# Convexity for invariant differential operators on semisimple symmetric spaces 

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Introduction. Let $X=G / H$ be a homogeneous space of a Lie group $G$, and let $D$ : $C^{\infty}(X) \rightarrow C^{\infty}(X)$ be a non-trivial $G$-invariant differential operator. One of the natural questions one can ask for the operator $D$ is whether it is solvable, in the sense that $D C^{\infty}(X)=C^{\infty}(X)$. If $G$ is the group of translations of $X=\mathbf{R}^{n}$ and $H$ is trivial, then $D$ has constant coefficients, and it is a well known result of Ehrenpreis and Malgrange that hence $D$ is solvable.

Assume for simplicity that $G / H$ carries an invariant measure. This measure induces a bilinear pairing of $C_{c}^{\infty}(X)$, the space of compactly supported smooth functions on $X$, with itself. Let $D^{*}$ denote the adjoint of $D$ with respect to this pairing. The strategy employed by Ehrenpreis and Malgrange was essentially to use the following properties of $D$ :
(i) There exists a fundamental solution for $D$, that is, $\delta \in D^{\prime}(X)^{H}$, where $\delta$ is the Dirac measure at the origin, and $\mathcal{D}^{\prime}(X)^{H}$ is the space of left- $H$-invariant distributions on $X$.
(ii) For each compact set $\Omega \subset X$ there exists a compact set $\Omega^{\prime} \subset X$ such that

$$
\operatorname{supp} D^{*} f \subset \Omega \Rightarrow \operatorname{supp} f \subset \Omega^{\prime}
$$

for all $f \in C_{c}^{\infty}(X)$.
In fact, for $X=\mathbf{R}^{n}$ one can take as $\Omega^{\prime}$ the convex hull of $\Omega$. For this reason the support property (ii) has become known as the $D$-convexity of $X$. It follows from (i)-(ii) that $D$ is solvable.

The strategy has been applied in other cases as well, for example by Helgason in [14], where surjectivity is established for all non-trivial invariant differential operators on a Riemannian symmetric space. In a variant of the strategy (i) is replaced by the following weaker property (semi-global solvability):
(i') For each compact set $\Omega \subset X$ and each function $g \in C^{\infty}(X)$ there exists a function $f \in C^{\infty}(X)$ such that $D f=g$ on $\Omega$.
The conjunction of (i') and (ii) is equivalent with the solvability of $D$ (see Theorem 1 below). This is used by Rauch and Wigner in [19] where it is proved that the Casimir operator on a semisimple Lie group is solvable, and more generally by Chang in [5] where the Laplace-Beltrami operator on a semisimple symmetric space is shown to be solvable.

The purpose of the present paper is to give, also for a semisimple symmetric space $X=G / H$, a sufficient condition on an invariant differential operator $D$ to imply (ii), the $D$-convexity of $X$. When $G / H$ has rank one, our result follows from the above mentioned result of Chang, since the algebra $D(G / H)$ of all invariant differential operators in this case is generated by the Laplace-Beltrami operator. In general this is not so, and our
result shows the $D$-convexity for a significantly larger class of operators $D$. In particular, when $G / H$ is split (that is, it has a vectorial Cartan subspace), all non-trivial elements of $\mathrm{D}(G / H)$ satisfy our condition.

Though we do not consider the properties (i) or (i') in this paper, we notice that in the above-mentioned references, an important step towards obtaining ( $\mathrm{i}^{\prime}$ ) is to prove that $D^{*}$ acts injectively on, say $C_{c}^{\infty}(X)$ (see for example [5]). In fact the injectivity of $D^{*}$ is an immediate consequence of ( $\mathrm{i}^{\prime}$ ). In the present case of a semisimple symmetric space, the sufficient condition that we give for (ii) is also sufficient for $D^{*}$ to be injective.

We also give a condition on $D$, which is necessary for both the $D$-convexity and the injectivity. In particular, when $G / H$ is not split, there exists a non-trivial operator $D \in \mathbb{D}(G / H)$, which does not have these properties and hence is not solvable. This provides a wide class of spaces $G / H$ for which there exist non-solvable non-trivial operators. Unfortunately our necessary condition is weaker than the sufficient condition, and the complete classification (for non-split $G / H)$ of all $D \in \mathbb{D}(G / H)$ which have these properties remains open.

In the special case where the semisimple symmetric space is Riemannian (that is, when $H$ is compact), we have that $G / H$ is split and thus our condition reduces to the requirement that $D$ is non-trivial. In this case our result is part of the above-mentioned proof by Helgason that $D$ is surjective (see [14, p.473]). Helgason's proof is based on his inversion formula and Paley-Wiener theorem for the Fourier transform on the Riemannian symmetric space $X$. These results are in turn based on the work of Harish-Chandra. Simplifications avoiding these strong tools were given by Chang, $[\mathbf{7}]$, and Dadok, $[\mathbf{8}]$. In another special case, that of a semisimple Lie group considered as a symmetric space, our result was obtained by Duflo and Wigner, [9].

All of the references mentioned above, except [14], use the uniqueness theorem of Holmgren to derive the $D$-convexity of $X$, and so do we. The main difficulty in the present generalization lies in the handling of the more complicated geometry of $X$. Our main tool to overcome this difficulty is the convexity theorem of [1].

In [3] (see also [4]) the result of the present paper will be applied to obtain injectivity of the Fourier transform on $C_{c}^{\infty}(X)$. Our reasoning will thus be the opposite of the original reasoning of Helgason in the Riemannian case: we shall deduce properties of the Fourier transform from the $D$-convexity.

Motivation. As mentioned in the introduction the main motivation for studying $D$ convexity is the following theorem. Here $G$ is a Lie group (with at most countably many connected components) and $H$ is a closed subgroup, of which we only assume that $G / H$ carries an invariant measure (this assumption is only used for defining $D^{*}$ ).

Theorem 1. Let $D \in \mathbb{D}(G / H)$ be an invariant differential operator. Then $D$ is solvable if and only if (i') and (ii) hold.

Proof: This follows from [21, Ch.I, Thm.3.3], using regularization by $C_{c}^{\infty}(G)$ to prove the equivalence of our definition of $D$-convexity with that of [21, Ch.I, Def.3.1]. Note also the final remark of that section in loc.cit.

Notation. From now on, let $G$ be a real reductive Lie group of Harish-Chandra's class, $\tau$ an involution of $G$, and $H$ an open subgroup of the fixed point group $G^{\tau}$. Then $X=G / H$ is a reductive symmetric space of Harish-Chandra's class (see [2]). Let $K$ be a $\tau$-stable maximal compact subgroup of $G$, and let $\theta$ be the associated Cartan involution. Let $\mathfrak{g}=\mathfrak{h}+\mathfrak{q}=\mathfrak{k}+\mathfrak{p}$ be the eigen-decompositions of the Lie algebra $\mathfrak{g}$ induced by $\tau$ and $\theta$, then $\mathfrak{h}$ and $\mathfrak{k}$ are the Lie algebras of $H$ and $K$, respectively. Let $B$ be a non-degenerate, $G$ - and $\tau$-invariant bilinear form on $\mathfrak{g}$ which extends the Killing form on $[\mathfrak{g}, \mathfrak{g}]$, and which is negative definite on $\mathfrak{k}$ and positive definite on $\mathfrak{p}$. Then the above-mentioned eigen-decompositions are orthogonal with respect to $B$.

Fix a maximal abelian subspace $\mathfrak{a}$ of $\mathfrak{p} \cap \mathfrak{q}$, and a maximal abelian subspace (a Cartan subspace) $\mathfrak{a}_{1}$ of $\mathfrak{q}$, containing $\mathfrak{a}$. Then $\mathfrak{a}=\mathfrak{a}_{1} \cap \mathfrak{p}$. Let $\mathfrak{m}$ be the orthocomplement (with respect to $B$ ) of $\mathfrak{a}$ in its centralizer $\mathfrak{g}^{\mathfrak{a}}$, and let $\mathfrak{a}_{m}=\mathfrak{a}_{1} \cap \mathfrak{m}$. Via the orthogonal decomposition $\mathfrak{a}_{1}=\mathfrak{a}_{m}+\mathfrak{a}$ we view $\mathfrak{a}_{m c}{ }_{c}^{*}$ and $\mathfrak{a}_{c}^{*}$ as subspaces of $\mathfrak{a}_{1 c}^{*}$. Let $\Sigma$ and $\Sigma_{1}$ denote the root systems of $\mathfrak{a}$ and $\mathfrak{a}_{1}$ in $\mathfrak{g}_{c}$, respectively, then $\Sigma$ consists of the non-trivial restrictions to $\mathfrak{a}$ of the elements of $\Sigma_{1}$. Denote by $W$ and $W_{1}$ the Weyl groups of these two root systems, then $W$ is naturally isomorphic to $N_{W_{1}}(\mathfrak{a}) / Z_{W_{1}}(\mathfrak{a})$, the normalizer modulo the centralizer of $\mathfrak{a}$ in $W_{1}$, and to $N_{K}(\mathfrak{a}) / Z_{K}(\mathfrak{a})$, the normalizer modulo the centralizer of $\mathfrak{a}$ in $K$. Let $W_{K \cap H}$ be the canonical image of $N_{K \cap H}(\mathfrak{a})$ in $W$.

Recall that $G=K A H$, and that if $g=k a h$ according to this decomposition, then the orbit $W_{K \cap H} \log a$ is uniquely determined by $g$. For a $W_{K \cap H}$-invariant set $S \subset \mathfrak{a}$, we denote the subset $K \exp (S) H$ of $X$ by $X_{S}$. Then $S=\left\{\log a \mid a H \in X_{S}\right\}$, and every $K$-invariant subset of $X$ is of the form $X_{S}$.

Invariant differential operators. Let $\mathbb{D}(G / H)$ be the algebra of invariant differential operators on $G / H$. Let $U(\mathfrak{g})$ be the enveloping algebra of $\mathfrak{g}_{c}$ and $U(\mathfrak{g})^{H}$ the subalgebra of $H$-invariant elements, then there is a natural isomorphism of the quotient $U(\mathfrak{g})^{H} /\left(U(\mathfrak{g})^{H} \cap\right.$ $\left.U(\mathfrak{g}) \mathfrak{h}_{c}\right)$ with $\mathbb{D}(G / H)$, induced by the right action $R$ of $U(\mathfrak{g})$ on $C^{\infty}(G)$ (see [15, p. 285]).

Let $\Sigma_{1}^{+}$be a positive system for $\Sigma_{1}$, and let $\mathfrak{n}_{1}$ be the sum of the corresponding positive root spaces $\mathfrak{g}_{c}^{\alpha}\left(\alpha \in \Sigma_{1}^{+}\right)$. We have the following direct sum decomposition

$$
\begin{equation*}
\mathfrak{g}_{c}=\mathfrak{n}_{1}+\mathfrak{a}_{1 c}+\mathfrak{h}_{c} . \tag{1}
\end{equation*}
$$

Using this decomposition and Poincare-Birkhoff-Witt, a map ' $\gamma: U(\mathfrak{g}) \rightarrow U\left(\mathfrak{a}_{1}\right)$ is defined by $u \equiv{ }^{\prime} \gamma(u)$ modulo $\mathfrak{n}_{1} U(\mathfrak{g})+U(\mathfrak{g}) \mathfrak{h}_{c}$. From this map an algebra isomorphism $\gamma$ of $\mathbb{D}(G / H) \simeq U(\mathfrak{g})^{H} /\left(U(\mathfrak{g})^{H} \cap U(\mathfrak{g}) \mathfrak{h}_{c}\right)$ onto $S\left(\mathfrak{a}_{1}\right)^{W_{1}}$, the set of $W_{1}$-invariant elements in the symmetric algebra of $\mathfrak{a}_{1 c}$ (which is isomorphic to $U\left(\mathfrak{a}_{1}\right)$ because $\mathfrak{a}_{1}$ is abelian), is obtained by letting $\gamma(u)(\lambda)={ }^{'} \gamma(u)\left(\lambda+\rho_{1}\right)$ for $u \in U(\mathfrak{g})^{H}, \lambda \in \mathfrak{a}_{1 c}^{*}$ (see [11, p. 15, Thm. 3]). Here $\rho_{1} \in \mathfrak{a}_{1}{ }_{c}^{*}$ is given by half the trace of the adjoint action on $\mathfrak{n}_{1}$. Thus $\mathbb{D}(G / H)$ is identified as a polynomial algebra with $\operatorname{dim} \mathfrak{a}_{1}$ independent generators.

Assume that $\Sigma_{1}^{+}$is chosen to be compatible with $\mathfrak{a}$, that is, the set of nonzero restrictions to $\mathfrak{a}$ of elements from $\Sigma_{1}^{+}$is a positive system $\Sigma^{+}$for $\Sigma$. Let $\mathfrak{n}$ be the sum of the corresponding positive root spaces $\mathfrak{g}^{\alpha}\left(\alpha \in \Sigma^{+}\right)$, then we also have the following direct sum decompostion

$$
\begin{equation*}
\mathfrak{g}=\mathfrak{n}+\mathfrak{m}+\mathfrak{a}+\mathfrak{h} \tag{2}
\end{equation*}
$$

Let $\rho \in \mathfrak{a}^{*}$ and $\rho_{m} \in \mathfrak{a}_{m}{ }_{c}^{*}$ be given by half the trace of the adjoint actions on $\mathfrak{n}$, and on $\mathfrak{n}_{1} \cap \mathfrak{m}_{c}$, respectively.

Using the decomposition (2) a map ' $\eta: U(\mathfrak{g}) \rightarrow U(\mathfrak{a})$ is defined by $u \equiv{ }^{\prime} \eta(u)$ modulo $\left(\mathfrak{n}_{c}+\mathfrak{m}_{c}\right) U(\mathfrak{g})+U(\mathfrak{g}) \mathfrak{h}_{c}$, and we obtain by restriction to $U(\mathfrak{g})^{H}$ a homomorphism, also denoted ' $\eta$, from $\mathbb{D}(G / H) \simeq U(\mathfrak{g})^{H} /\left(U(\mathfrak{g})^{H} \cap U(\mathfrak{g}) \mathfrak{h}_{c}\right)$ into $S(\mathfrak{a})$. Let $\eta(D) \in S(\mathfrak{a})$ be defined by $\eta(D)(\lambda)=' \eta(D)(\lambda+\rho)$.

Lemma 1. We have

$$
\begin{equation*}
\eta(D)(\lambda)=\gamma(D)\left(\lambda \Leftrightarrow \rho_{m}\right) \tag{3}
\end{equation*}
$$

for all $D \in \mathbb{D}(G / H), \lambda \in \mathfrak{a}_{c}^{*}$. Moreover $\eta(D) \in S(\mathfrak{a})^{W}$, and $\eta(D)$ is independent of the choice of $\Sigma^{+}$.

Proof: We first prove the following equation:

$$
\begin{equation*}
\rho_{1}=\rho+\rho_{m} \tag{4}
\end{equation*}
$$

We have $\rho_{1}=\frac{1}{2} \sum_{\alpha \in \Sigma_{1}^{+}}\left(\operatorname{dim} \mathfrak{g}_{c}^{\alpha}\right) \alpha$ and $\rho_{m}=\frac{1}{2} \sum_{\alpha \in \Sigma_{1}^{+},\left.\alpha\right|_{\mathfrak{a}}=0}\left(\operatorname{dim} \mathfrak{g}_{c}^{\alpha}\right) \alpha$. Let

$$
\bar{\rho}=\rho_{1} \Leftrightarrow \rho_{m}=\frac{1}{2} \sum_{\alpha \in \Sigma_{1}^{+},\left.\alpha\right|_{\mathfrak{a}} \neq 0}\left(\operatorname{dim} \mathfrak{g}_{c}^{\alpha}\right) \alpha,
$$

then it is clear that $\bar{\rho}=\rho$ on $\mathfrak{a}$. On the other hand, since the set of $\alpha \in \Sigma_{1}^{+}$with $\left.\alpha\right|_{\mathfrak{a}} \neq 0$ is $\sigma \theta$-invariant, we get that $\sigma \theta \bar{\rho}=\bar{\rho}$, and hence $\bar{\rho}=0$ on $\mathfrak{a}_{m}$, so that in fact $\bar{\rho}=\rho$.

Since $\mathfrak{m}_{c}=\mathfrak{m}_{c} \cap \mathfrak{n}_{1}+\mathfrak{a}_{m c}+\mathfrak{m}_{c} \cap \mathfrak{h}_{c}$ it follows from (1) and (2) that $\quad \eta(D)(\lambda)={ }^{\prime} \gamma(D)(\lambda)$. From this and (4) we get (3).

The proof will be completed by using the following observation: Every element $w \in W$ can be represented by an element $\bar{w} \in N_{W_{1}}(\mathfrak{a})$; this element also normalizes $\mathfrak{a}_{m}$, and can be chosen so that $\bar{w} \rho_{m}=\rho_{m}$.

The $W$-invariance of $\eta(D)$ now follows from (3) and the $W_{1}$-invariance of $\gamma(D)$, in view of the above observation. By using this observation once more, it follows from (3) and the fact that $\gamma$ is independent of the choice of the positive system $\Sigma_{1}^{+}$, that $\eta$ is independent of the choice of $\Sigma^{+}$.

Let $s: S(\mathfrak{g}) \rightarrow U(\mathfrak{g})$ be the symmetrization map, then the restriction of $s$ to the set $S(\mathfrak{q})^{H}$ of $H$-invariants in $S(\mathfrak{q})$ gives rise to a linear bijection (also denoted by $s$ ) of $S(\mathfrak{q})^{H}$ with $\mathbb{D}(G / H)$ (see [15, p. 287, Thm. 4.9]). A differential operator $D \in \mathbb{D}(G / H)$ is called homogeneous if it is the image of a homogeneous element of $S(\mathfrak{q})^{H}$. For $P \in S(\mathfrak{q})^{H}$ let $r(P) \in S(\mathfrak{a})$ denote the restriction of $P$ to $\mathfrak{a}$. Here $P$ is identified with a polynomial on $\mathfrak{q}$ by means of the Killing form.

Lemma 2. Let $D \in \mathbb{D}(G / H)$ be non-constant and let $D=s(P), P \in S(\mathfrak{q})^{H}$. Then

$$
\begin{equation*}
\operatorname{deg}(\eta(D) \Leftrightarrow r(P))<\operatorname{deg} P=\operatorname{order} D \tag{5}
\end{equation*}
$$

In particular, if $D$ is homogeneous then $\operatorname{deg} \eta(D)=$ order $D$ if and only if $r(P) \neq 0$.
Proof: That order $D=\operatorname{deg} P$ follows from the explicit expression for $s(P)$ in $[\mathbf{1 5}, \mathrm{p} .287$, Thm. 4.9]. Let $r_{1}(P)$ denote the restriction of $P$ to $\mathfrak{a}_{1}$, then it follows from [15, p. 305, eq. (38)] that

$$
\begin{equation*}
\operatorname{deg}\left(\gamma(D) \Leftrightarrow r_{1}(P)\right)<\operatorname{deg} P \tag{6}
\end{equation*}
$$

It follows from $(3)$ that $\eta(D) \Leftrightarrow r(P)$ and the restriction of $\gamma(D) \Leftrightarrow r_{1}(P)$ to $\mathfrak{a}$ have the same degree, and hence (5) follows from (6). If $P$ is homogeneous, then either $\operatorname{deg} r(P)=\operatorname{deg} P$ or $r(P)=0$, and the final statement follows from (5).

Notice that $r_{1}(P)$ has the same degree as $P$ (to see this, let $P$ be homogeneous, then $\operatorname{deg} r_{1}(P)=\operatorname{deg} P$ unless $r_{1}(P)=0$. But $r_{1}(P)=0$ implies $P=0$ by the $H$-invariance, because $\operatorname{Ad}(H)\left(\mathfrak{a}_{1}\right)$ contains an open subset of $\left.\mathfrak{q}\right)$. Hence it follows from (6) that also $\gamma(D)$ has this degree (which equals the order of $D$ ). Thus $\gamma$ is a degree preserving isomorphism of $\mathbb{D}(G / H)$ onto $S\left(\mathfrak{a}_{1}\right)^{W_{1}}$.

However, a similar statement is not valid for $\eta(D)$; its degree can be strictly smaller than that of $D$. In fact $\eta$ is not injective in general: Since $\mathbb{D}(G / H)$ and $S(\mathfrak{a})^{W}$ are polynomial algebras in $\operatorname{dim} \mathfrak{a}_{1}$ and $\operatorname{dim} \mathfrak{a}$ algebraically independent generators, respectively, $\eta$ is not injective if $\mathfrak{a} \neq \mathfrak{a}_{1}$ (otherwise it would cause the existence of an injection of the quotient field of $\mathbb{D}(G / H)$ into the quotient field of $S(\mathfrak{a})^{W}$, which is impossible, since their transcendence degrees over $\mathbf{C}$ are $\operatorname{dim} \mathfrak{a}_{1}$ and $\operatorname{dim} \mathfrak{a}$, respectively (see [22, Ch.II, §12])). On the other hand, if $\mathfrak{a}_{1}=\mathfrak{a}$, in which case the symmetric space $G / H$ is called split, then $\eta$ is injective since it equals $\gamma$. Examples of split symmetric spaces are the Riemannian symmetric spaces and the symmetric spaces of $K_{\epsilon}$-type (see [18]). In the special case (the 'group case') of a semisimple Lie group $G^{\prime}$ considered as a symmetric space, where $G$ is $G^{\prime} \times G^{\prime}$ and $H$ is the diagonal, the notion of split for the space $G / H$ coincides with the notion of split (also called a normal real form) for $G^{\prime}$.

Notice also that $\eta$ in general is not surjective. This can be seen already in the group case mentioned above, where $\mathbb{D}(G / H)$ is naturally isomorphic with $Z\left(\mathfrak{g}^{\prime}\right)$, the center of $U\left(\mathfrak{g}^{\prime}\right)$, and where $\eta$ by transference under a suitable isomorphism can be identified with the natural homomorphism of $Z\left(\mathfrak{g}^{\prime}\right)$ into $\mathbb{D}\left(G^{\prime} / K^{\prime}\right)$. It is known from $[\mathbf{1 3}, \mathbf{1 6}]$ that this homomorphism is surjective when $G^{\prime}$ is classical, but not surjective for certain exceptional groups $G^{\prime}$.

For $v \in S\left(\mathfrak{a}_{1}\right)$ or $v \in S(\mathfrak{a})$ we define $v^{*}$ by $v^{*}(\nu)=v(\Leftrightarrow \nu)$, where $\nu \in \mathfrak{a}_{1 c}^{*}$ or $\nu \in \mathfrak{a}_{c}^{*}$.
Lemma 3. Let $D \in \mathbb{D}(G / H)$. Then $\gamma\left(D^{*}\right)=\gamma(D)^{*}$ and $\eta\left(D^{*}\right)=\eta(D)^{*}$.
Proof: Choose $u \in U(\mathfrak{g})^{H}$ such that $D=R_{u}$, and let $v \mapsto \breve{v}$ be the antiautomorphism of $U(\mathfrak{g})$ determined by $\breve{v}=\Leftrightarrow$ for $v \in \mathfrak{g}$. Using [15, Ch.I, Thm.1.9 and Lemma 1.10] it is easily seen that $D^{*}=R_{\breve{u}}$. The equality for $\gamma$ will follow if we prove that $\gamma(\breve{u})=\gamma(u)^{*}$ for $u \in U(\mathfrak{g})^{H}$. Using [11, p.16, Cor.4] it is now seen that it suffices to consider the case of a Riemannian symmetric space, that is, we may assume that $H$ is compact. In this special case, the statement is proved in [15, p.307]. This proves that $\gamma\left(D^{*}\right)=\gamma(D)^{*}$.

From (3) we now get that

$$
\eta\left(D^{*}\right)(\lambda)=\gamma\left(D^{*}\right)\left(\lambda \Leftrightarrow \rho_{m}\right)=\gamma(D)\left(\Leftrightarrow \lambda+\rho_{m}\right) .
$$

Using that there exists an element $w$ in the Weyl group of the root system of $\mathfrak{a}_{m}$ in $\mathfrak{m}$ such that $w \rho_{m}=\Leftrightarrow \rho_{m}$, and that this Weyl group is a subgroup of $W_{1}$, we get that

$$
\gamma(D)\left(\Leftrightarrow \lambda+\rho_{m}\right)=\gamma(D)\left(\Leftrightarrow \lambda \Leftrightarrow \rho_{m}\right)=\eta(D)(\Leftrightarrow \lambda),
$$

proving the equality for $\eta$.
In the final section of this paper we relate $\eta(D)$ to the radial part of $D$ with respect to the KAH decomposition. In particular we shall prove that the condition that $\eta(D)=0$ has the following strong consequence:

Lemma 4. Let $D \in \mathbb{D}(G / H)$ and assume that $\eta(D)=0$. Then $D f=0$ for all $K$-invariant smooth functions $f$ on $G / H$.

Convexity. We are now ready to state our main theorem:
Theorem 2. Let $D \in \mathbb{D}(G / H)$ be non-zero.
(i) If $\operatorname{deg} \eta(D)=$ order $D$ then

$$
\operatorname{supp} f \subset X_{S} \Leftrightarrow \operatorname{supp} D f \subset X_{S} \Leftrightarrow \operatorname{supp} D^{*} f \subset X_{S}
$$

for all $f \in C_{c}^{\infty}(X)$ and all convex, compact $W_{K \cap H}$-invariant sets $S \subset \mathfrak{a}$. In particular, $X$ is $D$-convex, and $D^{*}$ is injective on $C_{c}^{\infty}(X)$.
(ii) If $\eta(D)=0$ there exists for each closed ball $S \subset \mathfrak{a}$, centered at the origin, a function $f \in C_{c}^{\infty}(X)$ such that $D^{*} f=0$ and $\operatorname{supp} f=X_{S}$. In particular, $X$ is not $D$-convex, and $D^{*}$ is not injective on $C_{c}^{\infty}(X)$.

Proof: We first prove (i). The implication of $\operatorname{supp} D f \subset X_{S}$ from $\operatorname{supp} f \subset X_{S}$ is obvious. Assume supp $D f \subset X_{S}$. Expanding $f$ as a sum of $K$-finite functions, we have, since $X_{S}$ is $K$-invariant, that $f$ is supported in $X_{S}$ if and only if all the summands are supported in $X_{S}$. Moreover, $D$ can be applied termwise to the sum, and hence we see that we may assume $f$ to be $K$-finite. Then the support of $f$ is $K$-invariant, and it suffices to prove that $\operatorname{supp} f \cap A H \subset \exp (S) H$.

Let $m=\operatorname{order} D$, then $m=\operatorname{deg} \eta(D)$ by the assumption on $D$. Let $u_{0}$ denote the homogeneous part of $\eta(D)$ of degree $m$, then $u_{0} \neq 0$. Notice that $u_{0}$ is also the homogeneous part of ' $\eta(D)$ of degree $m=\operatorname{deg}{ } \quad \eta(D)$ for any choice of $\Sigma^{+}$.

Assume that $\operatorname{supp} f \cap A H \not \subset \exp (S) H$, and write

$$
\operatorname{supp}_{\mathfrak{a}} f=\{Y \in \mathfrak{a} \mid \exp (Y) H \in \operatorname{supp} f\} .
$$

Then $\operatorname{supp}_{\mathfrak{a}} f$ is compact and not contained in $S$. By the convexity of $S$ there exists a non-empty open set of linear forms $\lambda \in \mathfrak{a}^{*}$ with the property that

$$
\begin{equation*}
0<\max _{Y \in S} \lambda(Y)<\max _{Y \in \text { supp }_{\mathfrak{a}} f} \lambda(Y) . \tag{7}
\end{equation*}
$$

Since $u_{0} \neq 0$ there exists a $\lambda \in \mathfrak{a}^{*}$ with $u_{0}(\lambda) \neq 0$, and satisfying (7). Let $Y_{0} \in \operatorname{supp}_{\mathfrak{a}} f$ be a point where the value on the right side of (7) is attained. Then $Y_{0} \notin S$ and we have that

$$
\begin{equation*}
\lambda(Y) \leq \lambda\left(Y_{0}\right), \quad\left(Y \in \operatorname{supp}_{\mathfrak{a}} f\right) . \tag{8}
\end{equation*}
$$

Let $a_{0}=\exp Y_{0}$, then

$$
\begin{equation*}
a_{0} H \notin \operatorname{supp} D f \tag{9}
\end{equation*}
$$

by the assumption on $\operatorname{supp} D f$, and

$$
\begin{equation*}
a_{0} H \in \operatorname{supp} f . \tag{10}
\end{equation*}
$$

Choose a positive system $\Sigma^{+}$such that $\lambda$ is antidominant, and let $\mathfrak{n}$ and $N$ be given correspondingly. Let $\Omega$ denote the open (see [20, Prop. 7.1.8]) subset $\Omega=$ NMAH of $X=G / H$, and define $g \in C^{\infty}(\Omega)$ by $g(n m a H)=\lambda(\log a)$ for $n \in N, m \in M, a \in A$. We claim that

$$
\begin{equation*}
f=0 \quad \text { on } \quad\left\{x \in \Omega \mid g(x)>g\left(a_{0}\right)\right\} . \tag{11}
\end{equation*}
$$

To prove (11) let $x=n m a H \in \Omega \cap \operatorname{supp} f$. Then we must show that $g(x) \leq g\left(a_{0}\right)$, or equivalently, that $\lambda(\log a) \leq \lambda\left(Y_{0}\right)$. To see that this holds, write

$$
n m a=k \exp (Z) h, \quad\left(k \in K, Z \in \mathfrak{a}, h \in H_{e}\right)
$$

according to the $G=K A H_{e}$ decomposition; here $H_{e}$ denotes the identity component of $H$. Then

$$
\exp (Z) h \in K N M a=K M a N
$$

and by the convexity theorem of $[\mathbf{1}, \mathrm{Thm} .3 .8]$ it follows that $\log a=U+V$, where $U$ is contained in the convex hull of $W_{K \cap H} Z$, and $V$ belongs a certain subcone of the closed convex cone $\left\{V \in \mathfrak{a} \mid\langle V, Y\rangle \geq 0, Y \in \mathfrak{a}^{+}\right\}$, which is dual to the positive Weyl chamber $\mathfrak{a}^{+}$. In particular, $\lambda(V) \leq 0$ by the antidominance of $\lambda$, and hence

$$
\lambda(\log a) \leq \lambda(U) \leq \max _{w \in W_{K \cap H}} \lambda(w Z)
$$

Now $\exp (w Z) H=w \exp (Z) H=w k^{-1} x H$ for $w \in W_{K \cap H}$, and from $x \in \operatorname{supp} f$ and the $K$-invariance of the support we then see that $\exp (w Z) H \in \operatorname{supp} f$. Hence $w Z \in \operatorname{supp}_{\mathfrak{a}} f$, and we conclude by (8) that

$$
\lambda(\log a) \leq \lambda\left(Y_{0}\right)
$$

This implies (11).
Let $\sigma(D)$ be the principal symbol of $D$. We have

$$
\begin{equation*}
\sigma(D)\left(d g\left(a_{0}\right)\right)=\frac{1}{m!} D\left(\left(g \Leftrightarrow g\left(a_{0}\right)\right)^{m}\right)\left(a_{0}\right) . \tag{12}
\end{equation*}
$$

It follows immediately from the definition of $g$ that $R_{u} g=0$ for $u \in U(\mathfrak{g}) \mathfrak{h}_{c}$. Moreover, since $g$ is left $N M$-invariant, and since $\mathfrak{n}$ and $\mathfrak{m}$ are normalized by $A$, we also have that $R_{u} g(a)=0$ for $a \in A, u \in(\mathfrak{n}+\mathfrak{m})_{c} U(\mathfrak{g})$. Hence $D g(a)=R_{{ }_{\eta(D)} g} g(a)$. Applying the same reasoning to the function $\left(g \Leftrightarrow g\left(a_{0}\right)\right)^{m}$ we obtain that

$$
\begin{equation*}
D\left(\left(g \Leftrightarrow g\left(a_{0}\right)\right)^{m}\right)(a)=R_{\eta(D)}\left(g \Leftrightarrow g\left(a_{0}\right)\right)^{m}(a)=m!u_{0}(\lambda) . \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
\sigma(D)\left(d g\left(a_{0}\right)\right) \neq 0 \tag{14}
\end{equation*}
$$

by the assumption on $\lambda$.
From (9), (11) and (14) it follows by Holmgren's uniqueness theorem ([17, Thm. 5.3.1]) that $f=0$ on a neighbourhood of $a_{0} H$, contradicting (10). This completes the proof of the first biimplication in (i). From Lemma 3 we get that $D^{*}$ also satisfies the assumption of (i), and hence the remaining statements in (i) follow.

We now prove (ii). Let $S$ be the ball of radius $R$ centered at the origin, and let $\varphi \in C^{\infty}(\mathbb{R})$ be positive on $\left[0 ; R^{2}\left[\right.\right.$ and zero on $\left[R^{2} ; \infty\left[\right.\right.$. Define $f(k a H)=\varphi\left(\|\log a\|^{2}\right)$ for $k \in K, a \in A$. Then $f \in C^{\infty}(X)$ by [10, Thm. 4.1], and we clearly have $\operatorname{supp} f=X_{S}$. Now (ii) follows from Lemma 4.

Corollary 1.
(i) If $X=G / H$ is split, then $X$ is $D$-convex and $D$ is injective on $C_{c}^{\infty}(X)$ for all non-trivial invariant differential operators $D$.
(ii) If $X$ is not split there exists a non-trivial invariant differential operator $D$, such that $X$ is not $D$-convex and which is not injective on $C_{c}^{\infty}(X)$.

REMARK 1. By regularization it follows that the statements of Theorem 2 and its corollary hold with $C_{c}^{\infty}(X)$ replaced by the space of compactly supported distributions on $X$.

REMARK 2. An explicit example of an operator $D$ as in part (ii) of Theorem 2 and its corollary is given in [6], where it is shown that the "imaginary part" $C_{i}$ of the Casimir operator on a complex semisimple Lie group $G^{\prime}$ is not solvable. Viewing $G^{\prime}$ as a symmetric space for $G^{\prime} \times G^{\prime}$ it is actually easily seen that $\eta\left(C_{i}\right)=0$ (see also loc. cit. p. ?).

The radial part. Let $D \in \mathbb{D}(G / H)$. Choose a positive system $\Sigma^{+}$and let $A^{+} \subset A$ be the corresponding open chamber. Via the canonical map from $G$ to $G / H$ we identify $A^{+}$with a submanifold of $X$. According to [15, p. 259] there exists a unique differential operator $\Pi(D)$ on $A^{+}$such that $\left.(D f)\right|_{A^{+}}=\Pi(D)\left(\left.f\right|_{A^{+}}\right)$for all $K$-invariant smooth functions $f$ on $X . \Pi(D)$ is called the radial part of $D$. The following result establishes a connection between $\Pi(D)$ and $\eta(D)$. It is a generalization of [12, p. 267, Lemma 26] (see also [15, p. 308, Prop. 5.23]).

Let $\mathfrak{R}^{+}$denote the ring of analytic functions $\varphi$ on $A^{+}$which can be expanded in an absolutely convergent series on $A^{+}$with zero constant term:

$$
\varphi=\sum_{\nu \in \Lambda} c_{\nu} e^{-\nu}, \quad c_{\nu} \in \mathbb{C}, c_{0}=0
$$

where the sum is over the set $\Lambda=\mathbb{N} \Sigma^{+}$and where $e^{-\nu}$ is defined by $e^{-\nu}(a)=e^{-\nu(\log a)}$.
Proposition 1. Let $D \in \mathbb{D}(G / H)$. There exist a finite number of elements $v_{i} \in S(\mathfrak{a})$ and functions $g_{i} \in \mathfrak{R}^{+}$such that

$$
\begin{equation*}
\Pi(D)=e^{-\rho} R_{\eta(D)} \circ e^{\rho}+\sum_{i} g_{i} R_{v_{i}} \tag{15}
\end{equation*}
$$

on $A^{+}$. Moreover the order $m$ of $\Pi(D)$ equals the degree of $\eta(D)$, and we can select the $v_{i}$ such that

$$
\begin{equation*}
\operatorname{deg} v_{i} \leq m \Leftrightarrow 1 \tag{16}
\end{equation*}
$$

for all $i$ (where a negative degree of $v_{i}$ means that $v_{i}=0$ ). In particular, $\Pi(D)=0$ if and only if $\eta(D)=0$.

Proof: The existence of the $v_{i}$ and $g_{i}$ such that (15) holds follows from [2, Lemma 3.9]. It remains to prove (16) (from the lemma of loc. cit. we only get that $\operatorname{deg} v_{i}<\operatorname{order}(D)$, which is not sharp enough to conclude (16), because the order of $\Pi(D)$ in general may be smaller than that of $D$ ).

Let

$$
\begin{equation*}
\Pi(D)=\sum_{\nu \in \Lambda} e^{-\nu} R_{v_{\nu}} \tag{17}
\end{equation*}
$$

be the expansion of $\Pi(D)$ derived from (15), where $v_{\nu} \in S(\mathfrak{a})$ and where $v_{0}$ is given by $v_{0}(\lambda)=\eta(D)(\lambda+\rho)$. We claim that

$$
\begin{equation*}
\operatorname{deg} v_{\nu} \leq \operatorname{deg} v_{0} \Leftrightarrow 1 \quad \text { for all } \quad \nu \neq 0 \tag{18}
\end{equation*}
$$

from which both the statement that order $\Pi(D)=\operatorname{deg} \eta(D)$ and (16) follow. We shall obtain (18) by means of a recursion formula for the $v_{\nu}$, derived from the relation $L_{X} D=$ $D L_{X}$, where $L_{X}$ is the Laplace-Beltrami operator on $X$ given in terms of the Casimir operator $\omega \in U(\mathfrak{g})^{H}$ by $L_{X}=R_{\omega}$.

The radial part of $L_{X}$ is easily computed (see [10, eq. (4.12)]):

$$
\begin{equation*}
\Pi\left(L_{X}\right)=J^{-1 / 2}\left(L_{A} \circ J^{1 / 2} \Leftrightarrow L_{A}\left(J^{1 / 2}\right)\right) \tag{19}
\end{equation*}
$$

where $L_{A}$ is the Laplacian on $A$, and $J=\prod_{\alpha \in \Sigma+}\left(e^{\alpha} \Leftrightarrow e^{-\alpha}\right)^{p_{\alpha}}\left(e^{\alpha}+e^{-\alpha}\right)^{q_{\alpha}}$. Here $p_{\alpha}$ and $q_{\alpha}$ are certain integers given by root space dimensions, see [20, Thm 8.1.1].

Put $\tilde{\Pi}(D)=J^{1 / 2} \Pi(D) \circ J^{-1 / 2}$, then it follows from the commutation relation $\left[L_{X}, D\right]=$ 0 and (19) that $\tilde{\Pi}(D)$ commutes with $L_{A} \Leftrightarrow d$, where $d$ is the function $J^{-1 / 2} L_{A}\left(J^{1 / 2}\right)$. Expanding $d$ in a power series $d(a)=\sum_{\gamma \in \Lambda} d_{\gamma} a^{-\gamma}$ on $A^{+}$and expanding $\tilde{\Pi}(D)$ in analogy with (17) as

$$
\tilde{\Pi}(D)=\sum_{\nu \in \Lambda} e^{-\nu} R_{\tilde{v}_{\nu}}
$$

we obtain the following expression

$$
\sum_{\nu, \gamma \in \Lambda}\left(\left[L_{A}, e^{-\nu}\right] R_{\tilde{v}_{\nu}} \Leftrightarrow d_{\gamma} e^{-\nu}\left[e^{-\gamma}, R_{\tilde{v}_{\nu}}\right]\right)=0 .
$$

Comparing coefficients to $e^{-\nu}$ we get

$$
\left[L_{A}, e^{-\nu}\right] R_{\tilde{v}_{\nu}}=\sum_{\gamma \in \Lambda, \nu-\gamma \in \Lambda} d_{\gamma} e^{-(\nu-\gamma)}\left[e^{-\gamma}, R_{\tilde{v}_{\nu}-\gamma}\right]
$$

where the sum is finite. In this equation, if $\nu \neq 0$ and $\tilde{v}_{\nu} \neq 0$, the left side is a differential operator on $A^{+}$of order $1+\operatorname{deg} \tilde{v}_{\nu}$, whereas the order of the operator on the other side is less than the maximum of the degrees of all $\tilde{v}_{\nu-\gamma}, \gamma \in \Lambda \backslash\{0\}$. In particular, it follows by an easy induction that $\operatorname{deg} \tilde{v}_{\nu} \leq \operatorname{deg} \tilde{v}_{0} \Leftrightarrow 2$ for $\nu \neq 0$.

In the series

$$
\Pi(D)=J^{-1 / 2} \tilde{\Pi}(D) \circ J^{1 / 2}=J^{-1 / 2} \sum_{\nu \in \Lambda} e^{-\nu} R_{\bar{v}_{\nu}} \circ J^{1 / 2}
$$

it is seen that the only contribution in degree deg $\tilde{v}_{0}$ is obtained in the $e^{0}$ term. Hence $v_{0}$ and $\tilde{v}_{0}$ have the same degree (in fact it is easily seen that $\tilde{v}_{0}=\eta(D)$ ), and $v_{\nu}$ has a lower degree for all other $\nu$. From this the claimed property (18) of the $v_{\nu}$ follows.

The final statement of the proposition follows from the previous statements.
Proof of Lemma 4: Assume $\eta(D)=0$ and let $f$ be smooth and $K$-invariant. It follows from the final statement of Proposition 1 that $D f=0$ on $A^{+}$. Since $\Sigma^{+}$was arbitrary we conclude that $D f=0$ on an open dense subset of the submanifold $A H$ of $X$. By $G=K A H$ and the $K$-invariance of $f$ we conclude that $D f=0$.

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