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NPSNET - Large-Scale Virtual Environment Technology Testbed (presentation to the International Conference on Artificial Reality & Tele-existence (ICAT))



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NPSNET - Large Scale Virtual Environment Technology Testbed Michael Zyda, Don Brutzman, Rudy Darken, Robert McGhee, John Falby, Eric Bachmann, Kent Watsen, & Ben Kayanagh Naval Postgraduate School zyda@siggraph.org



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Talk Outline

NPSNET Research Group Overview

- Techno software technology for the networked VE.
- Interact interaction technology for the networked VE.
- Apps VE applications.

Educational Infrastructure - MOVES Curriculum

How I spent my summer vacation

NPSNET Research Group

The focus of the NPSNET Research Group is on the complete breadth of humancomputer interaction and software technology for implementing large scale virtual environments (LSVEs).

In addition, we apply that research in constructing VEs useful for the DoD.



NPSNET **NPSNET Research Group NPSNET Techno** Interact Apps **NPSNET-V Inertial Motion LSVE Network** Tracking **NPSNET-IV** Software Arch. **Locomotion Devices Amphibious VE** Web-Based **Human Modeling** Interoperability in the VE Bamboo -**Spatial Sound VE Toolkit** Wayfinding World-Building

LSVE Network Software Architecture



LSVE - large scale virtual environment -

- a networked virtual environment with greater than 1,000 players in it.
 - When we say this large a number of players, we mean both live/interactive and autonomous/ computer-generated characters.

LSVE Network Software Architecture



Network Software Architecture (NSA) -

 the combination of the network protocol used for the LSVE and the software architecture that supports that protocol within the confines of available bandwidth and processor cycles.

 There are many protocol-only and software architecture-only solutions. There are few full NSA solutions.

NSA for the VE Research Directions



Web-Based VE Interoperability

- What are the issues?
 - What types of information need to be transferred between web-based networked VEs?
 - How do we transfer that information on the Internet (protocol)?
 - What is the NSA for this?



What types of information need to be transferred between networked VEs?

- State changes/entity interactions (peer-to-peer).
- Heavy-Weight Objects (http client/server requests).
- Network pointers (URLs).
- Real-time streams (Mbone audio/video).



How do we transfer that information (protocol)?

- Projects
 - Dial-a-protocol project (peer-to-peer).

 virtual reality transfer protocol - vrtp (the applications-layer protocol used to wrap together dissimilar application layer protocols).



Dial-a-protocol project

- Development of tools/methods for the rapid generation of peer-to-peer VE applications layer network protocols.
 - How do we formally specify the state change and entity interaction information?
 - How do we embed semantics in syntax in general? How do we do this on-the-fly?



Dial-a-protocol project

- How do we formally specify the state change and entity interaction information?
 - Formal BNF specification of DIS.
 - PDU specification editor and code generator for DIS readers/writers.
 - HTML combo-form PDU specification editor.



Dial-a-protocol project

 How do we formally specify the state change and entity interaction information?

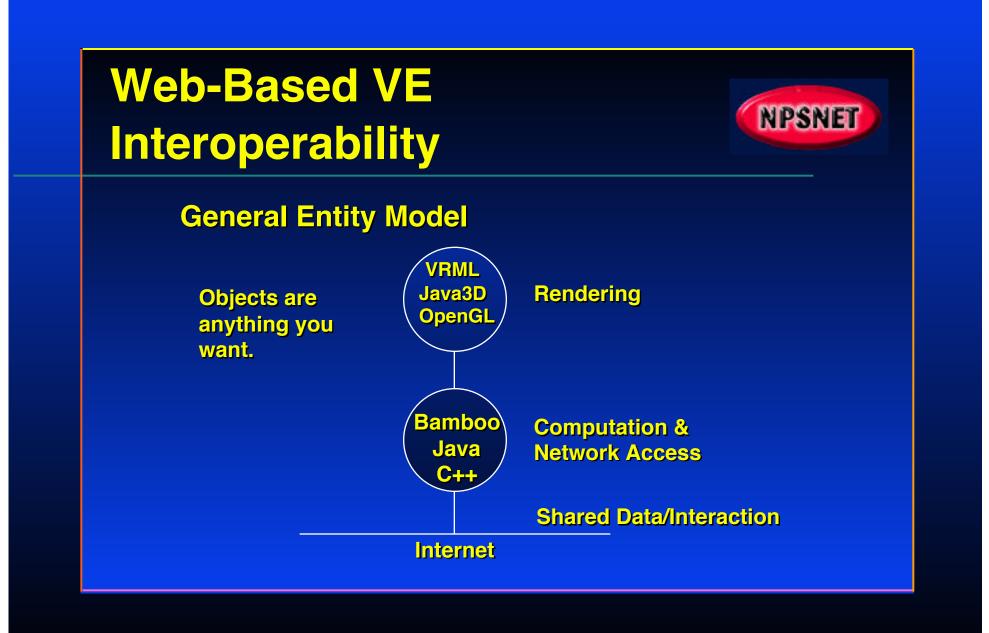
- DIS-Java-VRML

There is a working group working on how we provide DIS-like interoperability for the web. This is a fast-track effort with early success (1500 PDUs per second).



Dial-a-protocol project

- How do we embed semantics in syntax in general? How do we do this on-the-fly?
 - What we are looking at very much has the flavor of Internet agents.
 - ▲ Behavior is encoded in a packet.
 - ▲ Syntax is (identifier type, number of bits).
 - ▲ Semantics is Java object & methods.





How do we transfer that information (protocol)?

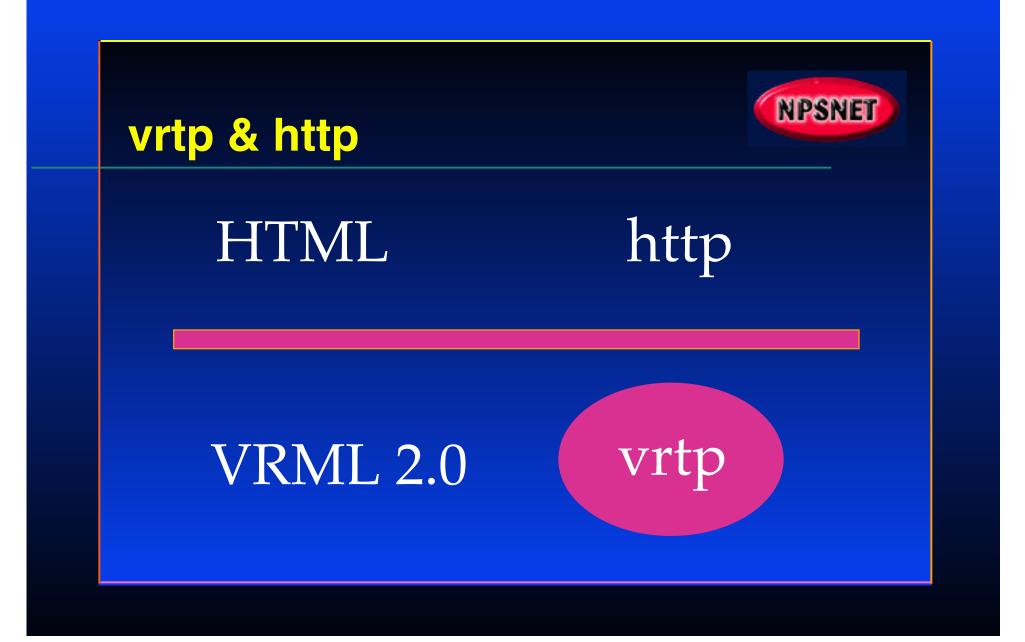
 The dial-a-protocol project looks at a very small piece of the peer-to-peer, light-weight entity interaction problem in networking VEs.

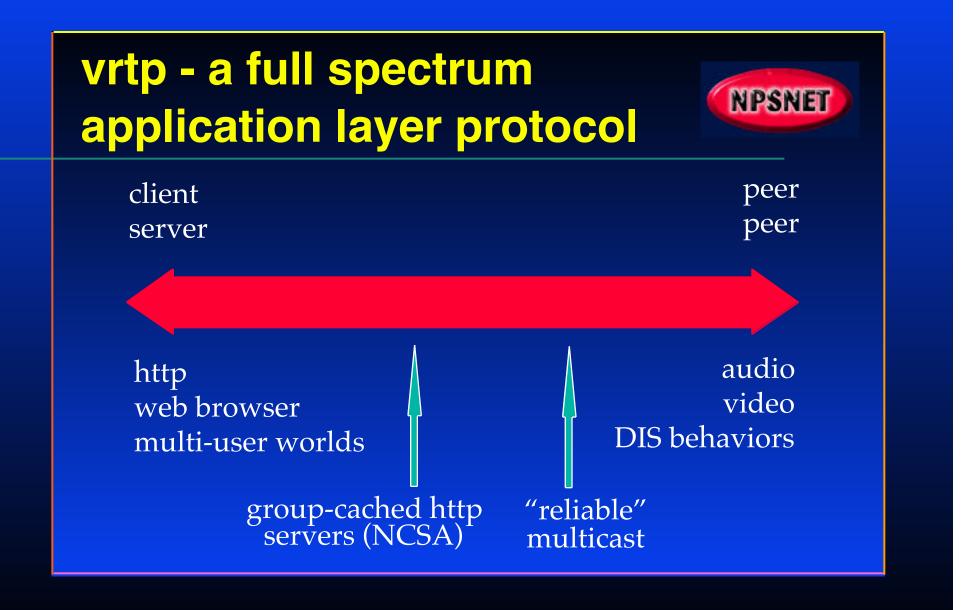
 If we go back and look at our list of types of information to be transferred between VEs, we see there are other types of data in our VE ...



virtual reality transfer protocol - vrtp

- the application-layer protocol used to wrap together dissimilar application layer protocols.
- vrtp will support:
 - Light-weight entity interactions (peer-to-peer).
 - Network pointers (URLs).
 - Heavy-weight objects (http client/server request).
 - Real-time streams (Mbone audio/video).







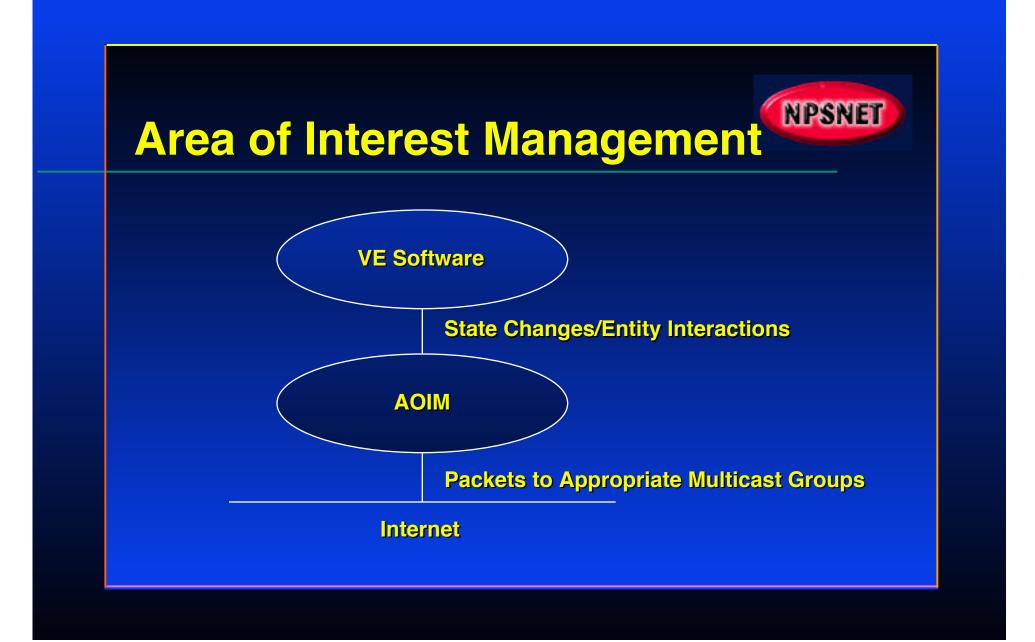
The primary problem we are trying to solve is how to optimize available bandwidth and available processor cycles for our LSVE.

- We don't want to bury the CPU in processing packets at the applications layer of the operating system.
- We don't want to flood the network with unnecessary packets.

We have done a lot of software experimentation and systems testing to get a good understanding of the software architecture issues.

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 We are now focusing on a layer of software we call the Area of Interest Manager (AOIM).



State Changes/Entity Interactions

 instead of being broadcast to everyone, are assigned to particular multicast groups (groups are interested parties, spatial partitioning, functional partitioning, temporal partitioning, ...).

Packets to Appropriate Multicast Groups

- Multicast groups are subscribed to by appropriate parties.
- Packets not part of subscribed multicast groups are killed off at the network interface unit rather than at the applications layer in the CPU!
- So your VE only gets packets from groups formally subscribed to.

Research Issues in AOIMs

How do we program in a general way an AOIM?

- AOIMs are application dependent. How do we design such systems for dynamic AOIM replacement?
- In a distributed fashion, how do we dynamically assign information to a particular set of multicast groups?

DoD Standards for Interoperability



The NPSNET Research Group has always been on the leading edge in the development and utilization of DoD standards for interoperability.

- NPSNET-IV is SIMNET and DIS compliant.
- We are currently evaluating HLA for its utility in interactive LSVEs.

Bamboo - An Extensible Framework for Networked VES

Motivation:

 A general-purpose, cross-platform, high-level toolkit providing a framework facilitating VE application research and development.

What is Bamboo?



- Core mechanisms common to networked VEs.
 - an API toolkit for serious programmers.
- Dynamically extensible runtime environment.
 an application which puts it all together.
- Based on OpenGL++.
 - which implies OpenGL, C++, STL.



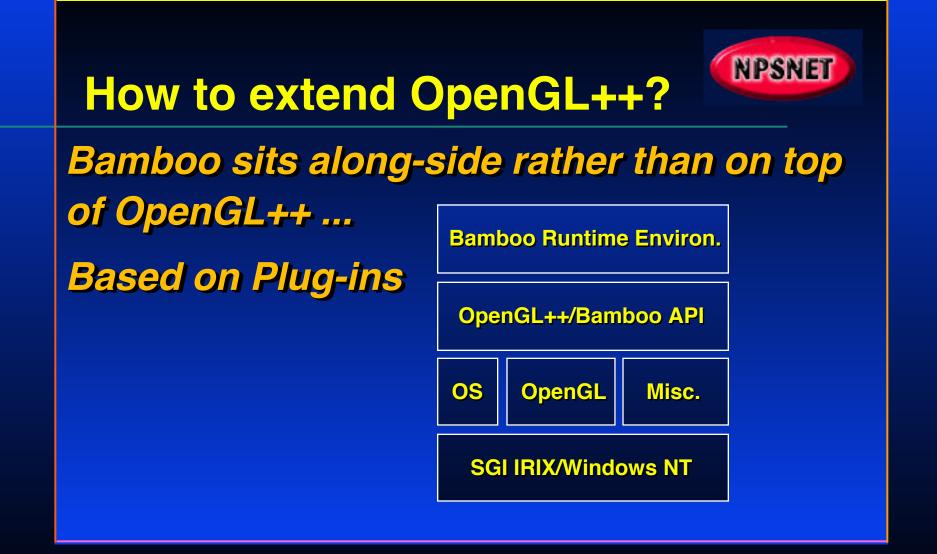
What is OpenGL++?

Multi-platform (SGI, Windows NT, BeOS, Linux, etc.)

Visualization toolkit (Performer + Inventor)

Mechanisms:

 RTTI, linear math routines, scene graph, construction and manipulation, draw/probe/sound actions (traversals), engines (spline, morph), fields, routes, and some extensibility.



Bamboo's Mechanisms

Extensibility Networking Security Process Management Inter-Process Communication Remote Procedure Calls Callbacks Event Handling Device Manager Database Handling Statistics Manager Graphical User Interface Undo/Redo Physically-Based Modeling Friendly OpenGL++

VE World Building











Interact

Inertial Motion Tracking of Humans in a Networked VE Locomotion Devices Human Modeling in the VE Spatial Sound Wayfinding

Current technologies are unable to provide a natural and intuitive interface for inserting a human into a large scale networked virtual environment.

Advances in the design of micromachined accelerometers and angular rate sensors and 3D spatial positioning using RF, present the possibility of tracking human body motion inertially in a manner similar to that of an inertial navigation system (INS).

Current human motion capture systems suffer from numerous limitations:

- User encumbrance
- Restricted Range
- Susceptibility to Interference
- Latency
- Shadowing

The hybrid inertial tracking system is essentially sourceless and does not suffer from these limitations.

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Inertial body tracking is based upon same algorithms as inertial navigation of missiles, aircraft and ships.

Physics resemble those of the human vestibular system.

Proposed tracking system advantages:

- High data rates without perceptible lag.
- Tolerant to environmentally induced errors.
- Will produce consistent registration between physical and virtual worlds.
- Allow multiple users in a large working volume simultaneously.

Basic Concept:

 Instrument the Human body with 15 micromachined inertial sensors.

- Each sensor contains:
 - Three-axis accelerometer.
 - Three-axis rate sensor.
 - Three-axis magnetometer.

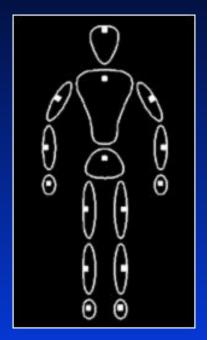
Complementary filtering would correct for sensor errors and drift.

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The sensors would provide an orientation vector for each body segment.

RF positioning of a single point on the body would accurately place the articulated human within the VE.

Human Body Tracking Sensor Configuration



Locomotion Devices



Most of our work in locomotion devices has been to integrate other people's locomotion devices into the NPSNET-IV software platform.

Two of our most successful demos

AUSA 95 Treadport



Joint project with Sarcos Engineering, UPENN & NPS.

 NPS role was to integrate treadport into NPSNET-IV.



AUSA 96 Omni Directional Treadmill (ODT)



Human Modeling in the VE

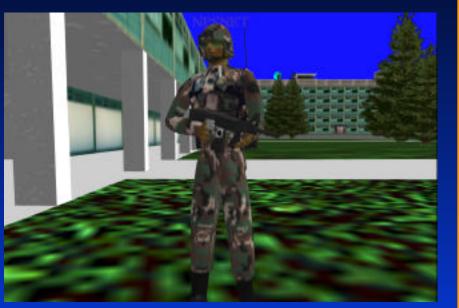
We have explored commercial solutions for animating articulated humans in the VE.

- UPENN Jack-ML
- BDI DI-Guy
- All of these solutions are too slow once you get above about 5 to 10 humans in view.

Human Modeling in the VE

Low-cost, articulated humans.

 We want to develop articulated human support software capable of displaying 100 to 150 humans in the NPSNET-V VE.



Spatial Sound for the VE



Virtual Environment Auditory & Visual Intersensory Modality Issues

- Measuring performance & immersion during wayfinding and target acquisition tasks in a VE.
 - Are manipulating both auditory & visual display fidelities.
 - Want to find out the effects of both modalities on performance & immersion.

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Wayfinding in the VE

Training Spatial Knowledge Acquisition Using Virtual Environments

 The goal of the work is to show that VEs can be used to acquire spatial knowledge of a specific real space (training transfer).

Wayfinding in the VE



- Future work will involve the investigation of environmental features and perceptual stimuli and their role in navigation and wayfinding so that we may understand how to degrade the fidelity of a VE without substantially degrading navigation performance.
- We will then extend these concepts to training general navigation skills, including map usage (perspective transformation) and landmarking abilities.

Applications of VE Technology NPSNET-IV Completion NPSNET-V An Amphibious VE



NPSNET-IV Completion

NPSNET-IV Capabilities

- Building walkthroughs.
- Articulated humans mounting/dismounting capability.
- Networking play across the multicast backbone of Internet.

 Terrain database integration, terrain paging (70km x 70km).

- Any vehicle capability air, ground, articulated human.
- Testbed for VE NSA issues.
- Interoperability SIMNET/DIS
 - Constructive model integration - Janus World Modeler
 - ModSAF

NPSNET-ODT Press Conference & AUSA 96











NPSNET-V

Features & Plans

- Redesigning the network software architecture of NPSNET.
- Plug & play VE where additional modules of capabilities (networking, human models, terrain models, walkthroughs, mounting/dismounting of humans, general interaction ...) can be developed with a uniform, published API.

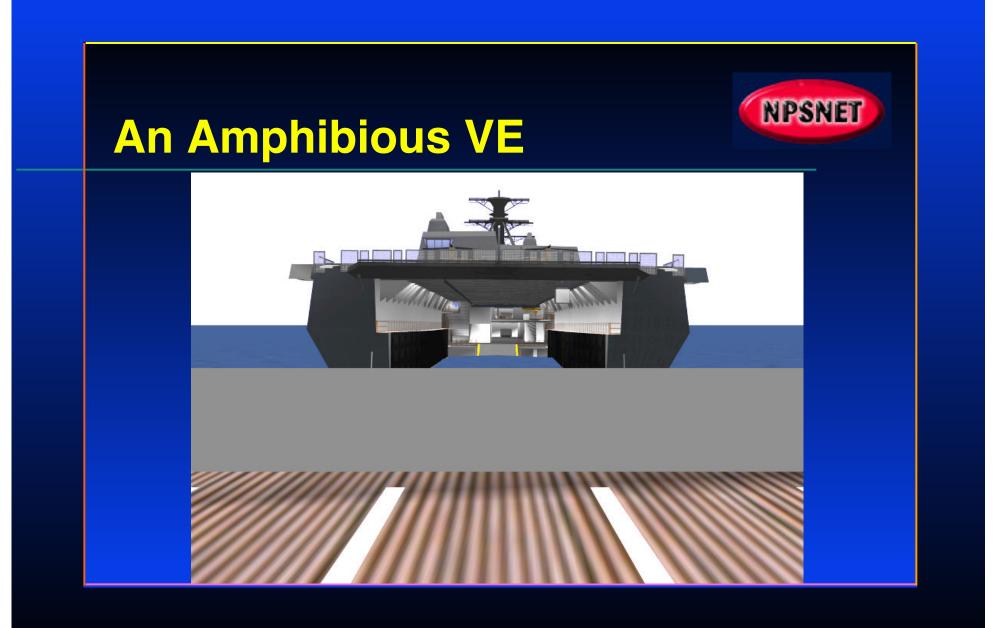


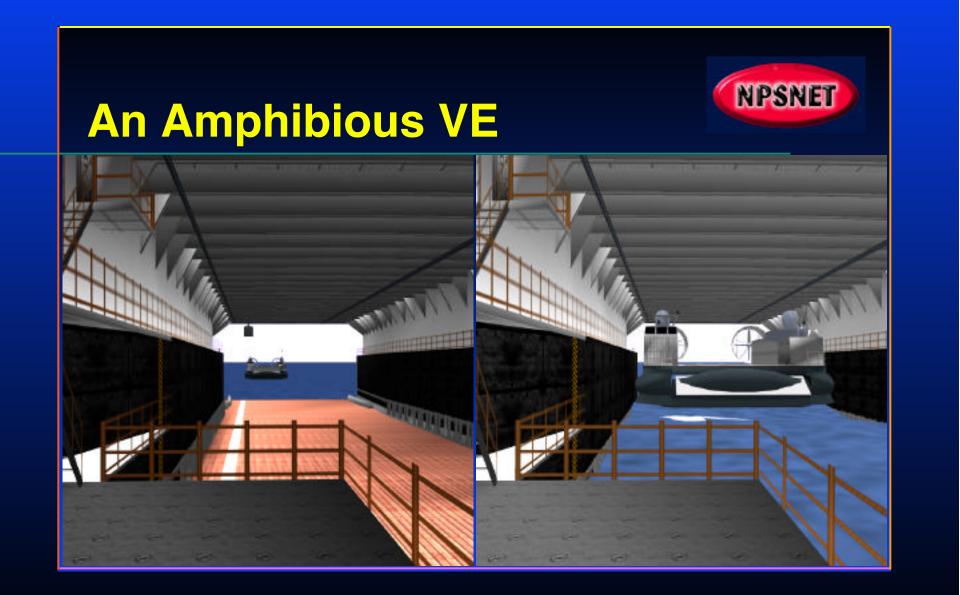
NPSNET-V

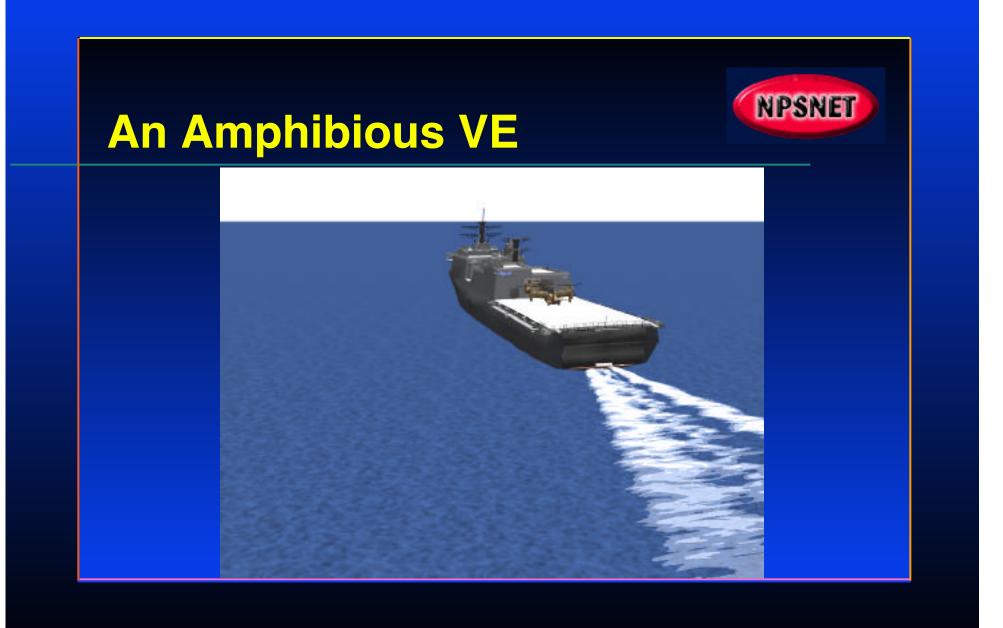
Technologies for NPSNET-V

- Bamboo Next Generation Toolkit
 - OpenGL++
 - -C++/Java
 - vrtp & HLA









Educational Infrastructure

MS & PhD Program in Computer Science, with specialization in Computer Graphics & Visual Simulation

Educational Infrastructure - MOVES Curriculum



Modeling, Virtual Environments & Simulation Curriculum

 The MOVES Curriculum provides the MS and Ph.D. student both fundamental & specialized courses in applied computer simulation technology & the application of quantitative analyses to humancomputer interaction in simulation technology.

Educational Infrastructure - MOVES Curriculum



- There are two tracks that support the curriculum's research efforts, the Visual Simulation Track and the Human-Computer Interaction Track.
 - The Visual Simulation track is focused on developing the technolgy for VEs.
 - The Human-Computer Interaction track is focused on evaluating human performance with the developed technology.

NRC CSTB - Modeling & Simulation Linking Entertainment & Defense

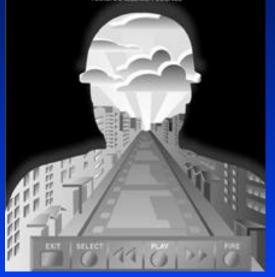
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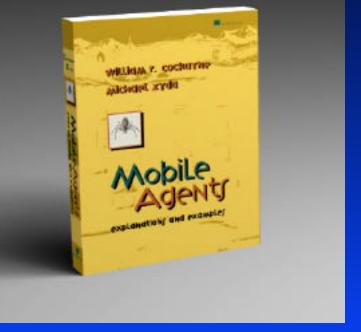
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