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Common fixed point theorems for mappings satisfying (E.A)-property via C-class functions in b-metric spaces

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Abstract

In this paper, we consider and generalize recent b-(E.A)-property results in [11] via the concepts of C-class functions in b- metric spaces. A example is given to support the result.

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KEYWORDS: Common fixed point; (E.A)-property; b-metric space; C-class function.

1. Introduction and preliminaries

Bakhtin in [5] introduced the consept of b—metric space and prove the Banach fixed point theorem in the setting of b—metric spaces. Since then many authors have obtain various generalizations of fixed point theorems in b—metric spaces.

On the other hand, Aamri and Moutaawakil in [1] introduced the idea of (E.A) –property in metric spaces. Later on some authors employed this concept to obtain some new fixed point results. See ([6, 10]).

In this paper, we prove common fixed point results for two pairs of mappings which satisfy the b-(E.A)-property using the concept of C-class functions in b-metric spaces.

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Definition 1.1 ([5]). Let X be a nonempty set and $s \geq 1$ be a given real number. A function $d: X \times X \to [0, \infty)$ is a b-metric if, for all $x, y, z \in X$, the following conditions are satisfied:

- (b1) d(x,y) = 0 if and only if x = y,
- (b2) d(x,y) = d(y,x),
- (b3) $d(x,z) \le s [d(x,y) + d(y,z)]$.

In this case, the pair (X, d) is called a b-metric space.

It should be noted that, the class of b-metric spaces is effectively larger than that of metric spaces, every metric is a b-metric with s = 1.

However, if (X, d) is a metric space, then (X, ρ) is not necessarily a metric space.

Definition 1.2 ([7]). Let $\{x_n\}$ be a sequence in a b-metric space (X, d).

- (a) $\{x_n\}$ is called b-convergent if and only if there is $x \in X$ such that $d(x_n, x) \to 0 \text{ as } n \to \infty.$
- (b) $\{x_n\}$ is a b-Cauchy sequence if and only if $d(x_n,x_m)\to 0$ as $n,m\to \infty$

A b-metric space is said to be complete if and only if each b-Cauchy sequence in this space is b-convergent.

Proposition 1.3 ([7]). In a b-metric space (X,d), the following assertions hold:

- (p1) A b-convergent sequence has a unique limit.
- (p2) Each b-convergent sequence is b-Cauchy.
- (p3) In general, a b-metric is not continuous.

Definition 1.4 ([7]). Let (X,d) be a b-metric space. A subset $Y \subset X$ is called closed if and only if for each sequence $\{x_n\}$ in Y is b-convergent and converges to an element x.

Definition 1.5 ([11]). Let (X,d) be a b-metric space and f and g be selfmappings on X.

(i) f and g are said to compatible if whenever a sequence $\{x_n\}$ in X is such that $\{fx_n\}$ and $\{gx_n\}$ are b-convergent to some $t \in X$, then

$$\lim_{n\to\infty} d\left(fgx_n, gfx_n\right) = 0.$$

- (ii) f and q are said to noncompatible if there exists at least one sequence $\{x_n\}$ in X is such that $\{fx_n\}$ and $\{gx_n\}$ are b-convergent to some $t \in X$, but $\lim_{n\to\infty} d(fgx_n, gfx_n)$ does not exist.
- (iii) f and g are said to satisfy the b (E.A)-property if there exists a sequence $\{x_n\}$ such that

$$\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = t,$$

for some $t \in X$.

Remark 1.6 ([11]). Noncompatibility implies property (E.A).

Example 1.7 ([11]). X = [0, 2] and define $d : X \times X \to [0, \infty)$ as follows $d(x, y) = (x - y)^2$.

Let $f, g: X \to X$ be defined by

$$f\left(x\right) = \left\{ \begin{array}{l} 1, x \in \left[0,1\right] \\ \frac{x+1}{8}, x \in \left(1,2\right] \end{array} \right. \quad g\left(x\right) = \left\{ \begin{array}{l} \frac{3-x}{2}, x \in \left[0,1\right] \\ \frac{x}{4}, x \in \left(1,2\right] \end{array} \right.$$

For a sequence $\{x_n\}$ in X such that $x_n = 1 + \frac{1}{n+2}, n = 0, 1, 2, ...,$

$$\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = \frac{1}{4}.$$

So f and g are satisfy the b-(E.A)-property. But

$$\lim_{n\to\infty} d\left(fgx_n, gfx_n\right) \neq 0.$$

Thus f and g are noncompatible.

Definition 1.8 ([8]). Let f and g be given self-mappings on a set X. The pair (f,g) is said to be weakly compatible if f and g commute at their coincidence points (i.e. fgx = gfx whenever fx = gx).

In 2014, Ansari [3] introduced the concept of C-class functions. See also [4]

Definition 1.9. A mapping $F:[0,\infty)^2\to\mathbb{R}$ is called C-class function if it is continuous and satisfies following axioms:

- (i) $F(s,t) \leq s$;
- (ii) F(s,t) = s implies that either s = 0 or t = 0; for all $s, t \in [0, \infty)$.

Note for some F we have that F(0,0) = 0.

We denote C-class functions as \hat{C} .

Example 1.10. The following functions $F:[0,\infty)^2\to\mathbb{R}$ are elements of \mathcal{C} , for all $s,t\in[0,\infty)$:

- (1) F(s,t) = s t, $F(s,t) = s \Rightarrow t = 0$;
- (2) F(s,t) = ms, 0 < m < 1, $F(s,t) = s \Rightarrow s = 0$;
- (3) $F(s,t) = \frac{s}{(1+t)^r}$; $r \in (0,\infty)$, $F(s,t) = s \Rightarrow s = 0$ or t = 0;
- (4) $F(s,t) = \log(t+a^s)/(1+t)$, a > 1, $F(s,t) = s \Rightarrow s = 0$ or t = 0;
- (5) $F(s,t) = \ln(1+a^s)/2$, a > e, $F(s,1) = s \Rightarrow s = 0$;
- (6) $F(s,t) = (s+l)^{(1/(1+t)^r)} l, \ l > 1, r \in (0,\infty), \ F(s,t) = s \Rightarrow t = 0;$
- (7) $F(s,t) = s \log_{t+a} a, \ a > 1, \ F(s,t) = s \Rightarrow s = 0 \text{ or } t = 0;$
- (8) $F(s,t) = s (\frac{1+s}{2+s})(\frac{t}{1+t}), F(s,t) = s \Rightarrow t = 0;$
- (9) $F(s,t) = s\beta(s), \ \beta: [0,\infty) \to (0,1), \ \text{and is continuous}, \ F(s,t) = s \Rightarrow s = 0;$
- (10) $F(s,t) = s \frac{t}{k+t}, F(s,t) = s \Rightarrow t = 0;$
- (11) $F(s,t) = s \varphi(s), F(s,t) = s \Rightarrow s = 0$, here $\varphi : [0,\infty) \to [0,\infty)$ is a continuous function such that $\varphi(t) = 0 \Leftrightarrow t = 0$;
- (12) $F(s,t) = sh(s,t), F(s,t) = s \Rightarrow s = 0, \text{here } h : [0,\infty) \times [0,\infty) \rightarrow [0,\infty) \text{ is a continuous function such that } h(t,s) < 1 \text{ for all } t,s > 0;$
- (13) $F(s,t) = s (\frac{2+t}{1+t})t, F(s,t) = s \Rightarrow t = 0.$

- (14) $F(s,t) = \sqrt[n]{\ln(1+s^n)}, F(s,t) = s \Rightarrow s = 0.$
- (15) $F(s,t) = \phi(s), F(s,t) = s \Rightarrow s = 0, \text{here } \phi : [0,\infty) \to [0,\infty) \text{ is a upper}$ semicontinuous function such that $\phi(0) = 0$, and $\phi(t) < t$ for t > 0,
- (16) $F(s,t) = \frac{s}{(1+s)^r}$; $r \in (0,\infty)$, $F(s,t) = s \Rightarrow s = 0$.

Definition 1.11 ([9]). A function $\psi:[0,\infty)\to[0,\infty)$ is called an altering distance function if the following properties are satisfied:

- (i) ψ is non-decreasing and continuous,
- (ii) $\psi(t) = 0$ if and only if t = 0.

See also [2] and [12].

Definition 1.12 ([3]). An ultra altering distance function is a continuous, nondecreasing mapping $\varphi:[0,\infty)\to[0,\infty)$ such that $\varphi(t)>0$, t>0 and $\varphi(0) \geq 0$

2. Main results

Through out this section, we assume ψ is altering distance function, φ is ultra altering distance function and F is a C-class function. We shall start the following theorem.

Theorem 2.1. Let (X,d) be a b-metric space and $f,g,S,T:X\to X$ be mappings with $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$ such that

(2.1)
$$\psi(d(fx,gy)) \leq F(\psi(M_s(x,y)), \varphi(M_s(x,y))), \text{ for all } x,y \in X$$
 where.

$$M_{s}\left(x,y\right)=\max\left\{ d\left(Sx,Ty\right),d\left(fx,Sx\right),d\left(gy,Ty\right),\frac{d\left(fx,Ty\right)+d\left(Sx,gy\right)}{2s}\right\} .$$

Suppose that one of the pairs (f, S) and (g, T) satisfy the b - (E.A)-property and that one of the subspaces f(X), g(X), S(X) and T(X) is closed in X. Then the pairs (f, S) and (g, T) have a point of coincidence in X. Moreover, if the pairs (f,S) and (g,T) are weakly compatible, then f,g,S and T have a unique common fixed point.

Proof. If the pairs (f, S) satisfies the b - (E.A)-property, then there exists a sequence $\{x_n\}$ in X satisfying

$$\lim_{n\to\infty} fx_n = \lim_{n\to\infty} Sx_n = q,$$

for some $q \in X$. As $f(X) \subseteq T(X)$ there exists a sequence $\{y_n\}$ in X such that $fx_n = Ty_n$. Hence $\lim_{n\to\infty} Ty_n = q$. Let us show that $\lim_{n\to\infty} gy_n = q$. By (2.1), (2.2)

$$\psi\left(d\left(fx_{n},gy_{n}\right)\right) \leq F\left(\psi\left(M_{s}\left(x_{n},y_{n}\right)\right),\varphi\left(M_{s}\left(x_{n},y_{n}\right)\right)\right) \leq \psi\left(M_{s}\left(x_{n},y_{n}\right)\right)$$

where

$$M_{s}(x_{n}, y_{n}) = \max \left\{ \begin{array}{l} d(Sx_{n}, Ty_{n}), d(fx_{n}, Sx_{n}), d(Ty_{n}, gy_{n}), \\ \frac{d(Sx_{n}, gy_{n}) + d(fx_{n}, Ty_{n})}{2s} \end{array} \right\}$$

$$= \max \left\{ \begin{array}{l} d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n}), \\ \frac{d(Sx_{n}, gy_{n}) + d(fx_{n}, fx_{n})}{2s} \end{array} \right\}$$

$$\leq \max \left\{ \begin{array}{l} d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n}), \\ \frac{s[d(Sx_{n}, fx_{n}), d(fx_{n}, gy_{n})]}{2s} \end{array} \right\}.$$

In (2.2), on taking limit,

$$\psi\left(\lim_{n\to\infty} d\left(q,gy_n\right)\right) \le F(\psi\left(\lim_{n\to\infty} d\left(q,gy_n\right)\right), \varphi\left(\lim_{n\to\infty} d\left(q,gy_n\right)\right)\right).$$

So,
$$\psi(\lim_{n\to\infty} d(q, gy_n)) = 0$$
, or $\varphi(\lim_{n\to\infty} d(q, gy_n)) = 0$. Thus

$$\lim_{n\to\infty} d\left(q, gy_n\right) = 0.$$

Hence $\lim_{n\to\infty} gy_n = q$.

If T(X) is closed subspace of X, then there exists a $r \in X$, such that Tr = q. By (2.1),

$$(2.3) \qquad \psi\left(d\left(fx_{n},gr\right)\right) \leq F\left(\psi\left(M_{s}\left(x_{n},r\right)\right),\varphi\left(M_{s}\left(x_{n},r\right)\right)\right)$$

where

$$M_{s}(x_{n}, r) = \max \left\{ \begin{array}{ll} d(Sx_{n}, Tr), d(fx_{n}, Sx_{n}), d(Tr, gr), \\ \frac{d(fx_{n}, Tr) + d(Sx_{n}, gr)}{2s} \end{array} \right\}$$

$$= \max \left\{ \begin{array}{ll} d(Sx_{n}, q), d(fx_{n}, Sx_{n}), d(q, gr), \\ \frac{d(fx_{n}, q) + d(Sx_{n}, gr)}{2s} \end{array} \right\}.$$

Letting $n \to \infty$,

$$\lim_{n\to\infty} M_s(x_n, r) = \max \left\{ d(q, q), d(q, q), d(q, gr), \frac{d(q, q) + d(q, gr)}{2s} \right\}$$
$$= d(q, gr).$$

Now, (2.3) and definition of ψ and φ , as $n \to \infty$,

$$\psi(d(q,qr) \leq F(\psi(d(q,qr)), \varphi(d(q,qr)))$$

which implies $\psi(d(q,gr)) = 0$ or $\varphi(d(q,gr)) = 0$ gives gr = q. Thus r is a coincidence point of the pair (g,T). As $g(X) \subseteq S(X)$, there exists a point $z \in X$ such that q = Sz. We claim that Sz = fz. By (2.1), we have

$$(2.4) \qquad \psi(d(fz,qr)) < F(\psi(M_s(z,r)), \varphi(M_s(z,r)))$$

where

$$\begin{split} M_{s}\left(z,r\right) &= \max \left\{ d\left(Sz,Tr\right), d\left(fz,Sz\right), d\left(Tr,gr\right), \frac{d\left(fz,Tr\right) + d\left(Sz,gr\right)}{2s} \right\} \\ &= \max \left\{ d\left(q,q\right), d\left(fz,q\right), d\left(q,q\right), \frac{d\left(fz,q\right) + d\left(q,q\right)}{2s} \right\} \\ &\leq \max \left\{ d\left(fz,q\right), \frac{d\left(fz,q\right)}{2s} \right\} \\ &= d\left(fz,q\right). \end{split}$$

Thus from (2.4).

$$\psi(d(fz,gr)) = \psi(d(fz,q)) \le F(\psi(d(fz,q)), \varphi(d(fz,q)))$$

implies that $\psi(d(fz,q)) = 0$, or $\varphi(d(fz,q)) = 0$. Therefore Sz = fz = q. Hence z is a coincidence point of the pair (f, S). Thus fz = Sz = gr = Tr = q. By weak compatibility of the pairs (f, S) and (g, T), we deduce that fq = Sqand gq = Tq. We will show that q is a common fixed point of f, g, S and T. From (2.1),

$$(2.5) \qquad \psi\left(d\left(fq,q\right)\right) = \psi(d\left(fq,gr\right)) \le F(\psi\left(M_s\left(q,r\right)\right),\varphi\left(M_s\left(q,r\right)\right))$$
 where,

$$\begin{aligned} M_{s}\left(q,r\right) &=& \max \left\{ d\left(Sq,Tr\right), d\left(fq,Sq\right), d\left(Tr,gr\right), \frac{d\left(fq,Tr\right) + d\left(Sq,gr\right)}{2s} \right\} \\ &=& \max \left\{ d\left(fq,q\right), d\left(fq,fq\right), d\left(q,q\right), \frac{d\left(fq,q\right) + d\left(fq,q\right)}{2s} \right\} \\ &=& d\left(fq,q\right). \end{aligned}$$

By (2.5)

$$\psi\left(d\left(fq,q\right)\right) \leq F(\psi(d\left(fq,q\right)), \varphi\left(d\left(fq,q\right)\right)).$$

So fq = Sq = q. Similarly, it can be shown gq = Tq = q.

To prove the uniqueness of the fixed point of f, g, S and T. Suppose for contradiction that p is another fixed point of f, g, S and T. By (2.1), we obtain

$$\psi\left(d\left(q,p\right)\right) = \psi\left(d\left(fq,gp\right)\right) \le F\left(\psi\left(M_s\left(q,p\right)\right),\varphi\left(M_s\left(q,p\right)\right)\right)$$

and

$$M_{s}(q,p) = \max \left\{ d(Sq,Tp), d(fq,Sq), d(Tp,gp), \frac{d(fq,Tp) + d(Sq,gp)}{2s} \right\}$$

$$= \max \left\{ d(q,p), d(q,q), d(p,p), \frac{d(q,p) + d(q,p)}{2s} \right\}$$

$$= d(q,p).$$

Hence we have

$$\psi\left(d\left(q,p\right)\right) \leq F(\psi\left(d\left(q,p\right)\right),\varphi\left(d\left(q,p\right)\right)),$$

which implies that $\psi(d(q, p)) = 0$ or $\varphi(d(q, p)) = 0$. So q = p.

Corollary 2.2. Let (X,d) be a b-metric space and $f,g,S,T:X\to X$ be mappings with $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$ such that

$$d(fx, gy) \leq F(M_s(x, y), \varphi(M_s(x, y))), \text{ for all } x, y \in X,$$

where

$$M_{s}\left(x,y\right)=\max\left\{ d\left(Sx,Ty\right),d\left(fx,Sx\right),d\left(gy,Ty\right),\frac{d\left(fx,Ty\right)+d\left(Sx,gy\right)}{2s}\right\} .$$

Suppose that one of the pairs (f, S) and (g, T) satisfy the b - (E.A)-property and that one of the subspaces f(X), g(X), S(X) and T(X) is closed in X. Then the pairs (f,S) and (g,T) have a point of coincidence in X. Moreover, if the pairs (f,S) and (g,T) are weakly compatible, then f,g,S and T have a unique common fixed point.

Corollary 2.3. Let (X,d) be a b-metric space and $f,T:X\to X$ be mappings such that

$$\psi(d(fx, fy)) \leq F(\psi(M_s(x, y)), \varphi(M_s(x, y))), \text{ for all } x, y \in X,$$

where

$$M_{s}\left(x,y\right)=\max\left\{ d\left(Tx,Ty\right),d\left(fx,Tx\right),d\left(fy,Ty\right),\frac{d\left(fx,Ty\right)+d\left(Tx,fy\right)}{2s}\right\} .$$

Suppose that the pair (f,T) satisfies the b-(E.A)-property and T(X) is closed in X. Then the pair (f,T) has a common point of coincidence in X. Moreover, if the pair (f,T) is weakly compatible, then f and T have a unique common fixed point.

Example 2.4. Let $F(s,t) = \frac{99}{100}s$, X = [0,1] and define $d: X \times X \to [0,\infty)$ as follows

$$d(x,y) = \left\{ \begin{array}{c} 0, x = y \\ (x+y)^2, x \neq y \end{array} \right.$$

Then (X,d) is a b-metric space with constant s=2. Let $f,g,S,T:X\to X$ be defined by

$$f\left(x\right) = \frac{x}{4} , g\left(x\right) = \left\{ \begin{array}{l} 0, x \neq \frac{1}{2} \\ \frac{1}{8}, x = \frac{1}{2} \end{array} \right\}, \quad S\left(x\right) = \left\{ \begin{array}{l} 2x, 0 \leq x < \frac{1}{2} \\ \frac{1}{8}, \frac{1}{2} \leq x \leq 1 \end{array} \right\} \text{ and }$$

$$T\left(x\right) = \left\{ \begin{array}{l} x, 0 \leq x < \frac{1}{2} \\ \frac{1}{2}, \frac{1}{2} < x < 1 \end{array} \right\}.$$

Clearly, f(X) is closed and $f(X) \subseteq T(X)$ and $g(X) \subseteq S(X)$. The sequence $\{x_n\}, x_n = \frac{1}{2} + \frac{1}{n}$, is in X such that $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} Sx_n = \frac{1}{8}$. So that the pair (f, S) satisfies the b - (E.A) -property. But the pair (f, S) is noncompatible for $\lim_{n\to\infty} d(fSx_n, Sfx_n) \neq 0$. The altering functions ψ, φ : $[0,\infty) \to [0,\infty)$ are defined by $\psi(t) = \sqrt{t}$. To check the contractive condition (2.1), for all $x, y \in X$,

if x = 0 or $x = \frac{1}{2}$, then (2.1) is satisfied.

if $x \in (0, \frac{1}{2})$, then

$$\psi\left(d\left(fx,gy\right)\right) = \frac{x}{4} \le \frac{99}{100} \frac{9x}{4} = \frac{99}{100} d\left(fx,Sx\right) \le \frac{99}{100} \psi(M_s\left(x,y\right)).$$
 If $x \in \left(\frac{1}{2},1\right]$, then
$$\psi\left(d\left(fx,gy\right)\right) = \frac{x}{4} \le \frac{99}{100} \left(\frac{x}{4} + \frac{1}{8}\right) = \frac{99}{100} d\left(fx,Sx\right) \le \frac{99}{100} \psi(M_s\left(x,y\right)).$$

Then (2.1) is satisfied for all $x, y \in X$. The pairs (f, S) and (g, T) are weakly compatible. Hence, all of the conditions of Theorem 2.1 are satisfied. Moreover 0 is the unique common fixed point of f, g, S and T.

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