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2005-03

Battlespace Language Activities at NPS

Blais, Curtis L.

Battlespace Language Activities at NPS, Coalition Battle Management Language (C-BML)

Workshop, ODU/VMASC, 7-9 March 2005

<http://hdl.handle.net/10945/36558>



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Battlespace Language Activities at NPS

Curtis Blais, MOVES Institute
Coalition BML SISO Study Group Workshop
7-9 March 2005

Relevant NPS Efforts 2000-present

■ C2IEDM

- Scenario Authoring and Visualization for Advanced Graphical Environments (SAVAGE)
- Interoperability, Data Control and Battlespace Visualization
- MOOTW FAST Toolbox Data Interchange
- Coalition Secure Management and Operations System (COSMOS)

■ C2IEDM and BML

- Common Maneuver Network (CMN) and Mobility Common Operational Picture (M-COP)

■ Maritime BML

- Autonomous Vehicle Control Language (AVCL)

Scenario Authoring and Visualization for Advanced Graphical Environments

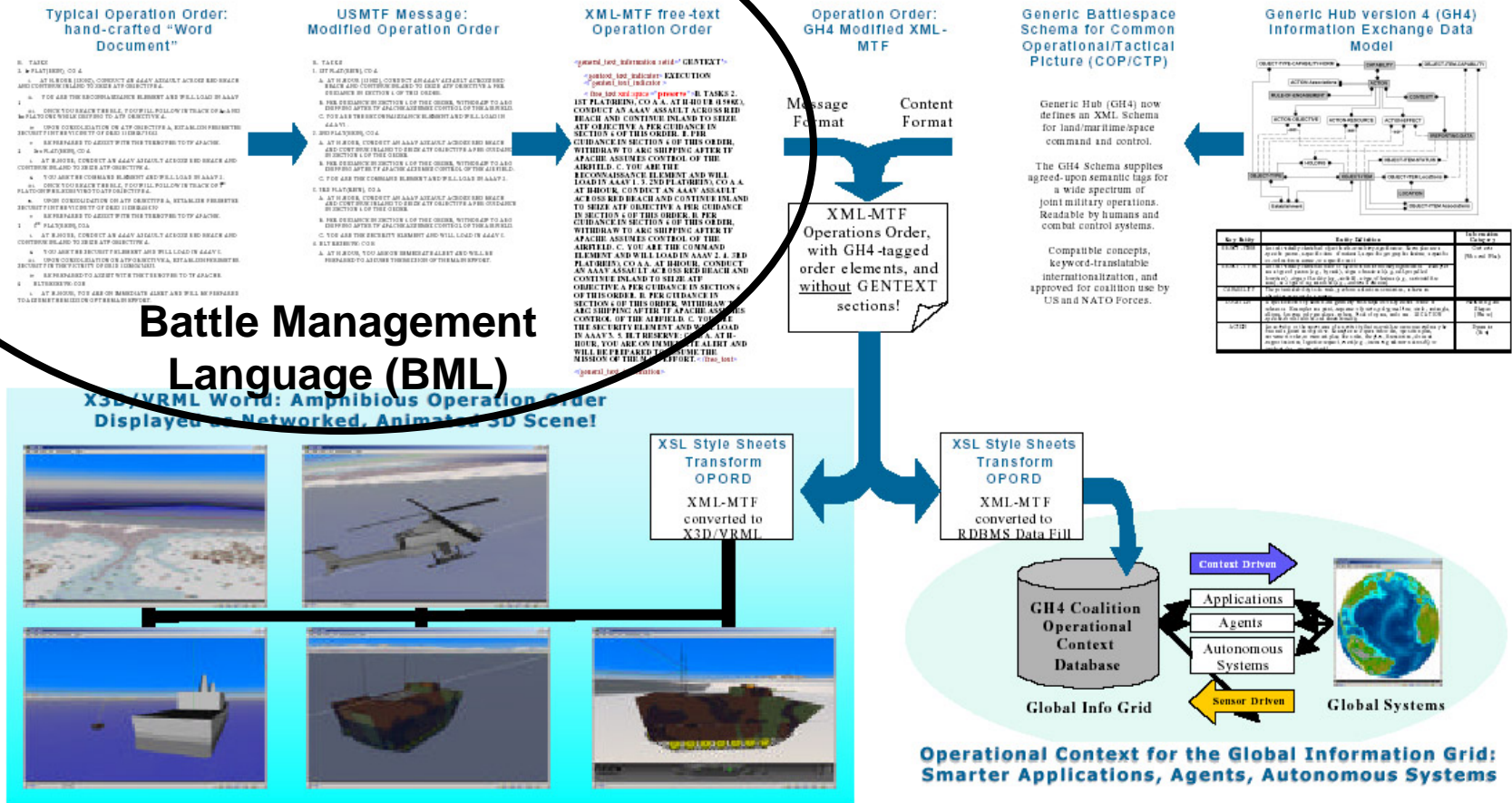
- Maj Shane Nicklaus, USMC, *Scenario Authoring and Visualization for Advanced Graphical Environments (SAVAGE)*, Master's Thesis, September 2001

<http://MovesInstitute.org/Theses/ShaneNicklaus.pdf>

- “This research presents an integrated Web access and 3D visualization strategy for Department of Defense (DOD) tactical messaging and operation orders using the Generic Hub data model and the Extensible Markup Language (XML).”

Operations Order Data Interchange

Generic Hub Design Methodology for Battlespace Visualization + Semantics: DoD-wide Autoconversion Of Operation Orders into 3D Virtual Environments



Points of Contact: Erik Chalm NUTC ChalmE@npt.navy.mil - Francisco Loaiza IDA FLoaiza@ida.org - Eugene Simaitis IDA GSimatt@ida.org - Don Brutzman, Shane Nicklaus, Doug Horner NPS brutzman@nps.navy.mil
13 September 2001

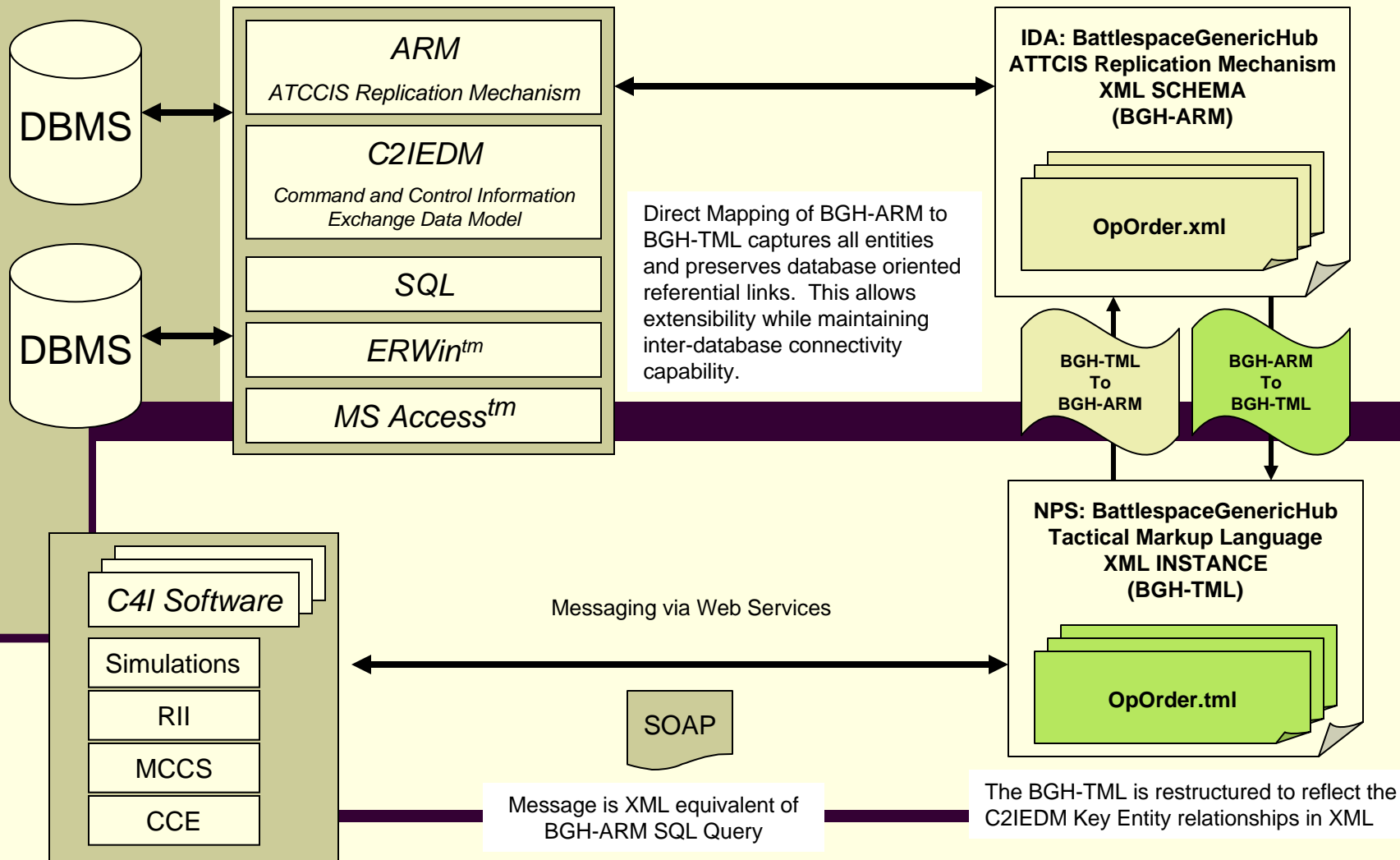
Interoperability, Data Control and Battlespace Visualization

- Capt James Neushul, USMC, *Interoperability, Data Control and Battlespace Visualization Using XML, XSLT, and X3D*, Master's Thesis, September 2003

<http://MovesInstitute.org/Theses/NeushulThesis.pdf>

- “The application of structured data methodologies using the Extensible Markup Language (XML) allows organizations and systems to exchange and process battlespace information cooperatively.”

Battlespace Generic Hub (BGH) – XML Schema Extensions



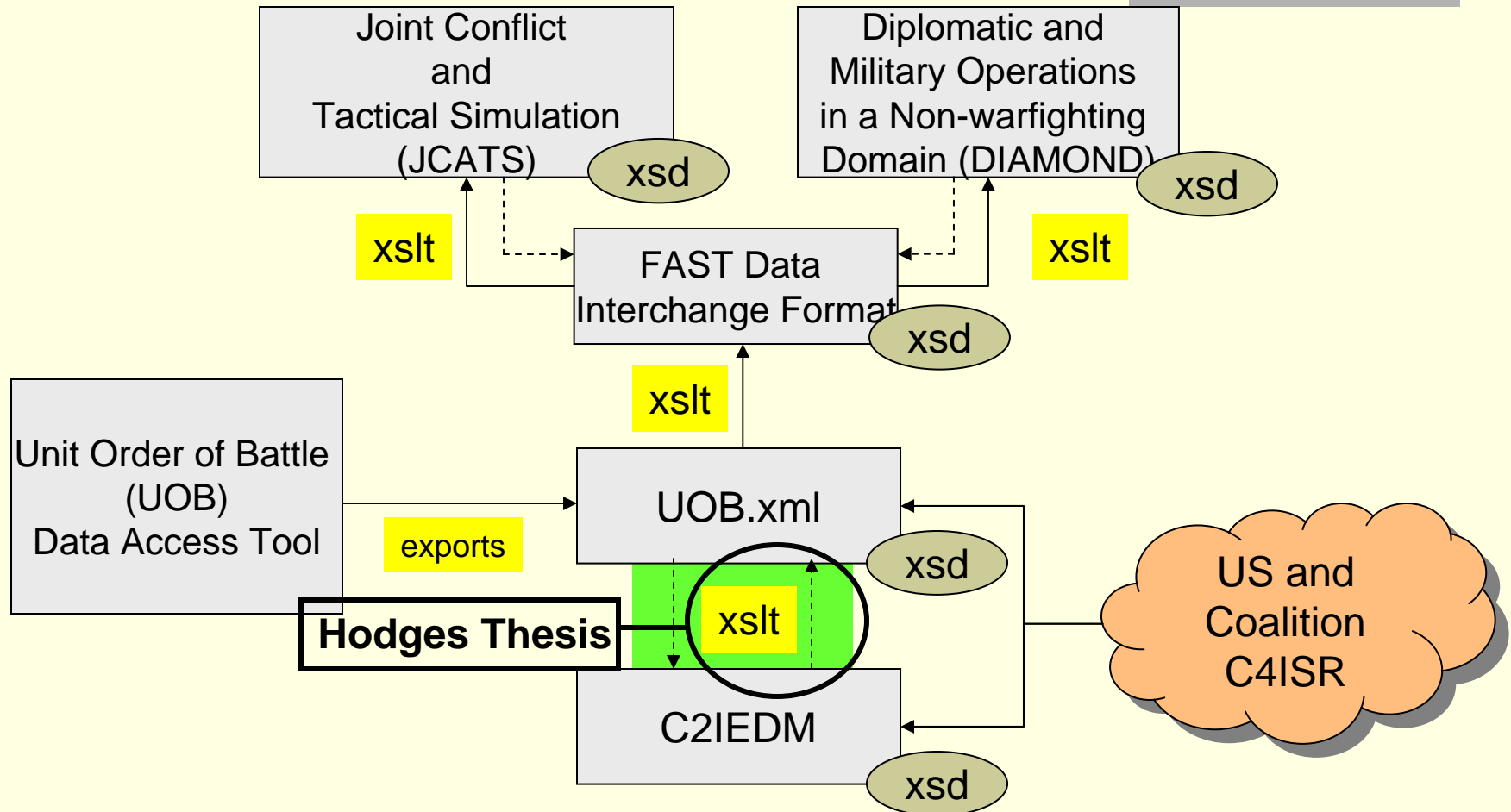
MOOTW FAST Toolbox Data Interchange

- Capt Glenn Hodges, USA, *Designing a Common Interchange Format for Unit Data using the Command and Control Information Exchange Data Model (C2IEDM) and XSLT*, Master's Thesis, September 2003

<http://www.movesinstitute.org/Theses/Hodgesthesis.pdf>

- “Using a common data representation like C2IEDM coupled with the power of XML and XSLT, unit information can be transformed and interchanged between applications.”

Unit Data Interchange



COSMOS ACTD

- Coalition Secure Management and Operations System (COSMOS) Advanced Concept Technology Demonstration (ACTD)
 - “Enable rapid information exchange among MIP-compliant coalition C2 applications using the MIP specifications and procedures.”
- Various initiatives planned/proposed:
 - C2IEDM-enabled data interchange under role-based access controls
 - C2IEDM for description of roles
 - C2IEDM for description of the network
 - C2IEDM-based tactical chat (“possibly part of a virtual collaborative environment supported by DEM replication?”)

Extending C2IEDM for CBRN*

Professor Tom Johnson

Department of National Security Affairs (NSA/JO)

Naval Postgraduate School

APM for Data, JPM IS under JPEO CBD (SPAWAR PMW 150)

Deputy DoD CBRN XML Namespace Manager

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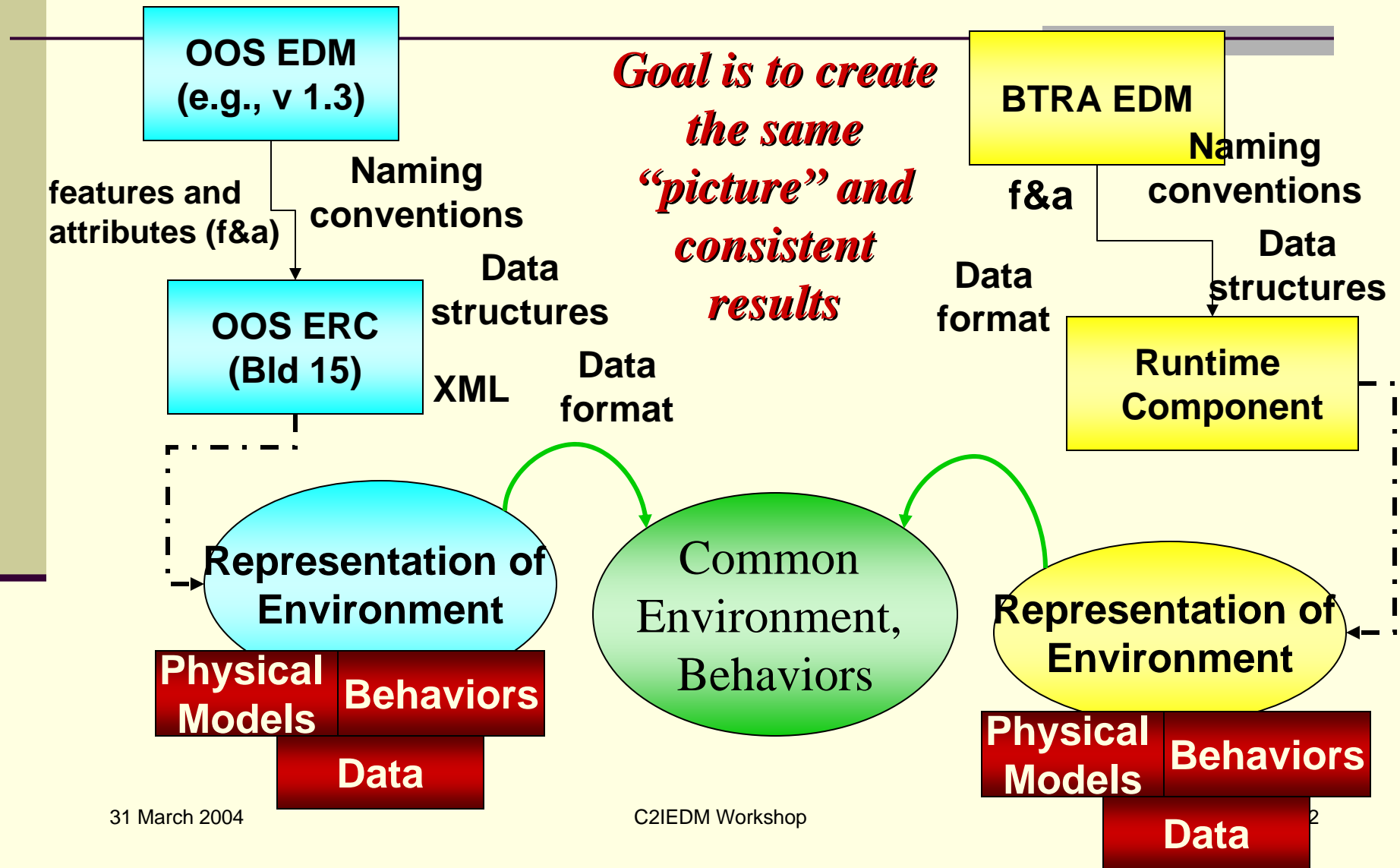
thjohnson@msiac.dmsso.mil (703-933-3301)

*Chemical, Biological,
Radiological, and Nuclear

Common Maneuver Network

- Common data representations across C4I systems and M&S (embedded M&S in FCS)
 - Battlespace Terrain Reasoning and Awareness (BTRA)
 - OneSAF Objective System (OOS)
- Various maneuver network representations
 - BML
 - C2IEDM
 - Military Scenario Definition Language (MSDL)
 - Geography Markup Language (GML)

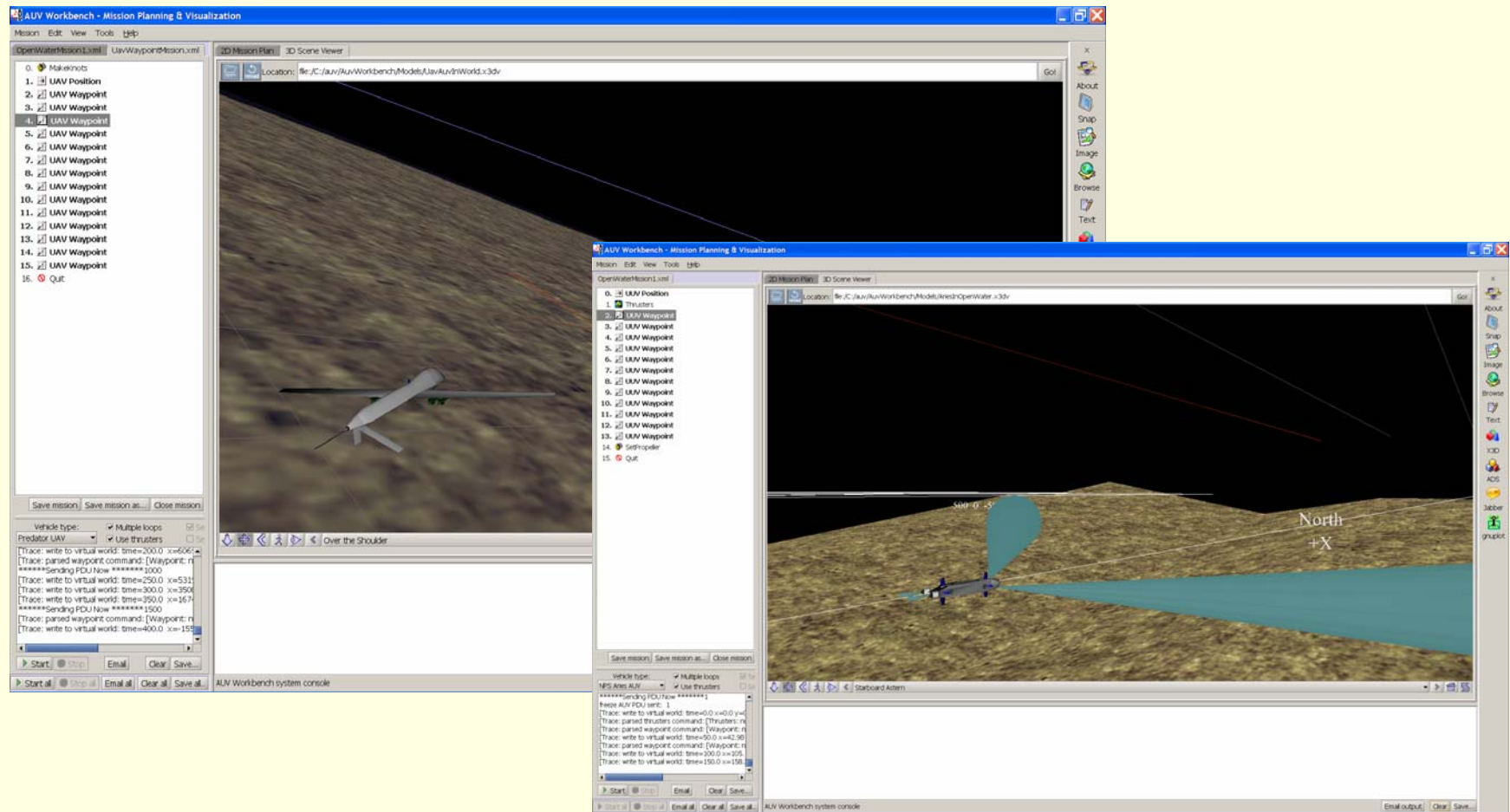
Common Maneuver Networks



Maritime BML

- Adapt BML to context of Naval operations
 - Work proposed; not yet started
 - Scenarios: Anti-Submarine Warfare (ASW), SSBN / Special Operations Forces
- Autonomous Vehicle Control Language (AVCL)
 - XML language for arbitrary autonomous vehicle mission definition, inter-vehicle communication and mission-data storage
 - CDR Duane Davis, USN, PhD dissertation, in progress – designing the language for compatibility with JC3IEDM
 - May be useful to BML/C-BML as start of the control language for robotic forces

AVCL in the Autonomous and Unmanned Vehicle (AUV) Workbench



Questions?

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