

## Two positive solutions for a nonlinear four-point boundary value problem with a $p$ -Laplacian operator \*

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**Abstract:** In this paper, we study the existence of positive solutions for a nonlinear four-point boundary value problem with a  $p$ -Laplacian operator. By using a three functionals fixed point theorem in a cone, the existence of double positive solutions for the nonlinear four-point boundary value problem with a  $p$ -Laplacian operator is obtained. This is different than previous results.

**Key words:**  $p$ -Laplacian operator; Positive solution; Fixed point theorem; Four-point boundary value problem

### 1. Introduction

In this paper we are interested in the existence of positive solutions for the following nonlinear four-point boundary value problem with a  $p$ -Laplacian operator:

$$(\phi_p(u'))' + e(t)f(u(t)) = 0, \quad 0 < t < 1, \quad (1.1)$$

$$\mu\phi_p(u(0)) - \omega\phi_p(u'(\xi)) = 0, \quad \rho\phi_p(u(1)) + \tau\phi_p(u'(\eta)) = 0. \quad (1.2)$$

where  $\phi_p(s)$  is a  $p$ -Laplacian operator, i.e.,  $\phi_p(s) = |s|^{p-2}s, p > 1, \phi_q = (\phi_p)^{-1}, \frac{1}{q} + \frac{1}{p} = 1, \mu > 0, \omega \geq 0, \rho > 0, \tau \geq 0, \xi, \eta \in (0, 1)$  is prescribed and  $\xi < \eta, e : (0, 1) \rightarrow [0, \infty), f : [0, +\infty) \rightarrow [0, +\infty)$ .

In recent years, because of the wide mathematical and physical background [1,2,12], the existence of positive solutions for nonlinear boundary value problems with  $p$ -Laplacian has received wide attention. There exists a very large number of papers devoted to the existence of solutions of the  $p$ -Laplacian operators with two or three-point boundary conditions, for example,

$$u(0) = 0, \quad u(1) = 0,$$

$$u(0) - B_0(u'(0)) = 0, \quad u(1) + B_1(u'(1)) = 0,$$

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$$\begin{aligned} u(0) - B_0(u'(0)) &= 0, & u'(1) &= 0, \\ u'(0) &= 0, & u(1) + B_1(u'(1)) &= 0, \end{aligned}$$

and

$$\begin{aligned} u(0) &= 0, & u(1) &= u(\eta), \\ u(0) - B_0(u'(\eta)) &= 0, & u(1) + B_1(u'(1)) &= 0, \\ u(0) - B_0(u'(0)) &= 0, & u(1) + B_1(u'(\eta)) &= 0, \\ au(r) - bp(r)u'(r) &= 0, & cu(R) + dp(R)u'(R) &= 0. \end{aligned}$$

For further knowledge, see [3-11,13]. The methods and techniques employed in these papers involve the use of Leray-Schauder degree theory [4], the upper and lower solution method [5], fixed point theorem in a cone [3,6-8,10,11,13], and the quadrature method [9]. However, there are several papers dealing with the existence of positive solutions for four-point boundary value problem [13-15,18].

Motivated by results in [14], this paper is concerned with the existence of two positive solutions of the boundary value problem (1.1)-(1.2). Our tool in this paper will be a new double fixed point theorem in a cone [11,16,17,19]. The result obtained in this paper is essentially different from the previous results in [14].

In the rest of the paper, we make the following assumptions:

(H1)  $f \in C([0, +\infty), [0, +\infty))$ ;

(H2)  $e(t) \in C((0, 1), [0, +\infty))$ , and  $0 < \int_0^1 e(t)dt < \infty$ . Moreover,  $e(t)$  does not vanish identically on any subinterval of  $(0, 1)$ .

Define

$$f_0 = \lim_{u \rightarrow 0^+} \frac{f(u)}{u^{p-1}}, \quad f_\infty = \lim_{u \rightarrow \infty} \frac{f(u)}{u^{p-1}}.$$

## 2. Some background definitions

In this section we provide some background material from the theory of cones in Banach space, and we state a two fixed point theorem due to Avery and Henderson [19].

If  $P \subset E$  is a cone, we denote the order induced by  $P$  on  $E$  by  $\leq$ . That is

$$x \leq y \text{ if and only if } y - x \in P.$$

**Definition 2.1** Given a cone  $P$  in a real Banach spaces  $E$ , a functional  $\psi : P \rightarrow R$  is said to be increasing on  $P$ , provided  $\psi(x) \leq \psi(y)$ , for all  $x, y \in P$  with  $x \leq y$ .

**Definition 2.2** Given a nonnegative continuous functional  $\gamma$  on a cone  $P$  of a real Banach space  $E$  (i.e.,  $\gamma : P \rightarrow [0, +\infty)$  continuous), we define, for each  $d > 0$ , the set

$$P(\gamma, d) = \{x \in P | \gamma(x) < d\}.$$

In order to obtain multiple positive solutions of (1.1)-(1.2), the following fixed point theorem of Avery and Henderson will be fundamental.

**Theorem 2.1** [19] *Let  $P$  be a cone in a real Banach space  $E$ . Let  $\alpha$  and  $\gamma$  be increasing, nonnegative continuous functional on  $P$ , and let  $\theta$  be a nonnegative continuous functional on  $P$  with  $\theta(0) = 0$  such that, for some  $c > 0$  and  $M > 0$ ,*

$$\gamma(x) \leq \theta(x) \leq \alpha(x), \quad \text{and} \quad \|x\| \leq M\gamma(x)$$

*for all  $x \in \overline{P(\gamma, c)}$ . Suppose there exist a completely continuous operator  $\Phi : \overline{P(\gamma, c)} \rightarrow P$  and  $0 < a < b < c$  such that*

$$\theta(\lambda x) \leq \lambda\theta(x) \quad \text{for} \quad 0 \leq \lambda \leq 1 \quad \text{and} \quad x \in \partial P(\theta, b),$$

*and*

- (i)  $\gamma(\Phi x) < c$ , for all  $x \in \partial P(\gamma, c)$ ,
- (ii)  $\theta(\Phi x) > b$  for all  $x \in \partial P(\theta, b)$ ,
- (iii)  $P(\alpha, a) \neq \emptyset$  and  $\alpha(\Phi x) < a$ , for  $x \in \partial P(\alpha, a)$ .

*Then  $\Phi$  has at least two fixed points  $x_1$  and  $x_2$  belonging to  $\overline{P(\gamma, c)}$  satisfying*

$$a < \alpha(x_1) \quad \text{with} \quad \theta(x_1) < b,$$

*and*

$$b < \theta(x_2) \quad \text{with} \quad \gamma(x_2) < c.$$

### 3. Existence of two positive solutions of (1.1)-(1.2)

In this section, by defining an appropriate Banach space and cones, we impose growth conditions on  $f$  which allow us to apply the above two fixed point theorem in establishing the existence of double positive solutions of (1.1)-(1.2). Firstly, we mention without proof several fundamental results.

**Lemma 3.1** [Lemma 2.1, 14]. *If condition (H2) holds, then there exists a constant  $\delta \in (0, \frac{1}{2})$  that satisfies*

$$0 < \int_{\delta}^{1-\delta} e(t)dt < \infty.$$

*Furthermore, the function:*

$$y_1(t) = \int_{\delta}^t \phi_q \left( \int_s^t e(r)dr \right) ds + \int_t^{1-\delta} \phi_q \left( \int_t^s e(r)dr \right) ds, \quad t \in [\delta, 1 - \delta],$$

*is a positive continuous function on  $[\delta, 1 - \delta]$ . Therefore  $y_1(t)$  has a minimum on  $[\delta, 1 - \delta]$ , so it follows that there exists  $L_1 > 0$  such that*

$$\min_{t \in [\delta, 1-\delta]} y_1(t) = L_1.$$

If  $E = C[0, 1]$ , then  $E$  is a Banach space with the norm  $\|u\| = \sup_{t \in [0,1]} |u(t)|$ . We note that, from the nonnegativity of  $e$  and  $f$ , a solution of (1.1)-(1.2) is nonnegative and concave on  $[0, 1]$ . Define

$$P = \{u \in E : u(t) \geq 0, u(t) \text{ is concave function, } t \in [0, 1]\}.$$

**Lemma 3.2** [Lemma 2.2, 14]. *Let  $u \in P$  and  $\delta$  be as Lemma 3.1, then*

$$u(t) \geq \delta \|u\|, \quad t \in [\delta, 1 - \delta].$$

**Lemma 3.3** [Lemma 2.3, 14]. *Suppose that conditions (H1), (H2) hold. Then  $u(t) \in E \cap C^2(0, 1)$  is a solution of boundary value problem (1.1)-(1.2) if and only if  $u(t) \in E$  is a solution of the following integral equation:*

$$u(t) = \begin{cases} \phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r)f(u(r))dr\right) + \int_0^t \phi_q\left(\int_s^{\sigma} e(r)f(u(r))dr\right)ds, & 0 \leq t \leq \sigma, \\ \phi_q\left(\frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r)f(u(r))dr\right) + \int_t^1 \phi_q\left(\int_{\sigma}^s e(r)f(u(r))dr\right)ds, & \sigma \leq t \leq 1, \end{cases}$$

where  $\sigma \in [\xi, \eta] \subset (0, 1)$  and  $u'(\sigma) = 0$ .

By means of the well known Guo-Krasnoselskii fixed point theorem in a cone, Su et al. [14] established the existence of at least one positive solution for (1.1)-(1.2) under some superlinear and sublinear assumptions imposed on the nonlinearity of  $f$ , which can be listed as

- (i)  $f_0 = 0$  and  $f_{\infty} = +\infty$  (superlinear), or
- (ii)  $f_0 = +\infty$  and  $f_{\infty} = 0$  (sublinear).

Using the same theorem, the authors also proved the existence of two positive solutions of (1.1)-(1.2) when  $f$  satisfies

- (iii)  $f_0 = f_{\infty} = 0$ , or
- (iv)  $f_0 = f_{\infty} = +\infty$ .

When  $f_0, f_{\infty} \notin \{0, +\infty\}$ , set

$$\theta^* = \frac{2}{L_1}, \quad \theta_* = \frac{1}{\left(1 + \phi_q\left(\frac{\omega}{\mu}\right)\right)\phi_q\left(\int_0^1 e(r)dr\right)},$$

and in the following, always assume  $\delta$  be as in Lemma 3.1, the existence of double positive solutions of boundary value problem (1.1)-(1.2) can be list as follows:

**Theorem 3.1** [Theorem 4.3, 14]. *Suppose that conditions (H1),(H2) hold. Also assume that  $f$  satisfies*

- (A1)  $f_0 = \lambda_1 \in \left[0, \left(\frac{\theta_*}{4}\right)^{p-1}\right)$ ;
- (A2)  $f_{\infty} = \lambda_2 \in \left[0, \left(\frac{\theta_*}{4}\right)^{p-1}\right)$ ;
- (A3)  $f(u) \leq (MR)^{p-1}, 0 \leq u \leq R$ ,

where  $M \in (0, \theta_*)$ . Then the boundary value problem (1.1)-(1.2) has at least two positive solutions  $u_1, u_2$  such that

$$0 < \|u_1\| < R < \|u_2\|.$$

**Theorem 3.2** [Theorem 4.4, 14]. *Suppose that conditions (H1),(H2) hold. Also assume that  $f$  satisfies*

- (A4)  $f_0 = \lambda_1 \in \left[\left(\frac{2\theta^*}{\delta}\right)^{p-1}, \infty\right)$ ;

- (A5)  $f_\infty = \lambda_2 \in \left[ \left( \frac{2\theta^*}{\delta} \right)^{p-1}, \infty \right)$ ;  
 (A6)  $f(u) \geq (mr)^{p-1}, \delta r \leq u \leq r$ ,

where  $m \in (\theta^*, \infty)$ . Then the boundary value problem (1.1)-(1.2) has at least two positive solutions  $u_1, u_2$  such that

$$0 < \|u_1\| < r < \|u_2\|.$$

When we see such a fact, we cannot but ask “Whether or not we can obtain a similar conclusion if neither  $f_0 \in \left[ \left( \frac{2\theta^*}{\delta} \right)^{p-1}, \infty \right)$  nor  $f_0 \in \left[ 0, \left( \frac{\theta^*}{4} \right)^{p-1} \right)$ .” Motivated by the above mentioned results, in this paper, we attempt to establish simple criteria for the existence of at least two positive solutions of (1.1)-(1.2). Our result is based on Theorem 2.1 and gives a positive answer to the question stated above.

Set

$$y_2(t) := \phi_q \left( \int_\delta^t e(r) dr \right) + \phi_q \left( \int_t^{1-\delta} e(r) dr \right), \quad \delta \leq t \leq 1 - \delta.$$

For notational convenience, we introduce the following constants:

$$L_2 = \min_{\delta \leq t \leq 1-\delta} y_2(t),$$

and

$$L_3 = \delta \phi_q \left( \int_0^1 e(r) dr \right) + \max \left\{ \phi_q \left( \frac{\omega}{\mu} \int_\xi^\eta e(r) dr \right), \phi_q \left( \frac{\tau}{\rho} \int_\xi^\eta e(r) dr \right) \right\},$$

$$Q = \phi_q \left( \int_0^1 e(r) dr \right) + \max \left\{ \phi_q \left( \frac{\omega}{\mu} \int_\xi^\eta e(r) dr \right), \phi_q \left( \frac{\tau}{\rho} \int_\xi^\eta e(r) dr \right) \right\}.$$

Finally, we define the nonnegative, increasing continuous functions  $\gamma, \theta$  and  $\alpha$  by

$$\gamma(u) = \min_{t \in [\delta, 1-\delta]} u(t),$$

$$\theta(u) = \frac{1}{2} [u(\delta) + u(1-\delta)], \quad \alpha(u) = \max_{0 \leq t \leq 1} u(t).$$

We observe here that, for every  $u \in P$ ,

$$\gamma(u) \leq \theta(u) \leq \alpha(u).$$

It follows from Lemma 3.2 that, for each  $u \in P$ , one has  $\gamma(u) \geq \delta \|u\|$ , so  $\|u\| \leq \frac{1}{\delta} \gamma(u)$ , for all  $u \in P$ . We also note that  $\theta(\lambda u) = \lambda \theta(u)$ , for  $0 \leq \lambda \leq 1$ , and  $u \in \partial P(\theta, b)$ .

The main result of this paper is as follows:

**Theorem 3.3** Assume that  $(H_1)$  and  $(H_2)$  hold, and suppose that there exist positive constants  $0 < a < b < c$  such that  $0 < a < \delta b < \frac{\delta^2 L_2}{2L_3} c$ , and  $f$  satisfies the following conditions

- (D1)  $f(v) < \phi_p \left( \frac{a}{Q} \right)$ , if  $0 \leq v \leq a$ ;  
 (D2)  $f(v) > \phi_p \left( \frac{2b}{\delta L_2} \right)$ , if  $\delta b \leq v \leq \frac{b}{\delta}$ ;  
 (D3)  $f(v) < \phi_p \left( \frac{c}{L_3} \right)$ , if  $0 \leq v \leq \frac{c}{\delta}$ ;

Then, the boundary value problem (1.1) and (1.2) has at least two positive solutions  $u_1$  and  $u_2$  such that

$$a < \max_{t \in [0,1]} u_1(t), \quad \text{with} \quad \frac{1}{2} [u_1(\delta) + u_1(1-\delta)] < b;$$

and

$$b < \frac{1}{2}[u_2(\delta) + u_2(1 - \delta)], \quad \text{with} \quad \min_{t \in [\delta, 1 - \delta]} u_2(t) < c.$$

**Proof.** We define the operator:  $\Phi : P \rightarrow P$ ,

$$(\Phi u)(t) := \begin{cases} \phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r)f(u(r))dr\right) + \int_0^t \phi_q\left(\int_s^{\sigma} e(r)f(u(r))dr\right)ds, & 0 \leq t \leq \sigma, \\ \phi_q\left(\frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r)f(u(r))dr\right) + \int_t^1 \phi_q\left(\int_{\sigma}^s e(r)f(u(r))dr\right)ds, & \sigma \leq t \leq 1, \end{cases}$$

for each  $u \in P$ , where  $\sigma \in [\xi, \eta] \subset (0, 1)$ . It is shown in Lemma 3.3 that the operator  $\Phi : P \rightarrow P$  is well defined with  $\|\Phi u\| = \Phi u(\sigma)$ . In particular, if  $u \in P(\gamma, c)$ , we also have  $\Phi u \in P$ , moreover, a standard argument shows that  $\Phi : P \rightarrow P$  is completely continuous (see [Lemma 2.4, 14]) and each fixed point of  $\Phi$  in  $P$  is a solution of (1.1)-(1.2).

We now show that the conditions of Theorem 2.1 are satisfied.

To fulfill property (i) of Theorem 2.2, we choose  $u \in \partial P(\gamma, c)$ , thus  $\gamma(u) = \min_{t \in [\delta, 1 - \delta]} u(t) = c$ . Recalling that  $\|u\| \leq \frac{1}{\delta}\gamma(u) = \frac{c}{\delta}$ , we have

$$0 \leq u(t) \leq \|u\| \leq \frac{1}{\delta}\gamma(u) = \frac{c}{\delta}, \quad 0 \leq t \leq 1.$$

Then assumption (D3) of Theorem 3.2 implies

$$f(u(t)) < \phi_p\left(\frac{c}{L_3}\right), \quad 0 \leq t \leq 1.$$

(i) If  $\sigma \in (0, \delta)$ , we have

$$\begin{aligned} \gamma(\Phi u) &= \min_{t \in [\delta, 1 - \delta]} (\Phi u)(t) = (\Phi u)(1 - \delta) \\ &= \phi_q\left(\frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r)f(u(r))dr\right) + \int_{1 - \delta}^1 \phi_q\left(\int_{\sigma}^s e(r)f(u(r))dr\right)ds \\ &\leq \phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)f(u(r))dr\right) + \int_{1 - \delta}^1 \phi_q\left(\int_0^1 e(r)f(u(r))dr\right)ds \\ &\leq \left[\phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)dr\right) + \delta\phi_q\left(\int_0^1 e(r)dr\right)\right] \cdot \frac{c}{L_3} < c. \end{aligned}$$

(ii) If  $\sigma \in [\delta, 1 - \delta]$ , we have

$$\begin{aligned} \gamma(\Phi u) &= \min_{t \in [\delta, 1 - \delta]} (\Phi u)(t) = \min\{(\Phi u)(\delta), (\Phi u)(1 - \delta)\} \\ &= \min\left\{\phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r)f(u(r))dr\right) + \int_0^{\delta} \phi_q\left(\int_s^{\sigma} e(r)f(u(r))dr\right)ds, \right. \\ &\quad \left.\phi_q\left(\frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r)f(u(r))dr\right) + \int_{1 - \delta}^1 \phi_q\left(\int_{\sigma}^s e(r)f(u(r))dr\right)ds\right\} \\ &\leq \max\left\{\phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\eta} e(r)f(u(r))dr\right) + \int_0^{\delta} \phi_q\left(\int_0^1 e(r)f(u(r))dr\right)ds, \right. \\ &\quad \left.\phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)f(u(r))dr\right) + \int_{1 - \delta}^1 \phi_q\left(\int_0^1 e(r)f(u(r))dr\right)ds\right\} \\ &< \left[\max\left\{\phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\eta} e(r)dr\right), \phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)dr\right)\right\} + \delta\phi_q\left(\int_0^1 e(r)dr\right)\right] \cdot \frac{c}{L_3} \\ &= c. \end{aligned}$$

(iii) If  $\sigma \in (1 - \delta, 1)$ , we have

$$\begin{aligned} \gamma(\Phi u) &= \min_{t \in [\delta, 1 - \delta]} (\Phi u)(t) = \Phi u(\delta) \\ &= \phi_q \left( \frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r) f(u(r)) dr \right) + \int_0^{\delta} \phi_q \left( \int_s^{\sigma} e(r) f(u(r)) dr \right) ds \\ &\leq \phi_q \left( \frac{\omega}{\mu} \int_{\xi}^{\eta} e(r) f(u(r)) dr \right) + \int_0^{\delta} \phi_q \left( \int_0^1 e(r) f(u(r)) dr \right) ds \\ &\leq \left[ \phi_q \left( \frac{\omega}{\mu} \int_{\xi}^{\eta} e(r) dr \right) + \delta \phi_q \left( \int_0^1 e(r) dr \right) \right] \cdot \frac{c}{L_3} \\ &< c. \end{aligned}$$

Therefore, condition (i) of Theorem 2.2 is satisfied.

We next address (ii) of Theorem 2.2. For this, we choose  $u \in \partial P(\theta, b)$  so that  $\theta(u) = \frac{1}{2}[u(\delta) + u(1 - \delta)] = b$ . Noting that

$$\|u\| \leq (1/\delta)\gamma(u) \leq (1/\delta)\theta(u) = b/\delta,$$

we have

$$\delta b < \delta \|u\| \leq u(t) \leq \frac{b}{\delta}, \quad \text{for } t \in [\delta, 1 - \delta].$$

Then (D2) yields

$$f(u(t)) > \phi_p \left( \frac{2b}{\delta L_2} \right), \quad \text{for } t \in [\delta, 1 - \delta].$$

As  $\Phi u \in P$ :

(i) If  $\sigma \in (0, \delta)$ , we have

$$\begin{aligned} \theta(\Phi u) &= \frac{1}{2}(\Phi u(\delta) + \Phi u(1 - \delta)) \geq \Phi u(1 - \delta) \\ &= \phi_q \left( \frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r) f(u(r)) dr \right) + \int_{1 - \delta}^1 \phi_q \left( \int_{\sigma}^s e(r) f(u(r)) dr \right) ds \\ &\geq \int_{1 - \delta}^1 \phi_q \left( \int_{\sigma}^{1 - \delta} e(r) f(u(r)) dr \right) ds \\ &\geq \int_{1 - \delta}^1 \phi_q \left( \int_{\delta}^{1 - \delta} e(r) f(u(r)) dr \right) ds \\ &= \delta \phi_q \left( \int_{\delta}^{1 - \delta} e(r) f(u(r)) dr \right) \\ &\geq \delta \phi_q \left( \int_{\delta}^{1 - \delta} e(r) dr \right) \cdot \frac{2b}{\delta L_2} \geq 2b > b. \end{aligned}$$

(ii) If  $\sigma \in [\delta, 1 - \delta]$ , we have

$$\begin{aligned} 2\theta(\Phi u) &= [\Phi u(\delta) + \Phi u(1 - \delta)] \\ &\geq \int_0^{\delta} \phi_q \left( \int_s^{\sigma} e(r) f(u(r)) dr \right) ds + \int_{1 - \delta}^1 \phi_q \left( \int_{\sigma}^s e(r) f(u(r)) dr \right) ds \\ &\geq \int_0^{\delta} \phi_q \left( \int_{\delta}^{\sigma} e(r) f(u(r)) dr \right) ds + \int_{1 - \delta}^1 \phi_q \left( \int_{\sigma}^{1 - \delta} e(r) f(u(r)) dr \right) ds \\ &= \delta \left[ \phi_q \left( \int_{\delta}^{\sigma} e(r) f(u(r)) dr \right) + \phi_q \left( \int_{\sigma}^{1 - \delta} e(r) f(u(r)) dr \right) \right] \\ &\geq \delta \left[ \phi_q \left( \int_{\delta}^{\sigma} e(r) dr \right) + \phi_q \left( \int_{\sigma}^{1 - \delta} e(r) dr \right) \right] \cdot \frac{2b}{\delta L_2} \\ &\geq 2b. \end{aligned}$$

(iii) If  $\sigma \in (1 - \delta, 1)$ , we have

$$\begin{aligned}
\theta(\Phi u) &= \frac{1}{2}(\Phi u(\delta) + \Phi u(1 - \delta)) \geq \Phi u(\delta) \\
&= \phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r)f(u(r))dr\right) + \int_0^{\delta} \phi_q\left(\int_s^{\sigma} e(r)f(u(r))dr\right)ds \\
&\geq \int_0^{\delta} \phi_q\left(\int_{\delta}^{1-\delta} e(r)f(u(r))dr\right)ds \\
&> \delta\phi_q\left(\int_{\delta}^{1-\delta} e(r)dr\right) \cdot \frac{2b}{\delta L_2} \geq 2b > b.
\end{aligned}$$

Hence, condition (ii) of Theorem 2.2 holds.

To fulfill property (iii) of Theorem 2.2, we note  $u_*(t) \equiv a/2, 0 \leq t \leq 1$ , is a member of  $P(\alpha, a)$  and  $\alpha(u_*) = a/2$ , so  $P(\alpha, a) \neq 0$ . Now, choose  $u \in \partial P(\alpha, a)$ , so that  $\alpha(u) = \max_{t \in [0,1]} u(t) = a$  and implies  $0 \leq u(t) \leq a, 0 \leq t \leq 1$ . It follows from assumption (D1),  $f(u(t)) \leq \phi_p(a/Q), t \in [0, 1]$ . As before we obtain

$$\begin{aligned}
\alpha(\Phi u) &= \|\Phi u\| = \Phi u(\sigma) \\
&= \phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\sigma} e(r)f(u(r))dr\right) + \int_0^{\sigma} \phi_q\left(\int_s^{\sigma} e(r)f(u(r))dr\right)ds \\
&= \phi_q\left(\frac{\tau}{\rho} \int_{\sigma}^{\eta} e(r)f(u(r))dr\right) + \int_{\sigma}^1 \phi_q\left(\int_{\sigma}^s e(r)f(u(r))dr\right)ds \\
&\leq \max\left\{\phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\eta} e(r)dr\right) + \phi_q\left(\int_0^1 e(r)dr\right), \right. \\
&\quad \left. \phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)dr\right) + \phi_q\left(\int_0^1 e(r)dr\right)\right\} \cdot \frac{a}{Q} \\
&\leq a.
\end{aligned}$$

Thus, condition (iii) of Theorem 2.1 is also satisfied. Consequently, an application of Theorem 2.1 completes the proof.  $\square$

Finally, we present an example to explain our result.

**Example.** Consider the boundary value problem (1.1)-(1.2) with

$$p = \frac{3}{2}, \mu = 2, \rho = \omega = 1, \xi = \frac{1}{4}, \eta = \frac{1}{2}, \tau = 1, \delta = \frac{1}{4}, e(t) = t^{-\frac{1}{2}},$$

and

$$f(u) = \begin{cases} \frac{6\sqrt{2u}}{40 + 1}, & 0 \leq u \leq 200, \\ \frac{67}{180} + \frac{1202}{335}(u - 200), & 200 \leq u \leq 250, \\ 180, & 250 < u, \end{cases}$$

Then (1.1)-(1.2) has at least two positive solutions.

**Proof.** In this example we have

$$L_1 = \min_{1/4 \leq x \leq 3/4} \left\{ \int_{1/4}^x \phi_q\left(\int_s^x t^{-1/2}dt\right)ds + \int_x^{3/4} \phi_q\left(\int_x^s t^{-1/2}dt\right)ds \right\} = \frac{3\sqrt{3} - 5}{9},$$

$$L_2 = \min_{1/4 \leq x \leq 3/4} \left( \phi_q\left(\int_{1/4}^x t^{-1/2}dt\right) + \phi_q\left(\int_x^{3/4} t^{-1/2}dt\right) \right) = 2 - \sqrt{3},$$

$$L_3 = \delta\phi_q\left(\int_0^1 e(r)dr\right) + \max\left\{\phi_q\left(\frac{\omega}{\mu} \int_{\xi}^{\eta} e(r)dr\right), \phi_q\left(\frac{\tau}{\rho} \int_{\xi}^{\eta} e(r)dr\right)\right\} = 4 - 2\sqrt{2},$$



$$Q = \phi_q\left(\int_0^1 e(r)dr\right) + \max\left\{\phi_q\left(\frac{\omega}{\mu}\int_\xi^\eta e(r)dr\right), \phi_q\left(\frac{\tau}{\rho}\int_\xi^\eta e(r)dr\right)\right\} = 7 - 2\sqrt{2}.$$

Let  $a = 80, b = 1000, c = 40000$ . Then we have

$$\begin{aligned} f(u) &= \frac{6\sqrt{2}u}{u+1} < \phi_p(a/Q), \quad \text{for } 0 \leq u \leq 80, \\ f(u) &= 180 > \phi_p((2b)/(\delta L_2)), \quad \text{for } 250 \leq u \leq 4000, \\ f(u) &= 180 < \phi_p(c/L_3), \quad \text{for } 0 \leq u \leq 160000. \end{aligned}$$

Therefore, by Theorem 3.3 we deduce that (1.1)-(1.2) has at least two positive solutions  $u_1$  and  $u_2$  satisfying

$$80 < \max_{t \in [0,1]} u_1(t), \quad \text{with } \frac{1}{2}[u_1(\delta) + u_1(1 - \delta)] < 1000;$$

and

$$1000 < \frac{1}{2}[u_2(\delta) + u_2(1 - \delta)], \quad \text{with } \min_{t \in [\delta, 1-\delta]} u_2(t) < 40000.$$

**Remark.** We notice that in the above example,  $f_0 = 6\sqrt{2} \approx 8.48528, (\frac{\theta_*}{4})^{p-1} = \frac{\sqrt{5}}{10} \approx 0.223607$  and  $(\frac{2\theta_*}{\delta})^{p-1} = 6\sqrt{10 + 6\sqrt{3}} \approx 27.0947$ . Therefore, Theorem 3.1 and Theorem 3.2 are not applicable to this example since conditions (A1) and (A4) fail.

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