

## Annex: Llistats

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# 1. Elelelin.m

```
%[q,qos,K,state_new,ok]=elelelin(d,ele,state)
%Total Interaction Nonlinear Sectional Analysis
%Sectional Linear Element
%By: J. M. Bairan
%under development at UPC
%
%Input description:
%*****
%d: degrees of freedom d=[ksia;df];
%ele: element's description structure
%*.ra: nodal coordinates with respect to the beam's reference axis
%*.Abar: area of a bar
%*.Sx: bar spacing
%*.theta: inclination angle of bars on the plane x-s, with angle=0
% meaning bars parallel to the element's line, and pi/2 bars parallel to x.
%*.mat: structure of material's properties
%*.mat.name: material id. name
%*.mat.fname: name of the constitutive equation
%*.mat.prop: material properties

%state: state of the element:
%*.Ag: elements gross area
%*.W: internal work of the element
%*.xgm: 1st area moment of shear strains.
%*.mat: material's state structure at each gauss-point (vector)
%(depends on the material's constitutive model)
%
%Output description:
%*****
%q:vector of generalized stresses corresponding to ksia and warp
%q=[qksia,qw].
%qos: fictitious force vector corresponding to elastic prestrains, follows
%the same structure as q.
%K: stiffness matrix relating q and d [ksia;df]X[ksia;df]
%state_new: new element state (follows same structure as state)
%ok: 1 good result, 0 bad result
%

function [q,qos,K,state_new,ok]=elelelin(d,ele,state)
ok=0;
%check to initialize state
if ~isfield(state,'Ag'); state=setfield(state,'Ag',0); end;
if ~isfield(state,'Bem'); state=setfield(state,'Bem',0); end;
if ~isfield(state,'W'); state=setfield(state,'W',0); end;
if ~isfield(state,'xgm'); state=setfield(state,'xgm',0); end;
if ~isfield(state,'V'); state=setfield(state,'V',0); end;
if ~isfield(state,'mat'); state=setfield(state,'mat',cell(1,1)); end;
if ~isfield(state,'RME'); state=setfield(state,'RME',0); end;

%initialize
ngl=size(d,1);
ksia=d(1:8);
df=d(9:ngl);
intAg=0; if state.Ag==0; intAg=1; end
MX=[1,0,0,0,0,0;
    0,0,0,0,0,0;
    0,0,0,0,0,0];
qw1=0;qk=0;Kww=0;Kwk=0;Kkk=0;
qwos=0;qkos=0;
qw2=0;
Qwk=0;
RME=0;

%Gauss-Legendre Integration parameters
npg=1;
ZI=[0]; WI=[1];
Iksi=[1];
```

```
state_new.W=0;
state_new.xgm=0;
state_new.V=0;

%Loop over all Gauss-Points
for ipg=1:npg
    ksi=ZI(Iksi(ipg));

    %material principal direction: transformation matrixes
    slong=norm(ele.ra(:,2)-ele.ra(:,1),2);
    ey=(ele.ra(1,2)-ele.ra(1,1))/slong;
    ez=(ele.ra(2,2)-ele.ra(2,1))/slong;
    l=sin(ele.thetha); %x directional cosine with of principal direction
    m=cos(ele.thetha)*ey; %y directional cosine with of principal direction
    n=cos(ele.thetha)*ez; %z directional cosine with of principal direction
    t=[l;m;n];
    T=[t',zeros(1,3);zeros(1,3),t']; %vector transformation matrix (from global to local)
    ne=[l^2,m^2,n^2,1*m,n*1,m*n]; %transformation vector from global coordinates (strain
tensor) to principal direction (scalar)
    ns=[l^2,m^2,n^2,2*1*m,2*n*1,2*m*n]; %transformation vector from global coordinates (stress
tensor) to principal direction (scalar)

    %Equivalent J determinant
    detJ=slong*ele.Abar/ele.Sx;

    %Shape functions and derivatives in Gauss-Point:
    Nke=0.5*[1-ksi,(1+ksi)];

    %Interpolation matrixes for displacements and quantities (scalar)
    Nf=[Nke(1)*eye(3,3),Nke(2)*eye(3,3)];
    %Interpolation matrix for derivative along s (in plane projection of the bar) (scalar)
    dNs=1/slong*[-1,1];
    %Interpolation matrix for derivatives along Y and Z
    if ey==0; dNy=zeros(1,2); else; dNy=1/ey*dNs; end;
    if ez==0; dNz=zeros(1,2); else; dNz=1/ez*dNs; end;

    %physical location of gauss point
    Y=Nke*ele.ra(1,:);
    Z=Nke*ele.ra(2,:);

    %strains interpolation matrixes
    %plain global section:
    Npsa=[1,0,Z,-Y;zeros(2,4);0,-Z,0,0;0,Y,0,0;zeros(1,4)];
    %warping strains:
    Bf1=[0,0,0,0,dNy(1),0;0,0,dNz(1);dNy(1),0,0;dNz(1),0,0;0,dNz(1),dNy(1)];
    Bf2=[0,0,0,0,dNy(2),0;0,0,dNz(2);dNy(2),0,0;dNz(2),0,0;0,dNz(2),dNy(2)];
    Bf=[Bf1,Bf2];

    %
    %strains:
    eps=Npsa*ksia(1:4); %plane section strains
    deps=Npsa*ksia(5:8); %derivatives of plane section strains
    ew=Bf*df; %warp-distortion strains
    e=(eps+ew); %total strain
    eL=ne*e; %total strain on local direction

    %stresses:
    [sL,sosL,eL,DL,state_new.mat(ipg),ok]=feval(ele.mat.fname,eL,ele.mat.prop,state.mat(ipg));
    %component on global directions
    s=ne'*sL;
    sos=ne'*sosL;
    D=ne'*DL*ne;

    %derivative of the traction vector normal to the cross-section (on global direction):
    ds=D*deps;
    txp=MX*ds;

    %integrations:
    %gross area and mean strains matrix
    if intAg==1
        state.Ag=state.Ag+WI(Iksi(ipg))*detJ;
        state.Bem=state.Bem+[Npsa,zeros(6,4),Bf]*WI(Iksi(ipg))*detJ;
    end
end
```

```
end
%work:
state_new.W=state_new.W+state_new.mat{ipg}.W*(WI(Iksi(ipg))*detJ);
%shear strains 1st moment of area
state_new.xgm=state_new.xgm+e(4:5)*(WI(Iksi(ipg))*detJ);
%shear force
state_new.V=state_new.V+s(4:5)*(WI(Iksi(ipg))*detJ);

%Internal forces:
%warp-distortion problem
qw2=qw2+(Nf'*txp)*(WI(Iksi(ipg))*WI(Iksi(ipg))*detJ);
qw1=qw1+(Bf'*s)*(WI(Iksi(ipg))*WI(Iksi(ipg))*detJ);
qwos=qwos+(Bf'*sos)*(WI(Iksi(ipg))*WI(Iksi(ipg))*detJ);

%generalized forces equilibrium
qk=qk+([Npsa', zeros(4,6); zeros(4,6), Npsa'*MX'*MX]*[s;ds])*(WI(Iksi(ipg))*detJ);
qkos=qkos+([Npsa', zeros(4,6); zeros(4,6), Npsa'*MX'*MX]*[sos; zeros(6,1)])*(WI(Iksi(ipg))*detJ);

%stiffness:
%warp-distortion problem
Kww=Kww+(Bf'*D*Bf)*(WI(Iksi(ipg))*detJ);
Kwk=Kwk+([Bf'*D*Npsa, zeros(ngl-8,4)]*(WI(Iksi(ipg))*detJ));
Qwk=Qwk+([zeros(ngl-8,4), Nf'*MX*D*Npsa]*(WI(Iksi(ipg))*detJ));
%generalized forces equilibrium
%Kkw=Kkw+([Npsa'*D*Bf; -Npsa'*D*MX'*Nf]*(WI(Iksi(ipg))*detJ));
Kkw=Kkw+([Npsa'*D*Bf; zeros(4, ngl-8)]*(WI(Iksi(ipg))*detJ));
Kkk=Kkk+([Npsa'*D*Npsa, zeros(4,4); zeros(4,4), Npsa'*D*Npsa]*(WI(Iksi(ipg))*detJ);

%Rigid movement matrix
C=[1,0,0;
    0,1,0;
    0,0,1;
    0,-Z,Y];

RME=RME+WI(Iksi(ipg))*C*Nf*detJ;

end

q=[qk;qw1];
qos=[qkos;qwos];

state_new.Ag=state.Ag;
state_new.Bem=state.Bem;
state_new.RME=RME;
state_new.qw2=qw2;
state_new.Qwk=Qwk;

K=[Kkk, Kkw; Kwk, Kww];
ok=1;
return
```

## 2. Elelelin2.m

```
 %[q,qos,K,state_new,ok]=elelelin2(d,ele,state)
%Total Interaction Nonlinear Sectional Analysis
%Sectional Linear Element
%By: J. M. Bairan
%under development at UPC
%
%Input description:
%*****
%d: degrees of freedom d=[ksia;df];
%ele: element's description structure
%*.ra: nodal coordinates with respect to the beam's reference axis
%*.Abar: row containing the areas of the bars
%*.Sx: row containing bar spacements
```

```

%*.thetha: row containing inclination angles of the bars on the plane x-s,
%  with angle=0 meaning bars parallel to the element's line, and pi/2 bars
%  parallel to x.
%*.mat: structure of material's properties
%*.mat.name: material id. name
%*.mat.fname: name of the constitutive equation
%*.mat.prop: material properties

%state: state of the element:
%*.Ag: elements gross area
%*.W: internal work of the element
%*.xgm: 1st area moment of shear strains.
%*.mat: material's state structure at each gauss-point (vector)
%(depends on the material's constitutive model)
%
%Output description:
%*****
%q:vector of generalized stresses corresponding to ksia and warp
%q=[qksia,qw].
%qos: fictitious force vector corresponding to elastic prestrains, follows
%the same structure as q.
%K: stiffness matrix relating q and d [ksia;df]X[ksia;df]
%state_new: new element state (follows same structure as state)
%ok: 1 good result, 0 bad result
%

function [q,qos,K,state_new,ok]=elelin2(d,ele,state)
ok=0;
%check to initialize state
if ~isfield(state,'Ag'); state=setfield(state,'Ag',0); end;
if ~isfield(state,'Bem'); state=setfield(state,'Bem',0); end;
if ~isfield(state,'W'); state=setfield(state,'W',0); end;
if ~isfield(state,'xgm'); state=setfield(state,'xgm',0); end;
if ~isfield(state,'V'); state=setfield(state,'V',0); end;
if ~isfield(state,'mat'); state=setfield(state,'mat',cell(1,2)); end;
if ~isfield(state,'RME'); state=setfield(state,'RME',0); end;

%initialize
ngl=size(d,1);
ksia=d(1:8);
df=d(9:ngl);
intAg=0; if state.Ag==0; intAg=1; end
MX=[1,0,0,0,0,0;
    0,0,0,0,0,0;
    0,0,0,0,0,0];
RME=0;
qw1=0;qk=0;Kww=0;Kwk=0;Kkw=0;Kkk=0;
qwos=0;qkos=0;
qw2=0;
Qwk=0;
nbar=length(ele.thetha);
q=[]; qos=[]; K=[]; state_new=[];

%Gauss-Legendre Integration parameters
npg=1;
ZI=[0]; WI=[1];
Iksi=[1];

state_new.W=0;
state_new.xgm=0;
state_new.V=0;

%Loop over all bars
for ibar=1:nbar
%Loop over all Gauss-Points
for ipg=1:npg

    ksi=ZI(Iksi(ipg));

    %material principal direction: transformation matrixes
    slong=norm(ele.ra(:,2)-ele.ra(:,1),2);
    ey=(ele.ra(1,2)-ele.ra(1,1))/slong;

```

```

ez=(ele.ra(2,2)-ele.ra(2,1))/slong;
l=sin(ele.thetha(ibar)); %x directional cosine with of principal direction
m=cos(ele.thetha(ibar))*ey; %y directional cosine with of principal direction
n=cos(ele.thetha(ibar))*ez; %z directional cosine with of principal direction
t=[l;m;n];
T=[t',zeros(1,3);zeros(1,3),t']; %vector transformation matrix (from global to local)
ne=[l^2,m^2,n^2,l*m,n*1,m*n]; %transformation vector from global coordinates (strain
tensor) to principal direction (scalar)
ns=[l^2,m^2,n^2,2*l*m,2*n*1,2*m*n]; %transformation vector from global coordinates (stress
tensor) to principal direction (scalar)

%Equivalent J determinant
detJ=slong*ele.Abar(ibar)/ele.Sx(ibar);

%Shape functions and derivatives in Gauss-Point:
Nke=0.5*[(1-ksi),(1+ksi)];

%Interpolation matrixes for displacements and quantities (scalar)
Nf=[Nke(1)*eye(3,3),Nke(2)*eye(3,3)];
%Interpolation matrix for derivative along s (in plane projection of the bar) (scalar)
dNs=1/slong*[-1,1];
%Interpolation matrix for derivatives along Y and Z
if ey==0; dNy=zeros(1,2); else; dNy=1/ey*dNs; end;
if ez==0; dNz=zeros(1,2); else; dNz=1/ez*dNs; end;

%physical location of gauss point
Y=Nke*ele.ra(1,:);
Z=Nke*ele.ra(2,:);

%strains interpolation matrixes
%plain global section:
Npsa=[1,0,Z,-Y;zeros(2,4);0,-Z,0,0;0,Y,0,0;zeros(1,4)];

%warping strains:
Bf1=[0,0,0,0,dNy(1),0;0,0,dNz(1);dNy(1),0,0;dNz(1),0,0,0,dNz(1),dNy(1)];
Bf2=[0,0,0,0,dNy(2),0;0,0,dNz(2);dNy(2),0,0;dNz(2),0,0,0,dNz(2),dNy(2)];
Bf=[Bf1,Bf2];

%
%strains:
eps=Npsa*ksia(1:4); %plane section strains
deps=Npsa*ksia(5:8); %derivatives of plane section strains
ew=Bf*df; %warp-distortion strains
e=(eps+ew); %total strain
eL=ne*e; %total strain on local direction

%stresses:
[sL,sosL,eL,DL,state_new.mat{ibar},ok]=feval(ele.mat.fname,eL,ele.mat.prop,state.mat{ibar});
%component on global directions
s=ne'*sL;
sos=ne'*sosL;
D=ne'*DL*ne;

%derivative of the traction vector normal to the cross-section (on global direction):
ds=D*deps;
txp=MX*ds;

%integrations:
%gross area and mean strains matrix
if intAg==1
    state.Ag=state.Ag+WI(Iksi(ipg))*detJ;
    state.Bem=state.Bem+[Npsa,zeros(6,4),Bf]*WI(Iksi(ipg))*detJ;
end
%work:
state_new.W=state_new.W+state_new.mat{ipg}.W*(WI(Iksi(ipg))*detJ);
%shear strains 1st momemt of area
state_new.xgm=state_new.xgm+e(4:5)*(WI(Iksi(ipg))*detJ);
%shear force
state_new.V=state_new.V+s(4:5)*(WI(Iksi(ipg))*detJ);

```

```
%Internal forces:
%warp-distortion problem
qw2=qw2+(Nf'*txp)*(WI(Iksi(ipg))*WI(Iksi(ipg))*detJ);
qw1=qw1+(Bf'*s)*(WI(Iksi(ipg))*WI(Iksi(ipg))*detJ);
qwos=qwos+(Bf'*sos)*(WI(Iksi(ipg))*detJ);
%generalized forces equilibrium
qk=qk+([Npsa',zeros(4,6);zeros(4,6),Npsa'*MX'*MX]*[s;ds])*(WI(Iksi(ipg))*detJ);

qkos=qkos+([Npsa',zeros(4,6);zeros(4,6),Npsa'*MX'*MX]*[sos;zeros(6,1)])*(WI(Iksi(ipg))*detJ);

%stiffness:
%warp-distortion problem
Kww=Kww+(Bf'*D*Bf)*(WI(Iksi(ipg))*detJ);
Kwk=Kwk+([Bf'*D*Npsa,zeros(ngl-8,4)]*(WI(Iksi(ipg))*detJ));
Qwk=Qwk+([zeros(ngl-8,4),Nf'*MX*D*Npsa]*(WI(Iksi(ipg))*detJ));
%generalized forces equilibrium
Kkw=Kkw+([Npsa'*D*Bf;zeros(4,ngl-8)])*(WI(Iksi(ipg))*detJ);
Kkk=Kkk+([Npsa'*D*Npsa,zeros(4,4);zeros(4,4),Npsa'*D*Npsa]*(WI(Iksi(ipg))*detJ);

%Rigid movement matrix
C=[1,0,0;
   0,1,0;
   0,0,1;
   0,-Z,Y];
RME=RME+WI(Iksi(ipg))*C*Nf*detJ;

end % Gauss points

q=[qk;qw1];
qos=[qkos;qwos];

state_new.Ag=state.Ag;
state_new.Bem=state.Bem;
state_new.RME=RME;
state_new.qw2=qw2;
state_new.Qwk=Qwk;

K=[Kkk,Kkw;Kwk,Kww];

end % bars

ok=1;
return
```

### 3. Codi de buildtinsa2.m corresponent a la construcció d'elements inclinats dobles

```
%elelin2 structure:
nnodele=2;
for i=1:section.nelel2
    j=j+1;
    section.ele{j}.fele=fele{j};
    section.ele{j}.conec=conec{3}(i,1:nnodele);
    section.ele{j}.ra(1,:)=section.coord(section.ele{j}.conec,1)';%section.r0(1);
    section.ele{j}.ra(2,:)=section.coord(section.ele{j}.conec,2)';%section.r0(2);
    section.ele{j}.theta(1)=conec{3}(i,nnodele+1);
    section.ele{j}.Abar(1)=conec{3}(i,nnodele+2);
    section.ele{j}.Sx(1)=conec{3}(i,nnodele+3);
    section.ele{j}.theta(2)=conec{3}(i,nnodele+4);
    section.ele{j}.Abar(2)=conec{3}(i,nnodele+5);
    section.ele{j}.Sx(2)=conec{3}(i,nnodele+6);
    section.ele{j}.mat=section.mat{conec{3}(i,nnodele+7)};
    section.ele{j}.npg=2;
end
```





Annex: Llistats

```

coord( 15,:)=[ 350, 250];
coord( 16,:)=[ 312.5, 300];
coord( 17,:)=[ 312.5, 290];
coord( 18,:)=[ 312.5, 280];
coord( 19,:)=[ 312.5, 265];
coord( 20,:)=[ 312.5, 250];
coord( 21,:)=[ 275, 300];
coord( 22,:)=[ 275, 290];
coord( 23,:)=[ 275, 280];
coord( 24,:)=[ 275, 265];
coord( 25,:)=[ 275, 250];
coord( 26,:)=[ 243.75, 300];
coord( 27,:)=[ 243.75, 290];
coord( 28,:)=[ 243.75, 280];
coord( 29,:)=[ 243.75, 265];
coord( 30,:)=[ 243.75, 250];
coord( 31,:)=[ 212.5, 300];
coord( 32,:)=[ 212.5, 290];
coord( 33,:)=[ 212.5, 280];
coord( 34,:)=[ 212.5, 265];
coord( 35,:)=[ 212.5, 250];
coord( 36,:)=[ 181.25, 300];
coord( 37,:)=[ 181.25, 290];
coord( 38,:)=[ 181.25, 280];
coord( 39,:)=[ 181.25, 265];
coord( 40,:)=[ 181.25, 250];
coord( 41,:)=[ 150, 300];
coord( 42,:)=[ 150, 290];
coord( 43,:)=[ 150, 280];
coord( 44,:)=[ 150, 265];
coord( 45,:)=[ 150, 250];
coord( 46,:)=[ 150, 234.59];
coord( 47,:)=[ 150, 216.65];
coord( 48,:)=[ 150, 195.13];
coord( 49,:)=[ 125, 300];
coord( 50,:)=[ 125, 290];
coord( 51,:)=[ 125, 280];
coord( 52,:)=[ 125.42, 264.21];
coord( 53,:)=[ 125.83, 248.42];
coord( 54,:)=[ 150, 169.7];
coord( 55,:)=[ 125.96, 231.19];
coord( 56,:)=[ 126.06, 212.53];
coord( 57,:)=[ 150, 140.11];
coord( 58,:)=[ 126.1, 190.65];
coord( 59,:)=[ 100, 300];
coord( 60,:)=[ 100, 290];
coord( 61,:)=[ 100, 280];
coord( 62,:)=[ 100.83, 263.42];
coord( 63,:)=[ 101.66, 246.84];
coord( 64,:)=[ 122.58, 172.34];
coord( 65,:)=[ 101.93, 229.22];
coord( 66,:)=[ 150, 110.39];
coord( 67,:)=[ 102.2, 211.61];
coord( 68,:)=[ 126.79, 144.68];
coord( 69,:)=[ 87.5, 300];
coord( 70,:)=[ 87.5, 290];
coord( 71,:)=[ 87.5, 280];
coord( 72,:)=[ 87.915, 266.73];
coord( 73,:)=[ 101.43, 199.52];
coord( 74,:)=[ 88.33, 253.25];
coord( 75,:)=[ 88.548, 238.53];
coord( 76,:)=[ 88.932, 223.9];
coord( 77,:)=[ 89.986, 211.48];
coord( 78,:)=[ 150, 85.33];
coord( 79,:)=[ 127.68, 116.18];
coord( 80,:)=[ 75, 300];
coord( 81,:)=[ 75, 290];
coord( 82,:)=[ 75, 280];
coord( 83,:)=[ 75, 270.26];
coord( 84,:)=[ 75, 259.67];
coord( 85,:)=[ 75, 247.76];
coord( 86,:)=[ 80.44, 212.24];

```

Annex: Llistats

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```

coord( 87,:)=[ 75, 234];
coord( 88,:)=[ 87.419, 184.32];
coord( 89,:)=[ 79.14, 205.14];
coord( 90,:)=[ 75, 217.18];
coord( 91,:)=[ 95.431, 152.27];
coord( 92,:)=[ 130.33, 89.992];
coord( 93,:)=[ 150, 64.573];
coord( 94,:)=[ 80.692, 187.82];
coord( 95,:)=[ 62.5, 300];
coord( 96,:)=[ 62.5, 290];
coord( 97,:)=[ 62.5, 280];
coord( 98,:)=[ 62.085, 266.73];
coord( 99,:)=[ 75, 197.1];
coord( 100,:)=[ 69.56, 212.24];
coord( 101,:)=[ 61.67, 253.25];
coord( 102,:)=[ 70.86, 205.14];
coord( 103,:)=[ 103.59, 119.66];
coord( 104,:)=[ 61.452, 238.53];
coord( 105,:)=[ 81.21, 164.73];
coord( 106,:)=[ 61.068, 223.9];
coord( 107,:)=[ 75, 173.16];
coord( 108,:)=[ 133.02, 68.178];
coord( 109,:)=[ 69.308, 187.82];
coord( 110,:)=[ 150, 47.641];
coord( 111,:)=[ 50, 300];
coord( 112,:)=[ 50, 290];
coord( 113,:)=[ 50, 280];
coord( 114,:)=[ 60.014, 211.48];
coord( 115,:)=[ 85.789, 137.22];
coord( 116,:)=[ 110.53, 91.898];
coord( 117,:)=[ 49.17, 263.42];
coord( 118,:)=[ 48.339, 246.84];
coord( 119,:)=[ 62.581, 184.32];
coord( 120,:)=[ 68.79, 164.73];
coord( 121,:)=[ 150, 34];
coord( 122,:)=[ 75, 145.14];
coord( 123,:)=[ 135.44, 49.459];
coord( 124,:)=[ 48.07, 229.22];
coord( 125,:)=[ 116.33, 68.688];
coord( 126,:)=[ 83.361, 119.34];
coord( 127,:)=[ 47.801, 211.61];
coord( 128,:)=[ 89.293, 104.97];
coord( 129,:)=[ 48.574, 199.52];
coord( 130,:)=[ 137.5, 34];
coord( 131,:)=[ 97.444, 84.662];
coord( 132,:)=[ 121.11, 49.565];
coord( 133,:)=[ 150, 17];
coord( 134,:)=[ 75, 115.83];
coord( 135,:)=[ 64.211, 137.22];
coord( 136,:)=[ 104.14, 66.321];
coord( 137,:)=[ 54.569, 152.27];
coord( 138,:)=[ 25, 300];
coord( 139,:)=[ 25, 290];
coord( 140,:)=[ 25, 280];
coord( 141,:)=[ 125, 34];
coord( 142,:)=[ 66.639, 119.34];
coord( 143,:)=[ 24.585, 264.21];
coord( 144,:)=[ 137.47, 16.999];
coord( 145,:)=[ 105.92, 52.563];
coord( 146,:)=[ 24.17, 248.42];
coord( 147,:)=[ 85.817, 75.456];
coord( 148,:)=[ 24.045, 231.19];
coord( 149,:)=[ 150, 0];
coord( 150,:)=[ 75, 90.294];
coord( 151,:)=[ 91.853, 62.78];
coord( 152,:)=[ 23.938, 212.53];
coord( 153,:)=[ 104.45, 42.003];
coord( 154,:)=[ 125, 17];
coord( 155,:)=[ 60.707, 104.97];
coord( 156,:)=[ 93.981, 52.365];
coord( 157,:)=[ 80.651, 68.083];
coord( 158,:)=[ 137.5, 0];

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Annex: Llistats

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coord( 159,:)=[ 23.9, 190.65];
coord( 160,:)=[ 27.422, 172.34];
coord( 161,:)=[ 94.339, 44.882];
coord( 162,:)=[ 83.476, 56.977];
coord( 163,:)=[ 46.414, 119.66];
coord( 164,:)=[ 97.077, 38.556];
coord( 165,:)=[ 75, 68.437];
coord( 166,:)=[ 100, 34];
coord( 167,:)=[ 85.031, 48.169];
coord( 168,:)=[ 125, 0];
coord( 169,:)=[ 69.349, 68.083];
coord( 170,:)=[ 64.183, 75.456];
coord( 171,:)=[ 0, 300];
coord( 172,:)=[ 87.669, 41.336];
coord( 173,:)=[ 0, 290];
coord( 174,:)=[ 0, 280];
coord( 175,:)=[ 0, 265];
coord( 176,:)=[ 0, 250];
coord( 177,:)=[ 0, 234.59];
coord( 178,:)=[ 75, 50];
coord( 179,:)=[ 52.556, 84.662];
coord( 180,:)=[ 23.207, 144.68];
coord( 181,:)=[ 100, 17];
coord( 182,:)=[ 66.524, 56.977];
coord( 183,:)=[ 0, 216.65];
coord( 184,:)=[ 75, 42];
coord( 185,:)=[ 58.147, 62.78];
coord( 186,:)=[ 0, 195.13];
coord( 187,:)=[ 39.475, 91.898];
coord( 188,:)=[ 64.969, 48.169];
coord( 189,:)=[ 75, 34];
coord( 190,:)=[ 100, 0];
coord( 191,:)=[ 22.323, 116.18];
coord( 192,:)=[ 56.019, 52.365];
coord( 193,:)=[ 0, 169.7];
coord( 194,:)=[ 45.86, 66.321];
coord( 195,:)=[ 62.331, 41.336];
coord( 196,:)=[ 55.661, 44.882];
coord( 197,:)=[ 75, 17];
coord( 198,:)=[ 0, 140.11];
coord( 199,:)=[ 44.081, 52.563];
coord( 200,:)=[ 33.672, 68.688];
coord( 201,:)=[ 52.923, 38.556];
coord( 202,:)=[ -31.25, 300];
coord( 203,:)=[ -31.25, 290];
coord( 204,:)=[ 19.671, 89.992];
coord( 205,:)=[ -31.25, 280];
coord( 206,:)=[ -31.253, 265];
coord( 207,:)=[ 45.551, 42.003];
coord( 208,:)=[ -31.25, 250];
coord( 209,:)=[ 50, 34];
coord( 210,:)=[ 75, 0];
coord( 211,:)=[ 0, 110.39];
coord( 212,:)=[ 28.891, 49.565];
coord( 213,:)=[ 16.975, 68.178];
coord( 214,:)=[ 50, 17];
coord( 215,:)=[ 0, 85.33];
coord( 216,:)=[ 50, 0];
coord( 217,:)=[ 25, 34];
coord( 218,:)=[ 14.557, 49.459];
coord( 219,:)=[ 0, 64.573];
coord( 220,:)=[ -62.5, 300];
coord( 221,:)=[ -62.5, 290];
coord( 222,:)=[ -62.5, 280];
coord( 223,:)=[ -62.499, 265];
coord( 224,:)=[ 25, 17];
coord( 225,:)=[ -62.5, 250];
coord( 226,:)=[ 12.5, 34];
coord( 227,:)=[ 0, 47.641];
coord( 228,:)=[ 25, 0];
coord( 229,:)=[ 12.53, 17.002];
coord( 230,:)=[ 0, 34];

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Annex: Llistats

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conec ( 24, :)= [ 24, 159, 186, 193, 160, 1];
conec ( 25, :)= [ 25, 204, 215, 219, 213, 1];
conec ( 26, :)= [ 26, 204, 213, 200, 187, 1];
conec ( 27, :)= [ 27, 204, 187, 163, 191, 1];
conec ( 28, :)= [ 28, 204, 191, 211, 215, 1];
conec ( 29, :)= [ 29, 180, 198, 211, 191, 1];
conec ( 30, :)= [ 30, 180, 191, 163, 137, 1];
conec ( 31, :)= [ 31, 180, 137, 119, 160, 1];
conec ( 32, :)= [ 32, 180, 160, 193, 198, 1];
conec ( 33, :)= [ 33, 87, 106, 114, 100, 1];
conec ( 34, :)= [ 34, 127, 129, 114, 106, 1];
conec ( 35, :)= [ 35, 119, 100, 114, 129, 1];
conec ( 36, :)= [ 36, 188, 195, 189, 184, 1];
conec ( 37, :)= [ 37, 188, 184, 178, 182, 1];
conec ( 38, :)= [ 38, 188, 182, 185, 192, 1];
conec ( 39, :)= [ 39, 188, 192, 196, 195, 1];
conec ( 40, :)= [ 40, 199, 192, 185, 194, 1];
conec ( 41, :)= [ 41, 199, 194, 200, 212, 1];
conec ( 42, :)= [ 42, 199, 212, 217, 207, 1];
conec ( 43, :)= [ 43, 199, 207, 196, 192, 1];
conec ( 44, :)= [ 44, 179, 194, 185, 170, 1];
conec ( 45, :)= [ 45, 179, 170, 150, 155, 1];
conec ( 46, :)= [ 46, 179, 155, 163, 187, 1];
conec ( 47, :)= [ 47, 179, 187, 200, 194, 1];
conec ( 48, :)= [ 48, 120, 107, 99, 109, 1];
conec ( 49, :)= [ 49, 120, 109, 119, 137, 1];
conec ( 50, :)= [ 50, 120, 137, 163, 135, 1];
conec ( 51, :)= [ 51, 120, 135, 122, 107, 1];
conec ( 52, :)= [ 52, 189, 195, 201, 209, 1];
conec ( 53, :)= [ 53, 196, 207, 201, 195, 1];
conec ( 54, :)= [ 54, 217, 209, 201, 207, 1];
conec ( 55, :)= [ 55, 185, 182, 169, 170, 1];
conec ( 56, :)= [ 56, 178, 165, 169, 182, 1];
conec ( 57, :)= [ 57, 150, 170, 169, 165, 1];
conec ( 58, :)= [ 58, 99, 90, 102, 109, 1];
conec ( 59, :)= [ 59, 87, 100, 102, 90, 1];
conec ( 60, :)= [ 60, 119, 109, 102, 100, 1];
conec ( 61, :)= [ 61, 122, 135, 142, 134, 1];
conec ( 62, :)= [ 62, 163, 155, 142, 135, 1];
conec ( 63, :)= [ 63, 150, 134, 142, 155, 1];
conec ( 64, :)= [ 64, 52, 44, 43, 51, 1];
conec ( 65, :)= [ 65, 52, 51, 61, 62, 1];
conec ( 66, :)= [ 66, 52, 62, 63, 53, 1];
conec ( 67, :)= [ 67, 52, 53, 45, 44, 1];
conec ( 68, :)= [ 68, 55, 46, 45, 53, 1];
conec ( 69, :)= [ 69, 55, 53, 63, 65, 1];
conec ( 70, :)= [ 70, 55, 65, 67, 56, 1];
conec ( 71, :)= [ 71, 55, 56, 47, 46, 1];
conec ( 72, :)= [ 72, 72, 71, 82, 83, 1];
conec ( 73, :)= [ 73, 72, 83, 84, 74, 1];
conec ( 74, :)= [ 74, 72, 74, 63, 62, 1];
conec ( 75, :)= [ 75, 72, 62, 61, 71, 1];
conec ( 76, :)= [ 76, 123, 130, 121, 110, 1];
conec ( 77, :)= [ 77, 123, 110, 93, 108, 1];
conec ( 78, :)= [ 78, 123, 108, 125, 132, 1];
conec ( 79, :)= [ 79, 123, 132, 141, 130, 1];
conec ( 80, :)= [ 80, 75, 74, 84, 85, 1];
conec ( 81, :)= [ 81, 75, 85, 87, 76, 1];
conec ( 82, :)= [ 82, 75, 76, 67, 65, 1];
conec ( 83, :)= [ 83, 75, 65, 63, 74, 1];
conec ( 84, :)= [ 84, 58, 73, 88, 64, 1];
conec ( 85, :)= [ 85, 58, 64, 54, 48, 1];
conec ( 86, :)= [ 86, 58, 48, 47, 56, 1];
conec ( 87, :)= [ 87, 58, 56, 67, 73, 1];
conec ( 88, :)= [ 88, 92, 108, 93, 78, 1];
conec ( 89, :)= [ 89, 92, 78, 66, 79, 1];
conec ( 90, :)= [ 90, 92, 79, 103, 116, 1];
conec ( 91, :)= [ 91, 92, 116, 125, 108, 1];
conec ( 92, :)= [ 92, 68, 79, 66, 57, 1];
conec ( 93, :)= [ 93, 68, 57, 54, 64, 1];
conec ( 94, :)= [ 94, 68, 64, 88, 91, 1];
conec ( 95, :)= [ 95, 68, 91, 103, 79, 1];

Annex: Llistats

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conec( 96,:)=[ 96, 67, 76, 77, 73, 1];
conec( 97,:)=[ 97, 87, 86, 77, 76, 1];
conec( 98,:)=[ 98, 88, 73, 77, 86, 1];
conec( 99,:)=[ 99, 226, 229, 224, 217, 1];
conec( 100,:)=[ 100, 230, 232, 229, 226, 1];
conec( 101,:)=[ 101, 229, 231, 228, 224, 1];
conec( 102,:)=[ 102, 232, 237, 231, 229, 1];
conec( 103,:)=[ 103, 209, 214, 197, 189, 1];
conec( 104,:)=[ 104, 217, 224, 214, 209, 1];
conec( 105,:)=[ 105, 214, 216, 210, 197, 1];
conec( 106,:)=[ 106, 224, 228, 216, 214, 1];
conec( 107,:)=[ 107, 166, 181, 154, 141, 1];
conec( 108,:)=[ 108, 189, 197, 181, 166, 1];
conec( 109,:)=[ 109, 181, 190, 168, 154, 1];
conec( 110,:)=[ 110, 197, 210, 190, 181, 1];
conec( 111,:)=[ 111, 130, 144, 133, 121, 1];
conec( 112,:)=[ 112, 141, 154, 144, 130, 1];
conec( 113,:)=[ 113, 144, 158, 149, 133, 1];
conec( 114,:)=[ 114, 154, 168, 158, 144, 1];
conec( 115,:)=[ 115, 266, 265, 270, 271, 1];
conec( 116,:)=[ 116, 261, 260, 265, 266, 1];
conec( 117,:)=[ 117, 265, 264, 269, 270, 1];
conec( 118,:)=[ 118, 260, 259, 264, 265, 1];
conec( 119,:)=[ 119, 2, 6, 7, 3, 1];
conec( 120,:)=[ 120, 1, 5, 6, 2, 1];
conec( 121,:)=[ 121, 6, 12, 13, 7, 1];
conec( 122,:)=[ 122, 5, 11, 12, 6, 1];
conec( 123,:)=[ 123, 12, 17, 18, 13, 1];
conec( 124,:)=[ 124, 11, 16, 17, 12, 1];
conec( 125,:)=[ 125, 17, 22, 23, 18, 1];
conec( 126,:)=[ 126, 16, 21, 22, 17, 1];
conec( 127,:)=[ 127, 4, 9, 10, 8, 1];
conec( 128,:)=[ 128, 3, 7, 9, 4, 1];
conec( 129,:)=[ 129, 9, 14, 15, 10, 1];
conec( 130,:)=[ 130, 7, 13, 14, 9, 1];
conec( 131,:)=[ 131, 14, 19, 20, 15, 1];
conec( 132,:)=[ 132, 13, 18, 19, 14, 1];
conec( 133,:)=[ 133, 19, 24, 25, 20, 1];
conec( 134,:)=[ 134, 18, 23, 24, 19, 1];
conec( 135,:)=[ 135, 28, 29, 24, 23, 1];
conec( 136,:)=[ 136, 33, 34, 29, 28, 1];
conec( 137,:)=[ 137, 38, 39, 34, 33, 1];
conec( 138,:)=[ 138, 43, 44, 39, 38, 1];
conec( 139,:)=[ 139, 29, 30, 25, 24, 1];
conec( 140,:)=[ 140, 34, 35, 30, 29, 1];
conec( 141,:)=[ 141, 39, 40, 35, 34, 1];
conec( 142,:)=[ 142, 44, 45, 40, 39, 1];
conec( 143,:)=[ 143, 42, 37, 36, 41, 1];
conec( 144,:)=[ 144, 43, 38, 37, 42, 1];
conec( 145,:)=[ 145, 37, 32, 31, 36, 1];
conec( 146,:)=[ 146, 38, 33, 32, 37, 1];
conec( 147,:)=[ 147, 32, 27, 26, 31, 1];
conec( 148,:)=[ 148, 33, 28, 27, 32, 1];
conec( 149,:)=[ 149, 27, 22, 21, 26, 1];
conec( 150,:)=[ 150, 28, 23, 22, 27, 1];
conec( 151,:)=[ 151, 260, 255, 254, 259, 1];
conec( 152,:)=[ 152, 261, 256, 255, 260, 1];
conec( 153,:)=[ 153, 255, 250, 249, 254, 1];
conec( 154,:)=[ 154, 256, 251, 250, 255, 1];
conec( 155,:)=[ 155, 250, 245, 244, 249, 1];
conec( 156,:)=[ 156, 251, 246, 245, 250, 1];
conec( 157,:)=[ 157, 245, 240, 239, 244, 1];
conec( 158,:)=[ 158, 246, 241, 240, 245, 1];
conec( 159,:)=[ 159, 266, 267, 262, 261, 1];
conec( 160,:)=[ 160, 271, 272, 267, 266, 1];
conec( 161,:)=[ 161, 267, 268, 263, 262, 1];
conec( 162,:)=[ 162, 272, 273, 268, 267, 1];
conec( 163,:)=[ 163, 246, 247, 242, 241, 1];
conec( 164,:)=[ 164, 251, 252, 247, 246, 1];
conec( 165,:)=[ 165, 256, 257, 252, 251, 1];
conec( 166,:)=[ 166, 261, 262, 257, 256, 1];
conec( 167,:)=[ 167, 247, 248, 243, 242, 1];









```

for i=1:nelec
    fele(i)='elesup';
end

%6. Transversal Reinforcements (in-plane reinforcements)
%Numero de elementos de estribos
nstir= 24;
%
%
ElemID      Nod1      Nod2      alpha      As      Sx      mat
XStir( 1,:)=[ 285, 43, 38, 0, 78.54, 150, 3];
XStir( 2,:)=[ 286, 38, 33, 0, 78.54, 150, 3];
XStir( 3,:)=[ 287, 33, 28, 0, 78.54, 150, 3];
XStir( 4,:)=[ 288, 28, 23, 0, 78.54, 150, 3];
XStir( 5,:)=[ 289, 23, 18, 0, 78.54, 150, 3];
XStir( 6,:)=[ 290, 18, 13, 0, 78.54, 150, 3];
XStir( 7,:)=[ 291, 13, 7, 0, 78.54, 150, 3];
XStir( 8,:)=[ 292, 7, 3, 0, 78.54, 150, 3];
XStir( 9,:)=[ 293, 291, 286, 0, 78.54, 150, 3];
XStir( 10,:)=[ 294, 286, 281, 0, 78.54, 150, 3];
XStir( 11,:)=[ 295, 281, 276, 0, 78.54, 150, 3];
XStir( 12,:)=[ 296, 276, 271, 0, 78.54, 150, 3];
XStir( 13,:)=[ 297, 133, 113, 0, 78.54, 150, 3];
XStir( 14,:)=[ 298, 113, 83, 0, 78.54, 150, 3];
XStir( 15,:)=[ 299, 83, 75, 0, 78.54, 150, 3];
XStir( 16,:)=[ 300, 75, 65, 0, 78.54, 150, 3];
XStir( 17,:)=[ 301, 271, 265, 0, 78.54, 150, 3];
XStir( 18,:)=[ 302, 265, 252, 0, 78.54, 150, 3];
XStir( 19,:)=[ 303, 252, 233, 0, 78.54, 150, 3];
XStir( 20,:)=[ 304, 233, 201, 0, 78.54, 150, 3];
XStir( 21,:)=[ 305, 201, 166, 0, 78.54, 150, 3];
XStir( 22,:)=[ 306, 166, 133, 0, 78.54, 150, 3];
XStir( 23,:)=[ 307, 65, 51, 0, 78.54, 150, 3];
XStir( 24,:)=[ 308, 51, 43, 0, 78.54, 150, 3];
for i=nelec+1:nelec+nstir
    fele(i)='elelin';
end

%6. Transversal Reinforcements (in-plane reinforcements)
%Numero de elementos de estribos
nstir2=24;
XStir2( 1,:)=[ 261, 247, 243, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 2,:)=[ 262, 243, 238, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 3,:)=[ 263, 238, 224, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 4,:)=[ 264, 224, 212, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 5,:)=[ 265, 212, 189, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 6,:)=[ 266, 189, 171, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 7,:)=[ 267, 171, 152, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 8,:)=[ 268, 152, 135, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 9,:)=[ 269, 135, 123, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 10,:)=[ 270, 123, 107, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 11,:)=[ 271, 107, 99, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 12,:)=[ 272, 99, 91, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 13,:)=[ 273, 91, 87, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 14,:)=[ 274, 87, 85, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 15,:)=[ 275, 85, 84, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 16,:)=[ 276, 84, 88, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 17,:)=[ 277, 88, 97, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 18,:)=[ 278, 97, 103, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 19,:)=[ 279, 103, 119, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 20,:)=[ 280, 119, 128, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 21,:)=[ 281, 128, 142, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 22,:)=[ 282, 142, 151, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 23,:)=[ 283, 151, 161, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 24,:)=[ 284, 161, 167, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
for i=nelec+nstir+1:nelec+nstir+nstir2
    fele(i)='elelin2';
end

%7. Longitudinal Reinforcements (along element's axis)
%Numero de barras longitudinales
nbar= 8;
%
%
1      2      3

```

```

%
XReBar(    1,:)=[    23,    78.54,3];
XReBar(    2,:)=[    65,    78.54,3];
XReBar(    3,:)=[    91,    50.27,2];
XReBar(    4,:)=[   133,    78.54,3];
XReBar(    5,:)=[   167,    50.27,2];
XReBar(    6,:)=[   206,    78.54,3];
XReBar(    7,:)=[   247,    50.27,2];
XReBar(    8,:)=[   271,    78.54,3];

for i=nelec+nstir+nstir2+1:nelec+nstir+nstir2+nbar
    fele(i)='elepoint';
end

return

```

## 6. Tearpetit (abreujat)

```

%1. Section's name
PName='section1';

%1.1. Allowed degrees of freedom for warp-distortion
ADOF=[1,1,1]';

%2. Reference position of the bar's axis
r0=[    75,    197.162]';

%3. Materials definition
%number of materials
nmat=    3;
mat{    1}.name='H30';
mat{    1}.fname='OU3DC';
mat{1}.prop.fc=35.;
mat{1}.prop.e0=0.0022;
mat{1}.prop.E0=3e4;
mat{1}.prop.nu=0.2;
mat{1}.prop.epres=zeros(6,1);
mat{1}.prop.ft_=0.1;
mat{1}.prop.fbc_=1.5;
mat{1}.prop.ksil_=3.67;
mat{1}.prop.r1_=1.59;
mat{1}.prop.ksi2_=3.67;
mat{1}.prop.r2_=1.94;
mat{1}.prop.bbcurveC='CoPor';%mat{1}.prop.bbcurveC='ParSq';
mat{1}.prop.bbcurveT='Cervk';
mat{1}.prop.surface='FSWilliam_Warnke5P';

%material 2: acero celosia
mat{2}.name='B500';
mat{2}.fname='BilPlaCyclic';
mat{2}.prop.fy=809;
mat{2}.prop.E0=2e5;
mat{2}.prop.E1=2e1;
mat{2}.prop.epres=0;

%material 3: acero longitudinal
mat{3}.name='B500';
mat{3}.fname='BilPlaCyclic';
mat{3}.prop.fy=588;
mat{3}.prop.E0=2e5;
mat{3}.prop.E1=2e1;
mat{3}.prop.epres=0;

%4. Coordinates
%number of nodes
nnod=    389;

```



```
XStir2( 8,:)=[ 346, 180, 166, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2( 9,:)=[ 347, 166, 153, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(10,:)=[ 348, 153, 144, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(11,:)=[ 349, 144, 142, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(12,:)=[ 350, 142, 143, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(13,:)=[ 351, 143, 145, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(14,:)=[ 352, 145, 149, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(15,:)=[ 353, 149, 161, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(16,:)=[ 354, 161, 169, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(17,:)=[ 355, 169, 179, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(18,:)=[ 356, 179, 187, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(19,:)=[ 357, 187, 196, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
XStir2(20,:)=[ 358, 196, 204, 0.451633441, 12.5663 200, -0.451633441, 12.5663 200, 2];
for i=nelec+nstir+1:nelec+nstir+nstir2
    fele{i}='elelin2';
end

%7. Longitudinal Reinforcements (along element's axis)
%Numero de barras longitudinales
nbar=      8;
%
%          1      2      3
%          NodID  As    mat
XReBar( 1,:)=[    23,    78.54,3];
XReBar( 2,:)=[   111,    78.54,3];
XReBar( 3,:)=[   144,    50.27,2];
XReBar( 4,:)=[   175,    78.54,3];
XReBar( 5,:)=[   204,    50.27,2];
XReBar( 6,:)=[   250,    78.54,3];
XReBar( 7,:)=[   328,    50.27,2];
XReBar( 8,:)=[   357,    78.54,3];
for i=nelec+nstir+nstir2+1:nelec+nstir+nstir2+nbar
    fele{i}='elepoint';
end

return
```

## 7. Teargran.m (abreujat)

```
%1. Section's name
PName='section1';

%1.1. Allowed degrees of freedom for warp-distortion
ADOF=[1,1,1]';

%2. Reference position of the bar's axis
r0=[    75,    197.162]';

%3. Materials definition
%number of materials
nmat=      3;
mat{    1}.name='H30';
mat{    1}.fname='OU3DC';
mat{1}.prop.fc=35.;
mat{1}.prop.e0=0.0022;
mat{1}.prop.E0=3e4;
mat{1}.prop.nu=0.2;
mat{1}.prop.epres=zeros(6,1);
mat{1}.prop.ft_=0.1;
mat{1}.prop.fbc_=1.5;
mat{1}.prop.ksi1=3.67;
mat{1}.prop.r1_=1.59;
mat{1}.prop.ksi2=3.67;
mat{1}.prop.r2_=1.94;
mat{1}.prop.bbcurveC='CoPor';%mat{1}.prop.bbcurveC='ParSq';
mat{1}.prop.bbcurveT='Cervk';
mat{1}.prop.surface='FSWilliam_Warnke5P';
```



Annex: Llistats

```

XStir( 26,:)= [ 410, 67, 59, 0, 78.54, 150, 3];
XStir( 27,:)= [ 411, 59, 51, 0, 78.54, 150, 3];
XStir( 28,:)= [ 412, 51, 43, 0, 78.54, 150, 3];
XStir( 29,:)= [ 413, 345, 333, 0, 78.54, 150, 3];
XStir( 30,:)= [ 414, 333, 315, 0, 78.54, 150, 3];
XStir( 31,:)= [ 415, 315, 290, 0, 78.54, 150, 3];
XStir( 32,:)= [ 416, 290, 265, 0, 78.54, 150, 3];
for i=nelec+1:nelec+nstir
    fele(i)='elelin';
end

%6. Transversal Reinforcements (in-plane reinforcements)
%Numero de elementos de estribos
nstir2=24;
XStir2( 1,:)= [ 361,350, 340, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 2,:)= [ 362, 340, 328, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 3,:)= [ 363, 328, 308, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 4,:)= [ 364, 308, 283, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 5,:)= [ 365, 283, 251, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 6,:)= [ 366, 251, 229, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 7,:)= [ 367, 229, 205, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 8,:)= [ 368, 205, 188, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 9,:)= [ 369, 188, 176, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 10,:)= [ 370, 176, 162, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 11,:)= [ 371, 162, 153, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 12,:)= [ 372, 153, 145, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 13,:)= [ 373, 145, 141, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 14,:)= [ 374, 141, 139, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 15,:)= [ 375, 139, 138, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 16,:)= [ 376, 138, 142, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 17,:)= [ 377, 142, 150, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 18,:)= [ 378, 150, 157, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 19,:)= [ 379, 157, 172, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 20,:)= [ 380, 172, 183, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 21,:)= [ 381, 183, 194, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 22,:)= [ 382, 194, 204, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 23,:)= [ 383, 204, 215, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
XStir2( 24,:)= [ 384, 215, 225, 0.409351919, 12.5663 200, -0.409351919, 12.5663 200, 2];
for i=nelec+nstir+1:nelec+nstir+nstir2
    fele(i)='elelin2';
end

%7. Longitudinal Reinforcements (along element's axis)
%Numero de barras longitudinales
nbar= 8;
% 1 2 3
% NodID As mat
XReBar( 1,:)= [ 23, 78.54,3];
XReBar( 2,:)= [ 114, 78.54,3];
XReBar( 3,:)= [ 145, 50.27,2];
XReBar( 4,:)= [ 187, 78.54,3];
XReBar( 5,:)= [ 225, 50.27,2];
XReBar( 6,:)= [ 272, 78.54,3];
XReBar( 7,:)= [ 350, 50.27,2];
XReBar( 8,:)= [ 379, 78.54,3];
for i=nelec+nstir+nstir2+1:nelec+nstir+nstir2+nbar
    fele(i)='elepoint';
end

return

```

## 8. Tinsa\_te\*.m

```
tepetit; %tearpetit; tegran; teargran; (aquí cal executar el fitxer amb la malla que toqui)
conec={conec(:,2:6);XStir(:,2:7);XStir2(:,2:10);XReBar};

c=-1.5395e-006;
rampc=[0.125:0.125:1,1.1:0.1:3];
rampc=[rampc(1:18),2:0.1:3];
rampc=[rampc(1:23),2.4:0.1:3];
rampc=[rampc(1:24),2.5:0.1:3];
rampc=[rampc(1:30),3.1:0.1:4];
rampc=[rampc(1:40),4.1:0.1:5];
nstep=size(rampc,2);

for ibatch=2:2
    batchName=['tegran_out_',int2str(ibatch)];

    restart=0;
    istart=41;
    stoprun=0;
    istop=20;

    if restart==0
        %new start
        clear ss ssos es Ks state mate mats
        state=cell(nstep,1);
        [section,state{1}]=builddinsa2(ADOF,r0,coord,mat,conec,fele);
        i0=1;
    elseif restart==1
        i0=istart;
    end

    totaltime=0;
    initime=0;
    endtime=0;
    if stoprun==1;
        iend=istop;
    else
        iend=nstep;
    end

    disp(['-----']);
    disp(['TINSA']);
    disp(['TOTAL INTERACTION NONLINEAR SECTION ANALYSIS' ]);
    disp(['J. M. BAIRAN']);
    disp(['ver 1.0.0 / october 2004']);
    disp(['Analysis: ',batchName]);
    disp(['from step: ',int2str(i0),' to step: ',int2str(iend)]);
    disp(['-----']);
    disp(['press ENTER to begin analysis...']);
    %pause;disp(' ');
    disp(['begining...']);

    for i=i0:iend
        if i==1
            state0=state{1};
        else
            state0=state{i-1};
        end

        boundc.nresq=5;
        boundc.dofresq=[1,2,3,4,5,6];
        boundc.valresq=[0,0,0,0,0,0];
        boundc.nresd=1;
        boundc.dofresd=[];
```



```
boundc.valresd=[];

param.maxinc=20;
param.incauto=1;
param.lamb(1)=0.3;
param.flmin=0.01;
param.iteropt=4;
param.itercoef=0.5;
param.maxiter=20;
param.lq=0;
param.Id=0;
param.Ie=1;
param.bq=0.01;
param.bd=0.01;
param.be=0.01;
param.smallq=0.1;
param.smalld=1e-7;
param.smalle=1e-7;
L=1*sqrt(state0.Ag);iL=1/L;
param.Sq=[1,0,0,0,0,0;
 0,1,0,0,0,0;
 0,0,1,0,0,0;
 0,0,0,iL,0,0;
 0,0,0,0,iL,0;
 0,0,0,0,0,iL];
param.Sd=[1,0,0,0,0,0;
 0,1,0,0,0,0;
 0,0,1,0,0,0;
 0,0,0,L,0,0;
 0,0,0,0,L,0;
 0,0,0,0,0,L];

param.dcontrol.do=1;
param.dcontrol.igl=5;
param.dcontrol.val=c*rampc(i);
param.dcontrol.valresqbar=[0,0,1,0,350,0];

param.control=2;
param.tansec=2;
param.NR=0;
param.LS.do=0;

tic;
[ss{i},ssos{i},es{i},Ks{i},state{i},control,ok]=tinsa_3(boundc,section,state0,param);
steptime=toc;
totaltime=totaltime+steptime;

niter(i)=control.niter;
ninc(i)=control.ninc;

if ok==0
  disp(['-----']);
  disp(['!NOT CONVERGED!']);
  disp(['iteration failed on step: ',int2str(i),' out of: ',int2str(iend)]);
  disp(['total number of iterations: ',int2str(niter(i))]);
  disp(['total number of increments: ',int2str(ninc(i))]);
  disp(['step time: ',num2str(steptime)]);
  break
else
  disp(['-----']);
  disp(['converged on step: ',int2str(i),' out of: ',int2str(iend)]);
  disp(['total number of iterations: ',int2str(niter(i))]);
  disp(['total number of increments: ',int2str(ninc(i))]);
  disp(['step time: ',num2str(steptime)]);
end

j=i;
mate(:,j)=state{j}.es;
mats(:,j)=state{j}.ss;
```

Annex: Llistats

---

```
matdw(:,j)=state{j}.dw;
dades_Ks{j}=state{j}.Ks;
for k=1:nelec
    for m=1:4
        dades_mat{j,k}{m}.e=state{j}.ele{k}.mat{m}.e;
        dades_mat{j,k}{m}.s=state{j}.ele{k}.mat{m}.s;
        dades_mat{j,k}{m}.dt=state{j}.ele{k}.mat{m}.dt;
        dades_mat{j,k}{m}.fca=state{j}.ele{k}.mat{m}.fca;
    end
end
for k=nelec+1:nelec+nstir+nstir2+nbar
    dades_mat{j,k}=state{j}.ele{k}.mat;
end

state_new=state{i};
save resultats mate mats matdw dades_Ks dades_mat control state_new;

end

if ok==1;
    disp(['-----']);
    disp(['Analysis completed']);
    disp(['total time: ',num2str(totaltime)]);
    disp(['ok']);
    disp(['-----']);
else
    disp(['-----']);
    disp(['Analysis not completed']);
    disp(['total time: ',num2str(totaltime)]);
    disp(['-----']);
end

save(batchName)

end %(end batch)
```