

# Estimation of Grain Size Distribution of Friction Stir Welded Joint by using Machine Learning Approach

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KEYWORD	ABSTRACT
Friction Stir Weld- ing; Machine Learn- ing; Grain Size; Python Programming	Machine learning has widely spread in the areas of pattern recognition, pre- diction or forecasting, cognitive game theory and in bioinformatics. In recent days, machine learning is being introduced into manufacturing and material industries for the development of new materials and simulating the manufac- turing of the required products. In the recent paper, machine learning algo- rithm is developed by using Python programming for the determination of grain size distribution in the microstructure of stir zone seam of Friction Stir Welded magnesium AZ31B alloy plate The grain size parameters such as an equivalent diameter, perimeter, area, orientation etc. were determined. The results showed that the developed algorithm is able to determine various grain size parameters accurately.

## 1. Introduction

The development of various Artificial Intelligence applications is made possible by the usage of Machine Learning algorithms. In the available set of a massive amount of data, the Machine learning model uses a statistical technique to derive the required pattern. The Machine Learning model generally feeds on digitally available data which is composed of numbers, images, videos, or texts. Machine Learning algorithms generally operate on low-level tasks in which raw data is processed and is further acquired by an Artificial Intelligence-based system. The Machine Learning model generally feeds on digitally available data which is composed of numbers, images, videos, or texts. Machine Learning algorithms generally operate on low-level tasks in which raw data is processed and is further acquired by an Artificial Intelligence-based system. The Machine Learning model generally feeds on digitally available data which is composed of numbers, images, videos, or texts. Machine Learning algorithms generally operate on low-level tasks in which raw data is processed and is further acquired by an Artificial Intelligence-based system. The Machine Learning algorithm's working principle is based on three points. Firstly, a hypothesis of a certain phenomenon is formulated. Secondly, to test the hypothesis i.e. for the validation of the chosen model, a dataset is collected. Thirdly, the given hypothesis is refined by iterating it.

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Traditional manufacturing processes are being spiced up by the introduction of various Machine Learning algorithms in their applications. For example, GE research is combining artificial intelligence and machine learning models with "physics" to inspection, processing, and advanced manufacturing design to obtain the real-world product [1]. Li et al used a data-driven machine learning model approach for predicting the surface roughness of an additively manufactured part. It was observed that the developed machine learning model was able to predict the surface roughness with good accuracy [2]. Moreno et al. proposed an image processing and machine learning model based on the Random Forest algorithm for automatic classification of pores present in Al-alloys by laser melt deposition. The proposed model resulted in an accuracy of 94.41 % [3]. Kopper et al. predicted the mechanical property i.e. Ultimate Tensile Strength (UTS) of high-pressure die-cast Al-alloy component by using various regression machine learning models like Support Vector Machines (SVM), XG Boost, and Random Forest algorithm [4].

Machine Learning algorithms are also finding applications in solid-state welding processes like Friction Stir Welding (FSW). Unlike other conventional welding processes, Friction Stir Welding does not use any filler material for joining purposes. Friction Stir Welding tool which is harder than the base material to be joined is used. The schematic representation of the Friction Stir Welding process is shown in Figure 1 [5]. Verma et al. [6] used three machine learning models i.e. Artificial Neural Network, Random Forest, and M5P tree regression for analyzing and predicting the tensile behavior of aviation-grade aluminum alloy friction stir welded joint. It was observed from results that the Random Forest algorithm model outperforms the other two models in terms of predicting the tensile behavior accurately. Hartl et al. [7] used three Artificial Neural Network models i.e. Convolutional Neural Networks, Feedforward fully connected Neural Networks, and Recurrent Neural Networks for predicting the surface quality of friction stir welded EN AW-6082 T6 sheets. Out of these three used Artificial Neural Networks, Convolutional Neural Networks achieved the highest classification accuracy. Srinivasan et al. [8] improved the degraded microstructure of the friction stir welded joint by using a hybrid sparsity machine learning model.

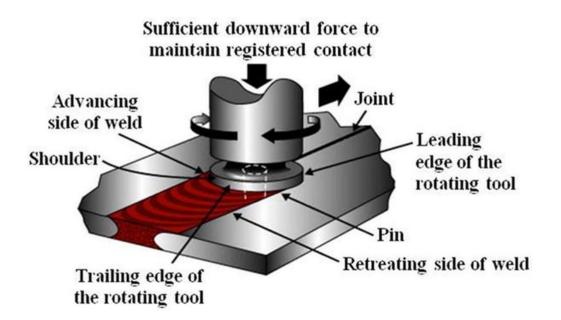


Figure 1. Working Mechanism of Friction Stir Welding process [5].

In the recent study, a machine learning algorithm has been developed for the study of grain size distribution in the microstructure of stir zone seam of Friction Stir Welded magnesium AZ31B obtained by Subramani et al [9].

### 2. Material and Methods

In the experiment, AZ31 B Magnesium alloy plates (commercial) of 6 mm thickness were joined by Friction Stir Welding process [9]. The weld plates were in the dimensions of 100 mm length and 75 mm width. SiC nanoparticles were incorporated and compacted in the grooves of width 0.3, 0.6, 0.9, 1.2, and 1.5 mm, of the corresponding volume percentages were indicated as V4, V8, V12, V16, and V20, respectively. The schematic diagram of volume fraction sample is shown in the Figure 2.

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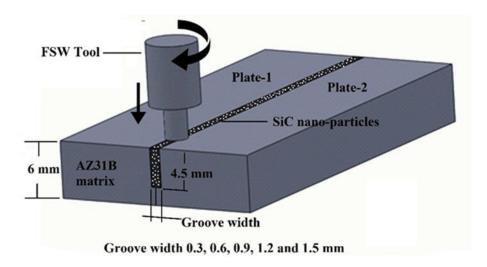


Figure 2 : Volume fraction sample [9].

The process parameter of the experimentation is shown in the Table 1.

Table 1. Friction stir welding (FSW) process parameters used in this study.

<b>Control Parameters</b>	Values			
Tool rotational speed, N (rpm)	1250 rpm			
Tool travel rate, F (mm/min)	25 mm/min			
Volume percentage V (%)	4 (V4), 8 (V8), 12 (V12), 16 (V16), 20 (V20)			
Groove width (W)	0.3, 0.6,			
0.9, 1.2, 1.5 D/d ratio and Pin height in r	nm 3 and			
5.7 mm Tool Pin profile profile Tool material	Cylindrical threaded tool pin H13 tool steel			

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The optical microstructure of the matrix alloy (Figure3a) and base metal welded joint without nano-SiC (Figure3b) is shown in Figure 3.

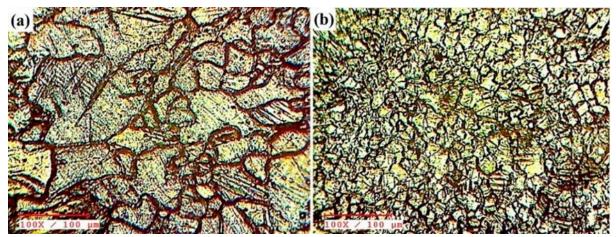


Figure 3. Optical microstructure: (a) as-received matrix alloy (b) FSW AZ31B joint (without reinforcement) [9].

Grain size distribution analysis is done by loading the above microstructures which have a whole bunch of grains and extracting some statistical features out of it. The given RGB image is converted to a grayscale image. It is important to define a particular scale in this case in order to track the size of the pixel while working on a microscopic image. The first step is to read an image and define pixel size state(if needed to convert results into microns, no pixels). The second step involves the denoising process if required and threshold image to separate grain from boundaries. Thirdly, image clean up is performed if needed and create a mask for observed grains in the microstructure. The fourth step involves the labeling of grains in the masked image. At the fifth stage, the measurement of the properties of each grain in the microstructure is performed. At the sixth and last stage, output results are obtained in the form of a CSV (Comma Seperated Values) file.

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## 3. Results and Discussions

The important Python programming libraries which were important for coding purpose are cv2, numpy, pyplot from matplotlib, ndimage, io, color to show images in the color library so we can assign a different color to grains, measure library to measure the grain size distribution. The image is read by indicating the file path, then the scale is defined which is 1 pixel= $0.5\mu$ m which is further multiplied to every measurements as shown in the Figure 4 and Figure 5. If the image has a scale bar in the microscope then the image needed to be cropped by slicing the dataset of an image array.

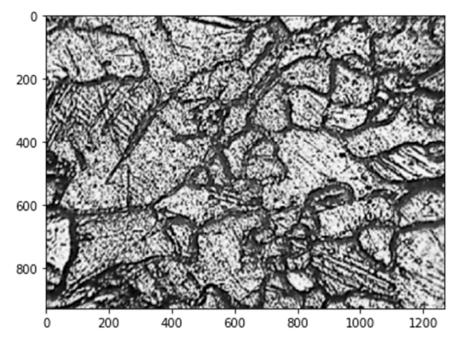


Figure 4. Loaded image of optical microstructure of received matrix alloy

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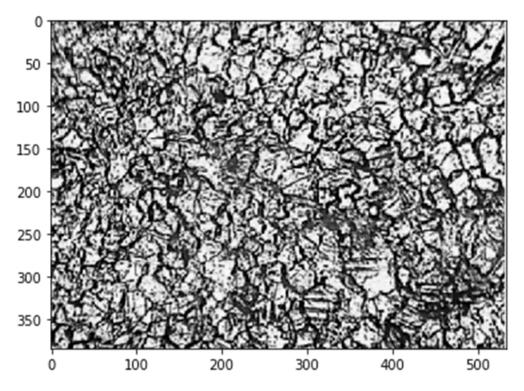


Figure 5. Loaded image of optical microstructure of FSW AZ31B joint (without reinforcement).

Step 1 of the thresholding is to look at the histogram itself as shown in Figure 6 and Figure 7. The loaded images are in form of a 2D array, so in order to obtain a histogram we need 1D array. So we need to flatten the image which takes a 2D image and flatten it to a 1D array of bins=100 and range = (0,255). From Figure 6 it is observed that a bunch of pixels lies between 130–200 and From Figure 7 it is observed that a bunch of pixels lies between 60–200.

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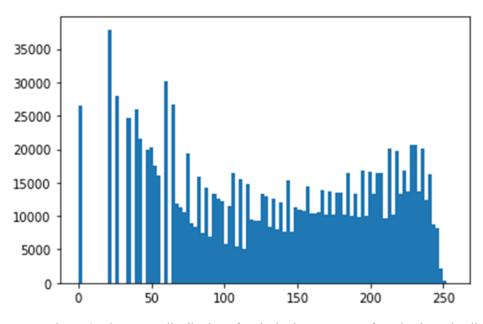


Figure 6. Histrogram distribution of optical microstructure of received matrix alloy

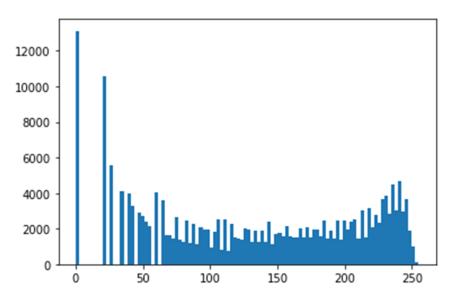


Figure 7. Histogram distribution of the optical microstructure of FSW AZ31B joint (without reinforcement).

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The two types of thresholding operation can be done i.e. either manual thresholding or auto thresholding. The threshold value obtained for the optical microstructure of received matrix alloy is 130 while thresholded value obtained for the optical microstructure of FSW AZ31B joint (without reinforcement) is 128. The obtained thresholded image for the optical microstructure of received matrix alloy and FSW AZ31B joint (without reinforcement) is shown in the Figure 8 and Figure 9.

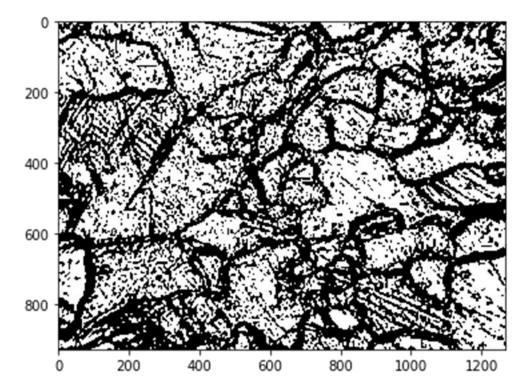


Figure 8. Thresholded image of the optical microstructure of received matrix alloy

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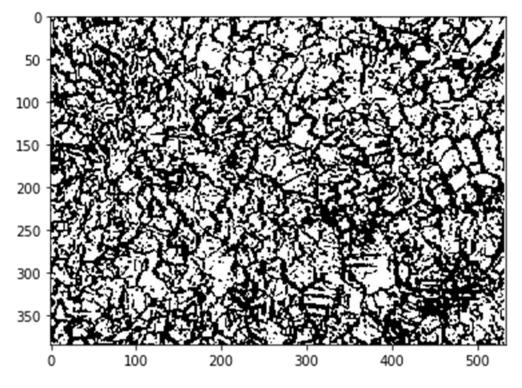


Figure 9. Thresholded image of the optical microstructure of FSW AZ31B joint (without reinforcement).

It is observed that all pixels corresponding to the grain will have a value of 255 and all pixels corresponding to the grain boundary have a value 0. So this is only a threshold image, not a binary image. So, we need to convert this thresholded image to a binary image. The thresholded image shows some missing pixels, we can close these areas of the grain by eroding and dilating process. When we use the eroding process then the grain will shrink by 1 pixel and when we use dilating process they go up by 1 pixel. In order to execute eroding and dilating operation, we created kernel size of (3,3) of type int 8. Eroding and dilating operation is carried out on thresholded image. The thresholded image is nothing but 8-bit integer with all values of 255 and 0's. It is a binary image but the system doesn't know its a binary image. So it is converted to a binary image with the help of masking as shown in the Figure 10 and Figure 11.

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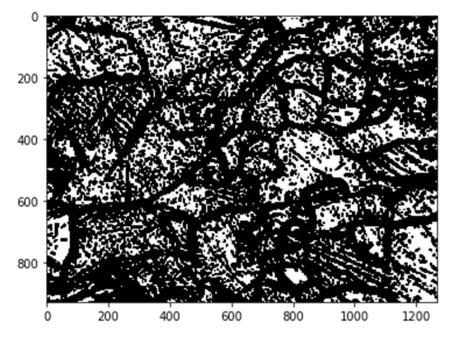


Figure 10. Masked image of the optical microstructure of received matrix alloy.

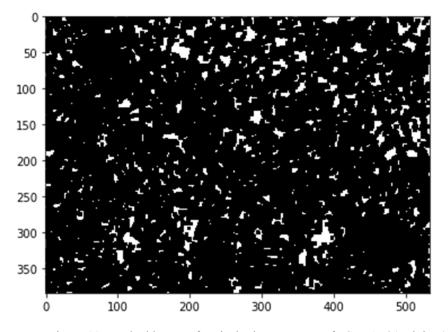


Figure 11. Masked image of optical microstructure of FSW AZ31B joint (without reinforcement).

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Each grain is labeled in the masked image as shown in Figure 12 and Figure 13. Structure factor of [[1,1,1], [1,1,1], [1,1,1]] is used to define the nature of pixel connection i.e. whether connected or disconnected. In the ndimage library, there is a function called label which labels the unconnected grains. Label assignment is done through the masked image and assigns a value to the all unconnected objects.

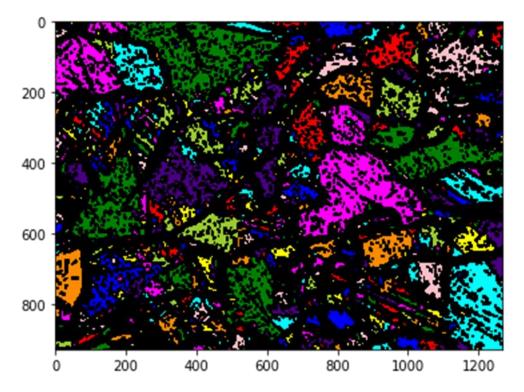


Figure 12. Labeled image of the optical microstructure of received matrix alloy

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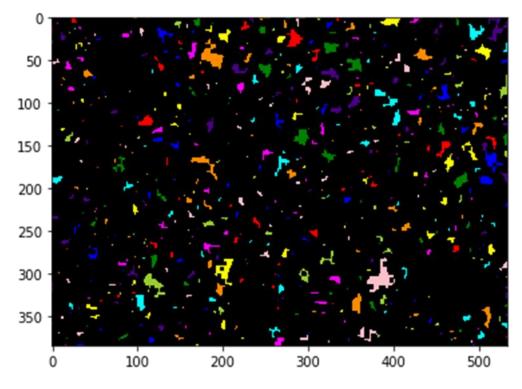


Figure 13. Labeled image of the optical microstructure of FSW AZ31B joint (without reinforcement).

Measuring the grain property is done by the extraction of property from each labeled image. The obtained measurement of grain size distribution of the optical microstructure of the received matrix alloy and FSW AZ31B joint (without reinforcement) is shown in the Table 2 and Table 3. Table 2 obtained as a CSV file has 1296 grain distribution properties of the optical microstructure of received matrix alloy out of which only 10 is shown in the Table 2 (rest can be further found in supplementary file) while Table 3 has 696 grain distribution properties out which only 10 is shown in the Table 3 (rest in supplementary file).

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Grain Num- ber	Equiva- lent Di- ameter	Orienta- tion	Major Axis	Minor Axis	Perim- eter	Area	Min Inten- sity	Mean Inten- sity	Max Inten- sity
1	4.5834978 44	76.241 38617	7.91 1677	3.34 9746	17.4 1421	16. 5	184	217. 3333	234
2	2.6462 83714	۔ 42.66053 638	3.28 4856	2.28 4291	8.12 132	5.5	138	159. 4091	178
3	3.2410 22407	17.795 39566	3.86 4296	2.74 9772	9.82 8427	8.2 5	180	208. 1212	225
4	22.546 41631	۔ 87.87354 752	59.2 9705	18.5 4393	259. 4858	39 9.25	138	214. 2918	251
5	88.073 22872	83.002 13477	190. 3864	102. 7502	364 2.112	60 92.25	131	216. 7196	253
6	2.7057 5819	۔ 84.64231 874	4.73 0204	1.53 8244	8.70 7107	5.7 5	192	218. 7391	240
7	0.7978 84561	0	1	0	0	0.5	165	169	173
8	18.220 79063	77.788 18815	60.8 2087	6.83 4718	140. 9264	26 0.75	157	229. 8102	249
9	3.3377 90589	85.655 51415	7.37 0103	1.59 0775	13.7 0711	8.7 5	175	210. 3143	227
10	4.8533 4231	83.956 76619	11.4 5849	3.07 6257	23.4 3198	18. 5	172	218. 3919	244

#### Table 2: Grain Size distribution Property of received metal matrix alloy

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Grain Num- ber	Equiva- lent Di- ameter	Orienta- tion	Major Axis	Minor Axis	Perime- ter	Area	Min Inten- sity	Mean Intensi- ty	Max Inten- sity
1	3.191	25.19	3.54	2.99	9.70			202.	
	538	141	9503	1304	7107	8	146	5313	239
2	0.977		1.63			0.			
	205	0	2993	0	0.5	75	233	242	247
3	1.381	90.00	3.41			1.		198.	
	977	003	565	0	2	5	177	1667	230
4	0.977	90.00	1.63			0.		235.	
	205	003	2993	0	0.5	75	232	3333	239
5	4.259	-	5.26	4.03	15.9	1		233.	
	538	23.7163	181	5167	3198	4.25	199	1228	252
6	2.585	66.20	3.47	2.47	7.81	5.		220.	
	441	713	4742	0433	066	25	152	619	248
7	3.038	-	7.64	1.26	12.3	7.		225.	
	254	86.7755	8602	0656	1066	25	176	8621	244
8	1.692	84.01	4.14	0.71		2.		200.	
	569	196	3543	4185	4	25	149	5556	243
9	3.141	-	7.20	4.94	13.1	7.		232.	
	275	40.6765	3717	8255	0355	75	184	2581	247
10	1.871	80.00	2.44	1.45	5.12	2.		224.	
	205	848	9648	995	132	75	195	0909	249

#### Table 3: Grain Size distribution Property of FSW AZ31B joint (without reinforcement).

#### 4. Conclusion

The research work focuses on the development of machine learning algorithm for estimating the grain size distribution property of received matrix alloy and FSW AZ31B joint (without reinforcement) by using Python Programming. The various grain size parameters such as equivalent diameter, orientation, major axis, minor axis, perimeter, area, minimum intensity, maximum intensity and mean intensity were successfully determined. It is further observed from the Table 2 and Table 3 that the area, perimeter and equivalent diameter of the grain decreases after carrying out Friction Stir Welding process due to the refinement. So, it can be concluded that the machine learning approach can be easily incorporated in mate-

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rial science and manufacturing domain in order to reduce the cost and time of the experiment. It is also observed that there is loss of information by the observation of two and three dimensional metrics distribution such as aspect ratio, number density, total curvature, interface line and area density when conventional method is used for microstructure characterization but the application of machine learning overcomes these problems. The future work will deal with implementing this algorithm to the microstructure obtained by other characterization techniques also some work will be carried out on the development of a unique microstructure identifier known as microstructural fingerprint in order to classify micrographs. Machine learning can be further combined with the advanced microstructural metrics for improving the classification accuracy.

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