

Parametric studies and optimisation of pumped thermal electricity storage

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Abstract

Several of the emerging technologies for electricity storage are based on some form of thermal energy storage (TES). Examples include liquid air energy storage, pumped heat energy storage and, at least in part, advanced adiabatic compressed air energy storage. Compared to other large-scale storage methods, TES benefits from relatively high energy densities, which should translate into a low cost per MWh of storage capacity and a small installation footprint. TES is also free from the geographic constraints that apply to hydro storage schemes. TES concepts for electricity storage rely on either a heat pump or refrigeration cycle during the charging phase to create a hot or a cold storage space (the thermal stores), or in some cases both. During discharge, the thermal stores are depleted by reversing the cycle such that it acts as a heat engine. The present paper is concerned with a form of TES that has both hot and cold packed-bed thermal stores, and for which the heat pump and heat engine are based on a reciprocating Joule cycle, with argon as the working fluid. A thermodynamic analysis is presented based on traditional cycle calculations coupled with a Schumann-style model of the packed beds. Particular attention is paid to the various loss-generating mechanisms and their effect on roundtrip efficiency and storage density. A parametric study is first presented that examines the sensitivity of results to assumed values of the various loss factors and demonstrates the rather complex influence of the numerous design variables. Results of an optimisation study are then given in the form of trade-off surfaces for roundtrip efficiency, energy density and power density. It is concluded that roundtrip efficiencies approaching those for pumped hydro schemes might be achievable whilst simultaneously attaining energy storage densities of around 200 MJ m^{-3} , but this is contingent upon attaining compression and expansion efficiencies for reciprocating devices that have yet to be proven.

Keywords: electricity storage; thermal energy storage; irreversibility; heat transfer; optimisation.

1. Introduction

The finite nature of fossil fuel reserves together with a wide range of health and environmental concerns arising from the release of combustion products have been acting as drivers for the increasing uptake of renewable sources of energy, such as solar and wind [1]. These energy sources have the potential to reduce the overall dependence on fossil fuels and the emissions arising from their use, however, both solar (especially PV) and wind energy are associated with variable, intermittent and (particularly for wind) uncertain outputs. Beyond the economic considerations of using a significant fraction of inherently variable power generation, the intermittent nature of these energy sources has given rise to concerns regarding their reliable integration into the electric grid. These factors have led to the widely accepted recognition that energy storage forms an essential part of efficient and sustainable future energy systems, in particular ones featuring significant amounts of renewable resources. In the UK, for example, it is estimated that over the next few decades the integration of intermittent sources into the power infrastructure will require storage capacities of the order of hundreds of GWh – an order of magnitude greater than current capacity [2].

Pumped hydro storage (PHS) is currently the dominant large-scale energy storage technology, with over 99% of the world’s installed storage capacity in this form. However, the high initial cost and geographical constraints of PHS mean that many new technologies are emerging, including batteries, flow batteries, compressed air storage (CAES) and, of particular interest here, thermal energy storage (TES). A comprehensive review of these technologies is given in Ref. [3]. TES systems suitable for large-scale storage (i.e., > 100 MWh) include: cryogenic systems for which energy is stored within tanks of liquid air or liquid nitrogen; pumped heat storage where energy is stored in high temperature reservoirs, either as ‘sensible heat’ or ‘latent heat’; and hybrid systems that simultaneously exploit both hot and cold thermal storage. Proposals for new types of CAES (notably ‘Advanced-Adiabatic’ CAES, or AA-CAES) also include a thermal storage component. Despite the variety of detailed arrangements, all TES systems effectively make use of some form of heat pump during the charge phase to extract thermal energy from a low temperature source and deliver it (together with the energy from the electrical work input) to a higher temperature sink. Energy flows are then reversed during discharge such that the system operates as a heat engine. Since the maximum (Carnot) efficiency of the heat engine is precisely the reciprocal of the maximum coefficient of performance of the heat pump, the round-trip efficiency is limited only by the reversibility of the system’s various processes.

The present paper focuses on a form of TES system referred to here as ‘pumped thermal’ electricity storage (PTES)*, several independent patents for which seem to have emerged almost simultaneously [4]–[7]. A similar system also seems to have been proposed much earlier [8]. For the particular variant of PTES considered here, based mainly on that described in Ref. [6], the charging (heat pumping) phase is achieved by an electrically driven reverse Joule-Brayton cycle, which establishes a temperature difference between two packed-bed thermal stores. Electrical energy is thus converted to thermal energy that then resides in the stores. When electricity is required, the cycle operates in forward (heat engine) mode, returning heat from the hot to the cold store, thereby recovering electrical work.

The important factors in determining the merit of any electrical energy storage technology are its round-trip efficiency (i.e., the fraction of electrical energy input retrieved upon discharge) and its capital costs per MW installed capacity and per MWh of storage. In this respect, PTES benefits from relatively high energy density, which implies a small plant footprint and low capital cost per MWh. (Comparison of a few large-scale storage

* Also known as ‘pumped heat’ electricity storage (PHES)

1 technologies suggests that PTES might achieve an energy density roughly an order of magnitude greater than
2 that for CAES and two orders of magnitude greater than for PHS [9].) However, power density (as opposed to
3 energy density) is also an important factor as it impinges on the size and cost of the machinery and hence on
4 the cost per MW. Table 1 compares power densities (in terms of exergetic flow rate per unit volumetric flow
5 rate of working fluid) for a few different technologies. The figure for PTES is relatively low, suggesting that
6 controlling pressure losses and designing small, cheap power conversion machinery for such a system will be
7 challenging.

8
9 Previous theoretical work relating to PTES includes ‘endoreversible’ analysis of a generic system [10] and
10 more practical studies of open [8] and closed-cycle devices [11] based on turbomachinery. For the system
11 proposed in Ref. [6] however, compression and expansion are achieved by reciprocating devices since there
12 is evidence that these are capable of higher polytropic efficiencies than turbomachinery. A second, crucial
13 advantage of reciprocating devices is that, by adjusting valve timings, they can in principle be reversed
14 such that compressors become expanders and *vice versa*. This means that the same devices can be used for
15 both charge and discharge, thereby lowering the capital cost per MW and enabling a rapid switch to meet
16 sudden increases in electricity demand.

17
18 A 1.5 MW and 6 MWh system based on reciprocating devices is currently being developed in the UK funded
19 by the Energy Technologies Institute (ETI)* and its proponents estimate that it will attain an overall round-trip
20 efficiency of 75%. Achieving this will require extremely low ‘thermodynamic’ losses in the compressors and
21 expanders, and in the other system components, notably the thermal stores. The objectives of the present
22 paper are to estimate the feasibility of such low losses, to examine the sensitivity of system performance to
23 the various loss parameters and to determine also the role of different operating and geometric parameters. In
24 the following sections an account is first presented of the loss-generating mechanisms that occur throughout a
25 PTES system. Sub-models for these components are then described and brought together into overall system
26 calculations, which are presented in the form of parametric studies. These serve to emphasise the interplay
27 between the different sources of loss, and how storage density and the distribution of exergetic losses depend
28 on the various system pressures and temperatures and on other, geometric factors. Although such parametric
29 studies provide a sound physical basis for guiding design, system optimisation remains a complex task due to
30 the large number of operational and design parameters, the multiple and often conflicting objectives (e.g.
31 efficiency and energy/power density) and the uncertainty associated with some aspects of the loss modelling.
32 An evolutionary-based optimisation algorithm has thus been applied to identify promising designs. This
33 algorithm allows trade-off surfaces (also known as a Pareto fronts) to be plotted, thereby giving insight into
34 how the optimal design may vary when multiple objectives are considered.

35 36 **2. Baseline Design**

37 The outline design features of a hypothetical 2 MW PTES system with 16 MWh of storage is given in Ref.
38 [12]. A system of this size has been adopted for the analysis presented here and it is useful to first provide
39 estimates for the main system parameters. The power and storage capacity given below are ‘nominal’
40 values in the sense that they are the values that would be achieved in the absence of losses and in the
41 (hypothetical) case where the reservoirs can be fully charged.

* See http://www.eti.co.uk/technology_programmes/energy_storage_and_distribution

1 2.1 Operating pressures and temperatures

2 Figure 1 shows the basic layout of a PTES system, together with T-s (temperature-entropy) diagrams for
3 typical discharge and charge processes, which follow the standard and reverse Joule cycle respectively. The
4 main system components are two compression-expansion devices (CE and EC) and two thermal reservoirs
5 (one hot, HR, and one cold, CR). Following [6], the discharged state of the reservoirs is set close to
6 ambient temperature: 310 K in the present case. With argon as the working fluid (as proposed in Ref. [5]),
7 and with a pressure ratio of 10:1, the nominal hot and cold storage temperatures (based on isentropic
8 compression and expansion) are then 778 K and 123 K respectively.

10 2.2 Reservoir sizing

11 For a reversible, adiabatic PTES system, the stored energy that can be converted back to useful work (i.e.,
12 the ‘available’ energy) is simply the difference between the stored internal energies of the two reservoirs,

$$13 \quad E = M_s^h c_s^h (T_2 - T_3) - M_s^c c_s^c (T_1 - T_4) = M_s^h c_s^h (T_2 - T_3 - T_1 + T_4), \quad (1)$$

14 where M_s is the mass of storage material, c_s is its average specific heat capacity over the relevant temperature
15 range, and the superscripts h and c refer to the hot and cold reservoirs respectively. The right hand equality in
16 Eq. (1) arises from the requirement that the two reservoirs should charge in the same period and must
17 therefore have the same heat capacity. As discussed in Ref. [13], Fe_3O_4 provides a suitable storage material
18 due to its high heat capacity per unit volume and its low fractional variation of heat capacity over the
19 temperature ranges of interest. Data for Fe_3O_4 are given in Table 2, together with the required storage masses
20 computed from Eq. (1) for 16 MWh of storage. The reservoir volumes are also given in the table, calculated
21 on the basis that the storage material is in the form of a packed bed of spherical pebbles with an average void
22 fraction of 0.35. Note that these volumes would correspond to ‘square’ (i.e., $L/D=1$) cylinders with internal
23 diameters of 4.5 m and 5.3 m for the hot and cold stores respectively.

25 2.3 Compression and expansion device sizing

26 The power output for a reversible, adiabatic PTES system is given by,

$$27 \quad \dot{W}_x = \dot{m} c_p \{ (T_2 - T_1) - (T_3 - T_4) \}. \quad (2)$$

28 Using the temperatures listed above and data for argon ($c_p = 520 \text{ J kg}^{-1}\text{K}^{-1}$), the mass flow rate required for
29 a 2 MW device comes to 13.7 kg s^{-1} . The total swept volumes for the compression-expansion cylinders are
30 computed from,

$$31 \quad \dot{m} = \rho_{\text{ref}} V_s \eta_v \omega / 2\pi, \quad (3)$$

32 where the reference density ρ_{ref} is at inlet for compression but at exit for expansion – i.e., ρ_1 for CE and ρ_4
33 for EC. The volumetric efficiency η_v is a function of the pressure ratio, β , and clearance volume ratio of the
34 cylinders ($V_{\text{min}}/V_{\text{max}}$). With the latter set at 0.05, the simplified model presented in Appendix A for an ideal
35 reciprocating device gives a volumetric efficiency of 0.84 at $\beta=10$. The resulting swept volumes are shown
36 in Table 3, together with various cylinder dimensions computed on the basis of 6-cylinder devices running
37 at 1200 RPM, with each cylinder having an aspect ratio (stroke/diameter) of 0.25. This low aspect ratio is
38 proposed in the designs described in Ref. [12] on the grounds that the resulting low piston velocity will
39 give low valve pressure losses and low inertial loading.

40

1 2.4 Other design considerations

2 In addition to the main components described above, the PTES system also requires heat exchangers (HX1
3 and HX3 in Fig. 1), and a buffer vessel (BV in the figure). The heat exchangers are needed to counter the
4 effects of irreversibility throughout the system and their size can only be determined, therefore, after
5 consideration of the cycle efficiency. The buffer vessel is required because the total mass of gas within the
6 two reservoirs changes during charge. The total change between fully charged and fully discharged for the
7 nominal design is 142 kg, as indicated from the figures in Table 2. This requires a buffer volume of 8.7 m³
8 if situated at Point 3 in the cycle, as in Fig. 1.

9

10 3. System and Component Modelling

11 In order to determine the influence of the various system parameters on round trip efficiency, power
12 density and storage density, a simple system model has been developed based on quasi-steady analysis of
13 each of the system components. Heat exchangers, compressors and expanders are treated as steady flow
14 devices (in the time-averaged sense), but the equations governing heat transfer within the reservoirs are
15 integrated in time in order to track the hot and cold thermal fronts. This is necessary because the stored
16 available energy and the exergetic losses in the reservoirs are dependent upon the time-history of their
17 operation, as described in Refs. [13,14]. For the other components, estimates are first made for various loss
18 parameters, based on the nominal design described above. Several of these parameters are, however,
19 subject to considerable uncertainty, either because they depend on detailed design (e.g., pressure losses
20 within pipework) or because the underlying theory has not yet been sufficiently developed (e.g., for
21 compression and expansion efficiencies). The approach adopted is therefore to undertake baseline
22 calculations using best estimates for minimum values of these parameters and then to examine the impact
23 of their variation on the overall performance.

24

25 3.1 Compression and expansion losses

26 The simplest approach for modelling ‘steady flow’ compressors and expanders is by either an isentropic or
27 polytropic efficiency. For turbomachines, published data suggest polytropic efficiencies (i.e., infinitesimal
28 stage efficiencies) of about 90% are achievable. For reciprocating devices, data is scant but compression
29 efficiencies in the range 75 – 85% seem typical [15]. Although this is lower than the values cited for
30 turbomachinery, much of the loss in reciprocating devices is associated with valve pressure drop and there
31 may be scope for considerable improvement. On the other hand, the relatively long residence time of the
32 gas within the device (compared to a turbo-compressor) means that there is often significant heat transfer to
33 the surroundings and hence isentropic efficiency is ill-defined. As shown in Ref. [16], the effects of heat
34 leakage and irreversibility can, however, be distinguished by combining a heat leakage factor (defined as
35 the ratio between the instantaneous heat and work transfer, $\alpha = dq/dw_x$) with a polytropic efficiency (defined
36 as $\eta = -vdp/dw_x$). This leads to polytropic relations of the form,

$$37 \quad \tau_c = \beta_c^{\phi_c} \quad \text{with} \quad \phi_c = \frac{\gamma-1}{\gamma} \left(\frac{1-\alpha_c}{\eta_c} \right), \quad (4)$$

38 where τ_c and β_c are the compressor temperature and pressure ratios respectively. Compressor work input is
39 then found by straightforward application of the steady flow energy equation, giving,

$$40 \quad w_c = \frac{c_p T_1 (\tau_c - 1)}{1 - \alpha_c}, \quad (5)$$

1 where T_1 here is the compressor inlet temperature. Similar expressions to (4) and (5) apply to expansion
 2 processes. Although this approach allows the impact of irreversibility and heat leakage to be studied
 3 separately, the fundamental difficulty lies in estimating values for α and η . In theory, with sufficient
 4 insulation, α could be reduced to zero, but η is difficult to estimate. The chief losses are likely to be: (i)
 5 pressure drop through the valves; (ii) cyclic heat transfer to and from the cylinder walls across finite
 6 temperature differences and (iii) mixing of fresh intake gas with the residual gas within the clearance
 7 volume. It is convenient to treat pressure losses separately as throttling losses external to the compression
 8 process, and so η is used here solely to represent heat transfer and mixing irreversibility. Rudimentary
 9 estimates of the minimum values of loss factors that might be achieved are given in Appendix A.

11 3.2 Pressure losses

12 Pressure losses in valves, pipework, heat exchangers and the reservoirs all contribute to the expander
 13 seeing a lower pressure ratio than the compressor. These losses are represented here by fractional pressure
 14 loss factors, $f_p = \Delta p/p$, since these are most closely tied to exergetic losses. Thus a given absolute pressure
 15 loss Δp has a greater impact on performance if it occurs in the low-pressure part of the cycle. Estimates of
 16 pressure losses through the compressor and expander valves are given in Appendix A, but losses within
 17 manifolds, ducts and heat exchangers etc. cannot easily be estimated without knowledge of the detailed
 18 geometry, and so a range of f_p values has been considered. It is worth noting, however, that if pressure
 19 losses are assumed to be of the order of $\frac{1}{2}\rho v^2$, and if these are to be kept within 1% of the local pressure
 20 then this would imply ducts of the order of 0.5 m diameter at Point 1 (Fig. 1) for the nominal design.
 21 Pressure losses in the reservoirs are treated separately and calculated explicitly, as discussed below.

23 3.3 Thermal reservoir losses

24 The main sources of loss within the reservoirs are frictional pressure loss and heat transfer (thermal)
 25 irreversibility. Heat leakage is not considered here since, with sufficient insulation, it can be reduced to any
 26 desired level. However, estimates suggest that a 1% heat leakage to or from each reservoir would typically
 27 reduce round-trip efficiency by about 2% since leakage reduces both the stored energy and the Carnot
 28 efficiency at which that energy can be converted to work [9].

30 Thermal losses occur because heat exchange necessarily takes place across a finite gas-solid temperature
 31 difference. The model used to quantify these losses is based on the well-established Schumann model of
 32 heat transfer in packed beds [17], which assumes that the flow is one-dimensional and that heat transfer is
 33 limited by surface effects (i.e., the internal thermal resistance of particles is negligible). The result is that
 34 the energy equations for the gas and solid can be expressed approximately as,

$$35 \quad \frac{\partial T_g}{\partial z} = \frac{T_s - T_g}{\ell}, \quad (6)$$

$$36 \quad \text{and} \quad \frac{\partial T_s}{\partial t} = \frac{T_g - T_s}{\tau}, \quad (7)$$

37 where the length and time scales are defined by,

$$38 \quad \ell = \frac{1}{\text{St} (1 - \epsilon) S_v}, \quad (8)$$

$$39 \quad \text{and} \quad \tau = \frac{\rho_s c_s}{\text{St} c_p G S_v}. \quad (9)$$

1 In these expressions, G is the mass flow rate of gas per unit (open-tube) area, St is the Stanton number
 2 (based on the open-tube velocity) and S_v is the particle surface-to-volume ratio, which is $6/d_p$ for spherical
 3 particles. In practice, a number of refinements to this model are included to account for unsteady
 4 accumulation terms for the gas, temperature dependence of the solid heat capacity, and variations in
 5 density, viscosity and other gas properties. Most of these have only a minor impact, but the variation of c_s
 6 can significantly affect the thermal losses. Full details of the numerical method are given in Refs. [13] and
 7 [14], and typical temperature profiles for a cold reservoir are shown in Fig. 2. The instantaneous entropy
 8 generation rate (and hence the thermal loss) is determined from the temperature profiles as,

$$9 \quad \dot{S}_{irr} = \int \left(\frac{1}{T_s} - \frac{1}{T_g} \right) d\dot{Q} = (1 - \epsilon) A S_v \int_0^L h \frac{(T_g - T_s)^2}{T_s T_g} dz, \quad (10)$$

10 where h is the local heat transfer coefficient and A is the (open-tube) area of the packed bed. Previous work
 11 has established that the fractional exergetic loss decreases with the dimensionless length of the reservoir
 12 ($\Lambda = L/\ell$) and depends in a rather complicated manner on the inlet and exit temperatures. For periodic,
 13 cyclic operation (as opposed to one-off charge and discharge), thermal losses are also a function of the
 14 charge period expressed in the dimensionless form $\Pi = t_{chg}/t_{nom}$, where $t_{nom} = \Lambda\tau$ is the nominal charge time.
 15 This parameter is referred to here as the ‘utilisation factor’ since it is approximately equal to the stored
 16 energy as a fraction of its full-charge value.

17 Pressure losses in packed beds are relatively straightforward and computed from,

$$18 \quad \frac{dp}{dz} = \frac{S_v(1 - \epsilon)C_f G^2}{2\epsilon^3 \rho_g}, \quad (11)$$

19 where C_f is the friction coefficient obtained from packed-bed correlations such as those given in Ref. [18].
 20

21 *3.4 Heat exchanger and other losses*

22 Geometric and other design details of the heat exchangers have not been included at this stage. Instead
 23 datum temperatures at Points 1 and 3 in the cycle are specified for each calculation and the heat exchange
 24 required to maintain these temperatures is then computed. As noted above, heat rejection must occur in
 25 order to counter irreversibility throughout the cycle and, because it occurs at above the environment
 26 temperature, there is a further exergetic loss associated with the heat exchangers themselves. In addition,
 27 there is a small throttling loss associated with returning the buffer volume gas to the low-pressure part of
 28 the cycle. Estimates indicate that this is very small and it has been neglected in these calculations.
 29

30 **4. Parametric Studies**

31 Before presenting an optimisation study, it is useful to examine how the various system parameters impinge
 32 upon overall performance. Loss factors, operating conditions and geometric parameters have all been
 33 varied over the ranges shown in Table 4. As each quantity is varied, all others listed in the table are held at
 34 their nominal values, except when varying pressure ratio, as discussed further below. The effect on
 35 performance is considered in terms of:

$$36 \quad \text{Round trip efficiency:} \quad \chi = \frac{\text{net work output}}{\text{net work input}} = \frac{W_{dis}^{net}}{W_{chg}^{net}} \quad (12)$$

$$37 \quad \text{Energy density:} \quad \rho_E = \frac{\text{net work output}}{\text{reservoir volume}} = \frac{W_{dis}^{net}}{V_{CR} + V_{HR}} \quad (13)$$

1 Power density:
$$\rho_p = \frac{\text{average power output}}{\text{hot cylinder volume}} = \frac{W_{\text{dis}}^{\text{net}} / t_{\text{dis}}}{V_s^{\text{CE}}} \quad (14)$$

2 The net work terms in the above are obtained by integrating the power input or output over the duration of
 3 the charge-discharge cycle. (Some variation of power occurs because the hot and cold fronts reach the exits
 4 of the reservoirs.) Note that the round-trip efficiency considered here reflects only the thermodynamic
 5 component of loss **since** electrical and mechanical losses will also occur. For a 2 MW machine using an
 6 induction motor-generator, electrical efficiencies of 97% (in each direction) are commonplace, but
 7 mechanical losses for a custom-built reciprocating compressor-expander are less easy to estimate. Howes
 8 [12] suggests that a mechanical efficiency of 92% (again in each direction) might be possible, which
 9 together with electrical losses would give an overall round-trip efficiency of $(\eta_{\text{mech}}\eta_{\text{elec}})^2\chi \approx 0.8\chi$.

10 Due to space constraints, power density is not discussed in this section, but it is taken into account during
 11 the optimisation process presented in Section 5.

12

13 *4.1 Sensitivity to the assumed values of loss parameters*

14 Figure 2 shows the thermodynamic round-trip efficiency, χ , as a function of each of the loss factors. The
 15 trends are in line with the simplified analysis presented in Ref. [9], except that a slightly greater sensitivity
 16 to heat leakage is predicted here. (Detailed scrutiny of the loss distribution suggests that this is associated
 17 with the ‘exit loss’, which was not accounted for in Ref. [9] and which occurs when the hot and cold fronts
 18 reach the reservoir exit, as indicated in Fig. 2.) The sensitivity to α and η are both very significant, showing
 19 the importance of minimising heat leakage and emphasising the need for a better understanding of thermal
 20 irreversibility in reciprocating devices. In what follows it is assumed that η is independent of operating
 21 conditions, but arguably it should fall with pressure ratio, as described in Appendix A.

22

23 *4.2 Variation of performance with operating conditions*

24 Figure 4 shows the effect of various cycle operating conditions on efficiency and power density. In varying
 25 these parameters, the nominal power and storage capacity have been held constant by adjusting the size of
 26 reservoirs and the mass flow rate. Pressure losses in the reservoirs are then adjusted in accord with Eq.
 27 (11), but the nominal f_p values have been retained for valve, pipework and manifold losses.

28

29 At fixed pressure ratio, the efficiency and energy density are both improved by either increasing T_1 or
 30 decreasing T_3 . Increasing the pressure ratio at fixed T_1 and T_3 has a similar effect, as shown in Fig. 4(a). These
 31 trends are consistent with the findings reported in Ref. [9] where it was argued that, if compression and
 32 expansion losses dominate, then the efficiency is governed mainly by the ratio T_2/T_3 since this determines the
 33 ratio between compression and expansion work. Increasing this ratio (as all of the above variations in T_1 , T_3
 34 and β will achieve) thus makes the cycle less susceptible to compression and expansion losses. However,
 35 improvements along these lines will almost certainly result in increased costs and technical challenges since
 36 they imply higher top temperatures or pressures, or lower bottom temperatures. A more detailed examination
 37 of the distribution of losses also reveals that the benefits of higher work ratio are partly offset by increased
 38 thermal losses in the reservoirs. If the maximum and minimum cycle temperatures (T_2 and T_4) are fixed,
 39 instead of fixing T_1 and T_3 , then variation of the pressure ratio gives trends similar to those observed for gas
 40 turbine cycles for which there are optimum pressure ratios, as shown in Fig. 4(b). The optimum pressure
 41 ratios for energy density and efficiency are, in this case, 7.6 and 9.1 respectively, but the corresponding values
 42 of T_3 (3.5 and 24.5 °C) lie below ambient temperature. This precludes the possibility of rejecting heat in HX3,
 43 making it difficult to manage the thermal fronts as they emerge from the reservoirs.

1
2 Figure 4(b) also shows the influence of ‘utilisation factor’ Π and the discharge pressure ratio. Increasing Π
3 (i.e., longer charge and discharge period) obviously increases the energy stored per cycle, but this is at the
4 expense of lower efficiency. This is due to steeper temperature gradients within the reservoirs, which imply
5 that gas-solid heat exchange occurs over a smaller interfacial area and hence with a larger temperature
6 difference. Varying β_{dis} effectively controls the balance of heat rejection between HX1 and HX3, as can be
7 seen by examining the T - s diagram shown in Fig. 1. A sharp optimum in this pressure ratio is observed in
8 Fig. 4(b) and occurs when heat rejection is roughly evenly divided between the two heat exchangers.
9

10 *4.3 Variation of performance with geometric factors*

11 The geometric parameters varied here are the hot and cold reservoir aspect ratios (L/D) and particle
12 diameters, d_p . The resulting maxima in efficiency shown in Fig. 5 reflect the trade-off, inherent in most
13 heat exchange processes, between heat transfer losses and pressure losses. For example, small particles
14 give large heat exchange area but increase the frictional effects. Likewise, long reservoirs give lower
15 thermal losses [14], but the associated reduction in cross-sectional area implies higher fluid velocities and
16 hence higher pressure drop. Due to the lower average gas density, pressure losses are more significant in
17 the cold reservoir and hence the optimum aspect ratio is lower and optimum particle size larger than for the
18 hot reservoir. However, it should be recalled that these results have been obtained with all other parameters
19 fixed at their nominal values, and the picture changes when overall system optimisation is considered.
20

21 **5. Preliminary Optimisation Studies**

22 The design space for a PTES system is multi-dimensional and is possibly multi-modal and disjoint due to the
23 large number of design variables, objectives and constraints. This makes optimisation by systematic
24 parameter variation a complex task. A stochastic optimisation algorithm has therefore been applied to identify
25 promising designs. The routine chosen for this purpose is a ‘non-dominated sorting genetic algorithm’
26 (NSGA-II) as described in Ref. [19]. Like other stochastic methods, this is well suited to the current problem
27 as it is able to traverse the entire design space with limited risk of becoming trapped in local optima.
28

29 Full optimisation clearly requires consideration of economic factors, material limits, and other practical
30 issues that lie outside the scope of the present paper. Nonetheless, a preliminary indication of useful design
31 trends can be obtained on the basis of thermodynamics alone by simultaneously maximising the round trip
32 efficiency and the energy and power densities. (Strictly, the optimiser minimises the negative of each of
33 these quantities.) Since increasing cost is associated with higher pressures and extremes of temperature,
34 limits are set for β , T_2 and T_4 . Likewise, a lower limit is set on both T_1 and T_3 of 10 °C above the ambient
35 temperature in order that HX1 and HX3 can both reject heat to the environment. This is necessary in order
36 to manage the thermal fronts as they emerge from the reservoirs. Ranges for all the design variables under
37 consideration are given in Table 5. Two design scenarios are considered: an *optimistic* scenario, for which
38 $\eta=0.99$, and a standard scenario with $\eta=0.90$ (i.e., achievable in principle with turbomachinery). Nominal
39 values have been retained for the other loss factors.
40

41 *5.1 Pareto fronts and parallax plots*

42 The best designs emerging from the optimisation are shown in Fig. 6 in the form of ‘Pareto fronts’. These
43 are the leading edges of the design space in that all other solutions lie either below or to the left of these

1 fronts. The Pareto fronts thus show the trade-off between the different objective functions and allow the
2 designer to see the entire range of potential solutions.

3
4 As expected, there is a trade-off between efficiency and energy density (Fig. 6(a)), whereas Fig. 6(b)
5 indicates that efficient designs are consistent with high power density. It is notable that roundtrip efficiency
6 changes by only a small amount over a wide range of energy density for both the optimistic and standard
7 scenarios. Thus, for example, a thermodynamic efficiency of 85% and energy density of 200 MJ/m³ could
8 be achieved simultaneously in the optimistic case.

10 5.2 Parallax plots

11 Figure 7 is a so-called parallax plot, which compares values of the different design variables of the optimal
12 solutions. To avoid overcrowding, only four designs have been plotted (Points 1 through 4 on Fig. 6), but
13 by examining a parallax plot for the full Pareto front it is possible to draw out information about the best
14 designs. For example, if all solutions converge on a narrow range of a particular parameter it suggests that
15 the objective functions are sensitive to that parameter. (Note that the parameter ranges shown in the figure
16 are taken from the full Pareto front.) From Fig. 7 it is apparent that:

17 (i) The main factor controlling the trade-off between efficiency and energy density is the utilisation, Π .

18 (ii) High polytropic efficiency, ($\eta=0.99$), seems to correlate with low pressure ratio (typically around 7.5:1)
19 and high T_1 . A further parametric study, centred on the optimal designs, indicated that the optimiser had not
20 quite converged: increasing the pressure ratio to 10:1 with a commensurate reduction in T_1 gave a very
21 slight (0.1%) improvement in efficiency. Nonetheless, the results shown in Fig. 7 suggest that almost the
22 same performance can be achieved at lower cost – lower pressure ratio and higher T_1 imply cheaper
23 components, notably CE, EC, HR and HX1.

24 (iii) Optimum discharge pressure ratios lie slightly below the charge pressure ratio.

25 (iii) Some parameters, notably the top temperature T_2 and hot reservoir discharged temperature, T_3 , are
26 ‘saturating’ at their limiting values, particularly for low η cases. Although this suggests that the bounds on
27 these parameters should be relaxed, this should only be done whilst also considering economic and other
28 practical factors.

29
30 Some of these observations could have been deduced from the parametric studies or from simple thermo-
31 dynamic considerations, but others (notably Point (ii)) are not so obvious and highlight the benefits of
32 optimisation techniques.

34 5.3 Comparison of loss distributions

35 The optimal designs in the optimistic scenario have considerably higher efficiency than the nominal design
36 (even when account is taken of the higher assumed value for η) and it is interesting to see how this has been
37 achieved. Figure 8 compares the breakdown of losses for the nominal design (but with $\eta=0.99$) and for the
38 design corresponding to Point 3 in Fig. 6. Most of the improvement evidently occurs by optimisation of the
39 thermal store geometries and particle sizes. The associated reduction in heat exchanger loss is really due to
40 the avoidance of exit losses that occur when the thermal fronts emerge from the stores (these losses are passed
41 on to the heat exchangers, rather than being associated with the stores themselves). As expected, optimisation
42 of the stores for high efficiency (i.e., Point 3) results in roughly a half-and-half split between thermal and
43 pressure losses. The resulting geometry is perhaps a little unrealistic in that the short, fat reservoirs would be
44 prone to uneven flow distributions through the packing, would require a larger footprint and would lead to

1 manifold and pipework complications. Such difficulties need to be explored further, but it is possible that they
2 can be mitigated by the use of segmented stores, as proposed by Crandall and Thatcher [20].
3

4 It is also apparent from Fig. 8 that a substantial part of the overall loss is due to heat leakage to and from
5 the compressors and expanders. This merely reflects the assumed heat leakage factors of 2% for both CE
6 and EC, and it is possible that lower heat leakage could be achieved in practice. Based on estimates from
7 early prototypes and approximate (not fully non-dimensionalised) scaling, Howes [12] argues that heat
8 leakage for a 2 MW machine should be negligible, which according to Fig. 8 would reduce thermodynamic
9 losses by another 3.5%.
10

11 **6. Conclusions**

12 A study of thermodynamic aspects of pumped thermal electricity storage (PTES) has been presented, based
13 on steady flow analysis of the compression and expansion devices coupled with a Schumann-style model of
14 the hot and cold thermal stores. Parametric studies reveal that there are optimum values for some design
15 variables, whilst others either lead to a trade-off between efficiency and energy density or can be varied so
16 as to improve both these quantities together. Sensitivity of performance to the various loss factors has also
17 been considered. Since the charge-discharge cycle for a PTES system involves two compressions and two
18 expansions, the roundtrip efficiency is (not unexpectedly) sensitive to the loss factors for these processes.
19 In this respect, a better understanding is required of the various sources of irreversibility within
20 reciprocating devices.
21

22 Multi-objective optimisation has been applied to generate trade-off surfaces known as Pareto fronts. These
23 show that curves of roundtrip efficiency vs. energy density are relatively flat over a considerable range, so
24 that high energy density can be attained with only a modest efficiency penalty. In the optimised designs,
25 losses associated with pressure drop and irreversible heat transfer in the stores are only a few percent, so
26 the success of PTES is likely to hinge upon compressor and expander performance. Predicted efficiencies
27 and storage densities obviously depend on the assumed loss factors; with an ‘optimistic’ set of parameters
28 that might be achievable with reciprocating devices, the thermodynamic round-trip efficiency could exceed
29 85% whilst the system simultaneously achieves an energy density almost an order of magnitude greater
30 than that for CAES. With reasonable estimates for mechanical and electrical losses, this would give an
31 overall roundtrip efficiency (i.e., electricity out over electricity in) of just under 70%. On the other hand, if
32 the compressors and expanders could only achieve efficiencies typical of turbomachinery then the overall
33 roundtrip efficiency is unlikely to exceed 50%.
34

35 **Acknowledgement**

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38 an EPSRC-funded studentship. All authors gratefully acknowledge this support.
39

1 Nomenclature

A	area, m ²	α	heat leakage factor, dq/dw
c_s	solid specific heat capacity, J kg ⁻¹ K ⁻¹	α_t	gas thermal diffusivity, m ² s ⁻¹
c_p	gas specific heat capacity, J kg ⁻¹ K ⁻¹	β	pressure ratio
C_f	friction coefficient in packed bed	γ	ratio of specific heats
D	reservoir diameter, m	χ	roundtrip efficiency
d_p	particle diameter, m	ε	void fraction or clearance ratio
E	stored energy, J	η, η_v	polytropic, volumetric efficiency
f_p	fractional pressure loss	Λ	dimensionless reservoir length
G	mass flow per unit area, kg s ⁻¹ m ⁻²	Π	reservoir utilisation factor
h	local heat transfer coefficient	ρ	density, kg m ⁻³
ℓ	length scale, m	ρ_E	energy density, J m ⁻³
L	reservoir length, m	ρ_P	power per unit flowrate, J m ⁻³
M_s	mass of storage material, kg	σ	valve-to-piston open area ratio
\dot{m}	gas mass flow rate, kg s ⁻¹	τ	time scale, s, or temperature ratio
p	pressure, Pa		
q	heat transfer per unit mass		
r_v	volume (compression) ratio		
\dot{S}_{irr}	entropy generation rate, J K ⁻¹ s ⁻¹		
St	Stanton number		
S_v	surface area to volume ratio, m ⁻¹		
t	time, s		
T	temperature, K		
V_s	swept volume, m ³		
w	specific work, J kg ⁻¹		
\dot{W}	power input/output, W		

Subscripts and superscripts

c, h	cold, hot
chg	charge
dis	discharge
g	gas
s	solid
CE	compressor-expander
EC	expander-compressor
1 – 4	points on cycle, as shown in Fig. 1

2
3 Other symbols are defined in the text where they are used.

4 Appendix A: Estimation of Loss Parameters

5 The intention of this section is to estimate minimum values of the various loss factors that might be
6 achieved with custom-built reciprocating devices. These estimates are rather approximate and further work
7 is clearly required, some of which is currently underway (see, for example, Ref. [21]).

8
9 *A1 Volumetric efficiency*

10 Figure 9 shows a p - V diagram for an ideal reciprocating device. As shown, the device is operating as a
11 compressor; the direction of the processes would be reversed for an expander. In the absence of heat loss
12 and irreversibility, Processes A-B and C-D are isentropic. The volumetric compression ratio is thus,

$$13 \quad r_v = \frac{V_A}{V_B} = \frac{V_D}{V_C} = \beta^{1/\gamma}. \quad (\text{A1})$$

14 If inlet valve pressure losses are small (see Section A2 below) then the mass of gas entering the cylinder
15 during the induction stroke (D-A) is,

$$16 \quad m = \rho_i(V_A - V_D) = \rho_i V_A (1 - \varepsilon r_v), \quad (\text{A2})$$

1 where ρ_i is the inlet density and ε is the clearance volume ratio, (V_C/V_A). The volumetric efficiency is thus,

$$2 \quad \eta_v = \frac{m}{\rho_i V_s} = \frac{1 - \varepsilon r_v}{1 - \varepsilon}, \quad (\text{A3})$$

3 where $V_s = (1 - \varepsilon)V_A$ is the swept volume. The same expression may be applied to expanders provided the
4 density in Eq. (A3) is replaced with the exit value. Eq. (A3) effectively gives the pressure ratio / mass flow
5 characteristic of the device. In real devices, Eq. (A3) would need to be modified to account for valve
6 pressure losses, mixing of the induced and residual gas, and non-isentropic Processes A-B and C-D.

7 8 *A2 Valve pressure losses*

9 Valve losses will be minimised if the valves open and close rapidly and are actuated when there is zero
10 pressure difference across them. Pressure traces for the prototype devices reported in Ref. [12] bear a
11 remarkable similarity to the p - V diagram of Fig. 9 and suggest that this ideal might well be achievable in
12 practice. Under these circumstances, the instantaneous total pressure drop may be estimated as,

$$13 \quad \Delta p = \frac{1}{2} \rho v_p^2 \left(\frac{1 - \sigma}{\sigma} \right)^2, \quad (\text{A4})$$

14 where v_p is the instantaneous piston speed and σ is the ratio of the valve free-flow area (including the
15 effects of *vena contractae*) to piston area. Strictly, Δp should be flow-averaged by integrating over the
16 valve open period but, in the spirit of engineering estimates, it is computed here on the basis of the piston
17 maximum velocity. Normalising by the local pressure then gives,

$$18 \quad f_p = \frac{\Delta p}{p} = \frac{\omega^2 s^2}{8RT} \left(\frac{1 - \sigma}{\sigma} \right)^2. \quad (\text{A5})$$

19 The fractional pressure losses for the valves computed from Eq. (A5) for the nominal design are
20 approximately 0.5% at exit from CE and inlet to EC (States 2 and 3 respectively in Fig. 1), 1% at inlet to
21 CE (State 1) and 1.4% at exit from EC (State 4).

22 23 *A3 Heat transfer losses in the compressors and expanders*

24 In theory, the time-mean heat leakage to or from the compressors and expanders can be reduced to very
25 small levels with sufficient insulation and so heat leakage factors have been arbitrarily set to 2% for
26 baseline calculations. However, even if the processes are globally adiabatic, an efficiency loss will still be
27 incurred due to time-varying irreversible heat transfer to and from the cylinder walls. To estimate the
28 magnitude of this loss, the irreversibility is divided into three parts as follows (estimates are made only for
29 compression and it is assumed that similar loss factor apply for expanders).

30
31 *(i) Heat transfer during induction and delivery.* The gas entering the compressor is preheated by the cylinder
32 walls prior to compression. Likewise, it is also cooled during the delivery stroke. The net effect is that heat is
33 transferred from the high exit temperature down to the low inlet temperature, as illustrated schematically in
34 Fig. 10. For simplicity it is assumed that the complete process (1 to 2 in the figure) is adiabatic and that the
35 compression (1' to 2') is isentropic. Writing the wall temperature as $T_w = T_1 + \theta(T_2 - T_1)$, where $0 < \theta < 1$,
36 the heat transferred to the gas during induction can be expressed as,

$$37 \quad Q = hS(T_w - T_1)\tau = hS\theta(T_2 - T_1)\tau, \quad (\text{A6})$$

38 where h is some average heat transfer coefficient, S is the average internal surface area and τ is the duration
39 of the induction stroke. This heat transfer increases the enthalpy of the induced mass according to,

$$Q = mc_p(T_1' - T_1) = \rho_1 v_p A c_p (T_1' - T_1) \tau, \quad (\text{A7})$$

where v_p is the average piston speed during induction and A is the piston face area. Equating these two expressions for Q gives,

$$T_1' - T_1 = St \theta \frac{S}{A} (T_2 - T_1) = T_2' - T_2, \quad (\text{A8})$$

where St is the Stanton number (based on the average piston speed) and the right hand equality stems from specifying that the overall process is adiabatic. By inspection of the T - s diagram of Fig. 10, and making use of Eq. (A8), the *isentropic* efficiency is simply,

$$\eta = \frac{T_2' / T_1' - 1}{T_2 / T_1 - 1} = 1 - f(\beta^{(\gamma-1)/\gamma} - 1) \quad \text{where} \quad f = St \theta \frac{S}{A}. \quad (\text{A9})$$

Note that f represents the heat transferred during induction as a fraction of the work transfer and this fraction is independent of the pressure ratio, as expected. The efficiency loss is larger at high pressure ratio, however, since the heat is then transferred across a higher temperature difference. The factor f is difficult to determine with any confidence, but a crude estimate may be obtained by setting $\theta = 1/2$ and approximating the Stanton number from turbulent pipe flow correlations. For the nominal design conditions given in Table 2, this gives $f=0.0025$, which translates to an efficiency loss of approximately 0.4% at a pressure ratio of 10:1.

(ii) *Heat transfer during the compression and expansion strokes.* Heat transfer also occurs during processes A-B and C-D of Fig. 9, but the use of a simple heat transfer coefficient is no longer appropriate in this case because of the interaction between heat and work transfers, and the inherently unsteady-state process that takes place during these processes. An excellent explanation of the underlying physics is given by Lawton [22], and a number of studies have attempted to quantify the effect in the context of gas springs. Early work by Lee [23] lead to the development of a simple analytical expression for the so-called hysteresis loss in gas springs. This has proved to fit experimental data to a reasonable extent, as reported by Kornhauser and Smith [24]. In recent work by Mathie *et al.* [21] an extended semi-analytical model was proposed for the full conjugate (solid-gas) thermal problem in gas-springs. The finite conductivity of the walls was shown to play a role, exacerbating losses in some cases. However, given the uncertainty associated with other loss parameters presented in this section, it suffices here to consider Lee's simpler approach. Lee's result is shown in Fig. 11, expressed as a decrement in polytropic efficiency by attributing half the hysteresis loss to the compression stroke, A-B. The horizontal axis in this figure is the Peclet number, $Pe = \omega D_h^2 / 2\alpha_t$, where D_h is the cylinder mean hydraulic diameter and α_t is the mean thermal diffusivity of the gas. Based on the dimensions and conditions listed in Tables 2 and 3, the Peclet number for the hot cylinder is 34 000, suggesting an efficiency loss of just 0.3 %. However, the thermal dissipation loss in a real compressor (as opposed to a gas spring) may be considerably larger because the eddying and turbulent motion generated by the inlet valve is likely to enhance the effective diffusivity. In this context, Lawton [22] found that good agreement between theory and experiment for heat transfer rates in a motored piston engine could be obtained by multiplying the gas conductivity by 25. This would have the effect of reducing the Peclet number to 1360 and thereby increasing the loss to 1.6%. It should be cautioned that other models (notably that presented in Ref. [21]) predict higher losses than this.

(iii) *Mixing loss.* Due to irreversibility and heat transfer during Process A→D, the residual gas may end up at a different temperature to that entering the cylinder, thereby giving rise to an additional mixing loss. With the small losses suggested by (i) and (ii) above, this mixing loss can be shown to be extremely small (less than one tenth of a percent), but it may be significant if there were heat losses to the surroundings.

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- 47

1 FIGURE CAPTIONS

2 **Figure 1:** Layout of PTES system and corresponding T - s diagram. Key: BV buffer vessel; HR/CR hot/cold reservoir;
3 CE/EC reversible compressor-expanders; HX1/HX3 heat exchangers. The T - s diagram shows the discharge cycle
4 operating at a lower pressure ratio, with heat rejection from both HX1 and HX3.

5 **Figure 2:** Typical temperature profiles in a cold reservoir for cyclic operation with a utilisation factor of $II=0.75$. The
6 profiles are shown at various stages through the cycle. Differences between the solid and chain lines highlight the
7 impact of the temperature-dependent solid heat capacity.

8 **Figure 3:** Sensitivity of thermodynamic round-trip efficiency to compressor and expander loss parameters.

9 **Figure 4:** Variation of roundtrip efficiency and energy density with operational parameters. Left: variation with T_1 , T_3
10 and charging pressure ratio, β_{chg} (T_1 and T_3 fixed). Right: variation with β_{chg} (T_2 and T_4 fixed), discharge pressure
11 ratio, β_{dis} , and utilisation factor II . For each curve the open and solid square symbols indicate the minimum and
12 maximum values of each parameter in accord with Table 4.

13 **Figure 5:** Variation of thermodynamic roundtrip efficiency with geometric parameters. Minimum, nominal and
14 maximum values of the parameters are given in Table 4.

15 **Figure 6:** Pareto fronts (trade-off surfaces) emerging from the optimisation.

16 **Figure 7:** ‘Parallax’ plots showing the combinations of design parameters for the ‘best’ designs, as defined by data
17 Points 1 to 4 in Fig. 6.

18 **Figure 8:** Comparison of loss distributions for the nominal design (but with $\eta=0.99$) and an optimised design (Point 3
19 in Fig. 6). Thermal losses refer to heat transfer irreversibility; heat leakage losses are due to heat exchange with the
20 environment above or below ambient temperature.

21 **Figure 9:** p - V diagram for an ideal reciprocating device. As shown the device is operating as a compressor; the cycle
22 would be reversed for an expander.

23 **Figure 10:** simplified model of the irreversibility associated with preheating during induction and cooling during
24 delivery, shown for a compression process. The overall Process 1-2 is assumed adiabatic.

25 **Figure 11:** Estimate of the hysteresis loss during the compression and expansion processes of Fig. 9, based on the
26 model of Lee [23].

27

28 TABLE CAPTIONS

29 **Table 1:** Comparison of maximum exergetic flows per unit mass and per unit volume of working fluid for various
30 technologies. (The dead state is taken as 20 °C and 1 bar.)

31 **Table 2:** Hot and cold reservoir details for a nominal 16 MWh PTES system. The storage material is Fe_3O_4 (density
32 5.175 tonne/m³) in the form of a packed bed with an assumed void fraction of 0.35

33 **Table 3:** Details of the compression-expansion devices for a nominal power of 2 MW. A clearance ratio ($V_{\text{min}}/V_{\text{max}}$) of
34 0.05 and a cylinder aspect ratio (stroke/diameter) of 0.25 and have been assumed for both devices.

35 **Table 4:** Nominal, minimum and maximum values of quantities varied for the parametric study. Note that the loss
36 factors are for each compressor/expander, CE and EC, with half the pressure loss assigned to each side of the device.

37 **Table 5:** Lower and upper bounds for parameters used in optimisation. Ambient temperature is $T_0=298$ K.

38

39

1 **TABLES**

2 **Table 1:** Comparison of maximum exergetic flows per unit mass and per unit volume of working fluid for various
3 technologies. (The dead state is taken as 20 °C and 1 bar.)

	CAES	PHS	PTES (Joule)	Rankine Cycle
Working fluid	air	water	argon	steam
Operating conditions	20 °C, 100 bar	500 m	500 °C, 10.5 bar	500 °C, 100 bar
Exergy per unit mass	390 kJ/kg	4.9 kJ/kg	250 kJ/kg	1400 kJ/kg
Exergy per unit volume	46 MJ/m ³	4.9 MJ/m ³	1.6 MJ/m ³	43 MJ/m ³

4
5 **Table 2:** Hot and cold reservoir details for a nominal 16 MWh PTES system. The storage material is Fe₃O₄ (density
6 5.175 tonne/m³) in the form of a packed bed with an assumed void fraction of 0.35.

	P (bar)	T (K)	ρ_g (kg m ⁻³)	M_g (kg)	\bar{c}_s (J kg ⁻¹ K ⁻¹)	M_s (tonne)	V (m ³)
HOT Chg	10.5 bar	778	6.5	162	860	238	71
	Dis.	10.5 bar	310	405			
COLD Chg.	1.05 bar	123	4.1	168	520	394	117
	Dis.	1.05 bar	310	67			

7
8 **Table 3:** Details of the compression-expansion devices for a nominal power of 2 MW. A clearance ratio (V_{\min}/V_{\max}) of
9 0.05 and a cylinder aspect ratio (stroke/diameter) of 0.25 and have been assumed for both devices.

	Speed (RPM)	V_s (total) (m ³)	N_{cyl}	D (m)	Stroke (m)	Clearance (mm)
Hot cylinders (CE)	1200	0.50	6	0.75	0.19	10
Cold cylinders (EC)	1200	0.20	6	0.55	0.14	7.4

10
11 **Table 4:** Nominal, minimum and maximum values of quantities varied for the parametric study. Note that the loss
12 factors are for each compressor/expander, CE and EC, with half the pressure loss assigned to each side of the device.

	Loss Factors			Operating Conditions					Geometric Parameters			
	f_p	$1-\eta$	α	T_1 (K)	T_3 (K)	β_{chg}	β_{dis}	Π	$(L/D)_{\text{CR}}$	$(L/D)_{\text{HR}}$	d_p^{CR} (cm)	d_p^{HR} (cm)
Nominal	0.02	0.02	0.02	310	310	10.0	10.0	0.75	1.00	1.00	2.0	2.0
Min	0.00	0.00	0.00	273	273	5.00	5.00	0.50	0.10	0.10	0.5	0.5
Max	0.04	0.04	0.04	347	347	15.0	15.0	1.00	1.90	10.0	3.5	3.5

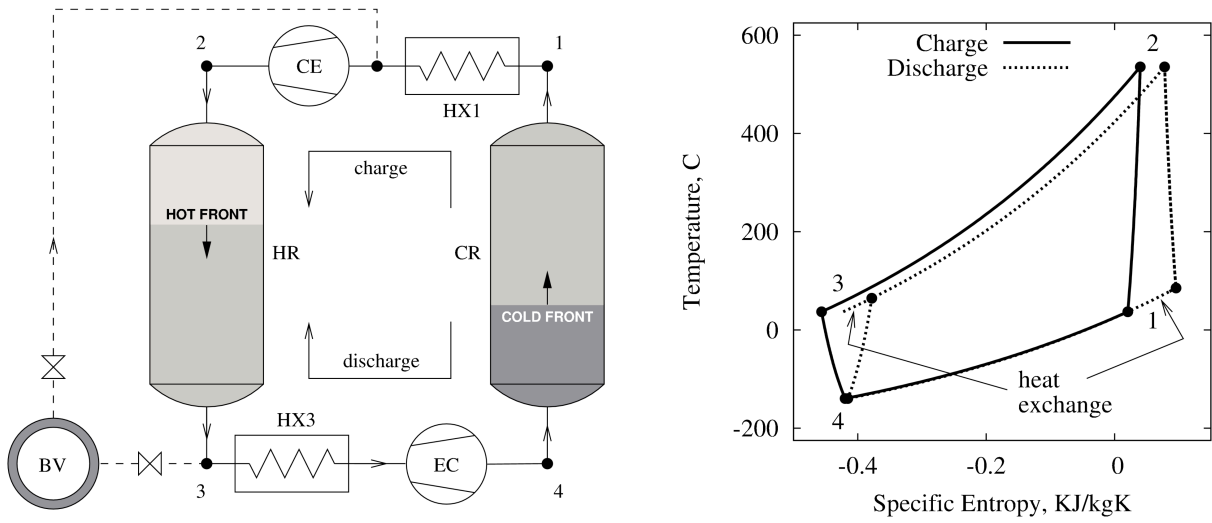
13
14 **Table 5:** Lower and upper bounds for parameters used in optimisation. Ambient temperature is $T_0=298$ K.

	L/D	d_p (cm)	Π	β	T_1 (K)	T_2 (K)	T_3 (K)	T_4 (K)
Lower bound	0.10	0.50	0.10	2.00	T_0+10	T_3+50	T_0+10	103
Upper bound	10.0	10.0	0.99	20.0	773	873	773	T_1-50

15

1 **FIGURES**

2



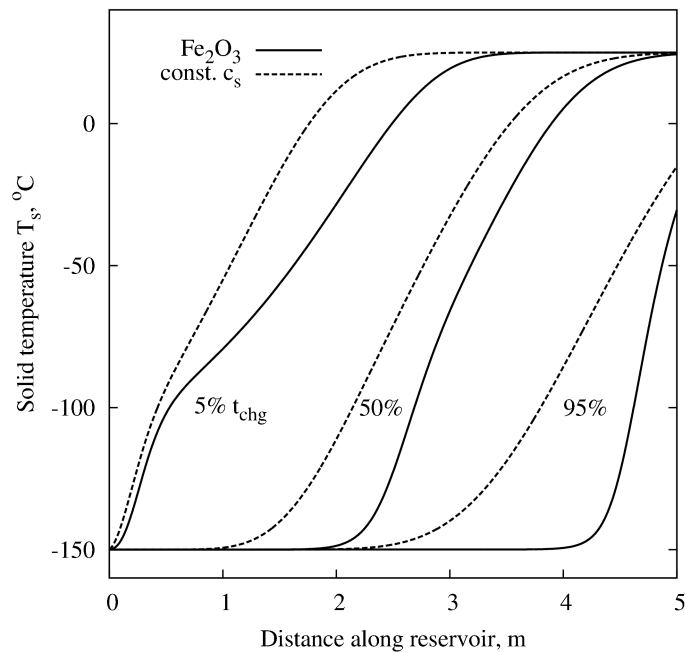
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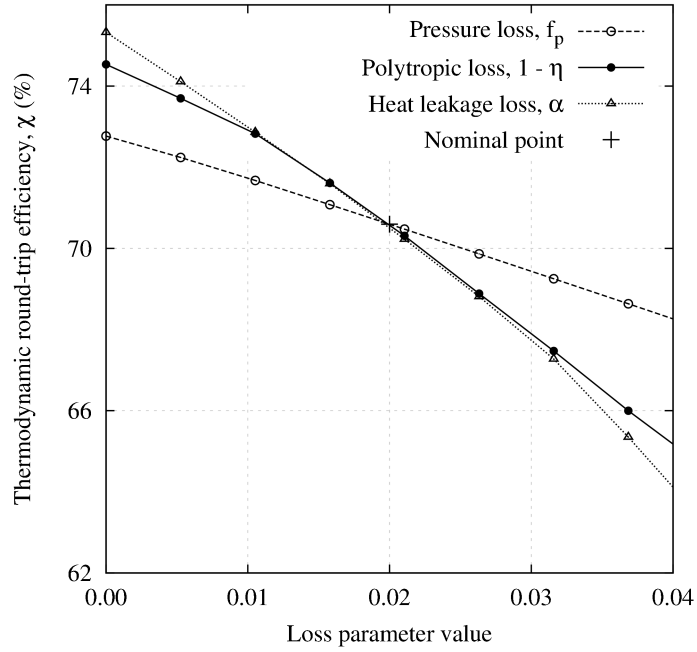


Figure 3: Sensitivity of thermodynamic round-trip efficiency to compressor and expander loss parameters.

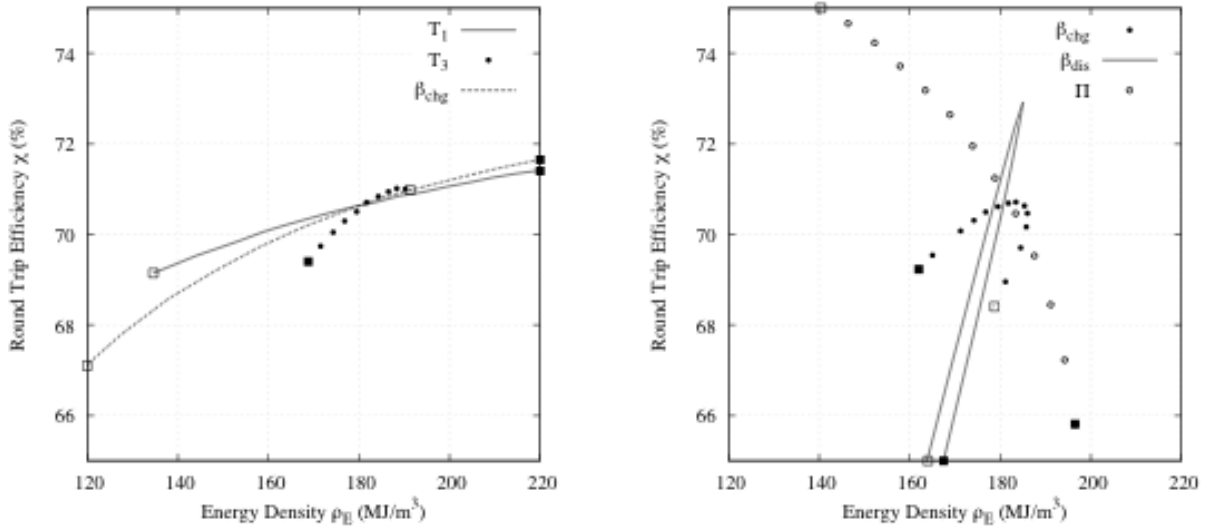
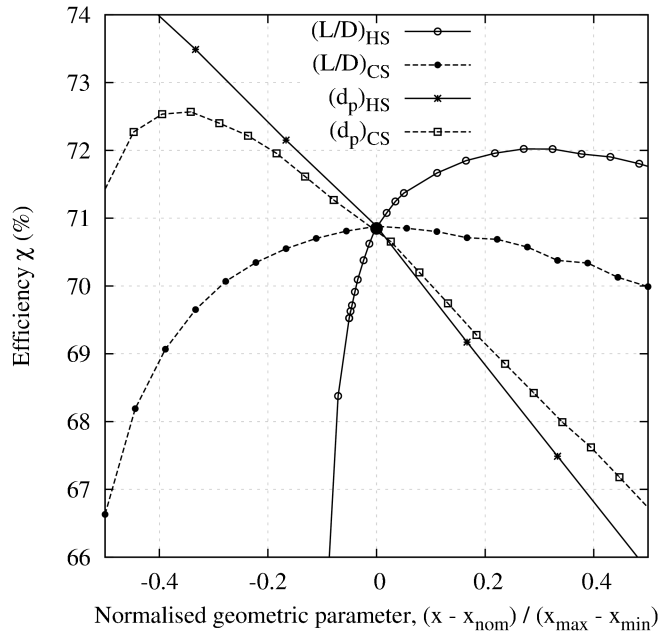
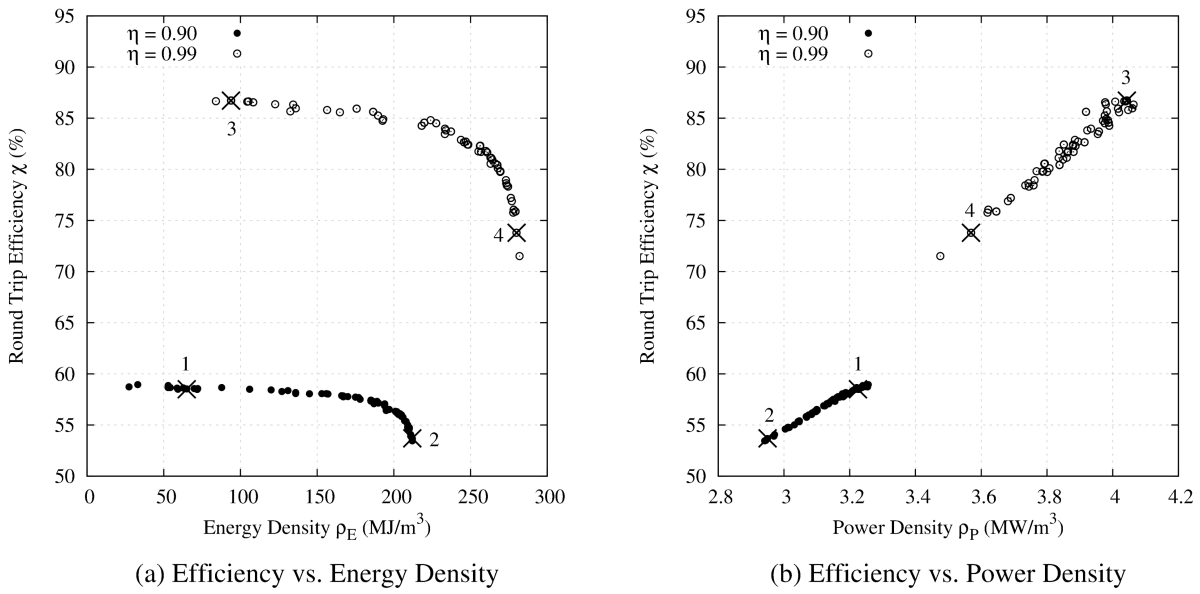


Figure 4: Variation of roundtrip efficiency and energy density with operational parameters. Left: variation with T_1 , T_3 and charging pressure ratio, β_{chg} (T_1 and T_3 fixed). Right: variation with β_{chg} (T_2 and T_4 fixed), discharge pressure ratio, β_{dis} , and utilisation factor Π . For each curve the open and solid square symbols indicate the minimum and maximum values of each parameter in accord with Table 4.



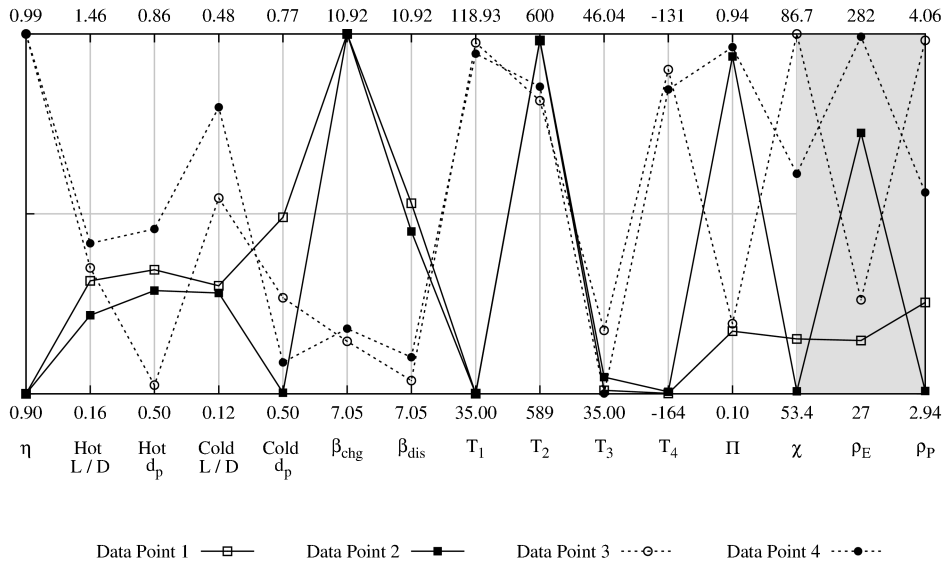
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Figure 5: Variation of thermodynamic roundtrip efficiency with geometric parameters. Minimum, nominal and maximum values of the parameters are given in Table 4.



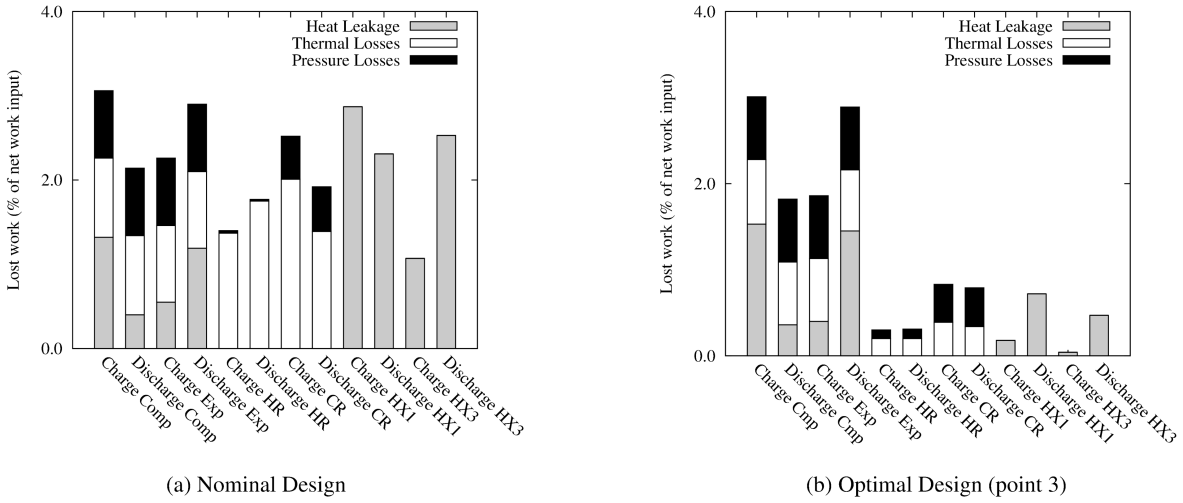
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Figure 6: Pareto fronts (trade-off surfaces) emerging from the optimisation.



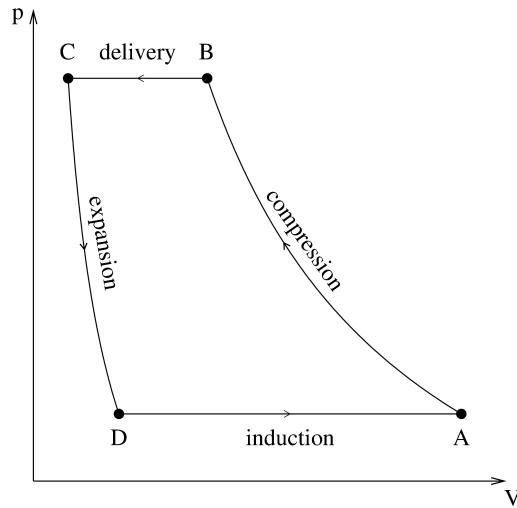
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Figure 7: ‘Parallax’ plots showing the combinations of design parameters for the ‘best’ designs, as defined by data Points 1 to 4 in Fig. 6.



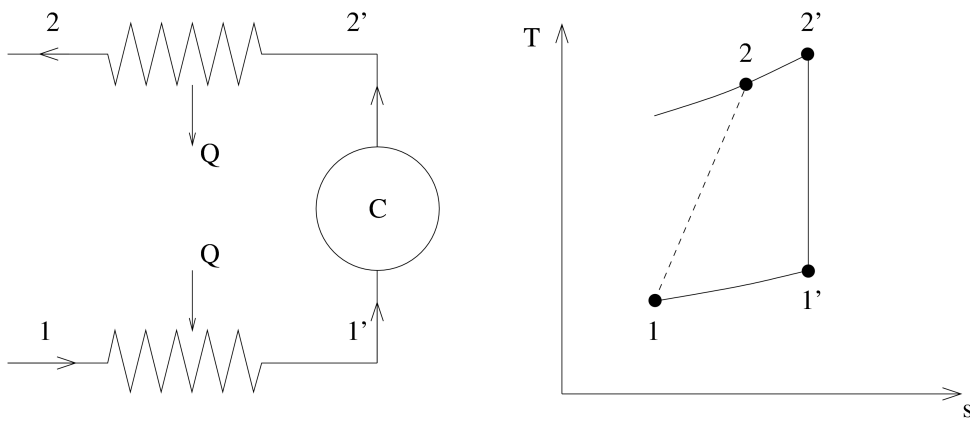
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Figure 8: Comparison of loss distributions for the nominal design (but with $\eta=0.99$) and an optimised design (Point 3 in Fig. 6). Thermal losses refer to heat transfer irreversibility; heat leakage losses are due to heat exchange with the environment above or below ambient temperature.



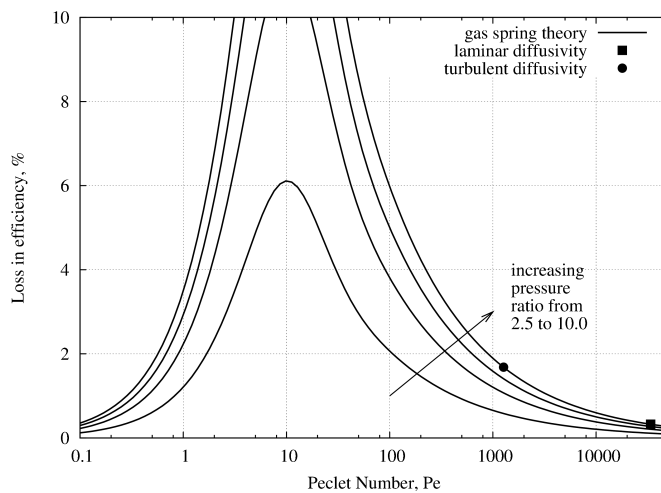
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Figure 9: p - V diagram for an ideal reciprocating device. As shown the device is operating as a compressor; the cycle would be reversed for an expander.



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Figure 10: Simplified model of the irreversibility associated with preheating during induction and cooling during delivery, shown for a compression process. The overall Process 1-2 is assumed adiabatic.



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Figure 11: Estimate of the hysteresis loss during the compression and expansion processes of Fig. 9, based on the model of Lee [23].