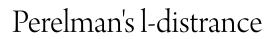


University of Wollongong Research Online

Faculty of Engineering and Information Sciences -Papers: Part A

Faculty of Engineering and Information Sciences

2008



V.-M Wheeler University of Wollongong, vwheeler@uow.edu.au

Publication Details

Vulcanov, V. (2008). Perelman's l-distrance. Oberwolfach Reports, 46 2637-2638.

Research Online is the open access institutional repository for the University of Wollongong. For further information contact the UOW Library: research-pubs@uow.edu.au

Perelman's l-distrance

Abstract

This talk is a preparation of the necessary tools for proving the non-collapsing results. The L-length defined by Perelman is the analog of an energy path, but defined in a Riemannian manifold context. The length is used to define the l reduced distance and later on, the reduced volume. So far the properties of the l-length have two applications in the proof of the Poincare conjecture. Associated with the notion of reduced volume, they are used to prove non-collapsing results and also to study the K- solutions.

Keywords

distrance, l, perelman

Disciplines

Engineering | Science and Technology Studies

Publication Details

Vulcanov, V. (2008). Perelman's l-distrance. Oberwolfach Reports, 46 2637-2638.

Perelman's *l*-distance

VALENTINA VULCANOV

This talk is a preparation of the necessary tools for proving the non-collapsing results. The \mathcal{L} -length defined by Perelman is the analog of an energy path, but defined in a Riemannian manifold context. The length is used to define the lreduced distance and later on, the reduced volume. So far the properties of the *l*-length have two applications in the proof of the Poincaré conjecture. Associated with the notion of reduced volume, they are used to prove non-collapsing results and also to study the κ - solutions.

The first step is introducing the reduced distance by means of the \mathcal{L} -length defined by Perelman, |2|.

Consider a backward solution of the Ricci flow $(M, g(\tau))$:

$$\frac{\partial}{\partial \tau}g_{ij}(\tau) = 2Ric_{ij}(g(\tau)),$$

where $\tau = T - t$ (T is the final time). Let $\gamma : [\tau_1, \tau_2] \rightarrow M$ be a curve on the manifold parametrized by backward time.

Definition 1 ([2]). The \mathcal{L} -length of a curve γ is

$$\mathcal{L}(\gamma) := \int_{\tau_1}^{\tau_2} \sqrt{\tau} (R(\gamma(\tau)) + |\dot{\gamma}(\tau)|^2) d\tau,$$

where $R(\gamma(\tau))$ is the scalar curvature at the point $\gamma(\tau)$.

Considering a variation of the curve γ , $\tilde{\gamma}(s,\tau)$, $s \in (-\epsilon, +\epsilon)$, $t \in [\tau_1, \tau_2]$ we can define the tangential and variational vector fields by $X = \frac{\partial \tilde{\gamma}}{\partial \tau}$ and $Y = \frac{\partial \tilde{\gamma}}{\partial s}$. The first properties obtained are the (Euler-Lagrange) equations of \mathcal{L} -geodesics:

Proposition 1 ([2]). There holds

$$\nabla_X X - \frac{1}{2}\nabla R + 2Ric(X, \cdot) + \frac{1}{2\tau}X = 0.$$

The proof comes easily from the first variation formula for the \mathcal{L} -length.

Let $\tau_1 = 0$ and $\tau_2 = \overline{\tau}$ we consider furthermore variations of curves on M, connecting points $p, q \in M$ with fixed starting point p and moving end point $q = q(\overline{\tau}).$

Definition 2 ([2]). Denote by $L(q,\overline{\tau})$ the \mathcal{L} -length of the \mathcal{L} - shortest curve $\gamma(\tau)$, $0 \leq \tau \leq \overline{\tau}$ connecting p and q.

The reduced length is defined as $l(q, \tau) = \frac{L(q, \tau)}{2\sqrt{\tau}}$.

From the definition one can see that properties of the reduced distance can be easily obtained if we have the corresponding ones for the \mathcal{L} -length. We are concentrating the last mentioned ones in two main propositions:

Proposition 2 ([2]). There holds

$$L_{\overline{\tau}}(q,\overline{\tau}) = 2\sqrt{\overline{\tau}}R(q) - \frac{1}{\overline{\tau}}K - \frac{1}{2\overline{\tau}}L(q,\overline{\tau}),$$
$$\nabla L|^2(q,\overline{\tau}) = -4\overline{\tau}R(q) + \frac{2}{\sqrt{\overline{\tau}}}L(q,\overline{\tau}) - \frac{4}{\sqrt{\overline{\tau}}}K.$$

where $K = K(\gamma, \overline{\tau}) = \int_0^{\overline{\tau}} \tau^{\frac{3}{2}} H(X(\tau)) d\tau$ and H(X) is the trace of the expression appearing in Hamilton's Harnack inequality, [4].

Proposition 3 ([2]). There holds

$$\Delta L \le \frac{n}{\sqrt{\tau}} - 2\sqrt{\tau}R - \frac{1}{\tau}\int_0^{\overline{\tau}} H(X)d\tau.$$

For the proof of the last one we have followed the detailed steps of [1, 3]. One starts by computing the second variation and then the Hessian of the \mathcal{L} -length. We define the \mathcal{L} -Jacobi fields along \mathcal{L} -geodesics and prove that they are minimizers of Hessian of the \mathcal{L} -length. Then making a special choice of orthonormal basis for $T_{\gamma(\tau)}M$ we obtain the result.

Using the above properties of the \mathcal{L} -length we can also obtain the reduced length $l(q, \tau)$ properties, which will be used in the following to prove monotonicity of reduced volume and non-collapsing results:

Proposition 4 ([2]). One has

$$\begin{split} l_{\overline{\tau}} &-\Delta l + |\nabla l|^2 - R + \frac{n}{2\overline{\tau}} \ge 0\\ 2\Delta l - |\nabla l|^2 + R + \frac{l - n}{\overline{\tau}} \le 0\\ \min_{\overline{\tau}} l(\cdot, \overline{\tau}) \le \frac{n}{2}\\ \frac{d}{d\tau}|_{\tau = \overline{\tau}} |\tilde{Y}|^2 \le \frac{1}{\overline{\tau}} - \frac{1}{\sqrt{\overline{\tau}}} \int_0^{\overline{\tau}} \sqrt{\tau} H(X, \tilde{Y}) d\tau, \end{split}$$

where \tilde{Y} is any \mathcal{L} - Jacobi field along $\gamma(\tau)$.

References

- [1] Bruce Kleiner, John Lott. Notes on Pereman's papers. http://arxiv.org/abs/math.DG/0605667
- [2] Grisha Perelman. The entropy formula for the Ricci flow and its geometric application. arxiv.org/abs/math.DG/0211159
- [3] John Morgan, Gang Tian. Ricci flow and the Poincaré conjecture. arxiv.org/abs/math.DG/0607607
- [4] Richard Hamilton. The Harnack estimate for the Ricci flow. J. Differential Geom. 41 (1995),215-226.