# TWO PARAMETRIC QUASI-CYCLIC CODES AS HYPERINVARIANT SUBSPACES 

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#### Abstract

It is known the relationship between cyclic codes and invariant subspaces. In this work we present a generalization considering "generalized" cyclic codes and hyperinvariant subspaces.


## Key words

Cyclic codes, two-parametric quasi cyclic codes, hyperinvariant subspaces.

## 1 Introduction

Let $\varphi$ be an endomorphism of a vector space $V$ over a field $\mathbb{F}$.
Recall that a $\varphi$-invariant subspace $F \subset V$ is called hyperinvariant if $F$ is invariant under all linear maps commuting with $\varphi$.
The main goal of this work is to establish the relationship between the set of some "generalized cyclic codes" and hyperinvariant linear subspaces of $\mathbb{F}^{n}$.
Despite of the fact that Commutative Algebra is the tool mostly used to study linear cyclic codes (see [MacWilliams and Sloane, 1977], for example), since linear codes have a structure of linear subspaces of $\mathbb{F}^{n}$, they can also be studied using Linear Algebra as [Garcia-Planas, Souidi and Um, 2012; Garcia-Planas, Souidi and Um, 2013].

## 2 Preliminaries

### 2.1 Hyperinvariant Subspaces of Cyclic Permutation Maps

Let $p$ be a prime number, $q=p^{k}$ for some $k \geq 1$ and $\mathbb{F}=G F(q)$. Let $\mathbb{F}^{n}$ be the $n$-dimensional vector space over the field $\mathbb{F}$.
We consider the following linear map

$$
\begin{align*}
\varphi: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(x_{n}, x_{1}, \ldots, x_{n-1}\right) \tag{1}
\end{align*}
$$

with associated matrix, with respect to the standard basis,

$$
A=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & 1  \tag{2}\\
1 & 0 & \ldots & 0 & 0 \\
0 & 1 & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & 1 & 0
\end{array}\right)
$$

This linear map is clearly orthogonal (in the sense $A^{t}=A^{-1}$ ) and verifies $A^{n}=I_{n}$. Cayley Hamilton Theorem ensures that its characteristic polynomial is

$$
p(s)=\operatorname{det}\left(A-s I_{n}\right)=(-1)^{n}\left(s^{n}-1\right)
$$

To study hyperinvariant subspaces (those which are invariant for all linear maps commmuting with $\varphi$ ) we need to compute the centralizer of $A$.

Proposition 2.1. The centralizer $\mathcal{C}(A)$ of $A$ is the set of circulant matrices

$$
X=\left(\begin{array}{ccccc}
x_{1} & x_{2} & \ldots & x_{n-1} & x_{n} \\
x_{n} & x_{1} & \ldots & x_{n-2} & x_{n-1} \\
x_{n-1} & x_{n} & \ldots & x_{n-3} & x_{n-2} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
x_{2} & x_{3} & \ldots & x_{n} & x_{1}
\end{array}\right)
$$

Proof. It suffices to solve the matrix equation $A X-$ $X A=0$.

Remark 2.1. Two matrices belonging to a given centralizer do not necessarily commute. But in our case, given any circulant matrix $X$ commuting with $A$, its centralizer is $\mathcal{C}(X)=\mathcal{C}(A)$.

Definition 2.1. Two vectors $x=\left(x_{1}, \ldots, x_{n}\right)$ and $y=$ $\left(y_{1}, \ldots, y_{n}\right)$ in $\mathbb{F}^{n}$ are called orthogonal when $x \cdot y^{t}=$ 0 .

## Lemma 2.1.

$$
X \in \mathcal{C}(A)
$$

if, and only if,

$$
X^{t} \in \mathcal{C}(A)
$$

Proof. All circulant matrices satisfy $X X^{t}=X^{t} X$ (they are normal matrices) and the Lemma follows.

Proposition 2.2. If $F$ is $\varphi$-hyperinvariant subspace, $F^{\perp}$ is also an hyperinvariant subspace.

Proof. Given any $w \in F^{\perp}, v \in F, X \in \mathcal{C}(A)$, we wish to prove that $X w^{t} \in F^{\perp}$. Since

$$
\left(X w^{t}\right)^{t} v^{t}=w X^{t} v^{t}
$$

and taking into account Lemma 2.1 we have that $X^{t} v^{t} \in F$ and therefore:

$$
w X^{t} v^{t}=0
$$

We conclude that $X w^{t} \in F^{\perp}$ and $F^{\perp}$ is hyperinvariant.

Notice that if $v=\left(v_{1}, \ldots, v_{n}\right)$ is an eigenvector of $A$, then the following equalities hold:

$$
\begin{array}{r}
v_{n}=\lambda v_{1} \\
v_{1}=\lambda v_{2} \\
\cdots  \tag{3}\\
v_{n-2}=\lambda v_{n-1} \\
v_{n-1}=\lambda v_{n}
\end{array}
$$

In particular, we obtain that any eigenvector of $A$ has the form.

$$
v=\left(\lambda^{n-1}, \lambda^{n-2}, \ldots, \lambda, 1\right)
$$

We can derive the following Proposition.
Proposition 2.3. Given any $\lambda \in G F(q)^{*}$ such that $\lambda^{n}=1$, then $\left.[v]=\left[\lambda^{n-1}, \lambda^{n-2}, \ldots, \lambda, 1\right)\right]$, the vector subspace spanned by $v$, is an hyperinvariant subspace of $\varphi$.

Corollary 2.1. The subspace $F=[(1,1, \ldots, 1,1)]$ is hyperinvariant.

Euler-Fermat Theorem provides information about the roots of $\lambda^{n}-1$.

Theorem 2.1. If $\mathbb{F}=G F(q)$, then $\lambda^{q-1}=1$ has $q-1$ different roots.

Example 2.1. Consider $\mathbb{F}=G F(7)$ and $n=6$. The characteristic polynomial of $A$ has, in this particular set-up, six different roots. In particular, the eigenvalues of $A$ are $\lambda_{1}=1, \lambda_{2}=2, \lambda_{3}=3, \lambda_{4}=4, \lambda_{5}=5$, $\lambda_{6}=6$.

In general, we have the following result.
Proposition 2.4. Let $v$ be an eigenvector of $A$ corresponding to the simple eigenvalue $\alpha$. Then $v$ is an eigenvector of $X$ for all $X \in \mathcal{C}(A)$.

Proof. As a consequence of the definitions,

$$
A X v=X A v=X \alpha v=\alpha X v
$$

then $X v$ is the zero vector or it is an eigenvector of $A$ of eigenvalue $\alpha$ for all $X \in \mathcal{C}(A)$.
Taking into account that $\alpha$ is a simple root of the characteristic polynomial of $a$, we have that $X v=\lambda v$, and the proof is completed.

We can compute the value of the eigenvalue associated to $v$ as follows.
Let $v$ be an eigenvector of $A$ corresponding to the eigenvalue $\alpha$. Taking into account that $v \neq 0$ we can consider $v=\left(v_{1}, \ldots, v_{i-1}, 1, v_{i+1}, \ldots, v_{n}\right)$.

$$
\left(\begin{array}{ccccc}
x_{1} & x_{2} & \ldots & x_{n-1} & x_{n} \\
x_{n} & x_{1} & \ldots & x_{n-2} & x_{n-1} \\
x_{n-1} & x_{n} & \ldots & x_{n-3} & x_{n-2} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
x_{2} & x_{3} & \ldots & x_{n} & x_{1}
\end{array}\right)\left(\begin{array}{c}
v_{1} \\
\vdots \\
1 \\
\vdots \\
v_{n}
\end{array}\right)=\lambda\left(\begin{array}{c}
v_{1} \\
\vdots \\
1 \\
\vdots \\
v_{n}
\end{array}\right)
$$

Then $\lambda$ is equal to the $i$-th coordinate of $X v$, $x_{n-i+2} v_{1}+\ldots+x_{n-i+1} v_{n}$.
Not only one-dimensional invariant subspaces are hyperinvariant, but all invariant subspaces are also hyperinvariant.

Proposition 2.5. Let $F$ be a $\varphi$-invariant subspace. Then $F$ it is hyperinvariant.

Proof. It suffices to observe that, for all $X \in \mathcal{C}(A)$,

$$
X=x_{1} I+x_{2} A^{n-1}+\ldots+x_{n-1} A^{2}+x_{n} A
$$

Then $F$ is an invariant subspace of $X$.

### 2.2 Linear Cyclic Codes

Let us assume that characteristic of $\mathbb{F}$ does not divide the length of the code $n$. This assumption is an usual one in the theory of cyclic block-codes in order to guarantee that the polynomial $s^{n}-1$ factorize into different prime polynomials over $\mathbb{F}$.

Definition 2.2. A code $C$ of length $n$ over the field $\mathbb{F}$ is called cyclic if whenever $c=\left(a_{1}, \ldots, a_{n}\right)$ is in $C$, its cycle shift sc $=\left(a_{n}, a_{1}, \ldots, a_{n-1}\right)$ is also in $C$.

Example 2.2. The linear code $C=\{000,110,011$, $101\}$ over $G F(2)$ is cyclic. To prove that, we compute the shift sc for all $c \in C: s(000)=000, s(110)=$ 011, $s(011)=101$, and $s(101)=110$.

It is easy to prove the following statement from the Definitions.
Let $P_{3}$ be a full cycle permutation matrix obtained from the identity matrix $I_{3}$ by moving its first column to the last column (observe that $P_{3}$ corresponds to the matrix $A$ of Equation (2) for $n=3$ ). The shift $s c$ can be expressed as

$$
\left(\begin{array}{lll}
0 & 0 & 1 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right)\left(\begin{array}{llll}
0 & 1 & 0 & 1 \\
0 & 1 & 1 & 0 \\
0 & 0 & 1 & 1
\end{array}\right)=\left(\begin{array}{llll}
0 & 0 & 1 & 1 \\
0 & 1 & 0 & 1 \\
0 & 1 & 1 & 0
\end{array}\right)
$$

In general, the shift $s c$ can be expressed as $P_{n} c^{t}$ where $P_{n}$ is a full cycle permutation matrix obtained from the identity matrix $I_{n}$ by moving its first column to the last column.
Taking into account that $P_{n}$ is a linear transformation of $\mathbb{F}^{n}$ (the map $\varphi$ as defined in Equation (1)), we can construct a cyclic code, as follows. Take a word $c$, and consider the set $S$ consisting of $c$ and its successive images by $P_{n}$ :

$$
S=\left\{c^{t}, P_{n} c^{t}, \ldots, P_{n}^{n-1} c^{t}\right\}
$$

The linear subspace $C$, defined as the linear space spanned by $S, C=[S]$, is the smallest linear cyclic code containing $c$.
Next two Propositions are proved in [Radkova and Van-Zanten, 2009] and [Radkova, Bojilov and VanZanten, 2007].

Proposition 2.6. A linear code $C$ of length $n$ over the field $\mathbb{F}$ is cyclic if, and only if, $C$ is an $A$-invariant subspace of $\mathbb{F}^{n}$.

Proposition 2.7. Let $C$ be a cyclic code, and $p(s)=$ $(-1)^{n} p_{1}(s) \cdot \ldots \cdot p_{r}(s)$ the decomposition of $p(s)$ in prime factors. Then $C=\operatorname{Ker} p_{i_{1}}(A) \oplus \ldots \oplus \operatorname{Ker} p_{i_{s}}(A)$ for some minimal $\varphi$-invariant subspaces $\operatorname{Ker} p_{i_{j}}(A)$ of $\mathbb{F}^{n}$.

After Proposition 2.5 we deduce the following result.

Proposition 2.8. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is cyclic if, and only if, $C$ is an $A$ hyperinvariant subspace of $F^{n}$.

Example 2.3. Consider the matrix $A$ of $\varphi$ for $n=7$ and $q=2$. Then we have $p(s)=s^{7}+1$. Factorizing $p(s)$ into prime factors over $G F(2)$ we have that $p(s)=p_{1}(s) p_{2}(s) p_{3}(s)=(s+1)\left(s^{3}+s+1\right)\left(s^{3}+\right.$ $\left.s^{2}+1\right)$. The factors $p_{i}(s)$ define minimal $P_{n}$-invariant subspaces $F_{i}=\operatorname{Ker} p_{i}(A)$, for $i=1,2,3$.
We define a cyclic linear code $C$ by

$$
C=F_{1} \oplus F_{2}=\operatorname{Ker}\left(p_{1}(A)\right) \oplus \operatorname{Ker}\left(p_{2}(A)\right)
$$

$p_{1}(s) \cdot p_{2}(s)=s^{4}+s^{3}+s^{2}+1$ and $A^{4}+A^{3}+A^{2}+I$ is the following matrix

$$
\left(\begin{array}{lllllll}
1 & 0 & 0 & 1 & 1 & 1 & 0 \\
0 & 1 & 0 & 0 & 1 & 1 & 1 \\
1 & 0 & 1 & 0 & 0 & 1 & 1 \\
1 & 1 & 0 & 1 & 0 & 0 & 1 \\
1 & 1 & 1 & 0 & 1 & 0 & 0 \\
0 & 1 & 1 & 1 & 0 & 1 & 0 \\
0 & 0 & 1 & 1 & 1 & 0 & 1
\end{array}\right)
$$

$\operatorname{Ker}\left(A^{4}+A^{3}+A^{2}+I\right)=$
$[(1,0,1,1,0,0,0),(1,1,1,0,1,0,0),(1,1,0,0,0,1,0)$, $(0,1,1,0,0,0,1)]$.

## 3 Generalized Case

If $q>2$, we can generalize the above case as follows.

$$
\begin{aligned}
\varphi_{a, b, c}: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(a \cdot x_{n}, b \cdot x_{1}, c \cdot x_{2}, \ldots, c \cdot x_{n-1}\right)
\end{aligned}
$$

with associated matrix with respect to the standard basis,

$$
A_{a, b, c}=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a \\
b & 0 & \ldots & 0 & 0 \\
0 & c & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & c & 0
\end{array}\right)
$$

for $a, b, c$ such that $a b c \neq 0$.
The characteristic polynomial of $A_{a, b, c}$ is $p_{a, b, c}(s)=(-1)^{n}\left(s^{n}-c^{n-2} a b\right)$,

Proposition 3.1. The centralizer $\mathcal{C}\left(A_{a, b, c}\right)$ of $A_{a, b, c}$ is
the set of matrices $X_{a, b, c}$ with:

$$
\begin{aligned}
& X_{a, b, c}= \\
& \left(\begin{array}{ccccccc}
x_{n} & \frac{a}{b} x_{1} & \frac{a}{c} x_{2} & \frac{a}{c} x_{3} & \ldots & \frac{a}{c} x_{n-2} & \frac{a}{c} x_{n-1} \\
\frac{b}{c} x_{n-1} & x_{n} & \frac{a}{c} x_{1} & \frac{a b}{c^{2}} x_{2} & \ldots & \frac{a b}{c^{2}} x_{n-3} & \frac{a b}{c^{2}} x_{n-2} \\
\vdots & & \ddots & \ddots & & & \\
\vdots & & & \ddots & \ddots & & \\
\frac{b}{c} x_{3} & x_{4} & x_{5} & x_{6} & \ldots & \frac{a}{c} x_{1} & \frac{a b}{c^{2}} x_{2} \\
\frac{b}{c} x_{2} & x_{3} & x_{4} & x_{5} & \ldots & x_{n} & \frac{a}{c} x_{1} \\
x_{1} & x_{2} & x_{3} & x_{4} & \ldots & x_{n-1} & x_{n}
\end{array}\right)
\end{aligned}
$$

Proof. It suffices to solve the matrix equation $A_{a, b, c} X_{a, b, c}-X_{a, b, c} A_{a, b, c}=0$.

Notice that if $v=\left(v_{1}, \ldots, v_{n}\right)$ is an eigenvector of $A_{a, b, c}$, then:

$$
\begin{array}{r}
a v_{n}=\lambda v_{1} \\
b v_{1}=\lambda v_{2} \\
c v_{2}=\lambda v_{3} \ldots  \tag{4}\\
c v_{n-2}=\lambda v_{n-1} \\
c v_{n-1}=\lambda v_{n}
\end{array}
$$

In particular, we obtain that

$$
v=\left(\lambda^{n-1} b^{-1} c^{-(n-2)}, \lambda^{n-2} c^{-(n-2)}, \ldots, \lambda c^{-1}, 1\right)
$$

and we have the following Proposition.
Proposition 3.2. Let $\lambda \in G F(q)^{*}$ be an element such that $\lambda^{n}=a b c^{n-2}$. Then $[v]=$ $\left[\left(\lambda^{n-1} b^{-1} c^{-(n-2)}, \lambda^{n-2} c^{-(n-2)}, \ldots, \lambda c^{-1}, 1\right)\right]$ is an hyperinvariant subspace.

Proof.

$$
A_{a, b, c} v=\lambda v
$$

and given any $X_{a, b, c} \in \mathcal{C}\left(A_{a, b, c}\right)$, then

$$
\begin{aligned}
& X_{a, b, c} v= \\
& \left(x_{1} I+\frac{x_{2}}{c} A_{a, b, c}+\frac{x_{3}}{c^{2}} A_{a, b, c}^{2}+\ldots+\right. \\
& \left.+\frac{x_{n-1}}{c^{n-2}} A_{a, b, c}^{n-2}+\frac{x_{n}}{b^{n-2}} A_{a, b, c}^{n-1}\right) v= \\
& x_{1} v+\frac{x_{2}}{c} \lambda v+\frac{x_{3}}{c^{2}} \lambda^{2} v+\ldots+ \\
& +\frac{x_{n-1}}{c^{n-2}} \lambda^{n-2} v+\frac{x_{n}}{b c^{n-2}} \lambda^{n-1} v= \\
& \alpha v
\end{aligned}
$$

with $\alpha=x_{1}+\frac{x_{2}}{c} \lambda+\frac{x_{3}}{c^{2}} \lambda^{2}+\ldots++\frac{x_{n-1}}{c^{n-2}} \lambda^{n-2}+$ $\frac{x_{n}}{b c^{n-2}} \lambda^{n-1} \in \mathbb{F}$.

Proposition 3.3. Let $F$ be an invariant subspace of $A_{a, b, c}$. Then $F$ is hyperinvariant.

Proof. It suffices to observe that, for all $X_{a, b, c} \in$ $\mathcal{C}\left(A_{a, b, c}\right)$ then

$$
\begin{aligned}
& X_{a, b, c}= \\
& x_{1} I+\frac{x_{2}}{c} A_{a, b, c}+\frac{x_{3}}{c^{2}} A_{a, b, c}^{2}+\ldots+ \\
& \quad \frac{x_{n-1}}{c^{n-2}} A_{a, b, c}^{n-2}+\frac{x_{n}}{b c^{n-2}} A_{a, b, c}^{n-1} .
\end{aligned}
$$

Therefore, we have that in this case the lattices of invariant and hyperinvariant subspaces are equal,i.e.:

$$
\operatorname{Hinv}\left(A_{a, b, c}\right)=\operatorname{Inv}\left(A_{a, b, c}\right)
$$

### 3.1 Particular Case $b=1$

Notice that it suffices to solve the case $b=1$ because:

$$
A_{a, b, c} X-X A_{a, b, c}=D\left(A_{a / b, 1, c / b} X-X A_{a / b, 1, c / b}\right)
$$

with $D=\operatorname{diag}(b)$.
So, we write the results in this simpler case.
Given $a, c \neq 0$, we consider the following linear map:

$$
\begin{aligned}
\varphi_{a, c}: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(a \cdot x_{n}, x_{1}, c \cdot x_{2} \ldots, c \cdot x_{n-1}\right)
\end{aligned}
$$

with associated matrix with respect to the standard basis,

$$
A_{a, c}=\left(\begin{array}{cccccc}
0 & 0 & 0 & \ldots & 0 & a \\
1 & 0 & 0 & \ldots & 0 & 0 \\
0 & c & 0 & \ldots & 0 & 0 \\
0 & 0 & c & \ldots & 0 & 0 \\
\vdots & & \ddots & & \\
0 & 0 & 0 & \ldots & c & 0
\end{array}\right)
$$

The characteristic polynomial of $A_{a, c}$ is $p_{a, c}(s)=(-1)^{n}\left(s^{n}-c^{n-2} a\right)$,

Proposition 3.4. The centralizer $\mathcal{C}\left(A_{a, c}\right)$ of $A_{a, c}$ is the set of matrices $X_{a, c}$ with:

$$
\begin{aligned}
& X_{a, c}= \\
& \left(\begin{array}{ccccccc}
x_{n} & a x_{1} & \frac{a}{c} x_{2} & \frac{a}{c} x_{3} & \ldots & \frac{a}{c} x_{n-2} & \frac{a}{c} x_{n-1} \\
\frac{1}{c} x_{n-1} & x_{n} & \frac{a}{c} x_{1} & \frac{a}{c^{2}} x_{2} & \ldots & \frac{a}{c^{2}} x_{n-3} & \frac{a}{c^{2}} x_{n-2} \\
\vdots & & \ddots & \ddots & & & \\
\vdots & & & \ddots & \ddots & & \\
\frac{1}{c} x_{3} & x_{4} & x_{5} & x_{6} & \ldots & \frac{a}{c} x_{1} & \frac{a}{c^{2}} x_{2} \\
\frac{1}{c} x_{2} & x_{3} & x_{4} & x_{5} & \ldots & x_{n} & \frac{a}{c} x_{1} \\
x_{1} & x_{2} & x_{3} & x_{4} & \ldots & x_{n-1} & x_{n}
\end{array}\right)
\end{aligned}
$$

Proof. It follows from Proposition 3.1, when $b=1$.

Notice that if $v=\left(v_{1}, \ldots, v_{n}\right)$ is an eigenvector of $A_{a, c}$, then:

$$
\begin{array}{r}
a v_{n}=\lambda v_{1} \\
v_{1}=\lambda v_{2}  \tag{5}\\
\cdots \\
c v_{n-2}=\lambda v_{n-1} \\
c v_{n-1}=\lambda v_{n}
\end{array}
$$

In particular, we obtain that

$$
v=\left(\lambda^{n-1} c^{-(n-2)}, \lambda^{n-2} c^{-(n-2)}, \ldots, \lambda^{-1}, 1\right)
$$

and we have the following Proposition.
Proposition 3.5. Given any $\lambda \in G F(q)^{*}$ such that $\lambda^{n}=a c^{n-2}$, then $v=$ $\left(\lambda^{n-1} c^{-(n-2)}, \lambda^{n-2} c^{-(n-2)}, \ldots, \lambda c^{-1}, 1\right)$ is an hyperinvariant subspace.

Proposition 3.6. Let $F$ be an invariant subspace of $A_{a, c}$. Then it is hyperinvariant.

Proof. It suffices from Proposition 3.3 that for all $X_{a, c} \in \mathcal{C}\left(A_{a, c}\right)$ then

$$
\begin{aligned}
& X_{a, c}= \\
& x_{1} I+\frac{x_{2}}{c} A_{a, c}+\frac{x_{3}}{c^{2}} A_{a, c}^{2}+\ldots+ \\
& \quad \frac{x_{n-1}}{c^{n-2}} A_{a, c}^{n-2}+\frac{x_{n}}{c^{n-2}} A_{a, c}^{n-1} .
\end{aligned}
$$

### 3.2 Two-parametric Quasi-Cyclic Codes

In this section, we will to generalize the concept of constacyclic code as follows.
Definition 3.1. Let $a, c$ be two nonzero elements of $\mathbb{F}$. $A$ code $C$ with length $n$ over the field $\mathbb{F}$ is called generalized constancyclic code if whenever $c=\left(a_{1}, \ldots, a_{n}\right)$ is in $C$, so is $s c=\left(a \cdot a_{n}, a_{1}, c \cdot a_{2} \ldots, c \cdot a_{n-1}\right)$.
As immediate consequence of definition we have the following Proposition.

Proposition 3.7. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is generalized constancyclic if, and only if, $C$ is an $A_{a, c}$-invariant subspace of $\mathbb{F}^{n}$.

After Proposition 3.6 we have the following result.
Proposition 3.8. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is two-parameter cyclic if, and only if, $C$ is a $A_{a, c}$-hyperinvariant subspace of $\mathbb{F}^{n}$.
Suppose now that $(n, q)=1$ and $p_{a, c}(s)=$ $(-1)^{n}\left(s^{n}-c^{n-2} a\right)$ has no multiple roots and splits into distinct irreducible monic factors.

Proposition 3.9. Let $C$ be generalized constancyclic code, and $p_{a, c}(s)=(-1)^{n} p_{a, c_{1}}(s) \cdot \ldots \cdot p_{a, c_{r}}(s)$ the decomposition of $p_{a, c}(s)$ in irreducible factors. Then $C=\operatorname{Ker} p_{a, c_{i_{1}}}\left(A_{a, c}\right) \oplus \ldots \oplus \operatorname{Ker} p_{a, c_{i_{s}}}\left(A_{a, c}\right)$ for some minimal $A_{a, c}$-invariant subspaces $\operatorname{Ker} p_{a, c_{i_{j}}}\left(A_{a, c}\right)$ of $\mathbb{F}^{n}$.

Proof. First, it is easy to see that $\operatorname{Ker} p_{a, c_{i}}\left(A_{a, c}\right)$ for $i=1, \ldots, r$ are $A_{a, c}$-invariant: let $v \in \operatorname{Ker} p_{a, c_{i}}\left(A_{a, c}\right)$ then $A_{a, c} v=p_{a, c_{1}}\left(A_{a, c}\right) \cdot \ldots \cdot p_{a, c_{r}}\left(A_{a, c}\right) v=0$.
The subspaces $\operatorname{Ker} p_{a, c_{i_{j}}}\left(A_{a, c}\right)$ are minimal because the polynomials $p_{a, c_{i}}(s)$ are irreducible.
Now, we define $\widehat{p}_{i}(s)=p_{a, c}(s) / p_{a, c_{i}}(s)$. Taking into account $\left(\widehat{p}_{1}(s), \ldots, \widehat{p}_{r}(s)\right)=1$, there exist polynomials $q_{1}(s), \ldots, q_{r}(s)$ such that $q_{1}(s) \widehat{p}_{1}(s)+\ldots+$ $q_{r}(s) \widehat{p}_{r}(s)=1$.
Let $x \in C$, then $x=q_{1}\left(A_{a, c}\right) \widehat{p}_{1}\left(A_{a, c}\right) x+\ldots+$ $q_{r}\left(A_{a, c}\right) \widehat{p}_{r}\left(A_{a, c}\right) x$. Calling $x_{i}=q_{i}\left(A_{a, c}\right) \widehat{p}_{i}\left(A_{a, c}\right) x$ and taking into account that $C$ is $A_{a, c}$-invariant, and that $x_{i} \in \operatorname{Ker} p_{a, c_{i}}\left(A_{a, c}\right)$ we have that $x_{i} \in C \cap$ $\operatorname{Ker} p_{a, c_{i}}\left(A_{a, c}\right)$.
Example 3.1. Consider the matrix $A_{a=2, c=4}$ for $n=8, q=5$. Then we have $p(s)=$ $p_{a=2, c=4}(s)=s^{8}-1$. Factorizing $p(s)$ into irreducible factors over $\mathbb{F}=G F(5)$ we have $p(s)=$ $p_{1}(s) p_{2}(s) p_{3}(s) p_{4}(s) p_{5}(s) p_{6}(s)=(s+1)(s+2)(s+$ $3)(s+4)\left(s^{2}+2\right)\left(s^{2}+3\right)$. The factors $p_{i}(s)$ define minimal $A_{a, c}$-invariant subspaces $F_{i}=\operatorname{Ker} p_{i}\left(A_{a, c}\right)$, for $i=1,2,3,4,5,6$.
We define a generalized constancyclic linear code $C_{a, c}$ by

$$
C_{a, c}=F_{1} \oplus F_{5}=\operatorname{Ker}\left(p_{1}\left(A_{a, c}\right)\right) \oplus \operatorname{Ker}\left(p_{5}\left(A_{a, c}\right)\right)
$$

$p_{1}(s) \cdot p_{5}(s)=s^{3}+s^{2}+2 s+2$ and $A_{a, c}^{3}+A_{a, c}^{2}+$ $2 A_{a, c}+2 I$ is the following matrix

$$
\left(\begin{array}{llllllll}
2 & 0 & 0 & 0 & 0 & 1 & 3 & 3 \\
2 & 2 & 0 & 0 & 0 & 0 & 3 & 4 \\
2 & 4 & 2 & 0 & 0 & 0 & 0 & 3 \\
4 & 4 & 4 & 2 & 0 & 0 & 0 & 0 \\
0 & 3 & 4 & 4 & 2 & 0 & 0 & 0 \\
0 & 0 & 3 & 4 & 4 & 2 & 0 & 0 \\
0 & 0 & 0 & 3 & 4 & 4 & 2 & 0 \\
0 & 0 & 0 & 0 & 3 & 4 & 4 & 2
\end{array}\right)
$$

$$
\begin{aligned}
& \operatorname{Ker}\left(A_{a, c}^{3}+A_{a, c}^{2}+2 A_{a, c}+2 I\right)= \\
& {[(1,4,2,1,3,4,2,1),(1,0,4,0,2,0,1,0),} \\
& \quad(0,3,0,4,0,2,0,1)]
\end{aligned}
$$

### 3.3 Particular Case: $b=c=1$

$$
\begin{aligned}
\varphi_{a}: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(a \cdot x_{n}, x_{1}, \ldots, x_{n-1}\right)
\end{aligned}
$$

where $a \neq 0$ and associated matrix respect to the standard basis,

$$
A_{a}=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a \\
1 & 0 & \ldots & 0 & 0 \\
0 & 1 & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & 1 & 0
\end{array}\right)
$$

This linear map verifies $A_{a}^{-1}=A_{1 / a}^{t}$. The characteristic polynomial is

$$
p(s)=\operatorname{det}\left(A_{a}-s I_{n}\right)=(-1)^{n}\left(s^{n}-a\right) .
$$

Proposition 3.10. The centralizer $\mathcal{C}\left(A_{a}\right)$ of $A_{a}$ is the set of matrices

$$
X_{a}=\left(\begin{array}{ccccc}
x_{1} & a x_{2} & \ldots & a x_{n-1} & a x_{n} \\
x_{n} & x_{1} & \ldots & a x_{n-2} & a x_{n-1} \\
x_{n-1} & x_{n} & \ldots & a x_{n-3} & a x_{n-2} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
x_{2} & x_{3} & \ldots & x_{n} & x_{1}
\end{array}\right)
$$

Proof. Is a particular case of Proposition 3.1.
Remark 3.1. If $X_{a} \in \mathcal{C}\left(A_{a}\right)$ then $X_{a}^{t} \in \mathcal{C}\left(A_{1 / a}\right)$. For that, it suffices to observe suffices to observe that

$$
X_{a}^{t}=\left(\begin{array}{ccccc}
x_{1} & \frac{1}{a} x_{n} & \ldots & \frac{1}{a} x_{3} & \frac{1}{a} x_{2} \\
x_{2} & x_{1} & \ldots & \frac{1}{a} x_{n-3} & \frac{1}{a} x_{n-2} \\
x_{3} & x_{2} & \ldots & \frac{1}{a} x_{n-3} & \frac{1}{a} x_{n-2} \\
\vdots & \vdots: & \vdots & \ddots & \vdots \\
x_{n} & x_{n-1} & \ldots & x_{2} & x_{1}
\end{array}\right) \in \mathcal{C}\left(A_{1 / a}\right)
$$

where $y_{1}=x_{1}$ and $y_{i}=a x_{i}$ for all $i \neq 1$.
Proposition 3.11. Let $F$ be a hyperinvariant subspace of $A_{a}$. Then, $F^{\perp}$ is a hyperinvariant subspace of $A_{1 / a}$.

Proof. Given any $w \in F^{\perp}, c \in F, X \in \mathcal{C}\left(A_{a}\right)$, if $\left(w^{\prime}\right)^{t}=X^{t} w^{t}$ then, we have:

$$
w^{\prime} c^{t}=w X c^{t}=0
$$

and then $X^{t} w^{t}=\left(w^{\prime}\right)^{t} \in F^{\perp}$ and $F^{\perp}$ is invariant for any matrix in $\mathcal{C}\left(A_{1 / a}\right)$; that is to say, it is an hyperinvariant subspace for $A_{1 / a}$.

Notice that if $v=\left(v_{1}, \ldots, v_{n}\right)$ is an eigenvector of $A_{a}$, then the following equalities hold:

$$
\begin{array}{r}
a v_{n}=\lambda v_{1} \\
v_{1}=\lambda v_{2}  \tag{6}\\
\ldots \\
v_{n-2}=\lambda v_{n-1} \\
v_{n-1}=\lambda v_{n}
\end{array}
$$

In particular, we obtain that

$$
v=\left(\lambda^{n-1}, \lambda^{n-2}, \ldots, \lambda, 1\right)
$$

and we have the following Proposition.

Proposition 3.12. Given any $\lambda \in G F(q)^{*}$ such that $\lambda^{n}=a$, then $[v]=\left[\left(\lambda^{n-1}, \lambda^{n-2}, \ldots, \lambda, 1\right)\right]$ is an hyperinvariant subspace.

Proposition 3.13. Let $F$ be an invariant subspace of $A_{a}$. Then it is hyperinvariant.

Proof. It suffices to observe that, for all $X_{a} \in \mathcal{C}\left(A_{a}\right)$,

$$
X_{a}=x_{1} I+x_{2} A_{a}+\ldots+x_{n-1} A_{a}^{n-2}+x_{n} A_{a}^{n-1}
$$

Example 3.2. Over $\mathbb{F}=G F(5)$ we consider

$$
A_{2}=\left(\begin{array}{lll}
0 & 0 & 2 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right)
$$

$F=[(1,2,4)]$ is invariant

$$
\left(\begin{array}{lll}
0 & 0 & 2 \\
1 & 0 & 0 \\
0 & 1 & 0
\end{array}\right)\left(\begin{array}{l}
1 \\
2 \\
4
\end{array}\right)=3\left(\begin{array}{l}
1 \\
2 \\
4
\end{array}\right)
$$

and also it is hyperinvariant

$$
\left(\begin{array}{ccc}
x_{1} & 2 x_{2} & 2 x_{3} \\
x_{3} & x_{1} & 2 x_{2} \\
x_{2} & x_{3} & x_{1}
\end{array}\right)\left(\begin{array}{l}
1 \\
2 \\
4
\end{array}\right)=\left(x_{1}+4 x_{2}+3 x_{3}\right)\left(\begin{array}{l}
1 \\
2 \\
4
\end{array}\right) .
$$

Notice that in fact we have solved the following slightly more general case with $b=c$

$$
\begin{aligned}
\varphi_{a b}: \mathbb{F}^{n} & \longrightarrow \mathbb{F}^{n} \\
\left(x_{1}, \ldots, x_{n}\right) & \longrightarrow\left(a \cdot x_{n}, b \cdot x_{1}, \ldots, b \cdot x_{n-1}\right)
\end{aligned}
$$

with associated matrix with respect to the standard basis,

$$
A_{a b}=\left(\begin{array}{ccccc}
0 & 0 & \ldots & 0 & a \\
b & 0 & \ldots & 0 & 0 \\
0 & b & \ldots & 0 & 0 \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & \ldots & b & 0
\end{array}\right) .
$$

for $a, b$ such that $a b \neq 0$ because of

$$
A_{a, b} X-X A_{a, b}=D\left(A_{a / b} X-X A_{a / b}\right)
$$

with $D=\operatorname{diag}(b)$.

### 3.4 Constacyclic Codes

A particular case of generalized constacyclic codes are constancyclic codes which were introduced in [Berlekamp, 1968].

Definition 3.2. Let a be a nonzero element of $\mathbb{F}$. A code $C$ with length $n$ over the field $\mathbb{F}$ is called constacyclic with respect to $a$ if whenever $c=\left(a_{1}, \ldots, a_{n}\right)$ is in $C$, so is its cycle constashift sc $=(a$. $\left.a_{n}, a_{1}, \ldots, a_{n-1}\right)$.

Obviously, when $a=1$ the constacyclic code is cyclic.
The constashift $s c$ can be expressed as $P_{a_{n}} c^{t}$ where $P_{a_{n}}$ is a generalized full cycle permutation matrix obtained from the identity matrix $I_{n}$ by moving its first column multiplied by $a$ to the last column.

$$
P_{a_{n}}=\left(\begin{array}{cccccc}
0 & 0 & \ldots & 0 & a \\
1 & 0 & & 0 & 0 \\
\vdots & \ddots & & \vdots & \vdots \\
0 & 0 & \ldots & 1 & 0
\end{array}\right)
$$

According to [Radkova and Van-Zanten, 2009], we have the following Propositions.

Proposition 3.14. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is constacyclic if, and only if, $C$ is an $P_{a_{n}}$ invariant subspace of $\mathbb{F}^{n}$.
Suppose now that $(n, q)=1$ and $p_{a}(s)=(-1)^{n}\left(s^{n}-\right.$ a) has no multiple roots and splits into distinct irreducible monic factors.

Proposition 3.15. Let $C$ be a constacyclic code, and $p_{a}(s)=(-1)^{n} p_{a_{1}}(s) \cdot \ldots \cdot p_{a_{r}}(s)$ the decomposition of $p_{a}(s)$ in irreducible factors. Then $C=\operatorname{Ker} p_{a_{i_{1}}}(A) \oplus$ $\ldots \oplus \operatorname{Ker} p_{a_{i_{s}}}(A)$ for some minimal $\varphi_{a}$-invariant subspaces $\operatorname{Ker} p_{a_{i_{j}}}(A)$ of $\mathbb{F}^{n}$.
After Proposition 3.13 we deduce the following result.
Proposition 3.16. A linear code $C$ with length $n$ over the field $\mathbb{F}$ is constacyclic if and only if $C$ is an $A_{a}$ hyperinvariant subspace of $\mathbb{F}^{n}$.

Example 3.3. Consider the matrix $A_{a=4}$ for $n=8$, $q=5$. Then we have $p(s)=s^{8}-4$. Factorizing $p(s)$ into irreducible factors over GF(5) we have $p(s)=$ $p_{1}(s) p_{2}(s)=\left(s^{4}-2\right)\left(s^{4}+2\right)$. The factors $p_{i}(s)$ define minimal $P_{a_{n}}$-invariant subspaces $F_{i}=\operatorname{Ker} p_{i}\left(A_{a}\right)$, for $i=1,2$.

We define a constacyclic linear code $C_{a}$ by

$$
C_{a}=F_{1}=\operatorname{Ker}\left(p_{1}(A)\right)
$$

$p_{1}(s)=s^{4}-2$ and $A^{4}-2 I$ is the following matrix

$$
\left(\begin{array}{llllllll}
3 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\
0 & 3 & 0 & 0 & 0 & 4 & 0 & 0 \\
0 & 0 & 3 & 0 & 0 & 0 & 4 & 0 \\
0 & 0 & 0 & 3 & 0 & 0 & 0 & 4 \\
1 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 3 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 & 3 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 & 0 & 3
\end{array}\right)
$$

$\operatorname{Ker}\left(A^{4}-2 I\right)=$
$[(2,0,0,0,1,0,0,0),(0,2,0,0,0,1,0,0)$,

$$
(0,0,2,0,0,0,1,0),(0,0,0,2,0,0,0,1)] .
$$

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