Multiple positive solutions to systems of nonlinear semipositone fractional differential equations with coupled boundary conditions^{*}

Chengjun Yuan^{1,5} DAQING JIANG¹ DONAL O'REGAN² RAVI P. AGARWAL^{3,4†}

1. School of Mathematics and Statistics, Northeast Normal University, Changchun 130024, Jilin, P. R. China

2. School of Mathematics, Statistics and Applied Mathematics, National University of Ireland, Galway, Ireland

3. Department of Mathematics, Texas A and M University, Kingsville, Texas, USA

4. Department of Mathematics and Statistics, King Fahd University of Petroleum and Minerals, Dhahran 31261, Saudi Arabia

5. School of Mathematics and Computer, Harbin University, Harbin 150086, Heilongjiang, P. R. China

Abstract. In this paper, we consider four-point coupled boundary value problem for systems of the nonlinear semipositone fractional differential equation

$$
\begin{cases}\n\mathbf{D}_{0+}^{\alpha}u + \lambda f(t, u, v) = 0, & 0 < t < 1, \lambda > 0, \\
\mathbf{D}_{0+}^{\alpha}v + \lambda g(t, u, v) = 0, \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n - 2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0, 1)\n\end{cases}
$$

where λ is a parameter, a, b, ξ, η satisfy $\xi, \eta \in (0, 1), 0 < ab\xi\eta < 1, \alpha \in (n-1, n]$ is a real number and $n \geq 3$, and \mathbf{D}_{0+}^{α} is the Riemann-Liouville's fractional derivative, and f, g are continuous and semipositone. We derive an interval on λ such that for any λ lying in this interval, the semipositone boundary value problem has multiple positive solutions.

Key words. Riemann-Liouville's fractional derivative; semipositone fractional differential equation; four-point coupled boundary value problem; positive solution; fixed-point theorem.

MR(2008) Subject Classifications: 34B15

1 Introduction

We consider the four-point coupled boundary value problem for nonlinear fractional differential equation involving the Riemann-Liouville's derivative

$$
\begin{cases}\n\mathbf{D}_{0+}^{\alpha}u + \lambda f(t, u, v) = 0, & 0 < t < 1, \lambda > 0, \\
\mathbf{D}_{0+}^{\alpha}v + \lambda g(t, u, v) = 0, & \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n - 2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0, 1)\n\end{cases}
$$
\n(1.1)

where λ is a parameter, a, b, ξ, η satisfy $\xi, \eta \in (0, 1), 0 < ab\xi\eta < 1, \alpha \in (n-1, n]$ is a real number and $n \ge 2$, \mathbf{D}_{0+}^{α} is the Riemann-Liouville's fractional derivative, and f, g are sign-changing continuous functions.

Fractional differential equation's modeling capabilities in engineering, science, economics, and other fields, over the last few decades has resulted in the rapid development of the theory of fractional differential equations, see

[∗]The work was supported by Natural Science Foundation of Heilongjiang Province of China (No. A201012), a grant from the Ph.D. Programs Foundation of Ministry of Education of China (No.200918), Key Subject of Chinese Ministry of Education (No.109051) and NNSF(No.10971021).

[†]Corresponding author. E-mail address: Agarwal@tamuk.edu (R.P. Agarwal)

[1]-[7] for a good overview. To our knowledge there are only a few papers which deal with the boundary value problem for nonlinear fractional differential equations (see for example [8]-[20]). Coupled boundary conditions arise in the study of reaction-diffusion equations and Sturm-Liouvillie problems, see [21, 22] and have wide applications in various fields of sciences and engineering, for example the heat equation [23, 24, 25] and mathematical biology [26, 27].

In [23], the authors study the case of two equations

$$
u_t = \Delta u, \quad v_t = \Delta v, \quad x \in \Omega, \quad 0 < t < T,
$$
\n
$$
\frac{\partial u}{\partial \eta} = v^p, \quad \frac{\partial v}{\partial \eta} = u^p, \quad X \in \partial \Omega, \quad 0 < t < T,
$$

and it was shown that if $pq \leq 1$, all nonnegative solutions are global, while if $pq > 1$, every nonnegative solution blows up in finite time.

In [26], the authors study the blow-up properties of the positive solutions to the system of heat equations with nonlinear boundary conditions

$$
u_{it} = \Delta u_i, i = l, \dots, k, u_{k+l} := u_l, \quad x \in \Omega, \quad 0 < t < T,
$$
\n
$$
\frac{\partial u_i}{\partial \eta} = u_{i+1}^{p_i}, \quad X \in \partial \Omega, \quad 0 < t < T,
$$
\n
$$
u_i(x, 0) = u_{i,0}(x), \quad x \in \Omega,
$$

where $p_i > 0$, $i = 1, \dots, k$. $\Omega \in R^N$ is a bounded domain with smooth boundary $\partial \Omega$, η is the unit outward normal vector, $u_{i,0}(x)$ are nonnegative nontrivial functions and satisfy appropriate compatibility conditions. The upper and lower bounds of the blow-up rate is derived.

In [28], Leung studied the reaction-diffusion system for prey-predator interaction

$$
u_t(t,x) = \sigma_1 \triangle u + u(a + f(u,v)), t \ge 0; x \in \Omega \subset R^n,
$$

$$
v_t(t,x) = \sigma_2 \triangle v + v(r + g(u;v)), t \ge 0; x \in \Omega \subset R^n,
$$

subject to the coupled boundary conditions

$$
\frac{\partial u}{\partial \eta} = 0; \frac{\partial v}{\partial \eta} - p(u) - q(v) = 0 \text{ on } \partial \Omega,
$$

where the functions $u(t, x), v(t, x)$ respectively represent the density of prey and predator at time $t \geq 0$ and at position $x = (x_1, \dots, x_n)$. Similar coupled boundary conditions are also studied in [27] for a biochemical system.

The above mentioned work and wide applications of coupled boundary conditions motivate us to study equation (1.1). In this paper, we give sufficient conditions for the existence of positive solution of the semipositone boundary value problems (1.1) for a sufficiently small $\lambda > 0$ where f, g may change sign. Our analysis relies on a nonlinear alternative of Leray-Schauder type and Krasnosel'skii's fixed-point theorems.

2 Preliminaries

For completeness, in this section, we first present some fundamental facts of the Riemann-Liouville's derivatives of fractional order which can been found in [3].

Definition 2.1 [3] The integral

$$
I_{0+}^{\alpha}f(x) = \frac{1}{\Gamma(\alpha)} \int_0^x \frac{f(t)}{(x-t)^{1-\alpha}} dt, \quad x > 0,
$$

where $\alpha > 0$, is called Riemann-Liouville fractional integral of order α .

Definition 2.2 [3] For a function $f(x)$ given in the interval [0, ∞), the expression

$$
D_{0+}^{\alpha}f(x) = \frac{1}{\Gamma(n-\alpha)} \left(\frac{d}{dx}\right)^n \int_0^x \frac{f(t)}{(x-t)^{\alpha-n+1}} dt,
$$

where $n = [\alpha] + 1$, $[\alpha]$ denotes the integer part of number α , is called the Riemann-Liouville fractional derivative of order s.

As examples, for $\mu > -1$, we have

$$
\mathbf{D}_{0+}^{\alpha}x^{\mu} = \frac{\Gamma(1+\mu)}{\Gamma(1+\mu-\alpha)}x^{\mu-\alpha}
$$

giving in particular $\mathbf{D}_{0+}^{\alpha} x^{\alpha-m}$, $m = i, 2, 3, \cdots, N$, where N is the smallest integer greater than or equal to α .

Lemma 2.1 Let $\alpha > 0$. Then the differential equation

 $\mathbf{D}_{0+}^{\alpha}u(t)=0$

has solutions $u(t) = c_1 t^{\alpha-1} + c_2 t^{\alpha-2} + \cdots + c_n t^{\alpha-n}, c_i \in \mathbb{R}, i = 1, 2, ..., n$, where n is the smallest integer greater than or equal to α .

Lemma 2.2 Let $\alpha > 0$. Then

$$
I_{0+}^{\alpha} \mathbf{D}_{0+}^{\alpha} u(t) = u(t) + c_1 t^{\alpha - 1} + c_2 t^{\alpha - 2} + \dots + c_n t^{\alpha - n},
$$

for some $c_i \in \mathbb{R}$, $i = 1, 2, ..., n$, n is the smallest integer greater than or equal to α .

Lemma 2.3 Let $x, y \in C[0, 1]$ be given functions. Then the boundary-value problem

$$
\begin{cases}\n\mathbf{D}_{0+}^{\alpha}u + x(t) = 0, & 0 < t < 1, \lambda > 0, \\
\mathbf{D}_{0+}^{\alpha}v + y(t) = 0, & \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n-2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0,1)\n\end{cases}
$$
\n(2.1)

has an integral representation

$$
\begin{cases}\n u(t) = \int_0^1 G_{\xi\eta}(t,s)x(s)ds + \int_0^1 K_{\xi\eta}(t,s)y(s)ds, \\
 v(t) = \int_0^1 G_{\eta\xi}(t,s)y(s)ds + \int_0^1 K_{\eta\xi}(t,s)x(s)ds\n\end{cases}
$$
\n(2.2)

where

$$
G_{\xi\eta}(t,s) = \begin{cases} \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\xi^{\alpha-1}t^{\alpha-1}(\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \le s \le t \le 1, s \le \eta, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \le s \le t \le 1, s \ge \eta, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\xi^{\alpha-1}t^{\alpha-1}(\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \le \eta, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \le \eta, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \ge \eta \end{cases} (2.3)
$$

$$
\begin{cases}\n(1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha) & (1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha) \\
\frac{t^{\alpha - 1}(1 - s)^{\alpha - 1}}{(1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha)},\n\end{cases}
$$

$$
G_{\eta\xi}(t,s) = \begin{cases} \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\eta^{\alpha-1}t^{\alpha-1}(\xi-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \le s \le t \le 1, s \le \xi, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \le s \le t \le 1, s \ge \xi, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\eta^{\alpha-1}t^{\alpha-1}(\xi-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \le \xi, \end{cases} (2.4)
$$

$$
\begin{cases}\n\frac{(1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha)}{(1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \le \xi, \\
\frac{t^{\alpha - 1}(1 - s)^{\alpha - 1}}{(1 - ab\xi^{\alpha - 1}\eta^{\alpha - 1})\Gamma(\alpha)}, & 0 \le t \le s \le 1, s \ge \xi\n\end{cases}
$$
\n
$$
\begin{cases}\na\xi^{\alpha - 1}t^{\alpha - 1}(1 - s)^{\alpha - 1} & at^{\alpha - 1}(\xi - s)^{\alpha - 1} \\
\alpha \le t \le 1, & \xi \le 1\n\end{cases}
$$

$$
K_{\xi\eta}(t,s) = \begin{cases} \frac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{at^{\alpha-1}(\xi-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & s \le \xi, \\ \frac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & s \ge \xi \end{cases}
$$
(2.5)

$$
K_{\eta\xi}(t,s) = \begin{cases} \frac{b\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{bt^{\alpha-1}(\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & s \le \eta, \\ \frac{b\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, & s \ge \eta. \end{cases}
$$
(2.6)

Proof. From Lemma 2.2 we can reduce (2.1) to an equivalent integral equation

$$
u(t) = c_{11}t^{\alpha - 1} + c_{12}t^{\alpha - 2} + \dots + c_{1n}t^{\alpha - n} - \int_0^t \frac{(t - s)^{\alpha - 1}}{\Gamma(\alpha)} x(s)ds
$$

$$
v(t) = c_{21}t^{\alpha - 1} + c_{22}t^{\alpha - 2} + \dots + c_{2n}t^{\alpha - n} - \int_0^t \frac{(t - s)^{\alpha - 1}}{\Gamma(\alpha)} y(s)ds.
$$
 (2.7)

From $u^{(j)}(0) = v^{(j)}(0) = 0, 0 \le j \le n-2$, we have $c_{in} = c_{i(n-1)} = \cdots = c_{i2} = 0, (i = 1, 2)$. Then

$$
u(t) = c_{11}t^{\alpha - 1} - \int_0^t \frac{(t - s)^{\alpha - 1}}{\Gamma(\alpha)} x(s)ds
$$

$$
v(t) = c_{21}t^{\alpha - 1} - \int_0^t \frac{(t - s)^{\alpha - 1}}{\Gamma(\alpha)} y(s)ds
$$

and from the condition $u(1) = av(\xi), v(1) = bu(\eta)$ we have

$$
\begin{array}{l}c_{11}-a\xi^{\alpha-1}c_{21}=\int_{0}^{1}\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-a\int_{0}^{\xi}\frac{(\xi-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds,\\c_{21}-b\eta^{\alpha-1}c_{11}=\int_{0}^{1}\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-b\int_{0}^{\eta}\frac{(\eta-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds.\end{array}
$$

Solving for c_{11} and c_{21} , we have

$$
\begin{array}{l}c_{11}=\frac{1}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-\frac{a}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\xi}\frac{(\xi-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds\\ \qquad+\frac{a\xi^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-\frac{ab\xi^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\eta}\frac{(\eta-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds,\\ c_{21}=\frac{1}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-\frac{1}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\eta}\frac{(\eta-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds\\ \qquad+\frac{b\eta^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{(1-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-\frac{ab\eta^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\xi}\frac{(\xi-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds.\end{array}
$$

Hence, we have

$$
\begin{array}{l} u(t)=\frac{1}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{t^{\alpha-1}(1-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-\frac{ab\xi^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^\eta\frac{t^{\alpha-1}(\eta-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-\int_0^t\frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds\\ \qquad+\frac{a\xi^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{t^{\alpha-1}(1-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-\frac{a}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\xi}\frac{t^{\alpha-1}(\xi-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds,\\ v(t)=\frac{1}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{t^{\alpha-1}(1-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-\frac{ab\eta^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^{\xi}\frac{t^{\alpha-1}(\xi-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds-\int_0^t\frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)}y(s)ds\\+\frac{b\eta^{\alpha-1}}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^1\frac{t^{\alpha-1}(1-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds-\frac{b}{1-ab\xi^{\alpha-1}\eta^{\alpha-1}}\int_0^\eta\frac{t^{\alpha-1}(\eta-s)^{\alpha-1}}{\Gamma(\alpha)}x(s)ds.\end{array}
$$

Thus

$$
\begin{cases} u(t) = \int_0^1 G_{\xi\eta}(t,s)x(s)ds + \int_0^1 K_{\xi\eta}(t,s)y(s)ds, \\ v(t) = \int_0^1 G_{\eta\xi}(t,s)y(s)ds + \int_0^1 K_{\eta\xi}(t,s)x(s)ds. \end{cases}
$$

Lemma 2.4 The function $G_{\xi\eta}(t,s)$ and $K_{\xi\eta}(t,s)$ defined respectively by (2.3) and (2.5) have the following properties:

$$
(R1) \ c_0 t^{\alpha-1} (1-s)^{\alpha-1} s \le G_{\xi\eta}(t,s) \le C_0 (1-s)^{\alpha-1} s, \ G_{\xi\eta}(t,s) \le C_0 t^{\alpha-1} \text{ for } t,s \in [0,1],
$$

$$
(R2) \ c_0 t^{\alpha-1} (1-s)^{\alpha-1} s \le K_{\xi\eta}(t,s) \le C_0 t^{\alpha-1} (1-s)^{\alpha-1} s \text{ for } t,s \in [0,1],
$$

where

$$
c_G = \frac{ab\xi^{\alpha-1}(1-\xi)\eta^{\alpha-1}(1-\eta)(1-ab\xi\eta)}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, \quad C_G = \frac{(\alpha-1)(1-ab\xi^{\alpha-1}\eta^{\alpha-1}+ab\xi^{\alpha-2}\eta^{\alpha-2})}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, \quad C_K = \frac{\min\{a\xi^{\alpha-2}(1-\xi), b\eta^{\alpha-2}(1-\eta)\}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}, \quad C_K = \frac{(\alpha-1)(a\xi^{\alpha-2}+b\eta^{\alpha-2})}{(1-ab\xi^{\alpha-2}+b\eta^{\alpha-2})}, \quad C_G = \min\{c_G, c_K\}, \quad C_0 = \min\{C_G, C_G^*(C_K)\}.
$$
\n(2.8)

Proof. (R_1) For $(t, s) \in [0, 1] \times [0, 1]$, from (2.3) , we discuss various cases.

Case 1. For $s \le t, s \le \eta$, we have

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}\ln[\alpha]}{1-\alpha k^{\alpha-1}r^{\alpha-1}\ln[\alpha-\frac{\alpha k^{\alpha-1}r^{\alpha-1}-(1-\alpha k^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}}{1-\alpha k^{\alpha-1}r^{\alpha-1}-(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}\newline = \frac{(1-\alpha k^{\alpha-1}r^{\alpha-1})(1-\alpha k^{\alpha-1}r^{\alpha-1})(1-\alpha)^{\alpha-1}}{1-(1-\alpha k^{\alpha-1}r^{\alpha-1})(1-\alpha)^{\alpha-1}}\\= \frac{(1-\alpha k^{\alpha-1}r^{\alpha-1})(1-\alpha k^{\alpha-1}-(1-s)^{\alpha-1}-(1-s)^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}\newline = \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1})}{1-(\eta^{n-1}r^{\alpha-1})}\\= \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^{\alpha-1})(1-\alpha)}\\= \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1}-(1-s)^{\alpha-1-1}-(1-s)^{\alpha-1})}{(1-(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}\newline = \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1}-(1-s)^{\alpha-1-1}-(1-s)^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}\newline = \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1}-(1-s)^{\alpha-1}-(1-s)^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^{\alpha-1})\ln[\alpha]}\newline = \frac{\alpha k^{\alpha-1}t^{\alpha-1}((\eta^{n-1}r^{\alpha-1})(1-s)^{\alpha-1}-(1-s)^{\alpha-1})}{(1-\alpha k^{\alpha-1}r^
$$

Case 2. For $s \le t, s \ge \eta$, from (2.3), we have

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\xi^{\alpha-1}}\frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} = \frac{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(t^{\alpha-1}(1-s)^{\alpha-1}-(t-s)^{\alpha-1})+ab\xi^{\alpha-1}\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha)} \geq \frac{ab\xi^{\alpha-1}\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha)} \geq \frac{ab\xi^{\alpha-1}\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha)} \geq c_Gt^{\alpha-1}(1-s)^{\alpha-1}s, G_{\xi\eta}(t,s) = \frac{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(t^{\alpha-1}(1-s)^{\alpha-1}-(t-s)^{\alpha-1})+ab\xi^{\alpha-1}\eta^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha-1)(1-a)^{\alpha-1}-(t-s)^{\alpha-1}+(1-a)^{\alpha-1}t^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}\eta} = \frac{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(t^{\alpha-1}(1-s)^{\alpha-1}-(t-s)^{\alpha-1})+ab\xi^{\alpha-1}\eta^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}\eta}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha-1)t^{\alpha-2}(1-s)^{\alpha-2}(1-t)s+ab\xi^{\alpha-1}\eta^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}s} \leq \frac{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(\alpha-1)t^{\alpha-2}(1-s)^{\alpha-2}t^{\alpha-1}t^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})(1-b\xi^{\alpha-1}\eta^{\alpha-1})(\alpha)} \leq C_G(1-s)^
$$

Case 3. For $t \leq s, s \leq \eta$, from (2.3), we have

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\xi^{\alpha-1}t^{\alpha-1}(\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
= \frac{t^{\alpha-1}(1-s)^{\alpha-1}-ab\xi^{\alpha-1}t^{\alpha-1}(\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
= \frac{(1-ab\xi^{\alpha-1})t^{\alpha-1}(1-s)^{\alpha-1}+ab\xi^{\alpha-1}t^{\alpha-1}((1-s)^{\alpha-1}-(\eta-s)^{\alpha-1})}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq \frac{(1-ab\xi^{\alpha-1})t^{\alpha-1}(1-s)^{\alpha-1}+ab\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-2}(1-\eta)}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq \frac{(1-ab\xi^{\alpha-1})t^{\alpha-1}(1-s)^{\alpha-1}+ab\xi^{\alpha-1}(1-\eta)t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq \frac{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq c_1t^{\alpha-1}(1-s)^{\alpha-1}s
$$

\n
$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} - \frac{ab\xi^{\alpha-1}t^{\alpha-1}(1-\eta-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq \frac{t^{\alpha-2}(1-s)^{\alpha-
$$

Case 4. For $t \leq s, s \geq \eta$, from (2.3), we have

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \ge \frac{t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \ge c_G t^{\alpha-1}(1-s)^{\alpha-1}s,
$$

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le \frac{t^{\alpha-2}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le \frac{(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le C_G(1-s)^{\alpha-1}s,
$$

$$
G_{\xi\eta}(t,s) = \frac{t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le \frac{t^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le C_{G}^{*}t^{\alpha-1}.
$$

Then, $c_0t^{\alpha-1}(1-s)^{\alpha-1}s \le G_{\xi\eta}(t,s) \le C_0(1-s)^{\alpha-1}s$, $G_{\xi\eta}(t,s) \le C_0t^{\alpha-1}$ for $t, s \in [0, 1]$.

 (R_2) For $(t, s) \in [0, 1] \times [0, 1]$, from (2.5) , we also discuss various cases. Case 1. For $s \leq \xi$, we have

$$
K_{\xi\eta}(t,s) = \frac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}-at^{\alpha-1}(\xi-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
= \frac{at^{\alpha-1}(\xi^{\alpha-1}(1-s)^{\alpha-1}-(\xi-s)^{\alpha-1})}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq \frac{at^{\alpha-1}(\xi^{\alpha-2}(1-s)^{\alpha-2}(1-\xi)s}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq \frac{a\xi^{\alpha-2}(1-\xi)t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\geq c_Kt^{\alpha-1}(1-s)^{\alpha-1-s},
$$

\n
$$
K_{\xi\eta}(t,s) = \frac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}-at^{\alpha-1}(\xi-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq \frac{at^{\alpha-1}(\xi^{\alpha-1}(1-s)^{\alpha-1}-(\xi-s)^{\alpha-1})}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq \frac{at^{\alpha-1}(\alpha-1)\xi^{\alpha-2}(1-s)^{\alpha-2}(1-\xi)s}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq \frac{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}{(1-ab\xi^{\alpha-1}m^{\alpha-1})\Gamma(\alpha)}
$$

\n
$$
\leq C_Kt^{\alpha-1}(1-s)^{\alpha-2}s.
$$

Case 2. For $s \geq \xi$, we have

$$
K_{\xi\eta}(t,s)=\tfrac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}\geq \tfrac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)}\geq c_Kt^{\alpha-1}(1-s)^{\alpha-1}s,
$$

$$
K_{\xi\eta}(t,s) = \frac{a\xi^{\alpha-1}t^{\alpha-1}(1-s)^{\alpha-1}}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} = \frac{a\xi^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}\xi}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le \frac{a\xi^{\alpha-2}t^{\alpha-1}(1-s)^{\alpha-1}s}{(1-ab\xi^{\alpha-1}\eta^{\alpha-1})\Gamma(\alpha)} \le C_Kt^{\alpha-1}(1-s)^{\alpha-1}s.
$$

Thus, we have $c_0t^{\alpha-1}(1-s)^{\alpha-1}s \leq K_{\xi\eta}(t,s) \leq C_0t^{\alpha-1}(1-s)^{\alpha-1}s$ for $t,s \in [0,1]$.

Similarly we have the following lemma.

Lemma 2.5 The function $G_{\eta\xi}(t,s)$ and $K_{\eta\xi}(t,s)$ defined respectively by (2.4) and (2.6) have the following properties:

$$
(R1) \ c_0 t^{\alpha-1} (1-s)^{\alpha-1} s \le G_{\eta\xi}(t,s) \le C_0 (1-s)^{\alpha-1} s, \ G_{\xi\eta}(t,s) \le C_0 t^{\alpha-1} \text{ for } t,s \in [0,1],
$$

$$
(R2) \ c_0 t^{\alpha-1} (1-s)^{\alpha-1} s \le K_{\eta\xi}(t,s) \le C_0 t^{\alpha-1} (1-s)^{\alpha-1} s \text{ for } t,s \in [0,1],
$$

where c_0 , C_0 are as in Lemma 2.4

Employing Lemma 2.3, the system (1.1) can be expressed as

$$
\begin{cases}\n u(t) = \lambda \left(\int_0^1 G_{\xi \eta}(t, s) f(s, u(s), v(s)) ds + \int_0^1 K_{\xi \eta}(t, s) g(s, u(s), v(s)) ds \right), \\
 v(t) = \lambda \left(\int_0^1 G_{\eta \xi}(t, s) g(s, u(s), v(s)) ds + \int_0^1 K_{\eta \xi}(t, s) f(s, u(s), v(s)) ds \right).\n\end{cases} \tag{2.9}
$$

The following theorems (the first a nonlinear alternative of Leray-Schauder type and the second Krasnosel'skii's fixed-point theorem) will play a major role in Section 3.

Theorem 2.6 [29] Let X be a Banach space with $\Omega \subset X$ closed and convex. Assume U is a relatively open subset of Ω with $0 \in U$, and let $S: \overline{U} \to \Omega$ be a compact, continuous map. Then either

- 1. S has a fixed point in \overline{U} , or
- 2. there exists $u \in \partial U$ and $\nu \in (0,1)$, with $u = \nu S u$.

Theorem 2.7 [30] Let X be a Banach space, and let $P \subset X$ be a cone in X. Assume Ω_1, Ω_2 are bounded open subsets of X with $0 \in \Omega_1 \subset \overline{\Omega}_1 \subset \Omega_2$, and let $S : P \to P$ be a completely continuous operator such that, either

- 1. $||Sw|| \le ||w||$, $w \in P \cap \partial \Omega_1$, $||Sw|| \ge ||w||$, $w \in P \cap \partial \Omega_2$, or
- 2. $||Sw|| \ge ||w||$, $w \in P \cap \partial \Omega_1$, $||Sw|| \le ||w||$ $w \in P \cap \partial \Omega_2$.

Then S has a fixed point in $P \cap (\overline{\Omega}_2 \backslash \Omega_1)$.

3 Main Results

We make the following assumption:

 (H_1) $f(t, u, v), g(t, u, v) \in C([0, 1] \times [0, +\infty) \times [0, +\infty), (-\infty, +\infty))$, moreover there exist function $e_i(t) \in$ $L^1([0,1],(0,+\infty))$ $(i=1,2)$ such that $f(t,u,v) \ge -e_1(t)$ and $g(t,u,v) \ge -e_2(t)$, for any $t \in [0,1], u, v \in [0,+\infty)$.

 (H_1^*) $f(t, u, v), g(t, u, v) \in C((0, 1) \times [0, +\infty), (-\infty, +\infty)), f, g$ may be singular at $t = 0, 1$, moreover there exist functions $e_i(t) \in L^1((0,1),(0,+\infty))$ $(i=1,2)$ such that $f(t,u,v) \geq -e_1(t)$ and $g(t,u,v) \geq -e_2(t)$, for any $t \in (0, 1), u, v \in [0, +\infty).$

 (H_2) $f(t, 0, 0) > 0, g(t, 0, 0) > 0$ for $t \in [0, 1].$

(H₃) There exists $[\theta_1, \theta_2] \subset (0, 1)$ such that $\lim_{u \uparrow +\infty} \inf \min_{t \in [\theta_1, \theta_2]}$ $\frac{f(t,u,v)}{u} = +\infty$, $\lim_{v \uparrow +\infty} \inf \min_{t \in [\theta_1,\theta_2]}$ $\frac{g(t,u,v)}{v} = +\infty.$

(H^{*}₃) There exists $[\theta_1, \theta_2] \subset (0, 1)$ such that $\lim_{v \uparrow +\infty} \inf \min_{t \in [\theta_1, \theta_2]}$ $\frac{f(t,u,v)}{v} = +\infty$, $\lim_{u \uparrow +\infty} \inf \min_{t \in [\theta_1,\theta_2]}$ $\frac{g(t,u,v)}{u} = +\infty.$

 $(H_4) \int_0^1 (1-s)^{\alpha-1} s e_i(s) ds < +\infty$, $\int_0^1 (1-s)^{\alpha-1} s f(s, u, v) ds < +\infty$ and $\int_0^1 (1-s)^{\alpha-1} s g(s, u, v) ds < +\infty$ for any $u, v \in [0, m], m > 0$ is any constant $(i = 1, 2)$.

We consider the boundary value problem

$$
\begin{cases}\n\mathbf{D}_{0+}^{\alpha}x + \lambda(f(t,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_1(t)) = 0, & 0 < t < 1, \lambda > 0, \\
\mathbf{D}_{0+}^{\alpha}y + \lambda(g(t,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_2(t)) = 0, \\
x^{(i)}(0) = y^{(i)}(0) = 0, & 0 \le i \le n-2, \\
x(1) = ay(\xi),y(1) = bx(\eta), & \xi, \eta \in (0,1)\n\end{cases}
$$
\n(3.1)

where

$$
z(t)^* = \begin{cases} z(t), & z(t) \ge 0, \\ 0, & z(t) < 0, \end{cases}
$$

and

$$
\begin{cases} w_1(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) e_1(s) ds + \lambda \int_0^1 K_{\xi\eta}(t,s) e_2(s) ds, \\ w_2(t) = \lambda \int_0^1 G_{\eta\xi}(t,s) e_2(s) ds + \lambda \int_0^1 K_{\eta\xi}(t,s) e_1(s) ds, \end{cases}
$$

which is the solution of the coupled boundary value problem

$$
\begin{cases}\n\mathbf{D}_{0+}^{\alpha}w_1 + \lambda e_1(t) = 0, & 0 < t < 1, \lambda > 0, \\
\mathbf{D}_{0+}^{\alpha}w_2 + \lambda e_2(t) = 0, & \\
w_1^{(i)}(0) = w_2^{(i)}(0) = 0, & 0 \le i \le n-2, \\
w_1(1) = aw_2(\xi), w_2(1) = bw_1(\eta), & \xi, \eta \in (0,1).\n\end{cases}
$$

We will show there exists a solution (x, y) for the boundary value problem (3.1) with $x(t) \geq w_1(t)$ and $y(t) \geq$ $w_2(t)$ for $t \in [0,1]$. If this is true, then $u(t) = x(t) - w_1(t)$ and $v(t) = y(t) - w_2(t)$ is a nonnegative solution (positive on $(0, 1)$ of the boundary value problem (1.1) . Since for any $t \in (0, 1)$,

$$
-\mathbf{D}_{0+}^{\alpha}x = -\mathbf{D}_{0+}^{\alpha}u + (-\mathbf{D}_{0+}^{\alpha}w_1) = \lambda[f(t, u, v) + e_1(t)],
$$

$$
-\mathbf{D}_{0+}^{\alpha}y = -\mathbf{D}_{0+}^{\alpha}v + (-\mathbf{D}_{0+}^{\alpha}w_2) = \lambda[g(t, u, v) + e_2(t)],
$$

we also have

$$
-\mathbf{D}_{0+}^{\alpha}u = \lambda f(t, u, v) \text{ and } -\mathbf{D}_{0+}^{\alpha}v = \lambda g(t, u, v).
$$

On the other hand, from the coupled value condition $x^{(i)}(0) = y^{(i)}(0) = 0, 0 \le i \le n-2$ and $x(1) = ay(\xi), y(1) =$ $bx(\eta)$, we have

$$
u^{(i)}(0) = v^{(i)}(0) = 0
$$
 for $0 \le i \le n-2$; $u(1) = av(\xi), v(1) = bu(\eta)$ for $\xi, \eta \in (0, 1)$.

As a result, we will concentrate our study on the boundary value problem (3.1).

Employing Lemma 2.3, we note that the system (3.1) is equivalent to

$$
\begin{cases}\nx(t) = \lambda \int_0^1 G_{\xi\eta}(t, s) (f(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_1(s)) ds \\
+ \lambda \int_0^1 K_{\xi\eta}(t, s) (g(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_2(s)) ds, \\
y(t) = \lambda \int_0^1 G_{\eta\xi}(t, s) (g(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_2(s)) ds \\
+ \lambda \int_0^1 K_{\eta\xi}(t, s) (f(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_1(s)) ds.\n\end{cases} \tag{3.2}
$$

We consider the Banach space $E = C[0, 1]$ equipped with the standard norm $||x|| = \max_{0 \le t \le 1} |x(t)|, x \in X$. We define a cone P of E by

$$
P = \{ x \in X | x(t) \ge \frac{c_0 t^{\alpha - 1}}{C_0} ||x||, \ t \in [0, 1], \alpha \in (n - 1, n], n \ge 3 \}.
$$

For each $(x, y) \in E \times E$, we write $||(x, y)||_1 = ||x|| + ||y||$. Clearly, $(E \times E, ||\cdot||_1)$ is a Banach space and $P \times P$ is a cone of $E\times E.$

Define an integral operator $T: P \times P \to P \times P$ by

$$
T(x,y) = (A(x,y), B(x,y)),
$$

where the operators $A, B: P \times P \to P$ are defined by

$$
\begin{cases}\nA(x,y)(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds \\
\quad + \lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds, \\
B(x,y)(t) = \lambda \int_0^1 G_{\eta\xi}(t,s) (g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds \\
\quad + \lambda \int_0^1 K_{\eta\xi}(t,s) (f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds.\n\end{cases} (3.3)
$$

Clearly, if $(x, y) \in P \times P$ is a fixed point of T, then (x, y) is a solution of system (3.1).

Notice, from Lemma 2.4, we have $T(x, y)(t) \ge (0, 0)$ on [0, 1] and for $(x, y) \in P \times P$

$$
A(x,y)(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_1(s))ds + \lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_2(s))ds, \leq \lambda \int_0^1 C_0 (1-s)^{\alpha-1} s (f(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_1(s))ds + \lambda \int_0^1 C_0 (1-s)^{\alpha-1} s (g(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_2(s))ds,
$$

and then $||A(x,y)|| \leq \lambda \int_0^1 C_0(1-s)^{\alpha-1} s(f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*)+e_1(s))ds+\lambda \int_0^1 C_0(1-s)^{\alpha-1} s(g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*)$ $w_1(t)]^*, [y(t) - w_2(t)]^*) + e_2(s)$

On the other hand, for $(x, y) \in P \times P$, $t \in [0, 1]$ we have

$$
A(x,y)(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds
$$

+ $\lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds,$
 $\geq \lambda \int_0^1 c_0 t^{\alpha-1} (1-s)^{\alpha-1} s (f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds$
+ $\lambda \int_0^1 c_0 t^{\alpha-1} (1-s)^{\alpha-1} s (g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds,$
 $\geq \frac{c_0}{c_0} t^{\alpha-1} \lambda \int_0^1 C_0 (1-s)^{\alpha-1} s (f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds$
+ $\frac{c_0}{c_0} t^{\alpha-1} \lambda \int_0^1 C_0 (1-s)^{\alpha-1} s (g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds,$
 $\geq \frac{c_0}{c_0} t^{\alpha-1} ||A(x,y)||.$

Consequently, $A(x, y) \in P$, i.e. $A(P \times P) \in P$. Similarly, we can show that $B(P \times P) \in P$. Hence, $T(P \times P) \subset P$. In addition, standard arguments in the literature guarantee that T is a completely continuous operator.

Theorem 3.1 Suppose that (H_1) and (H_2) hold. Then there exists a constant $\overline{\lambda} > 0$ such that, for any $0 < \lambda \leq \overline{\lambda}$, the boundary value problem (1.1) has at least one positive solution.

Proof. Fix $\delta \in (0, 1)$. From (H_2) , let $0 < \varepsilon < 1$ be such that

$$
f(t, u, v) \ge \delta f(t, 0, 0), \quad g(t, u, v) \ge \delta g(t, 0, 0), \quad \text{for} \quad 0 \le t \le 1, \quad 0 \le z_1, z_2 \le \varepsilon. \tag{3.4}
$$

Let $\overline{f}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{f(t, u, v) + e_1(t)\}, \overline{g}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{g(t, u, v) + e_2(t)\}$ and $c = \int_0^1 C_0 (1 - s)^{\alpha - 1} s ds$. We have

$$
\lim_{z\downarrow 0} \frac{\overline{f}(z)}{z} = +\infty, \quad \lim_{z\downarrow 0} \frac{\overline{g}(z)}{z} = +\infty.
$$

Suppose

$$
0<\lambda<\frac{\varepsilon}{8c\overline{h}(\varepsilon)}:=\overline{\lambda},
$$

where $\overline{h}(\varepsilon) = \max{\{\overline{f}(\varepsilon), \overline{g}(\varepsilon)\}}$. Since

$$
\lim_{z \downarrow 0} \frac{\overline{h}(z)}{z} = +\infty
$$

$$
\frac{\overline{h}(\varepsilon)}{\varepsilon} < \frac{1}{8c\lambda},
$$

ε

and

then exists a $R_0 \in (0, \varepsilon)$ such that

$$
\frac{h(R_0)}{R_0} = \frac{1}{8c\lambda}.
$$

Let $U = \{(x, y) \in P \times P : ||(x, y)||_1 \lt R_0\}, (x, y) \in \partial U$ and $\nu \in (0, 1)$ be such that $(x, y) = \nu T(x, y)$, i.e. $x = \nu A(x, y), y = \nu B(x, y)$. We claim that $\|(x, y)\|_1 \neq R_0$. In fact, for $(x, y) \in \partial U$ and $\|(x, y)\|_1 = R_0$, we have

$$
x(t) = \nu A(x, y)(t)
$$

\n
$$
\leq \lambda \int_0^1 G_{\xi\eta}(t, s) (f(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_1(s)) ds
$$

\n
$$
+ \lambda \int_0^1 K_{\xi\eta}(t, s) (g(s, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) + e_2(s)) ds,
$$

\n
$$
\leq \lambda \int_0^1 G_{\xi\eta}(t, s) \overline{f}(R_0) ds + \lambda \int_0^1 K_{\xi\eta}(t, s) \overline{g}(R_0) ds,
$$

\n
$$
\leq \lambda \int_0^1 C_0 (1 - s)^{\alpha - 1} s \overline{h}(R_0) ds + \lambda \int_0^1 C_0 (1 - s)^{\alpha - 1} s \overline{h}(R_0) ds,
$$

\n
$$
\leq 2\lambda \int_0^1 C_0 (1 - s)^{\alpha - 1} s ds \overline{h}(R_0),
$$

\n
$$
\leq 2\lambda c \overline{h}(R_0),
$$

\n(3.5)

and similarly, we also have

$$
y(t) = \nu B(x, y)(t) \le 2\lambda c\overline{h}(R_0).
$$
\n
$$
(3.6)
$$
\n
$$
R_0 = ||(x, y)||_1 \le 4\lambda c\overline{h}(R_0),
$$

that is

It follows that

$$
\frac{\overline{h}(R_0)}{R_0} \ge \frac{1}{4c\lambda} > \frac{1}{8c\lambda} = \frac{\overline{h}(R_0)}{R_0},
$$

which implies that $\|(x, y)\|_1 \neq R_0$. By the nonlinear alternative of Leray-Schauder type, T has a fixed point $(x, y) \in \overline{U}$. Moreover, combining (3.4)-(3.6) and the fact that $R_0 < \varepsilon$, we obtain

$$
x(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_1(s))ds + \lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(t) - w_1(t)]^*,[y(t) - w_2(t)]^*) + e_2(s))ds, \geq \lambda \int_0^1 G_{\xi\eta}(t,s) (\delta f(s,0,0) + e_1(s))ds + \lambda \int_0^1 K_{\xi\eta}(t,s) (\delta g(s,0,0) + e_2(s))ds, \geq \lambda \int_0^1 G_{\xi\eta}(t,s) e_1(s)ds + \lambda \int_0^1 K_{\xi\eta}(t,s) e_2(s)ds, = w_1(t) \text{ for } t \in (0,1),
$$

and similarly, we also have

$$
y(t) > w_2(t)
$$
 for $t \in (0, 1)$.

Then T has a positive fixed point (x, y) and $\|(x, y)\|_1 \le R_0 < 1$. Namely, (x, y) is positive solution of the boundary value problem (3.1) with $x(t) > w_1(t)$ and $y(t) > w_2(t)$ for $t \in (0,1)$.

Let $u(t) = x(t) - w_1(t) \ge 0$ and $v(t) = y(t) - w_2(t) \ge 0$. Then (u, v) is a nonnegative solution (positive on $(0, 1)$ of the boundary value problem (1.1) .

Theorem 3.2 Suppose that (H_1^*) and (H_3) - (H_4) hold. Then there exists a constant $\lambda^* > 0$ such that, for any $0 < \lambda \leq \lambda^*$, the boundary value problem (1.1) has at least one positive solution.

Proof. Let
$$
\Omega_1 = \{(x, y) \in E \times E : ||x|| < R_1, ||y|| < R_1\}
$$
, where $R_1 = \max\{1, r\}$ and $r = \frac{C_0^2}{c_0} \int_0^1 (e_1(s) + e_2(s))ds$). Choose

$$
\lambda^* = \min\{1, \frac{R_1}{2}(R+1)^{-1}, \frac{R_1}{2r}\},\
$$

where $R = \int_0^1 C_0(1-s)^{\alpha-1} s \left[\max_{0 \le z_1, z_2 \le R_1} f(s, z_1, z_2) + \max_{0 \le z_1, z_2 \le R_1} g(s, z_1, z_2) + e_1(s) + e_2(s) \right] ds$ and $R \ge 0$.

Then, for any $(x, y) \in (P \times P) \cap \partial \Omega_1$, we have $||x|| = R_1$ or $||y|| = R_1$. Moreover $x(s) - w_1(s) \leq x(s) \leq ||x|| \leq R_1$, $y(s) - w_2(s) \leq y(s) \leq ||y|| \leq R_1$, and it follows that

$$
||A(x,y)(t)|| \leq \lambda \int_0^1 C_0(1-s)^{\alpha-1}s(f(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_1(s))ds
$$

\n
$$
+ \lambda \int_0^1 C_0(1-s)^{\alpha-1}s(g(s,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) + e_2(s))ds,
$$

\n
$$
\leq \lambda \int_0^1 C_0(1-s)^{\alpha-1}s(\max_{0 \leq z_1,z_2 \leq R_1} f(s,z_1,z_2) + e_1(s))ds
$$

\n
$$
+ \lambda \int_0^1 C_0(1-s)^{\alpha-1}s(\max_{0 \leq z_1,z_2 \leq R_1} g(s,z_1,z_2) + e_2(s))ds,
$$

\n
$$
\leq \lambda \int_0^1 C_0(1-s)^{\alpha-1}s[\max_{0 \leq z_1,z_2 \leq R_1} f(s,z_1,z_2) + \max_{0 \leq z_1,z_2 \leq R_1} g(s,z_1,z_2) + e_1(s) + e_2(s)]ds,
$$

\n
$$
\leq \lambda R,
$$

\n
$$
\leq \frac{R_1}{2},
$$

and similarly, we also have

$$
||B(x,y)(t)|| \leq \frac{R_1}{2}.
$$

This implies

$$
||T(x,y)||_1 = ||A(x,y)|| + ||B(x,y)|| \le R_1 \le ||(x,y)||_1, (x,y) \in (P \times P) \cap \partial \Omega_1.
$$

On the other hand, choose a constant $N > 1$ such that

$$
\lambda N \frac{c_0^2}{2C_0} \gamma \int_{\theta_1}^{\theta_2} (1-s)^{\alpha-1} s^{\alpha} ds \ge 1,
$$

where $\gamma = \min_{\theta_1 \le t \le \theta_2} \{t^{\alpha - 1}\}.$

By assumptions (H₃) and (H₄), there exists a constant $B > R_1$ such that

$$
\frac{f(t, z_1, z_2)}{z_1} > N, \quad \text{namely} \quad f(t, z_1, z_2) > Nz_1, \quad \text{for} \quad t \in [\theta_1, \theta_2], \ z_2 > 0, z_1 > B
$$

and

$$
\frac{g(t, z_1, z_2)}{z_2} > N, \quad \text{namely} \quad g(t, z_1, z_2) > Nz_2, \quad \text{for} \quad t \in [\theta_1, \theta_2], \ z_1 > 0, z_2 > B.
$$

Choose $R_2 = \max\{R_1 + 1, 2\lambda r, \frac{2C_0(B+1)}{c_0\gamma}\}$, and let $\Omega_2 = \{(x, y) \in E \times E : ||x|| < R_2, ||y|| < R_2\}$. Then for any $(x, y) \in (P \times P) \cap \partial \Omega_2$, we have $||x|| = R_2$ or $||y|| = R_2$. If $||x|| = R_2$, then

$$
x(t) - w_1(t) = x(t) - (\lambda \int_0^1 G_{\xi\eta}(t, s) e_1(s) ds + \lambda \int_0^1 K_{\xi\eta}(t, s) e_2(s) ds)
$$

\n
$$
\geq x(t) - (\lambda \int_0^1 C_0 t^{\alpha - 1} e_1(s) ds + \lambda \int_0^1 C_0 t^{\alpha - 1} e_2(s) ds)
$$

\n
$$
= x(t) - (\lambda C_0 t^{\alpha - 1} \int_0^1 (e_1(s) + e_2(s)) ds)
$$

\n
$$
= x(t) - (\lambda \frac{c_0}{C_0} t^{\alpha - 1} \frac{C_0^2}{c_0} \int_0^1 (e_1(s) + e_2(s)) ds)
$$

\n
$$
= x(t) - \lambda \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
\geq x(t) - \frac{x(t)}{\|x\|} \lambda r
$$

\n
$$
\geq x(t) - \frac{x(t)}{R_2} \lambda r
$$

\n
$$
\geq (1 - \frac{\lambda r}{R_2}) x(t)
$$

\n
$$
\geq \frac{1}{2} x(t) \geq 0, t \in [0, 1],
$$

and then

$$
\min_{\theta_1 \le t \le \theta_2} \{ [x(t) - w_1(t)]^* \} = \min_{\theta_1 \le t \le \theta_2} \{ x(t) - w_1(t) \} \ge \min_{\theta_1 \le t \le \theta_2} \{ \frac{1}{2} x(t) \}
$$
\n
$$
\ge \min_{\theta_1 \le t \le \theta_2} \{ \frac{c_0}{2C_0} t^{\alpha - 1} ||x|| \} = \frac{c_0}{2C_0} R_2 \min_{\theta_1 \le t \le \theta_2} \{ t^{\alpha - 1} \} \ge B + 1 > B.
$$

Since $B > R_1 \geq m_0$, we have

$$
f(t,[x(t)-w_1(t)]^*,[y(t)-w_2(t)]^*) > N[x(t)-w_1(t)]^* \ge \frac{N}{2}x(t), \text{ for } t \in [\theta_1,\theta_2].
$$

It follows that

$$
A(x,y)(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*) + e_1(s))ds + \lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*) + e_2(s))ds, \geq \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*) + e_1(s))ds \geq \lambda \int_{\theta_1}^{\theta_2} G_{\xi\eta}(t,s) f(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*)ds \geq \lambda \int_{\theta_1}^{\theta_2} c_0 t^{\alpha} (1-s)^{\alpha-1} s \frac{N}{2} x(s) ds \geq \lambda t^{\alpha} \int_{\theta_1}^{\theta_2} c_0 (1-s)^{\alpha-1} s \frac{N}{2} \frac{c_0}{C_0} s^{\alpha-1} ||x|| ds \geq \lambda t^{\alpha} \int_{\theta_1}^{\theta_2} c_0 (1-s)^{\alpha-1} s N \frac{c_0}{2C_0} s^{\alpha-1} R_2 ds \geq \lambda N \frac{c_0^2}{2C_0} \gamma \int_0^1 (1-s)^{\alpha-1} s^{\alpha} ds R_2 \geq R_2, \quad t \in [\theta_1, \theta_2].
$$

If $||y|| = R_2$, we have

$$
y(t) - w_2(t) = y(t) - (\lambda \int_0^1 G_{\eta\xi}(t, s) e_1(s) ds + \lambda \int_0^1 K_{\eta\xi}(t, s) e_2(s) ds) \ge \frac{1}{2} y(t) \ge 0, \ t \in [0, 1],
$$

and

$$
\min_{\theta_1 \le t \le \theta_2} \{ [y(t) - w_2(t)]^* \} = \min_{\theta_1 \le t \le \theta_2} \{ y(t) - w_2(t) \} \ge \min_{\theta_1 \le t \le \theta_2} \{ \frac{1}{2} y(t) \} \n\ge \min_{\theta_1 \le t \le \theta_2} \{ \frac{c_0}{2C_0} t^{\alpha - 1} ||y|| \} = \frac{c_0}{2C_0} R_2 \min_{\theta_1 \le t \le \theta_2} \{ t^{\alpha - 1} \} \ge B + 1 > B.
$$

Then, for any $(x, y) \in (P \times P) \cap \partial \Omega_2$, we also have

$$
g(t, [x(t) - w_1(t)]^*, [y(t) - w_2(t)]^*) > N[y(t) - w_2(t)]^* \ge \frac{N}{2}y(t), \text{ for } t \in [\theta_1, \theta_2].
$$

It follows that

$$
A(x,y)(t) = \lambda \int_0^1 G_{\xi\eta}(t,s) (f(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*) + e_1(s))ds + \lambda \int_0^1 K_{\xi\eta}(t,s) (g(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*) + e_2(s))ds, \geq \lambda \int_{\theta_1}^{\theta_2} K_{\xi\eta}(t,s) g(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*)ds, \geq \lambda \int_{\theta_1}^{\theta_2} c_0 t^{\alpha} (1-s)^{\alpha-1} s g(s,[x(s) - w_1(s)]^*,[y(s) - w_2(s)]^*)ds, \geq \lambda t^{\alpha} \int_{\theta_1}^{\theta_2} c_0 (1-s)^{\alpha-1} s \frac{N}{2} g(s) ds \geq \lambda t^{\alpha} \int_{\theta_1}^{\theta_2} c_0 (1-s)^{\alpha-1} s \frac{N}{2} \frac{c_0}{C_0} s^{\alpha-1} ||y|| ds \geq \lambda t^{\alpha} \int_{\theta_1}^{\theta_2} c_0 (1-s)^{\alpha-1} s^{\alpha} N \frac{c_0}{2C_0} R_2 ds \geq \lambda N \frac{c_0^2}{2C_0} \gamma \int_0^1 (1-s)^{\alpha-1} s^{\alpha} ds R_2 \geq R_2, \quad t \in [\theta_1, \theta_2].
$$

Thus, for any $(x, y) \in (P \times P) \cap \partial \Omega_2$, we always have

$$
A(x, y)(t) \ge R_2, \quad t \in [\theta_1, \theta_2].
$$

Similarly, for any $(x, y) \in (P \times P) \cap \partial \Omega_2$, we also have

$$
B(x, y)(t) \ge R_2, \quad t \in [\theta_1, \theta_2].
$$

This implies

$$
||T(x,y)||_1 \ge ||(x,y)||_1, (x,y) \in (P \times P) \cap \partial \Omega_2.
$$

Thus condition (2) of Krasnoesel'skii's fixed-point theorem is satisfied. As a result T has a fixed point (x, y) with $r \leq R_1 < ||x|| < R_2, r \leq R_1 < ||y|| < R_2.$

Also since $r < R_1 < ||x||$ and $r < R_1 < ||y||$, then

$$
x(t) - w_1(t) \geq \frac{c_0}{C_0} t^{\alpha - 1} ||x|| - (\lambda \int_0^1 G_{\xi \eta}(t, s) e_1(s) ds + \lambda \int_0^1 K_{\xi \eta}(t, s) e_2(s) ds)
$$

\n
$$
\geq \frac{c_0}{C_0} t^{\alpha - 1} ||x|| - \lambda \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
\geq \frac{c_0}{C_0} t^{\alpha - 1} r - \lambda \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
\geq (1 - \lambda) \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
> 0, t \in (0, 1),
$$

and

$$
y(t) - w_2(t) = y(t) - (\lambda \int_0^1 G_{\eta\xi}(t, s) e_2(s) ds + \lambda \int_0^1 K_{\eta\xi}(t, s) e_1(s) ds)
$$

\n
$$
\geq y(t) - (\lambda \int_0^1 C_0 t^{\alpha - 1} e_2(s) ds + \lambda \int_0^1 C_0 t^{\alpha - 1} e_1(s) ds)
$$

\n
$$
= y(t) - (\lambda C_0 t^{\alpha - 1} \int_0^1 (e_1(s) + e_2(s)) ds)
$$

\n
$$
= \frac{c_0}{C_0} t^{\alpha - 1} ||y|| - \lambda \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
\geq \frac{c_0}{C_0} t^{\alpha - 1} r - \lambda \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
\geq (1 - \lambda) \frac{c_0}{C_0} t^{\alpha - 1} r
$$

\n
$$
> 0, t \in (0, 1).
$$

Thus, (x, y) is positive solution of the boundary value problem (3.1) with $x(t) > w_1(t)$ and $y(t) > w_2(t)$ for $t \in (0, 1).$

Let $u(t) = x(t) - w_1(t) \ge 0$ and $v(t) = y(t) - w_2(t) \ge 0$. Then (u, v) is a nonnegative solution (positive on $(0, 1)$ of the boundary value problem (1.1) .

Remark From the proof of Theorem 3.2, clearly condition (H_3) can be replaced by condition (H_3^*)

Theorem 3.3 Suppose that $(H_1^*), (H_3^*)$ and (H_4) hold. Then there exists a constant $\lambda^* > 0$ such that, for any $0 < \lambda \leq \lambda^*$, the boundary value problem (1.1) has at least one positive solution.

Since condition (H_1) implies conditions (H_1^*) and (H_4) , then from the proof of Theorem 3.1 and 3.2, we immediately have the following theorem:

Theorem 3.4 Suppose that (H_1) - (H_3) hold. Then the boundary value problem (1.1) has at least two positive solutions for $\lambda > 0$ sufficiently small.

In fact, let $0 < \lambda < \min\{\overline{\lambda}, \lambda^*\}$, then the boundary value problem (1.1) has at least two positive solutions. Similarly we have

Theorem 3.5 Suppose that (H_1) - (H_2) and (H_3^*) hold. Then the boundary value problem (1.1) has at least two positive solutions for $\lambda > 0$ sufficiently small.

4 Example

To illustrate the usefulness of the results, we give some examples.

Example 4.1 Consider the boundary value problem

$$
\begin{cases}\n-\mathbf{D}_{0+}^{\alpha}u = \lambda(u^{c} + \frac{1}{(t-t^{2})^{\frac{1}{2}}}\cos(\pi v)), & t \in (0,1), \lambda > 0, \\
-\mathbf{D}_{0+}^{\alpha}v = \lambda(v^{d} + \frac{1}{(t-t^{2})^{\frac{1}{2}}}\sin(2\pi u)), \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n-2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0,1)\n\end{cases}
$$
\n(4.1)

where c, $d > 1$. Then, if $\lambda > 0$ is sufficiently small, (4.1) has a positive solution (u, v) with $u > 0, v > 0$ for $t \in (0, 1)$.

To see this we will apply Theorem 3.2 with

$$
f(t, u, v) = u^c + \frac{1}{(t - t^2)^{\frac{1}{2}}} \cos(\pi v), \quad g(t, u, v) = v^d + \frac{1}{(t - t^2)^{\frac{1}{2}}} \sin(2\pi u),
$$

$$
e_i(t) = e(t) = \frac{2}{(t - t^2)^{\frac{1}{2}}} \quad (i = 1, 2).
$$

Clearly, for $t \in (0, 1)$,

$$
f(t, u, v) + e(t) \ge u^c + \frac{1}{(t - t^2)^{\frac{1}{2}}} > 0, \quad g(t, u, v) + e(t) \ge v^d + \frac{1}{(t - t^2)^{\frac{1}{2}}} > 0, \text{ for } t \in (0, 1);
$$

$$
\lim_{u \uparrow + \infty} \inf \frac{f(t, u, v)}{u} = +\infty, \quad \lim_{v \uparrow + \infty} \inf \frac{g(t, u, v)}{v} = +\infty, \text{ for } \forall t \in [\theta_1, \theta_2] \subset (0, 1),
$$

for $u, v \ge 0$. Thus (H_1^*) and (H_3) - (H_4) hold. Let $r = \frac{2C_0^2}{c_0} \int_0^1 \frac{2}{(s-s)^2}$ $\frac{2}{(s-s^2)^{\frac{1}{2}}}ds = \frac{2\pi C_0^2}{c_0}$ and let $R_1 = 1 + r$.

We have

$$
R = \int_0^1 C_0 (1-s)^{\alpha-1} s \left[\max_{0 \le z_1, z_2 \le R_1} f(s, z_1, z_2) + \max_{0 \le z_1, z_2 \le R_1} g(s, z_1, z_2) + \frac{4}{(s-s^2)^{\frac{1}{2}}} \right] ds \le C_0 (R_1^c + R_1^d + \pi).
$$

Let

$$
\lambda^* = \min\{1, R_1(R+1)^{-1}, \frac{R_1}{2r}\}.
$$

Now, if $\lambda < \lambda^*$, Theorem 3.2 guarantees that (4.1) has a positive solution (u, v) with $||u|| \geq 2\pi$ and $||v|| \geq 2\pi$. Example 4.2 Consider the boundary value problem

$$
\begin{cases}\n-D_{0+}^{\alpha}u = \lambda((u-a)(u-b) + \cos(\frac{\pi}{2a}v)), & t \in (0,1), \lambda > 0, \\
-D_{0+}^{\alpha}v = \lambda((v-c)(v-d) + \sin(\frac{\pi}{c}u)), \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n-2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0,1)\n\end{cases}
$$
\n(4.2)

where $b > a > 0$, $d > c > 0$. Then, if $\lambda > 0$ is sufficiently small, (4.2) has two solutions (u_1, v_1) , (u_2, v_2) with $u_i(t) > 0, v_i(t) > 0$ for $t \in (0, 1), i = 1, 2$.

To see this we will apply Theorem 3.4 with

$$
f(t, u, v) = (u - a)(u - b) + \cos(\frac{\pi}{2a}v)
$$
 and $g(t, u, v) = (v - c)(v - d) + \sin(\frac{\pi}{c}u)$.

Clearly, there exists a constant $e_1(t) = e_2(t) = M_0 > 0$ such that

$$
f(t, u, v) + M_0 > 0
$$
, $g(t, u, v) + M_0 > 0$, for $\forall t \in (0, 1)$.

Let $\delta = \frac{1}{16(ab+cd+1)} \min\{ab, cd\}, \varepsilon = \frac{1}{4} \min\{1, a, b\}$ and $c = \int_0^1 C_0(1-s)^{\alpha-1} s ds$. We have

$$
f(t, z_1, z_2) \ge \delta f(t, 0, 0) = \delta(ab + 1), \quad g(t, z_1, z_2) \ge \delta g(t, 0, 0) = \delta cd, \quad \text{for} \quad 0 \le t \le 1, \quad 0 \le z_1, z_2 \le \varepsilon.
$$

Thus (H_1) - (H_2) hold. Since

$$
\overline{f}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{ f(t, u, v) + e_1(t) \} \le ab + cd + 1,\n\overline{g}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{ g(t, u, v) + e_2(t) \} \le ab + cd + 1,\n\overline{h}(\varepsilon) = \max \{ \overline{f}(\varepsilon), \overline{g}(\varepsilon) \} \le ab + cd + 1,
$$

we can choose

$$
\overline{\lambda} = \frac{\varepsilon}{8c(ab+cd+1)}.\tag{4.3}
$$

Now, if $\lambda < \overline{\lambda}$, Theorem 3.1 guarantees that (4.2) has a positive solution (u_1, v_1) with $||u_1|| \leq \frac{1}{4}$. On the other hand,

$$
\lim_{u \uparrow +\infty} \inf \frac{f(t, u, v)}{u} = +\infty, \quad \lim_{v \uparrow +\infty} \inf \frac{g(t, u, v)}{v} = +\infty \text{ for } \forall t \in [\theta_1, \theta_2] \subset (0, 1), \quad u, v \in (0, \infty).
$$

Thus (H₁)-(H₄) also hold. Let $r = \frac{2C_0^2}{c_0}$ and $R_1 > 1 + r$. We have

$$
R = \int_0^1 C_0 (1 - s)^{\alpha - 1} s \left[\max_{0 \le z_1, z_2 \le R_1} f(s, z_1, z_2) + \max_{0 \le z_1, z_2 \le R_1} g(s, z_1, z_2) + 2M_0 \right] ds
$$

and

$$
\lambda^* = \min\{1, \frac{R_1}{2}(R+1)^{-1}, \frac{R_1}{2r}\}.
$$

Now, if $0 < \lambda < \lambda^*$, Theorem 3.2 guarantees that (4.2) has a positive solution (u_2, v_2) with $||u_2|| \geq 1$.

Since all the conditions of Theorem 3.4 are satisfied, if $\lambda < \min{\{\overline{\lambda}, \lambda^*\}}$, Theorem 3.4 guarantees that (4.2) has two solutions u_i with $u_i(t) > 0$ for $t \in (0, 1), i = 1, 2$.

Example 4.3 Consider the boundary value problem

$$
\begin{cases}\n-\mathbf{D}_{0+}^{\alpha}u = \lambda(v^{c} + \cos(2\pi u)), & t \in (0,1), \lambda > 0, \\
-\mathbf{D}_{0+}^{\alpha}v = \lambda(u^{d} + \cos(2\pi v)), \\
u^{(i)}(0) = v^{(i)}(0) = 0, & 0 \le i \le n-2, \\
u(1) = av(\xi), v(1) = bu(\eta), & \xi, \eta \in (0,1)\n\end{cases}
$$
\n(4.4)

where $c, d > 1$. Then, if $\lambda > 0$ is sufficiently small, (4.4) has two solutions (u_1, v_1) , (u_2, v_2) with $u_i(t) > 0$, $v_i(t) > 0$ for $t \in (0,1), i = 1,2.$

To see this we will apply Theorem 3.5 with

 $f(t, u, v) = v^c + \cos(2\pi u), \quad g(t, u, v) = u^d + \cos(2\pi v), \quad e(t) = 2.$

Clearly,

$$
f(t, u, v) + e(t) \ge v^{\alpha} + 1 > 0, \quad g(t, u, v) + e(t) \ge u^{\alpha} + 1 > 0 \quad \text{for } t \in (0, 1),
$$

\n
$$
f(t, 0, 0) = 1 > 0, \quad g(t, 0, 0) = 1 > 0,
$$

\n
$$
\lim_{v \uparrow +\infty} \inf \frac{f(t, u, v)}{v} = +\infty, \quad \lim_{u \uparrow +\infty} \inf \frac{g(t, u, v)}{u} = +\infty \quad \text{for } \forall t \in [\theta_1, \theta_2] \subset (0, 1).
$$

Thus (H_1) - (H_2) and (H_3^*) hold.

First, let $\delta = \frac{1}{2}$, $\varepsilon = \frac{1}{8}$ and $c = \int_0^1 C_0 (1 - s)^{\alpha - 1} s ds$. We have

$$
\overline{f}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{ f(t, u, v) + e_1(t) \} \le 8^{-c} + 3,
$$

\n
$$
\overline{g}(\varepsilon) = \max_{0 \le t \le 1, 0 \le u, v \le \varepsilon} \{ g(t, u, v) + e_2(t) \} \le 8^{-d} + 3,
$$

\n
$$
\overline{h}(\varepsilon) = \max \{ \overline{f}(\varepsilon), \overline{g}(\varepsilon) \},
$$

then $\frac{\varepsilon}{8c\overline{h}(\varepsilon)} \geq \frac{1}{8c(1+3)} = \frac{1}{32c}$.

Let $\overline{\lambda} = \frac{1}{32c}$. Now, if $0 < \lambda < \overline{\lambda}$ then $0 < \lambda < \frac{\varepsilon}{8c\hbar(\varepsilon)}$, Theorem 3.1 guarantees that (4.4) has a positive solution (u_1, v_1) with $||u_1|| \leq \frac{1}{8}$.

Next, from $r = \frac{4C_0^2}{c_0}$ and let $R_1 = 1 + r$. Then, we have

$$
R = \int_0^1 C_0 (1 - s)^{\alpha - 1} s \left[\max_{0 \le z_1, z_2 \le R_1} f(s, z_1, z_2) + \max_{0 \le z_1, z_2 \le R_1} g(s, z_1, z_2) + 4 \right] ds.
$$

Let $\lambda^* = \min\{1, \frac{R_1}{2}(R+1)^{-1}, \frac{R_1}{2r}\}\.$ Now, if $0 < \lambda < \lambda^*$ then Theorem 3.3 guarantees that (4.4) has a positive solution (u_2, v_2) with $||u_2|| \geq 1$.

So, if $\lambda < \min\{\overline{\lambda}, \lambda^*\}$, Theorem 3.5 guarantees that (4.4) has two solutions (u_1, v_1) and (u_2, v_2) with $u_i, v_i > 0$ for $t \in (0, 1), i = 1, 2.$

References

- [1] A. Ghorbani, Toward a new analytical method for solving nonlinear fractional differential equations, Comput. Methods Appl. Mech. Eng., 197(2008) 4173-4179
- [2] I. Podlubny, Fractional Differential equations, Mathematics in Science and Engineering, vol, 198, Academic Press, New Tork/Londin/Toronto, 1999.
- [3] S.G. Samko, A.A. Kilbas, O.I. Marichev, Fractional Integral And Derivatives (Theory and Applications). Gordon and Breach, Switzerland, 1993.
- [4] A. Ashyralyev, A note on fractional derivatives and fractional powers of operators, J. Math. Anal. Appl. 357(2009) 232-236.
- [5] S.P. Mirevski, L. Boyadjiev, R. Scherer, On the Riemann-Liouville fractional calculus, g-Jacobi functions and F-Gauss functions, Appl. Math. Comp., 187(2007) 315-325
- [6] A. Mahmood, S. Parveen, A. Ara, N.A. Khan, Exact analytic solutions for the unsteady flow of a non-Newtonian fluid between two cylinders with fractional derivative model, Commun. Nonlinear Sci. Numer. Simul., 14(2009) 3309-3319.
- [7] G. Jumarie, Table of some basic fractional calculus formulae derived from a modified Riemann-Liouville derivative for non-differentiable functions, Appl. Math. Lett. 22(2009) 378-385.
- [8] V. Lakshmikantham, S. Leela, A Krasnoselskii-Krein-type uniqueness result for fractional differential equations, Nonlinear Anal., 71(2009) 3421-3424.
- [9] Y. Zhou, F. Jiao, J. Li, Existence and uniqueness for fractional neutral differential equations with infinite delay, Nonlinear Anal., 71(2009) 3249-3256.
- [10] N. Kosmatov, Integral equations and initial value problems for nonlinear differential equations of fractional order, Nonlinear Anal., 70(2009), 2521-2529
- [11] C. Bai, Positive solutions for nonlinear fractional differential equations with coefficient that changes sign, Nonlinear Anal., 64(2006) 677-685
- [12] S. Zhang, Existence of Positive Solution for some class of Nonlinear Fractional Differential Equations, J. Math. Anal. Appl. 278(2003) 136-148.
- [13] M. Benchohra, S. Hamani, S.K. Ntouyas, Boundary value problems for differential equations with fractional order and nonlocal conditions, Nonlinear Anal., 71(2009) 2391-2396.
- [14] Z. Bai, Haishen Lü, Positive solutions for boundary-value problem of nonlinear fractional differential equation, J. Math. Anal. Appl. 311(2005) 495-505.
- [15] C. Yuan, Positive solutions for (n-1, 1)-type conjugate boundary value problems of nonlinear singular fractional differential equations, E. J. Qualitative Theory of Diff. Equ., $252(2010)$ 804-812.
- [16] C. Yuan, D. Jiang, and X. Xu, Singular positone and semipositone boundary value problems of nonlinear fractional differential equations, Math. Probl. Eng., Volume 2009, Article ID 535209, 17 pages.
- [17] X. Su, Boundary value problem for a coupled system of nonlinear fractional differential equations, Appl. Math. Lett., 22(2009) 64-69.
- [18] B. Ahmad, S. Sivasundaram, Existence results for nonlinear impulsive hybrid boundary value problems involving fractional differential equations, Nonlinear Anal. Hybrid Systems, 3(2009) 251-258.
- [19] B. Ahmad, J.J. Nieto, Existence results for a coupled system of nonlinear fractional differential equations with three-point boundary conditions, Comput. Math. Appl., 58 (2009) 1838-1843.
- [20] M. Benchohra, S. Hamani, The method of upper and lower solutions and impulsive fractional differential inclusions, Nonlinear Anal. Hybrid Systems, 3 (2009) 433-440.
- [21] H. Amann, Parabolic evolution equations with nonlinear boundary conditions, in: Nonlinear Functional Analysis and Its Applications, Berkeley (1983), in: Proc. Sympos. Pure Math., Amer. Math. Soc., Providence, RI 45 (1986) 17-27.
- [22] H. Amann, Parabolic evolution equations and nonlinear boundary conditions, J. Differential Equat. 72 (1988) 201-269.
- [23] K. Deng, Blow-up rates for parabolic systems, Zangew Math. Phys. 47 (1996) 132-143.
- [24] K. Deng, Global existence and blow-up for a system of heat equations with nonlinear boundary condition, Math. Methods Appl. Sci. 18 (1995) 307-315.
- [25] Z.G. Lin and C.H. Xie, The blow-up rate for a system of heat equations with nonlinear boundary condition, Nonlinear Anal., 34 (1998) 767-778.
- [26] M. Pedersen, Zhigui Lin. Blow-Up Analysis for a System of Heat Equations Coupled through a Nonlinear Boundary Condition, Appl. Math. Lett., 14 (2001) 171-176.
- [27] D.G. Aronson, A comparison method for stability analysis of nonlinear parabolic problems, SIAM Rev. 20 (1978) 245-264.
- [28] A. Leung, A semilinear reaction-diffusion prey-predator system with nonlinear coupled boundary conditions: Equilibrium and stability, Indiana Univ. Math. J., 31 (1982) 223-241.
- [29] R.P. Agarwal, M. Meehan, D. O'Regan, Fixed point theory and applications, Cambridge University Press, 2001.
- [30] M. A. Krasnosel'skii, Positive solutions of operator equations, Noordhoff Gronigen, Netherland, 1964.

(Received September 4, 2011)