

Comparative beach surveys using an unmanned aerial system, ground-based GPS, terrestrial laser scanning, and airborne laser scanning

AIMS OF THE RESEARCH PROJECT

- To compare accuracy of UAV-based surface modelling to terrestrial laser scanning and airborne laser scanning
- To test the potential of unmanned aerial systems for monitoring highly variable mixed sand and gravel beaches
- To evaluate the extent to which surface sediment characteristics affect measurement accuracy of TLS, ALS and UAV-based surface monitoring

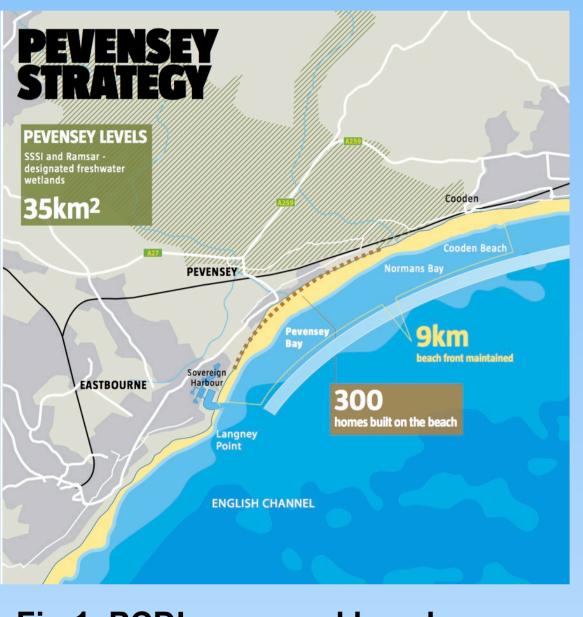




Fig 1. PCDL managed beach

Fig 2. Location of Pevensey Coastal Defence Ltd

PEVENSEY COASTAL DEFENCE LTD

- PCDL is the first UK public-private partnership flood defence project
- contracted to manage 9 km stretch of coastline from 2000 to 2025
- protect against breach from 1:400 storm
- core requirements: 2 million m³ of sediment distributed over 9 km frontage, minimum crest width 22m
- beach protects 50 km² against flood
- recharge from offshore, recycling sediment, winter reprofiling
- monthly GPS surveys since 2003
- composite mixed beach: reflective mixed sand and gravel upper beach, fine sand lower beach

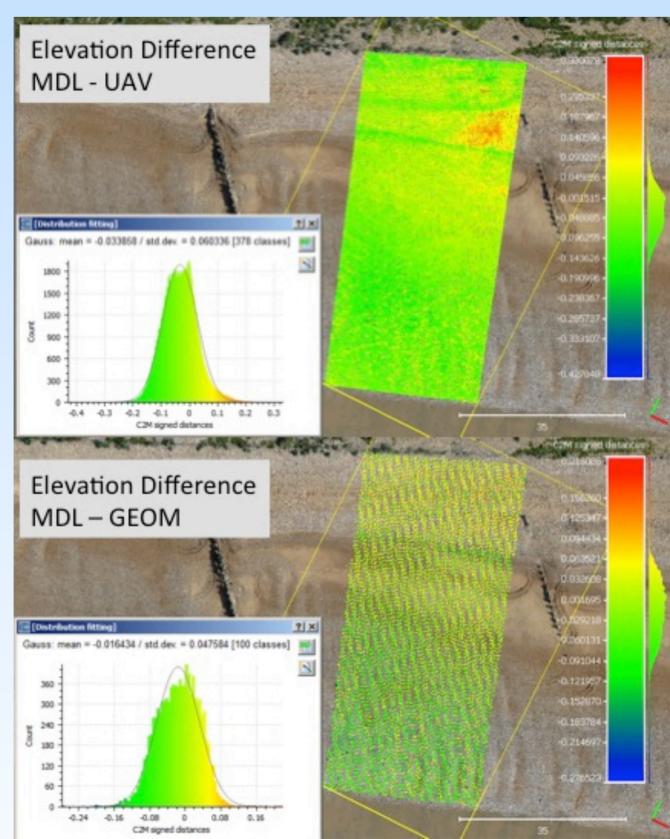
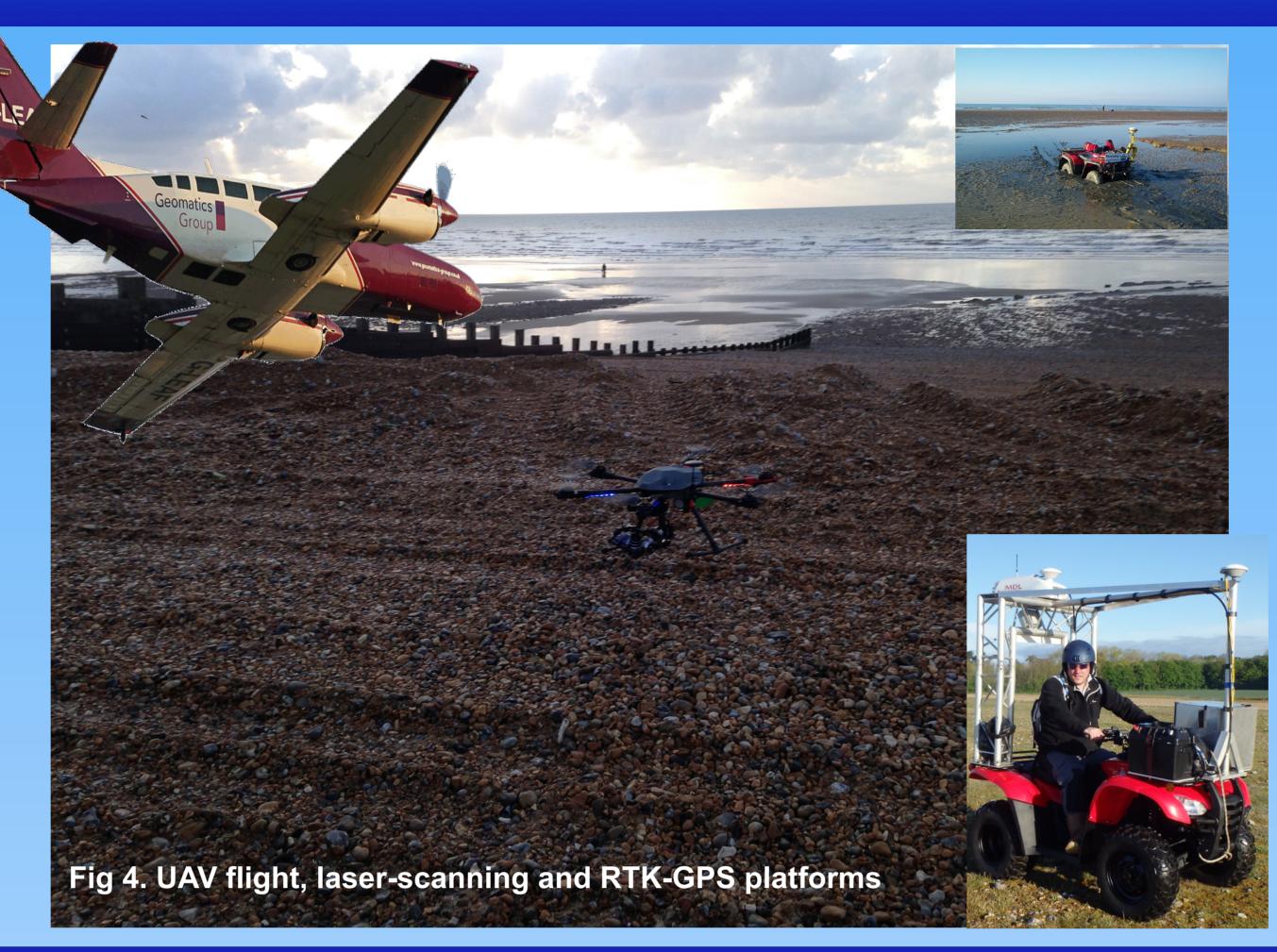


Fig 3. Elevation differences on dry beach UAV, GEOM(ALS), MDL(TLS)

Paul Elsner¹, Diane Horn¹, Uwe Dornbusch², Ian Thomas³, Dan Amos⁴, James Bovington⁴ Birkbeck College London¹, Environment Agency², Pevensey Coastal Defence Ltd³, Strategic Regional Coastal Monitoring Programme⁴





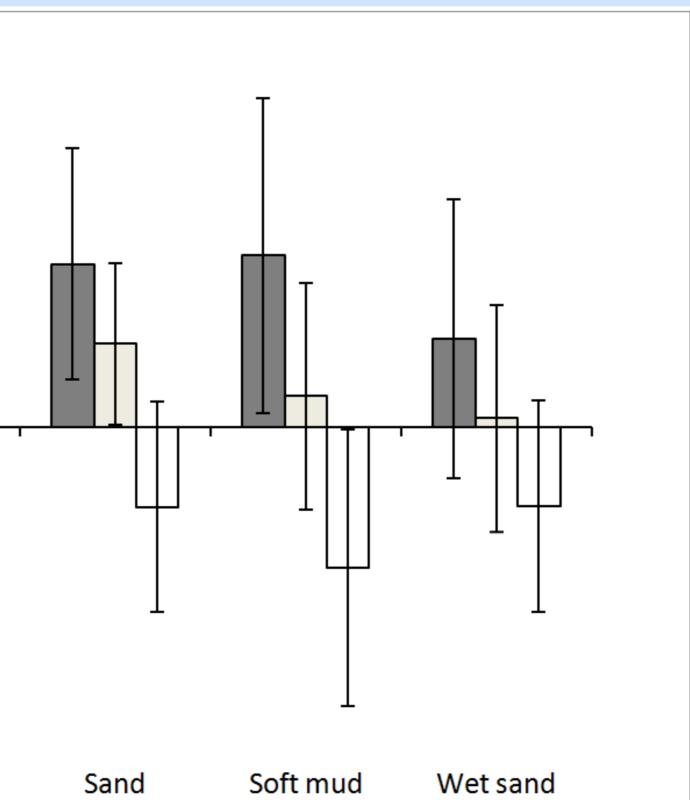
DATA COLLECTION AND ANALYSIS

- UAV flying height 60 m above ground
- simultaneous measurements using UAV-based photogrammetry, RTK-GPS, quad-based TLS and ALS
- Complemented by RTK-GPS line transects
- point-cloud inter-comparison
- data
 - 0.25 UAV-TLS UAV-ALS TLS-ALS 0.15 0.1 0.05 -0.05 -0.1 -0.15
- evaluation of differences between elevation models generated based on point clouds

Fig 5. : Mean differences and RMS (bars) between point clouds depending on surface type

-0.2

comparison of point-cloud performance against RTK transect



- (RMS 10 cm) compared to TLS
- (RMS 8 cm) compared to ALS
- worst for soft mud surfaces

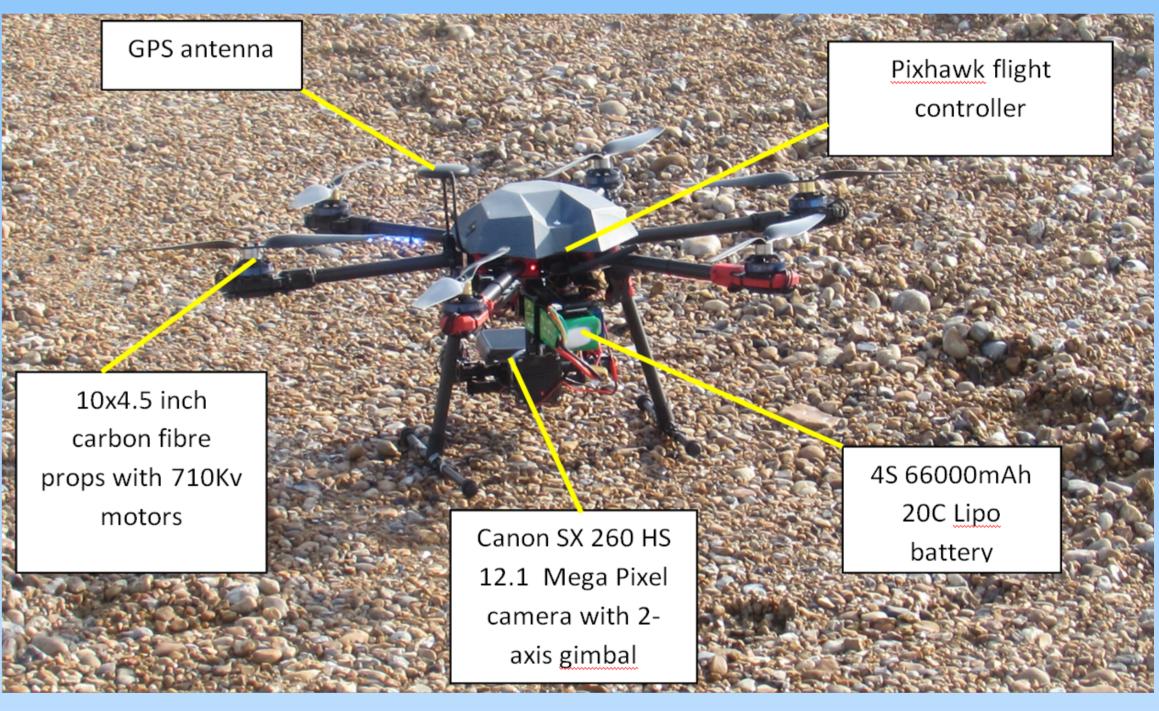


Fig 6. UAV set-up



- associated sediment fluxes
- limitations

Please take reprints below or get a pdf from d.horn@bbk.ac.uk

RESULTS

• UAV-based point cloud had positive offsets of 9 cm

X<mark>-</mark>X

• UAV-based point cloud had positive offsets of 6 cm

Significant performance differences between surface types, with best results for gravel and dry sand and

UAV and ALS data overall showed better agreement than UAV to TLS for nearly all surface types

CONCLUSIONS

• UAV appeared to systematically overestimate surface heights compared to laser scanning approaches but RMS is very similar

Needs to be considered when comparing UAV data with laser-scanning-based elevations

Overall UAV approaches show to be a robust method to detect \geq dm level elevation changes

Promising approach to deploy UAV for surveys in high temporal resolution to monitor short-term elevation changes and to spatially resolve

Flight regulations and sensitivity to wind / weather conditions represent significant operational