



## Synergetic use of IASI and TROPOMI space borne sensors for generating a tropospheric methane profile product

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**Abstract.** The thermal infrared nadir spectra of IASI (Infrared Atmospheric Sounding Interferometer) are successfully used for retrievals of different atmospheric trace gas profiles. However, these retrievals offer generally reduced information about the lowermost tropospheric layer due to the lack of thermal contrast close to the surface. Spectra of scattered solar radiation observed in the near and/or short wave infrared, for instance by TROPOMI (TROPOspheric Monitoring Instrument) offer higher sensitivity near ground and are used for the retrieval of total column averaged mixing ratios of a variety of atmospheric trace gases. Here we present a method for the synergetic use of IASI profile and TROPOMI total column data. Our method uses the output of the individual retrievals and consists of linear algebra a posteriori calculations (i.e. calculation after the individual retrievals). We show that this approach is largely equivalent to applying the spectra of the different sensors together in a single retrieval procedure, but with the substantial advantage of being applicable to data generated with different individual retrieval processors, of being very time efficient, and of directly benefiting from the high quality and most recent improvements of the individual retrieval processors.



We demonstrate the method exemplarily for atmospheric methane ( $\text{CH}_4$ ). We perform a theoretical evaluation and show that the a posteriori combination method yields a total column averaged  $\text{CH}_4$  product ( $\text{XCH}_4$ ) that conserves the good sensitivity of the corresponding TROPOMI product while merging it with the upper tropospheric and lower stratospheric (UTLS)  $\text{CH}_4$  partial column information of the corresponding IASI product. As consequence, the combined product offers in addition sensitivity for the tropospheric  $\text{CH}_4$  partial column, which is not provided by the individual TROPOMI nor the individual IASI product. The theoretically predicted synergetic effects are verified by comparisons to  $\text{CH}_4$  reference data obtained from collocated  $\text{XCH}_4$  measurements at six globally distributed TCCON (Total Carbon Column Observing Network) stations,  $\text{CH}_4$  profile measurements made by 24 individual AirCore soundings, and lower tropospheric  $\text{CH}_4$  data derived from continuous ground-based in-situ observations made at two nearby Global Atmospheric Watch (GAW) mountain stations. The comparisons clearly demonstrate that the combined product can reliably detect  $\text{XCH}_4$  signals and allows to distinguish between tropospheric and UTLS  $\text{CH}_4$  partial column averaged mixing ratios, which is not possible by the individual TROPOMI and IASI products. We find indications of a weak positive bias of about +1% of the combined lower tropospheric data product with respect to the references. For the UTLS  $\text{CH}_4$  partial columns we find no significant bias.

## 25 1 Introduction

Measurements from different ground- or satellite-based sensors target at the observations of the same atmospheric parameters (e.g. the same trace gases), but with different characteristics (e.g. sensitivities for different vertical regions). Often the different sensors use different observation geometries (limb scanning, nadir, solar light reflected at the Earth's surface) and/or different spectral regions (e.g. UV/vis, near infrared, thermal infrared, microwave). Dedicated experts and efforts are needed to develop retrieval techniques that are specifically optimized for an individual sensor. An algorithm that uses coincident measurements of all the different sensors for a multispectral approach for the optimal estimation of the atmospheric state would well exploit the synergies of the different observation geometries and spectral regions and thus allows for detecting the atmospheric state in more detail than achievable by individual optimal estimation retrievals.

Cuesta et al. (2013) present such 'super retrieval', which performs an optimal estimation of atmospheric ozone ( $\text{O}_3$ ) applying the spectra measured by the thermal nadir sensor IASI (Infrared Atmospheric Sounding Interferometer) and the UV/vis sensor GOME (Global Ozone Monitoring Experiment). Their publication shows that using the multispectral approach allows the detection of lower tropospheric  $\text{O}_3$ , which is not possible by an individual usage of the IASI and GOME spectra. Costantino et al. (2017) showed that the quality of this multispectral lower tropospheric  $\text{O}_3$  product can be further improved with improved thermal nadir and UV/vis sensors.

The development of these 'super retrievals' requires experts in different remote sensing techniques to work closely together. Furthermore, as soon as measurements from a new sensor become available (or as soon as sensors are modified/improved) such super retrieval processors have to be adapted accordingly, i.e. continuous collaborative retrieval developments are required. While this is certainly possible, it might be not the most efficient way. The optimal exploitation of the already available individual retrieval results would be much less computationally expensive than running dedicated combined retrievals.



45 Efficient a posteriori combination methods of individual retrieval products are currently of high interest, because the steadily  
increasing amount of available satellite data offers more and more possibilities for synergetic use. Worden et al. (2015) com-  
bines the thermal and near infrared observations of methane ( $\text{CH}_4$ ) made by TES (Thermal Emission Spectrometer) and  
GOSAT (Greenhouse gas mOnitoring SATellite), respectively, by performing approximative calculations and with a focus on  
monthly mean data. Data aggregation is necessary due to the reduced temporal and horizontal coverage of TES and GOSAT  
50 and their imperfect collocation. The method of Ceccherini et al. (2009) focuses on avoiding uncertainties in the combined  
product due to constraints and vertical interpolation, which might be a problem when combining two vertically resolved profile  
products generated applying different constraints. However, this method needs the Jacobians (changes in the spectra caused by  
changes in the atmospheric state) of the retrieved products, which are large matrices that are generally not stored in operational  
retrieval output files. Cortesi et al. (2016) applied this approach for combining the thermal infrared MIPAS-STR (Michelson  
55 Interferometer for Passive Atmospheric Sounding - STRatospheric aircraft) and microwave MARSCHALS (Millimetre-wave  
Airborne Receivers for Spectroscopic Characterisation in Atmospheric Limb Sounding) aircraft-based remote sensing products  
of  $\text{O}_3$ , nitric acid ( $\text{HNO}_3$ ), water vapour ( $\text{H}_2\text{O}$ ), and atmospheric temperature.

Here, we propose to generate a multi-sensor optimal estimation  $\text{CH}_4$  profile product by simple a posteriori calculations using  
available outputs of IASI and TROPOMI (Tropospheric Monitoring Instrument) retrievals. The method allows a computation-  
60 ally very efficient generation of global daily maps of the combined data product and only needs the individually retrieved states,  
averaging kernels and noise covariances provided by the respective remote sensing experts in the context of their standard re-  
trieval work. The proposed method can be used flexibly for combining measurement information of different satellite sensors.  
For most cases the method approximates closely a dedicated combined optimal estimation retrieval that uses the combined  
IASI and TROPOMI spectra as input.

65 The reliable and global detection of tropospheric  $\text{CH}_4$  independently from  $\text{CH}_4$  at higher altitudes can lead to an improved  
understanding of the  $\text{CH}_4$  cycle. Respective data allow a more direct investigation of the  $\text{CH}_4$  boundary layer source and sink  
signals than total column averaged mixing ratios ( $\text{XCH}_4$ ) provided globally for instance by GOSAT (e.g. Parker et al., 2020)  
or TROPOMI (Lorente et al., 2020). This is because  $\text{XCH}_4$  signals are strongly affected by vertical shifts of the tropopause  
altitude, i.e. their use for investigating  $\text{CH}_4$  absorption and release at ground depends on the correct consideration of the  
70 tropopause altitude by model simulations (Pandey et al., 2016).

This manuscript is organised as follows. Section 2 briefly discusses the used IASI and TROPOMI products (generated by  
two individual retrievals), presents the equations for the optimal a posteriori combination of the two independent retrieval  
outputs, and performs a theoretical evaluation of the individual and combined products. Section 3 validates the total column  
and tropospheric and UTLS (upper tropospheric/lower stratospheric) partial column products obtained by the individual IASI  
75 and TROPOMI retrievals and by the a posteriori combination. Section 4 discusses biases of the products and its latitudinal  
consistency. Section 5 resumes the results of our study and briefly discusses upcoming possibilities. Furthermore, in Appendix  
A we provide extensive background information on the theory of our a posteriori combination method and we show that the  
method is equivalent to performing a full multispectral optimal estimation retrieval. Appendix B introduces the operator for



transferring logarithmic scale differentials into linear scale differentials. Appendix C presents the operators used for converting  
80 vertical profile data into total and partial column data.

## 2 A posteriori combination of MUSICA IASI CH<sub>4</sub> and TROPOMI XCH<sub>4</sub> products

In this section we present the method for combining CH<sub>4</sub> profiles derived from IASI thermal nadir spectra and XCH<sub>4</sub> data obtained from the analysis of the near and short wave infrared spectra measured by TROPOMI.

The TROPOMI XCH<sub>4</sub> data used in this study are generated by the RemoTeC algorithm (Butz et al., 2011), which is used for  
85 the operational processing of Sentinel 5 Precursor/TROPOMI XCH<sub>4</sub> data (Hu et al., 2016; Hasekamp et al., 2019; Landgraf et al., 2019). The current operational processing algorithm version is 1.2.0. Here we use data from version 1.3.0 with the improvements as presented and validated in Lorente et al. (2020). It is foreseen to become the operational processing version with the operational processor update in April 2021. The TROPOMI output files provide the XCH<sub>4</sub> data together with the used a priori data (constructed from simulations of the global chemistry-transport model TM5, Krol et al., 2005), the column  
90 averaging kernels, and the error values. In order to filter out data with reduced quality, here we only use TROPOMI data, for which the variable `qa_value` has values larger than 0.5. This filter is consistent to the filtering as suggested in Table A1 of Lorente et al. (2020).

As IASI CH<sub>4</sub> data product we use the data generated by the retrieval processor MUSICA (MULTi-platform remote Sensing of Isotopologues for investigating the Cycle of Atmospheric water, a European Research Council project between 2011 and 2016).  
95 The MUSICA IASI data full retrieval product encompasses trace gas profiles of H<sub>2</sub>O, the HDO/H<sub>2</sub>O ratio, N<sub>2</sub>O, CH<sub>4</sub>, and HNO<sub>3</sub>. The data have been validated in several previous studies (Schneider et al., 2016; Borger et al., 2018; García et al., 2018), and it has been shown that the CH<sub>4</sub> product can very well detect the CH<sub>4</sub> signals originating in the upper troposphere/lower stratosphere. MUSICA IASI data using processor versions 3.2.1 and 3.3.0 are currently available for the 2014 to 2020 time period and are presented in Schneider et al. (2021). This MUSICA IASI data set is best suited for a posteriori data reuse (e.g.  
100 Diekmann et al., 2021), because in addition to the retrieved trace gas profiles it contains full information on retrieval settings (a priori states and constraints) and on averaging kernel and error covariance matrices. In order to ensure highest MUSICA IASI data quality, here we require the flag variable `musica_fit_quality_flag` to be set to 3 (the spectral fit of the MUSICA IASI retrieval has a good quality and the spectral residuals are close to the instrumental noise level). Furthermore, we only use MUSICA IASI data for which the flag variable `eumetsat_cloud_summary_flag` is set to 1, which guarantees that the  
105 IASI instrumental field of view is cloud-free.

A particularity of the MUSICA IASI processor is that the trace gas inversions are performed on a logarithmic scale. In Appendix B of Schneider et al. (2021) it is shown that the MUSICA IASI retrieval can be considered as a moderately non-linear problem, in particular if the differentials (averaging kernels and covariances) are used on the logarithmic scale. In the following equations we take special care on the correct usage of the corresponding logarithmic scale differentials. Nevertheless,  
110 all equations are also applicable for retrievals made on linear scale by replacing in the following the operator **L** by the identity operator.



## 2.1 Calculation of the combined state vector

For this study we use the CH<sub>4</sub> a priori profile as provided by the TROPOMI product as the common a priori for all products (these are simulations of the global chemistry-transport model TM5, Krol et al., 2005). For this purpose we modify the  
 115 MUSICA IASI product and bring it in line with the TROPOMI a priori profile choice by applying Eq. (A16).

For updating the IASI CH<sub>4</sub> profile product using the TROPOMI XCH<sub>4</sub> observation we apply a Kalman filter and obtain the combined CH<sub>4</sub> state as :

$$\hat{\mathbf{x}}_C^l = \hat{\mathbf{x}}_I^l + \mathbf{L}^{-1} \mathbf{m} [\hat{x}_T - \mathbf{a}_T^{*T} \hat{\mathbf{x}}_I]. \quad (1)$$

Here the vector  $\hat{\mathbf{x}}_I$  and scalar  $\hat{x}_T$  are the MUSICA IASI CH<sub>4</sub> profile and the TROPOMI XCH<sub>4</sub> column averaged products.  
 120 The row vector  $\mathbf{a}_T^{*T}$  is the total column averaged mixing ratio kernel of the TROPOMI product interpolated to the vertical grid used by the MUSICA IASI processor (for details on the interpolation see Appendix C). The state vector  $\hat{\mathbf{x}}_C^l$  represents the combined CH<sub>4</sub> profile product in logarithmic scale (i.e. the MUSICA IASI CH<sub>4</sub> data updated with the TROPOMI XCH<sub>4</sub> observation). The superscript <sup>l</sup>, used with  $\hat{\mathbf{x}}_C^l$  and  $\hat{\mathbf{x}}_I^l$  indicates the use of the logarithmic scale. Here and in the following we will mark scalars, vectors or matrix operators that are in logarithmic scale by the superscript <sup>l</sup>. The matrix  $\mathbf{L}$  is the operator for  
 125 the transformation of differentials or small changes (as given by averaging kernels or error covariances) from the logarithmic to the linear scale (for more details see Appendix B).

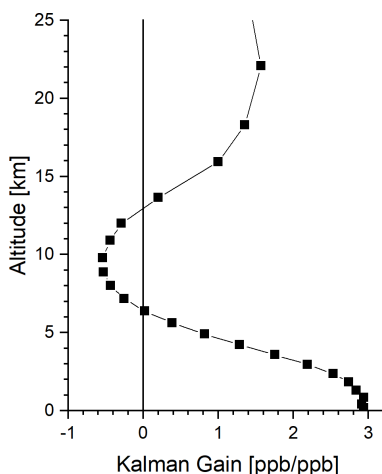
The column vector  $\mathbf{m}$  is the Kalman gain operator and it is given by:

$$\mathbf{m} = \mathbf{L} \mathbf{S}_{\hat{\mathbf{x}}_I}^l \mathbf{L}^T \mathbf{a}_T^* (\mathbf{a}_T^{*T} \mathbf{L} \mathbf{S}_{\hat{\mathbf{x}}_I}^l \mathbf{L}^T \mathbf{a}_T^* + S_{\hat{x}_T, n})^{-1}, \quad (2)$$

with the matrix  $\mathbf{S}_{\hat{\mathbf{x}}_I}^l$  and the scalar  $S_{\hat{x}_T, n}$  being the logarithmic scale retrieval noise error covariance of the MUSICA IASI CH<sub>4</sub>  
 130 product and the noise error variance of the TROPOMI XCH<sub>4</sub> product, respectively. The vector operator  $\mathbf{a}_T^*$  is the transpose of the TROPOMI column averaging kernel, i.e.  $\mathbf{a}_T^* = (\mathbf{a}_T^{*T})^T$ .

Except for the logarithmic scale transformation, the Eqs. (1) and (2) are analogous to Eqs. (A9) and (A10). As demonstrated in Appendix A2 this kind of Kalman filter application is equivalent to an optimal estimation retrieval that uses a combined IASI and TROPOMI measurement vector. The application of this Kalman filter is possible because the MUSICA IASI data  
 135 are provided with full information on a priori states, constraints, error covariances, and averaging kernels (Schneider et al., 2021), and because the TROPOMI data are provided together with their a priori state, averaging kernel, and retrieval noise error (Lorente et al., 2020).

The Kalman Gain according to Eq. (2) describes how differences between the MUSICA IASI and TROPOMI XCH<sub>4</sub> product are used to update the MUSICA IASI CH<sub>4</sub> profile. An example for a Kalman Gain operator is depicted in Fig. 1. It shows that  
 140 a positive difference of +1 ppb of  $[\hat{x}_T - \mathbf{a}_T^{*T} \hat{\mathbf{x}}_I]$  will lead to a combined CH<sub>4</sub> profile product that has been modified with respect to the MUSICA IASI CH<sub>4</sub> product by almost +3 ppb in the lowermost troposphere, by about −0.5 ppb at 10 km, and by about +1 ppb above 20 km.



**Figure 1.** Visualisation of a Kalman Gain operator for optimally combining TROPOMI XCH<sub>4</sub> data with MUSICA IASI CH<sub>4</sub> profile data. This is the column vector  $\mathbf{m}$  according to Eq. (2). The example shown is for a late summer atmosphere (27 September 2018) over Central Europe.

## 2.2 Collocation of TROPOMI and IASI observations

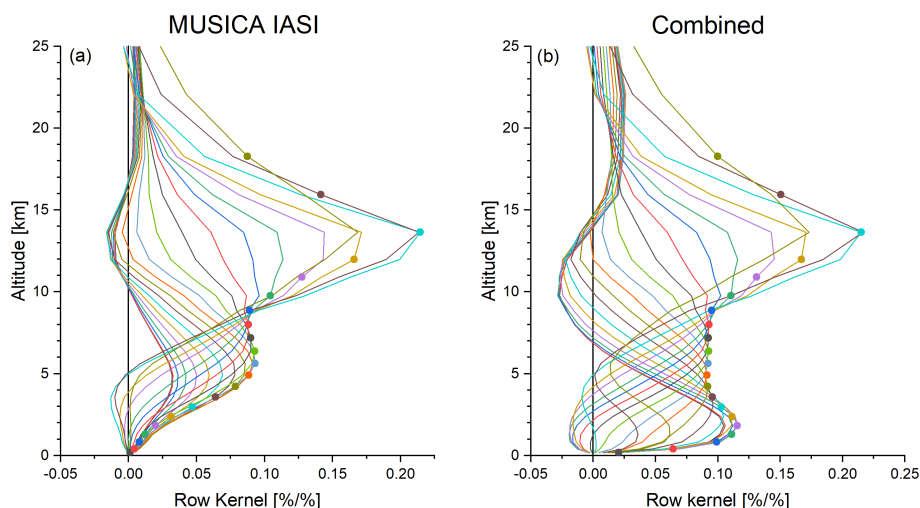
As temporal collocation criterion we use four hours, for a valid horizontal collocation the centres of the TROPOMI and IASI  
 145 ground pixels must be closer than 50 km, and the difference between the ground pressure at the TROPOMI and IASI ground  
 pixels must be within 50 hPa. Generally multiple TROPOMI/IASI ground pixel pairs fulfill the aforementioned criteria. In  
 such case we use the pair with the smallest spatial distance, which we define as the Euclidean distance that considers a norm  
 of 40 km for the horizontal distance and a norm of 5 hPa for the vertical distance. TROPOMI and IASI observations already  
 150 belonging to a valid collocation pair are disregarded for further collocations. This ensures that an individual IASI or TROPOMI  
 observation can only belong to a single collocation pair. The possible small difference in the TROPOMI and IASI ground pixel  
 pressures is taken into account by correcting the TROPOMI XCH<sub>4</sub> values, respectively.

## 2.3 Sensitivity and vertical resolution

In this section we compare the vertical representativeness of the individual retrieval products with those achieved when combin-  
 155 ing the two retrieval products. According to Eq. 1 the averaging kernels for the combined data product can be calculated  
 as:

$$\mathbf{A}_C^1 = \mathbf{A}_I^1 + \mathbf{L}^{-1} \mathbf{m} (\mathbf{a}_T^{*T} - \mathbf{a}_T^{*T} \mathbf{L} \mathbf{A}_I^1 \mathbf{L}^{-1}) \mathbf{L}. \quad (3)$$

Here  $\mathbf{A}_I^1$  and  $\mathbf{A}_C^1$  are the logarithmic scale averaging kernels of the MUSICA IASI CH<sub>4</sub> product and of the combined product  
 (the MUSICA IASI CH<sub>4</sub> product after being updated with the information provided by the TROPOMI XCH<sub>4</sub> data product),  
 respectively. These are the kernels for the profile products represented in *nal* (*nal*: number of atmospheric levels) levels,



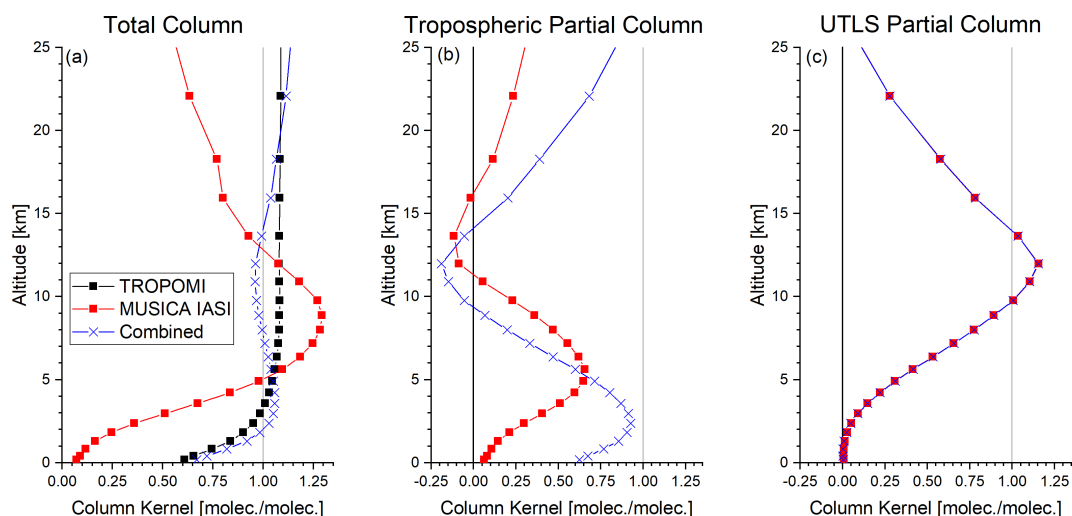
**Figure 2.** Logarithmic scale row kernels for (a) the MUSICA IASI and (b) the combined product for the same late summer observations as used in the context of Figs. 1 and 3. The symbols mark the kernel values at the nominal altitude.

160 i.e. they are matrices of dimension  $nal \times nal$ . Logarithmic scale kernels are also called fractional or relative averaging kernels (e.g. Keppens et al., 2015).

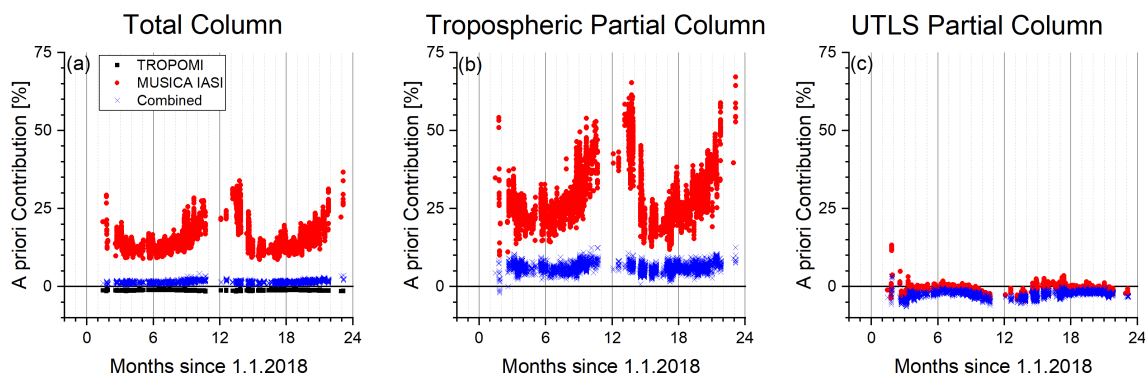
Figure 2 depicts the rows of typical averaging kernels for the MUSICA IASI product (panel a) and the combined data product (panel b). Adding the information provided by TROPOMI clearly improves the sensitivity in the lower troposphere: for the MUSICA IASI product the lower tropospheric kernels generally peak at the upper limit of the lower troposphere (at about 5 km  
165 a.s.l.). For the combined product these peak values are obtained at significantly lower altitudes (at about 2.5 km a.s.l.). In the upper troposphere/lower stratosphere (UTLS) we see no significant difference between the kernels.

In this work we focus on the total column and the partial columns between the surface and 6 km a.s.l. (the tropospheric partial column) and between 6 km a.s.l. and 20 km a.s.l. (the UTLS partial column). The total and partial column kernels are calculated from  $A_I^1$  and  $A_C^1$  by their transformation on linear scale (see Appendix B) and the vertical resampling as explained  
170 in Appendix C. Figure 3 depicts the total and partial column kernels corresponding to the row kernels of Fig. 2.

Total column amount kernels are available for all three products (see Fig. 3a): the TROPOMI, the MUSICA IASI, and the combined product. The TROPOMI kernel is close to unity for all altitudes, documenting the good sensitivity for  $CH_4$  at all altitudes. The combined total column amount kernel is very similar to the respective TROPOMI kernel (even correcting the overshoot at 4-6 km) and means that the combined retrieval product does also well reflect the actual atmospheric total column  
175 amounts. The MUSICA IASI kernel has relatively low values in the lower troposphere and above 15 km, only in the UTLS region the kernel values are between 0.75 and 1.25. This means that MUSICA IASI can actually not well detect total column amounts, because it lacks sensitivity in the lower troposphere. The altitude regions where the MUSICA IASI product has reduced sensitivities are the regions where TROPOMI's total column information has the strongest impact on the combined product (see Fig. 1).



**Figure 3.** Total column amount and partial column amount kernels corresponding to the TROPOMI, MUSICA IASI, and combined product for the same late summer observation as used in Figs. 1 and 2: (a) total column amount kernels; (b) lower tropospheric partial column amount kernels, surface - 6 km a.s.l.; (c) upper tropospheric/lower stratospheric (UTLS) partial column amount kernels, 6 - 20 km a.s.l.



**Figure 4.** Time series of the relative contribution of the a priori data to the retrieved products (example for Central Europe). Black squares: TROPOMI; red dots: MUSICA IASI; blue crosses: Combined product. (a) Total column; (b) tropospheric partial column; (c) UTLS partial column.

180 Partial column amount kernels are only available for profile products, i.e. the MUSICA IASI and the combined product  
 (MUSICA IASI updated with information from TROPOMI). Figure 3b shows tropospheric partial column amount kernels. For  
 the MUSICA IASI product we observe values that are generally lower than 0.5. The highest values are achieved around 6 km  
 a.s.l., i.e. at the upper boundary of the vertical layer we defined as the tropospheric partial column. The kernel of the combined  
 product shows a good sensitivity with peak values of almost 0.95 at 2.5 km a.s.l. and values above 0.75 for almost all altitudes  
 185 between the surface and 6 km a.s.l.





UTLS partial column amount kernels are depicted in Figure 3c. The values are close to unity for most of the altitudes that we attributed to the UTLS layer (altitudes between 6 km and 20 km a.s.l.). There is almost no difference between the MUSICA IASI and the combined kernels, meaning that the information provided by TROPOMI has almost no effect on the UTLS partial column, which is because the MUSICA IASI product is already very sensitive to this altitude region.

190 According to Eqs. (A1) and (A3) for the MUSICA IASI and combined retrieval data we can write

$$\hat{x}^l = \mathbf{A}^l \mathbf{x}^l + (\mathbf{I} - \mathbf{A}^l) \mathbf{x}_a^l, \quad (4)$$

with  $\mathbf{I}$  being the identity operator and  $\mathbf{x}^l$  the actual atmospheric state in logarithmic scale. Equation (4) reveals that the term  $(\mathbf{I} - \mathbf{A}^l) \mathbf{x}_a^l$  captures the relative contribution of the a priori to the retrieved product. The resampling of this term on total and partial columns is made according to Eq. (C6). For the TROPOMI total column averaged mixing ratios we can calculate the a priori contribution by  $(\mathbf{w}^{*T} - \mathbf{a}_T^{*T}) \mathbf{x}_a$ . For more details see Appendix C.

Figure 4 depicts the a priori contribution relative to the retrieved values for the total column, the tropospheric and UTLS partial columns. Shown are time series for measurements over Central Europe, which confirm the observations made in the context of the example kernels of Fig. 3: for the total column (Fig. 4a) the a priori contribution on the TROPOMI and the combined products are rather small and can be neglected, i.e. both products can detect total column signals. In contrast the MUSICA IASI total column product is significantly affected by the a priori data, i.e. provides no independent observation of the total column. Concerning partial column products (Fig. 4b and c) we can compare the MUSICA IASI and the combined product (the TROPOMI product has no information on the vertical distribution). The tropospheric MUSICA IASI partial column is significantly affected by the a priori, but the combined product is largely independent on the a priori data. In the UTLS both the MUSICA IASI and combined products are largely independent on the a priori data. In summary, with IASI alone we can well detect signals in the UTLS, but not in the lower troposphere. The detection of signals in both altitude regions independently from the a priori information is only possible by using the combined product.

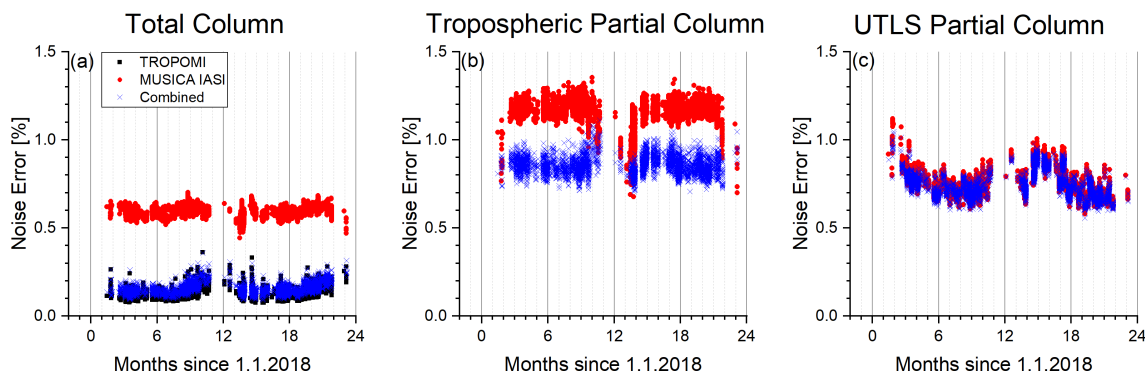
## 2.4 Retrieval noise error

In this section we compare the retrieval noise errors of the individual retrieval products with those achieved when combining the two retrieval products. According to Eq. (1) we can calculate the retrieval noise covariance matrix for the combined data product by

$$\mathbf{S}_{\hat{\mathbf{x}}_{C,n}}^1 = (\mathbf{I} - \mathbf{L}^{-1} \mathbf{m} \mathbf{a}_T^{*T}) \mathbf{L} \mathbf{S}_{\hat{\mathbf{x}}_{I,n}}^1 \mathbf{L}^T (\mathbf{I} - \mathbf{L}^{-1} \mathbf{m} \mathbf{a}_T^{*T})^T + (\mathbf{L}^{-1} \mathbf{m}) S_{\hat{\mathbf{x}}_{T,n}} (\mathbf{L}^{-1} \mathbf{m})^T. \quad (5)$$

Here  $\mathbf{S}_{\hat{\mathbf{x}}_{I,n}}^1$  is the retrieval noise covariance matrix of the MUSICA IASI retrieval. The error covariances resampled to the total and partial columns are then determined according to Appendix C. Figure 5 shows the retrieval noise errors (which are the square root values of the error variances) relative to the retrieved values for the total column and the tropospheric and UTLS partial columns.

The errors for the total columns (Fig. 5a) are generally below 0.2% for the TROPOMI product. For the MUSICA IASI product they are rather stable at about 0.6%. Concerning the combined product the retrieval noise error is very similar to the retrieval noise error of the TROPOMI data.



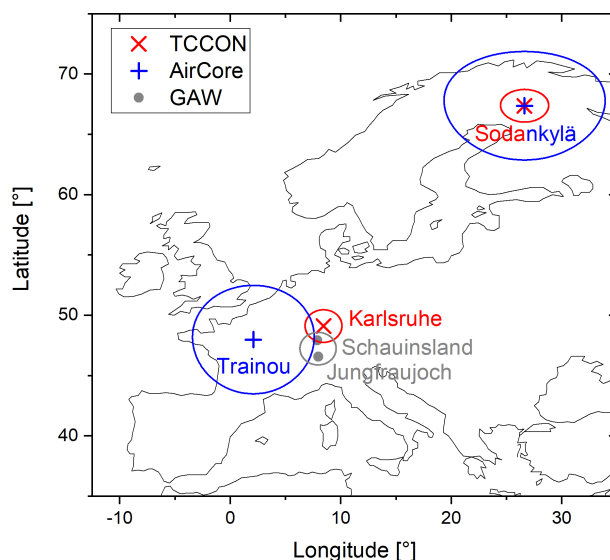
**Figure 5.** Time series of estimated relative noise error for the retrieved products (example for Central Europe). Colours are as in Fig. 4. (a) Total column; (b) tropospheric partial column; (c) UTLS partial column.

For the tropospheric partial columns (Fig. 5b) the error is in general above 1% for the MUSICA IASI product and below 1% for the combined product. For the UTLS partial columns (Fig. 5c) we observe an error of generally below 1% and no significant difference between the MUSICA IASI and the combined data products. This suggests that the error in the combined product is dominated by the error in the MUSICA IASI data, which reveals the very limited impact of the TROPOMI data on the combined UTLS data product.

### 3 Validation

In this section we compare the TROPOMI, MUSICA IASI, and combined products to different reference data products. As reference for the total column averaged mixing ratio ( $X_{CH_4}$ ) we use TCCON (Total Carbon Column Observing Network, Wunch et al., 2011) ground-based remote sensing data from six sites located in different climate zones. As reference for the total and the partial columns we use in-situ profiles measured by the AirCore system (Karion et al., 2010) at two geophysically different European locations. Furthermore, we use in-situ data measured at two nearby Central European Global Atmospheric Watch (GAW) mountain stations.

Figure 6 depicts the geographical location of the European reference observations. We consider the European TCCON stations at Sodankylä (Finland) and Karlsruhe (Germany). They are indicated as red crosses together with a circle around the stations with a radius of 150 km indicating the spatial collocation criteria: only satellite observations with ground pixels inside this circle are compared to the TCCON data. Blue crosses and circles represent the locations of AirCore measurements (at Trainou, France, and Sodankylä, Finland) and their spatial collocation criteria, respectively. Here we relax the radius of the collocation circle to 500 km in order to achieve a sufficient high number of coincidences between AirCore and satellite observations. The two grey dots indicate the locations of the two GAW stations (Jungfraujoch in Switzerland and Schauinsland in South-western Germany) and the respective grey spatial collocations circle around the middle distance point of the two stations has a radius of 150 km.



**Figure 6.** Map showing the location of the European reference measurements and the areas accepted for valid horizontal collocation. Blue crosses and circles: sites with AirCore measurements and circles with 500 km radius. Red crosses and grey dots: sites with TCCON and GAW measurements, respectively, and circles with 150 km radius.

**Table 1.** Locations of TCCON sites and references and amount of the TCCON data used in this study. "N" gives the total number of collocations with single satellite footprints and "Days" the number of days with collocations.

Name and Country	Latitude	Longitude	Altitude	Reference	N	Days
Sodankylä, Finland	67.4°N	26.6°E	190 m a.s.l.	Kivi et al. (2014); Kivi and Heikkinen (2016)	7416	112
Karlsruhe, Germany	49.1°N	8.4°E	120 m a.s.l.	Hase et al. (2015)	3261	101
Burgos, Philippines	18.5°N	120.7°E	40 m a.s.l.	Velazco et al. (2017)	58	11
Darwin, Australia	12.5°S	130.9°E	40 m a.s.l.	Griffith et al. (2014a)	704	47
Wollongong, Australia	34.4°S	150.9°E	30 m a.s.l.	Griffith et al. (2014b)	172	29
Lauder, New Zealand	45.0°S	169.7°E	610 m a.s.l.	Sherlock et al. (2014); Pollard et al. (2019)	71	14

### 240 3.1 TCCON XCH<sub>4</sub>

We use TCCON ground-based remote sensing data from six exemplary sites located in different climate zones representative for high, mid and low latitudes. The Sodankylä site is located at high latitudes, Karlsruhe and Lauder are located in the northern and southern hemispheric mid-latitudes, Wollongong is located in the subtropics, and Burgos and Darwin are located in the tropics. More details on the locations of these sites and references and amount of the used data sets are given in Table 1.



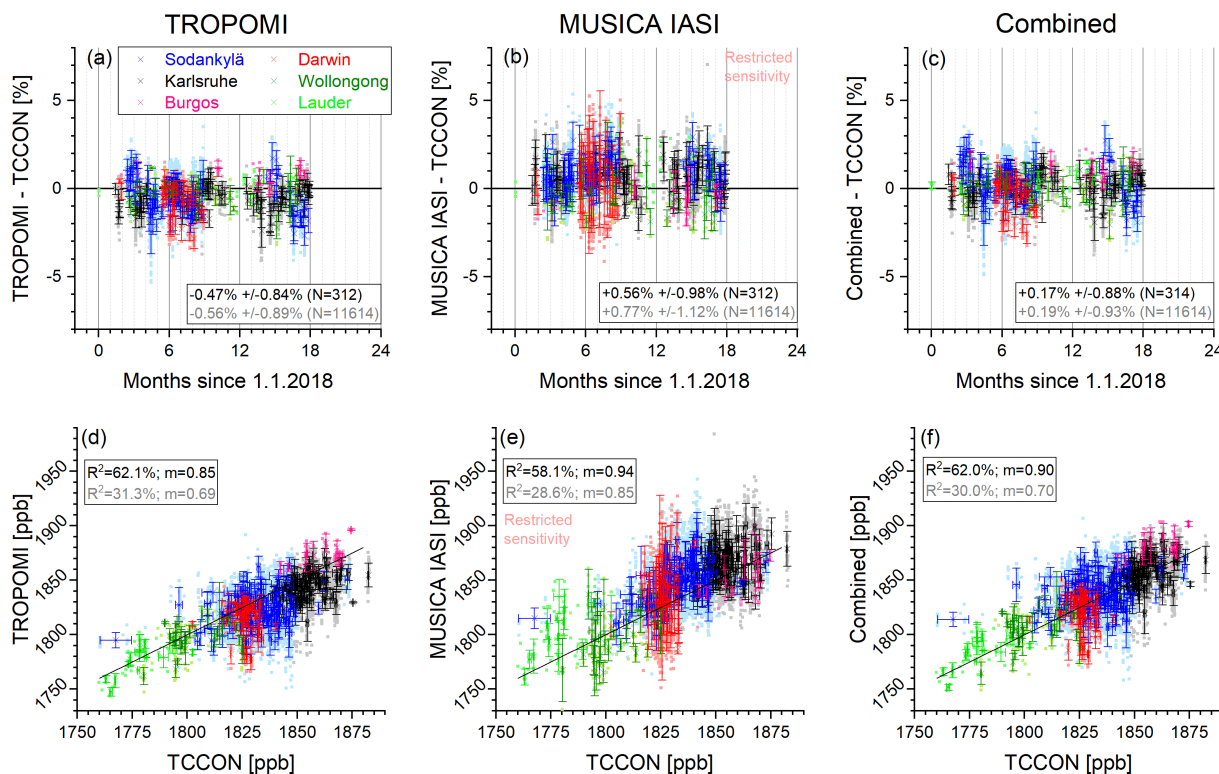
245 We use the TROPOMI a priori setting for the comparison between the ground-based TCCON and the satellite-based remote sensing products. For this purpose the TCCON product is adjusted to the TROPOMI a priori settings according to Eq. (A16), which ensures the usage of the same a priori data for all the remote sensing products. As spatial collocation criteria we require that the ground pixels of the TROPOMI and the IASI measurement fall within a circle with a radius of 150 km around the TCCON sites. For collocation with respect to time, TCCON, TROPOMI, and IASI observations have to be made within at  
 250 least 6 hours. Furthermore, we require that the altitude differences between the TCCON stations and the satellite ground pixels are within 250 m.

We estimate the reliability of the TCCON data as reference for the satellite observations. For this estimation we consider the TCCON retrieval noise errors, the incomparableness of TCCON and satellite data caused by their different averaging kernels, and the collocation mismatch. The total column uncertainty variance (the scalar  $S_{\text{ref}}$ ) for using the TCCON data as reference  
 255 for the satellite data can be estimated by:

$$S_{\text{ref}} = S_{\Delta_{\text{TC}}} + (\mathbf{a}^{*T} - \mathbf{a}_{\text{TC}}^{*T}) \mathbf{S}_{\Delta_{\mathbf{a}}} (\mathbf{a}^{*T} - \mathbf{a}_{\text{TC}}^{*T})^T + \mathbf{a}_{\text{TC}}^{*T} (\mathbf{S}_{\Delta_{\text{t}}} + \mathbf{S}_{\Delta_{\text{h}}}) \mathbf{a}_{\text{TC}}^{*T}, \quad (6)$$

The first term (the scalar  $S_{\Delta_{\text{TC}}}$ ) is the TCCON retrieval error covariance (the TCCON error is provided with the TCCON data is typically 1‰). The second term accounts for the different averaging kernels. The row vectors  $\mathbf{a}^{*T}$  and  $\mathbf{a}_{\text{TC}}^{*T}$  are the total column averaged mixing ratio kernels of the satellite and the TCCON retrievals, respectively (calculated according to  
 260 Appendix C). The matrix  $\mathbf{S}_{\Delta_{\mathbf{a}}}$  describes the uncertainty covariances of the used a priori data. We determine these uncertainty covariances from the TM5 CH<sub>4</sub> simulations (Krol et al., 2005), which are provided in the TROPOMI data set as the a priori data. For this purpose we assume a hypothetical out-of-phase of the model of 24 hours and in addition a horizontal mismatch of the modeled CH<sub>4</sub> fields of 500 km. The covariances obtained for the differences between the original TM5 model fields and the TM5 fields with the hypothetical model deficits are then used as the uncertainty covariances. We found an a priori uncertainty  
 265 covariance  $\mathbf{S}_{\Delta_{\mathbf{a}}}$  having largest values close to the surface but even there, the uncertainty variance is smaller than (4‰)<sup>2</sup>. Due to this good a priori knowledge the effect of the different averaging kernels on the comparison is less than 0.5‰ (even for the comparison between the TCCON and the MUSICA IASI products, where the difference in the averaging kernels is most significant). The third term takes into account that TCCON and the satellites might detect different air masses. The respective uncertainty covariances are again estimated with the TM5 CH<sub>4</sub> simulations. We determine the covariances between out-of-  
 270 phase model fields and the correct model fields for different out-of-phase time intervals. Similarly we calculate the covariances between model fields that have a horizontal mismatch and the correct model fields for different horizontal mismatch intervals. The temporal collocation uncertainty covariance ( $\mathbf{S}_{\Delta_{\text{t}}}$ ) and the horizontal collocation uncertainty covariance ( $\mathbf{S}_{\Delta_{\text{h}}}$ ) are then the covariances interpolated to the actual temporal and horizontal mismatch of the satellite and the TCCON measurements. The effect of this collocation mismatch on the comparison of the total columns is estimated to be smaller than 0.5‰. In summary,  
 275 we estimate the reliability of the TCCON data as reference for the satellite total column observations to be within 2‰.

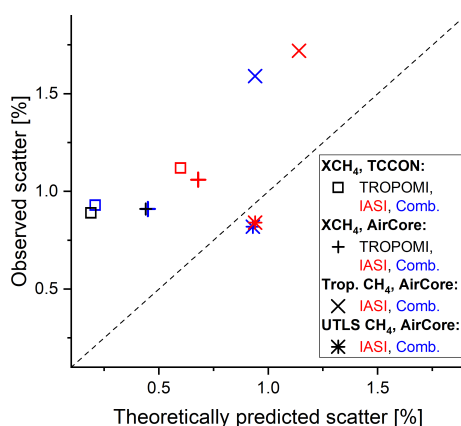
In Fig. 7 the TROPOMI, MUSICA IASI, and combined XCH<sub>4</sub> products are compared to the TCCON XCH<sub>4</sub> data. The crosses represent the daily mean data and the filled symbols in the background show all data corresponding to all individual valid collocations (between all single pixel satellite observations and individual TCCON observations). Figure 7a-c show time



**Figure 7.** Comparison of the different XCH<sub>4</sub> satellite products with TCCON XCH<sub>4</sub> data from five globally representative stations (the different colours correspond to the stations as given in the legend). Data for all individual coincidences are plotted in the background as squares and daily mean data are depicted as crosses with error bars representing the 1 $\sigma$  standard deviation: (a)-(c) shows time series of the differences, text in dark and pale fonts report mean and 1 $\sigma$  standard deviation (scatter) determined from daily mean data and from all individual collocations, respectively; (d)-(f) visualises the correlations (the black line is the one-to-one diagonal), text in dark and pale fonts report coefficients of determination ( $R^2$ ) and the slope of the linear regression line ( $m$ ) obtained for a linear least squares fit on daily mean data and on data from all individual collocations, respectively.

series of the differences with respect to the TCCON references. The daily mean data have error bars, which is the 1 $\sigma$  standard deviation of the data used for calculating the daily mean.

Statistics in form of mean difference and 1 $\sigma$  standard deviation (scatter) around the mean difference are given in each panel (for statistics using daily mean data in black fonts and for statistics using all individual valid collocations in grey fonts). Concerning TROPOMI (Fig. 7a) we observe – in line with Lorente et al. (2020) – a very good agreement. For daily mean data as well as for the statistics based on all individual differences, the mean difference is within 0.56% and the scatter lies below 0.9%. A very good agreement and low values for mean difference and scatter are also achieved for the combined product (Fig. 7c). For the MUSICA IASI product (Fig. 7b) we have reduced sensitivity in the lower troposphere (see Figs. 3 and 4) and the observed good agreement with the TCCON XCH<sub>4</sub> data can be partly explained by the reliable a priori data.



**Figure 8.** Theoretically predicted and observed  $1\sigma$  scatter for the comparison of single pixel satellite data with individual TCCON and AirCore reference data. Black, red and blue colours represent TROPOMI, MUSICA IASI, and combined satellite data, respectively. The squares and vertical crosses are for  $XCH_4$  comparisons with TCCON and AirCore references, respectively. The diagonal crosses and stars are for tropospheric and UTLS partial column comparisons, respectively, with AirCore references.

Figure 7d-f depicts correlation plots. For daily mean data the coefficients of determination ( $R^2$ ) are about 62% for the TROPOMI and the combined product. The slope of the obtained linear regression line is slightly closer to unity for the combined data product than for the TROPOMI data product. When considering all individual coincidences the  $R^2$  values are about 30%. The error bars on the daily mean data are the  $1\sigma$  standard deviations of the data used for calculating the daily mean. For the MUSICA IASI product, we observe a similar good correlation than for the TROPOMI and the combined products. However, concerning the MUSICA IASI data part of the common signal might be due to the a priori on which the MUSICA IASI total column product is not independent (see Fig. 4a).

The different satellite  $XCH_4$  data products show a very good agreement with the TCCON data (within 0.9%-1.1% concerning the comparison of single satellite pixel data with individual reference data). Figure 8 shows the correlations between the theoretically predicted scatter – considering the reference uncertainty according to Eq. (6) and the satellite products' noise error (see Fig. 5) – and the actually observed scatter. For the comparison of the MUSICA IASI product with TCCON (red square) we observe a larger scatter than for the comparison of the TROPOMI and combined products with TCCON (black and blue squares). The relatively larger scatter for the MUSICA IASI comparison is also theoretically predicted and mainly due to the increased noise error of this product (see Fig. 5a). Nevertheless, for all satellite products there is a systematic difference between the theoretically predicted and actually observed scatter values. Because it is consistently seen in all satellite products we assume that it is due to an underestimation of the reference uncertainty calculated according to Eq. (6).

We observe small systematic negative and positive differences for the TROPOMI versus TCCON and the MUSICA IASI versus TCCON comparisons, respectively. Although these systematic differences are not significant (within the observed standard deviation), they might indicate to a bias between the TROPOMI and MUSICA IASI  $XCH_4$  products of about 1%.



### 3.2 Air-Core in-situ CH<sub>4</sub> profiles

We use the AirCore balloon borne in-situ measurements (Karion et al., 2010) as the reference for CH<sub>4</sub> total columns as well as for the CH<sub>4</sub> vertical distribution. The AirCore system samples the vertical distribution of CH<sub>4</sub> with a much better vertical resolution than the satellite remote sensing systems. For this reason we can generate an AirCore profile ( $\hat{x}_{AC}$ ) that has the same vertical sensitivity and resolution characteristics as the remote sensing data. According to Eqs. (A1) and (A3) for the MUSICA IASI and the combined retrieval data we can write:

$$\hat{x}_{AC}^l = x_a^l + \mathbf{A}^l(x_{AC}^l - x_a^l). \quad (7)$$

Here  $\mathbf{A}^l$  and  $x_a^l$  are the logarithmic scale averaging kernels and the logarithmic scale a priori state of the satellite retrieval, respectively,  $x_{AC}^l$  is the measured logarithmic scale AirCore profile regridded to the atmospheric model grid used for the satellite retrievals. The resampling of these data on total and partial columns is made with the linear scale data according to Eq. (C6). For the TROPOMI total column averaged mixing ratios we calculated the adjusted AirCore total column averaged mixing ratio (a scalar) by  $\hat{x}_{AC} = \mathbf{w}^{*T} \mathbf{x}_a + \mathbf{a}_T^{*T} (\mathbf{x}_{AC} - \mathbf{x}_a)$ . For more details see Appendix C.

As spatial collocation criteria we require that the ground pixels of the TROPOMI and the IASI measurement fall within a circle with a radius of 500 km around the mean horizontal location of the AirCore system when sampling between the 450 and 550 hPa pressure levels. The temporal collocation is 6 hours. AirCore data are typically not available close to the ground and above the burst altitude of the balloon (approximately 25 hPa). At low altitudes we extend the profile with the concentrations closest to the ground. At high altitudes we extend the profile with the TM5 model data, with a smooth transition between the measured values and the modelled data.

Similar to the TCCON data we estimate the reliability of the AirCore profile data as reference for the satellite observations. For this estimation we consider an AirCore measurement noise covariance ( $\mathbf{S}_{\Delta AC,n}$ ). It is calculated assuming an uncertainty for altitudes with AirCore CH<sub>4</sub> data of 0.3% (Karion et al., 2010) and the uncertainty according to  $\mathbf{S}_{\Delta a}$  from Sect.3.1 for all other altitudes. The outer diagonal elements are determined by assuming the same vertical correlation as derived for  $\mathbf{S}_{\Delta a}$ . In addition, we consider uncertainties in the height attribution, which is according to Wagenhuser et al. (2021) below 10 m close to ground, about 200 m at 20 km a.s.l. and about 1 km at 27 km a.s.l. For some AirCore soundings there was a problem with the electronic board. For those measurements information on pressure, altitude and temperature had to be reconstructed from the radiosonde data and we use for all altitude levels an additional height attribution uncertainty value of 500 m. We construct a respective height attribution uncertainty covariance ( $\mathbf{S}_{\Delta AC,v}$ ) by assuming a very strong correlation of the height attribution uncertainties between different altitude levels. The temporal and spatial collocation uncertainty covariance between the AirCore and the satellite observations ( $\mathbf{S}_{\Delta t}$  and  $\mathbf{S}_{\Delta h}$ , respectively) are calculated as described in Sect. 3.1.

All the aforementioned uncertainties are independent and we can calculate the total uncertainty as:

$$\mathbf{S}_{\Delta AC} = \mathbf{S}_{\Delta AC,n} + \mathbf{S}_{\Delta AC,v} + \mathbf{S}_{\Delta t} + \mathbf{S}_{\Delta h}. \quad (8)$$



The reliability of the AirCore data – after its adjustment according to Eq. (7) – as reference for the MUSICA IASI and combined satellite data can then be estimated by:

$$340 \quad \mathbf{S}_{\text{ref}}^1 = \mathbf{A}^1 \mathbf{S}_{\Delta\text{AC}}^1 \mathbf{A}^{1T}. \quad (9)$$

Here and in Eq. (8) the covariances are determined for the full vertical profile. Respective covariances for total or partial columns can be derived according to Appendix C. The reliability for the TROPOMI total column averaged mixing ratio data can be calculated by  $S_{\text{ref}} = \mathbf{a}_T^{*T} \mathbf{S}_{\Delta\text{AC}} \mathbf{a}_T^*$ .

Table 2 gives an overview on the AirCore profiles measured at Trainou (France, 48.0°N, 2.1°E) and Sodankylä (Finland,  
 345 67.4°N, 26.6°E). In total we have 24 individual AirCore profiles with collocated satellite observations. The total number of collocated single pixel satellite observations is 4993. We estimate that the AirCore data can serve as reliable references for the satellite data validation. The three columns on the right report the uncertainties determined according to Eq. (8). For the reliability – according to Eq. (9) – we get very similar values (except for the total column and the partial tropospheric column of the MUSICA IASI product, because of the limited sensitivity). It is 3-6‰, 3-5‰, and 3-7‰, for the total column, the  
 350 tropospheric partial column and the UTLS partial column, respectively. In the troposphere the reliability depends mainly on the availability of AirCore data close to the ground and in the UTLS uncertainties of the altitude attribution have a dominating influence.

The comparison between the TROPOMI and the AirCore XCH<sub>4</sub> data is shown in Fig. 9. The differences of collocated measurements are shown in Fig. 9a. The agreement between TROPOMI and AirCore is very good and the mean difference  
 355 and the 1σ sigma standard deviation (scatter) around the mean difference is similar to the comparison between TROPOMI and TCCON. Considering the mean values for all coincidences corresponding to the same AirCore flight, we observe a coefficient of determination ( $R^2$ ) of about 30%. This is lower than the  $R^2$  value achieved for the correlation with TCCON data; however, we have to consider that the amplitude in the analysed total column signals is much smaller in the AirCore data set if compared to the TCCON data set.

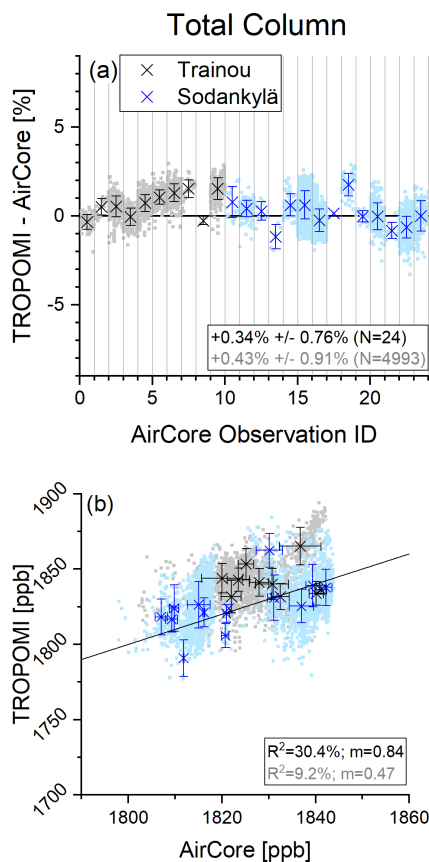
Figure 10 presents the comparison between the MUSICA IASI and AirCore total column and tropospheric and UTLS partial  
 360 column data. The differences between both data sets are depicted in Fig. 10a-c. We find a very good agreement for the UTLS partial column data (mean difference of about 0.6% and a scatter of about 1%). Because at this altitude region the MUSICA IASI product is almost independent from the a priori assumption (see Sect. 2.3), the a priori effect on  $\hat{x}_{\text{AC}}$  from Eq. 7 can also be neglected and we compare here two independent data sets. For the total column we also see a good agreement (Fig. 10a).  
 365 However according to Sect. 2.3 the MUSICA IASI total column products are significantly affected by the a priori data and so is  $\hat{x}_{\text{AC}}$  from Eq. 7, i.e. here we actually do not compare two independent data sets and a significant part of the good agreement might be due to the common a priori effect. For the tropospheric partial columns (Fig. 10b) the agreement worsens a bit. We get a mean difference of about 2.4% and a scatter around the mean differences of about 1.3% (for data averaged per flight). The increased mean difference might indicate a systematic bias in the MUSICA IASI lower tropospheric partial columns, which  
 370 might also explain the increased scatter: the bias will depend on the actual sensitivity of the MUSICA IASI product, which in





**Table 2.** List with information about the AirCore flights.  $[P_{\min}, P_{\max}]$  is the pressure range covered by the AirCore measurements.  $N$  is the number of collocated satellite observations (one collocation of IASI and TROPOMI counts as one).  $P_{\max} = \overline{P_{\text{GND}}^{\text{Sat}}} - P_{\max}$  is the mean difference between AirCore maximum pressure value and the pressure values for the collocated satellite ground pixels.  $\overline{\Delta h}$  is the mean horizontal distance between the AirCore system (location for AirCore system at 450-550 hPa) and the locations of the satellite ground pixels.  $\overline{\Delta t} = \overline{t^{\text{Sat}}} - t$  is the mean time difference between the AirCore observations (time for AirCore system at 450-550 hPa) and the satellite observations.  $\overline{\Delta AC_{\text{tot}}}$ ,  $\overline{\Delta AC_{\text{tro}}}$ , and  $\overline{\Delta AC_{\text{utls}}}$  are the square roots of the variances (determined according to Eq. (8) and the column calculations according to Appendix C). These are the estimated uncertainties for using the adjusted AirCore data as reference for the satellite data: for the total column (index: 'tot') and the tropospheric and UTLS partial columns (indices 'tro' and 'utls', respectively).

ID	Location	Date [YYYYMMDD]	$P_{\min}$ [hPa]	$P_{\max}$ [hPa]	$N$	$\overline{\Delta P_{\max}}$ [hPa]	$\overline{\Delta h}$ [km]	$\overline{\Delta t}$ [min]	$\overline{\Delta AC_{\text{tot}}}$ [%]	$\overline{\Delta AC_{\text{tro}}}$ [%]	$\overline{\Delta AC_{\text{utls}}}$ [%]
0-1	Trainou	20180523	29.0	962.3	68	+43.4	409	-41	0.4	0.4	0.4
1-2		20180525	26.4	972.2	23	-2.7	363	-47	0.3	0.4	0.3
2-3		20190220	21.9	983.4	240	+14.1	301	-76	0.6	0.5	0.7
3-4		20190220	19.2	940.5	183	+58.3	305	-138	0.3	0.4	0.3
4-5		20190221	19.8	902.7	433	+92.5	284	-76	0.6	0.5	0.7
5-6		20190221	19.4	986.3	318	+11.6	266	-118	0.3	0.4	0.4
6-7		20190617	20.5	910.9	399	+64.2	357	-227	0.5	0.4	0.6
7-8		20190618	23.8	972.8	31	+66.8	375	-104	0.6	0.5	0.7
8-9		20190621	44.6	869.1	2	+141.6	216	-47	0.6	0.5	0.6
9-10		20191011	38.1	914.8	287	+64.2	313	-82	0.5	0.5	0.6
10-11	Sodankylä	20180417	19.8	963.9	16	+20.2	281	-141	0.3	0.3	0.4
11-12		20180528	36.3	959.1	167	+43.3	401	+9	0.3	0.3	0.4
12-13		20180618	32.9	937.5	12	+57.2	411	-39	0.3	0.3	0.4
13-14		20180620	19.7	929.7	5	+66.4	316	-106	0.3	0.3	0.4
14-15		20180625	24.3	935.1	58	+67.3	360	-99	0.3	0.3	0.4
15-16		20180702	78.2	952.0	1171	+33.9	280	-127	0.3	0.3	0.3
16-17		20180801	15.8	962.6	452	+31.7	303	-203	0.5	0.4	0.6
17-18		20181003	13.0	916.5	1	+64.9	433	+61	0.3	0.3	0.4
18-19		20190410	15.1	975.7	51	+24.3	282	+39	0.3	0.3	0.4
19-20		20190628	16.6	952.8	18	+53.5	343	-9	0.3	0.3	0.4
20-21		20190724	16.8	961.1	207	+34.8	323	-13	0.5	0.4	0.6
21-22		20190801	16.3	957.8	10	+28.1	313	-14	0.3	0.3	0.3
22-23		20190828	13.8	966.1	680	+22.4	258	+9	0.3	0.3	0.3
23-24		20190909	24.0	968.0	161	+28.9	226	-43	0.3	0.3	0.3

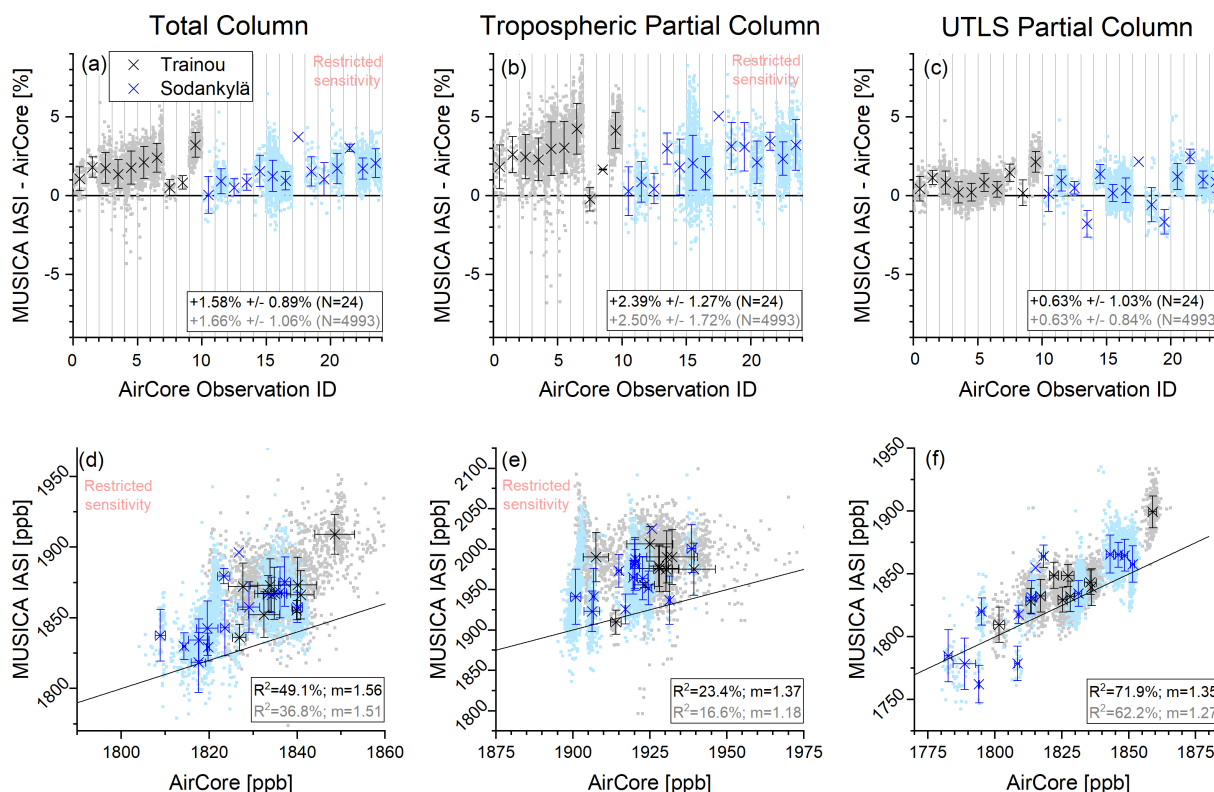


**Figure 9.** Comparison of AirCore measurements made at Trainou (black) and Sodankylä (blue) with the TROPOMI XCH<sub>4</sub> product. Data for all individual coincidences are shown in the background as squares and averages per flight are depicted as crosses with error bars representing the estimated uncertainty: (a) shows the series of differences ordered by flight number, text in dark and pale fonts report mean and 1 $\sigma$  standard deviation (scatter) determined from the averages per flight and from all individual collocations, respectively; (b) visualises the correlation (the black line is the one-to-one diagonal), text in dark and pale fonts report coefficients of determination ( $R^2$ ) and the slope of the linear regression line ( $m$ ) obtained for a linear least squares fit on the averages per flight and on all individual collocations, respectively. Details about the corresponding AirCore flights are provided in Table 2.

turn varies with the conditions present during the observation (mainly the surface temperature and the vertical temperature and humidity profiles).

Figure 10d-f shows respective correlation plots. We get very high  $R^2$  values for the UTLS partial column, where the two data sets are largely independent (almost not affected by the a priori data). This demonstrates that the MUSICA IASI product reliably captures the actual atmospheric CH<sub>4</sub> signals in the UTLS. Concerning the total column and the tropospheric partial column the MUSICA IASI and the adjusted AirCore data are not independent, nevertheless the  $R^2$  values are lower than for the

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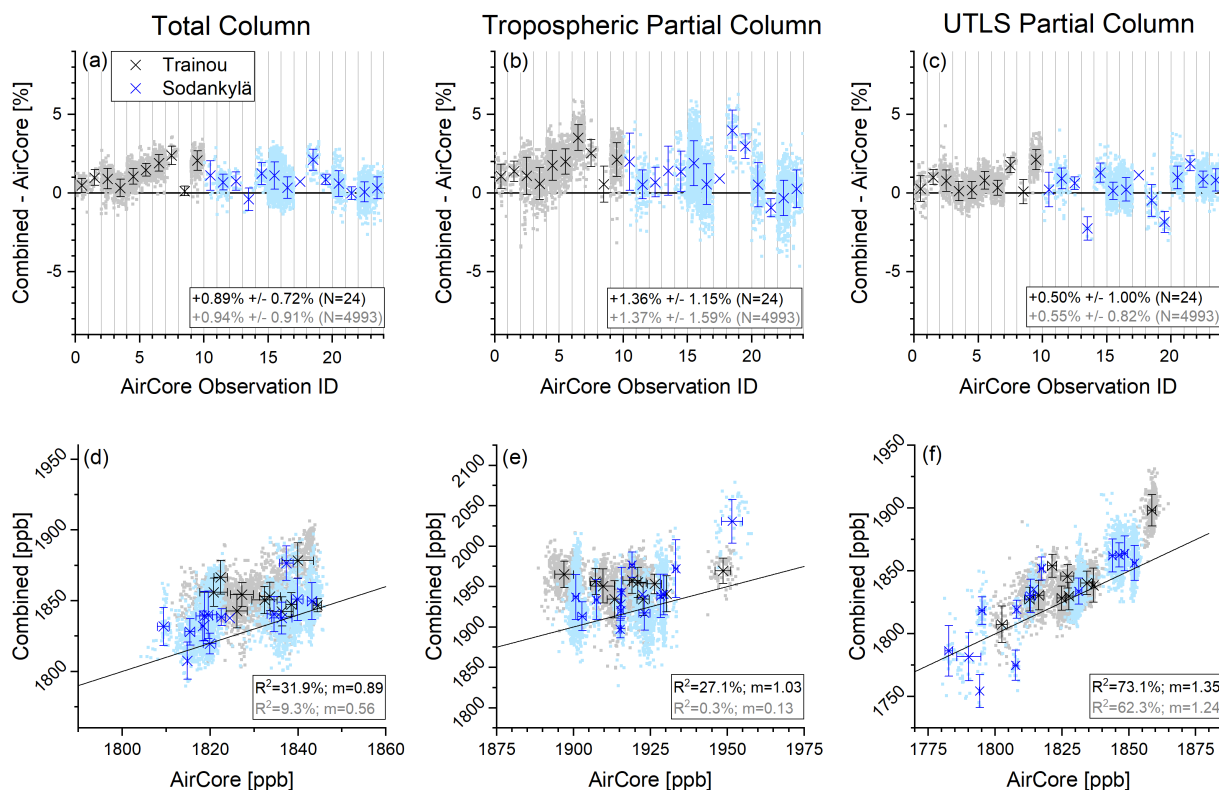


**Figure 10.** Same as Fig. 9, but for comparisons with the MUSICA IASI XCH<sub>4</sub>, tropospheric CH<sub>4</sub>, and UTLS CH<sub>4</sub> products: (a)-(c) shows the series of differences order by flight number; (d)-(f) visualises the correlation.

UTLS partial columns. This is due to a low amplitude of the respective signals (total column) and due to varying MUSICA IASI sensitivities, which causes a varying impact of a possible systematic bias (tropospheric partial column).

All combined products (total column and tropospheric and UTLS partial columns) are practically independent from the a priori assumptions (see Fig. 4). Figure 11a-c illustrates the differences between AirCore data and the combined products. For the total column we achieve values for the scatter that are similar to the comparison of the respective TROPOMI product. However, we observe a mean difference that is outside the 1 $\sigma$  scatter and also outside the uncertainty estimated for the AirCore references (see Table 2), which might indicate to a positive bias in the total columns of the combined data product. For the tropospheric partial column we observe a low scatter, but also mean difference of about 1.4% that is slightly outside the 1 $\sigma$  scatter of about 1.2% (for data averaged per flight). For the UTLS partial column the mean difference and scatter values are similar to the comparison of the respective MUSICA IASI product.

The correlation plots (Fig. 11d-f) allow similar conclusions: the combined product can capture total column signals as reliable as the TROPOMI product (apart from a possible weak bias) and UTLS partial columns signals as reliable as the MUSICA IASI product. Concerning the tropospheric partial column we observe higher R<sup>2</sup> values than for the respective correlation with MUSICA IASI data; however, only when correlating the mean values for all coincidences corresponding to



**Figure 11.** Same as Fig. 10, but for comparisons with the combined data products.

the same AirCore flight. When correlating all individual coincidences the  $R^2$  values are even lower than the already low  $R^2$  values achieved for the respective correlation with MUSICA IASI data (compare Fig. 10e with Fig. 11e). The low values for  $R^2$  are explained by the low  $\text{CH}_4$  variability encountered during the 24 individual AirCore profiles.

Figure 8 shows the correlations between the theoretically predicted scatter – considering the reference uncertainty according to Eqs. (8) and (9) and the satellite products’ noise error (see Fig. 5) – and the actually observed scatter values. The black, red and blue vertical crosses are for the scatter in the  $\text{XCH}_4$  data, and the red and blue diagonal crosses and stars for the scatter in the tropospheric and UTLS partial column data. There are large similarities to the scatter values obtained for the comparison with TCCON. Firstly, observation and theory agree concerning the relative scatter increases: lower scatter values for TROPOMI and combined data products than for MUSICA IASI data product. Secondly, for  $\text{XCH}_4$  as well as for the tropospheric partial column the observed scatter is significantly larger than the theoretically predicted scatter. For the UTLS partial column we find a very good agreement in the absolute values of the theoretically predicted and actually observed scatter. Because the observed scatter is consistently higher than the theoretically predicted scatter independent from the kind of  $\text{XCH}_4$  or tropospheric partial column satellite data product and also independent from the reference data (AirCore or TCCON), it is very reasonable to assume that close to ground we underestimate the temporal collocation uncertainty covariance ( $\mathbf{S}_{\Delta t}$ ) and the



405 horizontal collocation uncertainty covariance ( $S_{\Delta h}$ ). These are the only terms used consistently for all the different theoretical scatter predictions.

Similar to the TCCON comparisons, the AirCore study suggests a systematic bias between the TROPOMI and MUSICA IASI XCH<sub>4</sub> products of slightly above 1%, which seems to be mainly due to a positive bias of about 2% in the MUSICA IASI tropospheric data product. In the UTLS we observe no significant bias in the MUSICA IASI data.

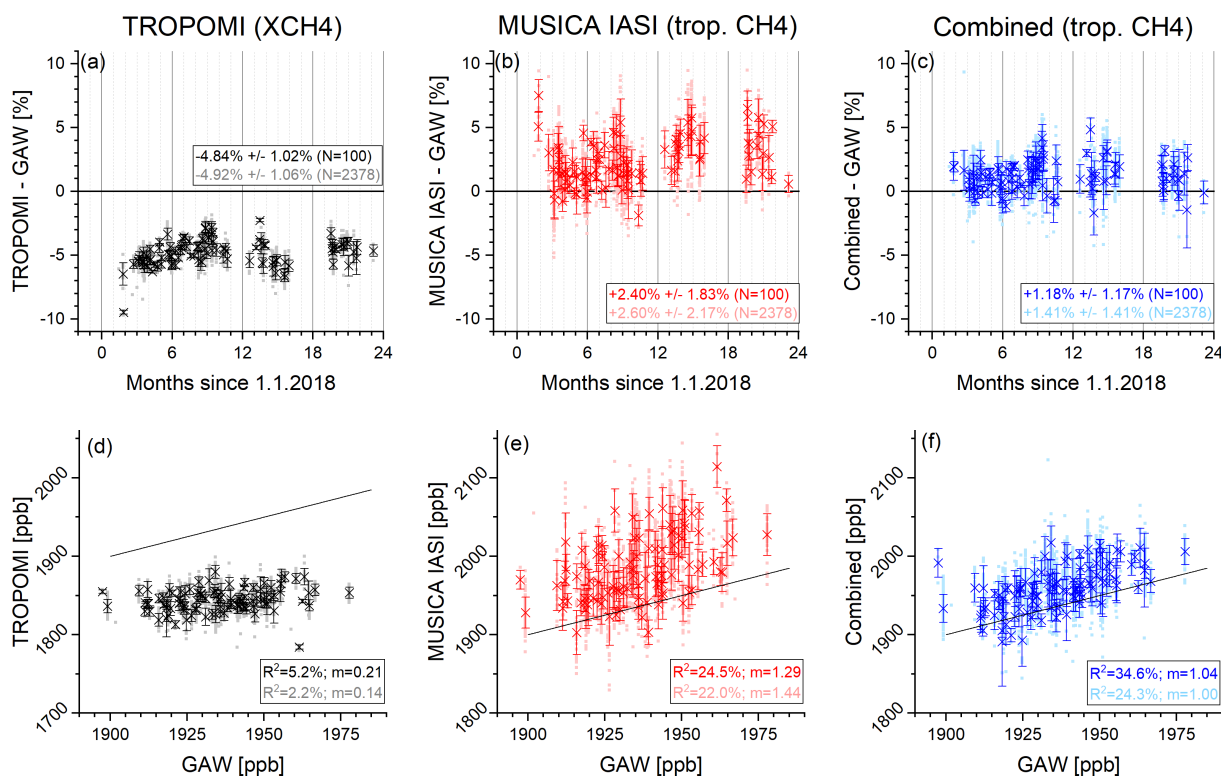
### 410 3.3 GAW surface in-situ CH<sub>4</sub> measurements

At many globally distributed sites atmospheric trace gas in-situ measurements are made continuously with the Global Atmospheric Watch (GAW, <https://community.wmo.int/activity-areas/gaw>) programme. Appendix A of Sepúlveda et al. (2014) presents a method for filtering common signals in night time CH<sub>4</sub> data of the two nearby mountain GAW stations Jungfraujoch (46.5°N, 8.0°E, 3580 m a.s.l.) and Schauinsland (47.9°N, 7.9°E, 1205 m a.s.l.). Data were retained as common signals when  
415 deviations of observations (after correction for vertical gradient, i.e. application of an offset, and a temporal shift in the annual cycles) at both sites were below a certain threshold. Sepúlveda et al. (2014) showed that the common signals are well representative for a broader layer in the lower free troposphere. Here we follow this approach and use the mean of the Jungfraujoch and Schauinsland CH<sub>4</sub> mixing ratio – whenever identified as a common signal – as a validation reference for the remote sensing data in South-western Germany and Northern Switzerland (indicated by the grey circle in Fig. 6). We assume that the signals  
420 obtained from this GAW data filtering are well representative for the tropospheric partial column averaged mixing ratios (surface - 6 km a.s.l.) and compare these data directly to different satellite products as a fully independent data set: we do not adjust the data to a common a priori data usage as in Sects. 3.1 and Sect. 3.2, because the in-situ data represent absolute measurements and do not depend on any a priori information. Furthermore, we do not adjust sensitivities as in Sect. 3.2 (see Eq. (7)), which means that we validate here also the sensitivities of the products.

425 Figure 12 shows the comparison with the different satellite products. Concerning the comparison with TROPOMI XCH<sub>4</sub> data we observe a very large systematic difference and very low values for  $R^2$  (Fig. 12a and d). This indicates that the total column (XCH<sub>4</sub>) signals are not a good proxy for lower tropospheric CH<sub>4</sub> signals, instead the former are strongly affected by signals in the UTLS, where CH<sub>4</sub> values are strongly affected by shifts of the tropopause height.

For the MUSICA IASI tropospheric partial column averaged mixing ratio product (Fig. 12b and e) we observe a smaller  
430 mean difference than for the TROPOMI XCH<sub>4</sub> comparison, but at the same time an increased  $1\sigma$  standard deviation (scatter) around the mean. The  $R^2$  values are larger than for the correlation of TROPOMI data; however, we have to be careful, because the lower tropospheric MUSICA IASI CH<sub>4</sub> data are significantly affected by the a priori assumptions (see Fig. 4b). This means that the observed correlation might actually be due to a correlation with the a priori data. Furthermore, the slope of the linear regression line is significantly larger than unity.

435 The combined tropospheric partial column averaged mixing ratio product is practically independent from the a priori assumptions (see Fig. 4b). The good agreement and correlation between the GAW data and the combined products as illustrated in Fig. 12c and f demonstrates that the combined product can reliably capture actual tropospheric CH<sub>4</sub> signals independently



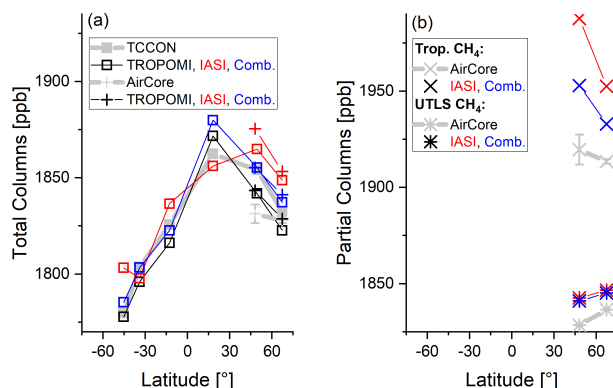
**Figure 12.** Comparison of GAW measurements made at Jungfraujoch and Schauinsland with the TROPOMI XCH<sub>4</sub>, the IASI tropospheric CH<sub>4</sub>, and the Combined tropospheric CH<sub>4</sub> product. Data for all individual coincidences are shown in the background as squares and daily averages are depicted as crosses with error bars representing the estimated uncertainty: (a)-(c) shows the time series of differences, text in dark and pale coloured fonts report mean and  $1\sigma$  standard deviation (scatter) determined from daily mean data and from all individual collocations, respectively; (d)-(f) visualises the correlation (the black line is the one-to-one diagonal), text in normal and bright coloured fonts report coefficients of determination ( $R^2$ ) and the slope of the linear regression line ( $m$ ) obtained for a linear least squares fit on daily mean data and on data from all individual collocations, respectively.

from the UTLS CH<sub>4</sub> signals. For daily mean data we find a mean difference of about 1.2%, a  $1\sigma$  scatter of also about 1.2%, an  $R^2$  value of almost 35%, and a slope of the linear regression line of very close to unity.

## 440 4 Bias discussion

### 4.1 Global validity of the observed bias

The AirCore comparison of Sect. 3.2 indicates to a positive bias of about +1% for the combined tropospheric CH<sub>4</sub> data product and suggests no significant bias for the combined UTLS data product; however, the study is limited to a middle and high



**Figure 13.** Latitudinal dependency of the overall mean values obtained at the six TCCON and two AirCore observation sites. Grey colour represents the TCCON and AirCore reference data and black, red and blue colours the TROPOMI, MUSICA IASI, and combined satellite data, respectively: (a) for total columns ( $XCH_4$ ) and (b) for tropospheric and UTLS partial columns. The error bars on the AirCore data describe the variability range due to the AirCore data treatment – according to Eq. (7) – with the different averaging kernels of the TROPOMI, MUSICA IASI and combined data product.

**Table 3.** Statistics based on the comparisons between satellite and TCCON data of the overall mean  $XCH_4$  values obtained for the six TCCON sites of Table 1.

Product	Difference (mean $\pm$ std)	$R^2$	Slope ( $m$ )
TROPOMI	-0.29% $\pm$ 0.43%	94.4%	1.04
MUSICA IASI	+0.45% $\pm$ 0.66%	85.0%	0.84
Combined	+0.23% $\pm$ 0.39%	96.3%	1.09

northern latitude site, respectively. Nevertheless, in this section we argue that it is reasonable to assume similar biases also for other locations.

According to Eq. (4) a varying error in the a priori state together with a poor sensitivity (i.e. an averaging kernel being very different from an identity matrix) can cause a varying bias. If the error in the a priori state is latitudinal dependent the bias will also be latitudinal dependent. Furthermore, a systematic error source (like an error in a spectroscopic parameter) can have a variable impact on the remote sensing product, if the sensitivity is variable. If the sensitivity has a dependency on latitude, a systematic error source can thus also cause a latitudinal dependent bias. In this context, variabilities (e.g. latitudinal dependencies) of biases are likely for a low or variable sensitivity. In contrast, inconsistencies in the bias are unlikely in case of a high and constant sensitivity (as observed in Fig. 4 for the total column and tropospheric and UTLS partial column of the combined data product).

Figure 13 depicts the overall mean total and partial column values obtained at the six TCCON and two AirCore observation sites. For total column data (Fig. 13a) we achieve a good latitudinal coverage by the TCCON observation sites and



can investigate possible latitudinal inconsistencies in the satellite data products. We find that the TROPOMI and the combined satellite data product capture practically the same latitudinal dependency as the TCCON data. Figures 3a and 4a reveal that for these data products the sensitivities are very high and stable, in contrast to the MUSICA IASI data product, which has a relatively weak and seasonally (and supposed latitudinally) varying sensitivity. This explains that in Fig. 13a the latitudinal dependency of the MUSICA IASI XCH<sub>4</sub> data is slightly different from the TCCON data. Table 3 resumes the statistics made with the overall mean XCH<sub>4</sub> values obtained for the six TCCON observation sites. For the TROPOMI and the combined data product the 1σ standard deviation calculated from the mean difference of the six stations is about 0.4%. The R<sup>2</sup> values of almost 100% and the regression line slope values of close to unity confirm the very good latitudinal data consistency. The MUSICA IASI data product shows poorer performance with regard to the values of standard deviation, R<sup>2</sup>, and regression line slope, which is in line with its weak and varying sensitivity.

A similar study of the latitudinal consistency of the partial column data products is compromised by the lack of profile references for low latitudes and southern hemispheric sites (Fig. 13b). Nevertheless, because the combined product has a rather high and constant sensitivity for the tropospheric as well as the UTLS partial column (see Figs. 3 and 4), we expect – as for XCH<sub>4</sub> – a good latitudinal consistency, i.e. a bias at low and/or southern latitudes that is similar to the bias of about +1% as observed at middle and high northern latitudes.

#### 4.2 MUSICA IASI and TROPOMI XCH<sub>4</sub> data inconsistency

The validation study of Sect. 3 suggest a small positive bias of about +1% of the MUSICA IASI XCH<sub>4</sub> data product with respect to the TROPOMI XCH<sub>4</sub> data product. This bias affects the term  $[\hat{x}_T - \mathbf{a}_T^{*T} \hat{\mathbf{x}}_I]$  of Eq. (1) and can introduce artefacts into the combined data product. For a constant Kalman gain operator the bias will mainly have a systematic effect on the combined product and will not cause variable artificial signals: the variability of XCH<sub>4</sub> is rather small (about 2%) and a bias of 1% only causes an artificial signal in the term  $[\hat{x}_T - \mathbf{a}_T^{*T} \hat{\mathbf{x}}_I]$  of  $1\% \times 2\% = 0.02\%$ . However, the Kalman gain operator varies from observation to observation and in consequence the impact of a 1% bias on the combined product is very likely also variable. Furthermore, if the reason of the bias is a systematic error source (e.e. an error in a spectroscopic parameter) the varying sensitivity of the MUSICA IASI data products (see Fig. 4) can cause variable signals in the term  $[\hat{x}_T - \mathbf{a}_T^{*T} \hat{\mathbf{x}}_I]$  that are misinterpreted by the combination method.

In summary, by reducing the systematic inconsistency between the TROPOMI and MUSICA IASI XCH<sub>4</sub> data we might be able to further improve the quality of the combined data product. Assuming that this inconsistency is mainly due to a positive bias in the lower/middle tropospheric MUSICA IASI CH<sub>4</sub> data (see Sect. 3.2), follow-up studies can focus on removing the MUSICA IASI bias (for instance, by an approach as discussed in Sect. 3.4 of Kulawik et al., 2021) and in documenting the impact of the bias removal on the quality of the combined data product. However, such studies are currently compromised by the lack of high quality CH<sub>4</sub> profile data at low latitudes over land for the period after October 2017 (period with operating TROPOMI and IASI instruments).





## 5 Summary and outlook

We present a method for a synergetic use of TROPOMI total column and IASI vertical profile retrieval products. The method  
490 is based on simple linear algebra calculations, i.e. the execution of computationally expensive dedicated combined retrievals  
is not needed. Nevertheless, it approximates closely to a dedicated combined optimal estimation retrieval using the combined  
TROPOMI and IASI measurements (see Appendix A2). We apply the method to CH<sub>4</sub> data. By providing a compilation with  
all important equations we support the application of this method to other data products.

We theoretically examine the sensitivity, vertical resolution, and errors of the individual TROPOMI and IASI products and  
495 of the combined product. The TROPOMI product consists of reliable total column CH<sub>4</sub> data, but does not offer information on  
the vertical distribution. The IASI product offers some information on the vertical distribution and has best sensitivity in the  
UTLS region, but lacks sensitivity in the lower troposphere, i.e. it is not well sensitive to the total column. We show that the  
combined product combines both strengths: it is a reliable reference for the total column and also for the UTLS partial column.  
In addition, we found as a clear synergetic effect that the combined product is also a reliable reference for the tropospheric  
500 partial column.

We generate the combined CH<sub>4</sub> product for the time period between November 2017 and December 2019 and compare  
the individual and combined products to reference data of TCCON, AirCore and GAW. TCCON data are available for the  
different latitudes in the northern and southern hemisphere and offer good references for XCH<sub>4</sub>. We get an agreement of all  
satellite XCH<sub>4</sub> products with the TCCON data within 1%. This comparison reveals a good reliability of the TROPOMI and  
505 the combined XCH<sub>4</sub> products, because of their independency on the a priori data (the comparison of the IASI data is affected  
by the a priori data and thus cannot be directly interpreted). We found that the AirCore data are a very good reference for the  
consistent validation of the CH<sub>4</sub> total column amounts and the CH<sub>4</sub> vertical distribution; however, they are limited to northern  
hemispheric high and middle latitudes. Concerning total column comparison we get a very low 1 $\sigma$  scatter between the satellite  
products and the AirCore reference data (within 1%, which is similar to the comparison with TCCON). For the UTLS partial  
510 columns the scatter is also within 1% and for the tropospheric partial columns it is 1.1% - 1.7%. While the comparison to  
TCCON shows no significant bias, the comparison to AirCore reveals a significant positive bias in the MUSICA IASI XCH<sub>4</sub>  
and tropospheric partial column data (significant in the sense that the systematic difference is outside the 1 $\sigma$  scatter and that it  
can also be not explained by the uncertainty of the AirCore references). For the combined tropospheric partial column product  
we report a slightly significant positive bias of about +1.4%.

We have only 24 AirCore profiles measured in collocation to satellite observations. A statistically more robust validation  
515 of the tropospheric partial column products can be achieved by using continuous CH<sub>4</sub> observations from two nearby GAW  
stations. The CH<sub>4</sub> signals that are common at both stations are a good validation reference for the troposphere. We get col-  
locations between the GAW data and satellite observations for 100 individual days and the comparison to the tropospheric  
partial column averaged mixing ratios generated from the combined data product confirms and widens the conclusions based  
520 on the comparison with the AirCore data: for the comparison of the daily mean data we get a mean difference and 1 $\sigma$  scatter  
of +1.2% $\pm$ 1.2%, which is in good agreement to the comparison with the AirCore data (i.e. the combined product agrees very



well with reference data, but we find indications of a weak positive bias). The continuous GAW CH<sub>4</sub> reference data cover seasonal cycle signals and have a larger amplitude than the AirCore data. We demonstrate that the lower tropospheric partial column averaged mixing ratio generated from the combined data product is able to capture these signals much better than the  
525 respective IASI product or the TROPOMI total column averaged product.

There might be a chance to further improve the quality of the combined data product by performing detailed investigations on the inconsistency between the TROPOMI and the MUSICA IASI XCH<sub>4</sub> data. The availability of additional CH<sub>4</sub> profile reference data for low latitudes (e.g. obtained by the AirCore system) would be very beneficial for such purpose.

The proposed method takes benefit from the outputs generated by the dedicated individual TROPOMI and IASI retrievals,  
530 it needs no extra retrievals, and is thus computationally very efficient. This makes it ideal for an application at large scale, and allows the combination of operational IASI and TROPOMI products in an efficient and sustained manner. This has a particular attraction, because IASI and TROPOMI successor instruments will be jointly aboard the upcoming Metop (Meteorological operational) Second Generation satellites (guaranteeing observations from the 2020s to the 2040s). There will be several 100,000 globally distributed and perfectly collocated observations (over land) of IASI and TROPOMI successor instruments  
535 per day, for which a combined product can be generated in a computationally very efficient way.

*Data availability.* Access to the MUSICA IASI data is provided via <http://www.imk-asf.kit.edu/english/musica-data.php>. The TROPOMI XCH<sub>4</sub> data used in this study are available for download at [ftp://ftp.sron.nl/open-access-data-2/TROPOMI/tropomi/ch4/14\\_14\\_Lorente\\_et\\_al\\_2020\\_AMTD/](ftp://ftp.sron.nl/open-access-data-2/TROPOMI/tropomi/ch4/14_14_Lorente_et_al_2020_AMTD/). TCCON data are made available via the TCCON Data Archive, hosted by CaltechDATA, California Institute of Technology, California (USA), <http://tccondata.org>. For Trainou AirCore data please contact Michel Ramonet ([michel.ramonet@lsce.ipsl.fr](mailto:michel.ramonet@lsce.ipsl.fr)) and for  
540 Sodankylä AirCore data please contact Huilin Chen ([huilin.chen@rug.nl](mailto:huilin.chen@rug.nl)). The GAW surface in-situ data are available via the World Data Centre for Greenhouse Gases (WDCGG), <https://gaw.kishou.go.jp/search/>.

## Appendix A: Theoretical considerations

In this appendix we give a brief overview on the theory of optimal estimation remote sensing methods and follow the notation as recommended by the TUNER activity (von Clarmann et al., 2020), which is closely in line with the notation used by Rodgers  
545 (2000). The overview focuses on the equations that are important for our work, i.e. the optimal a posteriori combination of two independently retrieved optimal estimation remote sensing products. We show analytically that our method of combining two individually retrieved optimal estimation products by means of a posteriori calculations, is in most cases equivalent to a combined optimal estimation retrieval that uses a combined measurement vector.

For a more detailed and general insight into the theory of optimal estimation remote sensing methods we refer to Rodgers  
550 (2000) and for a general introduction on vector and matrix algebra dedicated textbooks are recommended.



## A1 Basics on retrieval theory

If we assume a moderately non-linear problem (according to Chapter 5 of Rodgers, 2000), the retrieved optimal estimation product (the retrieved atmospheric state vector  $\hat{x}$ ) can be written as:

$$\hat{x} = x_a + \mathbf{G}[\mathbf{K}(x - x_a)]. \quad (\text{A1})$$

555 Here  $x$  and  $x_a$  are the actual atmospheric state vector and the a priori atmospheric state vector, respectively.  $\mathbf{K}$  is the Jacobian matrix, i.e. derivatives that capture how the measurement vector (the measured radiances) will change for changes of the atmospheric state (the atmospheric state vector  $x$ ).  $\mathbf{G}$  is the gain matrix, i.e. derivatives that capture how the retrieved state vector will change for changes in the measurement vector:

$$\mathbf{G} = (\mathbf{K}^T \mathbf{S}_{y,n}^{-1} \mathbf{K} + \mathbf{S}_a^{-1})^{-1} \mathbf{K}^T \mathbf{S}_{y,n}^{-1}, \quad (\text{A2})$$

560 with  $\mathbf{S}_{y,n}$  and  $\mathbf{S}_a^{-1}$  being the retrieval's noise covariance and the constraint matrices, respectively. In a strict optimal estimation sense, the constraint matrix is the inverse of the a priori covariance matrix  $\mathbf{S}_a$ .

The averaging kernel

$$\mathbf{A} = \mathbf{G}\mathbf{K}, \quad (\text{A3})$$

is an important component of a remote sensing retrieval, because according to Eq. (A1) it reveals how changes of the real atmospheric state vector  $x$  affect the retrieved atmospheric state vector  $\hat{x}$ .

Very useful is also the a posteriori covariance matrix, which can be calculated as follows:

$$\mathbf{S}_{\hat{x}} = (\mathbf{K}^T \mathbf{S}_{y,n}^{-1} \mathbf{K} + \mathbf{S}_a^{-1})^{-1}. \quad (\text{A4})$$

The linearised formulation of the retrieval solution according to (A1) is very useful for the analytic characterisation of the product. The retrieval state's noise error covariance matrix for noise can be analytically calculated as:

$$570 \mathbf{S}_{\hat{x},n} = \mathbf{G}\mathbf{S}_{y,n}\mathbf{G}^T, \quad (\text{A5})$$

where  $\mathbf{S}_{y,n}$  is the covariance matrix for noise on the measured radiances  $y$ .

Further very helpful equations are the relations between the a posteriori covariance, the averaging kernel, the constraint (or the a priori covariance), and the retrieval's state noise error covariance matrices:

$$\mathbf{S}_{\hat{x}} = (\mathbf{I} - \mathbf{A})\mathbf{S}_a, \quad (\text{A6})$$

575 and

$$\mathbf{S}_{\hat{x},n} = \mathbf{A}\mathbf{S}_{\hat{x}}, \quad (\text{A7})$$

with  $\mathbf{I}$  being the identity matrix.



## A2 Optimal combination of retrieval data products

In this subsection we discuss an optimal estimation retrieval that uses a combined measurement vector (two measurements  
 580 from different instruments). Then we briefly introduce the Kalman filter and show that the Kalman filter formalism enables us  
 to combine two individually retrieved remote sensing data products in equivalence to the optimal estimation retrieval using the  
 combined measurement vector.

### A2.1 Optimal estimation using a combined measurement vector

According to Eqs. (A1), (A2), and (A4) the retrieval product obtained from a combined measurement vector  $\{y_1, y_2\}$  can be  
 585 written as:

$$\begin{aligned}\hat{x} - x_a &= (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 + \mathbf{S}_a^{-1})^{-1} (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2) (x - x_a) \\ &= (\mathbf{S}_{\hat{x}_1}^{-1} + \mathbf{S}_{\hat{x}_2}^{-1} - \mathbf{S}_a^{-1})^{-1} (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2) (x - x_a),\end{aligned}\quad (\text{A8})$$

where  $\mathbf{S}_{y_1, n}$  and  $\mathbf{S}_{y_2, n}$  are the respective measurement noise covariances,  $\mathbf{K}_1$  and  $\mathbf{K}_2$  the respective Jacobians and  $\mathbf{S}_{\hat{x}_1}$  and  
 $\mathbf{S}_{\hat{x}_2}$  the respective a posteriori covariances.

### 590 A2.2 Linear Kalman filter

An important application of a Kalman filter (Kalman, 1960; Rodgers, 2000) is data assimilation in the context of atmospheric  
 modelling. There the filter operates sequentially in different time steps. Kalman filter data assimilation methods determine the  
 analysis state ( $\hat{x}^a$ ) by optimally combining the background (or forecast) state ( $\hat{x}^b$ ) with the information as provided by a new  
 observation ( $\hat{x}^o$ ):

$$595 \quad \hat{x}^a = \hat{x}^b + \mathbf{M}[\hat{x}^o - \mathbf{H}\hat{x}^b]. \quad (\text{A9})$$

Optimal means here that the uncertainties of both, the background state and the observation, are correctly taken into account  
 by the Kalman gain matrix ( $\mathbf{M}$ ):

$$\begin{aligned}\mathbf{M} &= \mathbf{S}_{\hat{x}^b} \mathbf{H}^T (\mathbf{H} \mathbf{S}_{\hat{x}^b} \mathbf{H}^T + \mathbf{S}_{\hat{x}^o, n})^{-1} \\ &= (\mathbf{H} + \mathbf{S}_{\hat{x}^o, n} \mathbf{H}^{-T} \mathbf{S}_{\hat{x}^b}^{-1})^{-1},\end{aligned}\quad (\text{A10})$$

600 with  $\mathbf{S}_{\hat{x}^b}$  and  $\mathbf{S}_{\hat{x}^o, n}$  being the uncertainty covariances of background state and the new measurement, respectively. The matrix  
 $\mathbf{H}$  is the measurement forward operator, which maps the background domain into the measurement domain.

The similarity between Eqs. (A9) and (A10), on the one hand, and Eqs. (A1) and (A2), on the other hand, reveals that remote  
 sensing optimal estimation and Kalman filter data assimilation methods use the same mathematical formalism.

### A2.3 Optimal a posteriori combination of individually retrieved data products

605 We have a first estimation of the atmospheric state (the first retrieval product  $\hat{x}_1$ ) and we want to optimally improve this  
 estimation by using a second retrieval product ( $\hat{x}_2$ ). This is a typical data assimilation problem and we can use the Kalman



filter formalism. We make the following settings:

$$\begin{aligned} \mathbf{S}_{\hat{x}^b} &= \mathbf{S}_{\hat{x}_1} \\ &= (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{S}_a^{-1})^{-1} \end{aligned} \quad (\text{A11})$$

610

$$\begin{aligned} \mathbf{S}_{\hat{x}^o, n} &= \mathbf{S}_{\hat{x}_2, n} \\ &= (\mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 + \mathbf{S}_a^{-1})^{-1} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 (\mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 + \mathbf{S}_a^{-1})^{-1} \\ &= \mathbf{S}_{\hat{x}_2} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 \mathbf{S}_{\hat{x}_2} \end{aligned} \quad (\text{A12})$$

$$\begin{aligned} \mathbf{H} &= \mathbf{A}_2 \\ &= (\mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 + \mathbf{S}_a^{-1})^{-1} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 \\ &= \mathbf{S}_{\hat{x}_2} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 \end{aligned} \quad (\text{A13})$$

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$$\begin{aligned} \hat{x}^b &= \hat{x}_1 - x_a \\ &= (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{S}_a^{-1})^{-1} \mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 (x - x_a) \\ &= \mathbf{S}_{\hat{x}_1} \mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 (x - x_a) \end{aligned} \quad (\text{A14})$$

620

$$\begin{aligned} \hat{x}^o &= \hat{x}_2 - x_a \\ &= (\mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 + \mathbf{S}_a^{-1})^{-1} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 (x - x_a) \\ &= \mathbf{S}_{\hat{x}_2} \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2 (x - x_a). \end{aligned} \quad (\text{A15})$$

625

In Eqs. (A11) and (A12) we assume that the two individual retrievals use the same constraint ( $\mathbf{S}_a^{-1}$ ). This is generally not the case and we can a posteriori modify a constraint and its effect on state vectors and covariances by the formalism as presented in Chapter 10.4 of Rodgers (2000) or Sect. 4.2 of Rodgers and Connor (2003). For our problem here this is of secondary importance, because we assume that TROPOMI total column data products are almost independent on the constraint (as long as the constraint is reasonable).

630

In Eqs. (A14) and (A15) we assume the usage of the same a priori for the two individual retrievals. Since generally two individually performed retrievals use two different a priori settings we have to perform an a priori adjustment. Using the a priori of retrieval 2 as the reference ( $x_{2, a} = x_a$ ) we can adjust the output of retrieval 1 by (see Eq. (10) of Rodgers and Connor, 2003):

$$\hat{x}_1' = \hat{x}_1 + (\mathbf{A}_1 - \mathbf{I})(x_{1, a} - x_{2, a}), \quad (\text{A16})$$

635

where  $x_{1, a}$  is the a priori used by retrieval 1.

Substitution of the settings from Eqs. (A11) - (A13) in Eq. (A10) gives:

$$\mathbf{M} = (\mathbf{S}_{\hat{x}_1}^{-1} + \mathbf{S}_{\hat{x}_2}^{-1} - \mathbf{S}_a^{-1})^{-1} \mathbf{S}_{\hat{x}_2}^{-1}, \quad (\text{A17})$$



where we use Eqs. (A6) and (A7).

640 Substituting Eq. (A17) together with the settings from Eqs. (A14) and (A15) in Eq. (A9) finally yields:

$$\hat{x}^a - x_a = (\mathbf{S}_{\hat{x}_1}^{-1} + \mathbf{S}_{\hat{x}_2}^{-1} - \mathbf{S}_a^{-1})^{-1} (\mathbf{K}_1^T \mathbf{S}_{y_1, n}^{-1} \mathbf{K}_1 + \mathbf{K}_2^T \mathbf{S}_{y_2, n}^{-1} \mathbf{K}_2) (x - x_a), \quad (\text{A18})$$

i.e. the analysis state is the same as the output  $\hat{x}$  of a retrieval with a combined measurement vector from Eq. (A8). This means that we can a posteriori calculate the result that would be obtained by an optimal estimation retrieval using a combined measurement vector.

#### 645 A2.4 Requirements

The optimal a posteriori combination of two remote sensing products is possible, whenever: (1) the two remote sensing observations are made at the same time and detect the same location, (2) the problem is moderately non-linear (according to Chapter 5 of Rodgers, 2000), and (3) the individual retrieval output as listed by Eqs. (A11) to (A15) is made available. This is for the first retrieval the a posteriori covariances ( $\mathbf{S}_{\hat{x}}$ , which might also be reconstructed from  $\mathbf{A}$  and  $\mathbf{R}$  according to Eq. (A6)), the  
 650 averaging kernels ( $\mathbf{A}$ ), and the retrieved and a priori state vectors ( $\hat{x}$  and  $x_a$ , respectively). For the second retrieval we need the noise covariances ( $\mathbf{S}_{\hat{x}, n}$ ), the averaging kernels ( $\mathbf{A}$ ), and the retrieved and a priori state vectors ( $\hat{x}$  and  $x_a$ , respectively).

### Appendix B: Operator for transformation between linear and logarithmic scales

Linear scale differentials and logarithmic scale differentials are related by  $\Delta x = x \Delta \ln x$ . For transforming differentials or covariances of a state vector with dimension  $nal$  ( $nal$ : number of atmospheric levels) from logarithmic to linear scale we  
 655 define the  $nal \times nal$  diagonal matrix  $\mathbf{L}$ :

$$\mathbf{L} = \begin{pmatrix} \hat{x}_1 & 0 & \cdots & 0 \\ 0 & \hat{x}_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \hat{x}_{nal} \end{pmatrix}. \quad (\text{B1})$$

Here  $\hat{x}_i$  is the value of the  $i$ th element of the retrieved state vector (i.e. in case of an atmospheric  $\text{CH}_4$  state vector the  $\text{CH}_4$  mixing ratios retrieved at the  $i$ th model level).

A logarithmic scale averaging kernel matrix  $\mathbf{A}^1$  can then be expressed in the linear scale as:

$$660 \quad \mathbf{A} = \mathbf{L} \mathbf{A}^1 \mathbf{L}^{-1}. \quad (\text{B2})$$

Similarly a logarithmic scale covariance matrix  $\mathbf{S}^1$  can then be expressed in the linear scale as:

$$\mathbf{S} = \mathbf{L} \mathbf{S}^1 \mathbf{L}^T. \quad (\text{B3})$$



## Appendix C: Operators for column data

This appendix explains the calculation of operators for partial (and total) column data. Although some sections are similar to  
 665 Appendix C of Schneider et al. (2021) we think it is here a very useful reference, because it facilitates the reproducibility of  
 our results.

For converting mixing ratio profiles into amount profiles we set up a pressure weighting operator  $\mathbf{Z}$ , as a diagonal matrix  
 with the following entries:

$$Z_{i,i} = \frac{\Delta p_i}{g_i m_{\text{air}} \left(1 + \frac{m_{\text{H}_2\text{O}}}{m_{\text{air}}} \hat{x}_i^{\text{H}_2\text{O}}\right)}. \quad (\text{C1})$$

670 Using the pressure  $p_i$  at atmospheric grid level  $i$  we set  $\Delta p_1 = \frac{p_2 - p_1}{2} - p_1$ ,  $\Delta p_{nal} = p_{nal} - \frac{p_{nal} - p_{nal-1}}{2}$ , and  $\Delta p_i = \frac{p_{i+1} - p_i}{2} - \frac{p_i - p_{i-1}}{2}$  for  $1 < i < nal$ . Furthermore,  $g_i$  is the gravitational acceleration at level  $i$ ,  $m_{\text{air}}$  and  $m_{\text{H}_2\text{O}}$  the molecular mass of dry  
 air and water vapour, respectively, and  $\hat{x}_i^{\text{H}_2\text{O}}$  the retrieved or modelled water vapour mixing ratio at level  $i$ .

We define an operator  $\mathbf{W}$  for resampling fine gridded atmospheric amount profiles into coarse gridded atmospheric partial  
 column amount profiles. It has the dimension  $c \times nal$ , where  $c$  is the number of the resampled coarse atmospheric grid levels  
 675 and  $nal$ , the number of atmospheric levels of the original fine atmospheric grid. Each line of the operator has the value '1' for  
 the levels that are resampled and '0' for all other levels:

$$\mathbf{W} = \begin{pmatrix} 1 & \dots & 1 & 0 & \dots & \dots & \dots & \dots & 0 \\ 0 & \dots & 0 & 1 & \dots & 1 & 0 & \dots & 0 \\ 0 & \dots & \dots & \dots & \dots & 0 & 1 & \dots & 1 \end{pmatrix}. \quad (\text{C2})$$

In analogy we can define a row vector  $\mathbf{w}^T$  (with the dimension  $1 \times nal$ ) with all elements having the value '1', which allows  
 the resampling for the total column amounts.

### 680 C1 Column amounts

The kernel that describes how a change in the amount at a certain altitude affects the retrieved partial (or total) column amount  
 can be calculated as:

$$\mathbf{A}' = \mathbf{WZAZ}^{-1}. \quad (\text{C3})$$

For the total column we replace  $\mathbf{W}$  by  $\mathbf{w}^T$  and get the row vector  $\mathbf{a}'^T$  (dimension  $1 \times nal$ ). This is the total column kernel  
 685 provided by the TROPOMI data and it is typically written as  $\mathbf{a}^T$ . Figure 3 shows examples of such total and partial columns  
 amount kernels. The total column amount kernel can be interpolated to different altitude grids. For the applications in Sects. 2  
 and 3 we interpolate the TROPOMI total column amount kernel to the vertical grid used by the MUSICA IASI retrieval.

### C2 Column averaged mixing ratios

We can also combine the operators  $\mathbf{Z}$  and  $\mathbf{W}$  for the calculation of a pressure weighted resampling operator by:

$$690 \mathbf{W}^* = (\mathbf{WZW}^T)^{-1} \mathbf{WZ}. \quad (\text{C4})$$



This operator resamples linear scale mixing ratio profiles into linear scale partial column averaged mixing ratio profiles. Its inverse is calculated as:

$$\mathbf{W}^{*-1} = \mathbf{Z}^{-1} \mathbf{W}^{-1} (\mathbf{W} \mathbf{Z} \mathbf{W}^T), \quad (\text{C5})$$

with  $\mathbf{W}^{-1} = (\mathbf{W}^T \mathbf{W})^{-1} \mathbf{W}^T$ . The respective total column operators  $\mathbf{w}^{*T}$  and  $(\mathbf{w}^{*T})^{-1}$  can be calculated in analogy by replacing  $\mathbf{W}$  by  $\mathbf{w}^T$ .

With operator  $\mathbf{W}^*$  we can calculate a coarse gridded partial column averaged state  $\hat{\mathbf{x}}^*$  from the fine gridded linear mixing ratio state  $\hat{\mathbf{x}}$  by:

$$\hat{\mathbf{x}}^* = \mathbf{W}^* \hat{\mathbf{x}}. \quad (\text{C6})$$

The kernels matrix of the partial column averaged mixing ratio state can then be calculated from the fine gridded linear scale kernel matrix ( $\mathbf{A}$ ) by:

$$\mathbf{A}^* = \mathbf{W}^* \mathbf{A}. \quad (\text{C7})$$

This kernel describes how a change in the mixing ratio at a certain altitude affects the retrieved partial column averaged mixing ratio. Covariances of the partial column averaged mixing ratio state can be calculated from the corresponding covariance matrices of the fine gridded linear scale ( $\mathbf{S}$ ) by:

$$\mathbf{S}^* = \mathbf{W}^* \mathbf{S} \mathbf{W}^{*T}. \quad (\text{C8})$$

The respective calculations for total column averaged mixing ratios can be made by replacing  $\mathbf{W}^*$  by  $\mathbf{w}^{*T}$ . For the total column averaged mixing ratios the covariance is a simple variance (the scalar  $\mathbf{S}^*$ ) and the kernel has the dimension  $1 \times n_{ol}$ , i.e. it is a row vector  $\mathbf{a}^{*T}$ .

The total column amount kernel ( $\mathbf{a}_T$ ) provided with the TROPOMI data set can be converted into a total column averaged mixing ratio kernel  $\mathbf{a}_T^{*T}$  by the following calculation:

$$\mathbf{a}_T^{*T} = \mathbf{w}^{*T} \mathbf{A} = (\mathbf{w}^T \mathbf{Z} \mathbf{w})^{-1} \mathbf{a}_T^T \mathbf{Z}. \quad (\text{C9})$$

The total column averaged mixing ratio kernel  $\mathbf{a}_T^{*T}$  used in Sects. 2 and 3 is valid for the vertical grid used by the MUSICA IASI retrieval. It is calculated according to Eq. (C9), but using a TROPOMI total column amount kernel ( $\mathbf{a}_T$ ) that is interpolated onto the MUSICA IASI grid (see also Appendix C1).

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