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Common fixed point theorems for mappings satisfying (E.A)-property via C-class functions in b-metric spaces

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ABSTRACT

In this paper, we consider and generalize recent $b-(E.A)$ -property results in [11] via the concepts of C-class functions in b- metric spaces. A example is given to support the result.

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1. Introduction and preliminaries

Bakhtin in [5] introduced the consept of b−metric space and prove the Banach fixed point theorem in the setting of b−metric spaces. Since then many authors have obtain various generalizations of fixed point theorems in b−metric spaces.

On the other hand, Aamri and Moutaawakil in [1] introduced the idea of $(E.A)$ –property in metric spaces. Later on some authors employed this concept to obtain some new fixed point results. See $([6, 10])$.

In this paper, we prove common fixed point results for two pairs of mappings which satisfy the $b - (E.A)$ -property using the concept of C-class functions in b−metric spaces.

Definition 1.1 ([5]). Let X be a nonempty set and $s \geq 1$ be a given real number. A function $d: X \times X \to [0, \infty)$ is a b-metric if, for all $x, y, z \in X$, the following conditions are satisfied:

- (b1) $d(x, y) = 0$ if and only if $x = y$,
- (b2) $d(x, y) = d(y, x)$,
- (b3) $d(x, z) \leq s [d(x, y) + d(y, z)].$

In this case, the pair (X, d) is called a b-metric space.

It should be noted that, the class of b-metric spaces is effectively larger than that of metric spaces, every metric is a b-metric with $s = 1$.

However, if (X, d) is a metric space, then (X, ρ) is not necessarily a metric space.

Definition 1.2 ([7]). Let $\{x_n\}$ be a sequence in a b-metric space (X, d) .

- (a) $\{x_n\}$ is called b–convergent if and only if there is $x \in X$ such that $d(x_n, x) \to 0$ as $n \to \infty$.
- (b) $\{x_n\}$ is a b–Cauchy sequence if and only if $d(x_n, x_m) \to 0$ as $n, m \to \infty$ ∞.

A b-metric space is said to be complete if and only if each b−Cauchy sequence in this space is b−convergent.

Proposition 1.3 ([7]). In a b−metric space (X, d) , the following assertions hold:

- (p1) A b−convergent sequence has a unique limit.
- (p2) Each b−convergent sequence is b−Cauchy.
- (p3) In general, a b−metric is not continuous.

Definition 1.4 ([7]). Let (X, d) be a b−metric space. A subset $Y \subset X$ is called closed if and only if for each sequence $\{x_n\}$ in Y is b−convergent and converges to an element x .

Definition 1.5 ([11]). Let (X, d) be a b−metric space and f and g be selfmappings on X .

(i) f and g are said to compatible if whenever a sequence $\{x_n\}$ in X is such that $\{fx_n\}$ and $\{gx_n\}$ are b−convergent to some $t \in X$, then

$$
\lim_{n \to \infty} d(fgx_n, gfx_n) = 0.
$$

- (ii) f and q are said to noncompatible if there exists at least one sequence ${x_n}$ in X is such that ${f x_n}$ and ${g x_n}$ are b−convergent to some $t \in X$, but $\lim_{n\to\infty} d(fgx_n, gfx_n)$ does not exist.
- (iii) f and g are said to satisfy the $b (E.A)$ -property if there exists a sequence $\{x_n\}$ such that

$$
\lim_{n \to \infty} f x_n = \lim_{n \to \infty} g x_n = t,
$$

for some $t \in X$.

Remark 1.6 ([11]). Noncompatibility implies property $(E.A)$.

Example 1.7 ([11]). $X = [0, 2]$ and define $d : X \times X \rightarrow [0, \infty)$ as follows

 $d(x, y) = (x - y)^{2}.$

Let $f, g: X \to X$ be defined by

$$
f(x) = \begin{cases} 1, x \in [0, 1] \\ \frac{x+1}{8}, x \in (1, 2] \end{cases} \quad g(x) = \begin{cases} \frac{3-x}{2}, x \in [0, 1] \\ \frac{x}{4}, x \in (1, 2] \end{cases}
$$

For a sequence $\{x_n\}$ in X such that $x_n = 1 + \frac{1}{n+2}$, $n = 0, 1, 2, ...$,

$$
\lim_{n \to \infty} f x_n = \lim_{n \to \infty} g x_n = \frac{1}{4}.
$$

So f and g are satisfy the $b - (E.A)$ -property. But

$$
\lim_{n \to \infty} d(fgx_n, gfx_n) \neq 0.
$$

Thus f and g are noncompatible.

Definition 1.8 ([8]). Let f and g be given self-mappings on a set X. The pair (f, g) is said to be weakly compatible if f and g commute at their coincidence points (i.e. $fgx = gfx$ whenever $fx = gx$).

In 2014, Ansari [3] introduced the concept of C-class functions. See also [4]

Definition 1.9. A mapping $F : [0, \infty)^2 \to \mathbb{R}$ is called C-class function if it is continuous and satisfies following axioms:

(i) $F(s,t) \leq s$;

(ii) $F(s,t) = s$ implies that either $s = 0$ or $t = 0$; for all $s, t \in [0,\infty)$.

Note for some F we have that $F(0, 0) = 0$. We denote C-class functions as \mathcal{C} .

Example 1.10. The following functions $F : [0, \infty)^2 \to \mathbb{R}$ are elements of C, for all $s, t \in [0, \infty)$:

- (1) $F(s,t) = s t$, $F(s,t) = s \Rightarrow t = 0$;
- (2) $F(s,t) = ms, 0 < m < 1, F(s,t) = s \Rightarrow s = 0;$
- (3) $F(s,t) = \frac{s}{(1+t)^r}$; $r \in (0,\infty)$, $F(s,t) = s \Rightarrow s = 0$ or $t = 0$;
- (4) $F(s,t) = \log(t + a^s)/(1 + t), a > 1, F(s,t) = s \Rightarrow s = 0 \text{ or } t = 0;$
- (5) $F(s,t) = \ln(1+a^s)/2, a > e, F(s,1) = s \Rightarrow s = 0;$
- (6) $F(s,t) = (s+t)^{(1/(1+t)^r)} l, l > 1, r \in (0,\infty), F(s,t) = s \Rightarrow t = 0;$
- (7) $F(s,t) = s \log_{t+a} a, a > 1, F(s,t) = s \Rightarrow s = 0 \text{ or } t = 0;$
- (8) $F(s,t) = s \left(\frac{1+s}{2+s}\right)\left(\frac{t}{1+t}\right), F(s,t) = s \Rightarrow t = 0;$
- (9) $F(s,t) = s\beta(s)$, $\beta : [0,\infty) \to (0,1)$, and is continuous, $F(s,t) = s \Rightarrow$ $s = 0;$
- (10) $F(s,t) = s \frac{t}{k+t}, F(s,t) = s \Rightarrow t = 0;$
- (11) $F(s,t) = s \varphi(s)$, $F(s,t) = s \Rightarrow s = 0$, here $\varphi : [0,\infty) \to [0,\infty)$ is a continuous function such that $\varphi(t) = 0 \Leftrightarrow t = 0;$
- (12) $F(s,t) = sh(s,t), F(s,t) = s \Rightarrow s = 0$, here $h : [0,\infty) \times [0,\infty) \rightarrow$ $[0, \infty)$ is a continuous function such that $h(t, s) < 1$ for all $t, s > 0$;

(13)
$$
F(s,t) = s - (\frac{2+t}{1+t})t
$$
, $F(s,t) = s \Rightarrow t = 0$.

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- (14) $F(s,t) = \sqrt[n]{\ln(1+s^n)}, F(s,t) = s \Rightarrow s = 0.$
- (15) $F(s,t) = \phi(s)$, $F(s,t) = s \Rightarrow s = 0$, here $\phi : [0,\infty) \rightarrow [0,\infty)$ is a upper semicontinuous function such that $\phi(0) = 0$, and $\phi(t) < t$ for $t > 0$,
- (16) $F(s,t) = \frac{s}{(1+s)^r}$; $r \in (0,\infty)$, $F(s,t) = s \Rightarrow s = 0$.

Definition 1.11 ([9]). A function $\psi : [0, \infty) \to [0, \infty)$ is called an altering distance function if the following properties are satisfied:

- (i) ψ is non-decreasing and continuous,
- (ii) $\psi(t) = 0$ if and only if $t = 0$.

See also [2] and [12].

Definition 1.12 ([3]). An ultra altering distance function is a continuous, nondecreasing mapping $\varphi : [0, \infty) \to [0, \infty)$ such that $\varphi(t) > 0$, $t > 0$ and $\varphi(0) \geq 0$

2. Main results

Through out this section, we assume ψ is altering distance function, φ is ultra altering distance function and F is a C-class function. We shall start the following theorem.

Theorem 2.1. Let (X,d) be a b−metric space and $f, g, S, T : X \rightarrow X$ be mappings with $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$ such that

$$
(2.1) \qquad \psi(d(fx, gy)) \le F(\psi(M_s(x, y)), \varphi(M_s(x, y))), \quad \text{for all } x, y \in X
$$

where,

$$
M_s(x,y) = \max \left\{ d\left(Sx,Ty\right), d\left(fx,Sx\right), d\left(gy,Ty\right), \frac{d\left(fx,Ty\right) + d\left(Sx,gy\right)}{2s} \right\}.
$$

Suppose that one of the pairs (f, S) and (g, T) satisfy the $b - (E.A)$ -property and that one of the subspaces $f(X), g(X), S(X)$ and $T(X)$ is closed in X. Then the pairs (f, S) and (g, T) have a point of coincidence in X. Moreover, if the pairs (f, S) and (g, T) are weakly compatible, then f, g, S and T have a unique common fixed point.

Proof. If the pairs (f, S) satisfies the $b - (E.A)$ -property, then there exists a sequence $\{x_n\}$ in X satisfying

$$
\lim_{n \to \infty} f x_n = \lim_{n \to \infty} S x_n = q,
$$

for some $q \in X$. As $f(X) \subseteq T(X)$ there exists a sequence $\{y_n\}$ in X such that $fx_n = Ty_n$. Hence $\lim_{n\to\infty} Ty_n = q$. Let us show that $\lim_{n\to\infty} gy_n = q$. By (2.1), (2.2)

$$
\psi(d(fx_n, gy_n)) \leq F(\psi(M_s(x_n, y_n)), \varphi(M_s(x_n, y_n))) \leq \psi(M_s(x_n, y_n))
$$

where

$$
M_{s}(x_{n}, y_{n}) = \max \left\{ \begin{array}{c} d(Sx_{n}, Ty_{n}), d(fx_{n}, Sx_{n}), d(Ty_{n}, gy_{n}), \\ \frac{d(Sx_{n}, gy_{n}) + d(fx_{n}, Ty_{n})}{2s} \end{array} \right\}
$$

=
$$
\max \left\{ \begin{array}{c} d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n}), \\ \frac{d(Sx_{n}, gy_{n}) + d(fx_{n}, fx_{n})}{2s} \end{array} \right\}
$$

$$
\leq \max \left\{ \begin{array}{c} d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n}), \\ \frac{s[d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n})]}{2s} \end{array} \right\}.
$$

In (2.2), on taking limit,

$$
\psi(\lim_{n\to\infty} d(q,gy_n)) \leq F(\psi(\lim_{n\to\infty} d(q,gy_n)), \varphi(\lim_{n\to\infty} d(q,gy_n))).
$$

So, $\psi(\lim_{n\to\infty}d(q,gy_n))=0$, or $\phi(\lim_{n\to\infty}d(q,gy_n))=0$. Thus

$$
\lim_{n \to \infty} d(q, gy_n) = 0.
$$

Hence $\lim_{n\to\infty} gy_n = q$.

If $T(X)$ is closed subspace of X, then there exists a $r \in X$, such that $Tr = q$. By (2.1) ,

(2.3)
$$
\psi(d(fx_n, gr)) \leq F(\psi(M_s(x_n, r)), \varphi(M_s(x_n, r)))
$$

where

$$
M_s(x_n, r) = \max \left\{ \begin{array}{c} d(Sx_n, Tr), d(fx_n, Sx_n), d(Tr, gr), \\ \frac{d(fx_n, Tr) + d(Sx_n, gr)}{2s} \end{array} \right\}
$$

=
$$
\max \left\{ \begin{array}{c} d(Sx_n, q), d(fx_n, Sx_n), d(q, gr), \\ \frac{d(fx_n, g) + d(Sx_n, gr)}{2s} \end{array} \right\}.
$$

Letting $n \to \infty$,

$$
\lim_{n \to \infty} M_s(x_n, r) = \max \left\{ d(q, q), d(q, q), d(q, gr), \frac{d(q, q) + d(q, gr)}{2s} \right\}
$$

= $d(q, gr).$

Now, (2.3) and definition of ψ and φ , as $n \to \infty$,

$$
\psi(d(q, gr) \le F(\psi(d(q, gr)), \varphi(d(q, gr)))
$$

which implies $\psi(d(q, gr)) = 0$ or $\varphi(d(q, gr)) = 0$ gives $gr = q$. Thus r is a coincidence point of the pair (g, T) . As $g(X) \subseteq S(X)$, there exists a point $z \in X$ such that $q = Sz$. We claim that $Sz = fz$. By (2.1), we have

(2.4)
$$
\psi(d(fz,gr)) \leq F(\psi(M_s(z,r)), \varphi(M_s(z,r)))
$$

 $M_s(z,r) = \max \left\{ d\left(Sz,Tr\right), d\left(fz, Sz\right), d\left(Tr, gr\right), \frac{d\left(fz,Tr\right) + d\left(Sz, gr\right)}{2\pi}\right\}$ 2s $=$ max $\begin{cases} d(q,q), d(fz,q), d(q,q), \frac{d(fz,q)+d(q,q)}{2} \end{cases}$ 2s <u>)</u> $\leq \max\left\{d(fz,q),\frac{d(fz,q)}{2}\right\}$ 2s <u>)</u> $= d(fz,q).$

Thus from (2.4) ,

where

$$
\psi(d(fz,gr)) = \psi(d(fz,q)) \leq F(\psi(d(fz,q)), \varphi(d(fz,q)))
$$

implies that $\psi(d(fz,q)) = 0$, or $\phi(d(fz,q)) = 0$. Therefore $Sz = fz = q$. Hence z is a coincidence point of the pair (f, S) . Thus $fz = Sz = gr = Tr = q$. By weak compatibility of the pairs (f, S) and (g, T) , we deduce that $fq = Sq$ and $gq = Tq$. We will show that q is a common fixed point of f, g, S and T. From (2.1) ,

(2.5)
$$
\psi(d(fq,q)) = \psi(d(fq,gr)) \leq F(\psi(M_s(q,r)), \varphi(M_s(q,r)))
$$

where,

$$
M_s(q,r) = \max \left\{ d(Sq, Tr), d(fq, Sq), d(Tr, gr), \frac{d(fq, Tr) + d(Sq, gr)}{2s} \right\}
$$

=
$$
\max \left\{ d(fq, q), d(fq, fq), d(q, q), \frac{d(fq, q) + d(fq, q)}{2s} \right\}
$$

=
$$
d(fq, q).
$$

By (2.5)

$$
\psi(d(fq,q)) \le F(\psi(d(fq,q)), \varphi(d(fq,q))).
$$

So $fq = Sq = q$. Similarly, it can be shown $gq = Tq = q$.

To prove the uniqueness of the fixed point of f, g, S and T. Suppose for contradiction that p is another fixed point of f, g, S and T . By (2.1), we obtain

$$
\psi(d(q,p)) = \psi(d(fq,gp)) \leq F(\psi(M_s(q,p)), \varphi(M_s(q,p)))
$$

and

$$
M_s(q, p) = \max \left\{ d(Sq, Tp), d(fq, Sq), d(Tp, gp), \frac{d(fq, Tp) + d(Sq, gp)}{2s} \right\}
$$

=
$$
\max \left\{ d(q, p), d(q, q), d(p, p), \frac{d(q, p) + d(q, p)}{2s} \right\}
$$

=
$$
d(q, p).
$$

Hence we have

$$
\psi(d(q, p)) \le F(\psi(d(q, p)), \varphi(d(q, p))),
$$

which implies that $\psi(d(q, p)) = 0$ or $\varphi(d(q, p)) = 0$. So $q = p$.

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Corollary 2.2. Let (X, d) be a b−metric space and $f, g, S, T : X \rightarrow X$ be mappings with $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$ such that

$$
d(fx, gy) \le F(M_s(x, y), \varphi(M_s(x, y))), \text{ for all } x, y \in X,
$$

where

$$
M_s(x,y) = \max \left\{ d\left(Sx,Ty\right), d\left(fx,Sx\right), d\left(gy,Ty\right), \frac{d\left(fx,Ty\right) + d\left(Sx,gy\right)}{2s} \right\}.
$$

Suppose that one of the pairs (f, S) and (g, T) satisfy the $b - (E.A)$ -property and that one of the subspaces $f(X), g(X), S(X)$ and $T(X)$ is closed in X. Then the pairs (f, S) and (g, T) have a point of coincidence in X. Moreover, if the pairs (f, S) and (g, T) are weakly compatible, then f, g, S and T have a unique common fixed point.

Corollary 2.3. Let (X, d) be a b−metric space and $f, T : X \to X$ be mappings such that

$$
\psi(d(fx, fy)) \leq F(\psi(M_s(x, y)), \varphi(M_s(x, y))), \text{ for all } x, y \in X,
$$

where

$$
M_s(x,y) = \max \left\{ d(Tx,Ty), d(fx,Tx), d(fy,Ty), \frac{d(fx,Ty) + d(Tx, fy)}{2s} \right\}.
$$

Suppose that the pair (f, T) satisfies the b - $(E.A)$ -property and $T(X)$ is closed in X. Then the pair (f, T) has a common point of coincidence in X. Moreover, if the pair (f, T) is weakly compatible, then f and T have a unique common fixed point.

Example 2.4. Let $F(s,t) = \frac{99}{100}s$, $X = [0,1]$ and define $d: X \times X \rightarrow [0,\infty)$ as follows

$$
d(x, y) = \{ \begin{array}{c} 0, x = y \\ (x + y)^{2}, x \neq y \end{array}
$$

Then (X, d) is a b−metric space with constant $s = 2$. Let $f, g, S, T : X \to X$ be defined by

$$
f(x) = \frac{x}{4}, g(x) = \begin{cases} 0, x \neq \frac{1}{2} \\ \frac{1}{8}, x = \frac{1}{2} \end{cases}, S(x) = \begin{cases} 2x, 0 \le x < \frac{1}{2} \\ \frac{1}{8}, \frac{1}{2} \le x \le 1 \end{cases}
$$
and

$$
T(x) = \begin{cases} x, 0 \le x < \frac{1}{2} \\ \frac{1}{2}, \frac{1}{2} \le x \le 1 \end{cases}.
$$

Clearly, $f(X)$ is closed and $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$. The sequence ${x_n}$, $x_n = \frac{1}{2} + \frac{1}{n}$, is in X such that $\lim_{n\to\infty} f x_n = \lim_{n\to\infty} S x_n = \frac{1}{8}$. So that the pair (f, S) satisfies the $b - (E.A)$ –property. But the pair (f, S) is noncompatible for $\lim_{n\to\infty} d(fSx_n, Sfx_n) \neq 0$. The altering functions ψ, φ : from the form $\lim_{n\to\infty} a(t) S x_n, S f x_n \neq 0$. The alternig functions $\psi, \varphi : [0,\infty) \to [0,\infty)$ are defined by $\psi(t) = \sqrt{t}$. To check the contractive condition (2.1) , for all $x, y \in X$,

if $x = 0$ or $x = \frac{1}{2}$, then (2.1) is satisfied. if $x \in \left(0, \frac{1}{2}\right)$, then

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$$
\psi(d(fx, gy)) = \frac{x}{4} \le \frac{99}{100} \frac{9x}{4} = \frac{99}{100} d(fx, Sx) \le \frac{99}{100} \psi(M_s(x, y)).
$$

If $x \in (\frac{1}{2}, 1]$, then

$$
\psi(d(fx, gy)) = \frac{x}{4} \le \frac{99}{100} \left(\frac{x}{4} + \frac{1}{8}\right) = \frac{99}{100} d(fx, Sx) \le \frac{99}{100} \psi(M_s(x, y)).
$$

Then (2.1) is satisfied for all $x, y \in X$. The pairs (f, S) and (g, T) are weakly compatible. Hence, all of the conditions of Theorem 2.1 are satisfied. Moreover 0 is the unique common fixed point of f, g, S and T.

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