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## Validation of Markerless Strain-Field Optical Tracking Approach for Soft Tissue Mechanical Assessment --Manuscript Draft--

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<b>Abstract:</b>	<p>Strain measurement during tissue deformation is crucial to elucidate relationships between mechanical loading and functional changes in biological tissues. When combined with specified loading conditions, assessment of strain fields can be used to craft models that accurately represent the mechanical behavior of soft tissue. Inhomogeneities in strain fields may be indicative of normal or pathological inhomogeneities in mechanical properties. In this study, we present the validation of a modified Demons registration algorithm for non-contact, marker-less strain measurement of tissue undergoing uniaxial loading. We validate the algorithm on a synthetic dataset composed of artificial deformation fields applied to a speckle image, as well as images of aortic sections of varying perceptual quality. Initial results indicate that Demons outperforms recent Optical Flow and Digital Image Correlation methods in terms of accuracy and robustness to low image quality, with similar runtimes. Demons achieves at least 8% lower maximal deviation from ground truth on 50% biaxial and shear strain applied to aortic images. To illustrate utility, we quantified strain fields of multiple human aortic specimens undergoing uniaxial tensile testing, noting the formation of strain concentrations in areas of rupture. The modified Demons algorithm captured a large range of strains (up to 50%) and provided spatially resolved strain fields that could be useful in the assessment of soft tissue pathologies.</p>

## Cover Letter

We hereby declare that there is no duplicate publication elsewhere of any part of this work. There are no commercial relationships which might lead to a conflict of interests. The typescript has been read and agreed by all authors.

We hereby declare that all authors were fully involved in the study and preparation of the manuscript and the material within has not been and will not be submitted for publication elsewhere.

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## Response to Reviewers

The authors would like to thank the editor and reviewers for their time and efforts. The valuable comments have helped us improve the manuscript.

The original comments from the reviewers are shown in italics, with the corresponding response from the authors provided directly below in red.

### Reviewer #1 (Remarks to the Author):

1. *Title: "... Soft Tissue Mechanical Assessment" is suggested to be replaced with a more specific description "... Aortic Strain Assessment"*

We prefer to keep the title as is, because we are confident that this technique can be used for a wide variety of soft tissues. Making the title more specific could unnecessarily limit the target audience. Instead, we have clarified in the Abstract that we have only tested on aortic specimens and have edited the Discussion to clarify that the technique has the potential for application to other tissues and imaging techniques.

2. *Abstract seems no specific results and conclusions, please add them.*

We have added results and a concluding sentence to the abstract.

3. *Line 21: DIC show be replaced with digital image correlation.*
4. *All the definition of abbreviations should be checked (they should be only defined at first appearance from Introduction to Conclusion, please do not define repeatly (sic), e.g. Line 144 MSE; Line 160 SNRS, ...)*
5. *Line 176: "4°C" should be "4 °C"*
6. *Line 177: "20 mm x 5 mm" should be "20 mm × 5 mm" (the multiplication character is different from English alphabet x)*
7. *Line 183: "0.01N" should be "0.01 N"*
8. *Line 195: "50mm" should be "50-mm"*
9. *Line 197: "15cm" should be "15 cm"*
10. *Line 204: "28.005s" should be "28.005 s", "450x450" should be "450 × 450"*
11. *Line 243: "29dB" should be "29 dB"*
12. *Line 244: "310 x 310" should be "310 × 310"*

We apologize for these mistakes. These have been corrected.

13. *The font in all figures should be the same or close, e.g. in Figure 2 & 4, "A" and "B" look much larger than "C" and "D".*
14. *Figure 4: In figure legend, the format of "A", "B", ... is different from those in other figures, e.g. (A)*

We apologize for the formatting errors. These have been corrected.

15. *Figure 6: I think it should be better to identify tissue rupture combined with force changes, because the identification with background relies on sample thickness and transactional structure changes (the background may be still absent even rupture happens)*

We have edited the legends of Figure 6 and 7 that the green arrow indicates “visible evidence of rupture”. We have also clarified that we did in fact use the force curves, not visual cues, to determine when rupture happened.

16. *Figure 7: Please also show x-y axis in Figure 1A-right, and check the description of the first sentence of Figure 7 legend (it is hard to read).*

The first sentence has now been edited for more clarity.

Other minor edits were made.

# 1 **Validation of Markerless Strain-Field Optical Tracking Approach for Soft** 2 **Tissue Mechanical Assessment**

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## 12 **ABSTRACT**

13 Strain measurement during tissue deformation is crucial to elucidate relationships between mechanical  
14 loading and functional changes in biological tissues. When combined with specified loading conditions,  
15 assessment of strain fields can be used to craft models that accurately represent the mechanical behavior  
16 of soft tissue. Inhomogeneities in strain fields may be indicative of normal or pathological  
17 inhomogeneities in mechanical properties. In this study, we present the validation of a modified Demons  
18 registration algorithm for non-contact, marker-less strain measurement of tissue undergoing uniaxial  
19 loading. We validate the algorithm on a synthetic dataset composed of artificial deformation fields  
20 applied to a speckle image, as well as images of aortic sections of varying perceptual quality. Initial  
21 results indicate that Demons outperforms recent Optical Flow and Digital Image Correlation methods in  
22 terms of accuracy and robustness to low image quality, with similar runtimes. Demons achieves at least  
23 8% lower maximal deviation from ground truth on 50% biaxial and shear strain applied to aortic images.  
24 To illustrate utility, we quantified strain fields of multiple human aortic specimens undergoing uniaxial  
25 tensile testing, noting the formation of strain concentrations in areas of rupture. The modified Demons  
26 algorithm captured a large range of strains (up to 50%) and provided spatially resolved strain fields that  
27 could be useful in the assessment of soft tissue pathologies.

28 *Key words:* Strain field, Tensile test, Demons

29

30 *Abstract Word Count:* 215

31 *Total Word Count (Intro-Discussion):* 3456

32

33

## 34 **INTRODUCTION**

35 Knowledge of the mechanical properties of soft tissues, such as the aorta, is essential in understanding  
36 pathological and physiological behaviors and the effects of different disease states, treatments, and  
37 pharmacological agents. This characterization can aid in predicting or diagnosing cardiovascular diseases  
38 (Vorp, 2007). Due to its non-homogeneity, anisotropy, and ability to undergo finite deformations,  
39 complex constitutive laws are required to model soft tissue mechanical behavior (Chen, Zhao, Lu, &  
40 Kassab, 2013) (Khanafar, et al., 2011). Estimation of model parameters requires high-fidelity strain  
41 measurements to ensure accurate tissue characterization (Watton & Hill, 2007).

42 There have been numerous algorithms developed for biomedical non-rigid registration, the most notable  
43 of which are Optical Flow (OF) and Digital Image Correlation (DIC). OF is one of the most widely used  
44 registration algorithms for local motion estimation and strain field calculation. However, OF assumes  
45 brightness constancy, which leads to poor accuracy in varied lighting. In addition, most OF variants suffer  
46 from accuracy losses in frame differencing, which depend highly on local feature speeds. DIC has  
47 emerged as a standard technique for soft tissue mechanical assessment. However, since DIC is reliant  
48 upon cross-correlation to determine shifts between images, the application of markers (Choudhury, et al.,  
49 2009) (Huang, Korhonen, Turunen, & Finnila, 2019) or textured surface finishes (Barranger, Doumalin,  
50 Dupré, & Germaneau, 2010) is necessary to provide sufficient contrast to correlate images well without  
51 phase ambiguity. Most soft tissues lack sufficient texture for DIC to be robust without surface preparation  
52 (Palanca, Tozzi, & Cristofolini, 2016). Attaching markers can modify material properties and may suffer  
53 from unreliable adherence to wet tissues.

54 In this study, we have investigated non-rigid registration techniques to overcome these issues. One  
55 popular class of algorithms for non-rigid registration is the Demons algorithm, which models the  
56 matching of two images as a diffusion process (Thirion, 1998). Further work has constrained the  
57 optimization scheme in Thirion's Demons to only diffeomorphic mappings (Vercauteren, Pennec,  
58 Perchant, & Ayache, 2009) by providing a Lie pseudo-group structure on the space of diffeomorphisms.  
59 This mathematical reformulation allows the displacement field to be efficiently calculated by the fast  
60 vector exponential of the flow field and converges to smooth, invertible transformations (Bossa, Zacur, &  
61 Olmos, 2008). Diffeomorphic Demons could therefore provide a promising framework for the estimation  
62 of strain fields of biological surfaces.

63 The goal of this study is to modify and apply an existing non-parametric image registration algorithm to  
64 calculate the marker-less deformation of soft biological tissues. We propose a modified Diffeomorphic  
65 Demons registration and strain tracking algorithm to compute two-dimensional strain fields from uniaxial  
66 tensile tests of aortic tissue using only the natural optical features of the tissue. We validate the modified  
67 Demons algorithm by measuring the convergence of the calculated strain field to a predefined strain field  
68 of an artificial dataset, created by applying linear biaxial as well as shear strain to a speckled image. We  
69 then compare the robustness of the modified Demons algorithms to standard DIC and OF algorithms on  
70 images of aortic aneurysm samples with varying surface quality (the number of discernable structures and  
71 grain boundaries, as well as the amount of texture). We also investigate the effects of downsampling and  
72 white noise injection on the performance of the Demons, DIC, and OF algorithms. Lastly, we use the  
73 modified Diffeomorphic Demons algorithm to measure the deformation of human aortic aneurysm  
74 specimens undergoing tensile testing. Hereafter, we refer to the modified Diffeomorphic Demons  
75 algorithm simply as "Demons".

76

77

78 **2. MATERIALS AND METHODS**

79

80 **2.1 Demons Strain Tracking Algorithm and Validation Testing**

81

82 Demons registration and strain tracking algorithm is proposed to compute two-dimensional strain fields  
83 from images acquired during uniaxial tensile tests of aortic aneurysm samples, using only the native  
84 optical features of the tissue. The strain fields are determined by Demons according to the protocol below:

85 **I.** Images are acquired during tensile testing at a frequency of 0.1 Hz. To better illuminate the  
86 sample, a near-UV LED light (395 nm, 20 W, 1200 lumens) is used, with blackout screens  
87 surrounding the testing chamber to block ambient light. After testing, the images are converted  
88 into 16-bit greyscale format and histogram intensities of each image pair are matched to account  
89 for LED flicker.

90 **II.** Demons (Cahill, Noble, & Hawkes, 2009) (Verauteren, Pennec, Perchant, & Ayache, 2009) is  
91 used to register the second (moving) image in the pair to the first (fixed) image (Thirion, 1998).  
92 The loss function implemented across each iteration is the Mean Square Error (MSE) of the  
93 intensity fields. This is calculated between the warped fixed image and moving image, without a  
94 regularization term, which is typically the gradient norm of the transformation. A sufficiently  
95 smooth displacement field is instead achieved by iterative Gaussian filtering of each step update  
96 to the flow fields. This results in a simpler loss function that is in most cases easier to solve, while  
97 still providing stable solutions. A Gradient Descent with Warm Restarts (GDR) solver is  
98 implemented (Loshchilov & Hutter, 2017) to optimize the loss function. Warm restarts are  
99 achieved by momentarily increasing the learning rate if the loss function was either steadily  
100 increasing or stalling.

101 Usually a Gauss-Newton solver is used, however, its performance noticeably deteriorates as the  
102 number of variables increases, due to the ill-posed approximation of the Hessian. Gradient



103 Descent (GD) methods offer a simple, computationally efficient way of minimizing the loss  
104 function, with nearly global convergence properties under mild conditions. Furthermore, with  
105 warm restarts, GD methods can escape non-optimal submanifolds (Chizat & Bach, 2018).

106 In this study, a configuration of 4 pyramid levels, with up to 5000 iterations and 8 restarts per  
107 level, and an accumulated field smoothing parameter of 3.0 were used. These hyperparameters  
108 were increased to the point of diminishing returns in terms of algorithm performance. In general,  
109 more pyramid levels, iterations, and restarts lead to higher accuracy, but longer computational  
110 time. A larger smoothing parameter provides greater regularization.

111 **III.** For an image sequence (more than two images), the image pixels are iteratively tracked and  
112 updated via the calculated displacement fields, generated for each  $k^{\text{th}}$  frame, showing the x and y  
113 distance each pixel moves from the  $k^{\text{th}}$  frame to the  $(k+1)^{\text{th}}$  frame. If the effect of the pixels  
114 moving is not considered, the displacements will be erroneously attributed to pixels further afield.  
115 Therefore, a total displacement field is generated, which tracks the x and y distance each pixel  
116 travels from the 1<sup>st</sup> frame to the  $(k+1)^{\text{th}}$  frame. It is calculated by iteratively warping the total  
117 displacement field with the displacement field of the  $k^{\text{th}}$  frame to update locations. Warping is  
118 executed via inverse mapping, which modifies the spatial coordinates of each input pixel via the  
119 displacement field found by Demons, followed by bicubic interpolation to determine the output  
120 pixel value.

121 **IV.** A triangular mesh grid is generated from equidistant points with stride lengths of 5 pixels  
122 along the image. This mesh size is changed programmatically for each trial to ensure accurate  
123 performance. In general, smaller elements are prone to noise, but larger elements do not  
124 sufficiently characterize the strain heterogeneity. Triangulation of the mesh is optimized using the  
125 Delaunay method, which maximizes the minimum angle of all angles of the triangular mesh  
126 elements. The triangulation implementation is based on a variant of the Quickhull algorithm

127 (Barber, Dobkin, & Huhdanpaa, 1996), which regularizes the grid, simplifying indexing of strain  
 128 elements.

129 V. Each mesh element in the moving image is matched with its homologous element in the fixed  
 130 image to calculate the two-dimensional Green-Lagrange strain tensor,  $\mathbf{E}$  (Hiorns, et al., 2016).

$$131 \quad \mathbf{E} = \frac{1}{2} [(\nabla_{\mathbf{x}} \mathbf{u})^T + \nabla_{\mathbf{x}} \mathbf{u} + (\nabla_{\mathbf{x}} \mathbf{u})^T \cdot \nabla_{\mathbf{x}} \mathbf{u}]$$

132 Where  $\nabla_{\mathbf{x}} \mathbf{u}$  is the gradient displacement tensor.

133 In 2D:

$$134 \quad \mathbf{E} = \begin{bmatrix} \mathbf{E}_{xx} & \mathbf{E}_{xy} \\ \mathbf{E}_{xy} & \mathbf{E}_{yy} \end{bmatrix}$$

$$135 \quad \mathbf{E}_{xx} = \frac{\partial u}{\partial X} + \frac{1}{2} \left[ \left( \frac{\partial u}{\partial X} \right)^2 + \left( \frac{\partial v}{\partial X} \right)^2 \right]$$

$$136 \quad \mathbf{E}_{yy} = \frac{\partial v}{\partial Y} + \frac{1}{2} \left[ \left( \frac{\partial u}{\partial Y} \right)^2 + \left( \frac{\partial v}{\partial Y} \right)^2 \right]$$

$$137 \quad \mathbf{E}_{xy} = \frac{1}{2} \left( \frac{\partial v}{\partial Y} + \frac{\partial u}{\partial X} \right) + \frac{1}{2} \left[ \left( \frac{\partial u}{\partial X} \frac{\partial u}{\partial Y} \right) + \left( \frac{\partial v}{\partial X} \frac{\partial v}{\partial Y} \right) \right]$$

138  
 139 The strain-tracking pipeline outputs a frame-by-frame analysis of x-strain, y-strain, and shear strain  
 140 magnitudes, including a contour map of strain elements for each Green-Lagrange strain component  
 141 (Olufsen & Andersen, 2019).

142 To validate the Demons algorithm, predefined strain fields of biaxial and shear strains of up to 50% were  
 143 applied to a 450x450 speckled image. The strain fields of the speckled image were calculated by Demons,  
 144 and the convergence of the calculated strain field was compared to the predefined strain field of the  
 145 artificial datasets. Maximal deviations, maximal standard deviation, and Pearson's Correlation  
 146 coefficients were recorded for the biaxial and shear strain dataset (Table 1). Maximal deviations were  
 147 calculated as the absolute difference between the predefined mean strain and mean strain given by  
 148 Demons. Maximal standard deviation was defined in the spatial sense. The Pearson's Correlation  
 149 Coefficient served as an additional accuracy metric for the algorithm validation. The effects of noise

150 injection and downsampling were also assessed at 5% biaxial strain, with respect to the MSE.  
151 Downsampling was achieved via bicubic interpolation. Signal-to-noise ratios (SNRs) between 10 and 30  
152 dBs and downsampling factors between 0.2 and 1 were considered.

## 153 **2.2 Validation Testing with DIC and OF Methods**

154 Methods from the Python library  $\mu$ DIC (Olufsen & Andersen, 2019) (Brox, Bregler, & Malik, 2009) were  
155 implemented to induce artificial deformations of up to 50% biaxial strain on two sample aortic tissue  
156 images, which had differing image quality with respect to the natural optical features for tracking. The  
157 image pair was chosen to assess the effect of image quality, measured by Perception Based Image Quality  
158 Evaluator (PIQE) scores, on the performance of Demons. To evaluate image quality, PIQE scores were  
159 measured. For comparison testing, standard OF and DIC methods were implemented. The OF method  
160 uses Large Displacement Optical Flow (LDOF), a variational coarse-to-fine algorithm that includes  
161 correspondences from sparse feature matching (Brox, Bregler, & Malik, 2009). The DIC method used  
162 (from the  $\mu$ DIC library) is a global DIC algorithm with a modified Newton-Raphson optimization scheme  
163 and B-spline discretization of deformation fields. The calculated strain field determined by Demons, OF,  
164 and DIC methods were compared for the artificial dataset. In addition, maximal deviations, maximal  
165 standard deviations, and Pearson's Correlation Coefficients were recorded for both images for Demons,  
166 OF, and DIC methods. The effects of noise injection and downsampling on MSE were evaluated at 5%  
167 biaxial strain, with SNRs between 10 and 30 dBs and downsampling factors between 0.2 and 1 assessed.

## 168 **2.3 Testing of Human Aortic Aneurysm Tissue**

169 Patients undergoing surgery for proximal aortic aneurysms (either root or ascending aorta) were recruited.  
170 The study received ethical approval from the Health Research Authority and Regional Ethics Committee  
171 (17/NI/0160) and was sponsored by the Imperial College London Joint Research and Compliance Office,  
172 as defined under the sponsorship requirements of the Research Governance Framework (2005).  
173 Participating UK healthcare organizations conducted a rigorous process of assessing capacity and

174 capability prior to issuing study approval. Human tissue was acquired and stored according to local  
175 guidelines in adherence to the Human Tissue Act.

176 Specimens were obtained *en-bloc* and acquired immediately after surgical excision in the operating  
177 theatre. Thin (~5 mm axial length) circumferential portions of the tissue were carefully dissected and  
178 immersed in formalin solution for fixation. The remainder of the aortic specimen was immersed in a 10%  
179 dimethyl sulfoxide (DMSO) in phosphate buffered saline (PBS) solution and stored within an hour in a -  
180 80 °C freezer (Bia, et al., 2006) (Figure 1).

181 Aortic tissue specimens were defrosted in a 4 °C refrigerator for 24 hours prior to testing. After thawing,  
182 samples were cut longitudinally and circumferentially into twelve 20 mm x 5 mm dogbone subsections,  
183 with a gauge length of 10 mm. We use “specimen” to describe the whole aortic tissue sample obtained  
184 from surgery. “Subsection” denotes a dogbone-shaped portion of the single tissue specimen, excised and  
185 used specifically in tensile testing. All subsections were tested using a TestResources USA R-Series  
186 Controller (Frame model no. 120R225; Transducer model no. SMT-1.1-294) in a 37 °C phosphate  
187 buffered saline (PBS) bath (Figure 1). The subsections were mounted lengthwise onto serrated clamps  
188 and imaged from the intimal side. A preload force of 0.01 N was used for both preconditioning and  
189 testing. Preconditioning was performed on all subsections following a similar protocol outlined in Garcia-  
190 Herrera *et al*, 2012. The subsection was cycled between 0% to 20% strain for five cycles at a crosshead  
191 speed of 2 mm/minute. After preconditioning, the subsection was tested at 2 mm/minute until sample  
192 rupture. Both the clamp displacement and force were recorded. The crosshead speed of 2 mm/minute is  
193 based off prior literature on tensile testing of aortic tissue (Sommer et. al, 2016). In total, five subsection  
194 samples were tested in this study; a comprehensive evaluation was conducted with a single aortic  
195 subsection, and four aortic subsections (two axial and two circumferential subsections) were additionally  
196 tested to assess method reproducibility.

197 [Figure 1 about here.]

198

199 For strain field analysis, the single-test aortic subsection was imaged using a Canon EOS 90D DSLR with  
200 a 50 mm f1.8 STM lens, and the 4 aortic subsections used in the reproducibility study were imaged using  
201 a 12 Megapixel Mako camera (Allied vision) with a fixed distortion-corrected lens. The cameras were  
202 placed 15 cm from the subsection loaded in the clamps, and images were acquired at a frequency of 0.1  
203 Hz. The strain fields were calculated for each consecutive image pair in the sequence.

204

205

### 206 **3. RESULTS**

207

#### 208 **3.1 Demons Strain Tracking Algorithm and Validation Testing**

209 The strains calculated by the Demons algorithm accurately reproduced the known strain fields in both  
210 tension and shear of an artificially strained speckle image (Figure 2). The runtime of the Demons method  
211 was 28.005 s on one active 2.9 GHz Intel i7 core for one pair of  $450 \times 450$  16-bit greyscale images. As  
212 shown in Figure 2, for both the applied biaxial tension and shear strains, the Demons strains coincide with  
213 the unity line of the known strain fields, with slopes of 1.003 and 1.030, respectively (Table 1). In  
214 addition, the Pearson's correlation coefficient, an overall accuracy metric, was above 0.999 for both tests,  
215 indicative of a strong correlation between the calculated and known strain datasets.

216 While both tests were considered successful, Demons was more robust to normal than pure shear strain  
217 field assessment. The spatial standard deviations increased with strain for both tests, but the mean errors  
218 between known and derived strains were higher in the shear test, as expressed by the slightly lower  
219 Pearson's correlation coefficients shown in Table 1. For the biaxial tension test, a maximum standard  
220 deviation of 1.38% was determined in the normal direction (Table 1). In contrast, the maximal standard  
221 deviation was marginally higher in the shear direction during the shear test, at 1.83%.

222

[Figure 2 about here.]

223 [Table 1 about here]

224

225 The effects of image resolution and white noise injection were assessed on the speckle image at 5%  
226 biaxial strain (Figure 3). Overall, the Demons algorithm was robust to downsampling, though the MSE  
227 began to increase with a downsampling factor less than 0.5. Decreasing the image SNR adversely affected  
228 the MSE, particularly below 26 dB.

229 [Figure 3 about here.]

### 230 **3.2 Validation Testing with DIC and OF Methods**

231 The performance of Demons was superior to DIC and OF methods in estimating the strains of an artificial  
232 biaxial tension strain field applied to two aortic aneurysm tissue images (Figure 4a and b). The two  
233 images were of differing quality and assessed by PIQE scores, where lower scores indicate higher quality  
234 images; Images 1 and 2 had PIQE scores of 28.19 and 61.92, respectively. For both images, the Demons  
235 algorithm outperformed both OF and DIC in terms of spatial error between the known and calculated  
236 strain fields, as well as spatial standard deviations, at higher strain fields (Figure 4c-f). When compared to  
237 the unity line of the known strain field of Image 1, Demons had a slope of 0.986, where DIC and OF  
238 methods had slopes of 0.810 and 0.642, respectively (Table 2). Demons similarly outperformed DIC and  
239 OF methods when compared to the unity line of the known strain field of Image 2, with a slope of 0.981  
240 achieved for the Demons algorithm, compared to 0.672 and 0.690 for DIC and OF methods, respectively.  
241 Overall, Demons achieved significantly lower maximal absolute deviations and spatial standard  
242 deviations, as well as higher Pearson's correlation coefficients, compared to OF and DIC (Table 2).  
243 Despite the lower quality of Image 2, there was only a small change in the standard deviations and  
244 Pearson's coefficients in the strain predictions from the Demons algorithm, demonstrating Demons'  
245 robustness to variation in image quality.

246 [Figure 4 about here]

247 [Table 2 about here]

248

249 Both Demons and OF outperformed DIC with respect to both noise injection and downsampling (Figure  
250 5). Demons and OF were equally resilient to noise, performing similarly with SNR values less than 29  
251 dB. Demons was more robust to downsampling than DIC and OF methods, up to a scale of 0.6 ( $310 \times 310$   
252 pixels). With further downsampling, OF slightly outperformed Demons.

253

[Figure 5 about here]

### 254 **3.3 Testing of Aortic Aneurysm Tissue**

255 The human aortic aneurysm tissue sample was tested until failure, with rupture occurring at a recorded  
256 clamp strain of 42%, corresponding to frame 19 of 24 in Figure 6. Failure occurred in the upper portion of  
257 the sample near the clamp. The corresponding strain field maps at rupture, as determined by Demons,  
258 highlighted the location of rupture, with localized pockets of up to 95%  $y$ -normal strain observed (Figure  
259 7). The mean normal and shear strains as determined by Demons exhibited variations due to the  
260 inhomogeneity of the arterial tissue at all strain levels, with the variations increasing near rupture. Overall,  
261 the clamp strain and the Demons  $y$ -strain approximately coincided, with mean Demons strain values being  
262 slightly higher than clamp strain (Figure 7). Recall that the Demons strain estimation is based on Green's  
263 strain, and thus differs from the engineering strain basis of clamp strain due to the additional higher order  
264 terms in the Green-Lagrange strain calculations.

265

[Figures 6 & 7 about here.]

266

267 After rupture, strain in the  $y$ -direction sharply decreased, which was also marked by a sharp discontinuity  
268 in the load curve. The elastic portion of the strain curve displayed hyperelastic, strain-stiffening behavior  
269 until rupture, which is common for arterial tissue. (Xiong, Wang, Zhou, & Wu, 2008) (Sokolis,  
270 Boudoulas, & Karayannacos, 2002) (Roach & Burton, 1957).

271

272 To assess the robustness of the Demons algorithm to different sample images, four additional aortic  
273 aneurysm dogbone samples were tested, with the corresponding strain assessed by Demons. As shown in  
274 Figure 8, the mean normal Demons strain in the y-direction increased monotonically with clamp strain in  
275 a manner similar to the results shown in Figure 7.

276 [Figure 8 about here.]

277

278

## 279 **DISCUSSION**

280

281 To the best of the authors' knowledge, this was the first application of a Demons-based registration  
282 algorithm to compute strain fields of deforming soft tissue undergoing tensile loading. Demons was  
283 successful in strain field computation and was able to fully capture the local dynamic behavior of aortic  
284 tissue deformation. The proposed pipeline presents a modified way of solving the Demons registration  
285 problem by simplifying the loss function and implementing an adaptive gradient descent solver, which  
286 increases the robustness of the algorithm and computational speed. When compared to other standard  
287 strain tracking methods, namely DIC and OF, the Demons algorithm outperformed both in terms of error  
288 between the known and calculated strain fields. Based on the results of this study, Demons should be  
289 applicable as a marker-less assessment of other soft tissue types. Our aortic specimens provided an  
290 appropriate test case tissue for the algorithm, since the intimal surfaces of blood vessels are generally  
291 smooth and featureless to the naked eye.

292 For this specific application, Demons was able to capture the evolving strain fields of aortic aneurysm  
293 tissue undergoing uniaxial tensile tests. All five samples tested demonstrated similar hyperelastic, strain-  
294 stiffening behaviors, with local strain fields that coincided with spatial points of rupture and with  
295 increasing strain field heterogeneity. Mean normal Demons strain in the y-direction increased  
296 monotonically with clamp strain. Mean normal y-strain fields also displayed a Demons strain/clamp strain



297 slope of approximately one at low strains, which is expected for hyperelastic materials. Deformation  
298 inhomogeneities were also captured; pockets of extreme Demons strain visually coincided with the local  
299 area of rupture.

300 At higher strains, the calculated Demons strain was greater than the clamp strain, the degree of which  
301 varied between the tested samples. Part of this deviation between the Demons and clamp strain is due to  
302 differing strain definitions, where Demons expression is based on Green's strain and clamp strain  
303 implements an engineering basis. However, the broad range of strain determined by Demons suggests a  
304 biomechanical contribution to this variation. It is theorized that micro-tears occur within the tissue sample  
305 at higher strains, leading to localized areas of high deformation. These are subsequently captured by the  
306 Demons algorithm, contributing to the overall increase in mean strain. This phenomenon is evident when  
307 analysing the box plots of the tested samples at higher strains; the strain range is large with a right-skewed  
308 distribution. These localized micro-tears would not impact the global behaviour of the sample recorded by  
309 tensile machine, as they would have minimal impact on the loading bearing capability of the sample, and  
310 are not reflected in the load curve as a result. These observations emphasize the inaccuracies of utilizing  
311 clamp strain to represent the strain field of soft tissues.

312 The large range in strain of all five samples tested raises an interesting question of how best to  
313 characterize the resulting strain field of aortic tissue when using optical strain tracking. For all samples  
314 tested, the strain distribution was right-skewed, with the mean consistently higher than the median; the  
315 degree of skewness also varied between samples due to tissue inhomogeneity. Depending on the desired  
316 objectives of a proposed study, the best metric to represent the strain field may vary. The importance of  
317 this aspect of study design is evident when analyzing the results of the Demons pipeline presented in this  
318 work.

319 The current runtime of the proposed method has been significantly improved via parallelization (each  
320 image pair is registered in parallel), with speeds comparable to OF and DIC. However, 85% of its run  
321 time is spent on image warping, used repetitively in calculating the vector exponential of the flow field

322 (Bossa, Zacur, & Olmos, 2008) and the loss function, as well as updating the flow and displacement  
323 fields. Future work could involve writing a GPU implementation to speed up the repetitive warping  
324 (Rosner, Fassold, Schallauer, & Bailer, 2010). We have achieved better performance by omitting a  
325 regularization term in the loss function, most likely because tissue micro-tearing that occurs during tensile  
326 loading violates smoothness constraints. Different regularization frameworks, dependent upon  
327 deformation behavior, should be considered.

328 Like many optical strain estimation algorithms, the current protocol struggled to characterize large  
329 displacements between consecutive frames, particularly compared to OF. This can be accounted for by  
330 imaging at a sufficiently high frame rate to ensure that strains between consecutive frames do not exceed  
331 15%. While DIC also has this limitation, variational OF can correctly characterize large displacements by  
332 considering feature matching. Future work could involve utilizing spectral correspondences, such as those  
333 used in Spectral Log-Demons (Lombaert, Grady, Pennec, Ayache, & Cheriet, 2017), to include global  
334 information in the minimization scheme.

335

336

## 337 **CONCLUSION**

338

339 The proposed Demons algorithm generates robustly estimated strain fields from image sequences of  
340 uniaxial tensile tests of unmarked human aortic aneurysm tissue. A synthetic dataset was utilized to  
341 validate the algorithm, and real data from uniaxial tensile tests of aortic aneurysm subsections  
342 demonstrated its utility and reproducibility. The results show the efficacy of using an image-based  
343 algorithm to calculate strain fields directly from a monochromatic image sequence of aortic tissue  
344 undergoing a uniaxial tensile test. These strain measurements are particularly valuable in the assessment  
345 of aortic tissue pathologies, such as atherosclerosis, leading to better understanding of associated  
346 conditions like aortic dissection.

347

348 **CONFLICT OF INTEREST STATEMENT:**

349 All listed authors declare no conflict of interest.

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351

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## LIST OF FIGURES

- 1** Explanted human aortic sample (**A** - left). Dogbone-shaped subsection (**A** - middle) are cut out for mechanical testing. An image of a portion of a dogbone subsection (**A** - right) was used for validation. (**B**) shows the test rig used for uniaxial tensile loading. Aortic subsections were attached with serrated clamps. Clamp strain was recorded continuously, and images were captured every 10 seconds.
- 2** An artificial biaxial strain field (maximum 50% strain) was applied on a speckled image (**A**) for 50 frames, and strains were assessed using the Demons algorithm (**C**). Similarly, an artificial shear strain field (maximum 50% strain) was applied on the speckled image (**B**) for 50 frames, and strains were calculated (**D**). Red arrows indicate directionality of strain fields in (**A**) and (**B**). Average of the normal strain components are calculated as  $\frac{1}{num\_pixels} \left\{ \sum_{pixels} \frac{E_{xx} + E_{yy}}{2} \right\}$  and the average shear strain components are calculated as  $\frac{1}{num\_pixels} \left\{ \sum_{pixels} E_{xy} \right\}$ .
- T1** Maximal deviation, maximal standard deviation, Pearson's Correlation coefficients, and best-fit slopes (regression coefficients) of normal and shear strain fields calculated with the Demons algorithm for up to 50% biaxial and shear strain applied to a speckle image.
- 3** Log-scale mean-squared error vs. downsampling factor (**A**) and signal-to-noise ratio (**B**) were analyzed for a 5% biaxial strain field on the speckle image.
- 4** Comparison of performance of Demons, OF, and DIC on the two aortic subsample images undergoing artificial biaxial strain. Image 1 with a low PIQE score is displayed in (**A**), and Image 2 with a high PIQE score is displayed in (**B**). (**C**) and (**D**) display mean calculated horizontal strains of the three algorithms for Images 1 and 2 respectively. (**E**) and (**F**) display mean calculated shear strains of the three algorithms for Images 1 and 2 respectively. Error bars represent 1 standard deviation for all plots.
- T2** Maximal deviation, maximal standard deviation, and Pearson's Correlation coefficients, and best-fit slopes (regression coefficients) of normal and shear strain fields calculated with Demons, OF, and DIC for up to 50% biaxial and shear strain applied to the two aortic images in Figures 5A and B.
- 5** Log-scale mean-squared error vs. downsampling factor (**A**), and noise (**B**) for aortic image 1 (Figure 4A). OF shows higher robustness to lower resolutions (higher downsampling) than both Demons and DIC, however demons outperform both OF and DIC at higher resolutions. Demons and OF show comparable robustness and accuracy to noise injection.

- 6** Uniaxial tensile test of a human aortic tissue subsection. Visible rupture occurs in the 19<sup>th</sup> frame, where there was a sharp decrease in tension. The region of interest (ROI) (highlighted in yellow in frame 19) for strain-field analysis is confined to the maximal area of the image with only tissue present (absent of any background) before tearing. The area of initiation of tearing is indicated by the green arrow.
  
- 7** Strain tracking was applied to an ROI (Figure 1A) of the aortic tissue subsection in Figure 7, which undergoes tensile loading until rupture. The strain fields of the ROI at rupture (determined from the decrease in tension to occur at frame 19, clamp strain 42%) are shown at left, with the green arrow indicating visible evidence of the point of rupture. Plots of x strain (top right), applied load and y- strain (middle right), and shear strain (bottom right) include box plots showing the 25<sup>th</sup> percentile, median, 75<sup>th</sup> percentile, and range of the strain components, accompanied by the mean strain values (continuous blue curves). The nonlinearity of the force curve is due to strain-stiffening, a well-observed behavior in arterial tissue. Variations in strain field are mainly due to tissue inhomogeneities.
  
- 8** Strain tracking was applied to 4 different subsections from one chosen patient case (Subsection 1-4), with the same plot formats and parameters as in Figure 10. Strain measurements are shown up to the point of rupture.

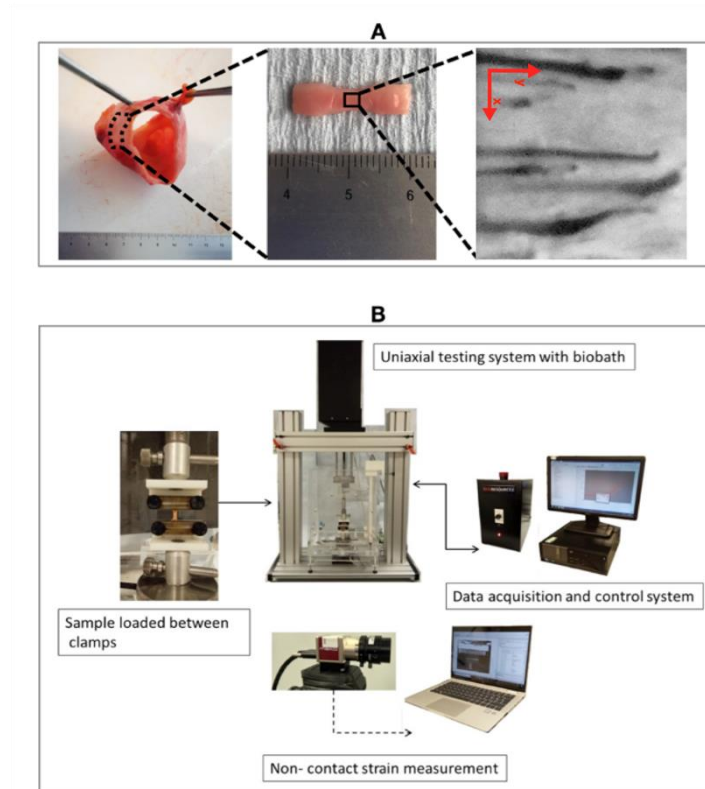


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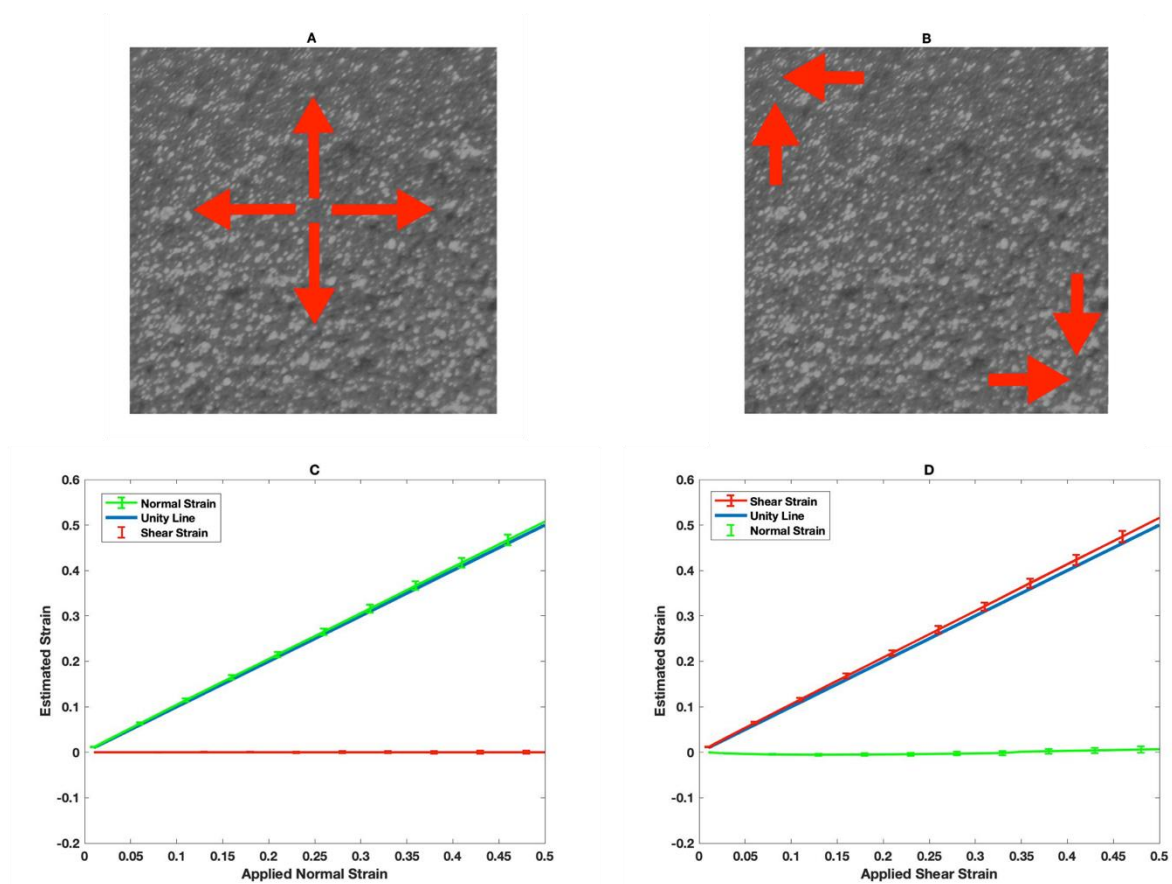


Figure 2. An artificial biaxial strain field (maximum 50% strain) was applied on a speckled image (A) for 50 frames, and strains were assessed using the Demons algorithm (C). Similarly, an artificial shear strain field (maximum 50% strain) was applied on the speckled image (B) for 50 frames, and strains were calculated (D). Red arrows indicate directionality of strain fields in (A) and (B). Average of the normal strain components are calculated as

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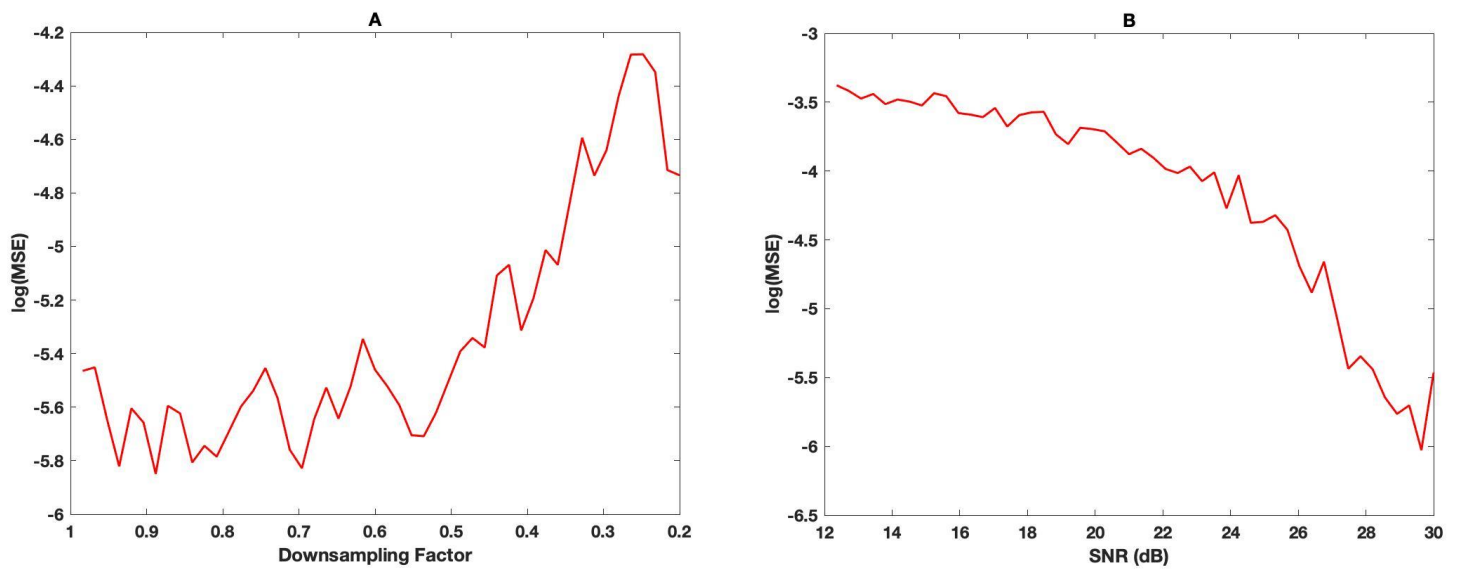


Figure 3. Log-scale mean-squared error vs. downsampling factor (A) and signal-to-noise ratio (B) were analyzed for a 5% biaxial strain field on the speckle image.

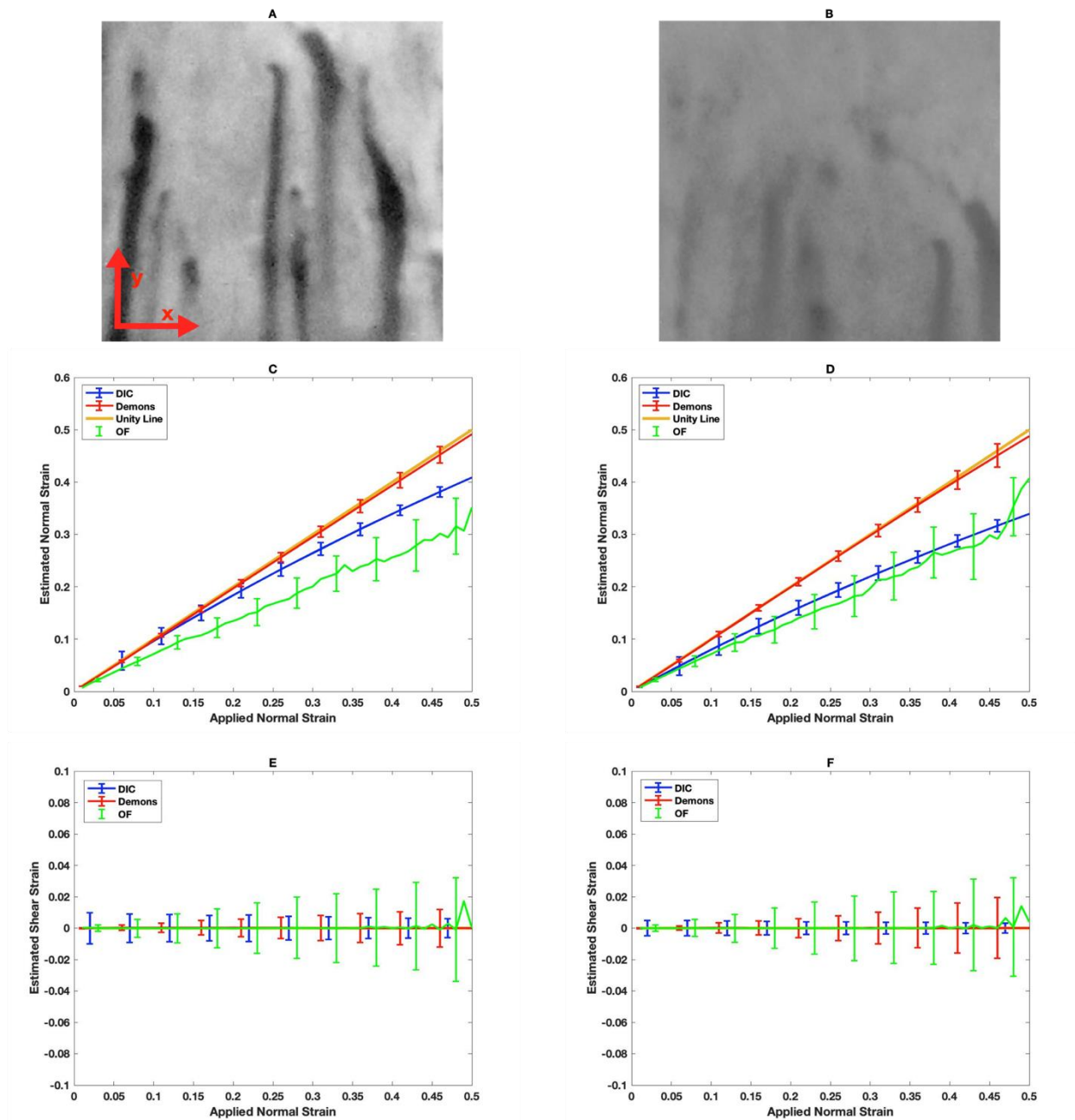


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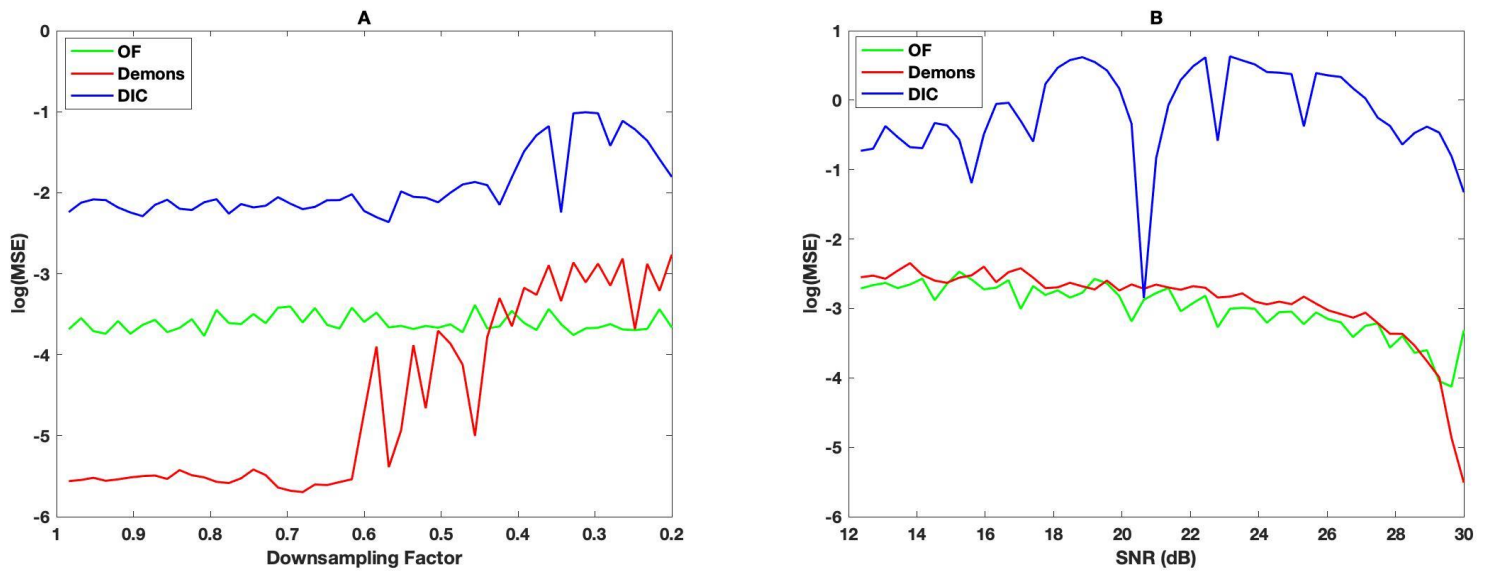


Figure 5. Log-scale mean-squared error vs. downsampling factor (**A**), and noise (**B**) for aortic image 1 (Figure 4A). OF shows higher robustness to lower resolutions (higher downsampling) than both Demons and DIC, however demons outperform both OF and DIC at higher resolutions. Demons and OF show comparable robustness and accuracy to noise injection.

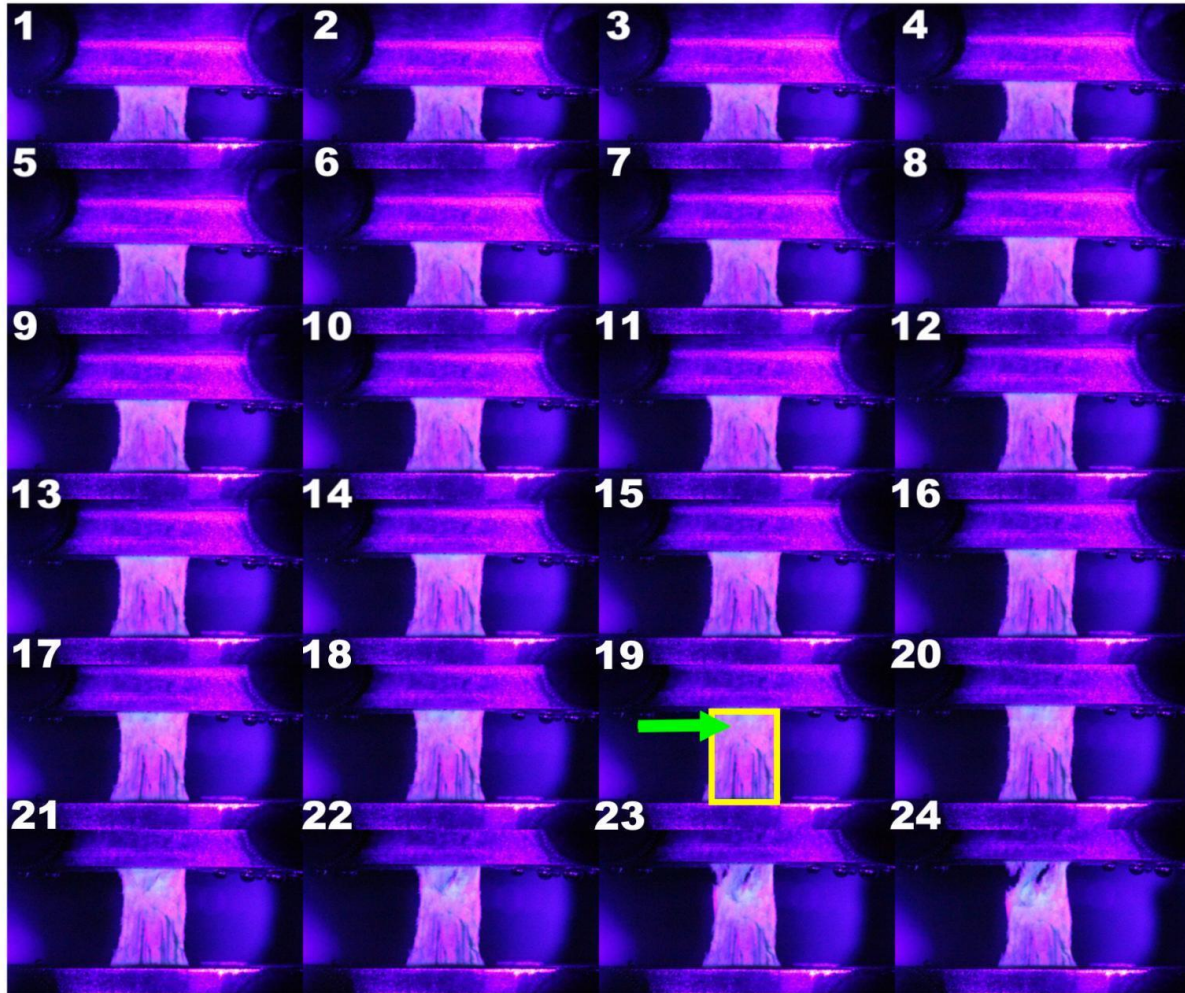


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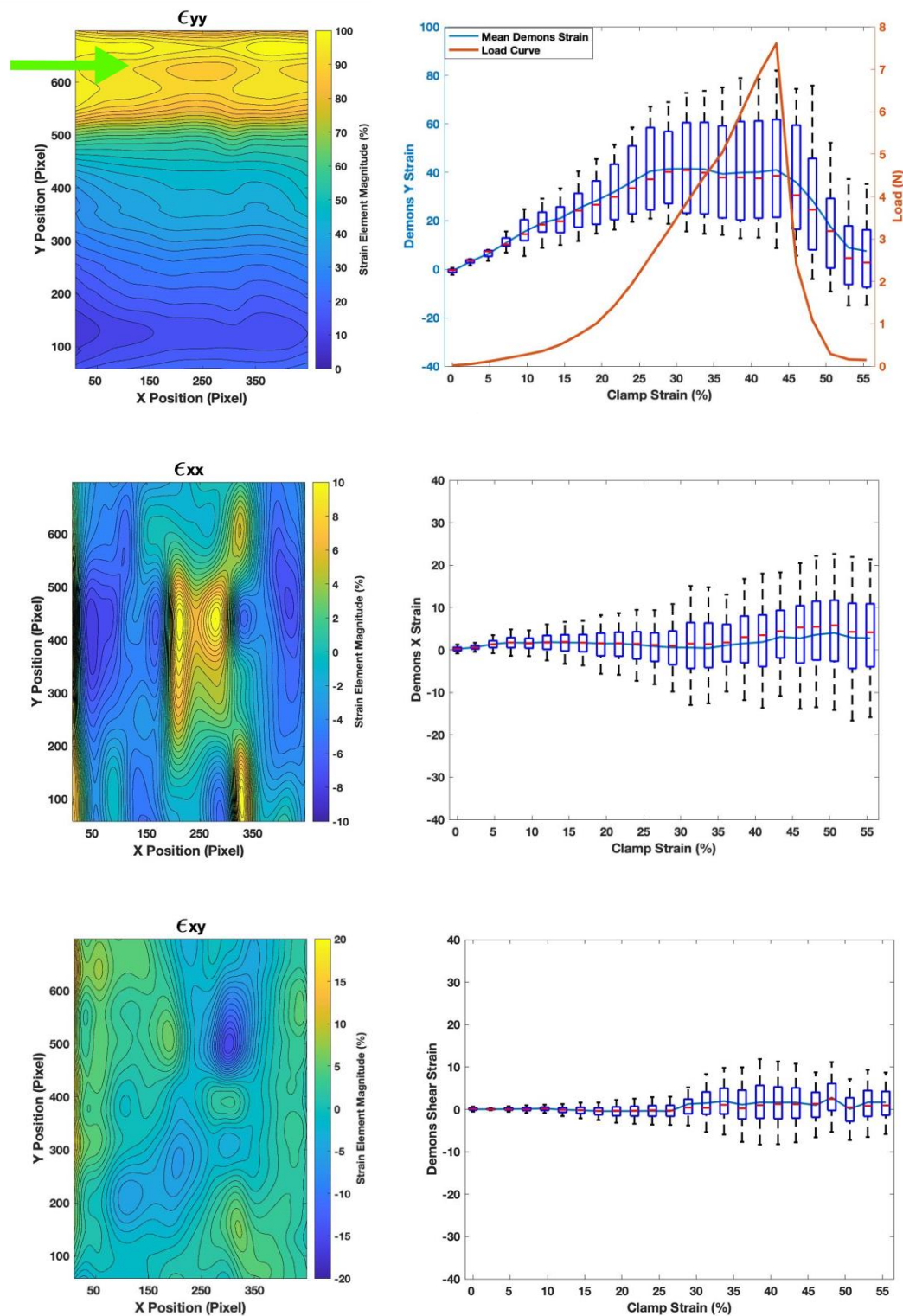


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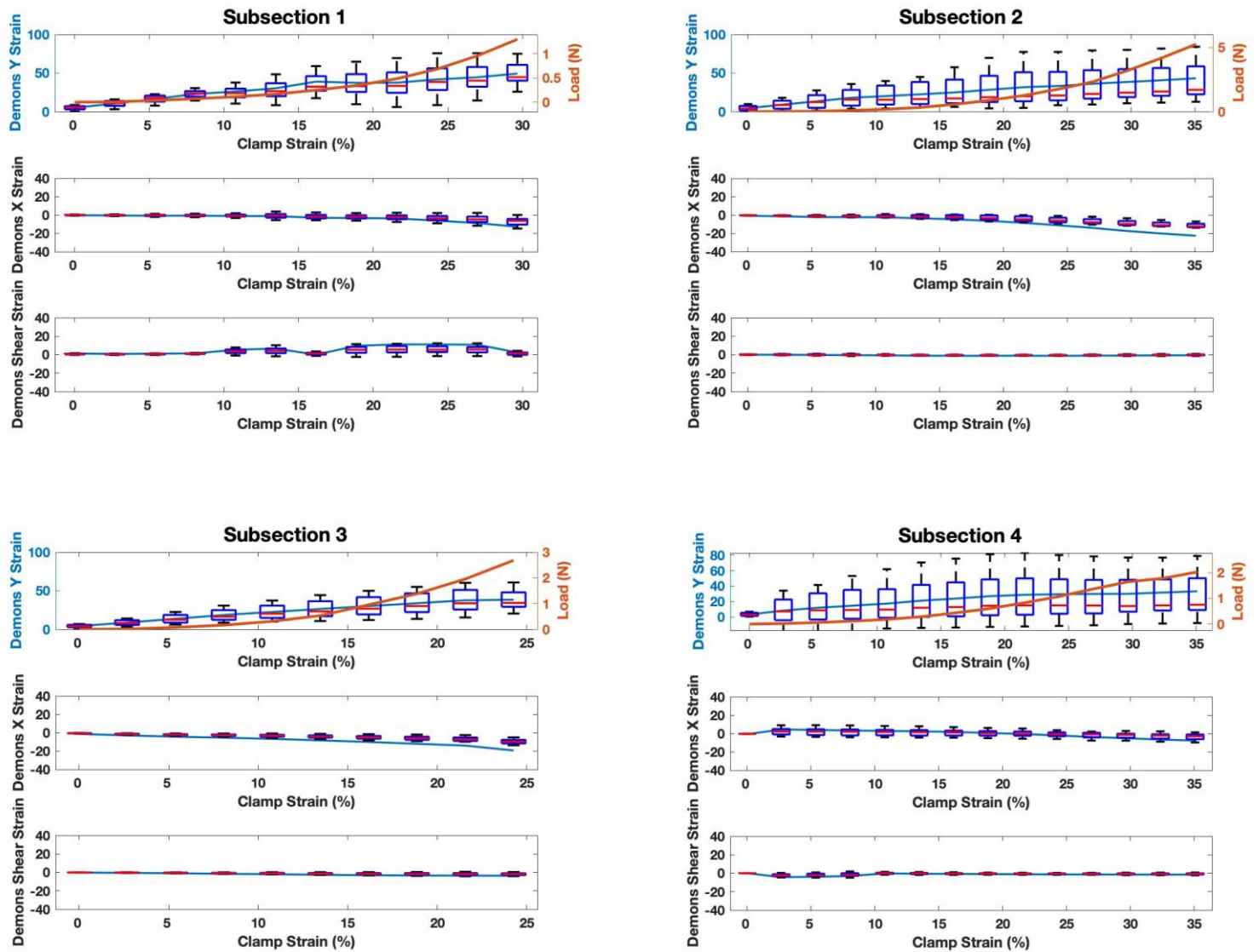


Figure 8. Strain tracking was applied to 4 different subsections from one chosen patient case (Subsection 1-4), with the same plot formats and parameters as in Figure 10. Strain measurements are shown up to the point of rupture.

Speckle Image															
Biaxial Test								Shear Test							
Normal				Shear				Shear				Normal			
Max Dev. (%)	Max SD (%)	P Coeff.	Reg Coeff.	Max Dev. (%)	Max SD (%)	P Coeff.	Reg Coeff.	Max Dev. (%)	Max SD (%)	P Coeff.	Reg Coeff.	Max Dev. (%)	Max SD (%)	P Coeff.	Reg Coeff.
0.64	1.38	0.9996	1.0027	0.10	0.15	0.9999	-1.19e-6	1.33	1.83	0.9990	1.0296	0.17	0.45	0.9996	-0.0032

Table 1. Maximal deviation, maximal standard deviation, Pearson's Correlation coefficients, and best-fit slopes (regression coefficients) of normal and shear strain fields calculated with the Demons algorithm for up to 50% biaxial and shear strain applied to a speckle image.



<b>Aortic Image 1 (Figure 5A)</b>								
	<b>Normal</b>				<b>Shear</b>			
	<b>Max Dev. (%)</b>	<b>Max SD (%)</b>	<b>P Coeff.</b>	<b>Reg Coeff.</b>	<b>Max Dev. (%)</b>	<b>Max SD (%)</b>	<b>P Coeff.</b>	<b>Reg Coeff.</b>
<b>Demons</b>	1.71	1.59	0.9981	0.986	0.85	1.33	0.9997	-4.28e-5
<b>OF</b>	17.48	6.86	0.9850	0.641	1.87	4.18	0.9938	0.005
<b>DIC</b>	9.34	1.80	0.9932	0.809	0.04	1.82	0.9999	-7.05e-6

<b>Aortic Image 2 (Figure 5B)</b>								
	<b>Shear</b>				<b>Normal</b>			
	<b>Max Dev. (%)</b>	<b>Max SD (%)</b>	<b>P Coeff.</b>	<b>Reg Coeff.</b>	<b>Max Dev. (%)</b>	<b>Max SD (%)</b>	<b>P Coeff.</b>	<b>Reg Coeff.</b>
<b>Demons</b>	2.80	3.25	0.9963	-8.42e-6	0.09	2.11	0.9997	0.9809
<b>OF</b>	13.85	7.23	0.9618	0.0064	1.44	3.90	0.9971	0.6897
<b>DIC</b>	15.29	1.96	0.9903	-1.18e-6	0.07	0.17	0.9999	0.6721

Table 2. Maximal deviation, maximal standard deviation, and Pearson's Correlation coefficients, and best-fit slopes (regression coefficients) of normal and shear strain fields calculated with Demons, OF, and DIC for up to 50% biaxial and shear strain applied to the two aortic images in Figures 5A and B.

## **CONFLICT OF INTEREST STATEMENT**

All listed authors declare no conflict of interest.

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