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# Tunable Bandpass Filter With Two Adjustable Transmission Poles and Compensable Coupling

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Abstract—In this paper, tunable microstrip bandpass filters with two adjustable transmission poles and compensable coupling are proposed. The fundamental structure is based on a half-wavelength  $(\lambda/2)$  resonator with a center-tapped open-stub. Microwave varactors placed at various internal nodes separately adjust the filter's center frequency and bandwidth over a wide tuning range. The constant absolute bandwidth is achieved at different center frequencies by maintaining the distance between the in-band transmission poles. Meanwhile, the coupling strength could be compensable by tuning varactors that are side and embedding loaded in the parallel coupled microstrip lines (PCMLs). As a demonstrator, a second-order filter with seven tuning varactors is implemented and verified. A frequency range of 0.58-0.91 GHz with a 1-dB bandwidth tuning from 115 to 315 MHz (i.e., 12.6%-54.3% fractional bandwidth) is demonstrated. Specifically, the return loss of passbands with different operating center frequencies can be achieved with same level, i.e., about 13.1 and 11.6 dB for narrow and wide passband responses, respectively. To further verify the etch-tolerance characteristics of the proposed prototype fitler, another second-order filter with nine tuning varactors is proposed and fabricated. The measured results exhibit that the tunable fitler with the embedded varactor-loaded PCML has less sensitivity to fabrication tolerances. Meanwhile, the passband return loss can be achieved with same level of 20 dB for narrow and wide passband responses, respectively.

*Index Terms*—Bandpass filter, compensable coupling, parallel coupled microstrip line (PCML), tunable, varactor.

## I. INTRODUCTION

T HE MODERN wireless communication systems require reconfigurability for a multi-mode and multi-band operation. Tunable RF bandpass filters, including microstrip filters with small size, are essential key components for practical RF front-ends and thus generate a great deal of research attention. The filters in [1] and [2] with loaded varactors are capable of tuning the center frequency of the passband and

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stopband. However, their absolute bandwidth increases rapidly for higher central resonant frequencies. In general, to maintain a constant passband/stopband bandwidth independent of the tuning frequency, the coupling coefficients must vary inversely with the tuning frequency. In [3], a varactor tuning combines bandpass filtering using step-impedance resonators so that the inter-resonator coupling could be controlled to meet the constant bandwidth with shorter electrical lengths of line elements. Meanwhile, in [4] and [5], p-i-n diodes are used to control the filter's central resonance, and varactors continuously adjust the bandwidth at the specific operating frequency. Besides, the bandwidth can be controlled at a fixed center frequency [6]–[8] or at different center frequencies [9], [10]. Moreover, some approaches using a few resonators, such as an open-stub resonator, a dual-mode resonator, and a multiple-mode resonator, are proposed to tune the bandwidth [11]-[21]. However, the coupling strength of passbands or stopbands seems to be always neglected during the design of the tunable filters, which sometimes results in invalid bands after adjustments for practical applications.

In this paper, a compact tunable microstrip bandpass filter is proposed based on a half-wavelength  $(\lambda/2)$  resonator with an open-stub tapped at its center. The center-tapped open-stub can not only contribute two transmission poles in conjunction with the  $\lambda/2$  resonator, but also create a single transmission zero at a particular frequency. Locations of the two transmission poles are theoretically analyzed and parallel-coupled microstrip lines (PCMLs) with loaded varactors are investigated to demonstrate the distributed coupling performance in terms of a *J*-inverter susceptance. Based on the analysis, a detailed design procedure of the tunable filter is proposed and then experimentally verified. Measurements show that the filters keep the absolute bandwidth constant over different center frequencies, but can also compensate for the passband coupling strength variation.

## II. TUNABLE BANDPASS FILTER SCHEMATIC AND OPERATION

Fig. 1 shows a configuration of the tunable bandpass filter. It consists of a  $\lambda/2$  resonator with an open-stub tapped at its center and two  $\lambda/4$  PCMLs connected to the input/output (I/O) ports. Tuning varactors are connected at various internal nodes:  $C_1$  and  $C_2$  tapped at the open-stub and  $\lambda/2$  resonator, respectively, and  $C_{31,32...,3n}$  are embedded in the  $\lambda/4$  PCMLs. Sections II-A–II-E investigate the characteristics and mechanism of the proposed filter.

## A. Mechanism of Stub-Tapped Bandpass Filter

Fig. 2 depicts a configuration of the conventional stub-tapped bandpass filter [22], [23], which is a second-order filter. Physical

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Fig. 1. Configuration of the proposed tunable bandpass filter.



Fig. 2. Configuration of a conventional stub-tapped bandpass filter.



Fig. 3. Frequency response of the conventional stub-tapped bandpass filter.

length of the open-stub tapped at the center of the  $\lambda/2$  resonator can be changed to adjust the notch frequency in the stopband. As the characteristic impedance  $Z_{os} = 1/Y_{os}$  increases, the transmission zero is located closer to the passband edge. Once the length of the center-tapped open-stub is shorter than  $\lambda/4$ , the transmission zero is then placed on the right side of the transmission pole allocated by the  $\lambda/2$  resonator and open-stub [24]. For the bandpass filter design, the characteristic impedances, i.e.,  $Z_1 = 1/Y_1$  and  $Z_{os}$  of the resonator and open-stub, respectively, are selected by the location of transmission poles as well as the filter bandwidth, and the frequency of the transmission zero is defined by the electrical length of the open-stub. Here, the center-tapped open-stub is constructed slightly shorter than  $\lambda/4$  at the center frequency to make the transmission zero implemented at the upper stopband, as depicted in Fig. 3. The proposed filter is designed to have a fractional bandwidth (FBW) of nearly 25% and its central frequency at 1.1 GHz with a passband return loss more than 20 dB.



Fig. 4. (a) Varactor-loaded open-stub. (b) Open-stub equivalence. (c) Equivalent model of the varactor-loaded open-stub.



Fig. 5. Effects of the varactor-loaded open-stub on the frequency response of stub-tapped bandpass filter.

## B. Varactor-Loaded Open-Stub

As mentioned above, adjusting the length of the open-stub can vary the location of the right-side transmission pole. Here, a varactor  $C_1$  is added between the open-stub and ground, as shown in Fig. 4(a). It is well known that a microstrip open-stub can be equivalent to a shunt capacitor [25], as shown in Fig. 4(b), whose input admittance is

$$Y_{\rm in} = j Y_{os} \tan\left(\frac{2\pi}{\lambda}l\right) \tag{1}$$

where *l* is the physical length of the open-stub. If  $l < \lambda/4$ , the input admittance is capacitive with an equivalent value of

$$C = \frac{Y_{os} \tan\left(\frac{2\pi}{\lambda}l\right)}{2\pi f} \tag{2}$$

Thus, the capacitor and open-stub can be equivalently converted to each other. The modified length l' of the varactor-loaded open-stub can then be expressed as

$$l' = l + \frac{\arctan(Z_{os}C_1 2\pi f)}{2\pi}\lambda.$$
 (3)

Equation (3) can be utilized to investigate the effect of the tuning varactor on the frequency response. Fig. 5 reveals that increasing the capacitance from 1 to 5.5 pF not only lowers the transmission zero, but also degrades the coupling strength of the passband around the resonances.

## C. Varactor-Loaded PCML

To compensate for the above degradation of the coupling strength of passband, various varactor-loaded PCMLs are introduced in Fig. 6. To analyze the characteristics of the



Fig. 6. Varactor-loaded PCMLs. (a) Shunt varactor-loaded PCML. (b) Series varactor-loaded PCML. (c) Embedded varactor-loaded PCML. (d) Array varactor-loaded PCML.

varactor-loaded PCMLs, the ABCD-matrix calculated from the boundary conditions is introduced. Here, for example, the ABCD-matrix of the shunt varactor-loaded PCML shown in Fig. 6(a) is expressed as follows:

$$A = \frac{\cos\theta_e \cos\theta_o + \frac{1}{2}jZ(\cos\theta_e \sin\theta_o Y_{0o} + \cos\theta_o \sin\theta_e Y_{0e})}{\cos\theta_o - \frac{1}{2}jZ(\sin\theta_e Y_{0e} - \sin\theta_o Y_{0o})}$$
(4)

$$B = \frac{\frac{1}{2}Z(1 + \cos\theta_e \cos\theta_o)}{\cos\theta_o - \frac{1}{2}jZ(\sin\theta_e Y_{0e} - \sin\theta_o Y_{0o})} - \frac{\frac{1}{4}(Z_{0e}Y_{0o}\sin\theta_e \sin\theta_o - Z_{0o}Y_{0e}\sin\theta_e \sin\theta_o)}{\cos\theta_o - \frac{1}{2}jZ(\sin\theta_e Y_{0e} - \sin\theta_o Y_{0o})} + \frac{\frac{1}{2}j(Z_{0o}\cos\theta_e \sin\theta_o + Z_{0e}\cos\theta_o\sin\theta_e)}{\cos\theta_o - \frac{1}{2}jZ(\sin\theta_e Y_{0e} - \sin\theta_o Y_{0o})}$$
(5)

$$C = \frac{j \sin \theta_e Y_{0e}(2 \cos \theta_o + jZ \sin \theta_o Y_{0o})}{\cos \theta_o - \frac{1}{2}jZ(\sin \theta_e Y_{0e} - \sin \theta_o Y_{0o})}$$
(6)

$$D = \frac{j\sin\theta_e Y_{0e} \left(j\sin\theta_o Z_{0o} + \frac{1}{2}Z(\cos\theta_e + \cos\theta_o)\right)}{\cos\theta_o - \frac{1}{2}jZ(\sin\theta_e Y_{0e} - \sin\theta_o Y_{0o})} + \cos\theta_e$$

where  $Z = -j/\omega C$  and  $Z_{0o,e}$ ,  $Y_{0o,e}$ , and  $\theta_{o,e}$  are the relevant parameters of the PCML. For further derivation about the *ABCD*-matrix for other blocks of Fig. 6 shown, please refer to Appendix A. Based on the *ABCD*-matrix of the structure, the two-port admittance  $\pi$ -model can then be derived. This model could be further simplified into a susceptance  $\pi$ -model if the lossless case is assumed [26]. Besides, considering the scheme shown in Fig. 6(a) being asymmetric, then the model could be transformed to the *J*-inverter topology consisting of a susceptance with two transmission lines (i.e.,  $Y_1/\theta_1$  and  $Y_2/\theta_2$ ) [27], as shown in Fig. 7,

$$\overline{J} = \frac{J}{\sqrt{Y_1 Y_2}} = \frac{\sin\left(-\frac{\phi_1}{2}\right) + \overline{B_{11}}\cos\left(-\frac{\phi_1}{2}\right)}{\overline{B_{12}}\sin\left(-\frac{\phi_2}{2}\right)} \tag{8}$$

$$\phi_1 = M_1 \pi + \arctan\left(\frac{2\left(\overline{B_{11}} + \overline{B_{22}}|\overline{B}|\right)}{1 + \overline{B_{22}}^2 - \overline{B_{11}}^2 - |\overline{B}|^2}\right) \quad (9)$$

$$\phi_2 = M_2 \pi + \arctan\left(\frac{2\left(\overline{B_{22}} + \overline{B_{11}}|\overline{B}|\right)}{1 + \overline{B_{11}}^2 - \overline{B_{22}}^2 - |\overline{B}|^2}\right) (10)$$



Fig. 7. Equivalent J-inverter topology of the structure in Fig. 6(a).



Fig. 8. Effects of the varactor on the normalized J-inverter susceptance  $\overline{J}$  refer to the structure in Fig. 6(a).

where  $\overline{B_{11}} = B_{11}/Y_1$ ,  $\overline{B_{22}} = B_{22}/Y_2$ ,  $\overline{B_{12}} = B_{12}/\sqrt{Y_1Y_2}$ ,  $|\overline{B}| = \overline{B_{11}B_{22}} - \overline{B_{12}}^2$ , and  $M_{1,2}$  are two positive integers and  $\overline{J}$  is the normalized J-inverter susceptance. Fig. 8 depicts the various cases of  $\overline{J}$  calculated from the shunt varactor-loaded PCML. It is shown that the trend of the  $\overline{J}$  curve shifts lower as the capacitance increases [i.e., marked by the green dotted line (in online version)]. Therefore, it can be concluded that the coupling strength could be adjusted by tuning the varactor for the specific operating frequency. For practical applications, the effects of the varactor on even and odd modes should be considered. For the even mode, the varactor has no effect on the overall capacitance between the strip and ground because one of the varactor ends is an open circuit. Meanwhile, for the odd mode, the varactor is in parallel with the capacitance (i.e.,  $C_{eq}$ ) between the strip and ground conductors. Therefore, once the varactor value increases, the overall capacitance  $C_{eq}$  increases, and thus the phase velocity of the odd mode is reduced, which causes a shift of the PCML resonance. Fig. 9 shows the effects of the varator on S-parameters. It is notable that the peak point of the coupling strength happens at the PCML resonant frequency and shifts lower as the varactor increases.

# D. Combined Varactor-Loaded Open-Stub and PCML

Fig. 10 shows the combined varactor-loaded open-stub and PCML with varactors  $C_1$  and  $C_2$ . From the boundary conditions for the PCML [24], the two-port network of the scheme is derived, then the *ABCD*-matrix is calculated as

$$A = \frac{1}{2} \frac{(2g_3 - Z_{c2}g_1)\cos\theta_e - 2Z_{c2}g_1\cos\theta_o - 2jZ_{0o}g_1\sin\theta_o}{g_3}$$
(11)



Fig. 9. Effects of the varactor on resonant frequency shifting.



Fig. 10. Configuration of the combined varactor-loaded open-stub and PCML.

$$B = \frac{1}{2} \frac{Z_{c2}(g_2 + g_3)(\cos \theta_e + \cos \theta_o)}{g_3} + \frac{j}{2} \frac{2Z_{0o}\left(g_2 + \frac{1}{2}g_3\right)\sin \theta_o + Z_{0e}g_3\sin \theta_e}{g_3}$$
(12)

$$C = \frac{\cos v_o}{g_3} - \frac{1}{2} \frac{j \left( Y_{0e} (Z_{c2}g_1 - 2g_3) \sin \theta_e + Y_{0o} Z_{c2}g_1 \sin \theta_o \right)}{g_3}$$
(13)

$$D = \frac{1}{2} \frac{(2g_2 + g_3)\cos\theta_e + g_3\cos\theta_e}{g_3} + \frac{j}{2} \frac{(g_2 + g_3)Z_{c2}(Y_{0e}\sin\theta_e + Y_{0o}\sin\theta_o)}{g_3}$$
(14)

$$g_1 = -\cos\theta_e + jY_{0e}Z_{c1}\sin\theta_e \tag{15}$$

$$g_{2} = \frac{1}{2} (Z_{c1} - Z_{c2}) (\cos \theta_{o} - \cos \theta_{e}) - \frac{j}{2} (Y_{0e} Z_{c1} Z_{c2} - Z_{0e}) \sin \theta_{e} - \frac{j}{2} (Y_{0o} Z_{c1} Z_{c2} - Z_{0o}) \sin \theta_{o}$$
(16)  
$$g_{3} = \frac{1}{2} (Z_{c2} \cos \theta_{o} - Z_{c2} \cos \theta_{e} - 2Z_{c1} \cos \theta_{o})$$

$$-\frac{j}{2} \left( (Y_{0o} \sin \theta_o - Y_{0e} \sin \theta_e) Z_{c1} Z_{c2} - 2 Z_{0o} \sin \theta_o \right)$$
(17)

where  $Z_{c1}$  and  $Z_{c2}$  are impedances of  $C_1$  and  $C_2$ , respectively. Similarly to the analysis in the previous section, the normalized *J*-inverter susceptance  $\overline{J}$  can be derived and the effect of varactor  $\overline{J}$  is illustrated in Fig. 11. It is notable that the parameter  $\overline{J}$  increases up to the maximum value first and then decreases as a nonmonotonic function of the frequency over 0.7–1.1 GHz for all the cases. The typical points with maximum  $\overline{J}$  of each case are studied to show the effects created by  $C_1$  and  $C_2$ . Two interesting effects can be found. The first effect is that once we



Fig. 11. Effects of the varactor on normalized J-susceptance  $\overline{J}$ .

set  $C_2 = 0.5$  pF and then increase  $C_1$  from 0.5 to 1 pF, the  $\overline{J}$  value of maximum point decreases from 0.46 to 0.415 at the same frequency 920 MHz. The second effect is that once we set  $C_1 = 0.5$  pF and increase  $C_2$  from 0.5 to 1 pF, the maximum point of  $\overline{J}$  changes from 920 MHz with 0.46 to 850 MHz with 0.506. From these effects, it is important to notice that the coupling strength of the structure not only can become weaker with increasing  $C_1$ , but also can be enhanced with increasing  $C_2$ . Thus, the coupling strength can be effectively compensated and kept invariant throughout various frequencies by properly tuning  $C_1$  and  $C_2$ .

# E. Design Example Investigation

Based on the aforementioned structures, four cases are investigated now for practical tunable bandpass filter designs. Case I is the filter consisting of a series varactor-loaded PCML and center-tapped varactor-loaded open-stub, as depicted in Fig. 12(a). Case II is the filter consisting of the shunt varactor-loaded PCML and center-tapped varactor-loaded open-stub, as illustrated in Fig. 12(b). Case III is the tunable bandpass filter shown in Fig. 12(c) with combined structures of Case I and Case II. Case IV is the tunable bandpass filter shown in Fig. 1. For all the cases in Fig. 12, the *ABCD*-matrix can be expressed as follows:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} A_1 & B_1 \\ C_1 & D_1 \end{bmatrix} \times \begin{bmatrix} 1 & -jZ_2 \cot(\theta_c + \theta_{os}) \\ 0 & 1 \end{bmatrix} \begin{bmatrix} D_1 & B_1 \\ C_1 & A_1 \end{bmatrix}$$
(18)

where the first and third ABCD-matrices are derived from the varactor-loaded PCMLs, and the middle one is for the center-tapped varactor-loaded open-stub. To maintain the bandwidth of the tunable bandpass filter over various center frequencies, the structure in Case II is introduced and investigated. To theoretically derive  $C_1$ , the model as illustrated in Fig. 12 is equivalently expressed as in Fig. 13. Since the structure is symmetrical, the odd- and even-mode analysis of the center section in Fig. 13 can be adopted to characterize it, as depicted in Fig. 13(b) and (c). Therefore, the fundamental resonance  $f_e$  and  $f_o$  can be derived for the center section. For



Fig. 12. Configurations of the tunable bandpass filter. (a) Case I. (b) Case II. (c) Case III. (d) Case IV.



Fig. 13. (a) Equivalent model of Fig. 12. (b) Even mode of the center section. (c) Odd mode of the center section.

the even mode at resonance  $f_e$ , the input impedances  $Z_L$  and  $Z_R$  must satisfy the following requirement:

$$Z_L + Z_R = 0 \tag{19}$$

and thus,

$$2Z_{os}\cot(\theta_c + \theta_{os}) + Z_2\cot\frac{\phi}{2} = 0.$$
 (20)

For the odd mode, the resonant frequency  $f_o$  can be determined by

$$Z_2 \tan \frac{\phi}{2} = 0 \tag{21}$$

The central frequency  $f_0$  of passband can then be expressed as

$$f_0 = \sqrt{f_e f_o} \tag{22}$$

which is assumed to be the center frequency between the two transmission poles. From (21), the lower transmission pole is determined by the odd mode. Once the desired odd mode is chosen by adjusting  $C_2$  of the series varactor-loaded PCML, the upper transmission pole introduced by the even mode can then be tuned by varactor  $C_1$  shown in Fig. 12(a). Thus far, the lower and upper transmission poles can be easily tuned. Therefore, since the varactors  $C_1$  and  $C_2$  tune the capacitance simultaneously, the adjusted center frequency with constant bandwidth can be easily achieved, as depicted in Fig. 14. However, the return loss of different passbands is not easily established at the same level in Case I. Fig. 8 suggests that it is possible to get the same  $\overline{J}$  at the same frequency by tuning the varactor  $C_3$ . Nevertheless, that frequency is actually not the center frequency because of the overall passband changes introduced by the adjusted  $C_3$ . Therefore,  $C_1$  should be adjusted to set the normalized value to be the same as the previous value at one frequency. Meanwhile, the frequency is just the current central frequency while  $C_3$  has been fixed to the new value. For instance, the return loss of the original passband is 20 dB and the return loss of the new passband after tuning should be 20 dB. Based on the equations investigated above, the  $S_{11}$  related to  $C_1$ ,  $C_3$ , and  $f_0$ can be expressed as

$$20\log_{10}\left(abs\left(S_{11}(C_1, C_3, f_0)\right)\right) = -20 \text{ dB.}$$
(23)

Thus, based on (20)–(23),  $C_3$  in Case II could be derived. For instance, once  $C_1$  is set to 0.6 pF,  $C_3$  could be calculated and optimized as 7.8 pF. In this way, the return loss can be tuned to the same level; however, the bandwidth cannot be kept the same, as shown in Fig. 15. Thus, to simultaneously achieve the equal coupling strengths and the constant bandwidth for the various center frequencies, the scheme depicted in Case III is implemented to achieve the frequency responses shown in Fig. 16. However, to design the tunable bandpass filter with much more flexibility, both the tunable transmission poles and compensable coupling are required. Therefore, Case IV in Fig. 12 is introduced. To clarify the selection of voltages to tune the varactors, the filter design procedure is summarized in a flowchart in Fig. 17. The first step is to design a fixed filter for a specific application with an acceptable performance [23]. The second step is to determine



Fig. 14. Effects of  $C_1$  and  $C_2$  on bandwidth at various center frequencies.



Fig. 15. Return loss  $|S_{11}|$  with various varactors  $C_1$  once  $C_3$  is fixed in Case II of Fig. 12.



Fig. 16. Return loss  $|S_{11}|$  with tunable varactors  $C_1$ ,  $C_2$ , and  $C_3$  in Case III of Fig. 12.

the capacitance of the varactors based on the desired requirements of the tunable frequency range and adjusted bandwidth. Based on the above analysis, it is notable that once the desired center frequency and bandwidth are given, the capacitance of varactors can be determined using the above-derived equations and design graphs.



Fig. 17. Flowchart of the tunable filter design. (refer to [23] for a detailed design procedure of a fixed filter).

# III. FILTER DESIGN AND EXPERIMENTAL RESULTS

### A. Design I

Based on the above investigation, a tunable bandpass filter (i.e., Filter I) is proposed, implemented, and fabricated on a Rogers 4350B substrate of thickness h = 0.508 mm and  $\epsilon_r = 3.66$ . The configuration of the fabricated filter is shown in Fig. 18. The varactors (BB857) with adjustable range of about 0.52–6.6 pF for variable voltage in the 0–28-V interval are used. Five different dc voltages (i.e.,  $V_1$ ,  $V_2$ ,  $V_{31}$ ,  $V_{32}$ , and  $V_G$ ) are used to achieve direct tuning of the varactors. They are isolated from each other by three dc blocks. The parasitic effects of the voltage supplies are isolated with a biasing circuit. For varactors  $C_1$  and  $C_2$ , whose one end shares the ground with the microstrip filter, another biasing circuit is used, just replacing the series inductor with capacitor C = 12 pF in parallel.  $C_{31}$ and  $C_{32}$  varactors use a simple biasing circuit consisting of the RF choke (i.e., 2.2- $\mu$ H inductor), which separates the dc power



Fig. 18. Configuration of the proposed tunable bandpass filter (i.e., Filter I). (a) Implementation (g = 0.15 mm,  $l_1 = 48.2$  mm,  $l_{21} = 10$  mm,  $l_{22} = 16.15$  mm,  $w_1 = 0.45$  mm, and  $w_2 = 4.2$  mm). (b) Fabrication.

from high frequency, and a resistance R of 10 k $\Omega$ , which is utilized to limit the bias current. Note that, for the symmetry sake, the dc voltage source (i.e.,  $V_G$ ) is applied to vary the reverse bias to control the varactor, which is implemented as a dual-tapped structure. The experimental performance of the proposed tunable bandpass filter is presented in Figs. 19 and 20. A frequency range of 0.58-0.91 GHz with a 1-dB bandwidth tuned between 115-315 MHz (i.e., 12.6%-54.3% FBW) is demonstrated. The typical insertion losses for the narrow and wide passband responses are 1.53 and 1.19 dB, respectively. Note that two interesting effects are considered for the passband return loss with the same level of various operated center frequencies. The first one is the mismatch of the symmetrical scheme after the soldering of the varactors, dc block, and bias components, which leads to imbalance of the tuning effects for the left and right part of the proposed filter. The second one is the capacitors for the dc block between the adjacent varactor bias circuits, which can introduce the interferences on the return loss level of different passbands. After optimization, the return loss level of the passbands with different operated center frequency in Fig. 19 and Fig. 20 can then be achieved to be 13.1 and 11.6 dB for the narrow and wide passband responses, respectively. Table I compares the tunable bandpass filters in this work to some tunable filters recently reported in the literature [15], [16], [18], [19], [21]. It



Fig. 19. Experimental results of the varactor-tuned bandpass filter (i.e., Filter I) with narrow passband responses. (Red line (in online version):  $V_1 = 3.9$  V,  $V_2 = 28$  V,  $V_{31} = 28$  V,  $V_{32} = 28$  V; Blue line (in online version):  $V_1 = 3.1$  V,  $V_2 = 10$  V,  $V_{31} = 28$  V,  $V_{32} = 18$  V; Green line (in online version):  $V_1 = 2.05$  V,  $V_2 = 6$  V,  $V_{31} = 28$  V,  $V_{32} = 5.5$  V; Black line:  $V_1 = 1$  V,  $V_2 = 4.25$  V,  $V_{31} = 28$  V,  $V_{32} = 3.8$  V.)



Fig. 20. Experimental results of the varactor-tuned bandpass filter (i.e., Filter I) with wide passband responses. (Red line (in online version):  $V_1 = 28$  V,  $V_2 = 28$  V,  $V_{31} = 28$  V,  $V_{32} = 28$  V; Blue line (in online version):  $V_1 = 13.5$  V,  $V_2 = 11$  V,  $V_{31} = 10$  V,  $V_{32} = 28$  V; Green line (in online version):  $V_1 = 8$  V,  $V_2 = 6.75$  V,  $V_{31} = 5$  V,  $V_{32} = 28$  V; Black line:  $V_1 = 5.85$  V,  $V_2 = 5$  V,  $V_{31} = 2.45$  V,  $V_{32} = 28$  V.)

can be concluded that the performance of our design based on two adjustable transmission poles and compensable coupling is competitive among the reported research works and attractive for practical application.

# B. Design II

In practical applications, due to the imperfections of the fabrication process, frequency responses of filters are usually affected by the manufacturing tolerance [28]. For a constant amount of etching error, the varied widths of the strip and gap in the PCML can largely perturb the coupling strength of coupled lines [29]. Therefore, a compensable method should be developed to further address this mismatching problem. Consequently, in this paper, to further demonstrate the flexibility of the coupling compensation about embedded varactor-loaded PCMLs and array varactor-loaded PCMLs, the second-order

 TABLE I

 Comparisons of Measurement With Other Tunable Filters

Ref	Frequency tuning Range (GHz)	BW tuning Range (MHz)	Insertion Loss (dB)	Return Loss (dB)	Number of tuning elements	Filter Order
*	0.59-0.88 0.59-0.905	115 315	1.53 1.19	13.1 ** 11.6 **	7	2
[15]	1.5-2.2	50-170	3-6.5	NA	9	3
[16]	1.55-2.1	40-120	4.5-6.0	NA	10	4
[18]	3-5.6	33-45	3.1	NA	6	2
[19]	2.9-3.5	134-402	1-3	NA	8	2
[21]	0.669-1.215	140-644	1-2	NA	6	3

\*: This work

\*\*: Same return-loss level using compensable coupling mechanism



Fig. 21. Fabrication of the proposed tunable bandpass filter (i.e., Filter II).  $(g = 0.15 \text{ mm}, l_1 = 48.2 \text{ mm}, l_{21} = 10 \text{ mm}, l_{22} = 16.15 \text{ mm}, w_1 = 0.45 \text{ mm}, and w_2 = 4.2 \text{ mm}.)$ 



Fig. 22. Measured sensitivity to etching tolerances for the proposed tunable bandpass filter (i.e., Filter II) with narrow passband responses. (For all the cases,  $V_1 = 3.1$  V,  $V_2 = 10$  V,  $V_{31} = 28$  V, and  $V_{32} = 9$  V. Red line (in online version):  $V_{33} = 3$  V; Green line (in online version):  $V_{33} = 5$  V; Black line:  $V_{33} = 7.2$  V; Pink line (in online version):  $V_{33} = 10$  V; and Blue line (in online version):  $V_{33} = 20$  V.)

tunable bandpass filter (i.e., Filter II) is implemented and fabricated as shown in Fig. 21. The dielectric substrate Rogers 4350B with thickness h = 0.508 mm and  $\epsilon_r = 3.66$  is used. Similar to Filter I, three dc blocks are utilized to isolate the varators, which are adjusted by six dc voltages (i.e.,  $V_1$ ,  $V_2$ ,  $V_{31}$ ,  $V_{32}$ ,  $V_{33}$ , and  $V_G$ ). The BB857 varactors  $C_1$ ,  $C_2$ ,  $C_{31}$ , and  $C_{32}$  with dc voltage circuits are implemented the same as in Filter I. Note that there is an additional pair of varactors  $C_{33}$  (i.e., SMV2202-040LF) identically embedded at the center positions of the left and right PCMLs. To show the sensitivity



Fig. 23. Measured sensitivity to etching tolerances for the proposed tunable bandpass filter (i.e., Filter II) with wide passband responses. (For all the cases  $V_1 = 13.5 \text{ V}$ ,  $V_2 = 11 \text{ V}$ ,  $V_{31} = 10 \text{ V}$ , and  $V_{32} = 28 \text{ V}$ . Red line (in online version):  $V_{33} = 0 \text{ V}$ ; Green line (in online version):  $V_{33} = 1 \text{ V}$ ; Black line:  $V_{33} = 4.5 \text{ V}$ ; Pink line (in online version):  $V_{33} = 10 \text{ V}$ ; and Blue line (in online version):  $V_{33} = 10 \text{ V}$ ; and Blue line (in online version):  $V_{33} = 17 \text{ V}$ .)

of etching tolerances for Filter II, the masks are modified during the fabrication process because printed circuit board (PCB) factories cannot change the processing parameters to match the study extent of this paper. Figs. 22 and 23 present the measured responses (i.e., wide and narrow passband) of the proposed filters (i.e., Filter II) versus etching error, i.e., from over-etching 0.05 mm (2 mil) to under-etching 0.05 mm (2 mil), to demonstrate the sensitivity, respectively. From the measurements, two interesting functions about the existing of varactor  $C_{33}$  can be concluded as follows: 1) the return loss of the passband can be enhanced to 20 dB, which implies a better impedance matching with the varactor compensation and 2) reasonably small discrepancies of frequency responses due to the etching error are achieved.

#### IV. CONCLUSION

A novel tunable bandpass filter structure, which is based on a  $\lambda/2$  resonator with a tapped open-stub in the middle, allows for both the two transmission poles and coupling strength tuning using only tuning elements attached to the filter. The center frequency and bandwidth of this structure can be easily tuned and the coupling weakened by tuning the poles can also be compensated by the tuning varactors between the coupled lines. The effect of the varactors has been theoretically analyzed in detail. Two second-order microstrip tunable filters have been designed, implemented, and measured. The passbands with different center frequencies, but nearly the same bandwidth and coupling strength, have been successfully realized in practice. Meanwhile, less sensitivity to fabrication tolerances of the frequency response can be achieved. This simple yet effective design can be useful for modern reconfigurable wireless communication systems.

### APPENDIX A

To derive the ABCD-matrix of the model, as illustrated in Fig. 24(a), the four-port network shown in Fig. 24(b) is introduced. From the boundary condition of the port voltages and



Fig. 24. Varactor-loaded PCMLs. (a) Series varactor-loaded PCML. (b) Fourport network of series varactor-loaded PCML. (c) Emebedded varactor-loaded PCML. (d) Four-port network of emebedded varactor-loaded PCML.

currents, the relationship at the reference plane A-A' can be expressed as

$$V_2 = I_2 Z. \tag{24}$$

Meanwhile, for the open-circuited boundary at port 4, the current  $I_4 = 0$ . Therefore, from the *ABCD*-matrix definition as follows:

$$\begin{bmatrix} V_1 \\ I_1 \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} V'_3 \\ I'_3 \end{bmatrix}.$$
 (25)

The ABCD-matrix can then be calculated as

$$A = \frac{a_{11}^2 - a_{12}^2 - Za_{11}c_{11} + Zc_{12}a_{12}}{Zc_{12} - a_{12}}$$
(26)

$$B = -\frac{a_{11}b_{11} - a_{12}b_{12} + Zb_{12}c_{12} - Za_{11}^2}{Zc_{12} - a_{12}}$$
(27)

$$C = \frac{a_{11}c_{11} - a_{12}c_{12} - Zc_{11}^2 + Zc_{12}^2}{Zc_{12} - a_{12}}$$
(28)

$$D = -\frac{b_{11}c_{11} - a_{12}^2 + Za_{12}c_{12} - Za_{11}c_{11}}{Zc_{12} - a_{12}}$$
(29)

where  $Z = -j/\omega C$ , and the parameters of  $a_{ii}$ ,  $b_{ii}$ ,  $c_{ii}$ , and  $d_{ii}$  can be found in Appendix B.

The *ABCD*-matrix of the embedded varactor-loaded PCML, as illustrated in Fig. 24(c), can be derived from the following boundary condition and current definition depicted in Fig. 24(d) as follows:

$$V_3 = V_2' \tag{30}$$

$$V_4 = V_1' \tag{31}$$

$$V_3 - V_4 = Z \left( I_4 + I_1' \right) = -Z \left( I_3 + I_2' \right)$$
(32)

$$I_2 = I_4' = 0. (33)$$

Considering the similar process of the derivation, the ABCD-matrix of this model is not listed here.

# APPENDIX B

The transmission line model of the conventional PCML is depicted in Fig. 25. The terminal behavior of such a four-port



Fig. 25. Transmission-line model of the PCML.

network has been investigated by [27] and the chain matrix is shown as follows:

$$\begin{bmatrix} V_1 \\ V_2 \\ I_1 \\ I_2 \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & b_{11} & b_{12} \\ a_{21} & a_{22} & b_{21} & b_{22} \\ c_{11} & c_{12} & d_{11} & d_{12} \\ c_{21} & c_{22} & d_{21} & d_{22} \end{bmatrix} \begin{bmatrix} V_4 \\ V_3 \\ -I_4 \\ -I_3 \end{bmatrix}$$
(34)

where

0

C

$$a_{11} = a_{22} = d_{11} = d_{22} = \frac{1}{2} (\cos \theta_e + \cos \theta_o) \qquad (35)$$

$$a_{12} = a_{21} = d_{12} = d_{21} = \frac{1}{2} (\cos \theta_e - \cos \theta_o)$$
 (36)

$$b_{11} = b_{22} = \frac{j}{2} (Z_{0e} \sin \theta_e + Z_{0o} \sin \theta_o)$$
(37)

$$b_{12} = b_{21} = \frac{j}{2} (Z_{0e} \sin \theta_e - Z_{0o} \sin \theta_o)$$
(38)

$$c_{11} = c_{22} = \frac{j}{2} (Y_{0e} \sin \theta_e + Y_{0o} \sin \theta_o)$$
(39)

$$c_{12} = c_{21} = \frac{j}{2} (Y_{0e} \sin \theta_e - Y_{0o} \sin \theta_o)$$
(40)

where  $Z_{0e}$  and  $Z_{0o}$  are even- and odd-mode characteristic impedances,  $Y_{0e}$  and  $Y_{0o}$  are even- and odd-mode characteristic admittances, and

$$\theta_{e,o} = \beta_{e,o}l = \frac{\pi}{2} \frac{f}{f_{0e,o}} \tag{41}$$

are even- and odd-mode electrical lengths of the coupled lines, respectively.

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