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# TAME AUTOMORPHISMS FIXING A VARIABLE OF FREE ASSOCIATIVE ALGEBRAS OF RANK THREE 

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Devoted to the 80th anniversary of Professor Boris Plotkin.


#### Abstract

We study automorphisms of the free associative algebra $K\langle x, y, z\rangle$ over a field $K$ which fix the variable $z$. We describe the structure of the group of $z$-tame automorphisms and derive algorithms which recognize $z$-tame automorphisms and $z$-tame coordinates.


## Introduction

Let $K$ be an arbitrary field of any characteristic and let $K\left[x_{1}, \ldots, x_{n}\right]$ and $K\left\langle x_{1}, \ldots, x_{n}\right\rangle$ be, respectively, the polynomial algebra in $n$ variables and of the free associative algebra of rank $n$, freely generated by $x_{1}, \ldots, x_{n}$. We may think of $K\left\langle x_{1}, \ldots, x_{n}\right\rangle$ as the algebra of polynomials in $n$ noncommuting variables. The automorphism groups Aut $K\left[x_{1}, \ldots, x_{n}\right]$ and Aut $K\left\langle x_{1}, \ldots, x_{n}\right\rangle$ are well understood for $n \leq 2$ only. The description is trivial for $n=1$, when the automorphisms $\varphi$ are defined by $\varphi\left(x_{1}\right)=\alpha x_{1}+\beta$, where $\alpha \in K^{*}=K \backslash 0$ and $\beta \in K$. The classical results of Jung-van der Kulk [J, K] for $K\left[x_{1}, x_{2}\right]$ and of Czerniakiewicz-MakarLimanov Cz, ML1, ML2] give that all automorphisms of $K\left[x_{1}, x_{2}\right]$ and $K\left\langle x_{1}, x_{2}\right\rangle$ are tame. Writing the automorphisms of $K\left[x_{1}, \ldots, x_{n}\right]$ and Aut $K\left\langle x_{1}, \ldots, x_{n}\right\rangle$ as $n$-tuples of the images of the variables, and using $x, y$ instead of $x_{1}, x_{2}$, this means that Aut $K[x, y]$ and Aut $K\langle x, y\rangle$ are generated by the affine automorphisms

$$
\psi=\left(\alpha_{11} x+\alpha_{21} y+\beta_{1}, \alpha_{12} x+\alpha_{22} y+\beta_{2}\right), \quad \alpha_{i j}, \beta_{j} \in K
$$

[^0](and $\psi_{1}=\left(\alpha_{11} x+\alpha_{21} y, \alpha_{12} x+\alpha_{22} y\right)$, the linear part of $\psi$, is invertible) and the triangular automorphisms
$$
\rho=\left(\alpha_{1} x+p_{1}(y), \alpha_{2} y+\beta_{2}\right), \quad \alpha_{1}, \alpha_{2} \in K^{*}, p_{1}(y) \in K[y], \beta_{2} \in K
$$

It turns out that the groups Aut $K\langle x, y\rangle$ and Aut $K[x, y]$ are naturally isomorphic. As abstract groups they are described as the free product $A *_{C} B$ of the group $A$ of the affine automorphisms and the group $B$ of triangular automorphisms amalgamating their intersection $C=A \cap B$. Every automorphism $\varphi$ of $K[x, y]$ and $K\langle x, y\rangle$ can be presented as a product

$$
\begin{equation*}
\varphi=\psi_{m}^{\varepsilon_{m}} \rho_{m} \psi_{m-1} \cdots \rho_{2} \psi_{1} \rho_{1}^{\varepsilon_{1}} \tag{1}
\end{equation*}
$$

where $\psi_{i} \in A, \rho_{i} \in B\left(\varepsilon_{1}\right.$ and $\varepsilon_{m}$ are equal to 0 or 1$)$, and, if $\varphi$ does not belong to the union of $A$ and $B$, we may assume that $\psi_{i} \in$ $A \backslash B, \rho_{i} \in B \backslash A$. The freedom of the product means that if $\varphi$ has a nontrivial presentation of this form, then it is different from the identity automorphism.

In the case of arbitrary $n$, the tame automorphisms are defined similarly, as compositions of affine and triangular automorphisms. One studies not only the automorphisms but also the coordinates, i.e., the automorphic images of $x_{1}$.

We shall mention few facts related with the topic of the present paper, for $z$-automorphisms of $K[x, y, z]$ and $K\langle x, y, z\rangle$, i.e., automorphisms fixing the variable $z$. For more details we refer to the books by van den Essen [E], Mikhalev, Shpilrain, and Yu [MSY], and our survey article DY1.

Nagata [N] constructed the automorphism of $K[x, y, z]$

$$
\nu=\left(x-2\left(y^{2}+x z\right) y-\left(y^{2}+x z\right)^{2} z, y+\left(y^{2}+x z\right) z, z\right)
$$

which fixes $z$. He showed that $\nu$ is nontame, or wild, considered as an automorphism of $K[z][x, y]$, and conjectured that it is wild also as an element of Aut $K[x, y, z]$. This was the beginning of the study of $z$-automorphisms.

It is relatively easy to see (and to decide algorithmically) whether an endomorphism of $K[z][x, y]$ is an automorphism and whether this automorphism is $z$-tame, or tame as an automorphism of $K[z][x, y]$. When char $K=0$, Drensky and Yu [DY2] presented a simple algorithm which decides whether a polynomial $f(x, y, z) \in K[x, y, z]$ is a $z$-coordinate and whether this coordinate is $z$-tame. This provided many new wild automorphisms and wild coordinates of $K[z][x, y]$. These results in

DY2] are based on a similar algorithm of Shpilrain and Yu SY1] which recognizes the coordinates of $K[x, y]$. Shestakov and Umirbaev [SU1, SU2, SU3] established that the Nagata automorphism is wild. They also showed that every wild automorphism of $K[z][x, y]$ is wild as an automorphism of $K[x, y, z]$. Umirbaev and Yu [UY] proved that the $z$-wild coordinates in $K[z][x, y]$ are wild also in $K[x, y, z]$. In this way, all $z$-wild examples in [DY2 give automatically wild examples in $K[x, y, z]$.

Going to free algebras, the most popular candidate for a wild automorphism of $K\langle x, y, z\rangle$ is the example of Anick $(x+(y(x y-y z), y, z+$ $(z y-y z) y) \in$ Aut $K\langle x, y, z\rangle$, see the book by Cohn [C], p. 343. It fixes one variable and its abelianization is a tame automorphism of $K[x, y, z]$. Exchanging the places of $y$ and $z$, we obtain the automorphism $(x+z(x z-z y), y+(x z-z y) z, z)$ which fixes $z$ (or a $z$ automorphism), and refer to it as the Anick automorphism. It is linear in $x$ and $y$, considering $z$ as a "noncommutative constant". Drensky and Yu [DY3] showed that such $z$-automorphisms are $z$-wild if and only if a suitable invertible $2 \times 2$ matrix with entries from $K\left[z_{1}, z_{2}\right]$ is not a product of elementary matrices. In particular, this gives that the Anick automorphism is $z$-wild. When char $K=0$, Umirbaev [U] described the defining relations of the group of tame automorphisms of $K[x, y, z]$. He showed that $\varphi=(f, g, h) \in$ Aut $K\langle x, y, z\rangle$ is wild if the endomorphism $\varphi_{0}=\left(f_{0}, g_{0}, z\right)$ of $K\langle x, y, z\rangle$ is a $z$-wild automorphism, where $f_{0}, g_{0}$ are the linear in $x, y$ components of $f, g$, respectively. This implies that the Anick automorphism is wild. Recently Drensky and Yu DY4, DY5 established the wildness of a big class of automorphisms and coordinates of $K\langle x, y, z\rangle$. Many of them cannot be handled with direct application of the methods of [DY3] and [U]. These results motivate the needs of systematic study of $z$-automorphisms of $K\langle x, y, z\rangle$. As in the case of $z$-automorphisms of $K[x, y, z]$, they are simpler than the arbitrary automorphisms of $K\langle x, y, z\rangle$ and provide important examples and conjectures for Aut $K\langle x, y, z\rangle$.

In the present paper we describe the structure of the group of $z$-tame automorphisms of $K\langle x, y, z\rangle$ as the free product of the groups of $z$-affine automorphisms and $z$-triangular automorphisms amalgamating the intersection. We also give algorithms which recognize $z$-tame automorphisms and coordinates of $K\langle x, y, z\rangle$. As an application, we show that all the $z$-automorphisms of the form $\sigma_{h}=(x+z h(x z-z y, z), y+h(x z-$ $z y, z) z$ ) are $z$-wild when the polynomials $h(x z-z y, z)$ are of positive
degree in $x$. This kind of automorphisms appear in DY4, DY5 but the considerations there do not cover the case when $h(x z-z y, z)$ belongs to the square of the commutator ideal of $K\langle x, y, z\rangle$. Besides, the polynomial $x+z h(x z-z y, z)$ is a $z$-wild coordinate. Finally, we show that the $z$-endomorphisms of the form $\varphi=(x+u(x, y, z), y+v(x, y, z))$, where $(u, v) \neq(0,0)$ and all monomials of $u$ and $v$ depend on both $x$ and $y$, are not automorphisms. A partial case of this result was an essential step in the proof of the theorem of Czerniakiewicz and Makar-Limanov for the tameness of Aut $K\langle x, y\rangle$. The paper may be considered as a continuation of our paper DY3.

## 1. The group of $z$-Tame automorphisms

We fix the field $K$ and consider the free associative algebra $K\langle x, y, z\rangle$ in three variables. We call the automorphism $\varphi$ of $K\langle x, y, z\rangle$ a $z$ automorphism if $\varphi(z)=z$, and denote the automorphism group of the $z$-automorphisms by $\operatorname{Aut}_{z}\langle x, y, z\rangle$. Since we want to emphasize that we work with $z$-automorphisms, we shall write $\varphi=(f, g)$, omitting the third coordinate $z$. The multiplication will be from right to left. If $\varphi, \psi \in \operatorname{Aut}_{z} K\langle x, y, z\rangle$, then in $\varphi \psi$ we first apply $\psi$ and then $\varphi$. Hence, if $\varphi=(f, g)$ and $\psi=(u, v)$, then

$$
\varphi \psi=(u(f, g, z), v(f, g, z)) .
$$

The $z$-affine and $z$-triangular automorphisms of $K\langle x, y, z\rangle$ are, respectively, of the form

$$
\psi=\left(\alpha_{11} x+\alpha_{21} y+\alpha_{31} z+\beta_{1}, \alpha_{12} x+\alpha_{22} y+\alpha_{32} z+\beta_{2}\right),
$$

$\alpha_{i j}, \beta_{j} \in K$, the $2 \times 2$ matrix $\left(\alpha_{i j}\right)_{i, j=1,2}$ being invertible,

$$
\rho=\left(\alpha_{1} x+p_{1}(y, z), \alpha_{2} y+p_{2}(z)\right)
$$

$\alpha_{j} \in K^{*}, p_{1} \in K\langle y, z\rangle, p_{2} \in K[z]$. The affine and the triangular $z$-automorphisms generate, respectively, the subgroups $A_{z}$ and $B_{z}$ of $\mathrm{Aut}_{z} K\langle x, y, z\rangle$. We denote by $\mathrm{TAut}_{z} K\langle x, y, z\rangle$ the group of $z$-tame automorphisms which is generated by the $z$-affine and $z$-triangular automorphisms. Of course, we may define the $z$-affine automorphisms as the $z$-automorphisms of the form $\psi=(f, g)$, where the polynomials $f, g \in K\langle x, y, z\rangle$ are linear in $x$ and $y$. But, as we commented in [DY3], this definition is not convenient. For example, the Anick automorphism is affine in this sense but is wild.

In the commutative case, the $z$-automorphisms of $K[x, y, z]$ are simply the automorphisms of the $K[z]$-algebra $K[z][x, y]$. A result of

Wright Wr states that over any field $K$ the group TAut ${ }_{z} K[x, y, z]$ has the amalgamated free product structure

$$
\operatorname{TAut}_{z} K[x, y, z]=A_{z} *_{C_{z}} B_{z},
$$

where $A_{z}$ and $B_{z}$ are defined as in the case of $K\langle x, y, z\rangle$ and $C_{z}=A_{z} \cap$ $B_{z}$. (The original statement in Wr holds in a more general situation. In the case of $K[x, y, z]$ it involves affine and linear automorphisms with coefficients from $K[z]$ but this is not essential because every invertible matrix with entries in $K[z]$ is a product of elementary and diagonal matrices.)

Every $z$-tame automorphism $\varphi$ of $K\langle x, y, z\rangle$ can be presented as a product in the form (11) where $\psi_{i} \in A_{z}, \rho_{i} \in B_{z}\left(\varepsilon_{1}\right.$ and $\varepsilon_{m}$ are equal to 0 or 1), and, if $\varphi$ does not belong to the union of $A_{z}$ and $B_{z}$, we may assume that $\psi_{i} \in A_{z} \backslash B_{z}, \rho_{i} \in B_{z} \backslash A_{z}$. Fixing the linear nontriangular $z$-automorphism $\tau=(y, x)$, we can present $\varphi$ in the canonical form

$$
\begin{equation*}
\varphi=\rho_{n} \tau \cdots \tau \rho_{1} \tau \rho_{0} \tag{2}
\end{equation*}
$$

where $\rho_{0}, \rho_{1}, \ldots, \rho_{n} \in B_{z}$ and only $\rho_{0}$ and $\rho_{n}$ are allowed to belong to $A_{z}$, see for example p. 350 in [C]. Let
$\rho_{i}=\left(\alpha_{i} x+p_{i}(y, z), \beta_{i} y+r_{i}(z)\right), \quad \alpha_{i}, \beta_{i} \in K^{*}, p_{i} \in K\langle y, z\rangle, r_{i} \in K[z]$.
Using the equalities for compositions of automorphisms

$$
(\alpha x+p(y, z), \beta y+r(z))=\left(x+\alpha^{-1}(p(y, z)-p(0, z)), y\right)(\alpha x+p(0, z), \beta y+r(z))
$$

$(\alpha x+p(z), \beta y+r(z)) \tau=(\beta y+r(z), \alpha x+p(z))=\tau(\beta x+r(z), \alpha y+p(z))$, $p(z), r(z) \in K[z]$, we can do further simplifications in (2), assuming that $\rho_{1}, \ldots, \rho_{n-1}$ are not affine and, together with $\rho_{n}$, are of the form $\rho_{i}=\left(x+p_{i}(y, z), y\right)$ with $p_{i}(0, z)=0$ for all $i=1, \ldots, n$. We also assume that $\rho_{0}=\left(\alpha_{0} x+p_{0}(y, z), \beta_{0} y+r_{0}(z)\right)$. The condition that $\rho_{1}, \ldots, \rho_{n-1}$ are not affine means that $\operatorname{deg}_{y} p_{i}(y, z) \geq 1$ and if $\operatorname{deg}_{y} p_{i}(y, z)=1$, then $\operatorname{deg}_{z} p_{i}(y, z) \geq 1, i=1, \ldots, n-1$.

The following result shows that the structure of the group of $z$-tame automorphisms of $K\langle x, y, z\rangle$ is similar to the structure of the group of $z$-tame automorphsims fo $K[x, y, z]$.

Theorem 1.1. Over an arbitrary field $K$, the group $\operatorname{TAut}_{z} K\langle x, y, z\rangle$ of $z$-tame automorphisms of $K\langle x, y, z\rangle$ is isomorphic to the free product $A_{z} *_{C_{z}} B_{z}$ of the group $A_{z}$ of the $z$-affine automorphisms and the group $B_{z}$ of $z$-triangular automorphisms amalgamating their intersection $C_{z}=A_{z} \cap B_{z}$.

Proof. We define a bidegree of $K\langle x, y, z\rangle$ assuming that the monomial $w$ is of bidegree bideg $w=(d, e)$ if $\operatorname{deg}_{x} w+\operatorname{deg}_{y} w=d$ and $\operatorname{deg}_{z} w=e$. We order the bidegrees $(d, e)$ lexicographically, i.e., $\left(d_{1}, e_{1}\right)>\left(d_{2}, e_{2}\right)$ means that either $d_{1}>d_{2}$ or $d_{1}=d_{2}$ and $e_{1}>e_{2}$. We denote by $\bar{p}$ the leading bihomogeneous component of the nonzero polynomial $p(x, y, z)$. Let $\varphi=(f, g)$ be in the form (2), with all the restrictions fixed above, and let $q_{i}(y, z)$ be the leading component of $p_{i}(y, z)$. Direct computations give that, if $\rho_{n}$ is not linear and $p_{0}(y, z) \neq \gamma_{0} y+p_{0}^{\prime}(z)$ in $\rho_{0}=\left(\alpha_{0} x+p_{0}(y, z), \beta_{0} y+r_{0}(z)\right)$, then

$$
\begin{gather*}
\bar{f}=q_{0}\left(q_{1}\left(\ldots q_{n-1}\left(q_{n}(y, z), z\right) \ldots, z\right), z\right),  \tag{3}\\
\bar{g}=\beta_{0} q_{1}\left(\ldots q_{n-1}\left(q_{n}(y, z), z\right) \ldots, z\right),
\end{gather*}
$$

and bideg $\bar{f}>(1,0)$. Hence $\varphi$ is not the identity automorphism. Similar considerations work when at least one of the automorphisms $\rho_{0}$ and $\rho_{n}$ is affine. For example, if $\rho_{0}=\left(\alpha_{0}+\gamma_{0} y+p_{0}^{\prime}(z), \beta_{0} y+r_{0}(z)\right)$, $\gamma_{0} \in K^{*}$, and bideg $p_{n}(y, z)>(1,0)$, then

$$
\begin{aligned}
& \bar{f}=\gamma_{0} q_{1}\left(\ldots q_{n-1}\left(q_{n}(y, z), z\right) \ldots, z\right), \\
& \bar{g}=\beta_{0} q_{1}\left(\ldots q_{n-1}\left(q_{n}(y, z), z\right) \ldots, z\right) .
\end{aligned}
$$

If bideg $p_{0}(y, z)>(1,0)$ and $\rho_{n}=\left(x+\gamma_{n} y, y\right), \gamma_{n} \in K^{*}$, then

$$
\begin{gathered}
\bar{f}=q_{0}\left(q_{1}\left(\ldots q_{n-1}\left(q_{n}(x+\gamma y, z), z\right) \ldots, z\right), z\right), \\
\bar{g}=\beta_{0} q_{1}\left(\ldots q_{n-1}\left(q_{n}(x+\gamma y, z), z\right) \ldots, z\right) .
\end{gathered}
$$

In all the cases, $\varphi$ is not the identity automorphism. Hence, if $\varphi$ has a nontrivial presentation in the form (2), then it is different from the identity automorphism, and we conclude that $\mathrm{TAut}_{z} K\langle x, y, z\rangle$ is a free product with amalgamation of the groups $A_{z}$ and $B_{z}$.

Following our paper DY3 we identify the group of $z$-automorphisms which are linear in $x$ and $y$ with the group $G L_{2}\left(K\left[z_{1}, z_{2}\right]\right)$. Let $f \in$ $K\langle x, y, z\rangle$ be linear in $x, y$. Then $f$ has the form

$$
f=\sum \alpha_{i j} z^{i} x z^{j}+\sum \beta_{i j} z^{i} y z^{j}, \quad \alpha_{i j}, \beta_{i j} \in K .
$$

The $z$-derivatives $f_{x}$ and $f_{y}$ are defined by

$$
f_{x}=\sum \alpha_{i j} z_{1}^{i} z_{2}^{j}, \quad f_{y}=\sum \beta_{i j} z_{1}^{i} z_{2}^{j}
$$

Here $f_{x}$ and $f_{y}$ are in $K\left[z_{1}, z_{2}\right]$ and are polynomials in two commuting variables. The $z$-Jacobian matrix of the linear $z$-endomorphism $\varphi=$
$(f, g)$ of $K\langle x, y, z\rangle$ is defined as

$$
J_{z}(\varphi)=\left(\begin{array}{ll}
f_{x} & g_{x} \\
f_{y} & g_{y}
\end{array}\right)
$$

By [DY3] the mapping $\varphi \rightarrow J_{z}(\varphi)$ is an isomorphism of the group of the $z$-automorphisms which are linear in $x, y$ and $G L_{2}\left(K\left[z_{1}, z_{2}\right]\right)$. Also, such an automorphism is $z$-tame if and only if its $z$-Jacobian matrix belongs to $G E_{2}\left(K\left[z_{1}, z_{2}\right]\right)$. (By the further development of this result by Umirbaev [U], the $z$-wild automorphisms of the considered type are wild also as automorphisms of $K\langle x, y, z\rangle$.)

Corollary 1.2. The group $\operatorname{TAut}_{z} K\langle x, y, z\rangle$ is isomorphic to the free product with amalgamation $G E_{2}\left(K\left[z_{1}, z_{2}\right]\right) *_{C_{1}} B_{z}$, where $G E_{2}\left(K\left[z_{1}, z_{2}\right]\right)$ is identified as above with the group of $z$-tame automorphisms which are linear in $x$ and $y$, and $C_{1}=G E_{2}\left(K\left[z_{1}, z_{2}\right]\right) \cap B_{z}$.

Proof. Everything follows from the observations that: (i) in the form (22), $\rho_{j} \tau \cdots \tau \rho_{i} \in G E_{2}\left(K\left[z_{1}, z_{2}\right]\right)$ if and only if all $\rho_{j}, \ldots, \rho_{i}$ belong to $G E_{2}\left(K\left[z_{1}, z_{2}\right]\right)$; (ii) $\rho_{j} \tau \cdots \tau \rho_{i} \in C_{1}$ if and only if $i=j$ and $\rho_{i} \in$ $G E_{2}\left[z_{1}, z_{2}\right]$; (iii) $\tau \in G E_{2}\left(K\left[z_{1}, z_{2}\right]\right)$.

## 2. RECOGNIZING $z$-TAME AUTOMORPHISMS AND COORDINATES

Now we use Theorem 1.1 to present algorithms which recognize $z$ tame automorphisms and coordinates of $K\langle x, y, z\rangle$. Of course, in all algorithms we assume that the field $K$ is constructive. We start with an algorithm which determines whether a $z$-endomorphism of $K\langle x, y, z\rangle$ is a $z$-tame automorphism. The main idea is similar to that of the well known algorithm which decides whether an endomorphism of $K[x, y]$ is an automorphism, see Theorem 6.8.5 in [C], but the realization is more sophisticated. In order to simplify the considerations, we shall use the trick introduced by Formanek [F] in his construction of central polynomials of matrices.

Let $H_{n}$ be the subspace of $K\langle x, y, z\rangle$ consisting of all polynomials which are homogeneous of degree $n$ with respect to $x$ and $y$. We define an action of $K\left[t_{0}, t_{1}, \ldots, t_{n}\right]$ on $H_{n}$ in the following way. If

$$
w=z^{a_{0}} u_{1} z^{a_{1}} u_{2} \cdots z^{a_{n-1}} u_{n} z^{a_{n}},
$$

where $u_{i}=x$ or $u_{i}=y, i=1, \ldots, n$, then

$$
t_{0}^{b_{0}} t_{1}^{b_{1}} \cdots t_{n}^{b_{n}} * w=z^{a_{0}+b_{0}} u_{1} z^{a_{1}+b_{1}} u_{2} \cdots z^{a_{n-1}+b_{n-1}} u_{n} z^{a_{n}+b_{n}}
$$

and then extend this action by linearity. Clearly, $H_{n}$ is a free $K\left[t_{0}, t_{1}, \ldots, t_{n}\right]$ module with basis consisting of the $2^{n}$ monomials $u_{1} \cdots u_{n}$, where $u_{i}=x$ or $u_{i}=y$. The proof of the following lemma is obtained by easy direct computation.

Lemma 2.1. Let $\beta \in K^{*}$,

$$
\begin{equation*}
v(x, y, z)=\sum \theta_{i}\left(t_{0}, t_{1}, \ldots, t_{k}\right) * u_{i_{1}} \cdots u_{i_{k}} \in H_{k}, \tag{4}
\end{equation*}
$$

$$
\begin{equation*}
q(y, z)=\omega\left(t_{0}, t_{1}, \ldots, t_{d}\right) * y^{d} \in H_{d} \tag{5}
\end{equation*}
$$

where $\theta_{i} \in K\left[t_{0}, t_{1}, \ldots, t_{k}\right], \omega \in K\left[t_{0}, t_{1}, \ldots, t_{d}\right], u_{i_{j}}=x$ or $u_{i_{j}}=y$. Then

$$
\begin{aligned}
u(x, y, z)= & q(v(x, y, z) / \beta, z)=\omega\left(t_{0}, t_{d}, t_{2 d}, \ldots, t_{k d}\right) / \beta^{d} \\
& \left(\sum \theta_{i}\left(t_{0}, t_{1}, \ldots, t_{k}\right) * u_{i_{1}} \cdots u_{i_{k}}\right)
\end{aligned}
$$

$$
\begin{gather*}
\left(\sum \theta_{i}\left(t_{0}, t_{1}, \ldots, t_{k}\right) * u_{i_{1}} \cdots u_{i_{k}}\right) \\
\left(\sum \theta_{i}\left(t_{k}, t_{k+1}, \ldots, t_{2 k}\right) * u_{i_{1}} \cdots u_{i_{k}}\right) \cdots  \tag{6}\\
\left(\sum \theta_{i}\left(t_{k(d-1)}, t_{k(d-1)+1}, \ldots, t_{k d}\right) * u_{i_{1}} \cdots u_{i_{k}}\right) .
\end{gather*}
$$

Algorithm 2.2. Let $\varphi=(f, g)$ be a $z$-endomorphism of $K\langle x, y, z\rangle$. We make use of the bidegree defined in the proof of Theorem 1.1.

Step 0. If some of the polynomials $f, g$ depends on $z$ only, then $\varphi$ is not an automorphism.

Step 1. Let $u, v$ be the homogeneous components of highest bidegree of $f, g$, respectively. If both $u, v$ are of bidegree $(1,0)$, i.e., linear, then we check whether they are linearly independent. If yes, then $\varphi$ is a product of a linear automorphism (from $G L_{2}(K)$ ) and a translation $(x+p(z), y+r(z))$. If $u, v$ are linearly dependent, then $\varphi$ is not an automorphism.

Step 2. Let bideg $u>(1,0)$ and bideg $u \geq \operatorname{bideg} v$. Hence $u \in H_{l}$, $v \in H_{k}$ for some $k$ and $l$. Taking into account (3), we have to check whether $l=k d$ for a positive integer $d$ and to decide whether $u=$ $q(v / \beta, z)$ for some $\beta \in K^{*}$ and some $q(y, z) \in H_{d}$. In the notation of Lemma 2.1. we know $u$ in (6) and $v$ in (4) up to the multiplicative constant $\beta$. Hence, up to $\beta$, we know the polynomials $\theta_{i}\left(t_{0}, t_{1}, \ldots, t_{n}\right)$ in the presentation of $v$. We compare some of the nonzero polynomial coefficients of $u=\sum \lambda_{j}\left(t_{0}, \ldots, t_{k d}\right) u_{j_{1}} \cdots u_{i_{k d}}$ with the corresponding coefficient of $q(v / \beta, z)$. Lemma 2.1 allows to find explicitly, up to the value of $\beta^{d}$, the polynomial $\omega\left(t_{0}, t_{1}, \ldots, \omega_{d}\right)$ in (5) using the usual
division of polynomials. If $l=k d$ and $u=q(v / \beta, z)$, then we replace $\varphi=(f, g)$ with $\varphi_{1}=(f-q(g / \beta, z), g)$. Then we apply Step 0 to $\varphi_{1}$. If $u$ cannot be presented in the desired form, then $\varphi$ is not an automorphism.

Step 3. If bideg $v>(1,0)$ and $\operatorname{bideg} u<\operatorname{bideg} v$, we have similar considerations, as in Step 2, replacing $\varphi=(f, g)$ with $\varphi_{1}=(f, g-$ $q(f / \alpha, z))$ for suitable $q(y, z)$. Then we apply Step 0 to $\varphi_{1}$. If $v$ cannot be presented in this form, then $\varphi$ is not an automorphism.

Corollary 2.3. Let $h(t, z) \in K\langle t, z\rangle$ and let $\operatorname{deg}_{u} h(u, z)>0$. Then

$$
\sigma_{h}=(x+z h(x z-z y, z), y+h(x z-z y, z) z, z)
$$

is a $z$-wild automorphism of $K\langle x, y, z\rangle$.
Proof. It is easy to see that $\sigma_{h}$ is a $z$-automorphism of $K\langle x, y, z\rangle$ with inverse $\sigma_{-h}$. We apply Algorithm [2.2. Let $w$ be the homogeneous component of highest bidegree of $h(x z-z y, z)$. Clearly, $w$ has the form $w=\bar{h}(x z-z y, z)=q(x z-z y, z)$ for some bihomogeneous polynomial $q(t, z) \in K\langle t, z\rangle$. The leading components of the coordinates of $\sigma_{h}$ are $z q(x z-z y, z)$ and $q(x z-z y, z) z$, and are of the same bidegree. If $\sigma_{h}$ is a $z$-tame automorphism, then we can reduce the bidegree using a linear transformation, which is impossible because $z q(x z-z y, z)$ and $q(x z-z y, z) z$ are linearly independent.

The algorithm in Theorem 6.8.5 in [C] which recognizes the automorphisms of $K[x, y]$ can be easily modified to recognize the coordinates of $K[x, y]$. Such an algorithm is explicitly stated in [SY3], where Shpilrain and Yu established an algorithm which gives a canonical form, up to automorphic equivalence, of a class of polynomials in $K[x, y]$. (The automorphic equivalence problem for $K[x, y]$ asks how to decide whether, for two given polynomials $p, q \in K[x, y]$, there exists an automorphism $\varphi$ such that $q=\varphi(p)$. It was solved over $\mathbb{C}$ by Wightwick Wi and, over an arbitrary algebraically closed constructive field $K$, by MakarLimanov, Shpilrain, and Yu [MLSY].) When char $K=0$, Shpilrain and Yu SY1 gave a very simple algorithm which decides whether a polynomial $f(x, y) \in K[x, y]$ is a coordinate. Their approach is based on an idea of Wright Wr and the Euclidean division algorithm applied for the partial derivatives of a polynomial in $K[x, y]$. Using the isomorphism of Aut $K[x, y]$ and Aut $K\langle x, y\rangle$ and reducing the considerations to the case of $K[x, y]$, Shpilrain and Yu [SY2] found the first algorithm which recognizes the coordinates of $K\langle x, y\rangle$. Now we want to modify

Algorithm 2.2 to decide whether a polynomial $f(x, y, z)$ is a $z$-tame coordinate of $K\langle x, y, z\rangle$.

Note, that if $\varphi=(f, g)$ and $\varphi^{\prime}=\left(f, g^{\prime}\right)$ are two $z$-automorphisms of $K\langle x, y, z\rangle$ with the same first coordinate, then $\varphi^{-1} \varphi^{\prime}$ fixes $x$. Hence $\varphi^{-1} \varphi^{\prime}=\left(x, g^{\prime \prime}\right)$ and, obligatorily, $g^{\prime \prime}=\beta y+r(x, z)$. In this way, if we know one $z$-coordinate mate $g$ of $f$, then we are able to find all other $z$-coordinate mates. These arguments and Corollary 2.3 give immediately:

Corollary 2.4. Let $h(t, z) \in K\langle t, z\rangle$ and let $\operatorname{deg}_{u} h(u, z)>0$. Then $f(x, y, z)=x+z h(x z-z y, z)$ is a z-wild coordinate of $K\langle x, y, z\rangle$.

Theorem 2.5. There is an algorithm which decides whether a polynomial $f(x, y, z) \in K\langle x, y, z\rangle$ is a $z$-tame coordinate.

Proof. We start with the analysis of the behavior of the first coordinate $f$ of $\varphi$ in (2). Let $h$ be the first coordinate of $\psi=\rho_{n-1} \tau \cdots \tau \rho_{1} \tau \rho_{0}$ and let, as in (2), $\rho_{n}=\left(x+p_{n}(y, z), y\right)$ and $p_{n}(0, z)=0$. Then

$$
\begin{equation*}
f(x, y, z)=\rho_{n} \tau(h(x, y, z))=h\left(y, x+p_{n}(y, z), z\right) . \tag{7}
\end{equation*}
$$

In order to make the inductive step, we have to recover the polynomials $h(x, y, z)$ and $p_{n}(y, z)$ or, at least their leading components with respect to a suitable grading.

For a pair of positive integers $(a, b)$, we define the $(a, b)$-bidegree of a monomial $w \in K\langle x, y, z\rangle$ by

$$
\operatorname{bideg}_{(a, b)} w=\left(a \operatorname{deg}_{x} w+b \operatorname{deg}_{y} w, \operatorname{deg}_{z} w\right)
$$

and order the bidegrees in the lexicographic order, as in Algorithm 2.2 For a nonzero polynomial $f \in K\langle x, y, z\rangle$ we denote by $|f|_{(a, b)}$ the homogeneous component of maximal $(a, b)$-bidegree. We write $\varphi=(f, g) \in \mathrm{TAut}_{z} K\langle x, y, z\rangle$ in the form (2). Let us assume again that bideg $p_{i}(y)>(1,0)$ for all $i=0,1, \ldots, n$, and let $h$ be the first coordinate of $\psi=\rho_{n-1} \tau \cdots \tau \rho_{1} \tau \rho_{0}$. Then the highest bihomogeneous component of $h$ is

$$
\bar{h}(y, z)=q_{0}\left(q_{1}\left(\ldots\left(q_{n-1}(y, z), z\right) \ldots\right), z\right) .
$$

The homogeneous component of maximal $\left(d_{n}, 1\right)$-bidegree of $x+p_{n}(y, z)$ is $\left|x+q_{n}(y, z)\right|_{\left(d_{n}, 1\right)}=x+\xi_{n} y^{d_{n}}$ if $\operatorname{deg}_{z} q_{n}(y, z)=0$ and $\left|x+q_{n}(y, z)\right|_{\left(d_{n}, 1\right)}=$ $q_{n}(y, z)$ if $\operatorname{deg}_{z} q_{n}(y, z)>0$. Direct calculations give

$$
|f|_{\left(d_{n}, 1\right)}=\left|\rho_{n} \tau(\bar{h})\right|_{\left(d_{n}, 1\right)}=\mid \bar{h}\left(x+\left.q_{n}(y, z)\right|_{\left(d_{n}, 1\right)} .\right.
$$

If $f^{\prime}(x, z)$ and $f^{\prime \prime}(y, z)$ are the components of $f(x, y, z)$ which do not depend on $y$ and $x$, respectively, we can recover the degree $d_{n}$ of $p_{n}(y, z)$ as the quotient $d_{n}=\operatorname{deg}_{x} f^{\prime} / \operatorname{deg}_{y} f^{\prime \prime}$. Now the problem is to recover $q_{n}(y, z)$ and $\bar{h}(y, z)$. Since $\bar{h}(y, z)$ does not depend on $x$, we have that

$$
\bar{h}(y, z)=\overline{h(x, y, z)}=\overline{h(0, y, z)} .
$$

From the equality (7) and the condition $p_{n}(0, z)=0$ we obtain that

$$
f(x, 0, z)=h\left(0, x+p_{n}(0, z), z\right)=h(0, x, z) .
$$

Hence $h(0, y, z)=f(y, 0, z)$ and we are able to find $\bar{h}(y, z)$. We write $\bar{h}$ and $\overline{q_{n}}$ in the form

$$
\bar{h}(y, z)=\theta\left(t_{0}, t_{1}, \ldots, t_{k}\right) * y^{k}, \quad q_{n}(y, z)=\omega\left(t_{0}, t_{1}, \ldots, t_{d}\right) * y^{d}
$$

where $\theta\left(t_{0}, t_{1}, \ldots, t_{k}\right) \in K\left[t_{0}, t_{1}, \ldots, t_{k}\right]$ is known explicitly and $\omega\left(t_{0}, t_{1}, \ldots, t_{d}\right) \in$ $K\left[t_{0}, t_{1}, \ldots, t_{d}\right]$. Similarly, the part of the component of maximal bidegree of $f(x, y, z)$ which does not depend on $x$ has the form
$\overline{f^{\prime \prime}}(y, z)=\zeta\left(t_{0}, t_{1}, \ldots, t_{k d}\right) * y^{k d}, \quad \zeta\left(t_{0}, t_{1}, \ldots, t_{k d}\right) \in K\left[t_{0}, t_{1}, \ldots, t_{k d}\right]$.
Since $\bar{h}\left(q_{n}(y, z), z\right)=\overline{f^{\prime \prime}}(y, z)$, by Lemma 2.1 we obtain

$$
\begin{gathered}
\zeta\left(t_{0}, t_{1}, \ldots, t_{k d}\right)=\theta\left(t_{0}, t_{d}, t_{2 d}, \ldots, t_{k d}\right) \omega\left(t_{0}, t_{1}, \ldots, t_{d}\right) \\
\omega\left(t_{d}, t_{d+1}, \ldots, t_{2 d}\right) \cdots \omega\left(t_{(k-1) d}, t_{(k-1) d+1}, \ldots, t_{k d}\right)
\end{gathered}
$$

Here we know $\zeta$ and $\theta$ and want to determine $\omega$. Let

$$
\begin{gathered}
\zeta^{\prime}\left(t_{0}, t_{1}, \ldots, t_{k d}\right)=\zeta\left(t_{0}, t_{1}, \ldots, t_{k d}\right) / \theta\left(t_{0}, t_{d}, t_{2 d}, \ldots, t_{k d}\right) \\
=\omega\left(t_{0}, t_{1}, \ldots, t_{d}\right) \omega\left(t_{d}, t_{d+1}, \ldots, t_{2 d}\right) \cdots \omega\left(t_{(k-1) d}, t_{(k-1) d+1}, \ldots, t_{k d}\right) .
\end{gathered}
$$

The greatest common divisor of the polynomials $\zeta^{\prime}\left(t_{0}, t_{1}, \ldots, t_{k d}\right)$ and $\zeta^{\prime}\left(t_{(k-1) d}, t_{(k-1) d+1}, \ldots, t_{(2 k-1) d}\right)$ in $K\left[t_{0}, t_{1}, \ldots, t_{(2 k-1) d}\right]$ is equal, up to a multiplicative constant $\beta$, to $\omega\left(t_{(k-1) d}, t_{(k-1) d+1}, \ldots, t_{k d}\right)$. Hence the knowledge of $\zeta^{\prime}$ allows to determine $\beta \omega\left(t_{0}, t_{1}, \ldots, t_{k}\right)$ as well as the value of $\beta^{d}$. This means that we know also all the possible values of $\beta$ and the polynomial $q_{n}(y, z)$. Now we apply on $f(x, y, z)$ the $z$-automorphism $\sigma=\left(x-q_{n}(y, z), y\right)$. Since $f(x, y, z)-\bar{h}\left(x+q_{n}(y, z), z\right)$ is lower in the $\left(d_{n}, 1\right)$-biordering than $f(x, y, z)$ itself, we may replace $f$ with $\sigma(f)$ and to make the next step. The considerations are almost the same when some of the automorphisms $\rho_{0}$ and $\rho_{n}$ is affine. For example, if $f=\varphi(x)$ and $\rho_{n}=(x+\gamma y, y), \gamma \in K$, in (2), then the leading bihomogeneous component of $h=\tau \rho_{n}^{-1}(f)$ does not depend on $y$, and we can do the next step. If $f$ is a $z$-tame coordinate, then the above process will stop when we reduce $f$ to a polynomial in the form $\alpha x+p(y, z)$. If $f$ is not
a $z$-tame coordinate, then the process will also stop by different reason. In some step we shall reduce $f(x, y, z)$ to a polynomial $f_{1}(x, y, z)$. It may turn out that the degree $d=\operatorname{deg}_{x} f_{1}(x, 0, z) / \operatorname{deg}_{y} f_{1}(0, y, z)$ is not integer. Or, the commutative polynomials $\theta$ and $\omega$ corresponding to $f_{1}$ do not exist.

The following corollary is stronger than Corollary 2.4.
Corollary 2.6. Let $h(t, z) \in K\langle t, z\rangle$ and let $\operatorname{deg}_{u} h(u, z)>0$. Then $f(x, y, z)=x+h(x z-z y, z)$ is not a $z$-tame coordinate of $K\langle x, y, z\rangle$.

Proof. We apply the algorithm in the proof of Theorem [2.5] Let $f(x, y, z)$ be a $z$-tame coordinate and let $h^{\prime}(x, z)=h(x z, z)$ and $h^{\prime \prime}(y, z)=$ $h(-z y, z)$ be the polynomials obtained from $h(x z-z y, z)$ replacing, respectively, $y$ and $x$ by 0 . Clearly, $\operatorname{bideg}_{x} h^{\prime}=\operatorname{bideg}_{y} h^{\prime \prime}$. Hence, as in the proof of Theorem 2.5 we can replace $f(x, y, z)$ with $\sigma(f)$, where $\sigma=(x-\alpha y, y)$, for a suitable $\alpha \in K^{*}$, and the leading bihomogeneous component of $\sigma(f)$ in the $(1,1)$-ordering does not depend on $y$. But this brings to a contradiction. If $h_{1}(t, z) \in K\langle t, z\rangle$ is homogeneous with respect to $t$, and

$$
h_{1}((x-\gamma y) z-z y, z)=h_{2}(x, z)
$$

for some $h_{2}(x, z)$, then, replacing $x$ with 0 , we obtain $h_{1}(-(\gamma y z+$ $z y), z)=0$, which is impossible.

Remark 2.7. In Corollary 2.6, we cannot guarantee that the polynomial $f(x, y, z)=x+h(x z-z y, z)$ is a $z$-coordinate at all. For example, let $f(x, y, z)=x+(x z-z y)$ be a $z$-coordinate with a coordinate mate $g(x, y, z)$. If $g_{1}(x, y, z)$ is the linear in $x, y$ component of $g$, then $\varphi_{1}=\left(f, g_{1}\right)$ is also a $z$-automorphism. Then, for suitable polynomials $c, d \in K\left[z_{1}, z_{2}\right]$, the matrix

$$
J_{z}\left(\varphi_{1}\right)=\left(\begin{array}{cc}
1+z_{2} & c\left(z_{1}, z_{2}\right) \\
-z_{1} & d\left(z_{1}, z_{2}\right)
\end{array}\right)
$$

is invertible. If we replace $z_{1}$ with 0 in its determinant $\operatorname{det}\left(J_{z}\right)=$ $\left(1+z_{2}\right) d\left(z_{1}, z_{2}\right)-z_{1} c\left(z_{1}, z_{2}\right)$ we obtain that $\left(1+z_{2}\right) d_{2}\left(0, z_{2}\right) \in K^{*}$ which is impossible.

## 3. Endomorphisms which are not automorphisms

In this section we shall establish a $z$-analogue of the following proposition which is the main step of the proof of the theorem of Czerniakiewicz [Cz] and Makar-Limanov [ML1, ML2] for the tameness of the automorphisms of $K\langle x, y\rangle$.

Proposition 3.1. Let $\varphi=(x+u, y+v)$ be an endomorphism of $K\langle x, y\rangle$, where $u, v$ are in the commutator ideal of $K\langle x, y\rangle$ and at least one of them is different from 0 . Then $\varphi$ is not an automorphism of $K\langle x, y\rangle$.

An essential moment in its proof, see the book by Cohn [C], is the following lemma.

Lemma 3.2. If $f, g \in K\langle x, y\rangle$ are two bihomogeneous polynomials, then they either generate a free subalgebra of $K\langle x, y\rangle$ or, up to multiplicative constants, both are powers of the same bihomogeneous element of $K\langle x, y\rangle$.

We shall prove a weaker version of the lemma for $K\langle x, y, z\rangle$ which will be sufficient for our purposes.

Lemma 3.3. Let $(0,0) \neq(a, b) \in \mathbb{Z}^{2}$ and let $f_{1}, f_{2} \in K\langle x, y, z\rangle$ be bihomogeneous with respect to the $(a, b)$-degree of $K\langle x, y, z\rangle$, i.e., $a \operatorname{deg}_{x} w+b \operatorname{deg}_{y} w$ is the same for all monomials of $f_{1}$, and similarly for $f_{2}$. If $f_{1}$ and $f_{2}$ are algebraically dependent, then both $\operatorname{deg}_{(a, b)} f_{1}$ and $\operatorname{deg}_{(a, b)} f_{2}$ are either nonnegative or nonpositive.
Proof. Let $v\left(f_{1}, f_{2}, z\right)=0$ for some nonzero polynomial $v\left(u_{1}, u_{2}, z\right) \in$ $K\left\langle u_{1}, u_{2}, z\right\rangle$. We may assume that both $f_{1}, f_{2}$ depend not on $z$ only. We fix a term-ordering on $K\langle x, y, z\rangle$. Let $\tilde{f}_{1}$ and $\tilde{f}_{2}$ be the leading monomials of $f_{1}$ and $f_{2}$, respectively. For each monomial $z^{k_{0}} u_{i_{1}} z^{k_{1}} \cdots z^{k_{s-1}} u_{i_{s}} z^{k_{s}} \in$ $K\left\langle u_{1}, u_{2}, z\right\rangle$ the leading monomial of $z^{k_{0}} f_{i_{1}} z^{k_{1}} \cdots z^{k_{s-1}} f_{i_{s}} z^{k_{s}} \in K\langle x, y, z\rangle$ is $z^{k_{0}} \tilde{f}_{i_{1}} z^{k_{1}} \cdots z^{k_{s-1}} \tilde{f}_{i_{s}} z^{k_{s}}$. Hence, the algebraic dependence of $f_{1}$ and $f_{2}$ implies that two different monomials $z^{k_{0}} \tilde{f}_{i_{1}} z^{k_{1}} \cdots z^{k_{s-1}} \tilde{f}_{i_{s}} z^{k_{s}}$ and $z^{l_{0}} \tilde{f}_{j_{1}} z^{l_{1}} \cdots z^{l_{t-1}} \tilde{f}_{j_{t}} z^{j_{t}}$ are equal. We write $\tilde{f}_{1}=z^{p_{1}} g_{1} z^{q_{1}}$ and $\tilde{f}_{2}=$ $z^{p_{2}} g_{2} z^{q_{2}}$, where $g_{1}, g_{2}$ do not start and do not end with $z$. After some cancelation in the equation

$$
z^{k_{0}} \tilde{f}_{i_{1}} z^{k_{1}} \cdots z^{k_{s-1}} \tilde{f}_{i_{s}} z^{k_{s}}=z^{l_{0}} \tilde{f}_{j_{1}} z^{l_{1}} \cdots z^{l_{t-1}} \tilde{f}_{j_{t}} z^{j_{t}}
$$

we obtain a relation of the form

$$
\begin{equation*}
g_{a_{1}} z^{m_{1}} \cdots z^{m_{k-1}} g_{a_{k}} z^{m_{k}}=g_{b_{1}} z^{n_{1}} \cdots z^{n_{l-1}} g_{b_{l}} z^{n_{l}} \tag{8}
\end{equation*}
$$

with different $g_{a_{1}}$ and $g_{b_{1}}$. Hence, if $\operatorname{deg} g_{1} \geq \operatorname{deg} g_{2}$, then $g_{1}=g_{2} g_{3}$ for some monomial $g_{3}$ (and $g_{2}=g_{1} g_{3}$ if $\operatorname{deg} g_{1}<\operatorname{deg} g_{2}$ ). Again, $g_{2}$ and $g_{3}$ satisfy a relation of the form (8). Since $\operatorname{deg} g_{1} \geq \operatorname{deg} g_{2}>$ 0 , we obtain $\operatorname{deg} g_{1}+\operatorname{deg} g_{2}>\operatorname{deg} g_{1}=\operatorname{deg} g_{2}+\operatorname{deg} g_{3}$. Applying inductive arguments, we derive that both $\operatorname{deg}_{(a, b)} g_{2}$ and $\operatorname{deg}_{(a, b)} g_{3}$ are either nonnegative or nonpositive, and the same holds for $f_{1}$ and $f_{2}$ because $g_{1}=g_{2} g_{3}, \operatorname{deg}_{(a, b)} g_{1}=\operatorname{deg}_{(a, b)} g_{2}+\operatorname{deg}_{(a, b)} g_{3}$, and $\operatorname{deg}_{(a, b)} f_{i}=$ $\operatorname{deg}_{(a, b)} g_{i}, i=1,2$.

The condition that $u(x, y)$ and $v(x, y)$ belong to the commutator ideal of $K\langle x, y\rangle$, as in Proposition [3.1, immediately implies that all monomials of $u$ and $v$ depend on both $x$ and $y$, as required in the following theorem.

Theorem 3.4. The z-endomorphisms of the form

$$
\varphi=(x+u(x, y, z), y+v(x, y, z))
$$

where $(u, v) \neq(0,0)$ and all monomials of $u$ and $v$ depend on both $x$ and $y$, are not automorphisms of $K\langle x, y, z\rangle$.

Proof. The key moment in the proof of Proposition [3.1] is the following. If $\varphi=(x+u, y+v)$ is an endomorphism of $K\langle x, y\rangle$, where $u, v$ are in the commutator ideal of $K\langle x, y\rangle$ and at least one of them is different from 0 , then there exist two integers $a$ and $b$ such that $(a, b) \neq(0,0)$ and $a \leq 0 \leq b$ with the property that $\operatorname{deg}_{(a, b)}(x+u)=\operatorname{deg}_{(a, b)} x=a$ and $\operatorname{deg}_{(a, b)}(y+v)=\operatorname{deg}_{(a, b)} y=b$. Ordering in a suitable way the $(a, b)$-bidegrees, one concludes that the $(a, b)$-degrees of the leading bihomogeneous components of $x+u$ and $y+v$ are with different signs. Then Lemma 3.2 shows that these leading components are algebraically independent and bidegree arguments as in the proof of Proposition 3.1 give that $\varphi$ cannot be an automorphism. We repeat verbatim these arguments, working with the same $(a, b)$-(bi)degree and bidegree ordering Proposition 3.1, without counting the degree of $z$. In the final step, we use Lemma 3.3 instead of Lemma 3.2.

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