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Influence of Earthquake Ground-Motion Duration on Damage Estimation: Application to Steel Moment Resisting Frames

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SUMMARY

This paper presents an analytical study evaluating the influence of ground motion duration on structural damage of 3-, 9-, and 20-story SAC steel moment resisting frame (SMRF) buildings designed for downtown Seattle, Washington, USA, using pre-Northridge codes. Two-dimensional nonlinear finite element models of the buildings are used to estimate the damage induced by the ground motions. A set of 44 ground motions is used to study the combined effect of spectral acceleration and ground motion significant duration on drift and damage measures. In addition, 10 spectrally equivalent short duration shallow crustal ground motions and long duration subduction zone records are selected to isolate duration effect and assess its effect on the response. For each ground motion pair, incremental dynamic analyses are performed at at least twenty intensity levels and response measures such as peak inter-story drift ratio and energy dissipated are tracked. These response measures are combined into two damage metrics that account for the ductility and energy dissipation. Results indicate that the duration of the ground influences, above all, the combined damage measures, although some effect on drift-based response measures is also observed for larger levels of drift. These results indicate that since the current assessment methodologies do not capture the effects of ground motion duration, both performance-based and code-based assessment methodologies should be revised to consider damage measures that are sensitive to duration. Copyright © 0000 John Wiley & Sons, Ltd.

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KEY WORDS: Damage, Fatigue, Long-duration ground motions, Steel Moment Frames, Subduction Zone Earthquakes

1. INTRODUCTION

The effects of earthquake duration on civil engineering structures has been addressed only in the last quarter century and consensus within the scientific community is yet to be reached [1]. Longer earthquakes have been shown to increase the risk of failure on liquefaction [2] and slope instability [3] problems. However, early studies on the sensitivity of structural response to ground motion duration reported mixed results [4, 5, 6, 7]. These mixed results, together with the lack of ground motion records for large magnitude subduction events, lead to seismic design code provisions considering only effects of short duration earthquakes [8]. Among the works available in the literature that address the effects of duration on structural response, the main observations can be classified into two groups. First, studies that employ response measures

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based on peak displacement demands, such as peak drift ratios, generally do not find strong correlation between duration and the magnitude of the response (e.g., [9, 10]). Second, studies that employ cumulative response measures such as number of inelastic cycles, cumulative inelastic strains, and hysteretic energy dissipated, find a positive correlation between ground motion duration and structural response measures (e.g., [11, 12, 13]), showing that longer duration ground motions cause collapse at lower intensities [13]. These conclusions are also supported by other authors [9, 14, 15]. Even though the cumulative damage induced by the ground motion has been shown to be dependent on the amplitude, source-to-site distance, fault type, as well as the duration of the ground motion, it is not trivial to decouple the specific influence of duration.

Due to the increase in available ground motion data from recent subduction zone earthquakes, mainly from Japan and Chile, ground motion records from large subduction zone megathrust earthquakes can now be used [16, 17, 18, 13]. To isolate the effects of ground motion duration, Foschaar et al. [17] and Chandramohan et al. [19], for example, selected ground motions with similar spectral shape and studied the relationship between the response and different intensity measures of ground motion duration.

The objective of this paper is to better understand differences in structural damage on 3-, 9-, and 20-story ductile steel moment resisting frames (SMRF) when subjected to long duration or short duration earthquake ground motions. The SMRFs are part of the SAC steel project and correspond to buildings located in Seattle, Washington, designed using pre-Northridge codes. These three buildings are representative of the design practice in the US for decades, and the conclusions of this work can be significant in the assessment/retrofit of thousands of buildings. Two-dimensional nonlinear finite element models of the buildings are developed in OpenSees [20] and are validated against data available in the literature [21]. A database of 44 ground motions is used to assess the combined influence of ground motion duration and spectral acceleration on structural response. To isolate the effects of duration, 10 spectrally equivalent ground motion pairs are selected from the initial database of 44 ground motions following a procedure proposed in Chandramohan et al. [19]. Structural response is investigated in terms of deformation, energy dissipation, number of inelastic cycles, and damage state. To track damage, the Park and Ang [22] and Reinhorn and Valles [23] damage indices are used. The results show that buildings with different number of stories display different deformation and energy dissipation distributions that significantly affect their postearthquake structural damage and that increases in ground motion duration produce increases in accumulated damage.

2. DAMAGE INDICES

During an earthquake, damage sustained by a structure is a result of several phenomena, typically described as a function of deformation, ductility, energy dissipated, stiffness degradation, and strength degradation among others. To account for the complex combination of these parameters, different damage indices have been proposed in the literature. These indices provide a measure of the accumulated damage sustained by the components of the structure or by the entire structure. Damage indices are often calibrated based on experimental data for each loading condition and for a set of failure modes. The indices associated with the entire structure are usually based on a weighted average of the damage indices for components.

The main damage indices used for seismic damage assessment can be divided into three groups: (i) indices based on peak drift-based response measures; (ii) indices based on measures related to the inelastic cyclic response; and (iii) indices that combine peak drift-based response measures and inelastic cyclic response measures. For example, in the first group, Veletsos and Newmark [24] proposed a damage index that is based on the peak inelastic deformation. Lybas and Sozen [25] incorporated the concepts of cyclic deterioration and proposed a damage index that consists a ratio of the initial stiffness to the secant stiffness corresponding to maximum deformation. Roufaiel and Meyer [26] defined a local index based on the ratio between the

minimum secant stiffness recorded, i.e. the stiffness at the most damaged state attained, and the secant stiffness at the onset of failure. In the second group, some damage indices consider explicitly the energy dissipated as the measure of the severity of inelastic response [27, 28], while some others consider the number and amplitude [29, 30], or even the history of the inelastic cyclic response [31]. These indices focus on the effects of cumulative loading and combine inelastic measures of the response to account for fatigue, namely low-cycle fatigue [32]. In the third and last group, the response parameters considered individually in each of the former groups are merged into single indices. For example, Park and Ang [22] defined a damage index that is a linear combination of the ratio of the peak observed to ultimate deformation and hysteretic energy dissipated. Reinhorn and Valles [23, 33, 34] developed an index entitled Fatigue Based Damage Model that models the damage due to low plastic cycles fatigue. The Reinhorn and Valles index, which was calibrated with experimental data, is based on an initial development by [22].

The damage index proposed by Park and Ang [22] is given by:

$$DI_{PA} = \frac{d_m}{d_u} + \beta \frac{\int E_h}{d_u \times F_y} \tag{1}$$

where F_y is the yield strength, d_m is the maximum attained deformation, d_u is the ultimate deformation under monotonic loading, β is the empirical non-negative strength deteriorating constant, and $\int E_h$ denotes the hysteretic energy dissipated during the cyclic loading. β depends on the value of shear and axial forces in the section and, for RC components, on the total amount of longitudinal and confining reinforcement. Available test data for 402 RC components of rectangular cross-sections and 132 steel specimens of H-shaped sections tested in the U.S. and Japan were used to estimate β , resulting in a value of $\beta = 0.05$ for concrete structures and $\beta = 0.025$ for steel structures [35, 36].

The index proposed by Reinhorn and Valles [23] is based on the product of the ratio of the maximum to ultimate deformations and a low inelastic cyclic fatigue rule calibrated by the authors using experimental data. This index is given by:

$$DI_{RV} = \begin{cases} 0, & (d_m - d_y) \le 0\\ \frac{d_m - d_y}{d_u - d_y} \times \frac{1}{1 - \frac{\int E_h}{4 \times (d_u - d_y) \times F_y}}, & (d_m - d_y) > 0 & \& \quad \int E_h < 4 \times (d_u - d_y) \times F_y \\ 1, & \int E_h \ge 4 \times (d_u - d_y) \times F_y \end{cases}$$
(2)

where $4 \times (d_u - d_y) \times F_y$ represents the reference hysteretic energy dissipation capacity associated with the low inelastic cyclic fatigue.

Calibration of damage indices performed by Park et al. [35] are presented in Table I, as well as the degree of observed damage in the structures. These are the definitions for damage used in this study.

Degree of Damage	Damage Index, DI	State
Collapse Severe Moderate Minor/Slight	$> 1.0 \ 0.4$ - 1.0 $< 0.4 \ < 0.2$	Loss of building Beyond repair Repairable

Table I. Physical Interpretation of the Damage Indices [35]

3. GROUND MOTION SELECTION

Subduction earthquake motions were selected from databases that include earthquake records from the 2011 Great East Japan Earthquake [37], the 2010 Santiago, Chile earthquake [38],

the 1985 Valparaiso, Chile earthquake, the 2010 Southern Peru earthquake, and the 1999 Chi-Chi, Taiwan earthquake. It is worth noting that due to the high-frequency site effects, amplifications in the 2011 Great East Japan Earthquake records are expected to be greater than those adopted in the U.S. for typical NEHRP site classes [39]. Twenty-two ground motions obtained from these databases had to be filtered and baseline corrected [40]. For each of these long duration records, a corresponding short duration record with D_{5-75} shorter than 25 s, and having a closely matching response spectrum was chosen from the PEER NGA-West2 database [41]. The spectral ordinates of each short duration record were then scaled, such that the mean spectral ordinates of the scaled record were similar to those of the long duration record. Among all candidate short duration records that had not already been selected, the one with the lowest sum of squared errors was chosen.

The complete ground motion database is presented in Table II. The characteristics of these ground motion records are shown in Figure 1, namely in terms of moment magnitudes and source-to-site distance for each ground motion, as well as, peak ground acceleration, PGA, and the significant duration, D_{5-75} , which are all detailed in Kramer [42]. Figure 1(a) shows the distribution of earthquake ground motions as a function of the ground motion duration, D_{5-75} . Figures 1(b) to 1(d) show the relationship between D_{5-75} and ground motion magnitude, source-to-site distance, and PGA. This figure shows also the linear Pearson correlation coefficient and the Spearman correlation coefficient, which highlight that although these determination coefficients are not very large, a correlation between ground motion duration and magnitude as well as distance and PGA exist.

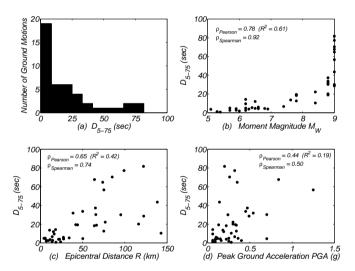


Figure 1. Ground motion records characteristics and correlation

Figure 2 shows the relationship between spectral acceleration at the fundamental period of each of the three buildings and ground motion duration. Figures 2a to 2c indicate that correlation between these two measures, although weak, can not be neglected as a trend can be observed graphically. In the interest of isolating duration effect on structural response, the comparison is based on ground motion pairs with similar response spectra. The selecting and scaling procedure is independent of the hazard at any site. However, for reference, the Seattle MCE values are shown in Figure 2 for each building.

These 44 ground motion records are used to first assess the influence of ground motion intensity and duration on the structural response and attained damage. Second, in order to decouple effect of duration from that related to intensity, ground motion pairs were defined following [19], to guarantee that both types of ground motions are spectrally equivalent. In this second analysis, ten ground motion pairs are considered. The ten selected shallow crustal ground motions and subduction zone ground motions are underlined in Table II. The table

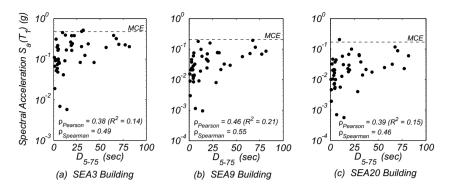


Figure 2. Ground motion spectral acceleration at the fundamental period of the intact structures versus significant duration for: (a) SEA3 Building; (b) SEA9 Building; and (c) SEA20 Building

lists the scale factors SF applied to the crustal motions response spectra. These factors are computed as to minimize the mean squared error of the logarithmic 5%-damped linear response spectral acceleration associated with each pair of subduction and crustal motions in the period range of interest of each building. The ratio between the spectral accelerations $(S_a(T_i))$, where T_i are the list of discretized periods of the response spectra) for each of the 10 pairs of subduction/crustal ground motion ranges between 0.44 to 2.46 (SEA3: 0.54-2.46, SEA9: 0.44-2.28, SEA20: 0.46-2.37) across the period range of interest for the spectral response. The period range of interest is defined as $0.2T_1$ to $1.5T_1$, where T_1 is the fundamental period of the structure after application of the gravity loads.

Figure 4 shows two of the 10 selected ground motion pairs used for analysis of the response of the SEA9 building. This figure shows a very good agreement between the individual response spectra for the two types of ground motions. For other pairs of ground motion and buildings, similar results are obtained, but not shown here in the interest of brevity. Moreover, median spectra of the long duration and short duration sets are, consequently, very similar. This similarity between the response spectra of the two types of earthquake ground motions is key in this study so that the effects of duration can be isolated from ground motion spectral response parameters.

4. BUILDING MODELS

4.1. General Description

The steel moment resisting frame (SMRF) buildings studied are a 3-, a 9-, and a 20-story building (denoted SEA3, SEA9, and SEA20, respectively), which were designed for Seattle, WA, as part of the SAC steel project [21] using pre-Northridge codes [43], considering a site class S2, similar to Site Class D [44]. In the buildings under analysis, the external frames were designed to resist the lateral (seismic) loads and the interior frames were designed as gravity frames. As shown in Figure 5, the three-story building presents no basement, while the nine-and 20-story buildings have one and two basement levels, respectively. The height of the frames is constant and equal to 3.96m, except for the two taller buildings, which have a first level with a height of 5.49m. A detailed description of the buildings is available in Gupta and Krawinkler [44].

Two-dimensional centerline nonlinear finite element models of a N-S external frame of each of the three buildings are developed in OpenSees and used for the structural analysis. Similar to the approach followed by Ribeiro et al. [45, 46] and Barbosa et al. [47], strong-column weakbeam ductile behavior is assumed for all structures. Brittle mechanisms and connection fracture modes are not considered. Geometric nonlinearities are accounted for during the analysis by considering a P- Δ leaning column. A rigid diaphragm is assumed for each floor. Soil-structure

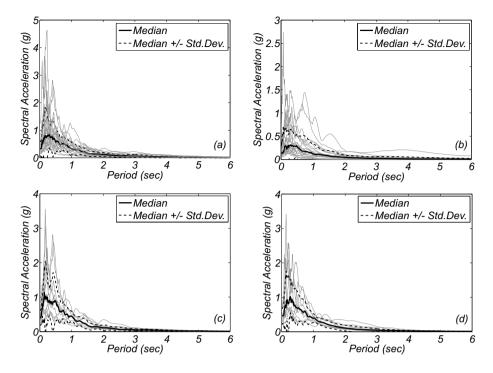


Figure 3. Comparison of the response spectra associated with the Suduction Zone and Shallow Crustal ground motions sets: (a) unscaled Subduction ground motions; (b) unscaled Crustal ground motions; (c) selected 10 Subduction ground motions (unscaled); and (d) selected and scaled Crustal ground motions.

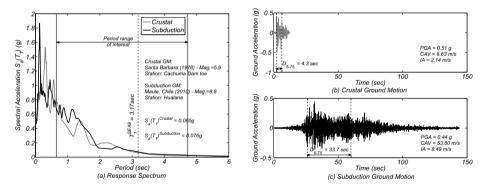


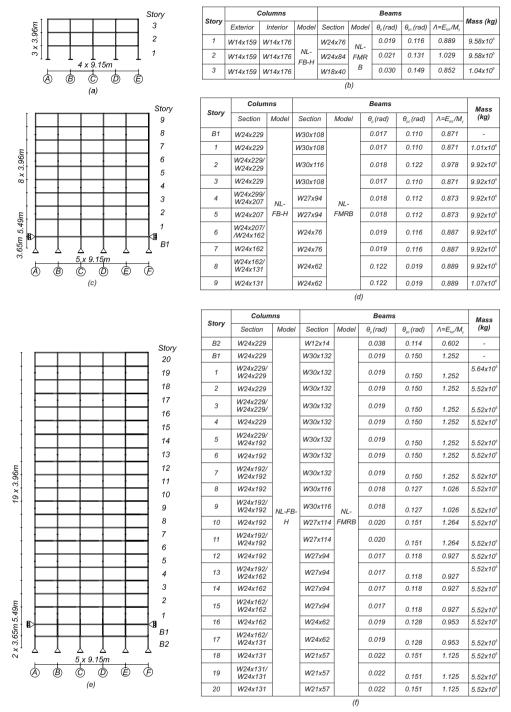
Figure 4. SEA9 Building: Comparison of the Suduction Zone and Shallow Crustal ground motion pair number 8: (a) Response Spectra; (b) Shallow Crustal Ground Motion; and (c) Subduction Zone Ground Motion

interaction is not considered. Floor masses are applied to beam-column joints whereas loads are applied to beam-columns joints and beam spans following the distribution of loads used in [45]. Rayleigh damping proportional to the mass and to committed stiffness is assigned to the models considering a damping ratio of 2% at the fundamental period T_1 of the intact structure of each building (shown in Table III) and at T = 0.2 sec for SEA3 and SEA9 buildings, and the fifth mode ($T_5 = 0.43$ sec) for SEA20.

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Pair	r Subduction Crustal																		
1 an	Earthquake	Year	Station		Mag.	R	PGA	D5-75	Earthquake	Year	Station	Comp.	Mag.	R	PGA	D5-75		SF	
	1			1	0	(km)	(g)	(s)				1		(km)	(g)	(s)	SEA 3		SEA 20
1	Valparaiso (Chile)	1985	El Almendral	L	7.8	63.8	0.22	18.3	Chalfant Valley-02	1986	Zack Brothers Ranch	360	6.2	7.6	0.40	2.6	0.73	0.68	0.58
2	Valparaiso (Chile)	1985	Llolleo	L	7.8	41.8	0.33	19.4	Livermore-02	1980	San Ramon-East. Kodak	180	5.4	18.3	0.28	0.7	1.47	2.04	1.92
3	Valparaiso (Chile)	1985	Laligua	200	7.8	44.0	0.13	19.3	Mammoth Lakes-02	1980	Convict Creek	90	5.7	9.5	0.16	2.6			
4	Valparaiso (Chile)	1985	San Fernando	EW	7.8	75.0	0.34	12.6	Gazli, USSR	1976	Karakyr	0	6.8	5.5	0.70	4.6			
5	Maule (Chile)	2010	Angol	EW	8.8	65.6	0.70	30.2	Irpinia, Italy-01	1980	Brienza	0	<u>6.9</u>	22.6	0.22	<u>4.0</u>	3.38	3.04	2.88
<u>6</u>	Maule (Chile)	2010	Constitucion	L	8.8	38.6	0.54	31.8	Managua, Nicaragua-01	1972	Managua, ESSO	90	6.2	4.1	0.36	4.9	1.99	1.94	1.92
7	Maule (Chile)	2010	Curico	NS	8.8	65.1	0.47	37.2	Coalinga-01	1983	Parkfield - St. Corral 3E	90	6.4	34.0	0.11	5.4	5.00	5.00	5.00
8	Maule (Chile)	2010	Hualane	T	8.8	50.0	0.45	33.7	<u>Santa Barbara</u>	1978	Cachuma Dam Toe	250	5.9	27.4	0.10	4.3	5.00	5.00	5.00
9	Maule (Chile)	2010	Papudo	\mathbf{L}	8.8	116.2	0.30	20.1	Lytle Creek	1970	Cedar Springs Pmp.	126	5.3	23.9	0.06	1.1			
10	Maule (Chile)	2010	Vina del Mar	\mathbf{EW}	8.8	66.4	0.34	18.9	San Fernando	1971	Lake Hughes No.1	21	6.6	27.4	0.15	4.4			
<u>11</u>	Tohoku (Japan)	2011	Miyakoji	EW	9.0	64.0	0.84	67.6	$\underline{\text{Parkfield-02, CA}}$	2004	Parkfield-Cholame 5W	90	<u>6.0</u>	6.9	0.25	<u>1.8</u>	2.79	2.38	2.43
<u>12</u>	Tohoku (Japan)	2011	Takahata	EW	9.0	122.0	0.20	81.7	Coyote Lake	1979	Gilroy Array No4	360	5.7	5.7	0.25	5.0	0.83	0.87	1.03
$\underline{13}$	Tohoku (Japan)	2011	Fukushima	EW	9.0	99.0	0.32	77.2	Friuli, Italy-02	1976	San Rocco	0	5.9	14.5	0.06	2.8	3.82	3.93	3.99
$\underline{14}$	Tohoku (Japan)	2011	Iwanuma	EW	9.0	85.0	0.26	70.3	L'Aquila, Italy	2009	Celano	NS	<u>6.3</u>	21.4	0.09	3.9	3.42	2.95	2.76
15	Tohoku (Japan)	2011	Tsukidate	\mathbf{EW}	9.0	75.1	1.25	56.6	Imperial Valley-06	1979	Compuertas	15	6.5	15.3	0.19	12.1			
16	Tohoku (Japan)	2011	Sakura	NS	9.0	122.3	0.49	28.6	Tabas, Iran	1978	Dayhook	\mathbf{L}	7.4	13.9	0.32	6.7			
17	Tohoku (Japan)	2011	Haga	\mathbf{EW}	9.0	95.1	0.24	30.0	Parkfield	1966	Cholame-Shandon No.12	50	6.2	17.9	0.06	14.3			
18	Tohoku (Japan)	2011	Chiba	\mathbf{EW}	9.0	138.4	0.14	43.6	San Francisco	1957	Golden Gate Park	10	5.3	13.7	0.09	1.1			
19	Tohoku (Japan)	2011	Hirata	NS	9.0	73.7	0.35	64.7	Hollister-03	1974	Hollister City Hall	181	5.1	11.5	0.09	3.7			
20	Southern Peru	2010	Moquegua	\mathbf{EW}	8.4	76.7	0.30	22.2	San Fernando	1971	Pasadena-CIT Ath.	0	6.6	27.2	0.10	6.0			
21	Southern Peru	2010	Arica Casa	NS	8.4	142.8	0.28	10.4	Imperial Valley-06	1979	Coachella Canal No.4	\mathbf{L}	6.5	50.1	0.12	4.7			
22	Chi-Chi (Taiwan)	1999	CWB ALS	NS	7.6	10.8	0.18	13.6	Irpinia, Italy-02	1980	Bisaccia	0	6.2	16.3	0.06	9.6			
μ								36.8								4.8	2.77	2.78	2.69
σ								22.6								3.4	1.63	1.60	1.57
min								10.4								0.7	0.46	0.34	0.28
max								81.7								14.3	5.00	5.00	5.00

Table II. Database of Shallow Crustal and Subduction Zone Earthquake Ground Motions



NL-FB-H - Nonlinear Force-Based Beam-Column Element with Fiber Section with 3% strain-Hardening NL-FMRB - Nonlinear Finite-Length Modified Gauss-Radau Beam-Column Element with Bilinear Flexural Hinge Model

Figure 5. Two-Dimensional Models of Steel Moment Resisting Frames Buildings in Seattle : (a) SEA3 Building; (b) SEA3 Sections, Model Parameters, and Floor Masses; (c) SEA9 Building; (d) SEA9 Sections, Model Parameters, and Floor Masses; (e) SEA20 Building; (f) SEA20 Sections, Model Parameters, and Floor Masses

4.2. Component Modeling

Two variations of a nonlinear finite element model are developed in OpenSees for the buildings. In both models, columns are modeled using nonlinear force-based fiber-section beam-column elements in which an elasto-plastic constitutive law with a 3% kinematic hardening is assigned to each fiber. Beams are modeled using a force-based finite length plastic-hinge beam-column element [48, 49], which models plastic hinge length explicitly and separates the behavior of beam in the span from that of beam-column connections. Both models use the modified Gauss-Radau integration scheme.

The difference between the two models lies in the modeling of the plastic-hinge employed for beams, which can be: (i) an elasto-plastic with hardening constitutive law; or (ii) bilinear model with strength deterioration. Here the first model is labeled FMRH (<u>F</u>inite-length <u>M</u>odified Gauss-Radau with <u>H</u>ardening), while the second model is labeled FMRB (<u>F</u>initelength <u>M</u>odified Gauss-Radau with <u>B</u>ilinear Model). The second model is also known as the modified Ibarra-Medina-Krawinkler deterioration model [50, 51], ModIMK model in short, and is a bilinear model that accounts for strength degradation. It was chosen for its versatility in modeling degrading hysteretic response of structural elements. This model was empirically calibrated for reproducing the moment-rotation relation of steel structural components [51]. The ModIMK model is based on a backbone curve defining the reference monotonic behavior and a set of rules defining the hysteretic behavior between the positive and negative backbone curves. The backbone curves are defined by three strength parameters: (i) effective yield moment, M_y , (ii) capping moment, M_c , and (iii) residual moment, M_r ; and four deformation parameters: (iv) yield rotation, θ_y , (v) pre-capping plastic rotation capacity, θ_p , (vi) postcapping plastic rotation capacity, θ_{pc} , and (vii) ultimate rotation capacity, θ_u .

This model defines four modes of cyclic deterioration: (i) basic strength, (ii) post-yield hardening ratio, (iii) post-capping strength, and (iv) unloading stiffness, controlled by a characteristic total hysteretic energy dissipation capacity E_{tot} and an energy-based rule developed by Rahnama and Krawinkler [52]. When a finite length plastic hinge element is used, a plastic hinge length of $L_p = L/6$ (where L is the beam span) should be used to recover the exact solution for the case of a fixed-fixed beam column element [53]. Otherwise, a plastichinge calibration approach is warranted for recovery of the elastic and inelastic stiffness [49]. All other model parameters are defined as proposed by Lignos and Krawinkler [51, 54]. Axial and shear behavior is assumed to be linear elastic. Joint shear deformations [44] and fracture due to low cycle fatigue [55] are not considered in this work.

4.3. Model Validation

The model validation performed here includes the comparison of results of nonlinear static pushover analysis and periods of the buildings models developed here using OpenSees with the FEMA355 M1 models [21]. The building periods available associated with the FEMA355 M1 models correlate well with the ones obtained in the FE models developed here, as shown in Table III. The FEMA355 models were developed using DRAIN-2DX [56]. The elements used in the DRAIN-2DX models correspond to concentrated plastic hinge models with a linear P-M interaction surface for compressive axial loads greater than $0.15P_{max}$. $P - \Delta$ effects were considered through modeling of a leaning column. Thus, the main differences between the FEMA355 models and the ones developed here are: (i) columns are now modeled using fiber section distributed plasticity elements and therefore account explicitly for the P-M interaction; and (ii) finite-length plastic hinge are modeled in two different ways: (a) similar to the FEMA models, assuming that the hinges do not have strength and stiffness degradation (FMRH models); and (b) considering degradation through use of the ModIMK model (FMRB model).

In all buildings the nonlinear static pushover analyses were performed assuming that the lateral load pattern applied is proportional to the 1^{st} mode of vibration of each structure.

Figure 6 shows the pushover curves for each of the three buildings and three finite element models (FMRH, FMRB, and FEMA355 M1 models). For reference, figures also show the design base shear quantified according to the allowable stress design method (ASD) of the

	SEA3 I	Building	SEA9 I	Building	SEA20 Building				
	OpenSees	FEMA355	OpenSees	FEMA355	OpenSees	FEMA355			
1^{st} Mode	1.36	1.36	3.15	3.17	3.82	3.92			
2^{nd} Mode	0.43	0.43	1.12	1.13	1.37	1.40			
3^{rd} Mode	0.22	0.22	0.60	0.61	0.81	0.82			

Table III. Periods of Vibration for OpenSees Models and FEMA355 Model

1994 Uniform Building Code [43]. In Figure 6, for the SEA3 building, it can be observed that the pushover curve of the model that does not consider strength deterioration (FMRH) matches relatively well the pushover curve of the FEMA model. For the SEA9 building, a good match is also found up to approximately 6% of roof drift ratio (RDR). At this RDR, the moment gradient of the columns is substantially reduced due to simplified axial force-bending moment P - M interaction surface considered in FEMA 355 M1 models, leading to a faster decrease in base shear. At this level of RDR (6%), the peak base shear has reduced by more than 80%, allowing for a validation of the model up to failure, if failure is described to correspond to the drift at which the strength capacity is reduced by 20% or more, as commonly assumed in earthquake engineering analyses. For the SEA20 building, significant differences are observed over the entire range. Such differences are expectable as a consequence of alternative modeling assumptions such as beam-column joint modeling.

In Figure 6(b), it can also be observed that the model FMRB, which considers the strength degradation in beams, has considerably greater strength deterioration. Note that the model has zero residual strength at about 6% RDR. Therefore, the results indicate that this model is valid until collapse, since it is only at this level of RDR that the column bending moment gradient would start playing an important role.

In summary, the model validation performed here is considered to be sufficient for the FMRH models. Although no direct validation of the FMRB models with experimental or numerical results is possible, the definition of component degradation is consistent with experimental results from a large database of component tests and P-M interaction is explicitly considered.

5. ANALYSIS METHODOLOGY

Following model validation, first, the buildings are analyzed under all ground motions described in Table II without considering any ground motion scaling. The objective of this first analysis is to evaluate the importance of duration on the damage indices. However, results obtained in this first analysis are both dependent of duration, D5-75, and the ground motion intensity, $S_a(T_1)$. Then, a second analysis is performed in which two groups of ten (10) ground motions are scaled to identical intensities in IDA analysis. This second analysis isolates the effect of ground motion duration, as for each intensity considered in the IDA analysis, the ground motions are selected to have identical response spectral values and shapes. IDA is performed at at least twenty intensity levels. Response measures recorded are the peak drift, residual drift, energy dissipated, and number of inelastic excursions at every beam section. The spectral acceleration at the fundamental period of the intact structure is taken as the intensity measure of the ground motions.

In this study, the damage indices are computed at the section level for each beam hinge and at the global level by aggregating the damage data for all beams. Structural damage is computed based on the performance of beams only, since these provide the largest contribution to the damage, as the design of these buildings was based on a strong column-weak beam concept. The section damage index is computed considering the curvature (χ) and moment (M) as the deformation (d) and strength (F) in Equations 1 and 2. The element damage index is taken as

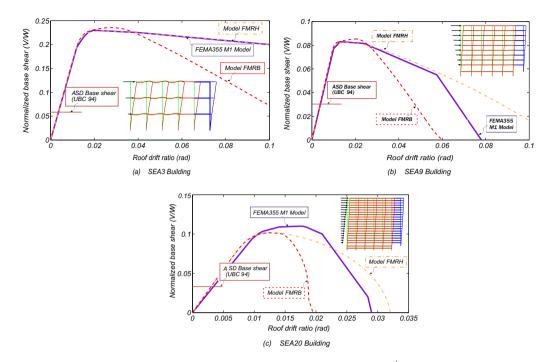


Figure 6. Nonlinear Static Pushover Capacity Curves Considering a 1st Mode Lateral Load Pattern: (a) SEA3 Building; (b) SEA9 Building; (c) SEA20 Building

the maximum of the section damage index of both hinges in a beam element, which is modeled as a finite-length concentrated plasticity finite element.

If some conditions are met, namely a regular distribution of mass, strength and stiffness in plan and height, such as the case of the buildings considered herein, a global value of the damage indices can be used to characterize damage in ductile members of steel frames [57]. Following the approach in IDARC2D [23], the damage index of the global structure is defined as the average of the element's damage indices weighted by their hysteretic energy dissipated, as:

$$DI^{structural} = \sum_{i=1}^{n_{element}} \lambda_{element,i} \times DI^{element,i}$$
(3)

where $DI^{element,i}$ is the damage index associated with element *i* and $\lambda_{element,i}$ is the ratio of the energy dissipated by element *i* to total element energy dissipated by all elements, given by:

$$\lambda_{element,i} = \frac{\int E_h^{element,i}}{\sum_{j=1}^{n_{element,j}} \int E_h^{element,j}}$$
(4)

where $\int E_h^{element,i}$ is the hysteretic energy dissipated by element *i*. If an element remains on an elastic state, its hysteretic energy dissipated is zero and according to Equations 3 and 4 it does not affect the structural damage index. On the other hand, if a single member has a damage index of 1.0 locally, the global index may not reach 1.0.

Using definitions in Equations 1 to 4, the following damage indices are recorded during the analysis: (i) damage index for each element, (ii) maximum element damage index over all floors, and (iii) structural damage index obtained through Equation 3. The second damage measure corresponds to the maximum among the damage indices computed for all beams and all floors. This value is intended to represent the damage state of the beam in worst condition. The

value is saved regardless of the beam/floor where it was attained. The third and last measure corresponds to a hysteretic energy dissipated weighted average of the observed damage over all beams at all floor levels. For each of the twenty ground motion intensities considered in this study, median values are computed for each damage measure.

It is worth noting that, when the hysteretic energy dissipated, $\int E_h$, exceeded the reference low inelastic cyclic energy dissipation capacity defined by Reinhorn and Valles [23] (Equation 2) as $4 \times (d_u - d_y) \times M_y$, it is assumed that $DI_{RV} = 1.0$. Although non-converged analyses can be incorporated in the collapse risk assessment when a fragility/collapse analysis is performed [58], the scope of this study is to compare the structural damage due to shallow crustal and subduction zone earthquakes, thus non-converged analyses are ignored.

In all analyses, the Newmark average acceleration method was employed. A maximum time step of 0.002 sec was used during analysis. This time step was deemed sufficient following a convergence study where the accuracy of roof acceleration time-history response due to large intensity shaking was studied using five time steps between 0.01 sec and 0.00005 sec. It was observed that a time step of 0.002 sec produces negligible errors (when compared to a time step of 0.00005 sec) and no significant changes in the response are observed when smaller time steps are used. The Newton-Raphson method is used to solve the nonlinear system of dynamic equations of equilibrium at each time step. An iterative scheme, which reduces the time-step, changes the solving algorithm, or slightly increases the tolerance criterion when a convergence issue was found, was implemented in the OpenSees analysis procedure.

6. RESULTS

6.1. Preliminary Results and Damage Assessment Calibration

6.1.1. Unscaled Ground Motions

The structural response of the three buildings was initially evaluated using all the unscaled records present in the database. Figures 7 and 8 show the structural response in terms of peak interstory drift ratio and Park and Ang structural damage index $DI_{PA}^{structural}$ for the three buildings as a function of the spectral acceleration and significant duration. Figure 9 shows similar plots for the remaining damage indices $(DI_{RV}^{structural}, DI_{PA}^{max-member})$, and $DI_{RV}^{max-member})$ for the SEA3 building. In these figures, 44 points associated with each performed analysis, are represented together with a multiple linear regression surface that best fits the data. Spectral acceleration is transformed so that the corresponding axis is in log-scale. In all figures a black line is also shown representing the maximum recorded response.

Figure 7 shows that there is a clear trend throughout all buildings. At first, for low values of spectral acceleration, there is no visible influence of ground motion duration on peak IDR. This is expected due to the existence of very few structural nonlinearities introduced by ground motions. Second, for intermediate spectral acceleration values the influence of ground motion duration increases as longer duration motions tend to induce larger peak IDR. Finally, for large intensity ground motions, long duration motions lead to significantly larger peak IDR. The coefficients of determination indicate that the performed multiple linear regression fit reasonably well the recorded data.

Figure 8 indicates that the trends identified in the previous figure hold for the case of this damage index for the three buildings. Since the obtained regression surfaces associated with the Park and Ang structural damage indices are similar for the three buildings, in Figure 9 results for the remaining damage indices are only represented for the SEA3 Building. In this Figure similar trends are identified. Comparison between $DI^{structural}$ and $DI^{max-member}$ shows that the influence of duration seems to be more relevant for the members.

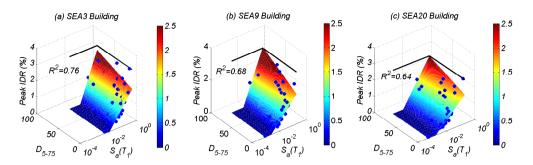


Figure 7. Peak interstory drift ratio as a function of the significant duration D_{5-75} and spectral acceleration $S_a(T_1)$ for the 44 unscaled ground motions for: (a) SEA3 Building; (b) SEA9 Building; and (c) SEA20 Building

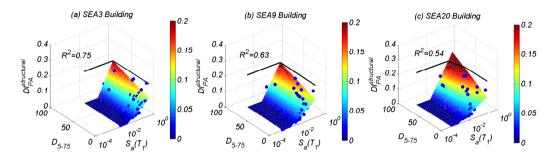


Figure 8. Park and Ang Structural Damage index $DI_{PA}^{structural}$ as a function of the significant duration D_{5-75} and spectral acceleration $S_a(T_1)$ for the 44 unscaled ground motions for: (a) SEA3 Building; (b) SEA9 Building; and (c) SEA20 Building

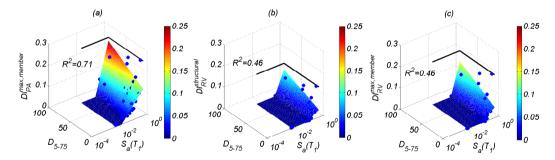


Figure 9. SEA3 Building: Damage indices as a function of the significant duration D_{5-75} and spectral acceleration $S_a(T_1)$ for the 44 unscaled ground motions: (a) Park and Ang maximum damage index $DI_{PA}^{max,element}$; (b) Reinhorn and Valles Structural Damage index $DI_{RV}^{structural}$; and (c) Reinhorn and Valles maximum damage index $DI_{RV}^{max,element}$;

6.1.2. Scaled Ground Motions

The structural response of the three buildings was then evaluated using selected scaled ground motion pairs. Results of the spectrally equivalent earthquake pair number 6 for SEA3 and pair number 8 for SEA9 building are shown next. Figure 10 shows the time-history results for the SEA3 building in terms of IDR and ratio between energy dissipated and total energy dissipation capacity (E_h/E_{tot}) for a left most plastic hinge at each story level. This figure shows that the difference in the peak IDR is not significant, where 2.95% is observed for the shallow motion against 3.09% for the subduction motion. However, the difference in terms of energy dissipation in the beam of the upper floor is significant, being 5.6% for the shallow motion and 20.4% for the subduction motion. Figure 11 shows results for SEA9 building. Only results of floors 1, 7, 8, and 9 are shown as these are the most critical floors, where higher IDRs are attained and more energy is dissipated. This figure shows that a peak IDR of 3.17% is induced by the subduction motion, while a peak IDR of 1.65% is induced by the crustal motion. Simultaneously, energy dissipated is considerably different for all the beams. Energy dissipation ratio is 12.0% for the subduction motion, while only 2.11% is attained for the crustal motion for the upper floor beam.

In summary, results in Figures 10 to 11 indicate that ground motion duration is an important factor that needs to be considered. Moreover, in the next subsection, structural response of the three buildings is evaluated using IDA.

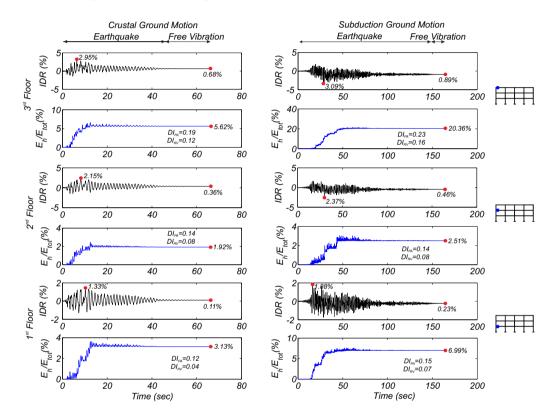


Figure 10. SEA3 Building: Response obtained with ground motion pair number 6 (with scaled crustal ground motion) in terms of Interstory Drift Ratio and ratio between energy dissipated and total energy dissipation capacity (E_h/E_{tot}) for a specific plastic hinge at each story level

6.2. Deformation and Energy Demands

The results in this section were obtained using 10 ground motion pairs underlined in Table II. In Figure 12 results for Incremental Dynamic Analysis (IDA) are shown for the three buildings. The intensity levels are chosen to guarantee that IDA structural failure is observed in all cases. This required twenty (20) intensity levels for SEA9 and SEA20 and twenty four (24) for SA3. In each figure, the median response is represented for the crustal and subduction ground motion sets. Overall, the median response is similar until approximately 4% peak IDR, up until which both types of earthquakes induce similar peak IDRs. Above the 4% peak IDR, the subduction ground motions seem to induce larger deformations than the crustal ground motions, for the same level of intensity, resulting in smaller spectral accelerations that cause collapse. This can be explained due to the concentration of damage, which is discussed in detail in the next

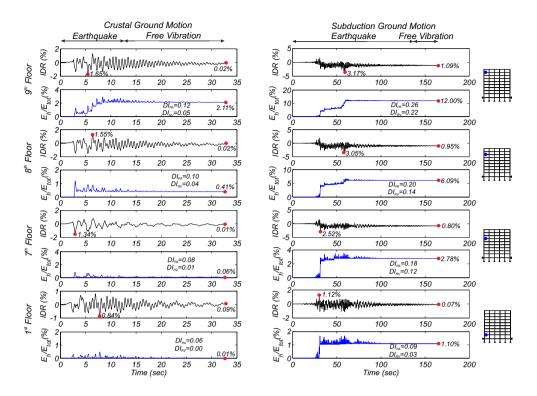


Figure 11. SEA9 Building: Response obtained with ground motion pair number 8 (with scaled crustal ground motion) in terms of Interstory Drift Ratio and ratio between energy dissipated and total energy dissipation capacity (E_h/E_{tot}) for a specific plastic hinge at each story level

paragraphs. It is worth noting that a similar trend was obtained by [59] for concentrically braced steel frames.

The residual interstory drift ratio (RIDR) has been referred as a good measure of the cumulative damage achieved by the structure and, consequently, a good indicator of the postearthquake resistant capacity [14]. Figure 12(d) shows the incremental dynamic analysis (IDA) curve for the RIDR for the twenty story building. Obtained results indicate that, for low intensities of shaking, shallow crustal ground motions tend to induce larger RIDRs than long duration subduction zone ground motions. The tendency of the longer duration motions to reduce the RIDR for lower intensities is related to the self-centering nature of the model, which has been discussed in detail by Barbosa et al. [47]. As the earthquake ground motion intensity increases, subduction ground motions induce larger residual deformations due to the increase in cumulative damage that is sustained by the structural members. Similar tendency, although less pronounced, is also observed for the 3-story building (not shown here). It is worth noting that RIDR is affected by the modeling approach used, especially when modeling structures to collapse. However, in the interest of the length of this paper, and because damage indices do not account for the RIDR, detailed discussion of the RIDR is left for future works.

Figure 13 shows the median ratio between the energy dissipated (E_h) and the total energy dissipation capacity (E_{tot}) in each plastic hinge at floor levels for each building. Results are shown for $S_a(T_1) = 0.56$ g for the SEA3 building, for $S_a(T_1) = 0.21$ g for the SEA9 building, and $S_a(T_1) = 0.15$ g for the SEA20 building. These values correspond to the spectral acceleration at the fundamental period of vibration of the buildings, based on Seattle MCE response spectrum. Note that an increase in the E_h/E_{tot} ratio corresponds to a reduction in the residual structural resistant capacity of the members. Figure 13 also shows the median interstory drift ratio (IDR) at each story for the same ground motion intensity levels, on the right side of each building. For the three buildings, it can be seen that the energy dissipated during subduction zone ground motions is significantly greater than that dissipated in shallow crustal ground motions,

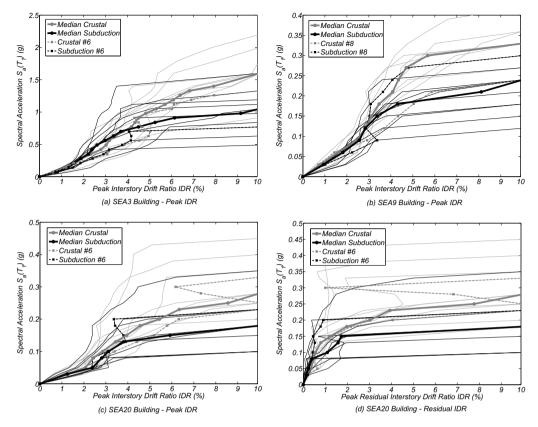


Figure 12. Incremental Dynamic Analysis: Capacity Curves Obtained Through of (a) SEA3 Building; (b) SEA9 Building; (c) SEA20 Building and (d) Residual Interstory Drift Ratio (RIDR) for SEA20

as a result of longer durations. In Figure 13(a), for the SEA3 building, the maximum ratio between the energy dissipated and the total energy dissipation capacity (E_h/E_{tot}) is reached at level 3, with a value of 16%. In Figure 13(b) it can be seen that building SEA9 is capable of redistributing deformations across a wide range of floors, where the peak ratios tend to be similar at multiple floors. In this building, the maximum ratio E_h/E_{tot} is 65%. Figure 13(c), for the SEA20, shows that the maximum energy dissipated in a plastic hinge is achieved in the SEA20 building, where the energy dissipation is concentrated in the 18^{th} and 19^{th} floors. For this building, the maximum ratio E_h/E_{tot} is 68%. For each ground motion type, a strong correlation between the energy dissipated at each floor and the interstory drift ratio is found. Building SEA20, in particular, presents a high concentration of energy dissipated in higher floors, where peak interstory drift ratios are also recorded, thus showing that this building may be more vulnerable after the earthquake. Possible reasons for the concentration of damage in higher floors are: (1) contribution of higher modes, and (2) smaller cross-sections of the beams in the upper two to three stories (see Figures 5c and 5d for building SEA9 and Figures 5e and 5f for building SEA20). It is worth noting, however, that even though a greater demand is expected from the subduction events, the distribution of the demand over the building height is similar for both groups of earthquakes.

In conclusion, at these levels of intensity, although subduction zone ground motions do not significantly influence peak interstory drift ratios, they impose a greater energy dissipation demand, that can negatively impact the performance of the structures. This highlights the importance of considering damage indices that account for the effect of energy dissipation.

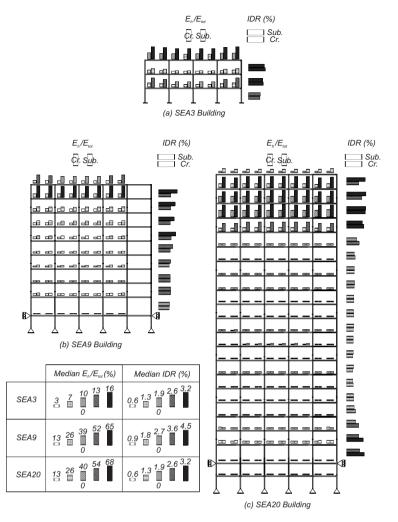


Figure 13. Median Ratio of the Energy Dissipated to the Total Energy Dissipation Capacity (E_h/E_{tot}) at Each Plastic Hinge Section and Median Interstory Drift Ratio (IDR) at Each Story for a Spectral Acceleration Corresponding to the Seattle MCE intensity levels: (a) SEA3 Building at Sa(T1) = 0.56g; (b) SEA9 Building at Sa(T1) = 0.21 g; and (c) SEA20 Building at Sa(T1) = 0.15 g

6.3. Damage Assessment

As mentioned before, three groups of results are obtained for each damage index $(DI_{PA}$ and DI_{RV}): (i) median damage index for each beam; (ii) median maximum beam damage index (regardless of the beam at which the maximums were recorded); and (iii) median structural damage index. The results for each damage index shown next were obtained using 10 ground motion pairs underlined in Table II.

Figure 14 shows the median DI_{PA} damage index recorded at three different intensities, $S_a(T_1) = 0.56$ g, $S_a(T_1) = 0.21$ g, and $S_a(T_1) = 0.15$ g for SEA3, SEA9, and SEA20 buildings, respectively. The subduction ground motions consistently lead to higher damage indices, thus proving to be more damaging than crustal ground motions. The maximum damage index is achieved in the SEA20 building, which is consistent with conclusions drawn from Figure 13. At the elements where the maximum damage index is recorded in SEA9 and SEA20 buildings, the index associated with crustal ground motions is, at most, 60% of the corresponding value for subduction ground motions.

Figure 15(a) shows the median structural damage indices obtained for subduction ground motions plotted versus the indices obtained for the crustal ground motions for all IDA intensity

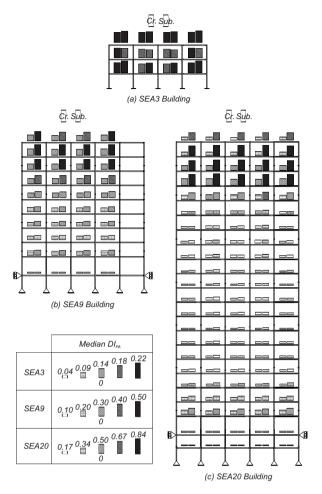


Figure 14. Median Park and Ang Damage Index at Each Element for a Spectral Acceleration Corresponding to the Seattle MCE Intensity Levels: (a) SEA3 Building at $S_a(T_1) = 0.56$ g; (b) SEA9 Building at $S_a(T_1) = 0.21$ g; and (c) SEA20 Building at $S_a(T_1) = 0.15$ g

levels. Every pair of results for ground motion types were obtained at the same ground motion intensity levels, as can be seen for an example pair of the IDA results shown in Figure 12. A similar plot is presented in Figure 15(b) but here considering the median maximum damage index recorded. In both figures, damage indices associated with subduction ground motions are always greater than the ones associated with crustal ground motions. Damage indices associated with building SEA20 are consistently larger than the ones associated with the other two buildings, namely for the structural damage index. In addition to this, damage index DI_{RV} is always greater than DI_{PA} , showing that building response presents high sensitivity to energy dissipation, which can be considered as a proxy for cumulative damage. For the subduction zone ground motions, a large number of elements exceeds the threshold value of $DI_{PA} = 0.4$, which according to Park et al. [35] indicates a non-repairable damage state. For the shallow crustal ground motions this threshold is only exceeded in the SEA20 building.

6.4. Influence of Duration on Deformation-Damage Relationships

Figures 16 to 19 show the damage indices associated with subduction and crustal ground motions plotted as a function of the peak IDR, for the 10 ground motion pairs underlined in Table II. Figure 16 shows, for the SEA9 building, the computed median results of the four different damage indices, namely the structural DI_{PA} index, maximum DI_{PA} index, structural

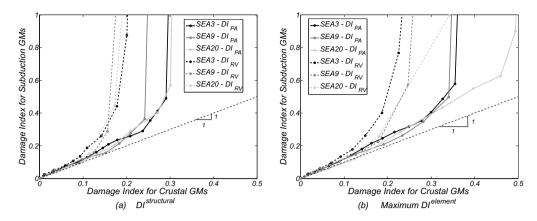


Figure 15. Comparison of the Median Damage Indices Recorded in the Analyses Carried Out With Shallow Crustal and Subduction Zone Ground Motion: (a) Structural Index; and (b) Median Maximum Element Value

 DI_{RV} index, and maximum DI_{RV} index, respectively. Figure 17 show the individual results, associated with ground motion pair number 8, of the same damage indices for the SEA9 building. Figure 18 shows the median Park and Ang DI_{PA} index for the SEA3 and SEA20 buildings. Finally, Figure 19 show the individual results of this damage index associated with ground motion pair number 6 for these buildings.

The coefficients of variation (CoV) of each damage index were estimated for all IDR levels presented in Figures 16 and 18. It was found that the CoV increase monotonically. However, for higher values of the IDR, the CoV is strongly influenced by the number of analysis that lead to collapse, losing some significance. r a threshold value this increase is exponential due to the larger dispersion in the results, namely because the analyses that lead to collapse. In the tables presented in this Figure is presented the threshold IDR that precede the exponential increase and the associated CoV. These values may be used in future probabilistic studies. After these threshold IDR values the CoV values are actually larger than those presented in the tables.

Similar trends are observed throughout these figures, i.e. similar damage indices are obtained for both subduction zone and shallow crustal motions for peak IDR lower than 2.0%, in terms of the median but also for individual pairs of ground motions. Up to this point, in most cases, subduction ground motions induce slightly larger damage indices, but the differences are not significant. However, beyond 2.0% IDR, the differences are significant and results clearly show that longer durations impose much larger damage indices at similar levels of peak IDR. For example, for a peak IDR of 4.0%, the damage index associated with subduction ground motion is at least 50% higher than that associated with crustal ground motions. Moreover, it is worth noting that smaller IDR tend to lead to smaller damage indices. However, in some cases larger IDR can be associated with lower damages (as seen of the top right of Figure 19b). This phenomenon, denoted "resurrection from death", was first identified by [60] when analyzing IDR under IDA. Figures 16 and 18 also show that the same damage index can be expected from a subduction earthquake with an intensity significantly lower than the corresponding crustal earthquake intensity. This difference tends to increase as the peak IDR increases since the slope of the two lines, corresponding to the two types of earthquakes, is significantly different.

Figures 16 and 18 also show tables with the CoVs of the peak IDR at two reference damage index values, i.e. 0.2 and 0.4. Results indicate that the CoV for subduction records are always greater or equal to that of crustal records. This highlights the limitations of the IDR as a surrogate for quantifying damage for subduction earthquakes.

As a conclusion, it can be stated that damage measures based on the peak IDR underestimate the potential consequences of long duration earthquakes. To accurately compute structural damage, it is paramount to define more accurate performance measures to use with both crustal and subduction earthquakes.

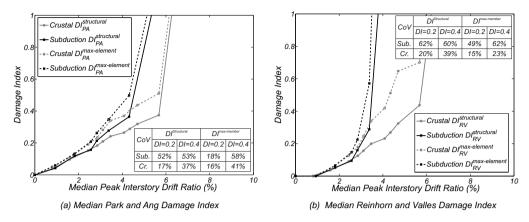


Figure 16. SEA9 Building: Median Damage Indices as a Function of the Median Peak Interstory Drift Ratio for Shallow Crustal and Subduction Zone Ground Motions: (a) Park and Ang Damage Index (DI_{PA}) ; and (b) Reinhorn and Valles Damage Index (DI_{RV})

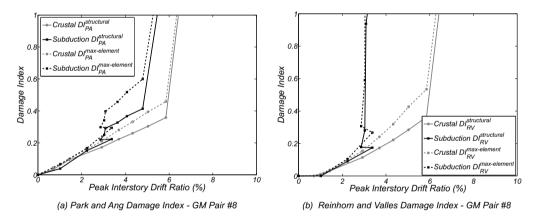


Figure 17. SEA9 Building: Damage Indices as a Function of the Peak Interstory Drift Ratio for Ground Motion Pair Number 8: (a) Park and Ang Damage Index (DI_{PA}) ; and (b) Reinhorn and Valles Damage Index (DI_{RV})

7. CONCLUSION

Structural damage estimation in civil engineering infrastructure due to long duration ground motions has received less attention than short duration earthquakes. As a result, present codes as well as performance-based design methodologies are typically based on response and damage measures calibrated to short duration shallow crustal earthquakes. Subduction zone earthquakes are responsible for developing ground motions longer than those expected to develop due to shallow crustal earthquakes. Even though some recent studies have shown that longer duration ground motions may lead to greater collapse risk, an extensive assessment of the influence of ground motion duration on structural damage is still lacking in the earthquake engineering literature. This paper aims at partially bridging that knowledge gap.

In the present paper, the performance of steel moment resisting frames under sets of 22 short duration and 22 long duration earthquakes is compared in terms of the expected level of damage caused by the earthquakes, to evaluate the combined influence of ground motion

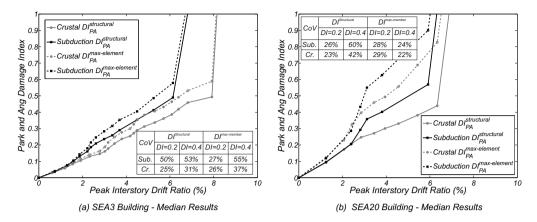


Figure 18. Median Park and Ang Damage Index as a Function of the Median Peak Interstory Drift Ratio for Shallow Crustal and Subduction Zone Ground Motions: (a) SEA3 Building; and (b) SEA20 Building

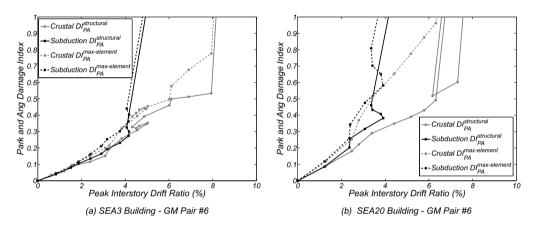


Figure 19. Park and Ang Damage Index as a Function of the Peak Interstory Drift Ratio for Ground Motion Pair Number 6: (a) SEA3 Building; and (b) SEA20 Building

duration and spectral acceleration. Subsequently, 10 ground motion pairs are selected from the initial sets and are used to investigate the influence of duration on structural response in terms of deformation, energy dissipation, number of inelastic cycles, and damage state. Crustal ground motions are scaled so that spectrally equivalence is guaranteed in each pair. Incremental dynamic analysis are then performed at at least 20 intensity levels.

The obtained results for short and long duration earthquakes indicate that:

- for low values of spectral acceleration, there is no visible influence of ground motion duration on deformations and damage; for large spectral accelerations, longer duration motions tend to induce larger peak IDRs and damage indices;
- in terms of deformation, the median response between the two sets of ground motions is similar until approximately 4% peak IDR; above this, the long duration ground motions tend to induce larger deformations under the same values of spectral acceleration;
- the relationship between the peak inter-story drift ratio and damage indices was found to be nonlinear; this level of nonlinearity increases with ground motion duration
- the 3- and the 9-story buildings presented a relatively homogeneous distribution of damage over the height, while the 20-story building presented a concentration of damage in the top three floors; this damage concentration was enhanced for the longer duration motions

- largest damage indices were obtained for the 20-story building as a consequence of the concentration of damage; on the other hand, the design of the 9-story building efficiently distributed deformations over the height
- although further work is needed, residual interstory drift ratio (RIDR) was found to be different for the two ground motion earthquake types; for the structural modeling approach used here, similar levels of RIDR are obtained only for smaller intensities.

The changes in strength and ductility requirements included after the Northridge earthquake will increase the energy dissipation capacity of the members and connections. This will likely lead to a reduction in the impact of ground motion duration on cumulative damage, but to assess the amplitude of this reduction, further studies are necessary. In addition, results in this paper indicate that regions affected by subduction zone earthquakes, such as the Cascadia Subduction Earthquake Zone, should be subjected to an extensive probabilistic assessment of the seismic performance of structures subjected to ground motions due to all potential sources. Such a study should account for the relative contribution of the various seismic sources, for example following the approach presented in FEMA P-695 [61]. If the trends recorded in this paper are maintained, these regions should have their design revised to account for the effects of duration. More research is required considering different types of buildings and different modeling assumptions, namely in what concerns modeling different failure mechanisms (e.g., low-cycle fatigue, shear failure, or connection failure) and materials (RC, timber, etc.). Further work is also required in order to develop accurate relationships between ground motion intensity measures and structural damage indices to be used within performance-based earthquake engineering frameworks.

8. ACKNOWLEDGMENTS

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