\left|\operatorname{Reach}_{G}(A)\right|_{r}\) for \(r \in G\) are finitely generated from sorts not in \(G\) using all the functions in \(\Omega\), hence \(\operatorname{Reach}_{G}(A) \vDash(s, \Omega)\) \(\ll G, \Omega, S \backslash G \gg\).

Proposition 6.4.3 \(\quad \frac{S P \vdash \ll G, F, S \gg}{R_{G^{\prime}} S P \vdash \ll G, F, S \gg} \quad\) is a sound inference rule provided \(G^{\prime} \cap S=\emptyset\) and \(\ll G^{\prime}, \Omega^{\prime}, S^{\prime} \backslash G^{\prime} \gg\) for \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle=\operatorname{Sig}[S P]\) is \(\emptyset\)-free.

Proof Given a \(\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\)-algebra \(A \in \operatorname{Mod}[S P]\), the operation \(R_{G^{\prime}}\) removes nonreachable values from carriers \(|A|_{r}\) for sorts \(r \in G^{\prime}\). By cases:
- If \(r \in G, R_{G^{\prime}}\) may remove some values from \(|A|_{r}\) but not all of them since \(\ll G^{\prime}, \Omega^{\prime}, S^{\prime} \backslash G^{\prime} \gg\) is \(\emptyset\)-free. Hence, because \(G^{\prime} \cap S=\emptyset\) all values in \(\mid\) Reach \(\left._{G^{\prime}}(A)\right|_{r}\) continue to be the evaluation of a term in \(T_{\langle G U S, F\rangle}\left(X_{S}\right)\) for a certain \(S\)-indexed set of variables \(X_{S}\) as they are in \(|A|_{r}\).
- If \(r \notin G, R_{G^{\prime}}\) may remove some but not all values from \(|A|_{r}\). Since \(r\) is neither a generated nor a generating sort in \(\ll G, F, S \gg\), reachability of \(A\) on sorts \(G\) is not affected.

Proposition 6.4.4 \(\frac{S P \vdash \ll G, F, S \gg}{F_{\sigma}^{e q} S P \vdash \ll \sigma(G), \Omega^{\prime}, S^{\prime} \gg} \quad\) is a sound inference rule provided \(\uparrow \sigma=\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\).

Proof A free extension can quotient the elements of the old carriers and add some new reachable values to them. Since quotients cannot prevent reachability from holding, all generated sorts continue to be generated.

Proposition 6.4.5 \(\quad \overline{F_{\sigma}^{e q} S P \vdash \ll G, \Omega^{\prime}, \sigma(S) \gg} \quad\) is a sound inference rule provided \(\sigma:\langle S, \Omega\rangle \rightarrow\left\langle\sigma(S) \uplus G, \Omega^{\prime}\right\rangle\).

Proof By definition of \(F_{\sigma}^{e q}\), carriers in the new sorts \(G\) are generated from the carriers in old sorts \(\sigma(S)\).

\subsection*{6.4.2 Specifications with hidden generators}

In chapter 4 some strategies to deal with hiding, \(D A T U \vDash D A T U\), have been presented. Strategies and results are independent of the nature of the sentences and therefore immediately translate into strategies for \(A S L \models A S L\). Nevertheless, checking for persistency and independence have a very different intuition when sentences are reachability constraints.

In the examples seen in chapter 4, persistency and independence looked like very reasonable requirements: Persistency as used there guarantees that the specification of some auxiliary functions does not affect the visible part and independence makes the choice of a model of the whole specification independent of the choice of model for the auxiliary functions when they are not completely defined. Some difficult cases where these requirements are not met, studied at the end of that chapter, stem from mistakes in the design of the specification or an incomplete specification of the auxiliary functions respectively, according to this view.

In chapter 5 , the same proof strategy is applied to abstracted specifications. In that context, independence rarely holds and persistency is easily violated.
```

SP = Enrich Bool by
sorts elem, set
operations
axioms
end

```

Figure 6-1: Booleans plus sorts for elements and sets

Now, if we consider that the hidden part of the consequent includes some of the generators and a constraint for a given sort, independence is generally lost and also persistency is lost unless the generated sort is hidden.

\section*{Example}

Consider for example a specification of sets generated by \(\emptyset\), singleton \(\{-\}\) and union - \(U_{-}\)where the only visible functions are insert, choose and remove, such as Set in figure 6-2, built on top of \(S P\) in figure 6-1. A user may implement such a specification using a representation of sets by lists as described in the specification Impl in figure 6-3.

It is our goal to prove that \(I m p l \models S e t\). Since \(S e t\) has the form of a specification \(S P\) with a hidden and a visible enrichment we may apply the inheriting strategy.

First of all, it makes little sense to discuss the persistency of the hidden generators, \(\left\{\emptyset, \cup_{-},\{-\}\right\}\), w.r.t. the visible sort set. In general, an enrichment including the hidden generators of a visible sort is never persistent w.r.t. the specification of the sort they generate, unless the generators are redundant. Moreover, independence fails since other operations on sets such as insert and remove are intimately dependent on the generators.

The most dramatic side of this problem is that the example corresponds to a common refinement style:
```

Set = Enrich SP by
Hidden
sorts
operations
|: set
_U_: set, set -> set
{-}: elem -> set
axioms
Reachable on {set} using {\emptyset, U_, {-}} from {elem}
* s:set. S U \emptyset=s
| s:set. S U S = S
\forall S1, S2:set. S1 U S2 = S2 U S1
\forall1, S2, S3:set. (S1 U S2) U S3 = S1 U (S2 U S3)
in
sorts
operations
insert: set, elem -> set
choose: set -> elem
remove: set, elem -> set
_\epsilon_: elem, set -> bool
axioms
|e:elem; S:set. insert(S, e) = {e} U S
\forall e1,e2:elem. e1 = e2 \Leftrightarrow e1\in{e2} = true
|:elem. e\in \emptyset= false
|:elem; S1,S2:set. e\in(S1US2) = (e\inS1 \vee e\inS2)
| e:elem; S:set. e\inremove(S, e) = false
|1,e2:elem; S:set. (e1\not=e2) => (e2\inremove(S, e1) = e2\inS)
S:set. (S\not=\emptyset) => (choose(S) }\inS=\mp@code{true)
end

```

Figure 6-2: Sets with hidden generators
```

Impl = Enrich SP by
Hidden
sorts list
operations
\alpha: list -> set
[]: list
_::_: elem, list -> list
axioms
Reachable on {list} using {[],::} from {elem}
Reachable on {set} using {\alpha} from {list}
in
sorts
operations
insert: set, elem -> set
choose: set -> elem
remove: set, elem -> set
_G_: elem, set -> bool
axioms
\foralle:elem; L:list. insert( }\alpha(\textrm{L}),\textrm{e})=\alpha(e::L
{Defining choose, remove and \in in terms of list operations}
end

```

Figure 6-3: Sets represented by lists

First a data type is specified in terms of its own constructors using a reachability constraint and some axioms (e.g. sets in terms of \(\emptyset,\{-\}\) and \(\cup\), natural numbers in terms of 0 and suc, stacks in terms of empty and push, etc.), and then the implementation is carried out in terms of some primitive data types (e.g. lists, arrays, pointers, etc.) substituting the set of generators by a unique abstraction function, \(\alpha\). Moreover, if the original generators are too low level, they are hidden from the user.

This may not be the most common approach when lists implement sets but it is certainly the approach used when arrays implement lists or stacks.

At first sight, our inference system for \(D A T U \vDash D A T U\) seems to fail badly in all the interesting cases where the hidden functions are generators. However, we recall from chapter 4 that persistency of the hidden enrichment w.r.t. the specification on which it is built is not necessary; as explained in proposition 4.4.2, the hidden enrichment only needs to preserve those models which are actually used in the antecedent (implementation). This is also the case in the \(\exists^{2}\)-strategy, where \(S P 2 \models D_{\sigma 1 ; \sigma}\left(A_{\Phi} T_{\sigma 1 ; \sigma}\right) S P 2\) is required (see section 4.2).

Although both the \(\exists^{2}\)-strategy and the inheriting strategy as formulated in proposition 4.4.2 can be used, only the \(\exists^{2}\)-strategy will deliver some good results. The reason for this stems from the close relationship between the interpretation of a sort and the interpretation of its generators. This "strongly interdependent" relationship ruins independence of the hidden enrichment defining the generators and, in almost all cases, prevents the success of the inheriting strategy.

Using the \(\exists^{2}\)-strategy in our example, we are required to prove the persistency of an enrichment over Impl such as
\[
\begin{aligned}
E I m p l= & \text { Enrich } I m p l \text { by } \\
& \text { sorts } \\
& \text { operations }
\end{aligned}
\]
```

            |: set
            _U_: set, set -> set
            {-}: elem -> set
    axioms
Reachable on {set} using {\emptyset, _U_, {-}} from {elem}
|}=\alpha([]
| elem. {e} = \alpha [e])
\forallL1, L2:list. }\alpha(\textrm{L}1)\cup\alpha(L2)=\alpha(append(L1, L2))
end

```

This holds since all possible sets generated from a list by \(\alpha\) can also be generated by \(\emptyset, U_{-}\)and \(\{-\}\)using their definitions in EImpl.

At this point we may recognize this as common practice in correctness proofs, particularly in abstract model specification. Nevertheless, this criterion is commonly used in an ad hoc fashion whereas here it belongs to a general strategy for \(D_{\sigma}\) in the particular case that sentences include reachability constraints and some generators are hidden.

Similarly to the last chapter for behavioural abstraction, the basic concepts of persistency and independence arise again as key factors in the proof of specification entailments. The multiple re-use of the same ideas shows the flexibility of our institution-independent results in chapter 4.

\subsection*{6.4.3 Behaviourally abstract specifications with hidden generators}

Very often, sorts with hidden generators happen to be non-observable sorts. In this case, as discussed in [ST 88b], the reachability constraint does not constrain the re-
sulting specification since a non-reachable algebra is, most of time \({ }^{3}\), behaviourally equivalent to its reachable subalgebra. However, many proofs of specification entailments extend the antecedent, e.g. using a persistent enrichment, to the point that the hiding in the consequent specification can be ignored; in this situation, also reachability constraints on non-observable sorts must be proven to hold in the extended antecedent.

In fact, when the hiding of constructors together with behavioural abstraction take place in a consequent specification, we run into sophisticated specification entailments known as data reification in abstract model specification languages (see for example chapter 8 in [Jon 86]).

Proofs can be carried out in our system using the \(\exists^{2}\)-strategy for the hidden generators and we can either prove all observable consequences or treat behavioural abstraction as hiding. Representation invariants like those used in [Jon 86] usually help to prove that the generators of the antecedent are redundant w.r.t. the generators of the same sort in the consequent and therefore the constraint in the consequent is persistent w.r.t. the antecedent.

\section*{Example}

Consider an example of data reification where a table specified in terms of a list of〈index, value〉 pairs, as shown in Tabll of figure 6-5, is implemented by a B-tree, as specified in Tabl2 of figure 6-6.

In this case we have to prove that \(T a b l 2 \models T a b l 1\) where \(T a b l 1\) contains simultaneously hidden generators and non-observable sorts.

\footnotetext{
\({ }^{3}\) This is always the case when observations are ground equations.
}
```

Pairs = sorts index, value, pair, table
operations
(-,-): index, value -> pair
axioms
end

```

Figure 6-4: Index and value pairs plus a sort for tables

Behavioural abstraction cannot be ignored since theorems such as: •
```

\foralli:index; v:value. remove(insert(T_empty, i, v), i) = T_empty

```
hold in Tabl1 but not in Tabl2. But, contrary to the case of stacks implemented by arrays and pointers, several different tables in Tabll can have a unique representation in Tabl2. In abstract model specifications this phenomenon is called implementation bias and makes proofs more complicated (cf. section 9.1 in [Jon 86]).

The entailment proof can be carried out as follows:
1. The hidden enrichment of Tabl1 is added to Tabl2 and proven persistent. This enrichment includes the specification of lists and the function \(\alpha 1\) with the reachability constraint over table by \(\alpha 1\), so that we obtain an enriched antecedent ETabl2 as in figure 6-7.

Due to the lack of independence, \(\alpha 1\) must be further specified in ETabl2 in terms of \(\alpha 2\) and B-trees. This can be done by a single axiom \(\varphi\) as follows:
\[
[\varphi] \quad \forall \mathrm{T}: \text { tree. } \alpha 2(\mathrm{~T})=\alpha 1(\text { tree } 2 l \text { ist }(\mathrm{T}))
\]
with tree2list: tree -> list delivering the preorder traversal of a tree in the form of a list.

From this definition, all those tables generated by \(\alpha 2\) from trees can also be generated using \(\alpha 1\) from lists. This can be formally proven by showing
```

Tabl1 = Non_observable on {table}
Enrich Pairs by
Hidden
sorts list
operations
\alpha1: list -> table
{Standard operations on lists of (index, value) pairs}
axioms
Reachable on {table} using {\alpha1} from {list}
Reachable on {list} using {[],::} from {pair}
{Standard axioms on lists of <index,value〉 pairs}
in
sorts
operations
T_empty: table
insert: table, index, value -> table
remove: table, index -> table
look_up: table, index -> value
axioms
T_empty = \alpha1([])
\foralli:index; v:value; L:list. insert( }\alpha1(\textrm{L}),\textrm{i},\textrm{v})=\alpha1((i,v)::L
\foralli:index; v:value; L:list. look_up(\alphal((i,v)::L), i) = v
\foralli1,i2:index; v:value; L:list. i1\not=i2 =>
look_up(\alpha1((i2,v)::L), i1) = look_up( }\alpha1(\textrm{L}),\textrm{i}
\forall i:index. remove( }\alpha1([]), i) = \alpha1([]
\foralli:index; v:value; L:list.
remove(\alphal((i,v)::L), i) = remove( }\alpha1(\textrm{L}),\textrm{i}
i1,i2:index; v:value; L:list. i1fi2 }
remove(\alphal((i2,v)::L), i1) = insert(remove( }\alpha1(\textrm{L}),\textrm{i}1), i2, v

```
    end
```

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```
Tabl2 =
```

Enrich Pairs by
Hidden
sorts tree
operations
mark: value
\alpha2: tree -> table
{Standard operations on B-trees of pairs 〈index, value\rangle
ordered by index}
axioms
Reachable on {table} using {\alpha2} from {tree}
Reachable on {tree} using {tree_empty, node} from {pair}
{Standard axioms for B-trees of pairs (index, value)
ordered by index}
in
sorts
operations
T_empty: table
insert: table, index, value -> table
remove: table, index -> table
look_up: table, index -> value
axioms
T_empty = \alpha2(tree_empty)
|i:index; v:value; T:tree.
insert( }\alpha2(\textrm{T}), i, v) = \alpha2(tree_add(T, i, v))
i:index; v:value. look_up(\alpha2(leaf(i, v)), i) = v
i1,i2:index; v:value; T1,T2:tree.
(i1<i2 }=>\mathrm{ look_up( }\alpha2(\operatorname{node(T1,T2,i2)), i1) = look_up( }\alpha2(T1), i1)
^(i1\geqi2 }=>\mathrm{ look_up( }\alpha2(\operatorname{mode(T1,T2,i2)), i1) = lookup( }\alpha2(\textrm{T}2), i1
i:index; T:tree. remove( }\alpha2(\textrm{T}),\textrm{i})=\alpha2(tree_add(T, i, mark)
end

```
```

ETabl2 = Enrich Tabl2 by
sorts list
operations
\alpha1: list -> table
{Standard operations on lists of {index,value\rangle pairs}
axioms
Reachable on {table} using {\alphal} from {list}
Reachable on {list} using {[],::} from {pair}
{Standard axioms on lists of <index,value\rangle pairs}
end

```

Figure 6-7: Enriched antecedent specification
the redundancy of \(\langle\{\) tree \(\},\{\alpha 2\}\rangle\) in \(\ll\{\) table \(\},\{\alpha 2, \alpha 1\},\{\) tree, list \(\} \gg\}\) w.r.t. a set of axioms \(\Phi\) defining lists and trees plus the corresponding induction schemata, and using \(\mathbb{H}\) to prove that:
\[
\left.\left.\begin{array}{rl}
\{\ll\{\text { table }\},\{\alpha 2\},\{\text { tree }\} \gg\} & H\{
\end{array}<\{\text { table }\},\{\alpha 2, \alpha 1\},\{\text { tree }, \text { list }\} \gg\right\}\right\}
\]

Summing up, all models satisfying \(\ll\) table \(\},\{\alpha 2\},\{\) tree \(\} \gg\) also satisfy \(\ll\{\) table \(\},\{\alpha 1\},\{\) list \(\} \gg ;\) i.e. adding \(\ll\{\) table \(\} .\{\alpha 1\},\{\) list \(\} \gg\) to \(T a b l 2\) is a persistent enrichment.

We can assume the specification of lists to be persistent w.r.t. the definition of 〈index, value〉 pairs, hence the specification of lists is also persistent w.r.t. Tabl2.
2. Prove that all visible consequences of Tabll hold in \(A_{\{\varphi\}} E T a b l 2\), i.e. all sentences such as
```

\foralli:index;v:value. look_up(insert(T_empty,i,v),i) = v
\foralli:index;v1,v2:value. look_up(insert(insert(T_empty,i,v1),i,v2),i) = v2

```

This amounts to restricting to those tables which can be generated by T_empty, insert and remove, under a context which can only be look_up since it is the only operation yielding an observable value from a nonobservable table. We shall call the whole collection of visible sentences \(\Delta_{\mathrm{inf}}\). Due to the persistency of the enrichment over \(T a b l 2\) and since \(\Delta_{\text {inf }}\) only refers to symbols defined in Tabl2, it suffices to prove that
\[
T a b l 2 \models \Delta_{\mathrm{inf}}
\]
but there are at least three ways to do this proof.
(a) The most straightforward solution seems to be structural induction on the tables used in \(\Delta_{\text {inf }}\), that is, those generated by T_empty, insert and remove.

In Tabl2, T_empty, insert and remove are specified in terms of \(\alpha 2\) and trees. Hence, in order to inductively prove a theorem on table we need to do a simultaneous induction on sorts table and tree, where the predicate on sort tree stands for something like: a tree generated by the definition of T_empty, insert and remove in Tabl2. Such a predicate is usually known in abstract model specifications as a representation invariant. In this case, due to the complexity of insert and remove, it is very hard to find such an invariant. By the definition of \(B\)-tree we know that insertions and removals must preserve the balance of a tree but it is difficult to know, a priori, if some other subtle properties also hold.

A nother problem is that there is no obvious way to inductively present \(\Delta_{\text {inf }}\) without referring to lists. Unlike Stack and other specifications without hiding studied in [Hen S8], we cannot identify the operations used in the observable terms and the generators of tables.
(b) In order to overcome these difficulties, we can try to prove something stronger than \(\Delta_{\text {inf }}\), namely a property holding for all tables generated from lists instead of those generated by T_empty, insert and remove. Consider the following set of sentences from Tabl1:
\([\Delta]\left\{\begin{array}{l}\forall \text { i:index; v:value; L:list. lookup }(\alpha 1((i, v):: L), i)=v \\ \forall i 1, i 2: \text { index; v:value; L:list. i1 } \neq \mathrm{i} 2 \Rightarrow \\ \operatorname{look} \quad \mathrm{up}(\alpha 1((\mathrm{i} 2, \mathrm{v}):: \mathrm{L}), \mathrm{i} 1)=\operatorname{look} \mathrm{up}(\alpha 1(\mathrm{~L}), \mathrm{i} 1)\end{array}\right.\) Since all tables are reachable by \(\alpha 1\) from a list and by definition of insert and remove in \(T a b l 1\), it is enough to prove that \(\Delta\) is satisfied by \(A_{\{\varphi\}}\) ETabl2.

At this point we need to complete \(\varphi\) so that all tables generated from a list can also be generated from a tree.
\(\left[\varphi^{\prime}\right] \forall\) L:list. \(\alpha 1(\mathrm{~L})=\alpha 2(\) list2tree(L))
with list2tree: list \(\rightarrow\) tree inserting all the elements of a list into an empty tree.

We could have chosen \(\varphi\) to be \(\left\{\varphi, \varphi^{\prime}\right\}\) in the first instance, but at that point there was no obvious need. Note that the pair of functions list2tree and tree2list plays the role of a many-to-many relation between lists representing tables and trees representing tables like the retrieve relation in reification proofs [Jon 86], but they are at the specification level instead of being model constructions.

Now, \(\Delta\) can be proven to hold in \(A_{\left\{\varphi, \varphi^{\prime}\right\}}\) ETabl2. First. \(\alpha 1\) is replaced by its definition in terms of \(\alpha 2\) and list2tree and then we can proceed by induction.

As before, we can devise a simultaneous induction on tree and table so that a predicate states an invariant over trees generated by list2tree, e.g. distinguishing trees with at most one value for each index. But, in contrast to the previous attempt, we expect to prove the two theorems in \(\Delta\) rather than an infinite set of theorems \(\Delta_{\mathrm{inf}}\).
(c) Alternatively, we can treat behavioural abstraction as the hiding of a predicate \(\equiv_{\text {Table }}\) in Tabl1 in the context of first order logic. The predicate \(\equiv \boldsymbol{T}_{\text {able }}\) should be explicitly defined by some axioms such as reflexivity, transitivity and congruence omitted in Tabll and used in the following axioms:
```

T_empty \equiv Table }\alpha1([]
\foralli:index; v:value; L:list. insert(\alpha1(L), i, v) \equivTable \alpha1((i,v)::L)
\foralli:index. remove(\alpha1([]), i) \equivTable \alpha1([])
\foralli:index; v:value; L:list.
remove(\alphal((i,v)::L), i) \equivTable remove( }\alpha1(\textrm{L}),\textrm{i}
\foralli1,i2:index; v:value; L:list. i1 fi2 }
remove(\alphal((i2,v)::L), i1) =Table insert(remove( }\alpha1(\textrm{L}),\textrm{i}1), i2, v

```

Similarly to the example of stacks in the last chapter (see page 177), this hidden enrichment specifying the predicate \(\equiv \boldsymbol{T}_{a b} b_{e}\) is persistent w.r.t. to the specification of the sort table because two tables are never required not to be equivalent (see discussion at the end of section 5.4.2).

Applying the \(\exists^{2}\)-strategy we can define \(\equiv_{\text {Table }}\) from Tabll as a predicate \(\equiv_{T_{a b 1}}\) in ETabl2. When defining \(\equiv_{T_{a b l},}\), it is difficult to identify exactly those trees which correspond to the same list for a certain sequence of operations on tables. It is easier to choose \(\equiv_{\text {Tablı }}\) big enough to include the desired cases and still respect different observations. In this particular example, we can define \(\equiv \boldsymbol{T}_{a b / 1}\) to identify all those trees with the same most recent values for each index.

In the end, this approach might not be very different from the previous one. For example \(\equiv_{T a b l 1}\) can be defined in ETabl2 as follows:
```

T1,T2:tree. T1\equivTabl1T2 }
list2tree(tree2list(T1)) = list2tree(tree2list(T2))

```

Proving that \(\equiv_{\text {Tabil }}\) is a congruence on sort table w.r.t. the rest of the operations in ETabl2 requires us to prove that look_up does not distinguish between equivalent tables, and that is similar to proving \(A_{\left\{\varphi, \varphi^{\prime}\right\}} E T a b l 2 \models \Delta\) as above.
3. The rest of the proof is standard theorem proving.

\section*{Chapter 7}

\section*{Structure and Proofs}

\subsection*{7.1 Introduction}

In previous chapters we were especially concerned with specification entailments where the consequent is flat or has a special structure. In the course of this analysis, three main problems in \(A S L\) proofs have arisen, namely: proving entailment w.r.t. specifications with hidden parts, proving entailment w.r.t. abstracted specifications and proving entailment involving specifications with reachability constraints. Now, we are acquainted with these problems and have some proof techniques to deal with them, however no attempt has been made to accommodate correctness proofs to the structure of specifications.

According to what has been said in previous chapters, confronting the problem of proving \(S P 2 \models S P 1\) for arbitrary structured specifications \(S P 2\) and \(S P 1\) there is little we can directly do. In general, \(S P 1\) over \(A S L\) can be flattened by eliminating \(T_{\sigma}\) and \(U\), putting together all axioms and all constraints and grouping all hiding into a single \(D_{\sigma}\), so that \(S P 1\) becomes a specification such as \(D_{\sigma} A_{(C, \Phi)} \epsilon_{\Sigma}\) for a set of ordinary \(\Sigma\)-sentences \(\Phi\) and a set of \(\Sigma\)-constraints \(C\). This is done by the systematic application of the reduction rules for \(T\) and \(U\) w.r.t. theorems and constraints - see sections 3.2 and 6.4 .1 - plus the permutation rules for \(D_{\sigma}\) - see section 4.2.

Then, if \(D_{\sigma}\) is trivial, \(S P 2 \models D_{\sigma} A_{\langle C, \Phi\rangle} \epsilon_{\Sigma}\) can be solved by mixed theorem proving of ordinary sentences and constraints, as described in section 6.3.2. Otherwise, we try to reduce \(S P 1\) to a specification with a hidden and a visible enrichment, so that the inheriting strategy or the \(\exists^{2}\)-strategy can be used.

Summing up, we are using a two-step procedure: first the consequent is reduced (normalized) to a poorly structured specification and then a simple strategy based on mixed theorem proving completes the proof.

As it was already pointed out in section 3.2 , this two-step procedure may make proofs harder or even impossible. Specifications \(S P 2\) and \(S P 1\) are, commonly, steps in a sequence of entailments from specification to implementation; therefore, we can expect many bits and pieces of \(S P 1\) to be shared by \(S P 2\), and both have a similar structure since only a few aspects of a specification are refined at a time. If a proof of \(S P 2 \vDash S P 1\) ignores these structural similarities by flattening \(S P 1\), the proof becomes harder. Moreover, consequents with constructors cannot be flattened because the inference rules for the constructors are not M-complete, hence entailment proofs cannot use a two-step procedure as sketched above.

The main goal of this chapter is to show that matching the structure of the antecedent to the structure of the consequent makes correctness proofs easier.

Section 2 formalizes the relation between inference rules and specification transformations so that a homogeneous presentation of the two-step strategy can be given. Section 3 studies how whole subspecifications of the consequent can be viewed as single requirements and dealt with as a unit. Section 4 is concerned with modular implementations and, in particular, with the case of consequents with constructors, \(S P 1\) over \(k+A S L\). In section 5 our attention is drawn to the structure of the antecedent and how it can ease theorem proving.

\subsection*{7.2 Revisiting MATU}

Although in the previous chapters we seemed to encourage the use of reduction rules and inference systems for sentences (theorem proving) and constraints, we promised to give a more homogeneous presentation which allows taking advantage of the structure of specifications during entailment proofs. In this section, the socalled two-step strategy flattening + theorem proving is formalized as a particular sequence of applications of some specification transformations.

Firstly, it is shown how sound and M -complete inference rules give rise to specification entailments.

According to the basic proof rule presented in theorem 3.5.1, sound inference rules are to be used for pulling theorems out of the antecedent, therefore the following theorem is as expected.

Theorem 7.2.1 For any sound inference rule \(\frac{S P \vdash f(\varphi)}{\xi S P \vdash g(\varphi)}\) and any specification \(S P\),
\[
\left.\xi A_{\{f(\varphi)\}} S P \vDash A_{\{g(\varphi)\}}\right\} A_{\{f(\varphi)\}} S P
\]

Proof By definition of \(A_{\Phi}\) we know that \(A_{\{f(\varphi)\}} S P \models f(\varphi)\) and by definition of soundness, we conclude that \(\xi A_{\{f(\varphi)\}} S P \models g(\varphi)\). By definition of \(A\) again,
\[
\left.\operatorname{Mod}\left[A_{\{g(\varphi)\}}\right\} A_{\{f(\varphi)\}} S P\right]=\operatorname{Mod}\left[\xi A_{\{f(\varphi)\}} S P\right]
\]

According to the basic proof rule presented in theorem 3.5.1, M-complete inference rules are to be used for pulling axioms out of the consequent, therefore the following theorem is as expected.

Theorem 7.2.2 For any \(M\)-complete inference rule \(\frac{S P \vdash f(\varphi)}{\xi S P \vdash g(\varphi)}\) and any specification \(S P\), provided \(\xi\) distributes over \(U\),
\[
A_{\{g(\varphi)\}} \xi S P \models \xi A_{\{f(\varphi)\}} S P
\]

Proof By the definition of \(A\) and \(U\), and the distributivity of \(\xi\) we know that:
\(\operatorname{Mod}\left[\xi A_{\{f(\varphi)\}} S P\right]=\operatorname{Mod}\left[\xi\left(S P \quad U A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\right)\right]=\operatorname{Mod}\left[(\xi S P) U\left(\xi A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\right)\right]\)
The theory \(C l(\{f(\varphi)\})\) is M-complete (in fact exact) w.r.t. \(A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\), then by definition of an M-complete inference rule, \(C l(\{g(\varphi)\})\) is also an M-complete theory for \(\xi A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\), i.e. \(\operatorname{Mod}\left[A_{\{g(\varphi)\}} \epsilon_{S i g[\xi S P]}\right] \subseteq \operatorname{Mod}\left[\xi A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\right]\). Hence, by monotonicity of \(U\),
\(A_{\{g(\varphi)\}} \xi S P=(\xi S P) U\left(A_{\{g(\varphi)\}} \epsilon_{S i g[\xi S P]}\right) \vDash(\xi S P) U\left(\xi A_{\{f(\varphi)\}} \epsilon_{S i g[S P]}\right)=\xi A_{\{f(\varphi)\}} S P\)

We recall from their definitions that most SBO's in \(A S L\) distribute over \(U\) (see proposition 2.2.6).

These results are valid for all sound and M-complete rules regardless of the nature of the axioms. In particular, axioms can be reachability constraints so that from sound and M-complete inference rules as above w.r.t. constraints, we obtain the corresponding entailments for pulling constraints:
\[
\begin{gathered}
\left.A_{\{g(<\sigma, l \gg)\}}\right\} S P \models \xi A_{\{f(<\sigma, l \gg)\}} S P \\
\left.\xi A_{\{f(<\sigma, c \gg)\}} S P \models A_{\{g(<\sigma, l \gg)\}}\right\} A_{\{f(<\sigma, l \gg)\}} S P
\end{gathered}
\]
for all specifications \(S P\).

A two-step strategy for proving correctness, as sketched at the beginning of this chapter, uses some reduction rules plus the inference rules for theorems and constraints. This strategy can be formalized as follows:

Definition 7.2.3 Given an institution \(\mathbf{I}\), the inference system \(\vdash_{F}\) for specification entailment in \(k+A S L(\mathbf{I})\) is composed of the following rules:
1. Basic proof rule:
\[
\frac{\Phi 2 \vdash^{\mathbf{I}} \Phi 1}{A_{\Phi 2} S P \vdash_{F} A_{\Phi 1} \epsilon_{S i g}[S P]}
\]
2. Pulling sentences (axioms) out of the consequent:
\[
\begin{array}{ll}
A_{\Phi}(S P 1 U S P 2) \vdash_{F}\left(A_{\Phi} S P 1\right) U S P 2 & A_{\sigma(\Phi)} T_{\sigma} S P \vdash_{F} T_{\sigma} A_{\Phi} S P \\
A_{\Phi}(S P 1 U S P 2) \vdash_{F} S P 1 U\left(A_{\Phi} S P 2\right) & A_{\Phi 1} A_{\Phi 2} S P \vdash_{F} A_{\Phi 2} A_{\Phi 1} S P
\end{array}
\]
3. Pulling sentences (theorems) out of the antecedent:
\(S P 1 U\left(A_{\Phi} S P 2\right) \vdash_{F} A_{\Phi}\left(S P 1 U\left(A_{\Phi} S P 2\right)\right) \quad T_{\sigma} A_{\Phi} S P \vdash_{F} A_{\sigma(\Phi)} T_{\sigma} A_{\Phi} S P\)
\(\left(A_{\Phi} S P 1\right) U S P 2 \vdash_{F} A_{\Phi}\left(\left(A_{\Phi} S P 1\right) U S P 2\right) \quad D_{\sigma} A_{\Phi} S P \vdash_{F} A_{\sigma^{-1}(\Phi)} D_{\sigma} A_{\Phi} S P\)
\(\langle P, \Lambda\rangle A_{\Phi} S P \vdash_{F} A_{\{\varphi\}}\langle P, \Lambda\rangle S P \quad\) provided \((\Phi, \varphi) \in \Lambda\)
4. Permuting \(D\) (equality \(=_{F}\) means logical derivability \(\vdash_{F}\) in both directions):
\[
A_{\Phi} D_{\sigma} S P={ }_{F} D_{\sigma} A_{\sigma(\Phi)} S P
\]
\(S P 1 U D_{\sigma} S P 2={ }_{F} D_{\sigma}\left(T_{\sigma} S P 1 U S P 2\right)\)
\(D_{\sigma} S P 1 U S P 2={ }_{F} D_{\sigma}\left(S P 1 U T_{\sigma} S P 2\right)\)
\(T_{\sigma} D_{\sigma 1} S P={ }_{F} D_{\sigma 1^{\prime}} T_{\sigma^{\prime}} S P\) provided \(\sigma, \sigma 1, \sigma^{\prime}\) and \(\sigma 1^{\prime}\) form
a pushout diagram as in proposition 4.2.1
5. Absorbing laws:
\[
\begin{array}{lll}
T_{\sigma} \epsilon_{\mathfrak{b}}={ }_{F} \epsilon_{\mathfrak{F}} & \epsilon_{\Sigma} U \epsilon_{\Sigma}={ }_{F} \epsilon_{\Sigma} & A_{\emptyset} \epsilon_{\Sigma}={ }_{F} \epsilon_{\Sigma} \\
A_{\Phi 1} A_{\Phi 2} S P={ }_{F} A_{\Phi 1 \cup \Phi 2} S P & D_{\sigma} D_{\sigma} S P={ }_{F} D_{\sigma ; \sigma^{\prime}} S P &
\end{array}
\]
6. Cut rule:
\[
\frac{S P 3 \vdash_{F} S P 2 \quad S P 2 \vdash_{F} S P 1}{S P 3 \vdash_{F} S P 1}
\]

Since all the rules of the system correspond to trivial equivalences or already proven theorems, soundness is immediate.

Fact 7.2.4 \(\vdash_{F}\) is sound w.r.t. specification entailment.

Note that the SBO \(M_{\langle\sigma,\rangle)}\) has been omitted since, without loss of generality, we can consider constraints to be a particular kind of sentences in \(\Phi\).

In the case of an institution ALG with algebras as models, injective morphisms and reachability constraints as a form of sentences, the basic rule becomes
\[
\frac{\langle C 2, \Phi 2\rangle \vdash^{\mathrm{ALG}}\langle C 1, \Phi 1\rangle}{A_{C 2} A_{\Phi 2} S P \vdash_{F} A_{C 1} A_{\Phi 1} \epsilon_{S i g}[S P]}
\]
as in section 6.3.2. If \(E Q\) is considered we can add some rules for the \(F R Q\) constructors corresponding to the sound inference rules presented in sections 3.4 (for equations) and 6.4.1 (for reachability constraints).

By the nature of \(\vdash_{F}\) typical correctness proofs of \(S P 2 \models S P 1\) rely on the systematic application of the rules for pulling axioms out of the consequent and permutation laws for \(D_{\sigma}\) on \(S P 1\) until it is reduced - once simplified by the absorbing laws - to a flat specification of the form \(D_{\sigma} A_{\Phi 1} \epsilon_{\Sigma}\),
\[
D_{\sigma} A_{\Phi 1} \epsilon_{\Sigma} \vdash_{F} \ldots \vdash_{F} S P 1
\]

If \(D_{\sigma}\) is trivial the consequent is just \(A_{\Phi 1} \epsilon_{\Sigma}\). On the side of the antecedent, we can pull out theorems
\[
S P 2_{F} \vdash_{F} \vdash_{F} A_{\Phi 2} S P 2
\]
as required until correctness is immediately proven by, at most, one application of the basic rule. That is, we prove that
\[
A_{\Phi 2} S P 2 \vdash_{F} A_{\Phi_{1} \epsilon_{\Sigma}}
\]
by proving that
\[
\Phi 2 \vdash^{\mathrm{I}} \Phi 1
\]
in the corresponding institution.

This inference system is the simplest we are going to consider and it produces correctness proofs according to a two-step procedure: flattening + theorem proving - from there comes the name, \(F\) for flattening.

Assuming a complete inference system \(\vdash^{\mathbf{1}}\) for the underlying institution, the \(\vdash_{F}\) system, although quite modest, it is complete for \(D A T U \models A T U\).

In the case of institutions where constraints are not considered as sentences, solving entailments in \(D A T U \models A T U\) is not enough. In order to solve entailments in \(A S L \vDash M A T U\), the institution needs to be extended to an institution with constraints and the corresponding inference system needs to be extended appropriately to handle constraints; e.g. \(\vdash^{\text {ALG }}\) extends \(\vdash^{\text {ALG }}\). This results in an inference system \(\vdash_{F}\) which is satisfactory for \(A S L \models M A T U\), already stronger that other strategies using an independent approach as suggested in [Bre 89] and [Far 89].

In order to handle \(D_{\sigma}\) in the consequent, the inference system \(\vdash_{F}\) can be immediately improved by adding the following rule:
\[
\text { [Bias] } \quad \frac{S P 2 \vdash_{F} S P 1}{D_{\sigma} S P 2 \vdash_{F} D_{\sigma} S P 1}
\]

This rule together with the cut rule allows the application of the \(\exists^{2}\)-strategy. We shall call such an enhanced system \(\vdash_{V H}\) and, as shown in chapter 4 , it is complete for \(D A T U \vDash D A T U^{*}\) and satisfactory for \(D A T U \models D A T U\) and for \(A S L \models A S L\) if we use an institution with constraints as discussed above.

Nevertheless, none of these systems makes use of the possible common structure between antecedent and consequent. In the following section \(\vdash_{F}\) is enriched to handle shared subspecifications.

\subsection*{7.3 Shared subspecifications}

Specifications in \(A S L\) can be seen as structured collections of requirements. We can use requirements of two kinds, sentences and constraints, i.e. \(A_{\Phi}\) and \(M_{(\sigma, \gamma)}\), whereas the rest of the operations group these requirements using \(T_{\sigma}\) and \(U\) and sometimes relax them by means of abstraction/hiding \(D_{\sigma}\).

According to this division of requirements, we are already provided with an inference system for sentences \(\vdash^{I}\) and an inference system for constraints, \(H\) in the case of reachability constraints of the form \(\ll G, F, S \gg\), and an inference system for their combination - see chapter 6.

In this section we treat whole subspecifications as single constraints, and in this sense \(U\) is considered as a third operation for introducing requirements. For example we can say that the following specification
\[
M_{\langle\sigma,\rangle} A_{\Phi} \epsilon_{\Sigma} U\left(T_{\imath} S S P\right)
\]
consists of three requirements: the axioms \(\Phi\), the constraint \(\ll \sigma, \iota \gg\) and the subspecification \(S S P\).

Note that considering \(U\) as an operation which structures requirements or an operation which introduces a new requirement is a choice left to the prover and this choice may lead to very different proofs. Moreover, any argument of the \(U\) or both can be treated as single requirements.

Consider for instance an implementation of sets of natural numbers by lists of natural numbers. Sets of natural numbers are specified by:
```

SetNat $=$ Reachable on $\{s e t\}$ using $\{\emptyset$, insert $\}$ from \{nat $\}$
Enrich NatBoolby
sorts set
operations
$\emptyset: \quad$ set
insert: nat, set -> set
$\epsilon$ : nat, set -> bool
axioms
$\forall \mathrm{n}$ :nat. $\mathrm{n} \in \emptyset=$ false
$\forall \mathrm{n}$ :nat; $\mathrm{S}:$ set. $\mathrm{n} \in$ insert $(\mathrm{n}, \mathrm{S})=$ true
$\forall \mathrm{n} 1, \mathrm{n} 2:$ nat; $\mathrm{S}:$ set. $\mathrm{n} 1 \neq \mathrm{n} 2 \Rightarrow$
n1 $\in$ insert ( $\mathrm{n} 2, \mathrm{~S}$ ) $=\mathrm{n} 1 \in \mathrm{~S}$
$\forall \mathrm{n} 1, \mathrm{n} 2:$ nat $; ~ S: s e t$.
insert(n1, insert (n2, $S)=\operatorname{insert}(n 2, \operatorname{insert}(n 1, S))$
$\forall n$ :nat; $S: s e t . \operatorname{insert}(n, i n s e r t(n, S))=i n s e r t(n, S)$
end

```
where NatBool is a specification of standard natural numbers as shown below:
```

NatBool = Reachable on {nat} using {0, suc} from }
Reachable on {bool} using {true, false} from }
sorts nat, bool
operations
0: nat
suc: nat -> nat
_+_: nat, nat -> nat
true, false: bool
_or_: bool, bool -> bool
_>_: nat, nat -> bool
axioms
\forallx:nat. }x+0=
\forallx,y:nat. x+suc (y) = suc( }x+y

```
```

0>0 = false
n:nat. suc(n)>0 = true
\forallx,y:nat. suc(x)>suc(y) = x>y
end

```

Consider now, a implementation of SetNat by lists of natural numbers
```

ListNat = Reachable on {list} using {[],_::-} from {nat}
Enrich NatBoolby
sorts list
operations
[]: list
-::-: nat, list -> list
count: list, nat -> nat
axioms
|}\mathrm{ :nat. count([],n) = 0
|}\mathrm{ :nat; L:list. count(n::L, n) = suc(count(L, n))
|1,n2:nat; L:list. n1\not=n2 =>
count(n1::L, n2) = count(L, n2)
end

```
and a constructor \(k\) such that \(k(\) ListNat \() \models\) SetNat.
An entailment proof may consist of a proof that the axioms over set in SetNat hold in \(k\) (ListNat), that the sort set is constrained in \(k\) (ListNat) and that NatBool is also a subspecification of \(k(\operatorname{ListNat})\). For the first two proofs we use theorem and reachability constraint proving rules respectively whereas for the third some new rules for inferring subspecifications must be developed.

If no inference system for subspecifications is provided the entailment proof could not consider NatBool as a single requirement. Then, the axioms in NatBool and its reachability constraint would be mixed up with those of Set, and only when the whole consequent is reduced to a single set of axioms and constraints could the real proof start, that is, as in the two-step strategy.

If we have an inference system for subspecifications, we can consider NatBool to be a single requirement and prove that it holds in ListNat. But we can also not consider it as a single requirement, or even try to consider \(S e t\) as a single requirement. It is up to the prover to discover which is the good choice.

\subsection*{7.3.1 Inferring subspecifications}

In this section we develop an inference system for specifications analogous to that for sentences and for reachability constraints.

In these systems there are two components, an underlying inference system such as \(\vdash^{I}\) or \(H\), for sentences and reachability constraints respectively, plus a collection of M-complete and sound inference rules for the different SBO's.

With respect to the underlying inference system we choose a trivial one: the identity. In other words, a subspecification can only be inferred from itself. That is why we can only deal, at this stage, with subspecifications shared by the antecedent and the consequent. We can take account of this by changing the basic proof rule in \(\vdash_{F}\) to
\[
\frac{\Phi 2 \vdash^{\mathrm{I}} \Phi 1}{A_{\Phi 2} S P U S S P \vdash_{F} A_{\Phi 1} \epsilon_{S_{i g}[S P]} U S S P}
\]
so that our "reduced" consequent contains some axioms \(\Phi 1\) and a shared specification \(S S P\). If we do not want to change the basic proof rule in \(\vdash_{F}\) we can deal with shared subspecifications by adding the following rule to \(\vdash_{F}\) :
\[
\text { [Shared] } \frac{S P 2 \vdash_{F} S P 1}{S P 2 U S S P \vdash_{F} S P 1 U S S P}
\]

Using this rule we can deal first with shared subspecification and then use \(\vdash_{F}\) to perform an entailment proof as before.

This rule opens the topic of the next section: modular proofs for modular implementations. For the moment, we shall stick to the problem of shared subspecifications.

With respect to M-complete and sound rules for subspecifications, we bypass these concepts and directly give pulling rules analogous to those given in the last section. This simplifies previous considerations showing how sound and Mcomplete rules can be used to pull requirements out of the consequent and the antecedent.

\section*{Pulling subspecifications out of the consequent}

We expect to reduce the consequent to a collection of requirements by pulling all of them out to the top level. Therefore we are after axioms of the following form:
\[
\xi S P U S S P \vdash \xi\left(S P \quad U S S P^{\prime}\right)
\]
for specifications \(S P, S S P\) and \(S S P^{\prime}\), and SBO \(\xi\).
Proving a pulling-subspecification axiom for each SBO can be shortened by giving the following technical lemma. Recall from chapter 2 the definition of invariance (see page 32) and that \(\{-\}\) is an SBO such that for all \(\Sigma\)-models \(A\) the specification \(\{A\}\) has signature \(\Sigma\) and models \(\{A\}\).

Lemma 7.3.1 If \(\xi\) is invariant w.r.t. \(S P\) and \(\langle\iota, \sigma\rangle\), then
\[
\xi S P \quad U T_{\sigma} S S P \models \xi\left(S P \quad U \quad T_{\imath} S S P\right)
\]
provided \(\xi\) distributes over the union of model classes.
Proof Let \(B\) be a model of \(\xi S P \quad U T_{\sigma} S S P\). Since \(B \in \operatorname{Mod}[\xi S P]\), by distributivity of \(\xi\) w.r.t. the union of model classes, there exists a model \(A \in \operatorname{Mod}[S P]\) such
 that \(B \in \operatorname{Mod}[\xi\{A\}]\) and, by invariance of \(\xi,\left.A\right|_{\iota}=\left.B\right|_{\sigma}\).

Since \(B\) is also a model of \(T_{\sigma} S S P,\left.B\right|_{\sigma} \in \operatorname{Mod}[S S P]\). Therefore, by definition of \(T, A\) must be a model of \(T_{\iota} S S P\) as well. In conclusion, \(A \in \operatorname{Mod}\left[S P \quad U \quad T_{\imath} S S P\right]\) and \(B \in \operatorname{Mod}\left[\xi\left(S P \quad U \quad T_{\imath} S S P\right)\right]\).

Now the actual rules are given and proven correct using the lemma.

Theorem 7.3.2 The following axioms are sound w.r.t. specification entailment:
\[
\begin{gathered}
A_{\Phi} S P U S S P \vdash A_{\Phi}(S P U S S P) \\
M_{(\sigma, \iota)} S P U S S P \vdash M_{(\sigma, \iota)}(S P U S S P) \\
(S P 1 U S P 2) U S S P \vdash S P 1 U(S P 2 U S S P) \\
(S P 1 U S P 2) U S S P \vdash(S P 1 U S S P) U S P 2 \\
T_{\sigma} S P U T_{\sigma} S S P \vdash T_{\sigma}(S P U S S P) \\
D_{\iota} S P U S S P \vdash D_{\iota}\left(S P U T_{\iota} S S P\right)
\end{gathered}
\]
for all specifications \(S P, S P 1, S P 2\) and \(S S P\).

Proof All selectors \(L\) are invariant w.r.t. any specification \(S P\) and \(\left\langle i d_{S i g[S P]}, i \dot{d}_{S i g[S P]}\right\rangle\), since by definition,
\[
\operatorname{Mod}[L S P] \subseteq \operatorname{Mod}[S P]
\]
for all specifications \(S P\). In other words, \(L\{A\}\) can only be \(\{A\}\) or empty. Hence, the first four axioms referring to selectors \(A_{\Phi}, M_{\{\sigma, \iota\rangle}\) and \(U\) are sound.
\(T_{\sigma}\) is invariant w.r.t. any specification \(S P\) and \(\left\langle i d_{S i g[S P]}, \sigma\right\rangle\) since by definition for any model \(A \in \operatorname{Mod}[S P]\) all models \(B \in \operatorname{Mod}\left[T_{\sigma}\{A\}\right]\) have reduct \(\left.B\right|_{\sigma}=A\).

In the last case, \(D_{\iota}\) is invariant w.r.t. a specification \(S P\) and \(\left\langle\iota, i d_{S i g[S P]}\right\rangle\) since for any model \(A \in \operatorname{Mod}[S P]\) and all \(B \in \operatorname{Mod}\left[D_{\iota}\{A\}\right]\) it holds that \(B=\left.A\right|_{\iota}\).

Finally, we recall from their definitions that all SBO's in \(A S L\) distribute over the union of model classes (see proposition 2.2.5).

\section*{Pulling subspecifications out of the antecedent}

We expect to prove that a subspecification \(S S P\) of the consequent holds in the antecedent by inheriting \(S S P\) to the top of the antecedent, i.e. we are after rules of the following form:
\[
\xi\left(S P \quad U S S P^{\prime}\right) \vdash \xi\left(S P \quad U S S P^{\prime}\right) U S S P
\]

Similarly to the previous case, pulling subspecifications out of the antecedent is immediate for invariant SBO's.

Lemma 7.3.3 If \(\xi\) is invariant w.r.t. \(T_{\iota} S S P\) and \(\langle\iota, \sigma\rangle\), then
\[
\xi\left(S P \quad U T_{\imath} S S P\right) \vDash \xi\left(S P \quad U T_{\imath} S S P\right) U T_{\sigma} S S P
\]
provided \(\xi\) distributes over the union of model classes.

Proof Let \(B\) be a model of \(\xi T_{\imath} S S P\). By distributivity of \(\xi\) over the union of model classes, there exists \(A \in \operatorname{Mod}\left[T_{\iota} S S P\right]\) such that \(B \in \operatorname{Mod}[\xi\{A\}]\) and, by invariance of \(\xi,\left.B\right|_{\sigma}=\left.A\right|_{\iota}\). Since \(\left.A\right|_{\iota} \in \operatorname{Mod}[S S P], B \in \operatorname{Mod}\left[T_{\sigma} S S P\right]\) and so, in general,
\[
\xi T_{\iota} S S P \models T_{\sigma} S S P
\]

By monotonicity of \(\xi\), it follows that \(\xi\left(S P \quad U T_{\iota} S S P\right) \vDash T_{\sigma} S S P\) and therefore
\[
\xi\left(S P \quad U T_{\iota} S S P\right) \vDash \xi\left(S P U T_{\imath} S S P\right) \cup T_{\sigma} S S P
\]

As a consequence of this lemma, pulling subspecification rules for \(A_{\Phi}, M_{\langle\sigma, \gamma}, U, T_{\sigma}\) and \(D_{\sigma}\) in the antecedent are sound since these SBO's are invariant and distribute over the union of model classes - see proof of theorem 7.3.2.

Corollary 7.3.4 The following axioms are sound w.r.t. specification entailment:
\[
\begin{gathered}
A_{\Phi}(S P \quad U S S P) \vdash A_{\Phi}(S P \quad U S S P) U S S P \\
M_{(\sigma, \iota\rangle}(S P \quad U S S P) \vdash M_{\langle\sigma, \iota\rangle}(S P U S S P) U S S P \\
S P 1 U(S P 2 U S S P) \vdash(S P 1 U(S P 2 U S S P)) U S S P \\
(S P 1 U S S P) U S P 2 \vdash((S P 1 U S S P) U S P 2) U S S P) \\
T_{\sigma}(S P U S S P) \vdash T_{\sigma}(S P U S S P) U T_{\sigma} S S P \\
D_{\iota}\left(S P U T_{\imath} S S P\right) \vdash D_{\iota}\left(S P U T_{\iota} S S P\right) U S S P
\end{gathered}
\]
for all specifications \(S P, S P 1, S P 2\) and \(S S P\).

There are other pulling subspecification rules for the antecedent corresponding to the constructors. In the following, we consider \(F R Q\)-constructors in EQ. Later, some comments are added for the case of generic constructors.

Proposition 7.3.5 Given a signature morphism \(\iota:\langle S, \Omega\rangle \rightarrow\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\),
\[
R_{\{s\}}\left(S P \quad U T_{\imath} S S P\right) \vdash R_{\{s\}}\left(S P U T_{\imath} S S P\right) \cup T_{\iota} S S P
\]
is sound w.r.t. specification entailment, provided \(s \in\left(\Omega^{\prime} \backslash \iota(\Omega)\right)\) or \(\operatorname{Mod}[S S P]\) is closed under subalgebras.

Proof As in the previous lemma, it is enough to prove that \(R_{\{s\}} T_{\imath} S S P \models T_{\iota} S S P\).
In the case where \(s \in \Omega^{\prime} \backslash \iota(\Omega)\), since \(R_{\{s\}}\) only changes the carrier of \(s\), we have that for all \(S P, D_{\iota} R_{\{s\}} S P=D_{\iota} S P\). In the particular case of \(S P\) being \(T_{\imath} S S P\) we obtain
\[
D_{\iota} R_{\{s\}} T_{\iota} S S P=D_{\imath} T_{\imath} S S P
\]
and applying \(T_{\imath}\) to both sides and simplifying, we conclude that
\[
R_{\{s\}} T_{\imath} S S P \models T_{\imath} D_{\imath} R_{\{s\}} T_{\iota} S S P=T_{\imath} D_{\iota} T_{\iota} S S P=T_{\imath} S S P
\]

In the case where \(\operatorname{Mod}[S S P]\) is closed under subalgebras, we recall that for every algebra \(A \in \operatorname{Mod}\left[T_{\imath} S S P\right]\), the application of \(R_{\{s\}}\) delivers a subalgebra \(\operatorname{Reach}_{\{s\}}(A)\) of \(A\). Since reduct functors preserve subalgebras, Reach \(\left._{\{s\}}(A)\right|_{c}\) is a subalgebra of \(\left.A\right|_{\iota}\). Since \(\left.A\right|_{\iota} \in \operatorname{Mod}[S S P]\) and \(\operatorname{Mod}[S S P]\) is closed under subalgebras, it holds that \(\left.\operatorname{Reach}_{\{s\}}(A)\right|_{\iota} \in \operatorname{Mod}[S S P]\). Hence, \(\operatorname{Reach}_{\{s\}}(A) \in \operatorname{Mod}\left[T_{\iota} S S P\right]\) and, in general, we conclude that
\[
R_{\{0\}} T_{\iota} S S P \vDash T_{\iota} S S P
\]

Define a signature morphism \(\sigma\) as forgetting a set of equations eq iff \(D_{\sigma} Q_{e q} S P=D_{\sigma} S P\) for all specifications \(S P^{1,2}\).

\section*{Proposition 7.3.6}
\[
Q_{e q}\left(S P \quad U \quad T_{\imath} S S P\right) \vdash Q_{e q}\left(S P \quad U T_{\imath} S S P\right) \cup T_{\imath} S S P
\]
is sound w.r.t. specification entailment, provided \(\iota\) forgets eq or \(\operatorname{Mod}[S S P]\) is closed under quotients.

Proof By definition, if \(\iota\) forgets \(e q, D_{\iota}\left(Q_{e q} T_{\imath} S S P\right)=D_{\iota} T_{\iota} S S P\). Applying \(T_{\iota}\) to both sides and simplifying,
\[
Q_{e q} T_{\imath} S S P \models T_{\iota} D_{\iota} Q_{e q} T_{\imath} S S P=T_{\imath} D_{\imath} T_{\imath} S S P=T_{\imath} S S P
\]

\footnotetext{
\({ }^{1}\) An alternative definition can be given in terms of the congruence \(\sim_{e q}\) induced by the set of equations eq: \(\sigma\) forgets eq iff every sort with a pair of different elements \((e 1, e 2) \in \sim_{e q}\) is not the image of any sort in \(\downharpoonright \sigma\).
\({ }^{2}\) In order to prove this property we can check that all the sorts mentioned in the equations eq are forgotten in \(\sigma\) plus those sorts which although not directly mentioned depend on the ones mentioned (see [KM 87] for a definition of dependency).
}
hence the entailment is correct as in the proof of lemma 7.3.3.
In the case where \(\operatorname{Mod}[S S P]\) is closed under quotients we can prove the same result. For all algebras \(A \in \operatorname{Mod}\left[T_{\imath} S S P\right]\), there is a homomorphism \(k: A \rightarrow\) \(\left(A / \sim_{e q}\right)\). Applying the reduct functor \(-\left.\right|_{c}\), we obtain \(\left.k\right|_{c}:\left.\left.A\right|_{\iota} \rightarrow\left(A / \sim_{e q}\right)\right|_{c}\) and \(\left.\left(A / \sim_{e q}\right)\right|_{c}\) is the quotient of \(\left.A\right|_{c}\) w.r.t. the kernel of \(\left.k\right|_{c},\left(\left.A\right|_{\iota}\right) / \operatorname{Ker}\left(\left.k\right|_{\iota}\right)\).


Finally, since \(\left.A\right|_{\imath} \in \operatorname{Mod}[S S P]\) its quotient will also be in \(\operatorname{Mod}[S S P],\left.A\right|_{\imath} / \operatorname{Ker}\left(\left.k\right|_{\imath}\right) \in\) \(\operatorname{Mod}[S S P]\), hence \(\left.\left(A / \sim_{e q}\right)\right|_{\iota} \in \operatorname{Mod}[S S P]\) and in general
\[
D_{\iota}\left(Q_{e q} T_{\iota} S S P\right) \models S S P
\]

Applying \(T_{\imath}\) to both sides and simplifying we again obtain that \(Q_{e q} T_{\iota} S S P \models\) \(T_{\iota} S S P\).

\section*{Proposition 7.3.7}
\[
F_{\sigma}^{e q}(S P U S S P) \vdash F_{\sigma}^{e q}(S P U S S P) \cup T_{\sigma} S S P
\]
is sound w.r.t. specification entailment, provided \(\left.\left(\right.\) Free \(\left._{\sigma}^{e q} A\right)\right|_{\sigma}=A\) for all \(A \in\) \(\operatorname{Mod}[S S P]^{3}\).

Proof Since all constructors distribute over the union of model classes, it is enough to show that \(F_{\sigma}^{e q}\) is invariant w.r.t. \(S S P\) and \(\left\langle i d_{S i g[S S P]}, \sigma\right\rangle\) under the condition given.

\footnotetext{
\({ }^{3}\) In this case sufficient completeness and consistency of \(F_{\sigma}^{\text {eq }} S S P\) is not enough. This new requirement is usually called strong persistency, see [EM 85].
}

For every algebra \(A \in \operatorname{Mod}[S S P], F_{\sigma}^{e q}\{A\}\) has a unique model \(F r e e_{\sigma}^{e q} A\) such that
\[
\left.\left(\text { Free }_{\sigma}^{e q} A\right)\right|_{\sigma}=A
\]

Hence, \(F_{\sigma}^{e q}\) is invariant w.r.t. \(S S P\) and \(\left\langle i d_{S i g[S S P]}, \sigma\right\rangle\).

The implementation of sets of natural numbers by lists of natural numbers \(k\) (ListNat \() \models\) SetNat as described at the beginning of the section can be proven correct using the above rules.

Let us consider the whole subspecification \(N a t B o o l\) to be a single requirement. Then, it must be proven that NatBool can be pulled out of SetNat using the rules for consequents, and out of \(k(\operatorname{ListNat})\) using the rules for antecedents.

In first place we shall rewrite specifications SetNat and ListNat in a more concise form with NatBool as a distinguished subspecification, i.e.
\[
\begin{aligned}
& \text { SetNat }=M_{C s e t} A_{A x S e t} T_{\iota_{s}}\left(\epsilon_{\Sigma} U \text { NatBool }\right) \\
& \text { ListNat }=M_{C l i s t} A_{A x L i s t} T_{\iota_{l}}\left(\epsilon_{\Sigma} U \text { NatBool }\right)
\end{aligned}
\]
where \(M_{C_{s e t}}\) stands for the reachability constraint on set and \(A_{A x S_{e t}} T_{\iota_{s}}\) stands for the enrichment adding sets, \(M_{\text {Clist }}\) stands for the reachability constraint on list, \(A_{A x L i s t} T_{\iota_{4}}\) stands for the enrichment adding lists and \(\Sigma\) is the signature of NatBool.

Since SetNat only contains \(T_{\sigma}\) and selectors, and all these have pulling subspecifications rules for the consequent, we can easily apply the rules in theorem 7.3.2 and conclude that,
\[
\begin{aligned}
\left(M_{C_{s e t}} A_{A x S e t} T_{\iota s} \epsilon_{\Sigma}\right) U\left(T_{\iota s} \text { NatBool }\right) & \vdash M_{C s e t}\left(\left(A_{A x S e t} T_{\iota_{s}} \epsilon_{\Sigma}\right) U\left(T_{\iota_{s}} \text { NatBool }\right)\right) \\
& \vdash M_{C_{s e t}} A_{A x S e t}\left(\left(T_{\iota_{s}} \epsilon_{\Sigma}\right) U\left(T_{\iota_{s}} \text { NatBool }\right)\right) \\
& \vdash M_{C_{s e t}} A_{A x S e t} T_{\iota s}\left(\epsilon_{\Sigma} U \text { NatBool }\right)=\text { SetNat }
\end{aligned}
\]

Similarly in the antecedent we can apply the rules in corollary 7.3.4 and conclude that
```

$k($ ListNat $)=k M_{C l i s t} A_{A x L i s t} T_{\iota_{l}}\left(\epsilon_{\Sigma} U\right.$ NatBool $)$
$\vdash k M_{\text {Clist }} A_{\text {AxList }}\left(\left(T_{\iota_{1}}\left(\epsilon_{\Sigma} U\right.\right.\right.$ NatBool $\left.)\right) U\left(T_{\iota_{1}}\right.$ NatBool $\left.)\right)$
$\vdash k M_{\text {Clist }}\left(\left(A_{A x L i s t}\left(\left(T_{\iota_{1}}\left(\epsilon_{\Sigma} U\right.\right.\right.\right.\right.$ NatBool $\left.)\right) U\left(T_{\iota_{1}}\right.$ NatBool $\left.\left.)\right)\right) U\left(T_{\iota!}\right.$ NatBool $\left.)\right)$
$\vdash k\left(\left(M_{C l i s t}\left(\left(A_{A x L i s t}\left(\left(T_{\iota_{l}}\left(\epsilon_{\Sigma} U\right.\right.\right.\right.\right.\right.\right.$ NatBool $\left.)\right) U\left(T_{\iota_{1}}\right.$ NatBool $\left.\left.)\right)\right) U\left(T_{\iota_{1}}\right.$ NatBool $\left.\left.)\right)\right) U\left(T_{\iota 1}\right.$ NatBool $\left.)\right)$

```

Imagine the constructor is composed of the following SBO's:
1. A free extension \(F_{\sigma 2}^{e q 2}\) defining the membership operation \(\in\) for lists, e.g. \(\sigma 2\) is a inclusion morphism which adds the membership operation \(\epsilon\), and
\[
e q 2=_{d e f}\{\forall \mathrm{n}: \text { nat, } \mathrm{L}: \text { list. } \operatorname{count}(\mathrm{L}, \mathrm{n})>0=\mathrm{n} \in \mathrm{~L}\}
\]
defines \(\in\) on lists.
2. A derive \(D_{\sigma 1}\) forgetting count and renaming list to set, [] to \(\emptyset\) and _ : : to insert.
3. A quotient \(Q_{e q 1}\) identifying those lists which have different numbers of occurrences of the same elements or different ordering, e.g.
```

eq1 = def { \forall n:nat; S:set. insert(n, insert(n, S)) = insert(n, S),
\foralln1,n2:nat; S:set.
insert(n1, insert(n2, S))=insert(n2, insert(n1, S))}

```

Summing up, the constructor is defined as
\[
k={ }_{d e f} Q_{e q 1} D_{\sigma 1} F_{\sigma 2}^{e q 2}
\]

The subspecification NatBool can be pulled along this constructor using the rules presented above as follows:
1. Since Free \(e_{\sigma 2}^{e q} 2\) is strongly persistent we can pull the subspecification and obtain
\[
Q_{e q 1} D_{\sigma 1}\left(\left(F_{\sigma 2}^{e q 2}\left(\left(M_{C l i s t} \ldots\right)\right)\right) U\left(T_{\iota ; \sigma 2} \text { NatBool }\right)\right)
\]
2. Morphism \(\sigma 1\) adds count and renames other symbols in the signature \(\uparrow \iota_{s}\) so that we can write \(\iota_{i} ; \sigma 2\) as \(\iota_{s} ; \sigma 1\), therefore the rule for \(D_{\sigma 1}\) in corollary 7.3.4 can pull the subspecification \(T_{\sigma 1} T_{\iota_{s}}\) NatBool and obtain
\[
Q_{e q 1}\left(\left(D_{\sigma 1}\left(\left(F_{\sigma 2}^{e q 2} \ldots\right)\right)\right) U\left(T_{\iota s} \text { NatBool }\right)\right)
\]
3. Finally, equations eq1 do not affect nat, i.e. \(\iota_{s}\) forgets \(e q 1\), hence
\[
\left(Q_{e q 1}\left(D_{\sigma 1} \ldots\right)\right) U\left(T_{\iota s} \text { NatBool }\right)
\]

At this point the [Shared] rule can be applied to match the subspecifications \(T_{\iota_{s}}\) NatBool of the consequent and the antecedent, reducing the entailment to
\[
Q_{e q 1}\left(\left(D_{\sigma 1}\left(\left(F_{\sigma 2}^{e q} \ldots\right)\right)\right) U\left(T_{\iota s} \text { NatBool }\right)\right) \models M_{C s e t} A_{A x S e t} T_{\iota s} \epsilon_{\Sigma}
\]
which can be proven if \(\vdash_{F}\) is extended with the rules corresponding to the sound inference rules for \(F R Q\) given in sections 3.4 and 6.4.1, as discussed above.

Note that rules pulling sentences and subspecification out of the antecedent enlarge the antecedent specifications, most of the time unnecessarily. This behaviour can be thought like that of a theorem prover which adds all inferred theorems from a presentation as axioms to the original presentation. In all the cases which have been considered, the rules for pulling sentences and subspecifications can be turned into equalities (bi-directional rules) in order to solve that problem.

Analogously to the inference rules for constructors in chapter 3 , pulling subspecifications along constructors is difficult. Most of the axioms given above have
strong side conditions restricting their use to the simplest cases and some of the side conditions are model-theoretical. Sufficient syntactic conditions can be given in most of the cases, but like theorem proving for \(F Q R\)-constructors in chapter 3, the model-theoretical nature of the \(F Q R\)-constructors prevents better results.

Generic constructors \(\langle P, \Lambda\rangle\) are useless for anything except theorem proving or, at most, mixed theorem proving depending on the nature of \(\Lambda\). If we would like to treat subspecifications as single constraints, generic constructors must be enriched with some information about the symbols which are modified and those which are not. This can be achieved by changing the notation for constructors to record explicitly over which subspecifications they are invariant.

Definition 7.3.8 A well-formed S-constructor is a triple \(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\), where \(\langle P, \Lambda\rangle\) is a generic constructor with
\[
\llbracket P \rrbracket=\left(\uparrow \iota, \uparrow \sigma, f_{P}\right)
\]
for some function \(f_{P}:|\operatorname{Mod}(\uparrow \iota)| \rightarrow|\operatorname{Mod}(\uparrow \sigma)|\), and for every specification \(S P\) over \(\uparrow \iota\) the \(\langle P, \Lambda\rangle\) is invariant w.r.t. \(S P\) and \(\langle\iota, \sigma\rangle\).

Trivially generic constructors are a particular case of S-constructors where \(\downarrow \iota=\downarrow \sigma\) is the empty signature.

Since constructors distribute over the union of model classes, we can use lemma 7.3 .3 to conclude that all subspecifications \(S S P\) over \(\downarrow \sigma=\downarrow \iota\) can be pulled out through \(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\), i.e.
\[
\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\left(S P U T_{\iota} S S P\right) \vdash\left(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\left(S P U T_{\iota} S S P\right)\right) \cup T_{\sigma} S S P
\]

Adding the rules for pulling subspecifications and the [Shared] rule to \(\vdash_{F}\) we obtain \(\vdash_{A S}\), that is, an inference system combining a basic rule for axioms (the basic rule in \(\vdash_{F}\) ) and a basic rule for subspecifications (the [Shared] rule).

Taking into consideration that sentences in \(A_{\Phi}\) can also be constraints, we have, in practice, a two step inference system flattening + requirement proving with three kinds of requirements: ordinary sentences, constraints and subspecifications.

Formal systems which include a treatment of subspecifications are a great deal better that previous ones; however, there is not a clear characterization of them unless we restrict attention to modular entailments, as discussed below.

\subsection*{7.4 Modular entailments}

In the introduction to this chapter we stressed that proofs of \(S P 2 \vDash S P 1\) should be able to take advantage of the similarities between the antecedent and the consequent, in particular, their structural similarities.

The work on shared subspecifications should be complemented with a structurematching mechanism, so that we do not need to pull out subspecifications in cases where antecedent and consequent specifications differ only in a small bit, deep in the structure. The obvious solution is a simplification rule
[Simpl]
\[
\frac{S P 2 \vdash S P 1}{\xi S P 2 \vdash \xi S P 1}
\]
whose soundness follows from the monotonicity of all SBO's (see proposition 2.2.4).
Although [Simpl] seems rather simple, it is an extremely powerful rule. For instance, adding [Simpl] to \(\vdash_{F}\) permits to derive rules such as [Bias] (page 248) and [Shared] (page 252). In fact. the combination of \(\vdash_{F}\) with \([\) Simpl] plus the rules for pulling subspecification form \(\vdash_{M}\), the most powerful inference system we are going to consider.

In order to characterize \(\vdash_{M}\), we restrict to the study of modular entailments, that is, those specification entailments where the antecedent respects the structure of the consequent. For example, let ListNat and NatBool be specifications
like those considered above, and SetNat', ListNat' and NatBool' be specifications analogous to SetNat, ListNat and NatBool but without any reachability constraint on nat, then \(k(\operatorname{ListNat}) \models\) SetNat' can be proven correct by proving, roughly, that
\[
\begin{gathered}
\text { NatBool } \models \text { NatBool }^{\prime} \\
k\left(\text { ListNat }^{\prime}\right) \models \operatorname{SetNat}^{\prime}
\end{gathered}
\]
since applying the simplification rule to the first entailment and combining the two entailments (cut rule) we obtain:
\[
\frac{N a t B o o l \vdash_{M} N a t B o o l}{}{ }^{\prime} \quad k\left(\text { ListNat }^{\prime}\right) \vdash_{M} \text { SetNat }^{\prime}
\]
\[
k(\text { ListNat }) \vdash_{M} \text { SetNat }^{\prime}
\]

Then, the entailment NatBool \(\vDash N a t\) Bool \(^{\prime}\) is proven using \(\vdash_{F}\) and \(k(\) ListNat \() \vDash\) Set \(N a t^{\prime}\) is proven using the rules for pulling subspecifications and sentences in \(\vdash_{M}\).

In the case of parameterized specifications in [SW 83, ST 88b], a modular entailment \(P 2(S P 2) \models P 1(S P 1)\) can be proven correct by proving that
\[
P 2 \models P 1 \quad S P 2 \models S P 1
\]
where \(P 2 \vDash P 1\) means that \(P 2(S P) \vDash P 1(S P)\) for any specification \(S P\) of the right signature.

There is a clear analogy between the proofs of \(P 2(S P 2) \vDash P 1(S P 1)\) and of \(k(\) ListNat \() \models S e t N a t^{\prime}\). Taking specifications \(S P 2\) and \(S P 1\) to be the subspecifications NatBool and NatBool', and \(P 2\) and \(P 1\) to be
\[
\begin{gathered}
P 2=\lambda X: \Sigma . k M_{\text {Clist }} A_{A x L i s t} T_{\iota_{l}}\left(\epsilon_{\Sigma} U X\right) \\
P 1=\lambda X: \Sigma . M_{C s e t} A_{A x S e t} T_{t_{s}}\left(\epsilon_{\Sigma} U X\right)
\end{gathered}
\]
our proof in \(\vdash_{M}\) becomes
\[
P 2(S P 2) \vdash_{M} P 1(S P 2) \quad S P 2 \vdash_{M} S P 1
\]

Although \(P 2 \vDash P 1\) is a stronger requirement than \(P 2(S P 2) \vDash P 1(S P 2)\), often the derivation \(P 2(S P 2) \vdash_{M} P 1(S P 2)\) treats \(S P 2\) as a shared subspecification and uses rules for pulling subspecifications which do not rely on the models of \(S P 2\). In this case, the same proof schema can be used for any \(\Sigma\)-specification \(S P\) taking the place of \(S P 2\); in other words, we have a proof of \(P 2 \vDash P 1\).

In some specification languages requiring parameterized specifications to denote persistent free extensions \(F_{\sigma}^{e q}\) (e.g. [EM 85]), parameterized specifications are always invariant w.r.t. any specification of the right signature and \({ }^{\prime}\left\langle i d_{\mathfrak{l}}, \sigma\right\rangle\). Therefore, the part of the proof handling shared parameters (subspecifications) is trivial. Other languages with a more general parameterization mechanism, such as \(\lambda\)-abstraction in \(\lambda+A S L\), cannot use these shortcuts in general and rules for pulling subspecifications are needed.

In this section we are mainly concerned with the use of the simplification rule and the cases where its application is safe, i.e. its application in goal-oriented (backwards) proofs cannot take us from a correct entailment to an entailment which cannot be proven correct. In this sense, we shall see how modular implementations lead to modular proofs of correctness.

\subsection*{7.4.1 Specifications as arrows}

A clean notation for dealing with structure is to consider the category of signatures and their products as objects, and ASL specifications, either ground or parameterized, as arrows, analogously to the concrete free theories used by Lawvere (see section 2.3).

For practical reasons we shall not consider arrows to be single specifications but sets of equivalent specifications, i.e. specifications with the same signature
and class of models and, in the parameterized case, parameterized specifications with the same signature pair and function between classes of models.

Fact 7.4.1 Given an institution with category of signatures SIG (closed under finite products) and model functor Mod then an ordered category Spec(SIG) is defined as follows:
- Objects: Objects in SIG.
- Morphisms: Triples \(\langle\Sigma 1, F, \Sigma 2\rangle: \Sigma 1 \rightarrow \Sigma 2\) where \(\Sigma 1\) and \(\Sigma 2\) are signatures in SIG and \(F\) is a function from model classes over \(\Sigma 1\) to model classes over \(\Sigma 2\), i.e. \(F: \mathcal{P}(|\operatorname{Mod}(\Sigma 1)|) \rightarrow \mathcal{P}(|\operatorname{Mod}(\Sigma 2)|)\).
- Composition is as expected: \(\langle\Sigma 1, F 1, \Sigma 2\rangle ;\langle\Sigma 2, F 2, \Sigma 3\rangle=\langle\Sigma 1, F 1 ; F 2, \Sigma 3\rangle\).
- Homsets are ordered as follows: \(\langle\Sigma 11, F 1, \Sigma 12\rangle \leq\langle\Sigma 21, F 2, \Sigma 22\rangle\) iff \(\Sigma 11=\) \(\Sigma 21, \Sigma 12=\Sigma 22\) and \(\forall M \subseteq|\operatorname{Mod}(\Sigma 11)| . F 1(M) \subseteq F 2(M)\).

Ordered categories can generally be viewed as 2 -categories. Then, composition as it has been defined above is called horizontal composition and the ordering induces another kind of composition known as vertical composition (following the terminology in [GB 80]).

Moreover, order preservation by composition in \(\operatorname{Spec}(S I G)\) is equivalent to the compatibility of horizontal and vertical composition for refinement, discussed in general in [GB 80] and proved for refinement relations in [ST 88b].

Note that all SBO's such as \(T_{\sigma}, A_{\Phi},(\lambda X: \Sigma . S P 1)\) and \(\langle P, \Lambda\rangle\) correspond to arrows in \(\operatorname{Spec}(S I G)\). In particular, specifications \(S P\) in \(\lambda+k+A S L\) correspond to arrows from the empty signature to \(\operatorname{Sig}[S P]\). For example, the specification NatBool with \(\Sigma=\operatorname{Sig}[\) NatBool corresponds to an arrow
\[
\Sigma \stackrel{\text { NatBool }}{\emptyset}
\]
and ListNat \(=P L\) List \((N a t B o o l)\) with PList \(=\lambda X: \Sigma . M_{\text {Clist }}\left(\left(A_{A x L i s t} T_{\iota_{\jmath}} \epsilon_{\Sigma}\right) U\left(T_{\iota_{1}} X\right)\right)\) can be represented by a compound arrow
\[
\operatorname{Sig}[\text { ListNat }] \stackrel{\text { PList }}{\leftarrow} \Sigma \text { NatBool } \emptyset
\]
or, if the finer structure is considered, we obtain


Note that the existence of finite products of signatures is needed to represent SBO's or parameterized specifications with several parameters, e.g. _ \(U_{-}\).

Following [ST 88b], refinements can be replaced by constructor implementations in order to capture the fact that some constructor (piece of code) can reduce our original specification (task) to a simpler one. The composition of constructor implementations and its compatibility with horizontal composition is rephrased as follows according to our new terminology.

Given a generic constructor \(\langle P, \Lambda\rangle\) with \(\llbracket P \rrbracket=\left(\Sigma 1, \Sigma 2, f_{P}\right)\), there is a morphism \(\langle\Sigma 1, F, \Sigma 2\rangle\) in \(\operatorname{Spec}(S I G)\) associated to that constructor where \(F\) is defined as \(F(M)=\left\{f_{P}(A) \mid A \in M\right\}\) for all \(M \subseteq|\operatorname{Mod}(\Sigma 1)|\). Morphisms in \(\operatorname{Spec}(\operatorname{SIG})\) whose function \(F\) is defined by lifting a function between single models form a subcategory Func \((S I G)\) of \(\operatorname{Spec}(S I G)\), i.e. such morphisms include the identities in \(\operatorname{Spec}(S I G)\) and are closed under composition.

Generic constructors are defined by programs \(P\) in a language \(L\), therefore \(F\) should be a recursive function and \(P\) a procedure to compute it. Nevertheless, we shall proceed ignoring this aspect of the nature of constructors. Constructors can
be either \(F Q R D\)-constructors, generic constructors, S-constructors or anything else with semantics in terms of functions between models but, for the time being, they are just treated as morphisms in a subcategory of \(\operatorname{Spec}(S I G)\).

Definition 7.4.2 A specification SP1 is implemented by an specification SP2 via a constructor \(k\) iff the following diagram commutes in \(\operatorname{Spec}(S I G)\).


Note: In a ordered category, such a diagram commutes if \(S P 2 ; k \leq S P 1\), i.e. if \(k(S P 2) \vDash S P 1\).

Since constructors are closed under composition, constructor implementations compose as expected. For instance in a situation such as the following diagram, it holds that \(S P 3 ; k 2 ; k 1 \leq S P 1\).


Compatibility of horizontal and vertical composition also follows immediately from the composability of constructors and the fact of working in an ordered category. For instance in a situation such as the following diagram, it holds that \(S P 2 ; k 2 ; P 2 ; k 1 \leq S P 1 ; P 1\).


\subsection*{7.4.2 Modular programming}

Modular programming amounts to the independent implementation of the different pieces of the specification. This simple idea is the clue for simplifying the verification and providing reusable implementations.

Some approaches distinguish between structured and modular specifications, where only the second kind of structure needs to be respected in the implementation (e.g. ACT ONE). Others prefer to see modular decomposition as an implementation decision which therefore is not reflected in the specification language (e.g. CLEAR and ASL). Many specification languages, despite using just one structuring mechanism, provide key words such as protected or use which allow modular implementation (programming) to be required by the specifier.

For us, all these differences are just different diagrams relating the antecedent to the consequent of a specification entailment. Imagine a consequent Set (Elem) specifying sets of elements

where the source signature of Elem is the empty signature or, more generally, the signature of the basic data types of our favorite programming language.

Consider an entailment \(k 1(\operatorname{Set} 2(k 2(N a t))) \vDash \operatorname{Set}(\) Elem \()\) such that the following diagram commutes (i.e. Set \(2 ; k 1 \leq\) Set and Nat; \(k 2 \leq\) Elem):


In this case, we say that the entailment is modular since \(k 2(N a t) \vDash E l e m\) and \(k 1(S e t 2(S P)) \vDash \operatorname{Set}(S P)\) for all specification \(S P\) of the right signature.

Other antecedents relying on the fact that the elements are natural numbers, or simply that they are ordered, give rise to the following diagrams:

where Nat; NSet; \(k^{\prime \prime} \leq\) Elem; Set and Cpo; OSet; \(k^{\prime} \leq\) Elem; Set and therefore
\[
k^{\prime \prime}(N S e t(N a t)) \models \operatorname{Set}(\text { Elem }) \quad k^{\prime}(\operatorname{OSet}(\operatorname{Cpo})) \models \operatorname{Set}(\text { Elem })
\]

However, OSet is only a correct implementation of Set provided there is an order relation among the elements, and NSet is only a correct implementation of Set if the elements are natural numbers. Then, we say that these entailments are not modular.

Definition 7.4.3 An entailment \(P 2(S P 2) \vDash P 1(S P 1)\) is modular iff \(P 2 \leq P 1\) and \(S P 2 \leq S P 1\).

In the example above, \(k 1(\operatorname{Set} 2(k 2(N a t))) \models \operatorname{Set}(\) Elem \()\) is modular whereas
\[
k^{\prime}(O S e t(C p o)) \models \operatorname{Set}(E l e m) \text { and } k^{\prime \prime}(N S e t(N a t)) \models \operatorname{Set}(\text { Elem })
\]
are not modular.

In terms of entailment between parameterized specifications, as in [ST 88b], we can say that \(k 1(\operatorname{Set} 2) \models\) Set since for all specification \(S P\) of the right signature \(k 1(\operatorname{Set} 2(S P)) \vDash \operatorname{Set}(S P)\). On the other hand, \(k^{\prime}(\operatorname{Oset}(S P)) \vDash \operatorname{Set}(k 3(S P))\) does not necessarily hold unless \(S P \vDash C p o\) and \(k 3(C p o) \vDash\) Elem.

In programming languages we can find the same idea of module referring to the compilation of programs, instead of referring to specification entailment. For example, if a program \(k 2 ; k 1\) is compiled to an object \(o 2 ; o 1\) using separate compilation, the linker can still reuse object \(o 1\) when the code in \(o 2\) is changed.

In specification languages, modular or separate entailment (opposed to separate compilation for programming languages) is very common but explicit semantics are rarely given. Remarkable exceptions are the stratified semantics of PLUSS [Bid 88] and ASL with \(\Pi\)-abstraction as in [SST 90].
\(\Pi\)-abstraction, contrary to standard \(\lambda\)-abstraction in \(\lambda+A S L\), forces correct entailments to be modular. This is a very reasonable restriction to a general syntactic mechanism based on substitution such as \(\lambda\)-parameterization. Similarly, classic parameterization mechanisms in algebraic specifications, as in [EM 85], consider also a syntactic construction, in this case the pushout of specifications (equational presentations). In turn, this pushout construction is required to agree with a functor interpretation of parameterized specifications. The existence of a functor interpretation is less demanding and, probably, more elegant than imposing modular entailment or stratified semantics; however, the latter caters to the urgent need of easing verification while the former does not.

The fact of a entailment being modular has immediate consequences in terms of verification techniques:

Fact 7.4.4 For arbitrary specifications \(S P 2\) and \(S P 1\), and an arbitrary \(S B O \xi\),
\[
\frac{\xi(S P 2) \vdash \xi(S P 1)}{S P 2 \vdash S P 1} \quad \text { provided } \xi(S P 2) \vDash \xi(S P 1) \text { is modular }
\]
is sound w.r.t. specification entailment.
Proof Immediate from the definition of modular entailment.
This fact guarantees that the tactic associated with the simplification rule (backwards application) is not just sound but safe for modular entailment, in
the sense that its application in proof search cannot reduce a valid purported entailment to a wrong one.

This is of great significance since it means that we do not need to carry the whole antecedent around in our proofs, but just the module of the antecedent corresponding to the module of the consequent we want to verify. In the large, a modular entailment can be proven correct in a module-by-module proof, i.e. a modular proof.

\subsection*{7.4.3 Modular programming and constructors}

Hitherto constructors have been viewed as arrows in \(\operatorname{Spec}(S I G)\) and therefore as particular specification building operations. However there is a fundamental difference between a constructor and a specification from the software development point of view: Once we have got a constructor we do not expect to implement it any further. At most, constructors may be refined by other constructors (program transformation) but here we are not concerned with this problem.

This principle of software development is reinforced by a proof-theoretic fact: Constructors lack M-complete inference rules. For this reason, neither generic constructors nor FQRD-constructors in EQ can be flattened to a set of axioms and constraints. In an inference system such as \(\vdash_{M}\), this means that entailments with constructors in the consequent can only be proven correct if the same constructors are also used in the antecedent and they can eventually be simplified using [Simpl].

This is particularly obvious for S -constructors, since we explicitly ignore in \(\vdash_{M}\) what an S-constructor \(\langle P, \Lambda,\langle\iota, \sigma)\rangle\) does except for what \(\Lambda, \iota\) and \(\sigma\) can tell us. Hence, \(S P 2 \models\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle S P 1\) cannot be proven correct unless \(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\) is also present in \(S P 2\). Moreover, no requirement in the consequent - neither axiom, reachability constraint nor subspecification - can be pulled through an S-constructor (generic constructor), hence entailment proofs must treat the re-
quirements in a consequent with a \(S\)-constructor as two separated blocks, those requirements preceding the \(S\)-constructor and those requirements following it.

If \(F Q R D\)-constructors are considered the result is similar. Inference rules for \(F_{\sigma}^{e q}, Q_{e q}\) and \(R_{\{s\}}\) are sound but not M-complete, hence no rules for pulling sentences (or constraints) out of the consequent appear in \(\vdash_{M}\).

We can conclude that for derivable specification entailments in \(\vdash_{M}\), intermixing constructors with specifications encourages modular programming. In fact, we can expect common entailments to be \(K\)-modular.

Definition 7.4.5 Given a subcategory of constructors \(K\) in \(\operatorname{Spec}(S I G)\), a entailment \(S P 2 \models S P 1\) is \(K\)-modular if for all constructors \(k \in|K|\) and decomposition \(P 1\left(k\left(S P 1^{\prime}\right)\right)\) of \(S P 1\), there exists a decomposition \(P 2\left(k\left(S P 2^{\prime}\right)\right)\) of \(S P 2\) such that
\[
P 2 \leq P 1 \quad S P 2^{\prime} \leq S P 1^{\prime}
\]

Immediately from this definition and the simplification rule, it follows that:

Fact 7.4.6 Given a specification language Lang, a language of constructors \(K\) and a complete inference system \(\vdash_{L}\) for entailments in \(K+\) Lang \(\vDash\) Lang, then \(\vdash_{L}\) with the simplification rule is complete w.r.t. \(K\)-modular entailments in \(K+\) Lang \(\vDash\) \(K+\) Lang.

Restricting to \(K\)-modular entailments allows constructors, which do not have M-complete inference rules, to be used in the consequent. However, for S-constructors (generic constructors) and FQRD-constructors, not even complete inference rules are available. The lack of complete rules prevents having a complete inference system for \(K+A S L \models A S L\).

In order to obtain completeness, we should restrict to constructors with complete inference rules like \(D_{\sigma}\). Nevertheless, if the inference rules for the constructors
are considered satisfactory, as is the case for S-constructors, we have a satisfactory inference system for \(K+A S L \vDash A S L\) and, therefore, we also have a satisfactory inference systems for \(K\)-modular entailments in \(K+A S L \vDash K+A S L\).

Our specification language lacks, however, an explicit way of forcing modular entailments during the development of software. Restricting to \(K\)-modular entailments, we can intermix some constructors with our specification in order to implicitly impose modular development and programming. Neverthelesं́, explicit use of \(\Pi\)-abstraction as proposed in [SST 90] would make specifications clearer.

\subsection*{7.5 Structure and theorem proving}

Theorem proving has already been treated in chapter 3 ; however, some aspects related to structured specifications and, in particular, to specifications with a modular implementation must be added.

In chapter 3, proving theorems from structured specifications was considered a more complicated task than proving theorems from presentations or flat specifications. On the other hand, as it has been shown in [SB 83], structure far from complicating can ease theorem proving over specifications.

Taking advantage of the locality of the symbols used in a purported theorem, a smart theorem prover can find a small subspecification where the theorem can actually be proven. Of course, in the worst case no advantage is gained from the structure but in many cases a lot of effort can be saved, particularly if the underlying inference system is hard to use.

Similar considerations apply to proving reachability constraints and whole subspecifications. In these two cases, however, locality is guaranteed.

But perhaps the most striking result relating structure to theorem proving is that of O.Schoett about proving theorems from abstracted specifications which are implemented in a modular fashion.

\subsection*{7.5.1 Modular programming and data abstraction}

In chapter 5 we studied in detail how to prove entailment w.r.t. behaviourally abstracted specifications, or in general, abstracted specifications.
\[
S P 2 \models T_{o} D_{o} S P 1
\]

Difficulties arise because the proof rule for \(D_{\sigma}\) is not M-complete and also because the number of observations is usually infinite. The first problem, although more fundamental, disappears when considering well-behaved observational abstractions, while the second one results harder to tackle.

Sound rules for the different SBO's in ASL never posed a problem. In particular for \(D_{\sigma}\) and \(T_{\sigma}\) we have sound and complete rules which imply we also have a sound and complete rule for abstraction
\[
\frac{S P \models \varphi}{T_{o} D_{o} S P \models \varphi} \varphi \in O b s_{⿺ 𠃊}
\]
and therefore we feel confident when proving theorems such as \(\xi\left(T_{o} D_{o} S P\right) \models \varphi\) or proving correctness of entailments such as \(\xi\left(T_{o} D_{o} S P\right) \vDash S P 1\). Nevertheless, the fact that only observations \(O b s_{\jmath^{\circ}}\) can be inferred by the rule and that there are infinitely many such observations, make such proofs very tedious.

Consider for example an abstracted specification of stacks within a bigger specification, e.g. the specification of a compiler \(\operatorname{Comp}\left(\alpha_{\Xi_{\Pi}} S t a c k\right)\). Every time we want to prove a simple property of the compiler involving the use of stacks, we have to write the whole proof using directly the observable properties of stacks. In some cases a single proof can require the use of all the observations and therefore drive us to the use of induction.

On the other hand, in a modular implementation of \(\operatorname{Comp}\left(\alpha_{\equiv_{\text {I }}} \operatorname{Stack}\right)\) a program (constructor) implementing Comp will use stacks but in the course of its execution it may never discriminate between two stacks which are behaviourally indistinguishable. Considering an execution of a program to be a theorem relating the input to the output, executions of the compiler can be seen as observable theorems \(\varphi\) over the signature of \(\operatorname{Comp}\left(\alpha_{\equiv_{\square}} S t a c k\right)\), hence we may expect
\[
\operatorname{Comp}\left(\alpha_{\equiv_{\mathrm{n}}} \operatorname{Stack}\right) \models \varphi \text { iff } \operatorname{Comp}(S t a c k) \models \varphi
\]

In consequence the abstraction on stacks can be ignored when proving theorems about the compiler.

In [Sch 87] an elegant formulation of this phenomenon is presented and a notion of stability is defined over programming languages characterizing when behavioural abstraction can be ignored in the course of proving properties of modular specifications. Now, the problem and its solution are revisited in our language of arrows.

Let us first define a stable constructor w.r.t. an abstracted specification as a constructor which cancels the effect of the abstraction.

Definition 7.5.1 A constructor \(k\) is stable \({ }^{\text {t }}\) w.r.t. a specification \(S P\) and an abstraction operation \(T_{o} D_{o}\) iff the following diagram commutes, i.e. \(k(S P)=\) \(k\left(T_{o} D_{o} S P\right)\).


If \(k\) is stable w.r.t. \(S P\) and \(T_{o} D_{o}\) we guarantee that for all sentences \(\varphi\)
\[
k(S P) \models \varphi \text { if } k\left(T_{o} D_{o} S P\right) \models \varphi
\]
actually this notion of stability is stronger than that in [Sch 87]] 7.5 .3 below recovers Scheat's notion of stability and hows their relationship.

Moreover, for any modular entailment \(k(k 2) \vDash P\left(T_{o} D_{o} S P\right)\) it follows that:
\[
\begin{aligned}
k(k 2) & \models k\left(T_{o} D_{o} S P\right) & & \text { by definition of modular entailment } \\
& \models k(S P) & & \text { by definition of stable constructor } \\
& \models P(S P) & & \text { by definition of modular entailment }
\end{aligned}
\]
hence, for all sentences \(\varphi\)
\[
P(S P) \vDash \varphi \quad \Longrightarrow \quad k(k 2) \vDash \varphi
\]

As in the case of a compiler using stacks, stability of \(k\) allows us to replace \(T_{0} D_{0} S P\) by \(S P\) when proving theorems from \(k\left(T_{o} D_{0} S P\right)\). In other words, we can assume that the implementation of stacks satisfies its specification when, in fact, it is only behavioural equivalent to an algebra satisfying it.

The main problem with this definition of stability is to determine when a constructor is stable.

In general, constructors are not stable. Consider for instance the case where \(k\) is the identity; requiring \(k(S P)=k\left(T_{o} D_{o} S P\right)\) means that abstraction does not abstract at all, \(S P=T_{o} D_{o} S P\). Although a characterization of stable constructor does not seem easy to obtain, a sufficient condition is available.

Fact 7.5.2 Constructors of the form \(D_{o} ; k\) are stable w.r.t. any specification SP and abstraction operation \(T_{o} D_{o}\).

Proof By definition of \(D_{\sigma}\) and \(T_{\sigma}\), it is clear that for all morphisms \(\sigma\),
\[
D_{\sigma} T_{\sigma} D_{\sigma} S P=D_{\sigma} S P
\]
hence \(k\left(D_{o} T_{o} D_{o} S P\right)=k\left(D_{o} S P\right)\).

Constructors of this form require \(k\) to "work" on the abstracted signature, but this change may be too demanding for the language of constructors. So, the main question is: Do constructors know how to work on abstracted signatures?

In a case such as \(\operatorname{Beh}(E Q)\) and \(F Q R D\)-constructors, the answer is no. Equations have only been defined for standard algebraic signatures, and sentences over an abstracted signature are only the observable sentences. Therefore, if \(k\) defines a 2-pop operation on \(D_{o} S t a c k\), an axiom like
\[
\forall \text { s:stack. 2-pop(s) }=\text { pop }(\text { pop }(s))
\]
is not allowed.
Changing the institution \(\operatorname{Beh}(E Q)\), by extending the set of sentences over an abstracted signature to include equalities between non-visible terms and a notion of satisfaction for them, might solve this problem. However, in a more realistic example where the constructors are programs, we are not concerned with equalities. What we expect is to be able to use the original functions such as pop and to ensure, by an encapsulation mechanism, that the constructor cannot gain access to any information about the nature of the non-observable values. For example, stable constructors should be able to use pop, store non-observable values and make copies of them, but it should not be able to check equality between non-observable values.

Technically this can be interpreted as follows: The encapsulation mechanism is a constructor implementing \(D_{o}\), for an abstraction morphism \(o: \Pi \rightarrow \Sigma\). Instructions in a constructor \(k\) on top of \(D_{o}\) when executed amount to sentences in \(\operatorname{Sen}(\Pi)\), that is, observations in \(\operatorname{Sen}(\Sigma)\).

Work in [Sch 87] looks at the problem and results from a different point of view since abstraction is, there, an atomic SBO.

Stable constructor do not need to have the form \(D_{o} ; k\). Intuitively, the hiding step \(D_{o}\) can be delayed in the implementation, e.g. a stable constructor can have the form \(k 1 ; D_{o^{\prime}} ; k 2\) where \(D_{o^{\prime}}\) is intended to hide the same things as \(D_{o}\). The hiding step can be shifted along the whole constructor to give a stable constructor \(k 3 ; D_{o^{\prime \prime}}\).

The condition for such delaying to be sound is that \(k 3\) (or \(k 1\) in the first case) preserves behavioural equivalence; i.e. for every two models \(A\) and \(B\) such that \(\left.A\right|_{o}=\left.B\right|_{o}\), it holds that \(\left.k 3(A)\right|_{o \prime \prime}=\left.k 3(B)\right|_{o^{\prime \prime}}\), which is essentially the definition of stability in [Sch 87].

Theorem 7.5.3 Consider a constructor \(k^{\prime}\) defined by a function \(f_{k^{\prime}}:|\operatorname{Mod}(\Sigma)| \rightarrow\) \(\left|\operatorname{Mod}\left(\Sigma^{\prime}\right)\right|\) and abstraction morphisms \(o: \Pi \rightarrow \Sigma\) and \(o^{\prime}: \Pi^{\prime} \rightarrow \Sigma^{\prime}\).


If for all \(\Sigma\)-models \(A\) and \(B,\left.A\right|_{o}=\left.\left.B\right|_{o} \Rightarrow f_{k^{\prime}}(A)\right|_{o^{\prime}}=\left.f_{k^{\prime}}(B)\right|_{o^{\prime}}\) then \(k^{\prime} ; D_{o^{\prime}}\) is stable w.r.t. any \(\Sigma\)-specification and \(T_{o} D_{o}\).

Proof Let \(k\) be a constructor defined by a function \(f_{k}:|\operatorname{Mod}(\Pi)| \rightarrow\left|\operatorname{Mod}\left(\Pi^{\prime}\right)\right|\) such that for all \(A \in \operatorname{Mod}(\Sigma)\)
\[
f_{k}\left(\left.A\right|_{o}\right)=\left.f_{k^{\prime}}(A)\right|_{o^{\prime}}
\]

Since every model over \(\Pi\) is the o-reduct of some model over \(\Sigma, f_{k}\) is totally defined over \(\operatorname{Mod}(\Pi)\). And since \(f_{k^{\prime}} ;-l_{o^{\prime}}\) delivers the same result for equivalent models, \(f_{k}\) is well-defined.

By definition of \(k\) the diagram commutes.


By fact 7.5.2, \(D_{o} ; k\) is stable w.r.t. any specification \(S P\) and abstraction operation \(T_{o} D_{o}\), hence
\[
D_{o^{\prime}}\left(k^{\prime}(S P)\right)=k\left(D_{o}(S P)\right)=k\left(D_{o}\left(T_{o} D_{o} S P\right)=D_{o^{\prime}}\left(k^{\prime}\left(T_{o} D_{o} S P\right)\right.\right.
\]

Using constructors of the form \(k^{\prime} ; D_{o^{\prime}}\) has two benefits. First, constructors and specifications only need to talk about sentences and signatures in the original institution, and that may be necessary if we do not have a syntax for sentences and signatures in the abstracted institution, e.g. infinitary signatures for behaviours in [MG 85]. In second place, \(D_{o^{\prime}}\) should be implemented by an encapsulation mechanism, but since it is at the "top" of the implementation, we can just ignore it.

Moreover, if abstraction is an atomic operation, as in [Sch 87], only the second presentation makes sense. But, if we have notions such as abstracted signatures, the first presentation considering \(D_{o}\) to be an encapsulation mechanism in the language of constructors is more concise.

\section*{Chapter 8}

\section*{Conclusions}

\subsection*{8.1 Main conclusions}
"This thesis seeks a formal system for proving implementation steps to be correct in ASL and related languages ..." (page 11 of the introduction)

The main conclusion is the feasibility of proving specification entailments in \(A S L(\mathbf{I})\) for a given institution \(\mathbf{I}\).

The results in this thesis can be summarized by a classification of specification entailments depending on whether they enjoy a complete inference system, a satisfactory inference system or just a sound inference system.

Assuming that we work in an institution whose consequence relation comes with a sound and complete inference system \(\vdash^{\mathbf{I}}\), entailment between specifications has a complete inference system in the case of
\[
D A T U \models A T U
\]
and also
\[
D A T U \models D A T U^{*}
\]
as discussed in chapter 4, where specifications in \(D A T U^{*}\) are those in DATU using \(D_{\sigma}\) only in the context of persistent and independent hidden enrichments.

Since abstraction \(\alpha\) is introduced in chapter 5 as a particular case of \(T_{\sigma} D_{\sigma}\), we can also say that \(\alpha+D A T U \vDash D A T U^{*}\) enjoys a complete inference system. Moreover, if we restrict the use of abstraction to an observational and well-behaved institution, \(\alpha+D A T U \vDash \alpha+D A T U^{*}\) also has a complete inference system.

Finally, if our institution I treats constraints as ordinary sentences and the inference system \(\vdash^{\mathrm{I}}\) is still sound and complete, we conclude that \(\alpha+D M A T U \models\) \(\alpha+D M A T U^{*}\left(\right.\) written \(\left.\alpha+A S L \models \alpha+A S L^{*}\right)\) has a complete inference system.

A satisfactory inference system is an informal notion intended to capture incomplete inference systems which appear to be good enough in the great majority of the cases. In practice, such inference systems can be considered satisfactory for formal software development.

In an institution with reachability constraints such as EQ we have that:
- Considering structural induction as a satisfactory solution for inferring the inductive consequences of a presentation, \(D M A T U \vDash D A T U^{*}\) has a satisfactory inference system.
- Considering set theory to be satisfactory for reasoning about sets and some additional assumptions, \(A S L \models A S L^{*}\) also has a satisfactory inference system.

Therefore, restricting the use of abstraction to an observational and wellbehaved abstracted institution w.r.t. \(\mathbf{E Q}, \alpha+A S L \vDash \alpha+A S L^{*}\) has a satisfactory inference system as well.
- Considering we have satisfactory means for checking consistency, the \(\exists^{2}\) strategy provides a satisfactory inference system for \(D A T U \vDash D A T U\). And, in conjunction with the previous considerations, there are satisfactory inference systems for \(A S L \models D A T U, A S L \models A S L\) and \(\alpha+A S L \models \alpha+A S L\).

If S-constructors \(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle\) are considered, we can consider \(\Lambda\) and the pair \(\langle\iota, \sigma\rangle\) to give a satisfactory account of the properties of the program \(P\). Then, we have a satisfactory inference system for \(k+A S L \models A S L\). Moreover, if specification entailments are restricted to \(K\)-modular entailments then
\[
k+A S L \models k+A S L
\]
also has a satisfactory inference system.

These results can be summarized in the following global conclusion: In order to make verification acceptable we must choose an institution with a good inference system (including inference of constraints if they are to be used) specify with care the hidden parts of specification so that they are persistent and independent, choose an abstraction notion related to an observational and well-behaved institution, produce \(S\)-constructors with an appropriate set of properties and use modular entailments. Moreover, the prover must be prepared to complete some of the specifications during the proof of entailment so that problems caused by a lack of independence, or even a lack of persistency, can be solved.

\subsection*{8.2 Problems and solutions}
"In the process, we use \(A S L\) as a tool to investigate the verification of implementations in general ..."

Although the main goal of the thesis has been solving specification entailments in \(A S L\), the structure of the thesis and most of the work is dedicated to specific verification problems which arise in \(A S L\) but also in most other specification languages. In the following a short summary is given.
1. The main verification problems arise in consequent specifications with hidden parts, behaviourally abstracted specifications, specifications with reachability
constraints and partially implemented specifications (specifications with constructors).

This is the conclusion of section 3.5 stemming from the characterization, in theorem 3.3.12, of the inference rules available for each SBO. From a technical point of view, all these verification problems arise because the inference rule for \(D_{\sigma}\) is not M -complete (see counterexample in figure 32) and the rules for \(M_{\langle\sigma, \lambda\rangle}\) and \(\langle P, \Lambda\rangle\) are not complete (see sections 3.3.2 and 3.4).
2. There is a complete inference system for reachability constraints of the form \(\ll G, F, S \gg\).

Although reachability and other kinds of constraints have been used in algebraic specification for a long time, no attempt has been made to infer reachability constraints from other constraints or from specifications. In chapter 6 inference systems for single constraints (Definition 6.3.4), sets of constraints (Definition 6.3.10) and mixed sets of equations and constraints (in section 6.3.2) are presented; the first (Theorem 6.3.5) and the second under some restrictions (Theorem 6.3.12) are complete.
3. "Proving all observable theorems to hold" is a sound strategy for proving correctness w.r.t. abstracted specifications, if we use an observational and well-behaved notion of abstraction (Theorem 5.3.3).

This conclusion is a solid argument for preferring certain notions of abstraction rather than others. Previous work on behavioural abstraction led to a multiplicity of "slightly different" definitions which can now be classified.

More striking is the fact that context induction [Hen 89] and many ad hoc proofs happen to be sound with respect to the standard notion of behaviour because they restrict the models of a specification to be reachable algebras,
hence restricting to the domain of an observational and well-behaved institution BehR(EQ) (Theorems 5.3.11 amd 5.3.13).
4. If the hidden parts of a specification are specified as persistent and independent enrichments, correctness proofs become very much simpler.

This conclusion follows from theorems 4.4.1, 4.4.3, 4.5.1 and 4.5.3 in chapter 4 where persistency and independence are proven sufficient and necessary for the soundness and completeness of the inheriting strategy.

In the case of hiding auxiliary functions, persistency and independence of the hidden enrichments are indeed very sensible and surely improve the clarity of structured specifications.
5. Treating behavioural abstraction as the hiding of equality and/or generators for non-observable sorts is a sound strategy but is not always applicable.

Since abstraction can be understood as \(T_{\sigma} D_{\sigma}\) in the appropriate institution, abstraction can be treated as the hiding of the equality symbols and/or generator functions. This strategy, if successful, requires the prover to define the "abstract" equality and/or the generators in the implementation (antecedent specification) before completing the proof, similarly as is generally done in verification w.r.t. abstract model specifications using an abstraction function (see example in 6.4.3).
6. In order to treat subspecifications as single requirements some rules are needed for pulling whole subspecifications out of antecedent and consequent specifications.

Most of the times common subspecification, e.g. actual parameters, are repeated in the antecedent and the consequent of a purported entailment. However, a subspecification in the consequent cannot be proven to follow
from the same subspecification in the antecedent unless both subspecifications can be pulled to the top and are in the same form on both sides of the entailment (see section 7.3.1).

This conclusion generalizes common requirements in specification languages saying that parameters must be preserved/protected.

If we take a common approach to algebraic specification such as the initial approach, we can find that all these problems/solutions also apply. In the initial approach parameterized specifications are required to denote persistent functors, which means that subspecifications can be trivially pulled out of parameterized specification (if they are parameter specifications) and hidden enrichments are trivially persistent and independent (if they are parameterized specifications). Functor persistency also guarantees consistency and sufficient completeness of parameter specifications w.r.t. to their actual parameters, hence redundancy of certain functions and sorts can be explicitly stated. Moreover, initial semantics guarantees models to be reachable algebras and therefore observationality and well-behaviour follow for the standard notion of behavioural abstraction.

In general, we have to study each of the verification problems mentioned above in the context of any specification language we use. Hopefully, some potential problems do not arise due to the particular definition of the specification language and/or the institution used.

\subsection*{8.3 Negative results and trade-offs}
> "... we shall ... exhibit trade-offs between sensible verification methods and the expressive power of specifications and the flexibility of implementations".

There are a number of negative results and trade-offs between flexibility and satisfactory verification. In the following we enumerate the most significant results.
1. An inference system for constraints has to be developed for each institution.

Due to the definition of institution and \(A S L\), there is no relation between morphisms in the category of models and the satisfaction relation. This results in a SBO \(M_{(\sigma, \ell)}\) without any sensible institution-independent verification treatment. Hence, the user proposing the use of an institution should develop an inference system for constraints in that institution.
2. Persistency of an enrichment is undecidable.

Although persistency of hidden enrichments plays a key role in most of this thesis, there is no effective procedure for checking persistency of enrichments w.r.t. basic specifications. This is also a well-known problem in the initial approach where some proof theoretical conditions have been established [Gan 83, Pad 80, Pad 85].
3. Lack of independence usually requires prover intervention.

Almost always the lack of independence of a hidden enrichment requires the prover to complete the specification with some extra axioms. This prevents proofs from being automatic when the generators of a visible sort are hidden or abstraction is treated as hiding.
4. There is no known observational and well-behaved institution for standard behavioural abstraction.

Non-reachable values in observable sorts prevent most institutions from being observational. The only available observational institution "modeling" standard behavioural abstraction, \(\mathrm{BehO}(\mathbf{E Q})\), is not well-behaved.
5. No inference system is available for inferring reachability constraints from sets of reachability constraints and equations.

Despite the satisfactory performance of \(H^{-}\)(Definition 6.3.10), we have no complete inference system for inferring a reachability constraint from a finite set of reachability constraints. Moreover, if reachability constraints are intermixed with other kind of sentences the satisfactory performance of \(H_{\Phi}\) (integrating \(H\) and \(\vdash^{\mathrm{EQ}}\) ) depends on a long list of assumptions.
6. Although \(\alpha+D A T U \vDash\) ATU has a complete inference system, proofs may be very hard.

In this case, despite the availability of a complete inference system for proving theorems from specifications in \(D A T U\), such proofs may be terribly tedious in practice since only observable premises are allowed.

Work in [Sch 87] (see section 7.5.1) solves this problem in the case of modular entailments, however, in general the problem persists.

\subsection*{8.4 Future developments}

The results of this thesis cover the verification of specification entailments in the whole of \(A S L\) including mechanisms for abstraction and parameterization. Future developments should address the application of these results to real specification languages and every day verification.

In particular, the semantics of a specification language can be designed so that hiding is only used in the context of persistent and independent hidden enrichments, explicit means for enforcing modular development are made available, etc.

At the institution level, some common institutions can be fixed and an inference system for their constraints developed, like the inference system for reachability constraints in chapter 6.

The actual inference rules in \(\vdash_{M}\) and in the appropriate \(\vdash^{I}\) can be incorporated into a software development environment so that specification entailment proofs are electronically supported. In this context, attention can be drawn to the support of some verification strategies such as the inheriting strategy.

In specification languages such as Extended ML [ST 86, ST 89], this environment can be used for proving the correctness of development steps and also for producing well-formed specifications. In particular, interface matching SP2:SP1 between structures and signatures in Extended ML amounts to specification entailment \(S P 2 \models S P 1\) as discussed in this thesis.

On a more theoretical side, results in this thesis can be used for analyzing other specification languages from the proof-theoretic point of view. Analogously to \(A S L\) which has been used for analyzing the semantics of other specification languages, e.g. by distinguishing the institutional from the institution-independent
aspects, we can use our collection of verification problems, inference systems and specification properties in order to classify different approaches to formal specification.

In the end, users will become aware of the trade-off between flexibility and verification techniques and, eventually, they should be able to identify which approach to formal program development is best suited for them.

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\section*{The inference system \(\vdash_{M}\)}
1. Basic proof rule:
\[
\frac{\Phi 2 \vdash^{\mathrm{I}} \Phi 1}{A_{\Phi 2} S P \vdash_{M} A_{\Phi 1} \epsilon_{S i g[S P]}}
\]
2. Pulling sentences (axioms) out of the consequent:
\[
\begin{array}{ll}
A_{\Phi}(S P 1 U S P 2) \vdash_{M}\left(A_{\Phi} S P 1\right) U S P 2 & A_{\sigma(\Phi)} T_{\sigma} S P \vdash_{M} T_{\sigma} A_{\Phi} S P \\
A_{\Phi}(S P 1 U S P 2) \vdash_{M} S P 1 U\left(A_{\Phi} S P 2\right) & A_{\Phi 1} A_{\Phi 2} S P \vdash_{M} A_{\Phi 2} A_{\Phi 1} S P
\end{array}
\]
3. Pulling subspecifications out of the consequent:
\[
\begin{aligned}
& A_{\Phi} S P \quad U S S P \vdash_{M} A_{\Phi}(S P U S S P) \\
& M_{\langle\sigma, \iota} S P U S S P \vdash_{M} M_{\langle\sigma,\rangle}(S P U S S P) \\
& (S P 1 U S P 2) U S S P \vdash_{M} S P 1 U(S P 2 U S S P) \\
& (S P 1 U S P 2) U S S P \vdash_{M}(S P 1 U S S P) U S P 2 \\
& T_{\sigma} S P U T_{\sigma} S S P \vdash_{M} T_{\sigma}(S P U S S P) \\
& D_{\iota} S P U S S P \vdash_{M} D_{\iota}\left(S P U T_{\imath} S S P\right)
\end{aligned}
\]
4. Pulling sentences (theorems) out of the antecedent:
\(S P 1 U\left(A_{\Phi} S P 2\right) \vdash_{M} A_{\Phi}\left(S P 1 U\left(A_{\Phi} S P 2\right)\right) \quad T_{\sigma} A_{\Phi} S P \vdash_{M} A_{\sigma(\Phi)} T_{\sigma} A_{\Phi} S P\)
\(\left(A_{\Phi} S P 1\right) U S P 2 \vdash_{M} A_{\Phi}\left(\left(A_{\Phi} S P 1\right) U S P 2\right) \quad D_{\sigma} A_{\Phi} S P \vdash_{M} A_{\sigma^{-1}(\Phi)} D_{\sigma} A_{\Phi} S P\) \(\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle A_{\Phi} S P \vdash_{M} A_{\{\varphi\}}\langle P, \Lambda,\langle\iota, \sigma\rangle\rangle S P \quad \operatorname{provided}(\Phi, \varphi) \in \Lambda\)
5. Pulling subspecifications out of the antecedent:
```

A

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```

SP1 U (SP2 U SSP) \vdash
(SP1 U SSP) USP2 }\mp@subsup{\vdash}{M}{((SP1 U SSP)USP2)USSP)
T}(SPUSSP)\mp@subsup{\vdash}{M}{}\mp@subsup{T}{\sigma}{}(SPUSSP)U\mp@subsup{T}{\sigma}{}SS
D\iota}(SPU\mp@subsup{T}{\iota}{}SSP)\vdash\mp@subsup{\vdash}{M}{}\mp@subsup{D}{\iota}{}(SP U T T\iotaSSP) USS
\langleP,\Lambda,\langle\iota,\sigma\rangle\rangle(SP U T

```
6. Permuting \(D\) (equality \(=_{M}\) means logical derivability \(\vdash_{M}\) in both directions):
\[
\begin{aligned}
& A_{\Phi} D_{\sigma} S P=_{M} D_{\sigma} A_{\sigma(\Phi)} S P \\
& S P 1 U D_{\sigma} S P 2=_{M} D_{\sigma}\left(T_{\sigma} S P 1 U S P 2\right) \\
& D_{\sigma} S P 1 U S P 2=_{M} D_{\sigma}\left(S P 1 U T_{\sigma} S P 2\right) \\
& T_{\sigma} D_{\sigma 1} S P=_{M} D_{\sigma 1^{\prime}} T_{\sigma^{\prime}} S P \quad \text { provided } \sigma, \sigma 1, \sigma^{\prime} \text { and } \sigma 1^{\prime} \text { form }
\end{aligned}
\]
a pushout diagram as in proposition 4.2.1
7. Absorbing laws:
\[
\begin{array}{lll}
T_{\sigma} \epsilon_{\emptyset}={ }_{M} \epsilon_{\emptyset} & \epsilon_{\Sigma} U \epsilon_{\Sigma}={ }_{M} \epsilon_{\Sigma} & A_{\emptyset} \epsilon_{\Sigma}={ }_{M} \epsilon_{\Sigma} \\
A_{\Phi 1} A_{\Phi 2} S P=_{M} A_{\Phi 1 \cup \Phi 2} S P & D_{\sigma} D_{\sigma^{\prime}} S P={ }_{M} D_{\sigma ; \sigma^{\prime}} S P &
\end{array}
\]
8. Cut rule:
\[
\frac{S P 3 \vdash_{M} S P 2 \quad S P 2 \vdash_{M} S P 1}{S P 3 \vdash_{M} S P 1}
\]
9. Simplification rule:
\[
\frac{S P 2 \vdash_{M} S P 1}{\xi S P 2 \vdash_{M} \xi S P 1}
\]

\section*{In first order logic.}
1. Structural induction
\[
M_{\{G, F, S\rangle} A_{\{\varphi\}} S P \vdash_{M} A_{\left\{\varphi^{\prime}\right\}} M_{\{G, F, S\rangle} A_{\{\varphi\}} S P
\]
where \(\varphi\) is
\[
\bigwedge_{s \in G} \bigwedge_{o p \in F_{s}} \forall \bar{x}: S, \bar{y}: G \cdot\left(\bar{Q}(\bar{y}) \Rightarrow Q_{s}(o p(\overline{x y}))\right)
\]
\(\varphi^{\prime}\) is \(\Lambda_{s \in G} \forall y: s . Q_{s}(y), Q\) is a \(G\)-indexed set of predicates, \(\bar{x}\) a \(S\)-sorted sequence of variables, \(\bar{y}\) a \(G\)-sorted sequence of variables, \(\overline{x y}\) is the concatenation of \(\bar{x}\) and \(\bar{y}, F\), those operations in \(F\) delivering a value of sort \(s\), and \(\bar{Q}\) the conjunction of the appropriate predicates in \(Q\) applied to a given \(G\)-sorted sequence of variables.

\section*{In EQ.}
1. Pulling sentences through \(F Q R\)-constructors:
\(Q_{e q} S P \vdash_{M} A_{e q} Q_{e q} S P\)
\(Q_{e q} A_{\Phi} S P \vdash_{M} A_{\Phi} Q_{e q} A_{\Phi} S P\)
\(R_{G} A_{\Phi} S P \vdash_{M} A_{\Phi} R_{G} A_{\Phi} S P\)
\(F_{\sigma}^{e q} S P \vdash_{M} A_{e q} F_{\sigma}^{e q} S P\)
\(F_{\sigma}^{e q} A_{\Phi} S P \vdash_{M} A_{\sigma(\Phi)} F_{\sigma}^{e q} A_{\Phi} S P\)
provided \(F_{\sigma}^{e q} S P\) is sufficiently complete and consistent.
2. Pulling reachability constraints through \(F Q R\)-constructors:
\[

\]
\(F_{\sigma}^{e q} M_{\langle G, F, S\rangle} S P \vdash_{M} M_{\left\langle\sigma(G), \Omega^{\prime}, S^{\prime}\right\rangle} F_{\sigma}^{e q} M_{\langle G, F, S\rangle} S P \quad\) provided \(\uparrow \sigma=\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\) \(F_{\sigma}^{e q} S P \vdash_{M} M_{\left\langle G, \Omega^{\prime}, \sigma(S)\right\rangle} F_{\sigma}^{e q} S P \quad\) provided \(\sigma:\langle S, \Omega\rangle \rightarrow\left\langle\sigma(S) \uplus G, \Omega^{\prime}\right\rangle\)
3. Pulling subspecifications through \(F Q R\)-constructors: Given a signature morphism \(\iota:\langle S, \Omega\rangle \rightarrow\left\langle S^{\prime}, \Omega^{\prime}\right\rangle\),
\(R_{\{s\}}\left(S P \quad U T_{\iota} S S P\right) \vdash_{M} R_{\{s\}}\left(S P U T_{\iota} S S P\right) U T_{\imath} S S P\)
provided \(s \in\left(\Omega^{\prime} \backslash \iota(\Omega)\right)\) or \(\operatorname{Mod}[S S P]\) is closed under subalgebras \(Q_{e q}\left(S P U T_{\imath} S S P\right) \vdash_{M} Q_{e q}\left(S P U T_{\imath} S S P\right) U T_{\imath} S S P\)
provided \(\iota\) forgets eq or \(\operatorname{Mod}[S S P]\) is closed under quotients
\(F_{\sigma}^{e q}(S P U S S P) \vdash_{M} F_{\sigma}^{e q}(S P U S S P) U T_{\sigma} S S P\)
provided \(\left.\left(\right.\) Free \(\left._{\sigma}^{e q} A\right)\right|_{\sigma}=A\) for all \(A \in \operatorname{Mod}[S S P]\)

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where
\[
f_{B}:|B|_{\text {shape }} \times|B|_{\text {suit }} \rightarrow|B|_{\text {suit }}
\]
is defined by the following table:
\begin{tabular}{l|l|l|l|}
\(f_{B}\) & 1 & 2 & 3 \\
\hline\(\square\) & 2 & 3 & 3 \\
\hline\(\triangle\) & 1 & 3 & 2 \\
\hline
\end{tabular}

Let \(i:|A| \rightarrow|B|\) be the \(S\)-sorted function such that
\[
i_{\text {shape }}={ }_{\text {def }}\{\square \mapsto \triangle, \triangle \mapsto \square\} \quad \text { and } \quad i_{\text {suit }}==_{\text {def }}\{\phi \mapsto 1, \triangleright \mapsto 2, \uparrow \mapsto 3\} .
\]

This defines a \(\Sigma\)-homomorphism \(i: A \rightarrow B\) which is a \(\Sigma\)-isomorphism, so \(A \cong B\).

\section*{Exercise 1.3.10}

Show that a homomorphism is an isomorphism iff it is bijective.

\section*{Exercise 1.3.11}

Show that there is an injective homomorphism \(h: A \rightarrow B\) iff \(A\) is isomorphic to a subalgebra of \(B\).

Example 1.3.12
Let \(\Sigma=\langle S, \Omega\rangle\) be the signature
\[
\begin{array}{ll}
\text { sorts } & s \\
\text { opns } & a: s \\
& f: s \rightarrow s
\end{array}
\]
and define \(\Sigma\)-algebras \(A\) and \(B\) by
\[
\begin{aligned}
|A|_{s}={ }_{\text {def }} & N a t \text { (the natural numbers), } \quad a_{A}==_{\text {def }} 0 \in|A|_{s}, \\
& f_{A}:|A|_{s} \rightarrow|A|_{s}=_{\text {def }}\{n \mapsto n+1 \mid n \in N a t\},
\end{aligned}
\]
\(|B|_{s}=_{\text {def }}\{n \in N a t \mid\) the Turing machine with Gödel number \(n\) halts on all inputs \(\}\), \(a_{B}={ }_{\text {def }}\) the smallest \(n \in N a t\) such that the TM with Gödel number \(n\) halts on all inputs, and
\(f_{B}:|B|_{s} \rightarrow|B|_{s}\) is defined by \(f_{B}(n)=\) the smallest \(m>n\) such that the TM with Gödel numk Let \(i:|A| \rightarrow|B|\) be the \(S\)-sorted function such that
\[
i_{s}(n)=_{\text {def }} \text { the }(n+1)^{\text {st }} \text { smallest element of }|B|_{s}
\]
for all \(n \in|A|_{s}\). The function \(i_{s}\) is well-defined since \(|B|_{s}\) is infinite. This defines a \(\Sigma\) homomorphism \(i: A \rightarrow B\) which is an isomorphism.

Although \(A \cong B\), the \(\Sigma\)-algebras \(A\) and \(B\) are not "the same" from the point of view of computability: everything in \(A\) is computable, in contrast to \(B\) ( \(|B|_{s}\) is not recursively enumerable and \(f_{B}\) is not computable). Isomorphisms capture structural similarity, ignoring what the values in the carriers are and what the functions actually compute. This example shows that, for some purposes, properties stronger than structural similarity are important.```


[^0]:    ${ }^{1}$ The more popular term persistent is avoided in this context since it is formally defined in chapter 2 for another purpose. However, both invariance and persistency (as defined in chapter 2) extend the standard notion of persistency from functors to SBO's.

[^1]:    ${ }^{1}$ Recall that Mod $1^{o p}: S I G 1^{o p} \rightarrow$ Cat $, \operatorname{Mod} 2^{o p}: S I G 2^{\circ}: \rightarrow$ Cat and $\alpha_{S I G}^{o p}: S I G 1^{o p}-$ $S I G 2^{o p}$ are as functors Mod $1: S I G 1 \rightarrow$ Cat $^{o p}, \operatorname{Mod} 2: S I G 2 \rightarrow$ Cat $^{\circ p}$ and $\alpha_{S I G}:$ $S I G 1 \rightarrow S I G 2$ but considered between the opposite categories.

[^2]:    ${ }^{2}$ More precisely, not $U$ but the unary SBO's "- $U S P 2$ " and "SP1 U _" for arbitrary specifications $S P 1$ and $S P 2$, are selectors.

[^3]:    ${ }^{3}$ Note that $f$ is a constant for $n=0$.

[^4]:    ${ }^{4}$ Indices prevent variables of different sorts with the same name in $X$ from being confused in $\sigma(X)$.
    $s$ formulation is incorrect. See $[G B 90]$ for the correct definition

