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Corrigendum

Corrigendum to: "Experimental study of prosthesis modifications based on passive dynamic walking model: A limit cycle stability analysis". [J. Biomech. 104 (2020) 109743]

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The authors regret an error and wish to make the following correction to their recently published paper Moradi et al. (2020):

In the results section, an error occurred in part B of Table 2; where the descriptive results of step length were reported incorrectly the same as part A. The corrected table is presented below.

References

Moradi, V., Sanjari, M.A., Saeedi, H., Hajiaghaei, B., 2020. Experimental study of prosthesis modifications based on passive dynamic walking model: a limit cycle stability analysis. J. Biomech. 104, 109743.

Table 2

The results of dynamic stability and step -wise symmetry index for four conditions.

(A) Floquet Multipl	ier (FM) and local diverge	nce exponents (LDE) statist	ics			
Condition	FM			LDE		
	Mean	Median	SD	Mean	Median	SD
NM	0.54	0.61	0.33	0.30	0.32	0.10
AM	0.52	0.55	0.31	0.31	0.30	0.07
K18	0.58	0.63	0.30	0.34	0.33	0.16
K37	0.62	0.65	0.28	0.31	0.32	0.09
(B) Step length and	step time symmetry inde	ex statistics				
Condition	Step length			Step time		
	Mean	Median	SD	Mean	Median	SD
NM	30.4	27.80	16.80	3.99	3.78	0.65
AM	29.80	24.5	19.04	3.57	3.76	0.51
K18	29.80	27.90	15.70	3.88	3.64	0.66
K37	31.40	32.10	15.30	3.96	3.81	0.76

NM condition: No-added mass; AM condition: Thigh mass increased 17%, shank mass decreased by 38%; K18 condition: The knee joint relocated downwards by 18% of the total shank length, shank mass decreased by 68%, thigh mass increased by 7%; K37 condition: The knee joint relocated downwards by 37% of the total shank length, shank mass decreased by 68%, thigh mass increased by 7%.

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