Intelligent Agents for Coalition Search and Rescue Task Support

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http://www.aiai.ed.ac.uk/project/cosar-ts/demo/isd/

Abstract

The Coalition Search and Rescue Task Support demonstration shows cooperative agents supporting a highly dynamic mission in which AI task planning, inter-agent collaboration, workflow enactment, policy-managed communications, semantic web queries, semantic web services matchmaking and knowledge-based notifications are employed.

Introduction

The Coalition Search and Rescue Task Support (CoSAR-TS) project is integrating AIAI's I-X planning and collaboration technology, IHMC's KAoS policy and domain management agent services, and semantic web services of various kinds. Search and rescue operations by nature require the kind of rapid dynamic composition of available policy-constrained services making it a good use case for Semantic Web technologies. Other participants in the application include BBN Technologies, SPAWAR, AFRL, and Carnegie Mellon University.

CoSAR-TS Scenario

The scenario is set in the Binni domain used for multinational research in Command and Control (Rathmell, 1999). It begins with an event that reports a downed airman in the Red Sea between the coastlines of two fictional nations: Binni (to the West) and Arabello (to the East). In this initial scenario it is assumed that excellent location knowledge is available, and that there are no local threats to counter or avoid in the rescue. The airman reports his own injuries via his suit sensors. Next is an investigation of the facilities available to rescue the airman. There will be three possibilities: a US ship-borne helicopter; a Gaoan helicopter from a land base in Binni; or a patrol boat situated off the Arabello coastline. Finally, there is a process to establish available medical facilities for the specialized injury reported using the information provided about the countries in the region. Arabello's hospital is best placed to provide the facilities, due to the fact that it has the necessary treatment facilities for burns. But the selection of the rescue resource is policy-constrained since no Gaoan helicopters may enter Arabello airspace.

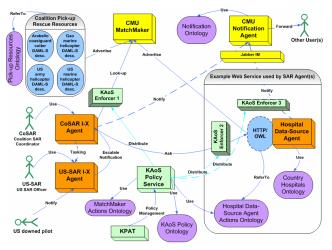


Figure 1: CoSAR-TS Components

Figure 1 shows the agents used in the demonstration, representing the roles and functions of the Coalition SAR coordinator, US SAR officer, hospital information provider, SAR resource provider and a Notification Agent. The Coalition SAR Coordinator and US SAR Officer each has an I-X process panel, which can be used for messaging concerning collaborative activity, and is also used to select, refine and execute a suitable standard operating procedure or plan. A query is made on a BBN Technologies semantic web service of OWL-encoded facts about country medical infrastructure. The selection of a SAR resource is made using the CMU Semantic Matchmaker to find a suitable service. These lookups obey policies set by the IHMC KAoS Policy Administration Tool (KPAT). Finally, the CMU Notification Agent uses knowledge of the recipients to make notifications to hospital administrators or pilots.

I-X Technology

I-X Process Panels (http://i-x.info - Tate, 2003) can provide task support by reasoning about and exchanging

with other agents and services any combination of Issues, Activities, Constraints and Annotations (in the <I-N-C-A> ontology). I-X can therefore provide collaborative task support and exchange of structured messages related to plans, activity and the results of such activity. These types of information can be exchanged with other I-X panels and with other tools using OWL, RDF or other languages.

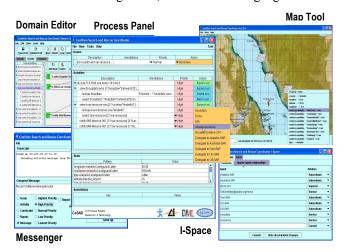


Figure 2: I-X Process Panel and Associated Tools

Figure 2 shows an I-X Process Panel $(I-P^2)$ and associated I-X Tools. I-X can make use of multiple communications methods ranging from simple XML instant messaging (e.g. via Jabber) to sophisticated policy constrained agent communications environments (e.g. CoABS Grid, KAoS). The I-Space tool maintains agent relationships. The relationships can be obtained from agent services such as KAoS. I-X Process Panels can also link to semantic web information and web services though an I-Q query adaptor.

I-X includes a process editor for creating process models (I-DE) to populate the domain model and an AI planner (I-Plan) that can compose a suitable plan for the given tasks when provided with a library of standard operating procedures or processes, and knowledge of other agents or web services that it may use. I-Plan can support hierarchical plan creation, precondition achievement, consistent binding of multiple variables, temporal constraint checking, etc.

KAoS Technology

Figure 3 shows the KAoS Policy Administration Tool (http://www.ihmc.us/research/projects/KAoS/ - Uszok et al. 2003). Through it, policies constraining usage of resources and agents' actions are inserted into the system. The policies are expressed using OWL. This allows the use of Description Logic reasoning algorithms to perform sophisticated queries and analysis of policies; supported by Stanford University's Java Theorem Prover (JTP) inferencing engine. Loading relevant application specific ontologies can dynamically extend the KAoS Services. The

layer of guards and enforcers integrated with the application facilitates the enforcement of the policies.

Actor Classes Namespaces Om Domain View	Name: Generic	Name: Generic DAML Editor					
Actor	Description: Generic	c editor for DAML	policies				
Agent	Policy Editor						
ArtificialActor							
DomainManager	Policy id: Apol	Policy id: #policy-6ffa1630-00f6-0000-8000-0000deadbeef					
GroupActor	Policy name: Not	Policy name: NotricatioAboutMove					
Guard HardwareActor	Description: mus			alif. a second h	uman when it indents moves to a cer	tele lessites	
Human		s policy obliges at	IN TOBOLIO II	only some n	ornan when it indents moves to a cer	sam location.	
MembershipRegistry	Priority: 2						_
NaturalActor							
Person PolicyMediator			Robot		▼ is obligated ▼		
Robot		to perform	Notificat	ionAction	▼ with propertie	s:	
SoftwareActor							
	Role		restriction	Cor	nplement Value(s)		
	hasDestination hasNotification		at least on	• •	(Human) (Pager, Email)		
	hasLatency	Mode is subset			Immediate1		
	intaction by the second				Innerented		
				Add	carriesMessage		
					hasContext	1	
					hasDestination	•	
	w	Ahen Robot	performs	MobilityAct	hasFocusOfAttention	, perties	
					hasLatency	•	
	Role		Restrictio	n (c	hasNotificationMode	•	
					hasRecipientPresenceRestriction	•	
					hasRecipientRestriction	•	
					hasSeverity	Classes Instances	AdvisorySe
				Add	performedOn triggerEvent	mondfices +	CriticalSev LogSeverite
				Add	a differences		SeverityMo
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1.0						Commit	Refresh
							romesn

Figure 3: KAoS Policy Administration Tool

Acknowledgements

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