# Averaging of kernel functions 

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#### Abstract

In kernel-based machines, the integration of several kernels to build more flexible learning methods is a promising avenue for research. In particular, in Multiple Kernel Learning a compound kernel is build by learning a kernel that is the weighted mean of several sources. We show in this paper that the only feasible average for kernel learning is precisely the arithmetic average. We also show that three familiar means (the geometric, inverse root mean square and harmonic means) for positive real values actually generate valid kernels.


## 1 Introduction

Kernel methods have won great popularity as a tool for the identification of nonlinear systems. Support Vector Machines (SVMs) are basic kernel-based methods that are used for tasks such as classification and regression, among others [1]. Perhaps the biggest limitation of kernel-based methods lies in the choice of a proper kernel for a given problem.

The kernel function is a very flexible container under which to express knowledge about the problem. One way of tayloring kernels is developing partial kernels (e.g., one for every descriptive variable) and building a final kernel as the composition or aggregation of these partial kernels, an idea that can be traced back to Vapnik [2]. Once these are built, the final obtained kernel is the one used in the SVM. How can this aggregation process be defined? A natural idea is to use a (possibly weighted) average of the partial kernels. We show that, for a wide family of averages (including the familiar means), the only average guaranteeing that the aggregated function is always a valid kernel is the arithmetic average, and give an easy-to-ckeck necessary condition for even more general averages. In addition, we show that three of the familiar means (the geometric, inverse root mean square and harmonic means) are generators of valid kernels.

## 2 Preliminaries

Probably the simplest characterization for a symmetric function $K: \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}$ being a kernel is via the matrix it generates on finite subsets [1].

Definition 1 In the real case, the symmetric matrix $A_{n \times n}$ is positive semidefinite (PSD) if, for all vectors $z \in \mathbb{R}^{n}, z^{\prime} A z \geq 0$.

Theorem 1 The function $K: \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}$ is a kernel in $\mathcal{H}$ if and only if for any positive $p \in \mathbb{N}$ and choice of finite subsets $\left\{x_{1}, x_{2}, \ldots, x_{p}\right\} \subset \mathcal{H}$, the associated matrix $K_{p \times p}=\left(k_{i j}\right)$, where $k_{i j}=K\left(x_{i}, x_{j}\right)$ is a symmetric PSD matrix.

Definition 2 Let $[a, b]$ be a non-empty real interval. Call $A\left(x_{1}, \ldots, x_{n}\right)$ the $A$-average of $x_{1}, \ldots, x_{n} \in[a, b]$ to every $n$-place real function $A$ fulfilling:

Axiom A1. $A$ is continuous, symmetric and strictly increasing in each $x_{i}$.
Axiom A2. $A(x, \ldots, x)=x$.
Axiom A3. For any $k \leq n: A\left(x_{1}, \ldots, x_{n}\right)=A(\underbrace{y_{k}, \ldots, y_{k}}_{k \text { times }}, x_{i_{k+1}}, \ldots, x_{i_{n}})$ where $y_{k}=A\left(x_{i_{1}}, \ldots, x_{i_{k}}\right)$ and $\left(i_{1}, \ldots, i_{n}\right)$ is a permutation of $(1, \ldots, n)$.

The means defined by these axioms fulfill Cauchy's property of means, namely, that $\min x_{i} \leq A\left(x_{1}, \ldots, x_{n}\right) \leq \max x_{i}$ (the proof is straightforward using axioms A1 and A2). A further interesting property of these means is that we can add averaged elements to an A-average without changing the overall result. Formally, $A\left(x_{1}, \ldots, x_{n}\right)=A\left(z_{1}, \ldots, z_{m}, x_{1}, \ldots, x_{n}\right)$ if and only if $A\left(z_{1}, \ldots, z_{m}\right)=A\left(x_{1}, \ldots, x_{n}\right)$. As a consequence, if $y=A\left(x_{1}, \ldots, x_{n}\right)$, then $A\left(x_{1}, \ldots, x_{n}, A\left(x_{1}, \ldots, x_{n}\right)\right)=y$.

Theorem 2 ([3]) Let $f:[a, b] \longrightarrow \mathbb{R}$ be a continuous, strictly monotone mapping. Let $g$ be the inverse function of $f$. Then,

$$
A\left(x_{1}, \ldots, x_{n}\right) \equiv g\left(\frac{1}{n} \sum_{i=1}^{n} f\left(x_{i}\right)\right)
$$

is a well-defined $A$-average for all $n \in \mathbb{N}$ and $x_{i} \in[a, b]$.
An important class of A-averages is formed by choosing $f(z)=z^{q}, q \in \mathbb{R}$ :

$$
M_{q}\left(x_{1}, \ldots, x_{n}\right)=\left(\frac{1}{n} \sum_{i=1}^{n}\left(x_{i}\right)^{q}\right)^{\frac{1}{q}}
$$

Several well-known means (usually called generalized means) are derived by choosing particular values of $q$. Specifically, the arithmetic mean for $q=1$, the geometric mean for $q=0$, the root mean square or RMS mean for $q=2$ and the harmonic mean for $q=-1$. A property of the means $M_{q}$ is that, for $q \neq q^{\prime}, M_{q}\left(x_{1}, \ldots, x_{n}\right) \geq M_{q^{\prime}}\left(x_{1}, \ldots, x_{n}\right)$ if and only if $q>q^{\prime}$, with equality only if $x_{1}=x_{2}=\ldots=x_{n}$. A substantial part of the classic book by Hardy et al [4] is devoted to the study of these functions and their applications.

## 3 A-averages as kernel aggregators

It is a well-known fact that the sum of $m>0$ kernels is again a kernel. Therefore the arithmetic average (function $M_{1}$ in the notation of this paper) is a valid kernel aggregator. The product of $m>0$ kernels is also a kernel. However, the product is not an average; it requires the application of the $m$-root to the result to form the geometric mean (function $M_{0}$ ). Is there any other generalized mean guaranteeing this kernel property? As we shall see in the remaining of this
section, the answer is 'no'. Given that this is a rather broad class of averaging functions, the result can be considered as a negative one.

It is convenient to express the aggregation in terms of a collection of a number $m$ of PSD matrices: for $k=1, \ldots, m$, let $A_{k}=\left(a_{i j}^{k}\right)$ represent $n \times n$ PSD real matrices. Given $f: \mathbb{R}^{m} \rightarrow \mathbb{R}$, define the $n \times n$ real matrix $\bar{A}=\left(f\left(a_{i j}^{1}, \ldots a_{i j}^{m}\right)\right)$.

Definition $3 A$ function $h: \mathbb{C}^{m} \rightarrow \mathbb{C}$ in the form
$h\left(x_{1}+i y_{1}, \ldots, x_{m}+i y_{m}\right)=P\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}\right)+i Q\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}\right)$
with $x_{i}, y_{i} \in \mathbb{R}$ is said to be entire if it is holomorphic on all $\mathbb{C}^{m}$, i.e., it is continuous and differentiable in each complex variable on all $\mathbb{C}^{m}$, and satisfies the Cauchy-Riemann equations in each complex variable:

$$
\begin{aligned}
\frac{\partial P}{\partial x_{i}}\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) & =+\frac{\partial Q}{\partial y_{i}}\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) \\
\frac{\partial P}{\partial y_{i}}\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) & =-\frac{\partial Q}{\partial x_{i}}\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) \\
\text { for each }\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) & \in \mathbb{C}^{m}, i=1, \ldots, m .
\end{aligned}
$$

Definition $4 A$ function $f: \mathbb{R}^{m} \rightarrow \mathbb{R}$ is said to be real entire if it is real on $\mathbb{R}^{m}$ and it is the restriction on $\mathbb{R}^{m}$ of an entire function $h$ defined on $\mathbb{C}^{m}$ :

$$
f\left(x_{1}, \ldots, x_{m}\right) \equiv \operatorname{Re}\left(h\left(x_{1}, \ldots, x_{m}, 0, \ldots, 0\right)\right)
$$

Proposition 1 Let $f: \mathbb{R}^{m} \longrightarrow \mathbb{R}$, the condition of differentiability on all $\mathbb{R}^{m}$ is necessary for the function $f$ to be real entire.

Proof. Let $f$ be non-differentiable at least in a point $\left(\bar{x}_{1}, \ldots, \bar{x}_{m}\right) \in \mathbb{R}^{m}$ and suppose that $f$ is real entire, i.e. there exists an entire function $h: \mathbb{C}^{m} \rightarrow \mathbb{C}$,

$$
\begin{gathered}
h\left(z_{1}, \ldots, z_{m}\right)=h\left(x_{1}+i y_{1}, \ldots, x_{m}+i y_{m}\right)= \\
=P\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}\right)+i Q\left(x_{1}, \ldots, x_{m}, y_{1}, \ldots, y_{m}\right)
\end{gathered}
$$

such that $f\left(x_{1}, \ldots, x_{m}\right) \equiv \operatorname{Re}\left(h\left(x_{1}, \ldots, x_{m}, 0, \ldots, 0\right)\right)$. Since $h$ is entire, all the partial derivatives $\frac{\partial}{\partial x_{i}} P\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right)$ exist and are continuous in each $\left(x_{1}^{0}, \ldots, x_{m}^{0}, y_{1}^{0}, \ldots, y_{m}^{0}\right) \in \mathbb{C}^{m}$, and in particular in $\left(\bar{x}_{1}, \ldots, \bar{x}_{m}, 0, \ldots, 0\right)$. However, $\frac{\partial}{\partial x_{i}} P\left(\bar{x}_{1}, \ldots, \bar{x}_{m}, 0, \ldots, 0\right)=\frac{\partial}{\partial x_{i}}\left(\operatorname{Re}\left(h\left(\bar{x}_{1}, \ldots, \bar{x}_{m}, 0, \ldots, 0\right)\right)\right)$, which, being equal to $\frac{\partial}{\partial x_{i}} f\left(\bar{x}_{1}, \ldots, \bar{x}_{m}\right)$, leads to an absurd.

Define now $\mathbb{Z}_{+}^{m}$ to mean all vectors in $\mathbb{Z}^{m}$ with nonnegative coordinates. For $\mathbf{x} \in \mathbb{R}^{m}$ and $\alpha \in \mathbb{Z}_{+}^{m}$, we use the standard notation $\mathbf{x}^{\alpha}=x_{1}^{\alpha_{1}} \cdots x_{m}^{\alpha_{m}}$. We now use the notion of a real entire function to characterize a general $A$-average function as a kernel aggregator thanks to the following theorem [5]:

Theorem 3 Let $f: \mathbb{R}^{m} \longrightarrow \mathbb{R}$. Then a matrix $\bar{A}$ generated by $f$ as above is PSD if and only if $f$ is a real entire function of the form $f(\boldsymbol{x})=\sum_{\alpha \in \mathbb{Z}_{+}^{m}} c_{\alpha} \boldsymbol{x}^{\alpha}, \boldsymbol{x} \in \mathbb{R}^{m}$, where $c_{\alpha} \geq 0$ for all $\alpha \in \mathbb{Z}_{+}^{m}$.

Application 1 (Generalized means) We apply the previous results to the Aaverage functions of the type $M_{q}$, as defined above. With $q=1$, it is plain to see that $M_{1}$ defines a matrix $\bar{A}$ that is a kernel, so we start with $M_{2}$ and $m=2$. Let $A_{1}=\left(a_{i j}^{1}\right), A_{2}=\left(a_{i j}^{2}\right)$ and consider the matrix $\bar{A}=\left(M_{2}\left(a_{i j}^{1}, a_{i j}^{2}\right)\right)=$ $\left(\left[\frac{1}{2}\left(\left(a_{11}^{1}\right)^{2}+\left(a_{11}^{2}\right)^{2}\right)\right]^{1 / 2}\right)$. Using Theorem 3, $f$ should be real entire; according to Proposition 1 we verify the differentiability of $M_{2}$ on $\mathbb{R}^{2}$ :

$$
\frac{\partial M_{2}\left(x_{1}, x_{2}\right)}{\partial x_{1}}=\frac{x_{1}}{\left(x_{1}^{2}+x_{2}^{2}\right)} ; \quad \frac{\partial M_{2}\left(x_{1}, x_{2}\right)}{\partial x_{2}}=\frac{x_{2}}{\left(x_{1}^{2}+x_{2}^{2}\right)}
$$

The partial derivatives of $M_{2}$ are not defined in $\boldsymbol{O} \in \mathbb{R}^{2}$, so $M_{2}$ is not real entire.
For general values of $q \neq 1$ and $m>0$ the matrix $\bar{A}_{n \times n}$ is in general not PSD because $M_{q}$ is not a real entire function. Indeed, the partial derivatives

$$
\frac{\partial M_{q}\left(x_{1}, \ldots, x_{m}\right)}{\partial x_{i}}=\left(x_{i}\right)^{q-1}\left(\frac{1}{m} \sum_{j=1}^{m}\left(x_{j}\right)^{q}\right)^{\frac{1}{q}-1}, \quad i=1, \ldots, m
$$

are never defined in $\boldsymbol{0} \in \mathbb{R}^{n}$ : for $q<1$ the first factor is a null denominator, whereas for $q>1$ the second factor is a null denominator. For $q=1$, the derivatives evaluate to 1 everywhere, showing that only $M_{1}$ is a valid choice.

Application 2 (Hyperbolic sine mean) Consider the real entire function $\sinh (x)$, continuous and monotonic on $\mathbb{R}$, and not expressable as a member of the $M_{q}$ family of means. Its inverse arcsinh $(x)$ is again a real entire function, because it is the restriction of the entire function $\operatorname{arcsinh}(z)=\ln \left(z \sqrt{1+z^{2}}\right), z \in \mathbb{C}$. $A$ valid average can be defined as:

$$
f_{\sinh }\left(x_{1}, x_{2}\right):=\operatorname{arcsinh}\left(\frac{\sinh \left(x_{1}\right)+\sinh \left(x_{2}\right)}{2}\right)
$$

This is a real entire function since it is the composition of real entire functions. However, its Taylor expansion has negative coefficients (the $c_{\alpha}$ in Theorem 3):

$$
f_{\sinh }\left(x_{1}, x_{2}\right)=\frac{1}{2} x_{1}+\frac{1}{2} x_{2}+\frac{1}{16} x_{1}^{3}-\frac{1}{16} x_{1}^{2} x_{2}-\frac{1}{16} x_{1} x_{2}^{2}+\frac{1}{16} x_{2}^{3}+O\left(x_{1}, x_{2}\right)^{4}
$$

Since an holomorphic function has a unique expansion as a power series [6], we conclude that this average is not a valid kernel aggregator.

## 4 Generalized means as kernel generators

A quite different perspective is obtained if we look at the generalized means as a way to generate new kernels from scratch. Under this light, it turns out that the harmonic $\left(M_{-1}\right)$, geometric $\left(M_{0}\right)$ and inverse RMS ( $M_{-2}$ ) means generate valid kernels within their domains ${ }^{1}$ (this is not true for the arithmetic mean).

[^0]Theorem 4 The functions (i) $k_{\text {geom }}:=M_{0}(x, y)=\sqrt{x y}$, (ii) $k_{\text {harm }}:=M_{-1}(x, y)=$ $\frac{2 x y}{x+y}$ and (iii) $k_{\text {IRMS }}:=M_{-2}(x, y)=\left(\frac{x_{i}^{-2}+x_{j}^{-2}}{2}\right)^{-\frac{1}{2}}=\frac{\sqrt{2} x_{i} x_{j}}{\sqrt{x_{i}^{2}+x_{j}^{2}}}$ are PSD kernels. Proof. Consider any $c \in \mathbb{R}^{n}$. We have:

$$
\begin{array}{r}
(i) \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} k_{\text {geom }}\left(x_{i}, x_{j}\right)=\sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} \sqrt{x_{i} x_{j}}=\left(\sum_{i=1}^{n} c_{i} \sqrt{x_{i}}\right)^{2} \geq 0 \\
(i i) \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} \frac{2 x_{i} x_{j}}{x_{i}+x_{j}}=2 \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} x_{i} x_{j} \int_{0}^{1} z^{x_{i}+x_{j}-1} d z= \\
2 \sum_{i=1}^{n} \sum_{j=1}^{n} \int_{0}^{1}\left(c_{i} x_{i} z^{x_{i}-1 / 2}\right)\left(c_{j} x_{j} z^{x_{j}-1 / 2}\right) d z=2 \int_{0}^{1}\left(\sum_{i=1}^{n} c_{i} x_{i} z^{x_{i}-1 / 2}\right)^{2} d z \geq 0 \\
(i i i) \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} \frac{\sqrt{2} x_{i} x_{j}}{\sqrt{x_{i}^{2}+x_{j}^{2}}}=\frac{\sqrt{2}}{\sqrt{\pi}} \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} x_{i} x_{j} \int_{0}^{\infty} t^{-1 / 2} e^{-t\left(x_{i}^{2}+x_{j}^{2}\right)} d t= \\
\sqrt{\frac{2}{\pi}} \int_{0}^{\infty} \sum_{i=1}^{n} \sum_{j=1}^{n} c_{i} c_{j} x_{i} x_{j} t^{-1 / 2} e^{-t\left(x_{i}^{2}+x_{j}^{2}\right)} d t=\sqrt{\frac{2}{\pi}} \int_{0}^{\infty}\left(\sum_{i=1}^{n} c_{i} x_{i} t^{-1 / 4} e^{-t x_{i}^{2}}\right)^{2} d t \geq 0
\end{array}
$$

The interest in these measures lies in the particular semantics that they offer. For example, in the geometric mean, the three numbers $a, M_{0}(a, b), b$ form a geometric sequence, whereas the harmonic mean penalizes big differences between its arguments: consider $M_{1}(0.5,11.5)=M_{1}(6,6)=6$ but $M_{-1}(0.5,11.5) \approx$ $0.96<M_{-1}(6,6)=6$; in all cases, the kernels are calculating "compromise" (i.e. average) values between their arguments.

A final point can be made about these three kernels, by forming their normalized counterparts. Given $k(x, y)$ a kernel, it is known that the function:

$$
\hat{k}(x, y)=\frac{k(x, y)}{\sqrt{k(x, x)} \sqrt{k(y, y)}} \in[-1,1]
$$

is again a valid kernel function [1]. Given that all these kernels are also averages, $k(x, x)=x$ always holds true, and therefore the normalization is always equal to $\sqrt{x y}$. We then find that (i) $\hat{k}_{\text {harm }}(x, y)=\frac{2 \sqrt{x y}}{x+y}$, (ii) $\hat{k}_{\text {geom }}(x, y)=1$ (not very useful) and (iii) $\hat{k}_{\text {IRMS }}(x, y)=\left(\sqrt{\frac{x}{y}+\frac{y}{x}}\right)^{-1}$ are valid kernels.

## 5 Application to Multiple kernel learning

The aggregation of kernels with the weighted arithmetic mean has at least two interpretations. First, we may define (partial) kernels $K_{i}$ on a finite collection of $n$ spaces $\mathcal{H}^{i}$; then an overall kernel in $\mathcal{H}=\mathcal{H}^{1} \times \ldots \times \mathcal{H}^{n}$ is built as:

$$
\mathcal{K}(x, y)=\sum_{i=1}^{n} \alpha_{i} K_{i}\left(x_{i}, y_{i}\right), x_{i}, y_{i} \in \mathcal{H}^{i}, \alpha_{i} \geq 0
$$

where the $\alpha_{i}$ sum to 1 (a convex combination). In the simplest instance of this scheme every $\mathcal{H}_{i}$ represents the domain of a single feature, and the $\alpha_{i}$
coefficients perform an explicit feature selection process; a more interesting case is found in selecting and combining appropriate sets of features.

Second, we can define kernels $K_{i}$ directly on $\mathcal{H}$ and then a new kernel as:

$$
\mathcal{K}(x, y)=\sum_{i=1}^{n} \alpha_{i} K_{i}(x, y), x, y \in \mathcal{H}, \alpha_{i} \geq 0
$$

In this case, the interest is in departing from a set of kernels (may be a big one) and perform a selection on this set. This set of kernels can be homogeneous (different realizations of the same kernel using a different value for a parameter) or heterogeneous (different kernels) or both. Multiple Kernel Learning (MKL) seeks to address these situations by learning the kernel (i.e., fitting the best $\alpha_{i}$ from training data), achieving very good results on bioinformatics and computer vision applications [7]. MKL learns linear combinations of base kernels, corresponding to the concatenation of the base kernel feature spaces.

Richer representations can be achieved by combining kernels in other ways. Taking products of kernels corresponds to taking a tensor product of their feature spaces, leading to a much higher dimensional feature representation as compared to concatenation. This big product is a kernel, and one would be then tempted to take the $n$-root in good fairness, which would not lead to a valid kernel.

## 6 Conclusions

We have proven that the only feasible average for kernel learning is the arithmetic average. Are there other "reasonable" averages that guarantee this kernel property? If by reasonable we understand any function expressible as an Aaverage then the answer is not easy to characterize. However, the necessary differentiability condition is quite simple to check and may serve to rule out many averaging candidates. Moreover, for the wide family $M_{q}$ of generalized means, defining $Q=\left\{q \in \mathbb{R} / M_{q}\right.$ is a kernel $\}$, we have proven that $\{-2,-1,0\} \subset Q$ (and certainly $1 \notin Q$ ). What exactly $Q$ is remains an open question.

Acknowledgements. This study has been partially funded by the Spanish Government project TIN2009-13895-C02-01.

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7] Bach, F. R., Lanckriet, G. R. G., Jordan, M. I. Multiple kernel learning, conic duality, and the SMO algorithm. International Conference on Machine Learning (pp. 6-13), 2004.


[^0]:    ${ }^{1}$ These domains are either $\mathbb{R}^{+}$or $\mathbb{R}^{-}$for $M_{0}$ and $M_{-1}$ and $\mathbb{R}^{+}$for $M_{-2}$.

