# Fracture unclogging: A numerical study of seismically induced viscous shear stresses in fluid-saturated fractured rocks

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### **Key Points:**

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11	•	We compute viscous shear stresses in fluid-saturated fractures in response to the
12		dynamic strain of body waves
13	•	We analyze fracture unclogging potential in terms of the seismic wave, the rock,
14		the saturating fluid, and the fracture network properties
15	•	Seismically-induced fracture unclogging is plausible for typical seismic strains and
16		frequencies

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### 17 Abstract

Dynamic shaking imposed by passing seismic waves is able to promote various hy-18 drological processes in fractured reservoirs. This is often associated with seismically-induced 19 fracture unclogging due to mobilization of deposited colloids in the fracture network which, 20 in turn, affects permeability at the reservoir scale. Numerous laboratory and field stud-21 ies pointed out that fracture unclogging can be initiated when viscous shear stresses in 22 the fracture fluid are in the range of 0.1-1 Pascals. In this numerical study, we compute 23 viscous shear stress in a fluid-saturated fractured medium due to the action of passing 24 25 P- and S-waves. We perform a sensitivity analysis in terms of fluid, fracture, and host rock physical properties as well as seismic wave characteristics. Our results show that 26 seismically-induced viscous shearing increases with frequency and seismic strain and can 27 be in the order of those initiating fracture unclogging for typical seismic strains and fre-28 quencies. S-waves tend to produce viscous shearing approximately two times larger than 29 P-waves and, for anisotropic distribution of fractures, it is extremely dependent on the 30 direction of wave propagation. Moreover, larger viscous shearing is expected for more 31 viscous fluids and stiffer host rocks. Regarding the fracture network distribution, for the 32 same fracture density, the presence of longer fractures drastically increases the poten-33 tial of fracture unclogging at seismic frequencies. The fracture aperture distribution, on 34 the other hand, can also affect the development of viscous shearing. Fractures with cor-35 related distributions of contact areas exhibit an order of magnitude larger viscous shear-36 ing than uncorrelated ones. 37

### 38 1 Introduction

For any given scale, fractures dominate the mechanical properties of reservoirs as 39 well as their hydraulic characteristics. In Earth Sciences and in particular in reservoir 40 characterization, fractures are key features affecting fluid flow and may determine whether 41 reservoirs are economically exploitable or not. The hydraulic conductivity of a reservoir 42 is a transient property (Borg et al., 1976; Ameli et al., 2014; Pyrak-Nolte & Nolte, 2016). 43 Hydraulic stimulation is arguably one of the most effective methods to increase the hy-44 draulic conductivity of a reservoir (Economides & Nolte, 1989). However, the permeabil-45 ity of reservoirs may also be increased by the mobilization of colloids at the pore scale 46 through pre-existing fractures (Elkhoury et al., 2011). Colloids are commonly defined 47 as fine particles between 1 nm and 10  $\mu$ m whose nature can be either inorganic (e.g., min-48 eral precipitates) or organic (e.g., bacteria). When a colloidal particle travels through 49 a fluid-saturated fracture it is affected by several processes among which the most im-50 portant are adsorption, desorption, physical straining, gravity settling, and diffusion into 51 the rock matrix (W. Zhang et al., 2012). Some of these processes promote collisions be-52 tween colloids and the fracture walls, which once established can favor further attach-53 ment of additional particles ultimately reducing the hydraulic conductivity of the frac-54 ture in a process commonly referred to as fracture clogging. When hydrodynamic drag 55 forces overcome the adhesive forces, colloidal desorption or detachment from fracture sur-56 faces can be initiated (Bergendahl & Grasso, 2000) leading to an enhancement of the over-57 all hydraulic conductivity (fracture unclogging). In this work, we investigate the abil-58 ity of body waves travelling across a fluid-saturated fractured medium to produce tran-59 sient drag forces in the fluid. In particular, we explore under which conditions, seismically-60 induced viscous shear stresses are capable of initiating fracture unclogging. 61

Direct observations of colloidal mobilization due to transient stimulation were conducted at the meso-scale (i.e. tens of meters). As an example, a two-year-long monitoring study at the Grimsel Test Site, Switzerland, showed that fracture fluids in crystalline rocks transported inorganic colloids at concentrations of about 10<sup>10</sup> particles per liter (Degueldre et al., 1989). Micro-seismicity and variations in the groundwater flow rate were the most likely reasons for the detachment of colloids. At the regional scale, field

data pointed out seismically-induced fracture unclogging due to colloidal mobilization 68 (Manga et al. (2012) and references therein). Although no dedicated experiments inves-69 tigated colloidal mobilization, it has been recognized as a mechanism of permeability en-70 hancement that could explain a number of hydrological and hydrogeological responses 71 to distant earthquakes (Rojstaczer et al., 1995). Field observations showed that pass-72 ing seismic waves affected stream-flow and spring discharge (Manga et al., 2003), ground-73 water level (Brodsky et al., 2003; Elkhoury et al., 2006; Kocharyan et al., 2011; Xue et 74 al., 2013; Y. Zhang et al., 2015; Shi et al., 2019), oil wells production (Beresnev & John-75 son, 1994; Mirzaei-Paiaman & Nourani, 2012) temperature and composition of ground-76 water (Mogi et al., 1989), seismicity at geothermal systems (Lupi, Fuchs, & Saenger, 2017), 77 eruption of mud volcanoes (Rudolph & Manga, 2010; Lupi et al., 2013), and liquefac-78 tion of unconsolidated sediments (C.-Y. Wang, 2007). Mogi et al. (1989) argued that the 79 observed increase of geothermal flux and turbidity in an artesian spring at the Usami 80 Hot Springs, Japan, after the passage of seismic waves was related to the mobilization 81 of colloids at the pore scale. Brodsky et al. (2003) proposed a model to explain water 82 level changes in wells based on the unclogging of highly conductive fractures due to the 83 rapid flow induced by seismic surface waves. Brodsky et al. (2003) showed that the seismically-84 induced fracture unclogging is a function of the frequency and amplitude of the dynamic 85 strain imposed by the passing seismic waves. By measuring permeability from water well 86 level changes in response to solid Earth tides, Elkhoury et al. (2006) found that perme-87 ability in a fractured rock system was significantly increased (up to three times) after 88 the passage of seismic waves from regional earthquakes. Their data indicated that the 89 permeability increases, which were approximately linearly related to the dynamic strains, 90 were followed by a slow permeability recovery to the pre-seismic stress state. The lat-91 ter is a common observation usually evoked to support the fracture unclogging mech-92 anism as the recovery is believed to be related to the subsequent clogging of fractures 93 (Kocharyan et al., 2011; Candela et al., 2014). 94

Permeability increases promoted by passing seismic waves are particularly effec-95 tive in geological systems characterized by elevated pore pressures at depth (Manga & 96 Brodsky, 2006; Farías et al., 2014). This is the case in geothermal systems or in geolog-97 ical settings where isolated compartments of high pressure fluids may develop at depth. 98 The subsequent redistribution of the pore fluid pressure may, in turn, cause permanent 99 changes in the mechanical and hydraulic properties at depth (Kocharyan et al., 2011). 100 In this sense, C.-Y. Wang (2007) argued that enhanced permeability may bridge hydrauli-101 cally isolated regions characterised by high pore pressure and low liquefaction potential 102 to regions more prone to liquefaction. Several studies (Hill, 2008; Saccorotti et al., 2013; 103 Lupi, Fuchs, & Saenger, 2017) have shown that dynamic stresses imposed by a passing 104 seismic wave in the order of a few kPa can be sufficient to destabilize critically loaded 105 faults by increasing their pore fluid pressure. In this scenario, the permeability increase 106 due to the seismically-induced unclogging of fine particles may accelerate the diffusion 107 of pore pressure into faults, decreasing the confining effective normal stress ultimately 108 prompting the system to failure. Although dynamic triggering effects are typically as-109 sociated with the seismic energy of surface waves generated by teleseismic events (Brodsky 110 et al., 2003; Brodsky & Prejean, 2005; Elkhoury et al., 2011), it has been shown that body 111 waves released from regional earthquakes can have a similar impact on a variety of fluid-112 saturated systems (C.-v. Wang et al., 2009; Lupi et al., 2013, 2015; Lupi, Frehner, et al., 113 2017). The effects of body waves can be even more important than those related to sur-114 face waves in geological settings (e.g. anticlines and piercement structures) focusing and 115 amplifying the incoming seismic energy (Lupi, Frehner, et al., 2017). 116

The physics of the changes of hydraulic conductivity of fractured media due to transient pressure changes has been investigated mostly via laboratory experiments. These are summarised in section 2 and reported in Table 1. During laboratory experiments, pore pressure (or stress) oscillations are imposed on intact or fractured fluid-saturated rock samples to investigate transient variations of effective permeability. In general, the permeability changes are found to be consistent with the mobilization of trapped colloidal particles. During the shaking, the development of viscous shear forces in the fluid removes colloids blocking flow paths thus changing the fracture internal structure and consequently their hydraulic properties (Liu & Manga, 2009). After the transient stimulation is ceased, the permeability recovery of the sample related to the progressive reclogging of the pores and fractures is investigated.

The viscous shear stress tensor components  $\tau_{ij}$ , caused by the motion of a viscous fluid are defined as (Kutay & Aydilek, 2009)

$$\tau_{ij} = \eta \left( \frac{\partial v_i}{\partial x_j} + \frac{\partial v_j}{\partial x_i} \right), \qquad i, j = x, y, z, \tag{1}$$

where  $\eta$  is the fluid viscosity and  $v_j$  is the *j*-component of the fluid velocity. From Eq. 131 1 it follows that high velocity gradients generated due to the presence of large local pres-132 sure gradients directly affect the magnitude of the viscous shear stress acting on the fluid-133 solid interface. In order to evaluate the plausibility of colloid mobilization as a mech-134 anism for seismically driven permeability changes, Manga et al. (2012) compared obser-135 vations of mobilization with the viscous shear stress that is being applied to the colloidal 136 deposits. They found that shear stresses of 0.1-1 Pa appear to be sufficient to initiate 137 colloidal mobilization in a wide range of systems. These relatively low values of viscous 138 shearing further support colloid mobilization as a plausible mechanism for some of the 139 commonly observed hydrogeological responses to dynamic stresses. Furthermore, Manga 140 et al. (2012) pointed out that the computed values may represent a conservative thresh-141 old as the consequences of permeability changes had to be large enough to be detectable. 142

Field (Brodsky et al., 2003; C.-y. Wang et al., 2009), laboratory (Bergendahl & Grasso, 143 2000; Li et al., 2005; Chen et al., 2018), and theoretical studies (Bai & Tien, 1997; Ku-144 tay & Aydilek, 2009) converge in showing that the removal efficiency of particles from 145 poroelastic materials is correlated with the viscous shear stress in the fluid driven by pore 146 pressure oscillations. Hence, investigating the behavior of seismically-induced viscous shear 147 stresses in fractured fluid-saturated systems is key to understand permeability changes 148 driven by colloidal mobilization. However, despite the recent analytical (Brodsky et al., 149 2003), field (Taira et al., 2018), and experimental (Candela et al., 2014) studies support-150 ing the wave-induced fracture unclogging mechanism, to the best of our knowledge, there 151 is a lack of numerical studies investigating such processes. In this work, we explore which 152 seismic wave characteristics favor the development of viscous shearing that may be suf-153 ficient to initiate fracture unclogging via colloidal mobilization. In this regard, it is im-154 portant to mention that although seismically-induced fracture unclogging may affect the 155 fracture physical properties (e.g., fracture aperture), accounting for such effects and their 156 corresponding evolution is beyond the scope of this study. In Section 2, we discuss the 157 underlying mechanism of permeability enhancement including a brief review of pertinent 158 laboratory experiments and a description of the conditions under which colloidal mobi-159 lization due to wave-induced viscous shearing can occur. In Section 3 we present our nu-160 merical strategy. In Section 4 the seismically-induced viscous shearing is analyzed as a 161 function of the properties of the propagating wave (e.g., wave mode, frequency, direc-162 tion of propagation) and the fractured rock (fracture, background rock, and fluid prop-163 erties). In Section 5, we further discuss the limitations and implications of our study and 164 summarize the most important results in the conclusions section. 165

# <sup>166</sup> 2 Fracture unclogging mechanism

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The magnitude of permeability changes caused by dynamic stresses (few kPa), is typically less than the changes caused by fracturing (few MPa) used to enhance reservoir permeability of about two orders of magnitude (Amann et al., 2018). The laboratory experiments listed in Table 1 investigated variations of the effective permeability of intact or fractured fluid-saturated rock samples upon imposing dynamic stresses sim<sup>172</sup> ilar or slightly larger than those created by solid Earth  $(10^{-3} \text{ MPa})$  or Ocean  $(10^{-2} \text{ MPa})$ <sup>173</sup> tides and passing seismic waves.

Roberts (2005) imposed sinusoidal cycles of axial stress (refer to Table 1 for the 174 frequencies and amplitudes) on fluid-saturated intact Berea sandstone samples. For low-175 amplitude oscillations, Roberts (2005) did not observe effective permeability variations. 176 However, upon increasing the amplitude of the transient stress variations to 0.6 MPa and 177 then to 0.9 MPa, permeability increased 15% and 20%, respectively. Permeability returned 178 to pre-stimulation values over a period of 24 hours after the cycles were stopped. Liu and 179 180 Manga (2009) performed oscillatory experiments on fractured water-saturated sandstone cores. The amplitude of the imposed axial stress was in the order of tens of kPa. Both 181 permeability and sample size decreased after each set of oscillations. Liu and Manga (2009) 182 speculated that this may have been due to a redistribution of fine particles in the frac-183 tures. The decrease resulted proportional to the cumulative amount of transient stress 184 applied to the samples. Kocharyan et al. (2011) studied wave-induced fracture unclog-185 ging effects by measuring changes in the water flow rate through a fracture artificially 186 clogged with fine corundum particles. In the experiment, the sample was subjected to 187 the action of dynamic pulses produced by steel ball hits. During the stimulation, some 188 of the particles were leached out when the flow rate drastically increased. After termi-189 nation of the stimulation, gradual re-clogging and restoring of broken barriers made the 190 effective permeability of the fracture to return to the initial values. Elkhoury et al. (2011)191 pointed out that imposing pore pressure oscillations in a fractured rock sample can change 192 permeability up to 50% of its original value. As a direct indication of the colloidal mo-193 bilization, Elkhoury et al. (2011) found gouge aligned over the fracture surface, with in-194 creasing quantities in the downstream direction, after taking the samples out of the ap-195 paratus. More recently, Candela et al. (2014) applied the same method and investigated 196 the evolution of permeability for intact and fractured rocks saturated with deionized wa-197 ter and brines with NaCl 25 wt%, NaCl 5 wt%, and CaCl<sub>2</sub> 5 wt%. These authors found 198 permeability enhancement on both intact and fractured samples. Furthermore, the mag-199 nitude of permeability enhancement and the rate of permeability recovery was propor-200 tional to the ionic strength of the pore fluid. The range of permeability enhancement re-201 ported by Candela et al. (2014) was 1-60% for dynamic strain amplitudes ranging from 202  $7 \times 10^{-7}$  to  $7 \times 10^{-6}$ . Candela et al. (2015) expanded on the experiments of Candela et 203 al. (2014) to analyze the dependence of the permeability changes with the frequency of 204 the oscillation. For a fractured Berea sandstone and pressure oscillation frequencies of 205 0.05, 0.2, and 1 Hz, Candela et al. (2015) observed average relative increases in perme-206 ability of 10%, 25%, and 70%, respectively. 207

The permeability changes recorded during the experiments listed in Table 1 were 208 attributed to the fast flushing and gradual re-clogging of colloids at the pore space or 209 between fracture asperities. Other possible mechanisms driving permeability changes in 210 laboratory experiments include micro-fracturing and shearing of the rock samples (Ishibashi 211 et al., 2018), fracture aperture changes (Liu & Manga, 2009), and differential poroelas-212 tic behavior of matrix and fractures (Faoro et al., 2012). Observations supporting the 213 unclogging mechanism over other mechanisms are (1) recovery of the initial permeabil-214 ity after stimulation (i.e., reversible mechanism), (2) fractured samples have shown slightly 215 higher direct permeability enhancement compared to intact samples (i.e., influence of 216 preferential flow paths), and (3) absence of permanent deformation of the sample after 217 stimulation ceases (except in Liu and Manga (2009)). The re-clogging of the fluid path-218 ways cleared by the seismic shaking has been found to depend on a complex combina-219 tion of the amount of permeability enhancement, the pore-space geometry, the flow rates, 220 the ionic strength of the pore-fluid, the colloidal size distribution and concentration (Roberts 221 & Abdel-Fattah, 2009; Elkhoury et al., 2011; Candela et al., 2014). Elkhoury et al. (2011) 222 proposed an empirical relation in which the recovery of permeability in samples affected 223 by oscillatory stresses occurs as  $t^{-p}$ , where t is the time and the exponent p can be in-224

Authors	Frequency (Hz)	Amplitude	Oscillations	Samples	Permeability response	Recovery time
Roberts $(2005)$	50	0.3 - 0.9 MPa	Axial stress	Intact	Increase	24  hs
Liu and Manga (2009)	0.3 - 2.5	Strains $10^{-4}$	Axial Dis- placement	Fractured	Decrease	No recovery
Elkhoury et al. $(2011)$	0.05	0.02 - 0.3 MPa	Pore pressure	Fractured	Increase	tens of min- utes
Kocharyan et al. (2011)	Not docu- mented	Strains $10^{-7}$ - $10^{-5}$	Steel ball impacts	Fractured	Increase	tens of min- utes
Candela et al. $(2014)$	0.05	0.01 - 0.5 MPa	Pore pressure	Fractured and intact	Increase	Several min- utes
Candela et al. (2015)	0.05 - 1	0.14 - 0.5 MPa	Pore pressure	Fractured	Increase	Several min- utes

**Table 1.** Summary of key experiments investigating pores and fractures unclogging as a result of applying transient pressure changes to the sample. The table was extended from the review of Manga et al. (2012).

terpreted as the inverse of the average flow dimension of the system. In the case of flow dominated by two-dimensional fractures, Elkhoury et al. (2011) found that p = 1/2.

In summary, the experimental literature described above points out that strain am-227 plitudes of the order of  $10^{-7}$ - $10^{-5}$  are capable of affecting permeability which is in agree-228 ment with natural observations for seismic waves (Elkhoury et al., 2006; Lupi, Frehner, 229 et al., 2017). Furthermore, the transient permeability enhancement due to fracture un-230 clogging scales with the amplitude and frequency of the oscillatory strain (Elkhoury et 231 al., 2011; Candela et al., 2014, 2015). In order to scale these observations to the field scale, 232 in the following, we investigate the coupling between the imposed strains during the pas-233 sage of seismic waves and the development of viscous shear forces in a fracture neces-234 sary to initiate the fracture unclogging. 235

# <sup>236</sup> **3** Methodology

Colloidal mobilization promoted by viscous shearing is caused by seismic waves whose 237 wavelengths can be much larger than the fracture-scale at which the process takes place 238 (Brodsky et al., 2003). Due to the large difference of scales, the direct numerical sim-239 ulation of seismically-induced fracture-scale processes is, in most cases, computationally 240 challenging (Rubino et al., 2016). An effective approach for bridging such a scale gap 241 consists in emulating the action of a propagating seismic wave through the application 242 of oscillatory displacement fields on the boundaries of a representative elementary vol-243 ume (REV) of the fractured formation (Fig. 1 arrow a). Given that the size of the REV, 244 whose structure and seismic response is typical of the whole medium, can be much smaller 245 than the dominant seismic wavelengths, it is possible to focus on sub-wavelength scale 246 features and processes (e.g., viscous shearing at the walls of a fracture). This numeri-247 cal upscaling approach is commonly used to infer effective seismic properties from the 248 resulting strain-stress state of the sample (Rubino et al., 2013; Quintal et al., 2016). Here, 249 we use it to calculate viscous shearing  $(\tau_{ij})$  in fluid-saturated fractured rocks due to the 250 strains imposed by seismic waves with wavelengths larger than the size of the REV (Fig. 251 1 arrow b). 252



Figure 1. Schematic illustration of the methodology used to compute viscous shear stresses at the fracture scale. A propagating seismic wave imposes dynamic strains to the fractured formation, which we emulate by applying an oscillatory relaxation test to the REV of the formation (a). The dynamic strains produce pressure gradients and fluid motion inside the fractures, which are translated into viscous shear stresses (b). Viscous shearing applied to colloidal deposits can detach colloids from the fracture walls leading to changes in the overall hydraulic conductivity of the formation (c).

Rubino et al. (2013) showed that in the presence of hydraulically connected frac-253 tures, seismic waves may experience attenuation and velocity dispersion related to fluid 254 pressure diffusion (FPD) within the fractures. The FPD occurs when the passing waves 255 induce a fluid pressure gradient between connected fractures. During the correspond-256 ing fluid pressure equilibration, seismic energy is dissipated. In this work, we explore the 257 link between the wave-induced FPD between connected fractures (FF-FPD) and the de-258 velopment of viscous shear stresses (Eq. 1) at the walls of the fractures (Fig. 1 arrow 259 b). To do so, we use the procedure of Quintal et al. (2016) and apply a finite element 260 technique to numerically solve a coupled system of equations stated in the space-frequency 261 domain and consisting of the quasi-static linearized Navier-Stokes equation for the lam-262 inar flow of a compressible viscous fluid and the linear elastic equation for a nonporous 263 solid material (Appendix A). This allows for modelling the associated spatial flow pat-264 terns inside the fractures (Quintal et al., 2016) from which the viscous shear stress can 265 be obtained using Eq. 1. The methodology also reproduces the energy dissipation due 266 to FF-FPD producing the frequency-dependent seismic wave attenuation and velocity 267 dispersion observed by Rubino et al. (2013). 268

For the computation of the seismically-induced viscous shear stress in the fluid of 269 the fractures, we first consider a simple 2D numerical model corresponding to an REV 270 of a periodically fractured medium (Fig. 2). The 2D problem that we tackle is equiv-271 alent to a 3D case under plane strain conditions (where no strain outside the modelling 272 plane is allowed to develop). We refer as x and y to the orthogonal directions in the mod-273 elling plane (Fig. 2) while z is the direction perpendicular to the x-y plane. It follows 274 that the only non-zero component of the viscous shear stress tensor is  $\tau_{xy}$ . Despite the 275 2D nature of the simulations, it allows to examine the dependence of  $\tau_{xy}$  on different seis-276 mic wave characteristics (i.e., wave mode, frequency, direction of propagation), fractured 277 rock (e.g., host rock stiffness, fracture network distributions), and fluid properties. Once 278



Figure 2. Synthetic sample representing a unit cell of a periodically fractured rock containing two connected orthogonal fluid-saturated fractures. The background is assumed to be elastic and the fractures are saturated with a viscous fluid. The corresponding physical properties are given in Table 2. The aspect ratio of the fractures is  $2.77 \times 10^{-4}$ . The red dashed square illustrates the region of the model shown in Fig. 4.

this sensitivity analysis is performed, a 3D fractured model is presented at the end of section 4.

The fractures of Fig. 2 are filled with a compressible viscous fluid, whereas the em-281 bedding background medium is described by the properties of an elastic solid. The fluid 282 properties considered in this work correspond to water and brine at ambient pressure 283 and temperature conditions (see Table 2), similar to those used in the laboratory exper-284 iments described in Section 2. We assume that the background rock hosting the frac-285 tures is modelled as a nonporous elastic medium while fractures are fluid-filled voids of 286 arbitrary shape. This modelling implies that the fractures are hydraulically isolated from 287 the surrounding background and thus FPD can only occur within the fractures. 288



**Figure 3.** Numerical oscillatory relaxation tests. Panels a), b), and c) show the imposed boundary conditions for the vertical, horizontal, and shear relaxation tests, respectively. Vertical and horizontal relaxation tests simulate the action of a normally (perpendicular to the *x*-axis) and horizontally (parallel to the *x*-axis) incident P-wave. The shear relaxation test simulates the action of normally incident S-wave.

To compute the effects of FPD between hydraulically connected fractures due to 289 the action of seismic waves at different incidence angles, it is necessary to determine the 290 effective anisotropic response of the REV shown in Fig. 2. This can be achieved by ap-291 plying the three oscillatory relaxation experiments shown Fig. 3 (Rubino et al., 2016). 292 Rubino et al. (2016) showed that for 2D heterogeneous samples, under plane strain con-293 ditions, it is possible to compute an equivalent homogeneous anisotropic viscoelastic solid 294 from the strain-stress response to three relaxation tests (Fig. 3). The first test consists 295 of the application of homogeneous time-harmonic normal displacements along the top 296 boundary of the sample, while the lateral and bottom boundaries are confined (Fig. 3a). 297 The second test is similar to the previous one, but the normal displacements are applied 298 on one lateral boundary of the sample (Fig. 3b). Finally, in the third test, we apply a 299 simple shear to the probed sample (Fig. 3c). Following Rubino et al. (2016), the aver-300 age stress and strain components computed from the oscillatory relaxation tests can be 301 related through a complex-valued and frequency-dependent equivalent stiffness matrix 302

$$\begin{vmatrix} < \sigma_{xx}(\omega) > \\ < \sigma_{yy}(\omega) > \\ < \sigma_{xy}(\omega) > \end{vmatrix} = \begin{vmatrix} C_{11}(\omega) & C_{12}(\omega) & C_{16}(\omega) \\ C_{12}(\omega) & C_{22}(\omega) & C_{26}(\omega) \\ C_{16}(\omega) & C_{26}(\omega) & C_{66}(\omega) \end{vmatrix} \cdot \begin{vmatrix} < \varepsilon_{xx}(\omega) > \\ < \varepsilon_{yy}(\omega) > \\ < 2\varepsilon_{xy}(\omega) > \end{vmatrix} ,$$
(2)

where the components of the equivalent stiffness matrix are evaluated for each angular frequency  $\omega$  following a classic least-square fitting procedure as we have nine equations (Eq. 2 holds for the three relaxation tests) and six unknown stiffness coefficients. The angular brackets correspond to averages over the sample's volume. Once the coefficients  $C_{ij}(\omega)$  are determined, it is possible to compute the equivalent seismic attenuation of P- and S-waves as a function of incidence angle and frequency following a standard procedure for anisotropic viscoelastic solids.

Finally, the spatial distribution inside the REV of a given field as a result of an arbitrarily imposed strain state can be computed as proposed by Rubino et al. (2016)

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$$f_{\varepsilon}(x, y, \omega) = \varepsilon_{xx}(\omega) f_{11}(x, y, \omega) + \varepsilon_{yy}(\omega) f_{22}(x, y, \omega) + \varepsilon_{xy}(\omega) f_{12}(x, y, \omega), \tag{3}$$

where the strain state imposed to the sample is defined by the components  $\varepsilon_{xx}$ ,  $\varepsilon_{yy}$ , and 314  $\varepsilon_{xy}$ .  $f_{11}$ ,  $f_{22}$ , and  $f_{12}$  correspond to the desired field spatial distribution in response to 315 strain states that have  $\langle \varepsilon_{xx} \rangle = 1$ ,  $\langle \varepsilon_{yy} \rangle = 1$ , or  $\langle \varepsilon_{xy} \rangle = 1$ , respectively, while 316 the rest of the strain components are zero. It is straightforward to obtain those fields 317 using the responses to the relaxation tests shown in Fig. 3 (Eqs. 34 to 39 in Rubino et 318 al. (2016)). For this work, we use Eq. 3 to compute the viscous shear stress components 319 (Eq. 1) in response to the strain state associated with body waves (i. e., P- and S-waves) 320 propagating at varying incidence angles and frequencies. 321

### 322 4 Results

There are several factors potentially affecting the magnitude of wave-induced vis-323 cous shear stresses in the fluid saturating a fracture. The methodology outlined in sec-324 tion 3 allows to perform a sensitivity analysis of the viscous shear stress in terms of the 325 physical properties of the viscous fluid saturating the fractures, the elastic moduli of the 326 host rock, and the geometrical properties of the fracture network. We present our nu-327 merical results as function of the seismic wave mode (P- or S-waves), frequency, and di-328 rection of propagation. We first consider the REV shown in Fig. 2 where the side length 329 is equal to 0.4 m and the length of both fractures is 0.36 m. The fracture aperture is 0.1 330 mm, which is considered within the range of realistic fracture apertures (Bakulin et al., 331 2000). We compare the viscous shear stresses for four cases defined by the properties given 332 in Table 2. In addition to the reference scenario, representative of a hard rock with brine 333 saturating the fractures, we investigate three further scenarios where we modify one prop-334 erty at the time. These are fluid viscosity (case 2: water instead of brine saturating the 335 fractures), fracture aperture (case 3: wider fractures), and elastic moduli of the back-336 ground medium (case 4: softer background medium). 337

**Table 2.** Physical properties utilized for the analysis of the angle and frequency dependence of  $\tau_{xy}$ .

	Reference case	Modified property
Fluid Viscosity $(\eta)$	$0.003  [Pa \cdot s]$	$0.001  [Pa \cdot s]  (Case  2)$
Fluid bulk modulus $(K_f)$	2.4 [GPa]	2.25 [GPa] (Case 2)
Fracture Aperture (h)	$0.1  [\mathrm{mm}]$	0.2  [mm] (Case  3)
Background bulk modulus $(K_b)$	36.4 [GPa]	9 [GPa] (Case 4)
Background shear modulus $(\mu_b)$	44 [GPa]	7 [GPa] (Case 4)

The angle dependence of  $\tau_{xy}$  for both P- and S-wave incidences is obtained by first 338 subjecting the REV to the three tests shown in Fig. 3 and then following the procedure 339 described in Section 3. In order to compare  $\tau_{xy}$  for different directions of wave propa-340 gation, we need to arbitrarily define the imposed average strain on the sample for dif-341 ferent incidence angles. We assume that the strain associated with a seismic wave is the 342 same for all incidence angles and equal to a realistic value. The strain amplitudes are 343 chosen based on the magnitude of the viscous shear stress that has been found to be suf-344 ficient to initiate fracture unclogging (Manga et al., 2012). Thus, for P-waves, we used 345 a fixed extensional strain in the direction of wave propagation such that, for the refer-346 ence scenario, at 10 Hz the mean wave-induced  $\tau_{xy}$  is ~0.1 Pa ( $\varepsilon_{\gamma\gamma} \sim 1.5 \times 10^{-7}$ , where 347 the  $\gamma$ -axis coincides with the direction of wave propagation). Similarly, for the analy-348 sis of S-waves, we assume that the shear strain is the same regardless of the incidence 349 angles and equal to the value used for P-waves. 350

We solve the oscillatory relaxation test in the frequency-space domain (Appendix 351 A). However, the viscous shear stress inside the REV as a function of time for a given 352 frequency of oscillation can be written as  $|\tau_{xy}(x, y, \omega)| \cos(\omega t + \phi(x, y, \omega))$ , where  $|\cdot|$ 353 and  $\phi$  represent the absolute value and the phase of a complex number, respectively. In 354 Fig. 4, we illustrate the time evolution of the viscous shear stress in response to a 10 Hz 355 normally incident P-wave, by computing  $\tau_{ij}(x, y, t)$  at three different times: t = 0 s (a), 356 t = T/4 (b), and t = T/2 (c), with T being the wave period. In order to show the de-357 tails of  $\tau_{xy}(x, y, t)$  inside the fracture, in Fig. 4 we only show the region delimited by the 358 red dashed square of Fig. 2. Note that the maximum value of  $\tau_{xy}(x, y, t)$  does not co-359 incide with the time of maximal compression (Fig. 4a). Instead, it occurs approximately 360 at a quarter of the wave period (Fig. 4b). In the following, we present results in terms 361 of  $|\tau_{xy}(\omega)|$ , which corresponds to the maximum of  $\tau_{xy}$  at a given position and at each 362 frequency  $\omega$  (Fig. 4d). In particular, we analyze the mean value of  $|\tau_{xy}(\omega)|$  at the bound-363 ary between the fractures and the background, where unclogging is expected to take place. 364 For brevity, we refer to this quantity as  $\tau_{xy}$ . 365

### 4.1 P-wave analysis

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Fig. 5a to d shows  $\tau_{xy}$  as a function of incidence angle (0° to 90°) and frequency 367  $(10^0 \text{ Hz to } 10^4 \text{ Hz})$  in response to a strain state produced by a plane P-wave. The white 368 zones in Fig. 5a to d correspond to viscous shear stress below 0.1 Pa, which is the thresh-369 old value of fracture unclogging initiation adopted for this work. We observe that  $\tau_{xy}$ 370 increases with frequency for all incidence angles. On the basis of Eq. 1, this is expected 371 because the fluid pressure gradient between the fractures and, hence, fluid velocity in-372 creases with frequency. Despite the different magnitudes of  $\tau_{xy}$  for the different scenar-373 ios, the frequency dependence remains approximately the same for all cases. This fre-374



Figure 4. Time dependence of  $\tau_{xy}$  in response to a normally incident P-wave having a frequency f=10 Hz. This figure shows a close-up of the dotted square shown in Fig. 2. Red marks indicate the fracture surfaces. Panels a), b), and c) correspond to times equal to 0 s (maximal compression), T/4, and T/2, respectively, where T=1/f is the wave period (note the different color ranges). Panel d) shows the absolute value of  $\tau_{xy}$ , which corresponds to the maximum of the viscous shear stress developed at a given position.

quency dependence is in qualitative agreement with laboratory results (Candela et al., 375 2015) that point out how fracture unclogging is proportional to the increase of frequency. 376 Fig. 5 also shows that the development (or lack) of viscous shear stresses is strongly de-377 pendent on the direction  $(\theta)$  of the imposed seismic strain. For  $\theta=0^{\circ}$  (or  $\theta=90^{\circ}$ ) the fluid 378 pressure of the horizontal (vertical) fracture is much larger than that of the connected 379 and less compressed vertical (horizontal) fracture. The corresponding pressure gradient 380 between the fractures produces the fluid motion that we observe in the form of strong 381  $\tau_{xy}$ . For  $\theta = 45^{\circ}$ , and due to the fracture distribution considered, both fractures are equally 382 compressed by the P-wave and hence experience a similar fluid pressure increase. The 383 lack of significant fluid pressure difference between horizontal and vertical fractures im-384 plies that there is no significant fluid pressure exchange and  $\tau_{xy}$  becomes negligible (Fig. 385 5). Interestingly, azimuthal dependence of permeability changes have been recently re-386 ported (Shi et al., 2019; Weaver et al., 2019). Shi et al. (2019) attributed the angle de-387 pendence to preferential seismically-induced unclogging for fractures with a certain ori-388 entation with respect to the direction of wave propagation. 389

To better understand the behavior of  $\tau_{xy}$  shown in Fig. 5a to d and its relation with 390 the FPD process between the fractures, in Fig. 5e to h we show the P-wave attenuation 391  $(Q_P^{-1})$  as a function of frequency and incidence angle. The frequency dependence of  $Q_P^{-1}$ 392 shows the typical behavior associated with the effects of FPD between connected frac-393 tures (Rubino et al., 2013). The frequency range where the fluid pressure exchange be-394 tween connected fractures during a half-cycle of the wave is maximum, leading to max-395 imal seismic attenuation, is directly proportional to an effective diffusivity of the frac-396 tured medium and inversely proportional to the distance between the tip of a fracture 397 and its connection with another one (Rubino et al., 2014; Guo et al., 2017). The former 398 corresponds to the diffusivity of an effective porous medium where fractures parallel to 399



Figure 5. P-wave-induced viscous shear stress at fracture interfaces (left column) and P-wave attenuation (right column) as functions of frequency and incidence angle. The REV properties used for the sensitivity analysis are described in Table 2. White zones in panels a) to d) indicate values of  $\tau_{xy}$  below the viscous shear stress threshold of 0.1 Pa. Reducing the fluid viscosity (panel b) shifts the threshold to higher frequencies. Increasing the fracture aperture (panel c) shifts the threshold to lower frequencies. Note the correlation between the changes in the attenuation peak frequency for different physical properties in panels e) to h) and the frequency shifts of the viscous shear stress threshold in panels a) to d).



Figure 6. Viscous shear stress along the interface fluid-fracture wall as function of a normalized frequency for a normally incident P-wave (stars). Red dots correspond to the ratio between the attenuation for each case and the attenuation of the reference scenario at 10 Hz. The REV properties for each case are described in Table 2. The case  $L < L_{ref}$  corresponds to a fracture length of 0.28 m instead of 0.36 m.

the direction of the wave propagation front and the background act as the pore space 400 and the solid phase, respectively. Note that the frequency shifts of the viscous shear stress 401 threshold for different physical properties (Fig. 5a to d) follow the changes of the atten-402 uation peak frequency in Fig. 5e to h. Lower fluid viscosity (Fig. 5f) as well as larger 403 fracture aperture (Fig. 5g) shift the attenuation peak frequency  $(f_{FF-FPD})$  towards higher 404 frequencies. As a consequence, lower values of  $\tau_{xy}$  compared to the reference scenario 405 are observed at low frequencies (compare Fig. 5a with Figs. 5b and c). An interesting 406 effect occurs for lower background elastic moduli as it shifts  $f_{FF-FPD}$  towards lower fre-407 quencies (Fig. 5h). However, this is not manifested as a higher  $\tau_{xy}$  at low frequencies 408 compared with the reference scenario. This is due to the fact that a reduced compress-409 ibility contrast produces a reduced pressure gradient between the connected fractures 410 and, hence, less pronounced FF-FPD effects. Nevertheless, the levels of  $\tau_{xy}$  are still above 411 0.1 Pa (Fig. 5d). 412

The analysis of Fig. 5 shows that spatially varying properties may lead to differ-413 ent levels of  $\tau_{xy}$  and correspondingly of fracture unclogging. We can further quantify the 414 changes in the magnitude of  $\tau_{xy}$  with varying physical properties by plotting  $\tau_{xy}$  as a 415 function of the ratio between the seismic wave frequency (10 Hz) and  $f_{FF-FPD}$  for each 416 case (Fig. 6). In general, as the seismic wave frequency approaches  $f_{FF-FPD}$ ,  $\tau_{xy}$  is ex-417 pected to increase. A fluid viscosity decrease from 0.003 Pa.s to 0.001 Pa.s produces a 418 decrease in  $\tau_{xy}$  of  $\sim 70\%$  for a fixed seismic frequency. Even larger changes in  $\tau_{xy}$  occur 419 when the aperture of the fractures is doubled with respect to the reference scenario. We 420 also include in Fig. 6 the ratio between the attenuation of each case and the attenua-421

tion of the reference scenario at 10 Hz. Fig. 6 shows that the changes in attenuation with 422 respect to the reference scenario follow a similar trend as  $\tau_{xy}$ . Fig. 6 also compares the 423 responses when the fracture length is changed from 0.36 m to 0.28 m (case L<L<sub>ref</sub>). This 424 is an interesting case regarding the link between  $\tau_{xy}$  and the changes in seismic atten-425 uation. We note that by decreasing the aspect ratio of the fractures, the attenuation does 426 not increase as much as expected from the comparison with the other cases. This is due 427 to the smaller fluid storage volume involved in the FPD process. On the other hand, the 428 seismically-induced  $\tau_{xy}$  is slightly larger than expected. For a background medium char-429 acterised by lower bulk and shear moduli compared with the reference scenario, the de-430 crease in  $f_{FF-FPD}$  results in a higher seismic attenuation. However, this does not trans-431 late into higher levels of  $\tau_{xy}$  as pointed out in Fig. 5d. Although the relative changes in 432 seismic attenuation are not always straightforwardly associated with the variations of 433  $\tau_{xy}$ , they can provide valuable insight on the regions that are more affected by fracture 434 unclogging in a reservoir. 435

436

# 4.2 S-wave analysis and comparison with P-waves

The frequency and angle dependence of  $\tau_{xy}$  as a result of the strain state produced 437 by a plane S-wave is shown in Fig. 7a to d. As for P-waves, we observe that for a given 438 fixed seismic strain imposed to the sample,  $\tau_{xy}$  increases with frequency. S-waves show 439 maximal  $\tau_{xy}$  for  $\theta = 45^{\circ}$  (Fig. 7). As pointed out by Rubino et al. (2017), the induced 440 pressures have opposite signs in the horizontal and vertical fractures, respectively, which 441 results in a particularly large pressure gradient between them. This, in turn, is observed 442 in Fig. 7 as a large  $\tau_{xy}$  at  $\theta = 45^{\circ}$ . At horizontal and normal incident directions of S-wave 443 propagation, the fluid pressure increase inside the fractures is negligible and, correspond-444 ingly,  $\tau_{xy}$  approaches zero. As for P-waves, the behavior of  $\tau_{xy}$  observed in Fig. 7a to 445 d follows a similar angle dependence as the S-wave attenuation (Fig. 7e to h) due to the 446 link between the development of strong viscous shear stresses and the fluid pressure dif-447 fusion process that produces the seismic energy dissipation. For completeness, in Fig. 448 8, we quantify the changes in  $\tau_{xy}$  for the different cases of Table 2 as well as for the case 449  $L < L_{ref}$ . 450

Comparison of the effects imposed by P- and S-waves (Fig. 6 and 8) suggests that 451 S-waves produce larger transient  $\tau_{xy}$  for equal extensional and shear strain, respectively. 452 Fig. 9 expands on the dependence of  $\tau_{xy}$  with the magnitude of the seismic strain for 453 P- and S-waves. We consider a frequency-dependent  $\varepsilon_{\gamma\gamma}$  such that, at each frequency, 454  $\tau_{xy}=0.1$  Pa at normal P-wave incidence. The frequencies considered are 1, 10 and 100 455 Hz. We observe that in order to obtain the same magnitude of  $\tau_{xy}$ , a decrease in one or-456 der of magnitude in seismic wave frequency, requires an increase of approximately one 457 order of magnitude in the seismic strain. Lastly, Fig. 9b shows that for the same val-458 ues of seismic strain, S-waves propagating at 45° produce  $\tau_{xy}$  approximately two times 459 larger than P-waves at normal incidence. Note that a rotation of the orthogonal system 460 of fractures with respect to the vertical axis would produce a similar rotation in the an-461 gle dependence shown in Fig. 9. 462

463

### 4.3 Stochastic fracture networks

The analysis shown in Section 4 assumes an REV having two orthogonal intersecting fractures (Fig. 2). Such scenario is useful to illustrate the development of seismicallyinduced viscous shear stress for different physical properties in anisotropic fractured rocks. In this section, we analyze with more detail the impact on  $\tau_{xy}$  of fracture network properties such as the fracture length distribution, the fracture density, and the degree of fracture connectivity. To do so, we generate stochastic fracture networks in a sample as in Hunziker et al. (2018) assuming that the number of fractures as function of their length



Figure 7. S-wave-induced viscous shear stress at the fracture interfaces (left column) and S-wave attenuation (right column) as functions of frequency and incidence angle. The REV properties used for the sensitivity analysis are described in Table 2. White zones in panels a) to d) indicate values of  $\tau_{xy}$  below the viscous shear stress threshold of 0.1 Pa. The threshold frequency follows a similar trend as for P-waves (Fig. 5).



Figure 8. Viscous shear stress along the interface fluid-fracture wall as function of a normalized frequency for a  $45^{\circ}$  incident S-wave (stars). Red dots correspond to the ratio between the attenuation for each case and the attenuation of the reference scenario at 10 Hz. The REV properties for each case are described in Table 2. The case L<L<sub>ref</sub> corresponds to a fracture length of 0.28 m instead of 0.36 m.



Figure 9. Wave-induced  $\tau_{xy}$  as a function of the incidence angle. Panels a) and b) show P- and S-waves, respectively. The physical properties correspond to those of the reference case in Table 2. For equal seismic strain values, the maximal  $\tau_{xy}$  produced by S-waves is larger than the maximal  $\tau_{xy}$  associated with P-waves.



Figure 10. Synthetic samples representative of four 2D fractured media. The samples have different stochastic fracture networks with length distributions generated using Eq. 4. A larger value of a produces more shorter fractures (b and d), while a smaller value of a produces an increasing probability of larger fractures (a and c).  $d_a$  denotes the fracture density which varies between 1.5% (a and b) and 3% (c and d).

l can be described as (de Dreuzy et al., 2001)

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$$n(l) = d_a(a-1)\frac{l^{-a}}{l_{min}^{-a+1}},\tag{4}$$

where  $l \in [l_{min}, l_{max}]$  with the maximum fracture length  $l_{max}$  being half of the side length 473 of the REV, and the minimum length of the fractures  $l_{min}$  set to 1 cm. An interesting 474 feature of Eq. 4 is that it allows to control the number of fractures of a given length n(l)475 with two parameters. The exponent a controls the relative probability of longer and shorter 476 fractures. The second parameter is the fracture density  $d_a$ , which is the area covered by 477 fractures per unit area. In order to minimize the effects due to an anisotropic fracture 478 distribution, the orientations of the fractures and the positions of the fracture centers 479 are drawn from a uniform distribution as in Hunziker et al. (2018). As a consequence, 480 the fractured medium is effectively isotropic. For the analysis, the thickness of all frac-481 tures is constant and equal to 0.5 mm. Fig. 10 illustrates the diversity of the considered 482 stochastic fracture networks. We consider two fracture densities  $d_a$  (1.5% and 3%) and 483 two characteristic exponents of the fracture size distribution a (1.5 and 3). Increasing 484 the parameter a increases the number of shorter fractures with respect to the longer ones 485 (e.g., Figs. 10a and b) while increasing the fracture density  $d_a$  increases the number of 486 fractures in the sample (e.g., Figs. 10a and c). 487



Figure 11. Distribution of  $\tau_{xy}$  inside the fractures of the samples shown in Fig. 10. The observed  $\tau_{xy}$  distribution results from the strain associated with a propagating P-wave with a frequency f=10 Hz. For a fixed fracture density, higher levels of  $\tau_{xy}$  are observed for fracture networks with larger number of long fractures due to the increased fracture characteristic length and connectivity (e.g., comparison of panels c and d).

In Fig. 11, we plot the viscous shear stress distribution for the different fracture 488 networks shown in Fig. 10. The strain state corresponds to a normally incident P-wave 489 of f=10 Hz with  $\varepsilon_{zz} = 3 \times 10^{-5}$ , which is obtained by subjecting the different sam-490 ples to the vertical relaxation test illustrated in Fig. 3a. We limit the analysis to nor-491 mal incidence due to the isotropic seismic response of the sample. Fig. 11 shows that 492 samples with larger fracture density as well as a lower parameter a exhibit higher val-493 ues of  $\tau_{xy}$  in the samples. The increase for higher fracture density is expected as it in-494 creases the fluid storage volume contributing to the FPD process for a fixed sample size. 495 The correlation between  $\tau_{xy}$  and the parameter a is related to the characteristic frac-496 ture length involved in the FPD process and the degree of fracture connectivity in the 497 sample. A decreasing value of a results in a lower number of shorter fractures and thus 498 in an increase of the characteristic time scale of the FPD process, which in turn leads 499 to a shift of  $f_{FF-FPD}$  towards the low frequency range (Hunziker et al., 2018). From 500 the analysis of Fig. 6, the corresponding larger ratio between the considered frequency 501 and  $f_{FF-FPD}$  is expected to be reflected in higher levels of  $\tau_{xy}$ . At the same time, a de-502 creasing value of a increases the number of fracture connections due to the presence of 503 longer fractures. This in turn increases the amount of fluid storage volume contribut-504 ing to the FPD. 505

In Fig. 12, we quantify this analysis by computing the viscous shear stress per unit of fracture area in the sample. We normalize by the area occupied by the fractures  $(A_{frac})$ 



Figure 12.  $\tau_{xy}$  per unit of fracture area  $(A_{frac})$  as a function of the parameter *a* of Eq. 4. Filled and empty circles correspond to P- and S-waves, respectively. Blue and red colors represent fracture densities of 1.5 and 3%. The quantity  $\tau_{xy}/A_{frac}$  decreases exponentially with *a* (i.e., as the number of short unconnected fractures increases).

in the sample to compare cases with different fracture density. We consider the same cases 508 shown in Fig. 10 plus an intermediate case given by a=2.25. It is important to mention 509 that the values plotted in Fig. 12 represent a single realization for each case. For com-510 pleteness, we also plot the values for S-waves. We observe that as the number of longer 511 fractures, and, hence, the characteristic length and degree of connectivity, in the sam-512 ple increases (decreasing a), the quantity  $\tau_{xy}/A_{frac}$  increases exponentially. Lastly, al-513 though P- and S-waves produce comparable levels of  $\tau_{xy}/A_{frac}$ , S-waves are more effi-514 cient than P-waves to produce large viscous shear stress. 515

# 516 4.4 Effect of fracture geometry

Until now, we have computed  $\tau_{xy}$  utilizing 2D samples (Figs. 2 and 10). A disad-517 vantage of considering 2D samples is that we cannot properly model the effects associ-518 ated with a spatially heterogeneous fracture aperture. The reason is that 2D simulations 519 assume that fractures extend infinitely in the third dimension and, hence, local varia-520 tions in fracture aperture cannot be modelled. In the following, we study the effects of 521 fracture aperture distribution by considering the 3D sample shown in Fig. 13. For brevity 522 we only subject the sample to one oscillatory relaxation test in which a normal displace-523 ment is applied along the top surface of the sample, while the lateral and bottom sur-524 faces are confined. This is a 3D generalization of the 2D test shown in Fig. 3a, and is 525 representative of the action of a normally incident P-wave. The fracture aperture dis-526 tribution is characterized by regions of zero aperture (contact areas) and regions with 527 aperture h=1 mm (open areas). Contact and open regions are represented with back-528 ground and fluid properties, respectively. The corresponding fluid and elastic background 529 physical properties are those given in Table 2 for the reference scenario. The aperture 530 distribution of the vertical and horizontal fractures in the REV of Fig. 13 is assumed 531 to be the same. Following Pyrak-Nolte and Nolte (2016), the aperture distribution of 532 the fractures was generated using the stratified percolation approach of Nolte and Pyrak-533



Figure 13. Synthetic sample representing a unit cell of a 3D periodically fractured rock. The sample contains two connected orthogonal fluid-saturated fractures. 3D samples allow for modelling contact areas between the fracture walls which is not possible for 2D samples as they would extend infinitely in the third dimension thus affecting the effective length of the fractures.

Nolte (1991). A detailed explanation of the fracture aperture distribution generation, 534 which is based on a recursive algorithm that defines a self-similar cascade can be found 535 in Lissa et al. (2019). One of the most important advantages of this model is that it al-536 lows to control the characteristic correlation length of the contact areas. Due to the higher 537 computational cost of the 3D simulations and to avoid problems with the meshing pro-538 cess, we have considered an open fracture aperture 10 and 2 times larger than for the 539 2D samples shown in Figs. 2 and 10, respectively. Given that a thicker fracture increases 540  $f_{FF-FPD}$  (e.g., Fig.6), we impose a seismic strain of  $\varepsilon_{zz} = 2 \times 10^{-5}$  to have viscous 541 shear stress values above 0.1 Pa for all the analyzed cases. 542

We first consider the case of two fracture aperture distributions with correlated (long 543 characteristic length) and uncorrelated (short characteristic length) contact area distri-544 butions (Fig. 14a and c, respectively). Both fractures have contact area density equal 545 to 10%, which means that the volume fraction of fractures is the same for both models. 546 Note that in Fig. 14 we only plot the aperture distribution for the vertical fracture as 547 it is the same for the horizontal one. For brevity, in Figs. 14b and d we only show the 548 component of the viscous shear stress tensor  $\tau_{yz}$  because it is the most affected by FPD between fractures due to the spatial distribution of the fractures. We only plot  $\tau_{yz}$  for 550 the vertical fracture because it shows a similar behavior in the horizontal fracture. Cold 551 and hot colours in Fig. 14 denote low and high  $\tau_{yz}$ , respectively, while contact areas are 552 plotted in black. Despite the spatially heterogeneous distribution of  $\tau_{yz}$  associated with 553 the geometry of the contact areas, large values of  $\tau_{yz}$  are still present in the open frac-554 ture regions. Due to the spatial distribution of the contact areas, the correlated fracture 555 is mechanically more compliant than the uncorrelated one. This results in larger  $\tau_{yz}$  in 556 the case of the fracture with correlated contact area distribution (Fig. 14b) compared 557 with an uncorrelated distribution. Moreover, although  $\tau_{uz}$  tends to increase in the vicin-558 ity of contact areas, the channelized flows produced by the contact area distribution seems 559 to dominate the development of large viscous shearing. In particular, contact area dis-560 tributions can significantly affect the hydraulic connectivity between the intersecting frac-561 tures. This, in turn, drastically changes the levels of  $\tau_{yz}$  (note the different color scales 562 in Figs. 14b and d). 563

In order to minimize the effect of the compressibility contrast between the fractures 564 and the background, we consider the contact area distribution shown in Fig. 14e, which 565 results in a similar fracture compliance as the one shown in Fig. 14a ( $\sim 2.5\%$  relative 566 difference). To produce similar mechanical compliance for correlated and uncorrelated 567 distributions, the contact area density has been decreased from 10% to 2.6%. Fig. 14f 568 shows that, as a consequence of the uncorrelated contact area distribution,  $\tau_{yz}$  exhibits 569 a channelized pattern as in Fig. 14d. However, the levels of  $\tau_{yz}$  are larger than in Fig. 570 14d due to the higher compressibility contrast between the fractures and the background 571 (note the different color scales in Fig. 14d and f). 572

### 573 5 Discussion

#### 574

# 5.1 Permeability changes due to fracture unclogging

The question regarding how seismically-induced viscous shearing changes the per-575 meability of a reservoir due to fracture unclogging remains unexplored in this work (Fig. 576 1 arrow c). Our study is limited to the analysis of the development of strong viscous shear 577 stress in the fluid saturating a fracture. Following previous studies, we adopted a thresh-578 old value of  $\tau_{xy}=0.1$  Pa to indicate potential fracture unclogging initiation. The repre-579 sentativeness of this value for the physical properties of the rock as well as for the char-580 acteristics of the seismic waves analyzed in this work is speculative. Nevertheless, we can 581 qualitatively verify the validity of the adopted threshold. Elkhoury et al. (2006) found 582 that the permeability changes  $(\Delta \kappa)$  in a reservoir follow a linear trend with the dynamic 583 shear strain imposed by the waves of earthquakes. This observation is in qualitative agree-584



Figure 14. Fracture geometry (left column) and  $|\tau_{yz}|$  for f=10 Hz and P-wave incidence (right column). The plots are computed at one of the interfaces between each fracture and the background. Black and white regions in a, c, and e illustrate contact areas and open fracture, respectively. Panels a and c correspond to fractures with same volume but correlated and uncorrelated contact area distributions, respectively. Panels a and e correspond to fractures with same compliance under dry conditions but with different contact area correlation length. Note the different color scales in panels b, d, and f.



Figure 15. Validity of  $\tau_{xy}=0.1$  Pa as a threshold for fracture unclogging initiation. Panel a shows the relation between seismic shear strain and increase in reservoir permeability found by Elkhoury et al. (2006). Panel b shows the relation between seismic shear strain and viscous shear stress from our numerical simulations.

ment with laboratory experiments (Elkhoury et al., 2011; Candela et al., 2014). These have also shown that the magnitude of the permeability enhancement due to fracture unclogging scales with the amplitude of the dynamic strain for a fixed frequency.

Elkhoury et al. (2006) quantified the above mentioned linear relation using mea-588 surements from two wells. Fig. 15a shows the strain- $\Delta \kappa$  relation assuming the mean value 589 of the two slopes obtained by Elkhoury et al. (2006). Note that we use a logarithmic x-590 axis to plot the linear strain- $\Delta \kappa$  relation. They observed permeability changes as small 591 as  $0.5 \times 10^{-15} \text{m}^2$ , which correspond to shear strains in the order of  $1 \times 10^{-6}$ . On the other 592 hand, we can plot the relation between the shear strain (for a  $45^{\circ}$  incident S-wave) and 593 the viscous shear stress for the same properties considered in the analysis of Fig. 9. In 594 Fig. 15b, we plot the relation for two frequencies (0.5 and 1 Hz) that are close to the fre-595 quency of the signals analyzed by Elkhoury et al. (2006). Assuming that the strain- $\Delta \kappa$ 596 relation found by Elkhoury et al. (2006) also holds for our fractured medium, we would 597 expect fracture unclogging effects at shear strains in the order of  $1 \times 10^{-6}$ . Indeed, those 598 strain values produce viscous shear stresses that are very close to 0.1 Pa for the frequen-599 cies considered. This supports not only our theoretical modelling but also the viscous 600 shearing threshold adopted. Lastly, note that as the seismic shear strain increases, our 601 simulated  $\tau_{xy}$  increases while the observed  $\Delta \kappa$  increases as well. This agreement further 602 supports fracture unclogging as the mechanism of permeability increase. 603

604

## 5.2 Fluid motion modelling

The frequencies considered in our study belong to the seismic frequency range. How-605 ever, in Figs. 5 and 7, we illustrate the frequency dependence of  $\tau_{xy}$  up to sonic frequen-606 cies. For relatively high frequencies, it is important to verify the validity of the assump-607 tions of the proposed numerical upscaling. One of the assumptions is related to the mod-608 elling of the fluid motion in the fractures in which advective acceleration terms are as-609 sumed to be small compared to the viscous terms in the Navier-Stokes equations (Ap-610 pendix A). The condition for the inertia forces to be negligible compared to the viscous 611 forces requires the reduced Reynolds number  $Re^{\star} = Re\alpha << 1$  (Zimmerman & Main, 612 2004). The Reynolds number Re can be approximated as  $\rho_f \tau_{xy} h^2/\eta^2$  and  $\alpha$  is the as-613 pect ratio of the fracture. The frequency dependence of  $Re^{\star}$  is given through  $\tau_{xy}(\omega)$ . For 614 the parameters in Table 2, and the maximal  $\tau_{xy}$  observed in Figs. 5 and 7,  $Re^{\star} < 0.01$ . 615 This means that for the order of magnitude of  $\tau_{xy}$  analyzed, our approach is valid. An-616

other assumption that must be examined for all frequencies is the validity of an effec-617 tive medium representation of the fractured sample. This assumption requires  $\lambda \gg \text{REV}$ , 618 where  $\lambda = v/f$  is the wavelength and v the seismic wave phase velocity. At 10 kHz, the 619 wavelengths become comparable to the size of the REV and departures from effective 620 medium responses are expected to arise. Although for the relatively low frequency (10 621 Hz) considered in the sensitivity analysis performed in this work these assumptions are 622 fulfilled, it is important to remark that the validity of both assumptions is extremely de-623 pendent on the fluid, background and fracture properties. Lastly, it is important to men-624 tion that we use the same mesh for all frequencies analyzed. In this case, the mesh needs 625 to be fine enough to be able to capture the spatial variability of the FPD process at the 626 highest frequency of interest. Additional information on the discretization process can 627 be found in Figures S1 to S3 of Supporting Information. 628

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# 5.3 Application of the methodology to surface waves

The numerical strategy utilized in this work, and Eq. 3 in particular, allows to quan-630 tify the spatial distribution of a desired field, such as fluid displacement or pressure, in 631 response to arbitrary strain states of the REV. We have computed the viscous shear forces 632 in response to the action of body waves at arbitrary directions of wave propagation. This 633 is in line with the laboratory experiments shown in section 2, which in most cases re-634 produce the action of a compressional wave to study fracture unclogging. Moreover, re-635 cent studies have shown that body waves characterised by relatively high frequencies may 636 impose strain rates in the order of  $10^{-5}$  and affect the fluid pressure in a reservoir (Lupi 637 et al., 2013; Lupi, Fuchs, & Saenger, 2017). However, most of the field evidence suggests 638 that the seismic strain inducing pore fluid pressure changes in reservoirs is predominantly 639 related to surface waves (Brodsky et al., 2003; Manga & Brodsky, 2006; C.-Y. Wang, 2007). 640 Moreover, most of the available field observations of fracture unclogging effects rely on 641 the analysis of surface waves (Manga et al., 2012). As an example, Taira et al. (2018) 642 recently used an ambient noise-based seismic interferometry approach to show that the 643 Salton Sea geothermal field experienced a number of sudden surface wave velocity re-644 ductions in response to the dynamic stresses from local and regional earthquakes. They 645 interpret the reduction of velocity as an increase of apparent fracture density due to the 646 unclogging of fractures in response to the seismically induced pore pressure fluctuations. 647 We have computed the effects of body plane waves due to the simplicity of the analyt-648 ical solution of the strain produced by them. Given that the strain state associated with a surface wave can be thought as a superposition of compressional and shear modes (Carcione, 650 2007), we believe that our analysis is also meaningful to understand the effects of sur-651 face waves. Nevertheless, extending our analysis to consider strains states typical of sur-652 face waves as the source of the pressure oscillations that create viscous shearing in the 653 fractures will be part of our future studies. 654

655

### 5.4 Seismic stimulation

As a result of documented field and laboratory experiments, it has been suggested 656 that stimulation of reservoirs with low-amplitude stresses could be a possible method for 657 active permeability enhancement. This is particularly relevant in engineered systems where 658 permeability is critically important, for example, in enhanced geothermal systems (Manga 659 et al., 2012). Indeed, the use of stimulation through the application of dynamic shak-660 ing has a long history of study for enhanced oil recovery. Beresnev and Johnson (1994) 661 reviewed a series of laboratory and field studies covering the seismic-ultrasonic frequency range that support and test the use of seismic stimulation for enhanced oil recovery. Pride 663 et al. (2008) refer to the common practice of using downhole seismic sources in stimu-664 lation wells for oil-reservoir stimulation. In that case, seismic waves are created by a sud-665 den release of fluid inside the borehole. Although our results suggest that dynamically 666 changing permeability of fractured systems may be feasible, we acknowledge the engi-667

neering challenges that artificial stimulation of reservoirs represent. Karve et al. (2017) 668 pointed out that the effectiveness of seismic stimulation for enhanced oil recovery using 669 artificial sources, such as, for example, a fleet of surface vibrators or downhole hydraulic 670 pumps, depends on the strength and spatial extent of the wave motion in the oil reser-671 voir. They proposed an optimization-based algorithm for designing an efficient wave en-672 ergy delivery system to generate the wave motion of the required magnitude in the reser-673 voir. Regarding the exposure time to seismic stimulation, Kocharyan et al. (2011) found 674 that as the imposed strain decreases, a substantially longer exposure to vibrations is re-675 quired for the permeability of a crack to increase. Our work points out that future re-676 search should be focused on exploring the impact of enhanced oil recovery technologies 677 on fracture unclogging considering additional factors, such as directivity, radiation pat-678 tern, stimulation duration, and reservoir structure, which are expected to influence the 679 magnitude of the seismically-induced viscous shearing. The methodology used in this work 680 to obtain the viscous shear stress inside an REV of a given formation of interest due to 681 an arbitrary strain state can help to find the corresponding set up optimization. 682

#### 683

# 5.5 Laboratory experiments

The results shown in Section 4.4 are in qualitative agreement with the findings of 684 Kutay and Aydilek (2009), which suggested that the maximum shear stresses caused by 685 the viscous fluid movement can be generated at pore space constrictions. In the study 686 of Kutay and Aydilek (2009), large viscous shearing due to water flow within the pore 687 structure of an asphalt was believed to cause the asphalt binder to separate from the ag-688 gregate surface. In the case of fractures, the viscous shearing is significantly affected by 689 the fracture aperture distribution which, in turn, may produce spatially variable frac-690 ture unclogging. Pyrak-Nolte and Morris (2000) showed that, as a result of the contact 691 area distribution, uncorrelated fractures tend to develop multiple flow paths making them less sensitive to aperture changes (e.g., due to increasing loading) than correlated ones. 693 In addition to the different levels of viscous shearing developed for correlated and un-694 correlated fractures, this may indicate that fracture unclogging effects are more easily 695 observed in correlated fractures. Manga et al. (2012) speculated that the differences in 696 the permeability response observed in some of the experiments listed in Table 1 are likely 697 due to the fracturing mechanism, the type of applied oscillation, and the frequency of 698 the oscillation. The effects associated with the internal structure of the fracture observed 699 in Fig. 14 may also explain some of the differences in permeability changes observed in 700 the laboratory. Although in our simulations the fracture properties are invariant dur-701 ing and after the passage of the seismic waves, the study of the evolution of the aper-702 ture of fractures as a result of the mobilization of particles can be addressed in the fu-703 ture. 704

# 705 6 Conclusions

We performed numerical simulations to assess the potential of seismic waves to pro-706 duce viscous shear stresses in fluid saturated fractures that are strong enough to initi-707 ate fracture unclogging. Our results show that seismically induced viscous shearing in 708 the order of those initiating fracture unclogging (0.1 to 1 Pa) are plausible for strain mag-709 nitudes and frequencies typically observed in field and laboratory measurements. In agree-710 ment with previously reported laboratory experiments, viscous shear stress was observed 711 to increase with frequency and seismic strain magnitude. For a relatively simple system 712 of orthogonal intersecting fractures, the development of viscous shear stress strongly de-713 pends on the direction of wave propagation and this anisotropy is different for P- and 714 S-waves. P- and S-wave related effects are at its minimum and maximum, respectively, 715 at  $45^{\circ}$  incidence angle. Moreover, for the same magnitude of seismic strain, the maxi-716 mal  $\tau_{xy}$  produced by S-waves was found to be approximately two times larger than the 717 maximal effects of P-waves. This points out the importance of not only considering mag-718

nitude and hypocentral distance of the earthquakes to interpret dynamic triggering events
 but also directivity and wave mode effects.

Our numerical study shows that, for a given seismic strain amplitude, frequency, 721 and direction of wave propagation, larger viscous shear stress is expected for more vis-722 cous fluids, stiffer background rocks, and thiner fractures. In other words, we showed that 723 higher viscous shear stresses are expected for higher ratios  $f/f_{FF-FPD}$ , where f is the 724 seismic wave frequency and  $f_{FF-FPD}$  is the frequency at which the fluid pressure gra-725 dient between the more compressed fracture and the connected (and less compressed) 726 727 fracture produces maximal seismic attenuation. This implies that regions where pore fluids change or with different pressure and temperature conditions may experience more 728 fracture unclogging, and consequently stronger permeability enhancement, than others. 729 We showed that seismic attenuation may be a valuable attribute to characterize regions 730 that are more affected by fracture unclogging. 731

We have also analyzed the importance of the fracture network distribution on the 732 development of strong viscous shearing. We showed that for isotropic fracture distribu-733 tions having the same fracture density, viscous shear stresses are more significant in frac-734 ture networks with a higher characteristic fracture length. This is related to both the 735 increased likelihood of fracture connections, and hence of the pore fluid volume involved 736 in the FPD process, and also to the fact that the FPD characteristic frequency is closer 737 to the frequency of seismic waves. Finally, we found that the fracture aperture distri-738 bution also controls the development of viscous shear stresses. Spatially heterogeneous 739 fracture apertures can produce locally enhanced viscous shear stress, which tend to be 740 more pronounced for correlated fractures. 741

# 742 7 Appendix A: Mathematical formulation

The methodology used for this work is based a numerical solution of a coupled system of equations consisting of the linearized Navier-Stokes equation for the laminar flow of a compressible viscous fluid and the linear elastic equation for a nonporous solid material (Quintal et al., 2016). The coupled system of equations can be found by solving the conservation of momentum

$$\nabla \cdot \boldsymbol{\sigma} = 0, \tag{5}$$

where  $\sigma$  is the stress tensor whose components  $\sigma_{ij}$  are defined through generalized stressstrain relations in frequency domain

$$\sigma_{ij} = 2\mu\varepsilon_{ij} + \lambda e\delta_{ij} + 2i\omega\eta\varepsilon_{ij} + i\omega\eta_{\lambda}e\delta_{ij},\tag{6}$$

with  $\mu$  being the shear modulus of the material,  $\eta$  and  $\eta_K$  the shear and bulk viscosi-

ties, respectively,  $\omega$  is the angular frequency and

$$\varepsilon_{ij} = \frac{1}{2} \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right),$$

$$e = \sum_{i=1}^3 \varepsilon_{ii},$$

$$\lambda = K - \frac{2}{3}\mu,$$

$$\eta_{\lambda} = \eta_K - \frac{2}{3}\eta,$$
(7)

754

759

748

751

where K is the bulk modulus of the material, u describes either the displacement of the fluid or that of the solid in the corresponding subdomains, and i, j = x, y, z. In the nonporous background,  $\eta = \eta_K = 0$  and Eq. 6 reduces to the classical Hooke's law in an elastic material

$$\sigma_{ij} = 2\mu\varepsilon_{ij} + \lambda e\delta_{ij}.\tag{8}$$

Assuming that a compressible viscous fluid is filling the fractures, and hence  $\mu = \eta_K =$ 

<sup>761</sup> 0, Eq. 6 in the fractures reduces to

762

$$\sigma_{ij} = Ke\delta_{ij} + 2i\omega\eta\varepsilon_{ij} - \frac{2}{3}i\omega\eta e\delta_{ij}.$$
(9)

The bulk viscosity of the fluid is set to zero under the assumption of quasistatic flow. As pointed out by Quintal et al. (2016), this means that in the fracture we solve the quasistatic (inertial terms neglected) linearized (advective acceleration neglected) Navier-Stokes equations for the laminar flow of a Newtonian fluid (Zimmerman & Main, 2004). Consequently, the viscous shear stresses can only be caused by fluid pressure diffusion inside the hydraulically connected fractures. This approach is relevant for lithologies with low permeability such as those prevailing in Enhanced Geothermal Systems in which hydraulically fracturing the host rock is crucial for the economic exploitation of geothermal resources. The hydraulic response of such low-permeability crystalline rocks containing fractures should be particularly susceptible to unclogging because small changes in the flow paths may have large impacts on effective permeability (Manga et al., 2012). Finally, in the frequency domain, the viscous shear stress in Eq. 1 can be written as

$$\tau_{ij}(\omega) = \eta i \omega \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right), \qquad i, j = x, y, z, \tag{10}$$

<sup>763</sup> which is zero in the nonporous background.

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