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Behavioral responses of rural and urban greater whitetoothed shrews (*Crocidura russula*) to sound disturbance

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Sound disturbance does not explain behavioral differences between rural and urban greater white-toothed shrews (Crocidura russula) --Manuscript Draft--

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Abstract:	The development of urban areas imposes challenges that wildlife must adapt to in order to persist in these new habitats. One of the greatest changes brought by urbanization was an increase in anthropogenic noise, which may impair communication and detection of acoustic cues required for survival. Small mammals have been neglected in the study of behavioral adaptations to urban environments and sound disturbance. In this study, we compared the behavioral responses of urban and rural greater white-toothed shrews, Crocidura russula, to different sound stimuli. A total of 32 shrews, 16 from each habitat, were exposed in captivity to four sound treatments: silence, tawny owl calls, traffic noise and white noise. Urban and rural shrews responded differently when exposed to the silence treatment. Urban animals were more active, fed more frequently, and used less torpor than rural counterparts. However, responses to the other three sound treatments were similar: both urban and rural shrews exhibited a slight decrease in activity and feeding behavior, as well as more fleeing responses, when exposed to traffic noise or white noise, but not to owl calls. These results confirm that adaptation to the urban environment leads to changes in the natural behavior of greater white-toothed shrews, but not to changes in their acoustic response. Factors besides soundscape are discussed in order to explain the behavioral differences between urban and rural shrews.		
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Impacts on small mammals along an urbanization gradient

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Urban ecology. Developed method to calculate the "recovery rate"

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Abstract

The development of urban areas imposes challenges that wildlife must adapt to in order to persist in these new habitats. One of the greatest changes brought by urbanization was an increase in anthropogenic noise, which may impair communication and detection of acoustic cues required for survival. Small mammals have been neglected in the study of behavioral adaptations to urban environments and sound disturbance. In this study, we compared the behavioral responses of urban and rural greater white-toothed shrews, Crocidura russula, to different sound stimuli. A total of 32 shrews, 16 from each habitat, were exposed in captivity to four sound treatments: silence, tawny owl calls, traffic noise and white noise. Urban and rural shrews responded differently when exposed to the silence treatment. Urban animals were more active, fed more frequently, and used less torpor than rural counterparts. However, responses to the other three sound treatments were similar: both urban and rural shrews exhibited a slight decrease in activity and feeding behavior, as well as more fleeing responses, when exposed to traffic noise or white noise, but not to owl calls. These results confirm that adaptation to the urban environment leads to changes in the natural behavior of greater white-toothed shrews, but not to changes in their acoustic response. Factors besides soundscape are discussed in order to explain the behavioral differences between urban and rural shrews.

Keywords: behavioral plasticity, heterothermy index, nocturnal activity, risk perception, Soricidae, urban noise.

Introduction

The increased concentration of human populations in urbanized areas is a global phenomenon severely affecting biodiversity (Seto et al. 2012). The resulting environment is extremely altered, with few patches of natural vegetation and high levels of anthropogenic disturbance such as chemical, light and noise pollution (Barber et al. 2010; Hölker et al. 2010). Animals persisting in these environments must overcome such disturbances through adaptation. These adaptations result from either a species' phenotypic plasticity of traits already present, or from genetic shifts in traits that increase the species' fitness under the new environmental conditions (Sol et al. 2013; McDonnell and Hahs 2015). Because the capacity to plastically adjust behaviors is limited (Snell-Rood 2013), not all species are able to adapt to these disturbances and colonize or persist in cities (Wong and Candolin 2015). In the case of small, ground-dwelling mammals, this is reflected in numerous studies showing a general decrease in abundance and richness of urban-sensitive species in cities when compared with adjacent areas (e.g. Cavia et al. 2009; Gomes et al. 2011; Klimant et al. 2017; Łopucki and Kitowski 2017). Without sufficient vegetation cover and high levels of habitat connectivity, many small mammals cannot persist in urban areas (Cavia et al. 2009; Gomes et al. 2011; Łopucki and Kitowski 2017). One of the most prominent and well-studied urban disturbances is man-made noise as a byproduct of urbanization (Read et al. 2014; Shannon et al. 2016b). Exposure to anthropogenic noise has several consequences for wildlife, from interfering with the ability to forage and stay alert for predators (Klett-Mingo et al. 2016; Finch et al. 2020) to declines in reproductive success (Halfwerk et al. 2011) and altered trophic relationships (Francis et al. 2009). The diverse arrays of anthropogenic sound sources, which vary in frequency, intensity, and duration, are relevant to

understand how organisms perceive, and react to, these sounds. Traffic noise is one of the most

common and best studied sources of anthropogenic noise (Luo et al. 2014; Pieniażek et al. 2017). Depending on the location inside the urban matrix, exposure to traffic noise can either be continuous and chronic or sudden and unpredictable. The later often elicits strong responses from animals similar to antipredator behavior (Frid and Dill 2002; Shannon et al. 2014; Klett-Mingo et al. 2016), and while the former may not be perceived as threatening due to habituation, it can interfere with the animals' ability to detect acoustic cues or signals such as calls from conspecifics or sounds made by predators or prey (Patricelli and Blickley 2006; Barber et al. 2010).

Small mammals partly depend on acoustic cues to communicate with conspecifics (Simeonovska-Nikolova 2004; Musolf et al. 2010) and to assess the structure of their habitat (Siemers et al. 2009). Several studies have shown the influence of noise on small mammal behavior in both the field and the lab: traffic noise can impact the activity levels (Shannon et al. 2014) and predator detection abilities (Shannon et al. 2016a) of black-tailed prairie dogs, interfere with communication signals (foot drumming) used by endangered Stephens' kangaroo rat (Shier et al. 2012), and impact the locomotor activity of striped field mice (Pieniażek et al. 2017). Furthermore, the behavior and physiology of wild mice has been shown to be negatively impacted by mining machinery noise, with different effects based on its amplitude and frequency (Mancera et al. 2018). However, to the best of our knowledge, no laboratory studies have yet compared the impacts of sound disturbance on the behavior of rural and urban populations of small mammals.

The main aim of the present study was to compare the behavioral responses of small mammals from rural and urban areas to sound disturbances, using as a model species the greater white-toothed shrew (Crocidura russula). Shrews are sensitive to urbanization, and decline in

abundance and richness in highly urbanized areas (Vergnes et al. 2013; Klimant et al. 2017; Lopucki and Kitowski 2017). Similar to other shrew species, *C. russula* is a vocal species, using a range of different sounds for communication and allegedly a rudimentary form of echolocation, termed echo-orientation (Siemers et al. 2009). As opposed to other small mammal species like mice, which communicate predominantly using ultrasonic calls over very short distances (Musolf et al. 2010), shrews mainly use sonic frequencies (Zsebők et al. 2015), which travel further and might thus be more affected by noise. Consequently, noise might affect the vocal communication and echo-orientation of shrews. They thus offer a good model species to test sound disturbance in a synurbic small mammal.

To differentiate if shrews from different habitats (urban vs. rural) respond differently to anthropogenic noise and natural sounds (the calls of predators), we exposed shrews at night to traffic noise and predator calls. We selected calls of the tawny owl (*Strix aluco*), a predator relatively common in rural areas but mostly absent in urban areas (Capizzi 2000). Since the soundscape differs along the rural-urban gradient, we predict rural shrews will react more strongly to owl calls and traffic noise. As owl calls are seldom heard in cities (personal observation), and urban shrews are likely habituated to traffic noise, we expect them to exhibit a weaker response to these sounds.

A recent study suggested daily torpor can be used not only as an energy-saving strategy but also as a strategy to avoid danger (Geiser and Brigham 2012; Nowack et al. 2017). Similarly to most shrew species, *C. russula* uses torpor to save energy when facing adverse environmental conditions (Nagel 1977; Taylor 1998; Oliveira et al. 2016). We thus additionally studied the effect of habitat and sound on torpor use. We predict that, if *C. russula* perceives traffic noise

and owl calls as a threat, they will use torpor more often when being exposed to either of the two

disturbance sounds.

 Methods

Capture Sites and Shrews

Thirty-two shrews were trapped with wooden-box live traps ("dziekanówka" type, size $16.5 \times 8.0 \times 9.5$ cm; produced by PPUH A. Marcinkiewicz, Rajgród, Poland) during the night. Traps were opened before sunset and checked every three hours until 01h00. No bait was provided, and no mortality was observed inside the traps. Captured C. russula were brought to the animal facility of the Faculty of Sciences, University of Lisbon, while pregnant females and other trapped animals were released on site.

Shrews were captured in two distinct locations with different habitats. Rural shrews (N =16) were captured in Sintra-Cascais Natural Park in June and July 2016. Trapping sites were characterized by a wet climate, typical forest habitats with Mediterranean shrubby-type vegetation and *Quercus spp.*, and had minimal human disturbance. Urban shrews (N = 16) were captured in the city of Lisbon in public gardens, parks and small patches of vegetation near buildings and roads in October and November 2016.

In the animal facility, shrews were housed in non-transparent plastic cages with a grid top (38×28×17 cm) enriched with soil, sand, and a cardboard eggbox, and maintained under room temperature (18 \pm 1 °C). Photoperiod was 12L:12D with lights on from 08h00 until 20h00. They had access to a water bowl and were fed with 0.5 g of mealworms, 1.5 g of blowfly pupae and 4.0 g of minced beef (Oliveira et al. 2016). Water and food were replenished daily during the afternoon. After approximately three weeks, captive shrews were released at their original capture site.

Experimental Procedure

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Each shrew was tested in four sequential trials, each lasting from 20h00 until 10h00 of the next morning. Subsequent trials were separated by three days to avoid habituation to the experiment itself. For each trial, shrews were taken out of their home cages at 19h00 and placed in the experimental arena (50×50×30 cm) inside another room with an ambient temperature of 18 \pm 1 °C. The experimental arena had white sand as substrate and a small (5×5×5 cm) cylindrical cardboard shelter (Fig. 1). To monitor shelter temperature, a pre-calibrated iButton datalogger (iButton DS1990A Thermocron, Maxim Integrated Products, Inc.), programmed to take temperature measurements every minute, was placed at the base of each shelter. In combination with video information (see below), we could deduct if a shrew inside the shelter was bellow normothermia or not (Willis et al. 2005). Food and water were provided to each shrew before the beginning of the experiment, at 20h00 (Fig. 1). Food consisted of 4.5 g of mealworms, which was shown in pilot studies to be enough to maintain their body mass throughout the experiment. At the end of the experiment, shrews were returned to their home cages.

The shrews' behavior was video-recorded during the entire experiment using a webcam (NGS Swift Cam-300). During the dark phase, the arena was illuminated with a dim red LED light (0.7 W) so we could observe shrews without disturbing them.

Sound Playback Experiments

Shrews were exposed individually to four different sound treatments, one per trial: tawny owl calls (as a predator sound), traffic noise (as an anthropogenic sound), silence and white noise (as control sounds). The order of sound treatments over each experimental night was randomized between individuals. During each night, the respective sound treatment was presented four times

for five minutes, starting at 21h, 00h, 03h, and 06h (Fig. 1). To avoid pseudo-replication, four different playbacks were used for each sound treatment (see below).

Silence was used as a baseline to analyse the behavioral differences between sound treatments. Note that, when the playback chain was activated, the played file did not contain any sound. White noise (a continuous sound containing similar energy along a wide range of frequencies) was used to assess the shrews' natural response to a disturbing and unfamiliar sound. Traffic noise was used to simulate anthropogenic disturbance and was obtained from various sources on the website freesound.org. Tawny owl calls were used to simulate the sound of a natural predator, and were often heard at night at the capture sites in Sintra (the rural habitat), but not in Lisbon (the urban habitat). Owl calls were also obtained from the freesound.org website and kindly provided by other sources (see Acknowledgements). Silence and white noise were generated using Audacity 2.1.0. All playbacks were edited using the same software so that playbacks for each sound treatment were similar in duration, intensity and frequency distribution (e.g. playbacks from different individuals but with similar numbers of calls for the owl calls treatment) (exemplary spectrograms of the four playback sounds are available in the Online Resource 1, Figs. S1–S4).

For playbacks, experimental stimuli generated by a laptop were converted to analog format (Edirol UA25-EX, D/A rate 44.1 Khz, 16 bit), amplified (Technics V500 Mark II) and delivered through a Tamon LB-10 loudspeaker. The frequency response of this audio chain, which varied within ± 7 dB in the range 20–20,000 Hz (Online Resource 1, Fig. S5), was measured by computing the transfer function between a constant amplitude sine sweep fed to the chain and recorded with a measuring 1/2" microphone Bruel & Kjaer 4188 (50 cm in front of the speaker, i.e. the position later occupied by shrews) and the same sweep sound at the entrance of

 the chain. Both signals (microphone and sweep) were simultaneously recorded (16 bit, 100 kHz) in different channels of a multifunction I/O USB device (USB-6521, National Instruments, Austin, TX, USA) and the transfer function computed with a custom-made software (PF) written in LabView. All experimental stimuli (except the silence treatment) were adjusted to 70 dB SPL (re 1 µPa) using the above-mentioned measuring microphone installed in a sound level meter Bruel and Kjaer 2238 Mediator positioned in the experimental arena.

Video Analysis

Boris version 4.1.10 (Friard and Gamba 2016) was used to analyse the recorded videos. We analysed the behavior in three steps: instant reaction (behavior observed immediately after the respective playback started), recovery rate (see section Data Analysis for details) and longterm reaction (behavioral patterns during one hour, beginning with the start of the playback). For the instant reaction, we registered three groups of behaviors: "shelter" (behavior could not be observed), "no reaction" (no apparent changes in behavior were observed), and "reaction" (immediate changes in behavior were observed) (Table 1). For the recovery rate and long-term reaction, we registered activity and feeding whenever the shrew was outside the shelter for 60 minutes after the start of the respective playback. The following criteria were used to ascertain activity and feeding behavior: activity was registered when the shrew was moving around, i.e. not being stationary for more than 30 seconds; feeding was registered when the shrew was eating mealworms for at least five seconds. When shrews were inside the shelter and their behavior could not be observed, we analysed the temporal variation in shelter temperature by calculating an heterothermy index (HI). The HI describes the temporal variation in body temperature of an individual during a given sampling period (see Boyles et al. 2011 for more details), and was calculated as follows: $HI = \sqrt{\frac{\sum (T_{b-mod} - T_{b-i})^2}{n-1}}$, where T_{b-mod} is the mode of the peak at the

highest iButton temperature values, T_{b-i} is the iButton measurements at a given time, and n is the number of measurements sampled. Higher HI values indicate an individual's body temperature was frequently below normothermia after a playback. Only data registered after every individual had been 10 minutes inside the shelter permanently was analysed.

Data Analysis

Statistical analyses were performed using R version 3.4.2 (R Core Team 2018) and Microsoft Excel 2016.

To analyse if shrews from the same habitat display different behavior categories ("no reaction", or "reaction") during the instant reaction, regardless of sound treatment, a Pearson's chi-squared test was performed. To analyse which sounds had significantly more reactions than silence, we followed with a post-hoc chi-square (X^2) analysis using the "fifer" package (Fife 2017).

For the recovery rates, we calculated the cumulative durations of activity and feeding (in seconds) from the start of a playback until 60 minutes later. One was attributed when an individual was displaying the respective behavior at the respective second, and zero was attributed otherwise. For each playback, we calculated a linear regression model in Excel with the evolution of the respective cumulative behavior over time, and an intercept crossing zero. The slope of each model was used as an estimate of the defensive response's attenuation over time, a modified version of the rate of recovery described in Vincze et al. (2016). A steeper positive slope indicates the respective individual performed a specific behavior earlier and/or for a longer period of time, i.e. had a faster recovery rate for that behavior.

For the long-term reaction to each sound, we quantified the relative duration of activity and feeding (range 0–1) during the same period (60 minutes) for each individual. Together with

the recovery rate (range 0-1), these measurements allowed us to have a clearer picture about the shrews' reaction to specific sounds. For example, if the recovery rate of activity is smaller than its relative duration, it means an individual's defensive response lasted longer, but the individual recovered quickly later.

To analyse the difference in recovery rates and long-term reactions of shrews on activity and feeding, linear mixed-effects models were used, accounting for repeated measurements from the same individuals, using the lme function from the 'nlme' package (Pinheiro et al. 2019). We used as fixed terms habitat (rural vs. urban), sound treatment (silence, owl calls, traffic noise and white noise), playback time (21h, 00h, 03h, 06h), and all two-way and three-way interactions between them. Homogeneity and independence assumptions were assessed graphically, visualizing the residuals versus fitted values (Zuur et al. 2010). Violations of these assumptions were dealt with using appropriate random effects and variance structures, and testing these using the Akaike information criterion corrected for small sample sizes (AICc). Models with lower AICc have less information loss, hence have higher quality. Using this procedure, the activity recovery model contained individual as a random slope, and time as the constant variance covariate; the feeding recovery model contained individual as a random slope and as a constant variance covariate. For the models on relative duration of activity, relative duration of feeding, and HI, we used the same fixed terms, and individual identity as a random intercept. Playback time was used as a random slope for activity, and sound was used as a random slope for HI, as these random terms gave the lowest AICc to the model. As some models still showed residual patterns, habitat and time were used as variance covariates in a constant variance function for activity. For feeding, we used individual identity as a variance covariate, and for HI, we used habitat as a variance covariate.

We then performed model selection using maximum likelihood estimation. Candidate models were generated using the dredge function implemented in the 'MuMIn' package (Bartoń 2019). The models with the lowest AICc from all the generated models for a particular response variable were selected as the best statistical models (Online Resource 1, Table S1), and the summary of their results are presented. Means \pm standard errors are reported.

Results

Behavioral Differences Between Rural and Urban shrews

Urban shrews spent, on average, 26.0% more time in activity and 37.4% more time feeding than rural shrews (activity: 1241.49 ± 57.34 s/h vs. 926.87 ± 52.84 s/h; feeding: $71.46 \pm$ $2.86 \text{ s/h vs. } 45.12 \pm 2.34 \text{ s/h}$; Fig. 2).

Shrews from both habitats increased their activity significantly over the night (Fig. 2, Table 2). Activity was the lowest in the first analysed hour (21–22h) in both shrew populations (470.71 s/h), and the highest in the last analysed hour (06–07h: 1683.70 s/h). Regarding feeding behavior, while urban shrews increased feeding throughout the night, rural shrews decreased feeding near the morning (Table 2; Fig. 2). Specifically, urban shrews increased their feeding from 77.05 ± 5.05 s/h to 80.94 ± 5.81 s/h from 03-04h to 06-07h, while rural shrews decreased from 49.57 ± 4.10 s/h to 38.36 ± 3.39 s/h from 03-04h to 06-07h.

In 76.56% of the cases for rural shrews and 72.27% of the cases for urban shrews, individuals were inside the shelter long enough to allow a valid heterothermy analysis. HI was significantly lower (by 14–26%) in urban than in rural shrews at all measured hours (Fig. 3, Table 3). More HI values were obtained at 21h (rural: 64; urban: 59), when shrews were less active, and less at 06h (rural: 32; urban: 28), when shrews were more active. In both populations HI values were significantly lower at 21h (1.70 \pm 0.08) and significantly higher at 06h (2.31 \pm 0.13) (Fig. 3, Table 3).

Influence of Sound on Behavior

The instant reaction to sound playbacks could not be observed in about two thirds of the shrews as they were inside the shelter when a sound was played (67.96% for rural shrews and 61.96% for urban shrews, Fig. 4). For shrews outside the shelter when a sound was played, the

 influence of sound treatment and habitat on the instant reaction was analysed. Shrews from both habitats showed significantly different instant reactions depending on the sound treatment (rural: $X^2 = 22.164$, p < 0.001; urban: $X^2 = 16.706$, p < 0.001). Compared with silence, both populations reacted significantly to traffic noise (rural: p = 0.001, urban: p = 0.008) and white noise (rural and urban: p < 0.001), while no significant reaction was observed for owl calls (rural: p = 0.607, urban: p = 0.220). Independently of the population, fleeing to the shelter was the most common reaction to traffic noise and white noise (Fig. 4), with shrews taking 8.2 ± 2.6 (n = 13) minutes and 12.8 ± 2.1 (n = 23) minutes, respectively, to leave the shelter again. Urban shrews, however, showed more diverse behaviors when hearing traffic noise and white noise than rural shrews (Fig. 4).

There was no difference in the long-term reaction to sound between rural and urban shrews, as seen by the lack of an interaction between habitat and sound (Table 2, Online Resource 1, Table S1). After owl calls and traffic noise playbacks, neither relative activity nor activity recovery were significantly different from silence (Fig. 5, Table 2). However, white noise lowered both the relative activity (by 21.2%) and the activity recovery (by 29.0%) in comparison to silence (Fig. 5, Table 2). Both traffic noise and white noise had an influence on feeding behavior, but not owl calls (Table 2). Shrews exposed to traffic or white noise spent less time feeding than shrews exposed to silence (decrease of 13.0% and 31.1% respectively; Fig. 5). Furthermore, feeding recovery was significantly decreased by traffic noise by 14.9%, and by white noise by 40.8%, (Fig. 5).

Sound treatment did not influence HI in both populations as this variable was not featured in the top two models for HI (Table 3, Online Resource 1, Table S1).

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Rural vs. Urban Shrews

Our results suggest C. russula inhabiting urban environments has modified its natural behaviour, with individuals captured in urban areas spending more time in activity and feeding than individuals captured in rural areas. One explanation might be an increased level of boldness typical of urban individuals (Sol et al. 2013). Higher activity levels have already been linked in other species with high levels of boldness (Herde and Eccard 2013; Rangel-Patiño et al. 2018) while an increase in time spent feeding has been correlated with a decrease in vigilant behaviors (Shannon et al. 2014; Klett-Mingo et al. 2016; Uchida et al. 2019). Such behaviors were likely selected in shrews to explore more territory and access more resources in the complex urban matrix, increasing their fitness. Another explanation for the increased activity and feeding observed in urban C. russula during our night-time tests might be that individuals adjusted their foraging behavior to periods of lower human activity, a behavior already described for other mammals (Dowding et al. 2010; Gaynor et al. 2018). Crocidurines are predominantly nocturnal, but still show some bouts of activity during the day (Baxter et al. 1979; Genoud and Vogel 1981; Oliveira et al. 2016). Possibly, urban individuals of C. russula changed their diel activity to peak at night to avoid exposure to human activities, such as traffic. However, as we did not test shrews during daylight, we cannot confirm urban individuals indeed showed lower levels of day-time activity and feeding than rural ones.

Discussion

Food intake (feeding behavior) was constant throughout the night in rural shrews, with a slight drop at the last hour (06h). In contrast, feeding behavior kept increasing throughout the night in urban shrews. This provides some support to our previous interpretation: if urban shrews shift their activity peak to the night period when human disturbance is lower, feeding behavior

will occur mainly during this period. Additionally, activity increased along the night for both populations. Activity results obtained at 06h match the mean nocturnal hourly rate of activity registered for wild and captive adult *C. russula* in summer by Genoud and Vogel (1981). Likely, individuals were more hesitant at the beginning of the experiment, then resumed their regular activity and exploration as the territory became more familiar.

The use of heterothermy was different between rural and urban shrews, with urban shrews making generally less use of daily torpor than rural shrews. The higher use of heterothermy in rural shrews may serve as an energetic compensatory mechanism. Such a mechanism has already been suggested in bats, in which populations roosting in buildings appear to use less torpor than rock-roosting populations (Lausen and Barclay 2006). For urban shrews, in contrast, a higher food intake may be more important than torpor as a compensatory behavior for their higher energy expenditure caused by higher levels of activity. Torpor use and depth is heavily influenced by food availability (Bozinovic et al. 2007; Doucette et al. 2012; Leslie et al. 2015), but also predation risk (Bieber and Ruf 2009; Nowack et al. 2017; Turbill and Stojanovski 2018) and competitor pressure (Geiser and Brigham 2012; Kronfeld-Schor and Dayan 2013; Vuarin and Henry 2014). Predation pressure is generally lower in urban environments (Eötvös et al. 2018) and shrews can forage with low mortality risk. But in Sintra, like many other natural areas, predators and competitors are more diverse and abundant (ICNF 2018). Therefore, we can assume rural C. russula struggle more to acquire resources, and consequently spend more time in torpor to save energy (Levy et al. 2011; Geiser and Brigham 2012; Kronfeld-Schor and Dayan 2013). Furthermore, shrews from both populations increased torpor use over the night. This matches findings from other studies that show small mammals enter torpor more frequently in the morning, when they start becoming less active (Nagel 1977; Oliveira et al. 2016).

 Although our results were based on an adapted HI, rather than direct body measurements, they suggest an interesting possible influence of urban environments on torpor patterns in daily heterotherms such as *C. russula*. Our results gain additional importance, as torpor is perceived as a possible relevant ability for endotherms facing global change (Nowack et al. 2017).

Influence of Sound on Behavior

Contrary to what we initially predicted, shrews from rural and urban habitats had similar reactions to the same sounds. Unlike other small mammals (Hendrie et al. 1998), shrews outside the shelter showed no changes in behavior when hearing tawny owl calls. Shrews exposed to traffic noise fled to the shelter initially, but returned quickly to their normal activity. However, time spent feeding was significantly reduced after hearing traffic noise. Other studies have shown significant negative impacts of traffic noise, e.g. in the locomotor activity of striped field mice *Apodemus agrarius* (Pieniążek et al. 2017) and the activity and feeding behavior of *Myotis spp.* (Finch et al. 2020). White noise had an even stronger effect on the shrews' behavior: they fled to the shelter more frequently and took longer to recover their regular behavior, as evidenced by reduced activity and feeding behaviors and recovery rates.

A possible explanation why shrews in our study showed no behavioral reaction to the playback of owl calls might be related with their hearing abilities. Branis & Burda (1994) suggested the hearing capabilities of all shrews should be tuned to higher frequencies and their ability to localise sound below 15 kHz should be limited. We only know of one audiogram conducted on a similar sized shrew species, namely *Sorex araneus*, which have their best range of hearing at 5–20 kHz (Konstantinov and Movchan 1985). These findings fit to the frequency spectrum of typical call types used by *C. russula*, like courtship (~10 kHz; Hutterer 1977) and twittering calls (4.4–7.0 kHz; Zsebők et al. 2015). Owl calls have their highest energy at

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 frequencies below 1 kHz and do not reach higher than 5 kHz (Figure S7). The lack of a reaction to owl calls in our study might thus confirm the hearing range of *C. russula* to be above 5 kHz like in *S. araneus*. Both traffic noise and white noise are broadband sounds, with higher energies within the alleged range of hearing of shrews (especially white noise; Online Resource 1, Figure S6), which can explain the shrews' reaction. It appears the higher the sound frequency, the more pronounced the defensive response of *C. russula* is. Comparable results have been observed in house mice, which show higher stress responses to anthropogenic noise emitted at higher frequencies than at low frequencies (Mancera et al. 2018).

Conclusion

Our results suggest cities have imposed new selective pressures on *Crocidura russula* that forced individuals inhabiting urban environments to change their natural behavior. Urban shrews were active for longer periods of time, spent more time feeding, and were heterothermic less often than rural shrews. Despite these behavioral differences and the fact that rural and urban environments have a vastly different soundscape, shrews from both habitats responded to different sound disturbances in the same way. Furthermore, behavioral differences observed when hearing sound disturbances where never as strong as behavioral differences observed between rural and urban populations. This means factors other than noise disturbance are responsible for this species' synurbic adaptations and should be investigated. Food availability (invertebrates, Ishitani et al. 2003), predator abundance (Eötvös et al. 2018), climatic differences (Oke 1995), or inter- and intraspecific competition (Francis et al. 2009) have all been shown previously to be dramatically different between rural and urban environments. It would also be interesting to compare our overall results with other small mammals living in cities, particularly rodents, to better understand what factors drive species' different responses to noise.

Understanding how these evolutionary processes work would allow city managers and politicians to better plan green infrastructures and allow rural biodiversity a better chance to adapt to an ever-increasing urbanized world.

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Fig. 1 Experimental design. On the left, the schematic representation of the experimental arena (images not to scale). On the right, the schematic representation of the timing of each playback, as well as the beginning and end of the experiment

Figure captions

Fig. 2 Duration of activity and feeding during one hour after the start of each playback (21–22h, 00–01h, 03–04h, 06–07h) in greater white-toothed shrews trapped in rural and urban habitats. Boxplots show the median and the upper and lower quartiles, with the whiskers representing data within the $1.5 \times$ interquartile range. Points represent outliers. n = 16 for each boxplot

Fig. 3 Heterothermy index (HI) calculated every three hours for shrews captured in rural and urban habitats. Boxplots show the median and the upper and lower quartiles, with the whiskers representing data within the 1.5× interquartile range

Fig. 4 Number of behavioral reactions observed in rural and urban shrews during a sound playback. See Table 1 for the definition of each behavior

Fig. 5 Relative activity (proportion of time shrews were active in an hour after each playback started) and activity recovery (estimate of the speed by which shrews recovered their normal behavior), as well as relative feeding and feeding recovery of shrews from two habitats exposed to silence, tawny owl calls, traffic noise and white noise. See Fig. 2 for explanations of boxplots

Table 1Behavioral reactions observed in shrews during a playback

Category	Behavior	Description
Shelter	Shelter	Shrew inside the shelter during playback
No reaction	Ignore	No apparent reaction to noise
	Rest	Shrew resting outside the shelter, with no apparent reaction
Reaction	Flee	Shrew fled to the shelter
	Wake	Shrew left the shelter during playback
	Freeze	Shrew stopped moving after hearing playback
	Freeze and flee	Shrew stopped moving after hearing playback, then fled to shelter

Table 2

Summary results of the top models regarding relative duration of activity, recovery rate of activity, relative duration of feeding and recovery rate of feeding

		Relative duration		Recovery rate	
Response	Parameter	$Effect \pm SE$	P	Effect \pm SE	P
Activitya	(Intercept)	0.090 ± 0.015	< 0.001	0.094 ± 0.030	0.002
	Urban	0.111 ± 0.026	< 0.001	0.084 ± 0.040	0.044
	Owl calls	0.005 ± 0.017	0.783	-0.002 ± 0.019	0.928
	Traffic noise	-0.001 ± 0.017	0.942	-0.005 ± 0.019	0.788
	White noise	-0.044 ± 0.017	0.010	-0.056 ± 0.019	0.004
	00h	0.179 ± 0.033	< 0.001	0.185 ± 0.022	< 0.001
	03h	0.213 ± 0.033	< 0.001	0.204 ± 0.020	< 0.001
	06h	0.362 ± 0.041	< 0.001	0.365 ± 0.024	< 0.001
Feeding ^b	(Intercept)	0.015 ± 0.002	< 0.001	0.015 ± 0.002	< 0.001
	Urban	0.007 ± 0.002	0.006	0.008 ± 0.002	< 0.001
	Owl calls	-0.001 ± 0.001	0.157	-0.002 ± 0.001	0.075
	Traffic noise	-0.003 ± 0.001	0.001	-0.003 ± 0.001	0.010
	White noise	-0.007 ± 0.001	< 0.001	-0.008 ± 0.001	< 0.001
	00h	0.002 ± 0.001	0.111	NA	NA
	03h	0.002 ± 0.001	0.203	NA	NA
	06h	-0.000 ± 0.001	0.677	NA	NA
	Urban:00h	-0.001 ± 0.002	0.667	NA	NA
	Urban:03h	0.002 ± 0.002	0.434	NA	NA
	Urban:06h	0.006 ± 0.002	0.007	NA	NA

Baseline levels: rural habitat, silence sound and 21h playback

^aIndividual identity was used as a random intercept. Different variances were allowed for each habitat and playback

^bIndividual identity was used as a random intercept and as a variance covariate (different variances were allowed for each individual

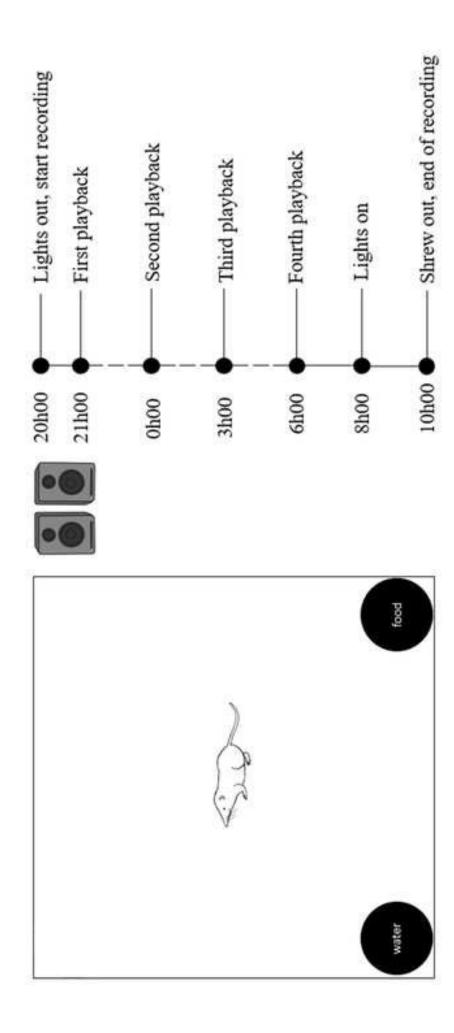
Table 3
Summary results of the top model for the heterothermy index

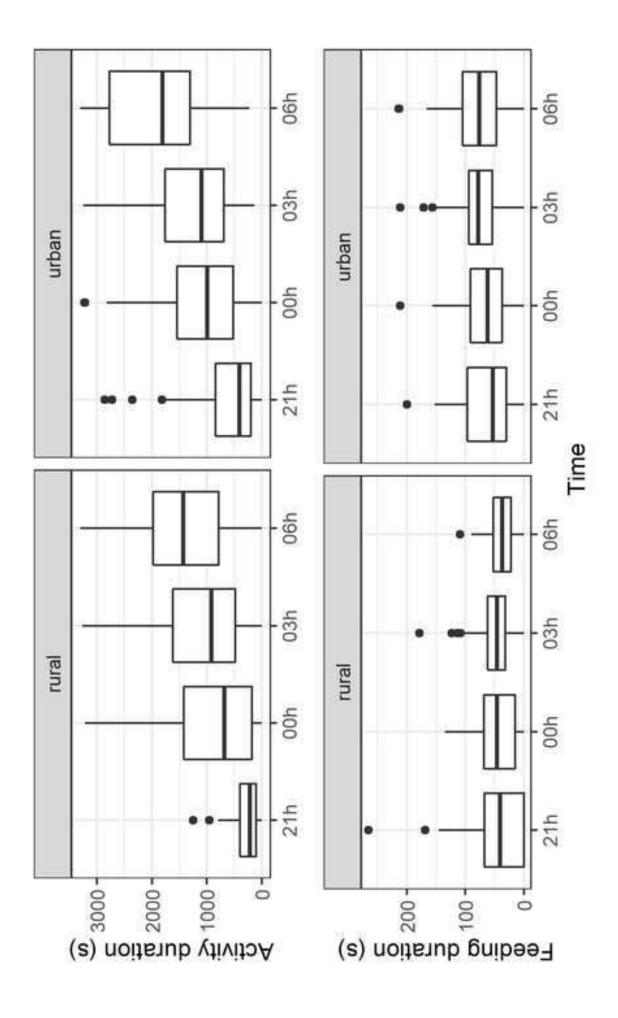
	Parameter	Effect \pm SE	P
Heterothermy Index (HI)	(Intercept)	-0.004 ± 0.083	0.958
	Urban	-0.238 ± 0.082	0.007
	00h	0.101 ± 0.047	0.016
	03h	0.105 ± 0.042	0.023
	06h	0.252 ± 0.048	< 0.001

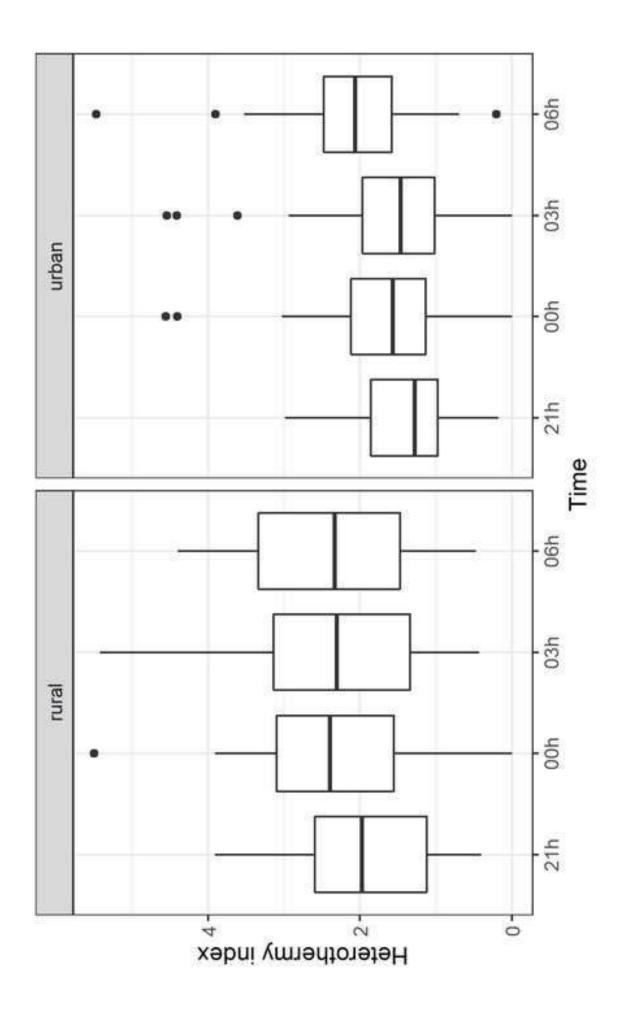
Baseline levels: rural habitat, silence sound and 21h playback

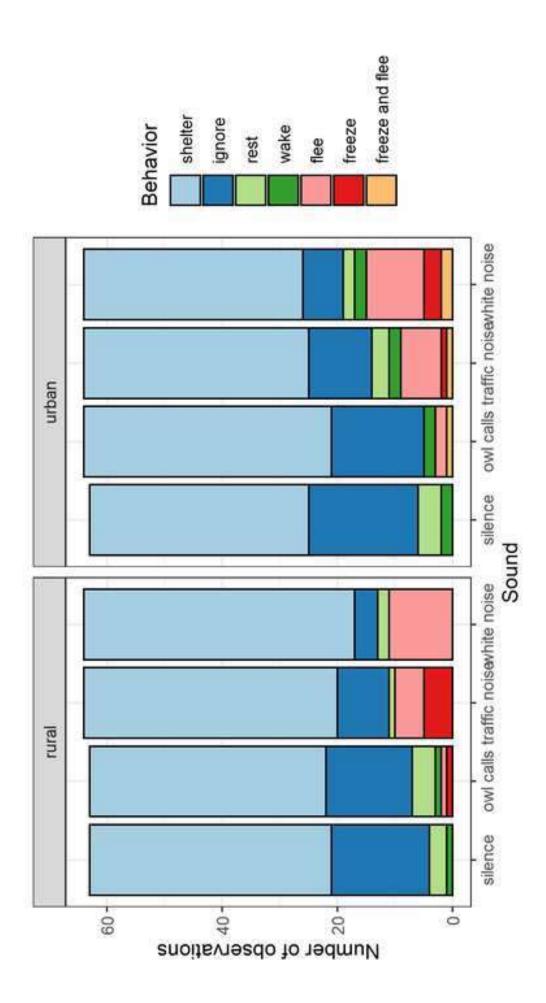
Individual identity was used as a random intercept, and sound was used as a random slope

Different variances were allowed for each habitat









ESM1

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