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EUCLID: FORECASTS FOR K-CUT 3×2 POINT STATISTICS*

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ABSTRACT

Modelling uncertainties at small scales, i.e. high k in the power spectrum P(k), due to baryonic feedback, nonlinear structure growth and the fact that galaxies are biased tracers poses a significant obstacle to fully leverage the constraining power of the *Euclid* wide-field survey. k-cut cosmic shear has recently been proposed as a method to optimally remove sensitivity to these scales while preserving usable information. In this paper we generalise the k-cut cosmic shear formalism to 3×2 point statistics and estimate the loss of information for different k-cuts in a 3×2 point analysis of the *Euclid* data. Extending the Fisher matrix analysis of Euclid Collaboration: Blanchard et al. (2019), we assess the degradation in constraining power for different k-cuts. We find that taking a k-cut at 2.6 h Mpc⁻¹ yields a dark energy Figure of Merit (FOM) of 1018. This is comparable to taking a weak lensing cut at $\ell = 5000$ and a galaxy clustering and galaxy-galaxy lensing cut at $\ell = 3000$ in a traditional 3×2 point analysis. We also find that the fraction of the observed galaxies used in the photometric clustering part of the analysis is one of the main drivers of the FOM. Removing 50% (90%) of the clustering galaxies decreases the FOM by 19% (62%). Given that the FOM depends so heavily on the fraction of galaxies used in the clustering analysis, extensive efforts should be made to handle the real-world systematics present when extending the analysis beyond the luminous red galaxy (LRG) sample.

Keywords: Cosmology, Weak Gravitational Lensing

1. INTRODUCTION

The *Euclid*¹ wide-field survey will measure the shapes and photometric redshifts of approximately 1.5 billion galaxies out to redshifts $z \sim 2$ (Laureijs et al. 2010). Cosmic shear, photometric clustering, and the correlation between background 'source galaxies' and foreground 'lens galaxies' - referred to as galaxy-galaxy lensing - will help constrain both the growth of structure and the background expansion of the late Universe. The galaxy-galaxy lensing signal is particularly important for constraining nuisance parameters which are marginalised over, to avoid a large degradation in constraining power (Tutusaus et al. 2020). At the two-point level these three signals are referred to as 3×2 point statistics.

Compared to today's photometric surveys, the *Euclid* widefield survey offers massive increases in statistical constraining power; hence 3×2 point analyses risk becoming limited by systematic effects. Modelling uncertainties at small scales is one of the primary causes as non-linear structure growth, baryonic feedback (Semboloni et al. 2011), intrinsic alignment (IA) of galaxies² (Kiessling et al. 2015), and galaxy

bias (Desjacques et al. 2018) are all uncertain at small scales.

Broadly speaking there are two ways to tackle these uncertainties. One can attempt to model the small scales potentially including a few free parameters that are either marginalised over in a likelihood analysis or calibrated against simulations - or scales can be cut. The two approaches are typically hybridised. For example, recent studies of Hyper-Suprime Cam (HSC), Dark Energy Survey (DES), and Kilo-Degree Survey (KiDS) data sets (Hikage et al. 2018; Troxel et al. 2018; Asgari et al. 2020a), all marginalised over IA parameters while cutting small angular scales.

The objective should always be to model small scales accurately. However, if scales must be cut to mitigate model bias, it is important that a maximal amount of 'useful' information at large scales is retained. Removing principal components where there is large disagreement between models (PCA) is a possible approach (Eifler et al. 2015; Huang et al. 2019, 2020). However in many circumstances it is known a priori that small scales are the most severely affected, so it is simpler and more physical to just cut these directly. Unlike PCA there is no requirement to have multiple competing models and no need to repeat the procedure for each systematic effect.

Most 3×2 point analyses take naïve angular scale or inverse angular scale cuts (i.e. ℓ -cuts in harmonic space, θ -cuts in configuration space or more optimally discrete modes (As-

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¹ http://euclid-ec.org

² Since the IA kernels are different from the lensing efficiency kernels, the k-cut developed in this work does not fully alleviate small-scale IA modelling bias.

gari et al. 2020b) when using Complete Orthogonal Sets of E/B-Integrals, abbreviated COSEBIs). None of these correspond exactly to cutting small physical scales. In this paper we present k-cut 3×2 point statistics, which are constructed to optimally filter out small scales.³ The objective of this work is to demonstrate how this formalism could be used in *Euclid* to remove sensitivity to small uncertain scales and provide forecasts for different scale cuts.

We note from the small angle approximation (or alternatively the Limber relation) that for structure at a comoving distance χ we have $\ell \sim k\chi$, so that each ℓ -mode corresponds to a unique inverse physical scale, k. Thus, in the galaxy clustering case, cutting all $\ell > k\chi$ after defining a 'typical' distance χ to each narrow tomographic bin (Lanusse et al. 2015) removes sensitivity to small scales (modes larger than k in the matter power spectrum).

This argument is not as straightforward for cosmic shear and galaxy-galaxy lensing because the lensing efficiency kernels are broad, so the lensing signal of galaxies inside a very narrow tomographic bin are sensitive to structure over a broad range in redshift. To overcome this issue, one can apply the Bernardeau-Nishimichi-Taruya (BNT) transformation (Bernardeau et al. 2014). This is a linear combination of tomographic bins which results in a set of kernels that are narrow in redshift. Then one can take tomographic bindependent ℓ -cuts to remove sensitivity to small scales. This is known as k-cut cosmic shear (Taylor et al. 2018) in harmonic space and x-cut cosmic shear (Taylor et al. 2020) in configuration space (Huterer & White 2005 proposed a similar nulling scheme). Simultaneously taking a bin-dependent angular scale cut for the galaxy-clustering auto-spectra (Lanusse et al. 2015) defines a 3×2 point statistic which is insensitive to small scale information. We refer to these as k-cut 3×2 point statistics.

While it is important to remove small scales which are not accurately modelled, this is not the only cut made in 3×2 point analyses. On the galaxy clustering side, it is typical to perform the analysis on a sub-population of the observed galaxies (or an external clustering data set). For example the Kilo-Degree Survey (KiDS-1000) 3×2 point analysis (Heymans et al. 2020) did not use the photometric data for the clustering part of the analysis, and instead used external spectroscopic data from the Baryon Oscillation Spectroscopic Survey (BOSS) (Ross et al. 2020) and 2-degree Field Lensing Survey (2dFLenS) (Blake et al. 2016). Meanwhile the DES year 1 (DESY1) analysis (Abbott et al. 2018; Elvin-Poole et al. 2018) took only luminous red galaxies (LRGs) using the red-sequence matched-filter galaxy catalog algorithm (REDMAGIC) (Rozo et al. 2016). In total 26 million 'source' galaxies were used in the DESY1 analysis, while only 650 000 'lens' galaxies were used in the clustering analysis. This amounts to approximately 2.5% of the available galaxies.

LRGs make ideal targets since they are bright, making selection effects less important, and there exists a tight photometric colour-redshift relation (Rozo et al. 2016). To expand beyond the typical LRG sample would require careful calibration of photometric redshifts, a sufficiently flexible galaxy bias model, b(k, z), to handle the expanded multiple tracer population (Kauffmann et al. 1997) and thorough mitigation of selection effects (Elvin-Poole et al. 2018) including blending, which will become more important for fainter galaxies.

In this paper we do not attempt to answer the question of how the lens galaxy sample should be extended beyond the LRG subsample. Rather we examine the trade-off between taking a larger k-cut and including a larger fraction of the available lens galaxies in the clustering analysis.

The structure of this paper is as follows. In Sect. 2 we present the k-cut 3×2 point statistics and review the Fisher matrix formalism. We present the results in Sect. 3 before concluding in Sect. 4.

2. FORMALISM

Table 1

The fiducial parameters and survey set-up used in this paper are from Euclid Collaboration: Blanchard et al. (2019) (EF19) assuming a spatially flat cosmology. We refer the reader to this work for detailed overview of the modelling assumptions. We also indicate which cosmological and nuisance parameters are fixed; all other parameters are varied in the Fisher analysis.

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Parameter value	
Survey Area $[deg^2]$ 15 000	
Number of Galaxies $[\operatorname{arcmin}^{-2}]$ 30	
σ_{ϵ} 0.3	
Number of Tomographic Bins 10	
$[z_{\min}, z_{\max}]$ $[0.0, 2.5]^a$	
σ ₈ 0.816	
$\Omega_{\rm m}$ 0.32	
$\Omega_{ m b}$ 0.05	
$\sum m_{\nu} [\text{eV}]$ 0.06 (fixed)	
h_0 0.67	
n _s 0.96	
$w_0 = -1.0$	
w_a 0.0	
A _{IA} 1.72	
$C_{\rm IA}$ 0.0134 (fixed)	
η_{IA} -0.41	
$\beta_{IA} = -2.17$	
b_i for $i \in [1, \overline{10}]$ $\sqrt{1 + \overline{z}_i}$	

^aRedshift limits before photometric smoothing.

2.1. 3×2 Point Statistics

Gravitational lensing of distant galaxies induces non-zero *E*-mode power in the angular correlations between galaxy ellipticities. For tomographic bin pairs $\{i, j\}$, with i < j, the relevant two-point statistic in harmonic space is the shear power spectrum, $C_{ij}^{\gamma\gamma}(\ell)$. Galaxy ellipticites also tidally align with large nearby dark matter halos leading to additional subdominant - yet important contributions - to the observed lensing spectrum, $C_{ij}^{\text{LL}}(\ell)$. These are referred to as intrinsic alignments. In particular the term, $C_{ij}^{\gamma \mathrm{I}}(\ell)$, accounts for correlation between shear acting on foreground galaxies and intrinsic alignments. This is taken to be zero because a background IA should not be correlated with a foreground shear. The $C_{ij}^{I\gamma}(\ell)$ terms gives the correlation between foreground IA and background shear and a $C^{\mathrm{II}}_{ij}(\ell)$ term accounts for the auto-correlation in IA. Finally a shot-noise term $N_{ij}^{LL}(\ell)$ accounts for the Poisson noise associated with the dispersion in the intrinsic ellipticities of galaxies before being sheared. We

³ We choose to work in harmonic space for the remainder of the paper, but the arguments are readily generalisable to configuration space as in Taylor et al. (2020).

are left with

$$C_{ij}^{\mathrm{LL}}(\ell) = C_{ij}^{\gamma\gamma}(\ell) + C_{ij}^{\mathrm{I}\gamma}(\ell) + C_{ij}^{\mathrm{II}}(\ell) + N_{ij}^{\mathrm{LL}}(\ell).$$
(1)

The clustering of foreground galaxies is correlated with (lensing) structure which shears background galaxies. This gives rise to the galaxy-galaxy lensing signal and we write the observed spectrum as $C_{ij}^{\text{GL}}(\ell)$. One must also account for the intrinsic alignment of galaxies so that

$$C_{ij}^{\mathrm{GL}}(\ell) = C_{ij}^{\mathrm{g}\gamma}(\ell) + C_{ij}^{\mathrm{Ig}}(\ell).$$
⁽²⁾

The terms $C_{ij}^{gI}(\ell)$ and $C_{ij}^{\gamma g}(\ell)$ are taken to be zero. There are also no shot-noise contributions since the dispersion in shear and clustering are uncorrelated.

Finally the observed clustering spectrum $C_{ij}^{\text{GG}}(\ell)$ is given as the sum of the cosmological signal and the shot-noise contributions

$$C_{ij}^{\mathrm{GG}}(\ell) = C_{ij}^{\mathrm{gg}}(\ell) + N_{ij}^{\mathrm{gg}}(\ell).$$
(3)

In practice we use the $C(\ell)$'s computed in Euclid Collaboration: Blanchard et al. (2019) (hereafter EF19 for 'Euclid forecasting'), to which we refer the reader to Sect. 3 for detailed models of the individual terms in equations (1) -(3). In brief, EF19 assume the extended Limber (LoVerde & Afshordi 2008), flat-sky (Kitching et al. 2017), Zeldovich (Kitching & Heavens 2017) and reduced shear approximations (Deshpande et al. 2020a). It has also recently been shown that k-cut cosmic shear reduces the impact of the reduced shear approximation Deshpande et al. (2020b). For the IA terms we use an extended nonlinear alignment model (eNLA) (Joachimi et al. 2011). The global IA amplitude is written as a product, $C_{IA}A_{IA}$, where A_{IA} is left as a free parameter and C_{IA} is fixed. Two free parameters η_{IA} and β_{IA} act as power law indices for the redshift and luminosity dependence respectively. The model reduces to the standard nonlinear alignment model (Bridle & King 2007) if η_{IA} and β_{IA} are taken to be zero. We also ignore the impact of magnification bias (Thiele et al. 2020). Finally, it is assumed that the galaxy bias is multiplicative leading to 10 additional nuisance parameters b_i for each tomographic bin *i*. The fiducial values are taken to be $b_i = \sqrt{1 + \bar{z}_i}$, where \bar{z}_i is the mean redshift of tomographic bin *i* in the absence of photometric redshift errors. A summary of the survey set-up, cosmological parameters, and their fiducial values are given in Tab. 1. In all cases we consider all $\ell \in [10, 5000]$, except when explicitly stated otherwise.

2.2. The Bernardeau-Nishimichi-Taruya (BNT) Transformation

For each tomographic bin, *i*, the lensing efficiency kernel, $q_i(\chi)$, gives the sensitivity of the lensing signal to structure at comoving distance χ . It is defined by

$$q_i(\chi) = \frac{3}{2} \Omega_{\rm m} \left(\frac{H_0}{c}\right)^2 \frac{\chi}{a(\chi)} \int_{\chi}^{\chi_{\rm H}} \mathrm{d}\chi' n_i(\chi') \frac{\chi' - \chi}{\chi'}, \quad (4)$$

where $\chi_{\rm H}$ is the distance to the horizon, H_0 is the Hubble parameter, $\Omega_{\rm m}$ is the fractional matter density parameter, c is the speed of light, and a is the scale factor.

As in EF19, we assume that galaxies are equipartitioned into 10 tomographic bins, and that

$$n(z) \propto (z/z_e)^2 \exp\left[-\left(z/z_e\right)^{3/2}\right],\tag{5}$$



Figure 1. Top: The radial PDF for the 10 tomographic bins considered in this work. **Middle**: The corresponding lensing efficiency kernels normalised against there maximum values. These are broad which means that the lensing signal in each tomographic bin is sensitive to structure over a broad range in redshift. **Bottom**: BNT transformed kernels. These are narrow in redshift making it possible to relate physical structure scales, k, with angular wave-modes, ℓ .

with $z_e = 0.9/\sqrt{2}$, smoothed by the Gaussian kernel

$$p(z'|z) = \frac{0.9}{\sqrt{2\pi}\sigma(z)} \exp\left[-\frac{1}{2}\left(\frac{z-z'}{\sigma(z)}\right)^2\right] + \frac{0.1}{\sqrt{2\pi}\sigma(z)} \exp\left[-\frac{1}{2}\left(\frac{z-z'-0.1}{\sigma(z)}\right)^2\right]$$
(6)

to account for photometric redshift uncertainty, with $\sigma(z) = 0.05 (1+z)$. The resulting $n_i(z)$ and $q_i(z)$ are plotted in

Fig. 1. The lensing efficiency kernels are broad in redshift which implies that the shear signal for galaxies inside each tomographic bin is sensitive to lensing structure over a broad range in redshift.

One can define new kernels which are narrow in redshift by taking a linear combination of tomographic bins

$$\tilde{q}_i(\chi) = M_{ij}q_j(\chi),\tag{7}$$

where M is the Bernardeau-Nishimichi-Taruya (BNT) transform matrix.⁴ This transform was proposed in Bernardeau et al. (2014) and the generalisation to the continuous case is explicitly written down in Taylor et al. (2020).

The BNT matrix, M, is an $N \times N$ matrix where N is the number of tomographic bins. After setting $M_{ii} = 0$ for all *i* and $M_{ij} = 0$ for i < j, the remaining BNT matrix elements are found by solving the system

$$\sum_{\substack{j=i-2}^{i}}^{i} M^{ij} = 0$$

$$\sum_{\substack{j=i-2}^{i}}^{i} M^{ij} B^{j} = 0,$$
(8)

where

$$B^{j} = \int_{0}^{z_{\text{max}}} \mathrm{d}z' \frac{n_{j}(z')}{\chi(z')} \tag{9}$$

and z_{max} is the maximum redshift of the survey. In this work we compute the BNT matrix, M, using the publicly available code at: https://github.com/pltaylor16/x-cut.

The BNT transformed kernels are shown in Fig. 1. These are narrow implying each new tomographic bin is only sensitive to lensing structure over a small range in redshift. This allows one to more precisely relate angular scale, ℓ , and physical scale, k, which we formalise in the next section.

2.3. 3×2 Point k-cut Statistics

One can also make the BNT transformation at the level of the two-point statistics by applying the BNT transformation each time the lensing efficiency kernel appears in the theoretical expressions in the spectra.⁵

In case of the lensing spectrum this is referred to as the kcut cosmic shear (Taylor et al. 2018) spectrum and is given by

$$\widetilde{C}_{ij}^{\mathrm{LL}}(\ell) = M_{ik} C_{kl}^{\mathrm{LL}}(\ell) \left(M^T \right)_{lj}.$$
(10)

In Taylor et al. (2020) this was extended to galaxy-galaxy lensing in configuration space. In harmonic space the galaxy-galaxy lensing spectrum, $\tilde{C}_{ij}^{\text{GL}}$, is given by

$$\widetilde{C}_{ij}^{\mathrm{GL}}(\ell) = C_{ik}^{\mathrm{GL}}(\ell) \left(M^T \right)_{kj}, \qquad (11)$$

The galaxy clustering spectrum is left unchanged so that

$$\widetilde{C}_{ij}^{\rm GG}(\ell) = C_{ij}^{\rm GG}(\ell).$$
(12)

⁴ Although the BNT transform formally has some cosmological dependence, it is shown in Bernardeau et al. (2014); Taylor et al. (2020) that this is an extremely small effect in practice. Nevertheless, we compute the BNT transform at the fiducial cosmology used in the rest of the paper.

⁵ The intrinsic alignment terms have different kernels from the $\gamma\gamma$ term leading to some suboptimality in the transformation. However, IA contributions account for only $\sim 10\%$ of the signal, so this is a small effect.

Each BNT transformed tomographic bin is only sensitive to structure inside a narrow redshift range. Now one can define a 'typical' comoving distance, χ_i , to each comoving bin by taking a weighted average⁶ of χ values over the BNT kernel

$$\chi_i^{\gamma} = \frac{\int_0^{\chi_H} d\chi \, \chi \tilde{q}_i(\chi)}{\int_0^{\chi_H} d\chi \, \tilde{q}_i(\chi)}.$$
(13)

In the case of galaxy clustering the kernels, $n_i(\chi)$, are already narrow and we define the typical distance as

$$\chi_i^{\rm G} = \frac{\int_0^{\chi_H} \mathrm{d}\chi \, \chi n_i(\chi)}{\int_0^{\chi_H} \mathrm{d}\chi \, n_i(\chi)}.$$
 (14)

Now using the Limber relation implies that cutting ℓ -modes with $\ell_i > k\chi_i$, for each tomographic bin, nearly completely removes sensitivity to small-scale structure above some predefined target k-mode, k. Because we are dealing with twopoint statistics, for each tomographic bin pair (i < j), there are two relevant kernels and hence – from the Limber relation – two choices for the angular scale cut. We take the most conservative of the two cuts and remove

$$\ell_{i} > \min\{k\chi_{i}^{\gamma}, k\chi_{j}^{\gamma}\},$$

$$\ell_{i} > \min\{k\chi_{i}^{G}, k\chi_{j}^{\gamma}\},$$

$$\ell_{i} > \min\{k\chi_{i}^{G}, k\chi_{j}^{G}\},$$
(15)

for the cosmic shear, galaxy-galaxy lensing, and galaxy clustering cases respectively. If this ℓ -value is larger than the global ℓ_{\max} , then no cut is made for these combination of bins. We refer to the resulting BNT transformed and cut estimators as k-cut 3×2 point statistics.

We note that it is straightforward to extend a traditional 3×2 point likelihood analysis to k-cut 3×2 statistics. The main obstacle may appear to be the computation of a valid covariance matrix to form the likelihood. However the 'likelihood sampling method' defined in Taylor et al. (2020) can be used to transform the standard 3×2 covariance into a k-cut 3×2 point covariance in a few CPU minutes. This method works by drawing noise realisations from $\mathcal{N}(0, \hat{C})$, where \hat{C} is an estimate of the covariance of $C_{ij}(\ell)$, before BNT-transforming the mock realisations and directly estimating the k-cut cosmic shear covariance matrix from the samples.⁷ To make a fair comparison with EF19, we do not perform Markov Chain Monte Carlo (MCMC) forecasting, focusing exclusively on Fisher matrix forecasting.

2.4. Fisher Forecasting

We assume a Gaussian covariance neglecting both the Super-Sample Covariance (SSC) and Non-Gaussian (NG) terms, as in EF19. Defining

$$\Delta C_{ij}^{AB}(\ell) = \sqrt{\frac{2}{(2\ell+1)f_{\rm sky}\Delta\ell}} C_{ij}^{AB}(\ell), \qquad (16)$$

⁶ To be extremely conservative, one could instead use the lower bound of the kernel, but it was found in Taylor et al. (2018) that using the mean nearly completely removes sensitivity below the desired cut.

⁷ At present the likelihood sampling method assumes the likelihood is Gaussian (although a more realistic likelihood could easily be used instead, as required). While the Gaussian likelihood approximation is valid at the level of parameter constraints for cosmic shear alone (Taylor et al. 2019; Lin et al. 2019), this must be explicitly checked for 3×2 point statistics.

where $\Delta \ell$ is the multipole bandwidth, the Fisher matrix for the 3×2 point statistics using a second-order covariance⁸ is given by

$$F_{\alpha\beta}^{\rm XC} = \sum_{\ell=\ell_{\rm min}}^{\ell_{\rm max}} \sum_{ABCD} \sum_{ij,mn} \frac{\partial C_{ij}^{AB}(\ell)}{\partial \theta_{\alpha}} \left[\Delta C^{-1}(\ell) \right]_{jm}^{AB} \times \frac{\partial C_{mn}^{CD}(\ell)}{\partial \theta_{\beta}} \left[\Delta C^{-1}(\ell) \right]_{ni}^{CD},$$
(17)

where $f_{\rm sky}$ is the fractional sky coverage, α and β label the cosmological parameters, i, j, m and n label tomographic bins and A, B, C, and D correspond to either lensing or galaxy clustering.

To make forecasts for the k-cut 3×2 point statistics we make the replacement

$$C_{ij}^{AB}(\ell) \to \widetilde{C}_{ij}^{AB}(\ell)$$
 (18)

in Eqs. (16)–(17), taking ℓ -cuts as required.

Using the publicly available⁹ Fisher matrix for the *Euclid* spectroscopic clustering analysis (see EF19), we can also include information from the spectroscopic survey

$$F_{\alpha\beta}^{\text{tot}} = F_{\alpha\beta}^{\text{XC}} + F_{\alpha\beta}^{\text{spec}}.$$
 (19)

In this paper we will consider both $F_{\alpha\beta}^{\rm XC}$ and $F_{\alpha\beta}^{\rm spec}$. This expression ignores cross-correlations that may exist between the spectroscopic and photometric probes. The majority of the spectroscopic sample lies above z = 0.9, so the cross-correlation with the photometric probes is expected to be small. For more details about the spectroscopic Fisher forecasts, we refer the reader to Sect. 3.2 of EF19.

In all that follows we use the dark energy Figure of Merit (FOM) (Albrecht et al. 2006) to compare the constraining power for different k-cuts. The FOM is proportional to the area enclosed by the 1σ contours in the $w_0 - w_a$ plane. As in Albrecht et al. (2006); Euclid Collaboration: Blanchard et al. (2019) we define the FOM as

$$FOM_{w_0w_a} = \sqrt{\tilde{F}_{w_0w_a}},$$
(20)

where $F_{w_0w_a}$ is the Fisher matrix after marginalising over all the other parameters, which is equivalent to taking the Schur complement (Kitching & Amara 2009).

3. RESULTS

We use the $C_{\ell}s$ and derivatives computed in EF19. The reader is referred to Sect. 4 of this work for a detailed discussion of the computation of the second derivatives. We perform a quick check to validate that we reproduce the results in EF19, using the standard 3×2 point statistics before exploring the *k*-cut constraints.

3.1. Verification

Taking a cut at $\ell = 3000$ for galaxy clustering and galaxygalaxy lensing while allowing the lensing spectra to range up to $\ell = 5000$, we compute the Fisher matrix for the 3×2 point statistics. The choice of ℓ -cuts is 'the optimistic case'



Figure 2. The absolute value of the computed marginal errors relative to the fiducial parameter values in EF19 (orange) and this work (blue). We find excellent agreement, validating our Fisher matrix code.

considered in EF19. After marginalising over the nuisance parameters, we compute the absolute value of the ratio of the marginal error relative to the fiducial values, $|\sigma/\theta_{\rm fid}|$,¹⁰ and compare our results to EF19 in Fig. 2. We find excellent agreement. The FOM differs by 1%.

3.2. Fiducial 3×2 Point Forecasts

We examine the change in the FOM for different k-cuts in Fig. 3. Even after taking k-cuts one may still need to take an ℓ -cut to remove detector systematics so we consider both $\ell_{\text{max}} = 5000$ (top) and $\ell_{\text{max}} = 3000$ (bottom), before taking additional ℓ -cuts to make the k-cut. The colour scale indicates the FOM. On the axes, $k_{\text{cut}}^{\text{L}}$ indicates the k-mode cut scale for cosmic shear while $k_{\text{cut}}^{\text{G}}$ gives the cut scale for galaxy clustering and galaxy-galaxy lensing.¹¹ The solid black line corresponds to the FOM target of 400 from the *Euclid* Red Book (Laureijs et al. 2010). It should be noted that the Red Book forecasts are for a non-flat cosmology, so the results presented here are not strictly comparable. The dotted and dashed continuous lines indicate FOMs of 367 and 1033, respectively. These are the FOMs for the 'pessimistic' and 'optimistic' cases in EF19 which are summarised in Tab. 2.

Table 2Overview of the cut scales for the 'optimistic' and 'pessimistic' analyses inEF19 and the fiducial k-cut 3×2 point analysis used in this work (see
Sect. 3.2).

	Optimistic	Pessimistic	Fiducial	
$\ell_{\rm cut}^{\rm G}$	5000	1500	5000	
$\ell_{\rm cut}^{\rm L}$	3000	750	5000	
$k_{\rm cut}^{\rm G}[h {\rm Mpc}^{-1}]$	N/A	N/A	2.6	
$k_{\rm cut}^{\rm L}[h{\rm Mpc}^{-1}]$	N/A	N/A	2.6	
FOM	1033	367	1018	

For the case $\ell_{\rm max} = 5000$, a cut of $k \sim 2.6 \ h \ {\rm Mpc}^{-1}$

 10 For the parameter w_a the fiducial value is zero, so we use $\sigma(w_a)$ instead of $|\sigma/\theta_{\rm fid}|.$ 11 We choose to have the same cut scale for galaxy-galaxy lensing and

¹¹ We choose to have the same cut scale for galaxy-galaxy lensing and clustering since they both have dependence on the galaxy bias. In a more realistic setting, this is uncertain at high-k.

⁸ It is shown in Carron (2013) that the the fourth-order covariance and second-order covariance Fisher formalisms will yield the same forecasts.

⁹ https://github.com/euclidist-forecasting/fisher_ for_public



Figure 3. Dark energy Figure of Merit (FOM). $k_{\text{cut}}^{\text{L}}$ gives the k-cut scale for cosmic shear while $k_{\text{cut}}^{\text{G}}$ gives the cut scale for galaxy clustering and galaxy-galaxy lensing. Dotted and dashed continuous black lines correspond to FOMs of 367 and 1033 respectively. These are the FOMs for the 'pessimistic' and 'optimistic' cases in EF19 which are summarised in Tab. 2. The solid black line marks a FOM of 400 from the *Euclid* Red Book **Top:** Global $\ell_{\text{max}} = 5000$. A cut scale of $k \sim 2.6 h \text{ Mpc}^{-1}$ yields a similar FOM to the optimistic case in EF19. **Bottom:** Global $\ell_{\text{max}} = 3000$.



Figure 4. Same as Fig. 3 except this we include the spectroscopic clustering information by adding the spectroscopic clustering Fisher matrix as in Eq. (19). For the spectroscopic forecasts we take the 'optimistic settings' from EF19 (we refer the reader to Sect. 4 of that work for more details). Compared to the fiducial case, the inclusion of the spectroscopic data increases the FOM by 20% while using the same cut scales ($k_{\rm cut}^{\rm L} = k_{\rm cut}^{\rm G} = 2.6 \ h \ {\rm Mpc}^{-1}$ and $\ell_{\rm max} = 5000$).

for clustering, lensing, and cross-correlations gives a similar



Figure 5. Same as Fig. 3 but using a sub-sample of the available galaxies for the photometric clustering analysis **Top**: FOM using 1% of the available galaxies. **Middle** FOM using 10% of the available galaxies. **Bottom**: FOM using 50% of the available galaxies. At the fiducial cut scale, $k_{\text{cut}}^{\text{L}} = k_{\text{cut}}^{\text{G}} = 2.6 h \text{ Mpc}^{-1}$, the FOMs for a subsample of 1%, 5%, 10%, 50% and 100% of available galaxies are 73, 378, 820, and 1018 respectively.

FOM to the optimistic case in EF19, while $k \sim 0.7 h \text{ Mpc}^{-1}$ yields a FOM of 400 from the *Euclid* Red Book.

Modelling uncertainties are problematic at high k but other systematics (e.g. point-spread function corrections) become a problem at high ℓ (Euclid Collaboration: Paykari et al. 2020). For this reason we also consider the case where $\ell_{\rm max} = 3000$. Then a cut scale of $k \sim 4 h \,{\rm Mpc}^{-1}$ and $k \sim 0.7 h \,{\rm Mpc}^{-1}$ for both clustering and lensing are needed to match the optimistic and Red Book FOMs respectively.

We take as our fiducial case $\ell_{\rm max} = 5000$ with $k_{\rm cut}^{\rm L} =$

 $k_{\rm cut}^{\rm G} = 2.6 \ h \ {\rm Mpc}^{-1}$, because it has a FOM of 1018, close to the optimistic case in EF19.

3.3. Inclusion of Spectroscopic Clustering

In Fig. 4 we again plot the FOM as function of cut scales $(k_{\text{cut}}^{\text{G}} \text{ and } k_{\text{cut}}^{\text{L}})$ but this time we also include information by adding the spectroscopic clustering Fisher matrix as in Eq. (19). For the spectroscopic Fisher matrix, we use the optimistic spec-*z* settings in EF19 (the reader is referred to Sect. 4 of this work for more details).

Including the information from spectroscopic clustering analysis means that it is possible to take a cut at a smaller k-value while achieving the same FOM. For example a FOM of 400 meeting the Red Book requirements can be achieved by taking a k-cut at 0.6 h Mpc⁻¹. Meanwhile at the fiducial cut scale of $k_{cut}^{L} = k_{cut}^{G} = 2.6 h$ Mpc⁻¹, the inclusion of spectroscopic information improves the FOM by 19%.

3.4. Reduced Tracer Population

So far we have assumed that 100% of the available galaxies are used in the photometric clustering analysis. However current Stage III 3×2 point analyses (Abbott et al. 2018; Heymans et al. 2020) use only a fraction of the galaxies for the clustering analysis compared to the cosmic shear measurement. This simplifies the analysis as galaxy bias is strongly dependent on type and using bright galaxies minimises the impact of foregrounds (Elvin-Poole et al. 2018). In this section we explore the impact of only using sub-sample of the available galaxies in the photometric clustering analysis. Specifically we recompute the FOM after multiplying the galaxy-clustering shot-noise term, defined in Eq. (3), by 1/F, where F is the fraction of galaxies used in the photometric clustering analysis.

The results of this computation are shown in Fig. 5 which are worth comparing to Fig. 3. The top, middle and bottom subplots correspond to using 1%, 10% and 50% of the available galaxies respectively.

When only 1% of the galaxies are used, the FOM never exceeds 400, while for 10%, the FOM never exceeds 1000 – for any choice of k-cut. When 50% of the galaxies are used, we achieve the 'optimistic' case FOM described in EF19 when we take a cut at $k \sim 5 h \text{ Mpc}^{-1}$ and a FOM of 400 with a cut at $k \sim 1 h \text{ Mpc}^{-1}$.

At the fiducial cut scale, $k_{\text{cut}}^{\text{L}} = k_{\text{cut}}^{\text{G}} = 2.6 \ h \ \text{Mpc}^{-1}$, the FOMs for a subsample of 1%, 5%, 10%, 50%, and 100% of available galaxies are 73, 378, 820, and 1018. Thus increasing the subsample from 10% to 50% more than doubles the FOM while expanding the subsample from 50% to 100% increases the FOM by 24%. This gain is similar to including the spectroscopic clustering (see the previous section) in the analysis. It is evident that including a larger fraction of the available galaxies in the photometric clustering analysis is one of the primary drivers of the FOM in *Euclid*.

Meanwhile when we include the spectroscopic information as in Sect. 3.3 taking the fiducial cut scale of $k_{\text{cut}}^{\text{L}} = k_{\text{cut}}^{\text{G}} =$ 2.6 h Mpc⁻¹, the FOMs for a subsample of 1%, 5%, 10%, 50%, and 100% of available galaxies are 228, 567, 1008 and 1207. When 50% of the galaxies are used we achieve we achieve the 'optimistic' case FOM of 1033 for a cut at $k \sim$ $3 h \text{ Mpc}^{-1}$ and an FOM of 400 when we take a cut at $k \sim$ $0.6 h \text{ Mpc}^{-1}$. This is in comparison to the case where we use 100% of the galaxies when we achieve we achieve the 'optimistic' case FOM for a cut at $k \sim 1 h \text{ Mpc}^{-1}$ and an FOM of 400 when for a cut at $k \sim 0.6 h \text{ Mpc}^{-1}$

It should be noted that we have made two useful first-order approximations in this section:

- The shape of redshift distribution function n(z) is fixed. In reality each tracer population has its own distribution function changing the global n(z) as more galaxies are included.
- The photometric uncertainty is fixed. In fact photo-z estimates for the commonly-used LRG subsample are more precise than for most other populations (Rozo et al. 2016). For this reason our results likely overestimate the information loss from excluding galaxies.

Studying the impact of these effects is left to a future work.

4. CONCLUSIONS

In this paper we have developed the formalism for k-cut 3×2 point statistics and provided Fisher forecasts for *Euclid*. In a more realistic setting one would likely need to include free parameters for multiplicative biases, as well as more complicated models for IA and galaxy bias. One would also need to consider the impact of non-Gaussian (Barreira et al. 2018) and super-sample corrections (Hu & Kravtsov 2003) to the covariance. Since the 3×2 point statistics are not linear in the cosmological parameters, MCMC forecasting would give more realistic constraints. These extensions are left to a future work.

The k-method efficiently removes sensitivity to small physical scales which are difficult to model. This enables the extraction of useful information at small angular scales which would otherwise need to be completely removed from the analysis. We find that taking a cut at $k = 2.6 \ h \ Mpc^{-1}$ (while taking a global $\ell_{max} = 5000$) for both galaxy clustering and lensing yields FOM of 1018 which is similar to the 'optimistic case' ($\ell_{max} = 5000$ for lensing and $\ell_{max} = 3000$ for clustering and galaxy-galaxy lensing) in EF19 where an FOM of 1033 is achieved. The final choice of k-cut in *Euclid* depends on the accuracy of the matter power spectrum model at the time the data arrives. This is left for investigation in a future work.

To avoid bias from 'observational' systematics (caused by e.g. point-spread function residuals, blending, foreground and charge transfer inefficiency) in k-cut 3×2 point analyses, it may be necessary to take additional angular scale cuts. A thorough investigation of 'observational' systematics (Euclid Collaboration: Paykari et al. 2020) at these typically excluded angular scales (high ℓ) is warranted.

The clustering part of Stage III 3×2 point analyses have worked with LRGs (Abbott et al. 2018) or directly with data from external spectroscopic surveys (Heymans et al. 2020; van Uitert et al. 2018; Joudaki et al. 2018) for the clustering analysis. Hence we have investigated the degradation in FOM when only sub population of the available galaxies are used in the clustering analysis. We find this to be one of the primary drivers of the FOM in *Euclid*.

We have demonstrated that k-cut 3×2 point statistics are a viable method to reduce sensitivity to small poorly modelled scales in *Euclid*. This comes at virtually no cost given the small computational overhead and the fact that this technique can be used in combination with other mitigation strategies (e.g. marginalising over baryonic feedback nuisance parameters). In light of ever-improving models of small-scale physics, we leave the determination of the optimal cut scale for *Euclid*, which must strike a balance between minimising bias and precision, to a future work. Meanwhile we have shown the importance of including as many galaxies in the photometric clustering sample as possible.

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