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ALGORITHM FOR MODELING THE CHARACTERISTICS OF UV COMMUNICATION CHANNELS OF A WIRELESS AD-HOC NETWORK

(Mobile Ad-Hoc Network, MANET)

() (non-line-of-sight, NLOS) MANET. MANET, MIMO,

A promising and little-studied direction is the construction of mobile ad-hoc networks (Mobile Ad-Hoc Network, MANET) with a UV communication channel for use in military and other responsible and dangerous facilities. Wireless optical communication systems in the ultraviolet (UV) range attract interest due to the unique ability to provide communication in the absence of direct visibility between the transmitter and receiver (non-line-of-sight mode, NLOS) due to the properties of UV radiation scattering, which significantly expands the possibilities of using MANET. To create UV communication networks with high tactical and technical parameters, it is necessary to develop effective algorithms for modeling such systems. The developed algorithm based on the Monte Carlo method combines the advantages of known analytical and numerical methods for modeling UV channels, allowing the calculation to take into account the location angles and azimuths of receivers and transmitters, the influence of obstacles, and choose combinations with a different number of transmitters and receivers of UV radiation.

Keywords: wireless UV communication, Mobile Ad-Hoc Network, MANET, MIMO, Monte Carlo method.

() (non-line-of-sight, NLOS) [1, 2]. (Mobile Ad-Hoc Network, MANET) [3, 4].

[6, 7],
[8, 9].

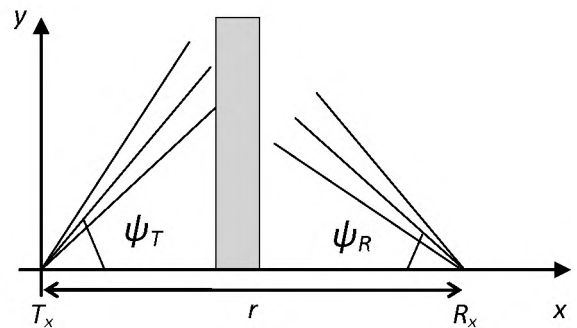
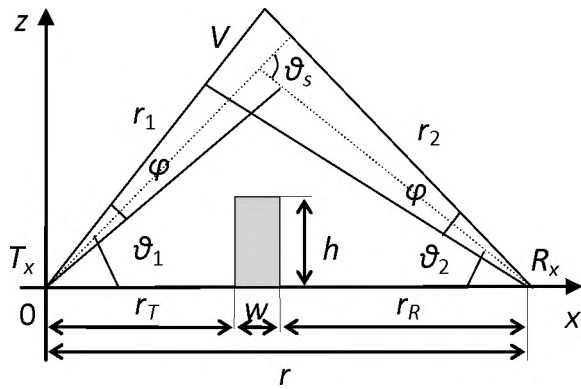
MANET:

(),
();
;
;
(
, single input, single output, SISO),
multiple output, MIMO);
([10])
()

UV NLOS

: - , Rx -
1
, V -
Rx V, $\hat{n}_{t,r}$ -
, r_{DR} -

1. Rx, $\hat{0}_{12}$ \hat{e}_{12} -
2 - \hat{e}_s -
Rx, r_{12} -
, w h -



1 -) UV NLOS:) ;

()

(Rayleigh)

(Mie) [5]:

$$P(\theta) = \frac{k^R}{k_S} \theta^R + \frac{k^M}{k_S} \theta^M$$

$$p = \cos \theta$$

$$k_s = k^+ + k^-$$

Heney-Greenstein,

$$P''(\theta) = \frac{[1 + 3/(1 - \theta)^2]}{16(1 + 2\theta)}$$

$$f''(\theta) = \frac{1-g}{4} \frac{1}{i^l + g^{2-2l} g^l j^l} + f \frac{0.5(\theta - 1)}{(1 + \theta)^2}$$

, g, f-

1. _____.

$$U = \arcsin[\text{rand}(1, M)], \theta_{j, \dots, 2} = \text{rand}(1)$$

rand(1, M) -

$$0 \leq 1$$

$$f^{(\cos)}(U) = \frac{1}{2} \cos U, U \in [0, \pi/2], \\ 0, U \in [\pi/2, \pi]$$

$$= \cos^{\theta_{j, \dots, 2}}, \sin^{\theta_{j, \dots, 2}}, \sin^{\theta_{j, \dots, 2}}, \sin^{\theta_{j, \dots, 2}}, \cos^{\theta_{j, \dots, 2}}$$

$$\theta_{j, \dots, 2}$$

$$' = \dots, = M \setminus \dots I-M, \theta_{j, \dots, 2}$$

$$M, (\theta) = \begin{pmatrix} \cos \theta & 0 & \sin \theta \\ 0 & 1 & 0 \\ -\sin \theta & 0 & \cos \theta \end{pmatrix}, M, (a) = \begin{pmatrix} \cos a & -\sin a & 0 \\ \sin a & \cos a & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

single output)

(MIMO MISO - multiple input,

Or

2. _____ ()

$$A_s = \frac{\ln}{s}$$

$$r_{i+1} = (x_{i+1}, y_{i+1}, z_{i+1})$$

$$r_0 = r_T = (x_T, y_T, z_T)$$

3. _____

$$= 2 \int_0^{\cos \theta} P(\lambda) d\lambda$$

$$0 \leq \lambda \leq 1$$

$$r_{i+1} = \begin{pmatrix} \cos \theta_i \\ \sin \theta_i \cos \phi_i \\ \sin \theta_i \sin \phi_i \end{pmatrix} r_i$$

4. _____

$$p_2 = \exp(-\dots)$$

$$r_R = (x_R, y_R, z_R)$$

5. _____ (survival probability)

$$= (1 - \dots)^{\dots}$$

$$r' = (x' y' z')$$

6. _____ (arrival probability)

$$f = \dots \text{obstacle}(r_i, r_R)$$

(MIMO SIMO - single input, single FOV,

output)

$$[10], \dots \text{(arrival probability)}$$

$$\text{obstacle}(r_i, r_R)$$

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