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# NON-NEGATIVE STEADY STATE SOLUTIONS TO AN ELLIPTIC BIOLOGICAL MODEL 

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#### Abstract

The non-existence and existence of positive solutions for the generalized predator-prey biological model for two species of animals $$
\begin{aligned} & \Delta u+u g(u, v)=0 \text { in } \Omega, \\ & \Delta v+v h(u, v)=0 \text { in } \Omega, \\ & u=v=0 \text { on } \partial \Omega, \end{aligned}
$$ is investigated in this paper. The techniques used in this paper are from elliptic theory, the upper-lower solution method, the maximum principles and spectrum estimates. The arguments also rely on detailed properties of solutions to logistic equations.

AMS Subject Classification: 78A70, 90B06 Key Words: non-existence and existence of positive solutions, generalized predator-prey biological model, logistic equations, maximum principles


## 1. Introduction

A lot of research has been focused on reaction-diffusion equations modeling the elliptic steady state solutions of predator-prey interacting processes with
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Dirichlet boundary conditions. Our knowledge about the existence of positive solutions is limited to rather specific systems, whose relative growth rates are linear;

$$
\begin{aligned}
& \Delta u+u(a-b u-c v)=0 \text { in } \Omega, \\
& \Delta v+v(d+e u-f v)=0 \text { in } \Omega, \\
& u=v=0 \text { on } \partial \Omega,
\end{aligned}
$$

where $\Omega$ is a bounded domain in $R^{N}$ with smooth boundary $\partial \Omega$, and where $a, d>0$ are reproduction rates, $b, f>0$ are self-limitation rates and $c, e>0$ are competition rates.

The question in this paper concerns the existence of positive coexistence when all the reproduction, self-limitation and competition rates are nonlinear and combined, more precisely, the existence of the positive steady state of

$$
\begin{aligned}
& \Delta u+u g(u, v)=0 \text { in } \Omega, \\
& \Delta v+v h(u, v)=0 \text { in } \Omega, \\
& u=v=0 \text { on } \partial \Omega
\end{aligned}
$$

where $\Omega$ is a bounded domain in $R^{N}$ with smooth boundary $\partial \Omega$, and where $g, h \in C^{1}$ are such that $g_{u}<0, g_{v}<0, h_{v}<0, h_{u}>0, g(0,0)>0, h(0,0)>0$, and there exists $c_{0}>0$ such that $g(u, 0) \leq 0$ and $h(0, v) \leq 0$ for $u, v \geq c_{0}$. Also, note that we assume $h_{u}, h_{v}$ and $g_{v}$ are functions that are bounded above.

In Section 3, we provide the coexistence region of the reproduction rates $(g(0,0), h(0,0))$ by virtue of Maximum Principles, upper-lower solutions method and the properties of the logistic equation.

## 2. Preliminaries

In this section, we state some preliminary results which will be useful for our later arguments.

Definition 2.1. (Upper and Lower Solutions)

$$
\left\{\begin{array}{l}
\Delta u+f(x, u)=0 \text { in } \Omega,  \tag{1}\\
\left.u\right|_{\partial \Omega}=0
\end{array}\right.
$$

where $f \in C^{\alpha}(\bar{\Omega} \times R)$ and $\Omega$ is a bounded domain in $R^{n}$.
(A) A function $\bar{u} \in C^{2, \alpha}(\bar{\Omega})$ satisfying

$$
\left\{\begin{array}{l}
\Delta \bar{u}+f(x, \bar{u}) \leq 0 \text { in } \Omega, \\
\left.\bar{u}\right|_{\partial \Omega} \geq 0,
\end{array}\right.
$$

is called an upper solution to (3).
(B) A function $\underline{u} \in C^{2, \alpha}(\bar{\Omega})$ satisfying

$$
\left\{\begin{array}{l}
\Delta \underline{u}+f(x, \underline{u}) \geq 0 \text { in } \Omega, \\
\underline{u} \mid \partial \Omega \leq 0,
\end{array}\right.
$$

is called a lower solution to (3).
Lemma 2.1. Let $f(x, \xi) \in C^{\alpha}(\bar{\Omega} \times R)$ and let $\bar{u}, \underline{u} \in C^{2, \alpha}(\bar{\Omega})$ be respectively, upper and lower solutions to (3) which satisfy $\underline{u}(x) \leq \bar{u}(x), x \in \bar{\Omega}$. Then (3) has a solution $u \in C^{2, \alpha}(\bar{\Omega})$ with $\underline{u}(x) \leq u(x) \leq \bar{u}(x), x \in \bar{\Omega}$.

Lemma 2.2. (The First Eigenvalue)

$$
\left\{\begin{array}{l}
-\Delta u+q(x) u=\lambda u \text { in } \Omega,  \tag{2}\\
\left.u\right|_{\partial \Omega}=0,
\end{array}\right.
$$

where $q(x)$ is a smooth function from $\Omega$ to $R$ and $\Omega$ is a bounded domain in $R^{n}$.
(A) The first eigenvalue $\lambda_{1}(q)$, denoted by simply $\lambda_{1}$ when $q \equiv 0$, is simple with a positive eigenfunction $\phi_{1}$.
(B) If $q_{1}(x)<q_{2}(x)$ for all $x \in \Omega$, then $\lambda_{1}\left(q_{1}\right)<\lambda_{1}\left(q_{2}\right)$.

Lemma 2.3. (Maximum Principles)

$$
L u=\sum_{i, j=1}^{n} a_{i j}(x) D_{i j} u+\sum_{i=1}^{n} a_{i}(x) D_{i} u+a(x) u=f(x) \text { in } \Omega,
$$

where $\Omega$ is a bounded domain in $R^{n}$.
(M1) $\partial \Omega \in C^{2, \alpha}(0<\alpha<1)$.
(M2) $\left|a_{i j}(x)\right|_{\alpha},\left|a_{i}(x)\right|_{\alpha},|a(x)|_{\alpha} \leq M(i, j=1, \ldots, n)$.
(M3) L is uniformly elliptic in $\bar{\Omega}$, with ellipticity constant $\gamma$, i.e., for every $x \in \bar{\Omega}$ and every real vector $\xi=\left(\xi_{1}, \ldots, \xi_{n}\right)$

$$
\sum_{i, j=1}^{n} a_{i j}(x) \xi_{i} \xi_{j} \geq \gamma \sum_{i=1}^{n}\left|\xi_{i}\right|^{2}
$$

Let $u \in C^{2}(\Omega) \cap C(\bar{\Omega})$ be a solution of $L u \geq 0(L u \leq 0)$ in $\Omega$.
(A) If $a(x) \equiv 0$, then $\max _{\bar{\Omega}} u=\max _{\partial \Omega} u\left(\min _{\bar{\Omega}} u=\min _{\partial \Omega} u\right)$.
(B) If $a(x) \leq 0$, then $\max _{\bar{\Omega}} u \leq \max _{\partial \Omega} u^{+}\left(\min _{\bar{\Omega}} u \geq-\max _{\partial \Omega} u^{-}\right)$, where $u^{+}=\max (u, 0), u^{-}=-\min (u, 0)$.
(C) If $a(x) \equiv 0$ and $u$ attains its maximum (minimum) at an interior point of $\Omega$, then $u$ is identically a constant in $\Omega$.
(D) If $a(x) \leq 0$ and $u$ attains a nonnegative maximum (nonpositive minimum) at an interior point of $\Omega$, then $u$ is identically a constant in $\Omega$.

Lemma 2.4. Let $g_{i}\left(u_{1}, u_{2}\right) \in C^{1}([0, \infty) \times[0, \infty))$ and suppose that there exists a positive constant $M$ such that for every $t \in[0,1]$, if $u=\left(u_{1}, u_{2}\right)$ is a non-negative solution of the problem

$$
\left\{\begin{array}{l}
-\Delta u_{1}=t g_{1}\left(u_{1}, u_{2}\right) \text { in } \Omega,  \tag{3}\\
-\Delta u_{2}=t g_{2}\left(u_{1}, u_{2}\right) \text { in } \Omega, \\
\left.u_{1}\right|_{\partial \Omega}=\left.u_{2}\right|_{\partial \Omega}=0,
\end{array}\right.
$$

then

$$
u_{1} \leq M, u_{2} \leq M .
$$

Assume that:
(1) Either $g_{1}(0,0)>\lambda_{1}, g_{2}(0,0) \neq \lambda_{1}$ or $g_{1}(0,0) \neq \lambda_{1}, g_{2}(0,0)>\lambda_{1}$,
$\left(g_{1}\right)_{u_{1}}\left(u_{1}, 0\right) \leq 0\left(u_{1} \geq 0\right),\left(g_{1}\right)_{u_{1}}\left(u_{1}, 0\right)$ is not identically zero $\left(u_{1} \in[0, b)\right)$,
$\left(g_{2}\right)_{u_{2}}\left(0, u_{2}\right) \leq 0\left(u_{2} \geq 0\right),\left(g_{2}\right)_{u_{2}}\left(0, u_{2}\right)$ is not identically zero $\left(u_{2} \in[0, b)\right)$, where $b$ is any fixed positive number,
(3) $\left(u_{1}^{*}, 0\right),\left(0, u_{2}^{*}\right)$ are any nontrivial non-negative solution with $\lambda_{1}\left(-g_{2}\left(u_{1}^{*}, 0\right)\right)$ $<0, \lambda_{1}\left(-g_{1}\left(0, u_{2}^{*}\right)\right)<0$.

Then there is a solution $u_{1}>0, u_{2}>0$ of (3) for $t=1$.
We also need some information on the solutions of the following logistic equations.

## Lemma 2.5.

$$
\left\{\begin{array}{l}
\Delta u+u f(u)=0 \text { in } \Omega, \\
\left.u\right|_{\partial \Omega}=0, u>0,
\end{array}\right.
$$

where $f$ is a decreasing $C^{1}$ function such that there exists $c_{0}>0$ such that $f(u) \leq 0$ for $u \geq c_{0}$ and $\Omega$ is a bounded domain in $R^{n}$.

If $f(0)>\lambda_{1}$, then the above equation has a unique positive solution, where $\lambda_{1}$ is the first eigenvalue of $-\Delta$ with homogeneous boundary condition. We denote this unique positive solution as $\theta_{f}$.

The main property about this positive solution is that $\theta_{f}$ is increasing as $f$ is increasing.

Especially, for $a>\lambda_{1}, b>0$, we denote $\theta \frac{a}{b}$ as the unique positive solution of

$$
\left\{\begin{array}{l}
\Delta u+u(a-b u)=0 \text { in } \Omega, \\
\left.u\right|_{\partial \Omega}=0, u>0 .
\end{array}\right.
$$

Hence, $\theta_{\frac{a}{b}}$ is increasing as $a>0$ is increasing.

## 3. Existence Region for Steady State

We consider

$$
\begin{align*}
& \Delta u+u g(u, v)=0 \text { in } \Omega \\
& \Delta v+v h(u, v)=0 \text { in } \Omega  \tag{4}\\
& u=v=0 \text { on } \partial \Omega
\end{align*}
$$

where $\Omega$ is a bounded domain in $R^{N}$ with smooth boundary $\partial \Omega, g, h \in C^{1}$ are such that $g_{u}<0, g_{v}<0, h_{v}<0, h_{u}>0, g(0,0)>0, h(0,0)>0$, and there exists $c_{0}>0$ such that $g(u, 0) \leq 0$ and $h(0, v) \leq 0$ for $u, v \geq c_{0}$. Note that we assume $h_{u}, h_{v}$ and $g_{v}$ are functions that are bounded above.

First, we see that the two species can not coexist when the reproduction capacities are not robust enough.

Theorem 3.1. Suppose $g(0,0) \leq \lambda_{1}, h(0,0) \leq \lambda_{1}$. Then $u=v \equiv 0$ is the only nonnegative solution to (4).

Proof. Let $(u, v)$ be a nonnegative solution to (4). By the Mean Value Theorem, there are $\tilde{u}, \tilde{v}$ such that

$$
g(u, v)-g(u, 0)=g_{v}(u, \tilde{v}) v, \quad h(u, v)-h(0, v)=h_{u}(\tilde{u}, v) u
$$

Hence, (4) implies that

$$
\begin{aligned}
\Delta u+u\left(g(u, 0)+g_{v}(u, \tilde{v}) v\right)=\Delta u+u(g(u, 0)+ & g(u, v)-g(u, 0)) \\
& =\Delta u+u g(u, v)=0 \text { in } \Omega
\end{aligned}
$$

$$
\begin{aligned}
& \Delta v+v\left(h(0, v)+h_{u}(\tilde{u}, v) u\right) \\
& \quad=\Delta v+v(h(0, v)+h(u, v)-h(0, v))=\Delta v+v h(u, v)=0 \text { in } \Omega
\end{aligned}
$$

Hence,

$$
\begin{aligned}
& \Delta u+u\left(g(u, 0)+\sup \left(g_{v}\right) v\right) \geq 0 \text { in } \Omega \\
& \Delta v+v\left(h(0, v)+\sup \left(h_{u}\right) u\right) \geq 0 \text { in } \Omega
\end{aligned}
$$

Therefore,

$$
\begin{aligned}
& \sup \left(h_{u}\right) \phi_{1} \Delta u+\sup \left(h_{u}\right) \phi_{1} u\left(g(u, 0)+\sup \left(g_{v}\right) v\right) \geq 0 \text { in } \Omega \\
& -\sup \left(g_{v}\right) \phi_{1} \Delta v-\sup \left(g_{v}\right) \phi_{1} v\left(h(0, v)+\sup \left(h_{u}\right) u\right) \geq 0 \text { in } \Omega
\end{aligned}
$$

So,

$$
\begin{aligned}
\int_{\Omega}-\sup \left(h_{u}\right) \phi_{1} \Delta u d x \leq \int_{\Omega}\left[g(u, 0) \sup \left(h_{u}\right) u+\sup \left(g_{v}\right) \sup \left(h_{u}\right) u v\right] \phi_{1} d x \\
\int_{\Omega} \sup \left(g_{v}\right) \phi_{1} \Delta v d x \leq \int_{\Omega}\left[-h(0, v) \sup \left(g_{v}\right) v-\sup \left(g_{v}\right) \sup \left(h_{u}\right) u v\right] \phi_{1} d x
\end{aligned}
$$

Hence, by Green's Identity, we have

$$
\begin{aligned}
& \int_{\Omega} \sup \left(h_{u}\right) \lambda_{1} \phi_{1} u d x \leq \int_{\Omega}\left[g(u, 0) \sup \left(h_{u}\right) u+\sup \left(g_{v}\right) \sup \left(h_{u}\right) u v\right] \phi_{1} d x \\
& \quad \int_{\Omega}-\sup \left(g_{v}\right) \lambda_{1} \phi_{1} v d x \leq \int_{\Omega}\left[-h(0, v) \sup \left(g_{v}\right) v-\sup \left(g_{v}\right) \sup \left(h_{u}\right) u v\right] \phi_{1} d x .
\end{aligned}
$$

Therefore,

$$
\int_{\Omega} \sup \left(h_{u}\right)\left(\lambda_{1}-g(u, 0)\right) u \phi_{1}-\sup \left(g_{v}\right)\left(\lambda_{1}-h(0, v)\right) v \phi_{1} d x \leq 0 .
$$

Since the left hand side is nonnegative from

$$
g(u, 0) \leq g(0,0) \leq \lambda_{1}, \quad h(0, v) \leq h(0,0) \leq \lambda_{1},
$$

we conclude that $u=v \equiv 0$.
Theorem 3.2. Let $u \geq 0, v \geq 0$ be a solution to (4). If $g(0,0) \leq \lambda_{1}$, then $u \equiv 0$.

Proof. Proceeding as in the proof of Theorem 3.1, we obtain

$$
0 \leq \int_{\Omega}\left(\lambda_{1}-g(u, 0)\right) u \phi_{1} d x \leq \int_{\Omega} \sup \left(g_{v}\right) v u \phi_{1} d x \leq 0
$$

and so, $u \equiv 0$.
Theorem 3.2 implies if $g(0,0) \leq \lambda_{1}$ and $h(0,0)>\lambda_{1}$, then all possible nonnegative solutions to $(4)$ are $(0,0)$ and $\left(0, \theta_{h(0, \cdot)}\right)$.

In order to prove further results, we will need the following lemma.
Lemma 3.3. Let $\tilde{u} \geq 0, \tilde{v} \geq 0$ be a solution of the problem

$$
\left\{\begin{array}{l}
-\Delta u=\operatorname{tug}(u, v) \text { in } \Omega,  \tag{5}\\
-\Delta v=\operatorname{tvh}(u, v) \text { in } \Omega, \\
u_{\partial \Omega}=v_{\partial \Omega}=0,
\end{array}\right.
$$

where $t \in[0,1]$. Then:
(1) $\tilde{u} \leq M_{1}, \tilde{v} \leq M_{2}$, where $M_{1}=-\frac{g(0,0)}{\sup \left(g_{u}\right)}, M_{2}=-\frac{h\left(M_{1}, 0\right)+h(0,0)}{\sup \left(h_{v}\right)}$.
(2) For $t=1$,

$$
\tilde{u} \leq \theta_{g(\cdot, 0)}, \tilde{v} \geq \theta_{h(0, \cdot)}
$$

if $\tilde{v}>0$ in $\Omega$.
Proof. (1) By the Mean Value Theorem and the monotonicity of $g$, we have

$$
g(\tilde{u}, \tilde{v})-g(0,0) \leq g(\tilde{u}, 0)-g(0,0) \leq \sup \left(g_{u}\right) \tilde{u},
$$

and so,

$$
\frac{g(\tilde{u}, \tilde{v})-g(0,0)}{\sup \left(g_{u}\right)} \geq \tilde{u} .
$$

Hence,

$$
\begin{aligned}
& \Delta\left(-\frac{g(0,0)}{\sup \left(g_{u}\right)}-\tilde{u}\right)+t\left(-\frac{g(0,0)}{\sup \left(g_{u}\right)}-\tilde{u}\right)(g(\tilde{u}, \tilde{v})-g(0,0)) \\
& \quad=-\Delta \tilde{u}-t \tilde{u}(g(\tilde{u}, \tilde{v})-g(0,0))-t \frac{g(0,0)}{\sup \left(g_{u}\right)}(g(\tilde{u}, \tilde{v})-g(0,0)) \\
& \quad=t \tilde{u} g(0,0)-t \frac{g(\tilde{u}, \tilde{v})-g(0,0)}{\sup \left(g_{u}\right)} g(0,0) \leq \operatorname{tg}(0,0) \tilde{u}-t g(0,0) \tilde{u}=0 .
\end{aligned}
$$

Since $g(\tilde{u}, \tilde{v})-g(0,0) \leq 0$, by the Maximum Principles, we conclude

$$
\tilde{u} \leq M_{1}=-\frac{g(0,0)}{\sup \left(g_{u}\right)}
$$

By the Mean Value Theorem, we have

$$
h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0) \leq \sup \left(h_{v}\right) \tilde{v}
$$

and so,

$$
\frac{h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0)}{\sup \left(h_{v}\right)} \geq \tilde{v} .
$$

Hence,

$$
\begin{aligned}
& \begin{array}{r}
\Delta\left(-\frac{h\left(M_{1}, 0\right)+h(0,0)}{\sup \left(h_{v}\right)}-\tilde{v}\right)+t\left(-\frac{h\left(M_{1}, 0\right)+h(0,0)}{\sup \left(h_{v}\right)}-\tilde{v}\right)(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0)) \\
=-\Delta \tilde{v}-t \tilde{v}(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0))
\end{array} \\
& \quad-t \frac{h\left(M_{1}, 0\right)(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0))}{\sup \left(h_{v}\right)}-t \frac{h(0,0)(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0))}{\sup \left(h_{v}\right)} \\
& =t \tilde{v} h(\tilde{u}, 0)-t \frac{h\left(M_{1}, 0\right)(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0))}{\sup \left(h_{v}\right)}-t \frac{h(0,0)(h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0))}{\sup \left(h_{v}\right)} \leq 0 .
\end{aligned}
$$

Since $h(\tilde{u}, \tilde{v})-h(\tilde{u}, 0) \leq 0$, by the Maximum Principles, we conclude

$$
\tilde{v} \leq M_{2}=-\frac{h\left(M_{1}, 0\right)+h(0,0)}{\sup \left(h_{v}\right)} .
$$

(2) If $g(0,0) \leq \lambda_{1}$, then by Theorem 3.2, $\tilde{u} \equiv 0$ and so obviously $\tilde{u} \leq \theta_{g(\cdot, 0)}$.

Suppose $g(0,0)>\lambda_{1}$. Since

$$
\left\{\begin{array}{l}
\Delta \tilde{u}+\tilde{u} g(\tilde{u}, 0)=-\tilde{u}(g(\tilde{u}, \tilde{v})-g(\tilde{u}, 0)) \geq 0 \text { in } \Omega, \\
\left.\tilde{u}\right|_{\partial \Omega}=0
\end{array}\right.
$$

$\tilde{u}$ is a lower solution to

$$
\left\{\begin{array}{l}
\Delta u+u g(u, 0)=0 \text { in } \Omega, \\
\left.u\right|_{\partial \Omega}=0 .
\end{array}\right.
$$

We can take large enough $M$ such that $M>\tilde{u}$ on $\bar{\Omega}$ and $u=M$ is an upper solution to

$$
\left\{\begin{array}{l}
\Delta u+u g(u, 0)=0 \text { in } \Omega, \\
\left.u\right|_{\partial \Omega}=0 .
\end{array}\right.
$$

Since

$$
\left\{\begin{array}{l}
\Delta u+u g(u, 0)=0 \text { in } \Omega, \\
\left.u\right|_{\partial \Omega}=0,
\end{array}\right.
$$

has a unique positive solution $\theta_{g(\cdot, 0)}$, by the upper-lower solution method, we conclude $\tilde{u} \leq \theta_{g(\cdot, 0)}$ in $\Omega$.

If $h(0,0) \leq \lambda_{1}$, then since $\theta_{h(0, \cdot)}=0$, obviously $\tilde{v} \geq \theta_{h(0, \cdot)}$.
Suppose $h(0,0)>\lambda_{1}$. Since

$$
\left\{\begin{array}{l}
\Delta \tilde{v}+\tilde{v} h(0, \tilde{v})=-\tilde{v}(h(\tilde{u}, \tilde{v})-h(0, \tilde{v})) \leq 0 \text { in } \Omega, \\
\left.\tilde{v}\right|_{\partial \Omega}=0
\end{array}\right.
$$

$\tilde{v}>0$ is an upper solution to

$$
\left\{\begin{array}{l}
\Delta v+v h(0, v)=0 \text { in } \Omega, \\
\left.v\right|_{\partial \Omega}=0 .
\end{array}\right.
$$

Since $\tilde{v}>0$, for large enough $n \in N, \frac{\theta_{h(0,)}}{n}<\tilde{v}$ in $\Omega$. Since

$$
\begin{aligned}
& \Delta\left(\frac{\theta_{h(0, \cdot)}}{n}\right)+\frac{\theta_{h(0, \cdot)}}{n} h\left(0, \frac{\theta_{h(0, \cdot)}}{n}\right)=\frac{1}{n}\left[\Delta \theta_{h(0, \cdot)}+\theta_{h(0, \cdot)} h\left(0, \frac{\theta_{h(0, \cdot)}}{n}\right)\right] \\
& \geq \frac{1}{n}\left[\Delta \theta_{h(0, \cdot)}+\theta_{h(0, \cdot)} h\left(0, \theta_{h(0, \cdot)}\right)\right]=0
\end{aligned}
$$

$\frac{\theta_{h(0, \cdot)}}{n}$ is a lower solution to

$$
\left\{\begin{array}{l}
\Delta v+v h(0, v)=0 \text { in } \Omega \\
\left.v\right|_{\partial \Omega}=0
\end{array}\right.
$$

Therefore, by the uniqueness of the solution and the upper-lower solution method, we conclude $\theta_{h(0, \cdot)} \leq \tilde{v}$.

Theorem 3.4. There exist two functions $M(g), N(h):\left[\lambda_{1}, \infty\right) \rightarrow R$ such that:
(A) if $g(0,0) \geq \lambda_{1}, h(0,0) \leq M(g)$, then all possible nonnegative solutions to (4) are $(0,0)$ and $\left(\theta_{g(\cdot, 0)}, 0\right)$,
(B) if $\lambda_{1}<g(0,0)<N(h), h(0,0)>\lambda_{1}$, then all possible nonnegative solutions to (4) are $(0,0),\left(\theta_{g(\cdot, 0)}, 0\right)$ and $\left(0, \theta_{h(0, \cdot)}\right)$,
(C) if $g(0,0)>\lambda_{1}, M(g)<h(0,0)<\lambda_{1}$, then all possible nonnegative solutions to (4) are $(0,0),\left(\theta_{g(\cdot, 0)}, 0\right)$ and a positive solution $u^{+}>0, v^{+}>0$,
(D) if $h(0,0)>\lambda_{1}, g(0,0)>N(h)$, then all possible nonnegative solutions to (4) are $(0,0),\left(\theta_{g(\cdot, 0)}, 0\right),\left(0, \theta_{h(0, \cdot)}\right)$ and a positive solution $u^{+}>0, v^{+}>0$.

Proof. For $g(0,0) \geq \lambda_{1}$, let $M(g)=\lambda_{1}\left(-h\left(\theta_{g(\cdot, 0)}, 0\right)+h(0,0)\right)$ and $N(h)=$ $\lambda_{1}\left(-g\left(0, \theta_{h(0, \cdot)}\right)+g(0,0)\right)$.
(A) Suppose $h(0,0) \leq M(g)$. Let $\tilde{u} \geq 0, \tilde{v} \geq 0$ be a solution to (4). If $\tilde{v}>0$ in $\Omega$, then $\lambda=h(0,0)$ is the smallest eigenvalue of the problem

$$
\left\{\begin{array}{l}
-\Delta v+v(-h(\tilde{u}, \tilde{v})+h(0,0))=\lambda v \text { in } \Omega, \\
\left.v\right|_{\partial \Omega}=0 .
\end{array}\right.
$$

By the monotonicity of $h$ and Lemma 3.3, we have

$$
-h(\tilde{u}, \tilde{v})>-h\left(\theta_{g(\cdot, 0)}, 0\right),
$$

and so

$$
h(0,0)=\lambda_{1}(-h(\tilde{u}, \tilde{v})+h(0,0))>\lambda_{1}\left(-h\left(\theta_{g(\cdot, 0)}, 0\right)\right)+h(0,0)=M(g),
$$

which is a contradiction to $h(0,0) \leq M(g)$. Hence, $\tilde{v} \equiv 0$. Therefore, we conclude that if $g(0,0) \geq \lambda_{1}$ and $h(0,0) \leq M(g)$, then all possible nonnegative solutions to (4) are $(0,0)$ and $\left(\theta_{g(\cdot, 0)}, 0\right)$.
(B) Suppose $\lambda_{1}<g(0,0) \leq N(h)$ and $h(0,0)>\lambda_{1}$. Let $u \geq 0, v \geq 0$ be a solution to (4) with $v>0$ in $\Omega$. If $u>0$ in $\Omega$, then $\lambda=0$ is the smallest eigenvalue of the problem

$$
\left\{\begin{array}{l}
-\Delta w-w g(u, v)=\lambda w \text { in } \Omega, \\
\left.w\right|_{\partial \Omega}=0 .
\end{array}\right.
$$

Since

$$
-g(u, v)>-\left(g\left(0, \theta_{h(0, \cdot)}\right)\right.
$$

from Lemma 3.3 and the monotonicity of $g$, using Lemma 2.2 we have

$$
0>\lambda_{1}\left(-g\left(0, \theta_{h(0, \cdot)}\right)\right)=\lambda_{1}\left(-g\left(0, \theta_{h(0, \cdot)}\right)+g(0,0)\right)-g(0,0)=N(h)-g(0,0) .
$$

This contradicts $g(0,0) \leq N(h)$. Hence $u=0$, so all possible nonnegative solutions to (4) are $(0,0),\left(0, \theta_{h(0, \cdot)}\right)$ and $\left(\theta_{g(\cdot, 0)}, 0\right)$.
(C) Suppose $g(0,0)>\lambda_{1}$ and $M(g)<h(0,0)<\lambda_{1}$. Let $u \geq 0, v \geq 0$ be a solution to (4) in which one component is zero. Then $u=0, v=0$ or $u=\theta_{g(\cdot, 0)}, v=0$. Since $\lambda_{1}\left(-h\left(\theta_{g(\cdot, 0)}, 0\right)\right)=\lambda_{1}\left(-h\left(\theta_{g(\cdot, 0)}, 0\right)+h(0,0)\right)-h(0,0)=$ $M(g)-h(0,0)<0$, by the combination of Lemmas 2.4 and 3.3 , there is a positive solution to (4) $u^{+}>0, v^{+}>0$.
(D) Suppose $g(0,0)>N(h)$ and $h(0,0)>\lambda_{1}$. Let $u \geq 0, v \geq 0$ be a solution
to (4) in which one component is zero. Then since

$$
\begin{aligned}
g(0,0) & >N(h)=\lambda_{1}\left(-\left(g\left(0, \theta_{h(0, \cdot)}\right)-g(0,0)\right)\right) \\
& >\lambda_{1}(-(g(0,0)-g(0,0)))=\lambda_{1}(0)=\lambda_{1},
\end{aligned}
$$

from Lemma 2.2 and the monotonicity of $g$, we have $u=0, v=0$ or $u=0, v=$ $\theta_{h(0, \cdot)}$ or $u=\theta_{g(\cdot, 0)}, v=0$. Since $\lambda_{1}\left(-g\left(0, \theta_{h(0, \cdot)}\right)\right)=\lambda_{1}\left(-g\left(0, \theta_{h(0, \cdot)}\right)+g(0,0)\right)-$ $g(0,0)=N(h)-g(0,0)<0$, by the combination of Lemmas 2.4 and 3.3, there is a positive solution to (4) $u^{+}>0, v^{+}>0$.

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