



<b>Title</b>	<b>Nonlinear magnetic circuit analysis for a novel stator-doubly-fed doubly-salient machine</b>
<b>Author(s)</b>	<b>Chau, KT; Cheng, M; Chan, CC</b>
<b>Citation</b>	<b>IEEE International Magnetics Conference Digest of Technical Papers, Netherland, 28 April - 2 May 2002, abstract no. AU-05</b>
<b>Issued Date</b>	<b>2002</b>
<b>URL</b>	<b><a href="http://hdl.handle.net/10722/46306">http://hdl.handle.net/10722/46306</a></b>
<b>Rights</b>	<b>©2002 IEEE. Personal use of this material is permitted. However, permission to reprint/republish this material for advertising or promotional purposes or for creating new collective works for resale or redistribution to servers or lists, or to reuse any copyrighted component of this work in other works must be obtained from the IEEE.</b>

**NONLINEAR MAGNETIC CIRCUIT ANALYSIS FOR A NOVEL STATOR-DOUBLY-FED DOUBLY-SALIENT MACHINE**

K.T. Chau\*, Ming Cheng<sup>#</sup> and C.C. Chan\*

\*Dept. of Electrical & Electronic Engineering, University of Hong Kong, Hong Kong, China  
<sup>#</sup>Dept. of Electrical Engineering, Southeast University, Nanjing 210096, China

**Purpose**

The doubly-salient permanent-magnet (DSPM) machine takes the advantages of high power density and high efficiency, but still suffers from limited constant-power speed range and high PM material cost [1]. This paper proposes a novel topology, namely the stator-doubly-fed doubly-salient (SDFDS) machine, which not only solves the problems of the DSPM machine, but also offers the flexibility to on-line optimize the efficiency. In order to effectively analyze and efficiently optimize the proposed machine, a new nonlinear magnetic circuit (NMC) analysis approach is also proposed.

**Proposed topology**

As shown in Fig.1, the proposed machine consists of two types of stator windings – polyphase armature winding and dc field winding. The polyphase armature winding operates like that for a DSPM machine, whereas the field winding not only works as an electromagnet but also as a tool for flux weakening and/or flux optimization.

**Proposed analysis**

A NMC model is proposed for effective analysis and efficient optimization of the SDFDS machine as shown in Fig.2, in which the non-idealities in both the airgap and pole permeances are also taken into account. The resulting static characteristics, including back EMF (Fig.3), self-inductance and mutual inductance, are verified by experimentation.

[1] M. Cheng, K.T. Chau and C.C. Chan, "Design and analysis of a new doubly salient permanent magnet motor," IEEE Trans Magnetics, 2001, pp. 3012-3020.

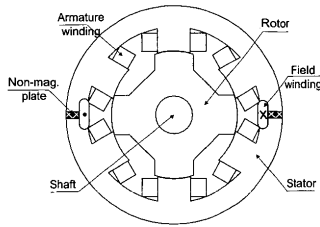


Fig.1. Proposed SDFDS machine topology.

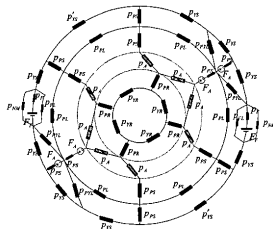


Fig.2. Proposed NMC model.

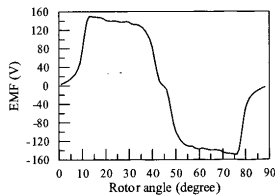


Fig.3. Back EMF characteristic.

**COGGING TORQUE MINIMIZATION FOR SMALL SPINDLE MOTOR THROUGH REDUCED-ORDER FINITE ELEMENT OPTIMIZATION**

Assoc. Prof. M. A. Jabbar, Win Lye Aye, A. B. Azeman

Electrical Machines and Drives Lab, National University of Singapore  
 WS2 #05-10 ECE, Engineering Drive 3, Singapore 117576  
 Tel: 65-8745257 Fax: 65-8744882 Email: elemaj@nus.edu.sg

**Introduction**

The optimization objective is to find a combination of magnet parameters (radial length, magnetic strength) which minimizes the cogging effect in a spindle motor (Figure 1). Reduced order finite element technique provides an accurate means to predict the cogging effect while keeping computational overhead low.

**Reduced-Order Formulation**

Reduced-order finite element formulation [1] reduces computation time by extrapolating a new solution of vector potential A from a solution set previously obtained (for various parameter combinations) when small changes to magnet parameters are made in the optimization iteration process. The problem then reduces to solving the linear system  $A_N u_N = b_N$  with  $A_N = W_N^T A_n W_N$ ,  $b_N = W_N^T b_n$ .  $u_n$  is the original n-order A vector (finite element problem with n nodes),  $u_N$  the reduced order A vector, and  $W_N$  is the  $n \times N$  set of previously calculated solutions of A. The computation is faster as it involves lower order matrix computation. The A values are then used to obtain the torque value [2] and the process repeated until a combination of magnet parameters is found to minimize the cogging torque. Typical torque profiles for various magnet properties are shown in Figure 2.

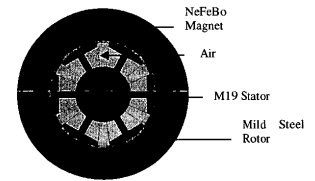


Figure 1: Spindle Motor Structure

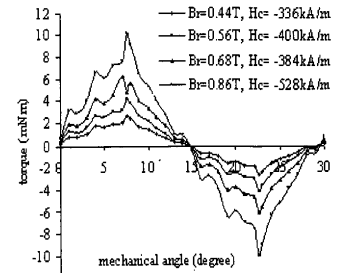


Figure 2: Cogging torque for various magnet types

**References**

- [1] Y. Maday, L. Machiels, Patera A.T., D.V. Rovas, 'Blackbox reduced-basis output bound methods for shape optimization', Proceedings 12<sup>th</sup> International Domain Decomposition Conference, Chiba Japan 2000
- [2] Salon S.J., 'Finite Element Analysis of Electrical Machines', Kluwer Academic Publishers 1995, pg 98