University of Montana

ScholarWorks at University of Montana

UM Graduate Student Research Conference (GradCon)

Are robots morally culpable? The role of intentionality and anthropomorphism

Sarah Sweezy ss163853@umconnect.umt.edu

Shailee Woodard shailee.woodard@umconnect.umt.edu

Follow this and additional works at: https://scholarworks.umt.edu/gsrc Let us know how access to this document benefits you.

Sweezy, Sarah and Woodard, Shailee, "Are robots morally culpable? The role of intentionality and anthropomorphism" (2021). *UM Graduate Student Research Conference (GradCon)*. 5. https://scholarworks.umt.edu/gsrc/2021/sshum_poster/5

This Poster Presentation is brought to you for free and open access by ScholarWorks at University of Montana. It has been accepted for inclusion in UM Graduate Student Research Conference (GradCon) by an authorized administrator of ScholarWorks at University of Montana. For more information, please contact scholarworks@mso.umt.edu.

Are robots morally culpable? The role of intentionality and anthropomorphism Sarah E. Sweezy, Shailee R. Woodard, & Rachel L. Severson **Department of Psychology**

MONTANA

INTRODUCTION

robot agents, in addition to the tendency to anthropomorphize.

- Perceiving intentionality for another's actions can influence moral judgment [1].
- mechanical devices do not [2].
- when the robot is behaving in a socially contingent manner [3].

	METHOD		
Participants		С	Dr
N=63 (46% female)		•	R
•	3-year-olds (<i>n</i> =32, <i>M</i> =3.60 years, <i>SD</i> =.58)	•	R
•	5-year-olds(<i>n</i> =31, <i>M</i> =5.55 years, <i>SD</i> =.33)	•	┠
		•	C
	DUMBBELL TASK		

- Participants viewed video of either a human or a robot (socially contingent or non-contingent) attempting to pull a wooden dumbbell apart, but failing to do so.
- Dumbbell was placed in front of the participant to see if they would imitate the intended-but-failed action.
- If children understood the agent (human or robot) as intentional, they should complete the intended-butfailed action.

Figure 1. Proportion of participants who pulled dumbbell apart (excluding those who did not touch the dumbbell).



This study examined children's judgments of intentionality and culpability of human and

• Previous work has demonstrated infants' ability to differentiate that humans have intentions and

• However, perceiving personified technology (such as robots) as social beings has been evidenced

+ **RESULTS**

nditions

- Robot(socially contingent)
- Robot (non-contingent)
- luman
- Control

Measures

- Dumbbell Task
- Tower Task
- Anthropomorphism



METHOD + RESULTS

TOWER TASK

- Participants viewed video of a person building a block tower, after which the agent (human, robot) knocked the tower over.
- acceptability, • Participants rated punishment, and act intentionality ('on purpose' or 'on accident').
- 'Culpability scores' were computed as the difference between acceptibility and punishment.

Figure 2. Mean judgments on Tower Task. Acceptibility — Punishment — Culpability Score



ANTHROPOMORPHISM

- Individual Participants the were given Differences in Anthropomorphism Questionnaire - Child Form (IDAQ-CF) [4].
- IDAQ-CF assessed attribution of internal states (e.g., intentions, thought, and emotions) to nonhuman animals, nature, and technology.

CONCLUSIONS

Three- and five-year-olds viewed a robot as intentional and morally culpable for its actions, and these attributions were tied to their tendency to anthropomorphize.

- Children inferred the robot had intentions to the same degree as humans.
- Although culpability for the agent's actions was tied to intentionality (I.e., acting on purpose), children viewed the robot as less culpable than the human.
- Children with greater tendency to anthropomorphize were more likely to judge the robot, but not the human, as morally culpable.

REFERENCES

- 1. Zelazo, P. D., Helwig, C. C., & Lau, A. (1996). Intention, act, and outcome in behavioral prediction and moral judgment. Child Development, 67(5), 2478-2492.
- 2. Meltzoff, A. N. (1995). Understanding the intentions of others: re-enactment of intended acts by 18-month-old children. Developmental Psychology, 31(5), 838.
- 3. Meltzoff, A. N., Brooks, R., Shon, A. P., & Rao, R. P. (2010). "Social" robots are psychological agents for infants: A test of gaze following. Neural *Networks*, *23*(8-9), 966-972.
- 4. Severson, R. L., & Lemm, K. M. (2016). Kids see human too: Adapting an individual differences measure of anthropomorphism for a child sample. Journal of Cognition and Development, 17(1), 122-141.

deservingness of







** *p* = .01