# Existence of solutions of nonlinear differential equations with $\psi$-exponential or $\psi$-ordinary dichotomous linear part in a Banach space 

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#### Abstract

In this article we consider nonlinear differential equations with $\psi$-exponential and $\psi$-ordinary dichotomous linear part in a Banach space. By the help of the fixed point principle of Banach sufficient conditions are found for the existence of $\psi$-bounded solutions of these equations on $\mathbb{R}$ and $\mathbb{R}_{+}$.


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## 1 Introduction

The problem of $\psi$-boundedness and $\psi$-stability of the solutions of differential equations in finite dimensional Euclidean spaces has been studied by many auhtors, as e.g. Akinyele [1], Constantin [6]. In these papers, the function $\psi$ is a scalar continuous function (and increasing, differentiable and bounded in [1], nondecreasing and such that $\psi(t) \geq 1$ on $\mathbb{R}_{+}$in [6]). In Diamandescu [8-15] and Boi [2-4] $\psi$ is a nonnegative continuous diagonal matrix function.

Inspired by the famous monographs of Coppel [5], Daleckii and Krein [7] and Massera and Schaeffer [17], where the important notion of exponential and ordinary dichotomy is considered in detail, Diamandescu [8-12] and Boi [2-4] introduced and studied the $\psi$-dichotomy for linear differential equations in finite dimensional Euclidean space.

In our paper [16] we introduced the concept of $\psi$-dichotomy for arbitrary Banach spaces, where $\psi$ is an arbitrary bounded invertible linear operator.

In this paper nonlinear perturbed differential equations with $\psi$-dichotomous linear part are considered in an arbitrary Banach space. We will show that some properties of these equations will be influenced by the corresponding $\psi$-dichotomous homogeneous linear equation. Sufficient conditions for the existence of $\psi$-bounded solutions of this equations on $\mathbb{R}$ and $\mathbb{R}_{+}$in case of $\psi$-exponential or $\psi$-ordinary dichotomy are found.

[^0]
## 2 Preliminaries

Let $X$ be an arbitrary Banach space with norm $|\cdot|$ and identity $I$. Let $L B(X)$ be the space of all linear bounded operators acting in $X$ with the norm $\|\cdot\|$. By $J$ we shall denote $\mathbb{R}$ or $\mathbb{R}_{+}=[0, \infty)$.

We consider the nonlinear differential equation

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} t}=A(t) x+F(t, x) \tag{2.1}
\end{equation*}
$$

the corresponding linear homogenous equation

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} t}=A(t) x \tag{2.2}
\end{equation*}
$$

and the appropriate inhomogeneous equation

$$
\begin{equation*}
\frac{\mathrm{d} x}{\mathrm{~d} t}=A(t) x+f(t) \tag{2.3}
\end{equation*}
$$

where $A(\cdot): J \rightarrow L B(X), f(\cdot): J \rightarrow X$ are strongly measurable and Bochner integrable on the finite subintervals of $J$ and $F(\cdot, \cdot): J \times X \rightarrow X$ is a continuous function with respect to $t$.

By a solution of equation (2.1) (or (2.2) or (2.3)) we will understand a continuous function $x(t)$ that is differentiable (in the sence that it is representable in the form $x(t)=\int_{a}^{t} y(\tau) d \tau$ of a Bochner integral of a strongly measurable function $y$ ) and satisfies (2.1) (or (2.2) or (2.3)) almost everywhere.

By $V(t)$ we will denote the Cauchy operator of (2.2).
Let $R L(X)$ be the subspace of all invertible operators in $L B(X)$ and $\psi(\cdot): J \rightarrow R L(X)$ be continuous for any $t \in J$ operator-function.

Definition 2.1 ([16]). A function $u(\cdot): J \rightarrow X$ is said to be $\psi$-bounded on $J$ if $\psi(t) u(t)$ is bounded on $J$.

Let $C_{\psi}(X)$ denote the Banach space of all $\psi$-bounded and continuous functions with values in $X$ with the norm

$$
\left\|\|f\|_{C_{\psi}}=\sup _{t \in J}|\psi(t) f(t)| .\right.
$$

Definition 2.2 ( [16]). The equation (2.2) is said to have a $\psi$-exponential dichotomy on $J$ if there exist a pair of mutually complementary projections $P_{1}$ and $P_{2}=I-P_{1}$ and positive constants $N_{1}, N_{2}, v_{1}, v_{2}$ such that

$$
\begin{array}{ll}
\left\|\psi(t) V(t) P_{1} V^{-1}(s) \psi^{-1}(s)\right\| \leq N_{1} e^{-v_{1}(t-s)} & (s \leq t ; s, t \in J) \\
\left\|\psi(t) V(t) P_{2} V^{-1}(s) \psi^{-1}(s)\right\| \leq N_{2} e^{-v_{2}(s-t)} & (t \leq s ; s, t \in J) \tag{2.5}
\end{array}
$$

The equation (2.2) is said to have a $\psi$-ordinary dichotomy on $J$ if (2.4) and (2.5) hold with $v_{1}=v_{2}=0$.

Remark 2.3. For $\psi(t)=I$ for all $t \in J$ we obtain the notion of exponential and ordinary dichotomy in [5,7,17].

Let us introduce the principal Green function of (2.3) with the projections $P_{1}$ and $P_{2}$ from the definition for $\psi$-exponential dichotomy

$$
G(t, s)= \begin{cases}V(t) P_{1} V^{-1}(s) & (t>s ; t, s \in J)  \tag{2.6}\\ -V(t) P_{2} V^{-1}(s) & (t<s ; t, s \in J)\end{cases}
$$

Clearly $G$ is continuous except at $t=s$ where it has a jump discontinuity.
Definition 2.4. Let $r>0$ be an arbitrary number. We say that the conditions (H) are fulfilled if there exist positive functions $m(t), k(t)$ such that

H1. $|\psi(t) F(t, x)| \leq m(t) \quad(|\psi(t) x| \leq r, t \in J)$
H2. $\left|\psi(t)\left(F\left(t, x_{1}\right)-F\left(t, x_{2}\right)\right)\right| \leq k(t)\left|\psi(t)\left(x_{1}-x_{2}\right)\right| \quad\left(\left|\psi(t) x_{1}\right|,\left|\psi(t) x_{2}\right| \leq r, t \in J\right)$
Definition 2.5. The nonnegative function $m(t)$ is said to be integrally bounded on $J$ if the following inequality holds:

$$
B(m(t))=\sup _{t \in J} \int_{t}^{t+1} m(s) \mathrm{d} s<\infty .
$$

Definition 2.6. We say that the function $F(t, x)$ belongs to the class $E D_{\psi}\left(a_{1}, a_{2}, r\right)$ if the conditions (H) are fulfilled, the functions $m(t), k(t)$ are integrally bounded on $J$ and $B(m(t)) \leq$ $a_{1}, B(k(t)) \leq a_{2}$.

For each integrable on $J$ function $m(t)$ we introduce the notation

$$
L(m(t))=\int_{J} m(s) \mathrm{d} s
$$

Definition 2.7. We say that the function $F(t, x)$ belongs to the class $D_{\psi}\left(a_{1}, a_{2}, r\right)$ if the conditions $(\mathrm{H})$ are fulfilled, the functions $m(t), k(t)$ are integrable on $J$ and $L(m(t)) \leq a_{1}, L(k(t)) \leq a_{2}$.

## 3 Main results

Theorem 3.1. Let the following conditions be fulfilled:

1. The linear part of (2.1) has $\psi$-exponential dichotomy on $\mathbb{R}$ with projections $P_{1}$ and $P_{2}$.
2. The function $F(t, x)$ belongs to the class $E D_{\psi}\left(a_{1}, a_{2}, r\right)$.

Then for an arbitrary $r>0$ for sufficient small values of $a_{1}, a_{2}$ the equation (2.1) has a unique solution $x(t)$, which is defined for $t \in \mathbb{R}$ and for which $|\psi(t) x(t)| \leq r(t \in \mathbb{R})$.

Proof. Let $J=\mathbb{R}$. We consider in the space $C_{\psi}(X)$ the operator $Q: C_{\psi}(X) \rightarrow C_{\psi}(X)$ defined by the formula

$$
\begin{equation*}
Q x(t)=\int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau \tag{3.1}
\end{equation*}
$$

where $G$ is defined by (2.6).
Let $x(t)$ be a solution of equation (2.1) that remains for $t \in J$ in the ball

$$
S_{\psi, r}=\left\{x:\|x\|_{C_{\psi}} \leq r\right\} .
$$

Then the function $F(t, x(t))$ is $\psi$-bounded on $J$ and it follows (see [16, Theorem 3.6]) that such solution satisfies the integral equation

$$
\begin{equation*}
x(t)=Q x(t) . \tag{3.2}
\end{equation*}
$$

The converse is also true: a solution of the integral equation (3.2) which remains for $t \in J$ in the ball $S_{\psi, r}$ satisfies the differential equation (2.1) for $t \in J$.

Now we shall show that the ball $S_{\psi, r}$ is invariant with respect to $Q$ and the operator $Q$ is contracting.

First we shall prove that the operator $Q$ maps the ball $S_{\psi, r}$ into itself. Indeed we have

$$
|\psi(t) Q x(t)| \leq\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| .
$$

We have

$$
\begin{aligned}
|\psi(t) Q x(t)| \leq & \left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \\
\leq & \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
= & \int_{t \leq \tau}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
& +\int_{t \geq \tau}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
\leq & N_{2} \int_{t \leq \tau} e^{-v_{2}(\tau-t)} m(\tau) \mathrm{d} \tau+N_{1} \int_{t \geq \tau} e^{-v_{1}(t-\tau)} m(\tau) \mathrm{d} \tau \\
\leq & N_{2} \int_{s \geq 0} e^{-v_{2} s} m(t+s) \mathrm{d} s+N_{1} \int_{s \leq 0} e^{v_{1} s} m(t+s) \mathrm{d} s \\
\leq & N_{2} a_{1} \sum_{k=0}^{\infty} e^{-v_{2} k}+N_{1} a_{1} \sum_{k=0}^{\infty} e^{-v_{1} k}=\frac{N_{2} a_{1}}{1-e^{-v_{2}}}+\frac{N_{1} a_{1}}{1-e^{-v_{1}} .}
\end{aligned}
$$

Hence by $a_{1} \leq r\left(\frac{N_{2}}{1-e^{-v_{2}}}+\frac{N_{1}}{1-e^{-v_{1}}}\right)^{-1}$ we obtain

$$
\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \leq r
$$

Thus the operator $Q$ maps the ball $S_{\psi, r}$ into itself.
Now we shall prove that the operator $Q$ is a contraction in the ball $S_{\psi, r}$. Let $x_{1}, x_{2} \in S_{\psi, r}$. We obtain

$$
\begin{aligned}
\mid \psi(t) Q x_{1}(t) & -\psi(t) Q x_{2}(t)|\leq| \psi(t) \int_{J} G(t, \tau)\left(F\left(\tau, x_{1}(\tau)\right)-F\left(\tau, x_{2}(\tau)\right) \mathrm{d} \tau \mid\right. \\
& \leq \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\| \mid \psi(\tau)\left(F\left(\tau, x_{1}(\tau)\right)-F\left(\tau, x_{2}(\tau)\right) \mid \mathrm{d} \tau\right. \\
& \left.\leq \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\| k(\tau) \mid \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid \mathrm{d} \tau \\
& \left.\leq \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\| k(\tau) \mathrm{d} \tau \sup _{\tau \in J} \mid \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid \\
& \left.\left.\leq\left(\frac{N_{2} a_{2}}{1-e^{-v_{2}}}+\frac{N_{1} a_{2}}{1-e^{-v_{1}}}\right) \sup _{\tau \in J} \right\rvert\, \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid .
\end{aligned}
$$

Hence

$$
\left\|Q x_{1}-Q x_{2}\right\|_{C_{\psi}} \leq\left(\frac{N_{2} a_{2}}{1-e^{-v_{2}}}+\frac{N_{1} a_{2}}{1-e^{-v_{1}}}\right)\left\|x_{1}-x_{2}\right\|_{C_{\psi}}
$$

Thus by $a_{2}<\left(\frac{N_{2}}{1-e^{-v_{2}}}+\frac{N_{1}}{1-e^{-v_{1}}}\right)^{-1}$ the operator $Q$ is a contraction in the ball $S_{\psi, r}$.
From Banach's fixed point principle the existence of a unique fixed point of the operator $Q$ follows.

Corollary 3.2. If the conditions of Theorem 3.1 are fulfilled and if, moreover, $F(t, 0)=0(t \in \mathbb{R})$ then $x=0$ is a unique solution of (2.1) in $C_{\psi}(X)$.

Proof. Let $F(t, 0)=0(t \in \mathbb{R})$. Then from H 2 it follows

$$
|\psi(t) F(t, x(t))| \leq k(t)|\psi(t) x(t)| \quad(t \in \mathbb{R})
$$

Thus every solution $x(t)$ except $x(t) \equiv 0(t \in \mathbb{R})$ will leave any ball $S_{\psi, r_{1}}\left(r_{1}<r\right)$ by $t \rightarrow \infty$ or $t \rightarrow-\infty$.

Theorem 3.3. Let the following conditions be fulfilled:

1. The linear part of (2.1) has $\psi$-ordinary dichotomy on $\mathbb{R}$ with projections $P_{1}$ and $P_{2}$.
2. The function $F(t, x)$ belongs to the class $D_{\psi}\left(a_{1}, a_{2}, r\right)$.

Then for each $r>0$ for sufficient small values of $a_{1}, a_{2}$ the equation (2.1) has a unique solution $x(t)$, which is defined for $t \in \mathbb{R}$ and for which $|\psi(t) x(t)| \leq r(t \in \mathbb{R})$.

Proof. Let $J=\mathbb{R}$. In the proof of Theorem 3.1 it was mentioned that each solution $x(t)$ of equation (2.1) that remains for $t \in J$ in the ball $S_{\psi, r}$ satisfies the integral equation

$$
x(t)=\int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau
$$

and vice versa.
We consider again in the space $C_{\psi}(X)$ the operator $Q: C_{\psi}(X) \rightarrow C_{\psi}(X)$ defined in (3.1).
For $|\psi(t) Q x(t)|$ we obtain the following estimate:

$$
|\psi(t) Q x(t)| \leq\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right|
$$

With $a_{1} \leq r \max \left\{N_{1}, N_{2}\right\}$ we have

$$
\begin{aligned}
|\psi(t) Q x(t)| \leq & \left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \\
\leq & \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
= & \int_{t \leq \tau}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
& +\int_{t \geq \tau}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\||\psi(\tau) F(\tau, x(\tau))| \mathrm{d} \tau \\
\leq & N_{2} \int_{t \leq \tau} m(\tau) \mathrm{d} \tau+N_{1} \int_{t \geq \tau} m(\tau) \mathrm{d} \tau \\
\leq & \max \left\{N_{1}, N_{2}\right\} \int_{J} m(\tau) \mathrm{d} \tau \leq \max \left\{N_{1}, N_{2}\right\} a_{1} \leq r
\end{aligned}
$$

Thus the operator $Q$ maps the ball $S_{\psi, r}$ into itself.

Now we shall prove that the operator $Q$ is a contraction in the ball $S_{\psi, r}$. Let $x_{1}, x_{2} \in S_{\psi, r}$. We obtain

$$
\begin{aligned}
\mid \psi(t) Q x_{1}(t) & -\psi(t) Q x_{2}(t)|\leq| \psi(t) \int_{J} G(t, \tau)\left(F\left(\tau, x_{1}(\tau)\right)-F\left(\tau, x_{2}(\tau)\right) \mathrm{d} \tau \mid\right. \\
& \leq \int_{J}\left|\psi \psi(t) G(t, \tau) \psi^{-1}(\tau) \|\right| \psi(\tau)\left(F\left(\tau, x_{1}(\tau)\right)-F\left(\tau, x_{2}(\tau)\right) \mid \mathrm{d} \tau\right. \\
& \left.\leq \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\| k(\tau) \mid \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid \mathrm{d} \tau \\
& \left.\leq \int_{J}\left\|\psi(t) G(t, \tau) \psi^{-1}(\tau)\right\| k(\tau) \mathrm{d} \tau \sup _{\tau \in J} \mid \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid \\
& \left.\leq\left(\max \left\{N_{1}, N_{2}\right\} a_{2}\right) \sup _{\tau \in J} \mid \psi(\tau)\left(x_{1}(\tau)\right)-x_{2}(\tau)\right) \mid .
\end{aligned}
$$

Hence

$$
\left\|Q x_{1}-Q x_{2}\right\|_{C_{\psi}} \leq\left(a_{2} \max \left\{N_{1}, N_{2}\right\}\right)\left\|x_{1}-x_{2}\right\|_{C_{\psi}} .
$$

Thus by $a_{2}<\left(\max \left\{N_{1}, N_{2}\right\}\right)^{-1}$ the operator $Q$ is a contraction in the ball $S_{\psi, r}$.
From Banach's fixed point principle the existence of a unique fixed point of the operator $Q$ follows.

Theorem 3.4. Let the following conditions be fulfilled:

1. The linear part of (2.1) has $\psi$-exponential dichotomy on $\mathbb{R}_{+}$with projections $P_{1}$ and $P_{2}$.
2. The function $F(t, x)$ belongs to the class $E D_{\psi}\left(a_{1}, a_{2}, r\right)$.

Then for any $r>0$ by sufficient small $a_{1}, a_{2}$ there exists $\rho<r$ such that the equation (2.1) has for each $\xi \in X_{1}=P_{1} X$ with $|\psi(0) \xi| \leq \rho$ a unique solution $x(t)$ on $\mathbb{R}_{+}$for which $P_{1} x(0)=\xi$ and $|\psi(t) x(t)| \leq r\left(t \in \mathbb{R}_{+}\right)$.

Proof. Let $J=\mathbb{R}_{+}$and $x(t)$ be a solution of equation (2.1) that remains for $t \in J$ in the ball $S_{\psi, r}=\left\{x:\| \| x \|_{C_{\psi}} \leq r\right\}$. From the results obtained in [16, Theorem 3.6 and Remark 3.8] it follows that such $x(t)$ satisfies the integral equation

$$
\begin{equation*}
x(t)=V(t) \xi+\int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau \tag{3.3}
\end{equation*}
$$

where $\xi=P_{1} x(0)$. The converse is also true: a solution of the integral equation (3.3) satisfies the differential equation (2.1) for $t \in J$.

Let $\xi \in X_{1}$ and $|\psi(0) \xi| \leq \rho<r$. We consider in the space $C_{\psi}(X)$ the operator $Q: C_{\psi}(X) \rightarrow$ $C_{\psi}(X)$ defined by the formula

$$
\begin{equation*}
Q x(t)=V(t) \xi+\int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau \tag{3.4}
\end{equation*}
$$

First we shall prove, that the operator $Q$ maps the ball $S_{\psi, r}$ into itself. Indeed we have

$$
|\psi(t) Q x(t)| \leq|\psi(t) V(t) \xi|+\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| .
$$

For the first addend with $\rho \leq \frac{r}{2 N_{1}}$ we obtain

$$
|\psi(t) V(t) \xi| \leq N_{1} e^{-v_{1} t}|\psi(0) \xi| \leq N_{1} e^{-v_{1} t} \rho \leq \frac{r}{2} .
$$

Using the same technique and notations as in the proof of Theorem 3.1 we obtain for the second addend the estimate

$$
\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \leq \frac{N_{2} a_{1}}{1-e^{-v_{2}}}+\frac{N_{1} a_{1}}{1-e^{-v_{1}}}
$$

Hence by $a_{1} \leq \frac{r}{2}\left(\frac{N_{2}}{1-e^{-v_{2}}}+\frac{N_{1}}{1-e^{-v_{1}}}\right)^{-1}$ we obtain

$$
\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \leq \frac{r}{2}
$$

Thus the operator $Q$ maps the ball $S_{\psi, r}$ into itself.
Now we shall prove that the operator $Q$ is a contraction in the ball $S_{\psi, r}$. Let $x_{1}, x_{2} \in S_{\psi, r}$. We obtain as in the proof of Theorem 3.1 the estimate

$$
\left\|\left\|Q x_{1}-Q x_{2}\right\|_{C_{\psi}} \leq\left(\frac{N_{2} a_{2}}{1-e^{-v_{2}}}+\frac{N_{1} a_{2}}{1-e^{-v_{1}}}\right)\right\| x_{1}-x_{2} \|_{C_{\psi}}
$$

By $a_{2}<\left(\frac{N_{2}}{1-e^{-v_{2}}}+\frac{N_{1}}{1-e^{-v_{1}}}\right)^{-1}$ the operator $Q$ is a contraction in the ball $S_{\psi, r}$.
From Banach's fixed point principle the existence of a unique fixed point of the operator $Q$ follows.

Theorem 3.5. Let the following conditions be fulfilled:

1. The linear part of (2.1) has $\psi$-ordinary dichotomy on $\mathbb{R}_{+}$with projections $P_{1}$ and $P_{2}$.
2. The function $F(t, x)$ belongs to the class $D_{\psi}\left(a_{1}, a_{2}, r\right)$.

Then for any $r>0$ by sufficiently small $a_{1}, a_{2}$ there exists $\rho<r$ such that the equation (2.1) has for each $\xi \in X_{1}=P_{1} X$ with $|\psi(0) \xi| \leq \rho$ a unique solution $x(t)$ on $\mathbb{R}_{+}$for which $P_{1} x(0)=\xi$ and $|\psi(t) x(t)| \leq r\left(t \in \mathbb{R}_{+}\right)$.

Proof. Let $J=\mathbb{R}_{+}, \xi \in X_{1}$ and $|\psi(0) \xi| \leq \rho<r$. We consider again in the space $C_{\psi}(X)$ the operator $Q: C_{\psi}(X) \rightarrow C_{\psi}(X)$ defined by the formula (3.4).

First we shall prove, that the operator $Q$ maps the ball $S_{\psi, r}$ into itself. We have

$$
|\psi(t) Q x(t)| \leq|\psi(t) V(t) \xi|+\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right|
$$

For the first addend with $\rho \leq \frac{r}{2 N_{1}}$ we obtain

$$
|\psi(t) V(t) \xi| \leq N_{1}|\psi(0) \xi| \leq N_{1} \rho \leq \frac{r}{2}
$$

For the second addend with $a_{1} \leq \frac{r}{2 \max \left\{N_{1}, N_{2}\right\}}$ as in the proof of Theorem 3.3 we have

$$
\left|\psi(t) \int_{J} G(t, \tau) F(\tau, x(\tau)) \mathrm{d} \tau\right| \leq \max \left\{N_{1}, N_{2}\right\} a_{1} \leq \frac{r}{2}
$$

Thus the operator $Q$ maps the ball $S_{\psi, r}$ into itself.
Let $x_{1}, x_{2} \in S_{\psi, r}$. As in the proof of Theorem 3.3 we obtain the estimate

$$
\left\|Q x_{1}-Q x_{2}\right\|_{C_{\psi}} \leq\left(a_{2} \max \left\{N_{1}, N_{2}\right\}\right) \mid\left\|x_{1}-x_{2}\right\|_{C_{\psi}} .
$$

Hence by $a_{2}<\left(\max \left\{N_{1}, N_{2}\right\}\right)^{-1}$ the operator $Q$ is a contraction in the ball $S_{\psi, r}$.

From the fixed point principle of Banach it follows the existence of a unique fixed point of the operator $Q$.

In the proof of Theorem 3.4 it was already mentioned that every solution of the differential equation (2.1) which lies in the ball $S_{\psi, r}$ fulfil the equality

$$
x(t)=Q x(t)
$$

and vice versa.
Corollary 3.6. Let the conditions of Theorem 3.5 hold and let $x_{1}(t)$ and $x_{2}(t)$ be two solutions whose initial values fulfil $P_{1} x_{1}(0)=\xi$ and $P_{1} x_{2}(0)=\eta$. Let $N=\max \left\{N_{1}, N_{2}\right\}$.

Then for $N a_{2}<1$ the following estimate holds

$$
\left|\psi(t)\left(x_{1}(t)-x_{2}(t)\right)\right| \leq \frac{N}{1-N a_{2}}|\psi(0)(\xi-\eta)| \quad\left(t \in \mathbb{R}_{+}\right)
$$

Proof. Applying the presentation (3.3) for the solutions $x_{1}$ and $x_{2}$ we obtain

$$
x_{1}(t)-x_{2}(t)=V(t)(\xi-\eta)+\int_{0}^{\infty} G(t, \tau)\left(F\left(\tau, x_{1}(\tau)\right)-F\left(\tau, x_{2}(\tau)\right)\right) \mathrm{d} \tau
$$

From here and the conditions of Theorem 3.5 for $u(t)=\psi(t)\left(x_{1}(t)-x_{2}(t)\right)$ we obtain

$$
|u(t)| \leq N|\psi(0)(\xi-\eta)|+N \int_{0}^{\infty} k(\tau) u(\tau) \mathrm{d} \tau
$$

Let us consider the equation

$$
\begin{equation*}
u(t)=\alpha+N \int_{0}^{\infty} k(\tau) u(\tau) \mathrm{d} \tau \tag{3.5}
\end{equation*}
$$

where $\alpha=N|\psi(0)(\xi-\eta)|$. Let us introduce the functional $\Phi: C \rightarrow \mathbb{R}_{+}$, where $C$ is the space of all bounded functions on $\mathbb{R}_{+}$with values in $\mathbb{R}_{+}$by the formula

$$
(\Phi u)(t)=N \int_{0}^{\infty} k(\tau) u(\tau) \mathrm{d} \tau
$$

For the norm of $\Phi$ we obtain the estimate

$$
\|\Phi\| \leq N \int_{0}^{\infty} k(\tau) \mathrm{d} \tau \leq N a_{2}
$$

For sufficiently small $a_{2}$ we have $\|\Phi\| \leq 1$.
Let $I_{C}$ be the identity of the space $C$. Then the equation $\left(I_{C}-\Phi\right) u=\alpha$ has a bounded solution $u(t)$, i.e. there exists a constant $c=\sup _{t \in \mathbb{R}_{+}}|u(t)|<\infty$. We shall estimate the constant $c$ from equation (3.5):

$$
c \leq \alpha+N c \int_{0}^{\infty} k(\tau) \mathrm{d} \tau \leq \alpha+N c a_{2}
$$

i.e.

$$
c \leq \frac{\alpha}{1-N a_{2}}
$$

Finally we obtain

$$
\left|\psi(t)\left(x_{1}(t)-x_{2}(t)\right)\right| \leq \frac{N|\psi(0)(\xi-\eta)|}{1-N a_{2}}
$$

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