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DIMERS AND CLUSTER INTEGRABLE SYSTEMS

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ABSTRACT. – We show that the dimer model on a bipartite graph Γ on a torus gives rise to a quantum integrable system of special type, which we call a *cluster integrable system*. The phase space of the classical system contains, as an open dense subset, the moduli space \mathcal{L}_{Γ} of line bundles with connections on the graph Γ . The sum of Hamiltonians is essentially the partition function of the dimer model.

We say that two such graphs Γ_1 and Γ_2 are *equivalent* if the Newton polygons of the corresponding partition functions coincide up to translation. We define elementary transformations of bipartite surface graphs, and show that two equivalent minimal bipartite graphs are related by a sequence of elementary transformations. For each elementary transformation we define a birational Poisson isomorphism $\mathcal{L}_{\Gamma_1} \to \mathcal{L}_{\Gamma_2}$ providing an equivalence of the integrable systems. We show that it is a cluster Poisson transformation, as defined in [10].

We show that for any convex integral polygon N there is a non-empty finite set of minimal graphs Γ for which N is the Newton polygon of the partition function related to Γ . Gluing the varieties \mathcal{L}_{Γ} for graphs Γ related by elementary transformations via the corresponding cluster Poisson transformations, we get a Poisson space \mathcal{X}_N . It is a natural phase space for the integrable system. The Hamiltonians are functions on \mathcal{X}_N , parametrized by the interior points of the Newton polygon N. We construct Casimir functions whose level sets are the symplectic leaves of \mathcal{X}_N .

The space \mathcal{X}_N has a structure of a cluster Poisson variety. Therefore the algebra of regular functions on \mathcal{X}_N has a non-commutative q-deformation to a *-algebra $\mathcal{O}_q(\mathcal{X}_N)$. We show that the Hamiltonians give rise to a commuting family of quantum Hamiltonians. Together with the quantum Casimirs, they provide a quantum integrable system. Applying the general quantization scheme [11], we get a *-representation of the *-algebra $\mathcal{O}_q(\mathcal{X}_N)$ in a Hilbert space. The quantum Hamiltonians act by commuting unbounded selfadjoint operators.

For square grid bipartite graphs on a torus we get discrete quantum integrable systems, where the evolution is a cluster automorphism of the *-algebra $\mathcal{O}_q(\mathcal{X}_N)$ commuting with the quantum Hamiltonians. We show that the octahedral recurrence, closely related to Hirota's bilinear difference equation [20], appears this way.

Any graph G on a torus \mathbb{T} gives rise to a bipartite graph Γ_G on \mathbb{T} . We show that the phase space \mathcal{X} related to the graph Γ_G has a Lagrangian subvariety \mathcal{R} , defined in each coordinate system by a system of monomial equations. We identify it with the space parametrizing resistor networks on G. The pair $(\mathcal{X}, \mathcal{R})$ has a large group of cluster automorphisms. In particular, for a hexagonal grid graph we get

a discrete quantum integrable system on \mathcal{X} whose restriction to \mathcal{R} is essentially given by the *cube* recurrence [33], [4].

The set of positive real points $\mathcal{X}_N(\mathbb{R}_{>0})$ of the phase space is well defined. It is isomorphic to the moduli space of simple Harnack curves with divisors studied in [26]. The Liouville tori of the real integrable system are given by the product of ovals of the simple Harnack curves.

In the sequel [17] to this paper we show that the set of complex points $\mathscr{X}_N(\mathbb{C})$ of the phase space is birationally isomorphic to a finite cover of the Beauville complex algebraic integrable system related to the toric surface assigned to the polygon N.

RÉSUMÉ. – Au modèle des dimères sur un graphe biparti sur le tore, on associe un système intégrable quantique, qu'on appelle système intégrable de type cluster.

L'espace des phases classique contient, comme ouvert dense, l'espace des modules \mathcal{L}_{Γ} des fibrés en lignes avec connexion sur le graphe Γ . La somme des hamiltoniens est essentiellement la fonction de partition du modèle des dimères.

Disons que deux graphes Γ_1 et Γ_2 sont équivalents si les polygones de Newton des fonctions de partitions correspondantes coïncident à translation près. Nous définissons des transformations élémentaires des graphes bipartis sur une surface, et montrons que deux graphes minimaux et équivalents sont reliés par une suite de transformations élémentaires. Pour chaque transformation élémentaire, nous définissons un isomorphisme de Poisson birationnel $\mathcal{L}_{\Gamma_1} \rightarrow \mathcal{L}_{\Gamma_2}$ donnant une équivalence des systèmes intégrables. Nous montrons que c'est une transformation de Poisson de type cluster, comme défini dans [10].

Nous montrons que, pour chaque polygone convexe entier N, il y a un ensemble fini et non-vide de graphes minimaux Γ pour lesquels N est le polygone de Newton de la fonction de partition sousjacente. Recollant les variétés \mathcal{L}_{Γ} pour les graphes Γ reliés par des transformations élémentaires via les transformations de Poisson correspondantes, on construit un espace de Poisson \mathcal{X}_N . C'est un espace de phases naturel pour le système intégrable.

Les hamiltoniens sont des fonctions sur \mathcal{X}_N , paramétrées par les points intérieurs de N. On construit des fonctions de Casimir dont les courbes de niveaux sont les feuilles symplectiques de \mathcal{X}_N .

L'espace \mathcal{X}_N a une structure de variété de Poisson de type cluster. Alors l'algèbre des fonctions régulières sur \mathcal{X}_N a une q-déformation non-commutative à une *-algèbre $\mathcal{O}_q(\mathcal{X}_N)$. Nous montrons que les hamiltoniens fournissent une famille commutative d'hamiltoniens quantiques. Avec les Casimirs quantiques ils engendrent un système intégrable quantique. La méthode générale de [11] donne une *-représentation de la *-algèbre $\mathcal{O}_q(\mathcal{X}_N)$ dans un espace de Hilbert. Les hamiltoniens quantiques agissent par operateurs auto-adjoints qui commutent entre eux.

Pour le cas d'un quotient de \mathbb{Z}^2 sur un tore, nous avons aussi un système intégrable quantique discret, dont l'évolution est un automorphisme de type cluster de la *-algèbre $\mathcal{O}_q(\mathcal{X}_N)$ commutant avec les hamiltoniens quantiques. Nous montrons que la récurrence octaédrale (récurrence de Hirota) apparaît de cette manière.

À n'importe quel graphe G sur le tore on associe un graphe biparti Γ_G sur T. Nous montrons que l'espace des phases \mathcal{X} associé à Γ_G a une sous-variété lagrangienne \mathcal{R} , définie dans chaque système de coordonnées par des équations monomiales.

On l'identifie avec l'espace paramétrisant les réseaux de résistances sur G. L'ensemble $(\mathcal{X}, \mathcal{R})$ a un grand groupe d'automorphismes de type cluster. En particulier, pour le graphe hexagonal, on trouve un système intégrable quantique discret sur \mathcal{X} dont la restriction à \mathcal{R} donne la récurrence cubique [33, 4].

L'ensemble des points positifs réels $\mathcal{X}_N(\mathbb{R}_{>0})$ de l'espace des phases est bien défini. Il est isomorphe à l'espace de modules des courbes simples de Harnack avec diviseurs étudié dans [26]. Les tores de Liouville du système intégrable réel sont donnés par des produits d'ovales des courbes simples de Harnack. Dans la suite [17] de cet article, nous montrons que l'ensemble des points complexes $\mathcal{X}_N(\mathbb{C})$ de l'espace des phases est birationnellement isomorphe à un revêtement du système de Beauville relié à la surface torique associée au polygone N.

1. Introduction

A line bundle V on a graph Γ is given by assigning a 1-dimensional complex vector space V_v to each vertex of Γ . A connection on V is a choice of isomorphism $\phi_{vv'}: V_v \to V_{v'}$ whenever v, v' are adjacent, satisfying $\phi_{v'v} = \phi_{vv'}^{-1}$.

We construct a Poisson structure on the space of line bundles with connections on a bipartite graph embedded on a surface. When the graph is embedded on a torus \mathbb{T} we construct an algebraic integrable system, with commuting Hamiltonians which can be written as Laurent polynomials in natural coordinates on \mathcal{L}_{Γ} , the moduli space of line bundles with connections on Γ . The Hamiltonians are sums of dimer covers of Γ .

A *dimer cover* of a graph Γ is a set of edges with the property that every vertex is the endpoint of a unique edge in the cover. Probability measures on dimer covers have been the subject of much recent work in statistical mechanics. In this paper we study some non-probabilistic applications of the dimer model, in particular to the construction of cluster integrable systems.

Below we introduce the key non-technical definitions which we use throughout the paper, and discuss the main results.

1.1. Dimer models and Poisson geometry

A surface graph Γ is a graph embedded on a compact oriented surface S whose faces, i.e., the connected components of $S - \Gamma$, are contractible. It is homotopy equivalent to an open surface $S_0 \subset S$, obtained by putting a puncture in every face. A bipartite graph is a graph with vertices of two types, black and white, such that each edge has one black and one white vertex.

1.1.1. Conjugate surface graph and Poisson structure. – Let \mathcal{L}_{Γ} be the moduli space of line bundles with connections on a graph Γ . Any oriented loop L on Γ gives rise to a function W_L on \mathcal{L}_{Γ} given by the monodromy of a line bundle with connection along L. One has $W_{-L} = W_L^{-1}$, where -L is the loop L with the opposite orientation. The monodromies around the loops provide an isomorphism

(1)
$$\mathscr{L}_{\Gamma} \cong \operatorname{Hom}(H_1(\Gamma, \mathbb{Z}), \mathbb{C}^*) = H^1(\Gamma, \mathbb{C}^*).$$

For any surface graph Γ , the moduli space \mathcal{L}_{Γ} has the *standard Poisson structure*. Namely, since Γ is homotopy equivalent to the surface S_0 , we have $\mathcal{L}_{\Gamma} = H^1(S_0, \mathbb{C}^*)$. This latter space has a Poisson structure provided by the intersection pairing on $H_1(S_0, \mathbb{Z})$.

Now let Γ be a bipartite surface graph. Then we introduce a *new* Poisson structure on \mathcal{L}_{Γ} related to the standard one by a "twist."

A surface graph is the same thing as a *ribbon graph*: a ribbon graph is a graph with an additional structure given by, for each vertex, a cyclic order of the edges at that vertex. Given a ribbon graph, we can replace its edges by ribbons, getting an oriented surface.

A bipartite surface graph Γ gives rise to a new ribbon graph $\widehat{\Gamma}_w = \widehat{\Gamma}$, the *conjugate graph*, obtained by reversing the cyclic orders at all white vertices⁽¹⁾. The topological surface with boundary corresponding to the ribbon graph $\widehat{\Gamma}_w$ is called the *conjugated surface* \widehat{S}_w .

Evidently a line bundle with connection on the graph $\widehat{\Gamma}$ is the same thing as a line bundle with connection on the original graph Γ . So there is a canonical isomorphism

(2)
$$\mathscr{L}_{\Gamma} = \mathscr{L}_{\widehat{\Gamma}}$$

The standard Poisson structure on the moduli space $\mathscr{L}_{\widehat{\Gamma}}$ combined with the isomorphism (2) provides the Poisson structure on \mathscr{L}_{Γ} we need. Precisely, consider the intersection pairing on \widehat{S}_w :

(3)
$$\varepsilon_{\widehat{S}_w} : H_1(\widehat{S}_w, \mathbb{Z}) \wedge H_1(\widehat{S}_w, \mathbb{Z}) \longrightarrow \mathbb{Z}$$

Given two loops L_1, L_2 on Γ , we define the Poisson bracket $\{W_{L_1}, W_{L_2}\}$ by setting

(4)
$$\{W_{L_1}, W_{L_2}\} = \varepsilon_{\widehat{S}_w}(L_1, L_2) W_{L_1} W_{L_2}$$

and extending it via the Leibniz rule to a Poisson bracket on the algebra generated by the functions W_L , which coincides with the algebra of regular functions on the variety \mathcal{L}_{Γ} .

1.1.2. Natural coordinates on \mathcal{L}_{Γ} . – The orientation of the surface S induces orientations of the faces of Γ . The group $H_1(\Gamma, \mathbb{Z})$ is generated by the oriented boundaries $\partial(F)$ of the faces F of Γ , whose orientation is induced by the orientation of F, and loops generating $H_1(S, \mathbb{Z})$. The only relation is that the sum of boundaries of all faces is zero. There is an exact sequence, where the map π is induced by the embedding $\Gamma \hookrightarrow S$:

$$0 \longrightarrow \operatorname{Ker} \pi \longrightarrow H_1(\Gamma; \mathbb{Z}) \xrightarrow{\pi} H_1(S; \mathbb{Z}) \longrightarrow 0.$$

The subgroup Ker π is generated by the oriented boundaries $\partial(F)$ of faces F.

Summarizing, the monodromies of connections around all but one oriented faces F of Γ , augmented by the monodromies around loops generating $H_1(S, \mathbb{Z})$, provide a coordinate system $\{X_i\}$ on the moduli space \mathcal{L}_{Γ} . The Poisson structure in these coordinates has a standard quadratic form

(5)
$$\{X_i, X_j\} = \varepsilon_{ij} X_i X_j, \qquad \varepsilon_{ij} \in \mathbb{Z},$$

where ε is the intersection pairing on \hat{S}_w .

1.1.3. Zig-zag loops and the center of the Poisson algebra of functions on \mathcal{L}_{Γ} . – A zig-zag path (see [24, 35]) on a ribbon graph Γ is an oriented path on Γ which turns maximally left at white vertices and turns maximally left at black vertices; see Figure 1. Zig-zag paths necessarily close up to form zig-zag loops. There is a bijection

(6) $\{\text{zig-zag loops on } \Gamma\} \leftrightarrow \{\text{boundaries of the holes on } \widehat{S}_w\}.$

The orientations of zig-zag loops match the orientations of the boundary loops on \hat{S}_w induced by the orientation of \hat{S}_w .

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⁽¹⁾ Reversing the cyclic order at the black vertices we get a ribbon graph $\hat{\Gamma}_b$, which differs from $\hat{\Gamma}_w$ by the orientation.



FIGURE 1. A Zig-zag path on a ribbon graph.

LEMMA 1.1. – Let Z be an (oriented) zig-zag loop on a bipartite oriented surface graph Γ . Then as Z runs over zig-zag loops, the functions W_Z generate the center of the Poisson algebra $\mathcal{O}(\mathcal{L}_{\Gamma})$ of functions on \mathcal{L}_{Γ} . The product of all of them is 1. This is the only relation between them.

We call the functions W_Z the Casimirs.

Proof. – It follows from the canonical bijection (6). Evidently the boundary loops on \widehat{S}_w generate the kernel of the intersection pairing on $H_1(\widehat{S}_w, \mathbb{Z})$. Clearly the sum of them is zero, and this is the only relation between them.

There is a similar Poisson moduli space \mathcal{L}_{Γ} for a bipartite graph Γ on an oriented surface S with boundary.

1.1.4. Gluing the Poisson phase space. – The set of homology classes of dimer coverings of Γ (as defined below) defines a convex polyhedron $N \subset H_1(S, \mathbb{R})$. It is the Newton polyhedron of the dimer partition function. Two bipartite surface graphs are equivalent if their Newton polyhedra coincide up to translation. In each equivalence class there are minimal bipartite surface graphs, which have the minimal number of faces. We prove that every two minimal bipartite surface graphs are related by certain elementary transformations, consisting of "spider" moves and "shrinking of a 2-valent vertex" moves. Each elementary transformation $\Gamma_1 \rightarrow \Gamma_2$ gives rise to a cluster Poisson birational isomorphism

(7)
$$i_{\Gamma_1,\Gamma_2}: \mathcal{L}_{\Gamma_1} \xrightarrow{\sim} \mathcal{L}_{\Gamma_2}$$

We define a Poisson variety \mathcal{X}_N , the *phase space*, by gluing the moduli spaces \mathcal{L}_{Γ} via transformations (7). The variety \mathcal{X}_N depends only on N.

Since the sets of zig-zag loops on equivalent bipartite surface graphs are naturally identified, the gluing maps (7) preserve the Casimirs. Therefore the center of the Poisson algebra of regular functions on the phase space \mathcal{X}_N is also described by the Casimirs.

1.2. Cluster integrable systems for dimer models on a torus

1.2.1. Classical integrable system. – Let us restrict to the case when Γ is a bipartite graph on a torus \mathbb{T} . In this case the Newton polyhedron N is a convex polygon in the plane $H_1(\mathbb{T}, \mathbb{R})$ with vertices at the lattice $H_1(\mathbb{T}, \mathbb{Z})$. Zig-zag loops are parametrized by the intervals on the boundary ∂N between two consecutive integral points, called *primitive boundary intervals*.

We show that the partition function of the dimer model on Γ gives rise to a regular function \mathcal{P} on \mathcal{X}_N , the *modified partition function*, well defined up to a multiplication by a monomial of Casimirs. It has a natural decomposition into a sum of components H_a , called the *Hamiltonians*, parametrized by the internal integral points of the Newton polygon N.

These Hamiltonians are Laurent polynomials in the X_i 's. The Hamiltonian flows are well defined.

THEOREM 1.2. – The Hamiltonian flows of the H_a commute, providing an integrable system on \mathcal{X}_N . Precisely, we get integrable systems on the generic symplectic leaves of \mathcal{X}_N , given by the level sets of the Casimirs.

In particular,

$$\dim \mathcal{X}_N = 2i(N) + e(N) - 1,$$

where i(N) (respectively e(N)) is the number of integral points inside (respectively on the boundary) of the polygon N.

1.2.2. Quantum integrable system. – The algebra of regular functions on any cluster Poisson variety \mathcal{X} has a natural q-deformation to a *-algebra $\mathcal{O}_q(\mathcal{X})$, defined in [10, Section 3]. It can be realized, in many different ways, as a subalgebra in the quantum torus algebra. The latter is generated by the elements $X_i^{\pm 1}$ satisfying the following relations, where q is a formal variable commuting with X_i 's:

(8)
$$q^{-\varepsilon_{ij}}X_iX_j = q^{-\varepsilon_{ji}}X_jX_i, \qquad \varepsilon_{ij} \in \mathbb{Z}.$$

It has an involutive antiautomorphism *, acting on the generators by

$$*(X_i) = X_i, \quad *(q) = q^{-1}.$$

So in our case we get a *-algebra $\mathcal{O}_q(\mathcal{X}_N)$. The ε_{ij} in (8) is the same as the Poisson tensor in (5). The quantum analog of Theorem 1.2 is

THEOREM 1.3. – The Hamiltonians H_a give rise to commuting selfadjoint elements \mathbb{H}_a in the *-algebra $\mathcal{O}_q(\mathcal{X}_N)$, which we call quantum Hamiltonians. The Casimirs give rise to the generators of the center of the algebra.

In any of the coordinate systems provided by bipartite graphs, the quantum Hamiltonians are given by Laurent polynomials with positive integral coefficients.

Let us assume now that |q| = 1. Then, according to [11], for any cluster Poisson variety \mathcal{X} , there is a family of Hilbert spaces \mathcal{H}_{χ} , parametrized by the characters χ of the center of the algebra $\mathcal{O}_q(\mathcal{X})$, and a *-representation of the *-algebra $\mathcal{O}_q(\mathcal{X})$ in (a certain Schwartz space \mathcal{A}_{χ} , dense in) \mathcal{H}_{χ} .

So in our case we get a family of Hilbert spaces $\mathcal{H}_{N,\chi}$, parametrized by a collection of real numbers χ , the eigenvalues of the Casimirs. The quantum Hamiltonians are realized by commuting unbounded selfadjoint operators in $\mathcal{H}_{N,\chi}$.

PROBLEM 1. – Find the generalized eigenfunctions of the quantum Hamiltonians, and the spectral decomposition.

We call the emerging object a *cluster integrable system*. A key point is that a cluster integrable system admits a quantum version, as described above. We believe that many interesting integrable systems are cluster integrable systems.

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1.2.3. Discrete cluster integrable systems. – In the case of the dimer model on a square grid on a torus⁽²⁾ our quantum integrable system has a remarkable automorphism A, called the *octahedron recurrence* or, in other language, *Hirota's bilinear difference equation* (HBDE) [20]. We show that it commutes with the quantum Casimirs and quantum Hamiltonians, and is given by an element of the *cluster modular group* [10] of the cluster variety χ —see Section 6.

There are similar discrete cluster integrable systems related to hexagonal graphs G on a torus, where the discrete evolution operator is described by the *cube recurrence*, see Sections 6.2-6.3. Its phase space is the phase space of the dimer model related to the resistor network model on G, see Section 1.3.

We stress that discrete cluster integrable systems are discrete quantum integrable systems. Indeed, the ring of regular functions on any cluster Poisson variety admits a canonical noncommutative q-deformation, and the discrete evolution operator is given by an element of the cluster modular group, which acts by an automorphism of the q-deformed space [10]. Finally, the classical Hamiltonians, in all examples we know, are given by functions which in any of the coordinate systems are Laurent polynomials with positive integral coefficients. Therefore they admit a natural upgrade to their non-commutative counterparts.

1.3. Cluster nature of a resistor network model on a torus

1.3.1. Dimer model arising from a graph on a torus. – A special case of the dimer model is one arising from a planar resistor network G via the generalized Temperley's trick [27]. Namely, an arbitrary graph G on a torus gives rise to a bipartite graph $\Gamma = \Gamma_G$, obtained by taking a barycentric subdivision of the graph G and declaring the centers of the edges of G to be the white vertices and the centers of the faces of G together with the vertices of G to be the black vertices. The graph Γ contains the dual graph G' to the graph of G, see Figure 2, where G is shown by solid lines, and G' by dotted lines.



FIGURE 2. The bipartite graph Γ_G (dashed and solid edges) assigned to a graph G (solid edges).

Given a surface graph G embedded on a surface S there is a graph \tilde{G} embedded on the universal cover \tilde{S} , which is the natural lift of G. A surface graph G embedded on surface S is called *minimal* if zig-zag paths (defined as unoriented paths which turn alternately maximally left and maximally right at consecutive vertices) on \tilde{G} do not have selfcrossings and different zig-zag paths do not intersect in more than one edge.

⁽²⁾ The square grid dimer models on a torus are parametrized by sublattices of the isomorphism group \mathbb{Z}^2 of the standard square grid bipartite graph in \mathbb{R}^2 .

The Newton polygon N(G) of the bipartite graph Γ_G is a centrally-symmetric integral polygon in $H_1(\mathbb{T}, \mathbb{Z})$ centered at the origin. It coincides with the Newton polygon of the spectral curve of the Laplacian related to a generic *resistor network* on G, see Section 5.

Any such polygon arises as a Newton polygon N(G) for a non-empty finite collection of minimal graphs G on a torus. Any two minimal graphs G_1 and G_2 on a torus with the same Newton polygon are related by a sequence of elementary transformations, called $Y - \Delta$ moves, see Figure 24.

A $Y - \Delta$ move $G_1 \rightarrow G_2$ induces a transformation $\Gamma_1 \rightarrow \Gamma_2$ of the corresponding bipartite graphs. We decompose it into a composition of four spider moves (Lemma 5.11), which provides us with a cluster birational isomorphism

(9)
$$\mu_{Y-\Delta}: \mathcal{L}_{\Gamma_1} \longrightarrow \mathcal{L}_{\Gamma_2}.$$

Gluing the tori \mathcal{L}_{Γ} assigned to the bipartite graphs Γ related to the equivalent minimal graphs G, we get a cluster Poisson space \mathcal{X} .⁽³⁾

1.3.2. Resistor network Lagrangian subvariety. – The moduli space \mathcal{L}_{Γ_G} of line bundles with connections on the graph Γ_G has a subvariety \mathcal{R}_G defined by the condition that the monodromies over any loop α in G and any loop α' in G' in the same homology class on \mathbb{T} are equal. These equations are given by equating certain monomials in the X_i 's to 1.

We prove that \mathcal{R}_G is a Lagrangian subvariety of the Poisson variety \mathcal{L}_{Γ_G} , i.e., its intersections with the generic symplectic leaves are Lagrangian subvarieties. We show that the space \mathcal{R}_G parametrizes resistor networks on G, justifying the name resistor network Lagrangian subvariety.

Equivalently, the conjugated surface \hat{S}_{Γ_G} is canonically realized as the boundary of a certain handlebody.

We show that the $(Y - \Delta)$ -cluster transformation (9) provides a birational isomorphism of the Lagrangian subvarieties

$$\mu_{Y-\Delta}^R: \ \mathcal{R}_{G_1} \longrightarrow \mathcal{R}_{G_2}.$$

Gluing the subvarieties \mathscr{R}_G via these birational isomorphisms, we get a Lagrangian subspace \mathscr{R} of the corresponding cluster Poisson space \mathscr{X} . It gives rise to a (uniquely defined up to a constant) functional on the Schwartz space \mathscr{G}_{χ} , see Section 5.2.7.

1.4. Toric surfaces, spectral data and the Beauville integrable system

Let $T := T_T \cong (\mathbb{C}^*)^2$ be the algebraic torus related to the torus \mathbb{T} . Recall that a bipartite graph Γ on \mathbb{T} gives rise to a Newton polygon N in $H_1(\mathbb{T}, \mathbb{R})$ with vertices at $H_1(\mathbb{T}, \mathbb{Z})$. Such a Newton polygon N, considered up to translation, provides us a toric surface \mathcal{N} together with a line bundle \mathcal{L} . The algebraic torus T acts on the pair $(\mathcal{N}, \mathcal{L})$. The points of \mathcal{N} where the action is not free form the divisor at infinity \mathcal{N}_{∞} of \mathcal{N} . It is a collection of \mathbb{P}^1 's which is combinatorially isomorphic to the polygon N.

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⁽³⁾ Gluing this space we use only the graphs Γ which are equivalent by the $(Y - \Delta)$ -moves. We may have other bipartite graphs which are still equivalent as bipartite graphs.

1.4.1. The Kasteleyn operator. – A Kasteleyn line bundle with connection \mathbb{K} on a bipartite surface graph Γ is a line bundle with connection with monodromy $(-1)^{\ell/2+1}$ around faces having ℓ edges, and ± 1 around topologically nontrivial loops. There are 2^{2g} non-isomorphic choices of \mathbb{K} when S has genus g. Given a line bundle with connection V on a bipartite surface graph Γ , we construct a new one $V \otimes \mathbb{K}$, and set

(10)
$$\mathbf{V}_{\mathrm{B}} := \bigoplus_{v \in \{\text{black vertices of } \Gamma\}} (V \otimes \mathbb{K})_{v},$$

(11)
$$\mathbf{V}_{\mathrm{W}} := \bigoplus_{v \in \{\text{white vertices of } \Gamma\}} (V \otimes \mathbb{K})_v.$$

A connection on the line bundle $V \otimes \mathbb{K}$ is encoded by an operator

$$K: \mathbf{V}_{\mathrm{B}} \longrightarrow \mathbf{V}_{\mathrm{W}},$$

the *Kasteleyn operator*, whose matrix elements are given by parallel transports for the connection along the edges of Γ . We let

(12)
$$\mathbf{L} = \det \mathbf{V}_{\mathrm{B}}^* \otimes \det \mathbf{V}_{\mathrm{W}}$$

be the determinant line (here det V denotes the highest exterior power of a vector space V). The determinant det K is an element of the determinant line.

1.4.2. *The spectral data*. – Let

$$\mathbf{T} := \mathrm{Hom}(H_1(\mathbb{T}, \mathbb{Z}), \mathbb{C}^*) = H_1(\mathbb{T}, \mathbb{C}^*) \cong (\mathbb{C}^*)^2.$$

The group T is identified with the group of complex line bundles with flat connections on the torus T. The embedding *i* of the graph Γ into the torus T provides a free action of the group T on the moduli space \mathcal{L}_{Γ} , given by $* \longmapsto * \otimes i^*L$, where *L* is a flat line bundle on the torus T. This action preserves the Poisson structure on \mathcal{L}_{Γ} .

The *partition function* can be calculated as the determinant of the Kasteleyn operator. It is a section of the determinant line bundle over \mathscr{L}_{Γ} . Let us restrict it to a T-orbit on \mathscr{L}_{Γ} . Then it extends to a section of the line bundle $\mathscr{L} \otimes \mathbf{L}$ over the toric surface \mathscr{N} which compactifies the orbit. The divisor of zeros of this section is called the *spectral curve* C.

The spectral curve C intersects the divisor at infinity \mathcal{N}_{∞} at a divisor C_{∞} . A choice of a point of $\mathcal{N}_0 := \mathcal{N} - \mathcal{N}_{\infty}$ provides a coordinate on every component of the divisor \mathcal{N}_{∞} . The divisors C_{∞} satisfy a single condition:

(13) The product of the coordinates of all points of C_{∞} is equal to 1.

We call such divisors admissible divisors at infinity. There is a bijection

(14) $\nu : \{\text{zig-zag paths on }\Gamma\} \xrightarrow{\sim} \text{divisor at infinity } C_{\infty}.$

It is uniquely determined by the condition that the Casimir functions on the phase space given by the monodromies along zig-zag paths α are proportional to the Casimir functions given by the coordinates of the boundary points $\nu(\alpha)$ on the corresponding components of \mathcal{N}_{∞} .

Pick a black vertex b of Γ . A non-zero vector in the fiber V_b provides a section s_b of the sheaf Coker K. The latter sheaf is a line bundle for a smooth C. The restriction of its divisor of zeros to \mathcal{N}_0 is a degree g effective divisor S, where g is the genus of C.

The triple (C, S, ν) is called the *spectral data*. It was studied in [26].

1.4.3. A cover of the Beauville integrable system. – Let \mathscr{G} be the moduli space parametrizing the spectral data. Let \mathscr{B} be the moduli space of pairs (C, ν) . Forgetting S, we get a projection

(15)
$$\pi: \mathscr{G} \longrightarrow \mathscr{G}, \qquad (C, S, \nu) \longmapsto (C, \nu)$$

We claim that it is an integrable system, which covers the Beauville integrable system—the latter does not take into account parametrizations (13).

Namely, let $\phi_{\chi} \subset \phi$ be the subspace parametrizing the spectral data (C, S, ν) with a given divisor C_{∞} . It carries a rational symplectic form Ω_{ϕ} defined as follows. The canonical T-invariant symplectic form ω on \mathcal{N}_0 gives rise to the Beauville symplectic form on $\operatorname{Sym}^g \mathcal{N}_0$:

$$\Omega_B := \sum_{i=1}^g s_i^* \omega.$$

Here $s_i : \mathcal{N}^g \longrightarrow \mathcal{N}$ is the projection to the *i*-th factor. There is a projection

$$p: \mathscr{A}_{\chi} \longrightarrow \operatorname{Sym}^{g} \mathscr{N}_{0}, \qquad (C, S, \nu) \longmapsto S.$$

It is a Galois cover, whose Galois group is a product of symmetric groups acting by permuting the points of C_{∞} at each boundary component, and hence altering the bijection (14). Indeed, one shows that, given a generic admissible divisor at infinity $C_{\infty} \subset \mathcal{N}_{\infty}$ and a generic degree g divisor $S \subset \mathcal{N}_0$, there is a unique spectral curve C passing through S and intersecting \mathcal{N}_{∞} at the divisor C_{∞} . So the pull-back $\Omega := p^*\Omega_B$ is a rational symplectic form on \mathscr{G}_{χ} . Let $\mathscr{G}_{\chi} \subset \mathscr{G}$ be the subspace given by the condition that $C \cap \mathcal{N}_{\infty}$ is a given divisor. There is a fibration

(16)
$$\pi_{\chi}: \mathscr{A}_{\chi} \longrightarrow \mathscr{B}_{\chi}.$$

Its fibers are Lagrangian. The fiber over a point (C, ν) is identified with an open part of $\operatorname{Pic}_g(C)$, which is a principal homogeneous space over the Jacobian of C. So (16) and therefore (15) are algebraic integrable systems.

1.4.4. Connection with the dimer integrable system. – A proof of Theorem 1.4 below will be given in [17]. Combined with the results of this paper it allows to quantize the integrable system (15).

THEOREM 1.4. – For any Newton polygon N, the spectral data provides a birational isomorphism S over the base \mathcal{B} :

It identifies the dimer integrable system with the integrable system (15), matching the symplectic leaves of χ and the symplectic varieties (ϕ_{χ}, Ω).

The map S intertwines the action of the torus T on \mathcal{X} with the action on \mathcal{A} provided by the action of T on the surface \mathcal{N} .

In Section 7 we prove a weaker statement: S is a finite cover over the generic part of \mathcal{A} . It implies the independence of the Hamiltonians.

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1.5. Analogies between dimers, Teichmüller theory and cluster varieties

Cluster Poisson varieties provide a framework for study of both (classical and higher) Teichmüller theory [9] and theory of dimers. Here is a dictionary relating key objects in these three theories.

Dimer Theory	Teichmüller Theory	Cluster varieties
Convex integral polygon N	Oriented surface S	
	with $n > 0$ punctures	
Minimal bipartite graphs	ideal triangulations of S	seeds
on a torus		
spider moves of graphs	flips of triangulations	seed mutations
Face weights	cross-ratio coordinates	Poisson cluster
		coordinates
Moduli space of spectral	Moduli space of framed	cluster Poisson variety
data on toric surface N	PGL(2) local systems	
simple Harnack curve + divisor	complex structure on S	
Moduli space of	Teichmüller space of S	positive real points of
simple Harnack curves + divisors		cluster Poisson variety
Tropical Harnak curve	Measured lamination	
with divisor		
Moduli space of tropical	space of measured	real tropical points of
Harnack curve + divisors	laminations on S	cluster Poisson variety
Dimer integrable system	Integrable system related to	
	pants decomposition of S	
Hamiltonians	Monodromies around loops	
	of a pants decomposition	

What distinguishes these two examples—the dimer theory and the Teichmüller theory from the general theory of cluster Poisson varieties is that in each of them the set of real / tropical real points of the relevant cluster variety has a meaningful and non-trivial interpretation as the moduli space of some geometric objects.

Here by moduli space of certain objects related to the toric surface \mathcal{N} we mean the space parametrizing the orbits of the torus T acting on the objects. For example, the moduli space of spectral data means the space \mathscr{O}/T . So combining results of [17] with Theorem 4.6 would imply that the latter corresponds to the hypersurface \mathcal{X}_N^0 in the cluster Poisson variety \mathcal{X}'_N .

1.5.0.1. Discrete cluster integrable systems in Teichmüller theory.– Consider the moduli space $\mathcal{X}_{PGL_2,S}$ of framed PGL₂-local systems on S [9]. If S has no punctures, it is just the moduli space of PGL₂-local systems on S, which has the classical symplectic structure. If S is a surface with punctures, the moduli space $\mathcal{X}_{PGL_2,S}$ has a cluster Poisson variety structure (*loc. cit.*). Take a collection of loops { α_i } providing a pants decomposition of S. The monodromies of local systems over the loops α_i commute under the Poisson bracket and, together with the Casimirs given by the monodromies around the punctures, provide an integrable system. When S is a surface with punctures it is a cluster integrable system.

Furthermore, the Dehn twists along the loops α_i generate a commutative subgroup \mathbb{Z}^{3g-3} in the modular group $\Gamma(S)$ of the surface S, which commutes with the Hamiltonians and acts by cluster Poisson automorphisms. So we get a discrete cluster integrable system.

We continue to develop these analogies in [17]. Yet parts of this dictionary are still missing. In particular, it would be very interesting to construct a canonical basis—in the spirit of the Duality Conjectures from [10]—in the space of regular functions on the cluster variety \mathcal{X}_N .

1.6. Further perspectives

We assigned to a Newton polygon N a cluster integrable system. Here is another way to assign to N an integrable system:

1. Newton polygons N, considered up to translation, parametrize smooth toric Calabi-Yau threefolds. Namely, the canonical bundle $K_{\mathcal{N}}$ of the toric surface \mathcal{N} assigned to Nis a toric Calabi-Yau threefold: the multiplicative group \mathbb{G}_m acts on the fibers, so the torus $T \times \mathbb{G}_m$ acts on $K_{\mathcal{N}}$. Alternatively, it can be described as follows. Put a Newton polygon N in the z = 1 plane in the lattice \mathbb{Z}^3 , and make a cone over it. The corresponding toric threefold is a Calabi-Yau. Every smooth quasiprojective toric Calabi-Yau threefold is obtained this way. See [21] for the connections between dimer models and toric Calabi-Yau threefolds.

2. Any Calabi-Yau threefold Y gives rise to an N = 2 supersymmetric Yang-Mills (N = 2 SUYM) theory on \mathbb{R}^4 . Namely, consider a IIB type string theory in 10-dimensional space $Y(\mathbb{C}) \times \mathbb{R}^4$ and compactify it on $Y(\mathbb{C})$.

3. An N = 2 SUYM theory on \mathbb{R}^4 gives rise to an algebraic integrable system—see [34] and references there.

Combining these three steps we conclude that any Newton polygon N gives rise to an algebraic integrable system. It is natural to conjecture that it is the dimer cluster integrable system assigned to N. It would be interesting to prove this, and understand the role of the cluster structure, and in particular of quantum integrability.

1.7. Historical remarks

Several of the concepts we use are present with different citations in the literature on the dimer model and the literature on cluster algebras/cluster varieties.

Zig-zag paths were defined in the dimer model in [24] but are implicitly present in work of Baxter on the Yang-Baxter equation in the 6-vertex model, see e.g., [1]. They also occur in a more general form, for "bicolored" planar graphs, in [35].

Elementary transformations for dimers and in particular the spider move were first defined by Kuperberg in the 90s (using the term "urban renewal" which was coined by Propp), see [5, 27]. In the cluster algebra literature these are sometimes referred to as Postnikov moves. The analogous elementary transformations for electrical networks (the star-triangle move, also known as Y-Delta move) appeared in Kennelly [23].

The notion of minimal network appeared for resistor networks in [6] and [7], and for dimers/clusters in [37] and [35].

Cluster algebras were introduced in [12]. A family of Poisson structures on cluster algebras was introduced in [15].

Cluster Poisson varieties were introduced in [10]. They are in duality with cluster algebras. The field of rational functions on a cluster Poisson variety has a natural non-commutative q-deformation, see Section 3 of *loc. cit.*. The cluster modular group, defined there as well, acts by automorphisms of the cluster Poisson variety, its q-deformation, and the cluster algebra. In general it does not, however, preserve the Poisson structures introduced in [15]. Non-commutative q-deformations of the cluster algebra corresponding to these Poisson structures were defined in [2] and called quantum cluster algebras.

Cluster Poisson varieties are related to cluster algebras as follows. The subvariety of a cluster Poisson variety obtained by equating all monomial Casimirs to 1 is a distinguished symplectic leaf. The restrictions of the cluster Poisson coordinates to that leaf can be realized as ratios of cluster monomials in the corresponding cluster algebra, considered already in [15]. The obtained elements generate a subfield in the field of fractions of the cluster algebra. Its transcendentality degree is smaller than the one of the field of fractions of the cluster algebra by the number of independent Casimirs, which coincides with the codimension of the generic symplectic leaf in the cluster Poisson variety.

In [16] Gekhtman, Shapiro and Vainshtein study a related model of paths in directed networks on an annulus, originally defined by Postnikov [35] for planar networks. The relation with our model is not completely straightforward, but in the cases of interest we believe the models are essentially equivalent. The results of [16] have some overlap with ours: in particular they construct the same Poisson structure, but do not discuss integrability (the annular system is not integrable). It would be worthwhile to study more closely the connection between these models.

The octahedron recurrence, although known as Hirota's bilinear difference equation, goes back to Hirota [20]. The cube recurrence, also known as the discrete BKP equation or Hirota-Miwa equation, goes back to the work of Miwa [33], and was rediscovered and studied several times afterwords, see [13], [4].

1.8. The structure of the paper

In Section 2 we study the set of minimal bipartite graphs Γ with a given Newton polygon.

In Section 3 we define a modified partition function, and prove that it is a sum of commuting Hamiltonians, providing a quantum integrable system.

In Section 4 we show that the spider move gives rise to a cluster Poisson transformation. We show that these transformations preserve the partition functions. We also briefly recall, for the convenience of the reader, basic definitions of quantum cluster varieties.

In Section 5 we study the dimer model of special kind corresponding to an arbitrary torus graph G, describing a resistor network on G.

In Section 6 we construct discrete cluster integrable systems related to the dimer models on square grids and dimer models related to hexagonal resistor networks.

In Section 7 we turn to the algebraic-geometric perspective of the story. As a biproduct we prove the independence of the Hamiltonians.

In Section 8 we give a local calculation of the Poisson structure on the space \mathcal{L}_{Γ} , and generalize the story to bipartite graphs on open surfaces.

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2. Newton polygons and minimal bipartite graphs on surfaces

2.1. Zig-zag paths and minimal bipartite surface graphs

Let $E = v_1v_2$ be an oriented edge of an oriented ribbon graph. There is a notion of the left and right edges adjacent to E: the left (respectively the right) edge to E is the previous (respectively the next) for the cyclic order at v_2 .

Let Γ be a bipartite graph on a surface S. The medial graph of Γ is the 4-valent graph with a vertex for each edge of Γ and an edge whenever two edges of Γ share a vertex and are consecutive in the cyclic order around that vertex. A strand or zig-zag strand is a path in the medial graph passing consecutively through the edges of a zig-zag path of Γ as in Figure 3; equivalently it is a path in the medial graph which goes "straight" at each (degree-4) vertex. For every edge E of Γ there are exactly two strands passing through E, see Figure 3. For every m-valent vertex v of Γ there is a unique m-gon formed by the parts of the strands intersecting the consecutive pairs of the edges incident to v, see the right picture on Figure 3. We call it the arc m-gon surrounding v.



FIGURE 3. Zig-zag strands and surrounding 4-gon.

DEFINITION 2.1. – A bipartite surface graph Γ is minimal if, in the universal cover $\tilde{\Gamma} \subset \tilde{S}$, strands have no self-intersections, and there are no parallel bigons, i.e., pairs of strands intersecting at two points and oriented the same way—see the left pictures on Figure 4.

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FIGURE 4. Minimal bipartite surface graphs have no self-intersections and parallel bigons (left); antiparallel bigons (right) are allowed.

2.2. From Newton polygons to collections of admissible graphs

Let N be a convex polygon in \mathbb{R}^2 with vertices in \mathbb{Z}^2 , considered up to a translation by a vector in \mathbb{Z}^2 , called below a *Newton polygon*. It is described by a collection $\{e_i\}$ of integral primitive vectors with the zero sum, obtained as follows. Take the set of all integral points on the boundary of N. It is cyclically ordered by the counterclockwise orientation of the boundary. The vectors e_i are obtained by connecting each of these points with the next one. So the number of integral primitive vectors on the boundary coincides with the number of integral points on the boundary.

Consider the torus $\mathbb{T} = \mathbb{R}^2/\mathbb{Z}^2$. Each vector e_i determines a homology class $[e_i] \in H_1(\mathbb{T}, \mathbb{Z})$. There is a unique up to translation geodesic representing this class—the projection of the vector e_i to the torus.

Take a family of oriented loops $\{\alpha_i\}$ on the torus \mathbb{T} in generic position such that the isotopy class of the loop α_i coincides with the isotopy class of the geodesic representing $[e_i]$. The union

$$G = \bigcup_i \alpha_i$$

is an oriented graph on the torus \mathbb{T} .

DEFINITION 2.2. – A graph G given by a collection of oriented loops on an oriented surface S is an admissible minimal graph if the following two conditions hold:

- 1. Going along any of the loops α_i , the directions of the loops intersecting it alternate.
- 2. The total number of intersection points is minimal.

The graph G provides a decomposition of the surface S into a union of polygons P_j . The sides of the polygons inherit orientations from the loops. The admissibility condition 1) is equivalent to the following:

1'. The sides of any of the polygons P_i are either oriented the same way, clockwise or counterclockwise, or their directions alternate.

2.2.1. From admissible surface graphs to bipartite surface graphs. – The admissibility condition 1') for a surface graph implies that there are three types of domains P_i :

- 1. Black domains: the sides are oriented counterclockwise.
- 2. White domains: the sides are oriented clockwise.
- 3. *Faces*: the directions of the sides alternate.

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Therefore an admissible graph G on S gives rise to a bipartite graph Γ on S: the black (white) vertices of Γ are the black (white) domains in S - G. Edges connecting black and white vertices correspond to the vertices of the graph G. Indeed, every vertex of G is 4-valent (since the loops α_i are in generic position), and locally looks as an intersection of two arrows. So it determines the black and the white domains.

2.2.2. Minimal triple point diagrams [37]. – A triple point diagram⁽⁴⁾ is a collection of oriented arcs in the disc with the ends at the boundary of the disc considered modulo isotopies, such that

- 1. Three arcs cross at each intersection point.
- 2. The endpoints of the arcs are distinct points on the boundary of the disc.
- 3. The orientation of the arcs induce consistent orientations on the complementary regions.

Observe that each complimentary region to a triple point diagram is a disc.

The orientation condition 3) is equivalent to the following:

3'. Orientations of the arcs alternate "in" and "out" around each intersection point.

Let n be the number of arcs. Then each of the 2n endpoints is oriented "in" or "out", and these orientations alternate as we move around the boundary. Furthermore, given a collection of 2n alternatively oriented points on the boundary, a triple crossing diagram inducing such a collection provides a matching between the "in" and "out" points.

A triple point diagram is *minimal* if the number of its intersection points is not bigger than for any other diagram inducing the same matching on the boundary.

THEOREM 2.3 ([37]). -1) In a disc with 2n endpoints on the boundary, all n! matchings of "in" endpoints with "out" endpoints are achieved by minimal triple point diagrams.

2) Any two minimal triple point diagrams with the same matching on the endpoints can be related by a sequence of $2 \leftrightarrow 2$ moves, shown on Figure 5.



FIGURE 5. The 2 - 2 move.

⁽⁴⁾ This is called in [37] a connected triple point diagram.

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2.3. From minimal triple point diagrams to minimal bipartite surface graphs

Each crossing point of a triple point diagram has a canonical resolution, obtained by moving a little bit one of the strands passing through the point so that the emerging little triangle is oriented by the strands the same way as the surface—the counterclockwise resolution shown on Figure 6. We apply this procedure to every intersection point of a triple point diagram.

The complimentary domains for the obtained configuration of arcs are of three possible types: *black domains, white domains* and *faces,* according to definitions (1)-(3) in Section 2.2.1. Namely, the black and white domains are the ones consistently oriented counterclockwise and clockwise respectively—while the directions of the sides of the remaining domains, the faces, alternate. So we arrive at a bipartite graph associated to a minimal triple point diagram, see Figure 6. Its black vertices correspond to the triple crossing points, and thus are 3-valent. The white vertices can have valencies two, three or higher.

Let us shrink all edges incident to white 2-valent vertices (and remove the white vertex, gluing its two neighbors into a single vertex). The bipartite graph obtained can have both black and white vertices of valencies four or higher.



FIGURE 6. The bipartite graph obtained by counterclockwise resolution of a triple crossing diagram.

Let us call two bipartite graphs *similar* if the graphs obtained by shrinking their 2-valent white vertices coincide. There is a canonical bijection between the faces as well as between the perfect matchings for similar bipartite graphs. So similar bipartite graphs have the same partition function, discussed in Section 3.2.

Remark. There is another option: resolving all triple crossings clockwise. If a triple crossing diagram was associated to a Newton polygon N, the counterclockwise resolution is the same as the clockwise resolution of the diagram associated to the polygon N rotated by 180 degrees. Indeed, the rotation changes the orientations of all strands of the triple crossing diagram. Then resolving clockwise is the same as resolving counterclockwise the original triple crossing diagram.

2.4. Boundary intervals of the Newton polygon and zig-zag paths

Recall that a zig-zag path has a natural orientation such that it turns right at the black vertices. Therefore the homology class of a zig-zag path is well defined. It is a natural invariant of a zig-zag path. On a minimal bipartite graph Γ , a zig-zag path has no self-intersections, and so it is naturally a simple loop.

LEMMA 2.4. – Let N be a Newton polygon, and Γ a minimal bipartite graph on the torus assigned to N. The homology class of a zig-zag loop is a primitive vector on a side of N, whose orientation is induced by the orientation of N. The cyclically ordered set of zig-zag paths with a given homology class is identified with the cyclically ordered set of boundary intervals on the corresponding side of N. So the number of zig-zag paths on Γ equals to the number of integral boundary points on N.

Proof. – It is clear from Figure 7 that zig-zag paths on the bipartite graph arising from a triple crossing diagram correspond to the strands of the triple crossing diagram. On the other hand by construction the latter correspond to the primitive vectors of the boundary of the Newton polygon.



FIGURE 7. Zig-zag paths correspond to strands of the triple crossing diagram.

2.5. Elementary transformations of bipartite surface graphs

Figure 8 shows an elementary transformation $\Gamma_1 \rightarrow \Gamma_2$ of bipartite graphs, called a *spider move*. (There are two versions of the move depending on the color of the two interior vertices.) We will see below that for appropriate choice of weights the spider move does not change the partition function for the dimer model.



FIGURE 8. A spider move $\Gamma_1 \rightarrow \Gamma_2$ of bipartite graphs. The white vertices are attached to the rest of the graph; the black vertices are only attached to white vertices as shown.

Figure 9 shows a pair of elementary transformations of bipartite graphs: splitting a vertex of valency k > 3 and collapsing a 2-valent vertex. We will see below that it does not change the partition function.

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2.6. From minimal bipartite surface graphs to minimal triple point diagrams

A minimal bipartite graph can be transformed back into a triple point diagram in two steps.

Step 1. By a sequence of moves inverse to the shrinking of a 2-valent white vertex, we replace an arbitrary bipartite graph by a bipartite graph with black vertices of valency 3, see Figure 9.



FIGURE 9. Replacing a 4-valent black vertex by two 3-valent black vertices. A similar vertex splitting splits any k-valent black vertex into k - 2 3-valent ones.

Step 2. Take a minimal bipartite graph Γ on S with the black vertices of valency 3. Draw zig-zag strands on S assigned for all edges of Γ —two per edge. So each vertex of Γ is surrounded by an oriented arc m-gon. Then there is a unique way to shrink the counterclockwise triangles into points, getting a triple point diagram. This procedure is evidently inverse to the one we used to get a bipartite graph from a triple point diagram.



FIGURE 10. From bipartite graphs (solid) to triple point diagrams (dashed).

2.7. Graphs from polygons

Here is the main result of this section.

THEOREM 2.5. -i) For any Newton polygon N there exists a minimal admissible graph G on a torus associated with N. It produces a minimal bipartite torus graph Γ associated with N.

ii) Any two minimal bipartite graphs on a torus associated with N are related by a sequence of spider moves and shrinking / expanding of 2-valent vertices.

This result is illustrated in an example in Figure 11.



FIGURE 11. Procedure for going from a convex integer polygon to a bipartite torus graph: 1. A convex integer polygon. 2. The corresponding geodesics on a torus. 3. Isotoping the geodesics to a triple-crossing diagram having specified order of intersection with the boundary of the square. 4. The resulting bipartite graph.

Proof. – Let us glue a torus \mathbb{T} from a rectangle R by identifying opposite edges. Consider a finite collection of oriented simple loops α_i on \mathbb{T} , whose homology classes correspond to the primitive edge vectors of N, read counterclockwise around ∂N . We choose the loops so that the total number of intersections of any loop with an edge of R is minimal: this can be accomplished by starting with Euclidean geodesics (but we will isotope these around preserving the number of intersections with R).

Since ∂N is a closed path the total homology class $\sum_i [\alpha_i]$ represented by these loops is zero. So the total intersection number of these loops with any edge of the rectangle R is zero. Therefore we can isotope the loops, by moving them one through the other, so that the intersection points of the loops with an edge of R alternate in orientation: outgoing loops interlaced with ingoing loops. During this isotopy we do not add any more crossings of loops with ∂R , and furthermore we do not exchange two outgoing or two ingoing loops, that is, the order of outgoing paths and the order of ingoing paths do not change. We can do this simultaneously for all edges of R, so that the crossings of the loops with ∂R alternate around the entire boundary of R. Note that we have not introduced any new crossings of "outgoing" paths or crossings of "ingoing" paths, only crossings of one outgoing and one ingoing path. Then we can apply the part 1) of Theorem 2.3, and isotope the paths α_i into a minimal triple point diagram while fixing the boundary points on ∂R .

Note that each path α_i intersects the boundary with a consistent orientation (consistent with being a straight geodesic). Thus no path α_i can self-intersect: a "monogon" on \mathbb{T} is homotopically trivial and so must either lie entirely in the interior of R (disallowed by minimality of the triple point diagram) or intersect one of the sides of R with both orientations (disallowed by construction). Furthermore in \mathbb{T}^2 there are no parallel bigons: such a bigon cannot lie in the interior of R by minimality of the triple point diagram, and if it crosses the boundary, its vertices correspond to crossings of two outgoing or two ingoing paths which are not present in the original geodesic path diagram (in other words, along any isotopy back to a straight geodesic diagram there must occur at some point an uncrossing of two outgoing paths, a contradiction).

The components of the intersection of a loop with the interior of R will be called strands. Thanks to the part 2) of Theorem 2.3, any two minimal triple point diagrams whose strands



FIGURE 12. Permuting the boundary intersections

intersect ∂R in the same order are related by $2 \leftrightarrow 2$ moves. We claim that by isotoping the loops on the torus \mathbb{T} any two minimal triple point diagrams for the same polygon N are related by $2 \leftrightarrow 2$ moves. Consider the set of strands intersecting an edge E of R. Some of these strands may be part of the same loop, or part of isotopic loops. The relative order of intersection of these subsets of strands with ∂R is fixed. However the strands which are parts of different non-isotopic geodesics do not have a unique relative order along ∂R . We need to show that by isotopy and $2 \leftrightarrow 2$ moves we can permute the order of intersection of these sets of strands with E.

Let a, c be consecutive "ingoing" strands on ∂R which by the alternating property necessarily are separated by a single "outgoing" strand b, so that a, b, c are three consecutive intersections of strands with ∂R . Suppose that the strands ending at a, c cross inside the rectangle R. We show that using $2 \leftrightarrow 2$ moves and isotopy on \mathbb{T} we can rearrange these strands so that they intersect ∂R consecutively in the reverse order c, b, a without changing the order of the other intersections. In other words, we can arbitrarily permute the "ingoing" strands by doing a sequence of these transpositions $\{a, c\} \rightarrow \{c, a\}$ as long as they intersect in R, and similarly for the "outgoing" strands. To accomplish this transposition, [37] shows that we can use $2 \leftrightarrow 2$ moves so that the triple point diagram inside R has the three strands at a, b, c meeting just adjacent to the boundary (that is, before meeting any other strands). Then one can simply isotope this triple crossing across the boundary which has the effect of switching the intersections order of the strands to c, b, a as desired. See Figure 12.

Now given a triple point diagram one can construct the minimal bipartite graph as above. Observe that there are two different $2 \leftrightarrow 2$ move diagrams: the one is obtained from the other by reversing the strand orientations. Resolving their triple intersection points in the standard (counterclockwise) way, we get two elementary moves of bipartite graphs: the spider move on Figure 13 and the move on Figure 14 which amounts to shrinking the edge with a 2-valent (white) vertex, and expanding it the other way.



FIGURE 13. This $2 \leftrightarrow 2$ move amounts to a spider move of bipartite graphs.



FIGURE 14. This $2 \leftrightarrow 2$ move amounts to collapsing the edges incident to a white 2-valent vertex and expanding the other way.

3. Integrability of the dimer model

3.1. Edge weights and line bundles with connections on a graph

A vector bundle with connection on a graph Γ is the following data: we assign to each vertex v of Γ a vector space V_v , and to each oriented edge E from a vertex v_1 to a vertex v_2 an isomorphism

$$i_E: V_{v_1} \to V_{v_2}$$

called parallel transport, so that $i_{-E} = i_E^{-1}$, where -E is the edge E with the opposite orientation. The monodromy of the connection along a loop is the composition of the parallel transports around the loop. Two vector bundles with connections $\{V, i_E\}, \{V', i'_E\}$ are isomorphic (gauge equivalent) if there are isomorphisms $\psi_v : V_v \to V'_v$ such that $i'_E = \psi_{v_2} \circ i_E \circ \psi_{v_1}^{-1}$ for all edges $E = v_1 v_2$.

The moduli space \mathscr{L}_{Γ} is the space of line bundles with connections on a graph Γ modulo isomorphisms. Here is another description of the moduli space \mathscr{L}_{Γ} . Choose a non-zero vector e_v in each space V_v . Then a line bundle with connection on Γ amounts to a collection of nonzero numbers, the *edge weights* a_E , assigned to the oriented edges E of the graph, so that $a_{-E} = a_E^{-1}$:

$$i_E e_{v_1} = a_E e_{v_2}, \qquad E = v_1 \to v_2.$$

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Another choice of base vectors $e'_v = b_v e_v$ gives rise to a different set of edge weights a'_E , related to the original one by a gauge transformation: $a'_E = b_v a_E b_{v'}^{-1}$. So

$$\mathscr{L}_{\Gamma} = \frac{\text{edge weights}}{\text{gauge transformations}}.$$

Given a trivialization $\{e_v\}$ of a line bundle with connection $\{V, i_E\}$, we can encode the connection by the Kasteleyn operator K, see Section 1.4.1, which in this case is just a matrix. However the determinant det(K) is not gauge invariant, and so is not a function on the moduli space \mathcal{L}_{Γ} .

3.2. The partition function and the Hamiltonians

3.2.1. The weight of a dimer cover. – A dimer cover of a bipartite graph Γ , also known as a *perfect matching*, is a collection of edges of Γ such that each vertex is the endpoint of a unique edge in the dimer cover.

Recall the determinant line **L**, see (12). Given a connection, a dimer cover M on Γ provides an **L**-valued function W(M) on \mathcal{L}_{Γ} , called the *weight of* M. For an edge E = bw, let i_E be the parallel transport along E of L. Then $i_E \in V_b^* \otimes V_w$. The product of these vectors over the edges of M is the weight:

$$W(M) \in \mathcal{O}(\mathcal{L}_{\Gamma}) \otimes \mathbf{L}$$

Precisely, choose an order of the edges E_1, \ldots, E_N of the matching. Write $i_E = a_E^* \otimes b_E$. Then $W(M) := a_{E_1}^* \wedge \cdots \wedge a_{E_N}^* \otimes b_{E_1} \wedge \cdots \wedge b_{E_N}$. It does not change when we alter the order of edges. The following result, due to Kasteleyn (in different language), is well known.

ТНЕОВЕМ 3.1 ([22]). – We have

(18)
$$\det K = \sum_{M} \operatorname{sgn}(M) W(M) \in \mathcal{O}(\mathcal{L}_{\Gamma}) \otimes \mathbf{L}$$

where the sum is over dimer covers and the sign gn(M) only depends on the choice of the Kasteleyn line bundle with connection (see Section 1.4.1) and the homology class modulo 2 of M (defined in Section 3.2.2).

DEFINITION 3.2. – The partition function is $\mathscr{P}_{\Gamma} = \det K$.

The partition function depends on our choice of κ , which we fixed once and for all.

3.2.2. The homology class of a dimer cover. – A dimer cover M on Γ provides a function

$$\omega_M : \{ \text{Edges of } \Gamma \} \to \{0, 1\}.$$

Its value on an edge is 1 if and only if the edge belongs to M. We view it as a 1-chain

$$[M] := -\sum_{E} \omega_M(E)[E],$$

where the sum is over all edges, and [E] is the edge E oriented from black to white. The condition that M is a dimer cover means that

$$d[M] = \sum_{v} \operatorname{sgn}(v)[v]$$

where the sum is over all vertices v of Γ , and sgn(v) = 1 for the black vertex v, and sgn(v) = -1 for the white.

If M_1, M_2 are dimer covers, $[M_1] - [M_2]$ is a 1-cycle, and thus each dimer cover defines an "affine" homology class. It is more convenient to define an absolute homology class for each dimer cover by fixing a chain Φ such that $[M] - \Phi$ is a cycle (for all M). We do this in Section 3.2.3.

REMARK. – A dimer cover M_2 trivializes the determinant line **L** by providing isomorphisms $V_b \rightarrow V_w$ for each edge E = bw. In Section 3.2.3 we consider "fractional" dimer covers provided by weighted zig-zag paths, and use them in a similar way to trivialize **L**.

3.2.3. The α -deformed partition function. – For every edge of an oriented ribbon graph there are exactly two zig-zag paths containing the edge (one in which the edge is traversed in either orientation). Let *E* be an edge of Γ . Denote by z^r (respectively z^l) the zig-zag path containing *E* in which the white vertex of *E* precedes the black (respectively follows the black). Let us consider a map

(19)
$$\alpha : \{ \text{zig-zag paths on } \Gamma \} \longrightarrow \mathbb{R}/\mathbb{Z}.$$

It provides a function

(20) $\varphi_{\alpha} = \varphi : \{ \text{Edges of } \Gamma \} \longrightarrow \mathbb{R}, \qquad \varphi(E) := \alpha_r - \alpha_l,$

where α_r (respectively α_l) is the evaluation of the map α on the zig-zag path z^r (respectively z^l) crossing the edge E, see Figure 15, and $\alpha_r - \alpha_l$ denotes the length of the counterclockwise arc on $S^1 = \mathbb{R}/\mathbb{Z}$ from α_l to α_r .



FIGURE 15. The weight is $\varphi(E) = \alpha_r - \alpha_l$.

The strands, and thus the oriented zig-zag paths, are in bijection with the set $\{e_1, \ldots, e_n\}$ of primitive edges of the boundary ∂N of N, and so inherit a circular order from ∂N .

THEOREM 3.3. – Let X be the set of circular-order-preserving maps

$$\{e_1,\ldots,e_n\}\to \mathbb{R}/\mathbb{Z}.$$

For any map $\alpha \in X$, the function φ_{α} satisfies

(21)
$$d\varphi_{\alpha} = \sum_{v} \operatorname{sgn}(v)[v]$$

The result is more generally true for arbitrary triple crossing diagrams in a disk.

Proof. – We need to show that $d\varphi_{\alpha} = 1$, respectively -1, at a black, respectively white, vertex. For this it suffices to show that at each vertex, the set of adjacent strands (the strands intersecting edges emanating from the vertex) has the same circular order as the circular order of the edges containing the vertex. This follows from Lemma 3.4 below.

LEMMA 3.4. – Given a triple-crossing diagram in a disk, at any triple-crossing the three intersecting strands occur in the same circular order as their ingoing endpoints on the boundary of the disk.

Proof. – The proof is by induction on the number of strands. Order the strands according to the counterclockwise circular order of their ingoing endpoints. We recall the construction of a triple crossing diagram of [37]: take a strand with the property that on one side, no other strand has both its endpoints. One can draw this strand following the boundary as illustrated in Figure 16, crossing the intermediate strands in pairs. Each of these crossings is positive. The remaining region again has the property that the strands alternate orientation along the boundary and so can be completed to a triple crossing diagram with one fewer strands by induction. Moreover the ingoing strands of the new region retain their original circular order.



FIGURE 16.

By taking limits in which all points $\alpha(e_i)$ collide (but preserve their circular order) there are circular-order-preserving maps α for which φ_{α} takes integer values $\varphi_{\alpha} \in \{0, 1\}$.

Given a map α provided by Theorem 3.3, there is a 1-chain

$$\Phi_{\alpha} = \sum_{E} \varphi_{\alpha}(E)[E] \quad \text{with} \quad d\Phi_{\alpha} = \sum_{v} \operatorname{sgn}(v)[v].$$

It is an integral 1-chain if ϕ_{α} is integer-valued. Thus $[M] - \Phi_{\alpha}$ is an integral cycle. It provides a monomial function on \mathcal{L}_{Γ}

(22)
$$\omega_{\alpha}(M): \mathscr{L}_{\Gamma} \longrightarrow \mathbb{C}^{*},$$

given by the monodromy around the cycle $[M] - \Phi_{\alpha}$. It is the complex character of the group \mathscr{L}_{Γ} corresponding to the homology class $[M] - \Phi_{\alpha}$ via the isomorphism (1).

DEFINITION 3.5. – Let Γ be a bipartite surface graph. Let α be a map satisfying (21). The α -deformed partition function \mathcal{P}_{α} of the dimer model on Γ is a function on the space \mathcal{L}_{Γ} given as the sum of monomials $\omega_{\alpha}(M)$ over all dimer covers M of Γ , with the same signs as in (18):

(23)
$$\mathscr{P}_{\alpha} := \sum_{M} \operatorname{sgn}(M) \omega_{\alpha}(M)$$

3.2.4. The Hamiltonians. – Let $[M]_{\alpha} \in H_1(\Gamma, \mathbb{Z})$ be the homology class of the cycle $[M] - \Phi_{\alpha}$. Recall the projection $\pi : H_1(\Gamma, \mathbb{Z}) \to H_1(S, \mathbb{Z})$. Given a homology class $a \in H_1(S, \mathbb{Z})$, take the part of the sum (23) over the matchings M such that the projection of $[M]_{\alpha}$ to $H_1(S, \mathbb{Z})$ is the class a:

$$H_{\alpha;a} := \sum_{M:\pi([M]_{\alpha})=a} \operatorname{sgn}(M)\omega_{\alpha}(M).$$

By Theorem 3.1 the sign sgn(M) depends only on a, and the partition function is a sum

(24)
$$\mathscr{P}_{\alpha} = \sum_{a \in H_1(S,\mathbb{Z})} \operatorname{sgn}(a) H_{\alpha;a}.$$

DEFINITION 3.6. – The functions $H_{\alpha;a}$ in (24) are the Hamiltonians of the dimer system.

Remark. A different map α' leads to another collection of Hamiltonians $\{H_{\alpha';a}\}$ which differ from $\{H_{\alpha;a}\}$ by a common monomial factor, which lies in the center of the Poisson algebra $\vartheta(\mathscr{L}_{\Gamma})$. Indeed, the monodromy along any zig-zag loop is a Casimir element. Therefore the Hamiltonian flows do not depend on the choice of α , and on each symplectic leaf any two collections of Hamiltonians differ by a common factor.

3.2.5. A coordinate expression. – Let z_1, \ldots, z_{2g} be loops on Γ whose homology classes generate $H_1(S, \mathbb{Z})$. Let $\sum n_i[z_i]$ be the homology class of the cycle $[M] - \Phi_{\alpha}$. Then there is a function ψ_M : {Faces of Γ } $\rightarrow \mathbb{R}$, which we interpret as a 2-chain, such that

$$d\psi_M = [M] - \Phi_\alpha - \sum n_i[z_i].$$

So one has

$$\mathcal{P}_{\alpha} := \sum_{M} \pm \prod_{F} W_{F}^{\psi_{M}(F)} \prod_{i} z_{i}^{n_{i}}.$$

Each Hamiltonian is, up to a sign, a sum of monomials with coefficients +1 in variables W_F, z_i with a given value of (n_1, \ldots, n_{2q}) . If S is the torus, P_{α} is a polynomial in z_1, z_2 .

3.3. The classical Hamiltonians commute

A minimal bipartite graph on a torus provides an algebraic integrable system:

THEOREM 3.7. – Let Γ be a minimal bipartite graph on a torus \mathbb{T} . Then

i) The Hamiltonians $H_{\alpha;a}$ commute under the Poisson bracket on \mathcal{L}_{Γ} .

ii) The Hamiltonians are independent and their number is the half of the dimension of the generic symplectic leaf.

The part i) of Theorem 3.7 is proved in Section 3.3. The number of Hamiltonians is counted in Section 3.7, based on the results of Section 3.6. Finally, the independence of Hamiltonians is proved in Section 7.4.

The quantum version of our integrable system is established in Section 4.3. The key point is that the classical Hamiltonians are Laurent polynomials in any coordinate system related to a minimal bipartite graph on the torus, and thus admit a natural upgrade to elements of the corresponding quantum tori. The claim that they commute follows then immediately from the combinatorial proof of commutativity of the classical Hamiltonians given below. We also need the independence of the classical Hamiltonians, proved in Section 7.4.

Section 5 is totally independent: it neither relies on nor is used in the proof of integrability. Section 6 is not used in the proof of integrability. It discusses more specific discrete cluster integrable systems, assuming Theorem 3.7.

Proof of part i). – Take a pair of matchings (M_1, M_2) on Γ . Let us assign to them another pair of matchings $(\widetilde{M}_1, \widetilde{M}_2)$ on Γ . Observe that $[M_1] - [M_2]$ is a 1-cycle. It is a disjoint union of

- 1. homologically trivial loops,
- 2. homologically non-trivial loops,
- 3. edges shared by both matchings.

For every edge E of each homologically trivial loop we switch the label of E: if E belongs to a matching M_1 (respectively M_2), we declare that it will belong to a matching \widetilde{M}_2 (respectively \widetilde{M}_1). For all other edges we keep their labels intact. Denote by μ_i and $\widetilde{\mu}_i$ the homology classes of the cycles $[M_i] - \Phi_{\alpha}$ and $[\widetilde{M}_i] - \Phi_{\alpha}$. Clearly $(\widetilde{\widetilde{M}}_1, \widetilde{\widetilde{M}}_2) = (M_1, M_2)$. We use a shorthand $\varepsilon(*, *)$ for $\varepsilon(*, *)_{S_{\Gamma}}$.

LEMMA 3.8. – One has

(25)
$$\varepsilon(\mu_1,\mu_2) + \varepsilon(\widetilde{\mu}_1,\widetilde{\mu}_2) = 0.$$

Proof. – We use a local calculation of the Poisson bracket on \mathcal{L}_{Γ} given in Section 8. Let us write (25) as a sum of the local contributions corresponding to the vertices v of Γ , and break it in three pieces as follows:

$$\varepsilon(\mu_1,\mu_2) + \varepsilon(\widetilde{\mu}_1,\widetilde{\mu}_2) = \left(\sum_{v \in \mathcal{E}_1} + \sum_{v \in \mathcal{E}_2} + \sum_{v \in \mathcal{E}_3}\right) \left(\delta_v(\mu_1,\mu_2) + \delta_v(\widetilde{\mu}_1,\widetilde{\mu}_2)\right).$$

Here \mathcal{E}_1 (respectively \mathcal{E}_2 and \mathcal{E}_3) is the set of vertices which belongs to the homologically trivial loops (respectively homologically non-trivial loops, double edges).

Then for any $v \in \mathcal{E}_1$ we have $\delta_v(\mu_1, \mu_2) + \delta_v(\tilde{\mu}_1, \tilde{\mu}_2) = 0$ since the element $l_v(\mu_1) \in \mathbb{A}_v$ provided by μ_i by the very construction coincides with the element $l_v(\tilde{\mu}_2)$, and similarly $l_v(\mu_2) = l_v(\tilde{\mu}_1)$. So the first sum is zero since it is a sum of zeros.

The third sum is also a sum of zeros. Indeed, the contribution of the matchings M_1 and M_2 at every vertex $v \in \mathcal{E}_3$ is the same, so the local pairing vanishes by the skew symmetry.

It remains to prove that

$$\sum_{v \in \mathscr{E}_2} \left(\delta_v(\mu_1, \mu_2) + \delta_v(\widetilde{\mu}_1, \widetilde{\mu}_2) \right) = 0.$$

Let γ be an oriented loop on Γ . We define the *bending* $b_v(\gamma; \varphi)$ of the function φ at a vertex v of γ as

$$b_v(\gamma; \varphi) = \sum_{E \in R_v} \varphi(E) - \sum_{E \in L_v} \varphi(E) \in \mathbb{R}.$$

Here R_v (respectively L_v) is the set of all edges sharing the vertex v which are on the right (respectively left) of the path γ , following the direction of the path γ . Lemma 3.8 now follows from Lemma 3.9 below.

Recall the set X of circular-order-preserving maps from the zig-zag paths to \mathbb{R}/\mathbb{Z} .

LEMMA 3.9. – There is an $\alpha \in X$ such that the corresponding function φ_{α} satisfies, for any simple topologically nontrivial loop γ ,

$$\sum_{v\in\gamma} b_v(\gamma;\varphi_\alpha) = 0.$$

Proof. – On a Euclidean torus, a simple closed polygonal curve which is not nullhomotopic has the property that its net curvature is zero, where the net curvature is the total amount of left turning minus right turning. This fact can be seen by taking an isotopy of the curve to a straight geodesic through a family of simple polygonal curves; the total curvature is an integer multiple of 2π but changes continuously under the isotopy, and for a geodesic it is zero.

A map $\alpha \in X$ allows us to draw our graph Γ on a Euclidean torus in such a way that $b_v(\gamma, \varphi_\alpha)$ is (with a small proviso) the net curvature of γ at vertex v. This is accomplished as follows. To each edge E, recall that α_r, α_l are the angles of the strands crossing E. We define a 1-cochain f by $f(E) = e^{i\alpha_l} + e^{i\alpha_r}$. We have df = 0, since strands cross two edges of every face, once with each orientation. Thus there is a multivalued function F on vertices of Γ , which is locally well defined but has additive periods ω_1, ω_2 for the generators of $H_1(S)$. Extending F linearly over the edges gives a map from Γ to a Euclidean torus $\mathbb{C}/\langle \omega_1, \omega_2 \rangle$. Locally, to each edge we are associating a Euclidean rhombus with vertices $z, z + e^{i\alpha_l}, z + e^{i\alpha_r}, z + e^{i\alpha_r}$, where z is determined by F; the edge E runs from z to $z + e^{i\alpha_l} + e^{i\alpha_r}$, and the vertices $z + e^{i\alpha_l}, z + e^{i\alpha_r}$ are the centers of the faces adjacent to E. These rhombi are glued edge to edge to form a Euclidean torus (possibly with conical singularities).

If for each E the angle $\varphi(E) = \alpha_r - \alpha_l$ is less than π , then the rhombi are positively oriented and, by Lemma 3.3, the total angle at each vertex is 2π and our Euclidean surface is smooth, that is, has no singularities. If a rhombus for edge E, connecting vertices v, v', has angle larger than π , by Lemma 3.3 it will be the only rhombus at v or v' with this property. Hence the singularities in our Euclidean structure are folds, as shown in Figure 17, and are separated from each other.

It remains to check that if γ contains a vertex v which has a singularity then it is still true that $b_v(\gamma, \varphi)$ measures the net curvature of γ at v. If γ passes through v but not along edge Ethis is trivially true. In the remaining case, γ contains edge E = vv': suppose γ contains consecutive vertices v_1, v, v', v_2 in order. Then it is straightforward to check that the sum of the curvature contributions at v and v' equals the change in Euclidean angle of the edge v_1v to the edge $v'v_2$. In all cases therefore b_v is the net curvature of γ , which is zero.

The part i) of Theorem 3.7 follows immediately from Lemma 3.8. Indeed, the sum calculating the Poisson bracket of two Hamiltonians can be presented as a sum of contributions (25). The part i) of Theorem 3.7 is proved. \Box

3.4. The matching polytope

Let Ω be the *matching polytope* of Γ . By definition this is the subset

$$\Omega \subset [0,1]^{\{\text{edges of }\Gamma\}}$$

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FIGURE 17.

consisting of functions ω on edges of Γ with values in [0, 1] such that the sum of the values at every vertex is 1. The subset Ω is a convex polyhedron.

LEMMA 3.10 ([30]). – The vertices of Ω are the perfect matchings of Γ .

Proof. – To make the paper self-contained, we give a proof. Let ω be a vertex of Ω . Let us show that for every vertex v of Γ there is just one edge E incident to v with $\omega(E) \neq 0$. Indeed, otherwise there is a vertex of v_1 incident to edges E_1, E_2 with the weights in (0, 1). Let v_2 be another vertex of E_2 . It is incident to another edge E_3 with the weight in (0, 1)—otherwise the sum of the weights at v_2 will be less than 1. Let v_3 be another edge of E_3 , and so on. We get a closed path on Γ whose edges have the weights in (0, 1). Let us add ε to the weight of each of these edges, where $|\varepsilon|$ is very small, and the signs alternate. The sign condition does not lead to a problem since Γ is a bipartite graph. Then we still get an element $\omega_{\varepsilon} \in \Omega$. So ω is inside of a segment in Ω . Thus it is not a vertex of Ω .

It follows that the values of ω at the edges are either 1 or 0. The edges where the value is 1 give a matching.

Elements of Ω are called *fractional matchings*.

LEMMA 3.11. – Let Γ be a minimal bipartite graph on a torus. Then Γ has a perfect matching.

Proof. – It suffices to show that Ω is nonempty. Indeed, by Lemma 3.10 any vertex of the polyhedron Ω provides a perfect matching. Any minimal bipartite graph Γ is obtained from some polygon N. The function φ_{α} from Theorem 3.3 is then a fractional matching by (21).

Let $\omega_0 \in \Omega$ be a fixed fractional matching. Then for any $\omega \in \Omega$ the difference $[\omega] - [\omega_0]$ is a 1-cycle on Γ . Taking its homology class we get a map $\Omega \to H_1(\Gamma, \mathbb{R})$. Its image is a convex polyhedron $[\Omega] \subset H_1(\Gamma, \mathbb{R})$. Its projection under the canonical map $\pi : H_1(\Gamma, \mathbb{R}) \to H_1(\mathbb{T}, \mathbb{R})$ is a convex polygon

$$\pi[\Omega] \subset H_1(\mathbb{T}, \mathbb{R}) \cong \mathbb{R}^2,$$

which depends on ω_0 only through a translation.

Recall the space X of order-preserving maps from $\{e_1, \ldots, e_n\}$ to \mathbb{R}/\mathbb{Z} . The image of X under the map $\alpha \to \varphi(\alpha)$ is a subpolyhedron $\Omega_0 \subset \Omega$. It is in fact a simplex: the simplex of order-preserving maps from the strands to \mathbb{R}/\mathbb{Z} , modulo rotation.

Let $\alpha_i \in X$ be the map which sends all E_i to 0 and assigns 1 to the arc between E_i and E_{i+1} , and 0 to all other arcs. The matching $\varphi(\alpha_i)$ maps to a vertex of Ω_0 , and every vertex of Ω_0 is of this type.

3.5. The Newton polygon

THEOREM 3.12. – Let Γ be a minimal bipartite graph with polygon N. Then the Newton polygon of the partition function $P_{\alpha}(z_1, z_2)$ for Γ is N (up to translation).

Proof. – Set $\omega_0 = \Phi_{\alpha}$. The Newton polygon of $P_{\alpha}(z_1, z_2)$ is a translate of $\pi[\Omega]$. Indeed, by definition the coefficient in P of $z_1^{i_1} z_2^{i_2}$ is the sum of weights of dimer covers M of Γ for which the homology class $[M] - \Phi_{\alpha}$ satisfies $[M] - \Phi_{\alpha} = i_1[z_1] + i_2[z_2]$.

We can define the intersection pairing of a chain with a zig-zag path Z as follows. If $C = \sum_E C_E[E]$ is a chain, the intersection pairing of C with Z is $\langle C, [Z] \rangle = \sum_{E \in Z} \pm C_E$ where the sign is alternating, and depends to whether the orientation of the edge of Z agrees with the white-to-black orientation or disagrees with it. In other words, this is the intersection pairing of C with the strand corresponding to Z.

We define another polygon $N_{\Gamma} \subset H_1(\mathbb{T}, \mathbb{R})$ by a set of inequalities

(26)
$$N_{\Gamma} := \left\{ \gamma \in H_1(\mathbb{T}, \mathbb{R}) \mid \langle \gamma, [Z] \rangle \leq \frac{l(Z)}{2} - \langle [\omega_0], [Z] \rangle \text{ for every zig-zag path } Z \right\}.$$

We claim that N, N_{Γ} and $\pi[\Omega]$ are translates of each other.

We first show that $\pi[\Omega] \subset N_{\Gamma}$. Let $\omega \in \Omega$. The sum of $\omega(E)$ over the edges E in a zig-zag path Z is at most equal to l(Z)/2, since this is the number of white vertices adjacent to Z (each white vertex adjacent to Z has total flow at most 1 across Z). Thus

$$\langle [\omega - \omega_0], [Z] \rangle = \langle [\omega], [Z] \rangle - \langle [\omega_0], [Z] \rangle \leq \frac{l(Z)}{2} - \langle [\omega_0], [Z] \rangle$$

which implies that $\pi[\Omega] \subset N_{\Gamma}$.

We now show that the edges of N and N_{Γ} coincide. Take $\gamma_i = [\omega(\alpha_i) - \omega_0]$. This satisfies the inequalities (26) and two of these are equalities: those for Z_i and Z_{i+1} , because in α_i every white vertex adjacent to Z_i is matched to a black vertex on the other side of Z_i , and similarly for Z_{i+1} . Note moreover that $\gamma_{i+1} = \gamma_i + [Z_i]$ so we see that $[Z_i] = e_i$ is an edge of N_{Γ} . Thus N_{Γ} has sides consisting of the e_i in order, which proves that N and N_{Γ} are translates. Note moreover that each corner of N_{Γ} is in the image of $\pi[\Omega]$ (in fact in the image of $\pi[\Omega_0]$). Thus $\pi[\Omega] = N_{\Gamma}$.

3.6. Counting triple crossings and faces

From Thurston [37], the number of triple crossings in any triple crossing diagram in a disk is a function solely of the strand order along the boundary, and can be obtained as follows. Take a linear order of the strand endpoints which is consistent with the circular order. Then we say two strands ac and bd, directed from a to c and b to d respectively, have a *parallel* crossing if their endpoints are in the order a < b < c < d or d < c < b < a.

LEMMA 3.13 ([37]). – In a minimal triple-crossing diagram in a disk, the number of triple crossings is the number of pairs of strands with a parallel crossing.

Now take a triple crossing diagram on the unit square $[0,1]^2$ obtained from a convex integral polygon N as in Section 2. Let $e_1, \ldots, e_n \in \mathbb{Z}^2$ be the primitive sides of N.

LEMMA 3.14. – The number of triple crossings is twice the area of N.

Proof. – A minimal triple crossing diagram can be obtained by starting with a configuration of straight geodesics on the torus $[0, 1]^2$, one for each e_i , and then isotoping them into position.

We count the number of parallel crossings in a standard configuration of the geodesics e_i and then notice that this number is invariant when we isotope the strands to their final position.

Let $\tau \in \mathbb{R}^2$ be a vector with positive coordinates having irrational ratio, and let v_{\min}, v_{\max} be respectively the unique vertices of N which minimize, respectively maximize, $v \cdot \tau$. Let N_R be the set of sides of N between v_{\min} and v_{\max} in counterclockwise order and N_L be the set of sides of N between v_{\max} and v_{\min} in counterclockwise order. Then after a circular reindexing, say that $e_1, \ldots, e_k \in N_R$ and $e_{k+1}, \ldots, e_n \in N_L$.

Let $p = \varepsilon \tau \in [0, 1)^2$ for some sufficiently small ε . Start by drawing all geodesics e_i in the torus through p. No geodesic contains the origin by irrationality of τ ; order the boundary points on the square counterclockwise starting from the origin. Then e_i and e_j have a parallel crossing at p if and only if e_i and e_j are either both in N_R or both in N_L . Moreover if p is sufficiently close to the origin all other crossings of e_i and e_j will be parallel or non-parallel according to the crossing at p.

Thus the number of parallel crossing strands in total is

$$\sum_{1 \le i < j \le k} |e_i \wedge e_j| + \sum_{k+1 \le i < j \le n} |e_i \wedge e_j|.$$

However the area of the part of N below the line through v_{\min} and v_{\max} is 1/2 of

$$e_1 \wedge e_2 + (e_1 + e_2) \wedge e_3 + \dots + (e_1 + \dots + e_{k-1}) \wedge e_k = \sum_{1 \le i < j \le k} |e_i \wedge e_j|,$$

as can be seen by triangulating this polygon using extra edges from v_{\min} to each other v. Similarly for the upper part of N.

Now as we isotope the geodesics e_i , without letting a strand cross the origin, it is easy to see that the number of parallel crossings does not change.

Let us denote by B and W the number of black and white faces for a triple point diagram graph G on the torus arising from a Newton polygon N. Let V be the number of vertices of G, that is the number of the triple crossings.

PROPOSITION 3.15. – One has

$$B = W = V$$
 = number of the triple crossings = 2(area of N).

Proof. – Euler's formula for the triple point diagram G gives V - E + F = 0. Counting flags (vertex, edge) we get 6V = 2E. Therefore F = 2V.

Lemma 3.11 implies that B = W. Indeed, the white (respectively black) domains of a triple point diagram G became the white (respectively black) vertices of the bipartite graph Γ . Thus F = B + W implies B = W = V. Lemma 3.14 implies the last statement.

3.7. The number of Hamiltonians

Let i(N) and e(N) be the number of interior and exterior points for the Newton polygon N. Pick's formula plus Proposition 3.15 gives

(27)
$$2i(N) + e(N) - 2 = 2(\text{area of } N) = B$$

Observe that i(N) is the number of Hamiltonians, and e(N) is the number of Casimirs plus one, that is the dimension of center of the Poisson algebra $\mathcal{O}(\mathcal{L}_{\Gamma})$ minus one. On the other hand, B is the number of faces minus one, and $\operatorname{rk} H_1(S, \mathbb{Z}) = 2$. So $B + 1 = \dim \mathcal{L}_{\Gamma}$. So (27) implies that

2(number of Hamiltonians) = dim
$$\mathcal{L}_{\Gamma}$$
 - dim(Center $\mathcal{O}(\mathcal{L}_{\Gamma})$).

4. Dimers, cluster Poisson transformations, and quantum integrability

4.1. Dimer models on surfaces and cluster Poisson varieties

4.1.1. Gluing the conjugated surfaces according to a spider move. – Given a bipartite ribbon graph Γ , let \hat{S}_{Γ} be the corresponding conjugated surface. Since the conjugated graph $\hat{\Gamma}$ coincides with Γ as a graph, there are canonical isomorphisms:

(28)
$$H_1(\widehat{S}_{\Gamma},\mathbb{Z}) = H_1(\widehat{\Gamma},\mathbb{Z}) = H_1(\Gamma,\mathbb{Z})$$

We denote by Λ_{Γ} the lattice (28). It is equipped with the skew symmetric integral bilinear form $(*, *)_{\widehat{\Gamma}}$ given by the intersection pairing on \widehat{S}_{Γ} . The boundaries ∂F of the faces F of Γ , whose orientations are induced by the orientation of S, give rise to a collection of cycles $\{\gamma_F\}$ on \widehat{S}_{Γ} . These cycles plus the generators $\alpha_1, \ldots, \alpha_{2g}$ of $H_1(S, \mathbb{Z})$ generate Λ_{Γ} , and satisfy the only relation $\sum_F \gamma_F = 0$.

A *spider move* is a transformation of a bipartite graph shown in dashed lines on Figure 18. We show on the same figure the transformation of the accompanying zig-zag paths (solid), and the unique cyclic order (1, 3, 2, 4) of the zig-zag paths compatible with the cyclic orders of the triples of the zig-zag paths at the black vertices. The white vertices give rise to the opposite cyclic order. These cyclic orders are the same for both graphs.

Let F be the rectangular face on Γ which determines a spider move $s : \Gamma \longrightarrow \Gamma'$. Denote by F_1, F_2, F_3, F_4 the faces of Γ sharing edges with F. We assume for simplicity of the



FIGURE 18. A spider move and zig-zag paths.

exposition that these are different faces. The spider move does not affect the graph Γ outside of a little domain U containing the face F and the two extra edges emanating from the two black vertices of F. We identify the conjugated surfaces \hat{S}_{Γ} and $\hat{S}_{\Gamma'}$ outside of the U. We want to extend this identification to a homeomorphism of surfaces

(29)
$$\widehat{s}:\widehat{S}_{\Gamma}\longrightarrow \widehat{S}_{\Gamma'}$$

LEMMA 4.1. – There is a unique up to isotopy homeomorphism (29) identifying the boundary loops and identical outside of U-domains. Let $\gamma'_G := \hat{s}(\gamma_G)$. Then one has

(30) $\gamma'_F = -\gamma_F$, $\gamma'_{F_1} = \gamma_{F_1} + \gamma_F$, $\gamma'_{F_2} = \gamma_{F_2}$, $\gamma'_{F_3} = \gamma_{F_3} + \gamma_F$, $\gamma'_{F_4} = \gamma_{F_4}$. Otherwise $\gamma'_G = \gamma_G$.



FIGURE 19. Identifying the conjugated surfaces according to a spider move. Recall our convention that a zig-zag path goes counterclockwise around black vertices and clockwise around the white ones. When we turn the surface over, the notion of counterclockwise and clockwise is interchanged. Since to get $\hat{\Gamma}$ we turned the white vertices over, the new orientation is counterclockwise for all vertices. (In the figure, we are seeing the underside of the surface near the black vertices.)



FIGURE 20. Identifying the conjugated surfaces according to a spider move, shown in the untwisted version.

Proof. – Figure 19 (and Figure 20 in the untwisted version) shows the ribbon graphs $\widehat{\Gamma}$ and $\widehat{\Gamma}'$ inside of the U-domains. Each component of the oriented boundary of a ribbon is a part of an oriented zig-zag path on Γ . Any map (29) preserving the boundaries and identical outside of U-domains identifies the zig-zag paths on the original graphs. This determines the gluing uniquely up to an isotopy. So we get the first claim of the lemma.

On each surface the four zig-zag paths inside of U bound an annulus. A pair of parallel zig-zag paths together with a pair of connecting them little segments form a boundary component of the annulus. Our gluing process amounts to gluing these two annuli.

Taking a loop going around the face on the left of Figure 19, and tracing its image on the right surface, we get $\gamma'_F = -\gamma_F$. Similarly we get the other identities.

4.1.2. Seeds, mutations, conjugated surfaces and spider moves

DEFINITION 4.2. – A seed **s** is a datum $(\Lambda, \{e_i\}, (*, *))$, where

- Λ is a lattice, i.e., a free abelian group, $\{e_i\}$ is a collection of non-zero vectors in Λ ;
- (*,*) is a skew-symmetric \mathbb{Z} -valued bilinear form on Λ .

DEFINITION 4.3. – A mutation of a seed \mathbf{s} in the direction of a basis vector e_k is a new seed $\mathbf{\tilde{s}}$. The lattice and the form of the seed $\mathbf{\tilde{s}}$ are the same as of \mathbf{s} . The collection of vectors $\{\tilde{e}_i\}$ of $\mathbf{\tilde{s}}$ is defined by applying a half reflection at e_k map to the old one:

(31)
$$\widetilde{e}_{i} := \begin{cases} e_{i} + (e_{i}, e_{k})_{+} e_{k} & \text{if } i \neq k \\ -e_{k} & \text{if } i = k. \end{cases} \quad a_{+} := \max(a, 0).$$

Definitions 4.2 and 4.3 generalize slightly the standard definitions of seeds and seed mutations, see Sections 1.2.1–1.2.4 of [10]. Unlike *loc. cit*, we demand neither that the vectors e_i are linearly independent, nor that they span the lattice Λ .⁽⁵⁾

Here is our main example.

DEFINITION 4.4. – The seed \mathbf{s}_{Γ} assigned to a bipartite graph Γ on a genus g surface S is

$$\mathbf{s}_{\Gamma} := (\Lambda_{\Gamma}, (*, *)_{\widehat{\Gamma}}, \{\gamma_F\}).$$

LEMMA 4.5. – The spider move $\Gamma \longrightarrow \Gamma'$ centered at a face F leads to a mutation of seeds $\mathbf{s}_{\Gamma} \longrightarrow \mathbf{s}_{\Gamma'}$ in the direction of the vector γ_F .

⁽⁵⁾ We simplify the discussion by considering only the "simply-laced" case, with the "multipliers" $d_i = 1$.

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Proof. – The only non-zero values $(\gamma_F, \gamma_G)_{\widehat{\Gamma}}$ are

$$(32) \qquad (\gamma_F, \gamma_{F_1})_{\widehat{\Gamma}} = 1, \quad (\gamma_F, \gamma_{F_2})_{\widehat{\Gamma}} = -1, \quad (\gamma_F, \gamma_{F_3})_{\widehat{\Gamma}} = 1, \quad (\gamma_F, \gamma_{F_4})_{\widehat{\Gamma}} = -1.$$

Thus formulae (30) from Lemma 4.1 are just equivalent to the mutation formulae (31). \Box

Therefore the geometric objects—the conjugated surfaces and the spider moves—are encoded, respectively, by the corresponding seeds and their mutations.

4.1.3. Quantum cluster transformations [10]. – A lattice Λ with a skew-symmetric \mathbb{Z} -valued bilinear form (*, *) gives rise to a quantum torus *-algebra \mathbf{T}_{Λ} . The algebra \mathbf{T}_{Λ} has a basis $\{X_v\}$ over the ring $\mathbb{Z}[q, q^{-1}]$ parametrized by the vectors v of the lattice Λ . The multiplication is given by

$$q^{-(v_1,v_2)}X_{v_1}X_{v_2} = X_{v_1+v_2}.$$

There is an involutive antiautomorphism

$$*: \mathbf{T}_{\Lambda} \longrightarrow \mathbf{T}_{\Lambda}, \qquad *(X_v) = X_v, \ *(q) = q^{-1}.$$

Let us choose an order of the basis $\{v_i\}$ of Λ . Then

(33)
$$X_{v} = q^{-\sum_{i < j} a_{i}a_{j}(v_{i}, v_{j})} \prod_{i=1}^{n} X_{i}^{a_{i}}, \qquad v = \sum_{i=1}^{n} a_{i}v_{i}$$

Consider the following formal power series, called the *q*-exponential:

(34)
$$\Psi_q(x) := \prod_{a=1}^{\infty} (1+q^{2a-1}x)^{-1} = \frac{1}{(1+qx)(1+q^3x)(1+q^5x)\cdots}$$

It is characterized up to a constant by the difference relation

(35)
$$\Psi_q(q^2x) = (1+qx)\Psi_q(x).$$

Denote by \mathbb{T}_{Λ} the non-commutative fraction field of the algebra \mathbf{T}_{Λ} . The quantum mutation map $\mu_{e_k}^q$ in the direction of a vector e_k is an automorphism of the skew field \mathbb{T}_{Λ} given by the conjugation by $\Psi_q(X_{e_k})$:

(36)
$$\mu_k^q := \operatorname{Ad}_{\Psi_q(X_{e_k})} : \mathbb{T}_{\Lambda} \longrightarrow \mathbb{T}_{\Lambda}.$$

Although $\Psi_q(X_{e_k})$ is not a rational function, this is a rational map.

4.1.4. Cluster Poisson varieties [10]. – Cluster Poisson varieties, also known as cluster χ -varieties [10], are geometric objects which are in duality to cluster algebras of Fomin-Zelevinsky [12].

We assign to a seed s a complex algebraic torus $\mathscr{X}_{\Lambda} := \operatorname{Hom}(\Lambda, \mathbb{C}^*)$, called the *seed* torus. A vector $v \in \Lambda$ gives rise to a function X_v on the torus obtained by evaluation at v. A mutation in the direction of a vector e_k gives rise to a birational isomorphism $\mu_{e_k} : \mathscr{X}_{\Lambda} \longrightarrow \mathscr{X}_{\Lambda}$, obtained by specializing q = 1 in (36). It acts on the function X_v by

(37)
$$\mu_{e_k}^*: X_v \longmapsto X_v (1 + X_{e_k})^{-(e_i, e_k)}$$

The Poisson bracket is the quasiclassical limit of the commutator:

$$\{X_{v_1}, X_{v_2}\} := \lim_{q \to 1} [X_{v_1}, X_{v_2}]/2(q-1) = (v_1, v_2)X_{v_1}X_{v_2}.$$

Thus (37) is a Poisson map. An isomorphism of seeds leads to a Poisson isomorphism of the seed tori. Compositions of seed mutations and seed isomorphisms are *seed cluster transformations*. So a seed cluster transformation gives rise to a Poisson birational isomorphism of the seed tori. A seed cluster transformation $\mathbf{s} \to \mathbf{s}$ acting trivially on the functions X_v is a *trivial seed cluster transformation*. Consider all seeds obtained from a given seed \mathbf{s} by a sequence of mutations. We assign to these seeds their seed torus, and glue pairs of tori related by mutations into a space $\widetilde{\mathcal{X}}$ by using birational isomorphisms (37). Trivial seed cluster transformations, we get a cluster transformation $\widetilde{\mathcal{X}}$. Taking the quotient of $\widetilde{\mathcal{X}}$ by these automorphisms, we get a cluster Poisson variety \mathcal{X} .⁽⁶⁾

Non-trivial cluster seed transformations $s \to s$ lead to automorphisms of the \mathcal{X} , which form the *cluster modular group*. We will see such examples in Section 6.

A cluster Poisson variety is nothing else but a collection of seed tori \mathcal{X}_{Λ} glued via the cluster transformations. The algebra of regular functions $\mathcal{O}(\mathcal{X}_{\Lambda})$ on a cluster torus is an algebra of Laurent polynomials. So a cluster Poisson variety is described by a collection of algebras of Laurent polynomials and birational automorphisms (37) providing the gluing transformations. The algebra $\mathcal{O}(\mathcal{X})$ of regular functions on a cluster Poisson variety \mathcal{X} can be identified with the subalgebra of the algebra $\mathcal{O}(\mathcal{X}_{\Lambda})$ consisting of the elements which remains Laurent polynomials after any cluster transformation.

This suggests that one should think about the quantum torus algebra \mathbf{T}_{Λ} as of the algebra of regular functions on a non-commutative quantum torus, and that these algebras together with the mutation maps (36) should be thought of as a quantum cluster variety. We define the algebra $\mathcal{O}_q(\mathcal{X})$ of regular functions on a quantum cluster variety as the subalgebra of the quantum torus algebra \mathbf{T}_{Λ} consisting of all elements which remain Laurent polynomials after any quantum cluster transformation.

4.1.5. Gluing the moduli spaces \mathcal{L}_{Γ} according to a spider move. – Instead of using the set of all seeds related to an initial seed s by seed cluster transformations, we can pick any subset of this set, and define a Poisson space by gluing the corresponding cluster tori. The cluster Poisson spaces which we need in our paper are defined this way: we use only finitely many seeds corresponding to minimal bipartite graphs associated with a given Newton polygon.

4.1.6. Traditional cluster Poisson variety related to the dimer model. – Traditional cluster Poisson varieties are the ones defined by using seeds where the vectors $\{e_i\}$ form a basis of the lattice. Let

$$\mathbf{T}_S := H_1(S, \mathbb{C}^*) \cong (\mathbb{C}^*)^{2g}.$$

It is the group of line bundles with flat connections on S. The embedding $\Gamma \hookrightarrow S$ provides a free Poisson action of the group T_S on the moduli space \mathcal{L}_{Γ} .

The monodromy of a line bundle on Γ around a face F is a function W_F on \mathcal{L}_{Γ} . The product of all W_F 's is 1. Define

$$\mathscr{X}'_{\Gamma} = (\mathbb{C}^*)^{\{\text{faces of } \Gamma\}}.$$

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⁽⁶⁾ It could be a non-separated space rather than a variety.

Let $\mathbb{W} : \mathscr{X}'_{\Gamma} \to \mathbb{C}^*$ be the product of all coordinates. Assigning to a line bundle on Γ its monodromies around the faces we get a canonical isomorphism

$$(\mathscr{L}_{\Gamma}/\mathrm{T}_{S}) \xrightarrow{\sim} \mathrm{Ker}\Big(\mathscr{X}'_{\Gamma} \xrightarrow{\mathbb{W}} \mathbb{C}^{*}\Big).$$

The birational Poisson transformations (7) are T_S -equivariant. So to describe them on the quotient is just the same as to describe their action on the face weights.

LEMMA 4.6. – The algebraic tori $\{\chi'_{\Gamma}\}$ parametrized by equivalent minimal bipartite graphs Γ on S are glued by cluster Poisson transformations (7) into a cluster Poisson variety χ'_N . The maps (7) preserve the function \mathbb{W} . So there is a hypersurface $\chi^0_N \subset \chi'_N$ given by the equation $\mathbb{W} = 1$. The group T_S acts freely on χ_N . There is a Poisson isomorphism

$$(38) \qquad \qquad \qquad \chi_N/T_S \xrightarrow{\sim} \chi_N^0.$$

Proof. – We just need to show that the product of the face weights is preserved by the spider move cluster transformations. This is clear from formulas (39) below.

4.2. Spider moves and partition functions

We have seen that elementary transformations $\Gamma \to \Gamma'$ give rise to rational maps between the moduli spaces $\mathcal{L}_{\Gamma} \to \mathcal{L}_{\Gamma'}$. In this section we show that they do not change the partition functions for the dimer models related to the graphs Γ and Γ' . Moreover, we show that the rational maps are characterized by the condition that they preserve the partition functions.

THEOREM 4.7. – Given a spider move, there is a unique rational transformation of the face weights preserving the modified partition function \mathcal{P}_{α} . This transformation is a cluster Poisson transformation, see Figure 21:

(39)

$$W' = W^{-1},$$

 $W'_i = W_i(1+W), \quad i = 1, 3,$
 $W'_j = W_j(1+W^{-1})^{-1}, \quad j = 2, 4.$

It preserves the product of the face weights.



FIGURE 21. A spider move and a mutation of the face weights.

Proof. – Let us show first that formula (39) is a cluster Poisson transformation. Precisely:

LEMMA 4.8. – Formula (39) describes the cluster Poisson mutation centered at γ_F , where F is the center of the spider move.

Proof. – Let us compare formula (39) with the formula for the cluster transformation at γ_F . For this purpose, let us write the action of the mutation at the vector e_k on the functions $X_{e'_i}$ in terms of the original functions X_{e_i} :

(40)
$$\mu_{e_k}^* : X_{e'_i} \longmapsto \begin{cases} X_k^{-1} & \text{if } i = k, \\ X_i (1 + X_k^{-\operatorname{sgn}(e_i, e_k)})^{-(e_i, e_k)} & \text{if } i \neq k. \end{cases}$$

Evidently, thanks to (32), formula (39) is a specialization of the general formula (40). \Box

Proof of Theorem 4.7. – We use the edge weights, where the notation are as on Figure 22. The equality of the modified partition functions reads as follows:

(41)
$$\frac{P_{\Gamma}}{M_{\alpha}} = \frac{P_{\Gamma'}}{M'_{\alpha}}$$

where P_{Γ} is the partition function of the dimer model on the bipartite graph Γ defined using the edge weights, and

$$M_{\alpha} := \prod_{\text{edges E}} \operatorname{weight}(E)^{\varphi(E)}$$

Here $\varphi(E) = \alpha_r - \alpha_l$ is determined by the function α , see (19), (20), and Figure 15. Observe that the maps α for the graphs Γ and Γ' are the same maps.

The face weights are calculated via the edge weights as follows, where W_i^* are factors common for both graphs Γ and Γ' , and the edge weights are as on Figure 22:

$$W = \frac{dc}{be}, \quad W_1 = \frac{b}{a}W_1^*, \quad W_2 = \frac{a}{c}W_2^* \quad W_3 = \frac{e}{f}W_3^*, \quad W_4 = \frac{f}{d}W_4^*.$$
$$W' = \frac{AC}{BD}, \quad W_1' = \frac{F}{A}W_1^*, \quad W_2' = \frac{B}{E}W_2^* \quad W_3' = \frac{E}{C}W_3^*, \quad W_4' = \frac{D}{F}W_4^*.$$



FIGURE 22. A spider move and a mutation of the edge weights.

Let us number the external vertices on the graphs shown on Figure 22 by 1, 2, 3, 4. We present the graphs as unions of the *inside* and *outside graphs*, where the inside graphs are the ones shown on Fig. 22. Given a pair of vertices $i, j \in \{1, 2, 3, 4\}$, consider all perfect matchings where the vertices i and j are matched to the outside vertices. Their contribution

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to the partition function is the product of the total weight of the perfect matchings for the outside graph by the weight p_{ij} of the perfect matchings for the inside graph. Similarly p'_{ij} for Γ' . One should have

$$(42) p_{ij} = Cp'_{ij}$$

i.e., the points in \mathbb{CP}^5 with the coordinates $(p_{12} : p_{13} : \cdots : p_{34})$ and $(p'_{12} : p'_{13} : \cdots : p'_{34})$ coincide. One has

(43)
$$p_{12} = bf, \ p_{13} = be + dc, \ p_{14} = cf, \ p_{23} = ad, \ p_{24} = af, \ p_{34} = ae.$$

(44)
$$p'_{12} = CF, \ p'_{13} = EF, \ p'_{14} = DE, \ p'_{23} = BF, \ p'_{24} = AC + BD, \ p'_{34} = AE.$$

For example, there are exactly two matchings of the inside graph which do not use the vertices 1, 3, and their total weight is $p_{13} = be + dc$.

Then for every pair (ij) and (kl) there is a condition

$$\frac{p_{ij}}{p_{kl}} = \frac{p'_{ij}}{p'_{kl}}.$$

Let us investigate its consequences. We deduce that $W' = W^{-1}$ by looking at

$$\frac{p_{13}p_{24}}{p_{12}p_{34}} = \frac{(be+dc)af}{(bf)(ae)} = 1 + \frac{dc}{be} = 1 + W;$$

$$\frac{p'_{13}p'_{24}}{p'_{12}p'_{34}} = \frac{(EF)(AC + BD)}{(CF)(AE)} = 1 + (W')^{-1}.$$

The condition $\frac{p_{12}}{p_{24}} = \frac{p'_{12}}{p'_{24}}$ leads to the following:

$$\frac{p_{12}}{p_{24}} = \frac{b}{a}, \quad \frac{p'_{12}}{p'_{24}} = \frac{F}{A} \frac{AC}{AC + BD} \quad \Rightarrow \quad W'_1 = W_1(1+W).$$

The rest of the relations (39), see Figure 21, are obtained by looking at $\frac{p_{23}}{p_{24}}$, $\frac{p_{34}}{p_{24}}$, and $\frac{p_{14}}{p_{24}}$. Conversely, transformation formulas (39) imply that the vectors (p_{ij}) and (p'_{ij}) in \mathbb{CP}^5 coincide.

Furthermore, we claim that (42) implies (41). The subtlety is that the modified partition function involves the function α . Let us set, see the right picture on Figure 18,

$$q_1 = p_3 - p_1, q_2 = p_2 - p_3, q_3 = p_4 - p_2, q_4 = p_1 - p_4.$$

Then the denominators in (41) for the inner graphs are

$$\begin{split} M^{\rm in}_{\alpha} &= a^{p_1 - p_2} b^{p_2 - p_3} c^{p_3 - p_1} d^{p_4 - p_2} e^{p_1 - p_4} f^{p_2 - p_1} = (cf)^{q_1} (bf)^{q_2} (ad)^{q_3} (ae)^{q_4}, \\ M'^{\rm in}_{\alpha} &= A^{p_1 - p_4} B^{p_4 - p_2} C^{p_2 - p_3} D^{p_3 - p_1} E^{p_3 - p_4} F^{p_4 - p_3} = (DE)^{q_1} (CF)^{q_2} (BF)^{q_3} (AE)^{q_4}. \end{split}$$

Therefore, using (42), $M_{\alpha}^{\text{in}} = C^{q_1+q_2+q_3+q_4} M'_{\alpha}^{\text{in}} = CM'_{\alpha}^{\text{in}}$ since $q_1 + q_2 + q_3 + q_4 = 1$. So, using (42) again, we get (41).

There is another transformation, see Figure 23, which obviously does not change the face weights and the Poisson structure. Its inverse involves splitting of a high valency vertices by adding valency two vertices.



FIGURE 23. Shrinking a 2-valent vertex.

4.3. Quantum integrable system

Recall the quantum torus algebra \mathbf{T}_{Λ} assigned to a lattice Λ with a skew-symmetric integral form (*, *), see Section 4.1.3. Each vector $v \in \Lambda$ gives rise to an element $X_v \in \mathbf{T}_{\Lambda}$.

Each Hamiltonian $H_{\alpha,a}$ is a sum of different monomials with coefficients +1. So it can be upgraded uniquely to an element of the quantum torus algebra \mathbf{T}_{Λ} assigned to a minimal bipartite surface graph Γ :

(45)
$$\mathbb{H}_{\alpha;a} := \sum_{v} X_{v} \in \mathbf{T}_{\Lambda}$$

where the sum is over the vectors v parametrizing the monomials in the classical Hamiltonian $H_{\alpha,a}$. The element (45) is the quantum Hamiltonian. Similarly one defines quantum Casimirs corresponding to the classical Casimir monomials.

PROPOSITION 4.9. – Let $\Gamma \rightarrow \Gamma'$ be a spider move. Then the corresponding quantum cluster transformation preserves the quantum Hamiltonians and Casimirs.

Proof. – The Casimirs lie in the center and thus commute with $\Psi_q(X_v)$.

For the quantum Hamiltonians we use a version of the strategy employed at Section 4.2. First, let us do a calculation at q = 1. Let us denote by $q_{ij}p_{ij}$ (respectively $q'_{ij}p'_{ij}$) the part of the modified partition function involving the dimer covers which connect the vertices *i* and *j* to the outside vertices. Here p_{ij} (respectively p'_{ij}) is the factor calculated by using the matchings involving only the six edges a, b, c, d, e, f (respectively, A, B, C, D, E, F) on Figure 22.

We write $A \sim B$ when A/B is independent of

(46)
$$W, W_1, W_2, W_3, W_4$$
, and $W', W'_1, W'_2, W'_3, W'_4$

Since the product of all face weights is equal to one, we have

$$WW_1W_2W_3W_4 \sim 1, \quad W'W_1'W_2'W_3'W_4' \sim 1.$$

Below we work modulo these relations. The 1-cycle assigned to any non trivial Laurent polynomial in W, W_1, W_2, W_3, W_4 has a non-trivial contribution of the edges a, b, c, d, e, f.

The q_{ij} are Laurent polynomials in the face weights for Γ , well defined modulo a common Casimir used to correct the partition function. Therefore they do not depend on the left face weights in (46). So we can calculate the contribution of the W's from (46) to the ratios of p's by looking at (43). For example, we get

$$\frac{p_{13}}{p_{12}} \sim \frac{be+dc}{bf} = \frac{e}{f} + \frac{dc}{bf} \sim W_3 + WW_3.$$

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Indeed, the contribution of a, b, c, d, e, f on Γ to the 1-cycle assigned to W_3 is [e] - [f], and the contribution to WW_3 is [d] + [c] - [b] - [f]. These Laurent polynomials in W are uniquely defined modulo $WW_1W_2W_3W_4 \sim 1$.

The same argumentation in general delivers the following result:

$$\frac{p_{13}}{p_{12}} \sim W_3 + WW_3, \quad \frac{p_{14}}{p_{12}} \sim WW_3W_4, \quad \frac{p_{23}}{p_{12}} \sim WW_2W_3,$$
$$\frac{p_{24}}{p_{12}} \sim W_1^{-1}, \quad \frac{p_{34}}{p_{12}} \sim W_1^{-1}W_3.$$

Similarly, we get

$$\frac{p'_{13}}{p'_{12}} \sim W'_3, \quad \frac{p_{14}}{p_{12}} \sim W'_3 W'_4, \quad \frac{p'_{23}}{p'_{12}} \sim W'_2 W'_3,$$
$$\frac{p'_{24}}{p'_{12}} \sim (W'_1)^{-1} + W(W'_1)^{-1}, \quad \frac{p'_{34}}{p'_{12}} \sim (W'_1)^{-1} W'_3$$

Now it is straightforward to check that the mutation at W formula amounts to mapping the five Laurent polynomials in W's to the similar Laurent polynomials in W's. Moreover, the same is true for the quantum mutation maps, assuming that the Laurent polynomials above are written with the correcting *q*-factors provided by the formula (33):

$$W'_3 \longmapsto W_3(1+qW). \quad q^{-1}W'_3W'_4 \longmapsto W_3WW_4, \quad \dots$$

It remains to notice that $WW_1W_2W_3W_4 \mapsto W'W_1'W_2'W_3'W_4'$.

THEOREM 4.10. – Let Γ be a minimal bipartite graph on a torus \mathbb{T} . Then the quantum Hamiltonians (45) commute.

The quantum Casimirs generate the center. The quantum Hamiltonians $\mathbb{H}_{\alpha;a}$ together with the quantum Casimirs provide a quantum cluster integrable system in $\mathcal{O}_q(\mathcal{X}_N)$.

Proof. - One has

$$[X_v, X_w] = (q^{(v,w)} - q^{(w,v)})X_{v+w}.$$

Using the notation of Lemma 3.8, we have

$$[X_{\mu_1}, X_{\mu_2}] + [X_{\tilde{\mu}_1}, X_{\tilde{\mu}_2}] = (q^{(\mu_1, \mu_2)} - q^{(\mu_2, \mu_1)}) X_{\mu_1 + \mu_2} + (q^{(\tilde{\mu}_1, \tilde{\mu}_2)} - q^{(\tilde{\mu}_2, \tilde{\mu}_1)}) X_{\tilde{\mu}_1 + \tilde{\mu}_2}.$$

By construction we have $\mu_1 + \mu_2 = \tilde{\mu}_1 + \tilde{\mu}_2$. So the commutator is zero by Lemma 3.8. Therefore the quantum Hamiltonians commute. The claim about Casimirs is obvious since they are monomials. The last claim follows Proposition 4.9 and Theorem 3.7ii).

5. Resistor network model and its cluster nature

5.1. Resistor network model

Let G be a (not necessarily bipartite) surface graph on a torus \mathbb{T} . Let c be a function on the edges of G with values in \mathbb{C}^* , called the *conductance function*, considered up to a multiplication by a non-zero scalar.⁽⁷⁾ A graph with a conductance function on its edges is called a *resistor network*.

⁽⁷⁾ Usually in applications the conductance function is a positive real-valued function.

5.1.1. Laplacians. – A line bundle with connection V on G gives rise to a vector space

$$\mathbb{V} = \bigoplus_{v} V_{v},$$

given by the sum of the fibers V_v of the line bundle over the vertices v of G, and a Laplace operator $\Delta : \mathbb{V} \to \mathbb{V}$ defined by

$$\Delta(f)(v) := \sum_{v' \sim v} c(v,v')(f(v) - i_{v'v}f(v'))$$

where the sum is over neighbors v' of v, and $i_{v'v}f(v')$ is the parallel transport of the vector f(v') to the fiber over v.

Suppose now that the bundle with connection V on G is flat, that is, the monodromies around the faces of G are trivial. The connection still has non-trivial monodromies z_1, z_2 around generators of $H_1(\mathbb{T}, \mathbb{Z})$. The determinant of Δ is a Laurent polynomial det $\Delta = P(z_1, z_2)$. It is symmetric, since Δ is Hermitian when $|z_1| = |z_2| = 1$ and c is a positive real function:

(47)
$$P(z_1, z_2) = P(z_1^{-1}, z_2^{-1}).$$

The Laplacian determinant is a weighted sum of combinatorial objects called *cycle-rooted* spanning forests (CRSFs), see [25]: these are maximal subsets of edges of G in which each connected component contains a unique cycle, and this cycle has nontrivial homology on the torus. The weight of a CRSF is the product over its edges of the conductances, times the product over its cycles of 2 - w - 1/w where w is the monodromy of the flat connection on that cycle.

Тнеокем 5.1 ([25]). – We have

$$\det \Delta = \sum_{\mathit{CRSFs} \ C} \prod_{e \in C} c(e) \prod_{\mathit{cycles} \ \gamma} 2 - w(\gamma) - 1/w(\gamma).$$

Two torus graphs G_1, G_2 with conductances c_1, c_2 are said to be *electrically equivalent* if their associated Laplacian determinants $P_1(z_1, z_2)$ and $P_2(z_1, z_2)$ are proportional (that is, their ratio is a monomial in z_1, z_2). A weaker notion is topological equivalence: torus graphs G_1, G_2 are *topologically equivalent* if for (any choice of) positive conductances, the Newton polygons of $P_1(z_1, z_2)$ and $P_2(z_1, z_2)$ are the same.

5.1.2. Dual graph. – Given a resistor network on a surface, the dual graph G' is also a resistor network, where we assign conductance 1/c to an edge dual to an edge of conductance c. The Laplacian determinants on G and G' are related:

LEMMA 5.2. – For a graph G with dual G' having the same flat line bundle, we have

(48)
$$\left(\prod_{edges} c(e)\right) \det \Delta_{G'} = \det \Delta_G.$$

In particular a resistor network on a torus is electrically equivalent to its dual network.

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Proof. – Use Theorem 5.1 and note that, given a CRSF C on G, there is a dual CRSF C' on G' consisting of the set of edges of G' which are not crossed by an edge of C. It has the same homology class as C, and thus the same weight $\prod_{\text{cycles}} 2-w-1/w$, and the contribution from the edge weights is $\prod_{e \in E} c(e)^{-1}$ times the product of the edge weights of C. \Box

5.1.3. Zig-zag paths for a graph G on a torus. – A zig-zag path on a surface graph G is a path which turns maximally left or right at each vertex, and the left/right turns alternate. A zig-zag path on G is unoriented. The collection $\{\alpha\}$ of zig-zag paths assigned to a graph G on a torus has the following property:

LEMMA 5.3. – Each zig-zag path intersects an even number of zig-zag paths (counted with multiplicity).

Proof. – Each vertex of a zig-zag path is either on the left or right of the corresponding path in the medial graph, so a zig-zag path has an even number of steps. At each step it crosses a single other zig-zag path. \Box

Conversely, any collection of smooth unoriented loops $\{\alpha\}$ on a torus, in general position, satisfying Lemma 5.3 and considered up to isotopy, arises as the set of medial strands of a graph on the torus. Namely, one can color the complementary domains black and white so that no domains of the same color share an edge. We declare the black domains to be the vertices of G, and connect two vertices of G by an edge if the corresponding domains are separated by an intersection point of two zig-zag paths. The white domains are the faces of G.

5.1.4. Elementary transformations. – Elementary transformations are local rearrangements of a resistor network which preserve electrical equivalence. There are four types: $Y - \Delta$ transformations, parallel and series reductions, and removal of dead branches. The $Y - \Delta$ transformations appeared first in 1899 in the work of Kennelly [23].

Recall that a $(Y - \Delta)$ -transformation of a resistor network is given by replacing a triangle Δ with conductances α , β , γ by the graph Y with conductances a, b, c, see Figure 24, related



FIGURE 24. An example of a $(Y - \Delta)$ -transformation.

as follows:

(49)
$$\alpha = \frac{bc}{a+b+c}, \quad \beta = \frac{ac}{a+b+c}, \quad \gamma = \frac{ab}{a+b+c},$$

(50)
$$a = \frac{\alpha\beta + \beta\gamma + \gamma\alpha}{\alpha}, \quad b = \frac{\alpha\beta + \beta\gamma + \gamma\alpha}{\beta}, \quad c = \frac{\alpha\beta + \beta\gamma + \gamma\alpha}{\gamma}.$$

The graph transformation induced by moving a zig-zag strand across a crossing of two other zig-zag strands is a $Y - \Delta$ move.

Two more elementary transformations of graphs with conductances, called *parallel and* series reductions, are shown in Figure 25.



FIGURE 25. Parallel and series reductions.

A last elementary transformation is *removing a dead branch*, which consist of contracting to a vertex any subgraph which is attached to the rest of the graph by a single vertex.

A torus graph is said to be *minimal* if the lifts of any zig-zag path to the plane (the universal cover of the torus) does not intersect itself, and the lift of two zig-zag paths to the plane intersect at most once.

THEOREM 5.4. – Every torus graph G with conductances c can be reduced to a minimal torus graph by a sequence of elementary transformations.

Two minimal torus graphs G_1, G_2 are topologically equivalent if and only if G_2 is related to G_1 or to its dual graph G'_1 by $(Y - \Delta)$ -moves.

We prove this at the end of Section 5.2.4. The corresponding statement for electrical equivalence is false: there are minimal graphs which are electrically equivalent but not related by $Y - \Delta$ moves. In fact the electrical equivalence class is a subvariety of the Hamiltonian dynamical system; see below.

5.2. The associated dimer model on a torus

5.2.1. The bipartite graph assigned to a graph on a torus. – Drawing the graph G and its dual graph G' simultaneously one can make a bipartite graph Γ_G on the torus whose white vertices are the edges of G, black vertices are the vertices and the faces of G, with an edge for each adjacency, see Figure 2. The graph Γ_G has the same number of white and black vertices since Euler's formula on a torus reads E = V + F. One can show [27] that the graph Γ_G admits dimer covers: in fact these are in bijection with CRSFs in which both the cycles and dual cycles (the dual of a CRSF is also a CRSF) have a chosen orientation.

5.2.2. The resistor network subvariety. – Let c be a conductance function on the edges of G, considered up to a non-zero scalar. It gives rise to a line bundle with connection V(c) on Γ_G , defined as follows. The fibers of V(c) at the vertices of Γ_G are identified with \mathbb{C} . So the connection is defined via the edge weights assigned to the oriented edges of Γ_G . The weight of an edge incident to a vertex corresponding to a face of G is 1. The weight of an edge going from a vertex of G to a midpoint of an edge E of G is the conductance c_E assigned to that edge.

The monodromies around a pair of generators of $H_1(\mathbb{T},\mathbb{Z})$ provide an isomorphism of the moduli space of line bundles with flat connections on Γ_G with $(\mathbb{C}^*)^2$. Taking the tensor product of V(c) with a line bundle with a flat connection on Γ_G we get a line bundle with connection on Γ_G . We denote by \mathcal{R}_G the moduli space of line bundles with connections on the graph Γ_G constructed in this way, and call it *the resistor network subvariety*. It is a closed subvariety

$$\mathcal{R}_G \subset \mathcal{L}_{\Gamma_G}, \qquad \dim \mathcal{R}_G = E_G + 1$$

where E_G is the number of edges of G (note that multiplying all conductances on G by a constant gives a gauge equivalent connection on Γ_G).

5.2.3. Determinant of the Laplacian and the dimer model partition function. – Using the conductances on G to define the connection on Γ_G , we have the following relation between the dimer partition function and det Δ .

LEMMA 5.5. – The partition function for the dimer model on Γ_G is equal to det Δ_G (up to a monomial factor in z_1, z_2).

Proof. – Let G' be the dual graph to G with conductance 1/c on an edge dual to an edge of conductance c. Recall Lemma 48 relating the Laplacian determinants on G and G'.

These two operators Δ_G , $\Delta_{G'}$ acting on the black vertices of Γ_G are related to the Kasteleyn matrix K as follows:

(51)
$$\begin{pmatrix} \Delta_G & 0\\ 0 & \Delta_{G'} \end{pmatrix} = -K_2^* K_1,$$

where K_1, K_2 are two copies of the black-to-white Kasteleyn matrix with appropriate gauge, defined as follows.

Embed G in a Euclidean torus with straight edges; this allows us to associate to each directed edge b_1b_2 a unit-modulus complex number $\zeta(b_1, b_2)$ representing its direction. Letting w be the vertex of Γ_G in the center of this edge we then define $K_1(b_1, w) = c(b_1, b_2)\zeta(b_1, b_2)$ where c is the conductance of edge b_1b_2 . If b_3 is a black vertex of G' in a face of G adjacent to edge b_1b_2 then $K_1(b_3, w)$ is 1 times the unit modulus complex number in the direction from b_3 to w and perpendicular to $\zeta(b_1, b_2)$. One can now check that the monodromy around a face of Γ_G is negative real (for positive conductances) and thus K_1 is a Kasteleyn matrix for Γ_G . One defines K_2 similarly but for the dual graph G'. Now (51) follows by inspection of the various cases: $-K_2^*K_1(b, b)$ is the sum of the conductances of edges emanating from b; $-K_2^*K_1(b, b') = 0$ if $b \in G$ and $b' \in G'$ or vice versa; $-K_2^*K_1(b_1, b_2) = -c$ if b_1, b_2 are adjacent vertices of G and the edge connecting them has conductance c; similarly for vertices adjacent in G'.

Finally, det K_2 , det K_1 are both the dimer partition function (up to constants which depend on our choice of gauge). Thus from (48) and (51) we have det $\Delta = \det K_1$ up to multiplicative factor which is a monomial in z_1, z_2 .

It follows from (47) that the Newton polygon of the dimer model on Γ_G is centrally symmetric with respect to the origin.

5.2.4. Zig-zag paths and the Newton polygon. – Zig-zag paths are defined for both a graph G on a torus and the associated bipartite graph Γ_G ; zig-zag paths on G are unoriented. Zig-zag paths for Γ_G are oriented. A zig-zag path α on G corresponds to a pair of zig-zag paths on Γ_G , isotopic to α and equipped with the opposite orientations. In this way we get all zig-zag paths on Γ_G .

The geometric Newton polygon N(G) is described as follows. Each zig-zag path α on G gives rise to a pair of homology classes $\pm[\alpha] \in H_1(\mathbb{T}, \mathbb{Z})$, where $[\alpha]$ is the homology class of the path α equipped with an orientation. There is a unique, centrally symmetric with respect to the origin, convex integral polygon

$$N(G) \in H_1(\mathbb{T},\mathbb{Z})$$

with the sides given by the vectors $\pm[\alpha]$ for all zig-zag paths α on G. Indeed, there is evidently a unique up to a translation convex integral polygon in $H_1(\mathbb{T},\mathbb{Z})$ with these sides, which is centrally symmetric. Thanks to Lemma 5.3, it can be centered at the origin.

Clearly the polygon N(G) coincides with the geometric Newton polygon $N(\Gamma_G)$ assigned in a similar way, using the homology classes of zig-zag paths, to the bipartite graph Γ_G . Thus Lemma 5.5 implies

LEMMA 5.6. – Let G be a minimal graph on a torus. Then the geometric Newton polygon N(G) coincides with the Newton polygon of det Δ_G .

Proof of Theorem 5.4. – By Lemma 5.6, two equivalent minimal graphs G and G' have the same geometric Newton polygons, whose boundary sides determine the homology classes of the zig-zag strands. Thus the collections of their zig-zag strands are isotopic. The isotopy is realized by moving zig-zag strands through zig-zag strand crossings, and thus the corresponding graphs are related by a sequence of $Y - \Delta$ moves.

To reduce a graph G to a minimal graph, consider the zig-zag strands for G, and isotope each to a straight geodesic through a generic isotopy. Each type of singularity which resolves corresponds to an elementary transformation: if it is a parallel, series, or dead branch move, it may change the topology of the set of strands, but also strictly reduces the number of crossings of strands. Eventually one arrives at a graph with a minimal number of strand crossings and the remaining moves are $Y - \Delta$ moves.

5.2.5. Equations defining the resistor network subvariety. – Denote by V_G , E_G , F_G the number of vertices, edges and faces of the graph G, and similarly V_{Γ} , E_{Γ} , F_{Γ} those for Γ_G . Then $F_{\Gamma} = 2E_G$. Indeed, every edge E of G is incident to four faces of Γ_G , and each face of Γ_G is counted twice. So one has

$$\dim \mathcal{L}_{\Gamma} = F_{\Gamma} + 1 = 2E_G + 1.$$

So the codimension of the resistor network subvariety \mathcal{R}_G is E_G . On the other hand, a line bundle with connection on Γ_G which belongs to the subvariety \mathcal{R}_G satisfies the following conditions:

- 1. The monodromies around the faces of the graph G and the graph G' are equal to 1.
- Given a loop α on the graph G and a loop α' on the graph G' whose homology classes in H₁(T, Z) coincide, the monodromies around these loops also coincide.

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Remarks. – The first condition tells that for each black vertex b on Γ_G , the product of the face weights for the faces adjacent to b is equal to 1.

Secondly, the second condition implies the first: to see this, alter a loop α by adding to it a loop going around a face of the graph G, and similarly for G'.

Finally, given the first condition, the second condition imposes only two more equations on the connection: one for each generator of $H_1(\mathbb{T},\mathbb{Z})$, since the first condition already implies that the monodromies around homologous paths, both in G or both in G', are equal.

Since the product of the monodromies over all faces of G, as well as over all faces of G', is 1, we get E_G equations for the subvariety $\mathcal{R}_G \subset \mathcal{L}_{\Gamma_G}$:

$$(V_G + F_G - 2) + 2 = E_G.$$

These conditions characterize the subvariety \mathscr{R}_G in \mathscr{L}_{Γ} :

LEMMA 5.7. – A line bundle with connection on Γ_G arises from a resistor network on G if and only if it satisfies the conditions 1 and 2 above.

Proof. – We have seen already that the line bundle with connection on Γ_G arising from a resistor network satisfies the conditions 1 and 2.

Let us prove the converse. Notice that the condition 1 says that we have a flat line bundle on the torus \mathbb{T} assigned to the graph G, and another flat line bundle on the torus assigned to the graph G'. The condition 2 then says that these two flat line bundles are isomorphic. So, untwisting by a flat line bundle on the torus, we can assume that our line bundle has trivial monodromy around any loop on G and around any loop on G'.

Let us trivialize the line bundle on Γ_G on the dual graph G'. Take an edge E_0 of G and assign it conductance 1. Recall that the *medial graph* of G is the graph with a vertex for every edge of G and an edge whenever two edges of G share a vertex of G. The parallel transports on Γ_G determine a curl-free flow on the medial graph of G; the value of the conductance of an edge E is then the integral of this flow along a path in the medial graph from E_0 to E. So we have reconstructed conductances up to a non-zero common factor.

5.2.6. *The resistor network subvariety is Lagrangian.* – An irreducible subvariety of a Poisson variety is *Lagrangian* if the generic part of its intersection with the generic symplectic leaves are Lagrangian subvarieties of the symplectic leaves.

THEOREM 5.8. – \mathcal{R}_G is a Lagrangian subvariety of the Poisson variety \mathcal{L}_{Γ_G} .

Proof. – The following crucial lemma implies that the intersection of \mathcal{R}_G with a generic symplectic leaf is coisotropic (that is, the symplectic form is zero on this intersection).

LEMMA 5.9. – The Poisson brackets between the defining Equations 1-2 of the resistor network subvariety \mathcal{R}_G are equal to zero.

Proof. – Let us show first that the monodromies around the black vertices of the graph Γ_G Poisson commute. Let b_1, b_2 be two black vertices of Γ_G corresponding to the faces F_1, F_2 of G. Let W_{b_1}, W_{b_2} be the corresponding monodromies. If the faces F_1, F_2 are not adjacent, the Poisson bracket is obviously zero. If they are adjacent, they share an edge E, which has, by construction, two black vertices at the ends and one white vertex at the middle, see Figure 2. Thus $\{W_{b_1}, W_{b_2}\} = 0$. The argument in the dual case when b_1, b_2 are two black vertices of Γ_G corresponding to the vertices of G is the same. Finally, let b be a black vertex assigned to a face F of G, and b' a black vertex assigned to a vertex v of G. Then the face F of G and the face F' of the dual graph G' corresponding to v either do not intersect, or intersect at two points. See Figure 2 where the boundary of F is a black loop and the one for F' is a dashed loop. In the former case the Poisson bracket is evidently zero. In the latter case, the contributions of the intersection points come with the opposite signs, and thus cancel.

Continuation of proof of Theorem 5.8. Let 2m be the number of Casimirs for the Poisson variety \mathcal{L}_{Γ_G} . It equals to the number of primitive boundary intervals of the Newton polygon $N(\Gamma_G)$ and thus is an even number, since the polygon is centrally symmetric. Since the product of all Casimirs is 1, the dimension of the generic symplectic leaf on \mathcal{L}_{Γ_G} is

$$2E_G + 1 - (2m - 1) = 2(E_G - m + 1).$$

The Casimirs are monodromies along the zig-zag paths, and the latter on the graph Γ_G come in pairs: $\{z_1, z'_1\}, \ldots, \{z_m, z'_m\}$, so that $\{z_k, z'_k\}$ have the opposite homology classes, and thus the corresponding Casimirs C_k, C'_k are inverse to each other, providing a relation $C_k C'_k = 1$. Since the product of all Casimirs is 1, the last relation $C_m C'_m = 1$ follows from the others, while the first m - 1 are independent.

Since dim \mathcal{R} equals to m-1 plus half of the dimension of the generic symplectic leaf, it is sufficient to show that the generic symplectic leaves intersected by \mathcal{R} are parametrized by (no less than) m-1 parameters. Let us assume that there is a relation $C_1^{n_1} \cdots C_m^{n_m} = 1$. Let us show that $n_1 = \cdots = n_m$. Take a pair of Casimirs C_a and C_b corresponding to non-parallel sides of the Newton polygon. Then the corresponding zig-zag strands intersect. So there is an edge E shared by them. Altering the conductance at the edge E we alter just the Casimirs C_a and C_b . This implies that $n_a = n_b$. Therefore $n_1 = \cdots = n_m$.

5.2.7. Quantized cluster monomial Lagrangian subvarieties. – The subvariety \Re is a cluster monomial Lagrangian subvariety—it is a Lagrangian subvariety of a cluster Poisson variety \Re , which is given in any cluster coordinate systems by equating certain monomials to 1.

According to the correspondence principle of quantum mechanics, a symplectic manifold X should give rise to a Hilbert space H_X —the quantization of X. Furthermore, a Lagrangian subvariety $L \subset X$ should provide a line in H_X . Here is how the story goes in the cluster situation.

The quantization of a cluster Poisson variety \mathcal{X} [11] provides a collection of Gelfand triples, parametrized by the eigenvalues χ of the Casimirs:

$$\mathscr{S}_{\chi} \subset \mathscr{H}_{\chi} \subset \mathscr{S}_{\chi}^*.$$

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Here \mathcal{H}_{χ} is the Hilbert space discussed in Section 1.2.2. The *modular double algebra*, given by the tensor product of quantum algebras at \hbar and $1/\hbar$:

(52)
$$\mathcal{O}_q(\mathcal{X}) \otimes \mathcal{O}_{q^{\vee}}(\mathcal{X}), \quad q = e^{i\pi\hbar}, q^{\vee} = e^{i\pi/\hbar},$$

is realized by unbounded selfadjoint operators in the Hilbert space \mathscr{H}_{χ} . The subspace \mathscr{G}_{χ} is the maximal subspace of \mathscr{H}_{χ} where the algebra (52) acts, equipped with a natural topology. The space \mathscr{G}_{χ}^* is its topological dual. One can show using the methods of *loc. cit.* that any cluster monomial Lagrangian subvariety $L \subset \mathscr{X}$ gives rise to a functional

$$\psi_L \in \mathscr{S}^*_{\chi},$$

defined uniquely up to a scalar by the condition that ψ_L is annihilated by the quantized monomial equations in the algebra $\mathcal{O}_q(\mathcal{X})$, and their counterparts in the algebra $\mathcal{O}_{q^{\vee}}(\mathcal{X})$.

Here is the basic example. Let $\mathcal{H} = L^2(\mathbb{R})$ be the Hilbert space of functions f(x). Consider unbounded operators

$$Xf(x) := f(x + i\pi\hbar), \quad Yf(x) := e^x f(x),$$

 $X^{\vee}f(x) := f(x + i\pi), \quad Y^{\vee}f(x) := e^{x/\hbar}f(x).$

Then

$$XY = q^2 Y X, \qquad X^{\vee} Y^{\vee} = q^{\vee^2} Y^{\vee} X^{\vee}.$$

So we get a representation of the modular double of the quantum torus algebra with two generators. The subspace $\mathscr{G} \subset \mathscr{H}$ consists of functions f(x) with exponential decay at $x \to \pm \infty$, whose Fourier transform has the same property. By the Payley-Wiener theorem f(x) has an analytic continuation to \mathbb{C} .

The equation X = 1 defines a Lagrangian subvariety L in the torus $(\mathbb{C}^*)^2$ with coordinates (X, Y). The quantized equations are (X - 1)f(x + iy) = 0, $(X^{\vee} - 1)f(x + iy) = 0$. For irrational \hbar , they imply that f(x + iy) = f(x). This implies that the functional ψ is a constant.

5.3. Cluster nature of the resistor network space

Recall that all our spaces are equipped with a free action of the two-dimensional torus T, and relating them to cluster varieties we have to consider their quotients by this action, or, equivalently, consider the action of all transformations on the face weights only.

In Section 5.3.1 we use ' in the notation \mathcal{X}'_G and \mathcal{R}'_G to indicate that, just like in Section 4.1.6, we work with the quotients \mathcal{X}_G/T and \mathcal{R}_G/T . Moreover we do not define the spaces \mathcal{A}_G and \mathcal{B}_G , only the "quotients" \mathcal{A}'_G and \mathcal{B}'_G .

5.3.1. The basic commutative diagram for a graph G. – Given a graph G on a torus, let us define four split algebraic tori (that is, varieties $(\mathbb{C}^*)^k$ for some k) \mathscr{C}'_G , \mathscr{B}'_G , \mathscr{R}'_G , \mathscr{X}'_G , fitting into a commutative diagram

(53)
$$\begin{array}{ccc} \mathscr{A}'_{G} & \stackrel{j}{\hookrightarrow} & \mathscr{B}'_{G} \\ p \downarrow \swarrow s \downarrow q \\ \mathscr{X}'_{G} & \stackrel{i}{\leftrightarrow} & \mathscr{R}'_{G}. \end{array}$$

The tori \mathscr{C}_G , \mathscr{B}_G' , \mathscr{R}_G' , \mathscr{X}_G' are defined as the tori with the following canonical coordinates:

- \mathscr{A}'_G : coordinates $\{A_f\}$ at the faces f of the graph Γ_G .
- \mathscr{B}'_G : coordinates $\{B_b\}$ at the black vertices b of the graph Γ_G .
- \mathscr{R}'_G : coordinates $\{C_w\}$ at the white vertices w of Γ_G , defined up to a scalar.
- \mathcal{X}'_G : coordinates $\{X_f\}$ at the faces f of Γ_G , whose product is 1.

The C_w -coordinates are nothing else but the conductances assigned to the edges of the graph G, which are identified with the white vertices of Γ_G .

We define the maps between these tori by their action on the coordinates. Below \sim means an incidence relation. So $b \sim f$ means that a black vertex b is incident to a face f, etc.

First, the map p is the standard map [10]

(54)
$$p^*X_f := \prod_g A_g^{\varepsilon_{fg}},$$

where the product is over faces g of Γ_G , and ε_{fg} is the bilinear form on the faces defined in Section 2.

Next,

(55)
$$j^* A_f := \prod_{b \sim f} B_b = B_b B_{b'}.$$

Here b, b' are the two black vertices of the face f of the graph Γ_G .



FIGURE 26. The map s^*X_f .

Then, we set

(56)
$$s^* X_f := \frac{B_{b_1} B_{b_3}}{B_{b_2} B_{b_4}}.$$

Here (b_1, b_2, b_3, b_4) are the four black vertices which lie outside of the face and incident to the two white vertices of the face, as shown on Figure 26.

Next,

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FIGURE 27. The map $i^*X_f := C_w/C_{w'}$.

Here w, w' are the two white vertices of the face f, and w, b, w' go counterclockwise around the face, and the black vertex b is a vertex of f, Figure 27.

Finally,

(58)
$$q^*C_w := \frac{B_{c_1}B_{c_3}}{B_{c_2}B_{c_4}},$$

where c_1, c_2, c_3, c_4 are the four black vertices incident to the white vertex w as shown on the Figure 28.



FIGURE 28. The map q^*C_w .

Define [9] a 2-form on the space \mathscr{C}'_G by

$$\Omega_{\mathscr{U}} := \sum_{f,g} \varepsilon_{fg} d \log A_f \wedge d \log A_g.$$

PROPOSITION 5.10. - i) The diagram (53) is commutative.

ii) The map j is an embedding. Its image is isotropic for the 2-form $\Omega_{\mathcal{B}}$.

iii) The subvariety $i(\mathcal{R}'_G)$ is defined by monomial equations. It is Lagrangian.

iv) The subvariety $s(\mathcal{B}'_G)$ is Lagrangian in the symplectic variety

$$\mathscr{U}'_G := p(\mathscr{C}'_G) \subset \mathscr{X}'_G$$

Proof. -i) One checks this by looking at the Figures 26, 27, 28.

ii) Follows easily from the definitions.

iii) The subvariety $i(\mathcal{R}_G') \subset \mathcal{X}_G'$ is given by monomial equations

(59)
$$\prod_{f: \ \sum \partial f = \alpha - \beta} X_f = 1.$$

Here equations are assigned to pairs of loops α , β on G which are homologous on the torus. The product is over a set of faces f of Γ_G whose total boundary is $\alpha - \beta$. In particular, taking the empty loop β , we get equations

(60)
$$\prod_{f \sim b} X_f = 1 \quad \text{for each black vertex } b \text{ of the graph } \Gamma_G.$$

Indeed, it is easy to see that $i^*(59) = 1$. Recall that E_G is the number of the edges of G. It is also the number of the black as well as the white vertices of Γ_G . One has

$$\dim i(\mathscr{R}'_G) = E_G - 1.$$

Indeed, there are E_G independent equations: $E_G - 2$ are given by (60), and two more by β 's generating $H_1(\mathbb{T}, \mathbb{Z})$. Since dim $\mathscr{R}'_G = E_G - 1$, we proved the first claim. The second is similar to the proof of Theorem 5.8.

iv) It is similar to the proof of Theorem 5.8.



FIGURE 29. Transformation law for B's under a $(Y - \Delta)$ -move.

5.3.2. Action of the $(Y - \Delta)$ -move on coordinates. – A $(Y - \Delta)$ -move acts on the conductances coordinates C_i as in (49)-(50). Referring to Figure 29, we have

$$\frac{B_1B_7}{B_5B_6} = C_1 = \frac{c_1c_2 + c_2c_3 + c_3c_1}{c_1} = \frac{\frac{B_2B_3}{B_0B_4}\frac{B_3B_1}{B_0B_5} + \frac{B_3B_1}{B_0B_5}\frac{B_1B_2}{B_0B_6} + \frac{B_1B_2}{B_0B_6}\frac{B_2B_3}{B_0B_4}}{\frac{B_2B_3}{B_0B_4}}$$

from which one obtains

(61)
$$B_7 = \frac{B_1 B_4 + B_2 B_5 + B_3 B_6}{B_0}$$

The same equation is obtained starting from the other two conductances C_2, C_3 . This equation is the so-called cube recurrence relation, see Section 6.3 below.

LEMMA 5.11. – The $Y - \Delta$ move $G \rightarrow G'$ is a composition of four cluster mutations. Precisely, there are commutative diagrams

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where the down arrows are birational maps induced by the $Y - \Delta$ move action on the B- and C-variables, given by (61) and (49)-(50), and the right ones are compositions of four cluster \mathcal{C} -and \mathcal{X} -mutations.

Proof. - i) See Figure 30. After this sequence of 4 cluster transformations, a little algebra



FIGURE 30. The $Y - \Delta$ move from spider moves.

using Theorem 4.7 shows that the new X variables are:

$$\begin{split} X_1^{(4)} &= \frac{1 + X_1 + X_1 X_3}{X_3(1 + X_2 + X_1 X_2)} \\ X_2^{(4)} &= \frac{1 + X_2 + X_1 X_2}{X_1(1 + X_3 + X_2 X_3)} \\ X_3^{(4)} &= \frac{1 + X_3 + X_2 X_3}{X_2(1 + X_1 + X_1 X_3)} \\ X_4^{(4)} &= X_4(1 + X_1 + X_1 X_3) \\ X_5^{(4)} &= X_5 \frac{X_1 X_3}{1 + X_1 + X_1 X_3} \\ X_6^{(4)} &= X_6(1 + X_3 + X_2 X_3) \\ X_7^{(4)} &= X_7 \frac{X_2 X_3}{1 + X_3 + X_2 X_3} \\ X_8^{(4)} &= X_8(1 + X_2 + X_1 X_2) \\ X_9^{(4)} &= X_9 \frac{X_1 X_2}{1 + X_2 + X_1 X_2}. \end{split}$$

If $X_1X_2X_3 = 1$, we will also have $X_1^{(4)}X_2^{(4)}X_3^{(4)} = 1$. Moreover if the conductances on the edges of the triangle opposite faces 1, 2, 3 are C_1, C_2, C_3 respectively then $X_1 = C_2/C_3$, $X_2 = C_3/C_1, X_3 = C_1/C_2$. One checks that the new conductances are those satisfying (50). ii) It follows by comparing formulas (49)-(50).

It follows that the diagram (53) gives rise to a similar diagram of spaces, obtained by gluing the tori assigned to minimal equivalent graphs G via the corresponding birational maps given either by the $(Y - \Delta)$ -move or the corresponding sequence of four cluster mutations.

6. Discrete cluster integrable systems

6.1. Discrete cluster integrable systems on a square grid on a torus

Let us consider the dimer model on a square grid on a torus. Such examples are constructed as follows. Take the standard square grid bipartite graph in \mathbb{Z}^2 , and map it onto torus by taking the quotient by a rank two subgroup of the (bipartite-coloring preserving) translation group (that is, $(1, 1)\mathbb{Z} + (1, -1)\mathbb{Z}$), see Figure 33.



FIGURE 31. Inserting two white 2-valent vertices, and performing the spider move in the dotted region we get a version of the spider move on Figure 32.

Let us construct an element A of the cluster modular group acting by a non-trivial automorphism of the corresponding cluster Poisson variety \mathcal{X}_N .

There is a version of the spider move, see Figure 32, given by a composition of two elementary moves on Figure 31.



FIGURE 32. A version of the spider move.

The squares of the grid are of two types: one, which we refer to as the *-faces, have the black bottom left vertex. Let us do the Figure 32 version of the spider move at all *-faces. The

result is illustrated at the right of Figure 34. Then we shrink the 2-valent vertices, as shown on Figure 23. We get again a square grid, but now the colors of the vertices flipped, see the bottom of Figure 34. So performing the same sequence of moves—the Figure 32 version of the spider moves at the *-faces and shrinking the 2-valent vertices—we get the original grid. The resulting cluster transformation A is non-trivial. Thanks to Theorem 4.7 it commutes with the quantum Hamiltonians.



FIGURE 33. Discrete cluster integrable system on a square grid on a torus.

The transformation A has appeared in various guises in the literature. A version of the transformation A first appeared in [28]. It was called the *octahedron recurrence* in [36]; the relation of the octahedron recurrence with the Hirota bilinear difference equation [20] is discussed there. A solution of the octahedron recurrence on a simplex was found in [9]. See also [8], [29] for other examples which are special cases.

The cluster transformation A together with the quantum Hamiltonians form a discrete quantum integrable system—we think of A as of an evolution with a discrete time. In the quantized picture [11] the operator A gives rise to a unitary operator in the Hilbert space of the system commuting with the quantum Hamiltonians. It is a composition of the quantum dilogarithm intertwiners parametrized by the faces.

6.2. Cluster automorphisms for resistor networks on a torus

One also finds cluster automorphisms for cluster varieties associated to resistor networks on a torus. The pair $(\mathcal{X}, \mathcal{R})$ assigned to an equivalence class of minimal graphs G on a torus has a large group \mathbb{A} of cluster automorphisms, isomorphic to (a quotient of) \mathbb{Z}^{s-2} , where 2s is the number of sides of the Newton polygon N(G). It is constructed as follows. (This material is also found in [19].)

For each pair E, E' of centrally symmetric sides of the Newton polygon N(G) of a minimal graph G on a torus there is a collection $\alpha_1, \ldots, \alpha_k$ of isotopic zig-zag strands on G which do not intersect due to minimality of G: their (well defined up to sign) homology class in $H_1(T, \mathbb{Z})$ is a primitive vector on E. We assume that they are written in their natural cyclic order provided by the embedding to the torus. Isotope them cyclically $(\alpha_1, \ldots, \alpha_k) \rightarrow (\alpha_2, \ldots, \alpha_k, \alpha_1)$, leaving the other zig-zag paths intact. Present this as a sequence of $(Y - \Delta)$ -moves corresponding to the zig-zag strands moving through simple crossings of other zig-zag strands, which transforms the graph G to itself. Take the product of the



FIGURE 34. Constructing an element A of the cluster modular group.

cluster transformations assigned by Lemma 5.11 to the $(Y - \Delta)$ -moves. We arrive at a cluster transformation, realized by a birational isomorphism of the pair $(\mathcal{X}, \mathcal{R})$. It is an element of the cluster modular group, as defined in Section 2.4 of [10]. The automorphisms assigned to different sides commute, and their product is 1.

6.3. The cube recurrence discrete cluster integrable system

Let us apply the construction of Section 6.2 to the honeycomb graph on a torus. In this case there are three families of parallel zig-zag loops. Moving cyclically one of the families we get a cluster automorphism. We show that its action on the *B*-variables is given by the so-called *cube recurrence* [4], also known as the *discrete BKP equation* or *Hirota-Miwa equation*, which goes back to the work of Miwa [33], see also [3].

A function $a : \mathbb{Z}^3 \to \mathbb{C}$ satisfies the cube recurrence if

(62) $a_{x+1,y+1,z+1}a_{x,y,z} = a_{x+1,y,z}a_{x,y+1,z+1} + a_{x,y+1,z}a_{x+1,y,z+1} + a_{x,y,z+1}a_{x+1,y+1,z}.$

Note that if a is defined and nonzero for $0 \le x + y + z \le 2$ then Equation (62) defines it for x + y + z = 3, also for x + y + z = -1, and by iteration for all $(x, y, z) \in \mathbb{Z}^3$.

Let G be the honeycomb graph, thought of as a resistor network. Vertices of G are the orthogonal projection to the plane $\{x + y + z = 0\}$ of the set $\{(x, y, z) \in \mathbb{Z}^3 \mid x + y + z = 0 \text{ or } 2\}$; edges connect vertices whose coordinate sum is 0 to those nearest neighbors whose coordinate sum is 2. We can likewise index faces of G by (x, y, z) satisfying x + y + z = 1. See Figure 35. Let V_k be the set of vertices or faces with x + y + z = k.

Assign variables $B_{x,y,z}$ to the vertices and faces of G.

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FIGURE 35. Vertex and face labeling for the cube recurrence.

Perform a $Y - \Delta$ move at each vertex $v_{x,y,z}$ where x + y + z = 0. The graph becomes the regular triangulation with vertices at V_2 , faces at V_1 and new faces at V_3 . Using (61), the *B*-value at a new face is obtained from (62). See Figure 36.

Next, perform $\Delta - Y$ moves on all faces in V_1 . The resulting graph is again a honeycomb, with vertices V_2, V_4 and faces at V_3 . Iterating this procedure we produce variables $B_{x,y,z}$ for all $(x, y, z) \in \mathbb{Z}^3$ and these variables satisfy the cube recurrence.

Equivalently, we can look at zig-zag strands and move cyclically one of the families of parallel zig-zag strands, say the vertical ones on Figure 35. Then each strand will cross two different sets of crossings of other two families, which can be thought of as the vertices of the grid, resulting into $Y - \Delta$ and $\Delta - Y$ moves described above.

By Lemma 5.11, the composition B of these $Y - \Delta$ moves and $\Delta - Y$ moves is a cluster automorphism, i.e., an element of the cluster modular group, of the dimer model phase space assigned to the graph G. Therefore it gives rise to a discrete cluster integrable system, with the discrete time evolution given by B. Thanks to (61), the cube recurrence is obtained by restricting the cluster automorphism B to the isotropic subvariety \mathcal{B} .

7. Newton polygons, toric surfaces and integrable systems

7.1. Newton polygons and toric surfaces

Let us briefly recall this well known connection. See [14] for more details. Let $T = (\mathbb{C}^*)^2$. Denote by $X^*(T)$ the group of its characters, isomorphic to \mathbb{Z}^2 .

A Newton polygon N is a convex polygon in the real plane $X_*(T)_{\mathbb{R}} := X^*(T) \otimes \mathbb{R} = \mathbb{R}^2$ with vertices at the lattice $X^*(T)$. It gives rise to a polarized projective toric surface \mathcal{N} , possibly singular. The polarization is given by a T-equivariant line bundle \mathcal{L} on \mathcal{N} . Shifting



FIGURE 36. Steps of the cube recurrence. The black dots are the vertices $v_{x,y,z}$ with x + y + z = 0.

the Newton polygon by a lattice vector $l \in X^*(T)$ amounts to changing the equivariant structure of the line bundle \mathcal{L} by multiplying it by the trivial line bundle with the torus T action given by the character χ_l assigned to l.

Each edge E of N gives rise to a ray ρ_E in the dual space $X_*(T)_{\mathbb{R}}$, consisting of the normals to the edge E looking inside of N. These rays form a fan Δ_N . It subdivides the plane $X_*(T)_{\mathbb{R}}$ into a disjoint union of cones. Each cone σ provides the dual cone σ^{\vee} , and hence a semigroup $R_{\sigma} := \sigma^{\vee} \cap X^*(T)$ and an affine surface $U_{\sigma} := \text{Spec } \mathbb{Z}[R_{\sigma}]$. Gluing the surfaces U_{σ} so that $U_{\sigma_1 \cap \sigma_2} = U_{\sigma_1} \cap U_{\sigma_2}$ we get the surface \mathcal{N} .

The torus T acts on \mathcal{N} . There is a unique 2-dimensional orbit, U_0 , where 0 is the origin, denoted below by \mathcal{N}_0 . Its complement is the *divisor at infinity* \mathcal{N}_∞ , whose shape is described by the polygon N: the irreducible components D_E are projective lines parametrized by the edges E of N, and their intersections match the vertices of N. The kernel of the action of the torus T on the component D_E is the cocharacter $\chi_E^{\vee} : \mathbb{C}^* \to T(\mathbb{C})$ assigned to the conormal line to the edge E.

There is a canonical isomorphism, serving as a definition of the line bundle \mathcal{L} :

$$i_N: \mathcal{L} \xrightarrow{\sim} \mathcal{O}(D), \qquad D = \sum_E a_E D_E,$$

where the coefficient $a_E \in \mathbb{Z}$ is the distance from the origin to the edge $E^{(8)}$. The torus T action on \mathcal{L} comes from the natural T-action on $\mathcal{O}(D)$, provided by the action on \mathcal{N} preserving the divisor D. Shifting the polygon N by a vector $l \in X^*(T)$ amounts to multiplication of the isomorphism i_N by the character χ_l , i.e., $i_{N+l} = i_N \chi_l$. Using the isomorphism i_N , we have

(63)
$$H^0(\mathcal{N}, \mathcal{L}) \xrightarrow{\sim} H^0(\mathcal{N}, \mathcal{O}(D)) \subset \mathbb{C}(\mathbb{T}) \stackrel{\simeq}{=} \mathbb{C}(z_1, z_2),$$

where (z_1, z_2) is a basis in the group of characters of T. It is identified with the space of all Laurent polynomials with the Newton polygon N.

So given a pair $(\mathcal{N}, \mathcal{L})$, the polygon N is recovered as the convex hull of the set of characters of the action of the torus T on $H^0(\mathcal{N}, \mathcal{L})$.

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⁽⁸⁾ The latter is the value at the origin of the unique surjective affine linear function $\alpha_E : X_*(T) \to \mathbb{Z}$ which vanishes on *E* and is non-negative on *N*.

Denote by ω the canonical up to a sign invariant 2-form on $\mathcal{N} - \mathcal{N}_{\infty}$. Given a basis (z_1, z_2) of characters of the torus T, it can be written as

$$\omega = d \log z_1 \wedge d \log z_2.$$

So it is a 2-form on \mathcal{N} with logarithmic singularities at \mathcal{N}_{∞} .

7.2. The spectral data [26]

A parametrization of a degree d divisor $C = \sum_{i=1}^{k} n_i c_i$ by a set S is a map

$$\nu: S \longrightarrow \{c_1, \ldots, c_k\}$$
 such that $|\nu^{-1}(c_i)| = n_i$.

Let $|\mathcal{L}|$ be a linear system of curves on \mathcal{N} given by the zeros of sections of \mathcal{L} .

DEFINITION 7.1. – A spectral data is a triple (C, S, ν) where C is a genus g curve on the toric surface \mathcal{N} from the linear system $|\mathcal{L}|$, S is a degree g effective divisor on $C_0 = C \cap \mathcal{N}_0$, and $\nu = \{\nu_E\}$ are parametrizations of the divisors $D_E \cap C$.

The moduli space $\mathscr{A}_N = \mathscr{A}$ parametrizes the spectral data related to N.

Let C be a curve on \mathcal{N} from the linear system $|\mathcal{L}|$. Its intersection with \mathcal{N}_0 is defined by a Laurent polynomial $P(z_1, z_2)$ with the Newton polygon N. The intersection of $C \cap D_E$ is determined by the sum of monomials of P supported on the edge E. The ratio of monomials assigned to two integral points on the sides of N are Casimirs. So the Casimirs are naturally assigned to the primitive boundary edges of N, and their product is equal to 1.

PROPOSITION 7.2. – Given a black vertex v of a minimal bipartite graph Γ assigned to N, there is a natural rational map

 $\kappa_{\Gamma,v}: \mathcal{X} \longrightarrow \mathscr{A}.$

Proof. – A point of \mathcal{X} parametrizes a line bundle with connection on Γ , encoded by the Kasteleyn operator K. Its determinant is a section of the line bundle $\mathcal{L} \otimes \mathbf{L}$. The divisor of zeros of the section is the *spectral curve* C on \mathcal{N} . The black point b defines a section of a line bundle on C. Its degree is the genus g of C, and its divisor is the divisor S. Homology classes $[\alpha_E]$ of zig-zag loops on Γ are in bijection with the sides of the Newton polygon N. There is a parametrization

(64) $\gamma_E : \{ \text{Zig-zag loops on } \Gamma \text{ in the homology class } [\alpha_E] \} \xrightarrow{\sim} D_E \cap C,$

uniquely determined by the following condition. The function given by the monodromy around a zig-zag loop α coincides with the function given by the coordinate of the boundary point $\gamma_E(\alpha)$.

Denote by \mathscr{G}_{χ} the subvariety of \mathscr{G} given by the condition that $C \cap \mathscr{N}_{\infty}$ is a given divisor C_{∞} . Using the parametrization (64), the divisor C_{∞} provides a subvariety \mathscr{X}_{χ} in \mathscr{X} defined by the condition that the monodromies around zig-zag paths are given by the coordinates of the corresponding boundary points. Since this condition uses only the boundary

divisor of the spectral curve, there is a similar subvariety \mathscr{B}_{χ} in \mathscr{B} . The map $\kappa_{\Gamma,v}$ is evidently fibered over \mathscr{B}_{χ} , providing a commutative diagram



THEOREM 7.3. – The image of the map $\kappa_{\Gamma,v}$ is open. The map $\kappa_{\Gamma,v}$ is a finite map over the generic point.⁽⁹⁾

See below for the proof. Since both spaces have the same dimension, the first claim implies the second.

7.3. The real positive points [26]

Since \mathcal{X} is a union of cluster coordinate tori, and the transition functions between different cluster coordinate systems are subtraction free rational functions, there is a well defined set $\mathcal{X}(\mathbb{R}_{>0})$ of its real positive points. It parametrizes connections on a minimal bipartite graph Γ associated with N whose face weights are positive numbers, and does not depend on the choice of Γ .

Simple Harnack curves were defined by G. Mikhalkin in [31] as real curves $P(z_1, z_2) = 0$ whose real components satisfy certain topological constraints. They are a very special case of the curves which appear in the Harnack constructions [18] of several series of real curves of degree d with the maximal number of connected components (M-curves). Several characterizations of simple Harnack curves were given in [31]. They include a definition via 2 - 1covering of its amoeba. Recall that the amoeba is the image of the curve under the map

$$\mathbb{C}^* \times \mathbb{C}^* \to \mathbb{R}^2$$
, $(z_1, z_2) \mapsto (\log |z_1|, \log |z_2|)$.

Another characterization of simple Harnack curves, due to [32], is that they are the curves which maximize the area of their amoeba among all curves with given Newton polygon.

The results of Kenyon-Okounkov [26, Theorems 1,3] are as follows:

- The real positive part $\mathscr{B}(\mathbb{R}_{>0}) := \pi(\mathscr{X}(\mathbb{R}_{>0}))$ parametrizes simple Harnack curves on \mathscr{N} which lie in the linear system $|\mathscr{L}|$. Such a genus g simple Harnack curve has g ovals O_i matching the integral points inside of the Newton polygon N.
- The space X(ℝ_{>0}) parametrizes the data {A simple Harnack curve C on N from |L|, a choice of a point on each oval O_i, a choice of parametrization of the intersection of C with each divisor at infinity}.

Therefore the fibers of the fibration

$$\pi_+: \mathcal{X}(\mathbb{R}_{>0}) \longrightarrow \mathcal{B}(\mathbb{R}_{>0})$$

are real g-dimensional tori. They are the Liouville tori of the integrable system restricted to $\mathcal{X}(\mathbb{R}_{>0})$.

⁽⁹⁾ In the sequel to this paper we prove that this map is a birational isomorphism.

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7.4. Independence of the Hamiltonians

COROLLARY 7.4. – Forgetting the parametrization, the space \mathcal{B} projects to an open part of $|\mathcal{L}|$.

Proof. – Thanks to Section 7.3 the image of \mathcal{B} is an algebraic subvariety of $|\mathcal{L}|$, and its real part contains an open subset of the real locus of $|\mathcal{L}|$.

COROLLARY 7.5. – The Hamiltonians are independent on X.

Proof. – Denote by $|\mathcal{L}|_{\chi}$ the moduli space of curves from the linear system $|\mathcal{L}|$ with a given intersection \mathcal{C}_{∞} with \mathcal{N}_{∞} . Thanks to Corollary 7.4, \mathcal{B}_{χ} is a finite cover over an open part of $|\mathcal{L}|_{\chi}$. We claim that the Hamiltonians are local coordinate functions on $|\mathcal{L}|_{\chi}$. Therefore they are independent on \mathcal{X} .

Let us prove the claim. Identify the sections of \mathcal{L} with Laurent polynomials in (z_1, z_2) with the Newton polygon N. Let \mathcal{P}_N^0 be the subspace of Laurent polynomials in (z_1, z_2) whose Newton polygon is the interior of N. Adding such a polynomial to a section of \mathcal{L} , we do not change the intersection with \mathcal{N}_{∞} of its divisor of zeros. So we get an action of the vector space \mathcal{P}_N^0 on $|\mathcal{L}|_{\chi}$. This action is transitive. The Hamiltonians are given by the coefficients of the monomials in \mathcal{P}_N^0 . So their differentials at a point $C \in |\mathcal{L}|_{\chi}$ form a basis of $T_C^* |\mathcal{L}|_{\chi}$. \Box

Proof of Theorem 7.3. – The restriction of the map $\kappa_{\Gamma,v}$ to $\mathscr{X}_{\chi}(\mathbb{R}_{>0})$ is an isomorphism. Thus its image is open in \mathscr{G}_{χ} .

8. Appendix: Calculating the Poisson structure on \mathcal{L}_{Γ}

Let us give a local description of the intersection pairing (3) as a sum of local contributions assigned to the vertices of Γ .

8.1. The local pairing

The star of a vertex v in a ribbon graph, Figure 37, is a vertex v together with the cyclically ordered edges incident to v.



FIGURE 37. The star of a vertex on an oriented surface.

The star of a vertex v gives rise to an abelian group \mathbb{A}_v , given by \mathbb{Z} -linear combinations of the oriented edges E_i at v of total degree zero:

$$\mathbb{A}_v = \{ \sum n_i \vec{E}_i \mid \sum n_i = 0, \ n_i \in \mathbb{Z} \},\$$

where \vec{E}_i is the edge E_i oriented out of v. Clearly \mathbb{A}_v is a torsion free abelian group of rank m-1, where m is the valency of v. It is generated by the "oriented paths" $\vec{E}_i - \vec{E}_j$, where $-\vec{E}_j$ is the edge E_j oriented towards v.



FIGURE 38. One has $\delta_v(\gamma_r, \gamma_l) = \frac{1}{2}$.

LEMMA 8.1. – There exists a unique skew symmetric bilinear form

$$\delta_v: \mathbb{A}_v \wedge \mathbb{A}_v \longrightarrow \frac{1}{2}\mathbb{Z}$$

such that for any triple E_0, E_1, E_2 of edges as in Figure 38 one has

(65)
$$\delta_v(\gamma_r \wedge \gamma_l) = \frac{1}{2}, \qquad \gamma_r := \vec{E_1} - \vec{E_0}, \quad \gamma_l := \vec{E_2} - \vec{E_0}.$$

Proof. – Let $\{x_1, \ldots, x_m\}$ be the cyclically ordered set of the endpoints of the edges sharing the vertex v. Let γ_i be the oriented path $x_i v x_{i+1}$. Then the elements $\gamma_1, \ldots, \gamma_m$ generate \mathbb{A}_v and satisfy the only relation $\sum_i \gamma_i = 0$. We define the local pairing by setting

$$\delta_v(\gamma_i \wedge \gamma_{i+1}) = \frac{1}{2}$$

Then $\sum_{i} \gamma_{i}$ is in the kernel, so the local pairing is well defined. It is easy to see that it satisfies formula (65).

8.2. The global pairing

Let L_1, L_2 be two oriented paths on Γ . Let v be a vertex shared by them. Each path L_i gives rise to an oriented path at the star of v, providing an element $l_i \in \mathbb{A}_v$. Let $\varepsilon_v(L_1, L_2)$ be the value of the local pairing δ_v on $l_1 \wedge l_2$.

DEFINITION 8.2. – Let L_1, L_2 be two oriented loops on a bipartite surface graph Γ . Then

$$\varepsilon(L_1, L_2) := \sum_v \operatorname{sgn}(v) \varepsilon_v(L_1, L_2)$$

where the sum is over all vertices v shared by L_1 and L_2 , and sgn(v) = 1 for the white vertex v, and -1 for the black vertex.



FIGURE 39. One has $\varepsilon(\gamma_1, \gamma_2) = -1$, $\varepsilon(\gamma_3, \gamma_4) = 0$.

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FIGURE 40. One has $\varepsilon(\gamma_1, \gamma_2) = 1$, $\varepsilon(\gamma_3, \gamma_4) = 0$.

PROPOSITION 8.3. – The bilinear form $\varepsilon(L_1, L_2)$ from Definition 8.2 coincides with the bilinear form defined using the conjugated graph $\widehat{\Gamma}$ in Section 1.1.1

Proof. – It is sufficient to show that in the examples on Figures 39 and 40 the sum of the local contributions coincides with the local intersection number of the corresponding paths on the conjugated graph. The latter clearly gives the results presented on Figures 39 and 40. So one needs to show that the former gives the same result. For example, to check that $\varepsilon(\gamma_1, \gamma_2) = 1$ for the left picture on Figure 40, notice that on Figure 41 we have

$$\delta_v(\gamma_1,\gamma_3) = -\frac{1}{2}, \qquad \delta_v(\gamma_1,\gamma_2+\gamma_3) = \frac{1}{2}.$$



FIGURE 41. Proving $\varepsilon(\gamma_1, \gamma_2) = 1$.

Example. – The face orientation provides the counterclockwise orientation of the boundary of the face. Given two different faces F_1 , F_2 , and an edge E, we calculate that

(66)
$$\delta_{E;F_1,F_2} := \begin{cases} 0 & \text{if } E \notin \partial(F_1) \cap \partial(F_2), \\ +1 & \text{if the "black to white" orientation of } E \\ & \text{is the same as the orientation induced} \\ & \text{by the orientation of the face } F_1, \\ -1 & \text{otherwise.} \end{cases}$$

Taking now the sum over all edges E, we get

$$\varepsilon(F_1, F_2) := \varepsilon(\partial(F_1), \partial(F_2)) = \sum_E \delta_{E;F_1, F_2}.$$

Example. – Given a face F and an oriented loop L on Γ , let us calculate $\varepsilon(F, L)$. Denote by Or_E the "black to white" orientation of the edge E. The orientation of L induces an orientation $\operatorname{Or}_{E,L}$ of any edge E of L. Set

(67)
$$\delta_{E,L} = -\operatorname{Or}_{E,L}/\operatorname{Or}_{E} \in \{\pm 1\}.$$

So if the orientation of L is opposite to the canonical orientation of E, then $\delta_{E,L} = 1$. Otherwise $\delta_{E,L} = -1$. Then it follows from Figure 39 that we have

(68)
$$\varepsilon(F,L) = \sum_{E \in L \cap \partial(F)} \delta_{E,L}.$$

Here the sum is over all edges E shared by the face F and the loop L.

Changing the orientation of the surface amounts to changing the sign of the Poisson bracket. Interchanging black and white we change the sign of the Poisson bracket.

8.3. Amalgamation and the Poisson structure on \mathcal{L}_{Γ}

We extend the story to the case Γ is a bipartite graph on an oriented surface S with boundary. Pairs (Γ, S) are encoded by bipartite ribbon graphs.

8.3.1. *Bipartite ribbon graphs.* – Take a bipartite graph embedded into an oriented surface S with boundary, so that some vertices of the graph may lie at the boundary of S. Let us add to every boundary vertex of the graph a few edges sticking out of the surface, called *external legs*. The graph Γ is then a bipartite ribbon graph. Every bipartite ribbon graph is obtained this way.

DEFINITION 8.4. – Given a bipartite ribbon graph Γ , the moduli space \mathcal{L}_{Γ} parametrizes line bundles with connection over the graph Γ , equipped with a trivialization of the restriction of the bundle to every external edge.

Let Γ_1 and Γ_2 be bipartite ribbon graphs. Let us assume that we are given a way to glue some pairs of their external legs into a bipartite ribbon graph Γ . So each external leg of each graph is glued to no more than one external leg of the other graph, and the result is a bipartite ribbon graph. Then there is a map of moduli spaces, the *amalgamation map*:

(69)
$$\alpha: \mathcal{L}_{\Gamma_1} \times \mathcal{L}_{\Gamma_2} \longrightarrow \mathcal{L}_{\Gamma}.$$

We use trivializations at the external legs of the bundles on Γ_1 and Γ_2 to glue a new bundle on Γ . It inherits a connection. The following is obvious.

LEMMA 8.5. – The gluing map (69) is a principal fibration over \mathcal{L}_{Γ} with the fiber $(\mathbb{C}^*)^k$, where k is the number of pairs of glued boundary legs.



FIGURE 42. White and black hedgehogs with six external legs.

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A bipartite ribbon graph with single internal vertex is called a *hedgehog*, see Figure 42. It is a white / black hedgehog according to the color of its internal vertex. Let H_v be a hedgehog with the internal vertex v. Then one has

(70)
$$\mathscr{L}_{H_v} = \operatorname{Hom}(\mathbb{A}_v, \mathbb{C}^*) = \operatorname{Ker}\left(\mu : (\mathbb{C}^*)^m \longrightarrow \mathbb{C}^*\right).$$

Here m is the number of legs and μ is the multiplication map. The first isomorphism assigns to an oriented path connecting two external legs the monodromy of the connection along this path. Since the line bundle is trivialized at the endpoints, it is just a non zero complex number. The second is obvious.

A ribbon graph Γ is glued from the hedgehogs provided by the stars of its internal vertices. Amalgamating the hedgehog moduli spaces we get the moduli space \mathscr{L}_{Γ} .



FIGURE 43. Gluing bipartite ribbon graphs from hedgehogs.

Thanks to identification (70), the skew symmetric local pairing on the abelian group \mathbb{A}_v provided by the color of the internal vertex v of the hedgehog gives rise to a Poisson structure on the moduli space \mathcal{L}_{H_v} . The following proposition follows easily from the definitions.

LEMMA 8.6. – There is a unique Poisson structure on the space \mathcal{L}_{Γ} such that the Poisson structure on the space \mathcal{L}_{H_v} assigned to a hedgehog H_v is the standard one, and the amalgamation maps (69) are Poisson.

When Γ is a bipartite graph on a surface without boundary we recover its Poisson structure.

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