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# Design guidelines for H-Darrieus wind turbines: optimization of the annual energy yield

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## Abstract

H-Darrieus wind turbines are gaining popularity in the wind energy market, particularly as they are thought to represent a suitable solution even in unconventional installation areas. To promote the diffusion of this technology, industrial manufacturers are continuously proposing new and appealing exterior solutions, coupled with tempting rated-power offers. The actual operating conditions of a rotor over a year can be, however, very different from the nominal one and strictly dependent on the features of the installation site.

Based on these considerations, a turbine optimization oriented to maximize the annual energy yield, instead of the maximum power, is thought to represent a more interesting solution. With this goal in mind, 21600 test cases of H-Darrieus rotors were compared on the basis of their energy-yield capabilities for different annual wind distributions in terms of average speed.

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23 The wind distributions were combined with the predicted performance maps of the rotors  
24 obtained with a specifically developed numerical code based on a Blade Element Momentum  
25 (BEM) approach. The influence on turbine performance of the cut-in speed was accounted for,  
26 as well as the limitations due to structural loads (i.e. maximum rotational speed and maximum  
27 wind velocity). The analysis, carried out in terms of dimensionless parameters, highlighted the  
28 aerodynamic configurations able to ensure the largest annual energy yield for each wind  
29 distribution and set of aerodynamic constraints.

### 30 **Keywords**

31 Darrieus, VAWT, wind turbine, design, energy yield, aerodynamics

### 32 **1. Introduction**

33 In 2011, the wind energy market grew by 6% compared to 2010, despite the economic and  
34 political turmoil in Europe and North America, with a newly installed power of 40.5 GW [1].

35 The great bulk of installed wind energy plant is today in the form of large wind farms [2]  
36 which mainly comprehend large Horizontal Axis Wind Turbines (HAWTs) feeding into power  
37 supply grids: turbines are becoming more and more efficient and a scale-up tendency is clearly  
38 distinguishable. Moreover, technological improvements in design and efficient maintenance  
39 have considerably reduced their operating cost and consequently disclosed new diffusion  
40 frontiers like the offshore applications [3-4]. Whereas these installations are a valuable addition  
41 to the grid capacity, they actually do not benefit people who are not served by grids. As a  
42 consequence, much interest is being paid to understand where wind turbines can effectively  
43 represent an alternative for delocalized power production [5-6]. Paradoxically, however, there  
44 has been very little research and commercial development in the second part of the century on  
45 small stand-alone systems, although great improvements in the blade aerodynamic design have  
46 been made. In recent times, a reversal of this trend has been fortunately experienced.

47 Increasing interest is especially being paid by architects, project developers and local  
48 governments to understand where small wind turbines can effectively be exploited to provide  
49 delocalized power in the built environment (e.g. see Refs. [7-12]). The real feasibility of this  
50 scenario has, however, yet to be proved, both in terms of real energy harvesting and of  
51 compatibility of the machines with a populated area [9-10,13].

52 In particular, Vertical-Axis Wind Turbines (VAWTs), both drag [14-16] and lift-driven [17-  
53 20], are gaining popularity in the wind energy scenario, especially in medium and small-size  
54 installations, where they can work effectively even in presence of low-speed and unstructured  
55 flows with low noise emissions and high reliability. Among others, H-Darrieus rotors are  
56 increasingly appreciated in unconventional contexts as they are even assumed to increase their  
57 performance in case of an oncoming flow misaligned with respect to the axis of the rotor [17-  
58 19]. In order to promote the diffusion of this technology, on one hand, industrial manufacturers  
59 are developing new and more appealing design solutions (e.g. [21-25]); on the other hand,  
60 efforts are being devoted to reducing the initial cost of the machines (primarily by means of  
61 new materials) and to increasing the efficiency, in order to make them competitive with respect  
62 to more conventional Horizontal Axis Wind Turbines (HAWTs) [20].

63 Focusing on the commercial aspects, it is also worth pointing out that almost all the industrial  
64 rotors are generally designed and optimized for a specific wind speed (i.e. the speed which  
65 ensures the highest energy production), but the rated power values, which are often perceived  
66 by the final customer as the most valuable indicator of the quality of the product, are declared  
67 for their nominal wind velocity, i.e. the highest functioning speed, which provides the  
68 maximum power production. Although the importance of accounting for energy instead of  
69 power does not come as a surprise for the applied-energy technicians, the implications of this  
70 theoretical dichotomy are quite often not completely understood by the final customer of small  
71 and medium wind turbines.

72 In detail, the actual operating conditions of a rotor over a year can indeed be very far from the  
73 nominal one [9-10,26]. In particular, the available wind energy can be concentrated at the lower  
74 wind velocities of the yearly distribution in the installation site, which can be often correctly  
75 approximated by a Weibull function [27-30]; in addition, the specific features of the final  
76 environment (e.g. local accelerations, effects of obstacles, etc.) are very important in  
77 determining the real characteristics of the flow which effectively invests the rotor (e.g. [9-10]).  
78 As a result, a turbine optimized only for a singular wind speed could provide poor performance  
79 during the largest part of its operating time, with a remarkable reduction of the energy  
80 produced and, consequently, of the suitability of the investment [10].

81 Stated the above, a design approach based on the maximization of the annual energy-yield  
82 (i.e. the sum of the energy contributions at all the wind speeds experienced over the year) was  
83 thought to represent a more valuable solution.

## 84 **2. Energy-yield-based design strategy**

85 The main goal of this study was to define some effective design guidelines for Darrieus wind  
86 turbines which would be able to ensure the maximum energy harvesting in a yearly horizon as  
87 a function of the attended wind distribution in the installation site.

88 With this goal in mind, 21600 test cases, i.e. permutations of a specific geometrical  
89 configuration (300 cases), an airfoil (4 selections), a wind distribution (6 cases) and a load  
90 system (3 cases), were tested and analyzed by means of a specifically developed numerical  
91 code based on an advanced BEM method, in order to highlight the configurations which ensure  
92 the largest annual energy yield for each wind condition.

### 93 **2.1 Wind distributions**

94 As a first step of the analysis, six annual wind profiles were hypothesized. As discussed, the  
95 most logical representation of the annual wind distribution must be based on the assumption of  
96 a Weibull distribution [27-30]. In particular, in the present study a constant shape factor equal

97 to 2.0 (Rayleigh distribution) was considered, whereas the scale factor was modified in each  
98 case in order to ensure an average wind speed ( $\bar{U}$ ) increasing by one from 3 to 8 m/s.

99 The choice of the Rayleigh distribution was based on literature data [9-10], which found that  
100 this particular Weibull curve nicely approximates the wind distributions of some medium-low  
101 velocity sites in Europe. The presented method, however, is of general validity and can be  
102 applied to any Weibull distribution attended in the installation site.

103 In further detail, the wind profiles investigated in this study are shown in Figure 1, where the  
104 cut-in and the cut-out limits are also displayed. In particular, it is worth pointing out that a  
105 maximum cut-out velocity of 18 m/s was imposed for safety reasons to all the tested rotors  
106 [26], based on the industrial experience for these rotors. On the other hand, the cut-in speed  
107 was specifically calculated for each rotor on the basis of its behavior at low wind speeds: as  
108 shown by Figure 1, a variable cut-in speed between 2 and 3 m/s was measured in the tested  
109 rotors. In particular, it is worth pointing out that in the present study the attention was focused  
110 only on the Darrieus machines, evaluating their actual self-starting characteristics. Although  
111 recent studies (e.g. [31-32]) showed indeed that the self-starting can be enhanced by coupling  
112 these rotors with drag-driven devices, the matching of the two turbines was not considered in  
113 the scope of the present work and destined to further studies.

## 114 **2.2 Main design parameters for Darrieus-type turbines**

115 The proper set of rotor configurations to be analyzed was then defined. Due to the large  
116 number of variables involved in the aerodynamic design of Darrieus rotors [20,26], some  
117 preliminary assumptions were needed to focus the analysis on a significant family of turbines.

118 In particular, the following main choices were made:

- 119 ■ The H-Darrieus configuration with straight blades was selected (see Figure 2). This turbine  
120 shape is presently the most exploited and studied solution in Darrieus turbines design, due  
121 to higher efficiency and lower manufacturing costs with respect to original troposkien-  
122 bladed rotors [20,24,33].

123   ▪ A blades number  $N=3$  was assumed. This turbine’s architecture guarantees a good  
 124 efficiency and a sufficiently flat torque profile during revolution, without compromising  
 125 solidity [20,23-24].

126   ▪ At least two supporting struts for each blade were applied (the number was increased by  
 127 one strut for each blade whenever too high structural stresses were calculated) [21,26].

128 On these bases, the resulting performance maps must be related only to this typology of rotors  
 129 and future works will be devoted at extending the validity range of the analyses.

130 Then, some significant design parameters to be investigated were chosen [26]. In order to  
 131 define a set of parameters able to provide a prompt description of the geometrical proportions  
 132 of the rotor, the attention was focused on:

- 133   ▪ The *height/diameter ratio* ( $\Phi=H/D$ );
- 134   ▪ The *chord/diameter ratio* ( $\xi=c/D$ );
- 135   ▪ The *swept area* of the rotor ( $A$ );
- 136   ▪ The airfoil type;
- 137   ▪ The struts dimensions.

138 In order to understand the aerodynamic implications of these parameters, one has to focus on  
 139 the physical functioning of Darrieus rotors. In particular, if it is generally well understood that a  
 140 rotational axis perpendicular to the flow actually results in a flow incidence continuously  
 141 variable during the revolution, the influence of the chord-based Reynolds number on the  
 142 airfoils (Eq.1) is generally underestimated, especially in small and medium rotors.

143 
$$Re_c = \frac{wc}{\nu} \tag{1}$$

144 In further details, when small-sized rotors are designed, the Reynolds number can be very low  
 145 (especially in case of low wind speeds), even lower than  $10^5$ , being therefore very critical for a  
 146 correct airfoil functioning.

147 A suitable  $Re_c$  on the blade can be achieved through different ways. Assuming that the wind  
 148 speed cannot be altered (i.e. a specific wind speed is analyzed), the most intuitive solution

149 would consist in a direct increase of the chord  $c$  (Eq. 1). This solution is definitely able to  
150 accomplish the goal, but strict limitations to its use must be introduced. In particular, notably  
151 longer chords produce both a reduction of the Aspect Ratio of the blade (i.e. the ratio between  
152 the blade length and the chord - Eq. 2) and an increase of the solidity of the rotor (Eq. 3)  
153 [21,24,26].

$$154 \quad AR_b = \frac{H}{c} \quad (2)$$

$$155 \quad \sigma = \frac{Nc}{D} \quad (3)$$

156 The first effect actually results in a detriment of the blade efficiency [18,21], as the increase  
157 of the rotor's height to compensate cannot be always provided as the swept area of the rotor is  
158 generally a priori selected (Eq.4 for an H-Darrieus).

$$159 \quad A = H \cdot D \quad (4)$$

160 On the other hand, an increase of the solidity also produces a reduction of the peak efficiency  
161 of the rotor [20,21,24], which once more cannot be simply compensated by reducing the  
162 diameter because this countermeasure would directly reduce the peripheral speed, thus leading  
163 to an undesired reduction of the relative speed  $W$  (given by the vector sum of the peripheral  
164 speed and the wind speed reduced by the induction factor  $a$  - see Eq.5):

$$165 \quad W = \omega R + U(1 - a) \quad (5)$$

166 The second way to control the Reynolds number on the blade is in fact the modification of the  
167 relative speed. Having assumed that the wind speed  $U$  is fixed, the only way to modify  $w$  is  
168 related to a variation of the peripheral speed  $\omega R$ .

169 Analogous to the previous analysis a double choice is given. An increase of the turbine radius  
170 would directly improve the Reynolds number: being  $A$  fixed, the turbine's height would be  
171 reduced (Eq. 4) and then the Aspect Ratio of the blades (Eq.2), leading to less efficient blades.  
172 On the other hand, increasing the revolution speed would improve the relative speed, having,



173 however, a notable impact on the incidence angles range and the structural behavior of the  
174 rotor.

175 Based on the above, the influence of the selected parameters can be readily highlighted.

176 ▪  **$\Phi$  ratio** - The  $\Phi$  ratio has a double effect in defining the features of the rotor. From an  
177 aesthetic point-of-view, it can be considered as a “shape factor” of the turbine, i.e. an  
178 indicator of the visual proportions of the virtual cylinder swept during the revolution. On  
179 the other hand, for a fixed swept area, low  $\Phi$  values are typical of a machine in which the  
180 optimal flow conditions on the airfoil are obtained thanks to large diameters in order to  
181 increase the peripheral speed. In this configuration, the velocity triangles on the airfoils are  
182 improved but the blades are generally short, with more relevant losses due to end-effects.  
183 Conversely, high  $\Phi$  values can be related to machines in which the efficiency of the blade  
184 (high blade Aspect Ratios - Eq. 2) is preferred.

185 ▪  **$\zeta$  ratio** - The  $c/D$  ratio is a direct indicator of the solidity ( $\sigma$ ) of the rotor (Eq. 3). High  
186 values of  $\zeta$  generally indicate that the chord length is increased to improve the Reynolds  
187 number, whereas low  $\zeta$  values can be related to rotors in which the relative wind speed is  
188 increased by means of an increase of the relative wind speed on the airfoil (Eq. 5).

189 ▪ **Swept Area ( $A$ )** - As one can argue from the previous discussion, the swept area of the  
190 turbine (Eq. 4 - valid for an H-Darrieus rotor) is unfortunately a dimensional parameter  
191 which cannot be bypassed in the analysis of small rotors. In particular, larger swept areas  
192 ensure less demanding limits of the turbine’s radius, ensuring higher peripheral speed and,  
193 therefore, fewer problems in ensuring a good Reynolds number on the blades. Moreover,  
194 being the optimal solidity ranges generally constant [20-21], the minimum requested  
195 chords are generally smaller, resulting in higher Aspect Ratios and more efficient blades.

196 ▪ **Design variables** - The airfoil type is very important in defining the performance of a  
197 Darrieus turbine; as a result, the dimensionless analysis on the best design trends must be  
198 individually carried out for each specific airfoil family [20,34-35]. Finally, the struts’

199 shape and dimensions must be carefully taken into account as they can substantially  
200 modify the power output of an H-Darrieus rotor (see Refs. [21,24,33,36]) due to the  
201 parasitic torque that is produced during the revolution. To this purpose, the impact of the  
202 struts was also included in this study by assuming a variation of their dimensions, and even  
203 number, as a function of the structural stresses on the blades.

### 204 **3. Test plan and design parameters**

205 The test plan of the investigated configurations is summarized in Table 1.

206 The limits of the  $\zeta$  and  $\Phi$  parameters were defined on the basis of a survey of the technical  
207 literature (e.g. [5,20,24]). In particular, the  $\xi$  range was limited to 0.200 as higher values would  
208 lead to solidities higher than 0.6. Design choices over this limit are in fact considered to be  
209 unsuitable for H-Darrieus rotors [20,24], due to the fact that the turbine is deemed to become  
210 similar to a solid obstacle for the wind and the interactions between upwind and downwind  
211 blades becomes so strong to compromise the aerodynamics of the airfoils. In addition, the  
212 theory applied in the simulations could become less predictive in similar test-cases [20].

213 The choice of the aerodynamic airfoils was also based on a literature survey [5,20-21]. In  
214 particular, four different airfoils were investigated in this work, in order to highlight the impact  
215 of their aerodynamic characteristics on the effective energy harvesting of the turbine. The  
216 airfoils were selected among the 4-digit NACA family, which is quite a conventional solution  
217 in Darrieus VAWTs [5,20,34-35].

218 In detail, three uncambered airfoils with different thickness/chord ratios (NACA0012,  
219 NACA0015, NACA0018) were compared to an asymmetrical and lightly-cambered airfoil  
220 (NACA4415). The first group of airfoils is a widely exploited solution in Darrieus turbines, as  
221 it ensures a suitable resistance to the stall coupled with good lift outputs at medium-range  
222 Reynolds numbers. Moreover, a symmetric airfoil is able to provide the same lift contribution  
223 either with positive or negative incidence [20,24]. On the other hand, a cambered profile, like  
224 the selected NACA4415, has been suggested in technical literature (e.g. see [5,21]) as an

225 interesting design choice in order to ensure high peak values of the torque in low-velocity  
226 cases, although some doubts on their effective application are due to the different behaviour of  
227 a non-symmetric airfoil in case of a positive or negative incidence [21].

228 Focusing on the boundary conditions in terms of loads applied to the rotor, three different  
229 configurations were analyzed:

- 230 ▪ **CASE 1 – Aerodynamics only:** in this configuration, the contribution of the resistant  
231 torque of the struts was not considered. By doing so, this configuration actually refers to a  
232 hypothetical solution of a fully aerodynamic relationship between the geometrical features  
233 of the rotor and the power performance. Although not practically applicable, the analysis  
234 of these results allows one to define the aerodynamic trends and to directly compare the  
235 functioning behavior of machines having different areas. Moreover, by defining the purely  
236 aerodynamic requests, one can also directly identify the effects induced by the secondary  
237 and parasitic effects due to auxiliary organs (e.g. the struts) and external loads.
- 238 ▪ **CASE 2 – Centrifugal load:** the contribution of the resistant torque of the struts was again  
239 not considered but a limitation on the centrifugal stress acting on the blades was added as a  
240 function of the rotational speed of each model.
- 241 ▪ **CASE 3 – Struts’ parasitic torque:** in this latter configuration, both a limitation on the  
242 centrifugal stress on the blades and variable struts dimensions, as a function of the  
243 rotational speed of each model, were included. Moreover, the resistant torque of the struts  
244 was taken into account.

245 In order to give a correct estimation of the structural loads, in this study a manufacturing  
246 technology based on extruded aluminium blades with a hollowed section was considered,  
247 utilizing real data on both the maximum centrifugal stress and on the maximum mechanical  
248 stress on the struts available from previous design experiences of the authors [33].

249 In further detail, in Case 2 the cut-out speed of the turbine was calculated in each case-study  
250 based on the hypothesis that the maximum centrifugal stress at the middle of the blade (where

251 the maximum displacement is located) would not exceed a fixed stress limit of the blade itself  
252 (Eq. 6).

$$253 \quad \zeta_b = \frac{F_b}{A_{res\_b}} = \frac{m_b \omega^2 R}{A_{res\_b}} \leq \zeta_{lim\_b} \quad (6)$$

254 where  $A_{res\_b}$  is a conventional resistance area which takes into account the structure of the  
255 stiffeners inside the airfoil and  $F_b$  is the centrifugal stress of the blade of mass  $m_b$ . In particular,  
256 all the airfoils were reproduced with a hollowed section having a constant skin thickness (3  
257 mm) and three, equally spaced, rectangular stiffeners perpendicular to the chord of variable  
258 thickness. The trailing edge was considered as solid with a fillet radius increasing proportionally  
259 to the chord of the blade (Figure 3). Based on the characteristics of an aluminium alloy tested  
260 by the authors in a previous industrial experience [33,37], a stress limit of 90 N/mm<sup>2</sup> was here  
261 considered.

262 In addition, in Case 3 even the dimensions of the struts (at least two for each blade) are  
263 variable from one configuration to another in order to satisfy the stress limit of the blades due  
264 to the centrifugal force (Eq. 7 with the same notation of Eq. 6).

$$265 \quad \zeta_{ST} = \frac{F_{ST}}{A_{res\_ST}} = \frac{1}{N_{ST}} \frac{m_b \omega^2 R}{A_{res\_ST}} \leq \zeta_{lim\_ST} \quad (7)$$

266 It is worth pointing out that the load case considered in Eq. 7 takes into account only the  
267 tensile stresses generated by the centripetal acceleration of the rotor. In authors' experience  
268 (see [33,37]), this load condition is quite realistic for small-size rotors (i.e. with a swept area up  
269 to 4.0 m<sup>2</sup>), whereas bending forces become significant in larger rotors with high  $\Phi$  ratios. In  
270 this work, the bending stresses were neglected but a more accurate description of their  
271 influence will be carried out in future works.

272 A correct evaluation of the strut's dimensions is particularly important in small rotors due to  
273 the fact that a fast-rotating turbine often needs thick supporting struts to balance the centrifugal

274 stresses [24]. Similar struts, however, are characterized by a notable parasitic torque generation  
275 which causes a remarkable detriment of the overall performance of the machine.

276 In particular, in this study a constant shape of the struts was considered. In case of  
277 symmetrical airfoils, the same profiles were used. On the other hand, when the NACA4415 is  
278 used, the struts are supposed to be realized with the NACA0015 (same  $t/c$  ratio but straight  
279 camber). By these choices, a constant virtual drag coefficient [24] during the revolution was  
280 considered, whereas the dimensions of the struts were varied in Case 3 until the minimum ones  
281 which satisfied Eq. 7 were found. In detail, the chord of the struts (and consequently also the  
282 thickness, being the  $t/c$  ratio fixed) was calculated on the basis of the resistant area defined by  
283 Eq.7. When the calculated struts dimensions exceeded the chord of the blade, the struts number  
284 was increased by one for each blade and the new dimensions of each element were re-  
285 calculated on the basis of the same procedure, in all the investigated configuration, a maximum  
286 struts' number of three was constantly observed. Finally, the effects of "bluff-section" struts  
287 was investigated, in order to stress more evidently the influence of the parasitic phenomena: the  
288 struts were assumed to have a constant virtual drag of 0.3 and a thickness varying with the  
289 same procedure described for the airfoil-shaped solutions.

#### 290 **4. Simulations and data reduction**

291 The performance simulations of the machines were carried out with the *VARDAR* code of the  
292 Department of Industrial Engineering of the University of Florence. The code makes use of the  
293 Blade Element Momentum (BEM) Theory, by which the rotor performance is calculated  
294 coupling the momentum equation in the mainstream direction of the wind and a one-  
295 dimensional aerodynamic analysis of the interactions between the airfoils in motion and the  
296 oncoming flow on the rotor [20,33,38-39] by means of pre-calculated polars. Even if more  
297 advanced simulations techniques (including computational fluid dynamics) are today available  
298 for the simulation of VAWTs (e.g. [39-41]), BEM approaches are still the most widely  
299 exploited tools for the preliminary design of these rotors, as they provide sufficiently reliable

300 results in terms of global performance (whereas a poor description of the instantaneous flow  
 301 field around the rotor is achieved) coupled with a notably reduced computational cost.

302 In particular, the VARDAR code has been specifically developed for H-Darrieus wind  
 303 turbines using an improved version of a *Double Multiple Streamtubes Approach with Variable*  
 304 *Interference Factors* [17,28,42] (Figure 4a). In this approach, the elementary torque for each  
 305 azimuthal position is therefore given by Eq. 8:

$$306 \quad T_{blade}(\vartheta) = F_t \cdot R = \frac{1}{2} \rho c W_{\vartheta}^2 C_{t(\vartheta)} R H \quad (8)$$

307 where  $C_t$  and  $W$  represent the tangential coefficient of the airfoil in the reference system of the  
 308 rotating blade (Figure 4b) and the relative velocity of the flow experienced by the airfoil itself  
 309 in the upwind or downwind half, respectively, expressed by Eqs. 9,10 and 11:

$$310 \quad C_t = C_L \cdot \sin \alpha - C_D \cdot \cos \alpha \quad (9)$$

$$311 \quad W_{up} = \sqrt{[(1-a) \cdot U_{\infty} \cdot \sin(\vartheta - \beta)]^2 + [(1-a) \cdot U_{\infty} \cos(\vartheta - \beta) + \omega R]^2} \quad (10)$$

$$312 \quad W_{down} = \sqrt{[(1-a_2) \cdot U_{eq} \cdot \sin(\vartheta - \beta)]^2 + [(1-a_2) \cdot U_{eq} \cos(\vartheta - \beta) + \omega R]^2} \quad (11)$$

313 As for the more general Eq. 5, the relative speed is given by the sum of peripheral speed and  
 314 wind speed, properly reduced by the induction factor (either upwind or downwind). The value  
 315  $U_{eq}$  in Eq. 25 indeed represents the wind equilibrium velocity between actuator disks (see  
 316 Figure 4).

317 The Glauert's correction for the BEM theory has been taken into account with the most recent  
 318 improvements, together with the corrections due to blades finite Aspect Ratio, using the  
 319 Lanchester-Prandtl model. This aspect is of particular relevance in the present analysis, as it  
 320 allows the designer to account for the increasing tip-losses connected to blades with small  
 321 height to chord ratios.

322 In order to increase the accuracy of the aerodynamic estimations, a specific sub model to  
 323 account for the dynamic stall has been provided, following the Paraschivoiu's adaptation to the

324 DMS approach described in; at the same time, the stream tube expansion along the flow path  
325 was considered. For additional details on the code please refer to Refs. [23,26,33,37,42-43].

326 The prediction capabilities of the VARDAR code have been validated during a several-years'  
327 experience in the design of three real H-Darrieus rotors, having swept areas of 1, 2.5 and 5 m<sup>2</sup>,  
328 respectively, and two or three blades, either straight or helix-shaped. The 1:1 models of all the  
329 rotors (two made of reinforce plastic and one of painted aluminium alloy) were tested in  
330 different wind tunnels (both with closed and open-jet). In all cases, the code was able to  
331 correctly predict both the power curves at different wind speeds and the starting ramps of rotor  
332 and is then considered fully predictive for the turbine typology investigated in this study. For  
333 further details on the code validation please refer to Refs. [23,33,37,42].

334 In the present analysis, the code provided the power coefficient of each configuration at all  
335 the wind speeds between the cut-in and the cut-out. The characteristic power coefficient of the  
336 machines at each wind velocity was conservatively evaluated in correspondence with the  
337 calculated performance 0.2 points of TSR after the peak of the operating curve. A similar  
338 precaution is often applied in order to define a load curve aimed at preventing the turbine from  
339 operating in the unstable part of the functioning curve [11,24]. Moreover, it is worth noticing  
340 that the cut-in speed in each case was set to the wind speed for which a positive power  
341 coefficient is obtained. This is, in fact, a precautionary assumption, because the self-starting of  
342 an H-Darrieus rotor in real wind is often ensured for several starting positions even if the  
343 overall power coefficient over the revolution is negative [42,45].

344 In further detail, for each configuration in terms of swept area (i.e. the discrete variable of the  
345 problem) specific performance maps were created [26] corresponding to a given wind  
346 distribution. Each map (e.g. see Figure 5) contains the overall efficiency of energy conversion  
347 ( $\eta_{en}$ ) of the specific rotor, defined as in Eq. 12 and 13.

$$348 \quad \eta_{en} = \frac{\sum_{u=cut-in}^{cut-out} c_p(u) \cdot u^3 \cdot T(u)}{\sum_{u=cut-in}^{cut-out} u^3 \cdot T(u)} \quad (12)$$

349 
$$T(u) = f(u) \cdot 8760 \quad (13)$$

350 Upon examination of the equations, it is worth pointing out that the energy conversion  
351 efficiency was defined as the annual energy yield of the turbine over the year (i.e. the real  
352 extracted power at each wind speed multiplied by the time fraction, in hours, during which that  
353 wind blows  $T(u)$ ) on the theoretical energy contained in the wind itself.

354 Based on its definition, this indicator differs from the classical power coefficient and allows  
355 one to simultaneously take into account both the efficiency of the turbine at all the wind speeds  
356 expected over the year and the effects related to the starting and resistance capabilities of the  
357 rotor (due to the variable cut-in and cut-out velocities considered).

358 Finally, within each map, a numerical identification of the maximum was performed, with the  
359 constraints of neglecting design solutions which imply Blade's Aspect Ratios higher than 35: in  
360 case of excessive ratios between the height and the chord, the bending resistance of such a  
361 slender blade would be indeed very poor, making the selected solution practically unfeasible.

362 This procedure would finally lead to the definition of the geometrical features of the rotor  
363 ensuring the largest energy harvesting over a year for the attended load case, average wind  
364 speed in the site and imposed swept area of the rotor.

365 The whole data reduction procedure is summarized in Figure 6, while a complete overview on  
366 the results in terms of best design solutions can be find in the Appendix Section.

## 367 **5. Results**

### 368 **5.1 Energy Efficiency maps interpretation**

369 A typical Energy Efficiency map has been presented in Figure 5 (e.g. for a swept area of 4.0  
370 m<sup>2</sup>, NACA0018 airfoil,  $\bar{U}=5$  m/s in Case 2). A linear interpolation was performed between the  
371 calculated points (see Table 1) in order to more precisely outline the contours.

372 It is readily noticeable that an optimum-design zone (white-colored in the figure) can be  
373 typically distinguished in the bottom side. This zone represents the combination of the  $\Phi$  and  $\zeta$



374 parameters which ensures the best compromise in terms of functioning Reynolds numbers on  
375 the airfoil (high peripheral speeds and chords) and efficiency of the blades (high Aspect  
376 Ratios). Moreover, one can also notice that the efficiency is almost zero in the left side of the  
377 map, where the very small chords remarkably reduce the lift generation, and becomes lower  
378 also in the right-bottom corner of the map, where the turbine heights tend to zero.

379 As discussed, within each map a numerical identification of the maximum was performed in  
380 order to define the geometrical features of the rotor ensuring the largest energy harvesting over  
381 a year under the present design constraints.

## 382 **5.2 Case 1 - Aerodynamics**

383 From a general point of view, it is worth remembering that Case 1 configuration actually  
384 refers to a hypothetical solution of a fully aerodynamic relationship between the geometrical  
385 features of the rotor and the power performance. By doing so, the influence of the main  
386 aerodynamic design parameters can be readily argued and the functioning behaviors of  
387 machines having different areas can be directly compared.

388 The main outcome of the analysis of Case 1 is that an opposite behavior was found between  
389 cambered and uncambered airfoils in this configuration.

390 As an example of uncambered airfoils, Figure 7 reports the variation trends which describe  
391 the dependence of the optimal values of the most relevant design parameters from the average  
392 wind speed for the NACA0015 airfoil.

393 Upon examination of Figure 7, some relevant markups can be promptly made. In particular:

- 394 ■ The dimensionless parameters present the same trends even when different swept areas are  
395 considered, although numerical values differ from one configuration to another,  
396 confirming that scale effects must be taken into account.
- 397 ■ When the average wind speed in the site increases, the best solidity decreases constantly  
398 and the Aspect Ratio rises significantly, whereas the Shape Factor  $\Phi$  increases for

399 medium-low average wind speeds and then becomes stable. As a general remark, however,  
400 the turbine tends to become slenderer by increasing the average wind speed.

401 ■ Focusing on the dimensional parameters, the aforementioned trend is basically obtained  
402 throughout a constant decrease of the blades' chord with the average wind speed increase  
403 (with a steeper trend for medium-low  $\bar{U}$  and a flatter trend with an increased  $\bar{U}$ ). The  
404 turbine diameter and height have instead an opposite trend, with a decrease and an increase  
405 in the first part, respectively, followed by a constant trend in the second part.

406 The main aerodynamic implication of these results is that, when the average wind velocity  
407 experienced by the turbine is low (left side of the plots), the best design is that ensuring the  
408 highest local Reynolds numbers on the blade by means of the geometrical proportions. As a  
409 consequence, the chord values are maximized (see Eq. 1) at low wind speeds and then the  
410 solidity values are high (Eq. 3).

411 By increasing the average wind speed, the velocity triangles on the airfoils are altered thanks  
412 to the increased relative velocities experienced by the blades: the chords can be therefore  
413 reduced without decreasing the functioning Reynolds numbers. For high mean wind velocities,  
414 however, the chord length stops decreasing and more efficient blades (i.e. higher Aspect Ratios,  
415  $AR=H/c$  [20-21,24]) are obtained by means of an increase of the turbine height (black curves in  
416 the graphs on the left). The optimal solidity constantly decreases with  $\bar{U}$ .

417 Moreover, a well-defined dependence on the  $t/c$  ratio of the airfoil was observed. For  
418 example, in Figures 7 and 8 the optimal trends of the solidity and the blade's Aspect Ratio for  
419 the three uncambered airfoils are reported.

420 In detail, by decreasing the  $t/c$  ratio of the selected airfoil (Figure 8), i.e. from NACA0018 to  
421 NACA0015 and NACA0012, the optimal solidity of the turbine is constantly reduced. This  
422 phenomenon can be related to a decrease of the requested chord. This solution is indeed  
423 allowed by an increase of the target peripheral speed of the rotor which, on one hand, ensure a  
424 suitable Reynolds number on the airfoil (Eq.1) and, on the other hand, decreases the incidence

425 angles range: thinner airfoils (e.g. the NACA0012), although more efficient for high relative  
426 speeds, have indeed a lower stall angle and are generally more sensitive to incidence angle  
427 variations. Contemporarily (Figure 9), the same reasons induce an opposite behavior of the  
428 blade's Aspect Ratio ( $AR_b$ ), which is constantly higher in case of thinner airfoils (the shorter  
429 chords are combined with an almost equal trend of optimal heights).

430 The optimal design trends in case of the cambered NACA4415 airfoil are notably different. In  
431 particular, whenever this typology of profile is applied, the scale effects due to the swept area  
432 become negligible, as the high  $C_L/C_D$  ratio of this airfoil [44] makes the dependence of the  
433 aerodynamic performance from the chord very low. The Aspect Ratio can then rise  
434 significantly to pursue the higher blade's efficiency. The optimal design proportions in Case 1  
435 for the NACA4415 airfoil are reported in Figure 10. In this configuration, the optimal solidity  
436 is low (see Eq. 3) and the  $AR_b$  very high mainly due to the very short chords.

### 437 **5.3 Case 2 - Limited centrifugal load**

438 The results obtained from the examination of Case 1 are very useful to comprehend the  
439 aerodynamic trends connected to a variation of the wind velocities experienced by the turbine;  
440 structural constraints like the centrifugal load have, however, relevant impact on the best design  
441 compromise of a machine [24,26].

442 To this purpose, next figures report some results of the investigation on the study-cases in  
443 Case 2, in which a  $\zeta_{lim\_b}$  (Eq. 6) of  $90 \text{ N/mm}^2$  was considered [26,33]; for a wider overview of  
444 the results, please see Appendix B.

445 First, it was noticed that, when the average wind velocities are low (i.e.  $3\div 4 \text{ m/s}$ ), the  
446 structural constraints actually do not affect the definition of the best design parameters; the  
447 operating rotational speeds at these velocities are low and the resulting centrifugal loads do not  
448 exceed the structural limits. In case of the NACA4415, the best design is once again imposed  
449 due to limitation on the blade's Aspect Ratio.

450 Once again, the two types of airfoils work differently. If the uncambered profiles are selected  
451 and the medium-high wind speeds become more frequent, the reduction of the solidity with the  
452 average wind speed noticed in Case 1 ceases (an almost constant value is reached – e.g. see  
453 Figure 11), mainly due to the stop in the decrease of the optimal chord (Figure 12).

454 This trend can be explained by considering that, when the wind velocities are high, the most  
455 suitable compromise in terms of energy-yield capabilities comes from a reduction of the peak  
456 efficiency of the turbine (higher solidity) which, however, implies a reduction of the operating  
457 rotational regime [24,26]. This reduction makes the centrifugal loads decrease and allows the  
458 turbine to extract energy from the wind with all the considered wind velocities.

459 In particular, after examining the Energy Efficiency maps (e.g. for the NACA0018, swept  
460 area  $A=4 \text{ m}^2$  in Figure 13), it is readily noticeable that, for low average wind speeds, the best  
461 efficiency zone first migrates towards lower solidities and higher  $\Phi$  ratios. When the high wind  
462 speeds become more frequent, however, a new zone of best efficiency arises at higher  $\zeta$  and  $\Phi$   
463 ratios.

464 On the other hand, in case the NACA4415 is adopted, the optimal design solution highlighted  
465 in Case 1 (small chords, very high  $AR_b$  and high revolution speeds) is no longer feasible due to  
466 the limitation to the centrifugal load.

467 As a result, the best solidity value is slightly increased for medium-high average wind speeds  
468 (Figure 14); contemporarily, the chords and diameters remarkably increase in order to achieve  
469 a drastic reduction of the revolution speed (Figure 15). One should indeed remember that  
470 longer chords ensure more favorable Reynolds numbers on the airfoil without increasing the  
471 relative speed (see Eq. 3), whereas higher diameters act oppositely by improving the relative  
472 speed (Eq. 4) or, conversely, ensure the same relative speed with lower revolution speeds.

473 Finally, it is also worth noticing that this increase of the diameter for high average wind speeds  
474 is avoided only for high swept areas (i.e.  $A=9.0 \text{ m}^2$ ), where the limit on the centrifugal load is

475 mitigated by the large diameters. In these conditions, the  $AR_b$  can be also slightly increased,  
476 with a partial recovery of the blades' efficiency (see Appendix B).

#### 477 **5.4 Case 3 - Centrifugal load and struts' parasitic torque**

478 Focusing now on a real-type machine, a further constraint must be included in the  
479 identification of the best design trends: the parasitic torque of the struts is, in fact, a key  
480 element in defining both the peak efficiency of the machine and its functioning behaviour at  
481 different wind speeds. Due to the relevance of this load case, the complete comparison of the  
482 optimal design configurations was reported in Appendix D.

483 The calculations showed that the general effect of the parasitic torque is to slightly flatten the  
484 trends of the design parameters as a function of the average wind speed. The best design  
485 solutions tend in fact to collapse in the configurations that minimize the contribution of the  
486 parasitic components [26]. The general tendencies described in Section 4.3 are, however, still  
487 of validity and will not be all again discussed. In particular, the efficiency maps shape  
488 discussed in Figure 13 was confirmed also under this load case, with the only discussed  
489 restriction of the high-efficiency zone. Some interesting remarks can however be made.

490 First, Figure 16 reports the comparison between the optimal solidity trends in Case 2 and 3 for  
491 NACA0012 and NACA0018 airfoils (swept area of  $1.0 \text{ m}^2$ ), as a function of the average wind  
492 speed. As one may notice, no great difference stands between the two cases when the average  
493 wind speed in the site is sufficiently high (i.e. higher than  $5 \text{ m/s}$ ). Conversely, in case of low  
494 average wind speeds, the optimal solidity in Case 3 is higher than that obtained in case the  
495 parasitic torque is neglected.

496 In order to give a correct interpretation of the results, it is worth remembering that the  
497 parasitic torque generated by the rotating structures which do not contribute to the torque  
498 generation (e.g. struts, tie-rods, etc.), has a quadratic dependence on the rotational speed of the  
499 rotor (directly affecting the tangential velocity) and a lighter and more complex dependence on  
500 the wind velocity (see Refs. [33,36]).

501 Based on these considerations, one can understand that, when the wind speeds are low, the  
502 impact of the parasitic torque on the effective energy-extraction capability of the rotor is more  
503 relevant: as a consequence, the optimal design tends to increase the solidity, in order to achieve  
504 a reduction of the revolution regime [24].

505 Focusing on the cambered airfoil, the situation is again quite different (see Figure 17). With  
506 this airfoil selection, which is thought to provide a good torque production even in low winds,  
507 the best design solution is almost unaltered within  $\bar{U}=5$  m/s with respect to Case 2.

508 When the high wind speeds in the site become more frequent, however, the “low solidity”  
509 solutions, which are associated with very high revolution speeds, are not suitable anymore, as  
510 the parasitic torque has become too high. The optimal solutions hence tend to higher solidities  
511 (i.e. slower revolution speeds), very similar to those identified for the uncambered airfoils.

512 Finally, in order to further stress the importance of the parasite torque of the struts, in Figure  
513 18 a comparison between the optimal solidity for a turbine with the NACA0012 airfoil and a  
514 swept area of  $1 \text{ m}^2$  is reported as a function of the strut’s shape. In detail, when the drag of the  
515 struts increases, the solidity tends to notably increase, in the attempt of reducing the revolution  
516 speed of the rotor. In the selected case, the more energy-efficient solution would be very solid  
517 (even up to the limit of  $\sigma = 0.6$ ), which is, however, a practically unfeasible solution. In a  
518 similar case, a compromise must be pursued in practically designing the rotor, including a  
519 reduction of the effective energy-yield capabilities.

520 At the end of this study, one could then conclude that, from an energy viewpoint, future  
521 design of medium and small-size Darrieus rotors should be based on the maximization of the  
522 energy yield on the basis of the characteristics of the potential installation site. In particular, for  
523 given rotor’s dimensions, a differently shaped turbine would be about to be preferred as a  
524 function of the average wind speed of the installation. For example, in Figure 19 the optimal  
525 design choices for a turbine having a swept area of  $4 \text{ m}^2$  and equipped with NACA0018 airfoils  
526 are presented as a function of the average wind speed in the site. In particular, the

527 aforementioned trends in terms of increase of the H/D ratio and decrease of the chord length  
528 are clearly distinguishable.

529 For the same family of turbines (presented trends are consistent with all the analyses  
530 presented in this study), the annual energy yield of the optimized rotors is presented in Figure  
531 20 as a function of the average wind speed in the site. In order to provide a sensitivity analysis  
532 on the benefits of the proposed approach, in the same figure the energy yield increase with  
533 respect to two others design choices is presented. In further details, Study Turbine A represents  
534 a hypothetical turbine designed to have the maximum efficiency at 6 m/s, which could be, for  
535 example, the average speed in the site [23]. Study Turbine B instead represents the turbine  
536 optimized by means of the maximum-energy-yield criterion at  $\bar{U}=6$  m/s.

537 Some very interesting remarks can be done. First, it is worth noticing that a design approach  
538 based on the maximum annual energy yield actually provides an increase of performance in all  
539 cases. In particular, focusing on the 6 m/s bar, one can notice that benefits can be achieved also  
540 in comparison to a design criterion based on the same average speed of the site.

541 Moreover, the proposed criterion is able to provide notable energy increase (up to 10% in the  
542 present case) when the wind speeds in the site are low, confirming the prospects of specific  
543 future design choices for these conditions.

## 544 **6. Conclusions**

545 In this study, a numerical analysis has been carried out to define some design guidelines for  
546 Darrieus wind turbines aimed at optimizing the annual energy yield of each machine in the  
547 installation site. The main outcomes of the analysis can be summarized as follows.

548 Focusing on the only aerodynamic requirements, an opposite behavior was found between  
549 cambered and symmetric, uncambered airfoils. For uncambered profiles, when the average  
550 wind speed in the site increases, the best solidity decreases constantly, the Aspect Ratio rises  
551 significantly, whereas the Shape Factor  $\Phi$  increases for medium-low average wind speeds and  
552 then becomes stable. This trend is mainly due to the fact that, by increasing the wind speed, the

553 relative velocity is increased, and the Reynolds number is improved. The chords can be then  
554 reduced, with notable benefits in terms of blade's efficiency. A well-defined dependence on the  
555  $t/c$  ratio was also observed: by decreasing the  $t/c$  ratio, the optimal solidity is constantly lower  
556 whereas higher Aspect Ratios are preferable. When a cambered airfoil is instead selected, the  
557 scale effects due to the swept area becomes negligible, as the high  $C_L/C_D$  ratio of this airfoil  
558 makes the dependence of the aerodynamic performance from the chord very low, hence  
559 allowing the Aspect Ratio to rise significantly to pursue the higher blade's efficiency. With this  
560 selection, the optimal solidity is consequently also very low.

561 On the other hand, when structural constraints and notable parasitic contributions are  
562 introduced, the best configurations when the average wind velocities are low are similar to that  
563 coming from the aerodynamic analysis, although the optimal design generally tends to increase  
564 the solidity, in order to ensure a better functioning conditions to the airfoils (higher Reynolds  
565 numbers, increased torque) and contemporarily achieve a reduction of the revolution regime,  
566 which contains the parasitic torque. On the other hand, when the medium-high wind speeds  
567 become more frequent, the most suitable compromise in terms of energy-yield capabilities  
568 generally comes from a reduction of the peak efficiency of the turbine which, however, ensures  
569 a good energy extraction is a wider range of functioning conditions. In case of uncambered  
570 airfoils, in particular, this goal is obtained with a general increase of the optimal solidity, which  
571 makes the revolution speed decrease and allows the turbine to extract energy from the wind  
572 with all the considered wind velocities. As a general remark, however, by increasing the  
573 parasitic contributions, the transition of the best design compromise to higher solidity solutions  
574 is anticipated, due to the stronger dependence of the performance on the rotational speed.

575 At the end of this work, it has to be noticed that the present analysis was carried out under  
576 specific assumptions in terms of dimensions, airfoil types, load system and struts' shape; on  
577 these bases, the reader has to consider that different performance maps could come from a new  
578 set of theoretical assumptions, although some general trends outlined in the work (e.g. the



579 influence of the turbine proportions on the Reynolds numbers and the rotational speed) are of  
580 general validity.

581 The proposed design criterion, however, besides being theoretically more rigorous from a  
582 truly energetic point-of-view than a conventional one based on a single reference wind speed,  
583 has shown interesting prospects in terms of energy production improving. In particular,  
584 different models could be designed for specific wind distributions in order to optimize the  
585 energy yield also at low wind speeds, which are very frequent in several countries and in  
586 unconventional installation sites, e.g. the urban environment.

## 587 **Nomenclature**

588	$A$	Swept Area	[m <sup>2</sup> ]
589	$a$	Induction Factor	
590	$AR$	Aspect Ratio	
591	$c$	Blade Chord	[m]
592	$C_D$	Drag Coefficient	
593	$C_L$	Lift Coefficient	
594	$C_t$	Tangential Force Coefficient	
595	$c_p$	Power Coefficient	
596	$D$	Turbine Diameter	[m]
597	$F_n$	Normal Force on the Blade	[N]
598	$F_{ST}$	Force due to Centrifugal Loads	[N]
599	$F_t$	Tangential Force on the Blade	[N]
600	$f$	Frequency	
601	$H$	Turbine Height	[m]
602	$m$	Mass	[kg]
603	$N$	Blades/Struts Number	
604	$P$	Power	[W]

605	$R$	Turbine Radius	[m]
606	$Re_c$	Chord-based Reynolds Number	
607	$T$	Annual Time of each Wind Class	[h]
608	$t$	Airfoil Thickness	[m]
609	$TSR$	Tip-Speed Ratio	
610	$u$	Wind Class	[m/s]
611	$U_\infty$	Absolute Wind Speed	[m/s]
612	$\bar{U}$	Average Wind Speed	[m/s]
613	$W$	Relative Wind Speed	[m/s]
614			
615	<u>Superscripts</u>		
616	*	Per Unit Area	
617	$\rightarrow$	Vectorial Quantity	
618			
619	<u>Subscripts</u>		
620	$air$	Air	
621	$b$	Blade	
622	$en$	Energy	
623	$eq$	Equilibrium (between upwind and downwind)	
624	$res$	Resistant Component	
625	$ST$	Struts	
626			
627	<u>Greek letters</u>		
628	$\Phi$	Turbine Shape Factor	
629	$\alpha$	Incidence Angle on the Airfoils	[deg]
630	$\beta$	Pitch Angle	[deg]
631	$\eta_{en}$	Energy-conversion Efficiency	

632	$\nu$	Kinematic Viscosity	$[\text{m}^2/\text{s}]$
633	$\xi$	Chord/Diameter Ratio	
634	$\rho$	Air Density	$[\text{kg}/\text{m}^3]$
635	$\sigma$	Solidity	
636	$\zeta$	Structural Stress	$[\text{N}/\text{m}^2]$
637	$\omega$	Rotational Speed	$[\text{rad}/\text{s}]$

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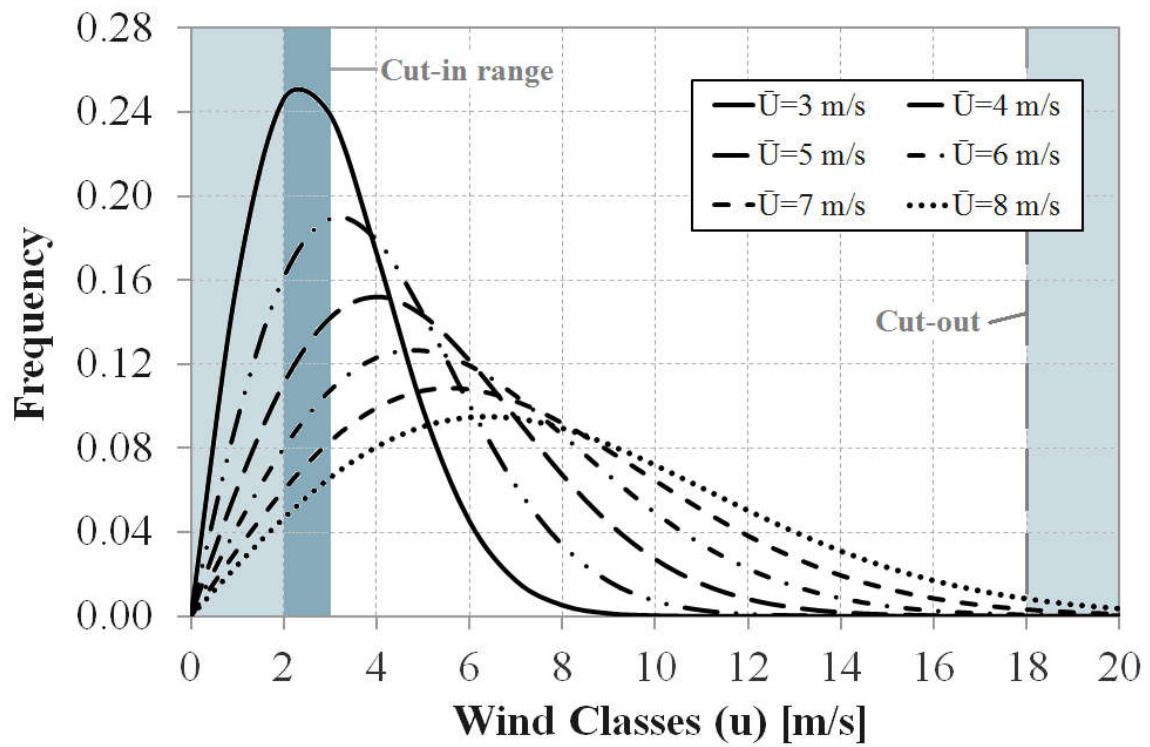
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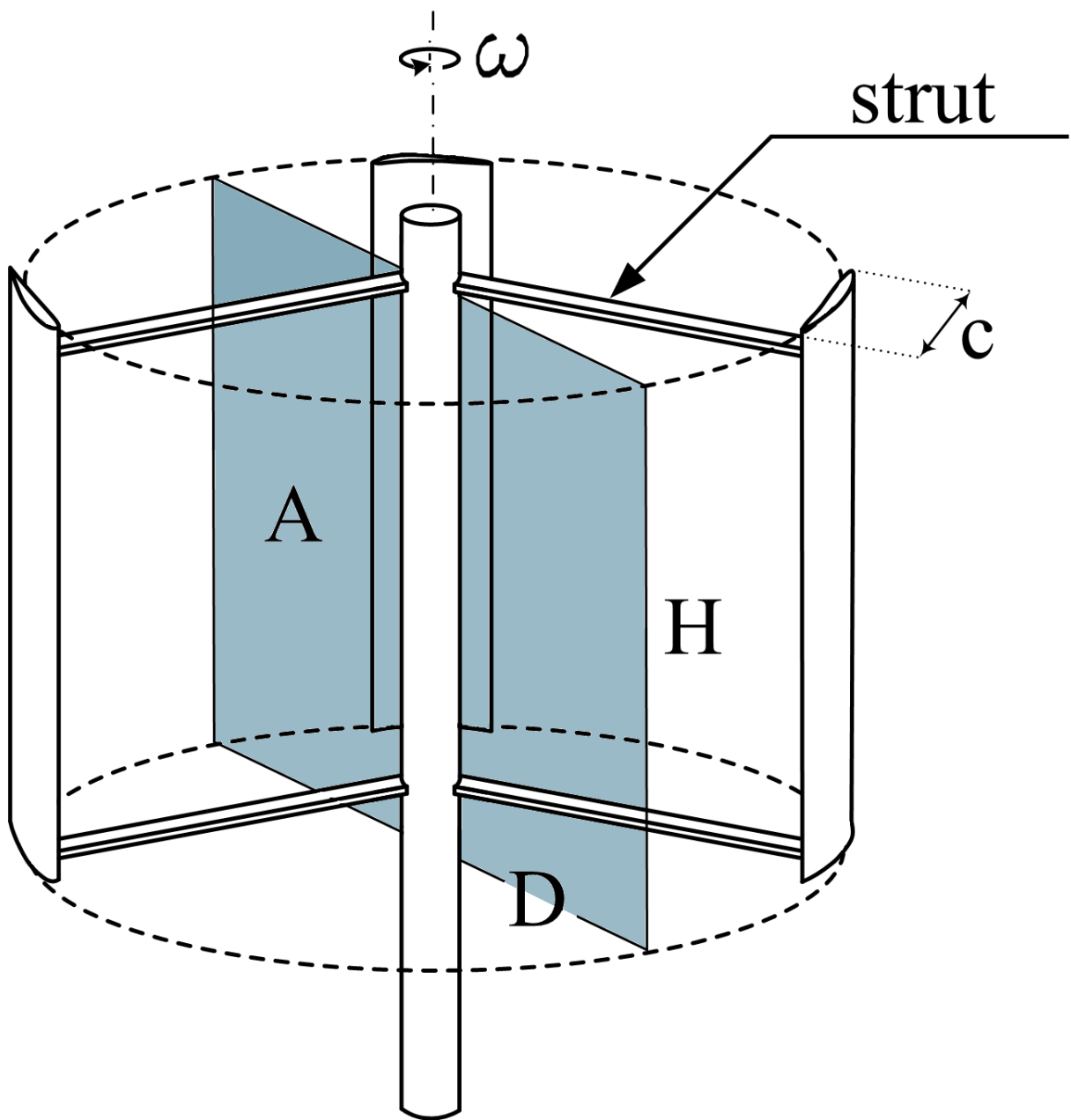
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= Operating turbine   
 = Turbine stopped   
 = Start-up dependent on the configuration

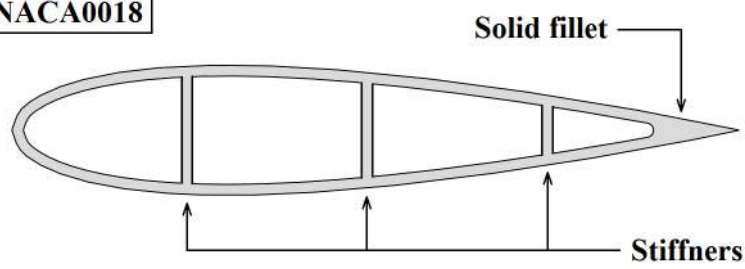
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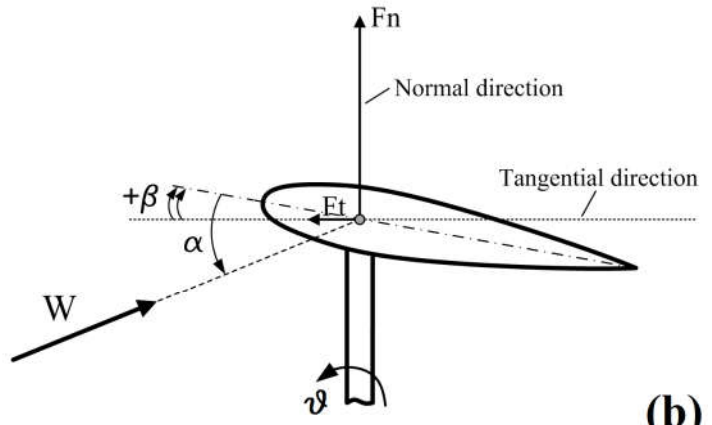
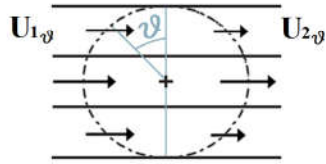
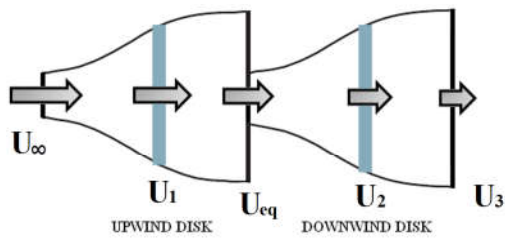


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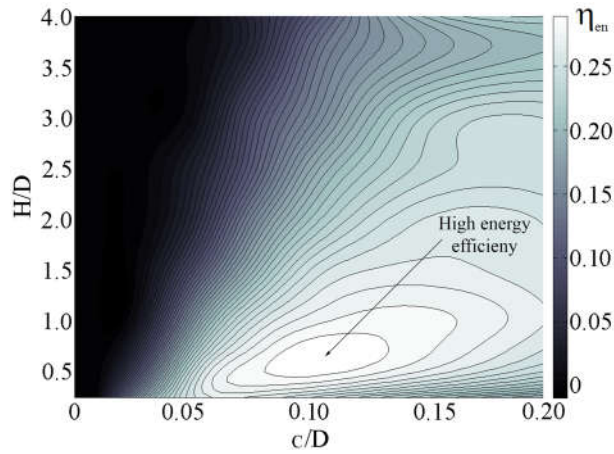
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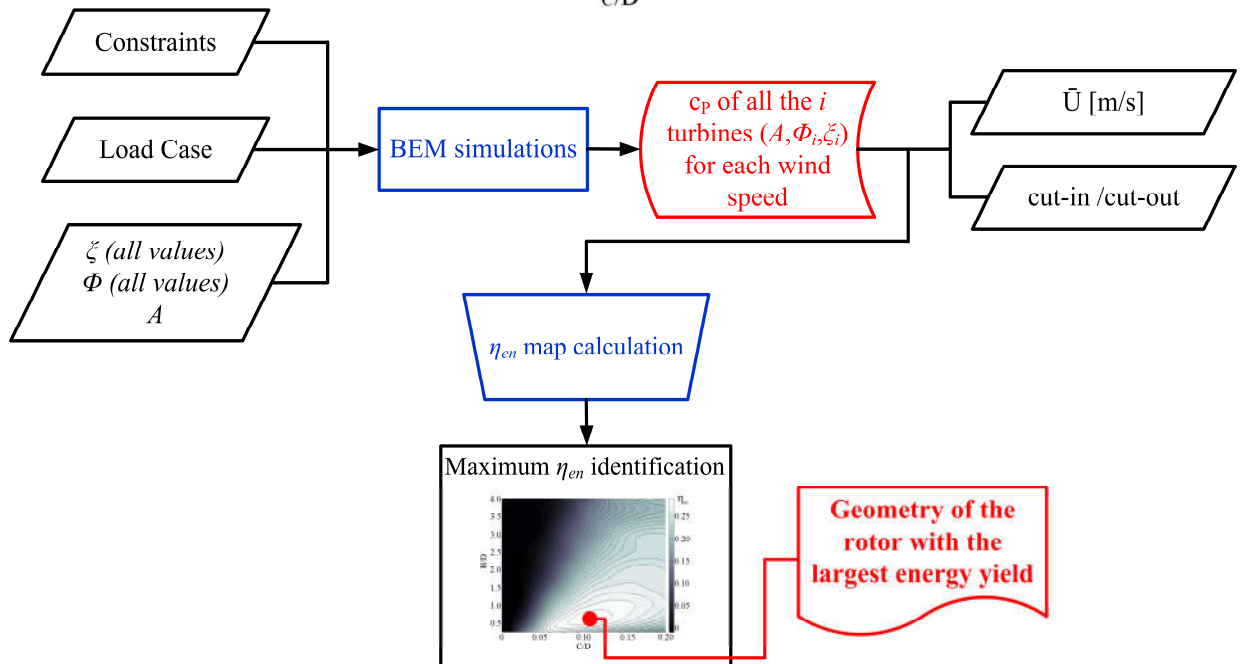
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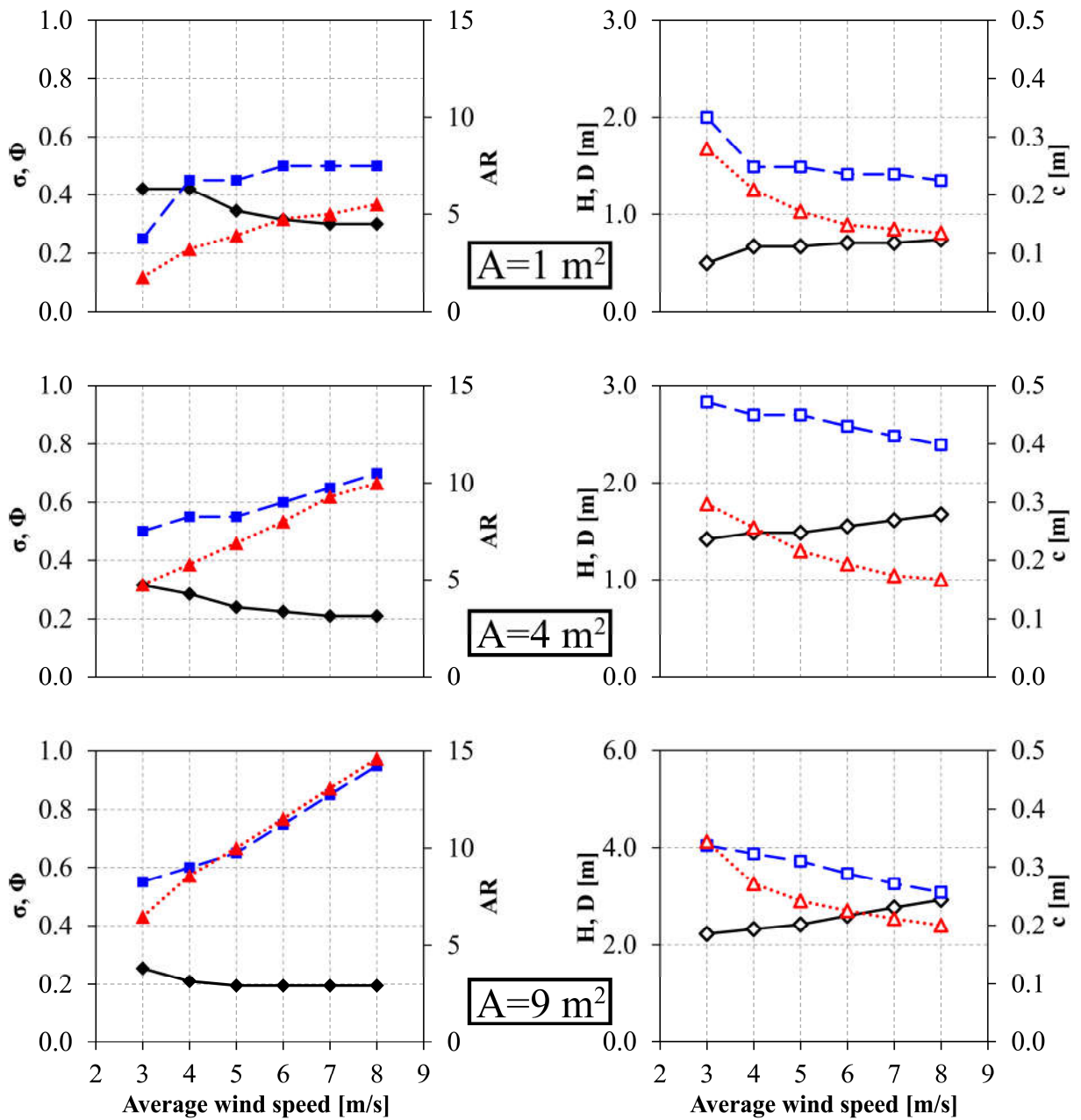
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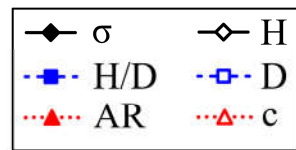
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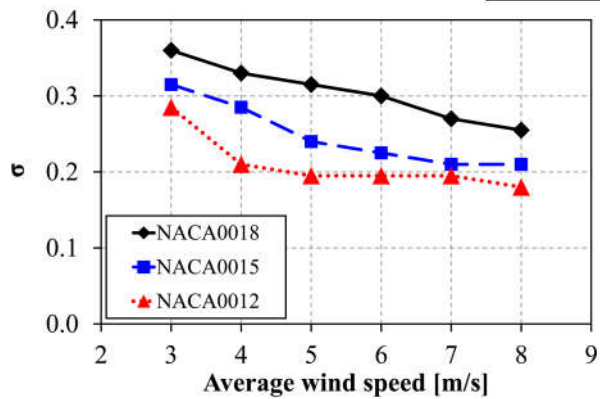
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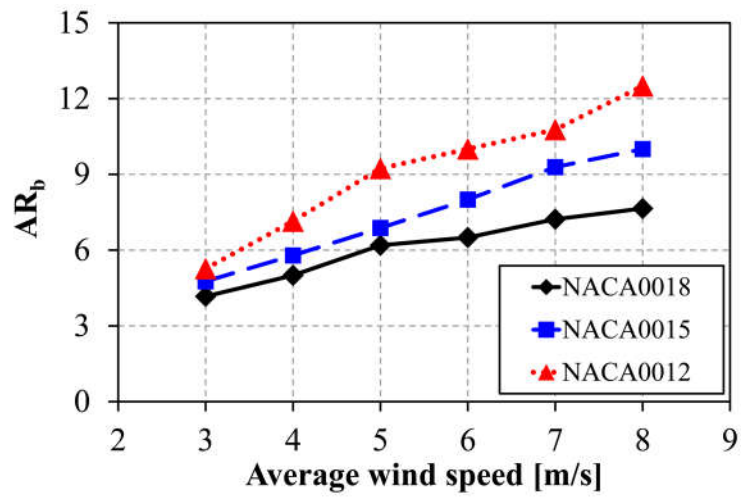
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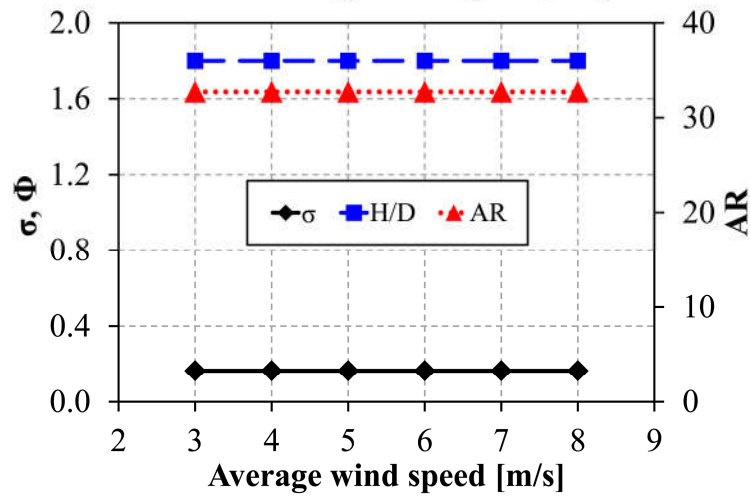
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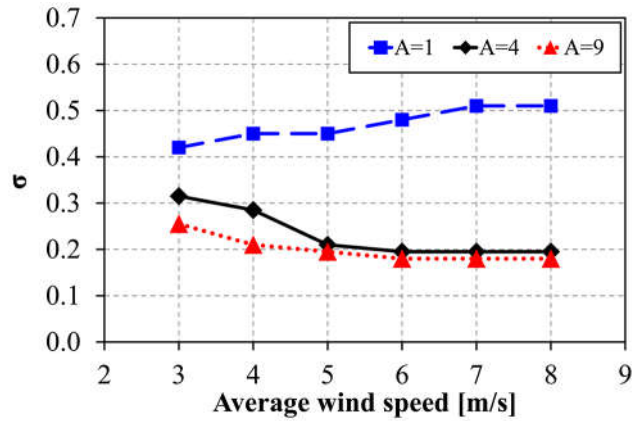
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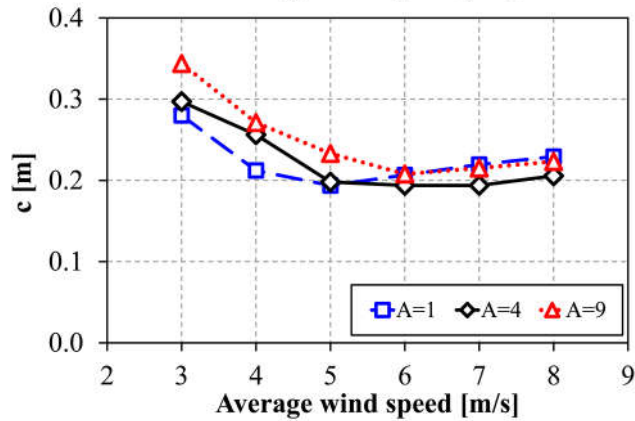
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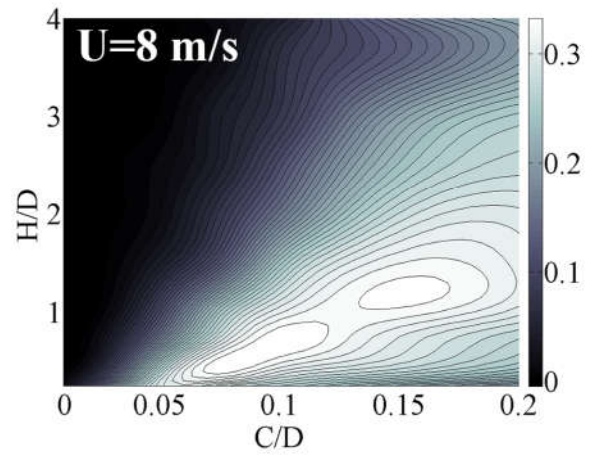
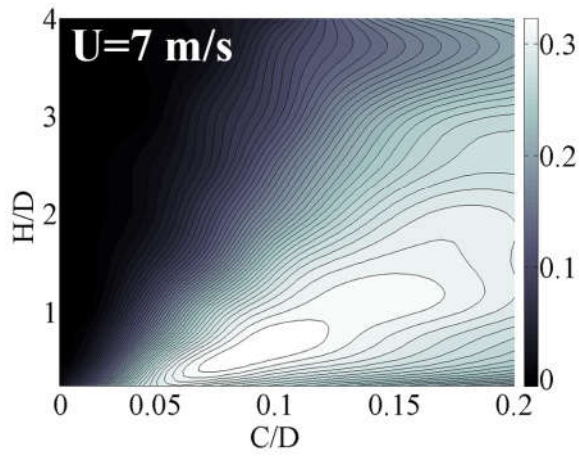
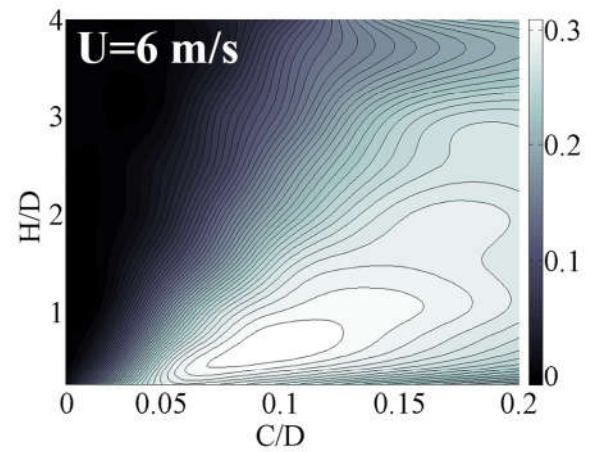
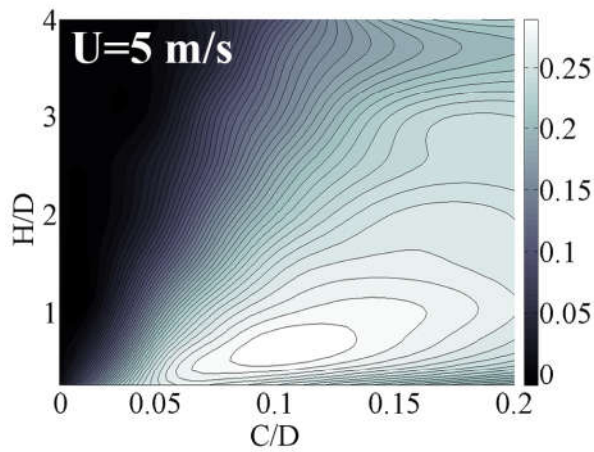
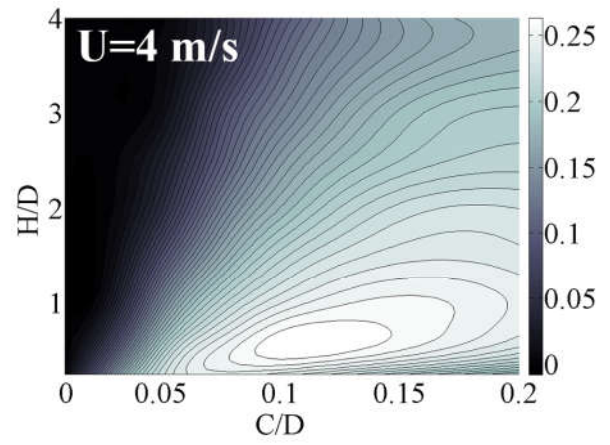
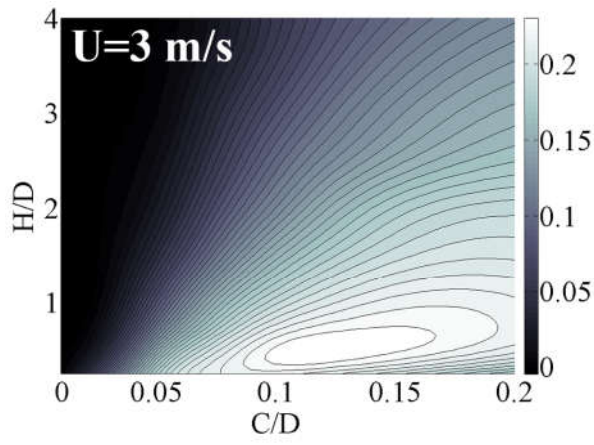
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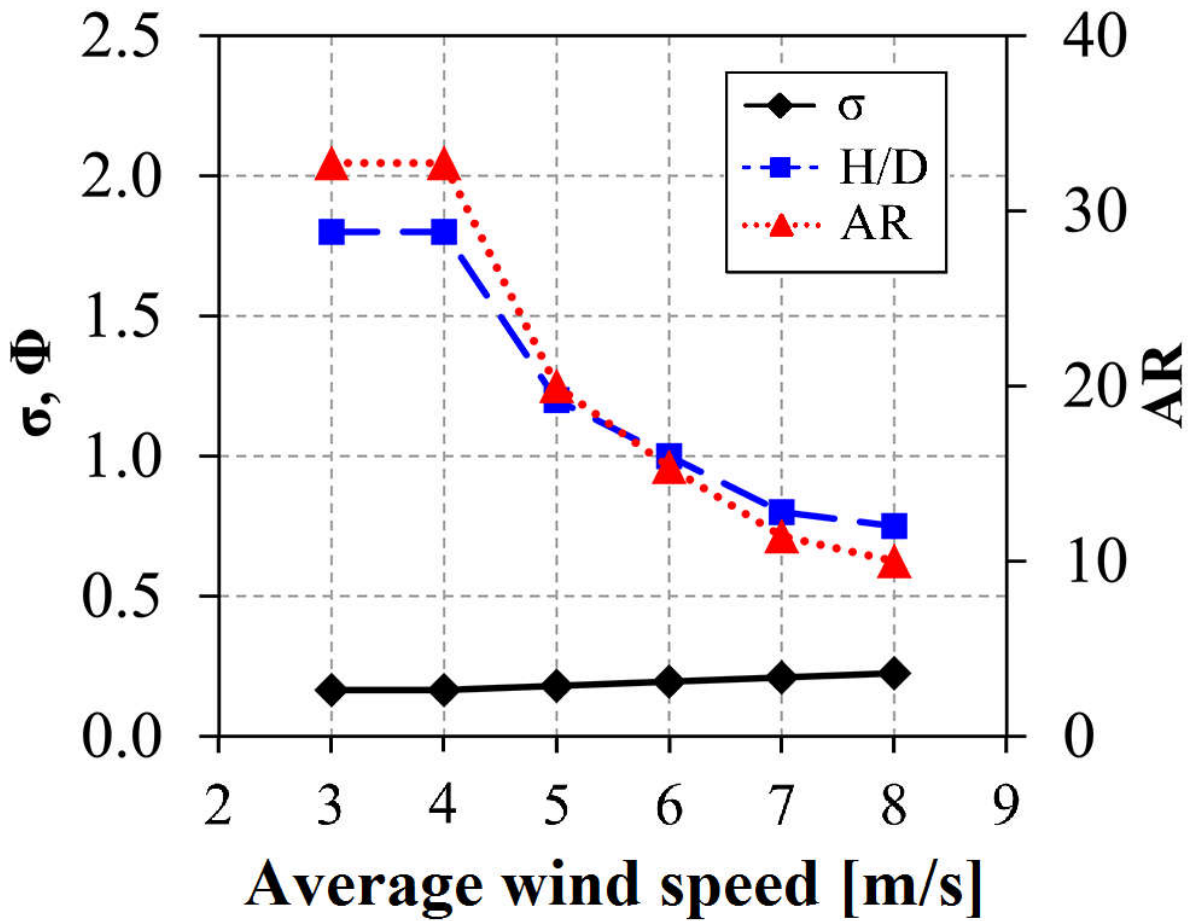
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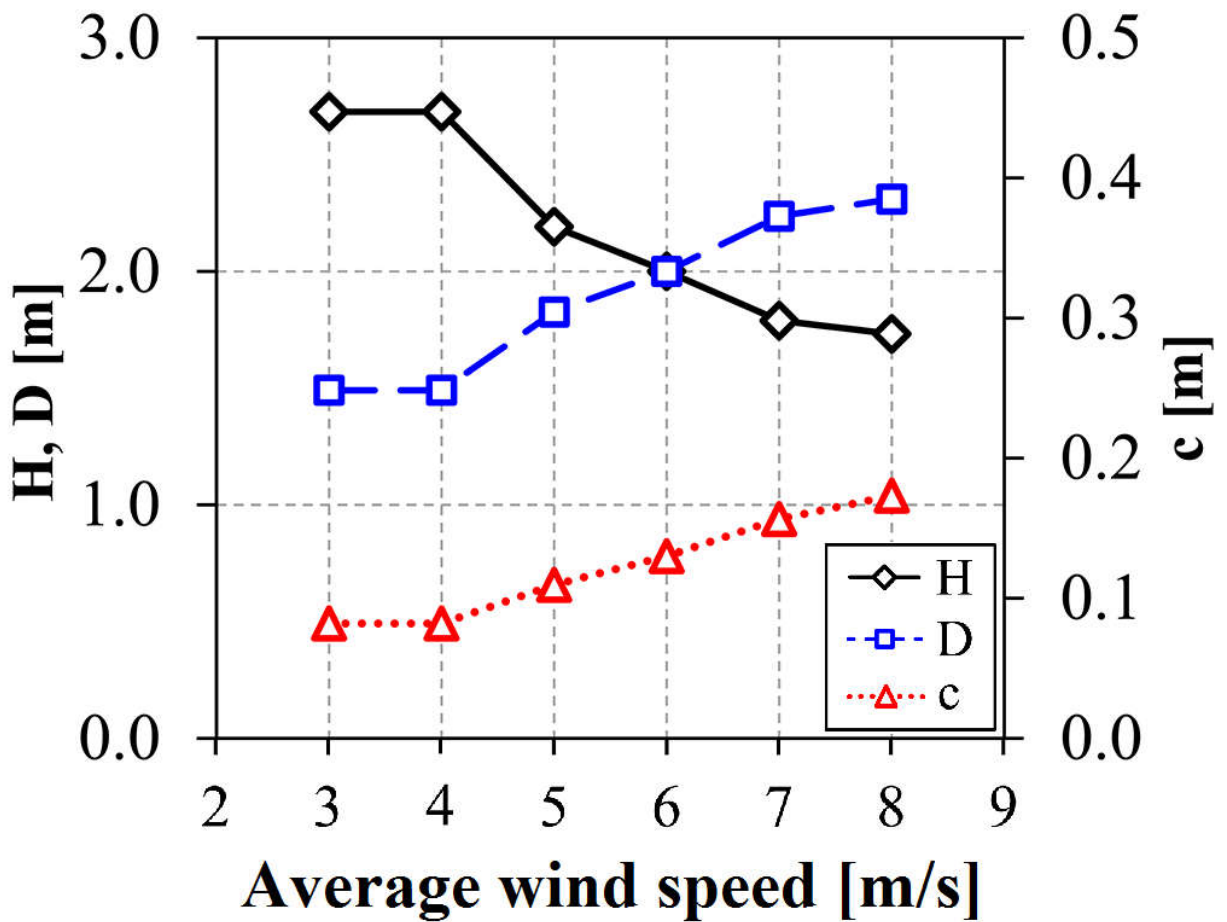
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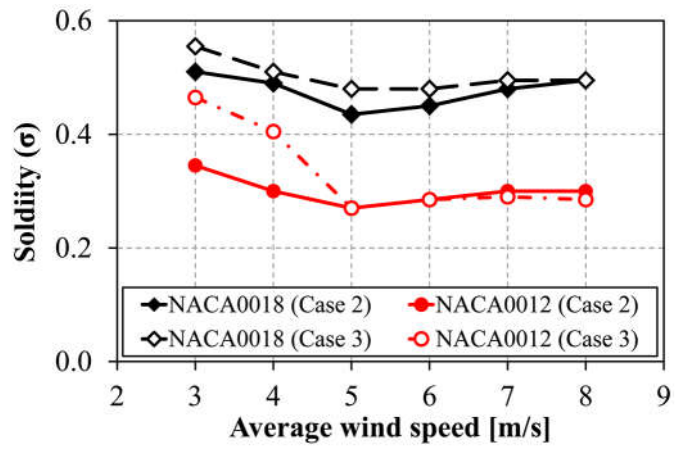


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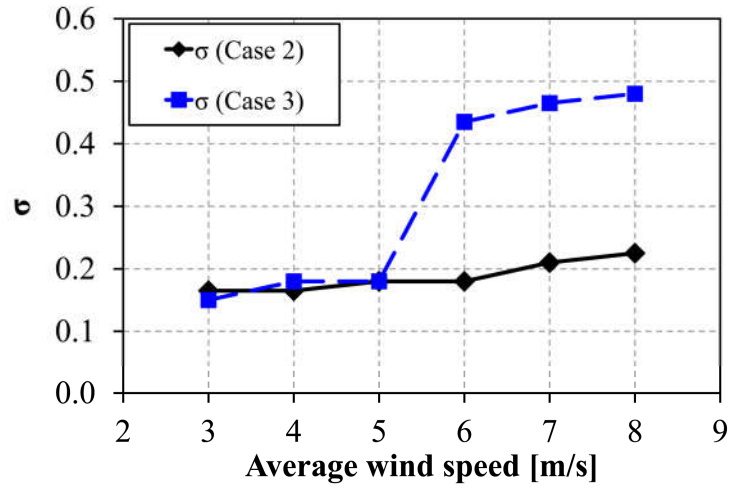


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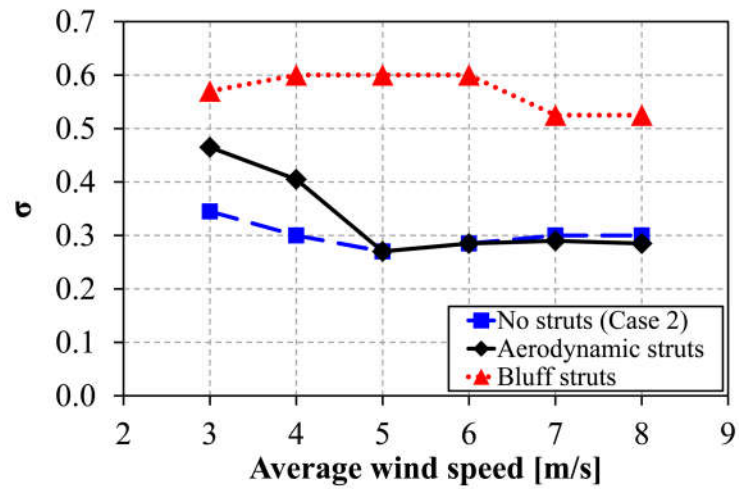
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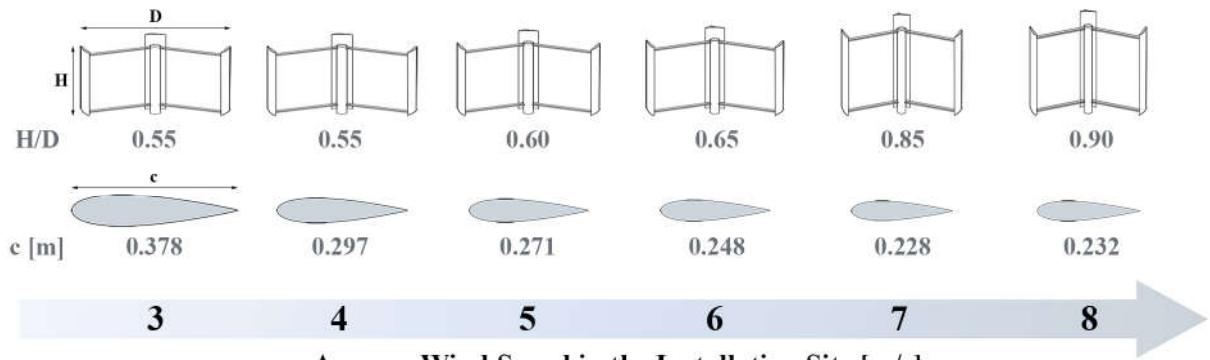


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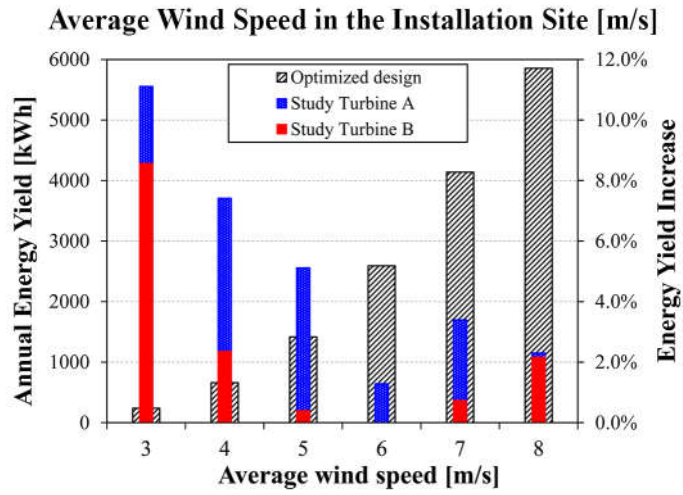


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