

# Rate of approach to the steady state for a diffusion-convection equation on annular domains\*

Liping Zhu<sup>†</sup> and Zhengce Zhang<sup>‡</sup>

## Abstract

In this paper, we study the asymptotic behavior of global solutions of the equation  $u_t = \Delta u + e^{|\nabla u|}$  in the annulus  $B_{r,R}$ ,  $u(x, t) = 0$  on  $\partial B_r$  and  $u(x, t) = M \geq 0$  on  $\partial B_R$ . It is proved that there exists a constant  $M_c > 0$  such that the problem admits a unique steady state if and only if  $M \leq M_c$ . When  $M < M_c$ , the global solution converges in  $C^1(\overline{B_{r,R}})$  to the unique regular steady state. When  $M = M_c$ , the global solution converges in  $C(\overline{B_{r,R}})$  to the unique singular steady state, and the blowup rate in infinite time is obtained.

**Keywords:** Convergence, Steady state, Gradient blowup.

## 1 Introduction and main results

In this paper we consider the problem

$$\begin{cases} u_t = \Delta u + e^{|\nabla u|}, & x \in B_{r,R}, t > 0, \\ u(x, t) = 0, & x \in \partial B_r, t > 0, \\ u(x, t) = M, & x \in \partial B_R, t > 0, \\ u(x, 0) = u_0(x), & x \in B_{r,R}. \end{cases} \quad (1.1)$$

Here  $r > 0$ ,  $B_{r,R} = \{x \in \mathbb{R}^N; r < |x| < R\}$ ,  $\partial B_r = \{x \in \mathbb{R}^N; |x| = r\}$ ,  $M \geq 0$ , and  $u_0(x) \in X$ , where  $X = \{v \in C^1(\overline{B_{r,R}}); v|_{\partial B_r} = 0, v|_{\partial B_R} = M\}$ , endowed with the  $C^1$  norm. Problem (1.1) admits a unique maximal classical solution

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<sup>†</sup>College of Science, Xi'an University of Architecture & Technology, Xi'an, 710054, P. R. China, E-mail: ny.zlp@stu.xjtu.edu.cn.

<sup>‡</sup>Corresponding author, School of Mathematics and Statistics, Xi'an Jiaotong University, Xi'an, 710049, P. R. China, E-mail: zhangzc@mail.xjtu.edu.cn.

$u(x, t)$ , whose existence time will be denoted by  $T = T(u_0) > 0$ , such that  $u \in C^{2,1}(\overline{B_{r,R}} \times (0, T)) \cap C^{1,0}(\overline{B_{r,R}} \times [0, T])$ .

The differential equation in (1.1) possesses both mathematical and physical interest. This equation arises in the viscosity approximation of Hamilton-Jacobi type equations from stochastic control theory [2] and in some physical models of surface growth [4].

On the other hand, it can serve as a typical model-case in the theory of parabolic PDEs. Indeed, it is the one of the simplest examples (along with Burger's equation) of a parabolic equation with a nonlinearity depending on the first-order spatial derivatives of  $u$ .

A basic fact about (1.1) is that the solutions satisfy a maximum principle:

$$\min_{\overline{B_{r,R}}} u_0 \leq u(x, t) \leq \max_{\overline{B_{r,R}}} u_0, \quad x \in \overline{B_{r,R}}, \quad 0 \leq t < T. \quad (1.2)$$

Since Problem (1.1) is well-posed in  $C^1$  locally in time, only three possibilities can occur:

(I)  $u$  exists globally and is bounded in  $C^1$ :

$$T = \infty \quad \text{and} \quad \sup_{t \geq 0} \|\nabla u(t)\|_\infty < \infty;$$

(II)  $u$  blows up in finite time in  $C^1$  norm (finite time gradient blowup):

$$T < \infty \quad \text{and} \quad \lim_{t \rightarrow T} \|\nabla u(t)\|_\infty = \infty;$$

(III)  $u$  exists globally but is unbounded in  $C^1$  (infinite time gradient blowup):

$$T = \infty \quad \text{and} \quad \limsup_{t \rightarrow \infty} \|\nabla u(t)\|_\infty = \infty.$$

For  $M = 0$  and  $\|u_0\|_{C^1}$  sufficiently small, it is known that (I) occurs and  $u$  converges to the unique steady state  $S_0 \equiv 0$ . On the contrary, if  $u_0$  suitably large, (II) occurs (see [5] and [8]).

For  $M > 0$ , the situation is slightly more complicated. There exists a critical value  $M_c$  (see Section 2 below for its existence) such that (1.1) has a unique, regular and radial ( $S_M(x) = S_M(\rho)$  with  $\rho = |x|$ ) steady state  $S_M$  if  $M < M_c$  and no steady state if  $M > M_c$ . For the critical case  $M = M_c$ , there still exists a radial steady state  $S_{M_c}$ , but it is singular, satisfying  $S_{M_c} \in C([r, R]) \cap C^\infty((r, R])$  with  $S_{M_c, \rho} = \infty$ .

For one dimensional case (see [8]), it was proved among other things that, if  $M > M_c$ , then all solutions of (1.1) satisfy (II), and if  $0 < M < M_c$ , then both

(I) and (II) can occur. Moreover, in [9], it was shown that if  $0 \leq M < M_c$ , then all global solutions of (1.1) are bounded in  $C^1$ , and they converge to  $S_M$  in  $C^1$ . If (II) occurs, with the assumption on the initial data so that the solution is monotonically increasing both in time and in space, Zhang and Hu in [8] studied the blowup estimate and obtained that the blowup rate is close to  $\ln \frac{1}{T-t}$  but not exactly equal to  $\ln \frac{1}{T-t}$ , which is very interesting because the blowup estimate can not be predicted by the usual self-similar transformations. For  $N(> 1)$  dimensional and zero-Dirichlet problem, in [10], Zhang and Li considered the gradient estimate near the boundary and the blowup rate of the radial case.

The purpose of this paper is to extend the results of [5, 8, 9, 10] to Problem (1.1), i.e., if  $M = M_c$  and  $u_0 \leq S_{M_c}$ , then (III) occurs and,  $u$  converges in  $C(\overline{B_{r,R}})$  exponentially to  $S_{M_c}$ , as well as  $u_\rho(r, t)$  grows up exponentially to infinity. Therefore, we provide a classification of large time behavior of the solutions of (1.1) for arbitrary spatial dimension. Our main results are as follows:

**Theorem 1.1** (1) *If  $0 \leq M < M_c$ , then all global solutions of (1.1) converges in  $C(\overline{B_{r,R}})$  to  $S_M$ . Moreover, if  $u_0 \leq S_M$ , then the solution of (1.1) is global in time and converges in  $C^1(\overline{B_{r,R}})$  to  $S_M$ , and we have the uniform exponential convergence*

$$\lim_{t \rightarrow \infty} \frac{\ln |U(\cdot) - u(\cdot, t)|}{t} = -\lambda_1,$$

where  $\lambda_1$  is the first eigenvalue of (3.2) (see Section 3 below).

(2) *If  $M = M_c$ , then all global solutions of (1.1) converge in  $C(\overline{B_{r,R}})$  to  $S_M$ . Moreover, if  $u_0 \leq S_M$ , then the solution of (1.1) is global in time and converges in  $C^1(\overline{B_{r,R}})$  to  $S_M$ , and we have the uniform exponential convergence*

$$\lim_{t \rightarrow \infty} \frac{\ln |U(\cdot) - u(\cdot, t)|}{t} = -\lambda_1,$$

as well as the blowup estimate

$$\lim_{t \rightarrow \infty} \frac{u_\nu(x, t)}{t} = \lambda_1, \quad x \in \partial B_r,$$

where  $\lambda_1$  is the first eigenvalue of (4.1) (see Section 4 below).

## 2 Stationary states and global existence

From the maximum principle, if Problem (1.1) admits a steady state  $S_M(x)$ , then it is unique and radial, and if  $M_1 > M_2$ , then  $S_{M_1} > S_{M_2}$  in  $(r, R]$ . So the stationary state satisfies

$$\begin{cases} -S_{M,\rho\rho} - \frac{N-1}{\rho} S_{M,\rho} = e^{S_{M,\rho}}, & r < \rho < R, \\ S_M(r) = 0, \quad S_M(R) = M. \end{cases} \quad (2.1)$$

For  $M > 0$ , from the existence theory of ODEs, we know that  $S_{M,\rho} > 0$  in  $(r, R]$ . Then  $S_{M,\rho}$  satisfies  $e^{S_{M,\rho}} \leq -S_{M,\rho} \leq ce^{S_{M,\rho}}$  in  $(r, R]$ , where  $c > 1$  is some constant. We consider a special case where  $S_{M,\rho}(r) = \infty$ , so we have

$$\ln \frac{1}{c(\rho - r)} \leq S_{M,\rho}(\rho) \leq \ln \frac{1}{\rho - r},$$

from which we get

$$(\rho - r) \left( 1 + \ln \frac{1}{c(\rho - r)} \right) \leq S_M(\rho) \leq (\rho - r) \left( 1 + \ln \frac{1}{\rho - r} \right). \quad (2.2)$$

So we can deduce that there exists  $M_c > 0$  such that if  $M > M_c$ , then Problem (1.1) does not admit a steady state, if  $0 < M < M_c$ , then Problem (1.1) admits a unique regular steady state  $S_M \in C^2([r, R])$ , and if  $M = M_c$ , then Problem (1.1) still admits a steady state  $S_{M_c} \in C([r, R]) \cap C^2((r, R])$ , which is singular in the sense that it has infinite derivative on the boundary  $\partial B_r$ .

**Theorem 2.1** *Assume that  $M \geq 0$ . If  $u$  is a global solution of Problem (1.1), then*

- (1) *Problem (1.1) admits a steady state  $S_M$  satisfying (2.1);*
- (2)  *$u(\cdot, t) \rightarrow S_M(\cdot)$  in  $C(\overline{B_{r,R}})$  as  $t \rightarrow \infty$ .*

**Proof.** (1) Let  $\chi(\rho)$  be the solution of

$$-\Delta \chi = 1, \quad r < \rho < R; \quad \chi(r) = 0, \quad \chi(R) = M, \quad (2.3)$$

and  $\kappa(\rho)$  be the solution of

$$-\Delta \kappa = 1, \quad r < \rho < R; \quad \kappa(r) = \kappa(R) = 0. \quad (2.4)$$

Set  $\underline{u}_0 = -\chi - \mu\kappa$ , then since  $u_0 \in C^1(\overline{B_{r,R}})$ , we have  $\underline{u}_0 \leq u_0$  in  $B_{r,R}$  if  $\mu > 0$  is suitably large, which implies that  $\underline{u} \leq u$  in  $B_{r,R} \times (0, \infty)$ . Moreover,  $\Delta \underline{u}_0 + e^{|\nabla \underline{u}_0|} \geq \mu + 1 > 0$ . So by the maximum principle, we have  $\underline{u}_t \geq 0$  in  $B_{r,R}$  for all  $t > 0$ . As a consequence, there exists a function  $S_M \in \overline{B_{r,R}}$  such that for all  $x \in B_{r,R}$ ,  $\underline{u}(x, t) \rightarrow S_M(x)$  as  $t \rightarrow \infty$ . Similar to the proof of [7, Theorem 3.2] or [10, Theorem 3.1], we have

$$|\nabla \underline{u}| \leq C \ln \frac{1}{\delta(x)} \quad \text{in } B_{r,R} \times (0, \infty),$$

where  $\delta(x) = \text{dist}(x, \partial B_{r,R})$ . Parabolic estimates imply that for any small  $\varepsilon > 0$ , for some  $0 < \alpha < 1$ , there holds

$$\|\underline{u}\|_{C^{2+\alpha, 1+\alpha/2}(\overline{B_{r+\varepsilon, R-\varepsilon}} \times [t, t+1])} \leq C(\varepsilon), \quad t > 0.$$

By the diagonal procedure, there exists a sequence  $t_n \rightarrow \infty$  such that  $\underline{u}_{t_n} = \underline{u}(x, t_n + t)$  converges in  $C_{loc}^{2,1}(\overline{B_{r,R}} \times [0, 1])$  to  $S_M(x)$ . So  $S_M(x) \in C^2(B_{r,R}) \cap C(\overline{B_{r,R}})$  is the unique steady state of Problem (1.1).

(2) Define  $w(t) = u(t) - S_M$ ,  $\phi(t) = \|w(t)\|_\infty$ . It follows from [7] that  $\phi(t)$  is non-increasing for all  $t > 0$ . Set

$$l = \lim_{t \rightarrow \infty} \phi(t) \in [0, \infty).$$

We know that

$$|\nabla u| \leq C \ln \frac{1}{\delta(x)}, \quad |u(x, t)| \leq \widehat{C} \delta(x) \left( \ln \frac{1}{\delta(x)} + 1 \right) + \widetilde{C} \quad \text{in } B_{r,R} \times [0, \infty). \quad (2.5)$$

Choose a sequence  $t_n \rightarrow \infty$  and set  $u_n(\cdot, t_n + \cdot)$  and  $f_n(\cdot, \cdot) = f(\cdot, t_n + \cdot)$ , where  $f(x, t) = e^{|\nabla u|}$ . Then the functions  $u_n$  then satisfy  $\partial_t u_n - \Delta u_n = f_n(x, t)$  in  $Q := B_{r,R} \times (0, \infty)$ , with the sequence  $f_n(\cdot, t)$  and  $u_n(\cdot, t)$  bounded in  $L_{loc}^\infty(Q)$  for  $t > 0$ . Theorem 1.1 in [7] implies that  $\nabla u_n$  is bounded in  $C_{loc}^{\beta, \beta/2}(Q)$  for some  $0 < \beta < 1$ . Using local parabolic Schauder estimates, we obtain that  $u_n$  is bounded in  $C_{loc}^{2+\gamma, 1+\gamma/2}(Q)$  for some  $0 < \gamma < 1$ . Therefore,  $u_n$  converges in  $C_{loc}^{2,1}(Q)$  to a function  $z \in C^{2,1}(Q)$ , which solves

$$z_t - \Delta z = e^{|\nabla z|} \quad \text{in } Q.$$

Moreover, (2.5) implies that  $\{u(\tau); \tau \geq 0\}$  is relatively compact in  $C(\overline{Q})$ . For each fixed  $t \geq 0$ , we may thus find a subsequence  $n_k$  such that  $u_{n_k}(t)$  converges to  $z(t)$  in  $C(\overline{Q})$ . It follows that

$$z(t) \in C(\overline{Q}) \quad \text{and} \quad \|z(t) - S_M\|_\infty = \lim_{k \rightarrow \infty} \|u(t_{n_k} + t) - S_M\|_\infty = l, \quad t \geq 0.$$

Setting  $\widetilde{w}(t) := z(t) - S_M$ , then  $\widetilde{w}(t)$  satisfies

$$\widetilde{w}_t - \Delta \widetilde{w} = \widetilde{b}(x, t) \cdot \nabla \widetilde{w} \quad \text{in } Q,$$

where  $\widetilde{b}(x, t) = \int_0^1 e^{|\nabla S_M + s \nabla \widetilde{w}|} \frac{\nabla S_M + s \nabla \widetilde{w}}{|\nabla S_M + s \nabla \widetilde{w}|} ds \in C(Q)$ . Assume for contradiction that  $l > 0$ . Since  $\widetilde{w}(\cdot, 2) \in C_0(\overline{B_{r,R}})$ , there exists  $x_0 \in B_{r,R}$ , such that  $|\widetilde{w}(x_0, 2)| = \|\widetilde{w}(\cdot, 2)\|_\infty = l = \|\widetilde{w}\|_{L^\infty(B_{r,R})}$ . For each  $\rho < \delta(x_0)$ , since  $\widetilde{b} \in L^\infty(B(x_0, \rho) \times (1, 2))$ , we may apply the strong maximum principle to deduce that  $|\widetilde{w}| = l$  in  $B(x_0, \rho) \times [1, 2]$ . But by letting  $\rho \rightarrow \delta(x_0)$ , this contradicts  $\widetilde{w}(\cdot, 2) \in C_0(\overline{B_{r,R}})$ . Therefore,  $l = 0$ . Since the sequence  $t_n$  was arbitrary, we conclude that  $\lim_{t \rightarrow \infty} \|u(t) - S_M\|_\infty = 0$ , and the assertion (2) is proved.

### 3 Subcritical case $M < M_c$

In this section, we assume that  $u_0 \leq S_M$  in  $B_{r,R}$ . By the maximum principle, we have  $-\chi - \mu\kappa \leq u \leq S_M$  for  $t < T$ , where  $\mu$  is a suitably large constant. Similar to the proof of [7, Theorem 3.2] or [10, Theorem 3.1], we can get that  $\nabla u$  blows up only on the boundary. So  $u$  exists globally and  $\nabla u$  is uniformly

bounded in  $B_{r,R} \times [0, \infty)$ . So standard arguments imply that  $u(\cdot, t) \rightarrow S_M(\cdot)$  as  $t \rightarrow \infty$ .

We consider the eigenvalue problem

$$\begin{cases} -\varphi_{\rho\rho} - \frac{N-1}{\rho}\varphi_{\rho} - e^{S_{M,\rho}}\varphi_{\rho} = \lambda\varphi, & r < \rho < R, \\ \varphi(r) = \varphi(R) = 0. \end{cases} \quad (3.1)$$

By (2.1), we get

$$e^{S_{M,\rho}} = -S_{M,\rho\rho} - \frac{N-1}{\rho}S_{M,\rho}.$$

So Equation (3.1) can be written as

$$-\varphi_{\rho\rho} + \left( S_{M,\rho\rho} + \frac{N-1}{\rho}S_{M,\rho} - \frac{N-1}{\rho} \right) \varphi_{\rho} = \lambda\varphi.$$

It is equivalent to

$$-(a(\rho)\varphi_{\rho})_{\rho} = \lambda a(\rho)\varphi, \quad r < \rho < R; \quad \varphi(r) = \varphi(R) = 0, \quad (3.2)$$

where  $a(\rho)$  satisfies

$$\frac{a'(\rho)}{a(\rho)} = -S_{M,\rho\rho} - \frac{N-1}{\rho}S_{M,\rho} + \frac{N-1}{\rho}.$$

Let  $\varphi(\rho)$  be the first eigenfunction and  $\lambda_1$  be the corresponding eigenvalue.

Let  $\underline{u}$  be the (global) solution of (1.1) with  $-\chi - \mu\kappa$  as the initial data for some  $\mu > 0$  such that  $-\chi - \mu\kappa \leq u_0$ . By the comparison principle, we get  $\underline{u} \leq u$ . Therefore  $S_M - u \leq \underline{v} := S_M - \underline{u}$ . Since  $\underline{u}$  is radially symmetric, then, by Taylor's expansion up to second order, we obtain

$$\begin{aligned} \underline{v}_t - \underline{v}_{\rho\rho} - \frac{N-1}{\rho}\underline{v}_{\rho} &= e^{S_{M,\rho}} - e^{\underline{u}_{\rho}} \\ &= e^{S_{M,\rho}} - e^{S_{M,\rho} - \underline{v}_{\rho}} \\ &= e^{S_{M,\rho}}\underline{v}_{\rho} - F(x, \underline{v}_{\rho}), \end{aligned} \quad (3.3)$$

where  $F(x, \underline{v}_{\rho}) = \frac{1}{2}e^{S_{M,\rho} - \theta(x, \underline{v}_{\rho})(S_{M,\rho} - \underline{v}_{\rho})}\underline{v}_{\rho}^2$ ,  $\theta \in (0, 1)$ . So we have

$$\underline{v}_t - \underline{v}_{\rho\rho} - \frac{N-1}{\rho}\underline{v}_{\rho} \leq e^{S_{M,\rho}}\underline{v}_{\rho}.$$

Let  $\varphi(\rho)$  be the first eigenfunction of (3.2) and choose a constant  $C > 0$  such that  $u_0 + \chi + \mu\kappa \leq C\varphi$ . We observe that  $Ce^{-\lambda_1 t}\varphi$  is a super-solution of (3.3). Then by the comparison principle, we get  $S_M - u \leq \underline{v} \leq Ce^{-\lambda_1 t}\varphi$ . By the strong maximum principle, we get  $u(\cdot, t_0) < S_M(\cdot)$  and  $-u_{\nu}(\cdot, t_0) < -S_{M,\nu}(\cdot)$  on the boundary of  $B_{r,R}$ . Without loss of generality we assume that  $t_0 = 0$ . So there is a radially symmetric function  $\vartheta(\rho)$  such that  $u_0 < \vartheta < S_M$ . Let  $\bar{u}$  be the

solution of (1.1) with  $\vartheta$  as the initial data. Then by comparison principle, we have  $u \leq \bar{u} \leq S_M$ . Let  $\bar{v} = S_M - \bar{u}$ , by the Taylor's expansion up to the second order, we also get (3.3) with replaced  $\underline{v}$  by  $\bar{v}$ . Since  $|F| \leq C_1 |\bar{v}_\rho|^2$  for some constant  $C_1$  independent of  $\bar{v}$  due to  $\bar{v}_\rho$  is uniformly bounded in  $\bar{B}_{r,R} \times [0, \infty)$ , we obtain

$$\bar{v}_t - \bar{v}_{\rho\rho} - \frac{N-1}{\rho} \bar{v}_\rho \geq e^{S_{M,\rho}} \bar{v}_\rho - C_1 |\bar{v}_\rho|^2.$$

Let  $z = 1 - e^{-C_1 \bar{v}}$ , then

$$z_t - z_{\rho\rho} - \frac{N-1}{\rho} z_\rho \geq e^{S_{M,\rho}} z_\rho.$$

So  $S_M - u \geq \bar{v} \geq C_1^{-1} z \geq ce^{-\lambda_1 t} \varphi$  if  $c > 0$  is suitably small. Thus we have

$$ce^{-\lambda_1 t} \varphi \leq S_M - u \leq Ce^{-\lambda_1 t} \varphi, \quad x \in B_{r,R}, \quad t > 0, \quad (3.4)$$

which implies Theorem 2.1 (1).

## 4 Critical case $M = M_c$

In this section, we assume that  $u_0 \leq S_{M_c}$  in  $B_{r,R}$ . We claimed that  $u$  exists globally. Assume for contradiction that  $T^* < \infty$ . By the maximum principle, we have  $u \geq -\chi - \mu\kappa$  for some  $\mu$ , so  $\nabla u$  blows up only on the boundary  $\partial B_r$  by the similar proof of [7, Theorem 3.2] or [10, Theorem 3.1]. Parabolic estimates imply that  $u$  can be extended to a function  $u \in C^{2,1}(\bar{B}_{r+\varepsilon,R}) \times (0, T^*]$  for  $0 < \varepsilon \ll 1$ . Since  $u < S_{M_c}$  in  $B_{r,R}$  for  $t > 0$ , by the maximum principle, we have  $u_\rho > S_{M_c,\rho}$  on  $\partial B_R$  for  $0 < t \leq T^*$ . Fixing  $t_0 \in (0, T^*)$ , we can find  $M < M_c$  close to  $M_c$  and  $0 < \varepsilon \ll 1$  such that  $u < S_M$  on  $\partial B_{R-\varepsilon} \times [t_0, T^*]$  and  $u < S_M$  in  $\bar{B}_{r,R-\varepsilon}$  at  $t = t_0$ . So we have  $u < S_M$  in  $B_{r,R-\varepsilon} \times [t_0, T^*]$ , contradicting to the blowup of  $\nabla u$  at  $t = T^*$ .

Fixing some  $t_0 > 0$ , we have  $u(x, t_0) < S_{M_c}(x)$  for  $x \in B_{r,R}$ . So there exists a radial function  $h(\rho)$  such that  $u(x, t_0) < h(\rho) < S_{M_c}(x)$ , therefore  $u(x, t) \leq H(\rho, t)$  in  $B_{r,R} \times [t_0, \infty)$ , where  $H$  is the solution of Problem (1.1) with  $H(\rho, t_0) = h(\rho)$ . Also, since  $-\chi(\rho) - \mu\kappa(\rho) \leq u_0(x)$  for some  $\mu$ , we have  $K(\rho, t) \leq u(x, t)$  in  $B_{r,R} \times [t_0, \infty)$ , where  $K$  is the solution of Problem (1.1) with  $K(\rho, t_0) = -\chi(\rho) - \mu\kappa(\rho)$ . So, similarly to Section 3, it is sufficient to consider the asymptotic behavior of the radial solution of Problem (1.1).

In the following, we use the idea of [6] to study the asymptotic behavior of the radial solution of Problem (1.1).

We consider the degenerate eigenvalue problem

$$-(a(\rho)\varphi_\rho)_\rho = \lambda a(\rho)\varphi, \quad r < \rho < R; \quad \varphi(r) = \varphi(R) = 0, \quad (4.1)$$

and its regularized problem

$$-(a(\rho)\varphi_{\varepsilon,\rho})_\rho = \lambda_\varepsilon a(\rho)\varphi_\varepsilon, \quad r + \varepsilon < \rho < R; \quad \varphi_\varepsilon(r + \varepsilon) = \varphi_\varepsilon(R) = 0. \quad (4.2)$$

Denote by  $\lambda_\varepsilon$  the first eigenvalue of (4.2) and by  $\varphi_\varepsilon$  the corresponding eigenfunction. Let  $\lambda_1 = \inf\{\int_r^R a(\rho)(v_\rho)^2 d\rho; v \in J, \int_r^R a(\rho)v^2 d\rho = 1\}$ , where  $J = \{v \in H_{loc}^1((r, R]); \int_r^R a(\rho)(v_\rho)^2 d\rho < \infty, v(R) = 0\}$ . Then from the similar proof of Proposition 5.1 in [6], we know that  $\lambda_1$  is well defined,  $0 < \lambda_1 = \lim_{\varepsilon \rightarrow 0} \lambda_\varepsilon < \infty$ , and there exists  $0 < \varphi \in J \cap C^2((r, R])$  which solves (4.1) with  $\lambda = \lambda_1$ .

Set  $v = S_{M_c} - u$ , then

$$\begin{aligned} v_t - \Delta v &= e^{|\nabla S_{M_c}|} - e^{|\nabla u|} \\ &= e^{|\nabla S_{M_c}|} \frac{\nabla S_{M_c}}{|\nabla S_{M_c}|} \cdot \nabla v - F(x, \nabla v), \end{aligned} \quad (4.3)$$

where  $F(x, \nabla v) = \frac{1}{2}e^{|\nabla S_{M_c} - \theta(x, \nabla v)\nabla v|}|\nabla v|^2$ ,  $\theta \in (0, 1)$ . So we have

$$v_t - \Delta v \leq e^{|\nabla S_{M_c}|} \frac{\nabla S_{M_c}}{|\nabla S_{M_c}|} \cdot \nabla v \quad \text{in } (r, R) \times (0, \infty).$$

So

$$S_{M_c} - u = v \leq Ce^{-\lambda_1 t} \varphi \quad (4.4)$$

if  $C$  is suitably large. Since  $|F| \leq C_\varepsilon |\nabla v|^2$  in  $[r + \varepsilon, R] \times (0, \infty)$ , we also have

$$v_t - \Delta v \geq e^{|\nabla S_{M_c}|} \frac{\nabla S_{M_c}}{|\nabla S_{M_c}|} \cdot \nabla v - C_\varepsilon |\nabla v|^2 \quad \text{in } [r + \varepsilon, R] \times (0, \infty).$$

Let  $z = 1 - e^{-C_\varepsilon v}$ , then

$$z_t - \Delta z \geq e^{|\nabla S_{M_c}|} \frac{\nabla S_{M_c}}{|\nabla S_{M_c}|} \cdot \nabla v.$$

So

$$S_{M_c} - u = v \geq C_\varepsilon^{-1} z \geq ce^{-\lambda_\varepsilon t} \varphi_\varepsilon \quad (4.5)$$

in  $[r + \varepsilon, R]$ , where  $c > 0$  is suitably small. The first assertion of Theorem 2.1 (2) is proved.

We consider the radial problem

$$\begin{cases} u_t - u_{\rho\rho} - \frac{N-1}{\rho} u_\rho = e^{|u_\rho|}, & r < \rho < R, \\ u(r, t) = 0, \quad u(R, t) = M_c, & t > 0. \end{cases} \quad (4.6)$$

Let  $v(\rho, t)$  be the solution of (4.3) with  $v_0(\rho) = -\chi(\rho) - \mu\kappa(\rho)$  ( $\mu > 0$ ), then  $v(\rho, t)$  is nondecreasing in time by the maximum principle. Therefore  $v_\rho(r, t)$  is also nondecreasing in time. So we have  $\lim_{t \rightarrow \infty} v_\rho(r, t) = \infty$ . For any radial function  $u_0 \in X$  one can find  $\mu$  suitable large such that  $u_0 > v_0$ , so we have

$$\lim_{t \rightarrow \infty} u_\rho(r, t) = \infty.$$



For  $M < M_c$ , as in [3], let  $N_M(t)$  be the number of intersections of  $u(\rho, t)$  and  $S_M$ . It is known that  $N_M(t)$  is non-increasing. It is obvious that there exists  $M_0$  close enough to  $M_c$  such that  $N_M(1) = 1$  if  $M_0 \leq M < M_c$ . Denote by  $S_{M(t)}$  the solution of (2.1) with  $S_{M,\rho}(r) = u_\rho(r, t)$ . By  $\lim_{t \rightarrow \infty} u_\rho(r, t) = \infty$ , there exists  $t_0 > 1$  such that  $M(t) > M_0$  for all  $t > t_0$ . By Hopf's lemma, if  $N_M(t) = 1$ , then  $u_\rho(r, t) < S_{M,\rho}(r)$ . Therefore,  $N_{M(t)}(t) = 0$ . So  $N_{M(t)}(s) = 0$  for  $s > t$  since  $N_M(t)$  is non-increasing. Thus we have by Hopf's lemma  $u_\rho(r, s) > S_{M(t),\rho}(r) = u_\rho(r, t)$  for  $s > t$ , i.e.,  $u_\rho(r, t)$  is strictly increasing in time for  $t > t_0$ .

By (4.4), we have

$$u(\rho, t) \geq S_{M_c}(\rho) - Ce^{-\lambda_1 t},$$

and by (2.2)

$$\frac{u(\rho, t)}{\rho - r} \geq \left(1 + \ln \frac{1}{c(\rho - r)}\right) - C(\rho - r)^{-1}e^{-\lambda_1 t}.$$

Using the method in [9] or [1], we can prove that  $u_{\rho\rho} < 0$  for  $t \gg 1$  and  $r < \rho < r + \varepsilon$ . Therefore, taking  $\rho - r = Ce^{-\lambda_1 t}$ , we have

$$u_\rho(r, t) \geq \frac{u(\rho, t)}{\rho - r} \geq Ct \quad \text{for } t \text{ large.} \quad (4.7)$$

On the other hand, for  $t$  large,  $u(\rho, t) > S_{M(t)}(\rho)$ , therefore

$$\begin{aligned} S_{M_c}(\rho) - u(\rho, t) &\leq S_{M_c}(\rho) - S_{M(t)}(\rho) \\ &\leq U_{M_c}(\rho) - U_{M(t)}(\rho) \\ &= (\rho - r) \left(1 + \ln \frac{1}{\rho - r}\right) \\ &\quad + (\rho - r + e^{-\alpha(t)}) \ln(\rho - r + e^{-\alpha(t)}) - (\rho - r) + \alpha(t)e^{-\alpha(t)} \\ &\leq Ce^{-\alpha(t)}, \end{aligned}$$

where  $U_M(\rho)$  is the solution of  $U_{\rho\rho} + e^{|U_\rho|} = 0$  in  $(r, R)$  and  $U(r) = 0, U(R) = M$ , and  $\alpha(t) = u_\rho(r, t)$ . By (4.5), we have

$$e^{-\alpha(t)} \geq \|S_{M_c} - u(t)\|_\infty \geq ce^{-\lambda_\varepsilon t},$$

therefore we get

$$u_\rho(r, t) \leq C\lambda_\varepsilon t \quad \text{for } t \text{ large.} \quad (4.8)$$

From (4.7) and (4.8), the second part of Theorem 2.1 (2) follows.

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