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# Lineament Extraction using Gravity Data in the Citarum Watershed

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**Abstract.** Lineament is one of the most important features showing subsurface elements or structural weakness such as faults. This study aims to identify subsurface lineament patterns using automatic lineament in Citarum watershed with gravity data. Satellite gravity data were used to generate a sub-surface lineament. Satellite gravity data corrected using Bouguer and terrain correction to obtain a complete Bouguer anomaly value. Butterworth filters were used to separate regional and residual anomaly from the complete Bouguer anomaly value. Residual anomaly gravity data used to analyze sub-surface lineament. Lineament generated using Line module in PCI Geomatica to obtain sub-surface lineament from gravity residual value. The orientations of lineaments and fault lines were created by using rose diagrams. The main trends observed in the lineament map could be recognized in these diagrams, showing a strongly major trend in NW-SE, and the subdominant directions were in N-S. Area with a high density of lineament located at the Southern part of the study area. High-density lineament might be correlated with fractured volcanic rock upstream of the Citarum watershed, meanwhile, low-density lineament is associated with low-density sediment. The high-density fracture might be associated with intensive tectonics and volcanism.

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## 1. Introduction

Area of approximately Seven thousand four hundred square kilometers, divided into three parts; the upper part (1771 squared kilometer), the middle part (4242 km<sup>2</sup>), the lower part (1387 square kilometer) (Juwana et al., 2016a). The average watershed rainfall is 2300 mm/year, and the Citarum flow measured by the Saguling Dam is around 5.7 billion m<sup>3</sup>/year (Juwana et al., 2016b). In 2008, there were just over 11 million people in the watershed. Most live on the Riverbanks and have used it directly in different domestic applications (Juwana et al., 2016b). The river runs through Jakarta and West, two central provinces. Water companies in the watershed also use the river as the raw water source for their water treatment plants (Juwana et al., 2016b).

A lot of Citarum researchers (Agaton et al., 2016; Djuangsih, 1993; Harashina et al., 2003; Herawati et al., 2016; Juwana et al., 2016a; Nastiti et al., 2015; Parikesit et al., 2001; Sunardi et al., 2012). None of them concerns the mapping of sub-surface geological structures. The mapping of geological structures in the area, particularly in areas with insufficient outcrop exposures, can take time and are difficult (Yeomans et al., 2019). Moreover, partial exposure and subtle topographic variation structures such as severe defects can be complicated to map a geologist on the field. Lineament detection can aid the mapping of geological structures (Yeomans et al., 2019). A lineament is a mappable rectilinear or curvilinear linear feature of a surface, distinct from adjacent patterns, representing a subsurface phenomenon (O'Leary et al., 1976). Lineaments are linear features evident at the land surface that express the underlying geological structure (Ibrahim & Mutua, 2012). It is a linear or

curvilinear mappable feature on a surface whose parts are aligned in a straight or somewhat curved relation due to a defect or other line defect (Ibrahim & Mutua, 2012). The surface characteristics that form a lineament can be geomorphological, i.e., relief or tonal differences i.e. (Hung et al., 2005; Haryono et al., 2016). Remotely sensed data, including satellite imaging, and airborne geophysical data, are usually used to map regionals (Yeomans et al., 2019). In addition, these lineaments may be used as a basis to infer the region's structural geology, with implications for mineral exploration (Moore and Camm, 1982; James et Moore, 1985; Ni et al., 2016; Verdiansyah, 2019), oil exploration (Peña and Abdelsalam, 2006). (Rutzinger et al., 2007). The conventional techniques of linear extraction include manual scanning of linear features. In addition, optical images are commonly used, but they take time, are subjective, and are reproductive inadequate (Masoud and Koike, 2006; Scheiber et al., 2015).

There are various applications for potential field methods (Zhdanov, 2002; Mehane and Zhdanov, 2002; Abdelrahman et al., 2004; Zhdanov et al., 2004; Essa et al., 2008; Mehane et al., 2011; Mehane, 2014, Mehane, 2015; Biswas, 2017; Zhang et al., 2018, Essa and Elhoussein, 2018). In many geophysical prospect areas, particularly in the determination of the crystalline basement depth (Abdelrahman and Essa 2015a; Yangfan Deng et al., 2016), which define structural environments, gravity and magnetic processes have been presented as beneficial results (Abdelrahman and Essa, 2015b; Gabtni et al., 2016), Exploring and delineating gravity and magnetic resources on minerals, hydrocarbons and geothermals (Eseas, 2007 and 2011; Khazri and Gabtni, 2018)

(Essa, 2014; Mehane and Essa, 2015; Abo-Ezz and Essa, 2016; Essa and Elhussein, 2017). For many subsurface investigations, gravity methods have been used (Araffa et al., 2015; Fallatah et al., 2019; Kurniawan, 2012; Mansour et al., 2018; Mohamed, 2019; Mukherjee & Ramachandran, 2018; Yang et al., 2019). Some researchers have been using gravity satellite information in their research (Álvarez et al., 2013; Chambers 2015.; Chen et al., 2014.; Holzrichter & Ebbing, 2016; Noréus et al (1997); Publishers & Kingdom, 1991).

For several decades, the automation in structural geology of remotely sensed data geological mapping has served as a central research topic (Yeomans et al., 2019). Automation overcomes time and subjectivity issues that influence the manual approach. While fully automatic methods go beyond current computer algorithms, semi-automatic techniques rapidly improve (Yeomans et al., 2019). An early critique of semi-automatic methods included misconceptions about roads and field borders in specific environments, as well as the adverse effects of vegetative cover (Yeomans et al., 2019). More elaborate processing and non-optical datasets such as airborne geophysical data, in particular, magnetic data (Middleton et al., 2015), electromagnetic data (Paananen, 2013), radiometric data (Debeglia et al., 2006), and gravity data can now be circumvented (Lahti et al., 2014).

Satellite imagery and gravity datasets can detect lineaments (Francés et al., 2014; Nur et al., 2017). Application of Sobel and gradient are various techniques including. The second is an automated linear extraction, where the image is automatically processed by specifying different parameters, such as the curve length, the connection of distance, kernel size. There are two main methods of removing lineaments from satellite images: (Nur et al., 2017). LINE from PCI Geomatica has been the most popular processing tool in recent years. This study aims to identify sub-surface linear models in the Citarum watershed with gravity data using automatic lineaments.

## 2. Method

This research was conducted in the Citarum watershed with the geographical location at coordinates  $106^{\circ}57'50.869''$  –  $107^{\circ}56'59.669''$  dan  $5^{\circ}54'53.468''$  –  $7^{\circ}14'38.517''$ . Gravity data obtained are from UCSD TOPEX satellite imagery. TOPEX has been used by many researchers (Bansal et al., 2005; Kurniawan, 2012; Noréus et al., 1997; Paolo & Molina, 2010). TOPEX UCSD has precision per unit second with a distance of 30-40 mm with a gravitational field resolution of 4-6 mGal. The basic concept of gravimetric satellites is detecting changes in Earth's gravity field by monitoring changes in distance that occur between pairs of 2 gravimetric satellites in their orbits (Chambers, 2015). The two satellites travel along an orbit path of approximately 220 kilometers between one and the second satellite. These satellites are connected to the exact distance by a K-band microwave link, and how significant the change is better than 1 micrometer per second with accuracy.

Both satellites feature a star camera and an accelerometer to see the exact movement and altitude because of the satellite's non-gravity force. In the meantime, a GPS installed in the two pairs of satellites determines satellite positions and speed. The accuracy of the gravimetric satellite is 1 cm in height, and one mGal in gravity anomalies is even less on the ground surface on the spatial grid of 100 kilometers (Chelton

et al., 2001). The data obtained in the form of the free air anomaly values is then processed by terrain correcting and correction of bougers to generate a cross-section of regional anomalies and remaining anomalies. Finally, fortified fault structure estimation is done through quality analysis, namely sub-surface structure modeling.

### Complete Bouguer Anomaly Gravity

According to Martín et al. (2011), Bouguer gravity anomalies were calculated with the equation that defines from Heiskanen and Moritz (1967), Figure 1.:

$$\Delta g^{Bouguer} = \Delta g^{Free-air} - B + C \quad (1)$$

Terrain correction tools provided by Geosoft Oasis Montaj were used to obtain the C value (Terrain Correction). B is the Bouguer correction that can be calculated using this equation:

$$B = 2\pi K\rho H \quad (2)$$

$\rho$  is the crustal density ( $2.67 \text{ gr/cm}^3$ ) used in the Bouguer correction and H is the height of the point in meters and K were universal gravitational constant. Complete Bouguer Anomaly values have been gridded with the Minimum Curvature Gridding (MCG) module provided by Geosoft Oasis Montaj software. The minimum curvature gridding method used by Briggs (1974) was first employed according to Martínez-moreno et al. (2015). The algorithm was later drawn up by Swain (1976) and modified by Webring (1981). It is based on a two-dimensional differential equation for disassembling a thin sheet, which is equivalent to a third-

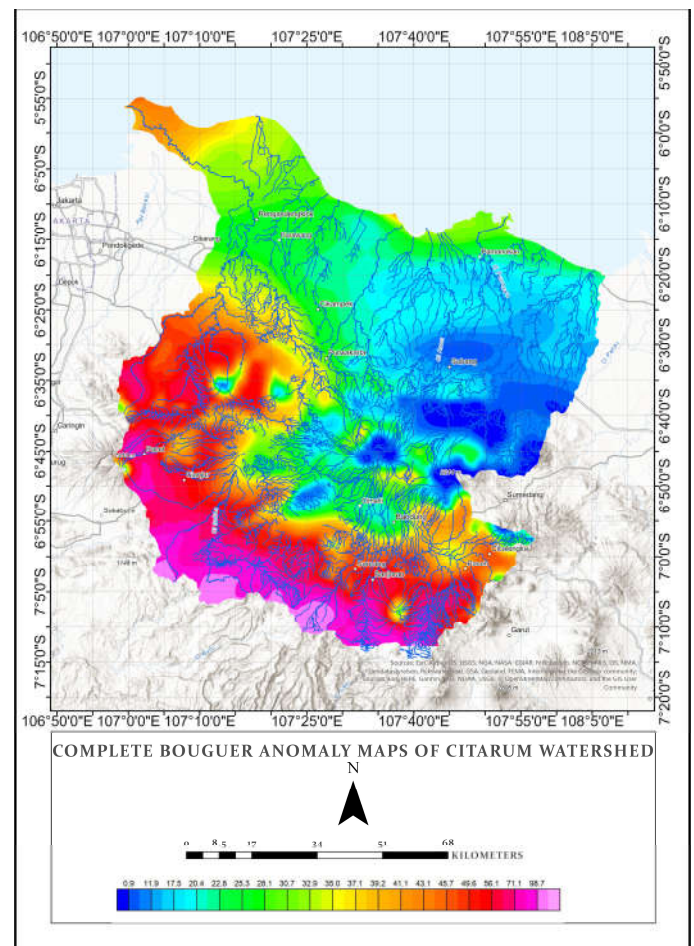


Figure 1. Complete Bouguer Anomaly Gravity

order spline, under the influence of the point forces (Briggs, 1974). The gravity measurements were filtered over the field of study to calculate the regional trend (Mickus et al., 1991). The Complete Bouguer anomaly (CBA) value is the regional and residual anomaly accumulation value. Butterworth filter was used to distinguish between regional and residual anomaly.

**Butterworth Filter**

Butterworth filters are known as maximally flat filters, according to Ellis (2012), because they have the sharpest possible roll-off without causing a peak in the Bode plot. The second-order Butterworth filter is the two-pole filter with a damping ratio of 0.707. Butterworth filters are used because of their ability to peak in control systems. It is conservative in removing all peaks from the filter. Allowing specific peaks may be advantageous as it allows an equal attenuation of lower frequencies with more minor phase delay. The Butterworth filter is nevertheless a natural choice in order to organize the many pole higher-order filter systems.

This is the equation for odd orders of butterworth:

$$T(s) = \left( \frac{\omega_N}{s + \omega_N} \right) \prod_1^{(M-1)/2} \left( \frac{\omega_N^2}{s^2 + 2 \cos(\theta_i) \omega_N s + \omega_N^2} \right), \theta_i = i \times 180/N \tag{3}$$

$\Pi$  it means the result (product),  $M$  its mean the orders of filter

**Lineament**

Various techniques have been developed to obtain the terrain's linear characteristics and geomorphology (Nur et al., 2017). This paper shows an automatic lineament with

edge enhancement, followed by a sharpening technique that gives the best outcome of non-human eye lines, and applies the PCI Geomatica V9.1 Line module to recognized lineaments. Edge-sharpening improvements make for analysis forms and details (Richards, 1986). The PCI Geomatics software package used edge sharpening. Finally, for automatic lineament extraction, final images from the study area were used. PCI geomatica have features of edge detection, thresholding, and curve extraction processes are part of the lineament extraction algorithm. There is some default parameter in the LINE feature of Geomatica software: RADI (Radius of filter in pixels), GTHR(Threshold for edge gradient), LTHR(Threshold for curve length), FTHR (Threshold for fitting line error), ATHR(Threshold for angular difference), and DTHR(Threshold for linking distance) (PCI Geomatica, 2001). Multiple line maps with different threshold values were generated. Those lineaments were considered default lines, and the best threshold values were selected (below). In order to determine threshold values, general characteristics were taken into account, such as length, curvature, segmentation, separation, and so on.

**3. Result and Discussion**

The range of gravity values is about 14.1 to 90.9 mGal (Figure 1). The lowest anomaly value is 14.1 mGal and the highest is 90.9 mGal. In general, the gravity anomaly values can be categorized into low, medium, high and very high anomaly values. Low anomaly value in the range of 14.1 to 25.6 mGal which is indicated in dark blue to light blue. The anomaly value is about 25.6 to 43.2 mGal which is indicated in light green to dark brown. The high anomaly is about 43.2 to 90.9 mGal, which is indicated by dark red to light red. The

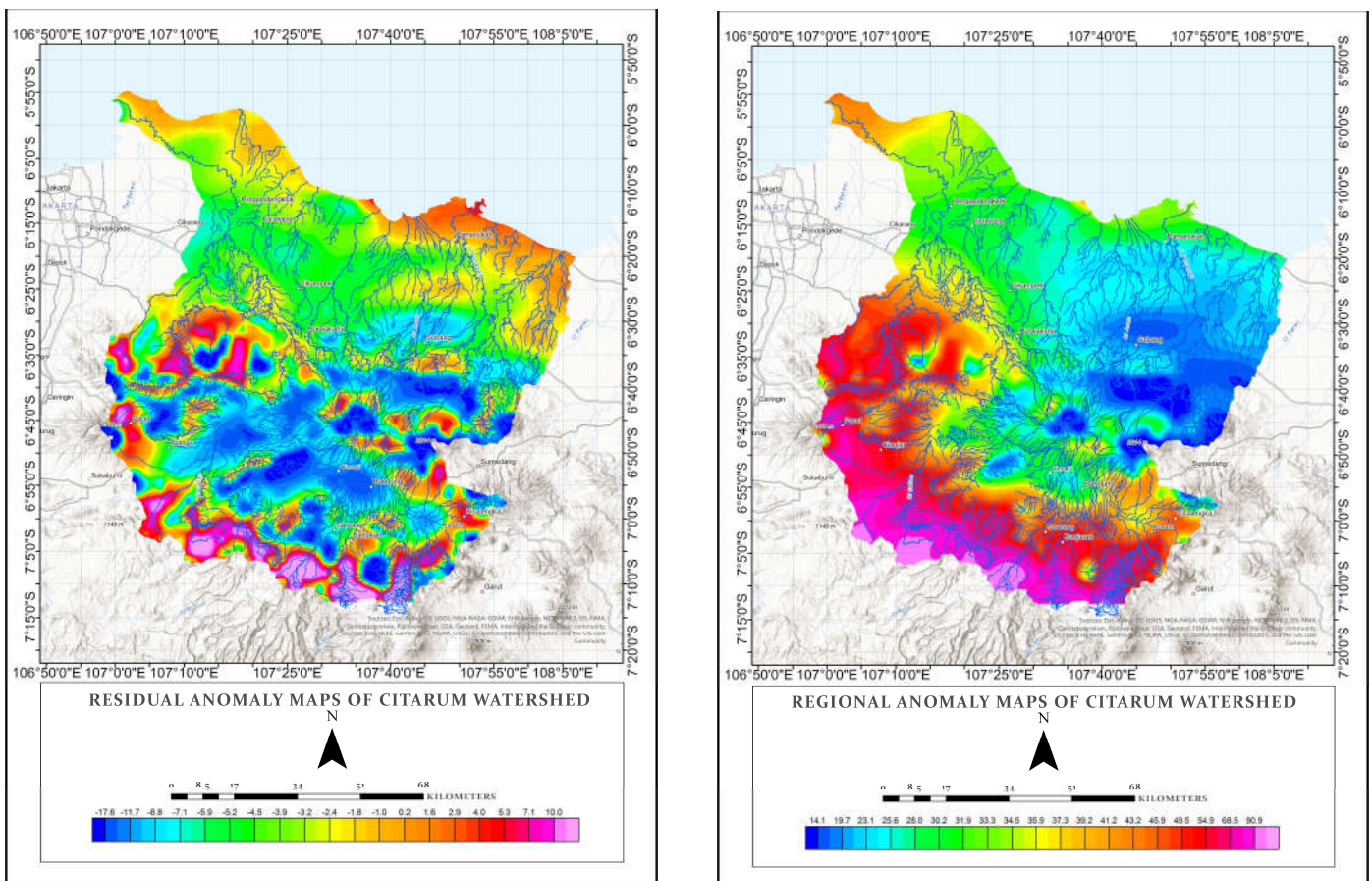


Figure 2. Gravity anomaly (a) Residual (b) Regional

residual anomaly map Figure 2(a), shows that the range of gravity values is about 17.6 to 10 mGal. The lowest anomaly value is -17.6 mGal and the highest is 10 mGal.

Regional anomaly maps reflect intense subsurface conditions. In contrast, residual anomaly maps describe the shallow sub-surface information. Based on regional anomaly maps, the southern part of the study area tends to be dominated by high anomaly values (43.2 to 90.0 mGal). The northwestern study area also has a high anomaly, but not higher than the southern part of the study area (30 mGal to 50 mGal). Medium anomaly zones tend to fill the central part of Citarum Watershed, northwestern and northeastern part of the regional anomaly map (28 mGal to 35.8 mGal). Low

anomaly values lie in the eastern part of the regional anomaly map with a range of 14.1 mGal to 32.1 mGal.

There is a slight difference in regional and residual anomaly patterns in the study area. Denser rocks cause the highest anomaly value in the southern part of the study area beneath the surface. Anomaly horst patterns can also be seen in the northern part of regional and residual anomaly maps. These horst patterns geometrically comprise the gravity of the basin anomaly. The existence of volcanic in the northern part dramatically affects the condition of the existing gravity anomaly. Low anomaly values in the middle of the watershed correlate with the presence of sedimentary layers with densities below the upstream (southern) area. Although the northern and southern parts have similar anomalous values, they are different, as is the case with rock genes that cause differences between the two regions.

To analyze lineament patterns was carried out using PCI Geomatica's LINE Algorithm with the following parameters, Figure 3. Filter Radius (pixels) = 10; Edge Gradient Threshold = 100; Curve Length Threshold (Pixels) = 30; Line Fitting Threshold Error (3); Angular Difference Threshold (Degrees) = 30; Linking Distance Threshold (Pixels) = 20. All parameters are the default parameters of the LINE PCI Geomatica 2017 module/algorithm.

The results (Figure 4.) show that the southern part tends to have a high enough lineament density compared to the northern part of the study area. Fractures might cause this in volcanic rocks that have a high enough density; this is at the same time concern about tectonic activity in the southern part of the Citarum watershed.

The rose diagram (Figure 5. ) shows the direction of the lineament is dominated by the northwest-southeast

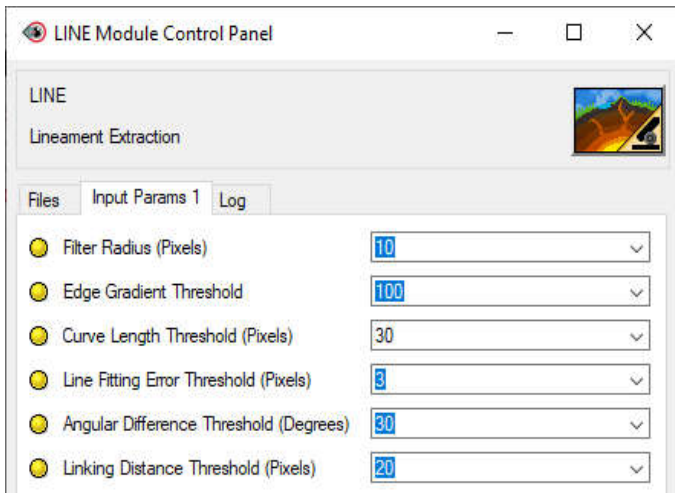
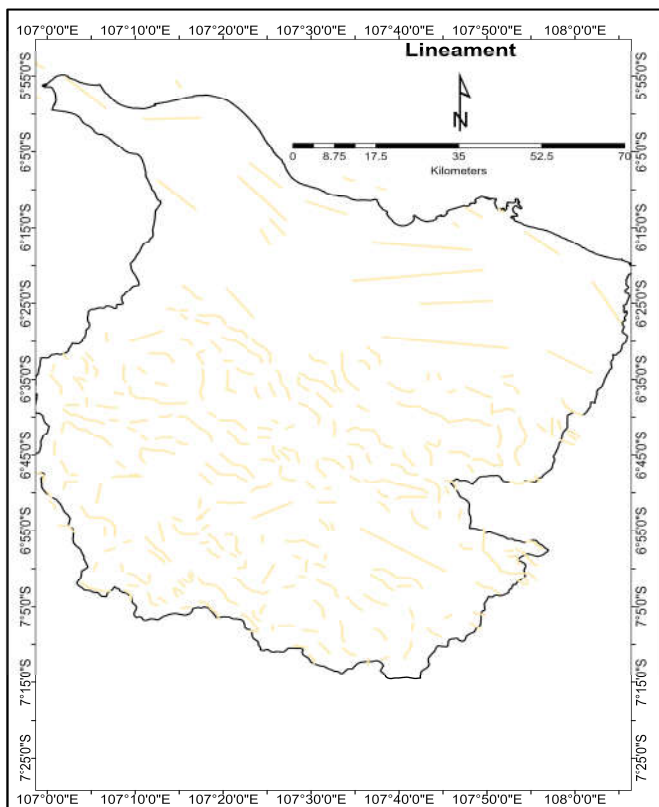
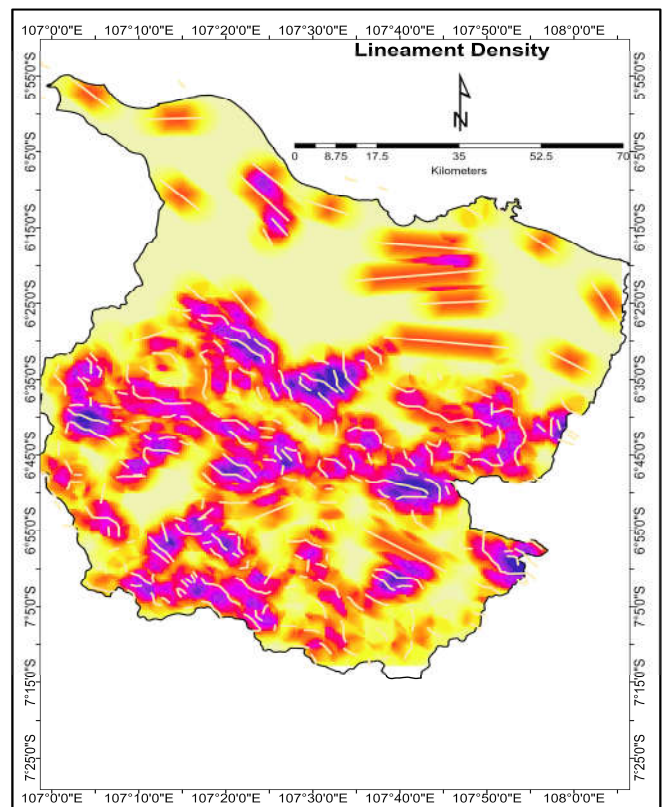


Figure 3. LINE Parameter



(a)



(b)

Figure 4. (a) Lineament pattern (b) Lineament density of the Study Area

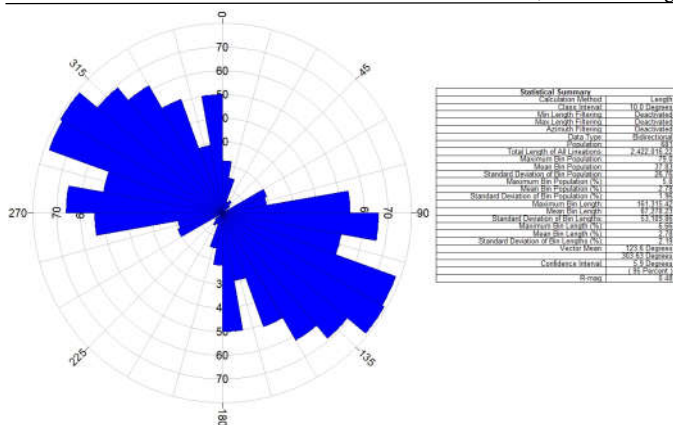


Figure 5. Rose Diagram

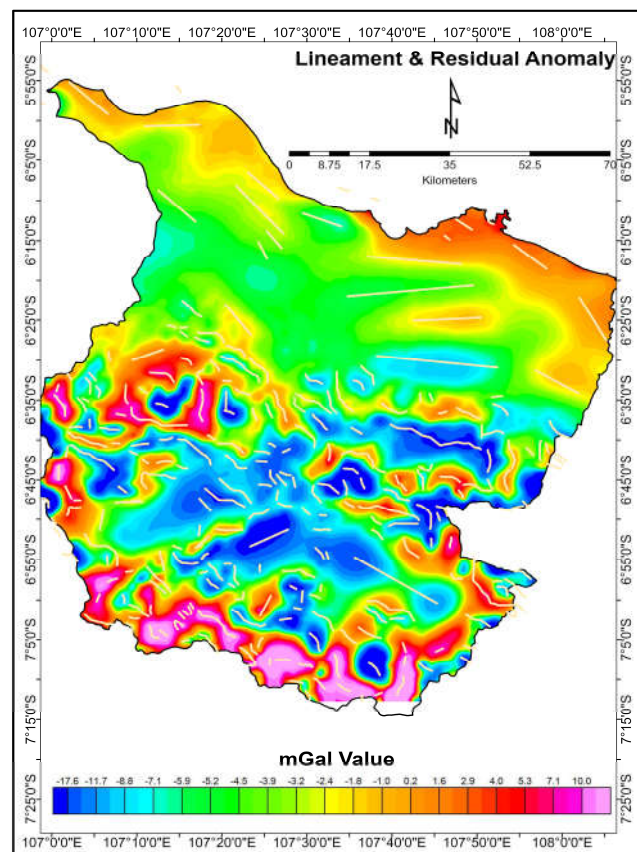


Figure 6. Overlay of Gravity and Lineament features

lineament direction, and the subdominant directions were in N-S. This direction might be influenced by regional lineament patterns in West Java that tend to be northwest-southeast direction, where the subduction zone is located relatively on the south coast of Java, leading to the north of the island of Java (subduction zone).

**4. Conclusion**

Based on regional anomaly maps, the range of gravity values is about 14.1 to 90.9 mGal. The lowest anomaly value is 14.1 mGal and the highest is 90.9 mGal. The residual anomaly map, shows that the range of gravity values is about 17.6 to 10 mGal.

The lowest anomaly value is -17.6 mGal and the highest is 10 mGal. The southern part of the study area tends to be dominated by high anomaly values ( 43.2 to 90.0 mGal). Medium anomaly zones tend to fill the central part of Citarum Watershed, northwestern and northeastern part of the regional anomaly map (28 mGal to 35.8 mGal). Low anomaly values tend to be lies in the eastern part of the regional anomaly map with a range of values of 14.1 mGal to 32.1 mGal.

There is a slight difference in regional and residual anomaly patterns at the study area. The highest anomaly value in the southern part of the study area is caused by denser rocks beneath the surface. The southern part tends to have a high enough lineament density when compared to the northern part of the study area. This might be caused by the presence of fractures in volcanic rocks which have a high enough density, this is at the same time concern about tectonic activity in the southern part of the Citarum watershed. The rose diagram shows the direction of the lineament is dominated by the northwest-southeast lineament direction and the subdominant directions were in N-S. This direction might be influenced by regional lineament patterns in West Java that tend to be northwest-southeast direction.

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