Exploring the cloud top phase partitioning in different cloud types using active and passive satellite sensors

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Key Points:

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9	• Despite phase and temperature mismatches, the retrievals based on passive and
10	active satellite sensors qualitatively agree on the following:
11	• Supercooled liquid fraction is larger in the Southern Hemisphere than in the North-
12	ern Hemisphere, except for continental low-level clouds
13	• In clouds with temperatures from -40° C to 0° C at the same height-level, super-
14	cooled liquid fraction increases with cloud optical thickness

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15 Abstract

One of the largest uncertainties in numerical weather prediction and climate models is 16 the representation of mixed-phase clouds. With the aim of understanding how the su-17 percooled liquid fraction (SLF) in clouds with temperature from -40°C to 0°C is related 18 to temperature, geographical location, and cloud type, our analysis contains a compar-19 ison of four satellite-based datasets (one derived from active and three from passive satel-20 lite sensors), and focuses on SLF distribution near-globally, but also stratified by lati-21 tude and continental/maritime regions. Despite the warm bias in cloud top temperature 22 of the passive sensor compared to the active sensor and the phase mismatch in collocated 23 data, all datasets indicate, at the same height-level, an increase of SLF with cloud op-24 tical thickness, and generally larger SLF in the Southern Hemisphere than in the North-25 ern Hemisphere (up to about 20% difference), with the exception of continental low-level 26 clouds, for which the opposite is true. 27

²⁸ Plain Language Summary

In mixed-phase clouds, hydrometeors consisting of ice and supercooled liquid wa-29 ter, i.e. water below 0°C, can exist simultaneously. In the mixed-phase temperature range 30 (-40°C to 0°C), ice-nucleating particles (e.g., mineral dusts, biological aerosol particles) 31 are needed for glaciation to be possible. The partitioning into liquid and ice depends not 32 only on the ice-nucleating particles, but also, for example, on cloud dynamics and ice mul-33 tiplication processes, influencing in turn the lifetime and the precipitation type of these 34 clouds, and the Earth-atmosphere energy balance locally and globally. In this study, we 35 show ice and liquid partitioning for different cloud types, comparing four satellite-based 36 datasets. This allows us to identify robustly their common trends despite their differ-37 ences. Our results show on average less ice in the Northern than in the Southern Hemi-38 sphere when considering all clouds together, and that the larger the cloud optical thick-39 ness, the less ice when treating the cloud types separately. The partitioning of cloud types 40 over sea and over land in both hemispheres show less ice in the Southern than in the North-41 ern Hemisphere for high- and mid-level clouds, but the opposite for low-level clouds over 42 land. This might be due to differences in aerosol composition and distribution. 43

44 **1** Introduction

⁴⁵ Mixed-phase clouds, i.e. clouds in which ice particles and supercooled liquid wa⁴⁶ ter can coexist in the temperature range of approximately -40°C to 0°C, are not fully
⁴⁷ understood yet and therefore not well represented in weather and climate models (Forbes
⁴⁸ & Ahlgrimm, 2014; McCoy et al., 2016).

Several studies have shown that mixed-phase clouds occur irrespective of the sea-49 son, can be found in diverse locations, and can be associated with various cloud types 50 (Korolev et al., 2017). Observations of mixed-phase clouds include active (e.g., Zhang 51 et al., 2010; Tan et al., 2014; Cesana & Storelvmo, 2017) and passive satellite (e.g., Coop-52 man et al., 2019; Noh et al., 2019; Tan et al., 2019), airborne in situ (e.g., Korolev, 2008; 53 Costa et al., 2017; Barrett et al., 2020), ground-based (e.g., Henneberger et al., 2013; Yu 54 et al., 2014; Gierens et al., 2020) and aircraft-based remote sensing measurements (e.g., 55 Wang et al., 2012; Plummer et al., 2014). In Tan et al. (2014), in particular, mixed-phase 56 clouds have been studied statistically in terms of supercooled cloud fraction, defined as 57 the ratio of the in-cloud frequency of supercooled liquid pixels to the total frequency of 58 supercooled liquid and ice pixels within 2° latitude by 5° longitude grid boxes, at sev-59 eral isotherms between -10°C and -30°C, distinguishing cases in the Northern Hemisphere 60 (NH) and in the Southern Hemisphere (SH), as well as cases over ocean and over land. 61 This study consisted of the analysis of about five years of data from NASA's spaceborne 62 lidar, CALIOP (Cloud-Aerosol Lidar with Orthogonal Polarization) level 2 Vertical Fea-63 ture Mask (VFM) in versions 3.01 and 3.02, and the relationship between the cloud phase 64

and several aerosol types was determined. They found that dust aerosols might strongly
influence the supercooled cloud fraction by acting as ice-nucleating particles (INPs), illustrating how important the atmospheric aerosol composition can be for the cloud phase.
Moreover, a larger supercooled cloud fraction in the SH than in the NH has been found,
which may be caused by the presence of more land in the NH, where efficient INPs originate. This result may also explain why a larger supercooled cloud fraction has been found,
over ocean than over land.

As in Tan et al. (2014), we apply a statistical approach to quantify the phase dis-72 73 tribution of mixed-phase clouds on isotherms. In addition, we use the International Satellite Cloud Climatology Project (ISCCP) cloud classification (Rossow & Schiffer, 1999) 74 to distinguish different cloud types. Our study includes data from passive (Advanced Very 75 High Resolution Radiometer — AVHRR) and active (Cloud-Aerosol Lidar and Infrared 76 Pathfinder Satellite Observation — CALIPSO) satellite sensors, with the intention to 77 identify robust signals despite differences, facilitating the potential identification of com-78 mon features based on different sources and algorithms. Passive sensors offer the ben-79 efit of long-period records with daily near-global coverage, which motivates us to com-80 pare three AVHRR-based datasets with the CALIPSO-based dataset, and to present this 81 work as a validation study. 82

After a description of the datasets and the method in Section 2, Section 3 contains the analysis and the results of our study, while discussion and conclusions are presented in Section 4.

⁸⁶ 2 Datasets and Method

2.1 Datasets

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The datasets we analyze are Cloud_cci AVHRR-PMv2 (Stengel et al., 2017), Cloud_cci AVHRR-PMv3 (Stengel et al., 2020), CLARA-A2 (Karlsson et al., 2017), and CALIOP V4 (Z. Liu et al., 2019). While the first three are based on the polar-orbiting passive satellite sensor AVHRR onboard NOAA satellites, CALIOP is an active sensor onboard the polar-orbiting CALIPSO satellite and is part of the NASA A-Train.

The AVHRR datasets provide cloud top information as global composites with a 93 spatial resolution of $0.05^{\circ} \times 0.05^{\circ}$, containing data twice per day from ascending and de-94 scending for each location. The swath width of AVHRR is wide enough to provide global 95 coverage daily. The AVHRR measurements are used to perform cloud detection and to 96 retrieve cloud top properties, e.g., the top phase, which consists of a binary flag (liquid/ice). 97 Table 1 contains more details about the phase retrieval algorithms. AVHRR-based re-98 trievals often lack sensitivity to high, optically very thin cloud layers, which might be qq missed or associated with larger uncertainties in the retrieved cloud properties (Stengel 100 et al., 2015). 101

CALIOP provides vertical distributions of clouds and aerosols along so-called "gran-102 ules". A granule is an orbit segment containing cloud, temporal, and geographical in-103 formation for every vertical profile. The horizontal resolution of CALIPSO is 333 m, while 104 the vertical resolution is 30-60m. In our analysis we use CALIOP level 2 Cloud Layer 105 Data in version 4.20 with a spatial resolution of 5 km, corresponding to approximately 106 0.05° as in AVHRR at the equator. The swath width is very narrow, so that about one 107 month of data must be collected to obtain a near-global coverage. The retrieved cloud 108 phase distinguishes liquid water from "randomly-oriented" and "horizontally-oriented" 109 ice. Table 1 includes further details on the phase retrieval algorithm. The dataset pro-110 vides vertical distributions of clouds in layers. Every layer can contain only one thermo-111 dynamic phase. CALIOP is able to retrieve up to an optical thickness of approximately 112 5 into the cloud (Karlsson & Håkansson, 2018). Only "medium" and "high" cloud-aerosol 113

Dataset	Cloud phase algorithm	Spectral bands (μm)	Reference
Cloud_cci v2	Cloud types are produced with a threshold decision tree (a series of spectral tests is applied to infrared brightness temperature); then, they are converted to a binary phase. If necessary, cloud top temperature is involved to re-set the phase for $T < -40^{\circ}$ C and at $T > 0^{\circ}$ C.	$0.6, \\ 1.6/3.75, \\ 10.8, \\ 12$	Algorithm Theoretical Baseline Document ATBD-CC4CLv5.1 (2017) Pavolonis and Heidinger (2004) Pavolonis et al. (2005a)
Cloud_cci v3	An artificial neural network trained by collocating AVHRR measurements with CALIOP cloud phase produces binary phase information. If necessary, cloud top temperature is involved to re-set the phase at $T < -40^{\circ}C$ and at $T > 0^{\circ}C$.	$0.6, \\ 1.6/3.75, \\ 10.8, \\ 12$	Algorithm Theoretical Baseline Document ATBD-CC4CLv6.2 (2019) Stengel et al. (2020)
CLARA-A2	As Cloud_cci v2, with some different threshold values in the decision tree scheme.	$0.6, \\ 1.6/3.75, \\ 10.8, \\ 12$	Algorithm Theoretical Baseline Document ATBD-CPP_AVHRR (2016) Pavolonis and Heidinger (2004) Pavolonis et al. (2005a)
CALIOP	Cloud altitude is derived as primary product, then converted to tempera- tures using model data from Goddard Earth Observing System, Version 5 (GEOS-5) vertical profiles. Next, the cloud phase is retrieved using the particulate depolarization ratio of backscattered light (and the cloud top height and temperature, if necessary).	0.532, 1.064	Hu et al. (2009)

Table 1. Cloud phase algorithms used by the analyzed datasets

discrimination scores and "medium" and "high" cloud phase confidence scores are usedin this study.

2.2 Method

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We analyzed collocated and non-collocated near-global (60° N to 60° S) data from 117 1 June 2009 to 31 May 2013. Using this time period, we benefit from the newest AVHRR/3118 instrument onboard the most recent NOAA satellite, avoiding sensor-calibration differ-119 ences with AVHRR onboard previous satellites leading to potential consistency issues. 120 Moreover, the data in this time period are not biased by the satellite drift yet. Latitudes 121 higher than 60° are excluded from our study because of the data low confidence, due to 122 the low solar zenith angle (Grosvenor & Wood, 2014) and the presence of sea ice (King 123 et al., 2004). The collocated data involve pixels retrieved as cloudy by all datasets within 124 3 minutes and 5 km. As the cloud optical thickness, involved in the cloud type classi-125 fication, can be detected by the AVHRR sensor only by the channels in the visible range, 126 we consider only daytime measurements, i.e. the ascending track; we do the same for CALIOP 127 to make the comparison as consistent as possible, although daytime CALIOP retrieval 128 has a higher backscatter sensitivity threshold (Winker et al., 2009). We constrain fur-129

ther analyses for latitudinal bands as follows: NH – from 60° N to 30° N; SH – from 30° 130 S to 60° S; Tropics – from 30° N to 30° S. Continental and maritime regions are also an-131 alyzed. Because only the cloud top information is available from AVHRR, we investi-132 gate the cloud top phase distribution in relation to the cloud top temperature, with a 133 focus on the mixed-phase temperature range. With a four-year analysis, we provide statis-134 tics on the supercooled liquid fraction (SLF) in clouds, computed as the ratio between 135 the number of liquid cloud top pixels and the sum of ice plus liquid cloud top pixels. The 136 analyzed isotherms cover the range -50° C to 5° C, with a 1°C increment. To sort the 137 cloud types, the ISCCP classification (Rossow & Schiffer, 1999) is used, based on thresh-138 old values of cloud top pressure (CTP = [0, 440, 680, 1000] hPa) and cloud optical thick-139 ness (COT= [0, 3.6, 23, 379]). For simplicity, for each COT-CTP combination the cor-140 responding cloud name (e.g., cirrus, stratocumulus, etc.) assigned in Rossow and Schif-141 fer (1999) is used here, despite being aware that a classification of cloud types purely based 142 on CTP and COT has limitations (Hahn et al., 2001). 143

For AVHRR datasets, all the cloudy pixels with COT < 0.3 are filtered out to improve the data quality (Stengel et al., 2015). To be comparable to the AVHRR datasets and mimic the view of the passive sensor, we remove the uppermost layers from the CALIOP profiles down to an optical thickness of 0.3 and consider the remaining highest cloud top layer for the study. The cloud classification precedes the computation of SLF on isotherms in the studies in which different cloud types are analyzed.

150 3 Results

As a first step, a comparison between the collocated (Fig. 1(a)) and non-collocated 151 (Fig. 1(b)) data is shown. The difference in SLF and the associated CTT among the datasets 152 stands out in these figures, and in particular the gap between the three AVHRR-based 153 datasets and CALIOP, up to about 25°C or SLF of about 80% at a fixed temperature. 154 In Fig. 1(c), we show that this disagreement is due to both the CTT and phase retrievals: 155 There is a CTT bias of Cloud_cci v3 compared to CALIOP mainly at lower tempera-156 tures, and a frequent disagreement on phase (with Cloud_cci v3 retrieving ice where CALIOP 157 retrieves liquid) in the mixed-phase temperature range. This figure uses the collocated 158 data and compares point-by-point the cloud top temperature retrieved by Cloud_cci v3 159 and CALIOP over the entire tropospheric temperature range and for three cloud top phase 160 combinations: same phase, CALIOP retrieving ice while Cloud_cci v3 liquid, and vice 161 versa. The contour lines indicate the areas (A, B, and C) where the frequency of occur-162 rence per 1K x 1K bin is greater than 240. This threshold highlights areas of agreement 163 and disagreement between the datasets, and separate the area where the sensors retrieve 164 the same phase into two regions (A and C) at around T=-28 °C. This temperature value 165 is used to compute the contributions of regions A and C separately. Because of the small 166 contribution given by the collocated pixels with CALIOP retrieving ice and Cloud_cci 167 v3 liquid, there is no contour line for this phase combination. Region A, including part 168 of the cases with the same phase and representing 45.9% of total cases, does not con-169 tribute systematically to the differences in the phase distribution in Fig. 1(a)-(b), be-170 cause it incorporates cases with good agreement in temperature and cases where the largest 171 temperature difference is about 10°C. Moreover, only a part of that region is within the 172 mixed-phase temperature range (around 13% of total cases). Conversely, a clear warm 173 bias in Cloud_cci v3 CTT with respect to CALIOP is indicated in region B, including 174 pixels with the same phase, which represents 26.6% of total cases. This region, albeit 175 including only around 0.7% of total cases between -40° C and 0° C for both datasets, in-176 cludes many cases contributing only to the SLF computation for Cloud_cci v3 (count-177 ing about 11% of total cases considering the mixed-phase temperature range for only Cloud_cci 178 v3), which are excluded from the SLF computation in CALIOP because they are out-179 side its mixed-phase temperature range. Finally, region C, with 9% of total cases (8.7%) 180 between -40°C and 0°C), refers to pixels retrieved liquid in CALIOP and ice in Cloud_cci 181



Figure 1. Comparison of supercooled liquid fractions (SLFs) vs. cloud top temperature (CTT) for collocated (a) and non-collocated (b) near-global (60° N to 60° S) data, followed by a point-by-point comparison of CTT and cloud top phase for CALIOP and Cloud_cci v3 using the collocated data (c), where the brightness of the bins (1K x 1K) represents the absolute frequency of occurrence and the different colors represent the different combinations of retrieved phase. The contour lines encompass bins with frequency greater than 240, while the percentages refer to the contoured areas and represent the relative amount of cases within the contour lines with respect to the total cases. A further comparison of SLF vs. CTT for non-collocated data follows constraining the extratropical Northern and the Southern Hemispheres (d), land and ocean (e), and extratropical Northern and Southern Hemispheres for only maritime (f) and only continental (g) regions. Different colors in SLF vs. CTT plots represent different datasets; different line types represent different regions.

v3. It includes, as region A, cases with good agreement in temperature and cases where 182 the largest difference is about 10° C. Nevertheless, region C contributes principally to the 183 phase mismatch. The percentage of cases in C changes only a little if considering solely 184 temperatures between -40° C and 0° C (8.7%). A point-by-point comparison of CALIOP 185 with CLARA-A2 and with Cloud_cci v2 (not shown) gives similar results. For AVHRR 186 datasets retrieving liquid while CALIOP retrieving ice, CLARA-A2 revealed more cases 187 than Cloud_cci v2 and v3 for temperatures below -30°C and down to -41°C; For this rea-188 son, CLARA-A2 shows SLF around 7% between -40° C and -41° C using the collocated 189 data (Fig. 1(a)) and around 17% using the non-collocated data (Fig. 1(b)). A quanti-190 tative analysis of the differences between CALIOP and Cloud_cci v2 and v3 can be found 191 in Stengel et al. (2020): While any phase bias of Cloud_cci v2 and v3 with respect to CALIOP 192 has nearly vanished for COTs of approximately 0.15 into the clouds, there is still a sig-193 nificant bias at COT = 1 for the cloud top height (CTH) of ice clouds, to which CTT 194 is linked. As a consequence, CTH is usually retrieved from levels below the levels used 195 to retrieve the phase, so that the retrieved CTT can be warmer than the effective tem-196 perature of the assigned cloud top phase, agreeing to our results. 197

We proceed with the study of SLF in separate geographical regions. Figure 1(d)198 shows, for all datasets, larger SLF in SH than in NH (with an average difference for sin-199 gle datasets between 1.7% and 9.8%). In Fig. 1(e), CALIOP shows clearly larger SLF 200 over ocean than over land (with an average difference of 11.2%), but the AVHRR-based 201 datasets do not agree with CALIOP for the entire temperature range. While larger SLF 202 in SH than in NH is confirmed when constraining the analysis to maritime pixels (Fig. 1(f), 203 with an average difference for single datasets between 2.1% and 7.3%), it is confirmed 204 only for specific temperature ranges over land (Fig. 1(g)), generally for $T < -23^{\circ}C$. Near-205 global SLF geographical distributions are shown in Fig. S1 in the supporting informa-206 tion. 207

Next, we investigate the global SLF distribution for different cloud types (Fig. 2). 208 The cloud types have been grouped into high-, mid-, and low-level clouds taking into ac-209 count the temperature ranges that the datasets have in common at the three heights in-210 dividually. This figure is derived from SLF-CTT distributions, for which the least fre-211 quent cases in CTT (frequency of occurrence lower than 2% with respect to the max-212 imum of each distribution in temperature) have been filtered out. Similarly to Fig. 1, 213 in Fig. 2 the systematically lower SLF in AVHRR compared to CALIOP is found. A fur-214 ther outcome can be identified in this figure for every height-level and almost all cases: 215 the optically thicker the clouds, the larger the SLF. This is consistent in all datasets with 216 a few exceptions. 217

Figure 3 condenses the SLF into average values for different cloud types, land and 218 ocean, NH and SH. All datasets confirm generally larger SLF for optically thicker clouds 219 at the same height-level. Figures 3(a)-(c) reveal larger SLF over ocean than over land 220 and in SH than in NH, respectively, for most of the cloud types with the exception of 221 some high- and mid-level clouds in Cloud_cci v2 and v3, especially in Fig. 3(a). In the 222 Tropics (Fig. 3(b)), most of the clouds show larger SLF over ocean than over land, ex-223 cept for again some high- and mid-level clouds in Cloud_cci v2 and v3, and low-level clouds 224 in Cloud_cci v2. Finally, Figure 3(d) shows that, separating the maritime and continen-225 tal pixels in NH and SH, SLF is larger in NH than in SH only for most of the low-level 226 clouds over land (cumulus, stratocumulus, and stratus clouds), otherwise again a larger 227 SLF in SH than NH is found. 228

This entire study has been conducted using the collocated data too (not shown), confirming the main results of our findings, although with more noise. The collocated data, in fact, represent only about 9.5% of CALIOP and 0.02% of AVHRR non-collocated data.



Figure 2. Boxplot of the supercooled liquid fraction (SLF) for different cloud types sorted in three height levels. Clouds at the same height-level share the same cloud top temperature range, specified at the top of each panel. The different datasets are separated by columns and every color corresponds to one cloud type. The boxes extend from the lower to upper quartile values of the data, whereas the whiskers show the entire range of the data. The horizontal lines within the boxes represent the median of the distributions, while the stars represent their mean values.



Figure 3. Comparison of mean SLF for different cloud types, considered in the temperature ranges they have in common at the same height-level and for each subplot individually, for near-global maritime and continental pixels (a), tropical maritime and continental pixels (b), and extratropical Northern and Southern Hemispheres (c), with the further separation of maritime and continental regions (d). Different markers identify different datasets, filling colors distinguish the cloud types, while edge colors refer to continental or maritime pixels in (d).

²³³ 4 Discussion and Conclusions

We performed a four-year statistical analysis to better understand the relationship 234 between cloud top phase and temperature in the mixed-phase temperature range $(-40^{\circ}C)$ 235 to 0°C). Our study is based on four datasets (Cloud_cci AVHRR-PM2.0, Cloud_cci AVHRR-236 PM3.0, CLARA-A2, and CALIOP v4.20) and consists of the comparison of the retrieved 237 cloud top phase and cloud top temperature in terms of SLF for specific isotherms. The 238 study included collocated data, to determine the inconsistencies among the retrievals, 239 and non-collocated data for the main study. The analysis was conducted from 60° N to 240 241 60° S, for extratropical Northern and Southern Hemispheres separately, for the Tropics, for continental and oceanic surfaces, and for different cloud types. To classify the 242 cloud types, cloud top pressure and cloud optical thickness thresholds have been used 243 (Rossow & Schiffer, 1999). Summarizing the main findings: 244

- Using collocated data, we found a warm bias of AVHRR CTT compared to CALIOP 245 and a phase mismatch (liquid cloud tops in CALIOP retrieved as ice in AVHRR-246 based datasets). Many factors can contribute to the disagreements between CALIOP 247 and AVHRR. One of the most important ones is the difference of the sensors, the 248 first passive and the second active: While the AVHRR has problems detecting mul-249 tilayer clouds that include top layers with small COT, leading to misclassifications 250 of cloud top phase, CALIOP can detect multilayer clouds with optical thickness 251 up to 5, and this might cause misclassifications too. Processing the data, cloud 252 edges have not been excluded because it was not possible for the AVHRR-based 253 datasets, representing a possible source of misclassification for low- and mid-level 254 clouds (Pavolonis et al., 2005b). Moreover, a possible phase change of a detected 255 cloud top would cause a modification of COT, and therefore a possible misclas-256 sification to an optically thicker or thinner cloud category, modifying the SLF of 257 another cloud type. Some of these issues have also been presented in Cesana et 258 al. (2019) for shallow cumulus and stratocumulus clouds, emphasizing that errors 259 in retrieving cloud phase, cloud optical thickness, and cloud top height can result 260 in cloud type misclassifications. Furthermore, the filter we apply to the optical thick-261 ness may be not sufficient to make sure that we are analyzing the cloud data in 262 the same way. In Stengel et al. (2015), CALIOP's liquid cloud fraction resulted 263 closer to the AVHRR-based dataset CLAVR-x (Cloud from AVHRR Extended) 264 than to other AVHRR-based datasets. One reason was that for CLAVR-x algo-265 rithms a priori information based on CALIOP climatologies was used for ice clouds. 266 This, in turn, prevented that phase and CTT were independently retrieved, a con-267 dition required for our study. 268
- We found higher SLF in the SH than in the NH, in agreement with Tan et al. (2014). 269 This result might be explained by the larger size of the continental area and there-270 fore the prevalence of continental aerosol with the ability to act as INPs in the NH. 271 Higher SLF in the SH than in the NH was found also when constraining the anal-272 vsis for maritime surfaces, while over-land cases agree on it for temperatures gen-273 erally colder than -23° C. Further analyses using different cloud types were nec-274 essary to understand the origin of this last feature, principally due to the low-level 275 clouds, which occur at warmer temperatures than the clouds at higher levels. More 276 details are included in the next point. 277
- Analyzing different cloud types and combining NH, SH, continental, and maritime 278 regions, we found higher SLF in the SH than in the NH (in line with Coopman 279 et al. (2020)), with the exception of the most low-level clouds over land, for which 280 the opposite occurs. This might be due to synoptic conditions or specific aerosol 281 conditions experienced by low-level clouds in those regions and impacting their 282 phase. Considering that the common temperature range of the analyzed continen-283 tal low-level clouds goes from -15° C to 0° C (not shown), our result shows agree-284 ments with Villanueva et al. (2020), where lower ice content was found in clouds 285

286	in NH than in SH for $T = (-15^{\circ} \pm 6^{\circ})C$, probably because of the larger amount
287	of feldspar in the SH. Our result could also be explained by the higher density of
288	particles acting as CCN in the NH, resulting in smaller droplet sizes, which might
289	limit secondary ice formation (Mossop, 1980). Our speculations are partially sup-
290	ported by further previous studies: Some anthropogenic aerosols such as black car-
291	bon, sulfate, and organic aerosols, do not act as efficient INPs but are efficient CCNs
292	(Hoose & Möhler, 2012); model outputs have shown that sulfate aerosol and black
293	carbon have the highest mass concentration in the lower troposphere of the NH
294	(X. Liu et al., 2009), where they act as CCN (Boucher & Lohmann, 1995), whereas
295	they act as INPs only at very high altitudes over the Tropics and the polar regions
296	(X. Liu et al., 2009). Indeed, Tan et al. (2014) found that dust (as mineral desert
297	dust), polluted dust (as dust mixed with urban pollution and biomass burning smoke),
298	and smoke (as biomass burning aerosols, principally made of soot and organic car-
299	bon) are mainly distributed in the Tropics and in the NH.
300	• In the analysis of different cloud types, same-height clouds showed SLF increas-
301	ing with COT. Although clouds containing more droplets than ice particles result
302	in higher optical thickness, we cannot exclude an influence of the cloud dynam-
303	ics on both COT and SLF. For example, optically thicker clouds tend to have stronger
304	updrafts and consequently higher supersaturation values, which may inhibit the
305	glaciation process (Korolev, 2007), potentially lowering the glaciation tempera-
306	ture in clouds and causing the presence of more supercooled liquid water than ice.
307	From our analysis, it is not possible to determine which process can explain the

308 obtained result.

In our study, we have considered possible limitations in the datasets linked to the 309 phase detection of the sensors. Because of this, particular attention has been paid to the 310 cloud optical thickness, bearing in mind that the cloud top phase as well as cloud type 311 might be influenced by it. Despite the differences found in the datasets, our results show 312 broad agreements among them in many aspects, not only proving the robustness of the 313 results but also showing that the passive satellite sensor AVHRR can contribute to the 314 cloud phase research once its limitations have been taken into account. The AVHRR-315 based datasets can be used for further studies (e.g., for comparison with climate mod-316

els), benefiting from the long temporal record and good spatial coverage.

318 Acknowledgments

³¹⁹ For the used AVHRR-PM datasets, the following DOIs provide additional documenta-

- tion and data download sites: Cloud_cci v2 https://doi.org/10.5676/DWD/ESA_Cloud_cci/AVHRR-
- PM/V002; Cloud_cci v3 https://doi.org/10.5676/DWD/ESA_Cloud_cci/AVHRR-PM/V003;
- 322 CLARA-A2 https://doi.org/10.5676/EUM_SAF_CM/CLARA_AVHRR/V002. CALIOP
- data are available online at the NASA Langley Atmospheric Sciences Data Center web-
- site (https://eosweb.larc.nasa.gov/order-data). For the collocated CALIOP data, the CAL_LID_L2_05kmCLay-
- Prov product was downloaded from the ICARE Data and Service Center (http://www.icare.univ-
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