Accepted Manuscript

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 PII:
 S0950-7051(18)30557-4

 DOI:
 https://doi.org/10.1016/j.knosys.2018.11.013

 Reference:
 KNOSYS 4576

To appear in: Knowledge-Based Systems

Received date : 2 May 2018 Revised date : 9 November 2018 Accepted date : 12 November 2018



Please cite this article as: C. Villavicencio, S. Schiaffino, J. Andres Diaz-Pace et al., Group recommender systems: A multi-agent solution, *Knowledge-Based Systems* (2018), https://doi.org/10.1016/j.knosys.2018.11.013

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Research highlights

- A group recommender approach based on multi-agent systems is proposed.
- The approach replaces the traditional aggregation techniques with neg tiation.
- The group members are satisfied in a more even way than whith traditional approaches.

Group Recommender Systems: A multi-agent Solution

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Abstract

Providing recommendations to groups of user has 'come a promising research area, since many items tend to be consumed by ε oups of people. Various techniques have been developed aiming at ma, 'ng recommendations to a group as a whole. Most works use aggregation technique, to combine preferences, recommendations or profiles. However, sati. 'vin, ...' group members in an even way still remains as a challenge. To deal with his problem, we propose an extension of a multi-agent approach based on vezotia ion techniques for group recommendation. In the approach, we use the m. Hilateral Monotonic Concession Protocol (MCP) to combine individual recommendations into a group recommendation. In this work, we extend the MCP , otocol to allow users to personalize the behavior of the agents. This extension was evaluated in two different domains (movies and points of int rest) with satisfactory results. We compared our approach against different be clines, namely: a preference aggregation algorithm, a recommendation ag regation algorithm, and a simple one-step negotiation. The results show evider e that, when using our negotiation approach, users in the groups are nore uniformly satisfied than with traditional aggregation approaches.

Keywords: recommender systems, group recommendations, multi-agent systems, negriation

1. Intr du cior

N wadays, when a user wants to purchase a product, contract a service or do som activity (e.g., watching a movie), she often faces the problem of information overleed [1, 2]. This is because users must deal with a variety of potentially increasing items in the target domain. In this context, a Recommender System (RS) allows users to identify those items that match their needs, preferences,

Preprint submitted to Elsevier

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tastes, and goals. To carry out this task, several recommendation techniques have been proposed in the literature [3, 4].

Most RS techniques have been developed to assist individual loss. However, in some domains such as movies, music or tourism, the red mendations can serve groups of people as well as individuals. A Grour mecommender System (GRS) looks for item recommendations that are good or a group of users as a whole. That is, the recommended items should satisfy, muck as possible, the individual preferences of all group members [5]. Clenerating recommendations that satisfy a group of users with possible competing interests is not straightforward. *Traditional approaches* make use of aggregation lechniques in order to produce group recommendations [6, 7, 8].

Although these traditional approaches are used in several domains, they still present some limitations. First, aggregation. * echn. ** es can produce values that might not represent correctly the data being as regated, especially when the data to be aggregated is small and has nign variance. For example, let us assume that 3 users rate a movie with scores 1 1 and 5, respectively; then the (aggregated) group rating can be: 2. 3 (, 2) average aggregation technique is used), 1 (if misery minimization or $_{L}$ ' rality voting is used), and 5 (if most pleasure is used). From this simple, we can see that neither of those aggregated ratings truly represent the "atings given by the users. Because of this problem, recommendations gen. "auch" ith aggregation techniques seldom satisfy the group members in a uniform way. Second, the decision-making process of the group and the group dvnamics [9, 10] are not reflected by the aggregation technique [6, 9, 8]. By dyr amics, ve mean any kind of group behavior during the decision making process. 'at car influence the decision result, such as: users' concession profiles, users' tore and or influence, among others. As a result, traditional approach s can produce a recommendation that does not match the group's interests or neal octs one of the group members to satisfy others, which often leads to the whole group rejecting the recommendation.

When a hur an bound has to choose an item, its members generally discuss and analy their options for achieving a consensus on the item. Different methods car be 'sed to achieve consensus, such as: voting, auction-biding or negotiation [1.] Particularly, the negotiation method is expected to generate recommer dations that satisfy the group members more uniformly than traditional a pro che. Along this line, we proposed a multi-agent approach for group recon. γe dation called PUMAS-GR [12], which was later re-named to MAC ReS (Multi-Agent Group Recommender System). In MAGReS, a personal agen represents each user of a group. This personal agent knows the user's preferences and acts on her behalf when making item proposals to other agents and ooking for agreements. These agreements are achieved by the agents through coope ative negotiation process. Particularly, we chose a multilateral negotia.... method known as Monotonic Concession Protocol (MCP) [13], since it $c \sim y$ mirrors the way in which human negotiation seems to work [14]. We rgue that this approach helps to increase the quality of the group recommena tions by increasing the satisfaction of the group as a whole.

The general idea of the approach was initially presented in [12], including

preliminary evaluation results. However, the agents were all equipped with one single acceptance criterion for item proposals, which did not flow gent personalization by the users. By personalization, we mean that a set can change the behavior of her representative agent to better capture in the beliefs and how the agent should act (accordingly) during a group negotiation. Thus, we argue that different acceptance criteria need to be supported, so that each agent can decide whether to accept or reject a given item proposa. Furtilermore, in some domains it is important to consider recommendations that contain items already rated by group members (in the past). These criteria can help to produce recommendations being closer to what users expect, thus increasing the probability of those recommendations being accepted by the group. In this context, the main contribution of this article is the divelopment of two new decisions strategies for the agents in MAGReS, which are the empirically assessed. We additionally analyze the amount of information divert a given user needs to reveal (to other agents/users) when making group recommendations.

To demonstrate the feasibility of MAG_KS with the two proposed strategies, we have evaluated MAGReS in the different (POI) recommendation domain (Yelp). We performed different experiments, and compared but proposal against traditional approaches for recommendation aggregation, preprende aggregation, and a simple one-step negotiation. The comparisons were called out using both item-based and userbased recommender systems. The effectiveness of the group recommendations was assessed in terms of the everage satisfaction of a group and how uniformly the group members were satisfied. The results showed that the average group satisfaction reported was light for the recommendations produced by MAGReS, and also the group members. The satisfied in a more uniform way than with traditional appraoch s.

The rest of the art, e is organized into 4 sections as follows. In Section 2 we discuss related works. In Section 3 we present the details of the MAGReS approach. The , in Cection 4 we report on the experiments carried out to evaluate our ar poach. Finally, in Section 5 we give the conclusions and outline future lines c, wo κ .

2. Rela'ed Vork

The generation of group recommendations began to be investigated in the RS field turing the last decade [7, 15]. Traditional GRS can be classified into three main catego les according to the strategy they follow to generate the recommendation. These categories include: (i) those that perform "recommendation (ggregation" [6], by producing individual recommendations for every member f the group and then merging those recommendations; (ii) those that perform "preferences/ratings in coller to obtain a group evaluation for each candidate item; and (iii) those hat perform "model/profile aggregation" [18], by merging individuals' models into a single group model first and then generating suggestions based on that model. There are various techniques for aggregating data, and their suitability

depends on both the data being aggregated (it is not possible) for example, to aggregate non-numeric data with an average) and the g \therefore being pursued. When it comes to merging individual recommendations, M sthered in [10] analyzed different techniques such as: average, average without mission, and least misery, among others. In [6], the authors analyzed the effectiveness of ranked list recommendations tailored to a group of users using different 1 ethods such as: Spearman footrule, Borda count, average and least missive [7, -0].

Multi-agent systems (MAS) have been applied in several areas and domains (see Chapter 10 of [14]). Regarding RS, some approximes have proposed MAS to generate recommendations both for individuals and groups. The way in which RS and MAS are combined depends on the main goal of the combination. In some cases, they are combined as a may to improve the quality of the recommendations [21, 22, 23]. In other calms, a Mins is used for recommendations because its architecture allows develope is to model the problem more adequately and prescribes a clear assign. But of responsibilities to the different system modules [24, 25, 26, 27, 28, 29, 30]. Euch ideas have been used together in [31, 32, 33]. There are many reference, in the literature about MAS being applied to RS for individual users in domains such as: adaptive customization of websites [28], tourism [24, 26], give is on mobile phones [34], TV shows [31], training courses [27], and e-commerce [32, 23], among others.

However, when it comes to MaC^{-1} ing applied to GRS, only a few works have been reported, mostly in the to mism domain. In [21], the authors present a GRS in the tourism domain that relies on the application of cooperative agentbased negotiation. The agents ac on behalf of group members and participate in a direct (alternating offer.) or mediated (merging rankings) negotiation, which ultimately produces group recommendations based on individual recommendations and user preference nodels. One of the limitations of this approach is that it has only been tertea with simulations involving two agents (therefore, it is a group of two peor e). We argue that this kind of approaches should be assessed in bigger groups in or 'er to be practical for RS.

In [25] an $r_{\rm c}$ pt-based negotiation schema that uses alternating offers is developed, in v nich the agents (each one representing a group member) negotiate the preference. (the whole group. This approach is said to be suitable for every domain, provided that the domain can be represented using ontologies. Like $MAGRe \leftarrow t$ is an proach does not use aggregation techniques, but a negotiation process in o. ¹er to compute the group preferences. In [35] a refined version of the ϵ proach is presented, in which new agent types are introduced for filtering the 1 st of ite ms according to the group preferences (resulting from the negotiation) at or mediating the negotiations among user agents. Our work differs rom [2, 35] in that they negotiate user preferences while MAGReS negotiates ecomm ndations. A similar idea is used by [36], with agents representing group me...' ars and a mediator to coordinate the agents' work. An interesting aspect o [22] is that a user agent not only tries to protect the interests of its repreented user, but also models her behavior with respect to conflicting situations. h this way, the attitude and behavior of the agent changes (and adapts to the situation) when looking for agreements during the negotiation. However, there

are two differences between MAGReS and [36], namely: (i) a project used on a *Merging Ranks* technique (instead of MCP), and (ii) a preference as gregation techniques used by the mediator agent (when computing negrous) rating for each item).

In [33] a MAS-based system called e-Tourism is preclated, which is able to produce both individual and group recommendations. Noneth 'ess, this system differs in that the agents are used for representing user, but ' so for modeling components of the RS. This approach differs from cars in that it relies on aggregation techniques to generate the group recommendations (specifically, profile aggregation techniques are used in order to aggregate the group members' profiles into a single group profile).

In [37] the authors present a review of the state of the art in RS using MAS from a game-theory point of view, with the objective of introducing examples of how social-choice mechanisms can be extended using social information extracted from the analysis of interactions or trun a social network.

In [10] a GRS for points of interest (PO₁, that uses dynamic elicitation of user preferences is proposed. The ap₁ road like users to iteratively express and revise their preferences during the apilision making process through a chatbased app. Although the main ide, of this approach is similar to our approach, the app requires the users to discust about the options and vote them, while in MAGReS the discussion and pregotile ion are carried out by the agents.

3. Proposed Multi-age a proach

In order to address the problems discussed in Section 1, we initially proposed a multi-agent negotiation approach called PUMAS-GR (later renamed to MA-GReS) as an alternative to a gregation techniques. In this article, we extend MAGReS and develop the raw strategies for the approach (see Section 3.4 and Section 3.5), so to enrich the modeling of the users' criteria and improve both the quality and the "acceptability" of the recommendations. Additionally, in Section 3.6 we "iscuss how the proposed approach affects the information privacy of the from members, in terms of how much information from each user needs to be reverted to the rest of the group members (during the negotiation).

3.1. MA "R S

M'. ReS (Inlti-Agent Group Recommender System) is based on a MAS in which each agent acts on behalf of a group member. Each agent maintains a profit that contains the user's preferences and it is capable of (i) predicting the rating the user would assign to an item not yet rated, and (ii) generating a canking of "interesting items" for the user (items the user would like). Initially, the past. MAGReS differs from traditional approaches (see Figure 1) that r ormally work with a central entity, which employs some aggregation technique wither for user profiles, user preferences or single-user recommendations) in tandem with a single-user recommender system. The novelty of MAGReS is the



Figure 1: Traditional approach to g. up recommendation

replacement of aggregation techniques by a negletiation process in which a group of User Agents (i.e., agents that represented as sets) try to reach a consensus on the most satisfying items for the group. Although various negotiation protocols are possible, only a few of them have addressed two important properties for us, namely: (i) mimic the negotiation process followed by humans, and (ii) be suitable for multi-lateral negotiation process followed by humans, we chose the protocol known as MCP (Monoral vic Concession Protocol) [13] to guide the negotiation. A general overwire of our approach is shown in Figure 2. More



Figure 2: Proposed approach

ormally, let $A = \{ag_1, ag_2, ..., ag_n\}$ be a finite set of N cooperative agents, and let $X = \{x_1, x_2, ..., x_m\}$ be a finite set of potential agreements or proposals, each one of them containing an item that can be recommended to one of the agents.



Each agent $ag_i \in A$ has a utility function $U_i : X \to [0,1]$ that \ldots are proposals to its satisfaction value. In our approach, each agent int ... ally a lies on a Single-User RS (SUR) to generate a ranking containing the it in. (candidate proposals) proposed by the agent. The ranking is sorted in escendant order according to the utility value of the item. This way, the set X can be seen as the union of the rankings produced for all the agents, µ us an s ecial agreement called *conflict deal*, which yields utility 0 for all the ag nts and will be chosen as the worst possible outcome (no agreement is po_sible)

For example, let us assume we want to generative ometantians of movies to (groups of) users. Along this line, let us have a group of three friends who want to watch a movie together, and a set of M polyible movies to be chosen. According to MAGReS, each user is equipped with he own personal agent that is able to access her user profile. For simplicity,ofile includes only ratings over (a subset of) the possible movies. A user sting $rt_i(item)$ is a value (in the range [0,1] where 0 means dissatisf, yion and 1 means high satisfaction) assigned by the user i to the given item (i.e., movie). Additionally, the utility function of each agent $ag_i \in A$ is defined a fillows:

$$U_i(x_j) = \begin{cases} r : (\neg \cdot) & \text{if } x_j \in R_i \\ SU : P_i(x_j) & \text{if } x_j \notin R_i \end{cases}$$
(1)

Where R_i is the list of items 'ated by user *i* (represented by ag_i) and $SUR_i(x_j)$ is the rating predicted by the SUR_i , which is the single-user recommender system¹ used by ag_i for generating its list of candidate proposals. In this context, let u. conside the following (initial) situation:

- ag_1 handles ratings $\langle rt_1(M5) = 0.75, rt_1(M3) = 0.56 \rangle$ on behalf of user #1,
- ag_2 handles $rt_2(M_{10}) = 0.82$, $rt_2(M_{52}) = 0.65 > \text{for user } \#2$, and
- $ag_3 \text{ hand} \log \langle rt_3(M32) \rangle = 0.88, rt_3(M46) \rangle = 0.8 \rangle$ for user #3.

Then we have $A = \{ag_1, ag_2, ag_3\}$ as the MAS in which the negotiation for the "best" movie (the one that will satisfy all the three agents) takes place.

3.2. Mon. + nic Joncession Protocol (MCP)

The agents engage in rounds of negotiation, each one making proposals (of item) that need to be assessed by the other agents, until an agreement is reache 1 or + le negotiation finishes with a *conflict*. Our agents abide by a set of redefined rules that specify the range of "legal" moves available at each agent it any s age of the negotiation process. In MCP, these rules have to do with:

¹Most single-user recommender systems provide a way to predict the rating of a user for given item. For example, the Mahout framework provides the estimatePreference function that accepts the IDs of both a user and an item as parameters and returns the predicted rating that particular user would assign to the item.



Figure 3: Steps of the MCP for MACRES (adapted from [13])

(i) the agreement criterion, (ii) which agent makes the next concession (after a round with no agreement), and (iii, no " much an agent should concede. The protocol presents some limitations, namely: (i) an agent cannot influence the negotiation position of other agen. (e.g., by exchanging a justification), and (ii) an agent needs to assign quantitative utilities to proposals (often, via a utility function). Additionally, in "ast to the benefits provided by the multi-agent system, there are some i sues that might affect the performance of the recommender system. For examp. negotiation involves reasoning (i.e. computation cost) and communication (i.e. communication overhead) [38]. However, we focus on two propertie. of the sciected negotiation protocol to diminish the effects of these issues: te minator and deadlock-freedom. The MCP protocol guarantees (a) that f_{11} , negotiation process following the protocol will eventually terminate (termination, and (b) that at least one agent can concede satisfying the concessior cr. erion at any negotiation stage, until an agreement has been reached. Tal 'ng' ito account both properties, as the overall number of agents is finite, the can vy be a finite number of concessions. Thus, the negotiation is bound to terr inate reaching an agreement or finishing in conflict. The steps of the MCr y too 1 are summarized in Figure 3. At the beginning (step 1), each agent akes a initial proposal according to its own *Initial Proposal* strategy (for xample the agent proposes its "favorite" or top-ranked item if its Initial *Prop.* al str .tegy is the one called *Egocentric*, i.e. it always selects the proposal y un the nighest utility value for the agent). Then, the initial proposals of all the agents are exchanged in order to determine if an agreement over one of the \mathbf{p} oposr is can be reached. The notion of *agreement* (also called deal) is defined in terms of the utility of a given proposal for the agents. Thus, there is an $\epsilon_{\rm s}$ greement if one agent makes a proposal that is at least as good (regarding tility) for any other agent as their own current proposals. Formally, we rely on the following criterion:



Multilateral Agreement Criterion²: An agreement is probability of there is an agent $ag_i \in A$ such that its propose' x_i is accepted by every other agent $ag_k \in A$. Whet'er a proposal is accepted by each agent $ag_k \in A$ is determined by '1' e Proposal Acceptance (PrA) strategy used by that agent (seconction 3.5).

If an agreement is reached, the proposal that satisfies a 'the agents is chosen (if several proposals meet this criterion, we simply pick the or them randomly). On the contrary, if no agreement can be reached, one (or root)) of the agents must concede. A concession means that an agent seeks an inferial proposal (for example, in terms of its own utility), with the hope of reaching an agreement. If none of the agents can concede, the process finishes with n eagreement (the *conflict deal* is returned). Several concession strategies are possible (see Section 3.3). Also, note that even though an agent can exclude from its proposals those items that her user has already rated, certain if the group. Along this line, users' opinions with regard to recommendations of the process they have already rated vary from one user to another. Given that agents should take this situation into account when assessing proposals sent by the agents, we propose the *Already-Rated Punishment (ARP)* strategies for M Tr (see Section 3.4).

3.3. Concession strategies

As it was explained before, when no agreement is reached during a round of negotiation, at least one of the gents must concede. At this point, there are two problems that need . be so ved, namely: (i) determining which agent(s) has to make the conce sion and (ii) selecting the next item to propose (i.e. the new proposal).

3.3.1. Concessior Decision Rule

From all the agent that can make an effective concession (i.e. those having alternative processals in their pool of proposals), it is necessary to find the one(s) that must conced in the next round of negotiation. One way for selecting the conceding agent s) is to apply the Zeuthen strategy [39] around the concept of willingness to risk conflict (WRC). This strategy was initially designed to be used in itlat ral egotiations and later extended to work in multi-lateral ones, as explained in '12]³. The WRC for ag_i (WRC_i) is then given by Equation 2:

$$WRC_{i} = \begin{cases} 1 & if U_{i}(x_{i}) = 0\\ \frac{U_{i}(x_{i}) - min\{U_{i}(x_{k})|k \in A\}}{U_{i}(x_{i})} & otherwise \end{cases}$$
(2)

"In one Strict PrA strategy is used this criterion works as the one proposed in [13]

[&]quot;re "product-increasing" and "sum of products" strategies proposed by Zeuthen were so generalized (from bilateral to multilateral negotiations) in [13] and are valid within our amework, but we did not use them in the experiments reported in this article.

Where $U_i(x_i)$ is the utility value for ag_i over the item it proposed (ω_i is the most recent proposal made by ag_i), and $U_i(x_k)$ is the utility. Lue $\omega_i ag_i$ over the item the agent ag_k proposed (x_k). Once the WRC_i of ever ω_i and is computed, the agent(s) with the lowest WRC_i value must man ω_i concession. In case two or more agents hold the same WRC value, different structures can be followed. Without losing generality, we make all the eagent concede in our implementation framework.

3.3.2. Concession strategy

Various strategies are discussed in the literat we for deliding on the item the conceding agent(s) should propose in the next roun. [13]. For our work, we initially selected the so-called Nash concession s. rategy, v hich states that an agent makes a proposal such that the product of *c*ilitie. The other agents increases (Nash product). When assessing the behavior of the Nash strategy in practical cases, we observed that sometimes it lears to "early conflicts" during the negotiation. An early conflict is a situation in which all agents quickly exhaust their potential proposals and the MC. 'en, _____th no deal. This is because once the Nash product is high enough, the count of candidate proposals reduces drastically, and so does the number of agents that can make concessions. This behavior therefore drives the negotia ion to a premature end, and also makes the agents discard potential agreement just because their Nash product was not high enough. The same behavior was observed when using the Utilitarian concession strategy (it uses addition instead of product of utilities). To mitigate this problem, we defined ε variation of the Utilitarian concession strategy called Desires Distance.

Desires Distance (DI). J D attempts to measure how far a candidate proposal is with respect to the desired of the other agents. Along this line, an agent makes a proposal that is "noser to the other agents' desires" (we denote the desires distance as ω_{-alue}) but also has a utility value lower or equal than the agent current proposal. DD guarantees termination and deadlock-freedom, the demonstratic follows from that for Utilitarian concession [13].

The DD s. γ^{i} gy works as follows. Initially, we consider that agent ag_i must make a concession and therefore find a new item to propose (in the next round of negotiation). To do this, we create a list with all the "eligible" candidate proposals $\langle \cdot \gamma, r \rangle$ oposals with a lower utility value than the current proposal), and then we select the first candidate from the list whose dd_{value} is lower or equal to the one of the current proposal. The dd_{value} is computed as explained in Equation 3. This strategy requires $U_k(x_i) - U_k(x_k) < 0$, because otherwise igent $\epsilon \gamma_k$ is already satisfied and therefore it should not be considered in the distance computation.

$$dd_{value}(x_i) = \sum_{k=0, k \neq i}^{N} |U_k(x_i) - U_k(x_k)|$$

where $U_k(x_i) - U_k(x_k) < 0$ and x_k is the current proposal of ag_k (3)



Figure 4: MCP negotiation example ov movies

Figure 4 shows an example of MCP when having a group of three users, each one represented by one of the three agen (uy_1, uy_2) and ag_3). In the first round (Figure 4a) each agent proposes a movie: a_{5} proposes M1, ag_2 proposes M24 and ag_3 proposes M3. According to t_{1} and t_{2} minusly defined agreement criterion (Figure 3, step 2) there is no agreement, γ none of the proposals satisfies all the agents and, therefore, one (or more st the sents has to make a concession. The concession decision rule determines has ag_2 must concede. For this example, ag_2 uses DD to select her next proposal and as a result she proposes M10 (as $dd_{value}(M10) = 0.26, dd_{value}(M24) = 0.23 \text{ and } dd_{value}(M10) \leq dd_{value}(M24)).$ All the proposals are assisted gain and the agreement criterion determines that ag_1 and ag_3 will rej rt M10 The process repeats until reaching Round k, in which ag_3 proposes he music M_46 that satisfies all the agents and therefore the negotiation ends successfully. Movie M46 will be then recommended to the group of users. If the area two observations that can be inferred from the example. The first one is that the negotiation is not guaranteed to terminate successfully (with an ogreement) among all the agents. The second one is that more than one correspondence to possible, meaning that in round k an agreement could have e liste over more than one proposal. In such a case, one of the agreements some d be selected and several selection strategies can be followed (e.g. random selection, choose the one that maximizes the satisfaction of the agents, f .nor g ot¹ er criteria).

3.4. Mread³¹-Kuted Punishment strategy

The recommended items will determine whether the recommendation is (partial) if fully) accepted by the group. Depending on the approach for generating the recommendations, items that were rated by some of the group number in the past might be recommended (again). For example, if a traditional preference-aggregation approach is used, during the preference aggregational tage, the RS needs to determine which items will be part of the group preferences profile (i.e. those items whose ratings are computed using the agg. egation technique). The approach for selecting items might vary from one RS to another. If all the items rated by at least one of the group members are used during the aggregation process, then there is no way an item being plready rated by a group member will be included in the recommendation "lower r, if only a subset of the items rated by at least one of the group members is "onsidered, those items that were not included in the group preference p." de have a chance of being recommended, especially if they received a high rating by the users.

During the field test of our approach [40], we old served that while some users would give a low feedback to recommendations co. taining items they had already rated, others gave a high feedback to item they had liked in the past, and others simply stated that they would take the item gain if their friends did not take it. This means that not every user might reject recommendations containing items already rated or always accept them. Therefore, we believe that agents should take this aspect into account during the negotiation.

The Already-Rated Punishment (ARP) strategy is proposed as a way to model the user behavior explained above. An P works as follows: when an agent ag_i is asked by another agent ag_k mouth its utility regarding a proposal x_k (made by ag_k), ag_i first uses its utility function to assess x_k , and then applies the ARP strategy to compute a preceding to be applied before the utility is reported. This way, ARP can indirect influence ag_k decision with respect to its next proposal (assuming that a_{ijk} mone sion strategy is not egocentric, i.e. it cares about other agents' opinions, the penalty is also taken into account when the agent decides whether more pt a proposal, and thus proposals that received a higher penalty will be lear likely to be accepted. Depending on the ARP strategy variant used by ag_i (which is determined by its associated user), the utility reported to a_{ik} will fary. At the moment MAGReS supports five variants for the ARP strategy, but other variants can be included in the future. These five variants are the form i ing:

- Easy-Going: N. p.nalt / is applied (the penalty is zero), the agent does not care abc it receiving proposals with an item already rated by its user.
- Flexible: The populty is computed as penalty = 1 flexibilityLevel, where fl_{abc} ilityLevel (f) is a value between 0 and 1 and it models how flexible the user is with regard to receiving recommendations of items she has plread rated. The higher the flexibility is, the lower the penalty should be. For example: if flexibilityLevel = 0.75 and the rating given by the user is 0.8, the penalty is computed as penalty = 1 - 0.75 = 0.25therefore ne reported utility is 0.8 - 0.25 = 0.55.
- Min-Sz isfaction: The penalty is 0 (zero) if the rating given by the user c_{coc} is the *minSatisfaction* (*ms*) value set⁵, otherwise the penalty is the whole utility value which would result on the agent reporting an utility of 0 tor the proposal (meaning that she would not accept a recommendation

 $^{^{4}}$ According to Equation 2 the utility is the same as the rating given by the user.

⁵Both the *flexibilityLevel* and the *minSatisfaction* of the variants *Flexible*, *Min-Satisfaction* and *Flexible Plus* can be either set explicitly by the user or learnt by using Machine Learning techniques.

with that item). For example, let us suppose minSatis, ction = 0.6, then if the rating given by the user is 0.5 the reported tility vill be 0, but if the rating given is 0.65 then the agent will report 0. σ , the utility value of the proposal.

- Flexible Plus: It is a combination of the *Flexil* e and *Min-Satisfaction* strategies. Firstly, it computes the penalty in the same way the *Flexible* strategy does. Then, if the rating given by the set set_P asses the *minSatisfaction* value set, the penalty is divided by two set erwise the penalty is not modified.
- Taboo: As the users prefer not to receive recommendations with items already rated, the penalty for proposal containing those items will be equal to the utility value defined by the regeners utility function (according to Equation 2, it corresponds to the ration iven by the user to the item), and therefore, the utility reported by the agent for those proposals will be 0.

Depending on the domain, some varian ould produce better results than others. For example, the *Easy-Goin* rational to could be useful in the music and restaurant recommendation domains, as users do not tend to reject recommendations containing items they rate of addy consumed. The *Min-Satisfaction* variant could be useful in other domains, like books, food, movies and music, where users would not mind to consume again an item they liked. Finally, the *Taboo* variant can be useful in n. stly all domains, but especially in those where the activity of consuming an item (e.g., watching a movie, or traveling to a certain location) requires a s_{15} iterat amount of effort, time or resources (e.g., money).

3.5. Proposals Ac eptance irategy

Not all the users . Now the same criteria (nor use the same strategy) when deciding whet¹ to accept a proposal from others, and the same is valid for the agents. I eper ding on the criteria used by the users (group members), one proposal can be acceptable or not. This aspect was not taken into account in our prevides work, where the *Multilateral Agreement Criterion* determined that a proport is accepted by an agent if it is better than its current one. While for some users a proposal might not be acceptable because it is not strictly better than their proposals; for others, the proposal might be good enough and herefore acceptable, although not being strictly better. This way, if all the agents to use the same acceptance strategy, many potential agreements would e discarded. Moreover, even if all the agents were to use the same trategy a strict strategy might not be always ideal to model their associated use...

Let us come back to the example presented in Figure 4 and suppose that in between rounds 2 (Figure 4b) and k (Figure 4c) there is a round i depicted by F gure 5. In such a case, according to the *Multilateral Agreement Criterion*, no agreement was reached. Interestingly, if we look closely, one of the proposals



(M71) could be considered as good enough to have an agreement because it is better than what ag_1 and ag_2 proposed and it is almost as g at as the current proposal of ag_3 . If all the agents use a strict criterion, M71 is $n' + e^{-1}$ sidered as an agreement, the negotiation will carry on and will later end. That an agreement on M46 (see Figure 4c), which does not satisfy the user as much as M71 does. This situation might be different if each agent, and particularly ig_3 , had its own acceptance criteria. Not only the negotiation would have find here find here earlier, but also the quality of the recommendation would have in regreed). Along this line, we propose the *Proposal Acceptance* (PrA) strateger as a wey to introduce a user decision criterion into the agent model.

The PrA strategy currently has three variants, but others can be defined so as to improve the model. These three variants and the following:

• Strict: The standard definition of multi local agreement is used⁶. An agent ag_i will accept a proposal x_k if it is at least as good (in terms of utility value) as its own proposal free Equation 4).

$$accept(ag_i, x_k) = tru$$
 iff $U_i(x_k) \ge U_i(x_i)$ (4)

• Relaxed: An agent accepts a proposal x_k if it is as good as its own proposal or very close to what she source. Equation 5 depicts the formalization of this strategy, where relaxPercestage (rp) can assume values in the [0, 0.2] range⁷. Each agent rr_{0}^{*} have a different rp, which is determined by the represented user, depending on her own criteria⁸.

$$accept(ag_i, x_k) = true \quad i, f \quad U_i(x_k) \ge U_i(x_i) * (1 - relaxPercentage)$$
(5)

• Next: A pr posal is accepted if it is better than the agent's next proposal (i.e. be one it would make if it had to concede in the next round). This strategy is solution to the one used by the agents in the single-issue negotiation nodel proposed in [41], in which an agent accepts an offer if its util. If nigher than that of the agent counter-offer. It works under the folloring a imption: "if I reject proposal x_k , which is not better than my cur ent proposal x_i but better than my next one (x_{i+1}) , and as a result the indicated accepted, then I would have lost some utility because I rejected proposal x_k that was better than my next one" (see Equation 6).

$$accept(ag_i, x_k) = true \quad iff \quad U_i(x_k) \ge U_i(x_{i+1})$$
(6)

where x_{i+1} is ag_i next proposal

⁶This is the one used by all agents in [12].

⁷The upper limit of the range was determined empirically.

⁸This value can be set explicitly by the user, or learnt automatically by using Machine Learning techniques over user feedback, among other options.



Figure 5: Example of potential agreement, discarded due to a strict striterion (Round i, with $2{<}i{<}k).$

3.6. Information privacy

Not every user will be comfortable with her p. vate information being shared, made public or exposed in any way [5]. If the recommendation area, the amount and type of information that every user needs to reveal about herself, so as to allow the recommender system to predice recommendation for her, depends on the approach used to make the recommendations. For example, when using a traditional approach based on predice recommendation, the system will require the user to inform about all her preferences. This is another advantage of using a multi-agent approach like $N_{\rm eff}$ and $N_{\rm eff}$ the agents can control the amount of information that needs to be revealed during the recommendation process. For example, the only information about the user preferences being revealed is the one related to: (i) the proposals he agent makes, and (ii) the utility values she reports when asked if sheir willing to accept a proposal made by another agent. This way, MAGReS is expected to be more respectful of the information privacy (i.e. by leaking less there is private information) than a traditional approach.

4. Evaluation

In this section we describe the experiments carried out to evaluate our approach for group becommendation in two domains: movies and points of interest (POI). In Section 4.1 we describe the datasets used. In Section 4.2 we establish the algorithm considered as baselines. In Section 4.3 we define the evaluation criteria. In flection 4.4 we describe the objectives of our experiments and explain some any fits of their design, such as the parameters taken into account and neir values. At last, in Section 4.5 we discuss the results obtained.

4 1 Duints

Two latasets were used to evaluate our approach: the first one in the movies comain and the second one in the POI domain. In both cases, we randomly sampled 180 users (without repetition) and created 45 groups of 3, 4 and 5 people (15 groups per size). The two datasets are described below.

- Movies: we used the popular *MovieLens*⁹ dataset with refines of users for different movies to generate user groups of varying sizes. In particular, the experiments were performed with *MovieLensLates Smeller* at contains 100,000 ratings, 700 users and 9,000 movies. We will perform this dataset as ML_LATEST_SMALL.
- POI: we used a dataset from the Yelp Dataset C 'allenge' ⁰ that contains check-ins (visits of users to places) from varients check-ins (visits of users to places) from varients check-ins belonging to Arizona (US), since the resulting network is dense. Also, we only considered those users having at least 9 check-ins. The resulting dataset contains 19, 193 users. Regarding the distribution of check-ins, the dataset contains 497, 029 check-ins in 85, 901 POIs conerated by the selected users. We will refer to this dataset as YELP.

4.2. Description of baselines

We compared the recommendations¹⁴ing from traditional group recommendation against those produced in MAGReS. As the baseline for this comparison, we implemented two non-index systems that rely on traditional approaches, namely:

- TRADGRec-PA: a GRS that uses preference aggregation, as proposed in [20, 42].
- TRADGRec-RA: a GRS t. at relies on the aggregation of recommendations produced for each group member. It is based on the approach proposed in [42] (cb. pter 2, section 2.4), which generates a recommendation containing k it ms or e.ch group member and then merges all those recommendations interesting recommendation (the group recommendation). For this make or, the group preference (or rating) of each candidate (i.e., an item recommended to a group member) is computed by aggregating the preference (either existing or predicted ones) of each group member over the candidate, and then the k candidates with the highest group preference relues are selected to be part of the group recommendation.

For MA $\cdot \text{Re}^{c}$, we also implemented a protocol known as the *One-Step protocol* [43] as an additional baseline. The *One-Step protocol* is a variant of MCP in which all the negotiations happen in one single round. The agents simply interchange their proposals (one proposal each) and seek for an agreement, but there is no concession.

The single-user recommender (SUR) system used by the agents in MA-ReS, 'RADGRec-PA and TRADGRec-RA, was implemented using the Duine

 $^{^{9}}$ http://grouplens.org/datasets/movielens/

 $^{^{10}}$ https://www.yelp.com/dataset_challenge



framework¹¹ and the Mahout framework¹². Duine was used in the first implementation stages and helped us to gain confidence that the opproach was viable [44, 12]. Nonetheless, Duine had some limitations regarding the loading time of the data models, which made it unsuitable for a responsive recommendation application¹³. Therefore, all the tests in this article were made using the Mahout-based implementation, which uses a CF-based Collaborative Filtering) approach. In the framework, both item-centered CF (ICF) and user-centered CF (UCF) filtering are supported, and thus we implemented two variants of the SUR, one using ICF and another one using UCF.

4.3. Evaluation criteria

4.3.1. Satisfaction

The satisfaction of the recommendation. for the users were measured in terms of several indicators. These indicators is a be computed both at the item- (i.e., an item recommended) and recommendation- (i.e., a list of items recommended) levels. These indicators are the following:

- - item level: the group satisfaction for an item x_j is computed as explained in Equation 5, where *n* is the number of group members (|g|) in the group $\langle ... \rangle$ and $\langle i(x_j)$ is the satisfaction of group member u_i over item $x = S_i(x_j)^{-1}$, computed as the rating for the pair $\langle u_i, x_j \rangle$ predicted by the SUR by using the rating prediction CF formula¹⁴ and the sin⁻¹ rity metric chosen for each experiment.

$$GS(x_j) = S_g(x_j) = \frac{\sum_{i=0}^{n} S_i(x_j)}{n}$$
(9)

- recombined ation level: the GS of a recommendation r consisting of k item: $(r = \langle x, x_2, ..., x_k \rangle)$ is computed as the average of the GS

$$r_{u_i,x_j} = \bar{r_{x_j}} + \frac{\sum (r_{u_i,x_k} - \bar{r_{x_k}}) \times Similarity(x_j, x_k)}{\sum |Similarity(x_j, x_k)|}$$
(7)

$$u_{i,x_{j}} = \bar{r}_{u_{i}} + \frac{\sum (r_{u_{k},x_{j}} - \bar{r}_{u_{k}}) \times Similarity(u_{i},u_{k})}{\sum |Similarity(u_{i},u_{k})|}$$
(8)

 $^{^{11}\,}htt$ $r^{.\,\prime}/du$. r .mework.org/

 $^{^{12}}h' \circ p://m' hout.apache.org/$

¹³For example, Duine needed around 30 seconds to load the data models when using the Movie. vns100. dataset, while Mahout only needed 2 seconds to perform the same task. The way a rating r_{u_i,x_j} is predicted depends on whether the SUR uses ICF (see Equation 7) or UCF we Equation 8).

of every item in r (see Equation 10).

$$GS(r) = S_g(r) = \frac{\sum_{j=0}^{k} GS(x_j)}{k}$$
(10)

- members satisfaction dispersion (MSD): it assesses now uniformly the group members are satisfied by either a single item x_j or a recommendation r. The lower the MSD is the more unifor, by solving the group members will be.
 - item level: as it can be seen in Equation 11, the MSD for an item x_j is computed as the standard deviation of the group members satisfaction.

$$MSD(x_j) = \sqrt{\frac{\sum_{i=1}^{n} o\left(\sum_{i=1}^{i} (x_i) - S_g(x_j)\right)^2}{n}}$$
(11)

- recommendation level: the M. \bigcirc for a recommendation r that consists of k items ($r = \langle x_1, x_2, ..., x_k \rangle$) is computed as the average of the MSD for every item in " (\searrow "quation 12).

$$MSP(r) = \frac{\sum_{j=0}^{k} MSD(x_j)}{k}$$
(12)

• fairness: it is a metric proposed in [45] for evaluating a recommendation of an item (x_j) to a group. It is defined as the percentage of group members satisfied by the recommendation (see Equation 13). To determine which users are satisfied, the authors set a threshold th to 3.5 stars (out of 5 stars, the equivalent to 0.1 but of 1) and any group member with a satisfaction value above the threshold is considered satisfied. We kept th = 0.7 and extended this better for applying it to a recommendation r of k items. As it can be seen . Equation 14, the fairness of a recommendation r of kitems is computed as the average of the fairness of the items.

$$fairness(g, x_j) = \frac{|\bigcup_{u_i \in g} : S_i(x_j) > th|}{n}$$
(13)

$$fairness(g,r) = \frac{\sum_{j=1}^{k} (fairness(g, x_j))}{k}$$
(14)

4.3.2. Infor at on Privacy

Another factor that needs to be taken into consideration is the amount of user information that gets leaked during the recommendation process. This information is mainly related to: (i) the utility function held by the user (i.e. the way she computes the ratings for the items) and (ii) the items she can propose during a negotiation (i.e. ther candidate proposals). This way, given two accommendation approaches R_1 and R_2 , we consider that R_1 produces be an error recommendation (than R_2) in terms of information privacy if it leaks leaks information while producing the recommendations.

To measure the amount of information revealed by *UserAgents* of MAGReS we computed two, namely: *UFIL* and *PIL*.

- Utility Function Information Leak (UFIL): it measures (i... a [0;1] range) the amount of information revealed with regard ... the user utility function of user u_i , either when recommending a sir sile it sin, γ_j or a list of items $r = \langle x_1, x_2, ..., x_k \rangle$.
 - (i) MAGReS: in this case *UFIL* measures the amout of information related to the utility function that is reveared by i gent ag_i (which represents user u_i). At the item-level, we use \Box_{i} action 15 for agent a_i recommending item x_j . For a list of iter stor recommendation), we use Equation 16.

$$UFIL(u_i, x_j) = UFIL(ag_i, x_j) = \frac{|items|'ithUtilityRevealed(ag_i, x_j)|}{|itemsTotal(ag_i)|}$$
(15)

where $| itemsWithUtilityRevealed(a_j, x_j) |$ is the amount of items for whom ag_i has revealed its unity (or satisfaction) value when item x_j was recommended; and $| itemsTotal(ag_i) |$ is the total amount of items over which ag_i can release some utility-related information.

$$UFIL(u_i, \cdot) = \frac{\sum_{j=0}^{k} UFIL(u_i, x_j)}{k}$$
(16)

- (ii) TRADGRec-PA: given that TRADGRec-PA uses a traditional approach based on preference aggregation, it requires the system to know everything related to the user preferences. Thus, $UFIL(u_i, x_j)$ is always set (1.)
- (iii) TRADGRE -RA: $h \to ses$ a traditional approach based on recommendation ag ,regr ion where the candidate items are selected by using preference agr legation (the k candidates with the highest group preference value are selected). Thus, it requires the system to know every ning "elated to the user preferences. Again, $UFIL(u_i, x_j)$ is alweed set to 1.
- **Propos.** 'Information Leak (PIL, MAGReS only): it represents the proportion (measured in a [0; 1] range) of candidate proposals that the ag nt (ιg_i) evealed during the negotiation process with regard to all the proposed is ι could have made. We use Equation 17 for a single item x_j (i.e., item level), and Equation 18 for a list of items (or recommendation) $r = \langle a_1, x_2, ..., x_k \rangle$ (i.e., recommendation level).

$$\Gamma IL(u_i, x_j) = PIL(ag_i, x_j) = \frac{| candidateProposalsRevealed(ag_i, x_j) |}{| candidateProposalsTotal(ag_i) |}$$
(17)

$$PIL(u_i, r) = \frac{\sum_{j=0}^{\kappa} PIL(u_i, x_j)}{k}$$
(18)

It is important to notice that the PIL indicator cannot be completed for TRADGRec-PA and TRADGRec-RA, because the concept of proposal does not exist in those systems¹⁵.

4.4. Experimental setting

The number of recommendations for a ranking wall set to z = 3, 5 and 10 items, since they are common amounts of recommendations (t-p-three, top-five and top-ten). In the case of MCP (either one-ster or multi-step variants), we run the protocol k times, in order to produce the k leconomendations. For a given run, we removed from the negotiation space those items that were agreed by all the agents in the previous run.

For all the approaches we conducted ex_F miment with several configurations using both user and item-based recommondation techniques (and different similarity metrics for each one). Mahout allow, to use user-based (UB) and item-based (IB) SURs. As it can be seen in Appendix A.1, depending on the type of SUR, different similarity functions are valiable. In summary, we exercised the three approaches below:

- TRADGRec-PA: it has a single parameter, which is the preference aggregation strategy used for conputing the group preferences (aggregated preferences) when building the group preference profile. We used five aggregation strategies: average (AVG), least misery (LM), most pleasure (MP), approval voting (AV) and upward leveling (UL) [7, 20, 42, 46]. The parameters (if r my) or each aggregation strategy are discussed in Appendix A.3.1.
- TRADGRec-RA. it 'as a single parameter that can be configured, which is the aggregation crategy used for computing the group preferences (aggregated preference) during the process of selecting the candidate recommended atoms. We used the same four aggregation strategies as in TRADGRec-PA.
- MAGP S: \cdot e tested with both the *One-Step* and *MCP* protocols. For each of ι , \cdot m, we tested three *Concession* strategies (*Desires Distance*, *Nas* ι and *Utulitarian*), the five *ARP strategies* (see Section 3.4) and all the *Pr pose*. *Acceptance* strategies (see Section 3.5). Despite the variety of paratic ers that can be tuned, based on the tests we performed, none of the ι produced a significant impact on the resulting recommendation nor on its quality.

L is important to note that for all the tests of Sections 4.5.1, 4.5.2, 4.5.3, and 4.5.4 we set the amount of items to be recommended (k) up to 10 (i.e., k = 10). C. 22 the results of the tests showed the effectiveness of our approach when

 $^{^{15}}$ For the sake of comparisons, we could assume PIL = 1 for the same reasons we set UFIL to 1, but we decided not to compare MAGReS against TRADGRec-PA and TRADGRec-RA with respect to the PIL.

making recommendations of 10 items, we conducted tests with a 'ower amount of items. A summary of the results for the experiments wit' dots = 3, and k = 5 can be found in Section 4.5.5.

4.5. Experiments

Given the variety of parameters that can be tweal d with a the approach, we decided to report the analysis over those that would 'save a high impact on both the recommendation process and the recommendations. These parameters are the following:

- 1. The type of SUR, and especially the type of . muarity metric.
- We tested both types of SUR, the user-based and the item-based ones. For the user-based SUR, we conducted experiments with the following similarity metrics: City Block, Euclidean Distance Log Likelihood, Pearson Correlation and Uncentered Cosine. Γ . The mem-based SUR, we conducted tests with the City Block, Euclidean Pistance, Pearson Correlation and Uncentered Cosine.
- 2. The *PrA* strategy. In this case we onducted experiments testing all the variants of the *PrA* strategy. *C^urict*, *Relaxed* and *Next*.
- 3. The Already Rated Punishmen' strategy. In this case we run tests using all the variants of the and trategy. Particularly, for the Flexible, Min-Satisfaction and Flexible Plus variants, we run tests with different parameterizations.

More details about the r tramete ization of each approach and strategy can be found in Appendix A.2 2.

4.5.1. Single-User I. cor mer ler: User and Item-based

The SUR was one or '1 e factors that affected the most both the recommendation process and the recommendations. During the experimentation, we observed some peculiar results for certain combinations of SUR and similarity metrics:

- When using a user-based (UB) SUR, the City Block, Euclidean Distance, and Un entered Cosine metrics caused all the recommendations to be almost the time for both datasets (MovieLens and Yelp) and the 45 groups (ner danget) involved in the test, both for the traditional (TRADGRec-PA and TRADGRec-RA) and MAS-based approaches. According to the results of the tests performed, we believe that the low density of the rating mannees for the datasets and the size of the neighborhoods selected for the experiments might have been the reasons for those results, as they directly affect the effectiveness of most user-based similarity metrics. We analyzed this issue empirically, but a deeper analysis and tests with larger datasets is subject of future work.
- When using a item-based (IB) SUR, the improvement observed for MA-GReS in terms of GS, MSD and fairness, was barely noticeable if the *City*

								TASET: ML	TEST_SMALL
	(higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGR- "A [U', ɔ]	TRADU. RA [AVG; T1]	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	0.7254 ± 0.0529	0.6297 ± 0.2547	0.7282 ± 0.0465	0.7303 ± 0.0499	0.7263 ± 0.0479	/255 ± ^476	0., , ± 0.0516	0.7395 ± 0.0516
RIC	(IB) EUCLIDEAN WEIGHTED	0.782 ± 0.0726	0.8103 ± 0.182	0.8472 ± 0.044	0.8207 ± 0.0689	0.5827 ± 0.1505	0.5718 . 0.1359	0.7 ± 0.0967	0.7 ± 0.0967
Y MET	(IB) PEARSON WEIGHTED	0.7752 ± 0.0595	0.9519 ± 0.0387	0.9545 ± 0.0318	0.9403 ± 0.0529	0.6069 0.0864	0.6135 0.0938	0.7275 ± 0.0562	0.7275 ± 0.0562
AILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.7782 ± 0.0716	0.8256 ± 0.1336	0.8464 ± 0.0452	0.8141 ± 0.0748	0.5667 ± 0.1546	0.5576	0.7017 ± 0.0936	0.7017 ± 0.0936
SIN	(UB) LOG LIKELYHOOD	0.9309 ± 0.0433	0.9672 ± 0.0113	0.9681 ± 0.0073	0.9415 ± 0.0352	J.8655 ± 0.0559	0.8655 ± 7.0558	0.8988 ± 0.0714	0.8988 ± 0.0714
	(UB) PEARSON WEIGHTED	0.7336 ± 0.0792	0.9206 ± 0.0378	0.9371 ± 0.019	0.8753 ± 0.0383	0.0922	.5898 ± 0.1013	0.6784 ± 0.0755	0.6784 ± 0.0755
								۵	DATASET: YELP
	GROUP SATISFACTION (higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [Mc. vt; M11]	TRADGR PA [AVG;]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	0.7886 ± 0.0724	0.3902 ± 0.4078	0.7885 ± 0.0719	υ. ⁻¹⁵ ± 0.07υ.	0.0662	0.7908 ± 0.0667	0.7845 ± 0.077	0.7845 ± 0.077
ß	(IB) EUCLIDEAN WEIGHTED	0.671 ± 0.1261	0.9057 ± 0.0488	0.9116 ± 0.0422	0.0608	0.1854 ± 0.0983	0.1901 ± 0.1182	0.6013 ± 0.0906	0.6013 ± 0.0906
Y METI	(IB) PEARSON WEIGHTED	0.7208 ± 0.1012	0.9773 ± 0.0249	0.9765 ± 0.0219	. ⁻⁴ ± 0.05.	0.3184 ± 0.1053	0.3277 ± 0.1236	0.6076 ± 0.0777	0.6076 ± 0.0777
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.6728 ± 0.1174	0.9064 ± 0.0475	0.5 `8± 0.04.	± 0.0602	0.1902 ± 0.108	0.1915 ± 0.1137	0.601 ± 0.0905	0.601 ± 0.0905
SIN	(UB) LOG LIKELYHOOD	0.7241 ± 0.1094	0.9989 ± 0.0064	0.9943 ± 0075	0.9896 ± 0.0293	0.3881 ± 0.0992	0.3881 ± 0.0992	0.6562 ± 0.1013	0.6677 ± 0.082
	(UB) PEARSON WEIGHTED	0.8192 ± 0.0913	0.9926 ± 0.0497	9905 6. 195	0.9757 ± 0.069	0.7225 ± 0.0935	0.7255 ± 0.1129	0.7747 ± 0.0784	0.7747 ± 0.0784

Figure 6: Average group satisfact in (GS) per similarity metric and approach

Block similarity metric was used. The opposite effect was observed when another similarity metric (Fixe Uncentered Cosine or Pearson Correlation) was used.

The parameterization and for this experiment is specified in Appendix A.4.1. As it can be seen in Figures 6, 7 and 8, the recommendations may vary depending on the similarity metric and type of SUR being used. In general we can see that M.1. ReS running with the MCP protocol outperformed both the traditional approaches (TRADGRec-PA and TRADGRec-RA) and MAGReS running the G. -Step protocol. One exception to the rule was the similarity metric (I_{i}) City block, in which the combination of the Taboo variant of the ARP states f and the Strict variant of the PrA strategy was the reason behind many recommendations being empty. This situation generated a group satisfaction of zero for all the groups affected (6 in the ML_LATEST_SMALL dataset and '3 in the YELP dataset) and had a direct impact on the values reported in Figures for M 7.

The results were validated through a statistical analysis. For each dataset a. d for each similarity metric, we first performed a Shappiro-Wilk test to determine if the samples were normal. Given that in most cases there was at least ϵ ne sample that did not follow the normal distribution, we performed a pairwise Vilcoxon Signed Ranks test (which is a non-parametric test) so as to compare each pair of recommendation techniques (for example: *MAGReS* [One Step;

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	MEMBERS SATISFACTION						ì		ATEST_SMALL
	DISPERSION (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADC act. [', T5]	TRADGRec A	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	0.0807 ± 0.0471	0.069 ± 0.0503	0.075 ± 0.0406	0.0788 ± 0.0418	0.0754 ± 0.04	176 ± 0.u	0.0801 ± 0.0411	0.0801 ± 0.0411
RIC	(IB) EUCLIDEAN WEIGHTED	0.1121 ± 0.0648	0.0745 ± 0.0517	0.0879 ± 0.0498	0.112 ± 0.0831	0.2671 ± 0.1267	.2496 ± 0.1357	0.1961 ± 0.1045	0.1961 ± 0.1045
'Y MET	(IB) PEARSON WEIGHTED	0.1053 ± 0.0431	0.0395 ± 0.0306	0.0357 ± 0.0242	0.0519 ± 0.0418	0.1502 0.0707	0.1504 ± 0.0683	0.116 ± 0.0493	0.116 ± 0.0493
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.1176 ± 0.0703	0.0803 ± 0.0487	0.0847 ± 0.0522	0.1127 ± 0.0935	0.2729 ±	0.2507	0.198 ± 0.1063	0.198 ± 0.1063
SIN	(UB) LOG LIKELYHOOD	0.035 ± 0.0368	0.0095 ± 0.0195	0.0046 ± 0.003	0.0429 ± 0.043	0.1102 0.0F	.1102 ±	0.1117 ± 0.0714	0.1117 ± 0.0714
	(UB) PEARSON WEIGHTED	0.1139 ± 0.0439	0.0385 ± 0.0452	0.0146 ± 0.0129	0.0893 ± 0.0532	0.1955 ± 0.0762	J.1991 ± 0.0854	0.1581 ± 0.0597	0.1581 ± 0.0597
	MEMBERS SATISFACTION							C	ATASET: YELP
	MEMBERS SATISFACTION DISPERSION (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	M, `^S [MCP Ne. `111]	TRADGRPA [AVC (1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
	MEMBERS SATISFACTION DISPERSION (lower is better) (IB) CITY BLOCK	MAGReS [One-Step; M19] 0.1015 ± 0.0546	MAGReS [MCP Strict; M5] 0.0538 ± 0.0693	MAGReS [MCP Relaxed; M17] 0.094 ± 0.0507	M, `αS [MCP Νε. ` ⁴ 11] 0.095 0.0512	TRADGR -PA [AVr ,1] 0.0919 ± 0.0413	TRADGRec-PA [UL; T5] 0.0905 ± 0.0388	TRADGRec-RA [AVG; T1] 0.1144 ± 0.0611	ATASET: YELP TRADGRec-RA [UL; T5] 0.1144 ± 0.0611
RIC	MEMBERS SATISFACTION DISPERSION (lower is better) (IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; M19] 0.1015 ± 0.0546 0.1633 ± 0.0712	MAGReS [MCP Strict; M5] 0.0538 ± 0.0693 0.0579 ± 0.0271	MAGReS [MCP Relaxed; M17] 0.094 ± 0.0507 0.0554 ± 0.0237	M, ΓαS [MCP Νε, 1411] 0.095 0.0512 0.0809 ± 0.0632	TRADGR -PA [AVr ,1] 0.0919 ± 0.0413 0.2907 ± 0.154	TRADGRec-PA [UL; T5] 0.0905 ± 0.0388 0.2875 ± 0.1747	TRADGRec-RA [AVG; T1] 0.1144 ± 0.0611 0.197 ± 0.0835	ATASET: YELP TRADGRec-RA [UL; T5] 0.1144 ± 0.0611 0.197 ± 0.0835
Y METRIC	MEMBERS SATISFACTION DISPERSION (lower is better) (IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED (IB) PEARSON WEIGHTED	MAGReS [One-Step; M19] 0.1015 ± 0.0546 0.1633 ± 0.0712 0.1419 ± 0.0725	MAGReS [MCP Strict; M5] 0.0538 ± 0.0693 0.0579 ± 0.0271 0.0242 ± 0.0229	MAGReS [MCP Relaxed; M17] 0.094 ± 0.0507 0.0554 ± 0.0237 0.0222 ± C	M, `as [MCP Ne. '41] 0.09J 0.0512 0.0809 ± 1.0632 0.04L 0.0621	TRADGR -PA [AVr 1] 0.0919 ± 0.0413 0.2907 ± 0.154 0.2048 ± 0.0799	TRADGRec-PA [UL; T5] 0.0905 ± 0.0388 0.2875 ± 0.1747 0.215 ± 0.0809	C TRADGRec-RA [AVG; T1] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881	ATASET: YELP TRADGRec-RA [UL; T5] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881
IILARITY METRIC	MEMBERS SATISFACTION DISPERSION (lower is better) (iB) CITY BLOCK (iB) EUCLIDEAN WEIGHTED (iB) PEARSON WEIGHTED (iB) UNCENTERED COSINE WEIGHTED	MAGReS [One-Step; M19] 0.1015 ± 0.0546 0.1633 ± 0.0712 0.1419 ± 0.07225 0.1639 ± 0.072	MAGRes [MCP Strict; M5] 0.0538 ± 0.0693 0.0579 ± 0.0271 0.0242 ± 0.0229 0.0579 ± 0.0257	MAGReS [MCP Relaxed; M17] 0.094 ± 0.0507 0.0554 ± 0.0237 0.0222 ± c 0.062 ± 0.062 ±	M. ^s [MCP Ne. ^111] 0.095 0.0512 0.0809 ± 0.0632 0.046 0.0621 0.0806 ± 0.0579	TRADGR -PA [AVr 1] 0.0919 ± 0.0413 0.2907 ± 0.154 0.00799 0.288 ± 0.1557	TRADGRec-PA [UL; T5] 0.0905 ± 0.0388 0.2875 ± 0.1747 0.215 ± 0.0809 0.2895 ± 0.1731	C TRADGRec-RA [AVG; T1] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881 0.1969 ± 0.0835	ATASET: YELP TRADGRec-RA [UL; T5] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881 0.1969 ± 0.0835
SIMILARITY METRIC	MEMBERS SATISFACTION DISPERSION (lower is better) (IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED (IB) PEARSON WEIGHTED (IB) UNCENTERED COSINE WEIGHTED (UB) LOG LIKELYHOOD	MAGReS [One-Step; M19] 0.1015 ± 0.0546 0.1633 ± 0.0712 0.1419 ± 0.0725 0.1639 ± 0.072 0.1436 ± 0.0718	MAGReS [MCP Strict; M5] 0.0538 ± 0.0693 0.0579 ± 0.0271 0.0242 ± 0.0229 0.0579 ± 0.0257 0.00257	MAGReS [MCP Relaxed; M17] 0.0594 ± 0.0507 0.0554 ± 0.0222 ± C 0.06c + 0.025 ± 0.0551 ± 0.x * 1	M. ~s [MCP Ne. ~11] 0.09- 0.0512 0.0806 ± 0.0579 0.0133 ± 0.0325	TRADGR -PA [AVr .1] 0.0919 ± 0.0413 0.2907 ± 0.154 0.2048 ± 0.0799 0.288 ± 0.1557 0.2898 ± 0.1105	TRADGRec-PA [UL; T5] 0.0905 ± 0.0388 0.2875 ± 0.1747 0.215 ± 0.0809 0.2895 ± 0.1731 0.2895 ± 0.1731	C TRADGRec-RA [AVG;T1] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881 0.1969 ± 0.0835 0.2113 ± 0.077	ATASET: YELP TRADGRec-RA [UL; T5] 0.1144 ± 0.0611 0.197 ± 0.0835 0.1965 ± 0.0881 0.1969 ± 0.0835 0.2003 ± 0.0791

							(DATASET: ML_L	ATEST_SMALL
	FAIRNESS (higher is better)	MAGReS [On Step; /19]	MAGReS L. " Str'; No.	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	.6596 ± 0.193/	0.5864 ± C 046	0.6912 ± 0.1971	0.6775 ± 0.1982	0.6609 ± 0.2166	0.6621 ± 0.22	0.6857 ± 0.1923	0.6857 ± 0.1923
lic	(IB) EUCLIDEAN WEIGHTED	0.8c 0.1332	.8862 ± 0.2147	0.9117 ± 0.1008	0.8864 ± 0.1073	0.6357 ± 0.1724	0.6383 ± 0.1589	0.6922 ± 0.144	0.6922 ± 0.144

0.9853 ± 0.0237

0.0519 ± 0.0418

0.5506 ± 0.1118

0.5556 ± 0.1202

0.6706 ± 0.0921

0.6706 ± 0.0921

0.9738 ± 0.0419

0.7204 ± 1.115

(IB) PEARSON WEIGHTE

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Figure 7: Average member satisfaction dispersion (MSD) per similarity metric	and approach
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Figure 8: Average fairness per similarity metric and approach

(IB) UNCENTERED COSINE WEIGHTED	0.797. 0.1347	0.9132 ± 0.1692	0.9246 ± 0.1002	0.8748 ± 0.1241	0.6237 ± 0.1808	0.6216 ± 0.169	0.6963 ± 0.1359	0.6963 ± 0.1359
(UB) LOG LIKE' AOOD	0.9743 ± 0.0392	0.9982 ± 0.0094	1 ± 0	0.9669 ± 0.044	0.8788 ± 0.0564	0.8788 ± 0.0564	0.8987 ± 0.0723	0.8987 ± 0.0723
(UB) PEARS() WEIGHT	0.7486 ± 0.0963	0.982 ± 0.0392	0.9996 ± 0.003	0.9204 ± 0.0507	0.5624 ± 0.0943	0.5991 ± 0.1039	0.6814 ± 0.0869	0.6814 ± 0.0869
							D	ATASET: YEL
Freness (higher is er)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-F [UL; T5]
(ІВ) СІТҮ ЭСК	0.822 ± 0.2032	0.429 ± 0.4651	0.8449 ± 0.199	0.8498 ± 0.1885	0.8438 ± 0.1927	0.8404 ± 0.1957	0.8259 ± 0.2055	0.8259 ± 0.2055
EIGHTED	0.6952 ± 0.1592	0.975 ± 0.0564	0.9838 ± 0.0426	0.9341 ± 0.0645	0.1879 ± 0.0988	0.2009 ± 0.1216	0.6092 ± 0.1229	0.6092 ± 0.1229
(IB) "EARSON WEIGHTED	0.6771 ± 0.1092	0.9959 ± 0.01	0.9959 ± 0.0148	0.9666 ± 0.0613	0.2854 ± 0.105	0.2928 ± 0.1264	0.5796 ± 0.0968	0.5796 ± 0.0968
(IB) UI ENTERED COSINE NEIGHTED	0.697 ± 0.1461	0.9816 ± 0.0446	0.9833 ± 0.041	0.9311 ± 0.0671	0.637 ± 0.1906	0.2036 ± 0.1175	0.6088 ± 0.123	0.6088 ± 0.123
UB) LOG LIKELYHOOD	0.736 ± 0.1189	1 ± 0	1 ± 0	0.9904 ± 0.0269	0.3881 ± 0.0992	0.3881 ± 0.0992	0.6669 ± 0.1097	0.6744 ± 0.0861
(UB) PEARSON WEIGHTED	0.8211 ± 0.0944	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9758 ± 0.0717	0.7272 ± 0.0921	0.7322 ± 0.1151	0.7771 ± 0.0824	0.7771 ± 0.0824

M19] versus MAGReS [MCP Strict; M5] or MAGReS [MCP . alaxea, M17]) versus TRADGRec-PA [AVG: T1]). To do this, we first us two ided test to determine if both samples were significantly different from the mother and then, if the samples were different, we used two one-sidea is to determine which of the samples was greater or less than the other. For the experiments in Figure 6 we wanted to test whether one approach, 4 (e.g., MAGReS [MCP Strict; M5]), was significantly better than the other L (e.g. TRADGRec-PA [AVG; T1] in terms of GS, so the null hypothesis was "the sample of the approach A is not greater than the sample of the app. pac'. B^* For the experiments reported in Figure 7 we wanted to test that or α approach A was significantly better than the other B in terms of MSD, and there, re the null hypothesis was "the sample of the approach A is not worse than the sample of the approach B". Finally, for the experiments reported in Fig. e 8. Anted to test whether one approach A was significantly better than other a proach B in terms of fairness, so the null hypothesis was "the sample \sim the approach A is not greater than the sample of the approach B". The statistic.,' analysis confirmed our observations as, in each test, the null hypoth sis _____ rejected at a significance level of 95% ($\alpha = 0.05$). Thus, we confirmed that the recommendations generated by MAGReS, and particularly those granted by MAGReS [MCP Relaxed; M17] outperformed those of TRADGRec-F.1 and TRADGRec-RA.

4.5.2. Already Rated Punishment survey

The ARP strategy was created to model how the user feels about receiving a recommendation with a titem the has already rated. Each variant of the ARPstrategy affects the way the proposals are treated by the agents, both when they decide about acceptine, (or rending) a proposal and about their next proposal, and this might ultimately reduce the amount of cases in which an item already rated is recommended to the group. We tested all the strategies using both user and item-based S⁻¹Rs, and each of them with different similarity metrics. The parameterization used for this experiment is detailed in Appendix A.4.2. At the moment, all the regents use the same ARP Strategy, but we plan to allow users to choose the rown strategy in their agents in the near future.

Figure 9 s. \sqrt{s} , per *ARP* strategy, the average percentage of items recommended (onsidering the 45 groups per dataset) that were already rated by at least on of the group members. As it can be seen, the tests revealed that when using ML_. T_ST_SMALL dataset, *Taboo* is the best-performing strategy at the task of reducing the amount of already-rated items being recommended. This implies that the desires of the users who chose the *Taboo* as the ARP Strategy for their agents are being properly represented and taken into account furing the recommendation process. The tests with the YELP dataset contrimed v hat we observed in the tests with the other dataset, but also showed that the using the other ARP strategies. This may be explained by the amount of items in the dataset (as the POI dataset has almost 10 times in ore items than the movies dataset) and the amount of items rated by each user (a minimum of 9 items per user in YELP dataset, and a minimum of 20

				(DATASET: ML_LA	TEST_SM
	OVERLAP (%) (lower is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. ms=0.6]	MIN- SATISFACTION [ms=0.6]	7
	(IB) CITY BLOCK	31.78% ± 32.77%	11.49% ± 25.65%	24.39% ± 31.05%	31.89% ± 32.83%	4.28% ± 17.34%
S	(IB) EUCLIDEAN WEIGHTED	6.72% ± 16.02%	0.84% ± 6.24%	1.14% ± 6.97%	6.94% ± 16.54%	0,
Y MET	(IB) PEARSON WEIGHTED	2.06% ± 7.3%	0.06% ± 0.75%	0.22% ± 2.98%	2% € %	0% ± (
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	4.63% ± 12.7%	0.86% ± 6.04%	2.22% ± 12.58%	3. %± 11. %	0% ± 0%
SIN	(UB) LOG LIKELYHOOD	2.72% ± 8.11%	0% ± 0%	0% ± 0%	7.72% ± 3.11%	± 0%
	(UB) PEARSON WEIGHTED	8.06% ± 12.1%	0.11% ± 1.49%	0.44% : 2.32%	8.5 ± .46%	0% ± 0%
						TASET: YELP
	OVERLAP (%) (lower is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE . [f=0.75. ms=0.6]	TISFACTION	TABOO
	(IB) CITY BLOCK	14.96% ± 31.16%	1.78% ± 10.07%	10.19% ± ^3%	1.)6% ± 16%	0% ± 0%
u ₩	(IB) EUCLIDEAN WEIGHTED	2.08% ± 6.65%	0.09% ± 1.24%	0.71% -	1.7% ± 6.07%	0% ± 0%
Y MET	(IB) PEARSON WEIGHTED	2.28% ± 7.76%	0.06% ±	0.41>.	2.73% ± 8.19%	0% ± 0%
ITARI	(IB) UNCENTERED COSINE WEIGHTED	2.43% ± 6.35%	0.16». 1.55%	0.97% ± 4.45%	2.31% ± 6.29%	0% ± 0%
SIN	(UB) LOG LIKELYHOOD	0.78% ± 4.66%	004 + U/v	u% ± 0%	0.78% ± 4.66%	0% ± 0%
	(UB) PEARSON WEIGHTED	0% ± 0%	09 .	0% ± 0%	0% ± 0%	0% ± 0%

Figure 9: Average overlap $percenta_b \circ p_{\circ}$ similarity metric and ARP strategy.

in ML_LATEST_SMALL), which reduces the probability of occurrence of the overlaps.

In Figure 9 we also observed that using *Min-Satisfaction* with the minsatisfaction parameter set ~ 0.6 (equivalent to 3 of 5 stars) is almost the same as using Easy-Going ; 1 ter ns or both group satisfaction and percentage of overlap. This means that even when the agents are not penalizing proposals with less than 3 stars, since the reusing the Easy-Going strategy that constraint is being maintained in plicitly. Finally, we observed that *Flexible Plus* seems to be a good point in between on aggressive strategy like *Taboo* and a relaxed strategy like Easy-Goi ig, elping to discard items (e.g., movies) the user will not like but still recommending those she will be willing to consume again (e.g., movies the user will be \mathbf{x} illing to watch again). The use of the ARP strategies has a side-effect on the group satisfaction value: the more restrictive the strategy is, the lower $h \circ \operatorname{gr} q$ ap satisfaction is. The reason behind this observation is that when wers (a. 1 therefore, their agents) do not "complain" (by penalizing the utili y repored) about receiving proposals with items they have already rated (i.e. then the Easy-Going strategy is used), it is more likely that the recommen $d_{\rm autons}$ contain items that received high ratings by the group members, which hen in eases the group satisfaction value (see Figure 10). This way, Easy- $\zeta_{\gamma ing}$ roduces the best recommendations in terms of group satisfaction, but the worst one in terms of the overlap, and Taboo produces recommendations v ith less overlap but also with an slightly lower value of group satisfaction.

With regard to the MSD and fairness (see Figures 11 and 12) of the recommendations, the results vary depending on the dataset. For the dataset

				C	ATASET: ML_LA	TEST_SM
	GROUP SATISFACTION (higher is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. ms=0.6]	MIN- SATISFACTION [ms=0.6]	7
	(IB) CITY BLOCK	0.7704 ± 0.0563	0.7006 ± 0.1965	0.7736 ± 0.0604	0.7704 ± 0.0563	0.6297 ± 0.2547
RIC	(IB) EUCLIDEAN WEIGHTED	0.8463 ± 0.0452	0.8266 ± 0.1334	0.8264 ± 0.1334	0.8458 ± 0.0456	±
Y MET	(IB) PEARSON WEIGHTED	0.9504 ± 0.0434	0.9495 ± 0.0433	0.9501 ± 0.043	0.94 ± 0.23	0.9519 ± 0.0 7
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.8441 ± 0.0457	0.8261 ± 0.1335	0.8448 ± 0.0442	0.1 36 ±	0.825€ 0.13?
SIN	(UB) LOG LIKELYHOOD	0.9649 ± 0.0175	0.9672 ± 0.0113	0.9686 ± 0.0128	0.9649 ± J.0175	2 ± 0.0113
	(UB) PEARSON WEIGHTED	0.9274 ± 0.0235	0.9214 ± 0.0358	0.9223 0.0351	0.9° ± ,236	0.9206 ± 0.0378
						TASET: YELP
	GROUP SATISFACTION (higher is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE . [f=0.75. ms=0.6]	TISFACTION	ТАВОО
	(IB) CITY BLOCK	0.6233 ± 0.3632	0.4284 ± 0.4093	0.5494 ± 267	0 233 ± 3632	0.3902 ± 0.4078
RIC	(IB) EUCLIDEAN WEIGHTED	0.9084 ± 0.0475	0.906 ± 0.0484	0.9075 ^ 048	0.9088 ± 0.048	0.9057 ± 0.0488
Y METI	(IB) PEARSON WEIGHTED	0.9799 ± 0.0234	0.9778 ±	0.978-	0.9797 ± 0.0233	0.9773 ± 0.0249
ILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.9098 ± 0.0473	0.90ь. 0.0473	0.9086 ± 0.0464	0.9097 ± 0.0465	0.9064 ± 0.0475
SIN	(UB) LOG LIKELYHOOD	0.9988 ± 0.0067	0.000 ±	0.9988 ± 0.0067	0.9989 ± 0.0061	0.9989 ± 0.0064
	(UB) PEARSON WEIGHTED	0.9926 ± 0.0497	`9°,± ,97	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9926 ± 0.0497

Figure 10: Average group satisfaction po similarity metric and ARP strategy.

ML_LATEST_SMALL, we can say that *Taboo* is the best ARP strategy with regard to MSD but *Min-S* $_{ousp}$ *stion* (with the *ms* parameter set to 0.6) is the best with regard to fair iss. For YELP, *Taboo* is the best with regard to the fairness but there is not a clear inner regarding to the MSD. Overall, and independently of the datase', we would choose *Taboo* as a default strategy (until the user chooses the line 'ra' egy ' nat better suits her personality) as, in most cases, it ensures the min inizate of the overlap.

All the results "ere validated through statistical tests. We first run the Shappiro-Wilk test on the samples to determine whether they followed or not the normal d'stri ution. Given that some of the samples did not follow that distribution on non-parametric test was used. We then proceeded like we did previously (see c rtion 4.5.1): by performing (for each dataset and for each similarity me ric) a pair-wise comparisons among the 5 samples (one for each ARP val. r) using the Wilcoxon Signed Ranks test. For Figures 9 and 11 the null h_{1} sthes. was "the sample of the variant A is not worse than the sample of tl e varia, B, as we wanted to test that one ARP variant A (e.g., Taboo) was significantly better than the other B (e.g., Easy-Going) in terms of the ε mount or overlap (Figure 9)/MSD (Figure 11). In the case of the Figures 10 and 12 the null hypothesis was "the sample of the variant A is not greater than t. \circ say ble of the variant B". The test results confirmed our observations as, in each test, the null hypothesis was rejected at a significance level of 95%. Thus, y e confirmed that the variants of the ARP proposed in this article helped to educe the overlap in the recommendations, but at the cost of causing a minor loss in their quality.

	MEMBERS SATISFACTION			(DATASET: ML_LA	TEST
	DISPERSION (lower is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. ms=0.6]	MIN- SATISFACTION [ms=0.6]	тавоо
	(IB) CITY BLOCK	0.0902 ± 0.0472	0.0819 ± 0.0559	0.0966 ± 0.0492	0.0917 ± 0.0472	0
RIC	(IB) EUCLIDEAN WEIGHTED	0.0749 ± 0.0502	0.0751 ± 0.0498	0.0756 ± 0.0497	0.077 0.1 36	0.0745 ± 0.0 `7
Y METI	(IB) PEARSON WEIGHTED	0.046 ± 0.0514	0.0458 ± 0.0506	0.0449 ± 0.0502	0.1 74 ± 0.1 ר	0.039: 0.030
ILARITY	(IB) UNCENTERED COSINE WEIGHTED	0.0802 ± 0.0444	0.0777 ± 0.0485	0.0811 ± 0.0468	0.0807	0.0 J ± J.J487
SIIV	(UB) LOG LIKELYHOOD	0.0124 ± 0.0207	0.0095 ± 0.0195	0.0093 - 0.0196	0.01 5_07	0.0095 ± 0.0195
	(UB) PEARSON WEIGHTED	0.0197 ± 0.0089	0.039 ± 0.0457	0.0382 ± 0 `?6	J.0337 ± 0.0247	0.0385 ± 0.0452
	MEMBERS SATISFACTION				D/	ATASET: YELP
	DISPERSION (lower is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. 0.6]	SATI ACTION s=0.6]	TABOO
	(IB) CITY BLOCK	0.09 ± 0.0741	0.0613 _ 0.0727	0.082c 1.0765	0.09 ± 0.0741	0.0538 ± 0.0693
ß	(IB) EUCLIDEAN WEIGHTED	0.0572 ± 0.0259	0.0576 ±	0.05.	0.0573 ± 0.0264	0.0579 ± 0.0271
Y MET	(IB) PEARSON WEIGHTED	0.0221 ± 0.0224	0.0∠. 0.0226	0.0235 ± 0.0223	0.0221 ± 0.0226	0.0242 ± 0.0229
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.0561 ± 0.0269	0.0577 ±	u. 558 ± 0.0264	0.0563 ± 0.0266	0.0579 ± 0.0257
SIM	(UB) LOG LIKELYHOOD	0.0006 ± 0.0028	1.00′± 17	0.0003 ± 0.0017	0.0006 ± 0.0028	0.0004 ± 0.0026
	(UB) PEARSON WEIGHTED	0.	0.0. `± 0.08t	0.0128 ± 0.0861	0.0128 ± 0.0861	0.0128 ± 0.0861

Figure 11: Average MSD per similar event depending on the ARP strategy used by all the group members

				(DATASET: ML_L4	TEST_SMALL
	FAIRNESS (higher better)	éASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. ms=0.6]	MIN- SATISFACTION [ms=0.6]	TABOO
	יי CITY ד אכג	0.761 ± 0.1818	0.6645 ± 0.2612	0.7596 ± 0.1877	0.7646 ± 0.1816	0.5864 ± 0.3046
sic) EUCLIDEAN 、 St .D	0.9 ± 0.1689	0.9032 ± 0.1771	0.9023 ± 0.1766	0.9196 ± 0.1021	0.8862 ± 0.2147
Y MET	(IL. TARSON WEIGHTED	0.9698 ± 0.0515	0.9679 ± 0.0507	0.9705 ± 0.0512	0.9748 ± 0.0472	0.9738 ± 0.0419
	(IB) UNCEN . D COSINE WEIGHTED	0.9295 ± 0.0977	0.9126 ± 0.175	0.9377 ± 0.0965	0.9269 ± 0.1011	0.9132 ± 0.1692
A	(UB) LOG LIKELYHOOD	0.9987 ± 0.0089	0.9982 ± 0.0094	0.9982 ± 0.0094	0.9987 ± 0.0089	0.9982 ± 0.0094
	(UB) PEARSON WEIGHTED	0.9996 ± 0.003	0.9816 ± 0.0367	0.9816 ± 0.0367	0.9904 ± 0.017	0.982 ± 0.0392
					D	ATASET: YELP
	FAIRNESS (higher is better)	EASY-GOING	FLEXIBLE [f=0.75]	FLEXIBLE PLUS [f=0.75. ms=0.6]	MIN- SATISFACTION [ms=0.6]	TABOO
	(IB) CITY BLOCK	0.6497 ± 0.4086	0.4657 ± 0.461	0.57 ± 0.4362	0.6497 ± 0.4086	0.429 ± 0.4651
Sec. 1	(IB) EUCLIDEAN WEIGHTED	0.9771 ± 0.0539	0.9758 ± 0.054	0.9768 ± 0.054	0.9761 ± 0.0606	0.975 ± 0.0564
V MET	(IB) PEARSON WEIGHTED	0.9953 ± 0.0126	0.9954 ± 0.0105	0.9945 ± 0.0115	0.9951 ± 0.011	0.9959 ± 0.01
IIIARIT	(IB) UNCENTERED COSINE WEIGHTED	0.9844 ± 0.0428	0.9822 ± 0.0447	0.9829 ± 0.0447	0.9841 ± 0.0436	0.9816 ± 0.0446
SIN	(UB) LOG LIKELYHOOD	1± 0	1 ± 0	1 ± 0	1± 0	1± 0
	(UB) PEARSON WEIGHTED	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9926 ± 0.0497

igure 12: Average fairness per similarity metric depending on the ARP strategy used by all t \circ group members

				C	ATASET: ML_L	ATEST_SM
(per	recommendation. lower is better)	STRICT	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	NEVT
	(IB) CITY BLOCK	38.9944 ± 53.627	28.7667 ± 51.0631	10.7444 ± 26.6792	2.5944 ± 7.0336	2.9667 ± 53.435
u U	(IB) EUCLIDEAN WEIGHTED	60.5222 ± 35.8288	59.1222 ± 34.727	56.5167 ± 34.4968	43.0278 ± 34.0513	1 067 ± 35. 11
Y METE	(IB) PEARSON WEIGHTED	55.7222 ± 54.5227	57.0389 ± 55.8777	53.8667 ± 56.2164	43.21* 51. 16	46.8444 ± 52.0 ~ 64
ILARIT	(IB) UNCENTERED COSINE WEIGHTED	49.7833 ± 27.7109	47.2556 ± 26.6756	44.7389 ± 25.2855	36. 78 ± 25 16	36.588 :
SIIV	(UB) LOG LIKELYHOOD	13.6611 ± 7.9003	12.1333 ± 6.5429	9.6444 ± 6.4102	2.5335 .9977	6.5° , ±
	(UB) PEARSON WEIGHTED	50.7333 ± 22.564	42.7556 ± 17.21	35.7833 18.040	18.3° 17 ∠09	25.6778 ± 14.4252
						ATASET: YELP
AN	(lower is better)	STRICT	RELAXED [rp=0.025]	RELA. [rp=0.05]	RE_ [rp=0.1]	NEXT
	(IB) CITY BLOCK	37.25 ± 90.5903	68.2944 ± 143.4417	52.6556 ± 137.5416	95 ± 4 1124	112.6167 ± 207.5576
1	(IB) EUCLIDEAN WEIGHTED	107.9944 ± 61.7056	112.2722 - 63.8519	111 `+ 64.2545	4333 ± 74.028	99.6389 ± 70.2895
	(IB) PEARSON WEIGHTED	46.9 ± 59.3681	42.0444 ± 59.4557	51.55	36.2611 ± 62.5769	41.3611 ± 62.4437
ITARI	(IB) UNCENTERED COSINE WEIGHTED	98.8 ± 58.394	, ¹ ± 58.67.	101.5667 ± 65.6866	93.2667 ± 64.3929	92.0389 ± 68.1616
	(UB) LOG LIKELYHOOD	9.8 ± 17.4892	9.55 ±	-056 ± 14.4676	7.0111 ± 12.6381	8.8444 ± 15.705
	(UB) PEARSON WEIGHTED	2.9889 ± 5.0539	2.9 1.9 4	2.7556 ± 4.5973	2.6111 ± 4.1714	2.7111 ± 4.797

Figure 13: Average amount of concession to generate a recommendation of k=10 items depending on the PrA strategy

4.5.3. Proposals Acceptance strategy

In addition to the (exiting) $L^{*}rict$ variant, we proposed two more strategies, namely: *Relaxed* and Ne_{*}^{*} Although the usage of the *PrA* strategy is merely dedicated to model acceptance criteria for user's proposals, we will compare the different variants of the strategy according to how they affect recommendation process and results L_{*} definition, the *Relaxed* and *Next* variants of the *PrA* strategy cause, it some wey, the agents to be more "flexible" when deciding whether to accept a proposal. This situation has the following consequences:

- 1. It helps the agents to reach agreements faster and therefore produce recommed dations faster. Given that the agents are "more relaxed" when assessing proposals and deciding whether to accept them, less concessions are needed to reach an agreement and the number of rounds of negotiation, wascountly decreases. As it can be seen in Figure 13 there are some to the rule, for example for ML_LATEST_SMALL when the (IB) diffusion to the rule, for example for ML_LATEST_SMALL when the (IB) diffusion with a millipside similarity metric is used, and for YELP when the (IB) Fuelid an Weighted similarity metric was used. In both cases the increase in the number of concessions when using the strategies Relaxed and Next can be explained by the difference in the GS of the recommendations produced when those PrA strategies were used.
- 2. It might increase the group satisfaction for certain configurations of groups and strategies (see Figure 14). This situation is highly dependent on the strategy followed by the agents to select their initial proposal and the *Concession* strategies. For the experiments we used the *Egocentric* [13] (the



initial proposal is the one that retains the highest utility $\neg ue$ and *Desires Distance* strategies respectively. In this context, *each* age. 's initial proposal is its best one in terms of utility (and therefore u_{e1} $\neg uisfaction$) and every time the agent has to concede it makes a $\neg w$ proposal with lower utility than its current one. Then, the mode concessions we have, the lower the user satisfaction will be. Moreover, each concession lowers the "agent's requirements" for accepting proposals and increases the probability of reaching an agreement. This way, the more concessions the agent makes, the lower its utility becomes, and therefore the lower the satisfaction of the corresponding user will be.

			4		DATA T: ML_L	ATEST_SMALL
	(higher is better)	STRICT	RELAXED [rp=0.02	к. ЧЕД [rp=0	LAXED [rp=0.1]	NEXT
	(IB) CITY BLOCK	0.6297 ± 0.2547	0.697 ± 0.1592	°784 ± 0.∪	0.7282 ± 0.0465	0.7303 ± 0.0499
RIC	(IB) EUCLIDEAN WEIGHTED	0.8103 ± 0.182	0.4.	0.0400 ± 0.0443	0.8472 ± 0.044	0.8207 ± 0.0689
Y MET	(IB) PEARSON WEIGHTED	0.9519 ± 0.0387	0.9553 ± 0.0369	1.9566 ± 	0.9545 ± 0.0318	0.9403 ± 0.0529
AILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.8256 ± 0.1336	0.844: 0.04 y	J.8453 ± 0.0452	0.8464 ± 0.0452	0.8141 ± 0.0748
SIN	(UB) LOG LIKELYHOOD	0.9°72 ± C	L 38± 0.L 3	0.9684 ± 0.0074	0.9681 ± 0.0073	0.9415 ± 0.0352
	(UB) PEARSON WEIGHTED	0.926 0.0378	1 9354 ⊭ 	0.9354 ± 0.0194	0.9371 ± 0.019	0.8753 ± 0.0383
						DATASET: YELP
	GROUP SATISFACTION (higher is better)	5, "	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	DATASET: YELP NEXT
	GROUP SATISFACTION (higher is better) (IB) CITY BLOCK	5. T 0.3902 ± 0.4078	RELAXED [rp=0.025] 0.7072 ± 0.2615	RELAXED [rp=0.05] 0.7572 ± 0.1791	RELAXED [rp=0.1] 0.7885 ± 0.0719	DATASET: YELP NEXT 0.7895 ± 0.0709
RIC	GROUP SATISFACTION (higher is better) (IB) CITY BLOCK (IB) EUCLIDEAN V .GHTED	5. * 0.3902 ± 0.4078 0.9057 ± 1.0488	RELAXED [rp=0.025] 0.7072 ± 0.2615 0.9076 ± 0.0471	RELAXED [rp=0.05] 0.7572 ± 0.1791 0.9108 ± 0.0464	RELAXED [rp=0.1] 0.7885 ± 0.0719 0.9116 ± 0.0422	DATASET: YELP NEXT 0.7895 ± 0.0709 0.8769 ± 0.0608
Y METRIC	GROUP SATISFACTION (higher is better) (IB) CITY BLOCK (IB) EUCLIDEAN V .GHTED (IB) PEARSON W. YED	5 0.3902 ± 0.4078 0.9057 ± 1.0488 3773 ± J.0249	RELAXED [rp=0.025] 0.7072 ± 0.2615 0.9076 ± 0.0471 0.9786 ± 0.0245	RELAXED [rp=0.05] 0.7572 ± 0.1791 0.9108 ± 0.0464 0.9787 ± 0.0246	RELAXED [rp=0.1] 0.7885 ± 0.0719 0.9116 ± 0.0422 0.9765 ± 0.0219	DATASET: YELP NEXT 0.7895 ± 0.0709 0.8769 ± 0.0608 0.964 ± 0.0531
11LARITY METRIC	GROUP SATISFACTION (higher is better) (iB) CITY BLOCK (IB) EUCLIDEAN Y .GHTED (IB) PEARSON W. "TED (IB) UNC" IFERED COSINE EIGHTET	5 0.3902 ± 0.4078 0.9057 ± 0.0488 3773 ± 0.0249 0.9064 ± 0.0475	RELAXED [rp=0.025] 0.7072 ± 0.2615 0.9076 ± 0.0471 0.9786 ± 0.0245 0.9076 ± 0.0245	RELAXED [rp=0.05] 0.7572 ± 0.1791 0.9108 ± 0.0464 0.9787 ± 0.0246 0.9089 ± 0.0449	RELAXED [rp=0.1] 0.7885 ± 0.0719 0.9116 ± 0.0422 0.9765 ± 0.0219 0.9108 ± 0.0436	DATASET: YELP NEXT 0.7895 ± 0.0709 0.8769 ± 0.0608 0.964 ± 0.0531 0.8755 ± 0.0602
SIMILARITY METRIC	GROUP SATISFACTION (higher is better) (iB) CITY BLOCK (iB) EUCLIDEAN V', GHTED (iB) PEARSON W., "TED (iB) UNC', IERED COSINE CIGHTER (U', "OG LIK", (HOOD	5. • 0.3902 ± 0.4078 0.9057 ± 1.0488 3773 ± 0.0249 0.9064 ± 0.0064 0.9989 ± 0.0064	RELAXED [rp=0.025] 0.7072 ± 0.2615 0.9076 ± 0.0471 0.9786 ± 0.0245 0.9071 ± 0.0466 0.9987 ± 0.0062	RELAXED [rp=0.05] 0.7572 ± 0.1791 0.9108 ± 0.0464 0.9787 ± 0.0246 0.9089 ± 0.0449 0.9976 ± 0.0064	RELAXED [rp=0.1] 0.7885 ± 0.0719 0.9116 ± 0.0422 0.9765 ± 0.0219 0.9108 ± 0.0436 0.9943 ± 0.0075	DATASET: YELP NEXT 0.7895 ± 0.0709 0.8769 ± 0.0608 0.964 ± 0.0531 0.8755 ± 0.0602 0.9896 ± 0.0293

Figure 14: Average "roup satisfaction (GS) depending on the PrA strategy

3. It might in rease the amount of effective recommendations produced by the vectors, order to each group, specially when the similarity metric is an term based one (see Figure 16). This is more noticeable when all the age, is use a "more relaxed" PrA strategy (like Next or Relaxed) and the millarn, metric is an item-based one. In fact, as expected, the less strict the agent is when determining whether to accept or reject proposals, the bigher the amount of effective recommendations is. The explanation for this is simple: if the agents are more prone to accepting proposals, more ne obtain will end with an *agreement* and therefore more items will be recommended to the group.

A reparameterization used for this experiment is specified in Appendix A.4.3. We have tested the strategies with different similarity metrics and ARP strateg.es, while keeping the *Initial Proposal* and *Concession* strategies fixed (to *Egocentric* and *Desires Distance* respectively). At the moment, all the agents use

	MEMBERS SATISFACTION			C	DATASET: ML_L	ATE STUD
	DISPERSION (lower is better)	STRICT	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	NEXT
	(IB) CITY BLOCK	0.069 ± 0.0503	0.0719 ± 0.0435	0.075 ± 0.0412	0.075 ± 0.0406	0.04. ±
S S	(IB) EUCLIDEAN WEIGHTED	0.0745 ± 0.0517	0.0782 ± 0.05	0.0835 ± 0.0502	0.08 ± 0.98	0.172 ± 0.6 '
/ METR	(IB) PEARSON WEIGHTED	0.0395 ± 0.0306	0.0372 ± 0.0311	0.0375 ± 0.0323	0.1 7 ±	0.0515
ILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.0803 ± 0.0487	0.081 ± 0.0489	0.0821 ± 0.0505	0 0847 ± J.0522	27 ± 0.0935
SIM	(UB) LOG LIKELYHOOD	0.0095 ± 0.0195	0.0054 ± 0.0037	0.0057	0.0° ±	0.0429 ± 0.043
	(UB) PEARSON WEIGHTED	0.0385 ± 0.0452	0.0174 ± 0.01	0.0174 ± 6. 1	0.0146 ± 0.0120	0.0893 ± 0.0532
	MEMBERS SATISFACTION				D	ATASET: YELP
	DISPERSION (lower is better)	STRICT	RELAXED [rp=0.025]	RELAXED -0.05]	R AXED	NEXT
	(IB) CITY BLOCK	0.0538 ± 0.0693	0.0863 0.0546	0.09∠ 0.0489	0.094 ± 0.0507	0.0954 ± 0.0512
ы	(IB) EUCLIDEAN WEIGHTED	0.0579 ± 0.0271	0.056 ±	0.05.	0.0554 ± 0.0237	0.0809 ± 0.0632
Y METE	(IB) PEARSON WEIGHTED	0.0242 ± 0.0229	0.0∠ 0.0247	0.0237 ± 0.024	0.0222 ± 0.0185	0.0404 ± 0.0621
ILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.0579 ± 0.0257	0.0572 ±	0.0279	0.0609 ± 0.0251	0.0806 ± 0.0579
SIM	(UB) LOG LIKELYHOOD	0.0004 ± 0.0026	7.00' ±	0.002 ± 0.0031	0.0051 ± 0.0054	0.0133 ± 0.0325
	(UB) PEARSON WEIGHTED	0. 0.0. 1	0.6. + 0.08.	0.0137 ± 0.0859	0.0144 ± 0.0858	0.0321 ± 0.0852

Figure 15: Average member satisfa and Aisportsion (MSD) depending on the Proposals Acceptance PrA strategy used by all the gamma members

_						
				C	ATASET: ML_LA	TEST_SMALL
	RECOMPLENDATIONS (hit per is betty)	STRICT	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	NEXT
	(IB) LOCK	7.0667 ± 3.84	9.4222 ± 2.1584	9.9111 ± 0.5963	10 ± 0	10 ± 0
	명) EUCLIDEAN WEIGHTED	9.3333 ± 2.1847	9.6 ± 1.8878	9.7111 ± 1.1604	9.7778 ± 1.0636	10 ± 0
	(IB) PEA. Y WEIGHTED	10 ± 0	10 ± 0	10 ± 0	10 ± 0	10 ± 0
	(IB) UNCENTERED COSINE WEIGHTED	9.4222 ± 2.0393	9.5111 ± 1.9024	9.7111 ± 1.2725	9.8889 ± 0.7454	10 ± 0
	(UB) LOG LIKELYHOOD	10 ± 0	10 ± 0	10 ± 0	10 ± 0	10 ± 0
	'B) PEARSON WEIGHTED	10 ± 0	10 ± 0	10 ± 0	10 ± 0	10 ± 0
	AMOUNT OF				D/	ATASET: YELP
	ECOMMENDATIONS (higher is better)	STRICT	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	NEXT
	(IB) CITY BLOCK	2.7778 ± 3.6549	7.6889 ± 3.4826	9.0444 ± 2.5312	9.7778 ± 1.0848	10 ± 0
	(IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED	2.7778 ± 3.6549 8.1778 ± 2.0702	7.6889 ± 3.4826 8.7556 ± 1.5249	9.0444 ± 2.5312 9.2889 ± 1.1406	9.7778 ± 1.0848 9.8667 ± 0.4573	10 ± 0 10 ± 0
	(IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED (IB) PEARSON WEIGHTED	2.7778 ± 3.6549 8.1778 ± 2.0702 9.6667 ± 1.3314	7.6889 ± 3.4826 8.7556 ± 1.5249 9.6 ± 1.3551	9.0444 ± 2.5312 9.2889 ± 1.1406 9.6667 ± 1.3314	9.7778 ± 1.0848 9.8667 ± 0.4573 9.7111 ± 1.325	10 ± 0 10 ± 0 10 ± 0
\mathbf{O}	(IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED (IB) PEARSON WEIGHTED (IB) UNCENTERED COSINE WEIGHTED	2.7778 ± 3.6549 8.1778 ± 2.0702 9.6667 ± 1.3314 8.1111 ± 2.1237	7.6889 ± 3.4826 8.7556 ± 1.5249 9.6 ± 1.3551 8.6222 ± 1.6691	$\begin{array}{c} 9.0444 \pm \\ 2.5312 \\ \hline 9.2889 \pm \\ 1.1406 \\ \hline 9.6667 \pm \\ 1.3314 \\ \hline 9.1333 \pm \\ 1.4397 \\ \hline \end{array}$	$\begin{array}{c} 9.7778 \pm \\ 1.0848 \\ \hline 9.8667 \pm \\ 0.4573 \\ \hline 9.7111 \pm \\ 1.325 \\ \hline 9.7556 \pm \\ 0.529 \\ \end{array}$	10 ± 0 10 ± 0 10 ± 0 10 ± 0
	(IB) CITY BLOCK (IB) EUCLIDEAN WEIGHTED (IB) PEARSON WEIGHTED (IB) UNCENTERED COSINE WEIGHTED (UB) LOG LIKELYHOOD	2.7778 ± 3.6549 8.1778 ± 2.0702 9.6667 ± 1.3314 8.1111 ± 2.1237 9.9556 ± 0.2084	7.6889 ± 3.4826 8.7556 ± 1.5249 9.6 ± 1.3551 8.6222 ± 1.6691 10 ± 0	9.0444 ± 2.5312 9.2889 ± 1.1406 9.6667 ± 1.3314 9.1333 ± 1.4397 10 ± 0	9.7778 ± 1.0848 9.8667 ± 0.4573 9.7111 ± 1.325 9.7556 ± 0.529 10 ± 0	10 ± 0 10 ± 0 10 ± 0 10 ± 0 10 ± 0

Figure 16: Average amount of effective recommendations depending on the PrA strategy

the same PrA Strategy, but we plan to allow users to choose the own strategy in their agents in the near future. Figures 13, 14, 15, 16 as 17 sn, v the results for the test with the *Taboo ARP* strategy and the mode relevant's similarity metrics.

Figure 13 shows that, as expected, the total amount \cdot concessions decreases drastically when using the *Relaxed* [rp=0.1] variant v th respect to the *Strict* variant (which was the one used by PUMAS in [12]), and the rest of the variants are in between those mentioned.

In Figure 14 we see that group satisfaction for the *Lelax d* and *Next* variants did not increase as much as we expected. The results of the experiments with ML_LATEST_SMALL show the GS increased for all the similarity metrics. However, the experiments performed with YFLP show that the GS only improved when an IB similarity metric was under the *PrA* strategore assume that, in some cases, it might be preferable to accept a properative (even if it is not exactly better than the agent current proposal but it is close enough), rather than risking "to let" the agent concede (which will cause an filty loss perhaps higher than the one incurred by accepting proposal x). The aresult, the agents accept more proposals, the agreement is reached factor and less concessions are made. Although this might be positive in some cases, there is a cost to pay: even if a proposal x is rejected, the agent might approximation is a utility loss that rejecting x would not have caused.

In Figure 15 we see that, in some cases the MSD decreases as the relax level increases (when using the *Relax 1* variant) but this is not always true. This effects follows from what we captained previously about the possible increase in group satisfaction but only in those cases on which the utility of the initial proposal of the agents in very similar and/or the same. Additionally, we can observe that the *ext* variant negatively impacted on how uniformly the group members were satisfied (by increasing the MSD), and once again, the explanation is the same is the one given above: the assumption that *Next* makes might lead the agents to make sub-optimal decisions.

Figure 16 s. we that, as expected, when all the agents use the *Strict* variant the amount of effective recommendations (i.e recommendations produced) is lower th n when hey use the *Relaxed* or *Next variants*.

In Figure 17 we can see that the fairness of the recommendations increases in most cases when the *Relaxed* and *Next* strategies are used. All the results were validated through statistical tests. We first run the Shappiro-Wilk test on the same in the determine whether they followed or not the normal distribution. Given that some of the samples did not follow that distribution a non-parametric est was used. We then proceeded like we did previously (see Section 4.5.1): by performing (for each dataset and for each similarity metric) a pair-wise computer on a mong the 5 samples (one for each PrA variant) using the Wilcoxon figured Ranks test:

• For Figures 13 and 15, the null hypothesis was defined as "the sample of

						4
	511511500				DATASET: ML_L	ATEST_SM
	FAIRNESS (higher is better)	STRICT	RELAXED [rp=0.025]	RELAXED [rp=0.05]	RELAXED [rp=0.1]	NEVT
	(IB) CITY BLOCK	0.5864 ± 0.3046	0.6619 ± 0.2454	0.6925 ± 0.1978	0.6912 ± 0.1971	J.6775 ± 0.1982
۹۲ ۱	(IB) EUCLIDEAN WEIGHTED	0.8862 ± 0.2147	0.9046 ± 0.1656	0.9212 ± 0.0936	0.9117 ± 0.1008	98F ,2
	(IB) PEARSON WEIGHTED	0.9738 ± 0.0419	0.9788 ± 0.029	0.9791 ± 0.0294	0.985 0.0 .7	0.9405 ± 0.0 ³⁶
	(IB) UNCENTERED COSINE WEIGHTED	0.9132 ± 0.1692	0.9383 ± 0.0903	0.9295 ± 0.0954	0.1 46 ± 0. 72	0.874 0.124
	(UB) LOG LIKELYHOOD	0.9982 ± 0.0094	1 ± 0	1 ± 0	1± 0	0.97 , ±
	(UB) PEARSON WEIGHTED	0.982 ± 0.0392	0.9973 ± 0.0088	0.9971 / 0.0086	0.99° 1 J3	0.9204 ± 0.0507
	511511500					TASET: YELF
	FAIRNESS (higher is better)	STRICT	RELAXED [rp=0.025]	RELA. [rp=0.05]	RE. [rp=0.1]	NEXT
	(IB) CITY BLOCK	0.429 ± 0.4651	0.7807 ± 0.3257	0.8193 ± 0.2588	ι 149 ± 199	0.8498 ± 0.1885
1	(IB) EUCLIDEAN WEIGHTED	0.975 ± 0.0564	0.9826 0.0405	0.5. 0.0537	.9838 ± 0.0426	0.9341 ± 0.0645
	(IB) PEARSON WEIGHTED	0.9959 ± 0.01	0.9962 ± 0.0105	u. '?± 0.014	0.9959 ± 0.0148	0.9666 ± 0.0613
	(IB) UNCENTERED COSINE WEIGHTED	0.9816 ± 0.0446	u. ¹⁷ ± 0.03c.	0.9841 ± 0.0406	0.9833 ± 0.041	0.9311 ± 0.0671
	(UB) LOG LIKELYHOOD	1± 0	1±	1.± 0	1 ± 0	0.9904 ± 0.0269
	(UB) PEARSON WEIGHTED	0.9926 ± 0.0497	0.997 ± 1.0 7	0.9926 ± 0.0497	0.9926 ± 0.0497	0.9758 ± 0.0717

Figure 17: Average fairness per sim, and metric depending on the PrA Strategy

the variant A is not worse than "he sample of the variant B" as we wanted to test that one PrA structegy A (e.g., *Strict*) was significantly better than the other B (e.g., $\land ext$) in terms of amount of concessions made by the agents (Figure 13)/ \land "SD (F.gure 15).

• For Figures 14–16 : ad 17, we tested that one PrA strategy A (e.g., Relaxed $[rp=0.05_{J}]$, " as significantly better than the other B (e.g., Relaxed [rp=0.025]) regarding to the GS (Figure 14)/amount of effective recommendation (right relations) (right relation (right relation)) for the sample of the variant A is not greater than the sample of the variant B".

All the previous lests confirmed our observations as, in each test, the null hypothesis was rejerted at a significance level of 95% ($\alpha = 0.05$). Thus, we confirmed that P A Belaxed was the best one with regard to reducing the amount of concession equivalence of the agents to reach an agreement, and also to increasing the it and recommended, while keeping the quality of the recommendations.

4.5.4. Infor action privacy

In order to measure the amount of information revealed by UserAgent's of MAGRe 3 during the negotiation process, the UFIL and PIL indicators were c. mput 3d (see Section 4.3).

The parameterization used for this experiment is specified in Appendix A.4.4. /.s it can be seen in Figure 18, the amount of information related to the utility . unction that was leaked when using MAGReS is always lower than when using the traditional approaches (the preference aggregation one, TRADGRec-PA,

IN	FORMATION LEAK - UTILITY							TASET: ML	TEST_SMALL
	FUNCTION (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGP- "4 [U', 5]	TRADU. RA [AVG; T1]	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	1.97% ± 2.62%	48.97% ± 36.02%	4.32% ± 3.5%	53.97% ± 26.84%	100% ± 0%	J0% ± 7%	1. ± 0%	100% ± 0%
RIC	(IB) EUCLIDEAN WEIGHTED	0.88% ± 0.36%	64.63% ± 17.73%	51.43% ± 20.28%	63.11% ± 14.54%	100% ± 0%	100% _ 0%	100% ± 0%	100% ± 0%
Y MET	(IB) PEARSON WEIGHTED	0.85% ± 0.01%	31.12% ± 15.35%	24.99% ± 13.98%	41.07% ± 9.71%	100% : 0%	100% - 0%	100% ± 0%	100% ± 0%
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.88% ± 0.36%	64.08% ± 17.4%	54.4% ± 19.54%	37.09% ± 11.36%	100% ±	100% ±	100% ± 0%	100% ± 0%
SIN	(UB) LOG LIKELYHOOD	0.84% ± 0.01%	16.91% ± 5.05%	4.86% ± 3.09%	19.67% ± 7.34%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
	(UB) PEARSON WEIGHTED	0.85% ± 0.01%	29.17% ± 9.7%	14.35% ± 6.49%	26.96% ± 3.19%	, ± 0%	.00% ± 0%	100% ± 0%	100% ± 0%
IN	FORMATION LEAK - UTILITY							D	ATASET: YELP
	FUNCTION (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [Mc. vt; M11]	TRADGR PA [AVG:]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
	(IB) CITY BLOCK	0.15% ± 0.2%	7.99% ± 10.01%	1.87% ± 4.87%	1. 7% ± 4.18/	_J% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
RC	(IB) EUCLIDEAN WEIGHTED	0.1% ± 0%	14.46% ± 6.09%	9.48% ± 4.57%	3.59%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
Y METI	(IB) PEARSON WEIGHTED	0.1% ± 0.01%	4.04% ± 2.55%	2.68% ± 2.22%	°% ± 1.85.	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
IILARIT	(IB) UNCENTERED COSINE WEIGHTED	0.1% ± 0%	14.57% ± 6.39%	10. %± 4.7⊾	± 0.01%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
SIN	(UB) LOG LIKELYHOOD	0.1% ± 0%	1.39% ± 1.73%	1.14% ± `85%	5.18% ± 2.09%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
	(UB) PEARSON WEIGHTED	0.1% ± 0.01%	0.71% ± 0.2%	65%. L 1%	3.41% ± 1.98%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%

Figure 18: Information Lea. Utility Function related information

and the recommendation aggreg tion one, TRADGRec-RA). Logically, when using MAGReS [One-Step, M19, MAGReS [MCP Next; M11] and MAGReS [MCP Relaxed; M17] the amount of information leaked is always lower than when using the MAC Ref [MCP Strict; M5], as MAGRef [One-Step; M19] only uses one negotiation round is adopted by MAGRef [MCP Next; M11] and MAGRef [MCP Relaxed; 1277] reduce the amount negotiation rounds by "making" the agents reach agreement faster (see Sections 3.5 and 4.5.3). The same conclusion was reached inelanalyzing the amount of information leaked regarding the candidate physicals. We found out that, again, MAGRefs [One-Step; M19], MAGRefs 'MCF Mext; M11] and MAGRefs [MCP Relaxed; M17] variants always leak less information than the MAGRefs [MCP Strict; M5] one. All in all, the best varial that the four tested seems to be MAGRefs [MCP Relaxed; M17], as it leath areas able amount of information while achieving, in many cases, the high st GS, 'airness and amount of effective recommendations, and the lowest MSL (see Section 4.5.3).

To commute validity of the results, we run statistical tests following the same strategy as the one used in previous sections. For each dataset and for ϵ ch similarity metric we first performed a normality test and then, when we confirmed that at least one of the samples did not follow the normal distribution, v e performed a pair-wise comparison among the samples (5 in Figure 18 and ' in Figure 19) using the Wilcoxon Signed Ranks test. As one approach, A, is better than another one, B, if it leaks less information with regard to the utility

				DATASET: ML_LA	TEST_SMAL
	PROPOSALS (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next M11]
	(IB) CITY BLOCK	0.01% ± 0%	0.32% ± 0.37%	0.02% ± 0.02%	0.64% 0.68
Ĩ	(IB) EUCLIDEAN WEIGHTED	0.01% ± 0%	0.4% ± 0.16%	0.28% ± 0.15%	0.84% 1 0.43%
	(IB) PEARSON WEIGHTED	0.01% ± 0%	0.35% ± 0.17%	0.28% ± 0.16%	0.39%
THAN	(IB) UNCENTERED COSINE WEIGHTED	0.01% ± 0%	0.33% ± 0.14%	0.23% ± 0.11%	0.59% ± 0.34%
	(UB) LOG LIKELYHOOD	0.01% ± 0%	0.09% ± 0.04%	0.02% ± 0.01	•% ± 0.0,
	(UB) PEARSON WEIGHTED	0.01% ± 0%	0.28% ± 0.11%	(.1% ± .08%	[~] ± 0.2.
	INFORMATION LEAK -				
	PROPOSALS (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS	JReS (MCP Next M11)
	(IB) CITY BLOCK	0% ± 0%	0.01%± 0.0.	0% ± 0.01%	0.02% ± 0.02%
L L	(IB) EUCLIDEAN WEIGHTED	0% ± 0%	02% ±	01%	0.01% ± 0.01%
T IME	(IB) PEARSON WEIGHTED	0% ± 0%	0.01% ± 0.01%	0.01% ±)1%	0.01% ± 0.01%
	(IB) UNCENTERED COSINE WEIGHTED	0% ± 0%	0.02% ± `01%	0.01% ± 0.01%	11.12% ± 3.58%
	(UB) LOG LIKELYHOOD	0% ±	0% - 0%	0% ± 0%	0% ± 0%
	(UB) PEARSON WEIGHTED	6. 0%	0% _	0% ±	0% ±

Figure 19: Information Leak: "a. ";date proposals related information

function (Figure 18) and the candid, 'e proposals of each agent (Figure 19), for each test we defined the null hypothesis as "the sample of the variant A is not worse than the sample of the valiant B". The results of the test confirmed our findings as, in each test, the null hypothesis was rejected at a significance level of 95% ($\alpha = 0.05$). At last, we confirmed that MAGReS leaked less information than TRADGRec-P', and TPADGRec-PA with respect to the users' utility function, and that, with the exception of MAGReS [One-Step; M19], MAGReS [MCP; M17] was diso the parameterization that fewer proposals revealed.

4.5.5. Smaller $\neg e$ recommendations (K=3 and K=5)

Once we determined that MAGReS was capable of producing better recommendations (an TRADGRec-RA and TRADGRec-PA when the amount of items to be recommended was 10, we wanted to know if the same situation would happen the making smaller recommendations (i.e., with less items). For this matter we applie ated the tests performed for k = 10 (see Section 4.4) but just using the similarity metrics that provided the best results in terms of the quality of the recommendations produced: *Euclidean Distance* similarity for the itembered of the results of the test of the user-based SUR. The results of the experiments conducted showed that for both k = 3 and k = 5 MAGReS outperformed the traditional approaches (TRADGRec-PA and TRADGRec-RA) in terms of:

• The GS and the MSD of her recommendations. As it can be seen in Figure 20 and Figure 21 the recommendations produced by all the variants of MAGReS not only achieved a higher level of satisfaction for the group (i.e.,

6

the GS) but also were able to satisfy all of its members h ore uniformly (i.e., the MSD was lower) and increased the fairness of \Box e recommendations.

worst case scenario (when using Taboo as the AR? stratingy and Strict as the PrA strategy) MAGReS leaked less utility-f nction elated informa-set k = 10 (see Section 4.5.4), in the worst case see ario the MCP-based variant of MAGReS leaked no more than the 0.5.10 (for the experiments with ML LATEST SMALL)/0.01% (for the vaperiments with YELP) of the information, which means that o_{x} " all the items present in the datasets (see Section 4.4), just the 0.35 (ML_LATEST_SMALL) and 0.01% (YELP) of them was effectively provided by every agent during each one the recommendations. Note that the amount of information (of all types) leaked was significant' lower than when making recommendations of 10 items, and this is exp'ai ed because a lower amount of items to be recommended implies of wer mount of negotiation processes to be carried out (see Section 4.4), which leads to less information leaked by the agents.

With regard to the analysis of the AP and PrA strategies, the tests proved that the observations made in the analysis for k = 10 were also valid for k = 3 and k = 5:

- The use of the *ARP*, 'rat gies reduced significantly the amount of "already rated iter is" ¹ eing recommended. The *Taboo* variant was able to completely elin. 'na e the overlap for both of the similarity metrics, while not producing a significant negative impact in the quality of the recommendation
- The *Pr*/. rategies helped to increase the group satisfaction while also increasing the amount of effective recommendations, reducing the amount of concestions needed to reach the end of the negotiation (either with an agreement or a conflict), increasing the fairness of the recommendations and in some cases, reducing the MSD.

4.5.6 Summary of results

The ARI strategy was created in order to model, as an agent-like behavior how the user feels about receiving a recommendation with an item she/he has all ady rated. The ARP strategy works as a penalty to the utility reorted by the agent when asked about a certain proposal. Each variant of the Au. Strategy has its own rules for computing the penalty. From all the varia wo of the ARP strategy, our tests showed that, independently the dataset used, Taboo was the most effective variant at the task of reducing (to zero in most of the cases) the overlap between items recommended and items already rated by the group members, but this came at the cost of reducing

								DATASET: ML_L	ATEST_SMALL
Ģ	GROUP SATISFACTION (higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRe 'A [AVG; T1 _.	TRADGRec-i [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN WEIGHTED	0.8028 ± 0.0835	0.8407 ± 0.1352	0.8577 ± 0.0424	0.8305 ± 0.0687	J.1727	_ ± 0.1856	0.701 ± 0.106	0.701 ± 0.106
SIMIL	(UB) PEARSON WEIGHTED	0.8182 ± 0.1192	0.962 ± 0.0264	0.9638 ± 0.0188	0.8837 ± 0.0712	0.539F	5429 ±).1651	0.7054 ± 0.1537	0.7054 ± 0.1537
								C	ATASET: YELP
G	GROUP SATISFACTION (higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next;	TRADuPA [AVG;]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
ARITY FRIC	GROUP SATISFACTION (higher is better) (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; M19] 0.7105 ± 0.1596	MAGReS [MCP Strict; M5] 0.7069 ± 0.408	MAGReS [MCP Relaxed; M17] 0.9222 ± 0.042	MAGReS [MCP Next; 	TRADGPA [AVG;] 0.20' / ± 323	TRADGRec-PA [UL; T5] 0.1959 ± 0.138	C TRADGRec-RA [AVG; T1] 0.5341 ± 0.1459	ATASET: YELP TRADGRec-RA [UL; T5] 0.5341 ± 0.1459

R

(a) Average GS per similarity retric and approach

ME	MBERS SATISFACTION						C	DATASET: ML_L	ATEST_SMALL
	DISPERSION (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGRe. "OP Relaxec. 71	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN WEIGHTED	0.1233 ± 0.0832	0.078 ± 0.0366	<1852 ⊥ 0. 177	0.1168 ± 0.0802	0.3181 ± 0.1363	0.2827 ± 0.1349	0.2313 ± 0.1053	0.2313 ± 0.1053
SIMIL	(UB) PEARSON WEIGHTED	0.1373 ± 0.1079	0.02 0.0238	0.0103	0.1321 ± 0.094	0.2933 ± 0.1238	0.3051 ± 0.1323	0.2377 ± 0.1199	0.2377 ± 0.1199
ME	MBERS SATISFACTION							C	ATASET: YELP
ME	MBERS SATISFACTION DISPERSION (lower is better)	MAGReS [One-Step; M19]	MGReS [MCr t; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY FRIC BIM	MBERS SATISFACTION DISPERSION (lower is better) (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; <u>M19]</u> 0.208(0.0935	MGReS [MCF t; M5] 0.0397 ± 0.0347	MAGReS [MCP Relaxed; M17] 0.0593 ± 0.0286	MAGReS [MCP Next; M11] 0.0987 ± 0.0706	TRADGRec-PA [AVG; T1] 0.3244 ± 0.2079	TRADGRec-PA [UL; T5] 0.3142 ± 0.1884	TRADGRec-RA [AVG; T1] 0.2853 ± 0.1265	ATASET: YELP TRADGRec-RA [UL; T5] 0.2853 ± 0.1265

(b) , or ge M $_{2}D$ per similarity metric and approach

							C	ATASET: ML_L	ATEST_SMALL
	FAIRNESS (higher is better)	i، PeS [One-s. ; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY 'RIC	(IB) EUCLIDEAN' /EIGHTE	0.8401 ± 0.1651	0.9286 ± 0.1629	0.9279 ± 0.0948	0.8863 ± 0.1103	0.6044 ± 0.212	0.6057 ± 0.2223	0.6885 ± 0.16	0.6885 ± 0.16
SIMIL	(UB) PEARົON WEIG. ີາ	0.8575 ± 0.1403	0.9985 ± 0.0099	1 ± 0	0.911 ± 0.0849	0.5438 ± 0.167	0.5464 ± 0.1654	0.7186 ± 0.1595	0.7186 ± 0.1595
		_							
								C	ATASET: YELP
	FL INESS (higher h. er)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
ARITY FRIC	FURNESS (higher), er) (IB) EUCLIDE ' WEIGHTED	MAGReS [One-Step; M19] 0.7362 ± 0.1887	MAGReS [MCP Strict; M5] 0.7511 ± 0.4331	MAGReS [MCP Relaxed; M17] 0.9867 ± 0.0505	MAGReS [MCP Next; M11] 0.9391 ± 0.072	TRADGRec-PA [AVG; T1] 0.2044 ± 0.1339	TRADGRec-PA [UL; T5] 0.2054 ± 0.1443	TRADGRec-RA [AVG; T1] 0.5426 ± 0.1693	ATASET: YELP TRADGRec-RA [UL; T5] 0.5426 ± 0.1693

(c) Average fairness per similarity metric and approach

Figure 20: Average GS, MSD and fairness for recommendations of size 3 (k = 3)

								DATASET: ML_L	ATEST_SMALL
C	GROUP SATISFACTION (higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRe 'A [AVG; T1 _.	TRADGRec-i [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN WEIGHTED	0.7984 ± 0.076	0.8353 ± 0.1347	0.8536 ± 0.0425	0.824 ± 0.0736	J.1724	, ± 0.1684	0.6871 ± 0.115	0.6871 ± 0.115
SIMIL	(UB) PEARSON WEIGHTED	0.78 ± 0.1078	0.949 ± 0.0304	0.9546 ± 0.0196	0.8881 ± 0.0539	0.5407	5417 ± 0.117	0.6838 ± 0.0944	0.6838 ± 0.0944
								C	DATASET: YELP
C	GROUP SATISFACTION (higher is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next;	TRADuPA [AVG;]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	DATASET: YELP TRADGRec-RA [UL; T5]
ARITY TRIC	GROUP SATISFACTION (higher is better) (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; M19] 0.6923 ± 0.1345	MAGReS [MCP Strict; M5] 0.8401 ± 0.2679	MAGReS [MCP Relaxed; M17] 0.918 ± 0.0423	MAGReS [MCP Next; 	TRADGPA [AVG;] 0.1°' /± 215	TRADGRec-PA [UL; T5] 0.1976 ± 0.1258	C TRADGRec-RA [AVG; T1] 0.594 ± 0.1215	DATASET: YELP TRADGRec-RA [UL; T5] 0.594 ± 0.1215

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(a) Average GS per similarity retric and approach

ME	MBERS SATISFACTION						[DATASET: ML_L	ATEST_SMALL
	DISPERSION (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGRe. ۲۰۵۲ Relaxec ۱۰۶۲	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN WEIGHTED	0.1194 ± 0.0703	0.0768 ± 0.0383	ر 1849 ⊥ 0.√ 192	0.1192 ± 0.0861	0.2995 ± 0.1354	0.2709 ± 0.1301	0.219 ± 0.1156	0.219 ± 0.1156
SIMIL	(UB) PEARSON WEIGHTED	0.1233 ± 0.0776	0.0∠. 0.028	0.0119	0.0983 ± 0.0589	0.2646 ± 0.0912	0.2622 ± 0.0948	0.2085 ± 0.076	0.2085 ± 0.076
ME	MBERS SATISFACTION							C	ATASET: YELP
ME	MBERS SATISFACTION DISPERSION (lower is better)	MAGReS [One-Step; M19]	[MCF t; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
ARITY FRIC BM	MBERS SATISFACTION DISPERSION (lower is better) (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; <u>M19]</u> 0.174 0.0808	MCP t; M5 0.0548 ± 0.0315	MAGReS [MCP Relaxed; M17] 0.0563 ± 0.0263	MAGReS [MCP Next; M11] 0.0933 ± 0.0725	TRADGRec-PA [AVG; T1] 0.3081 ± 0.1803	TRADGRec-PA [UL; T5] 0.3079 ± 0.1686	C TRADGRec-RA [AVG; T1] 0.2183 ± 0.0809	ATASET: YELP TRADGRec-RA [UL; T5] 0.2183 ± 0.0809

(b) ... r ge M D per similarity metric and approach

							[DATASET: ML_L	ATEST_SMALL
	FAIRNES (higher is better)	IOne-S. J; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN' /EIGHTE	0.8333 ± 0.1514	0.8353 ± 0.1347	0.9232 ± 0.0947	0.8886 ± 0.1114	0.5968 ± 0.203	0.615 ± 0.1956	0.6693 ± 0.1649	0.6693 ± 0.1649
SIMIL	(UB) PEARົON WEIG. ີາ	0.8047 ± 0.1226	0.9947 ± 0.0202	0.9991 ± 0.006	0.9174 ± 0.0703	0.4924 ± 0.0909	0.5025 ± 0.0905	0.6921 ± 0.105	0.6921 ± 0.105
		-							
								D	ATASET: YELP
	FL INESS (higher h. er)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
ARITY FRIC	FURNESS (higher), er) (IB) EUCLIDE ' WEIGHTED	MAGReS [One-Step; M19] 0.7169 ± 0.1712	MAGReS [MCP Strict; M5] 0.9053 ± 0.2873	MAGReS [MCP Relaxed; M17] 0.985 ± 0.0482	MAGReS [MCP Next; M11] 0.9287 ± 0.0764	TRADGRec-PA [AVG; T1] 0.2002 ± 0.1224	TRADGRec-PA [UL; T5] 0.2085 ± 0.1305	TRADGRec-RA [AVG; T1] 0.5995 ± 0.1398	ATASET: YELP TRADGRec-RA [UL; T5] 0.5995 ± 0.1398

(c) Average fairness per similarity metric and approach

Figure 21: Average GS, MSD and fairness for recommendations of size 5 (k = 5)

INF	ORMATION LEAK - UTILITY						[DATASET: ML_L	ATEST_SMALL
	FUNCTION (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGRes L. Next; M1.	JRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	TRADGRec-RA [UL; T5]
ARITY IRIC	(IB) EUCLIDEAN WEIGHTED	2.75% ± 0.01%	41.04% ± 14.36%	27.97% + 14.36	26 700 · 11.48%	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
SIMIL	(UB) PEARSON WEIGHTED	2.74% ± 0.01%	20.46% ± 6.24%	9.93% ± 4.65%	17% ±	100% ± 0%	100% ± 0%	100% ± 0%	100% ± 0%
INF	ORMATION LEAK - UTILITY							D	ATASET: YELP
INF	ORMATION LEAK - UTILITY FUNCTION (%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict· M5]	MAG S [MCP Rela. 1: M17]	MAGReS [MCP Next; M11]	TRADGRec-PA [AVG; T1]	TRADGRec-PA [UL; T5]	TRADGRec-RA [AVG; T1]	ATASET: YELP TRADGRec-RA [UL; T5]
ARITY FRIC	ORMATION LEAK - UTILITY FUNCTION (%) (lower is better) (IB) EUCLIDEAN WEIGHTED	MAGReS [One-Step; M19] 0.33% ± 0%	MAGReS [MCP Strict- M5] 5.6% ± 4.82%	MAG 5 [MCP Rela. :: M17] 5.5. * 3.22%	MAGReS [MCP Next; M11] 6.76% ± 2.23%	TRADGRec-PA [AVG; T1] 100% ± 0%	TRADGRec-PA [UL; T5] 100% ± 0%	TRADGRec-RA [AVG; T1] 100% ± 0%	TRADGRec-RA [UL; T5] 100% ± 0%

INFORM	ATIOL LEAK - PROPL ALS			DATASET: ML_LA	TEST_SMALL
	(%) (lower atter)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]
ARITY TRIC	(IB) EUCLIDEAN W	0.01% ± 0%	0.33% ± 0.13%	0.2% ± 0.11%	0.75% ± 0.41%
SIMIL	(UP EARSON' .IGHTED	0.01% ± 0%	0.16% ± 0.08%	0.06% ± 0.05%	0.28% ± 0.19%
FORM	ATION SA - PROPOSALS			D	ATASET: YELP
	(%) (lower is better)	MAGReS [One-Step; M19]	MAGReS [MCP Strict; M5]	MAGReS [MCP Relaxed; M17]	MAGReS [MCP Next; M11]
ARITY TRIC	UCLIDEAN WEIGHTED	0% ± 0%	0.01% ± 0.01%	0.01% ± 0.01%	0.01% ± 0.01%
SIMIL	(UB) PEARSON WEIGHTED	0% ± 0%	0% ± 0%	0% ± 0%	0% ± 0%

(a) Utility Funct. n related information

(b) Proposals related information

Fi are 22: Information leak for recommendations of size 3 $\left(k=3\right)$

the group satisfaction. The *Flexible* variant, on the other side provided a good *reduction of overlap/group satisfaction loss* ratio, parillularly when the *flexibilityLevel* (f) parameter was set to 0.75. In this cale, the overlap was reduced to almost a 1% overall except in the case of the similarity metric (*IB*) City Block, for which the overlap was around 11% in the experiments performed with ML LATES T_SMALL and 2% in those performed with YELP. Additionally, the group satisfaction loss was generally lower than when using the Taboo variant, with regard to the fairness, the *Min-Satisfaction* (for ML_LATEST_SMALL) and *LATEST_SMALL* and the overlap is high. All in all, depending on which ARL strategy is selected by the group members for their agents, the group recommendation will change.

The PrA strategy was introduced as a "ay it," inprove the model of users criteria with regards to the decision of accept. ~ a proposal. Three different variants were proposed, namely: Strict originally proposed in [12]), Relaxed and Next. For our tests we defined scenarios , here all the agents used the same PrA strategy, so as to analyze the effects c ch strategy on the recommendations. We observed that, independently 'ne dataset used, when all the agents used the Strict variant the amount γ ffec, ve recommendations was lower than when they used either the Next or the $Re_{i,i}xed$ variants. This was caused by the amount of negotiations that en equal with no agreement (i.e., with conflict), as many proposals were rejected because of not being exactly what the agents were expecting. Naturally, when the agents are more flexible when determining whether to accept or not a propisal, they are more prone to accept proposals that are not exactly what they τ anted but that are good enough, and so the amount of effective re ommen.' tions increases. In terms of the quality of the recommendations measured by the group satisfaction and how uniformly where the group member satified we observed that when the *Relaxed* variant was used there were one improvements (if compared to the *Strict* variant), but when the *Next* arian, was used the quality of the recommendations produced was lower (during the the sub-optimal decisions taken by the agents). Additionally, we oser ed that the use of the variants Relaxed and Next helped to improve the tak vess of the recommendations regardless of the dataset used.

Finall, regarding to the framework that supports the approach, we have also add d s ppo t for the use of Mahout-based SURs as they were faster than the Duine-t. see SURs for both loading the data models and generating the recommend tions. The similarity metrics available depended on the type of SUR used. The tests revealed that some of them were not able to produce reliable recommend tions (for example, *City Block* and *Euclidean Distance* similarities or the "ser-based SUR) and therefore have to be treated with care.

The nain insights from the experiments were the following:

• The *Relaxed* variant of the PrA strategy can be considered as the "ideal variant", as it not only helps to increase the number of recommended items but also reduces the number of concessions, without negatively impacting on the quality of the recommendations.

- Out of all the variants of the ARP strategy, Taboo performed the best at the task of preventing MAGReS from recommending it are also dy rated by the group members. On the downside, this variant mit and the downside it is still and the recommendations, but overall it is still and the densities of the recommendation in mind, we would recommended that an the agents use this strategy by default, unless their users decide to many ally change it. In terms of performance, the One-Step protocol allowed MAGReS to make faster recommendations, when compared to the MCP, but this came at the cost of drops in the recommendation quality.
- MCP, in turn, helped to improve the quality of the recommendations by increasing the group satisfaction and also satisfy, ig all the group members more uniformly.
- With regard to the SUR, we noticed that to best recommendations were generated when using the *Euclidean Pistance* similarity for the item-based SUR and the *Pearson Similarity* for the *cser-based* SUR.

5. Conclusions and Future W

In this article we proposed MAG1 eS, a group recommendation approach based on MAS as an alternative \cdot the traditional approaches, which employ a combination between aggregation techniques and SUR techniques to produce group recommendations. Let M. GReS, on the contrary, the agents act on behalf of the users, protecting their interests and representing them in a negotiation process that mimics the way. The ans negotiate about a certain topic. The results of the experiments showed that the use of negotiation instead of the aggregation techniques can great. I approve the quality of the recommendations, not only increasing the level of sat. Faction of the group as a whole (group satisfaction) but also satisfying the group members more uniformly (i.e. by reducing MSD and increasing fairness). Along this line, the inclusion of the *ARP* and *PrA* strategies have an impact on the the recommendations produced and allows the users to per onalize the behavior of the agents representing them in the recommendation, "ocess.

Althe ugh we obtained satisfactory results, our experimental study has some limitation. Fir ϵ , the user groups were selected randomly from the dataset, and ϵ , we ignored any potential relationships of group members. However, it might be the case that "similarities" between particular users (e.g., friendship, common taskes, etc.) within the group might affect the recommendations, and thus, change the resulting average satisfaction for some groups [8]. Also, user relationships of trust and influence might affect the item selection. There are a_1 provides for both automatically detecting groups [47, 48] (so as to avoid the random selection of users) and dealing with social relationships among the croup members [49], so we plan to tackle these aspects in future work. Second, the reliance of our current implementation of the users' utility function on the prediction made by the SURs. All the rating predictions are made based on



the configuration of the SUR and so increasing the quality of the predictions, by using a different approach like the one proposed in [50], conchelped improve the recommendations produced by MAGReS. According to or a londings, the datasets were small and their rating matrices were no deal enough for the similarity metrics to work properly when making recomplication, using a userbased SUR. This factor impacted on how the utility function of the agents works, and thus in the recommendations generated by MAGReS.

As a future work we plan to: (i) to compare or approach with other techniques for group recommendation, (ii) evaluate our approach with real users, (iii) assess the approach in a dataset with a more dense rating matrix, (iv) study alternative utility functions for the agents, and (v) analyze new variants for both the ARP and PrA strategies.

Acknowledgments. This work has been partially supported by CONICET PIP Project Number 112-201501-00030 and ANPCyT PICT Project Number 2016-2973.

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Appendix A. Experimental Parameters Summary

In this appendix we will sum up all the parameters take 1 introducideration in each of the experiments performed.

Appendix A.1. Similarity metrics

Mahout provides two types of recommendation tech iques based on Collaborative Filtering: one user-based and one item-based. As it can be seen in Figure A.23, for each type of technique different similarity here is are available. For example, whilst *Euclidean Distance* similarity is available for both techniques, *Spearman Correlation* is only available for the use based recommenders and *Adjusted Cosine* can only be used with the item-based recommenders.

Recommender Type	Similarity	Varit	Parameterization ID						
	Adjusted Casina	Non-Weighted	N/A						
	Adjusted Cosine	`^/eighted	N/A						
	City Block	is one	(IB) City Block						
	Euclidean Distance	Weighted	N/A						
	Euclidean Distance	Weighted	(IB) Euclidean Weighted						
ITEM BACED	Log Likelyho	None	N/A						
TIENI-BASED	Deemon Convolation	Non-Weighted	N/A						
	Pearson Correlat.	Weighted	(IB) Pearson Weighted						
	Tanimoto Coefficient	None	N/A						
		Non-Weighted	N/A						
	Uncentered Cc ine	None	(IB) Uncentered Cosine Weighted						
	City Block	None	(UB) City Block						
		Non-Weighted	N/A						
	∠uclidean D. `ance	Weighted	(UB) Euclidean Distance Weighted						
	L. 'ikely ood	None	(UB) Log Likelyhood						
		Non-Weighted	N/A						
USER-BASED	USER-BASED Jarson Correlation		(UB) Pearson Correlation Weighted						
	Spear an Correlation	None	N/A						
		Non-Weighted	N/A						
	Uncentered Cosine	Weighted	(UB) Uncentered Cosine Weighted						

Figure A.23: S[:] nilar y Metrics supported by each type of SUR (green = used in the experiments, red = $\iota_c + ed$ and discarded, N/A = it was not used in the experiments)

Appendix . 2. / pproaches parameters

Appe idix A 2.1. TRADGRec-PA and TRADGRec-RA parameters

For TRA DGRec-PA and TRADGRec-RA there is only one parameter than can be up a: the *preference aggregation strategy*. At the moment the approach uppor 3 only 5 aggregation strategies, which are specified in Figure A.24. The parameters of those strategies can be found in Figure A.25.

Providix A.2.2. MAGReS parameters

In MAGReS many parameters can be tuned and each one of them can assume n any possible values. In Figure A.26 we specify the most relevant parameters for the experiments carried out in this paper and their possible values. As it

Pre	ference/Rating Aggregation Strategy (PA Strategy)
Useful for:	To aggregate ratings/preferences
Used by:	TRADGRec-PA, TRADGRec-RA
Name	Abbreviation + Parameters
Average (AVG)	AVG
Least Missery (LM)	LM
Most Pleasure (MP)	MP
Approval voting (AV)	AV [approvalVotingThresh 1
Upward Leveling (UL)	UL [alpha,beta, gamma, appr/_arvotingThreshold]

Figure A.24: TRADGRec preference aggregation st ategies

Abbreviation	Value Range	Tester values	Used in comparisons (best results)
av_t	[0; 1]	0,2; 0,6; 0,8; 0,9	0,8*
а	14 LJ	0,2; 0,4*	0,2*
b	[0;	0,1*	0,1*
g	[0; 1]	0,5; 0,7*	0,7*
	Abbreviation av_t a b g	Abbreviation Value Range av_t [0; 1] a :: 1] b [0; 2, g [0; 1]	Abbreviation Value Range Teste values av_t [0; 1] 0,2; 0,6; 0,8; 0,9 a :: 1 0,2; 0,4* b [0; 0,1* g [0; 1] 0,5; 0,7*

Figure A.25: TRADGRec preference aggregation strategies parameters. *values were extracted from [46]

can be seen in the figure some of 1° strategies can be further customized with their own parameters. The range of valid values, the values we have used in the tests and the ones we used when doing comparisons among variants of the same strategy are detailed in ! igure A 27.

Appendix A.3. Apprenche parameterizations

Appendix A.3.1. TRA. FRe -PA and TRADGRec-RA parameterizations

In Table A.28⁺ e specify the most relevant parameterizations for TRADGRec-PA and TRADC Rec-PA.

Appendix A. .2. MAGReS parameterizations

Taking inter-onsideration the tables A.26 and A.27 it is possible to see that ther is γ high amount of possible parameterizations for MAGReS. The Table A 'd cails all the parameterizations used to test the approach for this paper, each the of them selected because they were relevant to the experiment we reded to perform. For example, the *One Step* protocol performs only one nego intion bound which renders the *PrA* strategies *Next* and *Relaxed* useless. In the finite case because it relies on what the agents would do in the next negotiation round, and in the second case because of how the agreement is 'etermited (according to this protocol the agents agree on the item with the higher, utility product, which means that the *PrA* strategy is not used).

Luch parameterization is identified by an ID which can be used to refer to he parameterization itself. For example, saying that the parameterization M1will used means that we set the protocol to MCP, the PrA strategy to Strict, the

CCEPTED MANUSCR

	Protocol
Useful for:	Determining how the agents should regotize
Name	Abbreviation + Parameters
Monotonic Concession Protocol	MCP
One-Step Protocol	ONE-STEP

(a) Protocols

Со	ncession Strategy
Useful for:	Defining the set of types the agent follow when choosing what to propose in the next round (if they have to make procession)
Name	Abbr. intion + Pargneters
Desires Distance	חי
Nash	NASH
Utilitarian	UT LL ARIAN

(b) Concession 5. retegies

Already Rated Pun	ishment Strategy (ARP Strategy)
Useful for:	Model how the users may react when items to the how already rated are proposed to her and increatifie agent behave in a similar way
Name	Abbreviation + Parameters
Easygoing	EASYGOING
Flexible	FLEXIBLE [f=X]
FlexiblePlus [flexibilityLevel, minSatisfaction]	FLEXIBLEPLUS [f=X, ms=Y]
MinSatisfaction [m Satisfact n]	MINSAT [ms=X]
Ta ^k o	TABOO

(2) ARP strategies

(s) F	ARP strategies				
Properal Accep	tance Strategy (PrA Strategy)				
Prope Al Acceptance Strategy (PrA Strategy) Useful for: Model the way the users determine wheth to accept or reject a proposal and make th agent behave in a similar way No.ne Abbreviation + Parameters Strict STRICT					
N. ne	Abbreviation + Parameters				
Strict	STRICT				
Next	NEXT				
Relaxed	RELAX [rp=X]				

(d) PrA strategies

Figure A.26: MAGReS parameters

Strategy Parameter	Abbreviation	Strategy	Value Range	Tested values	Used in comparisons (best results)
elaxPercentage	rp	Relaxed (PrA)	[0; 0,1]	0,025; 0,05; 0,1	0,025; 0,05; 0,1
flexibilityLevel	f	Flexible (ARP)	[0; 1]	0,25; 0,5; 0,75	0.75
minSatisfaction	ms	FlexiblePlus (ARP), MinSatisfaction (ARP)	[0; 1]	0,2; 0,4; 0,6; 0,8	0.6

Figure A.27: MAGReS strategies parameters

	APP	ROACH	PARAN	NETERS		
		PA S	trategy	,	PARAMETERIZATION	
	Newse		Paran	neters		
	Name	av_t	а	b	g	
TRADGRec-PA	AVG		N	/A		Tı
	LM		N	/A		77
	MP		N	/A		T3
TRADGRec-PA	AV	0.8		N/A		T4
	UL	0.8	0.2	0.1	0.7	<u>T5</u>
	APP	ROACH	PARAN	NETERS		
		PA S	trategy	1		PARAMETERIZATION
			Paran	neters		
	Name	av_t	а	b	4	
TRADGRec-RA AVG N/A						T1
	LM		N	/A		T2
	MP		N	/A	_	ТЗ
	AV	0.8		N'/A		T4
	UL	0.8	0.2	0.1	0.7	T5

Figure A.28: TRADGRec-RA and '1. ^DGRec-PA parameterizations

Concession strategy to Desires Distance and the ARP strategy to Easy-Going.

Appendix A.4. Experiments pa. multimentations

Appendix A.4.1. Single-User-Recom. ender experiment

For each of the similarⁱ, metrics listed with green background in the Table A.23 we analized the result, of the experiments that used the following parameterizations:

- For MAGReS:
 - One St ρ prote i: M19
 - MCP prov col: M5, M11, M13 and M17.
- For TR ADC Rec-PA: T1 and T5.
- For TRAL GRec-RA: T1 and T5.

Appendia 4 4.2. ARP experiment

To value, the impact of the ARP strategies on the agents behavior we performed experiments comparing the recommendations produced by the following MAC ReS preameterizations: M1, M2, M3, M4 and M5.

Appena. r A.4.3. PrA experiment

The MAGReS parameterizations used in the experiments were: M5, M11, M13, M15 and M17.

PARAMETERIZATIONS	QI	M1	M2	M3	M4	M5	MG	M7	M8	M9	M10	M11	M12	M13	M14	M15	M16	M17	NU	M19	M20	M21	N.C.	M23
	ARP	EASYGOING	FLEXIBLE [f=0.75]	FLEXIBLEPLUS [f=0.75, ms=0.6]	MINSAT [ms=0.6]	TABOO	EASYGOING	TABOO	EASYGOING	TABOO	EASYGOING	TABOO	EASYCOING	T/ 300	Er YGC JG	TAF O	CASN JOING	TAL 10	EASYGOING	TABOO	EASYGOING	TABOO	EASYGOING	TABOO
METERS	CONCESSION STRATEGY			DD			NACI	HCAN	TILT , A				20	nn		nn	2	nn		nn	NACU	LICENI	ITTITADIAN	UTILITANIAIN
APROACH PARA	PrA (CTRICT	SIRIC					NEVT	INEXI	BELAVED [m-0.036]		DELAVED [rn-0.05]	NELAAEU (IP-0.03)		RELAXED [rp=0.1]			CTDICT	SINCI		
	PROTO N									IMCF											ONE STEP	ONE SIEF		
											MAGReS													

Table A.1: MAGReS parameterizations

Appendix A.4.4. Information privacy experiment

For this experiment we decided to compare those pare interizations that produced the best results in terms of information privacy.

- For TRADGRec-PA: T1 and T5.
- For TRADGRec-RA: T1 and T5.
- For MAGReS: M5, M11, M17, M19.