

TITLE

Differences in Motor Control Strategies of Jumping Tasks, as Revealed by Group and Individual Analysis.

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1 **Differences in motor control strategies of jumping tasks,**
2 **as revealed by group and individual analysis**

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35 **Abstract**

36 The aim of this study was to investigate the motor control strategies adopted when performing
37 two jumping tasks with different task demands when analysed at an individual and group level.
38 Twenty-two healthy individuals performed two jumping tasks: jumping without the use of an
39 arm swing (CMJnas) and jumping starting in a plantar flexed position with the use of an arm
40 swing (PF). Principal component analysis (PCA) was performed using hip, knee and ankle joint
41 moment data on individual (PCAi) and group data (PCAc). The results demonstrate a greater
42 number of PCs are required to explain the majority of variance within the dataset in the PF
43 condition at both an individual and group level, compared to CMJnas condition. Whilst
44 common control strategies were observed between the two jumping conditions, differences in
45 the organisation of the movement (PC loading coefficients) were observed. Results from the
46 group analysis did not completely reflect the individual strategies used to perform each jumping
47 task and highlight the value in performing individual analysis to determine emergent control
48 strategies.

49 **Keywords: principal component analysis, vertical jumping, degrees of freedom, single-**
50 **subject analysis**

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61 **Introduction**

62 The process through which humans explore the perceptual motor workspace, as they seek to
63 satisfy task goals by exploring and discovering solutions under the influence of interacting
64 constraints, has long been of interest to researchers in the fields of motor control and motor
65 learning (cf. Chow, Davids, Button & Rein, 2008; Newell, Kugler, van Emmerik, & McDonald,
66 1989). Much of the focus of researchers has been concerned with understanding how the many
67 degrees of freedom available to perform actions are controlled and adapt to alterations in the
68 constraints acting on the performer (Majed, Heugas & Siegler, 2017; Lee, Liu & Newell, 2016;
69 Federolf, Roos & Nigg, 2013; Hong & Newell, 2006; Vaillancourt & Newell, 2002).

70

71 A task constraint which has been shown to affect the control of the degrees of freedom (DOF)
72 is the difficulty of the task, or the demand placed on the performer, with both increases and
73 decreases in DOF observed through application of principal component analyses (PCA)
74 (Cushion et al., 2020; Nordin & Dufek, 2016; Federolf et al., 2013). Geometrically, DOF
75 represent the minimum number of coordinates that can be used to describe the position and
76 orientation of a system. When applying PCA to determine coordinative structures in
77 movement, the term functional DOF (fDOF) has come to be used (Nordin & Dufek, 2016; Li
78 & Tang, 2007; Li, 2006). fDOF refer to the minimum number of principal components (PCs)
79 that are required to explain a high percentage of variance within the data. Within a given
80 movement there may be a high number of DOF, but due to coupling between DOF fewer fDOF
81 are required to describe the coordinative structure of a specific movement (Li & Tang, 2007).
82 The inclusion of a task constraint to maintain balance led to an increase in the fDOF required
83 to perform a jumping task compared to two jumping tasks which did not include this task
84 constraint (see Cushion et al., 2020). In contrast, Nordin and Dufek (2016) reported a reduction
85 in the available fDOF when participants performed more demanding tasks by landing from

86 increasing heights with increasing external loads. Nordin and Dufek (2016) suggested this
87 motor control strategy may occur due to more motor planning prior to the task and therefore a
88 reduction in automaticity and less flexibility of movement options as shown with a reduction
89 in fDOF. Based on the differences in findings between the two discussed studies, it is likely
90 the specific demand of the task drives the reduction in DOF. For instance, the demand on the
91 musculoskeletal system when landing from a height (as per the task used by Nordin & Dufek,
92 2016) is greater than required to maintain balance (as used by Cushion et al., 2020), which may
93 limit the ability of the system to explore movement options, a consequence which may not be
94 optimal for safe movement execution (Nordin & Dufek, 2016). In contrast, jumping with a
95 requirement to maintain balance could encourage movement exploration to maintain this
96 position and this has been demonstrated in other balance movements of high complexity (e.g.
97 one leg standing and tandem standing) (Federolf et al., 2013; Ko, Challis & Newell, 2003).

98

99 The continual fluctuations in constraints operating on the performer results in adjustments to
100 the DOF employed to control actions and explains why human movement is inherently variable
101 both between and within individuals (Newell & Corcos, 1993; Bernstein, 1967). Despite this
102 individual variability, the description of human movement is typically informed by group
103 analyses. Although application of mean data from group analyses provides a description of
104 common motor control strategies, it is limited in that it reflects the collective strategy of a group
105 and may hide relevant individual specific motor strategies (Bartlett, Wheat & Robbins, 2007).
106 Dufek, Bates, Stergiou and James (1995) showed this when analysing individual and group
107 strategies when performing impact activities, including landing and running tasks. Dufek et al.
108 (1995) demonstrated that group analyses, which presented an average across all participants,
109 did not provide an accurate nor representative description of any individual strategies employed
110 by participants. Therefore, appropriate consideration should be given to individual analysis to

111 better understand how motor control strategies are affected by the constraints that shape the
112 perceptual motor workspace. Similarly, within-individual variability across task repetitions
113 should be analysed to examine if individuals adopt a consistent strategy or whether this changes
114 over time. Examining both within and between participant motor control strategies provides a
115 more holistic and true approach to our understanding of motor behaviour, with such an
116 approach becoming increasingly popular (e.g., DiCesare et al., 2020; Nordin, Dufek, James &
117 Bates, 2017; Raffalt, Alkjaer & Simonsen, 2016; Komar, Seifert & Thouvarecq, 2015; Huber
118 et al., 2013; Feldrolf et al., 2013; Scholes, McDonald & Parker, 2012; Gittoes, Irwin,
119 Mullineaux & Kerwin, 2011; Borzelli, Cappizzo & Papa, 1999).

120

121 In this study, jumping tasks were used to investigate emergent motor control strategies, that is
122 we were interested in understanding how the system self-organised under differing movement
123 demands. Whilst individual and group differences have been observed using vertical jumping
124 tasks, this has largely been with the purpose of comparing different demographics such as
125 children and adults (Raffalt et al., 2016), or to analyse a specific joint (Ryan, Harrison & Hayes,
126 2006). We used two jumping tasks (jumping without an arm swing and jumping starting in a
127 plantar flexed position, with the use of an arm swing) that have previously shown the highest
128 and lowest amounts of variability in lower limb joint moment production at a group level which
129 would indicate constraints at specific joints differentially affect the movement outcome (see
130 Cushion, Warmenhoven, North & Cleather, 2019; Cushion et al., 2020). Whilst both jumping
131 tasks provide different biomechanical constraints, either gaining or restricting arm motion or
132 restricting ankle motion, it is suggested that the condition restricting ankle motion and
133 including an arm swing would be a more demanding task. This is due to the additional
134 requirement to balance in an unnatural position prior to the jump, and it is likely that jumping
135 with the use of an arm swing is a more novel movement for most participants. It may also be

136 the case that some participants may be more or less affected by constraints at each joint and
137 thus this may be reflected in the results. This study extends the work by Cushion et al. (2020)
138 and Cushion et al. (2019) and we had several objectives which we assessed using a principal
139 component analysis, which enables the analysis and decomposition of spatiotemporal data
140 (Daffertshofer, Lamoth, Meijer & Beck, 2004). Our first objective was to compare the
141 organisation of the fDOF in two jumping tasks with differing movement demands and
142 determine how the demand of the task influences the number of fDOF. This was explored at
143 both an individual and group level. It was hypothesised that the task with the higher movement
144 demand, due to the requirement to maintain balance and coordinate both upper and lower limbs
145 (plantar flexed and arm swing condition), would require a greater number of fDOF to describe
146 the variance in the dataset (see Cushion et al., 2020; Ko et al., 2017; Lee et al., 2016; Federolf
147 et al., 2013). Our second objective was to determine if similar strategies were used across both
148 tasks by the same individuals or whether this changed as a function of the change in task
149 constraint. In line with this, we also explored whether distinct coordination strategies observed
150 at a group level reflected individual movement strategies, as has been explored with other
151 movement tasks (Scholes et al., 2012; Gittoes et al., 2011). Based on previous literature
152 (Cushion et al., 2019; Scholes et al., 2012; Gittoes et al., 2011) it was hypothesised a similar
153 general pattern of coordination would be observed between the two tasks, but it was expected
154 that results from group analyses would not fully reflect the individual strategies used to carry
155 out the movement tasks.

156

157 **Methods**

158 *Participants*

159 A total of twenty-two healthy individuals (males = 13, females = 9) volunteered to take part in
160 this study (mean \pm SD; age = 26.5 ± 4.7 years, height = 171.3 ± 8.7 cm, body mass 74.1 ± 12.5
161 kg). Participants were free from musculoskeletal injuries at the time of testing. Details of the
162 study were provided before written informed consent was obtained. The experimental
163 procedure was approved by the ethics sub-committee at the institution where the research took
164 place.

165

166 *Protocol*

167 Prior to testing, participants' anthropometric measures (height and weight) were collected and
168 each participant was issued with a standardised shoe in their shoe size. Participants completed
169 a standardised warm up (bodyweight squats, lunges, inchworms, hip rotations and vertical
170 jumps) followed by the attachment of reflective markers. Eighteen reflective markers were
171 placed on the pelvis and on the right lower limb (Cleather, Goodwin & Bull, 2013). Markers
172 were placed on the right and left anterior superior iliac spine and posterior superior iliac spine,
173 lateral and medial femoral epicondyle, apex of lateral and medial malleolus, posterior aspect
174 of calcaneus, tuberosity of fifth metatarsal and head of second metatarsal. Three additional
175 markers placed on rigid plates were attached to the mid-thigh and anterior tibial shaft, with an
176 additional marker attached to the top of the foot (Cleather & Bull, 2015).

177

178 In a randomised order, participants completed five maximal effort countermovement jumps for
179 each jump condition. All five trials were used for further statistical analysis to increase the
180 statistical power of the PCA (see James & Bates, 1997), but which ensured a fatigue effect did
181 not impact the results of the analysis. Specifically, participants were asked to complete
182 maximal effort countermovement jumps (i) with no arm swing (nas) (CMJnas), and (ii) starting

183 in a plantar flexed position and with the use of an arm swing (PF), with these particular jumping
184 tasks having been previously employed to investigate motor control strategies by Cushion et
185 al. (2019) and are presented in Figure 1. Prior to completing any jumps, participants were
186 provided with instructions for the specific condition they were about to complete. Performing
187 a jump without the use of an arm swing required participants to jump with hands in contact
188 with the hips throughout the whole movement. An instruction to jump maximally was also
189 provided prior to all jumping trials. When completing the plantar flexed condition, participants
190 were asked to start the jump in a maximal plantar flexed position, but which allowed them to
191 maintain balance. An instruction to not touch the floor with their heels throughout the jump
192 was also given. Participants were again also instructed to perform all jumps maximally.

193 ***Figure 1 here***

194 Kinematic data were collected using a Vicon motion capture system (Vicon MX System, Nexus
195 2.2 software, Vicon Motion Systems Ltd, Oxford, UK) with fourteen LED cameras tracking
196 the reflective markers at a sampling frequency of 200Hz. Kinetic data were collected via two
197 force plates positioned flush to the laboratory floor (Kistler Type 9287BA, Bioware 3.24
198 software, Kistler Instruments Ltd, Hampshire, UK), at a rate of 1000Hz and synchronised with
199 the Vicon system.

200

201 ***Data analysis***

202 The unweighting, braking and propulsive phases of the countermovement jump (McMahon,
203 Suchomel, Lake & Comfort, 2018), that is from the moment the participant began moving
204 downwards at the start of the jump until the point at which they left the ground, were used for
205 analysis and were defined as being from the point where the right anterior superior iliac spine
206 marker moved below stationary height until take-off (which was defined as the point where the

207 ground reaction force fell to zero). Kinematic and kinetic data was filtered using a 5th order
208 Woltring filter with a cut off frequency of 10Hz. Hip, knee and ankle net joint moments (NJM)
209 in the sagittal plane were calculated using a standard inverse dynamics calculation (Winter,
210 2005) within the FreeBody software (Cleather & Bull, 2015). To standardise trial length
211 between individuals, data was spline interpolated and time normalised from 0 to 101 data
212 points. This data was then used within a PCA.

213

214 *Statistical Analysis*

215 PCA was used within this study as it has the advantage of retaining the spatiotemporal pattern
216 in the time series data whilst detecting coordination patterns between each jump condition and
217 between individuals. PCA produces principal components (PC) which describe a certain
218 percentage of the total variance within the dataset. The first PC accounts for the most amount
219 of variability, with subsequent PCs describing a lesser amount of variability within the data.
220 The PCs represent transformed data into new uncorrelated variables. Only those PCs that
221 cumulatively explained over 90% of the variance in the data set were retained and used in
222 further analysis (Jolliffe, 2002). The output of each PCA produces a coefficients matrix where
223 each column gives the coefficient loadings (loadings) of a PC. The loadings represent how
224 much each variable contributes to the production of a particular PC. In the context of motor
225 control strategies, loadings can provide an indication of how each variable features within a
226 PC. For example, a high loading value would indicate that variable contributes a greater
227 weighting to the reconstruction of a particular PC, whereas a low loading value would indicate
228 the opposite. This can be compared at both a group and individual level. PC scores are also
229 examined within the current study and these are obtained from the multiplication of the raw
230 data matrix and coefficients matrix. The PC scores represents the time series of the values for

231 each PC and thus show how the new variable in the new coordinate space evolves over time.
232 Put another way, the PC scores are the linear combination of the variables weighted by the
233 loading coefficients. The PC scores can be used to compare strategies between jumping
234 conditions, where similarities in waveforms would indicate similar strategies are being used to
235 perform the tasks (Thomas, Corcos & Hasan, 2005; Santello, Flanders & Soechting, 2002).
236 Using PC scores and loading coefficients the original variables can be reconstructed and thus
237 these outputs can show how each of the raw variables can be constructed from a smaller subset
238 of PCs. Within the current study we also present the sum of the PC scores weighted by the
239 averaged loading coefficients and show the variation of the PC scores about the mean by
240 presenting the standard deviation.

241

242 PCA within the current study was applied similarly to the methods proposed by Borzelli,
243 Cappizzon and Papa (1999). All trials from each jump condition were used within PCA. To
244 assess suitability of data for PCA Kaiser-Meyer-Olkin and Bartlett tests are sometimes used.
245 However, these tests were not meaningful for this dataset as it was not full rank. The dataset
246 consists of a large number of time series where a very large proportion of the variance can be
247 expressed with a small number of PCs. Prior to running the PCA, all NJM data were
248 normalised to the peak hip joint moment, by dividing all values of the time series by the
249 maximum hip joint moment of each trial to avoid the impact of some variables having greater
250 amplitude than others, which is equivalent to performing PCA on a correlation matrix (Joliffe
251 & Cadima, 2016; Abdi & Williams, 2010; Thomas, Corcos & Hasan, 2005). PCA were
252 performed to analyse differences within and between individuals and conditions. Before PCA
253 was performed, matrices of data were constructed. Within the current study, columns of the
254 matrix represent NJM time series and rows represent the time normalised intervals. Therefore,
255 for an individual case a matrix containing 101 rows and 15 columns (5 x hip NJM, 5 x knee

256 NJM, 5 x ankle NJM) was constructed (101 x 15). Matrix set ups for each PCA performed are
257 illustrated in Table 1. PCA were performed in Matlab (The MathWorks, Inc., M A, version
258 2017a) using the *pca* function, which also centres the data prior to analyses.

259

260

Table 1 here

261

262 Data obtained from PCAi was not normally distributed, as determined visually from stem and
263 leaf and Q-Q plots, therefore a Wilcoxon signed rank test was run to compare the number of
264 PCs and the explained variance attributed to each PC between the two jump conditions. To
265 compare loading coefficients between jump conditions, from PCAi, a 2 x 3 ANOVA was
266 performed. Data was normally distributed as determined visually from stem and leaf and Q-Q
267 plots. Data is presented as means \pm SD. Statistical analysis was conducted in SPSS (IBM SPSS
268 Statistics 24). The alpha level was set at $p < 0.05$.

269

270 **Results**

271 A large percentage of the dataset could be described by only a few PCs for each condition when
272 all the joint moments were included in the same PCA (within participants analysis: PCAi and
273 between participant analysis: PCAc). For the within-participant analysis (PCAi), a maximum
274 of three PCs was required to meet the 90% criteria (average of first three PCs: $96.4 \pm 1.9\%$) for
275 the CMJnas condition, whereas a maximum of four PCs was required during the PF condition
276 (average of the first four PCs: $95.5 \pm 2.5\%$). A statistically significant difference was observed
277 between the number of retained PCs between the two jumping conditions for PCAi ($Z = -3.477$,
278 $p = .001$). At the between-participant level (PCAc), the first four PCs described 92.3% of the
279 variance for CMJnas, and the first five PCs described 90.5% of the variance for PF condition.

280 The within-participant variability increased with an increase in task demand, based on the
281 number of PCs retained to explain over 90% of the dataset and variance explained within each
282 PC (Figure 2 and Table 2).

283

284 ***Figure 2 here***

285

286 Significant differences between the explained variance attributed to each PC between the two
287 jump conditions were observed across PC3 to PC5 for PCAi (Table 2).

288

289 ***Table 2 here***

290

291 Average PC score waveforms from PCAi for PC1, PC2 and PC3 between jumping conditions
292 (CMJnas and PF) are presented alongside averaged loading coefficients for PC1-PC4,
293 representing the maximum amount of PCs required by any individual to explain over 90% of
294 the variance within the dataset (Figure 3). A statistically significant difference between the
295 loading coefficients of the two jumping conditions was observed for PC1, $F(1,126) = 7.170, p$
296 $= .008$; PC2, $F(1,126) = 9.125, p = .003$ and PC3, $F(1,126) = 16.030, p = .000$. No further
297 statistically significant main effects or interactions were observed.

298

299 ***Figure 3 here***

300

301 PC score waveforms and loading coefficients are presented for two representative individuals
302 performing CMJnas and PF jumping conditions (Figure 4). Participant A represents an
303 individual with low explained variance for PC1 (58%) between both jump conditions, whereas

304 participant B represents an individual with high explained variance for PC1 (92%) between
305 both jump conditions.

306

307 ***Figure 4 here ***

308

309 The upper and lower boundaries of the variation in the sum of PC scores are presented in
310 Figures 5, 6 and 7 for hip, knee and ankle joint moments. A greater amount of variation is
311 observed within the knee and ankle compared to the hip. This variation was similar between
312 the two jump conditions for the knee and ankle, however there was differences in variation
313 between the two jump conditions at the hip. Specifically, more variation was observed in
314 CMJnas compared to PF condition within PC1 and PC2, however greater variation was
315 observed in PC3 – PC6 within the PF condition.

316

317 ***Figure 5 here***

318 ***Figure 6 here***

319 ***Figure 7 here***

320

321 **Discussion**

322 The current study investigated motor control strategies, at both an individual and group level,
323 between two jumping tasks with different task constraints. Specifically, we analysed the lower
324 limb joint moments between a vertical jump with no arm swing and a vertical jump starting in
325 a plantar flexed position with the use of an arm swing, which constrain motion at the lower

326 limb joints. Our two primary objectives were to explore the organisation of the fDOF between
327 the two jumping tasks and determine if motor control strategies differed between the two tasks
328 when analysing data at both a group and participant specific level. The results show that the
329 restriction of motion at specific lower limb joints influences the number of fDOF. These
330 constraints also impacted the demand of the task with a greater balance and coordination
331 requirement for the PF condition. The PF condition showed the greater number of fDOF
332 compared to the CMJnas condition, which was observed for both individual and group analysis.
333 However, group level analysis was not entirely comparable to individual data. The global motor
334 pattern between the two jumping conditions was very similar when compared at a group level
335 (through comparisons of PC waveforms and loading coefficients), although at an individual
336 level, whilst similarities in the PC score waveforms were observed there were some differences
337 in the structure of the loading coefficients when observing representative individual data. This
338 would suggest a global pattern of joint moment production is exhibited within jumping tasks,
339 but individuals self-organise such that the strategies used to perform the jumps are not
340 completely the same for each individual. These subtle differences may prove valuable in
341 understanding how factors such as skill level affect production and control of movement. It is
342 probable that the global pattern is driven from anatomical constraints which shape the
343 emergence of movement patterns, rather than a pattern that is learnt, as has previously been
344 suggested (see Cushion et al., 2019).

345

346 The application of PCA allows for an evaluation of how kinetic variables are weighted within
347 each PC, which provides an indication of the strategies used to perform movement tasks
348 (Daffertshofer & Lamoth, 2004; Hong & Newell, 2006). PC score waveforms reveal
349 characteristic patterns within each movement task and the loading of a variable describes the
350 degree to which those variables contribute to the production of each PC. Qualitatively it can be

351 seen that the waveforms for PC1 are very similar between both jumping conditions, when
352 observed at a group level. This indicates the repeatability of this pattern from PC1 in both
353 conditions. The loading coefficients for the hip on PC1 in both jumping conditions are high,
354 compared to the knee and ankle, suggesting for both conditions the hip joint moment waveform
355 contribute most to the explained variance within this PC. That is, to reconstruct the hip moment
356 waveform for both conditions a higher contribution from PC1 would be required. It is therefore
357 likely this represents a common control strategy, as assessed at a group level, and has been
358 observed in other jumping tasks (Cushion et al., 2019; Cushion et al., 2020). In contrast, the
359 patterns observed for PC2 and PC3 score waveforms are not so well defined between the two
360 jump conditions. In general, the loading coefficients of the knee was higher for PC2 for both
361 conditions. It is notable that the standard deviation is higher from PC2-PC4 suggesting that
362 these PCs contain greater between participant variation. The ankle loading coefficients were
363 higher for PC3 for the CMJnas, but this was not the case for the ankle for the PF condition until
364 PC4. In comparing the within participant variation for each joint (Figures 5-7), greater variation
365 in PF condition can be observed on PC1 at the ankle, compared to the knee and hip, suggesting
366 greater variability at this joint compared to CMJnas condition. This is likely driven by the fact
367 that there was an increase in the requirement to maintain balance during the PF jump compared
368 to the CMJnas condition. At an individual level there was a greater number of PCs required to
369 capture the characteristics of the data in the PF condition compared to the CMJnas condition.
370 This was also observed at the group level. Given the variability at the individual level, the
371 increased PCs at a group level could reflect the aggregation of variability between individuals
372 or reflect between participant variability. As differences in PC score waveforms and the loading
373 of each joint are observed between individuals it is likely that between participant variability
374 is captured within the increased number of PCs. The addition of PCs required may reflect the
375 ‘recruitment’ of additional DOF to aid in the emergence of new coordination patterns specific

376 for the constraints of the task (Majed et al., 2017; Fink, Kelso, Jirsa & DeGuzman, 2000;
377 Zanone & Kelso, 1997). Observations of longer-term practice of this task may provide further
378 insight of the organisation in movement as participants become more familiar with the
379 constraint.

380

381 Redundancy within the motor system allows for a range of options to organise multi-joint
382 movements, which may be beneficial to effectively solve and determine the most optimal
383 movement solutions (Yang & Scholz, 2005). Using PCA to study movement has the advantage
384 that high dimensional data is reduced to fewer components describing a high percentage of
385 variance within the whole data set. The results from the PCA in the current study demonstrated
386 that the task requirement impacts the organisation of the fDOF. The PF condition, which
387 restricted the motion at the ankle and allowed for the use of an arm swing required a greater
388 number of PCs to capture a high percentage of variance within the dataset, at both an individual
389 and group level. This jumping condition is likely to prove more difficult to the participants as
390 it required the challenge of balancing as well as coordinating lower and upper limbs, compared
391 to just a restriction of the arm swing in the CMJnas condition. This finding of an increase in
392 the requirement of fDOF in more demanding tasks is consistent with previous literature
393 (Cushion et al., 2020; Federolf et al., 2013; Lee et al., 2016). Lee et al. (2016) showed at the
394 initiation of learning to ride a unicycle as many as nine PCs were required to explain 90% of
395 the variance within the dataset, with a range between four and nine PCs based on participant
396 specific data. Similarly, when performing three standing tasks of different levels of difficulty
397 (bipedal, tandem and one leg stances) a greater number of PCs were required to explain 90%
398 of the variance in the more difficult stances (tandem and one leg) (Federolf et al., 2013).
399 Collectively, these results suggest greater exploration and utilisation of the DOF is required
400 within more complex tasks to establish coordination modes. However, this was not true for all

401 observations. During landing tasks with increasing mechanical demands (increased load and
402 drop height), the utilisation of the available DOF decreased, as quantified by reduced PCs with
403 increasing task demand (see also Nordin & Dufek, 2016). It is possible that the system allows
404 exploration of movement solutions within tasks which are more skill based, rather than tasks
405 which challenge the strength of the musculoskeletal system (as would jumping off a box with
406 added load) (Yeow, Lee & Goh, 2009).

407

408 Another explanation for the differences in the number of retained PCs in complex tasks, could
409 be related to if it is the demand or the constraint of the task which affects the organisation of
410 the movement the most. For example, the constraint imposed on the participants in the PF
411 condition is such that there is a restriction in the range of motion at the ankle and an increase
412 in range of motion of the arms (compared to CMJnas condition), whereas the demand of the
413 task is such that there is an increase in the balance requirement and a challenge to coordinate
414 both the lower and upper limbs. In the task used by Nordin and Dufek (2016), the task
415 constraint does not change greatly between conditions, but the demand of the task increases as
416 the height and added load increases, creating a greater demand on the organisation of the system
417 upon landing. The demand for the task in Nordin & Dufek's (2016) study may be such that it
418 did not allow much movement exploration. For the data presented in this study, it is not known
419 at this point if it is the demand (balance) or the constraint of the task (restriction or increase of
420 joint motion) that affects the requirement of fDOF within the task to a greater extent.
421 Disentangling the influence of task constraint and task demand on fDOF is an interesting
422 avenue for future research to consider.

423

424 One of the study objectives was to compare group and single participant analysis. Whilst there
425 are some similarities in the findings, the group analysis alone masks the individual strategies
426 observed when completing the two jumping tasks. In accordance with the group analysis, for
427 both representative individuals, the pattern of PC1 is similar between jump conditions and the
428 hip joint moment contributes most highly to the explained variance. It is therefore likely that
429 this represents an invariant coordination pattern important to produce jumping movements. As
430 with the group analysis there were less easily observable trends for PC2 and PC3 and the
431 loading of each joint was not consistent across individuals, demonstrating differences in the
432 organisation of the movements. In addition, neither participant employed the same motor
433 strategies to carry out the two tasks, which would suggest they had to alter motor control
434 strategies to successfully complete the two tasks (DiCesare et al., 2019). It is interesting to note
435 when observing the PC waveforms for both jumping conditions, they are similar for participant
436 B who showed the highest explained variance on PC1, but qualitatively different for participant
437 A who showed the lowest explained variance on PC1. It could be that participant A required
438 greater exploration of movement when carrying out the tasks compared to participant B, which
439 has been reflective of differences in skill level (Ko, Han & Newell, 2017; Verrel, Pologe,
440 Manselle, Lindenberger & Woollacott, 2013). The characteristics within the data could be
441 described by only one PC for participant B for both conditions, which would suggest a strong
442 coupling between joints. It has previously been suggested that the proximal to distal production
443 of sagittal plane lower limb joint moments can be captured by two fDOF (Cushion et al., 2019).
444 Therefore, the requirement of only one PC for participant B would suggest a more synchronous
445 production of lower limb joint moments. Participant A on the other hand required between four
446 (CMJnas) or five (PF) PCs to capture the majority of variance. This would suggest this
447 individual required a greater amount of fDOF in order to coordinate and control the DOF of
448 these two tasks, which has been illustrated in individuals less skilled to a task (Ko et al., 2017;

449 Wings & Furuya, 2015). Collectively these observations demonstrate that individual strategies
450 do not completely coincide with group strategies, an observation also made by others (Scholes
451 et al., 2012; Gittoes et al., 2011). This provides support for single participant analysis and the
452 utilisation of PCA within this study has allowed for greater insight into the sources of
453 movement variability as well as the motor control strategies adopted to accommodate the
454 demands of the tasks between individuals.

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456 This study has demonstrated that despite the different constraints on each jumping condition,
457 the system reorganised in such a way that similar coordination patterns emerged under both
458 conditions. This lends support for the notion that this represents a common control strategy
459 under the current constraints. The individual differences in the coefficient loadings on each PC
460 suggest that whilst there is a global coordination strategy, individual adaptations occur to
461 perform the task based on participant specific as well as task constraints. This research furthers
462 our understanding of how the CNS controls the coordination of the system and demonstrates
463 single subject analysis is important alongside group analysis to gain a more complete
464 understanding of motor control strategies and may uncover differences in skill levels between
465 individuals. The findings also further demonstrate the utility of PCA in exploring motor control
466 strategies and the organisation of the fDOF.

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471 **Word Count = 5226**

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610 Table 1. Description of data used within each PCA.

PCA Descriptor	Time Series Data Used (NJMs)	Number of separate analyses	Input Matrices (rows = time points x columns = NJMs)
PCAc	Data from all joint moments at the hip, knee and ankle for all participants and trials combined in one matrix. PCA run separately for CMJnas and PF conditions.	2	CMJnas: 101 x 309 PF: 101 x 333
PCAi	PCA run separately for each individual's data. Data included all joint moments from hip, knee and ankle and all trials combined in one matrix. Each jump condition run separately for each individual.	44	101 x 15
PCAc ^h	Data from all hip joint moments of all participants and trials combined in one matrix. PCA then run separately for CMJnas and PF conditions.	2	CMJnas: 101 x 103 PF: 101 x 100
PCAc ^k	Data from all knee joint moments of all participants and trials combined in one matrix.	2	CMJnas: 101 x 103 PF: 101 x 100

PCA then run separately for
CMJnas and PF conditions.

PCAc^a

Data from all ankle joint
moments of all participants and
trials combined in one matrix.

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CMJnas: 101 x 103

PF: 101 x 100

PCA then run separately for
CMJnas and PF conditions.

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625 Table 2. Within-participant variability only (PCAi) and between participant variability
 626 (PCAc) as indicated by the variability explained by the first five PCs for CMJnas and PF.
 627 Mean \pm SD of the individual analyses is presented for PCAi. *Indicates significant
 628 differences from CMJnas.

	PC1	PC2	PC3	PC4	PC5
PCAi					
CMJnas	80.92 \pm 10.44	11.97 \pm 8.97	3.51 \pm 2.09	1.60 \pm 0.80	0.86 \pm 0.57
PF	77.57 \pm 11.14	10.57 \pm 6.74	4.54 \pm 2.34*	2.85 \pm 1.49*	1.73 \pm 1.01*
PCAc					
CMJnas	62.94	20.36	5.36	3.68	1.86
PF	62.92	13.82	6.21	4.43	3.16

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661 **Figure Legends**

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663 **Figure 1.** Illustration of jumping conditions A = CMJnas and B = PF.

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665 **Figure 2.** Individual (PCAi) and group (PCAc) analysis showing number of PCs required to
666 explain over 90% of the variance for CMJnas and PF. Mean \pm SD of the individual analyses is
667 presented for PCAi. *Indicates significant difference between conditions.

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669 **Figure 3.** Average PC score waveforms from PCAi for PC1, PC2 and PC3 between CMJnas
670 and PF condition (Left panel). Average individual loading coefficients for hip (top), knee
671 (middle) and ankle (bottom) between CMJnas (black bars) and PF (grey bars) (right panel).
672 Results from PCAi. Data presented as means + SD.

673 **Figure 4.** Individual loading coefficients for hip, knee and ankle across PC1-3 for CMJnas
674 and PF condition (bar chart) and PC score waveforms for CMJnas and PF, from two
675 representative participants. Participant A presented with low explained variance on PC1 for
676 CMJnas (59%) and PF (58%) and participant B presented with high explained variance on
677 PC1 for CMJnas (92%) and PF (92%). Comparisons are made between CMJnas (dark grey
678 bar) and PF (light grey bar). Data analysed from PCAi.

679 **Figure 5.** Data presented shows upper and lower boundaries of the sum of PC scores
680 weighted by average loading coefficient with \pm 1SD for CMJnas (dark grey) and PF (light
681 grey) for the hip. A) PC1, B) PC1-PC2, C) PC1-PC3, D) PC1-PC4, E) PC1-PC5 and F) PC1-
682 PC6. Data from PCAc^h.

683 **Figure 6.** Data presented shows upper and lower boundaries of the sum of PC scores
684 weighted by average loading coefficient with \pm 1SD for CMJnas (dark grey) and PF (light
685 grey) for the knee. A) PC1, B) PC1-PC2, C) PC1-PC3, D) PC1-PC4, E) PC1-PC5 and F)
686 PC1-PC6. Data from PCAc^k.

687 **Figure 7.** Data presented shows upper and lower boundaries of the sum of PC scores
688 weighted by average loading coefficient with \pm 1SD for CMJnas (dark grey) and PF (light
689 grey) for the ankle. A) PC1, B) PC1-PC2, C) PC1-PC3, D) PC1-PC4, E) PC1-PC5 and F)
690 PC1-PC6. Data from PCAc^a.

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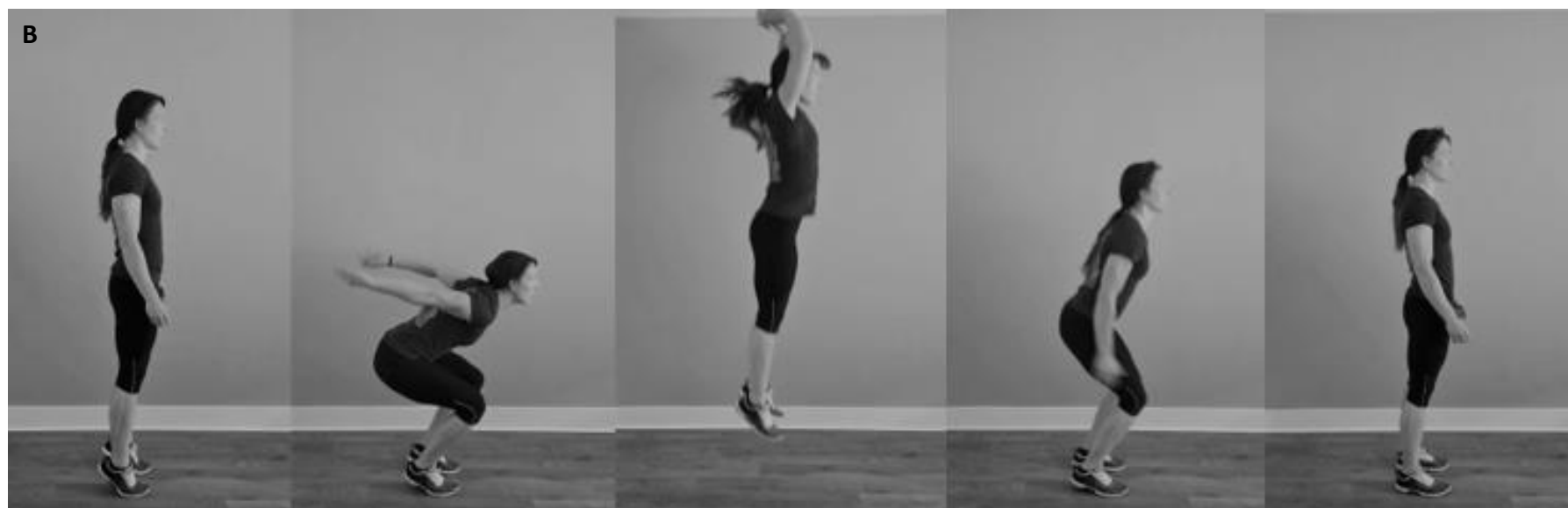
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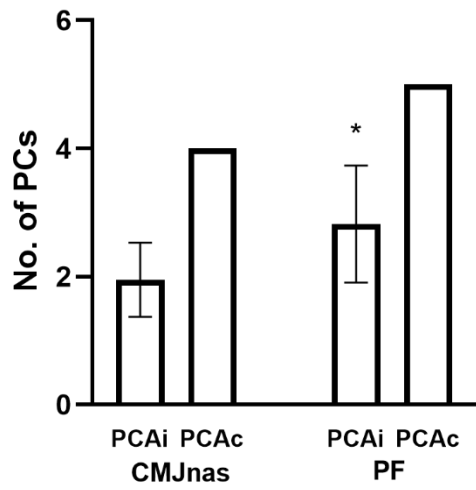
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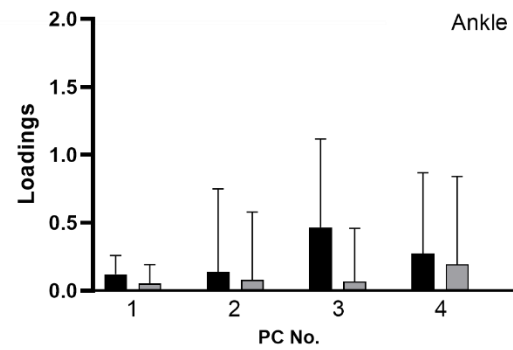
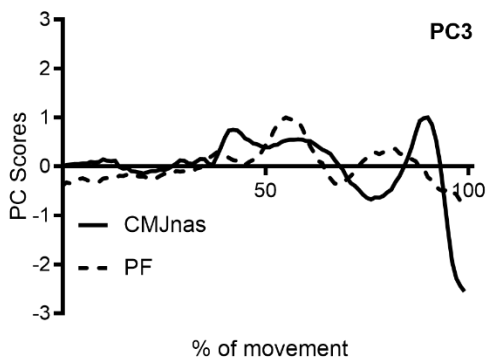
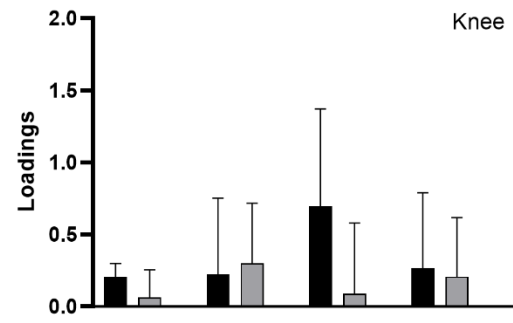
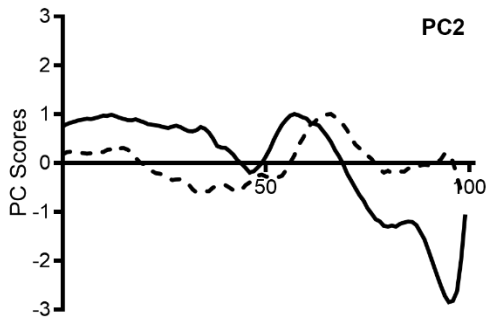
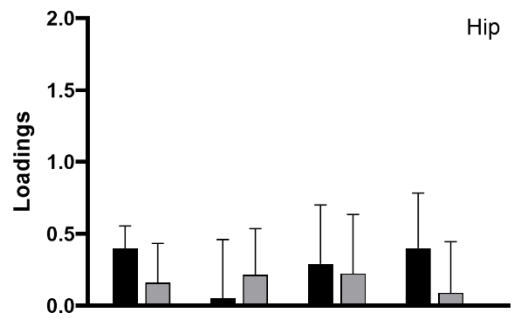
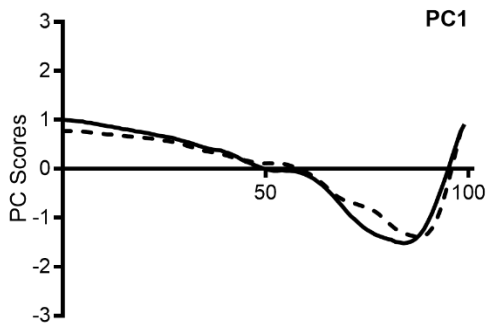
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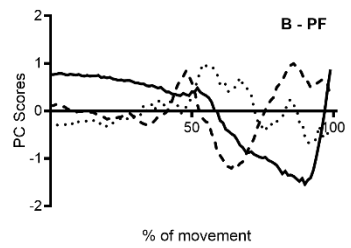
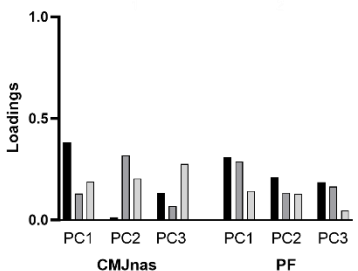
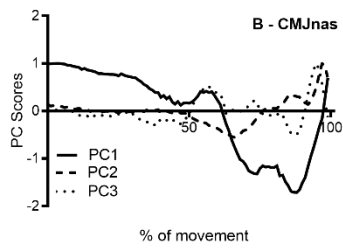
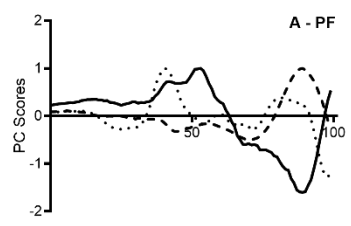
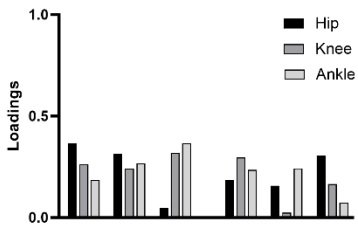
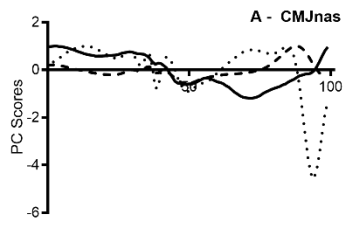
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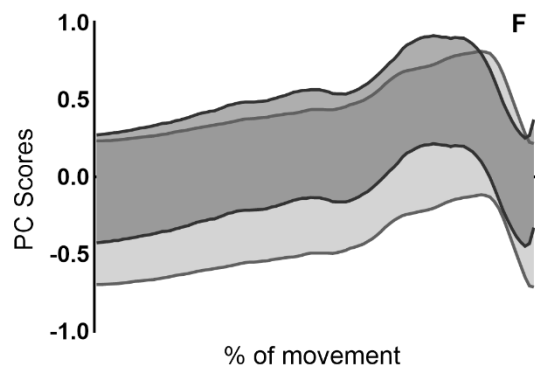
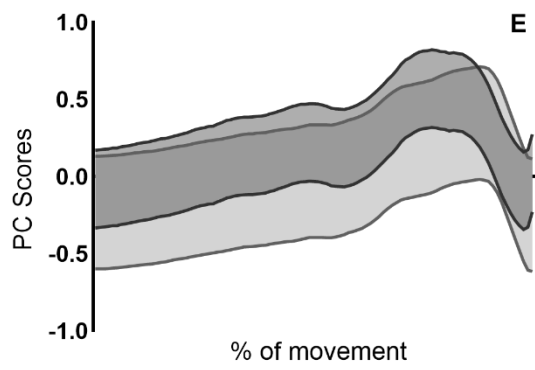
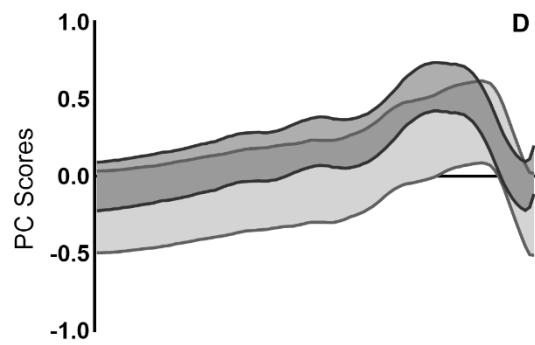
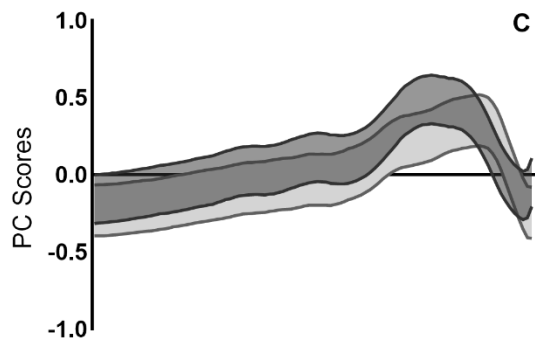
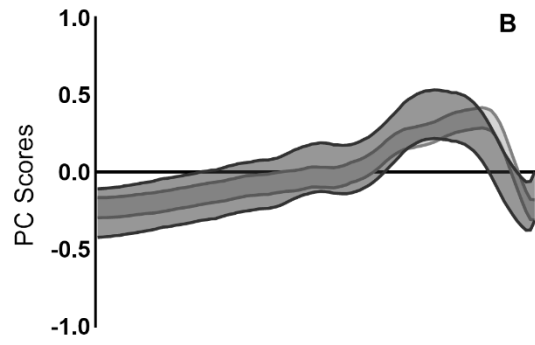
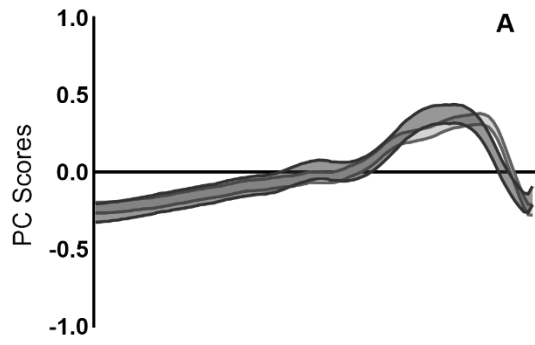
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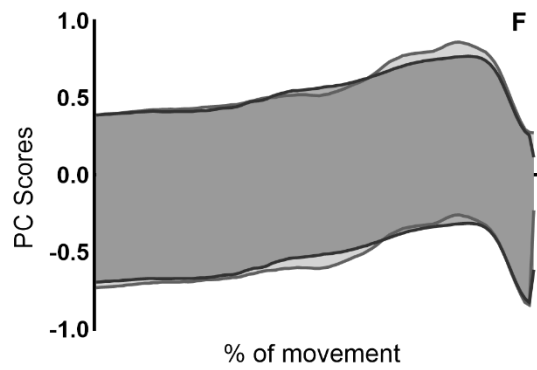
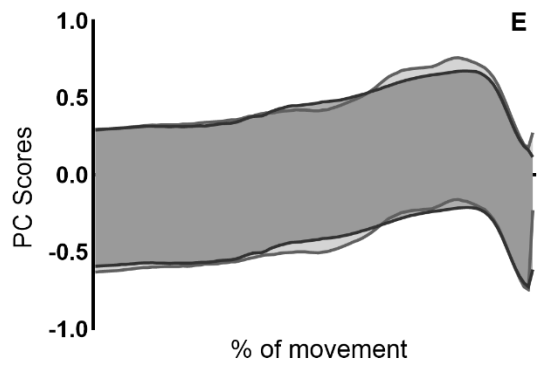
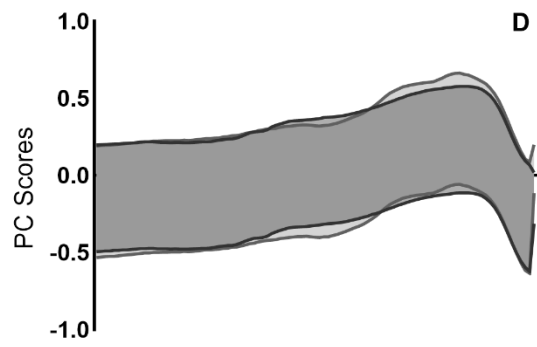
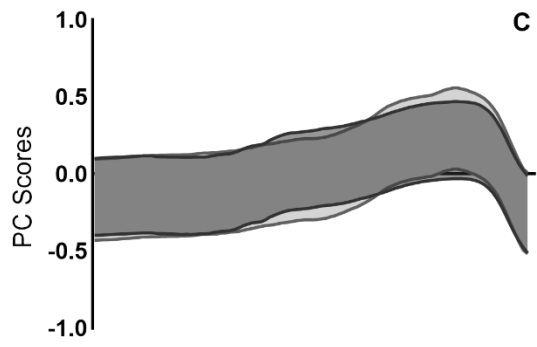
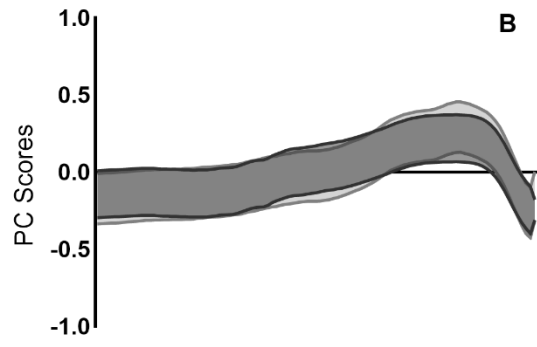
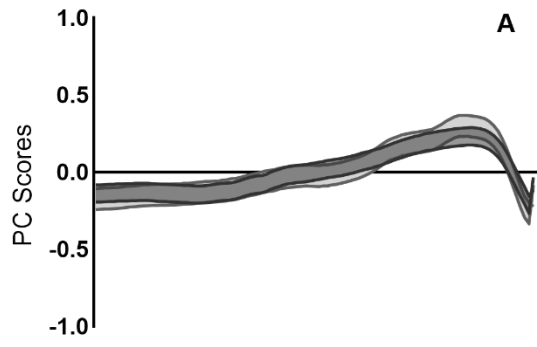
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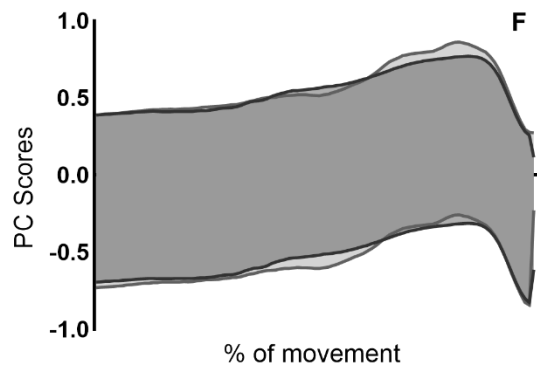
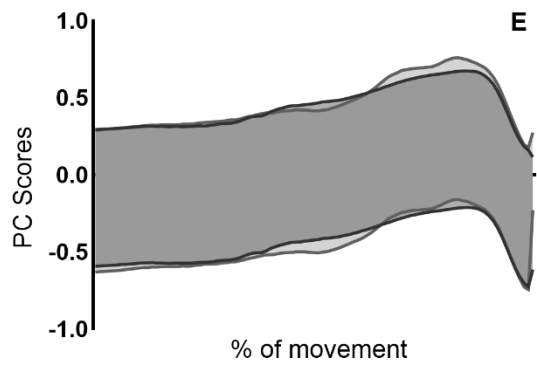
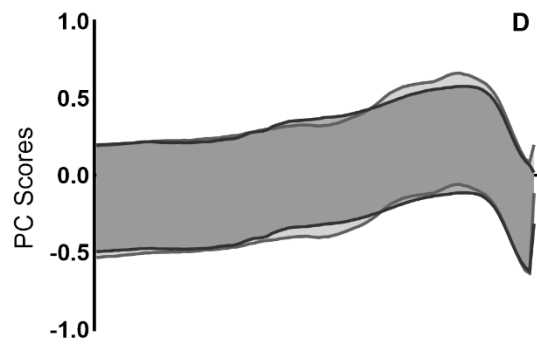
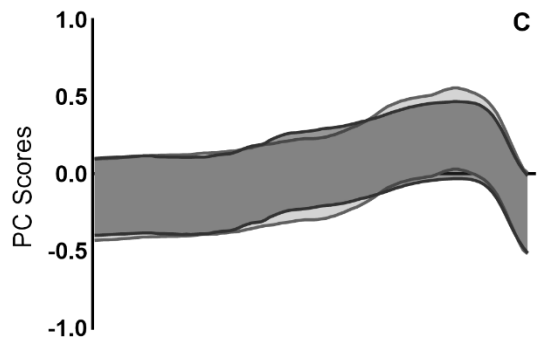
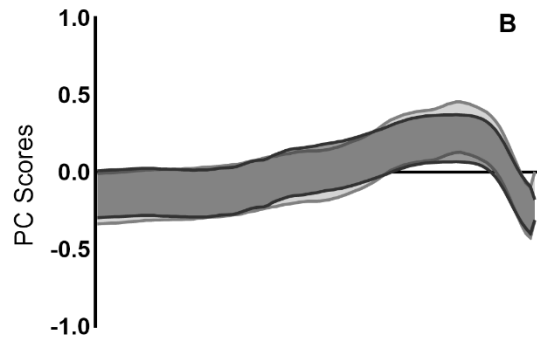
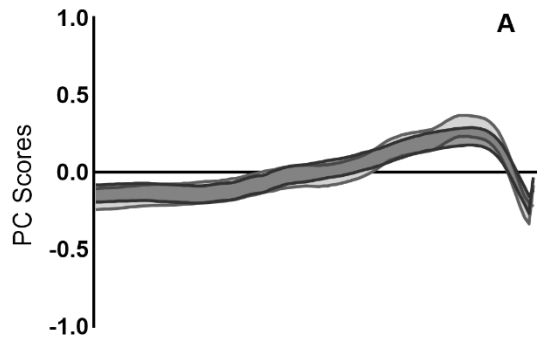
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