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Publication date: 1997

Link to publication in Tilburg University Research Portal

Citation for published version (APA): Klijn, F., Slikker, M., & Zarzuelo, J. (1997). *Characterizations of a Multi-Choice Value*. (FEW Research Memorandum; Vol. 756). Operations research.

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Characterizations of a Multi-Choice Value¹

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Abstract: A multi-choice game is a generalization of a cooperative game in which each player has several activity levels. This note provides several characterizations of the extended Shapley value as proposed by Derks and Peters (1993). Three characterizations are based on balanced contributions properties, inspired by Myerson (1980).

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Classification Number (J.E.L.): C71
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Keywords: multi-choice games, Shapley value, characterizations, balanced contributions

1 Introduction

Multi-choice games were introduced by Hsiao and Raghavan (1993). A multi-choice game is a cooperative game in which each player has a certain number of activity levels at which he can choose to play. The reward that a group of players can obtain depends on the efforts of the cooperating players.

Hsiao and Raghavan (1993) considered games in which all players have the same number of activity levels. We allow for different numbers of activity levels for different players. Several concepts from TU-games can be extended to the setting of multi-choice games in a straightforward manner. For instance, straightforward extensions of convexity and the core solution have been studied by van den Nouweland *et al.* (1995). For the Shapley value (see Shapley (1953)), however, there exist several more or less natural extensions to the setting of multi-choice games. Here we study the extended Shapley value as proposed by Derks and Peters (1993) and give several characterizations of it.

The work is organized as follows. Section 2 deals with notation, definitions, and the formal description of our model. In section 3 we discuss several extensions of the Shapley value to multi-choice games. In section 4 we present the characterizations of the extended Shapley value as proposed by Derks and Peters (1993).

¹We thank Stef Tijs for his comments and suggestions.

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2 The model

Let $N = \{1, \ldots, n\}$ be a set of players. Suppose each player $i \in N$ has m_i levels at which he can actively participate. Let $m = (m_1, \ldots, m_n)$ be the vector that describes the number of activity levels for every player. We set $M_i := \{0, \ldots, m_i\}$ as the action space of player $i \in N$, where the action 0 means not participating. Let $M := \prod_{i \in N} M_i$ be the product set of the action spaces. A characteristic function is a function $v : M \to \mathbb{R}$ which assigns to each coalition $s = (s_1, \ldots, s_n)$ the worth that the players can obtain when each player *i* plays at activity level $s_i \in M_i$ with v(0) = 0. A multi-choice game is given by a triple (N, m, v). If no confusion can arise a game (N, m, v) will be denoted by its characteristic function v. Let us denote the class of multi-choice games with player set N and activity level vector m by $MC^{N,m}$, and the class of all multi-choice games by MC. Clearly, the class of ordinary TU-games is a subclass of the class of multi-choice games, because a TU-game can be viewed as a multi-choice game in which every player has two activity levels, participate and not participate.

3 Multi-choice values

We will now discuss several solutions on MC that are extensions of the Shapley value. For $i \in N$, let $M_i^+ := M_i \setminus \{0\}$. Further, let $M^+ := \bigcup_{i \in N} (\{i\} \times M_i^+)$. A solution on MC is a map Ψ assigning to each multi-choice game $(N, m, v) \in MC$ an element $\Psi(N, m, v) \in \mathbb{R}^{M^+}$. As is pointed out in van den Nouweland (1993) there exists more than one reasonable extension of the definition of the Shapley value for TU-games to multi-choice games. The first extension of the Shapley value was introduced by Hsiao and Raghavan (1993). They restricted themselves to multi-choice games where all players have the same number of activity levels and defined Shapley values using weights on the actions, thereby extending ideas of weighted Shapley values (cf. Kalai and Samet (1988)). Another extension of the Shapley value as the average of all marginal vectors that correspond to admissible orders for the multi-choice game. Calvo and Santos (1997) study this value and focus on total payoff instead of payoff per level. Here we will consider a third extension, the value as proposed by Derks and Peters (1993). For this, let us start with some additional notation.

The analogue of unanimity games for multi-choice games are minimal effort games $(N, m, u_s) \in MC^{N,m}$, where $s \in \prod_{i \in N} M_i$, defined by

$$u_s(t) := \begin{cases} 1 & \text{if } t_i \ge s_i \text{ for all } i \in N; \\ 0 & \text{otherwise} \end{cases}$$

for all $t \in \prod_{i \in N} M_i$. One can prove that the minimal effort games form a basis of the space $MC^{N,m}$, and that for a multi-choice game (N, m, v) it holds that

$$v = \sum_{s \in \prod_{i \in N} M_i} \Delta_v(s) u_s,$$

where the $\Delta_v(s)$ are the extended dividends defined by

$$\Delta_v(0) := 0$$
 and
 $\Delta_v(s) := v(s) - \sum_{t \le s, t \ne s} \Delta_v(t)$ for $s \ne 0$

Now we can go on to the extension of the Shapley value of Derks and Peters (1993).

For a multi-choice game $(N, m, v) \in MC^{N, m}$ the value $\Theta(N, m, v)$ of Derks and Peters (1993) is given by

$$\Theta_{ij}(N,m,v) := \sum_{s \in \prod_{k \in N} M_k: s_i \ge j} \frac{\Delta_v(s)}{\sum_{k \in N} s_k}$$
(1)

for all $(i, j) \in M^+$. So, the dividend $\Delta_v(s)$ is divided equally among the necessary levels.

In fact, this value can be seen as the vector of marginal contributions of the pairs $(i, j) \in M^+$. Let us point this out formally. For this, we may suppose that $M^+ \neq \emptyset$. An order for a multi-choice game (N, m, v) is a bijection $\sigma : M^+ \to \{1, \ldots, \sum_{i \in N} m_i\}$. The subset $\sigma^{-1}(\{1, \ldots, k\})$ of M^+ , which is present after k steps according to σ , is denoted by $S^{\sigma,k}$. The marginal vector $w^{\sigma} \in \mathbb{R}^{M^+}$ corresponding to σ is defined by

$$w_{ij}^{\sigma} := v\left(\rho(S^{\sigma,\sigma(i,j)})\right) - v\left(\rho(S^{\sigma,\sigma(i,j)-1})\right)$$
(2)

for all $(i, j) \in M^+$. Here ρ is the map that assigns to every subset $S \subseteq M^+$ the maximal feasible coalition $\rho(S)$ that is a 'subset' of S. Formally, for $S \subseteq M^+$,

$$\rho(S) := (t_1, \ldots, t_n),$$

where

$$t_i = \begin{cases} \max\{k \in M_i^+ : (i, 1), \dots, (i, k) \in S\} & \text{if } (i, 1) \in S; \\ 0 & \text{otherwise.} \end{cases}$$

Now, define

$$\Lambda_{ij}(N,m,v) := \frac{1}{(\sum_{k \in N} m_k)!} \sum_{\sigma} w_{ij}^{\sigma}$$
(3)

for all $(i, j) \in M^+$. The number $\Lambda_{ij}(N, m, v)$ is the marginal contribution of the pair $(i, j) \in M^+$ to the maximal feasible coalition. In fact, the number $\Lambda_{ij}(N, m, v)$ is equal to the Shapley payoff of player (i, j) in the ordinary TU-game (M^+, \bar{v}) , where the characteristic function \bar{v} is defined by

$$\bar{v}(T) := v(\rho(T)) \quad \text{ for all } T \subseteq M^+.$$

One can prove that a multi-choice game (N, m, v) is convex³ if and only if the TU-game (M^+, \bar{v}) is convex.

³A multi-choice game (N, m, v) is said to be convex if $v(s \lor t) + v(s \land t) \ge v(s) + v(t)$ for all $s, t \in \prod_{k \in N} M_k$, where $(s \land t)_i := \min\{s_i, t_i\}$ and $(s \lor t)_i := \max\{s_i, t_i\}$ for all $i \in N$. For ordinary TU-games this definition is equivalent to the usual one.

It is not difficult to see that for a minimal effort game (N, m, u_s) we have

$$\Theta_{ij}(N,m,u_s) = \Lambda_{ij}(N,m,u_s) = \begin{cases} \frac{1}{\sum_{k \in N} s_k} & \text{if } j \le s_i; \\ 0 & \text{otherwise} \end{cases}$$
(4)

for all $(i, j) \in M^+$. From this and the linearity of both Λ and Θ it follows that $\Lambda = \Theta$.

The following example shows that in some situations the extension of the Shapley value by Derks and Peters (1993) seems to be more appropriate than the extension of the Shapley value by van den Nouweland *et al.* (1995). Further, it illustrates why the players may be interested in the payoff for each level, not solely the sum of their levels, which is the case in Calvo and Santos (1997).

Example 3.1 Consider the following cost allocation problem related to airlines. Suppose there is an airline with several divisions, where each division has available a finite number of sizes of planes. Suppose further that each division has to perform a flight schedule, and therefore has to decide which sizes of planes it will use. Then the airline builds the smallest runway that suffices for the largest planes chosen by the divisions. The costs depend on the length of the runway. The question now arises how to allocate the forthcoming costs among the divisions.

For example, consider the situation of an airline with two divisions, a passenger division (division 1) and a cargo division (division 2). Suppose further that the company possesses small planes and large planes. The small planes need a runway of length 1 and are suitable for passengers as well as for cargo. The large planes need a runway of length 2 and can only carry cargo. Suppose also that the costs of a runway of length l (l = 1, 2) are l. To solve the problem, we model this situation as a multi-choice game and consider the multi-choice values.

We model this situation as a multi-choice game as follows. Let $N = \{1, 2\}$ be the set of players, i.e. the divisions. Let m = (1, 2) be the activity levels from which the players can choose, i.e. the sizes of the available planes. Now, the game (N, m, c), where c is the cost function defined by $c := u_{(0,1)} + u_{(1,0)} - u_{(1,1)} + u_{(0,2)}$, models the situation above.

The value of Derks and Peters (1993) gives $\Theta_{1,1}(N,m,c) = \frac{1}{2}$, $\Theta_{2,1}(N,m,c) = 1$, and $\Theta_{2,2}(N,m,u_s) = \frac{1}{2}$, while the value Γ of van den Nouweland *et al.* (1995) gives $\Gamma_{1,1}(N,m,c) = \frac{1}{3}$, $\Gamma_{2,1}(N,m,c) = \frac{2}{3}$, and $\Gamma_{2,2}(N,m,c) = 1$.

Now suppose that instead of modeling that division 1 has no possibility to use larger planes, we model the situation by allowing it to use 0 large planes. So, if they use all their large planes there will be no effect on the costs. Formally, the cost function c remains unchanged, but the vector of activity levels changes to m' = (2, 2). Some calculations yield $\Theta_{1,1}(N, m', c) = \Gamma_{1,1}(N, m', c) = \frac{1}{2}, \Theta_{1,2}(N, m', c) = \Gamma_{1,2}(N, m', c) = 0, \Theta_{2,1}(N, m', c) =$ $\Gamma_{2,1}(N, m', c) = 1$, and $\Theta_{2,2}(N, m', c) = \Gamma_{2,2}(N, m', c) = \frac{1}{2}$. We see that the value of van den Nouweland *et al.* (1995) has a serious drawback in this example, since division 1 has to pay for being allowed to choose larger planes, although it does not use these planes.

Finally, note that the determination of costs per plane size can be an aid in cost allocation within the divisions. \diamond

4 Characterizations

In this section we recall one characterization of the extended Shapley value by Derks and Peters (1993), and provide four other characterizations. Therefore, consider the following properties of solutions on MC. A solution Ψ on MC satisfies

• efficiency (EFF) if for all games $(N, m, v) \in MC$:

$$\sum_{i\in\mathbb{N}}\sum_{j=1}^{m_i}\Psi_{ij}(N,m,v)=v(m).$$

• strong monotonicity (SMON) if for all games (N, m, v) and $(N, m, w) \in MC$, whenever $(i, j) \in M^+$ is such that for all $s \in \prod_{k \in N} M_k$ with $s_i = j$

$$v(s) - v(t) \ge w(s) - w(t),$$

where $t \in \prod_{k \in N} M_k$ is such that $t_k = s_k$ if $k \neq i$ and $t_i = s_i - 1$, then

$$\Psi_{ij}(N,m,v) \ge \Psi_{ij}(N,m,w)$$

• the veto property (VETO) if for all games $(N, m, v) \in MC$, and all $i_1, i_2 \in N$, whenever $j_1 \in M_{i_1}^+$, and $j_2 \in M_{i_2}^+$ are veto levels, then

$$\Psi_{i_1 j_1}(N, m, v) = \Psi_{i_2 j_2}(N, m, v).$$

Here, $j \in M_i^+$ is a veto level if v(s) = 0 for all $s \in \prod_{k \in N} M_k$ with $s_i < j$.

Property (SMON) says that if for two games (N, m, v) and $(N, m, w) \in MC$ and a player $i \in N$ it holds that the marginal contribution of level $j \in M_i^+$ in the game (N, m, v) is not smaller than the marginal contribution in the game (N, m, w), then the payoff to level $j \in M_i^+$ in the game (N, m, v) is not smaller than the payoff in the game (N, m, w). Property (VETO) says that for a game $(N, m, v) \in MC$ the payoffs to all players $i \in N$ and levels $j \in M_i^+$ that have veto power (i.e. a level of player *i* less than *j* yields worth 0, independent of the levels of the other players) should be equal. The following theorem can be found in van den Nouweland (1993).

Theorem 4.1 A solution Ψ satisfies (EFF), (SMON), and (VETO) if and only if $\Psi = \Theta$.

Inspired by theorem 4.1 we will provide a characterization of Θ using the following properties. A solution Ψ on MC satisfies

• additivity (ADD) if for all games $(N, m, v), (N, m, w) \in MC$:

$$\Psi(N,m,v+w) = \Psi(N,m,v) + \Psi(N,m,w).$$

• the dummy property (DUM) if for all games $(N, m, v) \in MC$, and all $i \in N$, whenever $j \in M_i^+$ is a dummy level, then

$$\Psi_{ij}(N,m,v) = 0.$$

Here, $j \in M_i^+$ is a dummy level if $v(s_{-i}, j-1) = v(s_{-i}, l)$ for all $s_{-i} \in \prod_{k \in N \setminus \{i\}} M_k$ and all $j \leq l \leq m_i$.

Next, we prove that by replacing the property (SMON) in theorem 4.1 with (ADD) and (DUM) we get another characterization. It is readily verified that (SMON) does not imply (ADD) nor (DUM), and that (ADD) and (DUM) do not imply (SMON).

Theorem 4.2 A solution Ψ satisfies (EFF), (ADD), (VETO), and (DUM) if and only if $\Psi = \Theta$.

Proof. First we prove that Θ satisfies the properties. Note that (EFF) and (VETO) follow from theorem 4.1. Property (ADD) follows readily from (1). Finally, Θ satisfies (DUM) as is easily seen with formulas (2) and (3).

To prove uniqueness, we note that, by additivity, it is sufficient to show that Ψ and Θ coincide on the class of minimal effort games. Let (N, m, u_s) be a minimal effort game. Let $i \in N$. Every level $k_i \in M_i^+$ with $k_i > s_i$ is a dummy level, and therefore, by (DUM), we have $\Psi_{ik_i}(N, m, u_s) = 0$. All other levels $k_i \in M_i^+$ are veto levels. Then, by (VETO), we have

$$\Psi_{ik_i}(N, m, u_s) = c \quad \forall (i, k_i) \in M^+, k_i \le s_i$$

for some constant $c \in \mathbb{R}$. By (EFF), $c = \frac{1}{\sum_{k \in N} s_k}$. Now formula (4) gives $\Psi_{ij}(N, m, u_s) = \Theta_{ij}(N, m, u_s)$ for all $(i, j) \in M^+$, which proves the theorem. \Box

In the next theorem we present the first of our series of three axiomatic characterizations of the extended Shapley value based on balanced contributions properties. For $i \in N$, let e^i be the *i*-th unit vector in \mathbb{R}^n . A solution Ψ on MC satisfies⁴

• the equal loss property (EL) if for all games $(N, m, v) \in MC$, all $(i, k) \in M^+$, $k \neq m_i$:

$$\Psi_{ik}(N, m, v) - \Psi_{ik}(N, m - e^{i}, v) = \Psi_{im_{i}}(N, m, v).$$

• the upper balanced contributions property (UBC) if for all games $(N, m, v) \in MC$, and all $(i, m_i), (j, m_j) \in M^+, i \neq j$:

$$\Psi_{im_i}(N, m, v) - \Psi_{im_i}(N, m - e^j, v) = \Psi_{jm_j}(N, m, v) - \Psi_{jm_j}(N, m - e^i, v).$$

⁴With a slight abuse of notation we write (N, m', v) for the restriction of the game (N, m, v) to the activity levels $m' \in M$.

The equal loss property and the upper balanced contributions property are inspired by the balanced contributions property of Myerson (1980). Property (EL) says that whenever a player gets available a higher activity level the payoff for all original levels changes with an amount equal to the payoff for the highest level in the new situation. Property (UBC) says that for every pair i, j of different players the change in payoff for the highest level of player i when player j gets available a higher activity level is equal to the change in payoff for the highest level of player i when player j when player j when player i gets available a higher activity level.

Theorem 4.3 A solution Ψ satisfies (EFF), (EL), and (UBC) if and only if $\Psi = \Theta$.

Proof. First we prove that Θ satisfies the properties. By linearity of Θ and theorem 4.1 it is sufficient to prove that all minimal effort games satisfy (EL) and (UBC). Let (N, m, u_s) be a minimal effort game.

(EL) Let $(i, k) \in M^+$. Then

$$\Theta_{ik}(N, m, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } k \leq s_i; \\ 0 & \text{if } k > s_i, \text{ and} \end{cases}$$
$$\Theta_{ik}(N, m - e^i, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } k \leq s_i < m_i; \\ 0 & \text{if } m_i = s_i \text{ or } s_i < k \end{cases}$$

Now one easily verifies that Θ indeed satisfies the equalities of (EL). (UBC) Let $(i, m_i), (j, m_j) \in M^+, i \neq j$. Then

$$\Theta_{im_i}(N, m, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } m_i = s_i; \\ 0 & \text{if } m_i > s_i, \text{ and} \end{cases}$$
$$\Theta_{im_i}(N, m - e^j, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } m_j > s_j; \\ 0 & \text{if } m_j = s_j. \end{cases}$$

Similar expressions hold when we interchange i and j. Again, one can check that Θ satisfies the equalities of (UBC).

To prove uniqueness, suppose there are two solutions, denoted Φ and Ψ , that satisfy (EFF), (EL), and (UBC). We will prove that $\Phi = \Psi$. The proof is with induction on the total number of levels $\sum_{k \in N} m_k$. It is clear that for all multi-choice games (N, m, v) with $\sum_{k \in N} m_k = 0$ we have $\Phi(N, m, v) = \Psi(N, m, v)$. Assume that for some $p \in \mathbb{R}$ and for all multi-choice games (N, m, v) with $\sum_{k \in N} m_k = p-1$ it holds that $\Phi(N, m, v) = \Psi(N, m, v)$. We will prove that Φ and Ψ coincide on the class of multi-choice games (N, m, v) with $\sum_{k \in N} m_k = p$. Let (N, m, v) be a multi-choice game with $\sum_{k \in N} m_k = p$. Then, by (EL) and the induction hypothesis, we have for all $(i, k) \in M^+$, $k \neq m_i$ that

$$\Phi_{ik}(N,m,v) - \Phi_{im_i}(N,m,v) = \Phi_{ik}(N,m-e^i,v) = = \Psi_{ik}(N,m-e^i,v) = \Psi_{ik}(N,m,v) - \Psi_{im_i}(N,m,v).$$

So,

$$\Phi_{ik}(N,m,v) - \Psi_{ik}(N,m,v) = \Phi_{im_i}(N,m,v) - \Psi_{im_i}(N,m,v) \quad \forall (i,k) \in M^+.$$
(5)

Furthermore, by (UBC) and the induction hypothesis, we have for all $(i, m_i), (j, m_j) \in M^+, i \neq j$ that

$$\begin{split} \Phi_{im_i}(N,m,v) - \Phi_{jm_j}(N,m,v) &= \Phi_{im_i}(N,m-e^j,v) - \Phi_{jm_j}(N,m-e^i,v) = \\ &= \Psi_{im_i}(N,m-e^j,v) - \Psi_{jm_j}(N,m-e^i,v) = \\ &= \Psi_{im_i}(N,m,v) - \Psi_{jm_j}(N,m,v). \end{split}$$

So,

 $\Phi_{im_i}(N, m, v) - \Psi_{im_i}(N, m, v) = \Phi_{jm_j}(N, m, v) - \Psi_{jm_j}(N, m, v) \quad \forall (i, m_i), (j, m_j) \in M^+.$ (6)

Combining (5) and (6) yields

$$\Phi_{ik}(N,m,v) - \Psi_{ik}(N,m,v) = c \quad \forall (i,k) \in M^+,$$

for some constant $c \in \mathbb{R}$. Finally, (EFF) gives c = 0, implying that $\Phi(N, m, v) = \Psi(N, m, v)$. \Box

We say that a solution Ψ on MC satisfies

• the lower balanced contributions property (LBC) if for all games $(N, m, v) \in MC$, and all $(i, 1), (j, 1) \in M^+, i \neq j$:

$$\Psi_{i1}(N,m,v) - \Psi_{i1}(N,m-m_j e^j,v) = \Psi_{j1}(N,m,v) - \Psi_{j1}(N,m-m_i e^i,v).$$

One can characterize the Shapley value by replacing property (UBC) with (LBC) in theorem 4.3. The proof of the characterization using (LBC) is similar to that of the characterization using (UBC), and is therefore omitted.

Theorem 4.4 A solution Ψ satisfies (EFF), (EL), and (LBC) if and only if $\Psi = \Theta$.

Consider the following two properties for a solution Ψ on MC.

• the general balanced contributions property (GBC): for all games $(N, m, v) \in MC$, and all $(i, k_i), (j, k_j) \in M^+, i \neq j$:

$$\Psi_{ik_i}(N,m,v) - \Psi_{ik_i}(N,m - (m_j - k_j + 1)e^j, v) = \Psi_{jk_j}(N,m,v) - \Psi_{jk_j}(N,m - (m_i - k_i + 1)e^i, v).$$

• the zero game property (ZGP): for all games $(N, m, v) \in MC$ with v(s) = 0 for all $s \in \prod_{i \in N} M_i$, and $(i, k) \in M^+$:

$$\Psi_{ik}(N,m,v) = 0.$$

Property (GBC) is a generalization of (UBC) and (LBC): if we take $k_i = m_i$ and $k_j = m_j$ in (GBC) we get (UBC), if we take $k_i = k_j = 1$ in (GBC) we get (LBC). Property (ZGP) is a natural and very weak axiom.

In the next theorem we provide a third balanced contribution characterization of the extended Shapley value by replacing (EL) and (LBC) with (ZGP) and (GBC) in theorem 4.4. For this, we restrict ourselves to solutions on the subclass of multi-choice games (N, m, v) for which it holds that whenever $v(s) \neq 0$, there are two players $i, j \in N, i \neq j$ with $s_i, s_j > 0$. Let us denote this subclass by MC^* . Note that for a TU-game (N, v) the condition above boils down to (N, v) being 0-normalized, i.e. v(i) = 0 for all players $i \in N$.

Theorem 4.5 A solution Ψ on MC^* satisfies the properties⁵ (EFF), (ZGP), and (GBC) if and only if Ψ coincides with Θ on MC^* .

Proof. First we prove that Θ satisfies (GBC). By linearity of Θ it is sufficient to prove that all minimal effort games satisfy (GBC). Let (N, m, u_s) be a minimal effort game. Let $(i, k_i), (j, k_j) \in M^+, i \neq j$. Then

$$\Theta_{ik_i}(N, m, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } k_i \leq s_i; \\ 0 & \text{if } k_i > s_i, \text{ and} \end{cases}$$
$$\Theta_{ik_i}(N, m - (m_j - k_j + 1)e^j, u_s) = \begin{cases} \frac{1}{\sum_{l \in N} s_l} & \text{if } k_i \leq s_i \text{ and } k_j > s_j; \\ 0 & \text{otherwise.} \end{cases}$$

Similar expressions hold when we interchange i and j. From this it follows that Θ indeed satisfies (GBC). Further, one easily verifies that if v(s) = 0 for all $s \in \prod_{i \in N} M_i$, then $\Delta_v(s) = 0$ for all $s \in \prod_{i \in N} M_i$. Then, by definition of Θ , $\Theta_{ik}(N, m, v) = 0$ for all $(i, k) \in M^+$. Hence, Θ satisfies (ZGP). From theorem 4.1 it follows that Θ satisfies (EFF). Hence, Θ satisfies the properties.

To prove uniqueness, suppose that there are two solutions, denoted Φ and Ψ , that satisfy (EFF), (ZGP), and (GBC). We will prove that $\Phi = \Psi$. The proof is with induction on the total number of levels $\sum_{k \in N} m_k$. It is clear that for all multi-choice games $(N, m, v) \in MC^*$ with $\sum_{k \in N} m_k = 0$ we have $\Phi(N, m, v) = \Psi(N, m, v)$. Assume that for some $p \ge 1$ and all multi-choice games $(N, m, v) \in MC^*$ with $\sum_{k \in N} m_k \le p - 1$ it holds that $\Phi(N, m, v) = \Psi(N, m, v)$. We will prove that Φ and Psi also coincide on the class of multi-choice games $(N, m, v) \in MC^*$ with $\sum_{k \in N} m_k = p$. Let $(N, m, v) \in MC^*$ be a multi-choice game with $\sum_{k \in N} m_k = p$. By (GBC) and the induction hypothesis, we have for all $(i, k_i), (j, k_j) \in M^+, i \ne j$ that

$$\begin{aligned} \Phi_{ik_i}(N,m,v) &- \Phi_{jk_j}(N,m,v) = \\ &= \Phi_{ik_i}(N,m-(m_j-k_j+1)e^j,v) - \Phi_{jk_j}(N,m-(m_i-k_i+1)e^i,v) = \\ &= \Psi_{ik_i}(N,m-(m_j-k_j+1)e^j,v) - \Psi_{jk_j}(N,m-(m_i-k_i+1)e^i,v) = \\ &= \Psi_{ik_i}(N,m,v) - \Psi_{jk_j}(N,m,v), \end{aligned}$$

⁵Of course, here we also restrict the properties to the subclass MC^* .

So,

$$\Phi_{ik_i}(N, m, v) - \Psi_{ik_i}(N, m, v) = \Phi_{jk_j}(N, m, v) - \Psi_{jk_j}(N, m, v)
\forall (i, k_i), (j, k_j) \in M^+, i \neq j$$
(7)

Let $(i, m_i) \in M^+$. If there is an agent $j \neq i$ with $(j, m_j) \in M^+$, then it follows from (7) that for all $k, l \in M_i^+$

$$\Phi_{ik}(N,m,v) - \Psi_{ik}(N,m,v) = \Phi_{j1}(N,m,v) - \Psi_{j1}(N,m,v) = = \Phi_{il}(N,m,v) - \Psi_{il}(N,m,v).$$

If there is not an agent $j \neq i$ with $(j, m_j) \in M^+$, then it follows from (ZGP) and the fact that $(N, m, v) \in MC^*$ that for all $k \in M_i^+$

$$\Phi_{ik}(N,m,v) = 0 = \Psi_{ik}(N,m,v).$$

Hence, in both cases we have that for all $k,l\in M_i^+$

$$\Phi_{ik}(N, m, v) - \Psi_{ik}(N, m, v) = \Phi_{il}(N, m, v) - \Psi_{il}(N, m, v).$$

Together with (7) this gives

$$\Phi_{ik}(N,m,v) - \Psi_{ik}(N,m,v) = c \quad \forall (i,k) \in M^+,$$

for some constant $c \in \mathbb{R}$. Finally, (EFF) gives c = 0, implying that $\Phi(N, m, v) = \Psi(N, m, v)$. \Box

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