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Zacharias Psaradakis Birkbeck, University of London

Marián Vávra National Bank of Slovakia

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Zacharias Psaradakis

Department of Economics, Mathematics and Statistics Birkbeck, University of London E-mail: z.psaradakis@bbk.ac.uk

Marián Vávra

Advisor to the Governor and Research Department National Bank of Slovakia E-mail: marian.vavra@nbs.sk

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Abstract

This paper considers a distance test for normality of the one-dimensional marginal distribution of stationary fractionally integrated processes. The test is implemented by using an autoregressive sieve bootstrap approximation to the null sampling distribution of the test statistic. The bootstrap-based test does not require knowledge of either the dependence parameter of the data or of the appropriate norming factor for the test statistic. The small-sample properties of the test are examined by means of Monte Carlo experiments. An application to real-world data is also presented.

Key Words: Distance test; Fractionally integrated process; Sieve bootstrap; Normality.

JEL Classification: C12; C22.

1 Introduction

Testing whether a sample of observations comes from a Gaussian distribution is a problem that has attracted a great deal of attention over the years. This is not perhaps surprising in view of the fact that normality is a common maintained assumption in a wide variety of statistical procedures, including estimation, inference and forecasting procedures. In model building, a test for normality is often a useful diagnostic for assessing whether a particular type of stochastic model may provide an appropriate characterization of the data (for instance, non-linear models are unlikely to be an adequate approximation to a time series having a Gaussian one-dimensional marginal distribution). Normality tests may also be useful in evaluating the validity of different hypotheses and models to the extent that the latter rely on or imply Gaussianity, as is the case, for example, with some option pricing, asset pricing, and dynamic stochastic general equilibrium models found in the economics and finance literature.¹

Although most of the voluminous literature on the subject of testing for univariate normality has focused on the case of independent, identically distributed (i.i.d.) observations (see Thode (2002) for an extensive review), a small number of tests which are valid for dependent data have also been considered. These include tests based on the bispectrum (e.g., Hinich (1982); Nusrat and Harvill (2008); Berg, Paparoditis, and Politis (2010)), the characteristic function (Epps (1987)), moment conditions implied by Stein's characterization of the Gaussian distribution (Bontemps and Meddahi (2005)), and classical measures of skewness and kurtosis involving standardized third and fourth central moments (Lobato and Velasco (2004); Bai and Ng (2005)). A feature shared by these tests is that they all rely on asymptotic results obtained under dependence conditions which typically require the autocovariances of the data to decay towards zero, as the lag parameter goes to infinity, sufficiently fast to be (at least) absolutely summable. It has long been recognized, however, that such short-range dependence conditions may

¹Kilian and Demiroglu (2000) and Bontemps and Meddahi (2005) give examples from economics, finance and econometrics where testing for normality is of interest.

not accord well with the slowly decaying autocovariances of many observed time series.

The purpose of this paper is to discuss a test for normality which may be used in the presence of not only short-range dependence but also long-range dependence and antipersistence. The defining characteristic of stochastic processes with such dependence structures is that their autocovariances decay to zero as a power of the lag parameter and, in the case of long-range dependence, slowly enough to be non-summable. Models that allow for long-range dependence have been found to be useful for modelling data occurring in fields as diverse as economics, geophysics, hydrology, meteorology, and telecommunications.²

The normality test we consider here is based on the Anderson–Darling distance statistic involving the weighted quadratic distance of the empirical distribution function of the data from a Gaussian distribution function (Anderson and Darling (1952)). Unlike tests based on measures of skewness and kurtosis, which can only detect deviations from normality that are reflected in the values of such measures, normality tests based on the empirical distribution function are known to be consistent against any fixed non-Gaussian alternative. The Anderson–Darling test also fares well in smallsample power comparisons for i.i.d. data relatively to the popular correlation test of Shapiro and Wilk (1965) and the moment-based tests of Bowman and Shenton (1975) and Jarque and Bera (1987) (see, e.g., Stephens (1974) and Thode (2002, Ch. 7)). Furthermore, the Anderson–Darling test is superior, in terms of asymptotic relative efficiency, to distance tests such as those based on the (unweighted) Cramér–von Mises and Kolmogorov–Smirnov statistics (Koziol (1986); Arcones (2006)).

Our analysis extends earlier work by considering the case of correlated data from (strictly stationary) fractionally integrated processes, which may be short-range dependent, long-range dependent or antipersistent depending on the value of their dependence parameter. Unfortunately, however, inference based on conventional large-sample approximations is anything but straightforward in such a setting because the weak limit

 $^{^{2}}$ A summary of some of the empirical evidence on long-range dependence can be found in the collection of papers in Doukhan, Oppenheim, and Taqqu (2003).

of the null distribution of the test statistic, as well as the appropriate norming factor, depend on the unknown dependence parameter of the data and on the particular estimators of location and scale parameters that are used in the construction of the test statistic.

As a practical way of overcoming these difficulties, we propose to use the bootstrap to estimate the null sampling distribution of the Anderson–Darling distance statistic and thus obtain estimates of *P*-values and/or critical values for a normality test. Our approach relies on the autoregressive sieve bootstrap, which is based on the idea of approximating the data-generating mechanism by an autoregressive sieve, that is a sequence of autoregressive models that increase in order as the sample size increases without bound (Kreiss (1992); Bühlmann (1997)). The bootstrap-based normality test is easy to implement and requires knowledge (or estimation) of neither the value of the dependence parameter of the data nor of the appropriate norming factor for the test statistic. Furthermore, the bootstrap scheme is the same under short-range dependence, long-range dependence and antipersistence.

We note that Beran and Ghosh (1991) and Boutahar (2010) obtained some results relating to the asymptotic behaviour of moment-based and distance-based statistics under long-range dependence, but they did not discuss how operational tests for normality might be constructed. To the best of our knowledge, the problem of developing an operational normality test which is valid for data that are neither independent nor short-range dependent has not been tackled in the existing literature.

The plan of the paper is as follows. Section 2 formulates the problem and introduces the test statistic and the class of stochastic processes of interest. Section 3 discusses the autoregressive sieve bootstrap approach to implementing the distance test of normality. Section 4 examines the finite-sample properties of the proposed test by means of Monte Carlo experiments. Section 5 presents an application to a set of US economic and financial time series. Section 6 summarizes and concludes.

2 Assumptions and Test Statistic

Suppose $\mathbf{X}_n := \{X_1, X_2, \dots, X_n\}$ are consecutive observations from a strictly stationary stochastic process $\mathbf{X} := \{X_t\}_{t \in \mathbb{Z}}$ satisfying

$$X_t - \mu = \sum_{j=0}^{\infty} \psi_j \varepsilon_{t-j}, \qquad t \in \mathbb{Z},$$
(1)

for some $\mu \in \mathbb{R}$, where $\{\psi_j\}_{j\geq 0}$ is a square-summable sequence of real numbers (with $\psi_0 = 1$) and $\{\varepsilon_t\}_{t\in\mathbb{Z}}$ is a sequence of i.i.d., real-valued, zero-mean random variables with variance $\sigma^2 \in (0, \infty)$. The objective is to test the hypothesis that the one-dimensional marginal distribution of **X** is Gaussian, that is

$$F(\mu + \gamma_0^{1/2} x) - \Phi(x) = 0 \quad \text{for all } x \in \mathbb{R},$$
(2)

where $\gamma_k := \operatorname{Cov}(X_k, X_0) = \sigma^2 \sum_{j=0}^{\infty} \psi_{j+|k|} \psi_j$ for $k \in \mathbb{Z}$, F is the distribution function of X_0 , and Φ denotes the standard-normal distribution function. Note that Gaussianity of the distribution of ε_0 is sufficient for (2) to hold.

To allow for different types of dependence, it will be maintained throughout that the transfer function $\psi(z) := \sum_{j=0}^{\infty} \psi_j z^j$, $z \in \mathbb{C}$, associated with (1) satisfies

$$\psi(z) = (1-z)^{-d} \pi(z), \qquad |z| < 1,$$
(3)

for some real $|d| < \frac{1}{2}$, where $\pi(z) := \sum_{j=0}^{\infty} \pi_j z^j$ and $\{\pi_j\}_{j\geq 0}$ is an absolutely summable sequence of real numbers such that $\pi(0) = 1$ and $\pi(1) \neq 0$. Under (1) and (3), **X** is a fractionally integrated process with dependence (memory/fractional differencing) parameter d. Using the Maclaurin series expansion

$$(1-z)^{-d} = \sum_{j=0}^{\infty} \frac{\Gamma(j+d)}{\Gamma(d)\Gamma(j+1)} z^j, \qquad |z| < 1, \ d \neq 0,$$

where Γ denotes the gamma function, it is not difficult to see that, for $d \neq 0$,

$$\psi_j = \sum_{h=0}^j \frac{\pi_{j-h} \Gamma(h+d)}{\Gamma(d) \Gamma(h+1)}, \qquad j \ge 1,$$

and so $\psi_j \sim {\pi(1)/\Gamma(d)} j^{d-1}$ as $j \to \infty$ (the tilde signifies that the limiting value of the ratio of two terms is 1). Hence, since $\gamma_k \sim C |k|^{2d-1}$ as $|k| \to \infty$ for $d \neq 0$ and some $C \neq 0$, the series $\sum_{k=-\infty}^{\infty} \gamma_k$ diverges for $0 < d < \frac{1}{2}$ and **X** is long-range dependent; if $-\frac{1}{2} < d < 0$, then $\sum_{k=-\infty}^{\infty} \gamma_k = 0$ and **X** is antipersistent. Short-range dependence corresponds to d = 0, with $\sum_{k=-\infty}^{\infty} \gamma_k = {\sigma\pi(1)}^2$. The class of stochastic processes defined by (1) and (3) is rich enough to include a wide range of processes with slowly decaying autocovariances. A prominent example are causal autoregressive fractionally integrated moving average (ARFIMA) processes with $\pi(z) = \vartheta(z)/\varphi(z)$, $\vartheta(z)$ and $\varphi(z)$ being relatively prime polynomials of finite order with $\varphi(z) \neq 0$ for $|z| \leq 1$ (see, e.g., Palma (2007, Sect. 3.2)).

The test for the hypothesis in (2) considered here is based on the Anderson– Darling distance statistic

$$\mathcal{A} := \int_{-\infty}^{\infty} \frac{\{\hat{F}(\bar{X} + \hat{\gamma}_0^{1/2} x) - \Phi(x)\}^2}{\Phi(x)\{1 - \Phi(x)\}} \,\mathrm{d}\Phi(x),\tag{4}$$

where $\hat{F}(x) := n^{-1} \sum_{t=1}^{n} \mathbb{I}(X_t \leq x), x \in \mathbb{R}$, is the empirical distribution function of \mathbf{X}_n , $\bar{X} := n^{-1} \sum_{t=1}^{n} X_t, \, \hat{\gamma}_k := n^{-1} \sum_{t=1}^{n-|k|} (X_{t+|k|} - \bar{X})(X_t - \bar{X})$ for $|k| \leq n-1$, and \mathbb{I} denotes the indicator function. Note that \mathcal{A} may equivalently be expressed as

$$\mathcal{A} = -1 - n^{-2} \sum_{t=1}^{n} (2t - 1) \left[\log \Phi(Y_t) + \log\{1 - \Phi(Y_{n-t+1})\} \right],$$
(5)

where $Y_t := \hat{\gamma}_0^{-1/2} (X_{n:t} - \bar{X})$ and $X_{n:t}$ is the *t*-th order statistic from \mathbf{X}_n .

As is well known, the asymptotic null distribution of distance statistics such as \mathcal{A} is closely related to the weak limit, as n tends to infinity, of (a suitably normalized version of) the random function $\hat{K}(x) := \hat{F}(x) - \Phi(\hat{\gamma}_0^{-1/2}(x - \bar{X})), x \in \mathbb{R}$ (see, e.g., Shorack and Wellner (1986, Ch. 5) for the case of i.i.d. data). However, unless one is dealing with the classical problem of testing a simple null hypothesis (μ and γ_0 known) for i.i.d. data, inference is complicated by the presence of both estimated parameters in \hat{K} and dependence in \mathbf{X} . To complicate matters further in our setup, the norming factor needed in order to obtain weak convergence of \hat{K} , and hence of the distribution of \mathcal{A} , as well as the weak limits themselves, depend on the value of the dependence parameter d and on the estimators of μ and γ_0 used in the construction of \hat{K} (see Beran and Ghosh (1991); Ho (2002); Kulik (2009)). For example, when ε_0 is normally distributed, the random function $K(x) := \hat{F}(x) - \Phi(\gamma_0^{-1/2}(x-\mu)), x \in \mathbb{R}$, converges weakly to a non-degenerate Gaussian process at the usual \sqrt{n} rate for d = 0 (Doukhan and Surgailis (1998)) and to a semi-deterministic Gaussian process at the slower rate $n^{(1-2d)/2}$ for $0 < d < \frac{1}{2}$ (cf. Dehling and Taqqu (1989); Giraitis and Surgailis (1999)). Replacing μ and γ_0 by estimates improves the rate of convergence under long-range dependence, with \hat{K} converging at rate \sqrt{n} for $0 \leq d < \frac{1}{3}$ (cf. Beran and Ghosh (1991)). The dependence of the appropriate norming factors and asymptotic distributions on the unknown value of the dependence parameter, combined with the complicated covariance structure of the relevant limiting processes, clearly make inference based on conventional large-sample asymptotics for \mathcal{A} extremely cumbersome.³

As a practical way of circumventing the problems mentioned above, we propose to use an autoregressive sieve bootstrap procedure to obtain P-values and/or critical values for the normality test based on \mathcal{A} . The principal advantage of the sieve bootstrap is that it can used to approximate the sampling properties of \mathcal{A} without knowledge or estimation of the dependence parameter and is valid for all $|d| < \frac{1}{2}$. Moreover, because bootstrap approximations are constructed from replicates of \mathcal{A} , there is no need to derive analytically, nor to make assumptions about, the appropriate norming factor for \mathcal{A} or its asymptotic null distribution.

3 Autoregressive Sieve Bootstrap Approximation

The autoregressive sieve bootstrap is motivated by the observation that, under (1), (3) and the additional assumption that $\pi(z) \neq 0$ for $|z| \leq 1$, **X** admits the representation

$$\sum_{j=0}^{\infty} \phi_j (X_{t-j} - \mu) = \varepsilon_t, \qquad t \in \mathbb{Z},$$
(6)

 $^{^{3}}$ It is worth remarking that similar difficulties also arise in the case of moment-based skewness and kurtosis statistics (cf. Boutahar (2010); Ho (2002)).

for a square-summable sequence of real numbers $\{\phi_j\}_{j\geq 0}$ (with $\phi_0 = 1$) such that $\phi(z) := \sum_{j=0}^{\infty} \phi_j z^j = (1-z)^d / \pi(z)$ for |z| < 1 (with $\phi_j \sim \{\pi(1)\Gamma(-d)\}^{-1}j^{-d-1}$ as $j \to \infty$ when $d \neq 0$). The idea is to approximate (6) by a finite-order autoregressive model and use this as the basis of a semi-parametric bootstrap scheme. If the order of the autoregressive approximation is allowed to increase simultaneously with n at an appropriate rate, the distribution of the process in (6) will be matched asymptotically (cf. Kreiss (1992); Bühlmann (1997); Kapetanios and Psaradakis (2006); Poskitt (2008)).

It is important to point out that, as discussed in Poskitt (2007), the autoregressive representation (6) provides a meaningful approximation even if $\pi(z)$ has zeros in the disk |z| < 1. In this case, the transfer function $\phi(z)$ associated with (6) may be viewed as arising, not from the inversion of $\psi(z)$, but as the limit of $\sum_{j=0}^{p} \phi_{pj} z^{j}$ ($\phi_{p0} := 1$) as $p \to \infty$, where, for any integer $p \ge 1$, $(-\phi_{p1}, \ldots, -\phi_{pp})$ are the coefficients of the best (in the mean-square sense) linear predictor of X_t based on $(X_{t-1}, \ldots, X_{t-p})$. Since $\gamma_0 > 0$ and $\gamma_k \to 0$ as $|k| \to \infty$ under (1) and (3), $(\phi_{p1}, \ldots, \phi_{pp})$ are uniquely determined as the solution of the set of equations $\sum_{j=0}^{p} \phi_{pj} \gamma_{k-j} = 0$ ($k = 1, \ldots, p$) (Brockwell and Davis (1991, Corollary 5.1.1)), and are such that $\sum_{j=0}^{p} \phi_{pj} z^{j} \neq 0$ for $|z| \le 1$ and $\operatorname{Var}[\sum_{j=0}^{p} \phi_{pj}(X_{t-j} - \mu)] \to \sigma^2$ as $p \to \infty$.

The bootstrap procedure used to approximate the sampling properties of the statistic \mathcal{A} under the normality hypothesis is as follows. For a positive integer p (chosen as a function of n so that $p^{-1} + n^{-1}p \to 0$ as $n \to \infty$), let $(\hat{\phi}_{p1}, \ldots, \hat{\phi}_{pp})$ and $\hat{\sigma}_p$ be estimators (based on \mathbf{X}_n) of the coefficients and the noise standard deviation, respectively, of an autoregressive model of order p for $X_t - \bar{X}$. Bootstrap replicates $\mathbf{X}^* := \{X_t^*\}_{t \in \mathbb{Z}}$ of \mathbf{X} are then defined via the recursion

$$\sum_{j=0}^{p} \hat{\phi}_{pj}(X_{t-j}^{*} - \bar{X}) = \hat{\sigma}_{p}\varepsilon_{t}^{*}, \qquad t \in \mathbb{Z},$$
(7)

where $\hat{\phi}_{p0} := 1$ and $\{\varepsilon_t^*\}_{t\in\mathbb{Z}}$ are i.i.d. standard-normal random variables (independent of \mathbf{X}_n). Finally, the bootstrap analogue \mathcal{A}^* of \mathcal{A} is defined as in (4) but with $\mathbf{X}_n^* := \{X_1^*, X_2^*, \dots, X_n^*\}$ replacing \mathbf{X}_n . The conditional distribution of \mathcal{A}^* , given \mathbf{X}_n , constitutes the sieve bootstrap approximation to the null sampling distribution of \mathcal{A} .

It is worth noting that, by requiring ε_t^* in (7) to be Gaussian, \mathbf{X}^* is constructed in a way which reflects the normality hypothesis under test even though \mathbf{X} may not satisfy (2). This is important for ensuring that the bootstrap test has reasonable power against departures from normality (cf. Hall and Wilson (1991); Lehmann and Romano (2005, Sect. 15.6)). The estimator $(\hat{\phi}_{p1}, \ldots, \hat{\phi}_{pp}, \hat{\sigma}_p)$ used in (7) to define \mathbf{X}^* may be the Yule–Walker estimator satisfying the equations $\sum_{j=0}^{p} \hat{\phi}_{pj} \hat{\gamma}_{k-j} = \delta_{0,k} \hat{\sigma}_p^2$ ($k = 0, 1, \ldots, p$), where $\delta_{0,k}$ is Kronecker's delta, or any other asymptotically equivalent estimator (e.g., the least-squares estimator).

Recalling that \mathcal{A} may be expressed as in (5), strong consistency of the sieve bootstrap estimator of the null sampling distribution of \mathcal{A} follows from Lemma 1, Theorem 2 and Remark 2 of Poskitt (2008) under a suitable assumption about the rate of increase of p. More specifically, let $\rho(H, H^*) := \{\int_0^1 |H^{-1}(u) - H^{*-1}(u)|^2 du\}^{1/2}$ stand for the Mallows–Wasserstein distance between the distribution function H of \mathcal{A} and the conditional distribution function H^* of \mathcal{A}^* given \mathbf{X}_n (with $G^{-1}(u) := \inf\{x : G(x) \ge u\}$, 0 < u < 1, for a distribution function G). Then, if \mathbf{X} satisfies (1) and (3), the distribution of ε_0 is Gaussian, and $p \to \infty$ and $(\log n)^{-\nu}p = O(1)$ as $n \to \infty$ for some $\nu \ge 1$, we have $\rho(H, H^*) \to 0$ with probability 1 as $n \to \infty$.⁴

The bootstrap estimator of the P-value for a test that rejects for large values of \mathcal{A} is $P_{\mathcal{A}}^* := 1 - H^*(\mathcal{A})$, and so normality is rejected at a given level of significance $\alpha \in (0, 1)$ if $P_{\mathcal{A}}^* \leq \alpha$. Since convergence with respect to ρ implies weak convergence (Bickel and Freedman (1981, Lemma 8.3)), the bootstrap P-value $P_{\mathcal{A}}^*$ is asymptotically equivalent to the P-value based on the null sampling distribution of \mathcal{A} under the conditions stated above. While H^* is unknown, an approximation (of any desired accuracy) can be obtained by Monte Carlo simulation. Specifically, if $(\mathcal{A}_1^*, \ldots, \mathcal{A}_m^*)$ are copies of \mathcal{A}^* , obtained from m independent bootstrap pseudo-samples \mathbf{X}_n^* from (7), then the empirical

⁴Poskitt (2008) considers a bootstrap scheme in which ε_t^* in (7) is drawn from the empirical distribution of the residuals $\hat{\varepsilon}_t := \sum_{j=0}^p \hat{\phi}_{pj}(X_{t-j} - \bar{X})$ (t = p + 1, ..., n), standardized to have mean 0 and variance 1. However, it is not difficult to see that the arguments in the proof of his Theorem 2 go through with little or no change when ε_t and ε_t^* are Gaussian.

distribution function of $(\mathcal{A}_{1}^{*}, \ldots, \mathcal{A}_{m}^{*})$ provides an approximation to H^{*} . Hence, $P_{\mathcal{A}}^{*}$ may be approximated by $\hat{P}_{\mathcal{A}}^{*} := m^{-1} \sum_{i=1}^{m} \mathbb{I}(\mathcal{A}_{i}^{*} > \mathcal{A})$, so that $\hat{P}_{\mathcal{A}}^{*} \to P_{\mathcal{A}}^{*}$ with probability 1 as $m \to \infty$. A bootstrap critical value of nominal level α for \mathcal{A} is given by $H^{*-1}(1-\alpha)$, which may be approximated by $\inf\{x: m^{-1} \sum_{i=1}^{m} \mathbb{I}(\mathcal{A}_{i}^{*} \leqslant x) \ge 1-\alpha\}$.

In the implementation of the bootstrap procedure in practice, replicates \mathbf{X}_n^* may be obtained according to (7) by setting $X_{-p+1}^* = \cdots = X_0^* = \bar{X}$, generating n + breplicates X_t^* , $t \ge 1$, for some large integer b > 0, and then discarding the initial b replicates to eliminate start-up effects (this procedure, with b = 100, is used in the sequel). The order p of the autoregressive sieve may be selected by means of the familiar Akaike information criterion (AIC), so that $\log \hat{\sigma}_p^2 + 2n^{-1}p$ is minimized over a suitable range of values of p. Under mild regularity conditions, a data-dependent choice of pbased on the AIC is asymptotically efficient, in the sense defined by Shibata (1980), for all $|d| < \frac{1}{2}$ (Poskitt (2007, Theorem 9)); furthermore, it satisfies, with probability 1, the growth conditions required for the asymptotic validity of the sieve bootstrap as long as the maximum allowable sieve order p_{max} (say) grows to infinity with n so that $(\log n)^{-s}p_{\text{max}}$ is eventually bounded for some $s \ge 1$ (Psaradakis (2015, Proposition 2)).

We conclude this section by remarking that the linear structure imposed by (1) and (3) may arguably be considered as somewhat restrictive. However, since nonlinear processes with a Gaussian one-dimensional marginal distribution appear to be a rarity (see, e.g., Tong (1990, Sect. 4.2)), the focus on linear dependence is not perhaps unjustifiable when the objective is to test for normality. In any case, the results of Bickel and Bühlmann (1997) suggest that linearity may not be too onerous a requirement in the sense that the closure (with respect to the total variation metric) of the class of linear processes is quite large; roughly speaking, for any stationary non-linear process, there exists another process in the closure of linear processes having identical sample paths with probability exceeding $e^{-1} \simeq 0.37$. This suggests that the autoregressive sieve bootstrap is likely to yield reasonably good approximations within a class of processes larger than that associated with (1) or (6).

4 Simulation Study

In this section, we present and discuss the results of a simulation study examining the small-sample properties of the distance-based test of normality under various datagenerating mechanisms.

4.1 Experimental Design and Simulation

In the first set of experiments, we examine the performance of the test based on \mathcal{A} under different types of dependence by considering artificial data generated according to the ARFIMA process

M1:
$$(1 - 0.7L)X_t = (1 - 0.3L)(1 - L)^{-d}\varepsilon_t, \quad d \in \{-0.4, -0.25, 0, 0.25, 0.4\},\$$

where $\{\varepsilon_t\}$ are i.i.d., zero-mean random variables with variance 1 and *L* denotes the lag operator.⁵ The distribution of ε_t is Gaussian (labeled N in what follows), lognormal (labeled LN), or a member of the family of generalized lambda distributions having inverse distribution function $F_{\varepsilon}^{-1}(u) = \lambda_1 + \lambda_2^{-1} \{u^{\lambda_3} - (1-u)^{\lambda_4}\}$; the parameter values used in the experiments are taken from Bai and Ng (2005) and can be found in Table 1. The distributions S1–S3 are symmetric, whereas A1–A3 and LN are asymmetric.

In the second set of experiments, we assess the robustness of the test based on \mathcal{A} with respect to departures from the linearity assumption underlying the autoregressive sieve bootstrap by using artificial data from the models

M2: $X_t = 0.5X_{t-1} - 0.3X_{t-1}\varepsilon_{t-1} + \varepsilon_t$,

M3:
$$X_t = (0.9X_{t-1} + \varepsilon_t)\mathbb{I}(|X_{t-1}| \le 1) + (-0.3X_{t-1} + 2\varepsilon_t)\mathbb{I}(|X_{t-1}| > 1),$$

M4: $X_t = 0.5X_{t-1} + \varepsilon_t \varepsilon_{t-1}$.

⁵The stationary solution of M1 satisfies (1) with $\mu = 0$, $\psi_1 = 0.4 + \zeta_1$ and $\psi_j = 0.7\psi_{j-1} - 0.3\zeta_{j-1} + \zeta_j$ for $j \ge 2$, where $\zeta_h := {\Gamma(d)\Gamma(h+1)}^{-1}\Gamma(h+d)$ for $h \ge 1$ and $d \ne 0$.

M2 is a bilinear model, M3 is a threshold autoregressive model, and M4 is an autoregressive model with one-dependent, uncorrelated noise. In all three cases, $\{X_t\}$ is short-range dependent and does not admit the representation (1) or (6). Furthermore, the distribution of X_t is non-Gaussian even if ε_t is normally distributed.

In the final set of experiments, we compare the distance test based on \mathcal{A} to the moment-based test discussed in Bai and Ng (2005). The latter is based on the statistic

$$\mathcal{B} := n \{ \hat{\tau}_3^{-2} \hat{\kappa}_3^2 + \hat{\tau}_4^{-2} (\hat{\kappa}_4 - 3)^2 \},\$$

where $\hat{\kappa}_r := n^{-1} \sum_{t=1}^n {\{\hat{\gamma}_0^{-1/2}(X_t - \bar{X})\}}^r \ (r \ge 3)$, and $\hat{\tau}_3^2$ and $\hat{\tau}_4^2$ are estimators of the asymptotic variance of $\sqrt{n}\hat{\kappa}_3$ and $\sqrt{n}(\hat{\kappa}_4 - 3)$, respectively, that are consistent under normality.⁶ When $\{X_t\}$ is a Gaussian process with $\sum_{k=-\infty}^\infty |\gamma_k| < \infty$, the asymptotic distribution of \mathcal{B} is chi-square with 2 degrees of freedom. Following Bai and Ng (2005), the data-generating mechanism is the autoregressive model

M5: $X_t = \varphi X_{t-1} + \varepsilon_t, \quad \varphi \in \{0, 0.5, 0.8\}.$

For each design point, 1000 independent realizations of $\{X_t\}$ of length 100 + n, with $n \in \{100, 200, 500\}$, are generated. The first 100 data points of each realization are then discarded in order to eliminate start-up effects and the remaining n data points are used to compute the value of the test statistic of interest. P-values for the distance test are computed from m = 1000 bootstrap replicates of \mathcal{A} . The sieve order is taken to be the minimizer of the AIC over the range $1 \leq p \leq \lfloor (\log n)^2 \rfloor$, where $\lfloor \cdot \rfloor$ denotes the greatest-integer function; the approximating autoregressive model is fitted by leastsquares (which is preferred over the Yule–Walker method because it produces estimates that exhibit smaller finite-sample bias).

4.2 Simulation Results

The Monte Carlo rejection frequencies, under M1, of the distance test at 5% significance level ($\alpha = 0.05$) are reported in Table 2. The null rejection probabilities of the test

⁶Note that the normality test considered by Lobato and Velasco (2004) is also based on \mathcal{B} , but their choice for $\hat{\tau}_3^2$ and $\hat{\tau}_4^2$ is different from that of Bai and Ng (2005).

are generally insignificantly different from the nominal level across all values of the dependence parameter. The test also performs well under non-Gaussianity, its rejection frequencies improving with larger sample sizes and smaller values of the dependence parameter. Asymmetry in the distribution of ε_t leads, perhaps unsurprisingly, to higher rejection rates. For long-range dependent data, the test generally suffers a loss in power compared to the short-range dependent or antipersistent cases, a loss which becomes more pronounced the larger the value of d is. Psaradakis (2015) reports a similar finding for bootstrap-based tests of distributional symmetry about an unspecified centre.

The distance test based on \mathcal{A} also works very well for data-generating processes which are not representable as (1) or (6). This can be seen in Table 3, which shows the rejection frequencies of a 5%-level test under M2, M3 and M4. The rejection rate of the distance test exceeds 57% for any design point with non-Gaussian noise, even for the smallest sample size considered.

Let us finally turn to Table 4, which contains the rejection frequencies, at the 5% significance level, of the tests based on \mathcal{A} and \mathcal{B} under M5; the rejection frequencies of the \mathcal{B} test are reproduced from Table 4 of Bai and Ng (2005). Unlike the distance test, the moment-based test is prone to level distortion (although the comparison is perhaps somewhat unfair since the \mathcal{B} test relies on a conventional large-sample approximation to its null sampling distribution). The differences in the empirical levels of the two tests notwithstanding, the distance test has a clear advantage under non-normality, outperforming the moment-based test for every design point in our simulations. The differences are particularly striking for symmetric noise distributions, cases in which the \mathcal{B} test has little or no power to detect non-Gaussianity when $\varphi \neq 0$.

5 Real-Data Application

The bootstrap-based distance test for normality is applied to a large set of US economic and financial time series. The data set consists of 79 time series associated with the financial markets (12 series), the labour market (22 series), prices (17 series), money and credit (7 series), output, income and capacity (14 series), and surveys (7 series). All time series are monthly, spanning the period 1971–2013, seasonally adjusted, and (with the exception of survey series) transformed to stationarity by differencing either the raw series (indicated by Δ in what follows) or their natural logarithms (indicated by $\Delta \log$).⁷

P-values for the normality test based on \mathcal{A} , computed from 10000 bootstrap replications, are presented in Table 5. For comparison, we also report asymptotic *P*values for the test based on \mathcal{B} ; following Bai and Ng (2005), $\hat{\tau}_3^2$ and $\hat{\tau}_4^2$ are obtained using a non-parametric kernel estimator with Bartlett weights and a data-dependent bandwidth selected according to the procedure of Andrews (1991). Finally, we report a semi-parametric estimate \hat{d} of the dependence parameter of each time series. The latter is obtained using the local Whittle estimator (Künsch (1987)), i.e., the minimizer, over $|d| \leq 0.499$, of the objective function

$$\log\left(\ell^{-1}\sum_{i=1}^{\ell}\omega_i^{2d}I_i\right) - 2\ell^{-1}d\sum_{i=1}^{\ell}\log\omega_i,$$

where ℓ is a positive integer (chosen as a function of n so that $\ell^{-1} + n^{-1}\ell \to 0$ as $n \to \infty$) and $I_i := (2\pi n)^{-1} |\sum_{t=1}^n X_t \exp(-\omega_i t \sqrt{-1})|^2$ is the periodogram ordinate of the observations at the *i*-th Fourier frequency $\omega_i := 2\pi i/n$. The bandwidth ℓ is set equal to $\lfloor \{16(-2.19\hat{c})^2\}^{-1/5}n^{4/5} \rfloor$, where \hat{c} is the least-squares estimate of the third coefficient in the pseudo-regression of log I_i on $(1, -2\log\omega_i, \omega_i^2/2), i = 1, \ldots, \lfloor 0.3n^{8/9} \rfloor$ (cf. Henry and Robinson (1996); Andrews and Sun (2004)).

Evidence in favour of non-Gaussianity in the US economic time series is overwhelming: the null hypothesis is rejected, at the 5% significance level, for 95% of the series on the basis of the \mathcal{A} test. Interestingly, non-normality is found to be a characteristic feature for all six categories of time series. By comparison, the moment-based test \mathcal{B} leads to rejection of normality in only 30% of the cases. It must be borne in mind, however, that the validity of the test based on \mathcal{B} relies heavily on the assumption of short-range dependence in the data. Such an assumption does not accord well with

⁷The data were downloaded from Haver Analytics (www.haver.com).

the estimates of the dependence parameter shown in Table 5, on the basis of which short-range dependence (d = 0) is rejected in favour of long-range dependence (d > 0)for almost 80% of the time series under consideration. It is also worth recalling from our earlier simulation study that, even for short-range dependent data, the moment-based test appears to be considerably less successful than the distance-based test at detecting deviations from Gaussianity.

6 Conclusion

This paper considered an Anderson–Darling distance test for normality of the onedimensional marginal distribution of strictly stationary, fractionally integrated processes. As a practical way of implementing the test, we proposed using an autoregressive sieve bootstrap procedure to estimate finite-sample *P*-values and/or critical values. The bootstrap-based test is valid for short-range dependent, long-range dependent and antipersistent processes, and does not require knowledge or estimation of the dependence parameter of the data or of the appropriate norming factor for the test statistic. Monte Carlo simulations showed that the distance test has good size and power properties in small samples, although it tends to lack power when the dependence parameter is large and positive. Under short-range dependence, the distance test was found to be more successful than the popular skewness/kurtosis test in detecting departures from normality. An application to a set of US economic and financial time series revealed than non-Gaussianity is a prevalent feature of the data.

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A Tables

 Table 1: Parameters of a Generalized Lambda Distribution and Selected Descriptive

 Statistics

	λ_1	λ_2	λ_3	λ_4	skewness	kurtosis
Ν	_	_	_	_	0.0	3.0
S1	0.000000	-1.000000	-0.080000	-0.080000	0.0	6.0
S2	0.000000	-0.397912	-0.160000	-0.160000	0.0	11.6
S3	0.000000	-1.000000	-0.240000	-0.240000	0.0	126.0
A1	0.000000	-1.000000	-0.007500	-0.030000	1.5	7.5
A2	0.000000	-1.000000	-0.100900	-0.180200	2.0	21.1
A3	0.000000	-1.000000	-0.001000	-0.130000	3.2	23.8
A4		_	_	_	6.2	113.9

	n = 100					n = 200					n = 500					
distr. $\backslash d$	-0.40	-0.25	0	0.25	0.40	-0.40	-0.25	0	0.25	0.40	-0.40	-0.25	0	0.25	0.40	
Ν	0.06	0.05	0.05	0.05	0.06	0.05	0.05	0.05	0.05	0.06	0.05	0.06	0.05	0.05	0.07	
S1	0.48	0.44	0.25	0.12	0.12	0.75	0.70	0.41	0.14	0.09	0.98	0.97	0.75	0.16	0.11	
S2	0.72	0.73	0.44	0.21	0.15	0.94	0.92	0.66	0.23	0.13	1.00	1.00	0.97	0.33	0.15	
S3	0.88	0.85	0.61	0.31	0.21	0.99	0.99	0.88	0.37	0.21	1.00	1.00	1.00	0.58	0.24	
A1	0.97	0.95	0.77	0.25	0.15	1.00	1.00	0.98	0.42	0.16	1.00	1.00	1.00	0.71	0.23	
A2	0.90	0.86	0.64	0.29	0.20	0.99	0.99	0.91	0.43	0.21	1.00	1.00	1.00	0.69	0.32	
A3	1.00	1.00	1.00	0.59	0.29	1.00	1.00	1.00	0.83	0.33	1.00	1.00	1.00	0.99	0.54	
A4	1.00	1.00	1.00	0.78	0.41	1.00	1.00	1.00	0.94	0.54	1.00	1.00	1.00	1.00	0.82	

Table 2: Rejection Frequencies of \mathcal{A} Test Under M1

	1	n = 10	0	7	n = 200)	n = 500				
distr.	M2	M3	M4	M2	M3	M4	M2	M3	M4		
Ν	0.37	0.28	0.94	0.64	0.43	1.00	0.93	0.82	1.00		
S1	0.68	0.65	0.99	0.93	0.91	1.00	1.00	1.00	1.00		
S2	0.81	0.79	0.99	0.97	0.97	1.00	1.00	1.00	1.00		
S3	0.87	0.89	1.00	0.99	0.99	1.00	1.00	1.00	1.00		
A1	0.57	0.86	0.97	0.84	0.99	1.00	0.99	1.00	1.00		
A2	0.71	0.86	0.99	0.91	0.99	1.00	1.00	1.00	1.00		
A3	0.96	1.00	0.97	1.00	1.00	1.00	1.00	1.00	1.00		
LN	1.00	1.00	0.99	1.00	1.00	1.00	1.00	1.00	1.00		

Table 3: Rejection Frequencies of \mathcal{A} Test Under M2-M4

	n = 100					n = 200					n = 500							
$\mathrm{distr.} \backslash \varphi$	0	.0	0	.5	0	.8	0	.0	0	.5	0	.8	0	.0	0	.5	0	.8
	\mathcal{A}	${\mathcal B}$																
N	0.05	0.05	0.05	0.03	0.08	0.01	0.05	0.09	0.06	0.05	0.06	0.02	0.05	0.08	0.05	0.09	0.05	0.04
S1	0.50	0.06	0.27	0.01	0.13	0.00	0.78	0.13	0.43	0.04	0.15	0.00	0.99	0.53	0.76	0.22	0.16	0.02
S2	0.72	0.07	0.43	0.04	0.17	0.01	0.95	0.22	0.70	0.09	0.24	0.02	1.00	0.50	0.97	0.34	0.39	0.06
S3	0.89	0.09	0.64	0.04	0.30	0.01	1.00	0.20	0.89	0.11	0.37	0.03	1.00	0.37	1.00	0.33	0.62	0.09
A1	0.98	0.81	0.79	0.21	0.26	0.00	1.00	1.00	0.98	0.83	0.44	0.03	1.00	1.00	1.00	1.00	0.81	0.46
A2	0.92	0.22	0.66	0.10	0.28	0.01	1.00	0.52	0.90	0.35	0.44	0.06	1.00	0.87	1.00	0.79	0.76	0.36
A3	1.00	0.95	1.00	0.45	0.59	0.00	1.00	0.99	1.00	0.97	0.87	0.03	1.00	1.00	1.00	1.00	1.00	0.73
LN	1.00	0.84	1.00	0.73	0.81	0.02	1.00	0.94	1.00	0.93	0.97	0.16	1.00	0.99	1.00	0.97	1.00	0.88

Table 4: Rejection Frequencies of ${\mathcal A}$ and ${\mathcal B}$ Tests Under M5

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series	transformation	\mathcal{A}	${\mathcal B}$	\hat{d}	$se(\hat{d})$
(A) Financial Markets					
10-Year Treasury Constant Maturity Rate	Δ	0.00	0.10	-0.03	0.06
1-Year Treasury Constant Maturity Rate	Δ	0.00	0.17	-0.10	0.06
3-Month Treasury Bill: Secondary Market Rate	Δ	0.00	0.16	-0.01	0.05
5-Year Treasury Constant Maturity Rate	Δ	0.00	0.16	-0.07	0.07
Effective Federal Funds Rate	Δ	0.00	0.12	-0.13	0.08
Moody's Seasoned Aaa Corporate Bond Yield	Δ	0.00	0.04	0.01	0.05
Moody's Seasoned Baa Corporate Bond Yield	Δ	0.00	0.12	0.16	0.07
Foreign Exchange rate (Yen per US Dolar)	$\Delta \log$	0.00	0.01	0.16	0.04
Foreign Exchange rate (Pound per US Dolar)	$\Delta \log$	0.00	0.12	-0.04	0.08
Foreign Exchange rate (Franc per US Dolar)	$\Delta \log$	0.00	0.01	0.05	0.05
SP 500 Composite Index $(1941-43=10)$	$\Delta \log$	0.00	0.05	0.03	0.07
SP Industrial Index (1941-43=10)	$\Delta \log$	0.00	0.04	0.02	0.07
(B) Labour Market					
All Employees: Construction	$\Delta \log$	0.00	0.00	0.49	0.07
All Employees: Durable goods	$\Delta \log$	0.00	0.05	0.43	0.08
All Employees: Financial Activities	$\Delta \log$	0.55	0.53	0.49	0.06
All Employees: Goods-Producing Industries	$\Delta \log$	0.00	0.12	0.49	0.07
All Employees: Government	$\Delta \log$	0.00	0.10	0.32	0.07
All Employees: Manufacturing	$\Delta \log$	0.00	0.05	0.44	0.08
All Employees: Mining and Logging: Mining	$\Delta \log$	0.00	0.16	0.24	0.07
All Employees: Nondurable goods	$\Delta \log$	0.00	0.33	0.22	0.09
All Employees: Retail Trade	$\Delta \log$	0.01	0.03	0.49	0.09
All Employees: Service-Providing Industries	$\Delta \log$	0.01	0.21	0.49	0.09
All Employees: Total nonfarm	$\Delta \log$	0.00	0.04	0.49	0.06
All Employees: Trade, Transportation and Utilities	$\Delta \log$	0.00	0.14	0.49	0.07
All Employees: Wholesale Trade	$\Delta \log$	0.02	0.22	0.49	0.06
Average Hourly Earnings of Production: Construction	$\Delta \log$	0.00	0.15	0.49	0.08
Average Hourly Earnings of Production: Goods-Producing	$\Delta \log$	0.00	0.00	0.49	0.08
Average Hourly Earnings of Production: Manufacturing	$\Delta \log$	0.00	0.00	0.49	0.08
Average Weekly Hours of Production: Goods-Producing	Δ	0.00	0.37	-0.06	0.07
Average Weekly Hours of Production: Manufacturing	Δ	0.00	0.35	-0.04	0.06

Table 5: *P*-values of the \mathcal{A} and \mathcal{B} Tests

Average Weekly Overtime Hours: Manufacturing	Δ	0.00	0.27	-0.07	0.04
Civilian Employment	$\Delta \log$	0.00	0.04	0.35	0.06
Civilian Labor Force	Δ	0.00	0.24	0.28	0.08
Civilian Unemployment Rate	Δ	0.00	0.21	0.49	0.07
(C) Prices					
Consumer Price Index: All Items	$\Delta \log$	0.00	0.00	0.49	0.07
Consumer Price Index: All Items Less Food	$\Delta \log$	0.00	0.02	0.41	0.07
Consumer Price Index: Apparel	$\Delta \log$	0.00	0.03	0.39	0.09
Consumer Price Index: Commodities	$\Delta \log$	0.00	0.19	0.18	0.06
Consumer Price Index: Durables	$\Delta \log$	0.00	0.00	0.28	0.05
Consumer Price Index: Medical Care	$\Delta \log$	0.00	0.09	0.49	0.08
Consumer Price Index: Services	$\Delta \log$	0.00	0.07	0.49	0.09
Consumer Price Index: Transportation	$\Delta \log$	0.00	0.32	0.06	0.08
Personal Consumption Expenditures	$\Delta \log$	0.00	0.00	0.49	0.08
Personal consumption expenditures: Durable goods	$\Delta \log$	0.03	0.16	0.49	0.08
Personal consumption expenditures: Nondurable goods	$\Delta \log$	0.00	0.10	0.18	0.04
Personal consumption expenditures: Services	$\Delta \log$	0.00	0.00	0.49	0.09
Producer Price Index: Commodities: Metals	$\Delta \log$	0.00	0.06	0.00	0.09
Producer Price Index: Crude Materials	$\Delta \log$	0.00	0.04	-0.17	0.09
Producer Price Index: Finished Consumer Goods	$\Delta \log$	0.00	0.16	0.21	0.05
Producer Price Index: Finished Goods	$\Delta \log$	0.00	0.11	0.25	0.06
Producer Price Index: Intermediate Materials	$\Delta \log$	0.00	0.11	0.15	0.09
(D) Money and Credit					
M1 Money Stock	$\Delta \log$	0.00	0.15	0.45	0.08
M2 Money Stock	$\Delta \log$	0.00	0.06	0.34	0.05
M3 Money Stock	$\Delta \log$	0.00	0.05	0.35	0.05
Commercial and Industrial Loans, All Commercial Banks	$\Delta \log$	0.01	0.08	0.49	0.04
Real Estate Loans, All Commercial Banks	$\Delta \log$	0.07	0.12	0.49	0.08
Real M2 Money Stock	$\Delta \log$	0.00	0.26	0.26	0.06
Total Nonrevolving Credit Owned, Outstanding	$\Delta \log$	0.00	0.34	0.49	0.07
(E) Output, Income and Capacity					
Industrial Production: Business Equipment	$\Delta \log$	0.00	0.21	0.40	0.05
Industrial Production: Consumer Goods	$\Delta \log$	0.00	0.17	0.13	0.06
Industrial Production: Durable Materials	$\Delta \log$	0.00	0.08	0.28	0.07
		•			

Industrial Production: Final Products	$\Delta \log$	0.00	0.07	0.26	0.08
Industrial Production: Fuels	$\Delta \log$	0.00	0.42	-0.15	0.09
Industrial Production Index	$\Delta \log$	0.00	0.18	0.31	0.08
Industrial Production: Manufacturing	$\Delta \log$	0.00	0.18	0.23	0.08
Industrial Production: Materials	$\Delta \log$	0.00	0.09	0.30	0.07
Industrial Production: Nondurable Goods	$\Delta \log$	0.76	0.55	0.17	0.08
Industrial Production: nondurable Materials	$\Delta \log$	0.00	0.17	-0.08	0.08
Personal Income	$\Delta \log$	0.00	0.09	0.49	0.09
Real Personal Income	$\Delta \log$	0.00	0.10	0.37	0.09
Real personal income excluding current transfers	$\Delta \log$	0.00	0.14	0.36	0.10
Capacity Utilization: Manufacturing	Δ	0.00	0.22	0.14	0.08
(F) Surveys					
ISM Manufacturing: Employment Index	_	0.04	0.06	0.49	0.08
ISM Manufacturing: Inventories Index	_	0.02	0.01	0.49	0.07
ISM Manufacturing: New Orders Index	_	0.00	0.01	0.35	0.08
ISM Manufacturing: PMI Composite Index	_	0.01	0.02	0.49	0.08
ISM Manufacturing: Prices Index	_	0.11	0.03	0.41	0.09
ISM Manufacturing: Production Index	_	0.00	0.03	0.28	0.09
ISM Manufacturing: Supplier Deliveries	_	0.00	0.11	0.34	0.09