



Article Use of the Modified Riccati Technique for Neutral Half-Linear Differential Equations

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Abstract: We study the second-order neutral half-linear differential equation and formulate new oscillation criteria for this equation, which are obtained through the use of the modified Riccati technique. In the first statement, the oscillation of the equation is ensured by the divergence of a certain integral. The second one provides the condition of the oscillation in the case where the relevant integral converges, and it can be seen as a Hille–Nehari-type criterion. The use of the results is shown in several examples, in which the Euler-type equation and its perturbations are considered.

Keywords: half-linear neutral differential equation; oscillation criteria; modified Riccati technique

MSC: 34K11; 34C10

1. Introduction

In this paper, we study the oscillatory properties of the second-order half-linear neutral differential equation

$$(r(t)\Phi(z'(t)))' + c(t)\Phi(x(\tau(t))) = 0, \quad z(t) = x(t) + b(t)x(\sigma(t)), \tag{1}$$

where $t \ge t_0$ and $\Phi(x) = |x|^{p-2}x$, $p \in \mathbb{R}$, and p > 1. We suppose that the coefficients of the equation satisfy the usual conditions: $r \in C([t_0, \infty), \mathbb{R}^+)$, $b \in C^1([t_0, \infty), \mathbb{R}^+_0)$, $c \in C([t_0, \infty), \mathbb{R}^+_0)$, c is not identically equal to zero in any neighborhood of infinity, and

b

$$(t) \le 1. \tag{2}$$

Concerning the deviating arguments, we assume that $\tau, \sigma \in C^1([t_0, \infty), \mathbb{R})$, $\lim_{t\to\infty} \tau(t) = \infty$, $\lim_{t\to\infty} \sigma(t) = \infty$ and

$$\tau' \ge 0, \quad \tau(t) \le t, \quad \sigma(t) \le t. \tag{3}$$

We also suppose that

$$\int^{\infty} r^{1-q}(t) \, dt = \infty, \tag{4}$$

where *q* denotes the conjugate number of *p*, i.e., $q = \frac{p}{p-1}$, and the symbol $\int_{-\infty}^{\infty}$ means that it does not matter what the lower limit of the integral is if it is large enough, and that the limit process is applied on the upper limit of the integral as it tends to infinity. The above setting and conditions (2)–(4) are intended to hold throughout this whole paper and in all of its statements.

A differential equation is called neutral if it contains the highest-order derivative of an unknown function both with and without delay. This means that the rate of growth depends on the current state and the state in the past, as well as on the rate of change in the past, which enables a suitable description for many real processes. For example, the process of



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Copyright: © 2021 by the authors. Licensee MDPI, Basel, Switzerland. This article is an open access article distributed under the terms and conditions of the Creative Commons Attribution (CC BY) license (https://creativecommons.org/licenses/by/4.0/). growth of a human population ([1]) or a population of *Daphnia magna* ([2]) can be modeled by neutral differential equations. Neutral Equation (1) is called half-linear, as its solution space is homogenous but not additive (it only has half of the linearity properties), and it can also be classified as Emden–Fowler equation. Neutral half-linear/Emden–Fowler equations arise in a variety of real-world problems, such as in the study of *p*-Laplace equations, non-Newtonian fluid theory, the turbulent flow of a polytrophic gas in a porous medium, and so forth (see, for example, [3–6]).

In recent years, the qualitative theory of Equation (1) has attracted considerable attention, and it has been studied under condition (4), for example, in [7–11] (see also the references therein). For the case where the integral in (4) converges, let us refer to [12,13]. If $b(t) \equiv 0$, then the studied equation becomes a delayed half-linear equation, and its oscillation results are provided, for example, in [14–20].

By a solution of (1), we mean a differentiable function x(t) that is eventually not identically equal to zero, such that $r(t)\Phi(z'(t))$ is differentiable and (1) holds for $t \ge t_0$. Equation (1) is said to be oscillatory if it does not have a solution that is eventually positive or negative.

In this paper, we formulate new oscillation criteria for Equation (1). One of them can be classified as a Hille–Nehari type statement. Our results are based on the modification of the Riccati technique. Instead of the usual Riccati inequality, we use the so-called modified Riccati inequality. The modified Riccati technique has been used in the theory of ordinary half-linear differential equations of the form

$$(r(t)\Phi(x'(t)))' + c(t)\Phi(x(t)) = 0,$$
(5)

and it has been revealed that it is a useful tool that can be regarded as a replacement of the missing half-linear version of the transformation formula known from the classical oscillation theory of linear equations. For the related results concerning this method, we refer to [21–23] and the references given therein. We point out that, within the same approach, Hille–Nehari-type criteria for (5) were last studied in [24]. In Ref. [18], the modified Riccati technique was extended and applied to half-linear differential equations with delay:

$$(r(t)\Phi(x'(t)))' + c(t)\Phi(x(\tau(t))) = 0.$$
(6)

Here, we show that the method can also be extended for neutral half-linear equations and used to derive some oscillation criteria for (1).

This paper is organized as follows. In the next section, we introduce the modified Riccati technique and formulate some preliminary results. In Section 3, we present our main results, the oscillation criteria for (1), and in the last section, we apply the results to a perturbed equation of the Euler type.

2. Preliminaries

We start with the properties of the eventually positive solutions of (1) that are ensured with condition (4). By the function Φ^{-1} , we mean the inverse function to Φ , i.e., $\Phi^{-1}(x) = |x|^{q-2}x$.

Lemma 1. Suppose that x(t) is a solution of (1) that is positive on $[t_0, \infty)$. Then, there exists $T > t_0$ such that

$$z(t) > 0, \quad z'(t) > 0, \quad (r(t)\Phi(z'(t)))' \le 0,$$
(7)

$$\frac{z'(\tau(t))}{z'(t)} \ge \Phi^{-1}\left(\frac{r(t)}{r(\tau(t))}\right) \tag{8}$$

and

$$(r(t)\Phi(z'(t)))' \le -c(t)\Phi[z(\tau(t))(1-b(\tau(t)))]$$
(9)

for $t \geq T$.

Proof. Condition (7) is a well-known statement and its proof can be found, e.g., in [7] (Lemma 3). Because $r(t)\Phi(z'(t))$ is non-increasing, we have

$$r(t)\Phi(z'(t)) \le r(\tau(t))\Phi(z'(\tau(t))),$$

which can be rearranged into (8). Now, we observe that $x(\sigma(\tau(t))) \le z(\sigma(\tau(t))) \le z(\tau(t))$ and, in view of (1),

$$0 = (r(t)\Phi(z'(t)))' + c(t)\Phi[z(\tau(t)) - b(\tau(t))x(\sigma(\tau(t)))]$$

$$\geq (r(t)\Phi(z'(t)))' + c(t)\Phi[z(\tau(t))(1 - b(\tau(t)))],$$

which implies (9). \Box

Grace et al. showed in [10] that, under some additional assumptions, condition (8) can be strengthened. Similarly to in [25], they considered the sequence

$$g_0(\varrho) := 1, \quad g_{n+1}(\varrho) := e^{\varrho g_n(\varrho)}, \quad n = 0, 1, 2, \dots,$$
 (10)

where ϱ is a positive constant. For $\varrho \in (0, \frac{1}{e}]$, the sequence is increasing and bounded above, and $\lim_{t\to\infty} g_n(\varrho) = g(\varrho) \in [1, e]$, where $g(\varrho)$ is a real root of the equation

$$g(\varrho) = e^{\varrho g(\varrho)}.$$
 (11)

With the use of this sequence and the notation

$$\begin{aligned} \mathcal{Q}(t) &:= \Phi(1 - b(\tau(t)))c(t), \quad \mathcal{R}(t) := \int_{t_1}^t r^{1-q}(s) \, ds, \\ \tilde{\mathcal{R}}(t) &:= \mathcal{R}(t) + \frac{1}{p-1} \int_{t_1}^t \mathcal{R}(s) \Phi(\mathcal{R}(\tau(s))) \mathcal{Q}(s) \, ds \end{aligned}$$

for $t \ge t_1$, where t_1 is large enough, Grace et al. proved the following lemma.

Lemma 2 ([10], Lemma 4). Assume that τ is strictly increasing, Equation (1) has a positive solution x(t) on $[t_0, \infty)$, and the condition

$$\int_{\tau(t)}^{t} \mathcal{Q}(s) \Phi(\tilde{\mathcal{R}}(s)) \, ds \ge \varrho \tag{12}$$

holds for some $\varrho > 0$ and a t that is large enough. Then,

$$\frac{z'(\tau(t))}{z'(t)} \ge \Phi^{-1}\left(\frac{g_n(\varrho)r(t)}{r(\tau(t))}\right)$$

for every *n* and *t* that are large enough, where $g_n(\varrho)$ is defined by (10).

Now, let us turn our attention to the Riccati technique. By our assumptions, conditions (2)–(4) hold, and we suppose that Equation (1) has an eventually positive solution x(t). Take

$$w(t) = r(t)\Phi\left(\frac{z'(t)}{z(\tau(t))}\right).$$
(13)

By a direct differentiation, we have

$$w'(t) = \frac{(r(t)\Phi(z'(t)))'}{\Phi(z(\tau(t)))} - (p-1)r(t)\tau'(t)\frac{\Phi(z'(t))z'(\tau(t))}{|z(\tau(t))|^p}$$

which, with the use of (9), gives

$$w'(t) \le -c(t)\Phi(1-b(\tau(t))) - (p-1)r^{1-q}(t)\tau'(t)\frac{z'(\tau(t))}{z'(t)}|w(t)|^{q}$$

Assuming that there exists a positive function f(t) (one possible choice is $\Phi^{-1}\left(\frac{r(t)}{r(\tau(t))}\right)$ by (8)) such that

$$\frac{z'(\tau(t))}{z'(t)} \ge f(t) > 0,$$
(14)

we obtain the Riccati-type inequality of the form

$$w'(t) \le -c(t)\Phi(1 - b(\tau(t))) - (p - 1)r^{1-q}(t)\tau'(t)f(t)|w(t)|^{q}.$$
(15)

Next, we introduce the modified Riccati technique. Let h(t) be a positive differentiable function, and put

$$G(t) = r(t)h(\tau(t))\Phi\left(\frac{h'(\tau(t))}{f(t)}\right).$$
(16)

Using the modified Riccati transformation

$$v(t) = h^{p}(\tau(t))w(t) - G(t),$$
(17)

we obtain the so-called modified Riccati inequality (18) that is derived in the next lemma.

Lemma 3. Suppose that Equation (1) has an eventually positive solution x(t) and w is defined by (13). Let f be a positive function satisfying (14), let h be a positive differentiable function, and let G be defined by (16). Then, the function v(t), given by (17), satisfies the inequality

$$v'(t) + C(t) + (p-1)r^{1-q}(t)\tau'(t)h^{-q}(\tau(t))f(t)H(v(t),G(t)) \le 0,$$
(18)

where

$$C(t) = h(\tau(t)) \left[\left(r(t)\Phi\left(\frac{h'(\tau(t))}{f(t)}\right) \right)' + c(t)\Phi(h(\tau(t)))\Phi(1-b(\tau(t))) \right]$$
(19)

and

$$H(v,G) = |v+G|^q - q\Phi^{-1}(G)v - |G|^q.$$
(20)

Proof. By a direct differentiation, we obtain

$$\begin{aligned} v'(t) &= ph^{p-1}(\tau(t))h'(\tau(t))\tau'(t)w(t) + h^p(\tau(t))w'(t) - G'(t) \\ &= ph'(\tau(t))\tau'(t)h^{-1}(\tau(t))(v(t) + G(t)) + h^p(\tau(t))w'(t) - G'(t), \end{aligned}$$

and with the use of (15), we have (suppressing the argument *t*)

$$\begin{aligned} v' &\leq ph'(\tau)\tau'h^{-1}(\tau)(v+G) - G' + h^{p}(\tau) \Big[-c\Phi(1-b(\tau)) - (p-1)r^{1-q}\tau'f|w|^{q} \Big] \\ &= ph'(\tau)\tau'h^{-1}(\tau)(v+G) - G' - h^{p}(\tau)c\Phi(1-b(\tau)) - (p-1)r^{1-q}\tau'h^{-q}(\tau)f|v+G|^{q} \\ &= -\tilde{C} - (p-1)r^{1-q}\tau'h^{-q}(\tau)f\Big[|v+G|^{q} - q\Phi^{-1}(G)v - |G|^{q} \Big], \end{aligned}$$

where

$$\begin{split} \tilde{C} &= -ph'(\tau)\tau'h^{-1}(\tau)(v+G) + G' + h^{p}(\tau)c\Phi(1-b(\tau)) \\ &+ (p-1)r^{1-q}\tau'h^{-q}(\tau)f\Big[q\Phi^{-1}(G)v + |G|^{q}\Big] \\ &= h^{p}(\tau)c\Phi(1-b(\tau)) + G' - ph'(\tau)\tau'h^{-1}(\tau)v - ph'(\tau)\tau'h^{-1}(\tau)rh(\tau)\Phi\bigg(\frac{h'(\tau)}{f}\bigg) \\ &+ pr^{1-q}\tau'h^{-q}(\tau)fr^{q-1}h^{q-1}(\tau)\frac{h'(\tau)}{f}v + (p-1)r^{1-q}\tau'h^{-q}(\tau)fr^{q}h^{q}(\tau)\frac{|h'(\tau)|^{p}}{f^{p}} \\ &= h^{p}(\tau)c\Phi(1-b(\tau)) + G' - r|h'(\tau)|^{p}\tau'f^{1-p}. \end{split}$$

Since

$$G'(t) = \left(r(t)\Phi\left(\frac{h'(\tau(t))}{f(t)}\right) \right)' h(\tau(t)) + r(t)|h'(\tau(t))|^p \tau'(t) f^{1-p}(t),$$

we have

$$\tilde{C}(t) = h^p(\tau(t))c(t)\Phi(1 - b(\tau(t))) + \left(r(t)\Phi\left(\frac{h'(\tau(t))}{f(t)}\right)\right)'h(\tau(t))$$
$$= h(\tau(t))\left[\left(r(t)\Phi\left(\frac{h'(\tau(t))}{f(t)}\right)\right)' + c(t)\Phi(h(\tau(t)))\Phi(1 - b(\tau(t)))\right].$$

Hence, $\tilde{C}(t) = C(t)$ and the lemma is proved. \Box

Similarly to in [18], we have the following two statements. In the first one, we formulate estimates for the function H(v, G) from (20). Note that by applying these estimates in (18), we obtain an inequality that is, in fact, the Riccati inequality associated with a certain ordinary linear equation. The second statement gives sufficient conditions for the eventual non-negativity of the solutions to (18). By studying the proof of the original statement in [18], one can easily see that it also holds for the neutral version of the modified Riccati inequality (18).

Lemma 4 ([21], Lemma 5 and Lemma 6). *The function* H(v, G) *defined by* (20) *is non-negative* and H(v, G) = 0 if and only if v = 0. Furthermore, if $\liminf_{t\to\infty} |G(t)| > 0$ and $v(t) \to 0$ for $t \to \infty$, then

$$H(v(t), G(t)) = \frac{q(q-1)}{2} |G(t)|^{q-2} v^2(t)(1+o(1)), \quad \text{as } t \to \infty.$$

Finally, for every T > 0, there exists a constant K > 0 such that

$$H(v(t), G(t)) \ge K|G(t)|^{q-2}v^2(t)$$

for any t and v satisfying $|v(t)/G(t)| \leq T$.

Lemma 5 ([18], Lemma 2.5). Let *h* be a positive continuously differentiable function such that $h' \neq 0$ for large t and $C(t) \ge 0$ for large t. Moreover, let either

$$\limsup_{t \to \infty} |G(t)| < \infty \tag{21}$$

and

$$\int^{\infty} \frac{f(t)\tau'(t)}{r^{q-1}(t)h^q(\tau(t))} dt = \infty$$
(22)

$$\lim_{t \to \infty} |G(t)| = \infty \tag{23}$$

and

$$\int^{\infty} \frac{\Phi(f(t))\tau'(t)}{r(t)h^{2}(\tau(t))|h'(\tau(t))|^{p-2}} dt = \infty.$$
(24)

Then, all possible proper solutions (i.e., solutions that exist in a neighborhood of infinity) of (18) *are eventually nonnegative.*

3. Main Results

Theorem 1. Let *f* be a positive function, let *G* and *H* be defined by (16) and (20), respectively, and let the conditions of Lemma 5 be satisfied. If

$$\int^{\infty} C(t) \, dt = \infty, \tag{25}$$

then Equation (1) is either oscillatory or, in every neighborhood of ∞ , there exists t^* such that $\frac{z'(\tau(t^*))}{z'(t^*)f(t^*)} < 1$ for all solutions of (1).

Proof. Suppose, by a contradiction, that there exists $T \ge t_0$ such that (1) has a solution x(t) that is positive for $t \in [T, \infty)$, and condition (14) holds on this interval. Then, v(t) defined by (17) satisfies (18), and hence,

$$v'(t) \le -C(t) - (p-1)r^{1-q}(t)\tau'(t)h^{-q}(\tau(t))f(t)H(v(t),G(t))$$

Integrating the inequality from $t_1 \ge T$ to t, we get

$$v(t) \le v(t_1) - \int_{t_1}^t C(s) \, ds - (p-1) \int_{t_1}^t r^{1-q}(s) \tau'(s) h^{-q}(\tau(s)) f(s) H(v(s), G(s)) \, ds.$$

Since the last subtracted term is nonnegative, we have

$$v(t) \le v(t_1) - \int_{t_1}^t C(s) \, ds$$

and letting $t \to \infty$, we are led to a contradiction with non-negativity of v(t) by Lemma 5. \Box

Denote

$$R(t) = r(t)\frac{1}{\tau'(t)}h^2(\tau(t))|h'(\tau(t))|^{p-2}f^{1-p}(t).$$
(26)

Under the assumptions of the paper, according to (8), we can take $f(t) = \Phi^{-1}\left(\frac{r(t)}{r(\tau(t))}\right)$ and the functions *G*, *C*, and *R* to get the following form:

.

$$G_{1}(t) = r(\tau(t))h(\tau(t))\Phi(h'(\tau(t))),$$

$$C_{1}(t) = h(\tau(t))[(r(\tau(t))\Phi(h'(\tau(t))))' + c(t)\Phi(h(\tau(t)))\Phi(1 - b(\tau(t)))],$$

$$R_{1}(t) = r(\tau(t))\frac{1}{\tau'(t)}h^{2}(\tau(t))|h'(\tau(t))|^{p-2}.$$

In this special case of the function f, we can formulate a version of Theorem 1 as follows.

Corollary 1. Let h be a positive continuously differentiable function such that $h' \neq 0$ for large t and $C_1(t) \ge 0$ for large t. Moreover, let either

$$\limsup_{t \to \infty} |G_1(t)| < \infty \quad and \quad \int^{\infty} \frac{\tau'(t)}{r^{q-1}(\tau(t))h^q(\tau(t))} \, dt = \infty$$
(27)

or

$$\lim_{t\to\infty}|G_1(t)|=\infty \quad and \quad \int^{\infty}R_1^{-1}(t)\,dt=\infty.$$

$$\int^{\infty} C_1(t) \, dt = \infty, \tag{28}$$

then Equation (1) *is oscillatory.*

The second and last theorem is of the Hille–Nehari type and concerns the case where the integral in (25) is convergent. We present a version with the general function f, and G, C, and R are given by (16), (19), and (26); however, one can also formulate the special case of the theorem with the function $f(t) = \Phi^{-1}\left(\frac{r(t)}{r(\tau(t))}\right)$ and G_1 , C_1 , and R_1 , similarly to in Corollary 1. Recall that the same types of results for half-linear Equation (5) were proved in [26], and for delayed half-linear Equation (6), comparison theorems providing qualitatively similar results were presented in [18].

Theorem 2. Let *h* be a positive continuously differentiable function such that $h' \neq 0$ for large *t* and let *f* be a positive function such that $C(t) \geq 0$ for large *t*, $\int_{\infty}^{\infty} R^{-1}(t) dt = \infty$, $\liminf_{t \to \infty} G(t) > 0$, and

$$\limsup_{t \to \infty} G(t) < \infty \quad or \quad \lim_{t \to \infty} G(t) = \infty.$$
⁽²⁹⁾

Suppose that $\int_{0}^{\infty} C(t) dt < \infty$. If

$$\liminf_{t \to \infty} \int^t R^{-1}(s) \, ds \int_t^\infty C(s) \, ds > \frac{1}{2q},\tag{30}$$

then Equation (1) is either oscillatory or in every neighborhood of ∞ , there exists t^* such that $\frac{z'(\tau(t^*))}{z'(t^*)f(t^*)} < 1$ for all solutions of (1).

Proof. Suppose, by a contradiction, that there exists $T \ge t_0$ such that (1) has a solution x(t) that is positive for $t \in [T, \infty)$, and condition (14) holds on this interval. All conditions of Lemma 5 are satisfied. Indeed, conditions (21) and (23) are given in (29), condition (24) is, in fact, $\int^{\infty} R^{-1}(t) dt = \infty$, and (22) can be written in the form $\int^{\infty} R^{-1}(t) |G(t)|^{2-q} dt = \infty$; this follows from (24) and the fact that $0 < \liminf_{t \to \infty} |G(t)| \le \limsup_{t \to \infty} |G(t)| < \infty$. With respect to Lemma 5, the function v(t) defined by (17) is eventually non-negative. We show that

 $\lim_{t\to\infty} v(t) = 0$. It follows from (18) that $v'(t) \le 0$; hence, the limit exists and is non-negative and finite. Integrating (18) from T_1 to t ($T_1 \ge T$) yields

$$v(T_1) - v(t) \ge \int_{T_1}^t C(s) \, ds + (p-1) \int_{T_1}^t r^{1-q}(s) \tau'(s) h^{-q}(\tau(s)) f(s) H(v(s), G(s)) \, ds.$$

Since $v(t) \ge 0$, we have

$$v(T_1) \ge \int_{T_1}^t C(s) \, ds + (p-1) \int_{T_1}^t r^{1-q}(s) \tau'(s) h^{-q}(\tau(s)) f(s) H(v(s), G(s)) \, ds.$$

Both the integrals in the inequality are non-negative, and letting $t \to \infty$, we see that the integral

$$\int_{T_1}^t r^{1-q}(s)\tau'(s)h^{-q}(\tau(s))f(s)H(v(s),G(s))\,ds$$

is convergent. With respect to conditions $\liminf_{t\to\infty} G(t) > 0$ and $\lim_{t\to\infty} v(t) < \infty$, there exists a positive constant M and $T_2 \ge T_1$ such that $|\frac{v(t)}{G(t)}| < M$ for $t \ge T_2$. According to Lemma 4, there exists K > 0 such that

$$K|G(t)|^{q-2}v^2(t) \le H(v(t), G(t)) \text{ for } t \ge T_2.$$

If

Since $R(t)|G(t)|^{q-2} = \frac{r^{q-1}(t)h^q(\tau(t))}{\tau'(t)f(t)}$, we have

$$K\frac{v^{2}(t)}{R(t)} \leq r^{1-q}(t)\tau'(t)h^{-q}(\tau(t))f(t)H(v(t),G(t)) \quad \text{for } t \geq T_{2}.$$

Integrating the last inequality from T_3 to t ($T_3 \ge T_2$) and letting $t \to \infty$, we obtain

$$K\int_{T_3}^{\infty} \frac{v^2(t)}{R(t)} dt \le \int_{T_3}^{\infty} r^{1-q}(t)\tau'(t)h^{-q}(\tau(t))f(t)H(v(t),G(t)) dt < \infty.$$

As $\int_{-\infty}^{\infty} R^{-1}(t) dt = \infty$, the last inequality implies that $\lim_{t \to \infty} v(t) = 0$. Now, we integrate (18) from t to ∞ to obtain

$$v(t) \ge \int_t^\infty C(s) \, ds + (p-1) \int_t^\infty r^{1-q}(s) \tau'(s) h^{-q}(\tau(s)) f(s) H(v(s), G(s)) \, ds.$$

Let $\varepsilon > 0$. According to Lemma 4, there exists a T_4 large enough such that

$$H(v(t), G(t)) \ge \left(\frac{q(q-1)}{2} - \varepsilon\right) v^2(t) |G(t)|^{q-2}$$

= $\left(\frac{q(q-1)}{2} - \varepsilon\right) r^{q-2}(t) h^{q-2}(\tau(t)) |h'(\tau(t))|^{2-p} f^{p-2}(t) v^2(t)$

for $t \geq T_4$. Hence,

$$v(t) \ge \int_t^\infty C(s) \, ds + (p-1) \left(\frac{q(q-1)}{2} - \varepsilon\right) \int_t^\infty \frac{v^2(s)}{R(s)} \, ds$$

for $t \ge T_4$. Denoting $\tilde{\varepsilon} = (p-1)\varepsilon$, the inequality becomes

$$v(t) \ge \int_t^\infty C(s) \, ds + \left(\frac{q}{2} - \tilde{\varepsilon}\right) \int_t^\infty R^{-1}(s) v^2(s) \, ds$$

and multiplication by $\mathcal{R}(t) = \int^t R^{-1}(s) \, ds$ gives

$$\mathcal{R}(t)v(t) \ge \mathcal{R}(t)\int_{t}^{\infty} C(s)\,ds + \left(\frac{q}{2} - \tilde{\varepsilon}\right)\mathcal{R}(t)\int_{t}^{\infty}\frac{R^{-1}(s)}{\mathcal{R}^{2}(s)}(\mathcal{R}(s)v(s))^{2}\,ds.$$
(31)

With respect to (30), there exists $\delta > 0$ such that $\liminf_{t \to \infty} \mathcal{R}(t) \int_t^{\infty} \mathcal{C}(s) ds \geq \frac{1}{2q} + \delta$. Furthermore, we observe that $\mathcal{R}(t) \int_t^{\infty} \frac{\mathcal{R}^{-1}(s)}{\mathcal{R}^2(s)} ds = 1$. There are two possible options: either $\liminf_{t \to \infty} \mathcal{R}(t)v(t) < \infty$ or $\liminf_{t \to \infty} \mathcal{R}(t)v(t) = \infty$. Let us discuss both cases.

(a) Suppose that $\liminf_{t\to\infty} \mathcal{R}(t)v(t) := L < \infty$. From (31), one can see that L > 0. For every $\bar{\varepsilon} > 0$, there exists a T_5 large enough so that $(\mathcal{R}(t)v(t))^2 > (1-\bar{\varepsilon})^2 L^2$ for $t \ge T_5$. Estimations of the terms in (31) give

$$(1+\overline{\varepsilon})L \ge rac{1}{2q} + \delta + \Big(rac{q}{2} - \widetilde{\varepsilon}\Big)(1-\overline{\varepsilon})^2 L^2.$$

Letting $\tilde{\varepsilon}, \bar{\varepsilon} \to 0$ gives a contradiction, since then,

$$L \ge \frac{1}{2q} + \delta + \frac{q}{2}L^2 \Leftrightarrow \frac{q}{2}\left(L - \frac{1}{q}\right)^2 + \delta \le 0.$$

(b) In the case where $\liminf_{t\to\infty} \mathcal{R}(t)v(t) = \infty$, we denote $m(t) = \inf_{t\leq s} \{\mathcal{R}(s)v(s)\}$. Then, from (31), it follows that

$$\mathcal{R}(t)v(t) \ge \frac{1}{2q} + \delta + \left(\frac{q}{2} - \tilde{\varepsilon}\right)m^2(t)$$

Since the function *m* is nondecreasing, we have for $s \ge t$:

$$\mathcal{R}(s)v(s) \ge \frac{1}{2q} + \delta + \left(\frac{q}{2} - \tilde{\varepsilon}\right)m^2(s) \ge \frac{1}{2q} + \delta + \left(\frac{q}{2} - \tilde{\varepsilon}\right)m^2(t),$$

and hence,

$$m(t) \ge \frac{1}{2q} + \delta + \left(\frac{q}{2} - \tilde{\varepsilon}\right)m^2(t) > \left(\frac{q}{2} - \tilde{\varepsilon}\right)m^2(t),$$

which gives a contradiction with the assumption $\liminf_{t\to\infty} \mathcal{R}(t)v(t) = \infty$.

The proof is finished. \Box

4. Examples

Consider the Euler-type equation

$$(\Phi(x(t) + b_0 x(\sigma(t)))')' + \frac{\gamma}{t^p} \Phi(x(\lambda t)) = 0,$$
(32)

where $\lambda \in (0, 1)$, $\sigma(t) \leq t$, $\lim_{t \to \infty} \sigma(t) = \infty$, and $b_0 \in [0, 1)$. Equation (32) is of the form (1), where r(t) = 1, $c(t) = \frac{\gamma}{t^p}$, $\tau(t) = \lambda t$, and $b(t) = b_0$.

Example 1. Take $h(t) = t^{\frac{p-1}{p}}$; then, by a direct computation, we have

$$G_1(t) = \left(\frac{p-1}{p}\right)^{p-1}, \quad R_1(t) = \left(\frac{p-1}{p}\right)^{p-2}t$$
 (33)

and

$$\int^{\infty} \frac{\tau'(t)}{r^{q-1}(\tau(t))h^q(\tau(t))} dt = \int^{\infty} \frac{1}{t} dt \to \infty.$$

Hence, condition (27) is satisfied. Furthermore, we have

$$C_{1}(t) = (\lambda t)^{\frac{p-1}{p}} \left[\left(\left(\frac{p-1}{p} \right)^{p-1} (\lambda t)^{\frac{1-p}{p}} \right)' + c(t) \Phi(1-b_{0}) \left((\lambda t)^{\frac{p-1}{p}} \right)^{p-1} \right]$$

$$= (\lambda t)^{\frac{p-1}{p}} \left[-\left(\frac{p-1}{p} \right)^{p} \lambda^{\frac{1}{p}-1} t^{\frac{1}{p}-2} + c(t) \Phi(1-b_{0}) (\lambda t)^{p-2+\frac{1}{p}} \right]$$

$$= t^{-1} \left[-\left(\frac{p-1}{p} \right)^{p} + c(t) \Phi(1-b_{0}) \lambda^{p-1} t^{p} \right]$$

$$= t^{-1} \left[-\left(\frac{p-1}{p} \right)^{p} + \gamma \Phi(1-b_{0}) \lambda^{p-1} \right].$$
 (34)

The positivity of the expression $-\left(\frac{p-1}{p}\right)^p + \gamma \Phi(1-b_0)\lambda^{p-1}$ *implies* (28). *So, by Corollary* 1, *Equation* (32) *is oscillatory if*

$$\gamma > \left(\frac{p-1}{p}\right)^p \frac{1}{\lambda^{p-1}\Phi(1-b_0)}.$$
(35)

This corresponds to the result known in the case where $b_0 = 0$ (equations with delay, see [18]) and also with the case where $b_0 = 0$ and $\lambda = 1$ (ordinary equations).

Example 2. Condition (35) can even be strengthened for a class of Equation (32), which satisfies (12) with $\varrho \in (0, \frac{1}{e})$. By a direct computation (or see [10]), one can show that for (32),

$$\varrho = (1 - b_0)^{p-1} \gamma \lambda^{p-1} \left(1 + \frac{1}{p-1} \lambda^{p-1} (1 - b_0)^{p-1} \gamma \right)^{p-1} \log\left(\frac{1}{p-1}\right).$$

Note that here and in what follows, the symbol log stands for the natural logarithm. If $\varrho \in (0, \frac{1}{e})$, according to Lemma 2, we can use in place of the positive function f(t) from (14) the function $\Phi^{-1}\left(\frac{g(\varrho)r(t)}{r(\tau(t))}\right)$, where $g(\varrho)$ is defined by (11). Then, functions R, G, and C become

$$\begin{aligned} G_2(t) &= r(\tau(t))h(\tau(t))\Phi(h'(\tau(t)))(g(\varrho))^{-1}, \\ C_2(t) &= h(\tau(t)) \left[\left(r(\tau(t)) \frac{\Phi(h'(\tau(t)))}{g(\varrho)} \right)' + c(t)\Phi(h(\tau(t)))\Phi(1-b_0) \right], \\ R_2(t) &= r(\tau(t)) \frac{1}{\tau'(t)} h^2(\tau(t)) |h'(\tau(t))|^{p-2} (g(\varrho))^{-1}. \end{aligned}$$

In our setting for Equation (32) and again with $h(t) = t^{\frac{p-1}{p}}$, these read as

$$G_2(t) = \left(\frac{p-1}{p}\right)^{p-1} (g(\varrho))^{-1}, \quad R_1(t) = \left(\frac{p-1}{p}\right)^{p-2} (g(\varrho))^{-1} t$$

and

$$C_2(t) = t^{-1} \left[-\left(\frac{p-1}{p}\right)^p (g(\varrho))^{-1} + \gamma \Phi(1-b_0)\lambda^{p-1} \right].$$

Since (21) and (22) hold and (25) is implied by the positivity of the expression

$$\left[-\left(\frac{p-1}{p}\right)^p(g(\varrho))^{-1}+\gamma\Phi(1-b_0)\lambda^{p-1}\right],$$

Equation (32) is oscillatory, according to Theorem 1, provided that

$$\gamma > \left(\frac{p-1}{p}\right)^p \frac{1}{(g(\varrho))\lambda^{p-1}\Phi(1-b_0)}.$$

This corresponds to the condition derived in [10].

In the theory of ordinary equations, i.e., in the case where $\lambda = 1$ and $b_0 = 0$ in (32), it is known that Equation (32) oscillates if and only if (35) holds. This means that the constant $\gamma = \left(\frac{p-1}{p}\right)^p$ is the critical constant between oscillation and non-oscillation of (32), and it is natural to study perturbations of the Euler-type equation with this critical constant and to find critical constants in the added terms. This corresponds to the concept of conditional oscillation (for details, see [23,27] and the references given therein). In the case of the delayed and neutral equations, there is not such a boundary between oscillation and nonoscillation of (32). However, based on the results known from the ordinary case, let us study the neutral version of the Euler–Weber-type equation

$$(\Phi(x(t) + b_0 x(\sigma(t)))')' + \left(\frac{\left(\frac{p-1}{p}\right)^p}{\lambda^{p-1}\Phi(1-b_0)t^p} + \frac{\mu}{t^p \log^2 t}\right) \Phi(x(\lambda(t)) = 0.$$
(36)

Example 3. For (36), we use Theorem 2 with $f(t) = \Phi^{-1}\left(\frac{r(t)}{r(\tau(t))}\right)$. Similarly to in Example 1, we take $h(t) = t^{\frac{p-1}{p}}$, we obtain (33), and, with the use of the relevant coefficient function c(t) in (34), we have

$$C_1(t) = \frac{\mu}{t \log^2 t} \Phi(1 - b_0) \lambda^{p-1}$$

and

$$\int_{t}^{\infty} C_{1}(s) \, ds = \int_{t}^{\infty} \frac{\mu \Phi(1-b_{0})\lambda^{p-1}}{s \log^{2} s} \, ds = \frac{\mu \Phi(1-b_{0})\lambda^{p-1}}{\log t}$$

Since $R_1^{-1} = \left(\frac{p}{p-1}\right)^{p-2} \frac{1}{t}$, condition (30) becomes

$$\left(\frac{p}{p-1}\right)^{p-2}\mu\Phi(1-b_0)\lambda^{p-1} > \frac{1}{2q}$$

which, by Theorem 2, implies that Equation (36) is oscillatory if

$$\mu > \frac{1}{2\Phi(1-b_0)\lambda^{p-1}} \left(\frac{p-1}{p}\right)^{p-1}.$$
(37)

Note that in the ordinary case where $\lambda = 1$ and $b_0 = 0$, the constant from (37) is critical, which means that (36) is oscillatory if and only if $\mu > \frac{1}{2} \left(\frac{p-1}{p}\right)^{p-1}$.

Example 4. Let us consider the perturbation of the Euler–Weber equation. Take $h(t) = t^{\frac{p-1}{p}} \log^{\frac{1}{p}} t$ and consider Equation (1) with r(t) = 1, $\tau(t) = \lambda t$, and b(t) = 0. Observe that

$$h'(t) = \frac{p-1}{p} t^{-\frac{1}{p}} \log^{\frac{1}{p}} t \left[1 + \frac{1}{(p-1)\log t} \right].$$

By a direct computation, we see that

$$G_{1}(t) = \left(\frac{p-1}{p}\right)^{p-1} \log(\lambda t)(1+o(1)),$$

$$R_{1}(t) = \left(\frac{p-1}{p}\right)^{p-2} t \log(\lambda t)(1+o(1))$$

as $t \to \infty$ *. With the use of the power expansion formula*

$$(1+x)^s = 1 + sx + \frac{s(s-1)}{2}x^2 + \frac{s(s-1)(s-2)}{6}x^3 + o(x^3) \quad as \quad x \to 0,$$

one can show that for

$$c(t) = \left(\frac{p}{p-1}\right)^{p} \frac{1}{\lambda^{p-1}t^{p}} + \frac{1}{2} \left(\frac{p}{p-1}\right)^{p-1} \frac{1}{\lambda^{p-1}t^{p} \log^{2}(\lambda t)} + \frac{\mu}{t^{p} \log^{2}(\lambda t) \log^{2}(\log(\lambda t))}$$

we have

$$C_1(t) = \frac{\mu \lambda^{p-1}}{t \log(\lambda t) \log^2(\log(\lambda t))} (1 + o(1)) \quad \text{as } t \to \infty$$

Because

$$\int R_1^{-1}(t) \, dt \sim \left(\frac{p-1}{p}\right)^{2-p} \log(\log(\lambda t))$$

and

$$\int C_1(t) \, dt \sim -\frac{\mu \lambda^{p-1}}{\log(\log(\lambda t))},$$

condition (30) becomes

$$\left(\frac{p-1}{p}\right)^{2-p}\mu\lambda^{p-1} > \frac{1}{2q}.$$

Since $\frac{1}{q} = \frac{p-1}{p}$, the considered equation is oscillatory if

$$\mu > \frac{1}{2} \left(\frac{p-1}{p}\right)^{p-1} \frac{1}{\lambda^{p-1}}.$$

5. Conclusions

The aim of this paper was to study how the modified Riccati technique can be applied to Equation (1), which has not been tried for neutral equations before, and what results this approach can provide. According to our results, the modified Riccati method is applicable to Equation (1), and it can be used to find new criteria, for whose proofs it is enough to manipulate the modified Riccati inequality. We have presented two new oscillation criteria and illustrated their uses in examples dealing with a half-linear Euler-type equation and its perturbations.

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